

**(SHORT) CURRICULUM VITAE - September 2020**  
**Massimiliano Patacchiola, PhD**

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Name	Massimiliano
Surname	Patacchiola
Address	Edinburgh, Scotland, United Kingdom
Scholar	<a href="https://scholar.google.com/citations?user=L4GcSrsAAAAJ">https://scholar.google.com/citations?user=L4GcSrsAAAAJ</a>
Blog	<a href="http://mpatacchiola.github.io/blog">http://mpatacchiola.github.io/blog</a>
GitHub	<a href="https://github.com/mpatacchiola">https://github.com/mpatacchiola</a>
Nationality	Italian
Sex	Male

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## **Profile**

Researcher working on efficient deep learning, where “efficient” means: less data, less supervision, less computation. *Research interests:* deep learning (few-shot, self-supervised, and continual learning), Bayesian inference (Gaussian Processes), reinforcement learning and robotics.

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## **Work/Research Experience**

- 2018-Present    Postdoctoral Researcher. University of Edinburgh. United Kingdom.  
Member of the Machine Learning group. Research project on efficient few-shot learning via Bayesian methods and self-supervised learning (in collaboration with Huawei). ([www.anc.ed.ac.uk/machine-learning](http://www.anc.ed.ac.uk/machine-learning))  
Supervisor: [Amos Storkey](#)
- 2018             Internship, Snapchat inc. London. United Kingdom. Research project on the disentanglement of latent representations in deep autoencoders for applications such as style transfer and face-attributes generation ([www.snapchat.com](http://www.snapchat.com))  
Supervisors: Patrick-Fox Roberts, [Edward Rosten](#)
- 2012-2015      Robotics Engineer. Eurolink Systems group. Rome. Italy. Development of models for the control of UGV (Unmanned Ground Vehicle) and UAV (Unmanned Aerial Vehicle) in critical applications such as search-and-rescue and bomb disposal ([www.eurolinksystems.com](http://www.eurolinksystems.com))
- 2011-2012      Internship, LARAL (Laboratory of Artificial Life and Robotics). Institute of Cognitive Sciences and Technologies. Rome, Italy. Development of computational models for various experiments in Evolutionary Robotics (<http://laral.istc.cnr.it>)
- 2008-2009      Placement, ECONA (Research Centre for Cognitive Elaboration on Natural and Artificial Systems). La Sapienza University. Rome, Italy. Research project on visual perception and memory (<https://web.uniroma1.it/econa>)
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## Education

- 2015-2018 PhD in “Cognitive Robotics and Machine Learning”. Plymouth University, School of Computing, Electronics and Mathematics. United Kingdom. Research project on effective machine learning methods for human-robot interaction. This work has been cited [>100 times](#), the [repository](#) has 1400 stars and 400 forks on GitHub. Supervisors: [Angelo Cangelosi](#), Torbjorn Dahl, [Giorgio Metta](#)
- 2009-2011 MSc in “Cognitive Neuroscience”. La Sapienza University. Rome, Italy. Supervisors: Stefano Puglisi Allegra, [Gianluca Baldassarre](#), [Domenico Parisi](#)
- 2006-2009 BSc in “Experimental Cognitive Psychology”. La Sapienza University. Rome, Italy. Supervisor: Marta Olivetti Belardinelli
- 1999-2004 Secondary School. Scientific Course: National Plan of Computer Science. Rieti, Italy. It gives entry to university. Main subjects: computer science, mathematics (linear algebra, pre-calculus, calculus), physics, biology, English, French.
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## Technical Skills

- Machine Learning
- Programming experience (~2 years) with PyTorch and TensorFlow for deep learning applications and scientific publications.
  - Experience with Artificial Neural Networks and the most recent Deep Learning architectures (e.g ResNet, ResNeXt, WideResNet, DenseNet, GAN, VAE, etc).
  - Experience with supervised, unsupervised learning algorithms, reinforcement learning (DQN, Double DQN, MC, SARSA, etc), and Bayesian methods (Gaussian Processes, Bayesian networks).
- Robotics
- Developement of libraries for the control of humanoid robots, drones, and autonomous ground rover.
  - Experience with the most important software tools for Robotics and Computer Vision (e.g. ROS, YARP, NAOqi, OpenAI Gym, OpenCV).
- IT
- Proficiency in Python (~5 years, primary language).
  - Past exposure to several programming languages such as C/C++, C#, Visual Basic, HTML, PHP, JavaScript.
  - Daily usage of Unix OS (Shell, Bash scripting, SSH) and related tools.
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## Languages

Italian (native speaker), English (advanced), French (intermediate)

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## Awards, Fellowships and Scholarships

- 06-2020 Distinguished Service Award as an Outstanding Reviewer for the IEEE Robotics and Automation Letters (RA-L). Announced at ICRA 2020 award ceremony.
- 2018-present Associate Fellowship, Higher Education Academy (HEA). Programme that supports

early career researchers who have responsibility for teaching and learning.

03-2016 Academic Hardware Grant, NVIDIA corporation. Received a Tesla K40 GPU in support of a project on head pose estimation via convolutional neural networks.

2012-present Member, Mensa International. Society for people with high intelligence quotient.

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### Talks, Conferences, Workshops, Media

27-07-2017 (Extra) BBC documentary. Hyper Evolution: Rise of the Robots. Episode 1 and 2, the iCub humanoid robot at CRNS lab.

2015-present Reviewer for different conferences and journals: AISTATS (International Conference on Artificial Intelligence and Statistics), ICRA (International Conference on Robotics and Automation), IROS (International Conference on Intelligent Robots and Systems).

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### Selected Publications [\[scholar\]](#)

**Patacchiola, M.**, Storkey, A. (2020). “Self-Supervised Relational Reasoning for Representation Learning”. (under review). [\[arxiv\]](#) [\[GitHub\]](#)

**Patacchiola, M.**, Turner, J., Crowley, E. J., Storkey, A. (2019). “Deep Kernel Transfer in Gaussian Processes for Few-shot Learning”. (under review). [\[arxiv\]](#) [\[GitHub\]](#)

**Patacchiola, M.**, Cangelosi, A. (2017). “Head Pose Estimation in the Wild using Convolutional Neural Networks and Adaptive Gradient Methods”. *Pattern Recognition*, vol. 71, pp. 132-143. [\[pdf\]](#) [\[GitHub\]](#)

Polvara\*, R., **Patacchiola\***, M., Hanheide, M., & Neumann, G. (2020). Sim-to-Real Quadrotor Landing via Sequential Deep Q-Networks and Domain Randomization. *Robotics*, 9(1), 8. \*Co-first authors. [\[paper\]](#)

Thabet, M., **Patacchiola, M.**, & Cangelosi, A. (2019). “Sample-efficient Deep Reinforcement Learning with Imaginary Rollouts for Human-Robot Interaction”. *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*. [\[arxiv\]](#)