

Parameter	Description	Value
svo_file	Specify SVO filename	Path to an SVO file
resolution	Select ZED camera resolution	'0': HD2K, '1': HD1080, '2': HD720, '3': VGA
frame_rate	Set ZED camera video framerate	int
sensing_mode	Select depth sensing mode	'0': STANDARD, '1': FILL
quality	Select depth map quality	'0': NONE, '1': PERFORMANCE, '2': MEDIUM, '3': QUALITY
openni_depth_mode	Convert 32bit depth in meters to 16bit in millimeters	'0': 32bit float meters, '1': 16bit uchar millimeters
zed_id	Select a ZED camera by its ID. ID are assigned by Ubuntu. Useful when multiple cameras are connected. ID is ignored if an SVO path is specified.	int, default '0'
gpu_id	Select a GPU device for depth computation	int, default '-1' (best device found)
publish_tf	Enable/Disable publish odometry TF	true, false
odometry_frame	Odometry frame name	string, default='odometry_frame'
base_frame	Base link frame name	string, default='base_frame'
camera_frame	Camera frame name	string, default='camera_frame'
depth_frame	Depth frame name	string, default='depth_frame'