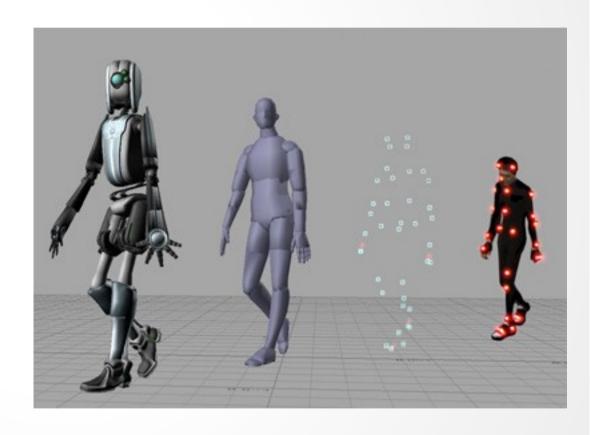
# **Character Animation**

Stamatios Katsaganis March 9, 2017



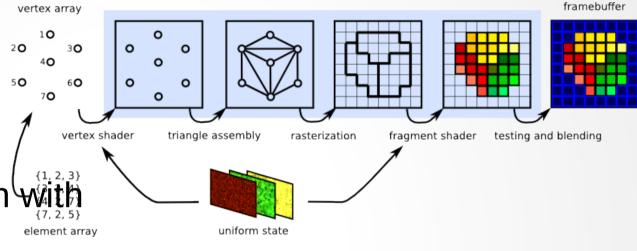
# Outline

#### Intorduction

- Skeletal Animation

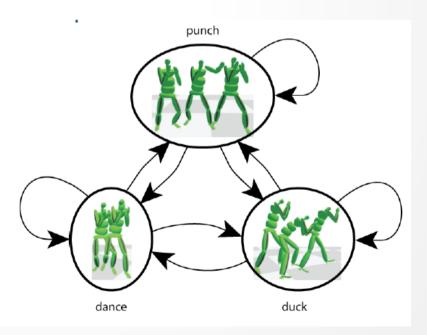
Motion Capture

Controllable motion constraints



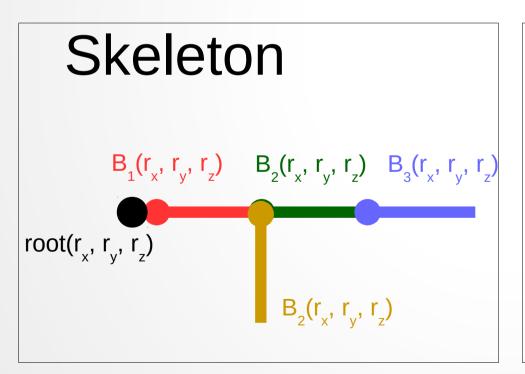
#### Motion Graphs

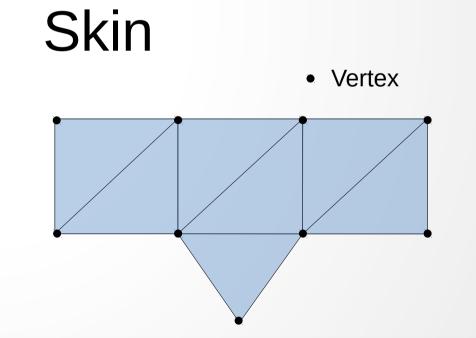
- What is a motion graph?
- Creating Transitions
- Motion graph construction
- What can motion graphs be used for



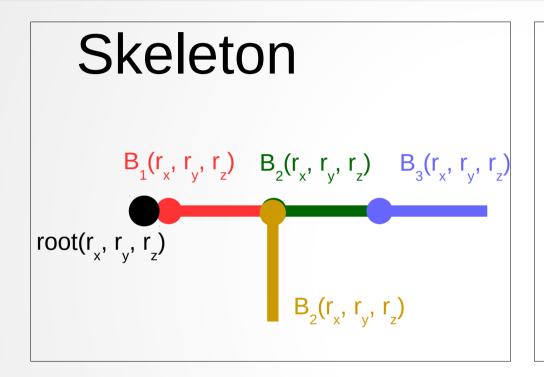
#### Introduction - Skeletal Animation

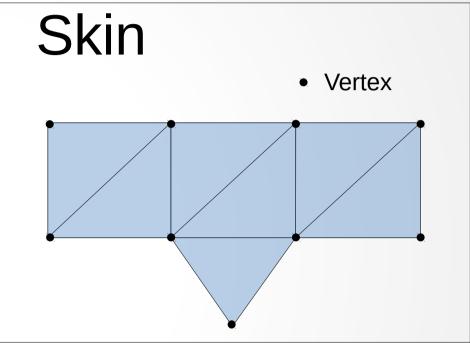
- An animated character consists of:
  - An invisible bone hierarchy called a skeleton.
  - A visible polygon mesh enclosing the skeleton called a skin.





#### Introduction - Skeletal Animation

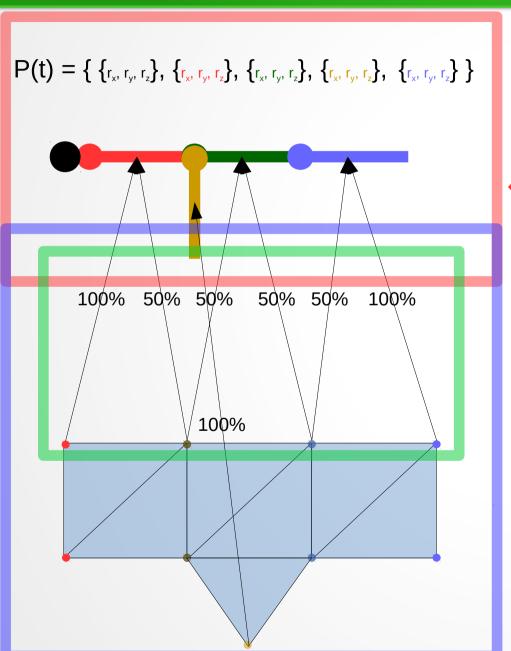


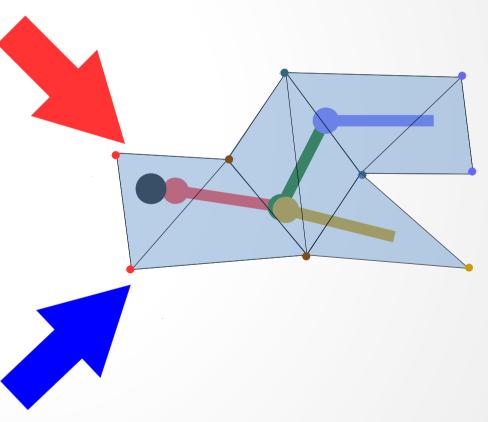


- A *pose* is defined as a vector of rotation values.  $P = \{ \{r_x, r_y, r_z\}, \{r_x, r_y, r_z\} \}$
- Bind Pose is the pose at the time the association between bones and skin vertices is made.

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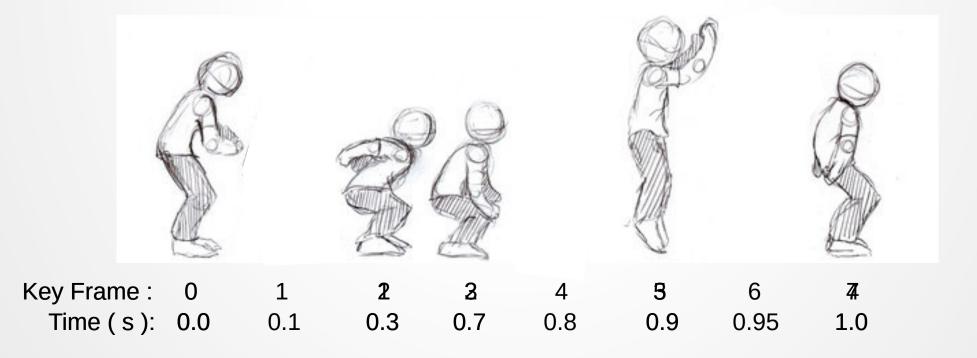
#### Introduction - Skeletal Animation





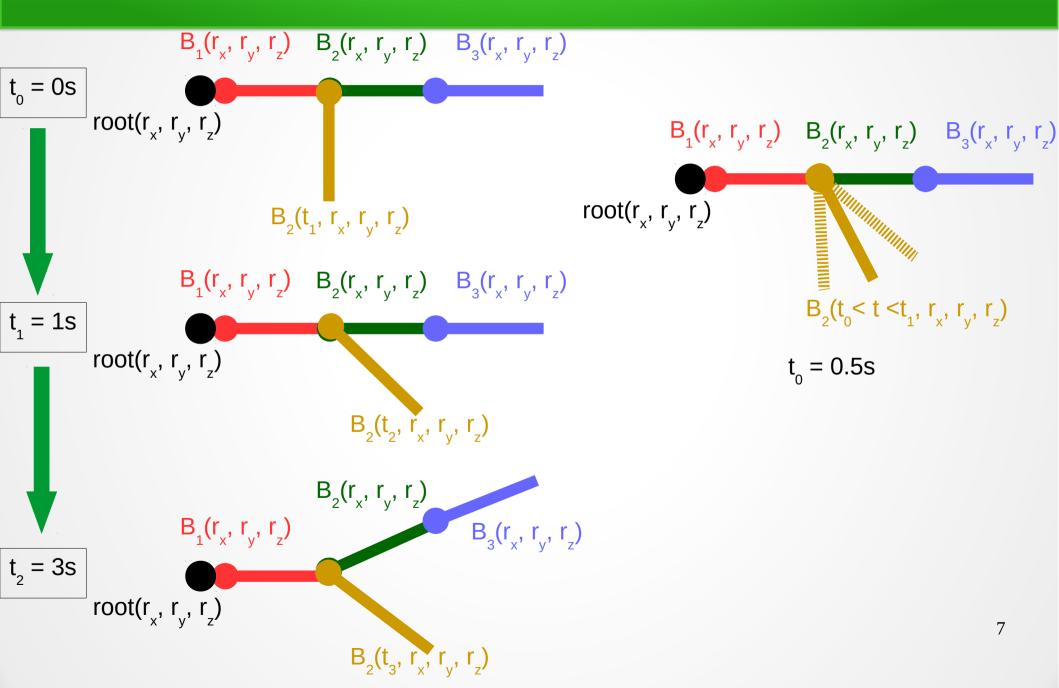
# Introduction - Key Framing

 Key framing: Define a skeleton pose at specified time points. Assume that motion in between these time points is smooth.

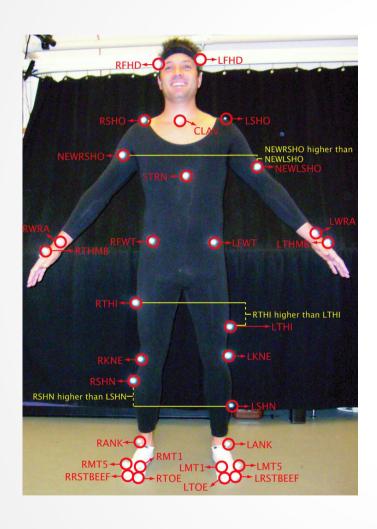


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# Introduction – Key Framing



## Introduction – Motion Capture



- Recorded images of an actor performing different movements while wearing special equipment are analyzed from various angles in order to extract bone rotation angles.
- Rotation angles and skeleton information are saved usually in text files.
- The rotation angles can then be transferred to a virtual character.

## Introduction - Motion Capture

- Yields high detail keyframe data.
- Bone speed and acceleration is captured naturally.
- Data can be noisy and needs post processing.
- Huge amount of data (60 to 120 fps).
- A motion clip consists of a a sequence of poses parameterized by time (or frame number).

# Introduction – Motion Capture

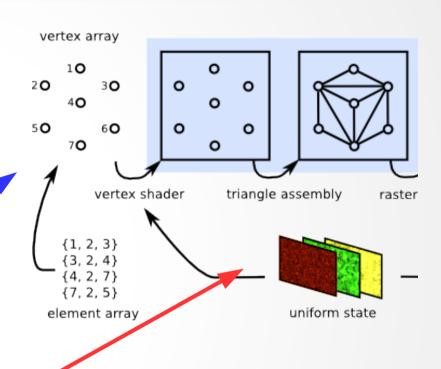
Motion Clip Demo

#### Introduction - Motivation

- Reuse existing motion clips to create new motions.
- Contol character motion at interactive rates suitable for real time applications.
- Synthesize motion to satisfy logical, spatial, temporal constraints.

# **Animation Engine – Skinning**

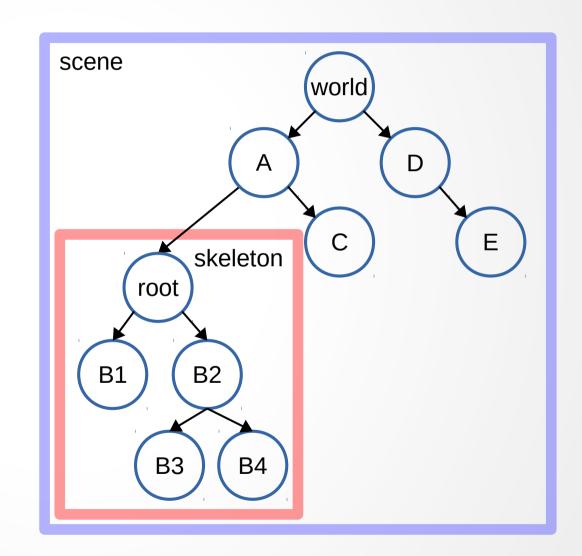
- **Skinning** is the process of computing a mesh configuration based on a pose and a rig.
- Skinning is done on the GPU
  - -Vertex shader input:
    - position coordinates ( p ).
    - bone indices affecting each vertex ( I
    - weights affecting each vertex (W).
  - -Uniform State:
    - bind pose inverse matrices one for each bone (BPInv).
    - current pose matrices one for each bone ( M ).



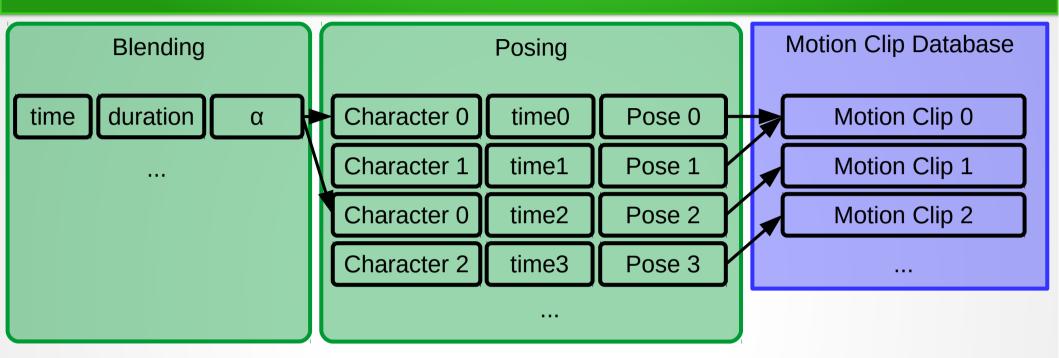
$$p'[i] = W[i] * M[I[i]] * BPInv[I[i]] * p[i]$$

# Animation Engine – Scene Graph

- The spatial dependency of the objects in a scene is represented as a rooted tree.
- The position and orientation of each node is relative to the coordinate system of its parent node.
- Animated skeletons are trees themselves and therefore they are parts of the scene tree.



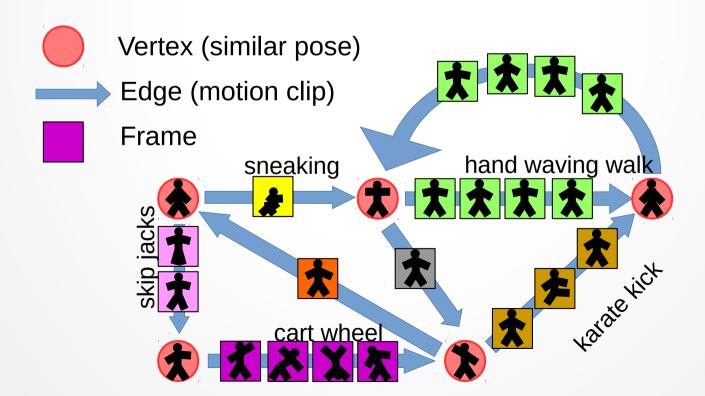
# **Animation Engine – Blending**



- Blend entries are kept in an array.
- time is relative to the beginning of the blend.
- duration is the total time required to complete the blend.
- $\alpha$  is the blend factor  $\alpha = time / duration$
- $Pose' = \alpha * Pose 2 (time 2) + (1 \alpha) * Pose 0 (time 0)$

## **Motion Graphs**

- •A *motion graph* is a directed graph where:
- Edges represent motion clips
- Vertices represent connection points between clips
   It maps the motion synthesis problem to that of finding optimal graph paths that satisfy a high level goal.



# Motion Graphs – Desired Features

- The motion graph should have as many vertices as possible.
- The graph should be strongly connected (every vertex is reachable from any other vertex).

- A motion clip is an edge in the motion graph.
  - The start and the end frames are the 2 vertices.
  - There is only one edge.



This graph is not strongly connected.

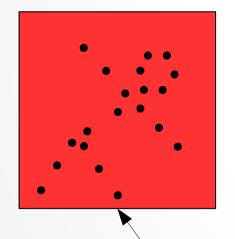
It needs more vertices.

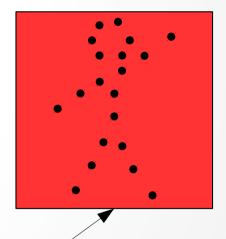
## **Motion Graphs - Transitions**

- Transitions are automatically generated motion clips.
- They add more vertices to the graph by connecting similar frames.
- Generating transitions is hard and depends on the similarity between motions.

 We use a simplified skin mesh to construct a point cloud p for every frame in the motion clip.

$$p_i = p_{i,0}, p_{i,1}, \dots, p_{i,N-1}$$
  $p_j = p_{j,0}, p_{j,1}, \dots, p_{j,N-1}$ 





 For any two frames (i, j) compute the square of the Euclidean distance between respective points in the point clouds.

NOT GOOD ENOUGH 
$$\longrightarrow d(i,j) = \sum_{l} w_{l} ||p_{i,l} - p_{j,l}||^{2}$$

- Pose can be the same even though the character is rotated around the vertical axis.
- Pose can be the same even though the character is translated on the horizontal plane.

- Lets fix it :
  - assume a rotation around the vertical axis
  - and a translation on the horizontal plane

$$d(i,j) = \min_{\theta,x_0,z_0} \sum_l w_l \|p_{i,l} - T_{\theta,x_0,z_0} p_{j,l}\|^2$$
 STILL NOT GOOD 
$$\theta,x_0,z_0 = 1$$
 ENOUGH

 A good transition should take into account speed and acceleration of moving bones.

- Lets fix it :
  - Use a window of m frames.



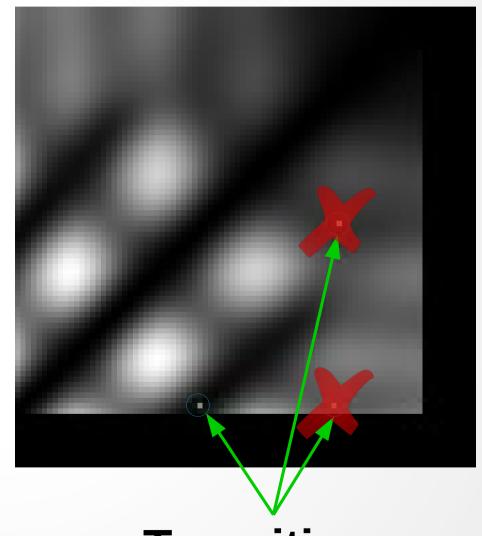
$$d(i,j) = \min_{\theta,x_0,z_0} \{ \sum_{m} \{ w_m \sum_{l} w_l || p_{i+m,l} - T_{\theta,x_0,z_0} p_{j+m-M,l} ||^2 \} \}$$



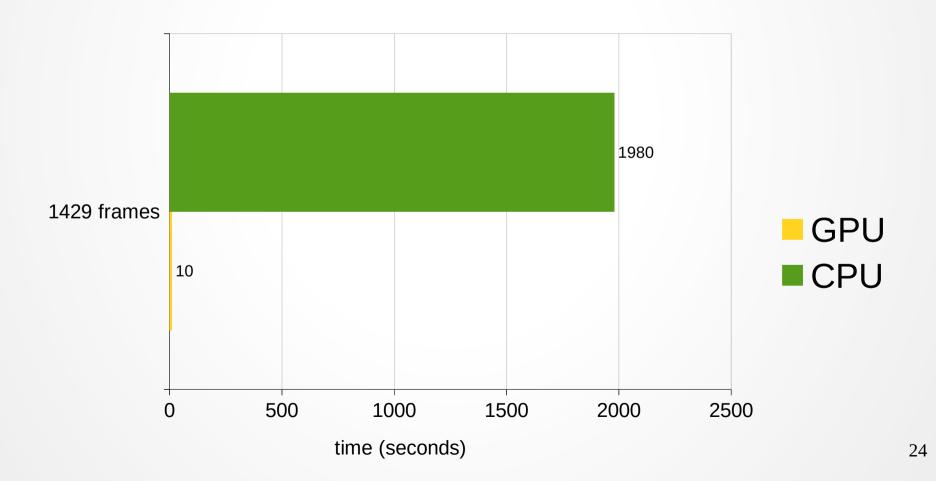
 Repeat process for all frames in the motion clips.

clips. (i,j)• Search for j for which is a local minima.

• Choose transition points from the local minima using a  $\varepsilon$  threshold  $d(i,j) < \varepsilon$ 

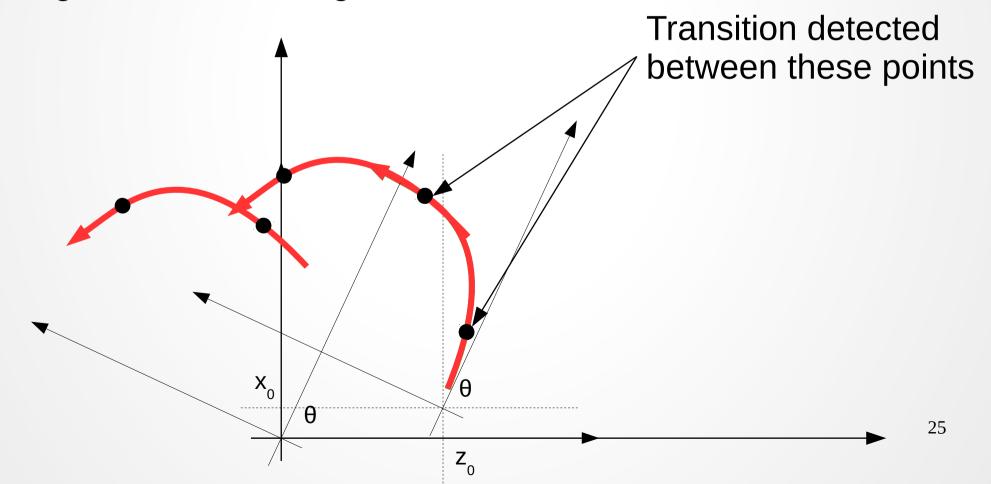


Creation of point clouds and transition detection are both done entirely on the GPU.

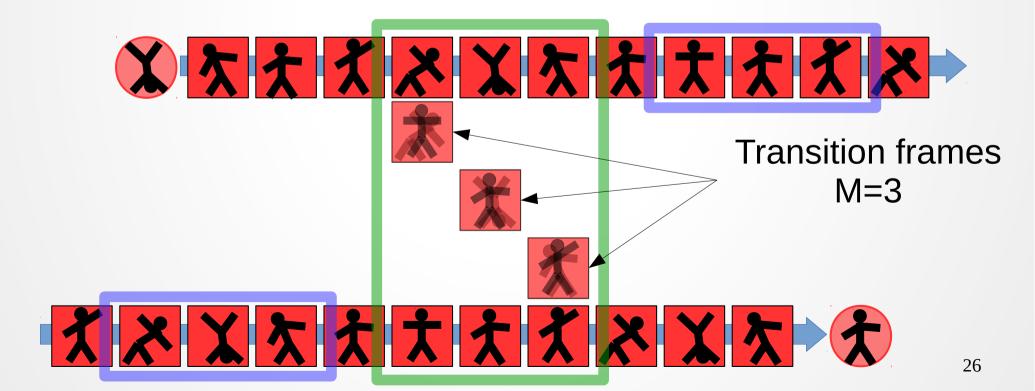


# Motion alignment

Imagine a walk veering left motion



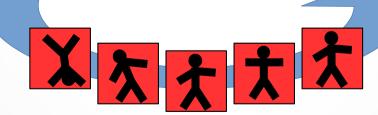
- Creating the poses for the transition.
- Transitions are created by blending M frames chosen from the original motion clip and the one we just reoriented and repositioned.



**Transition Demo** 

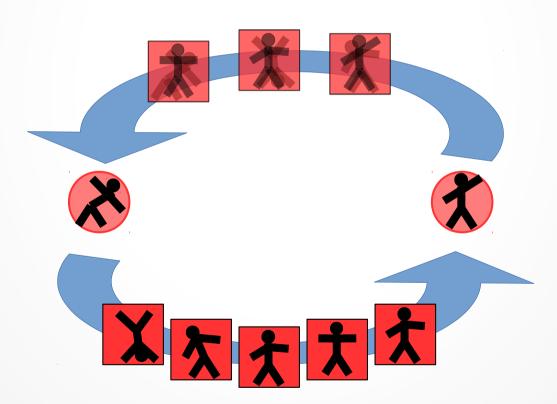
Updated motion graph with a transition





This graph is still not strongly connected.

Prunning the graph ensures that every vertex is reachable from any other vertex.



**Motion Graph Demos** 

# Backup Slides

Keep flipping ...

# Introduction – Pose computation

