# Homework 1

Convex Optimization

Matthieu Boyer

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# 1 Exercises

#### Convex Sets

- Let  $C = \{x \in \mathbb{R}^2_+ \mid x_1 x_2 \ge 1\}$ . We can see that  $C = \{(x_1, x_2) \in \mathbb{R}^2_{+*} \mid x_1 \ge \frac{1}{x_2}\}$ . Thus, C is the epigraph of  $x \mapsto \frac{1}{x}$  which is convex since its second derivative is  $x \mapsto \frac{2x}{x^4}$ . Thus, C is convex.
- In general, this set is not convex. Indeed, for sets in  $\mathbb{R}$ , take  $S = \{-1, 1\}, T = \{0\}$ . Then the set of points closer to S than to T is  $\{x \in \mathbb{R} \mid x \le -0.5 \lor x \ge 0.5\}$  which is not an interval and thus not convex.
- Let us take  $x_1, x_2 \in \{x \mid x + S_2 \subseteq S_1\}$ . For  $x = \lambda x_1 + (1 \lambda) x_2$  consider x + y for  $y \in S_2$ :

$$x + y = \lambda x_1 + (1 - \lambda) x_2 + y = \lambda (x_1 + y) + (1 - \lambda x_2 + y)$$

Since  $x_i + S_2 \subseteq S_1$  for i = 1, 2, and since  $S_1$  is convex, for all  $y \in S_2$  the above sum is in  $S_1$  and thus  $x + S_2 \subseteq S_2$ . Finally, our set is convex.

• Let  $x_1, x_2 \in \{x \mid \exists y \in S_2, x + y \in S_1\}$ . Then let  $y_1, y_2$  be associated points to  $x_1, x_2$ . For  $x = \lambda x_1 + (1 - \lambda) x_2$  and  $y = \lambda y_1 + (1 - \lambda) y_2$ . Then, since  $S_2$  is convex,  $y \in S_2$ . Moreover:

$$x + y = \lambda \underbrace{(x_1 + y_1)}_{\in S_1} + (1 - \lambda) \underbrace{(x_2 + y_2)}_{\in S_1}$$

$$\underbrace{(x_1 + y_1)}_{\in S_1 \text{ since } S_1 \text{ is convex}}$$

Then, our set is convex.

#### **Convex Functions**

- The hessian of f at (x, y) is the matrix  $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ . On  $\mathbb{R}^2$  this matrix is not positive nor negative and thus the function is neither convex, or concave. However, the upper level sets for  $\alpha$  are convex if and only if  $\alpha \geq 0$  (from our first example) and thus the function is neither quasi-concave nor quasi-convex.
- On  $\mathbb{R}^2_{+*}$ , the hessian of the function is positive semidefinite and thus the function is convex.
- The hessian matrix of f is the matrix  $\begin{pmatrix} 0 & -\frac{1}{x_2^2} \\ -\frac{1}{x_2^2} & \frac{2x_1}{x_2^3} \end{pmatrix}$  Since its determinant is < 0 the Hessian is not positive semi-definite and the function is not convex. However, its sublevel sets are defined by the equations  $x_1 \le \alpha x_2$  and are thus convex (since half-planes). Thus, f is quasi-convex.

Let us define the Löwner order 

as the partial order defined by the convex cone of positive semi-definite matrices.

We know that:

$$A \leq B \Rightarrow B^{-1} \leq A^{-1}, \forall A, B \in S_{++}^n$$

From this, we know that for all  $t \leq 1$ :

$$((1-t)X+tY)^{-1} \leq (1-t)X^{-1}+tY^{-1}$$

By linearity of the trace, we can now see that  $X \mapsto \text{Tr}(X^{-1})$  is convex.

#### Fenchel Conjugate

• We have :

$$f^*(y) = \sup_{x} (^{\mathsf{t}} xy - ||x||) = \begin{cases} 0 & \text{if } ||y||_* \le 1\\ \infty & \text{otherwise} \end{cases}$$

To show this, let y such that  $||y||_* = \sup_{||x|| \le 1} ||^t xy|| \le 1$ . Then by Cauchy-Schwarz inequality, we know that  $^t xy \le ||x|| \, ||y||_* \le ||x||$  and the term in the supremum is always  $\le 0$ . If  $||y||_* > 1$  however, then there exists z such that  $||z|| \le 1$  such that  $^t zy > 1$ . Taking x = tz in the supremum, we know that  $f^*(y) \ge t (^t zy - ||z||)$  which goes to infinity with  $t \to \infty$ . Thus, the fenchel conjugate of a norm is the convex indicator of the unit ball of the dual norm.

• Let us denote the infimal convolution of g,h by  $g\square h$ . Then we will show that :

$$g\square h)^* = (g^* + h^*)$$

Note that:

$$(g\Box h)^{*}(\alpha) = \sup_{x,y} \left\{ {}^{\mathsf{t}}x\alpha - g(y) - h(x - y) \right\}$$

$$= \sup_{x_{1},x_{2}} \left\{ {}^{\mathsf{t}}(x_{1} + x_{2})\alpha - g(x_{1}) - h(x_{2}) \right\}$$

$$= \sup_{x_{1},x_{2}} \left\{ {}^{\mathsf{t}}x_{1}\alpha - g(x_{1}) \right\} + \sup_{x_{2}} \left\{ {}^{\mathsf{t}}x_{2}\alpha - h(x_{2}) \right\}$$

$$= g^{*} + h^{*}$$

Given  $g = \|\cdot\|_1$  and  $h = \frac{1}{2\alpha} \|\cdot\|_2^2$ . Let x = u + v. Then :

$$f(x) = \inf_{v} \left\{ g(x - v) + h(v) \right\}$$

Substituting the expressions, we get :

$$f(x) = \inf_{v} \left\{ \|x - v\|_{1} + \frac{1}{2\alpha} \|v\|_{2}^{2} \right\}$$
$$= \sum_{i=1}^{n} \inf_{v_{i}} \left\{ |x_{i} - v_{i}| + \frac{1}{2\alpha} v_{i}^{2} \right\}$$

We will now compute the infima independently. We have two cases:

- 1.  $v_i \leq x_i$ : Let  $\varphi(v_i) = x_i v_i + \frac{1}{2\alpha}v_i^2$ . We want to find a minimum for  $\varphi$ , which is found at  $v_i = \alpha$ . This solution is valid if  $\alpha \leq x_i$ .
- 2.  $v_i > x_i$ : Let  $\varphi(v_i = \frac{1}{2\alpha} + v_i x_i)$ . We want to find a minimum for  $\varphi$ , which is at  $v_i = -\alpha$ . This solution is valid if  $\alpha > x_i$ .

Then, we have three possible cases for the optimal  $v_i$ :

- 1. If  $x_i \geq \alpha$ ,  $v_i = \alpha$
- 2. If  $x_i \leq -\alpha$ ,  $v_i = -\alpha$
- 3. If  $-\alpha < x_i < \alpha$ ,  $v_i = x_i$ .

Plugging this into f:

$$f(x) = \sum_{i=1}^{n} \left( \begin{cases} \frac{1}{2\alpha} x_i^2 & |x_i| \le \alpha \\ |x_i - \alpha| - \frac{\alpha}{2} & |x_i| > \alpha \end{cases} \right)$$

Now, clearly,  $f = g \Box h$  is a convex function (as the infimum of two convex functions (if  $\alpha > 0$ )). Moreover, f is clearly lower semi-continuous from its expression. Now, we have  $f^{**} = f$  from the Fenchel-Moreau theorem (proved below):

**Théorème 1.1** The biconjugate of f is the largest lower semi-continuous convex function below than f.

Démonstration. Let  $x \in \mathbb{R}^n$ . For all y, the directional derivative :

$$\partial_y f(x) = \lim_{\mathrm{d}t \to 0} \frac{f(x + \mathrm{d}ty) - f(x)}{\mathrm{d}t}$$

is a sublinear as a function of y. From the Hahn-Banach theorem, there exists  $\tilde{\partial f} \in (\mathbb{R}^n)^* = \mathbb{R}^n$  such that :

$$\langle \tilde{\partial f}, \cdot \rangle \leq \partial_y f(x) \leq f(x+y) - f(x), \forall y \in \mathbb{R}^n$$

Then:

$$f(x) + f^* \left( \tilde{\partial f} \right) = \left\langle \tilde{\partial f}, x \right\rangle$$

which completes our proof that  $f^{**} = f$ .

• We want to compute:

$$\ell^*(y) = \sup_{z \in \mathbb{R}} \{yz - \ell(z)\} \text{ where } \ell : z \mapsto \log(1 + e^z)$$

We differentiate  $\varphi(z)$  the function in the supremum :

$$\varphi'(z) = y - \frac{1}{1 + e^{-z}}$$

Then, we find  $z = \log\left(\frac{y}{1-y}\right)$ , which only makes sense for  $y \in ]0,1[$ . Finally, we compute:

$$\ell^*(y) = y \log \left(\frac{y}{1-y}\right) + \log(1-y)$$
  
=  $-y \log(1-y) + y \log(y) + \log(1-y)$   
=  $(1-y) \log(1-y) + (y) \log(y)$ 

In the end,

$$(1-y)\log(1-y) + (y)\log(y)$$

#### Duality

• The Lagrangian of the problem associated with Ax = b is:

$$\mathcal{L}(x,\lambda) = \frac{1}{2} \left\| Ax - b \right\|_2^2 + \alpha \left\| x \right\|_1 - {}^{\mathsf{t}} \lambda \left( Ax - b \right) = \frac{1}{2} \left\| Ax - b \right\|_2^2 + \alpha \left\| x \right\|_1 - {}^{\mathsf{t}} \lambda Ax + {}^{\mathsf{t}} \lambda b$$

Then, by separating terms involving x:

$$\mathcal{L}(x,\lambda) = \frac{1}{2} \|b\|_{2}^{2} - \frac{1}{2} \|\lambda - b\|_{2}^{2} + {}^{t}\lambda b + \alpha \|x\|_{1} - ({}^{t}\lambda A) x$$

In solving  $\max_{\lambda} \min_{x} \mathcal{L}(x, \lambda)$ , the inner minimization on x only depends on  $||x||_1$  and  $({}^{\mathsf{t}}\lambda A) \, x$ . Minimizing it results in  $||{}^{\mathsf{t}}A\lambda||_{\infty} \leq \alpha$ . Finally, we get that :

$$\boxed{ \max_{\lambda \in \mathbb{R}^m} -\frac{1}{2} \left\|\lambda - b\right\|_2^2 + \frac{1}{2} \left\|b\right\|_2^2 - \inf_{\left\{\|\cdot\|_{\infty} \leq 1\right\}} \left(\frac{{}^{\mathsf{t}} A \lambda}{\alpha}\right) \text{ is a dual problem for the LASSO} }$$

• We start with:

$$\min_{w,w_1,\dots,w_m \in \mathbb{R}^n} \left\{ \frac{1}{n} \sum_{i=1}^m h_i\left(w_i\right) + \frac{\lambda}{2} \left\|w\right\|_2^2 \; \middle| \; w_i = w, \forall i \in \llbracket 1, m \rrbracket \right\}$$

Its Lagrangian is:

$$\mathcal{L}\left(w, w_{1}, \dots, w_{m}, v_{1}, \dots, v_{m}\right) = \frac{1}{n} \sum_{i=1}^{m} h_{i}\left(w_{i}\right) + \frac{\lambda}{2} \left\|w\right\|_{2}^{2} + \sum_{i=1}^{m} {}^{\mathsf{t}}v_{i}\left(w - w_{i}\right) = \frac{\lambda}{2} \left\|w\right\|_{2}^{2} + \sum_{i=1}^{m} {}^{\mathsf{t}}v_{i}w + \sum_{i=1}^{m} \frac{1}{n} h_{i}\left(w_{i}\right) - {}^{\mathsf{t}}v_{i}w_{i}$$

For the minimization step, we minimize for each of the  $w_i$  and for w. Let  $g_i(v_i)$  be the minimized value of  $\frac{1}{n}h_i(w_i) - {}^{\mathrm{t}}v_iw_i$ . For w, we want to minimize  $\frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^m {}^{\mathrm{t}}v_iw$ , which is quadratic in w. Computing its minimum we find  $\frac{-1}{2\lambda} \|\sum_{i=1}^m v_i\|_2^2$ . Finally, the dual problem is:

$$\left[ \max_{v_1, \dots, v_m} \sum_{i=1}^m g_i(v_i) - \frac{1}{2\lambda} \left\| \sum_{i=1}^m v_i \right\|_2^2 \right]$$

For logistic regression, we have:

$$h_i: w \mapsto \log\left(1 + \exp\left(-y_i^{\mathsf{t}} x_i w\right)\right)$$

Then we have:

$$g_{i}\left(v_{i}\right) = \min_{w_{i}} \left\{ \frac{1}{n} \log \left(1 + \exp\left(-y_{i}^{\mathsf{t}} x_{i} w_{i}\right)\right) - {}^{\mathsf{t}} v_{i} w_{i} \right\}$$

Since  $h_i$  is differentiable, we can compute its gradient :

$$\nabla h_i(w_i) = \frac{1}{n} \cdot \frac{-y_i x_i}{1 + \exp(y_i^{\mathsf{t}} x_i w_i)}$$

which gives us a minimality condition:

$$\frac{-y_i x_i}{1 + \exp\left(y_i^{\mathsf{t}} x_i w_i\right)} = n v_i$$

which rearranges to:

$$w_{i} = \frac{-y_{i} \log \left(\frac{-y_{i}^{t} v_{i} x_{i} - n \|v_{i}\|_{2}^{2}}{n \|v_{i}\|_{2}^{2}}\right)}{\|x_{i}\|_{2}^{2}} x_{i} = \frac{-y_{i} t}{\|x_{i}\|_{2}^{2}} x_{i}$$

Inputing this into  $y_i^{\mathsf{t}} x_i w_i$ :

$$y_i^{\mathsf{t}} x_i w_i = + \underbrace{y_i^2}_{-1} \underbrace{\frac{\mathbf{t}_{x_i x_i}}{\|x_i\|_2^2}}_{\mathbf{t}} t = t$$

Thus:

$$g_i(w_i) = \frac{1}{n} \log \left( -\frac{y_i^{\mathsf{t}} v_i x_i}{\|v_i\|_2^2} \right) - \frac{y_i^{\mathsf{t}} v_i w_i}{\|x_i\|_2^2} \log \left( -1 - \frac{y_i^{\mathsf{t}} v_i x_i}{\|v_i\|_2^2} \right)$$

Finally our dual problem is:

$$\left[ \max_{v_1, \dots, v_m} \sum_{i=1}^m \frac{1}{n} \log \left( -\frac{y_i^{\mathsf{t}} v_i x_i}{\|v_i\|_2^2} \right) - \frac{y_i^{\mathsf{t}} v_i w_i}{\|x_i\|_2^2} \log \left( -1 - \frac{y_i^{\mathsf{t}} v_i x_i}{\|v_i\|_2^2} \right) - \frac{1}{2\lambda} \left\| \sum_{i=1}^m v_i \right\|_2^2 \right]$$

and I will not be trying to find a closer form manually.

ullet We consider the problem :

$$\min_{X \in \mathbb{S}^n} \left\{ \operatorname{Tr} \left( A_0 X \right) \mid X \succeq 0, \operatorname{Tr} \left( A_1 X \right) = b_1, \dots, \operatorname{Tr} \left( A_m X \right) = b_m \right\}$$

Its Lagrangian is (for  $\lambda_i > 0, S \succeq 0$ ):

$$\mathcal{L}(X, \lambda_1, \dots, \lambda_m, S) = \operatorname{Tr}(A_0 X) + \sum_{i=1}^m \lambda_i \left( \operatorname{Tr}(A_i X) - b_i \right) + \operatorname{Tr}({}^{\mathsf{t}} S X) = \operatorname{Tr}\left( \left( A_0 + \sum_{i=1}^m \lambda_i A_i + S \right) X \right) - \sum_{i=1}^m \lambda_i b_i$$

Minimizing everything in X can be done since everything is differentiable in X:

$$\nabla \mathcal{L} = {}^{\mathsf{t}}A_0 + \sum_{i=1}^m \lambda_i {}^{\mathsf{t}}A_i + 2SX = A_0 + \sum_{i=1}^m \lambda_i A_i + S$$

which is 0 when:

$$S = -\left(A_0 + \sum_{i=1}^{m} \lambda_i A_i\right)$$

Finally we get the dual problem:

$$\left| \max_{\lambda_1, \dots, \lambda_m, S} \left\{ -\sum_{i=1}^m \lambda_i b_i \mid S \succeq 0, S = -A_0 - \sum_{i=1}^m \lambda_i A_i \right\} \right|$$

Strong duality holds only if the Karush-Kuhn-Tucker conditions are satisfied. Since  $\operatorname{Tr}(S_*X_*)$  is a rewriting of complementary slackness, clearly strong duality implies  $\operatorname{Tr}(S_*X_*) = 0$ . If we have  $\operatorname{Tr}(S_*X_*) = 0$  for the optimal solutions, in particular, both the primal and dual problems are attained and the relaxation term vanishes. Finally:

Strong Duality holds if and only if 
$$\operatorname{Tr}(X_*S_*) = 0$$

### 2 Problem

We consider the following problem:

$$\min_{w \in \mathbb{R}^n} \frac{1}{2} \|w\|_2^2 + \alpha \sum_{i=1}^m \max \left\{ 0, 1 - {}^{\mathsf{t}} w x_i y_i \right\}$$
 (1)

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#### 2.1 Dual problem.

Considering the constraints, we have :

$$s_i \geq 1 - y_i^{\mathsf{t}} w x_i \wedge s_i \geq 0$$

and thus, minimizing in s, for w fixed gives :

$$s_i = \max\left\{0, 1 - y_i^{\mathsf{t}} w x_i\right\}$$

which proves the equivalent reformulation:

$$\min_{w \in \mathbb{R}^n, s \in \mathbb{R}^m} \frac{1}{2} \|w\|_2^2 + \alpha \sum_{i=1}^m s_i$$
s. t.  ${}^{\mathsf{t}} w x_i y_i \ge 1 - s_i$ 

$$s_i \ge 0$$

Computing the dual problem needs two constraints :

$$\lambda_i \geq 0$$
 for  ${}^{\mathsf{t}} w X_i \geq 1 - s_i$  and  $\mu_i \geq 0$  for  $s_i \geq 0$ 

The Lagrangian is thus:

$$\mathcal{L}(w, s, \lambda, \mu) = \frac{1}{2} \|w\|_{2}^{2} + \alpha \sum_{i=1}^{m} s_{i} - \sum_{i=1}^{m} \lambda_{i} (^{\mathsf{t}} w X_{i} - 1 + s_{i}) - \sum_{i=1}^{m} \mu_{i} s_{i}$$

Then:

$$\frac{\partial \mathcal{L}}{\partial w} = w - \sum_{i=1}^{m} \lambda_i X_i = 0 \Rightarrow w = X\lambda$$
$$\frac{\partial \mathcal{L}}{\partial s_i} = \alpha - \lambda_i - \mu_i = 0 \Rightarrow \lambda_i \le \alpha$$

Finally, subtituting, the dual problem is:

$$\max_{0 \le \lambda \le \alpha} \mathcal{D}(\lambda) = -\frac{1}{2}^{\mathsf{t}} \lambda^{\mathsf{t}} X X \lambda + \sum_{i=1}^{m} \lambda_{i}$$

### 2.2 Algorithms

Everything in this section has been implemented using Python 3.12. Preamble :

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```
import functools

from random import randint
import numpy as np
import numpy.linalg as npl

def projection(lower, upper, value):
    return min(upper, max(value, lower))

def d(lam, X):
    return -(1/2) * lam.T.dot(X.T).dot(X).dot(lam) + sum(lam)

def gradientD(lam, X):
    return np.array([1 for _ in lam]) - X.T.dot(X).dot(lam)
```

• Implementation for Gradient Ascent

```
def gradient_ascent_dual_svm(dataset, alpha, iterations):
    :param alpha: parameter of the {\tt SVM} problem
    :param dataset: List of couples x_{i}:np.array, y_{i}:+-1 representing our classes
    :param iterations: Number of iterations to compute
    :return:
   proj = functools.partial(projection, lower=0.0, upper=alpha)
   X = np.zeros((n:=len(dataset[0][0]), m:=len(dataset)))
   for i in range(m):
       X[i] = dataset[i][0] * dataset[i][1]
   h = max(npl.eigvalsh(X))
   for _ in range(iterations):
        lam = map(proj, olam + h * gradientD(olam, X))
        while d(lam, X) > d(olam, X) + (1/(h * 2)) * (npl.norm(lam - olam) ** 2):
            h = h /2
            lam = map(proj, olam + h * gradientD(olam, X))
    return X.dot(lam)
```

• Implementaion for Randomized Coordinate Ascent

```
def randomized_coordinate_ascent(dataset, alpha, iterations):
    proj = functools.partial(projection, lower=0.0, upper=alpha)
    lam = np.zeros(m:= len(dataset))
    n = len(dataset[0][0])
    w = np.zeros(n)
    for _ in range(iterations):
        i = randint(0, m - 1)
        olam = lam[i]
        lam = lam.copy()
        lam[i] = proj(olam + (1 - (yi := dataset[i][1]) * (xi := dataset[i][0]).T.dot(w))/(npl.norm(xi)**2))
        w = w + yi * xi.dot(lam[i] - olam)
    return w
```

Let us prove the algorithm leads to optimization, by optimizing on one dimension at a time. At each iteration, only one dimension  $\lambda_{i_k}$  is modified, and the rest remain the same. Since the part of  $D(\lambda)$  dependent on  $\lambda_{i_k}$  is

$$-\frac{1}{2} \|x_{i_k}\|^2 \lambda_{i_k}^2 + \left(1 - y_{i_k}^{\ t} x_{i_k} w\right) \lambda_{i_k}$$

then taking

$$\lambda_{i_k}^{(k+1)} = \lambda_{i_k}^{(k)} + \frac{(1 - y_{i_k}^{\ t} x_{i_k} w)}{\|x_{i_k}\|_2^2}$$

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maximizes the above quadratic term and the projection ensures the solution is feasible, leading to an exact maximization along  $\lambda_{i_k}$  by the properties of quadratic forms.