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# **Neural Networks Trained to Solve Differential Equations** Learn General Representations

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#### Overview

- In machine vision, CNN layers can be visualized as the features they learn to identify.
- Neural networks can learn the solutions to differential equations.
- Question: Do the layers in these networks encode useful information about the solution?
- **Answer:** Yes! For instance, the first layer identifies important regions of the input domain.
- **Bonus:** The same representations are learned reliably, even when the equations are modified.

### Family of problems

Used 4-layer fully-connected tanh neural networks to solve the **boundary value problem (BVP)** 

$$\nabla^2 u(x,y) = s(x,y) \quad \text{for} \quad (x,y) \in \Omega,$$

$$u(x,y) = 0 \quad \text{for} \quad (x,y) \in \partial\Omega,$$

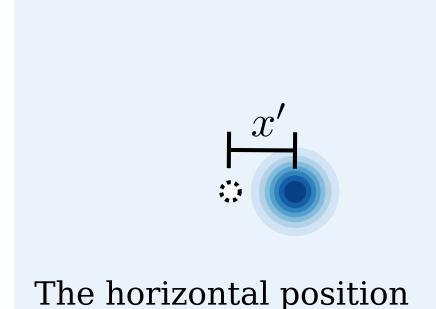
$$s(x,y) = -\frac{\exp\left(-\frac{(x-x')^2 + (y-y')^2}{2r^2}\right)}{2\pi r^2},$$

where  $\Omega$  is a square domain.

This models the **electric potential** of a localized charge distribution on a square with grounded edges.

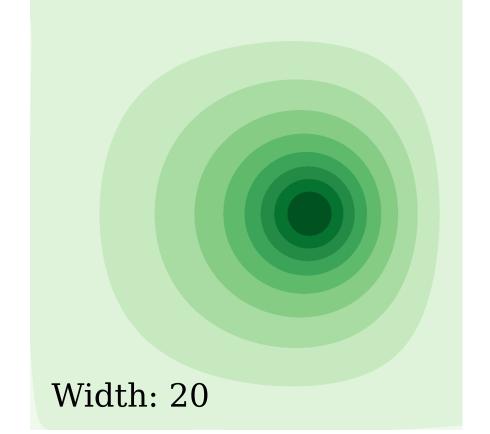
#### Charge distribution

Electric potential



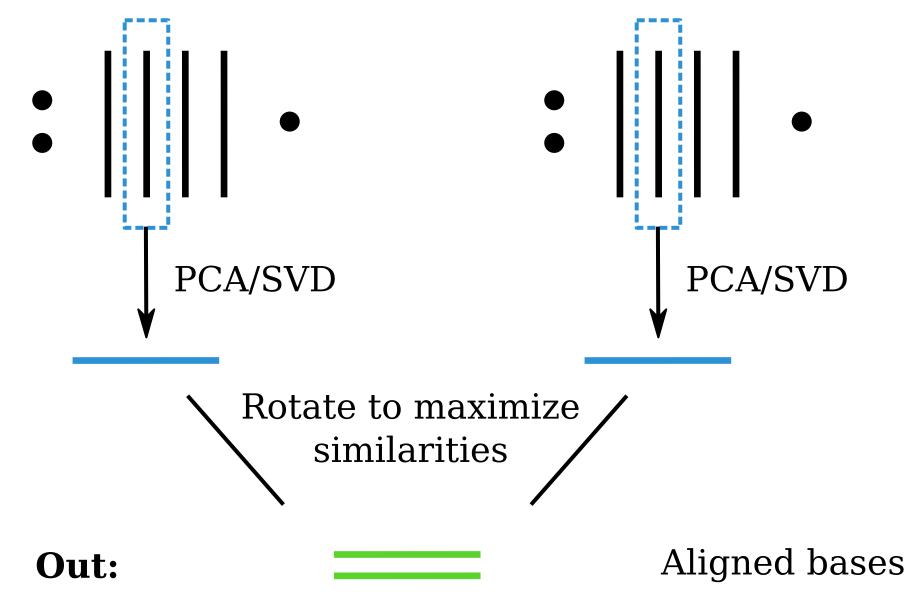
of the source was varied

from 0 to 0.6.



### Layer-wise SVCCA

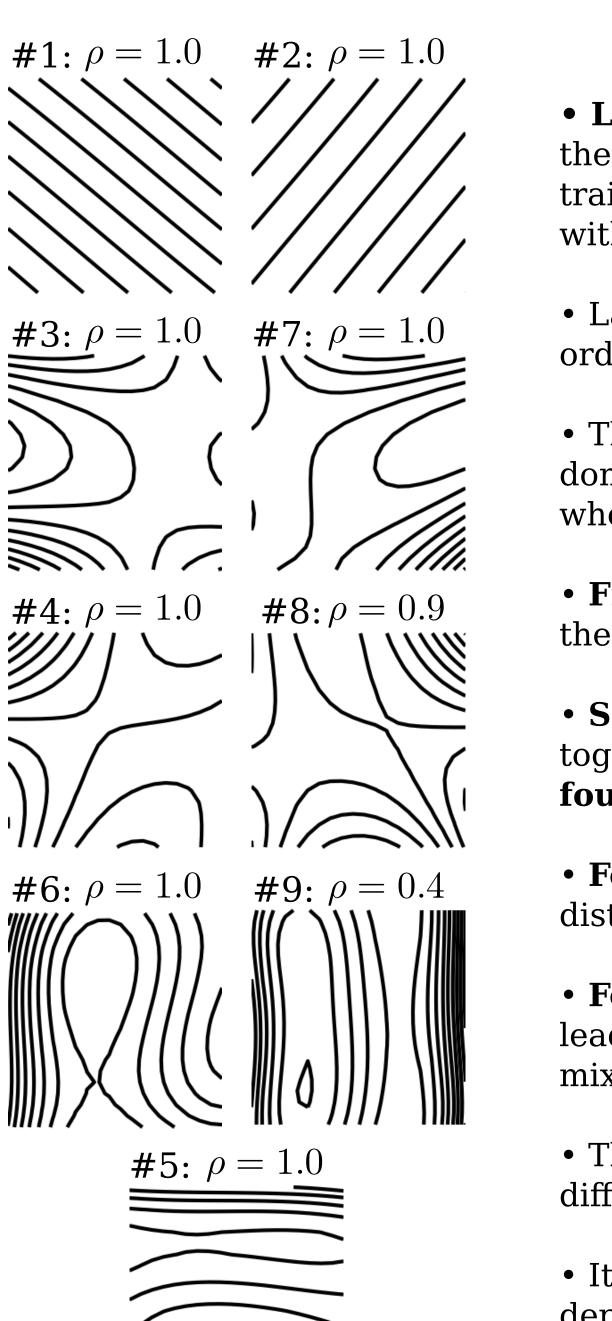
**In:** activation vectors of each layer.



#### Interpreting the networks

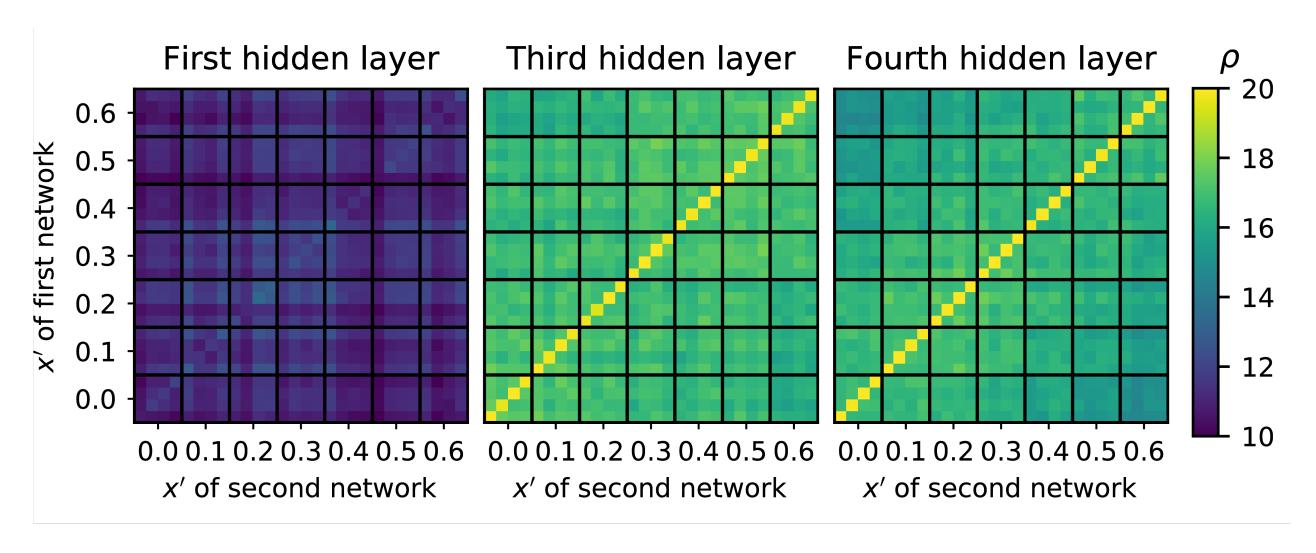
- **Inputs:** coordinates of a point (x,y).
- **Output:** estimated potential u(x,y).
- Loss: MSE of BVP equations.
- **Left:** Activation vectors of each neuron in a network trained at x'=0.3, shown as functions over the input domain.
- Note that it is difficult to interpret the activation vectors directly.
  - **Right:** The same network after layer-wise SVCCA with a second network trained at x'=0.6.
  - Components are sorted from top to bottom by similarity scores.
- The components in the **first layer** accentuate the input regions that are important to both networks simultaneously.
- The fourth component, for instance, highlights the top-left and bottom-right corners.
- The functions in the **last layer** form a basis that represents both outputs efficiently.
- In all layers, higher-order components become more multimodal, like Fourier modes.

## The first layer learns coordinates



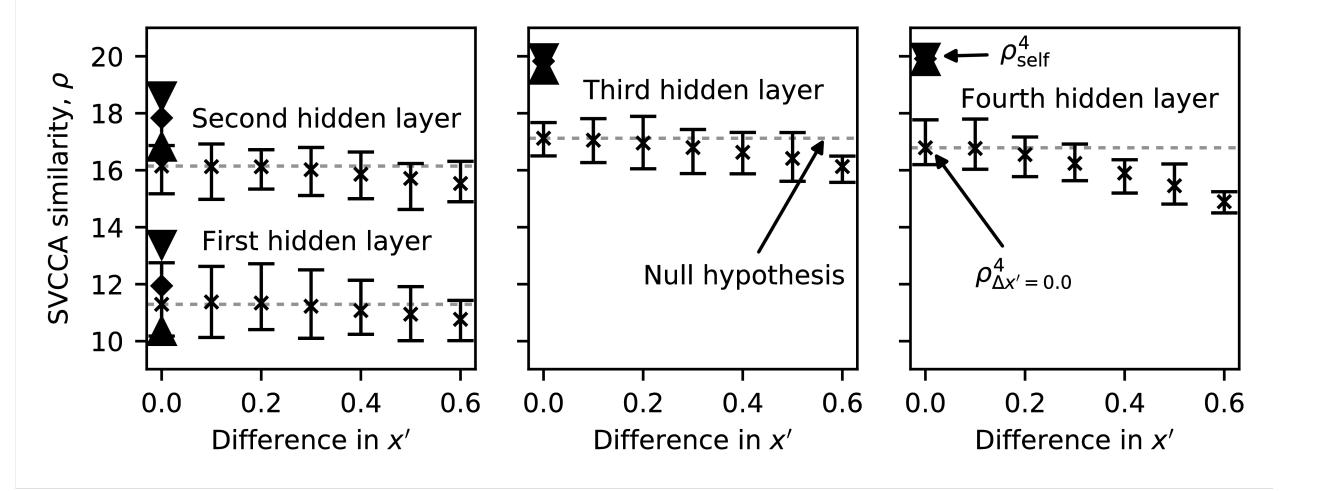
- **Left:** The nine leading components in the first layer of a network of width 192 trained at x'=0.6 after layer-wise SVCCA with itself.
- Labels show similarity values and their order when sorted by similarity.
- They act as coordinates over the input domain. The contour lines are densest where each coordinate is most sensitive.
- **First row:** These are simply rotations of the two **original coordinates**, x and y.
- Second and third rows: These four, together, show position relative to the four corners of the domain.
- Fourth and fifth rows: These capture distance to the **four walls** of the domain.
- For all sufficiently wide networks, the leading components of the first layer are mixtures of these features.
- This result is **reproducible** across different random initializations.
- It is also **general**, in that it does not depend on the x' of the two networks used for layer-wise SVCCA.

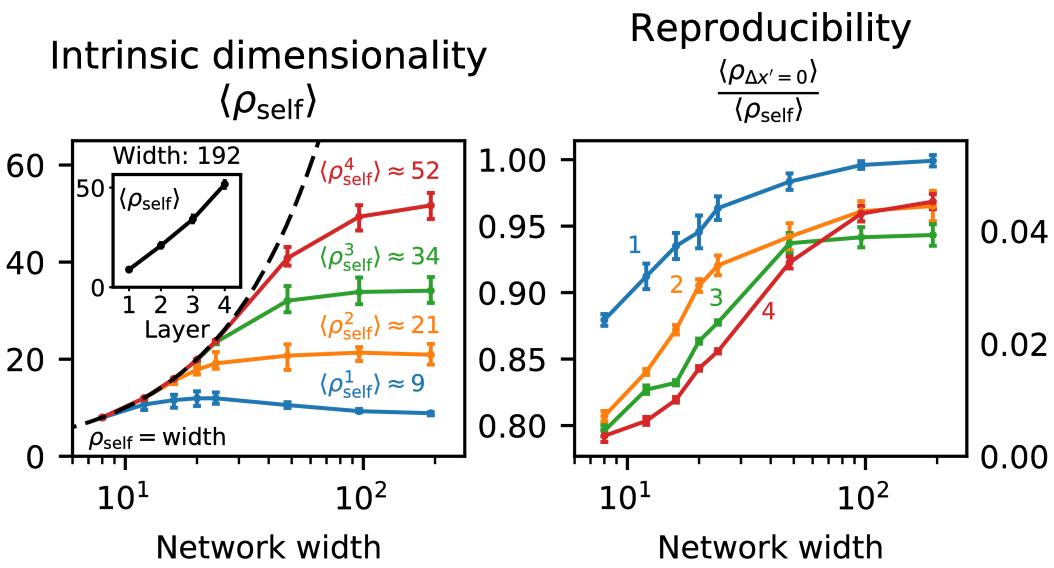
# Quantifying layer specificity versus generality

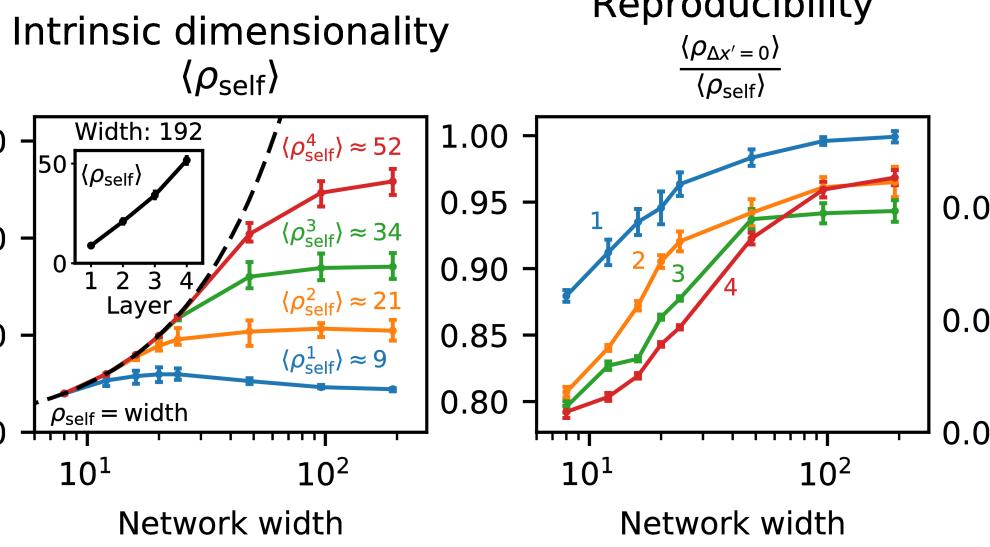


• **Above:** Matrices of  $\rho$ , the sum of the SVCCA similarities, computed layerwise between networks trained from different random seeds (between black lines) and at different x' values.

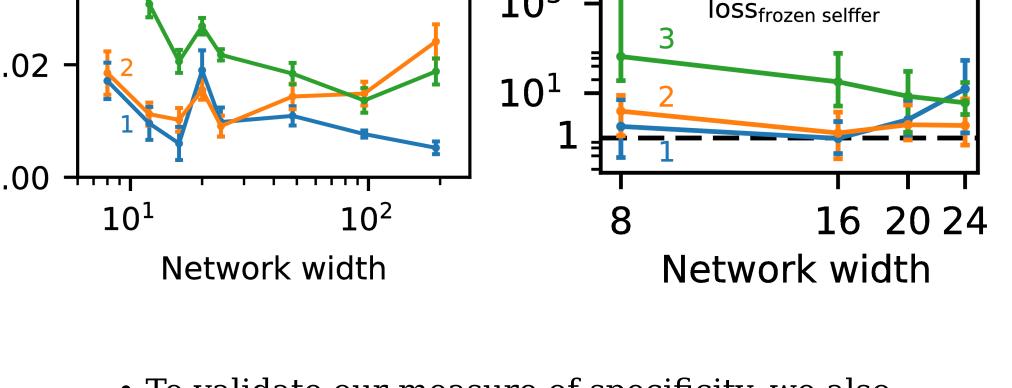
• **Below:** From the matrices, we extract the self-similarity  $ho_{\rm self}$ , the similarity  $\rho_{\Delta x'=0}$  across random seeds at fixed x', and the similarity as a function of x',  $\rho_{\Lambda x'}$ .







- The intrinsic dimensionality converges at high widths, as layers converge to finite-dimensional representations.
- Wide layers also have very high **reproducibility** across different random initializations.
- The fourth layer has high specificity, as its functional behaviour changes significantly when x' varies.
- The first layer has low specificity, because it learns a **general representation** that works well for all x'.
- The second layer is also quite general, but the third layer transitions from specific in narrow networks to general in wide networks.



- To validate our measure of specificity, we also measured specificity using an existing approach based on transfer learning tests (Yosinski et al. 2014, Adv Neural Inf Process Syst. 3320-3328).
- We found good agreement between the measures, and our method was orders of magnitude faster.



Specificity

 $\sum_{\Delta x'} |\langle \rho_{\Delta x'=0} \rangle - \langle \rho_{\Delta x'} \rangle|$ 

 $N_{\Delta x'} \langle \rho_{\Delta x'=0} \rangle$ 





Transfer specificity

