GTEC

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Chapter 1

Class Index

1.1 Class List

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Chapter 2

File Index

2.1 File List

Here is a list of all documented files with brief descriptions:

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/home/mowais/GTEC/src/ephemerisR.hpp													
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File Index

Chapter 3

Class Documentation

3.1 ephemerisGE Class Reference

Public Attributes

- int Toc
- int Toe
- int week
- · float Ahalf
- float e
- float M0
- float w
- float i0
- float Omega0
- float deltan
- float idot
- float Omegadot
- float Cuc
- float Cus
- float Crc
- float Crs
- float Cic
- float Cis

The documentation for this class was generated from the following file:

• /home/mowais/GTEC/src/ephemerisGE.hpp

3.2 ephemerisR Class Reference

Public Attributes

- int tb
- float px
- float py
- float pz
- float vx
- float vy
- float vz
- float xdd
- float ydd
- float zdd

The documentation for this class was generated from the following file:

• /home/mowais/GTEC/src/ephemerisR.hpp

3.3 inout Class Reference

Public Member Functions

- void process_Inputs (int ac, char *args[])
- void dump (std::ostream &s)

Public Attributes

- · int nobsfiles
- · int nnavfiles
- bool systemGPS
- bool systemGlonass
- bool systemGalileo
- bool systemBeidou
- bool systemQZSS
- int numDays
- std::string inputDirectory
- std::string satSys
- · std::string marker
- int sampingTime
- · int firstDayOfYear
- int year
- int minArcLen
- int intrpollntrvl
- int deg
- std::vector< std::string > obsfiles
- std::vector< std::string > navfiles

Private Member Functions

• void checkInputFiles ()

The documentation for this class was generated from the following files:

- /home/mowais/GTEC/src/inout.hpp
- /home/mowais/GTEC/src/inout.cpp

3.4 int_pair Class Reference

Public Member Functions

• int_pair (int, int)

Public Attributes

- int start
- int end

The documentation for this class was generated from the following files:

- /home/mowais/GTEC/src/int_pair.hpp
- /home/mowais/GTEC/src/int_pair.cpp

3.5 internalTime Class Reference

```
#include <internalTime.hpp>
```

Public Member Functions

• internalTime (int Y, int M, int D, int h, int m, int s)

Constructor with explicit values.

• void parse (std::string strtime)

Member function parse.

- void parse (std::string, std::string &)
- void toUNIXTime ()

Member Function, providing UNIX time.

- void toUNIXTime (int)
- internalTime ()

Public Attributes

- int year
- int month

Stores Month as Integer.

• int day

Stores day as Integer.

• int hour

Stores hour as Integer.

· int minute

Stores minute as Integer.

· int second

Stores second as Integer.

• int UNIX

Stores Converted UNIX Time as Integer.

3.5.1 Detailed Description

Author

Muhammad Owais

Date

04/12/16

3.5.2 Constructor & Destructor Documentation

3.5.2.1 internalTime::internalTime (int Y, int M, int D, int h, int m, int s)

Constructor with explicit values.

Constructs internal Time object explicitly taking date/time values as parameters. Requires 6 integers ($YY \leftarrow YY,MM,DD,hh,mm,ss$).

Parameters

Y	year(YYYY), given as integer
М	Month(MM), given as integer
D	Day(DD), given as integer
h	Hour(hh), given as integer
m	Minute(mm), given as integer
s	Second(ss), given as integer

3.5.2.2 internalTime::internalTime()

Default Constructor.

3.5.3 Member Function Documentation

3.5.3.1 void internalTime::parse (std::string strtime)

Member function parse.

Member function parse sets internal values by parsing a given string representing date/time values.

Parameters

```
strtime string representing time.
```

3.5.3.2 void internalTime::toUNIXTime ()

Member Function, providing UNIX time.

Member function, converting stored time to UNIX time.

3.5.4 Member Data Documentation

3.5.4.1 int internalTime::year

Stores Year as Integer

The documentation for this class was generated from the following files:

- /home/mowais/GTEC/src/internalTime.hpp
- /home/mowais/GTEC/src/internalTime.cpp

3.6 navigation Class Reference

```
#include <navigation.hpp>
```

Public Member Functions

• void read ()

Member function read.

navigation (std::vector< std::string > fnames)

Constructor with Input files.

• void getPositionR (ephemerisR &initialConditions, int h, triple &pos)

Function to compute GLONASS satellite positions.

• void getPositionGE (ephemerisGE &initial, int t, triple &pos)

Function to compute GPS/Galileo/BeiDou satellite positions.

Public Attributes

std::vector< std::string > fileNames

list of file names to read from

· float version

Stores RINEX version.

• int leapSeconds

Stores leapSeconds from Navigation files.

• std::vector< std::vector< ephemerisGE >> ephemeris_G

Vector to store objects of type ephemerisGE for GPS.

• std::vector< std::vector< ephemerisGE >> ephemeris_E

Vector to store objects of type ephemerisGE for Galileo.

std::vector< std::vector< ephemerisR >> ephemeris_R

Vector to store objects of type ephemerisR for GLONASS.

std::vector< std::vector< ephemerisGE >> ephemeris_C

Vector to store objects of type ephemerisGE for BeiDou.

Private Member Functions

- navigation ()
- float eccAnomaly (float M, float e)

Function to compute eccentricity anomaly Ek.

void applyRotations (float &Lk, float &ik, float &uk, float &rk, triple &pos)

This Function apply rotations around uk, ik and Lk.

3.6.1 Detailed Description

Author

Muhammad Owais

Date

05/12/16

3.6.2 Constructor & Destructor Documentation

3.6.2.1 navigation::navigation (std::vector< std::string > fnames)

Constructor with Input files.

Constructs navigation object by reading input navigation files defined by fnames.

fnames	Vector of Navigation file names.

3.6.2.2 navigation::navigation() [private]

Default Constructor. Hidden, cannot be used.

3.6.3 Member Function Documentation

3.6.3.1 void navigation::applyRotations (float & Lk, float & ik, float & uk, float & rk, triple & pos) [private]

This Function apply rotations around uk, ik and Lk.

This Function apply rotations around uk, ik and Lk, Rotation == $|Xk| | rk | |Yk | = R3(-Lk)R1(-ik)R3(-uk) | 0 | |Zk | | 0 | Wwhere R1 and R3 are the rotation matrices defined at: http://www.navipedia.net/index. <math>\leftarrow$ php/Transformation_between_Terrestrial_Frames By Hernández-Pajares, Technical University of Catalonia, Spain.

Parameters

Lk	Longitude of the ascending node LAMBDAk.
ik	Inclination of the orbital plane.
uk	Argument of latitude.
rk	Radial distance rk.
pos	triple object returned with computed coordinates.

3.6.3.2 float navigation::eccAnomaly (float M, float e) [private]

Function to compute eccentricity anomaly Ek.

This Function computes eccentricity anomaly Ek by Solving (iteratively) the Kepler equation for the eccentricity anomaly, using Newton-Raphson method, Equation -> Mk = Ek - (e * Sin(Ek))

Parameters

М	mean anomaly for reference time tk.
е	eccentricity.

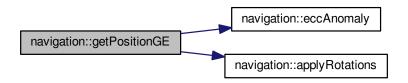
3.6.3.3 void navigation::getPositionGE (ephemerisGE & initial, int t, triple & pos)

Function to compute GPS/Galileo/BeiDou satellite positions.

This function calculates GPS/Galileo/BeiDou satellite coordinates given an ephemerisGE object and time for which coordinates are required.

initial	ephemerisR object containing initial Keplerian elements.
t	Integer time for which coordinates are to be computed.
pos	triple object returned with computed coordinates.

Here is the call graph for this function:



3.6.3.4 void navigation::getPositionR (ephemerisR & initialConditions, int h, triple & pos)

Function to compute GLONASS satellite positions.

This function calculates GLONASS satellite coordinates given an ephemerisR object, and a step size.

Parameters

initialConditions	ephemerisR object containing initial conditions.	
h	Integer step size for next coordinate.	
pos	triple object returned with computed coordinates.	

3.6.3.5 void navigation::read ()

Member function read.

Member function read parses input navigation files and constructs internal navigation structure.

Here is the call graph for this function:



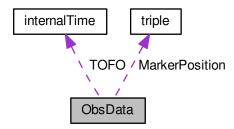
The documentation for this class was generated from the following files:

- /home/mowais/GTEC/src/navigation.hpp
- /home/mowais/GTEC/src/navigation.cpp

3.7 ObsData Class Reference

#include <ObsData.hpp>

Collaboration diagram for ObsData:



Public Member Functions

• void read ()

Member function read.

ObsData (std::vector< std::string > fvec, std::string sysString)

Constructor with Input files, and system string.

- int dumpArc (char, int)
- int dumpArcByTime (char, int)
- int dumpArcBinary (char, int)
- int dumpSizes ()
- void pre_process (int minArcLen, int intrpolIntrvl, int deg)

Function to perform preprocessing.

- void dumpNonZeroArcs ()
- int dumpArcBinaryPtrsAll ()
- int dumpArcValuePtrsAll ()

Public Attributes

std::vector< std::string > fnames

list of file names to read from

• triple MarkerPosition

triple Object to store receiver-station position

· float version

Stores RINEX version of observation files.

int interval

Interval between observations in data file.

bool hasGPS

Flag to indicate whether Data file contains GPS Data.

· bool hasGLO

Flag to indicate whether Data file contains GLONASS Data.

bool hasGAL

Flag to indicate whether Data file contains Galileo Data.

· bool hasBEI

Flag to indicate whether Data file contains BeiDou Data.

· bool readGPS

Flag to indicate whether to process GPS Data.

· bool readGLO

Flag to indicate whether to process GLONASS Data.

· bool readGAL

Flag to indicate whether to process Galileo Data.

· bool readBEI

Flag to indicate whether to process BeiDou Data.

bool hasTOFO

Time of first observation flag.

std::string TOFO system

Time system of first observation from observation Header.

internalTime TOFO

internalTime Object to store Time of first observation

• std::vector< int > timeline main

Integer vector to store epochs in UNIX time.

std::vector< std::vector< float >> GPS_ucTEC

Vectors to store raw non-calibrated TEC for GPS Satellites.

std::vector< std::vector< float > > GLO_ucTEC

Vectors to store raw non-calibrated TEC for GLONASS Satellites.

std::vector< std::vector< float > > GAL ucTEC

Vectors to store raw non-calibrated TEC for Galileo Satellites.

• $std::vector < std::vector < float >> BDU_ucTEC$

Vectors to store raw non-calibrated TEC for BeiDou Satellites.

std::vector< float > S

Stores matrix S (non-calibrated TEC).

std::vector< int > S arcnum

Stores arc numbers for S.

std::vector< int > S_prn

Stores Satellite IDs for S.

· int size_of_S

Indicates size of S.

- std::vector< int pair > intse
- · int numArcs

Indicates total number of arcs.

- std::vector < int > prnid
- int GPS_Mark [32]
- int GLO_Mark [24]
- int GAL Mark [30]
- int BDU_Mark [34]
- int NonZero_Mark [120]
- int numNonZeroArcs
- $std::vector < ptr_pair > arcs$

Initial non-zero arc pinters.

std::vector< ptr_pair > arcs2

Arc pointers without zeros.

std::vector< ptr_pair > arcs3

Arc pointers without gaps.

Private Member Functions

• ObsData ()

default hidden Constructor

• void setSysFlags (std::string sysString)

Sets system flags.

- int pad_zero (int)
- void resetMark ()
- int pad_zero ()
- void markNonZeroArcs (int, int)
- void getnumNonZeroArcs ()
- void setArcStartEnd ()

Sets Arc pointers using ptr_pair objects.

• int lagrangeInterpolation (float *target, float *s, float *e, int deg)

Function to perform lagrange interpolation.

3.7.1 Detailed Description

Author

Muhammad Owais

Date

05/12/16

3.7.2 Constructor & Destructor Documentation

3.7.2.1 ObsData::ObsData (std::vector < std::string > fvec, std::string sysString)

Constructor with Input files, and system string.

Constructs observation object by seting input observation file name vector fnames given file names and setting system flags given system string.

fvec	Vector of observation file names.
sysString	string (any combination of 'G', 'R', 'E', 'C') defining constellations being processed.

Here is the call graph for this function:



3.7.3 Member Function Documentation

3.7.3.1 int ObsData::lagrangeInterpolation (float * target, float * s, float * e, int deg) [private]

Function to perform lagrange interpolation.

This function performs lagrange Interpolation needed in preprocessing phase, given a required degree for interpolation.

Parameters

target	pointer to the value being interpolated.
s	start pointer of the arc.
e	end pointer of the arc.
deg	degree of Interpolation.

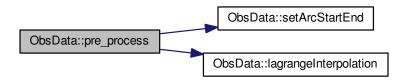
3.7.3.2 void ObsData::pre_process (int minArcLen, int intrpolIntrvl, int deg)

Function to perform preprocessing.

This function performs preprocessing by filling gaps using lagrange interpolation and removing phase jumps using quartiles and Inter Quartile Range.

minArcLen	minimum data duration(Seconds) to consider an arc valid.	
intrpolIntrvl	Maximum gap duration (Seconds) to interpolate.	
deg	Degree of Interpolation, passed to lagrangeInterpolation.	

Here is the call graph for this function:

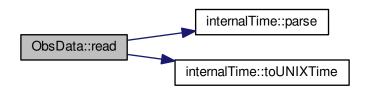


3.7.3.3 void ObsData::read ()

Member function read.

Member function read parses input observation files and constructs internal observation structure.

Here is the call graph for this function:



3.7.3.4 void ObsData::setArcStartEnd() [private]

Sets Arc pointers using ptr_pair objects.

This function sets Arc pointers to start/end pairs using ptr_pair, which serve as input arcs to preprocessing phase.

3.7.3.5 void ObsData::setSysFlags (std::string sysString) [private]

Sets system flags.

This function sets system flags given sysString, to indicate which constellations are processed.

<i>sysString</i> strir	ing (any combination of 'G	S','R','E','C') indicating constellation	ons being processed.
------------------------	----------------------------	--	----------------------

3.7.4 Member Data Documentation

3.7.4.1 std::vector<ptr_pair> ObsData::arcs

Initial non-zero arc pinters.

ptr_pair Object containing Initial non-zero arcs, without preprocessing being applied.

3.7.4.2 std::vector<ptr_pair> ObsData::arcs2

Arc pointers without zeros.

ptr pair Object containing arcs, without leading and trailing zeros.

3.7.4.3 std::vector<ptr_pair> ObsData::arcs3

Arc pointers without gaps.

ptr_pair Object containing arcs, with gaps removeed by lagrangeInterpolation and phase jumps removed. These are the processed Arcs.

3.7.4.4 std::vector < std::vector < float > > ObsData::BDU_ucTEC

Vectors to store raw non-calibrated TEC for BeiDou Satellites.

This is a Vector of float-vectors, where first index is the Satellite prn-id and the second index is the raw non-calibrated TEC for BeiDou satellites corresponding to the epoch index in timeline_main.

3.7.4.5 std::vector < std::vector < float > > ObsData::GAL_ucTEC

Vectors to store raw non-calibrated TEC for Galileo Satellites.

This is a Vector of float-vectors, where first index is the Satellite prn-id and the second index is the raw non-calibrated TEC for Galileo satellites corresponding to the epoch index in timeline_main.

3.7.4.6 std::vector< std::vector<float>> ObsData::GLO_ucTEC

Vectors to store raw non-calibrated TEC for GLONASS Satellites.

This is a Vector of float-vectors, where first index is the Satellite prn-id and the second index is the raw non-calibrated TEC for GLONASS satellites corresponding to the epoch index in timeline main.

3.7.4.7 $std::vector < std::vector < float > > ObsData::GPS_ucTEC$

Vectors to store raw non-calibrated TEC for GPS Satellites.

This is a Vector of float-vectors, where first index is the Satellite prn-id and the second index is the raw non-calibrated TEC for GPS satellites corresponding to the epoch index in timeline_main.

3.7.4.8 bool ObsData::hasTOFO

Time of first observation flag.

Flag to indicate whether Time of first observation was present in observation Header.

3.7.4.9 int ObsData::numArcs

Indicates total number of arcs.

Indicates total number of arcs formed. Arc numbers are defined by pre_processing phase using pre_process.

3.7.4.10 std::vector<float> ObsData::S

Stores matrix S (non-calibrated TEC).

This vector stores all computed non-calibrated TEC values, arranged by epochs. This is the input vector given to the system solver.

3.7.4.11 std::vector<int> ObsData::S_arcnum

Stores arc numbers for S.

This vector stores for each element in S , a corresponding value indicating the its arc number. Arc numbers are defined by pre_processing phase using pre_process.

3.7.4.12 std::vector<int> ObsData::S_prn

Stores Satellite IDs for S.

This vector stores for each element in S , a corresponding value indicating the its Satellite ID.

The documentation for this class was generated from the following files:

- /home/mowais/GTEC/src/ObsData.hpp
- /home/mowais/GTEC/src/ObsData.cpp

3.8 ptr_pair Class Reference

#include <ptr_pair.hpp>

Public Member Functions

• ptr_pair ()

Default constructor.

ptr_pair (float *s, float *e)

Custom constructor.

Public Attributes

```
float * start
```

Start pointer.

float * end

End pointer.

3.8.1 Detailed Description

Author

Muhammad Owais

Date

05/12/16

3.8.2 Constructor & Destructor Documentation

```
3.8.2.1 ptr_pair::ptr_pair()
```

Default constructor.

Default constructur, creates ptr_pair object with NULLL start and end pointers.

```
3.8.2.2 ptr_pair::ptr_pair ( float * s, float * e )
```

Custom constructor.

Constructur, creates ptr_pair object with start and end pointers set to given pointers.

Parameters

	Input start pointer for new ptr_pair object.
e	Input end pointer for new ptr_pair object.

The documentation for this class was generated from the following files:

- /home/mowais/GTEC/src/ptr_pair.hpp
- /home/mowais/GTEC/src/ptr_pair.cpp

3.9 triple Class Reference

#include <triple.hpp>

Public Member Functions

void dump (std::ostream &s)
 Member function dump.

Public Attributes

double X

Stores X Coordinate.

double Y

Stores Y Coordinate.

double Z

Stores Z Coordinate.

3.9.1 Detailed Description

Author

Muhammad Owais

Date

05/12/16

3.9.2 Member Function Documentation

3.9.2.1 void triple::dump (std::ostream & s)

Member function dump.

Member function dump output coordinates into a given output stream.

Parameters

s output stream

The documentation for this class was generated from the following files:

- /home/mowais/GTEC/src/triple.hpp
- /home/mowais/GTEC/src/triple.cpp

Chapter 4

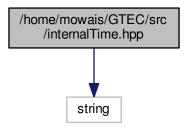
File Documentation

4.1 /home/mowais/GTEC/src/internalTime.hpp File Reference

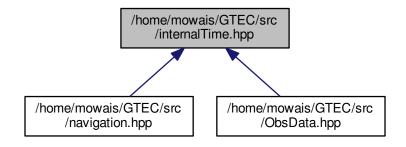
Class defining internal time format.

#include <string>

Include dependency graph for internalTime.hpp:



This graph shows which files directly or indirectly include this file:



24 File Documentation

Classes

· class internalTime

4.1.1 Detailed Description

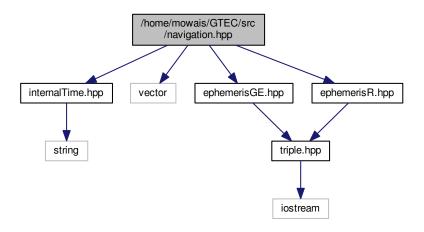
Class defining internal time format.

This Class Defines Internal time which is based on Unix Time. It stores the normal Date/Time as (Year,Month,Day,Hour,Minute,Second), while also providing equivalent UNIX Time. An instance of this class could be generated by explicitly providing normal Date/Time values or by providing a string which would be parse to store time in both formats.

4.2 /home/mowais/GTEC/src/navigation.hpp File Reference

This class navigation data.

```
#include "internalTime.hpp"
#include <vector>
#include "ephemerisGE.hpp"
#include "ephemerisR.hpp"
Include dependency graph for navigation.hpp:
```



Classes

· class navigation

4.2.1 Detailed Description

This class navigation data.

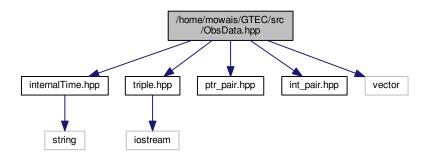
This class defines navigation data, stored after reading RINEX navigation files, for different constellations.

4.3 /home/mowais/GTEC/src/ObsData.hpp File Reference

Class defining observation data.

```
#include "internalTime.hpp"
#include "triple.hpp"
#include "ptr_pair.hpp"
#include "int_pair.hpp"
#include <vector>
```

Include dependency graph for ObsData.hpp:



Classes

· class ObsData

4.3.1 Detailed Description

Class defining observation data.

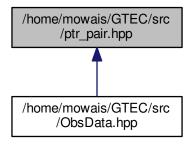
This Class Defines observation data handling, including reading from observation files and storing in internal data structure, the raw non-calibrated TEC from phase observables. This class also includes preprocessing routines being applied to internal data structure, and allot of dump routines for debugging and ploting arc states.

4.4 /home/mowais/GTEC/src/ptr_pair.hpp File Reference

Class defining pointer pairs.

26 File Documentation

This graph shows which files directly or indirectly include this file:



Classes

· class ptr_pair

4.4.1 Detailed Description

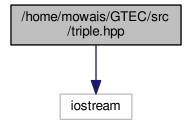
Class defining pointer pairs.

This Class Defines pointer pairs objects used in preprocessing to define arcs. Each arc coud be defined as a ptr_pair object having a start pointer (pointer to first value in arc) and an end pointer (pointer to last value in arc).

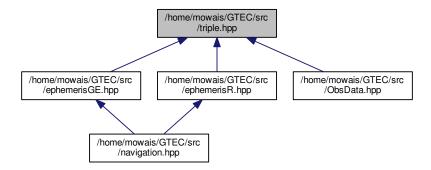
4.5 /home/mowais/GTEC/src/triple.hpp File Reference

This class defines a 3-D Coordinate.

#include <iostream>
Include dependency graph for triple.hpp:



This graph shows which files directly or indirectly include this file:



Classes

• class triple

4.5.1 Detailed Description

This class defines a 3-D Coordinate.

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