

GTEC

version 0.1

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Chapter 1

Class Index

1.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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Chapter 2

File Index

2.1 File List

Here is a list of all documented files with brief descriptions:

/home/mowais/GTEC/src/ constants.hpp	??
/home/mowais/GTEC/src/ ephemerisGE.hpp	??
/home/mowais/GTEC/src/ ephemerisR.hpp	??
/home/mowais/GTEC/src/ inout.hpp	??
/home/mowais/GTEC/src/ int_pair.hpp	??
/home/mowais/GTEC/src/ internalTime.hpp	
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Class defining observation data	27
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Chapter 3

Class Documentation

3.1 ephemerisGE Class Reference

Public Attributes

- int **Toc**
- int **Toe**
- int **week**
- float **Ahalf**
- float **e**
- float **M0**
- float **w**
- float **i0**
- float **Omega0**
- float **deltan**
- float **idot**
- float **Omegadot**
- float **Cuc**
- float **Cus**
- float **Crc**
- float **Crs**
- float **Cic**
- float **Cis**

The documentation for this class was generated from the following file:

- /home/mowais/GTEC/src/ephemerisGE.hpp

3.2 ephemerisR Class Reference

Public Attributes

- int **tb**
- float **px**
- float **py**
- float **pz**
- float **vx**
- float **vy**
- float **vz**
- float **xdd**
- float **ydd**
- float **zdd**

The documentation for this class was generated from the following file:

- /home/mowais/GTEC/src/ephemerisR.hpp

3.3 inout Class Reference

Public Member Functions

- void **process_Inputs** (int ac, char *args[])
- void **dump** (std::ostream &s)

Public Attributes

- int **nobsfiles**
- int **nnavfiles**
- bool **systemGPS**
- bool **systemGlonass**
- bool **systemGalileo**
- bool **systemBeidou**
- bool **systemQZSS**
- int **numDays**
- std::string **inputDirectory**
- std::string **satSys**
- std::string **marker**
- int **samplingTime**
- int **firstDayOfYear**
- int **year**
- int **minArcLen**
- int **intrpolIntrvl**
- int **deg**
- std::vector< std::string > **obsfiles**
- std::vector< std::string > **navfiles**

Private Member Functions

- void **checkInputFiles** ()

The documentation for this class was generated from the following files:

- /home/mowais/GTEC/src/inout.hpp
- /home/mowais/GTEC/src/inout.cpp

3.4 int_pair Class Reference

Public Member Functions

- **int_pair** (int, int)

Public Attributes

- int **start**
- int **end**

The documentation for this class was generated from the following files:

- /home/mowais/GTEC/src/int_pair.hpp
- /home/mowais/GTEC/src/int_pair.cpp

3.5 internalTime Class Reference

```
#include <internalTime.hpp>
```

Public Member Functions

- **internalTime** (int Y, int M, int D, int h, int m, int s)
Constructor with explicit values.
- void **parse** (std::string strtime)
Member function parse.
- void **parse** (std::string, std::string &)
- void **toUNIXTime** ()
Member Function, providing UNIX time.
- void **toUNIXTime** (int)
- **internalTime** ()

Public Attributes

- int [year](#)
- int [month](#)
Stores Month as Integer.
- int [day](#)
Stores day as Integer.
- int [hour](#)
Stores hour as Integer.
- int [minute](#)
Stores minute as Integer.
- int [second](#)
Stores second as Integer.
- int [UNIX](#)
Stores Converted UNIX Time as Integer.

3.5.1 Detailed Description

Author

Muhammad Owais

Date

04/12/16

3.5.2 Constructor & Destructor Documentation

3.5.2.1 `internalTime::internalTime (int Y, int M, int D, int h, int m, int s)`

Constructor with explicit values.

Constructs [internalTime](#) object explicitly taking date/time values as parameters. Requires 6 integers (YY↔YY,MM,DD,hh,mm,ss).

Parameters

<i>Y</i>	year(YYYY), given as integer
<i>M</i>	Month(MM), given as integer
<i>D</i>	Day(DD), given as integer
<i>h</i>	Hour(hh), given as integer
<i>m</i>	Minute(mm), given as integer
<i>s</i>	Second(ss), given as integer

3.5.2.2 `internalTime::internalTime ()`

Default Constructor.

3.5.3 Member Function Documentation

3.5.3.1 void internalTime::parse (std::string *strtime*)

Member function parse.

Member function parse sets internal values by parsing a given string representing date/time values.

Parameters

<i>strtime</i>	string representing time.
----------------	---------------------------

3.5.3.2 void internalTime::toUNIXTime ()

Member Function, providing UNIX time.

Member function, converting stored time to UNIX time.

3.5.4 Member Data Documentation

3.5.4.1 int internalTime::year

Stores Year as Integer

The documentation for this class was generated from the following files:

- [/home/mowais/GTEC/src/internalTime.hpp](#)
- [/home/mowais/GTEC/src/internalTime.cpp](#)

3.6 navigation Class Reference

```
#include <navigation.hpp>
```

Public Member Functions

- void [read](#) ()
Member function read.
- [navigation](#) (std::vector< std::string > frames)
Constructor with Input files.
- void [getPositionR](#) ([ephemerisR](#) &initialConditions, int h, [triple](#) &pos)
Function to compute GLONASS satellite positions.
- void [getPositionGE](#) ([ephemerisGE](#) &initial, int t, [triple](#) &pos)
Function to compute GPS/Galileo/BeiDou satellite positions.

Public Attributes

- `std::vector< std::string > fileNamees`
list of file names to read from
- `float version`
Stores RINEX version.
- `int leapSeconds`
Stores leapSeconds from Navigation files.
- `std::vector< std::vector< ephemerisGE > > ephemeris_G`
*Vector to store objects of type *ephemerisGE* for GPS.*
- `std::vector< std::vector< ephemerisGE > > ephemeris_E`
*Vector to store objects of type *ephemerisGE* for Galileo.*
- `std::vector< std::vector< ephemerisR > > ephemeris_R`
*Vector to store objects of type *ephemerisR* for GLONASS.*
- `std::vector< std::vector< ephemerisGE > > ephemeris_C`
*Vector to store objects of type *ephemerisGE* for BeiDou.*

Private Member Functions

- `navigation ()`
- `float eccAnomaly (float M, float e)`
*Function to compute eccentricity anomaly *Ek*.*
- `void applyRotations (float &Lk, float &ik, float &uk, float &rk, triple &pos)`
*This Function apply rotations around *uk*, *ik* and *Lk*.*

3.6.1 Detailed Description

Author

Muhammad Owais

Date

05/12/16

3.6.2 Constructor & Destructor Documentation

3.6.2.1 `navigation::navigation (std::vector< std::string > fnames)`

Constructor with Input files.

Constructs navigation object by reading input navigation files defined by fnames.

Parameters

<i>fnames</i>	Vector of Navigation file names.
---------------	----------------------------------

3.6.2.2 navigation::navigation () [private]

Default Constructor. Hidden, cannot be used.

3.6.3 Member Function Documentation

3.6.3.1 void navigation::applyRotations (float & *Lk*, float & *ik*, float & *uk*, float & *rk*, triple & *pos*) [private]

This Function apply rotations around *uk*, *ik* and *Lk*.

This Function apply rotations around *uk*, *ik* and *Lk*, Rotation == $\begin{bmatrix} X_k \\ rk \\ Y_k \\ 0 \end{bmatrix} = R3(-Lk)R1(-ik)R3(-uk) \begin{bmatrix} 0 \\ 0 \\ Z_k \\ 0 \end{bmatrix}$ Where *R1* and *R3* are the rotation matrices defined at: http://www.navipedia.net/index.php/Transformation_between_Terrestrial_Frames By Hernández-Pajares, Technical University of Catalonia, Spain.

Parameters

<i>Lk</i>	Longitude of the ascending node LAMBD _{Ak} .
<i>ik</i>	Inclination of the orbital plane.
<i>uk</i>	Argument of latitude.
<i>rk</i>	Radial distance <i>rk</i> .
<i>pos</i>	triple object returned with computed coordinates.

3.6.3.2 float navigation::eccAnomaly (float *M*, float *e*) [private]

Function to compute eccentricity anomaly *E_k*.

This Function computes eccentricity anomaly *E_k* by Solving (iteratively) the Kepler equation for the eccentricity anomaly, using Newton–Raphson method, Equation $\rightarrow M_k = E_k - (e * \sin(E_k))$

Parameters

<i>M</i>	mean anomaly for reference time <i>t_k</i> .
<i>e</i>	eccentricity.

3.6.3.3 void navigation::getPositionGE (ephemerisGE & *initial*, int *t*, triple & *pos*)

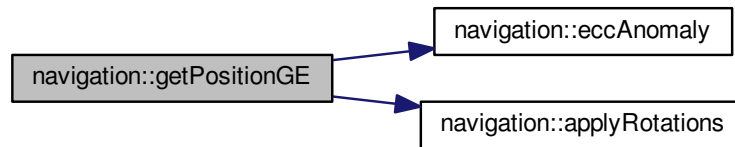
Function to compute GPS/Galileo/BeiDou satellite positions.

This function calculates GPS/Galileo/BeiDou satellite coordinates given an [ephemerisGE](#) object and time for which coordinates are required.

Parameters

<i>initial</i>	ephemerisGE object containing initial Keplerian elements.
<i>t</i>	Integer time for which coordinates are to be computed.
<i>pos</i>	triple object returned with computed coordinates.

Here is the call graph for this function:



3.6.3.4 void navigation::getPositionR (*ephemerisR* & *initialConditions*, int *h*, *triple* & *pos*)

Function to compute GLONASS satellite positions.

This function calculates GLONASS satellite coordinates given an [ephemerisR](#) object, and a step size.

Parameters

<i>initialConditions</i>	ephemerisR object containing initial conditions.
<i>h</i>	Integer step size for next coordinate.
<i>pos</i>	triple object returned with computed coordinates.

3.6.3.5 void navigation::read ()

Member function read.

Member function read parses input navigation files and constructs internal navigation structure.

Here is the call graph for this function:



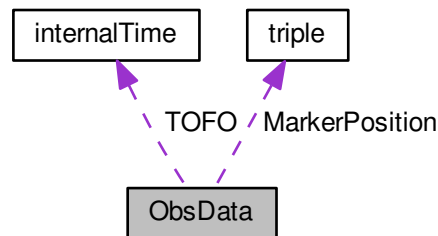
The documentation for this class was generated from the following files:

- [/home/mowais/GTEC/src/navigation.hpp](#)
- [/home/mowais/GTEC/src/navigation.cpp](#)

3.7 ObsData Class Reference

```
#include <ObsData.hpp>
```

Collaboration diagram for ObsData:



Public Member Functions

- void [read](#) ()
Member function read.
- [ObsData](#) (std::vector< std::string > fvec, std::string sysString)
Constructor with Input files, and system string.
- void [cleanUp](#) ()
Clean-up function.
- int **dumpArc** (char, int)
- int **dumpArcByTime** (char, int)
- int **dumpArcBinary** (char, int)
- int **dumpSizes** ()
- void [pre_process](#) (int minArcLen, int intrpolIntrvl, int deg)
Function to perform preprocessing.
- void **dumpNonZeroArcs** ()
- int **dumpArcBinaryPtrsAll** ()
- int **dumpArcValuePtrsAll** ()
- void [buildB](#) ()
Builds matrix B.
- void [dumpRawMatrix](#) (const double *mat, int &dim1, int &dim2)
Function to dump raw matrix.

Public Attributes

- std::vector< std::string > [fnames](#)
list of file names to read from
- [triple](#) [MarkerPosition](#)
triple Object to store receiver-station position
- float [version](#)
Stores RINEX version of observation files.

- int [interval](#)
Interval between observations in data file.
- bool [hasGPS](#)
Flag to indicate whether Data file contains GPS Data.
- bool [hasGLO](#)
Flag to indicate whether Data file contains GLONASS Data.
- bool [hasGAL](#)
Flag to indicate whether Data file contains Galileo Data.
- bool [hasBEI](#)
Flag to indicate whether Data file contains BeiDou Data.
- bool [readGPS](#)
Flag to indicate whether to process GPS Data.
- bool [readGLO](#)
Flag to indicate whether to process GLONASS Data.
- bool [readGAL](#)
Flag to indicate whether to process Galileo Data.
- bool [readBEI](#)
Flag to indicate whether to process BeiDou Data.
- bool [hasTOFO](#)
Time of first observation flag.
- std::string [TOFO_system](#)
Time system of first observation from observation Header.
- [internalTime](#) [TOFO](#)
[internalTime](#) Object to store Time of first observation
- std::vector< int > [timeline_main](#)
Integer vector to store epochs in UNIX time.
- std::vector< std::vector< float > > [GPS_ucTEC](#)
Vectors to store raw non-calibrated TEC for GPS Satellites.
- std::vector< std::vector< float > > [GLO_ucTEC](#)
Vectors to store raw non-calibrated TEC for GLONASS Satellites.
- std::vector< std::vector< float > > [GAL_ucTEC](#)
Vectors to store raw non-calibrated TEC for Galileo Satellites.
- std::vector< std::vector< float > > [BDU_ucTEC](#)
Vectors to store raw non-calibrated TEC for BeiDou Satellites.
- std::vector< double > [S](#)
Stores vector S (non-calibrated TEC).
- std::vector< int > [S_arcnum](#)
Stores arc numbers for S .
- std::vector< int > [S_prn](#)
Stores Satellite IDs for S .
- int [size_of_S](#)
Indicates size of S .
- std::vector< [int_pair](#) > [intse](#)
- int [numArcs](#)
Indicates total number of arcs.
- double * [B](#)
Stores matrix B .
- std::vector< int > [prnid](#)
- int [GPS_Mark](#) [32]
- int [GLO_Mark](#) [24]
- int [GAL_Mark](#) [30]

- int **BDU_Mark** [34]
- int **NonZero_Mark** [120]
- int **numNonZeroArcs**
- std::vector< [ptr_pair](#) > [arcs](#)
Initial non-zero arc pinters.
- std::vector< [ptr_pair](#) > [arcs2](#)
Arc pointers without zeros.
- std::vector< [ptr_pair](#) > [arcs3](#)
Arc pointers without gaps.

Private Member Functions

- [ObsData](#) ()
default hidden Constructor
- void [setSysFlags](#) (std::string sysString)
Sets system flags.
- int **pad_zero** (int)
- void **resetMark** ()
- int **pad_zero** ()
- void **markNonZeroArcs** (int, int)
- void **getnumNonZeroArcs** ()
- void [setArcStartEnd](#) ()
Sets Arc pointers using [ptr_pair](#) objects.
- int [lagrangeInterpolation](#) (float *target, float *s, float *e, int deg)
Function to perform lagrange interpolation.

3.7.1 Detailed Description

Author

Muhammad Owais

Date

05/12/16

3.7.2 Constructor & Destructor Documentation

3.7.2.1 [ObsData::ObsData](#) (std::vector< std::string > *fvec*, std::string *sysString*)

Constructor with Input files, and system string.

Constructs observation object by seting input observation file name vector [frames](#) given file names and setting system flags given system string.

Parameters

<i>fvec</i>	Vector of observation file names.
<i>sysString</i>	string (any combination of 'G','R','E','C') defining constellations being processed.

Here is the call graph for this function:



3.7.3 Member Function Documentation

3.7.3.1 void ObsData::buildB ()

Builds matrix B.

This function builds and stores matrix B.

3.7.3.2 void ObsData::cleanUp ()

Clean-up function.

This function cleans up internal workspace, should be called before end of object's lifetime.

3.7.3.3 void ObsData::dumpRawMatrix (const double * *mat*, int & *dim1*, int & *dim2*)

Function to dump raw matrix.

This Function dumps raw matrix to standard output stream, usefull in debugging purposes.

Parameters

<i>mat</i>	pointer to stored matrix.
<i>dim1</i>	First dimension of matrix (number of rows).
<i>dim2</i>	Second dimension of matrix (number of columns).

3.7.3.4 int ObsData::lagrangeInterpolation (float * *target*, float * *s*, float * *e*, int *deg*) [private]

Function to perform lagrange interpolation.

This function performs lagrange Interpolation needed in preprocessing phase, given a required degree for interpolation.

Parameters

<i>target</i>	pointer to the value being interpolated.
---------------	--

Parameters

<i>s</i>	start pointer of the arc.
<i>e</i>	end pointer of the arc.
<i>deg</i>	degree of Interpolation.

3.7.3.5 void ObsData::pre_process (int *minArcLen*, int *intrpollIntrvl*, int *deg*)

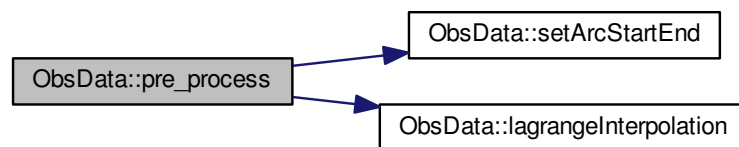
Function to perform preprocessing.

This function performs preprocessing by filling gaps using lagrange interpolation and removing phase jumps using quartiles and Inter Quartile Range.

Parameters

<i>minArcLen</i>	minimum data duration(Seconds) to consider an arc valid.
<i>intrpollIntrvl</i>	Maximum gap duration (Seconds) to interpolate.
<i>deg</i>	Degree of Interpolation, passed to lagrangeInterpolation .

Here is the call graph for this function:

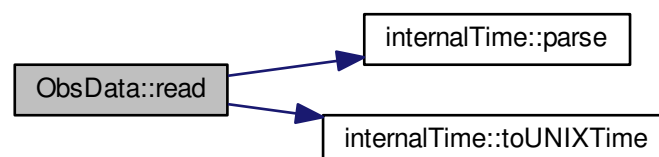


3.7.3.6 void ObsData::read ()

Member function read.

Member function read parses input observation files and constructs internal observation structure.

Here is the call graph for this function:



3.7.3.7 void ObsData::setArcStartEnd () [private]

Sets Arc pointers using [ptr_pair](#) objects.

This function sets Arc pointers to start/end pairs using [ptr_pair](#), which serve as input arcs to preprocessing phase.

3.7.3.8 void ObsData::setSysFlags (std::string sysString) [private]

Sets system flags.

This function sets system flags given sysString, to indicate which constellations are processed.

Parameters

<i>sysString</i>	string (any combination of 'G','R','E','C') indicating constellations being processed.
------------------	--

3.7.4 Member Data Documentation

3.7.4.1 std::vector<ptr_pair> ObsData::arcs

Initial non-zero arc pinters.

[ptr_pair](#) Object containing Initial non-zero arcs, without preprocessing being applied.

3.7.4.2 std::vector<ptr_pair> ObsData::arcs2

Arc pointers without zeros.

[ptr_pair](#) Object containing arcs, without leading and trailing zeros.

3.7.4.3 std::vector<ptr_pair> ObsData::arcs3

Arc pointers without gaps.

[ptr_pair](#) Object containing arcs, with gaps removed by [lagrangeInterpolation](#) and phase jumps removed. These are the processed Arcs.

3.7.4.4 double* ObsData::B

Stores matrix B.

This is stored matrix B. B is a boolean matrix relating each value in vector S to a given arc number. The i^{th} row of B has only one non-zero (a one) in the j^{th} column, relating i^{th} value in vector S to j^{th} arc numbers defined in S_arcnun. Size of B is (size_of_S x numArcs).

3.7.4.5 `std::vector< std::vector<float> > ObsData::BDU_ucTEC`

Vectors to store raw non-calibrated TEC for BeiDou Satellites.

This is a Vector of float-vectors, where first index is the Satellite prn-id and the second index is the raw non-calibrated TEC for BeiDou satellites corresponding to the epoch index in [timeline_main](#).

3.7.4.6 `std::vector< std::vector<float> > ObsData::GAL_ucTEC`

Vectors to store raw non-calibrated TEC for Galileo Satellites.

This is a Vector of float-vectors, where first index is the Satellite prn-id and the second index is the raw non-calibrated TEC for Galileo satellites corresponding to the epoch index in [timeline_main](#).

3.7.4.7 `std::vector< std::vector<float> > ObsData::GLO_ucTEC`

Vectors to store raw non-calibrated TEC for GLONASS Satellites.

This is a Vector of float-vectors, where first index is the Satellite prn-id and the second index is the raw non-calibrated TEC for GLONASS satellites corresponding to the epoch index in [timeline_main](#).

3.7.4.8 `std::vector< std::vector<float> > ObsData::GPS_ucTEC`

Vectors to store raw non-calibrated TEC for GPS Satellites.

This is a Vector of float-vectors, where first index is the Satellite prn-id and the second index is the raw non-calibrated TEC for GPS satellites corresponding to the epoch index in [timeline_main](#).

3.7.4.9 `bool ObsData::hasTOFO`

Time of first observation flag.

Flag to indicate whether Time of first observation was present in observation Header.

3.7.4.10 `int ObsData::numArcs`

Indicates total number of arcs.

Indicates total number of arcs formed. Arc numbers are defined by pre_processing phase using [pre_process](#).

3.7.4.11 `std::vector<double> ObsData::S`

Stores vector S (non-calibrated TEC).

This vector stores all computed non-calibrated TEC values, arranged by epochs. This is the input vector given to the system solver.

3.7.4.12 `std::vector<int> ObsData::S_arcnum`

Stores arc numbers for [S](#).

This vector stores for each element in [S](#) , a corresponding value indicating the its arc number. Arc numbers are defined by pre_processing phase using [pre_process](#).

3.7.4.13 `std::vector<int> ObsData::S_prn`

Stores Satellite IDs for [S](#).

This vector stores for each element in [S](#) , a corresponding value indicating the its Satellite ID.

The documentation for this class was generated from the following files:

- [/home/mowais/GTEC/src/ObsData.hpp](#)
- [/home/mowais/GTEC/src/ObsData.cpp](#)

3.8 `ptr_pair` Class Reference

```
#include <ptr_pair.hpp>
```

Public Member Functions

- [ptr_pair](#) ()
Default constructor.
- [ptr_pair](#) (float *s, float *e)
Custom constructor.

Public Attributes

- float * [start](#)
Start pointer.
- float * [end](#)
End pointer.

3.8.1 Detailed Description

Author

Muhammad Owais

Date

05/12/16

3.8.2 Constructor & Destructor Documentation

3.8.2.1 ptr_pair::ptr_pair ()

Default constructor.

Default constructor, creates [ptr_pair](#) object with NULLL start and end pointers.

3.8.2.2 ptr_pair::ptr_pair (float * s, float * e)

Custom constructor.

Constructor, creates [ptr_pair](#) object with start and end pointers set to given pointers.

Parameters

s	Input start pointer for new ptr_pair object.
e	Input end pointer for new ptr_pair object.

The documentation for this class was generated from the following files:

- [/home/mowais/GTEC/src/ptr_pair.hpp](#)
- [/home/mowais/GTEC/src/ptr_pair.cpp](#)

3.9 triple Class Reference

```
#include <triple.hpp>
```

Public Member Functions

- void [dump](#) (std::ostream &s)
Member function dump.

Public Attributes

- double [X](#)
Stores X Coordinate.
- double [Y](#)
Stores Y Coordinate.
- double [Z](#)
Stores Z Coordinate.

3.9.1 Detailed Description

Author

Muhammad Owais

Date

05/12/16

3.9.2 Member Function Documentation

3.9.2.1 void triple::dump (std::ostream & s)

Member function dump.

Member function dump output coordinates into a given output stream.

Parameters

s	output stream
---	---------------

The documentation for this class was generated from the following files:

- [/home/mowais/GTEC/src/triple.hpp](#)
- [/home/mowais/GTEC/src/triple.cpp](#)

Chapter 4

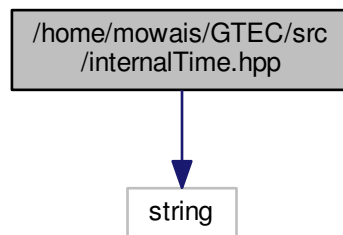
File Documentation

4.1 /home/mowais/GTEC/src/internalTime.hpp File Reference

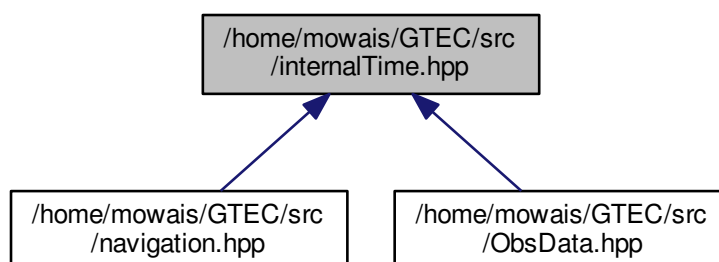
Class defining internal time format.

```
#include <string>
```

Include dependency graph for internalTime.hpp:



This graph shows which files directly or indirectly include this file:



Classes

- class [internalTime](#)

4.1.1 Detailed Description

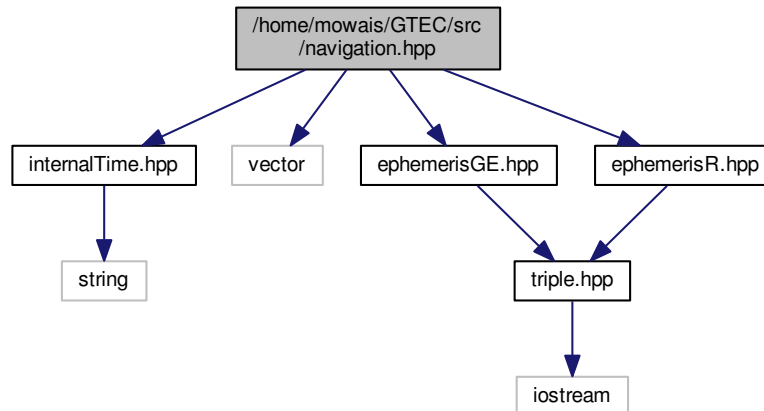
Class defining internal time format.

This Class Defines Internal time which is based on Unix Time. It stores the normal Date/Time as (Year,Month,Day,Hour,Minute,Second), while also providing equivalent UNIX Time. An instance of this class could be generated by explicitly providing normal Date/Time values or by providing a string which would be parse to store time in both formats.

4.2 /home/mowais/GTEC/src/navigation.hpp File Reference

This class navigation data.

```
#include "internalTime.hpp"
#include <vector>
#include "ephemerisGE.hpp"
#include "ephemerisR.hpp"
Include dependency graph for navigation.hpp:
```



Classes

- class [navigation](#)

4.2.1 Detailed Description

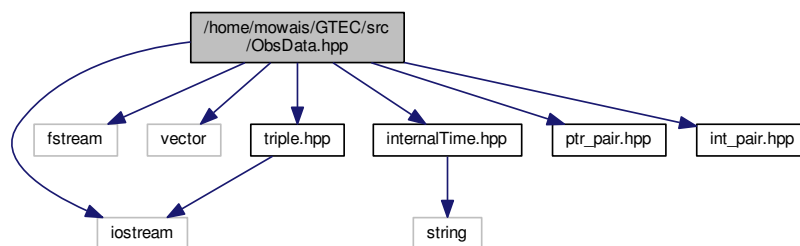
This class navigation data.

This class defines navigation data, stored after reading RINEX navigation files, for different constellations.

4.3 /home/mowais/GTEC/src/ObsData.hpp File Reference

Class defining observation data.

```
#include <iostream>
#include <fstream>
#include <vector>
#include "internalTime.hpp"
#include "triple.hpp"
#include "ptr_pair.hpp"
#include "int_pair.hpp"
Include dependency graph for ObsData.hpp:
```



Classes

- class [ObsData](#)

4.3.1 Detailed Description

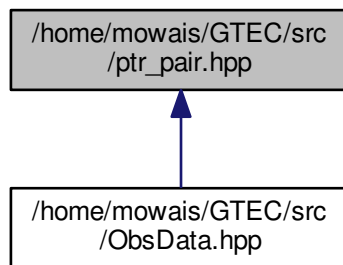
Class defining observation data.

This Class Defines observation data handling, including reading from observation files and storing in internal data structure, the raw non-calibrated TEC from phase observables. This class also includes preprocessing routines being applied to internal data structure, and allot of dump routines for debugging and plotting arc states.

4.4 /home/mowais/GTEC/src/ptr_pair.hpp File Reference

Class defining pointer pairs.

This graph shows which files directly or indirectly include this file:



Classes

- class [ptr_pair](#)

4.4.1 Detailed Description

Class defining pointer pairs.

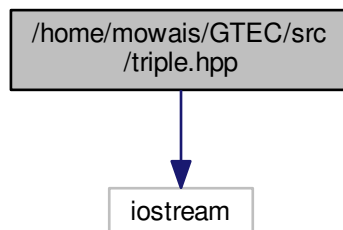
This Class Defines pointer pairs objects used in preprocessing to define arcs. Each arc could be defined as a [ptr_pair](#) object having a start pointer (pointer to first value in arc) and an end pointer (pointer to last value in arc).

4.5 /home/mowais/GTEC/src/triple.hpp File Reference

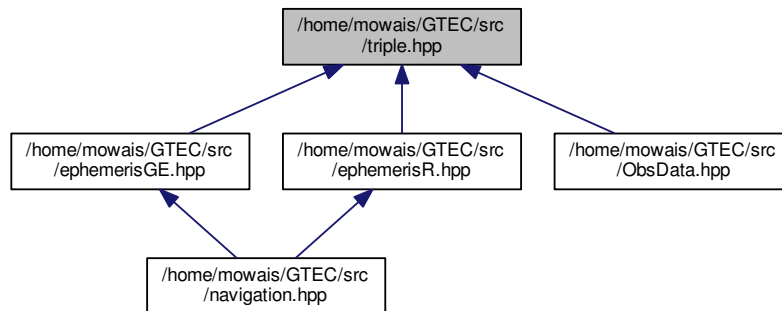
This class defines a 3-D Coordinate.

```
#include <iostream>
```

Include dependency graph for triple.hpp:



This graph shows which files directly or indirectly include this file:



Classes

- class [triple](#)

4.5.1 Detailed Description

This class defines a 3-D Coordinate.

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