Homework 1

Convex Optimization

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1 Exercises

Convex Sets

- Let $C = \{x \in \mathbb{R}^2_+ \mid x_1 x_2 \ge 1\}$. We can see that $C = \{(x_1, x_2) \in \mathbb{R}^2_{+*} \mid x_1 \ge \frac{1}{x_2}\}$. Thus, C is the epigraph of $x \mapsto \frac{1}{x}$ which is convex since its second derivative is $x \mapsto \frac{2x}{x^4}$. Thus, C is convex.
- In general, this set is not convex. Indeed, for sets in \mathbb{R} , take $S = \{-1, 1\}, T = \{0\}$. Then the set of points closer to S than to T is $\{x \in \mathbb{R} \mid x \le -0.5 \lor x \ge 0.5\}$ which is not an interval and thus not convex.
- Let us take $x_1, x_2 \in \{x \mid x + S_2 \subseteq S_1\}$. For $x = \lambda x_1 + (1 \lambda) x_2$ consider x + y for $y \in S_2$:

$$x + y = \lambda x_1 + (1 - \lambda) x_2 + y = \lambda (x_1 + y) + (1 - \lambda x_2 + y)$$

Since $x_i + S_2 \subseteq S_1$ for i = 1, 2, and since S_1 is convex, for all $y \in S_2$ the above sum is in S_1 and thus $x + S_2 \subseteq S_2$. Finally, our set is convex.

• Let $x_1, x_2 \in \{x \mid \exists y \in S_2, x + y \in S_1\}$. Then let y_1, y_2 be associated points to x_1, x_2 . For $x = \lambda x_1 + (1 - \lambda) x_2$ and $y = \lambda y_1 + (1 - \lambda) y_2$. Then, since S_2 is convex, $y \in S_2$. Moreover:

$$x + y = \lambda \underbrace{(x_1 + y_1)}_{\in S_1} + (1 - \lambda) \underbrace{(x_2 + y_2)}_{\in S_1}$$

$$\underbrace{(x_1 + y_1)}_{\in S_1 \text{ since } S_1 \text{ is convex}}$$

Then, our set is convex.

Convex Functions

- The hessian of f at (x, y) is the matrix $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$. On \mathbb{R}^2 this matrix is not positive nor negative and thus the function is neither convex, or concave. However, the sub-level sets for α are convex if and only if $\alpha \geq 0$ (from our first example) and thus the function is neither quasi-concave nor quasi-convex.
- On \mathbb{R}^2_{+*} , the hessian of the function is positive semidefinite and thus the function is convex.
- The hessian matrix of f is the matrix $\begin{pmatrix} 0 & -\frac{1}{x_2^2} \\ -\frac{1}{x_2^2} & \frac{2x_1}{x_2^3} \end{pmatrix}$ Since its determinant is < 0 the Hessian is not positive semi-definite and the function is not convex. Moreover, since its determinant is < 0 and the hessian is symmetric real, it must have a strictly positive eigenvalue, and thus it is not concave. However, its sublevel sets are defined by the equations $x_1 \le \alpha x_2$ and are thus convex (since half-planes). Similarly the sub-level sets are concave. Thus, f is quasi-convex and quasi-concave.

Let us define the Löwner order ≤ as the partial order defined by the convex cone of positive semi-definite matrices.
 We know that :

$$A \leq B \Rightarrow B^{-1} \leq A^{-1}, \forall A, B \in S_{++}^n$$

From this, we know that for all $t \leq 1$:

$$((1-t)X+tY)^{-1} \leq (1-t)X^{-1}+tY^{-1}$$

By linearity of the trace, we can now see that $X \mapsto \operatorname{Tr}(X^{-1})$ is convex.

Fenchel Conjugate

• We have :

$$f^*(y) = \sup_{x} (^{\mathsf{t}} xy - ||x||) = \begin{cases} 0 & \text{if } ||y||_* \le 1\\ \infty & \text{otherwise} \end{cases}$$

To show this, let y such that $||y||_* = \sup_{||x|| \le 1} ||^t xy|| \le 1$. Then by Cauchy-Schwarz inequality, we know that $^t xy \le ||x|| \, ||y||_* \le ||x||$ and the term in the supremum is always ≤ 0 . If $||y||_* > 1$ however, then there exists z such that $||z|| \le 1$ such that $^t zy > 1$. Taking x = tz in the supremum, we know that $f^*(y) \ge t (^t zy - ||z||)$ which goes to infinity with $t \to \infty$. Thus, the fenchel conjugate of a norm is the convex indicator of the unit ball of the dual norm.

For the case of the square of the ℓ^2 norm, we want to compute :

$$f^*(y) = \sup_{x} {}^{\mathsf{t}} yx - {}^{\mathsf{t}} xx = {}^{\mathsf{t}} (s - x) x$$

Fenchel-Young's theorem gives us:

$$f^*(y) = {}^{\mathsf{t}} yx - f(x) \Leftrightarrow y \in \partial f(x) \Leftrightarrow y = 2x$$

Thus:

$$f^*\left(y\right) = \frac{1}{4} t y y$$

• Let us denote the infimal convolution of g, h by $g \square h$. Then we will show that :

$$g\Box h)^* = (g^* + h^*)$$

Note that:

$$(g\Box h)^* (\alpha) = \sup_{x,y} \left\{ {}^{\mathsf{t}}x\alpha - g(y) - h(x - y) \right\}$$

$$= \sup_{x_1,x_2} \left\{ {}^{\mathsf{t}}(x_1 + x_2)\alpha - g(x_1) - h(x_2) \right\}$$

$$= \sup_{x_1,x_2} \left\{ {}^{\mathsf{t}}x_1\alpha - g(x_1) \right\} + \sup_{x_2} \left\{ {}^{\mathsf{t}}x_2\alpha - h(x_2) \right\}$$

$$= g^* + h^*$$

Given $g = \|\cdot\|_1$ and $h = \frac{1}{2\alpha} \|\cdot\|_2^2$. Let x = u + v. Then:

$$f(x) = \inf_{v} \left\{ g(x - v) + h(v) \right\}$$

Substituting the expressions, we get:

$$f(x) = \inf_{v} \left\{ \|x - v\|_{1} + \frac{1}{2\alpha} \|v\|_{2}^{2} \right\}$$
$$= \sum_{i=1}^{n} \inf_{v_{i}} \left\{ |x_{i} - v_{i}| + \frac{1}{2\alpha} v_{i}^{2} \right\}$$

We will now compute the infima independently. We have two cases:

- 1. $v_i \leq x_i$: Let $\varphi(v_i) = x_i v_i + \frac{1}{2\alpha}v_i^2$. We want to find a minimum for φ , which is found at $v_i = \alpha$. This solution is valid if $\alpha \leq x_i$.
- 2. $v_i > x_i$: Let $\varphi(v_i = \frac{1}{2\alpha} + v_i x_i)$. We want to find a minimum for φ , which is at $v_i = -\alpha$. This solution is valid if $\alpha > x_i$.

Then, we have three possible cases for the optimal v_i :

- 1. If $x_i \geq \alpha$, $v_i = \alpha$
- 2. If $x_i \leq -\alpha$, $v_i = -\alpha$
- 3. If $-\alpha < x_i < \alpha$, $v_i = x_i$.

Plugging this into f:

$$f(x) = \sum_{i=1}^{n} \left(\begin{cases} \frac{1}{2\alpha} x_i^2 & |x_i| \le \alpha \\ |x_i - \alpha| - \frac{\alpha}{2} & |x_i| > \alpha \end{cases} \right)$$

Now, clearly, $f = g \Box h$ is a convex function (as the infimum of two convex functions (if $\alpha > 0$)). Moreover, f is clearly lower semi-continuous from its expression. Now, we have $f^{**} = f$ from the Fenchel-Moreau theorem (proved below):

Théorème 1.1 The biconjugate of f is the largest lower semi-continuous convex function below than f.

Démonstration. Let $x \in \mathbb{R}^n$. For all y, the directional derivative :

$$\partial_y f(x) = \lim_{dt \to 0} \frac{f(x + dty) - f(x)}{dt}$$

is a sublinear as a function of y. From the Hahn-Banach theorem, there exists $\tilde{\partial f} \in (\mathbb{R}^n)^* = \mathbb{R}^n$ such that :

$$\langle \tilde{\partial f}, \cdot \rangle \leq \partial_u f(x) \leq f(x+y) - f(x), \forall y \in \mathbb{R}^n$$

Then:

$$f(x) + f^*(\tilde{\partial f}) = \langle \tilde{\partial f}, x \rangle$$

which completes our proof that $f^{**} = f$.

• We want to compute:

$$\ell^*(y) = \sup_{z \in \mathbb{R}} \{yz - \ell(z)\} \text{ where } \ell : z \mapsto \log(1 + e^z)$$

We differentiate $\varphi(z)$ the function in the supremum :

$$\varphi'(z) = y - \frac{1}{1 + e^{-z}}$$

Then, we find $z = \log\left(\frac{y}{1-y}\right)$, which only makes sense for $y \in]0,1[$. Finally, we compute :

$$\ell^*(y) = y \log\left(\frac{y}{1-y}\right) + \log(1-y)$$

= $-y \log(1-y) + y \log(y) + \log(1-y)$
= $(1-y) \log(1-y) + (y) \log(y)$

In the end,

$$(1-y)\log(1-y) + (y)\log(y)$$

Duality

• The Lagrangian of the problem is :

$$\mathcal{L}(x,\lambda) = \frac{1}{2} \left\| Ax - b \right\|_2^2 + \alpha \left\| x \right\|_1 - {}^{\mathsf{t}} \lambda \left(Ax - b \right) = \frac{1}{2} \left\| Ax - b \right\|_2^2 + \alpha \left\| x \right\|_1 - {}^{\mathsf{t}} \lambda Ax + {}^{\mathsf{t}} \lambda b$$

Then, by separating terms involving x:

$$\mathcal{L}(x,\lambda) = \frac{1}{2} \|b\|_{2}^{2} - \frac{1}{2} \|\lambda - b\|_{2}^{2} + {}^{t}\lambda b + \alpha \|x\|_{1} - ({}^{t}\lambda A) x$$

In solving $\max_{\lambda} \min_{x} \mathcal{L}(x, \lambda)$, the inner minimization on x only depends on $||x||_1$ and $({}^{\mathsf{t}}\lambda A) \, x$. Minimizing it results in $||{}^{\mathsf{t}}A\lambda||_{\infty} \leq \alpha$. Finally, we get that :

$$\boxed{\max_{\lambda \in \mathbb{R}^m} -\frac{1}{2} \left\|\lambda - b\right\|_2^2 + \frac{1}{2} \left\|b\right\|_2^2 - \inf_{\left\{\|\cdot\|_{\infty} \leq 1\right\}} \left(\frac{{}^{\mathsf{t}}A\lambda}{\alpha}\right) \text{ is a dual problem for the LASSO}}$$

• We start with:

$$\min_{w,w_{1},...,w_{m}\in\mathbb{R}^{n}}\left\{\frac{1}{n}\sum_{i=1}^{m}h_{i}\left(w_{i}\right)+\frac{\lambda}{2}\left\Vert w\right\Vert _{2}^{2}\;\middle\vert\;w_{i}=w,\forall i\in\llbracket1,m\rrbracket\right\}$$

Its Lagrangian is:

$$\mathcal{L}(w, w_1, \dots, w_m, v_1, \dots, v_m) = \frac{1}{n} \sum_{i=1}^{m} h_i(w_i) + \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} {}^{\mathsf{t}}v_i(w - w_i) = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} {}^{\mathsf{t}}v_iw + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} {}^{\mathsf{t}}v_iw + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} {}^{\mathsf{t}}v_iw + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} {}^{\mathsf{t}}v_iw + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} {}^{\mathsf{t}}v_iw + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} {}^{\mathsf{t}}v_iw + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} {}^{\mathsf{t}}v_iw + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} {}^{\mathsf{t}}v_iw + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} {}^{\mathsf{t}}v_iw + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} {}^{\mathsf{t}}v_iw + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} {}^{\mathsf{t}}v_iw + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} \frac{1}{n} h_i(w_i) - {}^{\mathsf{t}}v_iw = \frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^{m} \frac{1}{n} \|w\|_2^2 + \sum_{i=1}^{m} \frac{1}{n} \|w\|_2^2 + \sum_{i=1}^{m} \frac{1}{n} \|w\|_2^2 + \sum_{i=1}^{m}$$

For the minimization step, we minimize for each of the w_i and for w. Let $g_i(v_i)$ be the minimized value of $\frac{1}{n}h_i(w_i) - {}^{\mathrm{t}}v_iw_i$. For w, we want to minimize $\frac{\lambda}{2} \|w\|_2^2 + \sum_{i=1}^m {}^{\mathrm{t}}v_iw$, which is quadratic in w. Computing its minimum we find $\frac{-1}{2\lambda} \|\sum_{i=1}^m v_i\|_2^2$. Finally, the dual problem is:

$$\left\| \max_{v_1, \dots, v_m} \sum_{i=1}^m g_i(v_i) - \frac{1}{2\lambda} \left\| \sum_{i=1}^m v_i \right\|_2^2 \right\|$$

For logistic regression, we have:

$$h_i: w \mapsto \log\left(1 + \exp\left(-y_i^{\mathsf{t}} x_i w\right)\right)$$

Then we have:

$$g_{i}\left(v_{i}\right) = \min_{w_{i}} \left\{ \frac{1}{n} \log \left(1 + \exp\left(-y_{i}^{\mathsf{t}} x_{i} w_{i}\right)\right) - {}^{\mathsf{t}} v_{i} w_{i} \right\}$$

Since h_i is differentiable, we can compute its gradient :

$$\nabla h_i(w_i) = \frac{1}{n} \cdot \frac{-y_i x_i}{1 + \exp(y_i^{\mathsf{t}} x_i w_i)}$$

which gives us a minimality condition:

$$\frac{-y_i x_i}{1 + \exp\left(y_i^{\mathsf{t}} x_i w_i\right)} = n v_i$$

which rearranges to:

$$w_{i} = \frac{-y_{i} \log \left(\frac{-y_{i}^{\dagger} v_{i} x_{i} - n \|v_{i}\|_{2}^{2}}{n \|v_{i}\|_{2}^{2}}\right)}{\|x_{i}\|_{2}^{2}} x_{i} = \frac{-y_{i} t}{\|x_{i}\|_{2}^{2}} x_{i}$$

Inputing this into $y_i^{\mathsf{t}} x_i w_i$:

$$y_i^{\mathsf{t}} x_i w_i = + \underbrace{y_i^2}_{\mathsf{t}} \underbrace{\frac{=1}{\mathsf{t} x_i x_i}}_{||x_i||_2^2} t = t$$

Thus:

$$g_i(w_i) = \frac{1}{n} \log \left(-\frac{y_i^{\mathsf{t}} v_i x_i}{\|v_i\|_2^2} \right) - \frac{y_i^{\mathsf{t}} v_i w_i}{\|x_i\|_2^2} \log \left(-1 - \frac{y_i^{\mathsf{t}} v_i x_i}{\|v_i\|_2^2} \right)$$

Finally our dual problem is:

$$\left[\max_{v_1, \dots, v_m} \sum_{i=1}^m \frac{1}{n} \log \left(-\frac{y_i^\mathsf{t} v_i x_i}{\|v_i\|_2^2} \right) - \frac{y_i^\mathsf{t} v_i w_i}{\|x_i\|_2^2} \log \left(-1 - \frac{y_i^\mathsf{t} v_i x_i}{\|v_i\|_2^2} \right) - \frac{1}{2\lambda} \left\| \sum_{i=1}^m v_i \right\|_2^2 \right]$$

and I will not be trying to find a closer form manually.

• We consider the problem :

$$\min_{X \in \mathbb{S}^n} \left\{ \operatorname{Tr} \left(A_0 X \right) \mid X \succeq 0, \operatorname{Tr} \left(A_1 X \right) = b_1, \dots, \operatorname{Tr} \left(A_m X \right) = b_m \right\}$$

Its Lagrangian is (for $\lambda_i > 0, S \succeq 0$):

$$\mathcal{L}(X, \lambda_1, \dots, \lambda_m, S) = \operatorname{Tr}(A_0 X) + \sum_{i=1}^m \lambda_i \left(\operatorname{Tr}(A_i X) - b_i \right) + \operatorname{Tr}({}^{\mathsf{t}} S X) = \operatorname{Tr}\left(\left(A_0 + \sum_{i=1}^m \lambda_i A_i + S \right) X \right) - \sum_{i=1}^m \lambda_i b_i$$

Minimizing everything in X can be done since everything is differentiable in X:

$$\nabla \mathcal{L} = {}^{\mathsf{t}}A_0 + \sum_{i=1}^m \lambda_i {}^{\mathsf{t}}A_i + 2SX = A_0 + \sum_{i=1}^m \lambda_i A_i + S$$

which is 0 when:

$$S = -\left(A_0 + \sum_{i=1}^{m} \lambda_i A_i\right)$$

Finally we get the dual problem:

$$\left| \max_{\lambda_1, \dots, \lambda_m, S} \left\{ -\sum_{i=1}^m \lambda_i b_i \mid S \succeq 0, S = -A_0 - \sum_{i=1}^m \lambda_i A_i \right\} \right|$$

Strong duality holds only if the Karush-Kuhn-Tucker conditions are satisfied. Since $\operatorname{Tr}(S_*X_*)$ is a rewriting of

complementary slackness, clearly strong duality implies $\operatorname{Tr}(S_*X_*) = 0$. If we have $\operatorname{Tr}(S_*X_*) = 0$ for the optimal solutions, in particular, both the primal and dual problems are attained and the relaxation term vanishes. Finally:

Strong Duality holds if and only if
$$\mathrm{Tr}\left(X_{*}S_{*}\right)=0$$

2 Problem

We consider the following problem:

$$\min_{w \in \mathbb{R}^n} \frac{1}{2} \|w\|_2^2 + \alpha \sum_{i=1}^m \max \left\{ 0, 1 - {}^{\mathsf{t}} w x_i y_i \right\}$$
 (1)

2.1 Dual problem.

Considering the constraints, we have:

$$s_i \ge 1 - y_i^{\mathsf{t}} w x_i \wedge s_i \ge 0$$

and thus, minimizing in s, for w fixed gives :

$$s_i = \max\left\{0, 1 - y_i^{\mathsf{t}} w x_i\right\}$$

which proves the equivalent reformulation:

$$\min_{w \in \mathbb{R}^n, s \in \mathbb{R}^m} \frac{1}{2} \|w\|_2^2 + \alpha \sum_{i=1}^m s_i$$
s. t. $^t w x_i y_i \ge 1 - s_i$

$$s_i \ge 0$$

Computing the dual problem needs two constraints:

$$\lambda_i \geq 0$$
 for ${}^{\mathsf{t}}wX_i \geq 1 - s_i$ and $\mu_i \geq 0$ for $s_i \geq 0$

The Lagrangian is thus:

$$\mathcal{L}(w, s, \lambda, \mu) = \frac{1}{2} \|w\|_{2}^{2} + \alpha \sum_{i=1}^{m} s_{i} - \sum_{i=1}^{m} \lambda_{i} (^{t}wX_{i} - 1 + s_{i}) - \sum_{i=1}^{m} \mu_{i}s_{i}$$

Then:

$$\frac{\partial \mathcal{L}}{\partial w} = w - \sum_{i=1}^{m} \lambda_i X_i = 0 \Rightarrow w = X\lambda$$
$$\frac{\partial \mathcal{L}}{\partial s_i} = \alpha - \lambda_i - \mu_i = 0 \Rightarrow \lambda_i \le \alpha$$

Finally, subtituting, the dual problem is:

$$\max_{0 \le \lambda \le \alpha} \mathcal{D}(\lambda) = -\frac{1}{2}^{\mathsf{t}} \lambda^{\mathsf{t}} X X \lambda + \sum_{i=1}^{m} \lambda_{i}$$

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2.2 Algorithms

Everything in this section has been implemented using Python 3.12. Preamble:

```
import functools

from random import randint
import numpy as np
import numpy linalg as npl

def projection(lower, upper, value):
    return min(upper, max(value, lower))

def d(lam, X):
    return -(1/2) * lam.T.dot(X.T).dot(X).dot(lam) + sum(lam)

def gradientD(lam, X):
    return np.array([1 for _ in lam]) - X.T.dot(X).dot(lam)
```

• Implementation for Gradient Ascent

```
def gradient_ascent_dual_svm(dataset, alpha, iterations):
    :param alpha: parameter of the SVM problem
    :param dataset: List of couples x_{i}:np.array, y_{i}:+-1 representing our classes
    :param iterations: Number of iterations to compute
    :return:
   proj = functools.partial(projection, lower=0.0, upper=alpha)
   X = np.zeros((n:=len(dataset[0][0]), m:=len(dataset)))
   for i in range(m):
       X[i] = dataset[i][0] * dataset[i][1]
   lam = 0
   h = max(npl.eigvalsh(X))
   for _ in range(iterations):
        olam = lam
        lam = map(proj, olam + h * gradientD(olam, X))
        while d(lam, X) > d(olam, X) + (1/(h * 2)) * (npl.norm(lam - olam) ** 2):
            h = h /2
            lam = map(proj, olam + h * gradientD(olam, X))
    return X.dot(lam)
```

• Implemenation for Randomized Coordinate Ascent

```
def randomized_coordinate_ascent(dataset, alpha, iterations):
    proj = functools.partial(projection, lower=0.0, upper=alpha)
    lam = np.zeros(m:= len(dataset))
    n = len(dataset[0][0])
    w = np.zeros(n)
    for _ in range(iterations):
        i = randint(0, m - 1)
        olam = lam[i]
        lam = lam.copy()
        lam[i] = proj(olam + (1 - (yi := dataset[i][1]) * (xi := dataset[i][0]).T.dot(w))/(npl.norm(xi)**2))
        w = w + yi * xi.dot(lam[i] - olam)
    return w
```

Let us prove the algorithm leads to optimization, by optimizing on one dimension at a time. At each iteration, only one dimension λ_{i_k} is modified, and the rest remain the same. Since the part of $D(\lambda)$ dependent on λ_{i_k} is

$$-\frac{1}{2} \|x_{i_k}\|^2 \lambda_{i_k}^2 + \left(1 - y_{i_k}^{\ t} x_{i_k} w\right) \lambda_{i_k}$$

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then taking

$$\lambda_{i_k}^{(k+1)} = \lambda_{i_k}^{(k)} + \frac{(1 - y_{i_k}^{t} x_{i_k} w)}{\|x_{i_k}\|_2^2}$$

maximizes the above quadratic term and the projection ensures the solution is feasible, leading to an exact maximization along λ_{i_k} by the properties of quadratic forms.