

Elastic Full Procrustes Means for Sparse and Irregular Planar Curves

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Motivation

Calculate **shape means** for **2D curves**:

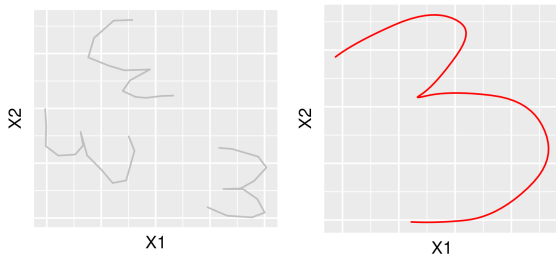


Figure: digits3.dat from the `shapes` package (Dryden 2019) with estimated elastic full Procrustes mean. Data: Anderson (1997)

Challenges:

Sparse and irregular, warping, translation/scaling/rotation

Outline

1. What is an Elastic Full Procrustes Mean?
2. Estimation Strategy
3. Results (so far), Problems, Outlook

Sparse and Irregular Planar Curves

How can we compare observations $\beta_i = (\beta_{i1}, \beta_{i2}, \dots, \beta_{im_i})$?

→ Treat β_i as **functional** data $\beta_i(t)$: $\beta_i : [0, 1] \rightarrow \mathbb{R}^2$

$\beta_i(t)$ sampled at $t_i = (t_{i1}, \dots, t_{im_i})$:

$$\beta_{i1} = \beta_i(t_{i1}), \dots, \beta_{im} = \beta_i(t_{im_i})$$

How to construct $(t_{i1}, \dots, t_{im_i})$?

- ▶ simple: arc-length
- ▶ better: same values of t relate to same "part" of curve

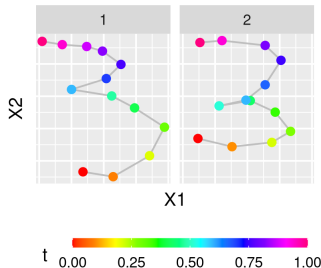


Figure: digits3.dat with arc-length parametrisation

Elastic Mean and Warping

Problem: Need to find an optimal re-parametrization (**warping**).

Well known problem in functional data analysis:

- ▶ Perform **warping alignment** on SRV curves

Square-Root-Velocity (SRV) Framework (Srivasta et al. 2011)

$$q : [0, 1] \rightarrow \mathbb{R}^2, \quad q(t) = \frac{\dot{\beta}(t)}{\sqrt{\|\dot{\beta}(t)\|}} \quad \text{for } \|\dot{\beta}(t)\| \neq 0$$

- ▶ Use warping methods for sparse and irregular curves as implemented in `elasdics` (Steyer 2021)
- ▶ Mean under optimal re-parametrization is called **elastic**

Elastic Mean and Warping

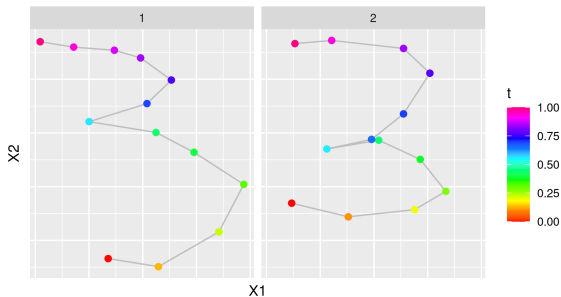


Figure: with `align_curves()` from package `elastdics` (Steyer 2021)

Problem: Methods are not invariant under rotation/scaling!

Full Procrustes Mean and Procrustes Fits

Basic idea:

1. Calculate mean that is invariant under rotation, scaling
 2. Align rotation and scaling
 3. Align parametrisation
- use estimated mean as reference for alignment

1+2 are known problems in **statistical shape analysis** (see e.g. Dryden and Mardia (2016)) → **Procrustes mean** and **Procrustes fits**

Note: More efficient to perform steps directly on the SRV curves!

Full Procrustes Mean and Procrustes Fits

Now: Need to derive the Procrustes mean for functional data

We can show using **complex** notation

$$q_i : [0, 1] \rightarrow \mathbb{C}, \quad q_i(t) = x_i(t) + i y_i(t)$$

that the population level **full Procrustes mean** for normalized curves \tilde{q} is given by:

$$\mu_q = \operatorname{argmax}_{z: [0,1] \rightarrow \mathbb{C}, \|z\|=1} \int_0^1 \int_0^1 \bar{z}(s) \mathbb{E} [\tilde{q}(s) \overline{\tilde{q}(t)}] z(t) ds dt$$

→ $\mathbb{E} [\tilde{q}(s) \overline{\tilde{q}(t)}]$ is the **complex covariance function** $C(s, t)$

Full Procrustes Mean and Procrustes Fits

Population level full Procrustes mean:

$$\mu_q = \operatorname{argmax}_{z:[0,1] \rightarrow \mathbb{C}, \|z\|=1} \int_0^1 \int_0^1 \bar{z}(s) C(s, t) z(t) ds dt$$

- **Functional PCA** problem (see Ramsay and Silverman (2005))
- Solution is the leading complex eigenfunction of $C(s, t)$
- We only need to find a good estimate $\hat{C}(s, t)$ to get $\hat{\mu}_q$!

Procrustes fits:

$$\hat{q}_i^P = \langle \tilde{q}_i, \hat{\mu}_q \rangle \tilde{q}_i$$

with $\langle f, g \rangle = \int_0^1 \overline{f(t)} g(t) dt$



Hermitian Covariance Smoothing

Treat estimation of $C(s, t) = \mathbb{E}[\tilde{q}(s)\tilde{q}(t)]$ as a regression problem:

- ▶ we can build response $y_{ijk} = \tilde{q}_i(t_{ij})\tilde{q}_i(t_{ik})$
- ▶ treat parametrisation t_{ij}, t_{ik} as “covariates” s and t
- ▶ non-parametric regression: $\mathbb{E}[y] = f(s, t)$
- ▶ use $\hat{C}(s, t) = \hat{f}(s, t)$ for functional PCA

Note: Using symmetry properties of $C(s, t)$ is important for efficient estimation (see Cederbaum, Scheipl, and Greven (2018)).

→ use every combination (t_{ij}, t_{ik}) only once

Hermitian Covariance Smoothing

Here: Complex covariance function is **hermitian** $C(s, t) = \overline{C}(t, s)$

$$\mathbb{E}[\operatorname{Re}(y)] = f_{\text{symm}}(s, t)$$

$$\mathbb{E}[\operatorname{Im}(y)] = f_{\text{skew}}(s, t)$$

- ▶ model real and imaginary parts separately using e.g. mgcv (Wood 2017)
- ▶ with **symmetric** and **skew-symmetric** tensor product P-splines from sparseFLMM (Cederbaum, Volkman, and Stöcker 2021)

We get:

$$\hat{C}(s, t) = b(s)^T \hat{\Xi} b(t), \quad \text{with} \quad \hat{\Xi} = \hat{\Xi}_{\text{symm}} + i \hat{\Xi}_{\text{skew}}$$

Hermitian Covariance Smoothing

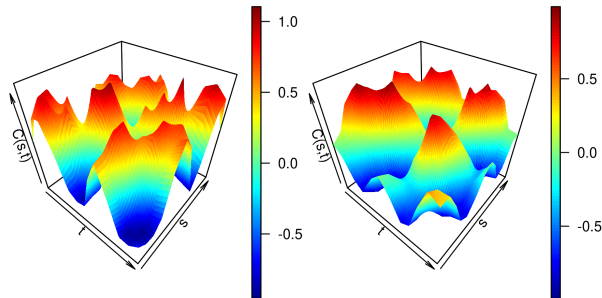


Figure: Estimated real (left) and imaginary (right) parts of $C(s, t)$

Empirical Procrustes Mean in a Fixed Basis

Idea: Estimate covariance function and mean in the same basis.

Then the optimization problem reduces to:

$$\hat{\theta}_{\mu} = \operatorname{argmax}_{\theta: \theta^H G \theta = 1} \theta^H G \hat{\Xi} G \theta \quad \text{with} \quad G_{kl} = \langle b_k, b_l \rangle$$

Eigenvalue problem treating $\theta = \theta_{Re} + i \theta_{Im}$ separately:

$$\begin{pmatrix} \hat{\Xi}_{symm} & -\hat{\Xi}_{skew} \\ \hat{\Xi}_{skew} & \hat{\Xi}_{symm} \end{pmatrix} \begin{pmatrix} G & 0 \\ 0 & G \end{pmatrix} \begin{pmatrix} \theta_{Re} \\ \theta_{Im} \end{pmatrix} = \lambda \begin{pmatrix} \theta_{Re} \\ \theta_{Im} \end{pmatrix}$$

\Rightarrow Solution is the leading normalized eigenvector of $\hat{\Xi} G$

Procrustes Fits

After obtaining $\hat{\mu}_q$ we can estimate the Procrustes fits:

$$\hat{q}_i^P = \langle \tilde{q}_i, \hat{\mu}_q \rangle \tilde{q}_i$$

- ▶ at the moment: integration with linear interpolation of \tilde{q}_i 's
- ▶ alternative: smoothing in mean basis with $\langle \hat{\tilde{q}}_i, \hat{\mu}_q \rangle = \hat{\theta}_i^H G \hat{\theta}_\mu$

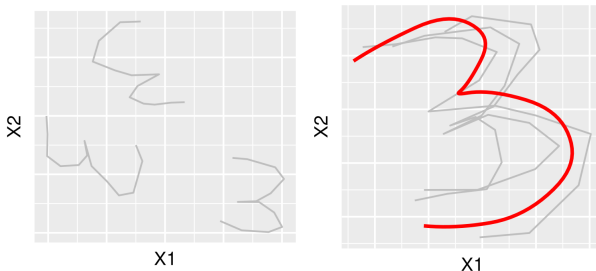


Figure: Procrustes fits and mean (on full dataset) before warping.

Results

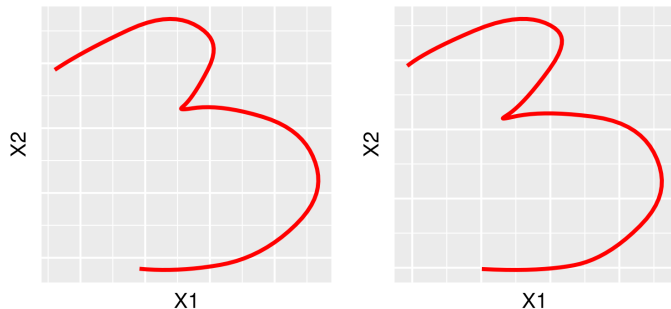


Figure: Full Procrustes mean (left) and elastic full Procrustes mean (right) on digits3.dat.

Results / Problems

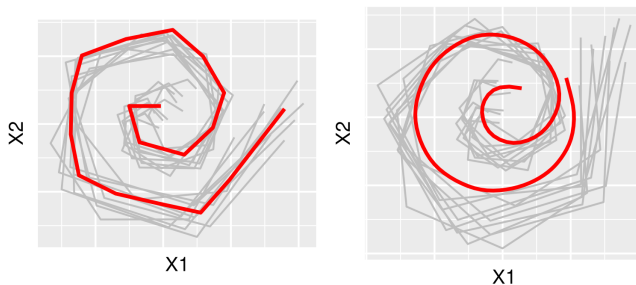


Figure: Polygon (left) and smooth (right) elastic full Procrustes mean with procrustes fits.

- Parameters: **knots, spline degree, penalty**
- Consistent results for piecewise constant splines (at SRV level) and zero order penalty (in the cov. estimation).

Outlook





Next steps:







- ▶ Real world data application (open curves)
- ▶ Better normalization / estimation of procrustes fits

Nice to have (maybe later):

- ▶ Mean for closed curves
- ▶ **Code:** bugs, testcases, faster

References

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Putting it all together

Algorithm Elastic Full Procrustes Mean

Input: Data curves β_1, \dots, β_N

Output: Procrustes mean $\hat{\mu}$ and Procrustes fits $\hat{\beta}_1^P, \dots, \hat{\beta}_N^P$

- 1: initialize arc-length parametrisation t_i for all β_i
- 2: calculate normalized SRV curves $\tilde{q}_i = \frac{q_i}{\|q_i\|}$
- 3: **while** convergence not reached **do**
- 4: estimate $C(s, t)$ using t_i
- 5: calculate $\hat{\mu}_q$ as the leading eigenfunction of $\hat{C}(s, t)$
- 6: estimate Procrustes fits \tilde{q}_i^P
- 7: update $t_i \leftarrow t_i^{optim}$ using warping alignment on \hat{q}_i^P
- 8: **end while**
- 9: **return** integrated Procrustes mean and fits

Problems

Normalization: $\tilde{q}_i = \frac{q_i}{\|q_i\|}$ is itself an estimate ($\|q_i\| = \sqrt{\langle q_i, q_i \rangle}$)

→ can either restrict β_i 's to unit-length or normalize q_i directly

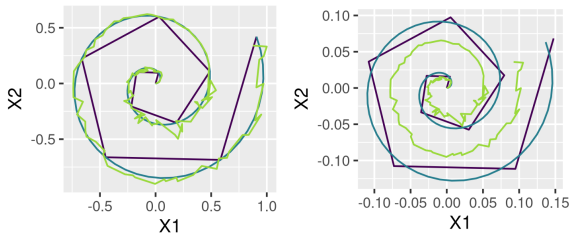


Figure: Spirals (left) and unit-length spirals (right).

- likely need smoothing (in the mean basis?) for this
- only ok, as long as all curves have same "amount" of sparsity

Derivation: Empirical Full Procrustes Mean

Full Procrustes Distance and Mean

$$d_F(q_1, q_2) = \inf_{\Gamma, b} \|q_1 - b\Gamma q_2\|$$

$$\mu_q : [0, 1] \rightarrow \mathbb{R}^2, \quad \hat{\mu}_q = \operatorname{argmin}_{z: [0, 1] \rightarrow \mathbb{R}^2} \sum_{i=1}^N d_F(z, q_i)^2$$

One can show that (Dryden and Mardia 2016, see Ch. 8):

$$\hat{\mu}_q = \operatorname{argmin}_{z: [0, 1] \rightarrow \mathbb{C}} \sum_{i=1}^N \underbrace{1 - \frac{\langle z, q_i \rangle \langle q_i, z \rangle}{\langle z, z \rangle \langle q_i, q_i \rangle}}_{=d_F(z, q_i)^2}$$

Derivation: Empirical Full Procrustes Mean

Note: $\langle q_1, q_2 \rangle = \int_0^1 \bar{q}_1(t) q_2(t) dt$, and $\|q_i\| = \sqrt{\langle q_i, q_i \rangle}$

$$\begin{aligned} \hat{\mu}_q &= \operatorname{argmax}_{z: \|z\|=1} \sum_{i=1}^N \langle z, \tilde{q}_i \rangle \langle \tilde{q}_i, z \rangle, \quad \text{with} \quad \tilde{q}_i = \frac{q_i}{\|q_i\|} \\ &= \operatorname{argmax}_{z: \|z\|=1} \sum_{i=1}^N \int_0^1 \bar{z}(s) \tilde{q}_i(s) ds \int_0^1 \bar{\tilde{q}}_i(t) z(t) dt \\ &= \operatorname{argmax}_{z: \|z\|=1} \int_0^1 \int_0^1 \bar{z}(s) \left(\sum_{i=1}^N \tilde{q}_i(s) \bar{\tilde{q}}_i(t) \right) z(t) ds dt \end{aligned}$$

→ sample analogue to $C(s, t) = \mathbb{E}[\tilde{q}(s) \bar{\tilde{q}}(t)]$

Derivation: Mean in a Fixed Basis

$$\mu_q = \operatorname{argmax}_{z:[0,1] \rightarrow \mathbb{C}, \|z\|=1} \int_0^1 \int_0^1 \bar{z}(s) C(s, t) z(t) ds dt$$

with $z(t) = b(t)^T \theta$ and $\hat{C}(s, t) = b(s)^T \hat{\Xi} b(t)$. Then

$$\begin{aligned} \hat{\theta}_\mu &= \operatorname{argmax}_{\theta: \|b^T \theta\|=1} \int_0^1 \int_0^1 \overline{(b(s)^T \theta)} b(s)^T \hat{\Xi} b(t) b(t)^T \theta ds dt \\ &= \operatorname{argmax}_{\theta: \|b^T \theta\|=1} \theta^H \left(\int_0^1 b(s) b(s)^T ds \right) \hat{\Xi} \left(\int_0^1 b(t) b(t)^T dt \right) \theta \\ &= \operatorname{argmax}_{\theta: \|b^T \theta\|=1} \theta^H G \hat{\Xi} G \theta \end{aligned}$$

Note: $\|b^T \theta\| = \sqrt{\theta^H G \theta}$