

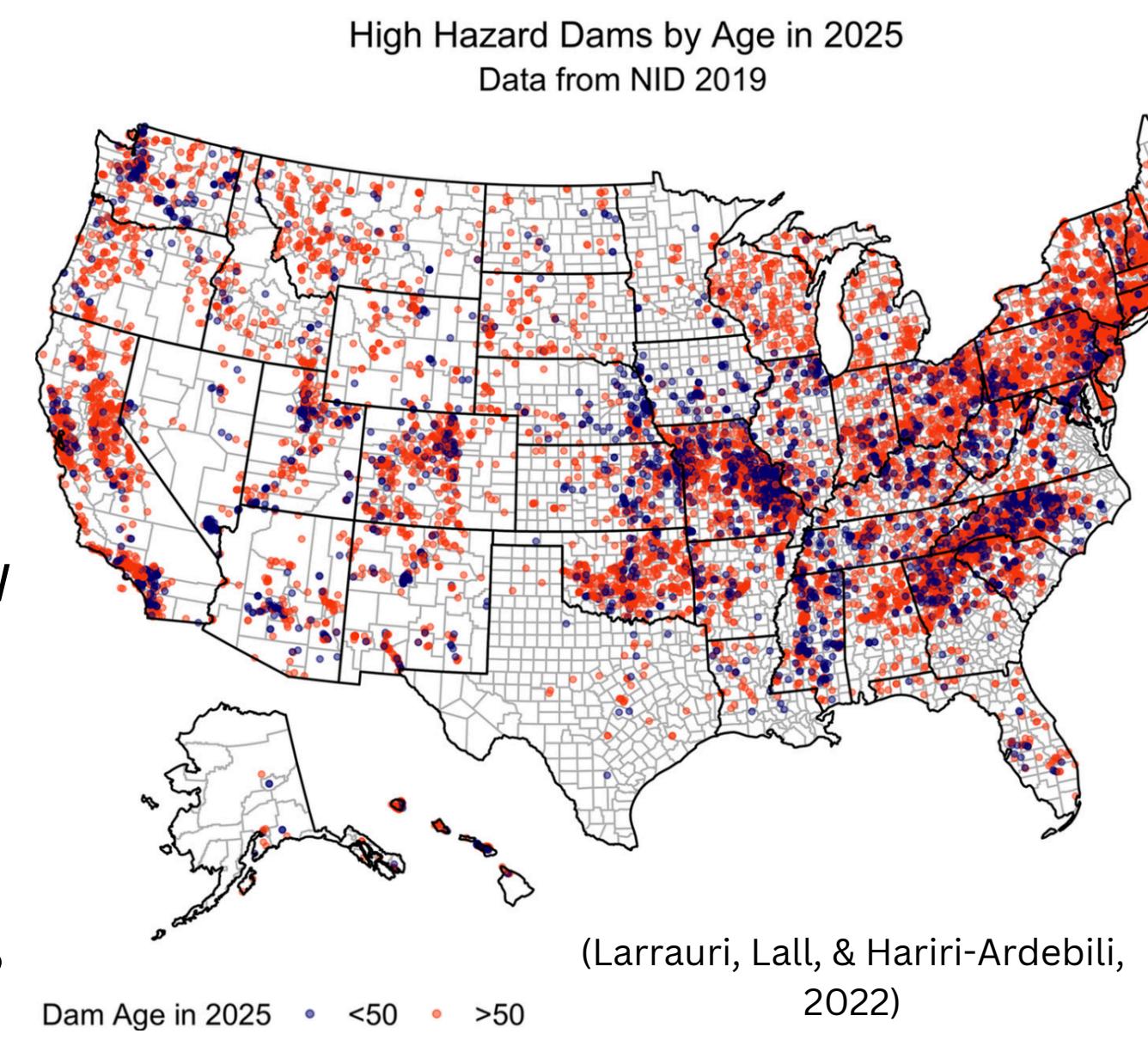
# Investigating Adaptive Chaos Control for Mitigating Weather Extremes

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## Background

### Current Issues

- Increasing frequency and intensity of floods and droughts under climate change.
- Traditional infrastructural solutions like dams are now beyond their lifespan and risking failure.
- Lack of investment makes replacing or repairing aging infrastructure challenging.



### Potential Solution: Chaos Control & Weather Modification

- Change the structure and trajectory of storms by small perturbations in mid-latitude circulation systems, thereby adaptively reduce the risks of floods and droughts.

### Previous studies (Karamperidou, Cioffi, & Lall, 2012)

- Apply the Lorenz 1984 (L84) model using real-world data.
- L84 can capture the El Niño-Southern Oscillation (ENSO) dynamic on mid-latitude, and it can guide real-world experiments for altering jet stream and eddy track dynamics.

### Our Goal

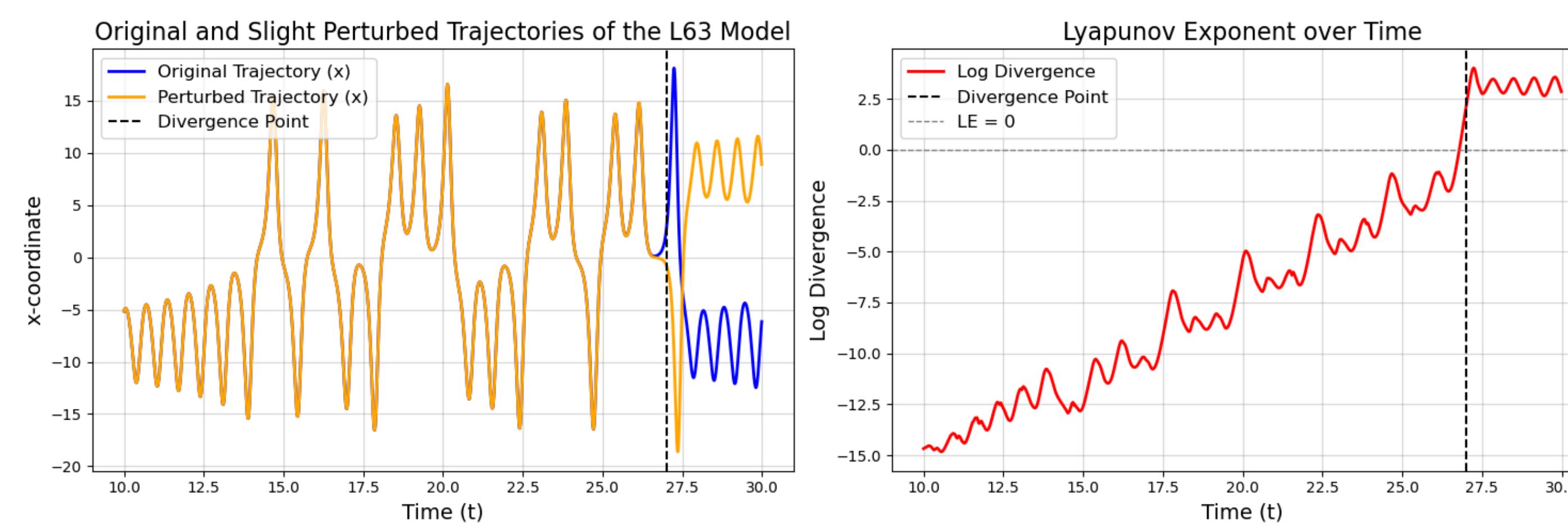
- Adaptive chaos control on L84 atmospheric circulation model.
- Lyapunov Exponents as a guiding method for control strategies.

## Lyapunov Exponents (LEs)

- Chaos system in atmospheric circulation: small perturbations will amplify rapidly in mid-latitude circulation systems
- Function of LEs: analyzing the Lyapunov Exponents to identify opportunities to modify and stabilize these chaotic circulation systems through targeted interventions.
- Calculation:

$$\text{LEs: } \lambda = \frac{\log \left( \frac{\|X_{\text{next}}\|}{\|X\|} \right)}{\Delta t}$$

- The plot indicates that two trajectories with close initial condition in the chaotic system will be diverged when LEs > 0.



## Lorenz Models

### Lorenz 1963 (L63)

$$\begin{aligned} \frac{dx}{dt} &= \sigma(y - x), \\ \frac{dy}{dt} &= x(\rho - z) - y, \\ \frac{dz}{dt} &= xy - \beta z, \end{aligned}$$

### Idealized Model of Mid-Latitude Circulation with External Forcing:

- F = Equator-to-pole temperature gradient (EPG)
- G = Ocean-land contrast (OLC)

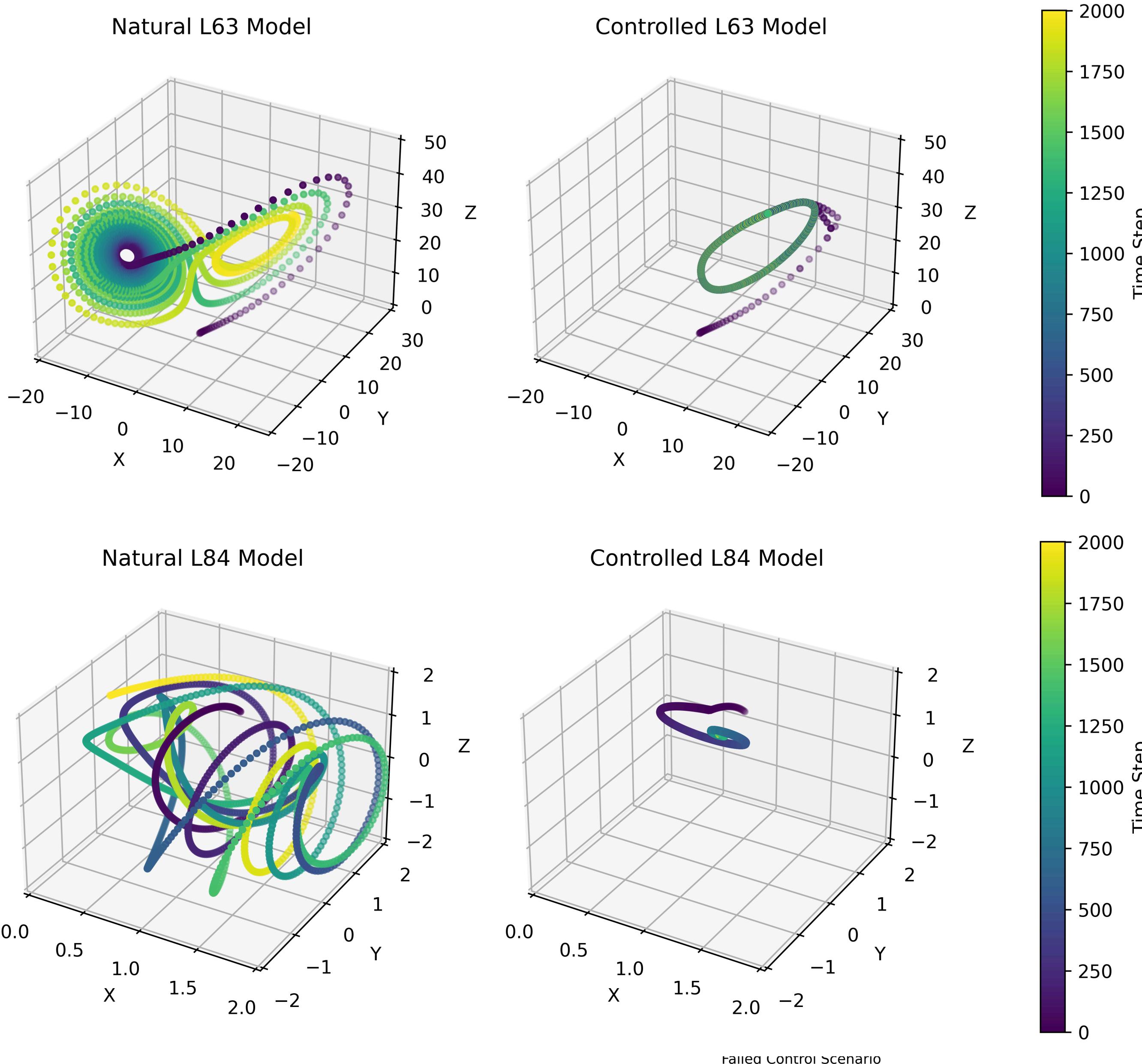
\*EPG and OLC are important drivers influencing jet stream and eddy.

### Lorenz 1984 (L84)

$$\begin{aligned} \frac{dX}{dt} &= -Y^2 - Z^2 - aX + aF, \\ \frac{dY}{dt} &= XY - bXZ - Y + G, \\ \frac{dZ}{dt} &= bXY + XZ - Z, \end{aligned}$$

## Result

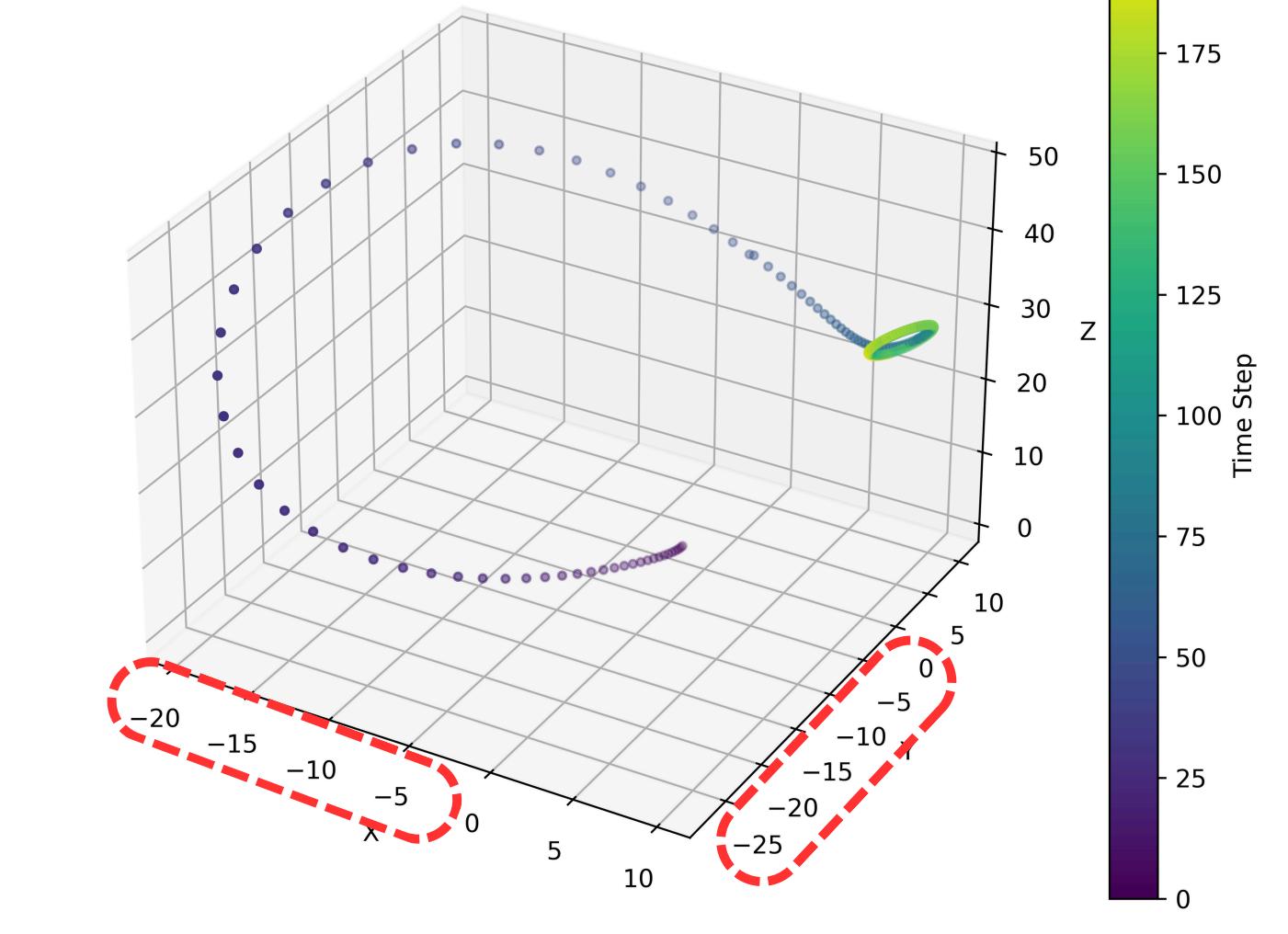
### Adaptive Chaos Control on both L63 and L84 model



### Uncontrolled Condition:

- If the initial LEs for applying control is too big that a large amount of perturbation will be required.

**Fail to Control**  
Initial LEs: 8.8752



## Control Methods

### Chaos control on both L63 and L84 model:

#### Involving the LEs for the control process.

- if LEs > 0, the system is in a chaotic region, and control is applied by perturbing the current state.

#### Optimizing the perturbation (u) for reducing energy usage.

- Objective function:

$$\text{Minimize: } \sum_{i=1}^n u_i^2$$

- Constraints (Boundary Constraint and Perturbation Magnitude Constraint):

$$\text{lower}_i \leq X_{t+k}[i] \leq \text{upper}_i, \quad \forall i \in \{1, 2, \dots, n\}$$

$$\|\mathbf{u}\| \leq u_{\max}$$

- Solver: Sequential Least Squares Programming (SLSQP)

### Settings:

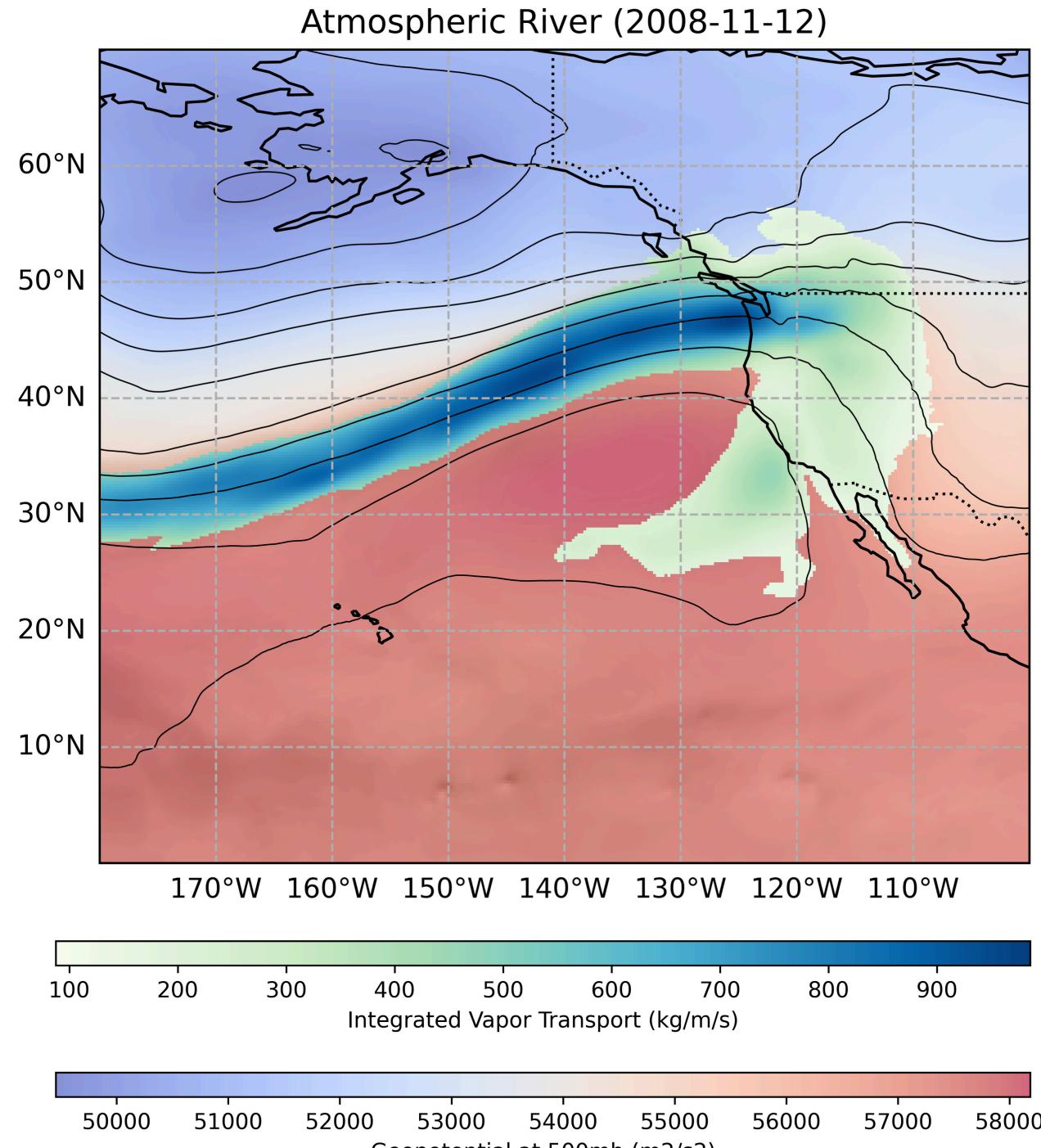
- Steps: 2000
- Look ahead steps: 5
- Boundary: trajectory remain at specific regimes

## Atmospheric Rivers (ARs)

- ARs: key drivers of floods at western US.

### Managing ARs:

- Applying LEs to identify unstable states.
- Adding adaptive chaos control to optimize perturbations to keep trajectories within safe bounds.



## Future Work

- Use deep learning method with high-resolution weather forecast models to build prediction engine for ARs.
- Data assimilation to refine ARs condition.
- Extend LEs-based optimal control to modify the ARs trajectory.

## References

- Concha Larrauri, P., Lall, U., & Hariri-Ardebili, M. A. (2022). Needs for portfolio risk assessment of aging dams in the United States. *Journal of Water Resources Planning and Management*, 149(1), 04022088.
- Karamperidou, C., Cioffi, F., & Lall, U. (2012). Surface temperature gradients as diagnostic indicators of midlatitude circulation dynamics. *Journal of Climate*, 25(12), 4154–4171.