

# Chapter 1 One-Dimensional Problems

2025/3/17



### 主題一

### **Lagrange Interpolation Functions**



#### Lagrange Interpolation Functions

> 線性近似函數

$$\phi_1^e(x) = \frac{x_2 - x}{x_2 - x_1} \qquad \phi_1(x) \qquad \phi_2(x)$$

$$\phi_2^e(x) = \frac{x - x_1}{x_2 - x_1} \qquad x_1 \qquad x_2$$

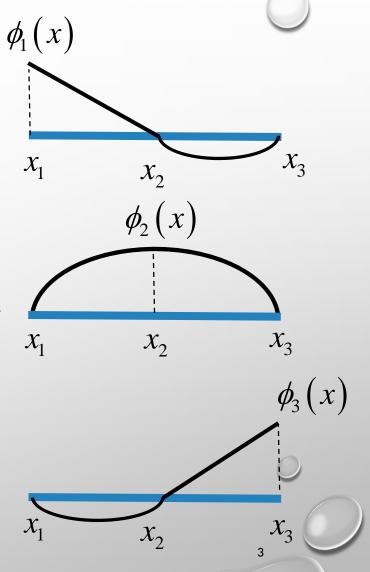
> 二次近似函數

$$\phi_1^e(x) = \frac{(x_2 - x)(x_3 - x)}{(x_3 - x_1)(x_2 - x_1)}$$

$$\phi_2^e(x) = \frac{(x_3 - x)(x_1 - x)}{(x_3 - x_2)(x_1 - x_2)}$$

$$(x - x)(x - x)$$

$$\phi_3^e(x) = \frac{(x_2 - x)(x_1 - x)}{(x_2 - x_3)(x_1 - x_3)}$$





#### Lagrange Interpolation Functions

▶ 對於一維 n個節點的 Lagrange 插值函數

$$\phi_i^e(\overline{x}) = \prod_{\substack{j=1\\j\neq i}}^n \frac{\overline{x} - \overline{x}_j}{\overline{x}_i - \overline{x}_j}, \qquad i = 1, 2, 3, ..., n$$

✓ Partition unity

$$\sum_{i=1}^{n} \phi_i^e(x) = 1$$

#### 其中:

- $\phi_i(\overline{x})$  是對應第i個節點的形狀函數
- <del>X</del> 為局部座標(通常範圍為[-1,1])
- 形狀函數滿足插值性質

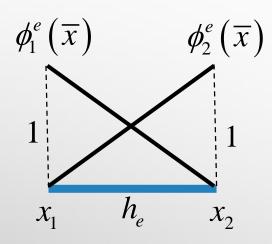
$$\phi_i(\overline{x}_j) = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$$





#### Lagrange Interpolation Functions

➤ Linear Largrange Interpolation Function



假設:

$$\phi_1^e(\overline{x}) = a_1 + b_1 \overline{x}$$
$$\phi_2^e(\overline{x}) = a_2 + b_2 \overline{x}$$

1. 當 
$$\overline{x} = 0$$
,  $\phi_1^e(0) = 1$   $a_1 = 1$ 

當 
$$\overline{x} = h_e, \quad \phi_1^e(0) = 0$$

$$b_1 = -\frac{1}{h_e}$$

2. 當
$$\bar{x} = 0$$
,  $\phi_2^e(0) = 0$   $a_2 = 0$ 

當 
$$\overline{x} = h_e, \quad \phi_2^e(0) = 1$$

$$b_2 = \frac{1}{h}$$

✓ 因此線性插值函數通式

$$\phi_1^e(\overline{x}) = 1 - \frac{\overline{x}}{h_e}$$

$$\phi_2^e(\overline{x}) = \frac{\overline{x}}{h_e}$$



Quadratic Largrange Interpolation Function

假設二階插值函數(n=3)

$$\phi_i^e(\overline{x}) = \prod_{\substack{j=1\\j\neq i}}^3 \frac{\overline{x} - \overline{x}_j}{\overline{x}_i - \overline{x}_j}$$

其中:

$$x_1 = 0$$

$$x_2 = \alpha \cdot h_e$$

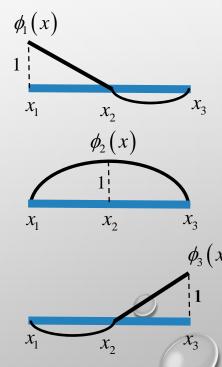
$$x_3 = h_e$$

✓ 因此二階插值函數通式

$$\phi_1^e(\overline{x}) = \frac{(\overline{x} - \overline{x}_2)(\overline{x} - \overline{x}_3)}{(\overline{x}_1 - \overline{x}_2)(\overline{x}_1 - \overline{x}_3)} = \left(1 - \frac{\overline{x}}{h_e}\right) \left(1 - \frac{1}{\alpha} \frac{\overline{x}}{h_e}\right)$$

$$\phi_2^e(\overline{x}) = \frac{(\overline{x} - \overline{x}_1)(\overline{x} - \overline{x}_3)}{(\overline{x}_2 - \overline{x}_1)(\overline{x}_2 - \overline{x}_3)} = \frac{1}{\alpha(1 - \alpha)} \frac{\overline{x}}{h_e} \left( 1 - \frac{\overline{x}}{h_e} \right)$$

$$\phi_3^e(\overline{x}) = \frac{(\overline{x} - \overline{x}_1)(\overline{x} - \overline{x}_2)}{(\overline{x}_3 - \overline{x}_1)(\overline{x}_3 - \overline{x}_2)} = \frac{\alpha}{(1 - \alpha)} \frac{\overline{x}}{h_e} \left( 1 - \frac{1}{\alpha} \frac{\overline{x}}{h_e} \right)$$



#### Lagrange Interpolation Functions

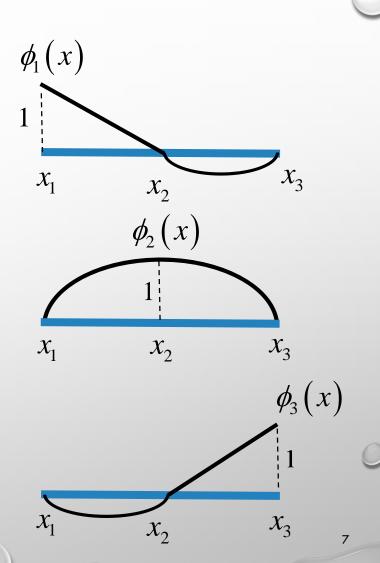
Quadratic Largrange Interpolation Function

$$\alpha = \frac{1}{2}$$
 (等距分佈)

$$\phi_1^e(\overline{x}) = \left(1 - \frac{\overline{x}}{h_e}\right) \left(1 - \frac{1}{\alpha} \frac{\overline{x}}{h_e}\right) \rightarrow \left(1 - \frac{\overline{x}}{h_e}\right) \left(1 - \frac{2\overline{x}}{h_e}\right)$$

$$\phi_2^e(\overline{x}) = \frac{1}{\alpha(1-\alpha)} \frac{\overline{x}}{h_e} \left( 1 - \frac{\overline{x}}{h_e} \right) \to 4 \frac{\overline{x}}{h_e} \left( 1 - \frac{\overline{x}}{h_e} \right)$$

$$\phi_3^e(\overline{x}) = \frac{\alpha}{(1-\alpha)} \frac{\overline{x}}{h_e} \left( 1 - \frac{1}{\alpha} \frac{\overline{x}}{h_e} \right) \to \frac{\overline{x}}{h_e} \left( 1 - \frac{2\overline{x}}{h_e} \right)$$





### 主題二

# **Derivation of Element Equation**



#### Derivation of Element Equation

➤ For example by Ritz method

Consider the P.D.E. problem

$$-\frac{d}{dx}\left(\frac{du}{dx}\right) + cu - f = 0 \quad \text{for } 0 < x < L$$

Boundary conditions:

$$u(0) = u_0, \left. \left( a \frac{\partial u}{\partial x} \right) \right|_{x=L} = Q_0$$

> Assume the polynomial approximation solution

$$U_N = \sum_{j=1}^N c_j \phi_j + \phi_0$$

$$c_j \phi_j$$
 is replace  $u_j^e \psi_j^e$   $(\phi_0 = 0)$ 

$$u_h^e = \sum_{j=1}^n u_j^e \cdot \psi_j^e(x)$$



#### Derivation of Element Equation

➤ For example by Ritz method

Weighted-integral form

$$\int_{x_a}^{x_b} \left( a \frac{dw}{dx} \frac{du}{dx} + cwu - wf \right) dx - \left[ wa \frac{du}{dx} \right]_{x_a}^{x_b} = 0$$

代入邊界條件: 
$$u(0) = u_0$$
,  $\left(a\frac{\partial u}{\partial x}\right)\Big|_{x=L} = Q_0$ 

$$\int_{x_a}^{x_b} \left( a \frac{dw}{dx} \frac{du}{dx} + cwu - wf \right) dx - w(x_a) Q_1 - w(x_b) Q_2 = 0$$

> Principles of minimum potential energy (MPE)

$$\delta I^e = B^e(w, u) - l^e(w) = 0 , w = \delta u$$

$$B^{e}(w,u) = \int_{x_{a}}^{x_{b}} \left( a \frac{dw}{dx} \frac{du}{dx} + cwu \right) dx = 0$$

$$l^{e}(w) = \int_{x_{a}}^{x_{b}} w f \, dx + w(x_{a}) Q_{1} + w(x_{b}) Q_{2}$$





#### Derivation of Element Equation

➤ For example by Ritz method

The *i*th algebraic equation of system of *n* equations:

$$0 = \sum_{j=1}^{n} K_{ij}^{e} u_{j}^{e} - f_{i}^{e} - Q_{i}^{e} \quad (i = 1, 2, ..., n)$$

where

$$K_{ij}^e = B^e(\psi_i^e, \psi_j^e) = \int_{x_a}^{x_b} \left( a \frac{d\psi_i^e}{dx} \frac{d\psi_j^e}{dx} + c\psi_i^e \psi_j^e \right) dx$$

$$f_i^e = \int_{x_a}^{x_b} f \psi_i^e \, dx$$

$$Q_i^e = \sum_{j=1}^n \psi_i^e \left( x_j^e \right) \cdot Q_j^e$$

➤ In matrix notation

$$\left[K^{e}\right]\left\{u^{e}\right\} = \left\{f^{e}\right\} + \left\{Q^{e}\right\}$$

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or

$$\mathbf{K}^e \mathbf{u}^e = \mathbf{f}^e + \mathbf{Q}^e$$



#### Derivation of Element Equation

> Linear Element

$$K_{ij}^{e} = \int_{x_{e}}^{x_{e+1}} \left( a \frac{d\psi_{i}^{e}}{dx} \frac{d\psi_{j}^{e}}{dx} + c\psi_{i}^{e} \psi_{j}^{e} \right) dx$$

$$f_{i}^{e} = \int_{x_{e}}^{x_{e+1}} f\psi_{i}^{e} dx$$

 $\triangleright$  In the local coordinate:  $x = x_1^e + \overline{x}$ 

$$K_{ij}^{e} = \int_{0}^{h_{e}} \left( a \frac{d\psi_{i}^{e}}{d\overline{x}} \frac{d\psi_{j}^{e}}{d\overline{x}} + c\psi_{i}^{e} \psi_{j}^{e} \right) d\overline{x}$$

$$f_{i}^{e} = \int_{0}^{h_{e}} f\psi_{i}^{e} d\overline{x}$$

➤ Linear Largrange Interpolation Function

$$\psi_1^e(\overline{x}) = 1 - \frac{\overline{x}}{h_e}$$

$$\psi_2^e(\overline{x}) = \frac{\overline{x}}{h_e}$$





#### Derivation of Element Equation

> Linear Element

$$\psi_1^e = 1 - \frac{\overline{x}}{h_e}, \quad \psi_2^e = \frac{\overline{x}}{h_e}$$

$$\frac{d\psi_1^e}{d\overline{x}} = -\frac{1}{h_e}, \quad \frac{d\psi_2^e}{d\overline{x}} = \frac{1}{h_e}$$

$$K_{11}^{e} = \int_{0}^{h_{e}} \left( a \frac{d\psi_{1}^{e}}{d\overline{x}} \frac{d\psi_{1}^{e}}{d\overline{x}} + c\psi_{1}^{e}\psi_{1}^{e} \right) d\overline{x}$$

$$= \int_{0}^{h_{e}} \left[ a \left( -\frac{1}{h_{e}} \right) \left( -\frac{1}{h_{e}} \right) + c \left( 1 - \frac{\overline{x}}{h_{e}} \right) \left( 1 - \frac{\overline{x}}{h_{e}} \right) \right] d\overline{x}$$

$$K_{12}^{e} = \int_{0}^{h_{e}} \left( a \frac{d\psi_{1}^{e}}{d\overline{x}} \frac{d\psi_{2}^{e}}{d\overline{x}} + c\psi_{1}^{e}\psi_{2}^{e} \right) d\overline{x}$$

$$= \int_{0}^{h_{e}} \left[ a \left( -\frac{1}{h_{e}} \right) \left( \frac{1}{h_{e}} \right) + c \left( 1 - \frac{\overline{x}}{h_{e}} \right) \left( \frac{\overline{x}}{h_{e}} \right) \right] d\overline{x} = K_{21}^{e}$$

$$K_{22}^{e} = \int_{0}^{h_{e}} \left( a \frac{d\psi_{2}^{e}}{d\overline{x}} \frac{d\psi_{2}^{e}}{d\overline{x}} + c\psi_{2}^{e}\psi_{2}^{e} \right) d\overline{x}$$

$$= \int_{0}^{h_{e}} \left[ a \left( \frac{1}{h_{e}} \right) \left( \frac{1}{h_{e}} \right) + c \left( \frac{\overline{x}}{h_{e}} \right) \left( \frac{\overline{x}}{h_{e}} \right) \right] d\overline{x}$$



#### Derivation of Element Equation

#### > Linear Element

G.E.

$$-\frac{d}{dx}\left(\frac{du}{dx}\right) + cu - f = 0 \quad \text{for } 0 < x < L$$

#### Stiffness Matrix

$$K_{11}^{e} = \frac{a_{e}}{h_{e}} + \frac{1}{3}c_{e}h_{e}$$

$$K_{12}^{e} = -\frac{a_{e}}{h_{e}} + \frac{1}{6}c_{e}h_{e} = K_{21}^{e}$$

$$K_{22}^{e} = \frac{a_{e}}{h_{e}} + \frac{1}{3}c_{e}h_{e}$$

$$f_{1}^{e} = \int_{0}^{h_{e}} f_{e} \left(1 - \frac{\overline{x}}{h_{e}}\right) dx = \frac{1}{2}f_{e}h_{e}$$

$$f_{2}^{e} = \int_{0}^{h_{e}} f_{e} \left(\frac{\overline{x}}{h_{e}}\right) dx = \frac{1}{2}f_{e}h_{e}$$

✓ The coefficient matrix and column vector

$$\begin{bmatrix} K^e \end{bmatrix} = \frac{a_e}{h_e} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} + \frac{c_e h_e}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

$$\left\{f^e\right\} = \frac{f_e h_e}{2} \begin{bmatrix} 1\\1 \end{bmatrix}$$





#### Derivation of Element Equation

#### Quadratic Element

$$\psi_{1}^{e}(\overline{x}) = \left(1 - \frac{\overline{x}}{h_{e}}\right) \left(1 - \frac{2\overline{x}}{h_{e}}\right) = 1 - 3\frac{\overline{x}}{h_{e}} + 2\left(\frac{\overline{x}}{h_{e}}\right)^{2}$$

$$\psi_{2}^{e}(\overline{x}) = 4\frac{\overline{x}}{h_{e}} \left(1 - \frac{\overline{x}}{h_{e}}\right) = 4\frac{\overline{x}}{h_{e}} - 4\left(\frac{\overline{x}}{h_{e}}\right)^{2}$$

$$\psi_{3}^{e}(\overline{x}) = \frac{\overline{x}}{h_{e}} \left(1 - \frac{2\overline{x}}{h_{e}}\right) = \frac{\overline{x}}{h_{e}} - 2\left(\frac{\overline{x}}{h_{e}}\right)^{2}$$

$$\frac{\partial \psi_{1}^{e}}{\partial \overline{x}} = -\frac{3}{h_{e}} + \frac{4\overline{x}}{h_{e}^{2}}$$

$$\frac{\partial \psi_{2}^{e}}{\partial \overline{x}} = \frac{4}{h_{e}} - \frac{8\overline{x}}{h_{e}^{2}}$$

$$\frac{\partial \psi_{3}^{e}}{\partial \overline{x}} = \frac{1}{h_{e}} - \frac{4\overline{x}}{h_{e}^{2}}$$

$$K_{11}^{e} = \int_{0}^{h_{e}} \left( a \frac{d\psi_{1}^{e}}{d\overline{x}} \frac{d\psi_{1}^{e}}{d\overline{x}} + c\psi_{1}^{e}\psi_{1}^{e} \right) d\overline{x}$$

$$= \int_{0}^{h_{e}} \left\{ a_{e} \left( -\frac{3}{h_{e}} + \frac{4\overline{x}}{h_{e}^{2}} \right) \left( -\frac{3}{h_{e}} + \frac{4\overline{x}}{h_{e}^{2}} \right) + c_{e} \left[ 1 - 3\frac{\overline{x}}{h_{e}} + 2\left(\frac{\overline{x}}{h_{e}}\right)^{2} \right] \left[ 1 - 3\frac{\overline{x}}{h_{e}} + 2\left(\frac{\overline{x}}{h_{e}}\right)^{2} \right] \right\} d\overline{x} = \frac{7}{3} \frac{a_{e}}{h_{e}} + \frac{2}{15} c_{e} h_{e}$$

$$K_{12}^{e} = \int_{0}^{h_{e}} \left( a \frac{d\psi_{1}^{e}}{d\overline{x}} \frac{d\psi_{1}^{e}}{d\overline{x}} + c\psi_{1}^{e}\psi_{1}^{e} \right) d\overline{x}$$

$$= \int_{0}^{h_{e}} \left[ a_{e} \left( -\frac{3}{h_{e}} + \frac{4\overline{x}}{h_{e}^{2}} \right) \left( \frac{4}{h_{e}} - \frac{8\overline{x}}{h_{e}^{2}} \right) + c_{e} \left[ 1 - 3\frac{\overline{x}}{h_{e}} + 2\left(\frac{\overline{x}}{h_{e}}\right)^{2} \right] \left[ 4\frac{\overline{x}}{h_{e}} \left( 1 - \frac{\overline{x}}{h_{e}} \right) \right] d\overline{x} = -\frac{8}{3} \frac{a_{e}}{h_{e}} + \frac{2}{30} c_{e} h_{e} = K_{21}^{e}$$



#### Derivation of Element Equation

#### Quadratic Element

G.E.

$$-\frac{d}{dx}\left(\frac{du}{dx}\right) + cu - f = 0 \quad \text{for } 0 < x < L$$

#### Stiffness Matrix

$$K_{11}^{e} = K_{21}^{e} \qquad f_{1}^{e} = \int_{0}^{h_{e}} f_{e} \left[ 1 - 3\frac{\overline{x}}{h_{e}} + 2\left(\frac{\overline{x}}{h_{e}}\right)^{2} \right] dx = \frac{1}{6} f_{e} h_{e}$$

$$K_{13}^{e} = K_{31}^{e} \qquad f_{2}^{e} = \int_{0}^{h_{e}} f_{e} \left[ 4\frac{\overline{x}}{h_{e}} - 4\left(\frac{\overline{x}}{h_{e}}\right)^{2} \right] dx = \frac{4}{6} f_{e} h_{e}$$

$$K_{23}^{e} = K_{32}^{e} \qquad f_{3}^{e} = f_{1}^{e} \quad \text{(by symmetry)}$$

$$K_{33}^{e} = f_{1}^{e} \quad \text{(by symmetry)}$$

✓ The coefficient matrix and column vector

$$\begin{bmatrix} K^e \end{bmatrix} = \frac{a_e}{3h_e} \begin{bmatrix} 7 & -8 & 1 \\ -8 & 16 & -8 \\ 1 & -8 & 7 \end{bmatrix} + \frac{c_e h_e}{30} \begin{bmatrix} 4 & 2 & -1 \\ 2 & 16 & 2 \\ -1 & 2 & 4 \end{bmatrix}$$

$$\left\{f^{e}\right\} = \frac{f_{e}h_{e}}{6} \begin{bmatrix} 1\\4\\1 \end{bmatrix}$$





#### Derivation of Element Equation

G.E. 
$$-\frac{d}{dx} \left( \frac{du}{dx} \right) + cu - f = 0 \quad \text{for } 0 < x < L$$

#### > Linear Element

$$\begin{bmatrix} K^e \end{bmatrix} = \frac{a_e}{h_e} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} + \frac{c_e h_e}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$
$$\{ f^e \} = \frac{f_e h_e}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

#### > Quadratic Element

$$\begin{bmatrix} K^e \end{bmatrix} = \frac{a_e}{3h_e} \begin{bmatrix} 7 & -8 & 1 \\ -8 & 16 & -8 \\ 1 & -8 & 7 \end{bmatrix} + \frac{c_e h_e}{30} \begin{bmatrix} 4 & 2 & -1 \\ 2 & 16 & 2 \\ -1 & 2 & 4 \end{bmatrix}$$

$$\left\{ f^e \right\} = \frac{f_e h_e}{6} \begin{bmatrix} 1\\4\\1 \end{bmatrix}$$





# 主題三

# Example



#### For example

G.E.

$$-\left(\frac{d^2u}{dx^2}\right) - u + x^2 = 0 \quad \text{for } 0 < x < L$$

Boundary conditions:

$$u(0) = u_0, u(1) = 0$$

Exact solution:

$$u_{exact} = \frac{\sin(x) + 2\sin(1-x)}{\sin 1} + x^2 - 2$$

已知係數矩陣形式

$$K_{ij}^{e} = \int_{x_a}^{x_b} \left( \frac{d\psi_i^e}{dx} \frac{d\psi_j^e}{dx} - \psi_i^e \psi_j^e \right) dx$$

$$f_i^e = \int_{x_a}^{x_b} \left(-x^2\right) \psi_i^e dx$$

分别使用線性及二次函數求解,並比較其誤差





**G.E.** 
$$-\left(\frac{d^2u}{dx^2}\right) - u + x^2 = 0$$
 for  $0 < x < L$ 

**Linear** Element

**B.C.** 
$$u(0) = u_0$$
,  $u(1) = 0$   $u_{exact} = \frac{\sin(x) + 2\sin(1-x)}{\sin 1} + x^2 - 2$ 

$$e^{1}$$
  $e^{2}$   $e^{3}$   $e^{4}$   $x_{1}$   $x_{2}$   $x_{3}$   $x_{4}$   $x_{5}$ 

$$a = 1$$
,  $c = -1$ ,  $h_e = \frac{1}{4}$ 

$$\phi_1^e(\overline{x}) = 1 - \frac{\overline{x}}{h_e}, \quad \phi_2^e(\overline{x}) = \frac{\overline{x}}{h_e}$$

$$\begin{bmatrix} K^e \end{bmatrix} = \frac{a_e}{h_e} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} + \frac{c_e h_e}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

$$\left\{f^e\right\} = \frac{f_e h_e}{2} \begin{bmatrix} 1\\1 \end{bmatrix}$$

> The element coefficient matrix

$$\begin{bmatrix} K^e \end{bmatrix} = \frac{1}{24} \begin{bmatrix} 94 & -97 \\ -97 & 94 \end{bmatrix} = \begin{bmatrix} 3.9167 & -4.0417 \\ -4.0417 & 3.9167 \end{bmatrix}$$

$$f_1^e = \int_{x_a}^{x_b} (-\overline{x}^2) \left( 1 - \frac{\overline{x}}{h_e} \right) d\overline{x} = -\frac{1}{h_e} \left[ \frac{x_b}{3} \left( x_b^3 - x_a^3 \right) - \frac{1}{4} \left( x_b^4 - x_a^4 \right) \right]$$

$$f_2^e = \int_{x_a}^{x_b} (-\overline{x}^2) \left( \frac{\overline{x}}{h_e} \right) d\overline{x} = -\frac{1}{h_e} \left[ \frac{1}{4} \left( x_b^4 - x_a^4 \right) - \frac{x_a}{3} \left( x_b^3 - x_a^3 \right) \right]$$



For example G.E. 
$$-\left(\frac{d^2u}{dx^2}\right) - u + x^2 = 0$$
 for  $0 < x < L$ 

**Linear** Element

**B.C.** 
$$u(0) = u_0$$
,  $u(1) = 0$   $u_{exact} = \frac{\sin(x) + 2\sin(1-x)}{\sin 1} + x^2 - 2$ 

$$f_{1}^{e} = \int_{x_{a}}^{x_{b}} (-\overline{x}^{2}) \left( 1 - \frac{\overline{x}}{h_{e}} \right) d\overline{x} = -\frac{1}{h_{e}} \left[ \frac{x_{b}}{3} \left( x_{b}^{3} - x_{a}^{3} \right) - \frac{1}{4} \left( x_{b}^{4} - x_{a}^{4} \right) \right]$$

$$f_{2}^{e} = \int_{x_{a}}^{x_{b}} (-\overline{x}^{2}) \left( \frac{\overline{x}}{h_{e}} \right) d\overline{x} = -\frac{1}{h_{e}} \left[ \frac{1}{4} \left( x_{b}^{4} - x_{a}^{4} \right) - \frac{x_{a}}{3} \left( x_{b}^{3} - x_{a}^{3} \right) \right]$$

• Element 1.

$$f_1^1 = -0.001302, \quad f_2^1 = -0.003906$$

• Element 2.

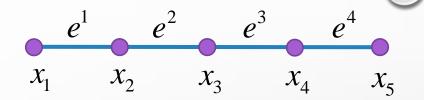
$$f_1^2 = -0.014323, \quad f_2^2 = -0.022135$$

• Element 3.

$$f_1^3 = -0.042969, \quad f_2^3 = -0.05599$$

Element 4.

$$f_1^4 = -0.08724, \quad f_2^4 = -0.10547$$



$$[F]_{5\times 1} = \sum_{e=1}^{4} [f^{e}]_{2\times 1}$$

$$= -\begin{bmatrix} 0.00130 \\ 0.00391 + 0.01432 \\ 0.02213 + 0.04297 \\ 0.05599 + 0.08724 \\ 0.10547 \end{bmatrix} = -\begin{bmatrix} 0.00130 \\ 0.01823 \\ 0.06510 \\ 0.14323 \\ 0.10547 \end{bmatrix}$$





For example G.E. 
$$-\left(\frac{d^2u}{dx^2}\right) - u + x^2 = 0$$
 for  $0 < x < L$ 

**Linear** Element

**B.C.** 
$$u(0) = u_0$$
,  $u(1) = 0$   $u_{exact} = \frac{\sin(x) + 2\sin(1-x)}{\sin 1} + x^2 - 2$ 

$$e^{1}$$
  $e^{2}$   $e^{3}$   $e^{4}$   $x_{1}$   $x_{2}$   $x_{3}$   $x_{4}$   $x_{5}$ 

$$[K]_{5\times 5} \{u\}_{5\times 1} = \{F\}_{5\times 1}$$

$$\begin{bmatrix} 3.9167 & -4.0417 & 0 & 0 & 0 \\ -4.0417 & 7.8333 & -4.0417 & 0 & 0 \\ 0 & -4.0417 & 7.8333 & -4.0417 & 0 \\ 0 & 0 & -4.0417 & 7.8333 & -4.0417 \\ 0 & 0 & 0 & -4.0417 & 3.9167 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \\ u_5 \end{bmatrix} = -\begin{bmatrix} 0.00130 \\ 0.01823 \\ 0.06510 \\ 0.14323 \\ 0.10547 \end{bmatrix} + \begin{bmatrix} Q_1^1 \\ Q_2^1 + Q_1^2 \\ Q_2^2 + Q_1^3 \\ Q_2^3 + Q_1^4 \\ Q_2^4 \end{bmatrix}$$
発矩陣:

解矩陣:

$$u_2 = -0.02323$$
,  $u_3 = -0.04052$ ,  $u_4 = -0.03919$ 



**G.E.** 
$$-\left(\frac{d^2u}{dx^2}\right) - u + x^2 = 0$$
 for  $0 < x < L$ 

Quadratic Element?

**B.C.** 
$$u(0) = u_0$$
,  $u(1) = 0$   $u_{exact} = \frac{\sin(x) + 2\sin(1-x)}{\sin 1} + x^2 - 2$ 

$$e^{1}$$
  $e^{2}$   $x_{1}$   $x_{2}$   $x_{3}$   $x_{4}$   $x_{5}$ 

$$a = 1$$
,  $c = -1$ ,  $h_e = \frac{1}{2}$ 

$$\begin{bmatrix} K^e \end{bmatrix} = \frac{a_e}{3h_e} \begin{bmatrix} 7 & -8 & 1 \\ -8 & 16 & -8 \\ 1 & -8 & 7 \end{bmatrix} + \frac{c_e h_e}{30} \begin{bmatrix} 4 & 2 & -1 \\ 2 & 16 & 2 \\ -1 & 2 & 4 \end{bmatrix}$$

$$\left\{ f^e \right\} = \frac{f_e h_e}{6} \begin{bmatrix} 1\\4\\1 \end{bmatrix}$$

> The element coefficient matrix

$$\begin{bmatrix} K^e \end{bmatrix} = \frac{1}{60} \begin{bmatrix} 276 & -322 & 41 \\ -322 & 624 & -322 \\ 41 & -322 & 276 \end{bmatrix} = \begin{bmatrix} 4.6000 & -5.3667 & 0.6833 \\ -5.3667 & 10.4000 & -5.3667 \\ 0.6833 & -5.3667 & 4.6000 \end{bmatrix}$$

$$f_1^e = -\frac{h_e}{60} \left( -h_e^2 + 10x_a^2 \right)$$

$$f_2^e = -\frac{h_e}{15} \left( 3h_e^2 + 10x_a^2 + 10x_a h_e \right)$$

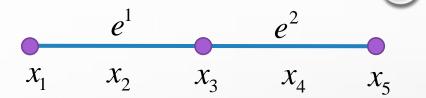
$$f_3^e = -\frac{h_e}{60} \left( 9h_e^2 + 10x_a^2 + 20x_a h_e \right)$$



**G.E.** 
$$-\left(\frac{d^2u}{dx^2}\right) - u + x^2 = 0$$
 for  $0 < x < L$ 

Quadratic Element?

**B.C.** 
$$u(0) = u_0$$
,  $u(1) = 0$   $u_{exact} = \frac{\sin(x) + 2\sin(1-x)}{\sin 1} + x^2 - 2$   $\mathcal{X}_1$ 



#### $[K]_{5\times5}\{u\}_{5\times1}=\{F\}_{5\times1}$

> Assemble

$$[?]_{5\times 5} \{u\}_{5\times 1} = \{?\}_{5\times 1}$$

#### > 代入邊界條件

$$\begin{bmatrix} 10.4000 & -5.3667 & 0 \\ -5.3667 & 9.2000 & -5.3667 \\ 0 & -5.3667 & 10.4000 \end{bmatrix} \begin{bmatrix} u_2 \\ u_3 \\ u_4 \end{bmatrix} = - \begin{bmatrix} 0.02500 \\ 0.03750 \\ 0.19167 \end{bmatrix}$$

#### 解矩陣:

$$u_2 = -0.02345$$
,  $u_3 = -0.04078$ ,  $u_4 = -0.03947$