

# MPI: A Message-Passing Interface Standard

Version 3.0

ticket0.

Message Passing Interface Forum

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# Chapter 1

## MPI Terms and Conventions

This chapter explains notational terms and conventions used throughout the MPI document, some of the choices that have been made, and the rationale behind those choices. It is similar to the MPI-1 Terms and Conventions chapter but differs in some major and minor ways. Some of the major areas of difference are the naming conventions, some semantic definitions, file objects, Fortran 90 *vs* Fortran 77, C++, processes, and interaction with signals.

### 1.1 Document Notation

*Rationale.* Throughout this document, the rationale for the design choices made in the interface specification is set off in this format. Some readers may wish to skip these sections, while readers interested in interface design may want to read them carefully. (*End of rationale.*)

*Advice to users.* Throughout this document, material aimed at users and that illustrates usage is set off in this format. Some readers may wish to skip these sections, while readers interested in programming in MPI may want to read them carefully. (*End of advice to users.*)

*Advice to implementors.* Throughout this document, material that is primarily commentary to implementors is set off in this format. Some readers may wish to skip these sections, while readers interested in MPI implementations may want to read them carefully. (*End of advice to implementors.*)

### 1.2 Naming Conventions

In many cases MPI names for C functions are of the form `MPI_Class_action_subset`. This convention originated with MPI-1. Since MPI-2 an attempt has been made to standardize the names of MPI functions according to the following rules. The C++ bindings in particular follow these rules (see Section 1.6.4 on page 10).

1. In C, all routines associated with a particular type of MPI object should be of the form `MPI_Class_action_subset` or, if no subset exists, of the form `MPI_Class_action`. In Fortran, all routines associated with a particular type of MPI object should be of the form `MPI_CLASS_ACTION_SUBSET` or, if no subset exists, of the form

MPI\_CLASS\_ACTION. For C and Fortran we use the C++ terminology to define the **Class**. In C++, the routine is a method on **Class** and is named `MPI::Class::Action_subset`. If the routine is associated with a certain class, but does not make sense as an object method, it is a static member function of the class.

2. If the routine is not associated with a class, the name should be of the form `MPI_Action_subset` in C and `MPI_ACTION_SUBSET` in Fortran, and in C++ should be scoped in the MPI namespace, `MPI::Action_subset`.
3. The names of certain actions have been standardized. In particular, **Create** creates a new object, **Get** retrieves information about an object, **Set** sets this information, **Delete** deletes information, **Is** asks whether or not an object has a certain property.

C and Fortran names for some MPI functions (that were defined during the MPI-1 process) violate these rules in several cases. The most common exceptions are the omission of the **Class** name from the routine and the omission of the **Action** where one can be inferred.

MPI identifiers are limited to 30 characters (31 with the profiling interface). This is done to avoid exceeding the limit on some compilation systems.

### 1.3 Procedure Specification

MPI procedures are specified using a language-independent notation. The arguments of procedure calls are marked as IN, OUT or INOUT. The meanings of these are:

- IN: the call may use the input value but does not update the argument,
- OUT: the call may update the argument but does not use its input value,
- INOUT: the call may both use and update the argument.

There is one special case — if an argument is a handle to an opaque object (these terms are defined in Section 1.5.1), and the object is updated by the procedure call, then the argument is marked INOUT or OUT. It is marked this way even though the handle itself is not modified — we use the INOUT or OUT attribute to denote that what the handle *references* is updated. Thus, in C++, IN arguments are usually either references or pointers to `const` objects.

*Rationale.* The definition of MPI tries to avoid, to the largest possible extent, the use of INOUT arguments, because such use is error-prone, especially for scalar arguments. (*End of rationale.*)

MPI's use of IN, OUT and INOUT is intended to indicate to the user how an argument is to be used, but does not provide a rigorous classification that can be translated directly into all language bindings (e.g., `INTENT` in Fortran 90 bindings or `const` in C bindings). For instance, the “constant” `MPI_BOTTOM` can usually be passed to OUT buffer arguments. Similarly, `MPI_STATUS_IGNORE` can be passed as the OUT status argument.

A common occurrence for MPI functions is an argument that is used as IN by some processes and OUT by other processes. Such an argument is, syntactically, an INOUT argument



and is marked as such, although, semantically, it is not used in one call both for input and for output on a single process.

Another frequent situation arises when an argument value is needed only by a subset of the processes. When an argument is not significant at a process then an arbitrary value can be passed as an argument.

Unless specified otherwise, an argument of type OUT or type INOUT cannot be aliased with any other argument passed to an MPI procedure. An example of argument aliasing in C appears below. If we define a C procedure like this,

```
void copyIntBuffer( int *pin, int *pout, int len )
{
    int i;
    for (i=0; i<len; ++i) *pout++ = *pin++;
}
```

then a call to it in the following code fragment has aliased arguments.

```
int a[10];
copyIntBuffer( a, a+3, 7);
```

Although the C language allows this, such usage of MPI procedures is forbidden unless otherwise specified. Note that Fortran prohibits aliasing of arguments.

All MPI functions are first specified in the language-independent notation. Immediately below this, the ISO C version of the function is shown followed by a version of the same function in Fortran and then the C++ binding. Fortran in this document refers to Fortran 90; see Section 1.6.

## 1.4 Semantic Terms

When discussing MPI procedures the following semantic terms are used.

**nonblocking** A procedure is nonblocking if the procedure may return before the operation completes, and before the user is allowed to reuse resources (such as buffers) specified in the call. A nonblocking request is **started** by the call that initiates it, e.g., MPI\_ISEND. The word complete is used with respect to operations, requests, and communications. An **operation completes** when the user is allowed to reuse resources, and any output buffers have been updated; i.e. a call to MPI\_TEST will return `flag = true`. A **request is completed** by a call to wait, which returns, or a test or get status call which returns `flag = true`. This completing call has two effects: the status is extracted from the request; in the case of test and wait, if the request was nonpersistent, it is **freed**, and becomes **inactive** if it was persistent. A **communication completes** when all participating operations complete.

**blocking** A procedure is blocking if return from the procedure indicates the user is allowed to reuse resources specified in the call.

**local** A procedure is local if completion of the procedure depends only on the local executing process.

**non-local** A procedure is non-local if completion of the operation may require the execution of some MPI procedure on another process. Such an operation may require communication occurring with another user process.

**collective** A procedure is collective if all processes in a process group need to invoke the procedure. A collective call may or may not be synchronizing. Collective calls over the same communicator must be executed in the same order by all members of the process group.

**predefined** A predefined datatype is a datatype with a predefined (constant) name (such as `MPI_INT`, `MPI_FLOAT_INT`, or `MPI_UB`) or a datatype constructed with `MPI_TYPE_CREATE_F90_INTEGER`, `MPI_TYPE_CREATE_F90_REAL`, or `MPI_TYPE_CREATE_F90_COMPLEX`. The former are **named** whereas the latter are **unnamed**.

**derived** A derived datatype is any datatype that is not predefined.

**portable** A datatype is portable, if it is a predefined datatype, or it is derived from a portable datatype using only the type constructors `MPI_TYPE_CONTIGUOUS`, `MPI_TYPE_VECTOR`, `MPI_TYPE_INDEXED`, `MPI_TYPE_CREATE_INDEXED_BLOCK`, `MPI_TYPE_CREATE_SUBARRAY`, `MPI_TYPE_DUP`, and `MPI_TYPE_CREATE_DARRAY`. Such a datatype is portable because all displacements in the datatype are in terms of extents of one predefined datatype. Therefore, if such a datatype fits a data layout in one memory, it will fit the corresponding data layout in another memory, if the same declarations were used, even if the two systems have different architectures. On the other hand, if a datatype was constructed using `MPI_TYPE_CREATE_HINDEXED`, `MPI_TYPE_CREATE_HVECTOR` or `MPI_TYPE_CREATE_STRUCT`, then the datatype contains explicit byte displacements (e.g., providing padding to meet alignment restrictions). These displacements are unlikely to be chosen correctly if they fit data layout on one memory, but are used for data layouts on another process, running on a processor with a different architecture.

**equivalent** Two datatypes are equivalent if they appear to have been created with the same sequence of calls (and arguments) and thus have the same typemap. Two equivalent datatypes do not necessarily have the same cached attributes or the same names.

## 1.5 Data Types

### 1.5.1 Opaque Objects

MPI manages **system memory** that is used for buffering messages and for storing internal representations of various MPI objects such as groups, communicators, datatypes, etc. This memory is not directly accessible to the user, and objects stored there are **opaque**: their size and shape is not visible to the user. Opaque objects are accessed via **handles**, which exist in user space. MPI procedures that operate on opaque objects are passed handle arguments to access these objects. In addition to their use by MPI calls for object access, handles can participate in assignments and comparisons.

In Fortran, all handles have type `INTEGER`. In C and C++, a different handle type is defined for each category of objects. In addition, handles themselves are distinct objects in C++. The C and C++ types must support the use of the assignment and equality operators.

*Advice to implementors.* In Fortran, the handle can be an index into a table of opaque objects in a system table; in C it can be such an index or a pointer to the object. C++ handles can simply “wrap up” a table index or pointer.

*(End of advice to implementors.)*

Opaque objects are allocated and deallocated by calls that are specific to each object type. These are listed in the sections where the objects are described. The calls accept a handle argument of matching type. In an allocate call this is an OUT argument that returns a valid reference to the object. In a call to deallocate this is an INOUT argument which returns with an “invalid handle” value. MPI provides an “invalid handle” constant for each object type. Comparisons to this constant are used to test for validity of the handle.

A call to a deallocate routine invalidates the handle and marks the object for deallocation. The object is not accessible to the user after the call. However, MPI need not deallocate the object immediately. Any operation pending (at the time of the deallocate) that involves this object will complete normally; the object will be deallocated afterwards.

An opaque object and its handle are significant only at the process where the object was created and cannot be transferred to another process.

MPI provides certain predefined opaque objects and predefined, static handles to these objects. The user must not free such objects. In C++, this is enforced by declaring the handles to these predefined objects to be `static const`.

*Rationale.* This design hides the internal representation used for MPI data structures, thus allowing similar calls in C, C++, and Fortran. It also avoids conflicts with the typing rules in these languages, and easily allows future extensions of functionality. The mechanism for opaque objects used here loosely follows the POSIX Fortran binding standard.

The explicit separation of handles in user space and objects in system space allows space-reclaiming and deallocation calls to be made at appropriate points in the user program. If the opaque objects were in user space, one would have to be very careful not to go out of scope before any pending operation requiring that object completed. The specified design allows an object to be marked for deallocation, the user program can then go out of scope, and the object itself still persists until any pending operations are complete.

The requirement that handles support assignment/comparison is made since such operations are common. This restricts the domain of possible implementations. The alternative would have been to allow handles to have been an arbitrary, opaque type. This would force the introduction of routines to do assignment and comparison, adding complexity, and was therefore ruled out. *(End of rationale.)*

*Advice to users.* A user may accidentally create a dangling reference by assigning to a handle the value of another handle, and then deallocating the object associated with these handles. Conversely, if a handle variable is deallocated before the associated object is freed, then the object becomes inaccessible (this may occur, for example, if the handle is a local variable within a subroutine, and the subroutine is exited before the associated object is deallocated). It is the user’s responsibility to avoid adding or deleting references to opaque objects, except as a result of MPI calls that allocate or deallocate such objects. *(End of advice to users.)*

*Advice to implementors.* The intended semantics of opaque objects is that opaque objects are separate from one another; each call to allocate such an object copies all the information required for the object. Implementations may avoid excessive copying by substituting referencing for copying. For example, a derived datatype may contain references to its components, rather than copies of its components; a call to `MPI_COMM_GROUP` may return a reference to the group associated with the communicator, rather than a copy of this group. In such cases, the implementation must maintain reference counts, and allocate and deallocate objects in such a way that the visible effect is as if the objects were copied. (*End of advice to implementors.*)

### 1.5.2 Array Arguments

An MPI call may need an argument that is an array of opaque objects, or an array of handles. The array-of-handles is a regular array with entries that are handles to objects of the same type in consecutive locations in the array. Whenever such an array is used, an additional `len` argument is required to indicate the number of valid entries (unless this number can be derived otherwise). The valid entries are at the beginning of the array; `len` indicates how many of them there are, and need not be the size of the entire array. The same approach is followed for other array arguments. In some cases `NULL` handles are considered valid entries. When a `NULL` argument is desired for an array of statuses, one uses `MPI_STATUSES_IGNORE`.

### 1.5.3 State

MPI procedures use at various places arguments with *state* types. The values of such a data type are all identified by names, and no operation is defined on them. For example, the `MPI_TYPE_CREATE_SUBARRAY` routine has a state argument `order` with values `MPI_ORDER_C` and `MPI_ORDER_FORTRAN`.

### 1.5.4 Named Constants

MPI procedures sometimes assign a special meaning to a special value of a basic type argument; e.g., `tag` is an integer-valued argument of point-to-point communication operations, with a special wild-card value, `MPI_ANY_TAG`. Such arguments will have a range of regular values, which is a proper subrange of the range of values of the corresponding basic type; special values (such as `MPI_ANY_TAG`) will be outside the regular range. The range of regular values, such as `tag`, can be queried using environmental inquiry functions (Chapter 7 of the MPI-1 document). The range of other values, such as `source`, depends on values given by other MPI routines (in the case of `source` it is the communicator size).

MPI also provides predefined named constant handles, such as `MPI_COMM_WORLD`.

All named constants, with the exceptions noted below for Fortran, can be used in initialization expressions or assignments, but not necessarily in array declarations or as labels in C/C++ `switch` or Fortran `select/case` statements. This implies named constants to be link-time but not necessarily compile-time constants. The named constants listed below are required to be compile-time constants in both C/C++ and Fortran. These constants do not change values during execution. Opaque objects accessed by constant handles are defined and do not change value between MPI initialization (`MPI_INIT`) and MPI completion (`MPI_FINALIZE`). The handles themselves are constants and can be also used in initialization expressions or assignments.

The constants that are required to be compile-time constants (and can thus be used for array length declarations and labels in C/C++ `switch` and Fortran `case/select` statements) are:

`MPI_MAX_PROCESSOR_NAME`

`[]`

`MPI_MAX_LIBRARY_VERSION_STRING`

`MPI_MAX_ERROR_STRING`

`MPI_MAX_DATAREP_STRING`

`MPI_MAX_INFO_KEY`

`MPI_MAX_INFO_VAL`

`MPI_MAX_OBJECT_NAME`

`MPI_MAX_PORT_NAME`

`MPI_STATUS_SIZE` (Fortran only)

`MPI_ADDRESS_KIND` (Fortran only)

`MPI_INTEGER_KIND` (Fortran only)

`MPI_OFFSET_KIND` (Fortran only)

and their C++ counterparts where appropriate.

The constants that cannot be used in initialization expressions or assignments in Fortran are:

`MPI_BOTTOM`

`MPI_STATUS_IGNORE`

`MPI_STATUSES_IGNORE`

`MPI_ERRCODES_IGNORE`

`MPI_IN_PLACE`

`MPI_ARGV_NULL`

`MPI_ARGVS_NULL`

`MPI_UNWEIGHTED`

*Advice to implementors.* In Fortran the implementation of these special constants may require the use of language constructs that are outside the Fortran standard. Using special values for the constants (e.g., by defining them through `PARAMETER` statements) is not possible because an implementation cannot distinguish these values from legal data. Typically, these constants are implemented as predefined static variables (e.g., a variable in an MPI-declared `COMMON` block), relying on the fact that the target compiler passes data by address. Inside the subroutine, this address can be extracted by some mechanism outside the Fortran standard (e.g., by Fortran extensions or by implementing the function in C). (*End of advice to implementors.*)

### 1.5.5 Choice

MPI functions sometimes use arguments with a *choice* (or union) data type. Distinct calls to the same routine may pass by reference actual arguments of different types. The mechanism for providing such arguments will differ from language to language. For Fortran, the document uses `<type>` to represent a choice variable; for C and C++, we use `void *`.

### 1.5.6 Addresses

Some MPI procedures use *address* arguments that represent an absolute address in the calling program. The datatype of such an argument is `MPI_Aint` in C, `MPI::Aint` in C++

and `INTEGER (KIND=MPI_ADDRESS_KIND)` in Fortran. These types must have the same width and encode address values in the same manner such that address values in one language may be passed directly to another language without conversion. There is the MPI constant `MPI_BOTTOM` to indicate the start of the address range.

### 1.5.7 File Offsets

For I/O there is a need to give the size, displacement, and offset into a file. These quantities can easily be larger than 32 bits which can be the default size of a Fortran integer. To overcome this, these quantities are declared to be `INTEGER (KIND=MPI_OFFSET_KIND)` in Fortran. In C one uses `MPI_Offset` whereas in C++ one uses `MPI::Offset`. These types must have the same width and encode address values in the same manner such that offset values in one language may be passed directly to another language without conversion.

## 1.6 Language Binding

This section defines the rules for MPI language binding in general and for Fortran, ISO C, and C++, in particular. (Note that ANSI C has been replaced by ISO C.) The C++ language bindings have been deprecated. Defined here are various object representations, as well as the naming conventions used for expressing this standard. The actual calling sequences are defined elsewhere.

MPI bindings are for Fortran 90, though they are designed to be usable in Fortran 77 environments.

Since the word `PARAMETER` is a keyword in the Fortran language, we use the word “argument” to denote the arguments to a subroutine. These are normally referred to as parameters in C and C++, however, we expect that C and C++ programmers will understand the word “argument” (which has no specific meaning in C/C++), thus allowing us to avoid unnecessary confusion for Fortran programmers.

Since Fortran is case insensitive, linkers may use either lower case or upper case when resolving Fortran names. Users of case sensitive languages should avoid the “`mpi_`” and “`pmpi_`” prefixes.

### 1.6.1 Deprecated Names and Functions

A number of chapters refer to deprecated or replaced MPI-1 constructs. These are constructs that continue to be part of the MPI standard, as documented in Chapter ??, but that users are recommended not to continue using, since better solutions were provided with MPI-2. For example, the Fortran binding for MPI-1 functions that have address arguments uses `INTEGER`. This is not consistent with the C binding, and causes problems on machines with 32 bit `INTEGER`s and 64 bit addresses. In MPI-2, these functions were given new names with new bindings for the address arguments. The use of the old functions is deprecated. For consistency, here and in a few other cases, new C functions are also provided, even though the new functions are equivalent to the old functions. The old names are deprecated. Another example is provided by the MPI-1 predefined datatypes `MPI_UB` and `MPI_LB`. They are deprecated, since their use is awkward and error-prone. The MPI-2 function `MPI_TYPE_CREATE_RESIZED` provides a more convenient mechanism to achieve the same effect.

Table 1.1 shows a list of all of the deprecated constructs. Note that the constants `MPI_LB` and `MPI_UB` are replaced by the function `MPI_TYPE_CREATE_RESIZED`; this is because their principal use was as input datatypes to `MPI_TYPE_STRUCT` to create resized datatypes. Also note that some C typedefs and Fortran subroutine names are included in this list; they are the types of callback functions.

Deprecated	MPI-2 Replacement
<code>MPI_ADDRESS</code>	<code>MPI_GET_ADDRESS</code>
<code>MPI_TYPE_HINDEXED</code>	<code>MPI_TYPE_CREATE_HINDEXED</code>
<code>MPI_TYPE_HVECTOR</code>	<code>MPI_TYPE_CREATE_HVECTOR</code>
<code>MPI_TYPE_STRUCT</code>	<code>MPI_TYPE_CREATE_STRUCT</code>
<code>MPI_TYPE_EXTENT</code>	<code>MPI_TYPE_GET_EXTENT</code>
<code>MPI_TYPE_UB</code>	<code>MPI_TYPE_GET_EXTENT</code>
<code>MPI_TYPE_LB</code>	<code>MPI_TYPE_GET_EXTENT</code>
<code>MPI_LB</code>	<code>MPI_TYPE_CREATE_RESIZED</code>
<code>MPI_UB</code>	<code>MPI_TYPE_CREATE_RESIZED</code>
<code>MPI_ERRHANDLER_CREATE</code>	<code>MPI_COMM_CREATE_ERRHANDLER</code>
<code>MPI_ERRHANDLER_GET</code>	<code>MPI_COMM_GET_ERRHANDLER</code>
<code>MPI_ERRHANDLER_SET</code>	<code>MPI_COMM_SET_ERRHANDLER</code>
<code>MPI_Handler_function</code>	<code>MPI_Comm_errhandler_function</code>
<code>MPI_KEYVAL_CREATE</code>	<code>MPI_COMM_CREATE_KEYVAL</code>
<code>MPI_KEYVAL_FREE</code>	<code>MPI_COMM_FREE_KEYVAL</code>
<code>MPI_DUP_FN</code>	<code>MPI_COMM_DUP_FN</code>
<code>MPI_NULL_COPY_FN</code>	<code>MPI_COMM_NULL_COPY_FN</code>
<code>MPI_NULL_DELETE_FN</code>	<code>MPI_COMM_NULL_DELETE_FN</code>
<code>MPI_Copy_function</code>	<code>MPI_Comm_copy_attr_function</code>
<code>COPY_FUNCTION</code>	<code>COMM_COPY_ATTR_FN</code>
<code>MPI_Delete_function</code>	<code>MPI_Comm_delete_attr_function</code>
<code>DELETE_FUNCTION</code>	<code>COMM_DELETE_ATTR_FN</code>
<code>MPI_ATTR_DELETE</code>	<code>MPI_COMM_DELETE_ATTR</code>
<code>MPI_ATTR_GET</code>	<code>MPI_COMM_GET_ATTR</code>
<code>MPI_ATTR_PUT</code>	<code>MPI_COMM_SET_ATTR</code>

Table 1.1: Deprecated constructs

### 1.6.2 Fortran Binding Issues

Originally, MPI-1.1 provided bindings for Fortran 77. These bindings are retained, but they are now interpreted in the context of the Fortran 90 standard. MPI can still be used with most Fortran 77 compilers, as noted below. When the term Fortran is used it means Fortran 90.

All MPI names have an `MPI_` prefix, and all characters are capitals. Programs must not declare variables, parameters, or functions with names beginning with the prefix `MPI_`. To avoid conflicting with the profiling interface, programs should also avoid functions with the prefix `PMPI_`. This is mandated to avoid possible name collisions.

All MPI Fortran subroutines have a return code in the last argument. A few MPI operations which are functions do not have the return code argument. The return code value

for successful completion is `MPI_SUCCESS`. Other error codes are implementation dependent; see the error codes in Chapter 2 and Annex 3.

Constants representing the maximum length of a string are one smaller in Fortran than in C and C++ as discussed in Section ??.

Handles are represented in Fortran as `INTEGERS`. Binary-valued variables are of type `LOGICAL`.

Array arguments are indexed from one.

The MPI Fortran binding is inconsistent with the Fortran 90 standard in several respects. These inconsistencies, such as register optimization problems, have implications for user codes that are discussed in detail in Section ??. They are also inconsistent with Fortran 77.

### 1.6.3 C Binding Issues

We use the ISO C declaration format. All MPI names have an `MPI_` prefix, defined constants are in all capital letters, and defined types and functions have one capital letter after the prefix. Programs must not declare variables or functions with names beginning with the prefix `MPI_`. To support the profiling interface, programs should not declare functions with names beginning with the prefix `PMPI_`.

The definition of named constants, function prototypes, and type definitions must be supplied in an include file `mpi.h`.

Almost all C functions return an error code. The successful return code will be `MPI_SUCCESS`, but failure return codes are implementation dependent.

Type declarations are provided for handles to each category of opaque objects.

Array arguments are indexed from zero.

Logical flags are integers with value 0 meaning “false” and a non-zero value meaning “true.”

Choice arguments are pointers of type `void *`.

Address arguments are of MPI defined type `MPI_Aint`. File displacements are of type `MPI_Offset`. `MPI_Aint` is defined to be an integer of the size needed to hold any valid address on the target architecture. `MPI_Offset` is defined to be an integer of the size needed to hold any valid file size on the target architecture.

### 1.6.4 C++ Binding Issues

The C++ language bindings have been deprecated. There are places in the standard that give rules for C and not for C++. In these cases, the C rule should be applied to the C++ case, as appropriate. In particular, the values of constants given in the text are the ones for C and Fortran. A cross index of these with the C++ names is given in Annex 3.

We use the ISO C++ declaration format. All MPI names are declared within the scope of a namespace called `MPI` and therefore are referenced with an `MPI::` prefix. Defined constants are in all capital letters, and class names, defined types, and functions have only their first letter capitalized. Programs must not declare variables or functions in the `MPI` namespace. This is mandated to avoid possible name collisions.

The definition of named constants, function prototypes, and type definitions must be supplied in an include file `mpi.h`.

*Advice to implementors.* The file `mpi.h` may contain both the C and C++ definitions. Usually one can simply use the defined value (generally `__cplusplus`, but not



required) to see if one is using C++ to protect the C++ definitions. It is possible that a C compiler will require that the source protected this way be legal C code. In this case, all the C++ definitions can be placed in a different include file and the “`#include`” directive can be used to include the necessary C++ definitions in the `mpi.h` file. (*End of advice to implementors.*)

C++ functions that create objects or return information usually place the object or information in the return value. Since the language neutral prototypes of MPI functions include the C++ return value as an OUT parameter, semantic descriptions of MPI functions refer to the C++ return value by that parameter name. The remaining C++ functions return `void`.

In some circumstances, MPI permits users to indicate that they do not want a return value. For example, the user may indicate that the status is not filled in. Unlike C and Fortran where this is achieved through a special input value, in C++ this is done by having two bindings where one has the optional argument and one does not.

C++ functions do not return error codes. If the default error handler has been set to `MPI::ERRORS_THROW_EXCEPTIONS`, the C++ exception mechanism is used to signal an error by throwing an `MPI::Exception` object.

It should be noted that the default error handler (i.e., `MPI::ERRORS_ARE_FATAL`) on a given type has not changed. User error handlers are also permitted. `MPI::ERRORS_RETURN` simply returns control to the calling function; there is no provision for the user to retrieve the error code.

User callback functions that return integer error codes should not throw exceptions; the returned error will be handled by the MPI implementation by invoking the appropriate error handler.

*Advice to users.* C++ programmers that want to handle MPI errors on their own should use the `MPI::ERRORS_THROW_EXCEPTIONS` error handler, rather than `MPI::ERRORS_RETURN`, that is used for that purpose in C. Care should be taken using exceptions in mixed language situations. (*End of advice to users.*)

Opaque object handles must be objects in themselves, and have the assignment and equality operators overridden to perform semantically like their C and Fortran counterparts.

Array arguments are indexed from zero.

Logical flags are of type `bool`.

Choice arguments are pointers of type `void *`.

Address arguments are of MPI-defined integer type `MPI::Aint`, defined to be an integer of the size needed to hold any valid address on the target architecture. Analogously, `MPI::Offset` is an integer to hold file offsets.

Most MPI functions are methods of MPI C++ classes. MPI class names are generated from the language neutral MPI types by dropping the `MPI_` prefix and scoping the type within the MPI namespace. For example, `MPI_DATATYPE` becomes `MPI::Datatype`.

The names of MPI functions generally follow the naming rules given. In some circumstances, the MPI function is related to a function defined already for MPI-1 with a name that does not follow the naming conventions. In this circumstance, the language neutral name is in analogy to the MPI name even though this gives an MPI-2 name that violates the naming conventions. The C and Fortran names are the same as the language neutral name in this case. However, the C++ names do reflect the naming rules and can differ from the C

and Fortran names. Thus, the analogous name in C++ to the MPI name may be different than the language neutral name. This results in the C++ name differing from the language neutral name. An example of this is the language neutral name of `MPI_FINALIZED` and a C++ name of `MPI::Is_finalized`.

In C++, function `typedefs` are made publicly within appropriate classes. However, these declarations then become somewhat cumbersome, as with the following:

```
{typedef MPI::Grequest::Query_function(); (binding deprecated, see Section ??)}
```

would look like the following:

```
namespace MPI {
  class Request {
    // ...
  };

  class Grequest : public MPI::Request {
    // ...
    typedef Query_function(void* extra_state, MPI::Status& status);
  };
};
```

Rather than including this scaffolding when declaring C++ `typedefs`, we use an abbreviated form. In particular, we explicitly indicate the class and namespace scope for the `typedef` of the function. Thus, the example above is shown in the text as follows:

```
typedef int MPI::Grequest::Query_function(void* extra_state,
                                           MPI::Status& status)
```

The C++ bindings presented in Annex ?? and throughout this document were generated by applying a simple set of name generation rules to the MPI function specifications. While these guidelines may be sufficient in most cases, they may not be suitable for all situations. In cases of ambiguity or where a specific semantic statement is desired, these guidelines may be superseded as the situation dictates.

1. All functions, types, and constants are declared within the scope of a `namespace` called `MPI`.
2. Arrays of MPI handles are always left in the argument list (whether they are IN or OUT arguments).
3. If the argument list of an MPI function contains a scalar IN handle, and it makes sense to define the function as a method of the object corresponding to that handle, the function is made a member function of the corresponding MPI class. The member functions are named according to the corresponding MPI function name, but without the “MPI\_” prefix and without the object name prefix (if applicable). In addition:
  - (a) The scalar IN handle is dropped from the argument list, and `this` corresponds to the dropped argument.
  - (b) The function is declared `const`.

4. MPI functions are made into class functions (static) when they belong on a class but do not have a unique scalar IN or INOUT parameter of that class.
5. If the argument list contains a single OUT argument that is not of type MPI\_STATUS (or an array), that argument is dropped from the list and the function returns that value.

**Example 1.1** The C++ binding for MPI\_COMM\_SIZE is  
 int MPI::Comm::Get\_size(void) const.

6. If there are multiple OUT arguments in the argument list, one is chosen as the return value and is removed from the list.
7. If the argument list does not contain any OUT arguments, the function returns void.

**Example 1.2** The C++ binding for MPI\_REQUEST\_FREE is  
 void MPI::Request::Free(void)

8. MPI functions to which the above rules do not apply are not members of any class, but are defined in the MPI namespace.

**Example 1.3** The C++ binding for MPI\_BUFFER\_ATTACH is  
 void MPI::Attach\_buffer(void\* buffer, int size).

9. All class names, defined types, and function names have only their first letter capitalized. Defined constants are in all capital letters.
10. Any IN pointer, reference, or array argument must be declared const.
11. Handles are passed by reference.
12. Array arguments are denoted with square brackets ([]), not pointers, as this is more semantically precise.

### 1.6.5 Functions and Macros

An implementation is allowed to implement MPI\_WTIME, MPI\_WTICK, PMPI\_WTIME, PMPI\_WTICK, and the handle-conversion functions (MPI\_Group\_f2c, etc.) in Section ??, and no others, as macros in C.

*Advice to implementors.* Implementors should document which routines are implemented as macros. (*End of advice to implementors.*)

*Advice to users.* If these routines are implemented as macros, they will not work with the MPI profiling interface. (*End of advice to users.*)

## 1.7 Processes

An MPI program consists of autonomous processes, executing their own code, in an MIMD style. The codes executed by each process need not be identical. The processes communicate via calls to MPI communication primitives. Typically, each process executes in its own address space, although shared-memory implementations of MPI are possible.

This document specifies the behavior of a parallel program assuming that only MPI calls are used. The interaction of an MPI program with other possible means of communication, I/O, and process management is not specified. Unless otherwise stated in the specification of the standard, MPI places no requirements on the result of its interaction with external mechanisms that provide similar or equivalent functionality. This includes, but is not limited to, interactions with external mechanisms for process control, shared and remote memory access, file system access and control, interprocess communication, process signaling, and terminal I/O. High quality implementations should strive to make the results of such interactions intuitive to users, and attempt to document restrictions where deemed necessary.

*Advice to implementors.* Implementations that support such additional mechanisms for functionality supported within MPI are expected to document how these interact with MPI. (*End of advice to implementors.*)

The interaction of MPI and threads is defined in Section ??.

## 1.8 Error Handling

MPI provides the user with reliable message transmission. A message sent is always received correctly, and the user does not need to check for transmission errors, time-outs, or other error conditions. In other words, MPI does not provide mechanisms for dealing with failures in the communication system. If the MPI implementation is built on an unreliable underlying mechanism, then it is the job of the implementor of the MPI subsystem to insulate the user from this unreliability, or to reflect unrecoverable errors as failures. Whenever possible, such failures will be reflected as errors in the relevant communication call. Similarly, MPI itself provides no mechanisms for handling processor failures.

Of course, MPI programs may still be erroneous. A **program error** can occur when an MPI call is made with an incorrect argument (non-existing destination in a send operation, buffer too small in a receive operation, etc.). This type of error would occur in any implementation. In addition, a **resource error** may occur when a program exceeds the amount of available system resources (number of pending messages, system buffers, etc.). The occurrence of this type of error depends on the amount of available resources in the system and the resource allocation mechanism used; this may differ from system to system. A high-quality implementation will provide generous limits on the important resources so as to alleviate the portability problem this represents.

In C and Fortran, almost all MPI calls return a code that indicates successful completion of the operation. Whenever possible, MPI calls return an error code if an error occurred during the call. By default, an error detected during the execution of the MPI library causes the parallel computation to abort, except for file operations. However, MPI provides mechanisms for users to change this default and to handle recoverable errors. The user may specify that no error is fatal, and handle error codes returned by MPI calls by himself

or herself. Also, the user may provide his or her own error-handling routines, which will be invoked whenever an MPI call returns abnormally. The MPI error handling facilities are described in Section 2.3. The return values of C++ functions are not error codes. If the default error handler has been set to `MPI::ERRORS_THROW_EXCEPTIONS`, the C++ exception mechanism is used to signal an error by throwing an `MPI::Exception` object. See also Section ?? on page ??.

Several factors limit the ability of MPI calls to return with meaningful error codes when an error occurs. MPI may not be able to detect some errors; other errors may be too expensive to detect in normal execution mode; finally some errors may be “catastrophic” and may prevent MPI from returning control to the caller in a consistent state.

Another subtle issue arises because of the nature of asynchronous communications: MPI calls may initiate operations that continue asynchronously after the call returned. Thus, the operation may return with a code indicating successful completion, yet later cause an error exception to be raised. If there is a subsequent call that relates to the same operation (e.g., a call that verifies that an asynchronous operation has completed) then the error argument associated with this call will be used to indicate the nature of the error. In a few cases, the error may occur after all calls that relate to the operation have completed, so that no error value can be used to indicate the nature of the error (e.g., an error on the receiver in a send with the ready mode). Such an error must be treated as fatal, since information cannot be returned for the user to recover from it.

This document does not specify the state of a computation after an erroneous MPI call has occurred. The desired behavior is that a relevant error code be returned, and the effect of the error be localized to the greatest possible extent. E.g., it is highly desirable that an erroneous receive call will not cause any part of the receiver’s memory to be overwritten, beyond the area specified for receiving the message.

Implementations may go beyond this document in supporting in a meaningful manner MPI calls that are defined here to be erroneous. For example, MPI specifies strict type matching rules between matching send and receive operations: it is erroneous to send a floating point variable and receive an integer. Implementations may go beyond these type matching rules, and provide automatic type conversion in such situations. It will be helpful to generate warnings for such non-conforming behavior.

MPI defines a way for users to create new error codes as defined in Section 2.5.

## 1.9 Implementation Issues

There are a number of areas where an MPI implementation may interact with the operating environment and system. While MPI does not mandate that any services (such as signal handling) be provided, it does strongly suggest the behavior to be provided if those services are available. This is an important point in achieving portability across platforms that provide the same set of services.

### 1.9.1 Independence of Basic Runtime Routines

MPI programs require that library routines that are part of the basic language environment (such as `write` in Fortran and `printf` and `malloc` in ISO C) and are executed after `MPI_INIT` and before `MPI_FINALIZE` operate independently and that their *completion* is independent of the action of other processes in an MPI program.

Note that this in no way prevents the creation of library routines that provide parallel services whose operation is collective. However, the following program is expected to complete in an ISO C environment regardless of the size of `MPI_COMM_WORLD` (assuming that `printf` is available at the executing nodes).

```
int rank;
MPI_Init((void *)0, (void *)0);
MPI_Comm_rank(MPI_COMM_WORLD, &rank);
if (rank == 0) printf("Starting program\n");
MPI_Finalize();
```

The corresponding Fortran and C++ programs are also expected to complete.

An example of what is *not* required is any particular ordering of the action of these routines when called by several tasks. For example, MPI makes neither requirements nor recommendations for the output from the following program (again assuming that I/O is available at the executing nodes).

```
MPI_Comm_rank(MPI_COMM_WORLD, &rank);
printf("Output from task rank %d\n", rank);
```

In addition, calls that fail because of resource exhaustion or other error are not considered a violation of the requirements here (however, they are required to complete, just not to complete successfully).

## 1.9.2 Interaction with Signals

MPI does not specify the interaction of processes with signals and does not require that MPI be signal safe. The implementation may reserve some signals for its own use. It is required that the implementation document which signals it uses, and it is strongly recommended that it not use `SIGALRM`, `SIGFPE`, or `SIGIO`. Implementations may also prohibit the use of MPI calls from within signal handlers.

In multithreaded environments, users can avoid conflicts between signals and the MPI library by catching signals only on threads that do not execute MPI calls. High quality single-threaded implementations will be signal safe: an MPI call suspended by a signal will resume and complete normally after the signal is handled.

## 1.10 Examples

The examples in this document are for illustration purposes only. They are not intended to specify the standard. Furthermore, the examples have not been carefully checked or verified.

## Chapter 2

# MPI Environmental Management

This chapter discusses routines for getting and, where appropriate, setting various parameters that relate to the MPI implementation and the execution environment (such as error handling). The procedures for entering and leaving the MPI execution environment are also described here.

## 2.1 Implementation Information

### 2.1.1 Version Inquiries

In order to cope with changes to the MPI Standard, there are both compile-time and run-time ways to determine which version of the standard is in use in the environment one is using.

The “version” will be represented by two separate integers, for the version and subversion: In C and C++,

```
#define MPI_VERSION    2
#define MPI_SUBVERSION 2
```

in Fortran,

```
INTEGER MPI_VERSION, MPI_SUBVERSION
PARAMETER (MPI_VERSION    = 2)
PARAMETER (MPI_SUBVERSION = 2)
```

For runtime determination,

`MPI_GET_VERSION( version, subversion )`

OUT	version	version number (integer)
OUT	subversion	subversion number (integer)

```
int MPI_Get_version(int *version, int *subversion)
```

```
MPI_GET_VERSION(VERSION, SUBVERSION, IERROR)
  INTEGER VERSION, SUBVERSION, IERROR
```

```

1 {void MPI::Get_version(int& version, int& subversion) (binding deprecated, see
2   Section ??) }
```

Valid (MPI\_VERSION, MPI\_SUBVERSION) pairs in this and previous versions of the MPI standard are (3,0), (2,2), (2,1), (2,0), and (1,2).

```

6 []
```

```

8 MPI_GET_LIBRARY_VERSION( version, resultlen )
```

```

9      OUT      version      version string (string)
```

```

10     OUT      resultlen     Length (in printable characters) of the result returned
11                                     in version (integer)
```

```

14 int MPI_Get_library_version(char *version, int *resultlen)
```

```

16 MPI_GET_LIBRARY_VERSION(VERSION, RESULTEN, IERROR)
```

```

17     CHARACTER*(*) VERSION
```

```

18     INTEGER RESULTLEN, IERROR
```

This routine returns a string representing the version of the MPI library. The version argument is a character string for maximum flexibility.

*Advice to implementors.* An implementation of MPI should return a different string for every change to its source code or build that could be visible to the user. (*End of advice to implementors.*)

The argument version must represent storage that is MPI\_MAX\_LIBRARY\_VERSION\_STRING characters long. MPI\_GET\_LIBRARY\_VERSION may write up to this many characters into version.

The number of characters actually written is returned in the output argument, resultlen. In C, a null character is additionally stored at version[resultlen]. The resultlen cannot be larger than MPI\_MAX\_LIBRARY\_VERSION\_STRING - 1. In Fortran, version is padded on the right with blank characters. The resultlen cannot be larger than MPI\_MAX\_LIBRARY\_VERSION\_STRING.

MPI\_GET\_VERSION [is one] and MPI\_GET\_LIBRARY\_VERSION are two of the few functions that can be called before MPI\_INIT and after MPI\_FINALIZE. [Valid (MPI\_VERSION, MPI\_SUBVERSION) pairs in this and previous versions of the MPI standard are (2,2), (2,1), (2,0), and (1,2).]

### 2.1.2 Environmental Inquiries

A set of attributes that describe the execution environment are attached to the communicator MPI\_COMM\_WORLD when MPI is initialized. The value of these attributes can be inquired by using the function MPI\_COMM\_GET\_ATTR described in Chapter ?? . It is erroneous to delete these attributes, free their keys, or change their values.

The list of predefined attribute keys include

**MPI\_TAG\_UB** Upper bound for tag value.

**MPI\_HOST** Host process rank, if such exists, MPI\_PROC\_NULL, otherwise.



**MPI\_IO** rank of a node that has regular I/O facilities (possibly myrank). Nodes in the same communicator may return different values for this parameter.

**MPI\_WTIME\_IS\_GLOBAL** Boolean variable that indicates whether clocks are synchronized.

Vendors may add implementation specific parameters (such as node number, real memory size, virtual memory size, etc.)

These predefined attributes do not change value between MPI initialization (MPI\_INIT and MPI completion (MPI\_FINALIZE), and cannot be updated or deleted by users.

*Advice to users.* Note that in the C binding, the value returned by these attributes is a *pointer* to an `int` containing the requested value. (*End of advice to users.*)

The required parameter values are discussed in more detail below:

### Tag Values

Tag values range from 0 to the value returned for MPI\_TAG\_UB inclusive. These values are guaranteed to be unchanging during the execution of an MPI program. In addition, the tag upper bound value must be *at least* 32767. An MPI implementation is free to make the value of MPI\_TAG\_UB larger than this; for example, the value  $2^{30} - 1$  is also a legal value for MPI\_TAG\_UB.

The attribute MPI\_TAG\_UB has the same value on all processes of MPI\_COMM\_WORLD.

### Host Rank

The value returned for MPI\_HOST gets the rank of the HOST process in the group associated with communicator MPI\_COMM\_WORLD, if there is such. MPI\_PROC\_NULL is returned if there is no host. MPI does not specify what it means for a process to be a HOST, nor does it require that a HOST exists.

The attribute MPI\_HOST has the same value on all processes of MPI\_COMM\_WORLD.

### IO Rank

The value returned for MPI\_IO is the rank of a processor that can provide language-standard I/O facilities. For Fortran, this means that all of the Fortran I/O operations are supported (e.g., OPEN, REWIND, WRITE). For C and C++, this means that all of the ISO C and C++, I/O operations are supported (e.g., fopen, fprintf, lseek).

If every process can provide language-standard I/O, then the value MPI\_ANY\_SOURCE will be returned. Otherwise, if the calling process can provide language-standard I/O, then its rank will be returned. Otherwise, if some process can provide language-standard I/O then the rank of one such process will be returned. The same value need not be returned by all processes. If no process can provide language-standard I/O, then the value MPI\_PROC\_NULL will be returned.

*Advice to users.* Note that input is not collective, and this attribute does *not* indicate which process can or does provide input. (*End of advice to users.*)

## Clock Synchronization

The value returned for `MPI_WTIME_IS_GLOBAL` is 1 if clocks at all processes in `MPI_COMM_WORLD` are synchronized, 0 otherwise. A collection of clocks is considered synchronized if explicit effort has been taken to synchronize them. The expectation is that the variation in time, as measured by calls to `MPI_WTIME`, will be less than one half the round-trip time for an MPI message of length zero. If time is measured at a process just before a send and at another process just after a matching receive, the second time should be always higher than the first one.

The attribute `MPI_WTIME_IS_GLOBAL` need not be present when the clocks are not synchronized (however, the attribute key `MPI_WTIME_IS_GLOBAL` is always valid). This attribute may be associated with communicators other than `MPI_COMM_WORLD`.

The attribute `MPI_WTIME_IS_GLOBAL` has the same value on all processes of `MPI_COMM_WORLD`.

## `MPI_GET_PROCESSOR_NAME( name, resultlen )`

OUT	name	A unique specifier for the actual (as opposed to virtual) node <span style="color: red;">[(string)]</span>
OUT	resultlen	Length (in printable characters) of the result returned in name <span style="color: red;">[(integer)]</span>

```
int MPI_Get_processor_name(char *name, int *resultlen)
```

```
MPI_GET_PROCESSOR_NAME( NAME, RESULTLEN, IERROR)
```

```
CHARACTER*(*) NAME
```

```
INTEGER RESULTLEN, IERROR
```

```
{void MPI::Get_processor_name(char* name, int& resultlen) (binding deprecated,  
see Section ??) }
```

This routine returns the name of the processor on which it was called at the moment of the call. The name is a character string for maximum flexibility. From this value it must be possible to identify a specific piece of hardware; possible values include “processor 9 in rack 4 of mpp.cs.org” and “231” (where 231 is the actual processor number in the running homogeneous system). The argument `name` must represent storage that is at least `MPI_MAX_PROCESSOR_NAME` characters long. `MPI_GET_PROCESSOR_NAME` may write up to this many characters into `name`.

The number of characters actually written is returned in the output argument, `resultlen`. In C, a null character is additionally stored at `name[resultlen]`. The `resultlen` cannot be larger [then] than `MPI_MAX_PROCESSOR_NAME-1`. In Fortran, `name` is padded on the right with blank characters. The `resultlen` cannot be larger [then] than `MPI_MAX_PROCESSOR_NAME`.

*Rationale.* This function allows MPI implementations that do process migration to return the current processor. Note that nothing in MPI *requires* or defines process migration; this definition of `MPI_GET_PROCESSOR_NAME` simply allows such an implementation. (*End of rationale.*)

*Advice to users.* The user must provide at least `MPI_MAX_PROCESSOR_NAME` space to write the processor name — processor names can be this long. The user should

examine the output argument, `resultlen`, to determine the actual length of the name.  
(*End of advice to users.*)

The constant `MPI_BSEND_OVERHEAD` provides an upper bound on the fixed overhead per message buffered by a call to `MPI_BSEND` (see Section ??).

## 2.2 Memory Allocation

In some systems, message-passing and remote-memory-access (RMA) operations run faster when accessing specially allocated memory (e.g., memory that is shared by the other processes in the communicating group on an SMP). MPI provides a mechanism for allocating and freeing such special memory. The use of such memory for message-passing or RMA is not mandatory, and this memory can be used without restrictions as any other dynamically allocated memory. However, implementations may restrict the use of the `MPI_WIN_LOCK` and `MPI_WIN_UNLOCK` functions to windows allocated in such memory (see Section ??).

`MPI_ALLOC_MEM(size, info, baseptr)`

IN	size	size of memory segment in bytes (non-negative integer)
IN	info	info argument (handle)
OUT	baseptr	pointer to beginning of memory segment allocated

`int MPI_Alloc_mem(MPI_Aint size, MPI_Info info, void *baseptr)`

`MPI_ALLOC_MEM(SIZE, INFO, BASEPTR, IERROR)`

INTEGER INFO, IERROR

INTEGER(KIND=MPI\_ADDRESS\_KIND) SIZE, BASEPTR

`{void* MPI::Alloc_mem(MPI::Aint size, const MPI::Info& info) (binding deprecated, see Section ??) }`

The `info` argument can be used to provide directives that control the desired location of the allocated memory. Such a directive does not affect the semantics of the call. Valid `info` values are implementation-dependent; a null directive value of `info = MPI_INFO_NULL` is always valid.

The function `MPI_ALLOC_MEM` may return an error code of class `MPI_ERR_NO_MEM` to indicate it failed because memory is exhausted.

`MPI_FREE_MEM(base)`

IN	base	initial address of memory segment allocated by <code>MPI_ALLOC_MEM</code> (choice)
----	------	--

`int MPI_Free_mem(void *base)`

`MPI_FREE_MEM(BASE, IERROR)`

<type> BASE(\*)

# INTEGER IERROR

```
{void MPI::Free_mem(void *base) (binding deprecated, see Section ??) }
```

The function `MPI_FREE_MEM` may return an error code of class `MPI_ERR_BASE` to indicate an invalid base argument.

*Rationale.* The C and C++ bindings of `MPI_ALLOC_MEM` and `MPI_FREE_MEM` are similar to the bindings for the `malloc` and `free` C library calls: a call to `MPI_Alloc_mem(..., &base)` should be paired with a call to `MPI_Free_mem(base)` (one less level of indirection). Both arguments are declared to be of same type `void*` so as to facilitate type casting. The Fortran binding is consistent with the C and C++ bindings: the Fortran `MPI_ALLOC_MEM` call returns in `baseptr` the (integer valued) address of the allocated memory. The `base` argument of `MPI_FREE_MEM` is a choice argument, which passes (a reference to) the variable stored at that location. (*End of rationale.*)

*Advice to implementors.* If `MPI_ALLOC_MEM` allocates special memory, then a design similar to the design of C `malloc` and `free` functions has to be used, in order to find out the size of a memory segment, when the segment is freed. If no special memory is used, `MPI_ALLOC_MEM` simply invokes `malloc`, and `MPI_FREE_MEM` invokes `free`.

A call to `MPI_ALLOC_MEM` can be used in shared memory systems to allocate memory in a shared memory segment. (*End of advice to implementors.*)

## Example 2.1

Example of use of `MPI_ALLOC_MEM`, in Fortran with pointer support. We assume 4-byte REALs, and assume that pointers are address-sized.

```
REAL A
POINTER (P, A(100,100)) ! no memory is allocated
CALL MPI_ALLOC_MEM(4*100*100, MPI_INFO_NULL, P, IERR)
! memory is allocated
...
A(3,5) = 2.71;
...
CALL MPI_FREE_MEM(A, IERR) ! memory is freed
```

Since standard Fortran does not support (C-like) pointers, this code is not Fortran 77 or Fortran 90 code. Some compilers (in particular, at the time of writing, g77 and Fortran compilers for Intel) do not support this code.

## Example 2.2 Same example, in C

```

float  (* f)[100][100] ;
/* no memory is allocated */
MPI_Alloc_mem(sizeof(float)*100*100, MPI_INFO_NULL, &f);
/* memory allocated */
...
(*f)[5][3] = 2.71;
...
MPI_Free_mem(f);

```

## 2.3 Error Handling

An MPI implementation cannot or may choose not to handle some errors that occur during MPI calls. These can include errors that generate exceptions or traps, such as floating point errors or access violations. The set of errors that are handled by MPI is implementation-dependent. Each such error generates an **MPI exception**.

The above text takes precedence over any text on error handling within this document. Specifically, text that states that errors *will* be handled should be read as *may* be handled.

A user can associate error handlers to three types of objects: communicators, windows, and files. The specified error handling routine will be used for any MPI exception that occurs during a call to MPI for the respective object. MPI calls that are not related to any objects are considered to be attached to the communicator MPI\_COMM\_WORLD. The attachment of error handlers to objects is purely local: different processes may attach different error handlers to corresponding objects.

Several predefined error handlers are available in MPI:

**MPI\_ERRORS\_ARE\_FATAL** The handler, when called, causes the program to abort on all executing processes. This has the same effect as if MPI\_ABORT was called by the process that invoked the handler.

**MPI\_ERRORS\_RETURN** The handler has no effect other than returning the error code to the user.

Implementations may provide additional predefined error handlers and programmers can code their own error handlers.

The error handler MPI\_ERRORS\_ARE\_FATAL is associated by default with MPI\_COMM\_WORLD after initialization. Thus, if the user chooses not to control error handling, every error that MPI handles is treated as fatal. Since (almost) all MPI calls return an error code, a user may choose to handle errors in its main code, by testing the return code of MPI calls and executing a suitable recovery code when the call was not successful. In this case, the error handler MPI\_ERRORS\_RETURN will be used. Usually it is more convenient and more efficient not to test for errors after each MPI call, and have such error handled by a non trivial MPI error handler.

After an error is detected, the state of MPI is undefined. That is, using a user-defined error handler, or MPI\_ERRORS\_RETURN, does *not* necessarily allow the user to continue to use MPI after an error is detected. The purpose of these error handlers is to allow a user to issue user-defined error messages and to take actions unrelated to MPI (such as flushing I/O buffers) before a program exits. An MPI implementation is free to allow MPI to continue after an error but is not required to do so.

*Advice to implementors.* A good quality implementation will, to the greatest possible extent, circumscribe the impact of an error, so that normal processing can continue after an error handler was invoked. The implementation documentation will provide information on the possible effect of each class of errors. (*End of advice to implementors.*)

An MPI error handler is an opaque object, which is accessed by a handle. MPI calls are provided to create new error handlers, to associate error handlers with objects, and to test which error handler is associated with an object. C and C++ have distinct typedefs for user defined error handling callback functions that accept communicator, file, and window arguments. In Fortran there are three user routines.

An error handler object is created by a call to `MPI_XXX_CREATE_ERRHANDLER(function, errhandler)`, where XXX is, respectively, COMM, WIN, or FILE.

An error handler is attached to a communicator, window, or file by a call to `MPI_XXX_SET_ERRHANDLER`. The error handler must be either a predefined error handler, or an error handler that was created by a call to `MPI_XXX_CREATE_ERRHANDLER`, with matching XXX. The predefined error handlers `MPI_ERRORS_RETURN` and `MPI_ERRORS_ARE_FATAL` can be attached to communicators, windows, and files. In C++, the predefined error handler `MPI::ERRORS_THROW_EXCEPTIONS` can also be attached to communicators, windows, and files.

The error handler currently associated with a communicator, window, or file can be retrieved by a call to `MPI_XXX_GET_ERRHANDLER`.

The MPI function `MPI_ERRHANDLER_FREE` can be used to free an error handler that was created by a call to `MPI_XXX_CREATE_ERRHANDLER`.

`MPI_{COMM,WIN,FILE}_GET_ERRHANDLER` behave as if a new error handler object is created. That is, once the error handler is no longer needed, `MPI_ERRHANDLER_FREE` should be called with the error handler returned from `MPI_ERRHANDLER_GET` or `MPI_{COMM,WIN,FILE}_GET_ERRHANDLER` to mark the error handler for deallocation. This provides behavior similar to that of `MPI_COMM_GROUP` and `MPI_GROUP_FREE`.

*Advice to implementors.* High-quality implementation should raise an error when an error handler that was created by a call to `MPI_XXX_CREATE_ERRHANDLER` is attached to an object of the wrong type with a call to `MPI_YYY_SET_ERRHANDLER`. To do so, it is necessary to maintain, with each error handler, information on the typedef of the associated user function. (*End of advice to implementors.*)

The syntax for these calls is given below.

### 2.3.1 Error Handlers for Communicators

`MPI_COMM_CREATE_ERRHANDLER(function, errhandler)`

IN	function	user defined error handling procedure (function)
OUT	errhandler	MPI error handler (handle)

```
int MPI_Comm_create_errhandler(MPI_Comm_errhandler_function *function,
                               MPI_Errhandler *errhandler)
```

```
MPI_COMM_CREATE_ERRHANDLER(FUNCTION, ERRHANDLER, IERROR)
```

```
EXTERNAL FUNCTION
```

```
INTEGER ERRHANDLER, IERROR
```

```
{static MPI::Errhandler
```

```
    MPI::Comm::Create_errhandler(MPI::Comm::Errhandler_function*  
    function) (binding deprecated, see Section ??) }
```

Creates an error handler that can be attached to communicators. This function is identical to MPI\_ERRHANDLER\_CREATE, whose use is deprecated.

The user routine should be, in C, a function of type MPI\_Comm\_errhandler\_function, which is defined as

```
typedef void MPI_Comm_errhandler_function(MPI_Comm *, int *, ...);
```

The first argument is the communicator in use. The second is the error code to be returned by the MPI routine that raised the error. If the routine would have returned MPI\_ERR\_IN\_STATUS, it is the error code returned in the status for the request that caused the error handler to be invoked. The remaining arguments are “stdargs” arguments whose number and meaning is implementation-dependent. An implementation should clearly document these arguments. Addresses are used so that the handler may be written in Fortran. This typedef replaces MPI\_Handler\_function, whose use is deprecated.

In Fortran, the user routine should be of the form:

```
SUBROUTINE COMM_ERRHANDLER_FUNCTION(COMM, ERROR_CODE)
```

```
    INTEGER COMM, ERROR_CODE
```

In C++, the user routine should be of the form:

```
{typedef void MPI::Comm::Errhandler_function(MPI::Comm &, int *, ...);  
    (binding deprecated, see Section ??)}
```

*Rationale.* The variable argument list is provided because it provides an ISO-standard hook for providing additional information to the error handler; without this hook, ISO C prohibits additional arguments. (*End of rationale.*)

*Advice to users.* A newly created communicator inherits the error handler that is associated with the “parent” communicator. In particular, the user can specify a “global” error handler for all communicators by associating this handler with the communicator MPI\_COMM\_WORLD immediately after initialization. (*End of advice to users.*)

```
MPI_COMM_SET_ERRHANDLER(comm, errhandler)
```

```
INOUT    comm                communicator (handle)
```

```
IN        errhandler          new error handler for communicator (handle)
```

```
int MPI_Comm_set_errhandler(MPI_Comm comm, MPI_Errhandler errhandler)
```

```
MPI_COMM_SET_ERRHANDLER(COMM, ERRHANDLER, IERROR)
```

```
INTEGER COMM, ERRHANDLER, IERROR
```

```

1 {void MPI::Comm::Set_errhandler(const MPI::Errhandler& errhandler) (binding
2   deprecated, see Section ??) }
3

```

Attaches a new error handler to a communicator. The error handler must be either a predefined error handler, or an error handler created by a call to MPI\_COMM\_CREATE\_ERRHANDLER. This call is identical to MPI\_ERRHANDLER\_SET, whose use is deprecated.

```

9 MPI_COMM_GET_ERRHANDLER(comm, errhandler)
10

```

IN	comm	communicator (handle)
OUT	errhandler	error handler currently associated with communicator (handle)

```

15 int MPI_Comm_get_errhandler(MPI_Comm comm, MPI_Errhandler *errhandler)
16

```

```

17 MPI_COMM_GET_ERRHANDLER(COMM, ERRHANDLER, IERROR)
18   INTEGER COMM, ERRHANDLER, IERROR
19

```

```

19 {MPI::Errhandler MPI::Comm::Get_errhandler() const (binding deprecated, see
20   Section ??) }
21

```

Retrieves the error handler currently associated with a communicator. This call is identical to MPI\_ERRHANDLER\_GET, whose use is deprecated.

Example: A library function may register at its entry point the current error handler for a communicator, set its own private error handler for this communicator, and restore before exiting the previous error handler.

### 2.3.2 Error Handlers for Windows

```

31 MPI_WIN_CREATE_ERRHANDLER(function, errhandler)
32

```

IN	function	user defined error handling procedure (function)
OUT	errhandler	MPI error handler (handle)

```

36 int MPI_Win_create_errhandler(MPI_Win_errhandler_function *function,
37   MPI_Errhandler *errhandler)
38

```

```

38 MPI_WIN_CREATE_ERRHANDLER(FUNCTION, ERRHANDLER, IERROR)
39   EXTERNAL FUNCTION
40   INTEGER ERRHANDLER, IERROR
41

```

```

42 {static MPI::Errhandler
43   MPI::Win::Create_errhandler(MPI::Win::Errhandler_function*
44   function) (binding deprecated, see Section ??) }
45

```

Creates an error handler that can be attached to a window object. The user routine should be, in C, a function of type MPI\_Win\_errhandler\_function which is defined as

```

47 typedef void MPI_Win_errhandler_function(MPI_Win *, int *, ...);
48

```



The first argument is the window in use, the second is the error code to be returned.

In Fortran, the user routine should be of the form:

```
SUBROUTINE WIN_ERRHANDLER_FUNCTION(WIN, ERROR_CODE)
  INTEGER WIN, ERROR_CODE
```

In C++, the user routine should be of the form:

```
{typedef void MPI::Win::Errhandler_function(MPI::Win &, int *, ...);
  (binding deprecated, see Section ??)}
```

MPI\_WIN\_SET\_ERRHANDLER(win, errhandler)

INOUT	win	window (handle)
IN	errhandler	new error handler for window (handle)

```
int MPI_Win_set_errhandler(MPI_Win win, MPI_Errhandler errhandler)
```

```
MPI_WIN_SET_ERRHANDLER(WIN, ERRHANDLER, IERROR)
  INTEGER WIN, ERRHANDLER, IERROR
```

```
{void MPI::Win::Set_errhandler(const MPI::Errhandler& errhandler) (binding
  deprecated, see Section ??) }
```

Attaches a new error handler to a window. The error handler must be either a pre-defined error handler, or an error handler created by a call to MPI\_WIN\_CREATE\_ERRHANDLER.

MPI\_WIN\_GET\_ERRHANDLER(win, errhandler)

IN	win	window (handle)
OUT	errhandler	error handler currently associated with window (handle)

```
int MPI_Win_get_errhandler(MPI_Win win, MPI_Errhandler *errhandler)
```

```
MPI_WIN_GET_ERRHANDLER(WIN, ERRHANDLER, IERROR)
  INTEGER WIN, ERRHANDLER, IERROR
```

```
{MPI::Errhandler MPI::Win::Get_errhandler() const (binding deprecated, see
  Section ??) }
```

Retrieves the error handler currently associated with a window.

## 2.3.3 Error Handlers for Files

MPI\_FILE\_CREATE\_ERRHANDLER(function, errhandler)

IN	function	user defined error handling procedure (function)
OUT	errhandler	MPI error handler (handle)

```
int MPI_File_create_errhandler(MPI_File_errhandler_function *function,
                               MPI_Errhandler *errhandler)
```

MPI\_FILE\_CREATE\_ERRHANDLER(FUNCTION, ERRHANDLER, IERROR)

EXTERNAL FUNCTION

INTEGER ERRHANDLER, IERROR

```
{static MPI::Errhandler
    MPI::File::Create_errhandler(MPI::File::Errhandler_function*
    function) (binding deprecated, see Section ??) }
```

Creates an error handler that can be attached to a file object. The user routine should be, in C, a function of type MPI\_File\_errhandler\_function, which is defined as

```
typedef void MPI_File_errhandler_function(MPI_File *, int *, ...);
```

The first argument is the file in use, the second is the error code to be returned.

In Fortran, the user routine should be of the form:

```
SUBROUTINE FILE_ERRHANDLER_FUNCTION(FILE, ERROR_CODE)
    INTEGER FILE, ERROR_CODE
```

In C++, the user routine should be of the form:

```
{typedef void MPI::File::Errhandler_function(MPI::File &, int *, ...);
    (binding deprecated, see Section ??)}
```

MPI\_FILE\_SET\_ERRHANDLER(file, errhandler)

INOUT	file	file (handle)
IN	errhandler	new error handler for file (handle)

```
int MPI_File_set_errhandler(MPI_File file, MPI_Errhandler errhandler)
```

MPI\_FILE\_SET\_ERRHANDLER(FILE, ERRHANDLER, IERROR)

INTEGER FILE, ERRHANDLER, IERROR

```
{void MPI::File::Set_errhandler(const MPI::Errhandler& errhandler) (binding
    deprecated, see Section ??) }
```

Attaches a new error handler to a file. The error handler must be either a predefined error handler, or an error handler created by a call to MPI\_FILE\_CREATE\_ERRHANDLER.

MPI\_FILE\_GET\_ERRHANDLER(file, errhandler)

IN	file	file (handle)
OUT	errhandler	error handler currently associated with file (handle)

int MPI\_File\_get\_errhandler(MPI\_File file, MPI\_Errhandler \*errhandler)

MPI\_FILE\_GET\_ERRHANDLER(FILE, ERRHANDLER, IERROR)

INTEGER FILE, ERRHANDLER, IERROR

{MPI::Errhandler MPI::File::Get\_errhandler() const *(binding deprecated, see Section ??)* }

Retrieves the error handler currently associated with a file.

#### 2.3.4 Freeing Errorhandlers and Retrieving Error Strings

MPI\_ERRHANDLER\_FREE( errhandler )

INOUT	errhandler	MPI error handler (handle)
-------	------------	----------------------------

int MPI\_Errhandler\_free(MPI\_Errhandler \*errhandler)

MPI\_ERRHANDLER\_FREE(ERRHANDLER, IERROR)

INTEGER ERRHANDLER, IERROR

{void MPI::Errhandler::Free() *(binding deprecated, see Section ??)* }

Marks the error handler associated with `errhandler` for deallocation and sets `errhandler` to `MPI_ERRHANDLER_NULL`. The error handler will be deallocated after all the objects associated with it (communicator, window, or file) have been deallocated.

MPI\_ERROR\_STRING( errorcode, string, resultlen )

IN	errorcode	Error code returned by an MPI routine
OUT	string	Text that corresponds to the <code>errorcode</code>
OUT	resultlen	Length (in printable characters) of the result returned in string

int MPI\_Error\_string(int errorcode, char \*string, int \*resultlen)

MPI\_ERROR\_STRING(ERRORCODE, STRING, RESULTLEN, IERROR)

INTEGER ERRORCODE, RESULTLEN, IERROR

CHARACTER\*(\*) STRING

{void MPI::Get\_error\_string(int errorcode, char\* name, int& resultlen) *(binding deprecated, see Section ??)* }

Returns the error string associated with an error code or class. The argument `string` must represent storage that is at least `MPI_MAX_ERROR_STRING` characters long.

The number of characters actually written is returned in the output argument, `resultlen`.

*Rationale.* The form of this function was chosen to make the Fortran and C bindings similar. A version that returns a pointer to a string has two difficulties. First, the return string must be statically allocated and different for each error message (allowing the pointers returned by successive calls to `MPI_ERROR_STRING` to point to the correct message). Second, in Fortran, a function declared as returning `CHARACTER*(*)` can not be referenced in, for example, a `PRINT` statement. (*End of rationale.*)

## 2.4 Error Codes and Classes

The error codes returned by MPI are left entirely to the implementation (with the exception of `MPI_SUCCESS`). This is done to allow an implementation to provide as much information as possible in the error code (for use with `MPI_ERROR_STRING`).

To make it possible for an application to interpret an error code, the routine `MPI_ERROR_CLASS` converts any error code into one of a small set of standard error codes, called *error classes*. Valid error classes are shown in Table 2.1 and Table 2.2.

The error classes are a subset of the error codes: an MPI function may return an error class number; and the function `MPI_ERROR_STRING` can be used to compute the error string associated with an error class. An MPI error class is a valid MPI error code. Specifically, the values defined for MPI error classes are valid MPI error codes.

The error codes satisfy,

$$0 = \text{MPI\_SUCCESS} < \text{MPI\_ERR\_...} \leq \text{MPI\_ERR\_LASTCODE}.$$

*Rationale.* The difference between `MPI_ERR_UNKNOWN` and `MPI_ERR_OTHER` is that `MPI_ERROR_STRING` can return useful information about `MPI_ERR_OTHER`.

Note that `MPI_SUCCESS = 0` is necessary to be consistent with C practice; the separation of error classes and error codes allows us to define the error classes this way. Having a known `LASTCODE` is often a nice sanity check as well. (*End of rationale.*)

`MPI_ERROR_CLASS( errorcode, errorclass )`

IN	<code>errorcode</code>	Error code returned by an MPI routine
OUT	<code>errorclass</code>	Error class associated with <code>errorcode</code>

`int MPI_Error_class(int errorcode, int *errorclass)`

`MPI_ERROR_CLASS(ERRORCODE, ERRORCLASS, IERROR)`

INTEGER ERRORCODE, ERRORCLASS, IERROR

`{int MPI::Get_error_class(int errorcode) (binding deprecated, see Section ??) }`

The function `MPI_ERROR_CLASS` maps each standard error code (error class) onto itself.

MPI_SUCCESS	No error
MPI_ERR_BUFFER	Invalid buffer pointer
MPI_ERR_COUNT	Invalid count argument
MPI_ERR_TYPE	Invalid datatype argument
MPI_ERR_TAG	Invalid tag argument
MPI_ERR_COMM	Invalid communicator
MPI_ERR_RANK	Invalid rank
MPI_ERR_REQUEST	Invalid request (handle)
MPI_ERR_ROOT	Invalid root
MPI_ERR_GROUP	Invalid group
MPI_ERR_OP	Invalid operation
MPI_ERR_TOPOLOGY	Invalid topology
MPI_ERR_DIMS	Invalid dimension argument
MPI_ERR_ARG	Invalid argument of some other kind
MPI_ERR_UNKNOWN	Unknown error
MPI_ERR_TRUNCATE	Message truncated on receive
MPI_ERR_OTHER	Known error not in this list
MPI_ERR_INTERN	Internal MPI (implementation) error
MPI_ERR_IN_STATUS	Error code is in status
MPI_ERR_PENDING	Pending request
MPI_ERR_KEYVAL	Invalid keyval has been passed
MPI_ERR_NO_MEM	MPI_ALLOC_MEM failed because memory is exhausted
MPI_ERR_BASE	Invalid base passed to MPI_FREE_MEM
MPI_ERR_INFO_KEY	Key longer than MPI_MAX_INFO_KEY
MPI_ERR_INFO_VALUE	Value longer than MPI_MAX_INFO_VAL
MPI_ERR_INFO_NOKEY	Invalid key passed to MPI_INFO_DELETE
MPI_ERR_SPAWN	Error in spawning processes
MPI_ERR_PORT	Invalid port name passed to MPI_COMM_CONNECT
MPI_ERR_SERVICE	Invalid service name passed to MPI_UNPUBLISH_NAME
MPI_ERR_NAME	Invalid service name passed to MPI_LOOKUP_NAME
MPI_ERR_WIN	Invalid win argument
MPI_ERR_SIZE	Invalid size argument
MPI_ERR_DISP	Invalid disp argument
MPI_ERR_INFO	Invalid info argument
MPI_ERR_LOCKTYPE	Invalid locktype argument
MPI_ERR_ASSERT	Invalid assert argument
MPI_ERR_RMA_CONFLICT	Conflicting accesses to window
MPI_ERR_RMA_SYNC	Wrong synchronization of RMA calls

Table 2.1: Error classes (Part 1)

MPI_ERR_FILE	Invalid file handle
MPI_ERR_NOT_SAME	Collective argument not identical on all processes, or collective routines called in a different order by different processes
MPI_ERR_AMODE	Error related to the <code>amode</code> passed to <code>MPI_FILE_OPEN</code>
MPI_ERR_UNSUPPORTED_DATAREP	Unsupported <code>datarep</code> passed to <code>MPI_FILE_SET_VIEW</code>
MPI_ERR_UNSUPPORTED_OPERATION	Unsupported operation, such as seeking on a file which supports sequential access only
MPI_ERR_NO_SUCH_FILE	File does not exist
MPI_ERR_FILE_EXISTS	File exists
MPI_ERR_BAD_FILE	Invalid file name (e.g., path name too long)
MPI_ERR_ACCESS	Permission denied
MPI_ERR_NO_SPACE	Not enough space
MPI_ERR_QUOTA	Quota exceeded
MPI_ERR_READ_ONLY	Read-only file or file system
MPI_ERR_FILE_IN_USE	File operation could not be completed, as the file is currently open by some process
MPI_ERR_DUP_DATAREP	Conversion functions could not be registered because a data representation identifier that was already defined was passed to <code>MPI_REGISTER_DATAREP</code>
MPI_ERR_CONVERSION	An error occurred in a user supplied data conversion function.
MPI_ERR_IO	Other I/O error
MPI_ERR_LASTCODE	Last error code

Table 2.2: Error classes (Part 2)

## 2.5 Error Classes, Error Codes, and Error Handlers

Users may want to write a layered library on top of an existing MPI implementation, and this library may have its own set of error codes and classes. An example of such a library is an I/O library based on MPI, see Chapter ?? on page ?. For this purpose, functions are needed to:

1. add a new error class to the ones an MPI implementation already knows.
2. associate error codes with this error class, so that `MPI_ERROR_CLASS` works.
3. associate strings with these error codes, so that `MPI_ERROR_STRING` works.
4. invoke the error handler associated with a communicator, window, or object.

Several functions are provided to do this. They are all local. No functions are provided to free error classes or codes: it is not expected that an application will generate them in significant numbers.

```
MPI_ADD_ERROR_CLASS(errorclass)
```

```
    OUT      errorclass      value for the new error class (integer)
```

```
int MPI_Add_error_class(int *errorclass)
```

```
MPI_ADD_ERROR_CLASS(ERRORCLASS, IERROR)
```

```
    INTEGER ERRORCLASS, IERROR
```

```
{int MPI::Add_error_class() (binding deprecated, see Section ??) }
```

Creates a new error class and returns the value for it.

*Rationale.* To avoid conflicts with existing error codes and classes, the value is set by the implementation and not by the user. (*End of rationale.*)

*Advice to implementors.* A high-quality implementation will return the value for a new `errorclass` in the same deterministic way on all processes. (*End of advice to implementors.*)

*Advice to users.* Since a call to `MPI_ADD_ERROR_CLASS` is local, the same `errorclass` may not be returned on all processes that make this call. Thus, it is not safe to assume that registering a new error on a set of processes at the same time will yield the same `errorclass` on all of the processes. However, if an implementation returns the new `errorclass` in a deterministic way, and they are always generated in the same order on the same set of processes (for example, all processes), then the value will be the same. However, even if a deterministic algorithm is used, the value can vary across processes. This can happen, for example, if different but overlapping groups of processes make a series of calls. As a result of these issues, getting the “same” error on multiple processes may not cause the same value of error code to be generated. (*End of advice to users.*)

The value of `MPI_ERR_LASTCODE` is a constant value and is not affected by new user-defined error codes and classes. Instead, a predefined attribute key `MPI_LASTUSED` is associated with `MPI_COMM_WORLD`. The attribute value corresponding to this key is the current maximum error class including the user-defined ones. This is a local value and may be different on different processes. The value returned by this key is always greater than or equal to `MPI_ERR_LASTCODE`.

*Advice to users.* The value returned by the key `MPI_LASTUSED` will not change unless the user calls a function to explicitly add an error class/code. In a multi-threaded environment, the user must take extra care in assuming this value has not changed. Note that error codes and error classes are not necessarily dense. A user may not assume that each error class below `MPI_LASTUSED` is valid. (*End of advice to users.*)

```

1 MPI_ADD_ERROR_CODE(errorclass, errorcode)
2     IN          errorclass          error class (integer)
3
4     OUT         errorcode           new error code to associated with errorclass (integer)

```

```

5
6 int MPI_Add_error_code(int errorclass, int *errorcode)

```

```

7 MPI_ADD_ERROR_CODE(ERRORCLASS, ERRORCODE, IERROR)

```

```

8     INTEGER ERRORCLASS, ERRORCODE, IERROR

```

```

9
10 {int MPI::Add_error_code(int errorclass) (binding deprecated, see Section ??) }

```

```

11
12     Creates new error code associated with errorclass and returns its value in errorcode.

```

*Rationale.* To avoid conflicts with existing error codes and classes, the value of the new error code is set by the implementation and not by the user. (*End of rationale.*)

*Advice to implementors.* A high-quality implementation will return the value for a new `errorcode` in the same deterministic way on all processes. (*End of advice to implementors.*)

```

21
22 MPI_ADD_ERROR_STRING(errorcode, string)

```

```

23     IN          errorcode           error code or class (integer)

```

```

24     IN          string              text corresponding to errorcode (string)

```

```

25
26
27 int MPI_Add_error_string(int errorcode, char *string)

```

```

28 MPI_ADD_ERROR_STRING(ERRORCODE, STRING, IERROR)

```

```

29     INTEGER ERRORCODE, IERROR

```

```

30     CHARACTER*(*) STRING

```

```

31
32 {void MPI::Add_error_string(int errorcode, const char* string) (binding
33     deprecated, see Section ??) }

```

Associates an error string with an error code or class. The string must be no more than `MPI_MAX_ERROR_STRING` characters long. The length of the string is as defined in the calling language. The length of the string does not include the null terminator in C or C++. Trailing blanks will be stripped in Fortran. Calling `MPI_ADD_ERROR_STRING` for an `errorcode` that already has a string will replace the old string with the new string. It is erroneous to call `MPI_ADD_ERROR_STRING` for an error code or class with a value  $\leq$  `MPI_ERR_LASTCODE`.

If `MPI_ERROR_STRING` is called when no string has been set, it will return a empty string (all spaces in Fortran, "" in C and C++).

Section 2.3 on page 23 describes the methods for creating and associating error handlers with communicators, files, and windows.



MPI\_COMM\_CALL\_ERRHANDLER (comm, errorcode)

IN        comm                                communicator with error handler (handle)  
 IN        errorcode                          error code (integer)

int MPI\_Comm\_call\_errhandler(MPI\_Comm comm, int errorcode)

MPI\_COMM\_CALL\_ERRHANDLER(COMM, ERRORCODE, IERROR)

INTEGER COMM, ERRORCODE, IERROR

{void MPI::Comm::Call\_errhandler(int errorcode) const(*binding deprecated, see Section ??*) }

This function invokes the error handler assigned to the communicator with the error code supplied. This function returns MPI\_SUCCESS in C and C++ and the same value in IERROR if the error handler was successfully called (assuming the process is not aborted and the error handler returns).

*Advice to users.* Users should note that the default error handler is MPI\_ERRORS\_ARE\_FATAL. Thus, calling MPI\_COMM\_CALL\_ERRHANDLER will abort the comm processes if the default error handler has not been changed for this communicator or on the parent before the communicator was created. (*End of advice to users.*)

MPI\_WIN\_CALL\_ERRHANDLER (win, errorcode)

IN        win                                window with error handler (handle)  
 IN        errorcode                          error code (integer)

int MPI\_Win\_call\_errhandler(MPI\_Win win, int errorcode)

MPI\_WIN\_CALL\_ERRHANDLER(WIN, ERRORCODE, IERROR)

INTEGER WIN, ERRORCODE, IERROR

{void MPI::Win::Call\_errhandler(int errorcode) const(*binding deprecated, see Section ??*) }

This function invokes the error handler assigned to the window with the error code supplied. This function returns MPI\_SUCCESS in C and C++ and the same value in IERROR if the error handler was successfully called (assuming the process is not aborted and the error handler returns).

*Advice to users.* As with communicators, the default error handler for windows is MPI\_ERRORS\_ARE\_FATAL. (*End of advice to users.*)

MPI\_FILE\_CALL\_ERRHANDLER (fh, errorcode)

IN        fh                                file with error handler (handle)  
 IN        errorcode                          error code (integer)

```

1  int MPI_File_call_errhandler(MPI_File fh, int errorcode)
2
3  MPI_FILE_CALL_ERRHANDLER(FH, ERRORCODE, IERROR)
4      INTEGER FH, ERRORCODE, IERROR
5
6  {void MPI::File::Call_errhandler(int errorcode) const(binding deprecated, see
7      Section ??) }

```

This function invokes the error handler assigned to the file with the error code supplied. This function returns MPI\_SUCCESS in C and C++ and the same value in IERROR if the error handler was successfully called (assuming the process is not aborted and the error handler returns).

*Advice to users.* Unlike errors on communicators and windows, the default behavior for files is to have MPI\_ERRORS\_RETURN. (*End of advice to users.*)

*Advice to users.* Users are warned that handlers should not be called recursively with MPI\_COMM\_CALL\_ERRHANDLER, MPI\_FILE\_CALL\_ERRHANDLER, or MPI\_WIN\_CALL\_ERRHANDLER. Doing this can create a situation where an infinite recursion is created. This can occur if MPI\_COMM\_CALL\_ERRHANDLER, MPI\_FILE\_CALL\_ERRHANDLER, or MPI\_WIN\_CALL\_ERRHANDLER is called inside an error handler.

Error codes and classes are associated with a process. As a result, they may be used in any error handler. Error handlers should be prepared to deal with any error code they are given. Furthermore, it is good practice to only call an error handler with the appropriate error codes. For example, file errors would normally be sent to the file error handler. (*End of advice to users.*)

## 2.6 Timers and Synchronization

MPI defines a timer. A timer is specified even though it is not “message-passing,” because timing parallel programs is important in “performance debugging” and because existing timers (both in POSIX 1003.1-1988 and 1003.4D 14.1 and in Fortran 90) are either inconvenient or do not provide adequate access to high-resolution timers. See also Section 1.6.5 on page 13.

```

36  MPI_WTIME()
37
38  double MPI_Wtime(void)
39
40  DOUBLE PRECISION MPI_WTIME()
41
42  {double MPI::Wtime() (binding deprecated, see Section ??) }

```

MPI\_WTIME returns a floating-point number of seconds, representing elapsed wall-clock time since some time in the past.

The “time in the past” is guaranteed not to change during the life of the process. The user is responsible for converting large numbers of seconds to other units if they are preferred.

This function is portable (it returns seconds, not “ticks”), it allows high-resolution, and carries no unnecessary baggage. One would use it like this:

```
{
    double starttime, endtime;
    starttime = MPI_Wtime();
    .... stuff to be timed ...
    endtime = MPI_Wtime();
    printf("That took %f seconds\n",endtime-starttime);
}
```

The times returned are local to the node that called them. There is no requirement that different nodes return “the same time.” (But see also the discussion of MPI\_WTIME\_IS\_GLOBAL).

MPI\_WTICK()

```
double MPI_Wtick(void)
```

```
DOUBLE PRECISION MPI_WTICK()
```

```
{double MPI::Wtick() (binding deprecated, see Section ??) }
```

MPI\_WTICK returns the resolution of MPI\_WTIME in seconds. That is, it returns, as a double precision value, the number of seconds between successive clock ticks. For example, if the clock is implemented by the hardware as a counter that is incremented every millisecond, the value returned by MPI\_WTICK should be  $10^{-3}$ .

## 2.7 Startup

One goal of MPI is to achieve *source code portability*. By this we mean that a program written using MPI and complying with the relevant language standards is portable as written, and must not require any source code changes when moved from one system to another. This explicitly does *not* say anything about how an MPI program is started or launched from the command line, nor what the user must do to set up the environment in which an MPI program will run. However, an implementation may require some setup to be performed before other MPI routines may be called. To provide for this, MPI includes an initialization routine MPI\_INIT.

MPI\_INIT()

```
int MPI_Init(int *argc, char ***argv)
```

```
MPI_INIT(IERROR)
```

```
INTEGER IERROR
```

```
{void MPI::Init(int& argc, char**& argv) (binding deprecated, see Section ??) }
```

```
{void MPI::Init() (binding deprecated, see Section ??) }
```

All MPI programs must contain exactly one call to an MPI initialization routine: `MPI_INIT` or `MPI_INIT_THREAD`. Subsequent calls to any initialization routines are erroneous. The only MPI functions that may be invoked before the MPI initialization routines are called are `MPI_GET_VERSION`, `MPI_GET_LIBRARY_VERSION`, `MPI_INITIALIZED`, and `MPI_FINALIZED`. The version for ISO C accepts the `argc` and `argv` that are provided by the arguments to `main` or `NULL`:

```
int main(int argc, char **argv)
{
    MPI_Init(&argc, &argv);

    /* parse arguments */
    /* main program */

    MPI_Finalize();    /* see below */
}
```

The Fortran version takes only `IERROR`.

Conforming implementations of MPI are required to allow applications to pass `NULL` for both the `argc` and `argv` arguments of `main` in C and C++. In C++, there is an alternative binding for `MPI::Init` that does not have these arguments at all.

*Rationale.* In some applications, libraries may be making the call to `MPI_Init`, and may not have access to `argc` and `argv` from `main`. It is anticipated that applications requiring special information about the environment or information supplied by `mpirexec` can get that information from environment variables. (*End of rationale.*)

## MPI\_FINALIZE()

```
int MPI_Finalize(void)

MPI_FINALIZE(IERROR)
    INTEGER IERROR

{void MPI::Finalize() (binding deprecated, see Section ??) }
```

This routine cleans up all MPI state. Each process must call `MPI_FINALIZE` before it exits. Unless there has been a call to `MPI_ABORT`, each process must ensure that all pending nonblocking communications are (locally) complete before calling `MPI_FINALIZE`. Further, at the instant at which the last process calls `MPI_FINALIZE`, all pending sends must be matched by a receive, and all pending receives must be matched by a send.

For example, the following program is correct:

Process 0	Process 1
-----	-----
<code>MPI_Init();</code>	<code>MPI_Init();</code>
<code>MPI_Send(dest=1);</code>	<code>MPI_Recv(src=0);</code>
<code>MPI_Finalize();</code>	<code>MPI_Finalize();</code>

Without the matching receive, the program is erroneous:

Process 0	Process 1
-----	-----
MPI_Init();	MPI_Init();
MPI_Send (dest=1);	
MPI_Finalize();	MPI_Finalize();

A successful return from a blocking communication operation or from `MPI_WAIT` or `MPI_TEST` tells the user that the buffer can be reused and means that the communication is completed by the user, but does not guarantee that the local process has no more work to do. A successful return from `MPI_REQUEST_FREE` with a request handle generated by an `MPI_ISEND` nullifies the handle but provides no assurance of operation completion. The `MPI_ISEND` is complete only when it is known by some means that a matching receive has completed. `MPI_FINALIZE` guarantees that all local actions required by communications the user has completed will, in fact, occur before it returns.

`MPI_FINALIZE` guarantees nothing about pending communications that have not been completed (completion is assured only by `MPI_WAIT`, `MPI_TEST`, or `MPI_REQUEST_FREE` combined with some other verification of completion).

**Example 2.3** This program is correct:

rank 0	rank 1
=====	=====
...	...
MPI_Isend();	MPI_Recv();
MPI_Request_free();	MPI_Barrier();
MPI_Barrier();	MPI_Finalize();
MPI_Finalize();	exit();
exit();	

**Example 2.4** This program is erroneous and its behavior is undefined:

rank 0	rank 1
=====	=====
...	...
MPI_Isend();	MPI_Recv();
MPI_Request_free();	MPI_Finalize();
MPI_Finalize();	exit();
exit();	

If no `MPI_BUFFER_DETACH` occurs between an `MPI_BSEND` (or other buffered send) and `MPI_FINALIZE`, the `MPI_FINALIZE` implicitly supplies the `MPI_BUFFER_DETACH`.

**Example 2.5** This program is correct, and after the `MPI_Finalize`, it is as if the buffer had been detached.

```

1      rank 0                                rank 1
2      =====
3      ...
4      buffer = malloc(1000000);              MPI_Recv();
5      MPI_Buffer_attach();                   MPI_Finalize();
6      MPI_Bsend();                           exit();
7      MPI_Finalize();
8      free(buffer);
9      exit();

```

**Example 2.6** In this example, `MPI_Iprobe()` must return a FALSE flag. `MPI_Test_cancelled()` must return a TRUE flag, independent of the relative order of execution of `MPI_Cancel()` in process 0 and `MPI_Finalize()` in process 1.

The `MPI_Iprobe()` call is there to make sure the implementation knows that the “tag1” message exists at the destination, without being able to claim that the user knows about it.

```

19     rank 0                                rank 1
20     =====
21     MPI_Init();                            MPI_Init();
22     MPI_Isend(tag1);                        MPI_Barrier();
23     MPI_Barrier();                          MPI_Iprobe(tag2);
24                                           MPI_Barrier();
25     MPI_Barrier();                          MPI_Finalize();
26                                           exit();
27
28     MPI_Cancel();
29     MPI_Wait();
30     MPI_Test_cancelled();
31     MPI_Finalize();
32     exit();

```

*Advice to implementors.* An implementation may need to delay the return from `MPI_FINALIZE` until all potential future message cancellations have been processed. One possible solution is to place a barrier inside `MPI_FINALIZE` (*End of advice to implementors.*)

Once `MPI_FINALIZE` returns, no MPI routine (not even `MPI_INIT`) may be called, except for `MPI_GET_VERSION`, `MPI_GET_LIBRARY_VERSION`, `MPI_INITIALIZED`, and `MPI_FINALIZED`. Each process must complete any pending communication it initiated before it calls `MPI_FINALIZE`. If the call returns, each process may continue local computations, or exit, without participating in further MPI communication with other processes. `MPI_FINALIZE` is collective over all connected processes. If no processes were spawned, accepted or connected then this means over `MPI_COMM_WORLD`; otherwise it is collective over the union of all processes that have been and continue to be connected, as explained in Section ?? on page ??.

*Advice to implementors.* Even though a process has completed all the communication it initiated, such communication may not yet be completed from the viewpoint of the underlying MPI system. E.g., a blocking send may have completed, even though the data is still buffered at the sender. The MPI implementation must ensure that a process has completed any involvement in MPI communication before MPI\_FINALIZE returns. Thus, if a process exits after the call to MPI\_FINALIZE, this will not cause an ongoing communication to fail. (*End of advice to implementors.*)

Although it is not required that all processes return from MPI\_FINALIZE, it is required that at least process 0 in MPI\_COMM\_WORLD return, so that users can know that the MPI portion of the computation is over. In addition, in a POSIX environment, they may desire to supply an exit code for each process that returns from MPI\_FINALIZE.

**Example 2.7** The following illustrates the use of requiring that at least one process return and that it be known that process 0 is one of the processes that return. One wants code like the following to work no matter how many processes return.

```
...
MPI_Comm_rank(MPI_COMM_WORLD, &myrank);
...
MPI_Finalize();
if (myrank == 0) {
    resultfile = fopen("outfile","w");
    dump_results(resultfile);
    fclose(resultfile);
}
exit(0);
```

MPI\_INITIALIZED( flag )

OUT	flag	Flag is true if MPI_INIT has been called and false otherwise.
-----	------	---

int MPI\_Initialized(int \*flag)

MPI\_INITIALIZED(FLAG, IERROR)

LOGICAL FLAG

INTEGER IERROR

{bool MPI::Is\_initialized() (*binding deprecated, see Section ??*) }

This routine may be used to determine whether MPI\_INIT has been called. MPI\_INITIALIZED returns true if the calling process has called MPI\_INIT. Whether MPI\_FINALIZE has been called does not affect the behavior of MPI\_INITIALIZED. It is one of the few routines that may be called before MPI\_INIT is called.

```

1 MPI_ABORT( comm, errorcode )
2     IN      comm      communicator of tasks to abort
3     IN      errorcode  error code to return to invoking environment
4
5
6 int MPI_Abort(MPI_Comm comm, int errorcode)
7 MPI_ABORT(COMM, ERRORCODE, IERROR)
8     INTEGER COMM, ERRORCODE, IERROR
9
10 {void MPI::Comm::Abort(int errorcode) (binding deprecated, see Section ??) }

```

This routine makes a “best attempt” to abort all tasks in the group of `comm`. This function does not require that the invoking environment take any action with the error code. However, a Unix or POSIX environment should handle this as a `return errorcode` from the main program.

It may not be possible for an MPI implementation to abort only the processes represented by `comm` if this is a subset of the processes. In this case, the MPI implementation should attempt to abort all the connected processes but should not abort any unconnected processes. If no processes were spawned, accepted or connected then this has the effect of aborting all the processes associated with `MPI_COMM_WORLD`.

*Rationale.* The communicator argument is provided to allow for future extensions of MPI to environments with, for example, dynamic process management. In particular, it allows but does not require an MPI implementation to abort a subset of `MPI_COMM_WORLD`. (*End of rationale.*)

*Advice to users.* Whether the errorcode is returned from the executable or from the MPI process startup mechanism (e.g., `mpiexec`), is an aspect of quality of the MPI library but not mandatory. (*End of advice to users.*)

*Advice to implementors.* Where possible, a high-quality implementation will try to return the errorcode from the MPI process startup mechanism (e.g. `mpiexec` or singleton init). (*End of advice to implementors.*)

### 2.7.1 Allowing User Functions at Process Termination

There are times in which it would be convenient to have actions happen when an MPI process finishes. For example, a routine may do initializations that are useful until the MPI job (or that part of the job that being terminated in the case of dynamically created processes) is finished. This can be accomplished in MPI by attaching an attribute to `MPI_COMM_SELF` with a callback function. When `MPI_FINALIZE` is called, it will first execute the equivalent of an `MPI_COMM_FREE` on `MPI_COMM_SELF`. This will cause the delete callback function to be executed on all keys associated with `MPI_COMM_SELF`, in the reverse order that they were set on `MPI_COMM_SELF`. If no key has been attached to `MPI_COMM_SELF`, then no callback is invoked. The “freeing” of `MPI_COMM_SELF` occurs before any other parts of MPI are affected. Thus, for example, calling `MPI_FINALIZED` will return false in any of these callback functions. Once done with `MPI_COMM_SELF`, the order and rest of the actions taken by `MPI_FINALIZE` is not specified.



*Advice to implementors.* Since attributes can be added from any supported language, the MPI implementation needs to remember the creating language so the correct callback is made. Implementations that use the attribute delete callback on MPI\_COMM\_SELF internally should register their internal callbacks before returning from MPI\_INIT / MPI\_INIT\_THREAD, so that libraries or applications will not have portions of the MPI implementation shut down before the application-level callbacks are made. (*End of advice to implementors.*)

### 2.7.2 Determining Whether MPI Has Finished

One of the goals of MPI was to allow for layered libraries. In order for a library to do this cleanly, it needs to know if MPI is active. In MPI the function `MPI_INITIALIZED` was provided to tell if MPI had been initialized. The problem arises in knowing if MPI has been finalized. Once MPI has been finalized it is no longer active and cannot be restarted. A library needs to be able to determine this to act accordingly. To achieve this the following function is needed:

MPI\_FINALIZED(flag)

OUT	flag	true if MPI was finalized (logical)
-----	------	-------------------------------------

```
int MPI_Finalized(int *flag)
```

MPI\_FINALIZED(FLAG, IERROR)

LOGICAL FLAG

INTEGER IERROR

```
{bool MPI::Is_finalized() (binding deprecated, see Section ??) }
```

This routine returns true if MPI\_FINALIZE has completed. It is legal to call MPI\_FINALIZED before MPI\_INIT and after MPI\_FINALIZE.

*Advice to users.* MPI is “active” and it is thus safe to call MPI functions if MPI\_INIT has completed and MPI\_FINALIZE has not completed. If a library has no other way of knowing whether MPI is active or not, then it can use MPI\_INITIALIZED and MPI\_FINALIZED to determine this. For example, MPI is “active” in callback functions that are invoked during MPI\_FINALIZE. (*End of advice to users.*)

## 2.8 Portable MPI Process Startup

A number of implementations of MPI provide a startup command for MPI programs that is of the form

```
mpirun <mpirun arguments> <program> <program arguments>
```

Separating the command to start the program from the program itself provides flexibility, particularly for network and heterogeneous implementations. For example, the startup script need not run on one of the machines that will be executing the MPI program itself.

Having a standard startup mechanism also extends the portability of MPI programs one step further, to the command lines and scripts that manage them. For example, a validation

suite script that runs hundreds of programs can be a portable script if it is written using such a standard startup mechanism. In order that the “standard” command not be confused with existing practice, which is not standard and not portable among implementations, instead of `mpirun` MPI specifies `mpiexec`.

While a standardized startup mechanism improves the usability of MPI, the range of environments is so diverse (e.g., there may not even be a command line interface) that MPI cannot mandate such a mechanism. Instead, MPI specifies an `mpiexec` startup command and recommends but does not require it, as advice to implementors. However, if an implementation does provide a command called `mpiexec`, it must be of the form described below.

It is suggested that

```
mpiexec -n <numprocs> <program>
```

be at least one way to start `<program>` with an initial `MPI_COMM_WORLD` whose group contains `<numprocs>` processes. Other arguments to `mpiexec` may be implementation-dependent.

*Advice to implementors.* Implementors, if they do provide a special startup command for MPI programs, are advised to give it the following form. The syntax is chosen in order that `mpiexec` be able to be viewed as a command-line version of `MPI_COMM_SPAWN` (See Section ??).

Analogous to `MPI_COMM_SPAWN`, we have

```
mpiexec -n    <maxprocs>
           -soft <      >
           -host <      >
           -arch <      >
           -wdir <      >
           -path <      >
           -file <      >
           ...
           <command line>
```

for the case where a single command line for the application program and its arguments will suffice. See Section ?? for the meanings of these arguments. For the case corresponding to `MPI_COMM_SPAWN_MULTIPLE` there are two possible formats:

Form A:

```
mpiexec { <above arguments> } : { ... } : { ... } : ... : { ... }
```

As with `MPI_COMM_SPAWN`, all the arguments are optional. (Even the `-n x` argument is optional; the default is implementation dependent. It might be 1, it might be taken from an environment variable, or it might be specified at compile time.) The names and meanings of the arguments are taken from the keys in the `info` argument to `MPI_COMM_SPAWN`. There may be other, implementation-dependent arguments as well.

Note that Form A, though convenient to type, prevents colons from being program arguments. Therefore an alternate, file-based form is allowed:

Form B:

```
mpiexec -configfile <filename>
```

where the lines of <filename> are of the form separated by the colons in Form A. Lines beginning with '#' are comments, and lines may be continued by terminating the partial line with '\'.

**Example 2.8** Start 16 instances of `myprog` on the current or default machine:

```
mpiexec -n 16 myprog
```

**Example 2.9** Start 10 processes on the machine called `ferrari`:

```
mpiexec -n 10 -host ferrari myprog
```

**Example 2.10** Start three copies of the same program with different command-line arguments:

```
mpiexec myprog infile1 : myprog infile2 : myprog infile3
```

**Example 2.11** Start the `ocean` program on five Suns and the `atmos` program on 10 RS/6000's:

```
mpiexec -n 5 -arch sun ocean : -n 10 -arch rs6000 atmos
```

It is assumed that the implementation in this case has a method for choosing hosts of the appropriate type. Their ranks are in the order specified.

**Example 2.12** Start the `ocean` program on five Suns and the `atmos` program on 10 RS/6000's (Form B):

```
mpiexec -configfile myfile
```

where `myfile` contains

```
-n 5 -arch sun    ocean
-n 10 -arch rs6000 atmos
```

*(End of advice to implementors.)*

## Chapter 3

# Language Bindings Summary

In this section we summarize the specific bindings for C, Fortran, and C++. First we present the constants, type definitions, info values and keys. Then we present the routine prototypes separately for each binding. Listings are alphabetical within chapter.

### 3.1 Defined Values and Handles

#### 3.1.1 Defined Constants

The C and Fortran name is listed in the left column and the C++ name is listed in the middle or right column. Constants with the type `const int` may also be implemented as literal integer constants substituted by the preprocessor.

Return Codes	
C type: <code>const int</code> (or unnamed <code>enum</code> ) Fortran type: <code>INTEGER</code>	C++ type: <code>const int</code> (or unnamed <code>enum</code> )
<code>MPI_SUCCESS</code>	<code>MPI::SUCCESS</code>
<code>MPI_ERR_BUFFER</code>	<code>MPI::ERR_BUFFER</code>
<code>MPI_ERR_COUNT</code>	<code>MPI::ERR_COUNT</code>
<code>MPI_ERR_TYPE</code>	<code>MPI::ERR_TYPE</code>
<code>MPI_ERR_TAG</code>	<code>MPI::ERR_TAG</code>
<code>MPI_ERR_COMM</code>	<code>MPI::ERR_COMM</code>
<code>MPI_ERR_RANK</code>	<code>MPI::ERR_RANK</code>
<code>MPI_ERR_REQUEST</code>	<code>MPI::ERR_REQUEST</code>
<code>MPI_ERR_ROOT</code>	<code>MPI::ERR_ROOT</code>
<code>MPI_ERR_GROUP</code>	<code>MPI::ERR_GROUP</code>
<code>MPI_ERR_OP</code>	<code>MPI::ERR_OP</code>
<code>MPI_ERR_TOPOLOGY</code>	<code>MPI::ERR_TOPOLOGY</code>
<code>MPI_ERR_DIMS</code>	<code>MPI::ERR_DIMS</code>
<code>MPI_ERR_ARG</code>	<code>MPI::ERR_ARG</code>
<code>MPI_ERR_UNKNOWN</code>	<code>MPI::ERR_UNKNOWN</code>
<code>MPI_ERR_TRUNCATE</code>	<code>MPI::ERR_TRUNCATE</code>
<code>MPI_ERR_OTHER</code>	<code>MPI::ERR_OTHER</code>
<code>MPI_ERR_INTERN</code>	<code>MPI::ERR_INTERN</code>
<code>MPI_ERR_PENDING</code>	<code>MPI::ERR_PENDING</code>

(Continued on next page)

**Return Codes (continued)**

MPI_ERR_IN_STATUS	MPI::ERR_IN_STATUS
MPI_ERR_ACCESS	MPI::ERR_ACCESS
MPI_ERR_AMODE	MPI::ERR_AMODE
MPI_ERR_ASSERT	MPI::ERR_ASSERT
MPI_ERR_BAD_FILE	MPI::ERR_BAD_FILE
MPI_ERR_BASE	MPI::ERR_BASE
MPI_ERR_CONVERSION	MPI::ERR_CONVERSION
MPI_ERR_DISP	MPI::ERR_DISP
MPI_ERR_DUP_DATAREP	MPI::ERR_DUP_DATAREP
MPI_ERR_FILE_EXISTS	MPI::ERR_FILE_EXISTS
MPI_ERR_FILE_IN_USE	MPI::ERR_FILE_IN_USE
MPI_ERR_FILE	MPI::ERR_FILE
MPI_ERR_INFO_KEY	MPI::ERR_INFO_VALUE
MPI_ERR_INFO_NOKEY	MPI::ERR_INFO_NOKEY
MPI_ERR_INFO_VALUE	MPI::ERR_INFO_KEY
MPI_ERR_INFO	MPI::ERR_INFO
MPI_ERR_IO	MPI::ERR_IO
MPI_ERR_KEYVAL	MPI::ERR_KEYVAL
MPI_ERR_LOCKTYPE	MPI::ERR_LOCKTYPE
MPI_ERR_NAME	MPI::ERR_NAME
MPI_ERR_NO_MEM	MPI::ERR_NO_MEM
MPI_ERR_NOT_SAME	MPI::ERR_NOT_SAME
MPI_ERR_NO_SPACE	MPI::ERR_NO_SPACE
MPI_ERR_NO_SUCH_FILE	MPI::ERR_NO_SUCH_FILE
MPI_ERR_PORT	MPI::ERR_PORT
MPI_ERR_QUOTA	MPI::ERR_QUOTA
MPI_ERR_READ_ONLY	MPI::ERR_READ_ONLY
MPI_ERR_RMA_CONFLICT	MPI::ERR_RMA_CONFLICT
MPI_ERR_RMA_SYNC	MPI::ERR_RMA_SYNC
MPI_ERR_SERVICE	MPI::ERR_SERVICE
MPI_ERR_SIZE	MPI::ERR_SIZE
MPI_ERR_SPAWN	MPI::ERR_SPAWN
MPI_ERR_UNSUPPORTED_DATAREP	MPI::ERR_UNSUPPORTED_DATAREP
MPI_ERR_UNSUPPORTED_OPERATION	MPI::ERR_UNSUPPORTED_OPERATION
MPI_ERR_WIN	MPI::ERR_WIN
MPI_ERR_LASTCODE	MPI::ERR_LASTCODE

**Buffer Address Constants**

C type: <code>void * const</code>	C++ type:
Fortran type: (predefined memory location)	<code>void * const</code>
MPI_BOTTOM	MPI::BOTTOM
MPI_IN_PLACE	MPI::IN_PLACE

**Assorted Constants**

C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER</code>	<code>const int</code> (or unnamed <code>enum</code> )
<code>MPI_PROC_NULL</code>	<code>MPI::PROC_NULL</code>
<code>MPI_ANY_SOURCE</code>	<code>MPI::ANY_SOURCE</code>
<code>MPI_ANY_TAG</code>	<code>MPI::ANY_TAG</code>
<code>MPI_UNDEFINED</code>	<code>MPI::UNDEFINED</code>
<code>MPI_BSEND_OVERHEAD</code>	<code>MPI::BSEND_OVERHEAD</code>
<code>MPI_KEYVAL_INVALID</code>	<code>MPI::KEYVAL_INVALID</code>
<code>MPI_LOCK_EXCLUSIVE</code>	<code>MPI::LOCK_EXCLUSIVE</code>
<code>MPI_LOCK_SHARED</code>	<code>MPI::LOCK_SHARED</code>
<code>MPI_ROOT</code>	<code>MPI::ROOT</code>

**Status size and reserved index values (Fortran only)**

Fortran type: <code>INTEGER</code>	
<code>MPI_STATUS_SIZE</code>	Not defined for C++
<code>MPI_SOURCE</code>	Not defined for C++
<code>MPI_TAG</code>	Not defined for C++
<code>MPI_ERROR</code>	Not defined for C++

**Variable Address Size (Fortran only)**

Fortran type: <code>INTEGER</code>	
<code>MPI_ADDRESS_KIND</code>	Not defined for C++
<code>MPI_INTEGER_KIND</code>	Not defined for C++
<code>MPI_OFFSET_KIND</code>	Not defined for C++

**Error-handling specifiers**

C type: <code>MPI_Errhandler</code>	C++ type: <code>MPI::Errhandler</code>
Fortran type: <code>INTEGER</code>	
<code>MPI_ERRORS_ARE_FATAL</code>	<code>MPI::ERRORS_ARE_FATAL</code>
<code>MPI_ERRORS_RETURN</code>	<code>MPI::ERRORS_RETURN</code>
	<code>MPI::ERRORS_THROW_EXCEPTIONS</code>

**Maximum Sizes for Strings**

C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER</code>	<code>const int</code> (or unnamed <code>enum</code> )
<code>MPI_MAX_PROCESSOR_NAME</code>	<code>MPI::MAX_PROCESSOR_NAME</code>
<code>[ticket204.] MPI_MAX_LIBRARY_VERSION_STRING</code>	
<code>MPI_MAX_ERROR_STRING</code>	<code>MPI::MAX_ERROR_STRING</code>
<code>MPI_MAX_DATAREP_STRING</code>	<code>MPI::MAX_DATAREP_STRING</code>
<code>MPI_MAX_INFO_KEY</code>	<code>MPI::MAX_INFO_KEY</code>
<code>MPI_MAX_INFO_VAL</code>	<code>MPI::MAX_INFO_VAL</code>
<code>MPI_MAX_OBJECT_NAME</code>	<code>MPI::MAX_OBJECT_NAME</code>
<code>MPI_MAX_PORT_NAME</code>	<code>MPI::MAX_PORT_NAME</code>

Named Predefined Datatypes		C/C++ types
C type: MPI_Datatype	C++ type: MPI::Datatype	
Fortran type: INTEGER		
MPI_CHAR	MPI::CHAR	char
		(treated as printable character)
MPI_SHORT	MPI::SHORT	signed short int
MPI_INT	MPI::INT	signed int
MPI_LONG	MPI::LONG	signed long
MPI_LONG_LONG_INT	MPI::LONG_LONG_INT	signed long long
MPI_LONG_LONG	MPI::LONG_LONG	long long (synonym)
MPI_SIGNED_CHAR	MPI::SIGNED_CHAR	signed char
		(treated as integral value)
MPI_UNSIGNED_CHAR	MPI::UNSIGNED_CHAR	unsigned char
		(treated as integral value)
MPI_UNSIGNED_SHORT	MPI::UNSIGNED_SHORT	unsigned short
MPI_UNSIGNED	MPI::UNSIGNED	unsigned int
MPI_UNSIGNED_LONG	MPI::UNSIGNED_LONG	unsigned long
MPI_UNSIGNED_LONG_LONG	MPI::UNSIGNED_LONG_LONG	unsigned long long
MPI_FLOAT	MPI::FLOAT	float
MPI_DOUBLE	MPI::DOUBLE	double
MPI_LONG_DOUBLE	MPI::LONG_DOUBLE	long double
MPI_WCHAR	MPI::WCHAR	wchar_t
		(defined in <stddef.h>)
		(treated as printable character)
MPI_C_BOOL	(use C datatype handle)	_Bool
MPI_INT8_T	(use C datatype handle)	int8_t
MPI_INT16_T	(use C datatype handle)	int16_t
MPI_INT32_T	(use C datatype handle)	int32_t
MPI_INT64_T	(use C datatype handle)	int64_t
MPI_UINT8_T	(use C datatype handle)	uint8_t
MPI_UINT16_T	(use C datatype handle)	uint16_t
MPI_UINT32_T	(use C datatype handle)	uint32_t
MPI_UINT64_T	(use C datatype handle)	uint64_t
MPI_AINT	(use C datatype handle)	MPI_Aint
MPI_OFFSET	(use C datatype handle)	MPI_Offset
MPI_C_COMPLEX	(use C datatype handle)	float _Complex
MPI_C_FLOAT_COMPLEX	(use C datatype handle)	float _Complex
MPI_C_DOUBLE_COMPLEX	(use C datatype handle)	double _Complex
MPI_C_LONG_DOUBLE_COMPLEX	(use C datatype handle)	long double _Complex
MPI_BYTE	MPI::BYTE	(any C/C++ type)
MPI_PACKED	MPI::PACKED	(any C/C++ type)

Named Predefined Datatypes		Fortran types
C type: MPI_Datatype	C++ type: MPI::Datatype	
Fortran type: INTEGER		
MPI_INTEGER	MPI::INTEGER	INTEGER
MPI_REAL	MPI::REAL	REAL
MPI_DOUBLE_PRECISION	MPI::DOUBLE_PRECISION	DOUBLE PRECISION
MPI_COMPLEX	MPI::F_COMPLEX	COMPLEX
MPI_LOGICAL	MPI::LOGICAL	LOGICAL
MPI_CHARACTER	MPI::CHARACTER	CHARACTER(1)
MPI_AINT	(use C datatype handle)	INTEGER (KIND=MPI_ADDRESS_KIND)
MPI_OFFSET	(use C datatype handle)	INTEGER (KIND=MPI_OFFSET_KIND)
MPI_BYTE	MPI::BYTE	(any Fortran type)
MPI_PACKED	MPI::PACKED	(any Fortran type)

C++-Only Named Predefined Datatypes	C++ types
C++ type: MPI::Datatype	
MPI::BOOL	bool
MPI::COMPLEX	Complex<float>
MPI::DOUBLE_COMPLEX	Complex<double>
MPI::LONG_DOUBLE_COMPLEX	Complex<long double>

Optional datatypes (Fortran)		Fortran types
C type: MPI_Datatype	C++ type: MPI::Datatype	
Fortran type: INTEGER		
MPI_DOUBLE_COMPLEX	MPI::F_DOUBLE_COMPLEX	DOUBLE COMPLEX
MPI_INTEGER1	MPI::INTEGER1	INTEGER*1
MPI_INTEGER2	MPI::INTEGER2	INTEGER*8
MPI_INTEGER4	MPI::INTEGER4	INTEGER*4
MPI_INTEGER8	MPI::INTEGER8	INTEGER*8
MPI_INTEGER16		INTEGER*16
MPI_REAL2	MPI::REAL2	REAL*2
MPI_REAL4	MPI::REAL4	REAL*4
MPI_REAL8	MPI::REAL8	REAL*8
MPI_REAL16		REAL*16
MPI_COMPLEX4		COMPLEX*4
MPI_COMPLEX8		COMPLEX*8
MPI_COMPLEX16		COMPLEX*16
MPI_COMPLEX32		COMPLEX*32



**Datatypes for reduction functions (C and C++)**

C type: MPI_Datatype	C++ type: MPI::Datatype
Fortran type: INTEGER	

MPI_FLOAT_INT	MPI::FLOAT_INT
MPI_DOUBLE_INT	MPI::DOUBLE_INT
MPI_LONG_INT	MPI::LONG_INT
MPI_2INT	MPI::TWOINT
MPI_SHORT_INT	MPI::SHORT_INT
MPI_LONG_DOUBLE_INT	MPI::LONG_DOUBLE_INT

**Datatypes for reduction functions (Fortran)**

C type: MPI_Datatype	C++ type: MPI::Datatype
Fortran type: INTEGER	

MPI_2REAL	MPI::TWOREAL
MPI_2DOUBLE_PRECISION	MPI::TWODOUBLE_PRECISION
MPI_2INTEGER	MPI::TWOINTEGER

**Special datatypes for constructing derived datatypes**

C type: MPI_Datatype	C++ type: MPI::Datatype
Fortran type: INTEGER	

MPI_UB	MPI::UB
MPI_LB	MPI::LB

**Reserved communicators**

C type: MPI_Comm	C++ type: MPI::Intracomm
Fortran type: INTEGER	

MPI_COMM_WORLD	MPI::COMM_WORLD
MPI_COMM_SELF	MPI::COMM_SELF

**Results of communicator and group comparisons**

C type: const int (or unnamed enum)	C++ type: const int
Fortran type: INTEGER	(or unnamed enum)

MPI_IDENT	MPI::IDENT
MPI_CONGRUENT	MPI::CONGRUENT
MPI_SIMILAR	MPI::SIMILAR
MPI_UNEQUAL	MPI::UNEQUAL

**Environmental inquiry keys**

C type: const int (or unnamed enum)	C++ type: const int
Fortran type: INTEGER	(or unnamed enum)

MPI_TAG_UB	MPI::TAG_UB
MPI_IO	MPI::IO
MPI_HOST	MPI::HOST
MPI_WTIME_IS_GLOBAL	MPI::WTIME_IS_GLOBAL

**Collective Operations**

C type: MPI_Op	C++ type: const MPI::Op
Fortran type: INTEGER	
MPI_MAX	MPI::MAX
MPI_MIN	MPI::MIN
MPI_SUM	MPI::SUM
MPI_PROD	MPI::PROD
MPI_MAXLOC	MPI::MAXLOC
MPI_MINLOC	MPI::MINLOC
MPI_BAND	MPI::BAND
MPI_BOR	MPI::BOR
MPI_BXOR	MPI::BXOR
MPI_LAND	MPI::LAND
MPI_LOR	MPI::LOR
MPI_LXOR	MPI::LXOR
MPI_REPLACE	MPI::REPLACE

**Null Handles**

C/Fortran name	C++ name
C type / Fortran type	C++ type
MPI_GROUP_NULL	MPI::GROUP_NULL
MPI_Group / INTEGER	const MPI::Group
MPI_COMM_NULL	MPI::COMM_NULL
MPI_Comm / INTEGER	<sup>1)</sup>
MPI_DATATYPE_NULL	MPI::DATATYPE_NULL
MPI_Datatype / INTEGER	const MPI::Datatype
MPI_REQUEST_NULL	MPI::REQUEST_NULL
MPI_Request / INTEGER	const MPI::Request
MPI_OP_NULL	MPI::OP_NULL
MPI_Op / INTEGER	const MPI::Op
MPI_ERRHANDLER_NULL	MPI::ERRHANDLER_NULL
MPI_Errhandler / INTEGER	const MPI::Errhandler
MPI_FILE_NULL	MPI::FILE_NULL
MPI_File / INTEGER	
MPI_INFO_NULL	MPI::INFO_NULL
MPI_Info / INTEGER	const MPI::Info
MPI_WIN_NULL	MPI::WIN_NULL
MPI_Win / INTEGER	

<sup>1)</sup> C++ type: See Section ?? on page ?? regarding class hierarchy and the specific type of MPI::COMM\_NULL

**Empty group**

C type: MPI_Group	C++ type: const MPI::Group
Fortran type: INTEGER	
MPI_GROUP_EMPTY	MPI::GROUP_EMPTY

**Topologies**

C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type: <code>const int</code>
Fortran type: <code>INTEGER</code>	(or unnamed <code>enum</code> )
<code>MPI_GRAPH</code>	<code>MPI::GRAPH</code>
<code>MPI_CART</code>	<code>MPI::CART</code>
<code>MPI_DIST_GRAPH</code>	<code>MPI::DIST_GRAPH</code>

**Predefined functions**

C/Fortran name	C++ name
C type / Fortran type	C++ type
<code>MPI_COMM_NULL_COPY_FN</code>	<code>MPI_COMM_NULL_COPY_FN</code>
<code>MPI_Comm_copy_attr_function</code>	same as in C <sup>1</sup> )
<code>/ COMM_COPY_ATTR_FN</code>	
<code>MPI_COMM_DUP_FN</code>	<code>MPI_COMM_DUP_FN</code>
<code>MPI_Comm_copy_attr_function</code>	same as in C <sup>1</sup> )
<code>/ COMM_COPY_ATTR_FN</code>	
<code>MPI_COMM_NULL_DELETE_FN</code>	<code>MPI_COMM_NULL_DELETE_FN</code>
<code>MPI_Comm_delete_attr_function</code>	same as in C <sup>1</sup> )
<code>/ COMM_DELETE_ATTR_FN</code>	
<code>MPI_WIN_NULL_COPY_FN</code>	<code>MPI_WIN_NULL_COPY_FN</code>
<code>MPI_Win_copy_attr_function</code>	same as in C <sup>1</sup> )
<code>/ WIN_COPY_ATTR_FN</code>	
<code>MPI_WIN_DUP_FN</code>	<code>MPI_WIN_DUP_FN</code>
<code>MPI_Win_copy_attr_function</code>	same as in C <sup>1</sup> )
<code>/ WIN_COPY_ATTR_FN</code>	
<code>MPI_WIN_NULL_DELETE_FN</code>	<code>MPI_WIN_NULL_DELETE_FN</code>
<code>MPI_Win_delete_attr_function</code>	same as in C <sup>1</sup> )
<code>/ WIN_DELETE_ATTR_FN</code>	
<code>MPI_TYPE_NULL_COPY_FN</code>	<code>MPI_TYPE_NULL_COPY_FN</code>
<code>MPI_Type_copy_attr_function</code>	same as in C <sup>1</sup> )
<code>/ TYPE_COPY_ATTR_FN</code>	
<code>MPI_TYPE_DUP_FN</code>	<code>MPI_TYPE_DUP_FN</code>
<code>MPI_Type_copy_attr_function</code>	same as in C <sup>1</sup> )
<code>/ TYPE_COPY_ATTR_FN</code>	
<code>MPI_TYPE_NULL_DELETE_FN</code>	<code>MPI_TYPE_NULL_DELETE_FN</code>
<code>MPI_Type_delete_attr_function</code>	same as in C <sup>1</sup> )
<code>/ TYPE_DELETE_ATTR_FN</code>	

<sup>1</sup> See the advice to implementors on `MPI_COMM_NULL_COPY_FN`, ... in Section ?? on page ??

**Deprecated predefined functions**

C/Fortran name	C++ name
C type / Fortran type	C++ type
MPI_NULL_COPY_FN	MPI::NULL_COPY_FN
MPI_Copy_function / COPY_FUNCTION	MPI::Copy_function
MPI_DUP_FN	MPI::DUP_FN
MPI_Copy_function / COPY_FUNCTION	MPI::Copy_function
MPI_NULL_DELETE_FN	MPI::NULL_DELETE_FN
MPI_Delete_function / DELETE_FUNCTION	MPI::Delete_function

**Predefined Attribute Keys**

C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER</code>	<code>const int</code> (or unnamed <code>enum</code> )
MPI_APPNUM	MPI::APPNUM
MPI_LASTUSEDPCODE	MPI::LASTUSEDPCODE
MPI_UNIVERSE_SIZE	MPI::UNIVERSE_SIZE
MPI_WIN_BASE	MPI::WIN_BASE
MPI_WIN_DISP_UNIT	MPI::WIN_DISP_UNIT
MPI_WIN_SIZE	MPI::WIN_SIZE

**Mode Constants**

C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER</code>	<code>const int</code> (or unnamed <code>enum</code> )
MPI_MODE_APPEND	MPI::MODE_APPEND
MPI_MODE_CREATE	MPI::MODE_CREATE
MPI_MODE_DELETE_ON_CLOSE	MPI::MODE_DELETE_ON_CLOSE
MPI_MODE_EXCL	MPI::MODE_EXCL
MPI_MODE_NOCHECK	MPI::MODE_NOCHECK
MPI_MODE_NOPRECEDE	MPI::MODE_NOPRECEDE
MPI_MODE_NOPUT	MPI::MODE_NOPUT
MPI_MODE_NOSTORE	MPI::MODE_NOSTORE
MPI_MODE_NOSUCCEED	MPI::MODE_NOSUCCEED
MPI_MODE_RDONLY	MPI::MODE_RDONLY
MPI_MODE_RDWR	MPI::MODE_RDWR
MPI_MODE_SEQUENTIAL	MPI::MODE_SEQUENTIAL
MPI_MODE_UNIQUE_OPEN	MPI::MODE_UNIQUE_OPEN
MPI_MODE_WRONLY	MPI::MODE_WRONLY

**Datatype Decoding Constants**

C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER</code>	<code>const int</code> (or unnamed <code>enum</code> )
<code>MPI_COMBINER_CONTIGUOUS</code>	<code>MPI::COMBINER_CONTIGUOUS</code>
<code>MPI_COMBINER_DARRAY</code>	<code>MPI::COMBINER_DARRAY</code>
<code>MPI_COMBINER_DUP</code>	<code>MPI::COMBINER_DUP</code>
<code>MPI_COMBINER_F90_COMPLEX</code>	<code>MPI::COMBINER_F90_COMPLEX</code>
<code>MPI_COMBINER_F90_INTEGER</code>	<code>MPI::COMBINER_F90_INTEGER</code>
<code>MPI_COMBINER_F90_REAL</code>	<code>MPI::COMBINER_F90_REAL</code>
<code>MPI_COMBINER_HINDEXED_INTEGER</code>	<code>MPI::COMBINER_HINDEXED_INTEGER</code>
<code>MPI_COMBINER_HINDEXED</code>	<code>MPI::COMBINER_HINDEXED</code>
<code>MPI_COMBINER_HVECTOR_INTEGER</code>	<code>MPI::COMBINER_HVECTOR_INTEGER</code>
<code>MPI_COMBINER_HVECTOR</code>	<code>MPI::COMBINER_HVECTOR</code>
<code>MPI_COMBINER_INDEXED_BLOCK</code>	<code>MPI::COMBINER_INDEXED_BLOCK</code>
<code>MPI_COMBINER_INDEXED</code>	<code>MPI::COMBINER_INDEXED</code>
<code>MPI_COMBINER_NAMED</code>	<code>MPI::COMBINER_NAMED</code>
<code>MPI_COMBINER_RESIZED</code>	<code>MPI::COMBINER_RESIZED</code>
<code>MPI_COMBINER_STRUCT_INTEGER</code>	<code>MPI::COMBINER_STRUCT_INTEGER</code>
<code>MPI_COMBINER_STRUCT</code>	<code>MPI::COMBINER_STRUCT</code>
<code>MPI_COMBINER_SUBARRAY</code>	<code>MPI::COMBINER_SUBARRAY</code>
<code>MPI_COMBINER_VECTOR</code>	<code>MPI::COMBINER_VECTOR</code>

**Threads Constants**

C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER</code>	<code>const int</code> (or unnamed <code>enum</code> )
<code>MPI_THREAD_FUNNELED</code>	<code>MPI::THREAD_FUNNELED</code>
<code>MPI_THREAD_MULTIPLE</code>	<code>MPI::THREAD_MULTIPLE</code>
<code>MPI_THREAD_SERIALIZED</code>	<code>MPI::THREAD_SERIALIZED</code>
<code>MPI_THREAD_SINGLE</code>	<code>MPI::THREAD_SINGLE</code>

**File Operation Constants, Part 1**

C type: <code>const MPI_Offset</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER (KIND=MPI_OFFSET_KIND)</code>	<code>const MPI::Offset</code> (or unnamed <code>enum</code> )
<code>MPI_DISPLACEMENT_CURRENT</code>	<code>MPI::DISPLACEMENT_CURRENT</code>

**File Operation Constants, Part 2**

C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER</code>	<code>const int</code> (or unnamed <code>enum</code> )
<code>MPI_DISTRIBUTE_BLOCK</code>	<code>MPI::DISTRIBUTE_BLOCK</code>
<code>MPI_DISTRIBUTE_CYCLIC</code>	<code>MPI::DISTRIBUTE_CYCLIC</code>
<code>MPI_DISTRIBUTE_DFLT_DARG</code>	<code>MPI::DISTRIBUTE_DFLT_DARG</code>
<code>MPI_DISTRIBUTE_NONE</code>	<code>MPI::DISTRIBUTE_NONE</code>
<code>MPI_ORDER_C</code>	<code>MPI::ORDER_C</code>
<code>MPI_ORDER_FORTRAN</code>	<code>MPI::ORDER_FORTRAN</code>
<code>MPI_SEEK_CUR</code>	<code>MPI::SEEK_CUR</code>
<code>MPI_SEEK_END</code>	<code>MPI::SEEK_END</code>
<code>MPI_SEEK_SET</code>	<code>MPI::SEEK_SET</code>

**F90 Datatype Matching Constants**

C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER</code>	<code>const int</code> (or unnamed <code>enum</code> )
<code>MPI_TYPECLASS_COMPLEX</code>	<code>MPI::TYPECLASS_COMPLEX</code>
<code>MPI_TYPECLASS_INTEGER</code>	<code>MPI::TYPECLASS_INTEGER</code>
<code>MPI_TYPECLASS_REAL</code>	<code>MPI::TYPECLASS_REAL</code>

**Constants Specifying Empty or Ignored Input**

C/Fortran name	C++ name
C type / Fortran type	C++ type
<code>MPI_ARGVS_NULL</code>	<code>MPI::ARGVS_NULL</code>
<code>char***</code> / 2-dim. array of <code>CHARACTER*(*)</code>	<code>const char ***</code>
<code>MPI_ARGV_NULL</code>	<code>MPI::ARGV_NULL</code>
<code>char**</code> / array of <code>CHARACTER*(*)</code>	<code>const char **</code>
<code>MPI_ERRCODES_IGNORE</code>	Not defined for C++
<code>int*</code> / <code>INTEGER</code> array	
<code>MPI_STATUSES_IGNORE</code>	Not defined for C++
<code>MPI_Status*</code> / <code>INTEGER</code> , <code>DIMENSION(MPI_STATUS_SIZE,*)</code>	
<code>MPI_STATUS_IGNORE</code>	Not defined for C++
<code>MPI_Status*</code> / <code>INTEGER</code> , <code>DIMENSION(MPI_STATUS_SIZE)</code>	
<code>MPI_UNWEIGHTED</code>	Not defined for C++

**C Constants Specifying Ignored Input (no C++ or Fortran)**

C type: <code>MPI_Fint*</code>
<code>MPI_F_STATUSES_IGNORE</code>
<code>MPI_F_STATUS_IGNORE</code>

**C and C++ preprocessor Constants and Fortran Parameters**

C/C++ type: <code>const int</code> (or unnamed <code>enum</code> )
Fortran type: <code>INTEGER</code>
<code>MPI_SUBVERSION</code>
<code>MPI_VERSION</code>

## 3.1.2 Types

The following are defined C type definitions, included in the file `mpi.h`.

```

/* C opaque types */
MPI_Aint
MPI_Fint
MPI_Offset
MPI_Status

/* C handles to assorted structures */
MPI_Comm
MPI_Datatype
MPI_Errhandler
MPI_File
MPI_Group
MPI_Info
MPI_Op
MPI_Request
MPI_Win

// C++ opaque types (all within the MPI namespace)
MPI::Aint
MPI::Offset
MPI::Status

// C++ handles to assorted structures (classes,
// all within the MPI namespace)
MPI::Comm
MPI::Intracomm
MPI::Graphcomm
MPI::Distgraphcomm
MPI::Cartcomm
MPI::Intercomm
MPI::Datatype
MPI::Errhandler
MPI::Exception
MPI::File
MPI::Group
MPI::Info
MPI::Op
MPI::Request
MPI::Prequest
MPI::Grequest
MPI::Win

```

## 3.1.3 Prototype [d]Definitions

ticket0.

The following are defined C typedefs for user-defined functions, also included in the file `mpi.h`.

```

/* prototypes for user-defined functions */
typedef void MPI_User_function(void *invec, void *inoutvec, int *len,
                               MPI_Datatype *datatype);

typedef int MPI_Comm_copy_attr_function(MPI_Comm oldcomm,
                                         int comm_keyval, void *extra_state, void *attribute_val_in,
                                         void *attribute_val_out, int*flag);
typedef int MPI_Comm_delete_attr_function(MPI_Comm comm,
                                         int comm_keyval, void *attribute_val, void *extra_state);

typedef int MPI_Win_copy_attr_function(MPI_Win oldwin, int win_keyval,
                                         void *extra_state, void *attribute_val_in,
                                         void *attribute_val_out, int *flag);
typedef int MPI_Win_delete_attr_function(MPI_Win win, int win_keyval,
                                         void *attribute_val, void *extra_state);

typedef int MPI_Type_copy_attr_function(MPI_Datatype oldtype,
                                         int type_keyval, void *extra_state,
                                         void *attribute_val_in, void *attribute_val_out, int *flag);
typedef int MPI_Type_delete_attr_function(MPI_Datatype type,
                                         int type_keyval, void *attribute_val, void *extra_state);

typedef void MPI_Comm_errhandler_function(MPI_Comm *, int *, ...);
typedef void MPI_Win_errhandler_function(MPI_Win *, int *, ...);
typedef void MPI_File_errhandler_function(MPI_File *, int *, ...);

typedef int MPI_Grequest_query_function(void *extra_state,
                                         MPI_Status *status);
typedef int MPI_Grequest_free_function(void *extra_state);
typedef int MPI_Grequest_cancel_function(void *extra_state, int complete);

typedef int MPI_Datarep_extent_function(MPI_Datatype datatype,
                                         MPI_Aint *file_extent, void *extra_state);
typedef int MPI_Datarep_conversion_function(void *userbuf,
                                         MPI_Datatype datatype, int count, void *filebuf,
                                         MPI_Offset position, void *extra_state);

```

For Fortran, here are examples of how each of the user-defined subroutines should be declared.

The user-function argument to `MPI_OP_CREATE` should be declared like this:

```

SUBROUTINE USER_FUNCTION(INVEC, INOUTVEC, LEN, TYPE)
  <type> INVEC(LEN), INOUTVEC(LEN)
  INTEGER LEN, TYPE

```



The copy and delete function arguments to MPI\_COMM\_CREATE\_KEYVAL should be declared like these:

```
SUBROUTINE COMM_COPY_ATTR_FN(OLDCOMM, COMM_KEYVAL, EXTRA_STATE,
    ATTRIBUTE_VAL_IN, ATTRIBUTE_VAL_OUT, FLAG, IERROR)
    INTEGER OLDCOMM, COMM_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE, ATTRIBUTE_VAL_IN,
        ATTRIBUTE_VAL_OUT
    LOGICAL FLAG
```

```
SUBROUTINE COMM_DELETE_ATTR_FN(COMM, COMM_KEYVAL, ATTRIBUTE_VAL,
    EXTRA_STATE, IERROR)
    INTEGER COMM, COMM_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL, EXTRA_STATE
```

The copy and delete function arguments to MPI\_WIN\_CREATE\_KEYVAL should be declared like these:

```
SUBROUTINE WIN_COPY_ATTR_FN(OLDWIN, WIN_KEYVAL, EXTRA_STATE,
    ATTRIBUTE_VAL_IN, ATTRIBUTE_VAL_OUT, FLAG, IERROR)
    INTEGER OLDWIN, WIN_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE, ATTRIBUTE_VAL_IN,
        ATTRIBUTE_VAL_OUT
    LOGICAL FLAG
```

```
SUBROUTINE WIN_DELETE_ATTR_FN(WIN, WIN_KEYVAL, ATTRIBUTE_VAL,
    EXTRA_STATE, IERROR)
    INTEGER WIN, WIN_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL, EXTRA_STATE
```

The copy and delete function arguments to MPI\_TYPE\_CREATE\_KEYVAL should be declared like these:

```
SUBROUTINE TYPE_COPY_ATTR_FN(OLDTYPE, TYPE_KEYVAL, EXTRA_STATE,
    ATTRIBUTE_VAL_IN, ATTRIBUTE_VAL_OUT, FLAG, IERROR)
    INTEGER OLDTYPE, TYPE_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE,
        ATTRIBUTE_VAL_IN, ATTRIBUTE_VAL_OUT
    LOGICAL FLAG
```

```
SUBROUTINE TYPE_DELETE_ATTR_FN(TYPE, TYPE_KEYVAL, ATTRIBUTE_VAL,
    EXTRA_STATE, IERROR)
    INTEGER TYPE, TYPE_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL, EXTRA_STATE
```

The handler-function argument to MPI\_COMM\_CREATE\_ERRHANDLER should be declared like this:

```
SUBROUTINE COMM_ERRHANDLER_FUNCTION(COMM, ERROR_CODE)
    INTEGER COMM, ERROR_CODE
```

The handler-function argument to `MPI_WIN_CREATE_ERRHANDLER` should be declared like this:

```
SUBROUTINE WIN_ERRHANDLER_FUNCTION(WIN, ERROR_CODE)
  INTEGER WIN, ERROR_CODE
```

The handler-function argument to `MPI_FILE_CREATE_ERRHANDLER` should be declared like this:

```
SUBROUTINE FILE_ERRHANDLER_FUNCTION(FILE, ERROR_CODE)
  INTEGER FILE, ERROR_CODE
```

The query, free, and cancel function arguments to `MPI_GREQUEST_START` should be declared like these:

```
SUBROUTINE GREQUEST_QUERY_FUNCTION(EXTRA_STATE, STATUS, IERROR)
  INTEGER STATUS(MPI_STATUS_SIZE), IERROR
  INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE
```

```
SUBROUTINE GREQUEST_FREE_FUNCTION(EXTRA_STATE, IERROR)
  INTEGER IERROR
  INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE
```

```
SUBROUTINE GREQUEST_CANCEL_FUNCTION(EXTRA_STATE, COMPLETE, IERROR)
  INTEGER IERROR
  INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE
  LOGICAL COMPLETE
```

The extend and conversion function arguments to `MPI_REGISTER_DATAREP` should be declared like these:

```
SUBROUTINE DATAREP_EXTENT_FUNCTION(DATATYPE, EXTENT, EXTRA_STATE, IERROR)
  INTEGER DATATYPE, IERROR
  INTEGER(KIND=MPI_ADDRESS_KIND) EXTENT, EXTRA_STATE
```

```
SUBROUTINE DATAREP_CONVERSION_FUNCTION(USERBUF, DATATYPE, COUNT, FILEBUF,
  POSITION, EXTRA_STATE, IERROR)
  <TYPE> USERBUF(*), FILEBUF(*)
  INTEGER COUNT, DATATYPE, IERROR
  INTEGER(KIND=MPI_OFFSET_KIND) POSITION
  INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE
```

The following are defined C++ typedefs, also included in the file `mpi.h`.

```
namespace MPI {
  typedef void User_function(const void* invec, void *inoutvec,
    int len, const Datatype& datatype);

  typedef int Comm::Copy_attr_function(const Comm& oldcomm,
```

```

        int comm_keyval, void* extra_state, void* attribute_val_in,
        void* attribute_val_out, bool& flag);
typedef int Comm::Delete_attr_function(Comm& comm, int
        comm_keyval, void* attribute_val, void* extra_state);

typedef int Win::Copy_attr_function(const Win& oldwin,
        int win_keyval, void* extra_state, void* attribute_val_in,
        void* attribute_val_out, bool& flag);
typedef int Win::Delete_attr_function(Win& win, int
        win_keyval, void* attribute_val, void* extra_state);

typedef int Datatype::Copy_attr_function(const Datatype& oldtype,
        int type_keyval, void* extra_state,
        const void* attribute_val_in, void* attribute_val_out,
        bool& flag);
typedef int Datatype::Delete_attr_function(Datatype& type,
        int type_keyval, void* attribute_val, void* extra_state);

typedef void Comm::Errhandler_function(Comm &, int *, ...);
typedef void Win::Errhandler_function(Win &, int *, ...);
typedef void File::Errhandler_function(File &, int *, ...);

typedef int Grequest::Query_function(void* extra_state, Status& status);
typedef int Grequest::Free_function(void* extra_state);
typedef int Grequest::Cancel_function(void* extra_state, bool complete);

typedef void Datarep_extent_function(const Datatype& datatype,
        Aint& file_extent, void* extra_state);
typedef void Datarep_conversion_function(void* userbuf,
        Datatype& datatype, int count, void* filebuf,
        Offset position, void* extra_state);
}

```

#### 3.1.4 Deprecated [p]PPrototype [d]Definitions

The following are defined C typedefs for deprecated user-defined functions, also included in the file `mpi.h`.

```

/* prototypes for user-defined functions */
typedef int MPI_Copy_function(MPI_Comm oldcomm, int keyval,
        void *extra_state, void *attribute_val_in,
        void *attribute_val_out, int *flag);
typedef int MPI_Delete_function(MPI_Comm comm, int keyval,
        void *attribute_val, void *extra_state);
typedef void MPI_Handler_function(MPI_Comm *, int *, ...);

```

The following are deprecated Fortran user-defined callback subroutine prototypes. The deprecated copy and delete function arguments to `MPI_KEYVAL_CREATE` should be declared like these:

```

1  SUBROUTINE COPY_FUNCTION(OLDCOMM, KEYVAL, EXTRA_STATE,
2      ATTRIBUTE_VAL_IN, ATTRIBUTE_VAL_OUT, FLAG, IERR)
3      INTEGER OLDCOMM, KEYVAL, EXTRA_STATE, ATTRIBUTE_VAL_IN,
4      ATTRIBUTE_VAL_OUT, IERR
5      LOGICAL FLAG
6
7  SUBROUTINE DELETE_FUNCTION(COMM, KEYVAL, ATTRIBUTE_VAL, EXTRA_STATE, IERR)
8      INTEGER COMM, KEYVAL, ATTRIBUTE_VAL, EXTRA_STATE, IERR
9

```

The deprecated handler-function for error handlers should be declared like this:

```

11
12  SUBROUTINE HANDLER_FUNCTION(COMM, ERROR_CODE)
13      INTEGER COMM, ERROR_CODE
14

```

### 3.1.5 Info Keys

```

16  access_style
17  appnum
18  arch
19  cb_block_size
20  cb_buffer_size
21  cb_nodes
22  chunked_item
23  chunked_size
24  chunked
25  collective_buffering
26  file_perm
27  filename
28  file
29  host
30  io_node_list
31  ip_address
32  ip_port
33  nb_proc
34  no_locks
35  num_io_nodes
36  path
37  soft
38  striping_factor
39  striping_unit
40  wdir
41

```

### 3.1.6 Info Values

```

45  false
46  random
47  read_mostly
48  read_once

```

reverse_sequential	1
sequential	2
true	3
write_mostly	4
write_once	5
	6
	7
	8
	9
	10
	11
	12
	13
	14
	15
	16
	17
	18
	19
	20
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# Bibliography

- [1] Martin Schulz and Bronis R. de Supinski. P<sup>N</sup> MPI Tools: A Whole Lot Greater Than the Sum of Their Parts. In *ACM/IEEE Supercomputing Conference (SC)*, pages 1–10. ACM, 2007.

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