

# MPI: A Message-Passing Interface Standard

Version **3.0**

(Draft, with MPI 3 Nonblocking Collectives

**and new Fortran 2008 Interface**)

Unofficial, for comment only

Message Passing Interface Forum

May 5, 2011

ticket0.

ticket229-A.

ticket0. 1 This document describes the Message-Passing Interface (MPI) standard, version 3.0.  
2 The MPI standard includes point-to-point message-passing, collective communications, group  
3 and communicator concepts, process topologies, environmental management, process cre-  
4 ation and management, one-sided communications, extended collective operations, external  
5 interfaces, I/O, some miscellaneous topics, and a profiling interface. Language bindings for  
ticket0. 6 C, C++ and Fortran are defined.

7 Historically, the evolution of the standards is from MPI-1.0 (June 1994) to MPI-1.1  
8 (June 12, 1995) to MPI-1.2 (July 18, 1997), with several clarifications and additions and  
9 published as part of the MPI-2 document, to MPI-2.0 (July 18, 1997), with new functionality,  
10 to MPI-1.3 (May 30, 2008), combining for historical reasons the documents 1.1 and 1.2  
11 and some errata documents to one combined document, and to MPI-2.1 (June 23, 2008),  
ticket0. 12 combining the previous documents. Version MPI-2.2 (September 2009) added additional  
13 clarifications and seven new routines. This version, MPI-3.0, is an extension of MPI-2.2.

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Version 3.0: xx, x, 2011. Coincident with the development of MPI-2.2, the MPI Forum began discussions of a major extension to MPI. This document contains the MPI-3 Standard. This draft version of the MPI-3 standard extends the collective operations by including nonblocking versions. Unlike MPI-2.2, this standard is considered a major update to the MPI standard. As with previous versions, new features have been adopted only when there were compelling needs for the users. Some features, however, may have more than a minor impact on existing MPI implementations.

Version 2.2: September 4, 2009. This document contains mostly corrections and clarifications to the MPI-2.1 document. A few extensions have been added; however all correct MPI-2.1 programs are correct MPI-2.2 programs. New features were adopted only when there were compelling needs for users, open source implementations, and minor impact on existing MPI implementations.

Version 2.1: June 23, 2008. This document combines the previous documents MPI-1.3 (May 30, 2008) and MPI-2.0 (July 18, 1997). Certain parts of MPI-2.0, such as some sections of Chapter 4, Miscellany, and Chapter 7, Extended Collective Operations have been merged into the Chapters of MPI-1.3. Additional errata and clarifications collected by the MPI Forum are also included in this document.

Version 1.3: May 30, 2008. This document combines the previous documents MPI-1.1 (June 12, 1995) and the MPI-1.2 Chapter in MPI-2 (July 18, 1997). Additional errata collected by the MPI Forum referring to MPI-1.1 and MPI-1.2 are also included in this document.

Version 2.0: July 18, 1997. Beginning after the release of MPI-1.1, the MPI Forum began meeting to consider corrections and extensions. MPI-2 has been focused on process creation and management, one-sided communications, extended collective communications, external interfaces and parallel I/O. A miscellany chapter discusses items that do not fit elsewhere, in particular language interoperability.

Version 1.2: July 18, 1997. The MPI-2 Forum introduced MPI-1.2 as Chapter 3 in the standard “MPI-2: Extensions to the Message-Passing Interface”, July 18, 1997. This section contains clarifications and minor corrections to Version 1.1 of the MPI Standard. The only new function in MPI-1.2 is one for identifying to which version of the MPI Standard the implementation conforms. There are small differences between MPI-1 and MPI-1.1. There are very few differences between MPI-1.1 and MPI-1.2, but large differences between MPI-1.2 and MPI-2.

Version 1.1: June, 1995. Beginning in March, 1995, the Message-Passing Interface Forum reconvened to correct errors and to make clarifications in the MPI document of May 5, 1994, referred to below as Version 1.0. These discussions resulted in Version 1.1. The changes from Version 1.0 are minor. A version of this document with all changes marked is available.

1      Version 1.0: May, 1994.    The Message-Passing Interface Forum (MPIF), with participation  
ticket0. 2      from over 40 organizations, has been meeting since January 1993 to discuss and to define a  
3      set of library interface standards for message passing. MPIF is not sanctioned or supported  
4      by any official standards organization.

5      The goal of the Message-Passing Interface, simply stated, is to develop a widely used  
6      standard for writing message-passing programs. As such the interface should establish a  
ticket0. 7      practical, portable, efficient, and flexible standard for message-passing.

8      This document contains all the technical features proposed for the interface. This copy  
9      of the draft was processed by L<sup>A</sup>T<sub>E</sub>X on May 5, 1994.

10      Please send comments on MPI to [mpi-comments@mpi-forum.org](mailto:mpi-comments@mpi-forum.org). Your comment will  
11      be forwarded to MPI Forum committee members who will attempt to respond.

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# Chapter 1

## Introduction to MPI

### 1.1 Overview and Goals

MPI (Message-Passing Interface) is a *message-passing library interface specification*. All parts of this definition are significant. MPI addresses primarily the message-passing parallel programming model, in which data is moved from the address space of one process to that of another process through cooperative operations on each process. Extensions to the “classical” message-passing model are provided in collective operations, remote-memory access operations, dynamic process creation, and parallel I/O. MPI is a *specification*, not an implementation; there are multiple implementations of MPI. This specification is for a *library interface*; MPI is not a language, and all MPI operations are expressed as functions, subroutines, or methods, according to the appropriate language bindings, which for C, C++, and Fortran, are part of the MPI standard. The standard has been defined through an open process by a community of parallel computing vendors, computer scientists, and application developers. The next few sections provide an overview of the history of MPI’s development.

The main advantages of establishing a message-passing standard are portability and ease of use. In a distributed memory communication environment in which the higher level routines and/or abstractions are built upon lower level message-passing routines the benefits of standardization are particularly apparent. Furthermore, the definition of a message-passing standard, such as that proposed here, provides vendors with a clearly defined base set of routines that they can implement efficiently, or in some cases for which they can provide hardware support, thereby enhancing scalability.

The goal of the Message-Passing Interface simply stated is to develop a widely used standard for writing message-passing programs. As such the interface should establish a practical, portable, efficient, and flexible standard for message passing.

A complete list of goals follows.

- Design an application programming interface (not necessarily for compilers or a system implementation library).
- Allow efficient communication: Avoid memory-to-memory copying, allow overlap of computation and communication, and offload to communication co-processor, where available.
- Allow for implementations that can be used in a heterogeneous environment.

- Allow convenient C, C++, and Fortran bindings for the interface.
- Assume a reliable communication interface: the user need not cope with communication failures. Such failures are dealt with by the underlying communication subsystem.
- Define an interface that can be implemented on many vendor's platforms, with no significant changes in the underlying communication and system software.
- Semantics of the interface should be language independent.
- The interface should be designed to allow for thread safety.

## 1.2 Background of MPI-1.0

MPI sought to make use of the most attractive features of a number of existing message-passing systems, rather than selecting one of them and adopting it as the standard. Thus, MPI was strongly influenced by work at the IBM T. J. Watson Research Center [1, 2], Intel's NX/2 [45], Express [12], nCUBE's Vertex [41], p4 [7, 8], and PARMACS [5, 9]. Other important contributions have come from Zipcode [48, 49], Chimp [16, 17], PVM [4, 14], Chameleon [25], and PICL [24].

The MPI standardization effort involved about 60 people from 40 organizations mainly from the United States and Europe. Most of the major vendors of concurrent computers were involved in MPI, along with researchers from universities, government laboratories, and industry. The standardization process began with the Workshop on Standards for Message-Passing in a Distributed Memory Environment, sponsored by the Center for Research on Parallel Computing, held April 29-30, 1992, in Williamsburg, Virginia [56]. At this workshop the basic features essential to a standard message-passing interface were discussed, and a working group established to continue the standardization process.

A preliminary draft proposal, known as MPI1, was put forward by Dongarra, Hempel, Hey, and Walker in November 1992, and a revised version was completed in February 1993 [15]. MPI1 embodied the main features that were identified at the Williamsburg workshop as being necessary in a message passing standard. Since MPI1 was primarily intended to promote discussion and "get the ball rolling," it focused mainly on point-to-point communications. MPI1 brought to the forefront a number of important standardization issues, but did not include any collective communication routines and was not thread-safe.

In November 1992, a meeting of the MPI working group was held in Minneapolis, at which it was decided to place the standardization process on a more formal footing, and to generally adopt the procedures and organization of the High Performance Fortran Forum. Subcommittees were formed for the major component areas of the standard, and an email discussion service established for each. In addition, the goal of producing a draft MPI standard by the Fall of 1993 was set. To achieve this goal the MPI working group met every 6 weeks for two days throughout the first 9 months of 1993, and presented the draft MPI standard at the Supercomputing 93 conference in November 1993. These meetings and the email discussion together constituted the MPI Forum, membership of which has been open to all members of the high performance computing community.

### 1.3 Background of MPI-1.1, MPI-1.2, and MPI-2.0

Beginning in March 1995, the MPI Forum began meeting to consider corrections and extensions to the original MPI Standard document [21]. The first product of these deliberations was Version 1.1 of the MPI specification, released in June of 1995 [22] (see <http://www.mpi-forum.org> for official MPI document releases). At that time, effort focused in five areas.

1. Further corrections and clarifications for the MPI-1.1 document.
2. Additions to MPI-1.1 that do not significantly change its types of functionality (new datatype constructors, language interoperability, etc.).
3. Completely new types of functionality (dynamic processes, one-sided communication, parallel I/O, etc.) that are what everyone thinks of as “MPI-2 functionality.”
4. Bindings for Fortran 90 and C++. MPI-2 specifies C++ bindings for both MPI-1 and MPI-2 functions, and extensions to the Fortran 77 binding of MPI-1 and MPI-2 to handle Fortran 90 issues.
5. Discussions of areas in which the MPI process and framework seem likely to be useful, but where more discussion and experience are needed before standardization (e.g. zero-copy semantics on shared-memory machines, real-time specifications).

Corrections and clarifications (items of type 1 in the above list) were collected in Chapter 3 of the MPI-2 document: “Version 1.2 of MPI.” That chapter also contains the function for identifying the version number. Additions to MPI-1.1 (items of types 2, 3, and 4 in the above list) are in the remaining chapters of the MPI-2 document, and constitute the specification for MPI-2. Items of type 5 in the above list have been moved to a separate document, the “MPI Journal of Development” (JOD), and are not part of the MPI-2 Standard.

This structure makes it easy for users and implementors to understand what level of MPI compliance a given implementation has:

- MPI-1 compliance will mean compliance with MPI-1.3. This is a useful level of compliance. It means that the implementation conforms to the clarifications of MPI-1.1 function behavior given in Chapter 3 of the MPI-2 document. Some implementations may require changes to be MPI-1 compliant.
- MPI-2 compliance will mean compliance with all of MPI-2.1.
- The MPI Journal of Development is not part of the MPI Standard.

It is to be emphasized that forward compatibility is preserved. That is, a valid MPI-1.1 program is both a valid MPI-1.3 program and a valid MPI-2.1 program, and a valid MPI-1.3 program is a valid MPI-2.1 program.

### 1.4 Background of MPI-1.3 and MPI-2.1

After the release of MPI-2.0, the MPI Forum kept working on errata and clarifications for both standard documents (MPI-1.1 and MPI-2.0). The short document “Errata for MPI-1.1” was released October 12, 1998. On July 5, 2001, a first ballot of errata and clarifications for

MPI-2.0 was released, and a second ballot was voted on May 22, 2002. Both votes were done electronically. Both ballots were combined into one document: “Errata for MPI-2”, May 15, 2002. This errata process was then interrupted, but the Forum and its e-mail reflectors kept working on new requests for clarification.

Restarting regular work of the MPI Forum was initiated in three meetings, at EuroPVM/MPI’06 in Bonn, at EuroPVM/MPI’07 in Paris, and at SC’07 in Reno. In December 2007, a steering committee started the organization of new MPI Forum meetings at regular 8-weeks intervals. At the January 14-16, 2008 meeting in Chicago, the MPI Forum decided to combine the existing and future MPI documents to one document for each version of the MPI standard. For technical and historical reasons, this series was started with MPI-1.3. Additional Ballots 3 and 4 solved old questions from the errata list started in 1995 up to new questions from the last years. After all documents (MPI-1.1, MPI-2, Errata for MPI-1.1 (Oct. 12, 1998), and MPI-2.1 Ballots 1-4) were combined into one draft document, for each chapter, a chapter author and review team were defined. They cleaned up the document to achieve a consistent MPI-2.1 document. The final MPI-2.1 standard document was finished in June 2008, and finally released with a second vote in September 2008 in the meeting at Dublin, just before EuroPVM/MPI’08. The major work of the current MPI Forum is the preparation of MPI-3.

## 1.5 Background of MPI-2.2

MPI-2.2 is a minor update to the MPI-2.1 standard. This version addresses additional errors and ambiguities that were not corrected in the MPI-2.1 standard as well as a small number of extensions to MPI-2.1 that met the following criteria:

- Any correct MPI-2.1 program is a correct MPI-2.2 program.
- Any extension must have significant benefit for users.
- Any extension must not require significant implementation effort. To that end, all such changes are accompanied by an open source implementation.

The discussions of MPI-2.2 proceeded concurrently with the MPI-3 discussions; in some cases, extensions were proposed for MPI-2.2 but were later moved to MPI-3.

## 1.6 Background of MPI-3.0

MPI-3.0 is a major update to the MPI standard. Areas of particular interest are the extension of collective operations to include nonblocking and sparse-group routines and more flexible and powerful one-sided operations. This *draft* contains the MPI Forum’s current draft of nonblocking collective routines.

A new Fortran `mpi_f08` module is introduced to provide extended compile-time argument checking and buffer handling in nonblocking routines. The existing `mpi` module provides compile-time argument checking for the existing MPI-2.2 routine definitions. The use of `mpif.h` is strongly discouraged.



## 1.7 Who Should Use This Standard?

This standard is intended for use by all those who want to write portable message-passing programs in Fortran, C and C++. This includes individual application programmers, developers of software designed to run on parallel machines, and creators of environments and tools. In order to be attractive to this wide audience, the standard must provide a simple, easy-to-use interface for the basic user while not semantically precluding the high-performance message-passing operations available on advanced machines.

## 1.8 What Platforms Are Targets For Implementation?

The attractiveness of the message-passing paradigm at least partially stems from its wide portability. Programs expressed this way may run on distributed-memory multiprocessors, networks of workstations, and combinations of all of these. In addition, shared-memory implementations, including those for multi-core processors and hybrid architectures, are possible. The paradigm will not be made obsolete by architectures combining the shared- and distributed-memory views, or by increases in network speeds. It thus should be both possible and useful to implement this standard on a great variety of machines, including those “machines” consisting of collections of other machines, parallel or not, connected by a communication network.

The interface is suitable for use by fully general MIMD programs, as well as those written in the more restricted style of SPMD. MPI provides many features intended to improve performance on scalable parallel computers with specialized interprocessor communication hardware. Thus, we expect that native, high-performance implementations of MPI will be provided on such machines. At the same time, implementations of MPI on top of standard Unix interprocessor communication protocols will provide portability to workstation clusters and heterogenous networks of workstations.

## 1.9 What Is Included In The Standard?

The standard includes:

- Point-to-point communication,
- Datatypes,
- Collective operations,
- Process groups,
- Communication contexts,
- Process topologies,
- Environmental management and inquiry,
- The Info object,
- Process creation and management,
- One-sided communication,

- External interfaces,
- Parallel file I/O,
- Language bindings for Fortran, C and C++,
- Profiling interface.

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## 1.10 What Is Not Included In The Standard?

The standard does not specify:

- Operations that require more operating system support than is currently standard; for example, interrupt-driven receives, remote execution, or active messages,
- Program construction tools,
- Debugging facilities.

There are many features that have been considered and not included in this standard. This happened for a number of reasons, one of which is the time constraint that was self-imposed in finishing the standard. Features that are not included can always be offered as extensions by specific implementations. Perhaps future versions of MPI will address some of these issues.

## 1.11 Organization of this Document

The following is a list of the remaining chapters in this document, along with a brief description of each.

- Chapter 2, MPI Terms and Conventions, explains notational terms and conventions used throughout the MPI document.
- Chapter 3, Point to Point Communication, defines the basic, pairwise communication subset of MPI. *Send* and *receive* are found here, along with many associated functions designed to make basic communication powerful and efficient.
- Chapter 4, Datatypes, defines a method to describe any data layout, e.g., an array of structures in the memory, which can be used as message send or receive buffer.
- Chapter 5, Collective Communications, defines process-group collective communication operations. Well known examples of this are barrier and broadcast over a group of processes (not necessarily all the processes). With MPI-2, the semantics of collective communication was extended to include intercommunicators. It also adds two new collective operations. **MPI-3 adds nonblocking collective operations.**
- Chapter 6, Groups, Contexts, Communicators, and Caching, shows how groups of processes are formed and manipulated, how unique communication contexts are obtained, and how the two are bound together into a *communicator*.

- Chapter 7, Process Topologies, explains a set of utility functions meant to assist in the mapping of process groups (a linearly ordered set) to richer topological structures such as multi-dimensional grids.
- Chapter 8, MPI Environmental Management, explains how the programmer can manage and make inquiries of the current MPI environment. These functions are needed for the writing of correct, robust programs, and are especially important for the construction of highly-portable message-passing programs.
- Chapter 9, The Info Object, defines an opaque object, that is used as input in several MPI routines.
- Chapter 10, Process Creation and Management, defines routines that allow for creation of processes.
- Chapter 11, One-Sided Communications, defines communication routines that can be completed by a single process. These include shared-memory operations (put/get) and remote accumulate operations.
- Chapter 12, External Interfaces, defines routines designed to allow developers to layer on top of MPI. This includes generalized requests, routines that decode MPI opaque objects, and threads.
- Chapter 13, I/O, defines MPI support for parallel I/O.
- Chapter 14, Profiling Interface, explains a simple name-shifting convention that any MPI implementation must support. One motivation for this is the ability to put performance profiling calls into MPI without the need for access to the MPI source code. The name shift is merely an interface, it says nothing about how the actual profiling should be done and in fact, the name shift can be useful for other purposes.
- Chapter 15, Deprecated Functions, describes routines that are kept for reference. However usage of these functions is discouraged, as they may be deleted in future versions of the standard.
- Chapter 16, Language Bindings, describes the C++ binding, discusses Fortran issues, and describes language interoperability aspects between C, C++, and Fortran.

The Appendices are:

- Annex A, Language Bindings Summary, gives specific syntax in C, C++, and Fortran, for all MPI functions, constants, and types.
- Annex B, Change-Log, summarizes major changes since the previous version of the standard.
- Several Index pages show the locations of examples, constants and predefined handles, callback routine prototypes, and all MPI functions.

MPI provides various interfaces to facilitate interoperability of distinct MPI implementations. Among these are the canonical data representation for MPI I/O and for

MPI\_PACK\_EXTERNAL and MPI\_UNPACK\_EXTERNAL. The definition of an actual binding of these interfaces that will enable interoperability is outside the scope of this document.

A separate document consists of ideas that were discussed in the MPI Forum and deemed to have value, but are not included in the MPI Standard. They are part of the “Journal of Development” (JOD), lest good ideas be lost and in order to provide a starting point for further work. The chapters in the JOD are

- Chapter 2, **Spawning Independent Processes**, includes some elements of dynamic process management, in particular management of processes with which the spawning processes do not intend to communicate, that the Forum discussed at length but ultimately decided not to include in the MPI Standard.
- Chapter 3, **Threads and MPI**, describes some of the expected interaction between an MPI implementation and a thread library in a multi-threaded environment.
- Chapter 4, **Communicator ID**, describes an approach to providing identifiers for communicators.
- Chapter 5, **Miscellany**, discusses Miscellaneous topics in the MPI JOD, in particular single-copy routines for use in shared-memory environments and new datatype constructors.
- Chapter 6, **Toward a Full Fortran 90 Interface**, describes an approach to providing a more elaborate Fortran 90 interface.
- Chapter 7, **Split Collective Communication**, describes a specification for certain non-blocking collective operations.
- Chapter 8, **Real-Time MPI**, discusses MPI support for real time processing.

## Chapter 2

# MPI Terms and Conventions

This chapter explains notational terms and conventions used throughout the MPI document, some of the choices that have been made, and the rationale behind those choices. It is similar to the MPI-1 Terms and Conventions chapter but differs in some major and minor ways. Some of the major areas of difference are the naming conventions, some semantic definitions, file objects, Fortran 90 *vs* Fortran 77, C++, processes, and interaction with signals.

### 2.1 Document Notation

*Rationale.* Throughout this document, the rationale for the design choices made in the interface specification is set off in this format. Some readers may wish to skip these sections, while readers interested in interface design may want to read them carefully. (*End of rationale.*)

*Advice to users.* Throughout this document, material aimed at users and that illustrates usage is set off in this format. Some readers may wish to skip these sections, while readers interested in programming in MPI may want to read them carefully. (*End of advice to users.*)

*Advice to implementors.* Throughout this document, material that is primarily commentary to implementors is set off in this format. Some readers may wish to skip these sections, while readers interested in MPI implementations may want to read them carefully. (*End of advice to implementors.*)

### 2.2 Naming Conventions

In many cases MPI names for C functions are of the form `MPI_Class_action_subset`. This convention originated with MPI-1. Since MPI-2 an attempt has been made to standardize the names of MPI functions according to the following rules. The C++ bindings in particular follow these rules (see Section 2.6.4 on page 19).

1. In C, all routines associated with a particular type of MPI object should be of the form `MPI_Class_action_subset` or, if no subset exists, of the form `MPI_Class_action`. In Fortran, all routines associated with a particular type of MPI object should be of the form `MPI_CLASS_ACTION_SUBSET` or, if no subset exists, of the form

MPI\_CLASS\_ACTION. For C and Fortran we use the C++ terminology to define the **Class**. In C++, the routine is a method on **Class** and is named `MPI::Class::Action_subset`. If the routine is associated with a certain class, but does not make sense as an object method, it is a static member function of the class.

2. If the routine is not associated with a class, the name should be of the form `MPI_Action_subset` in C and `MPI_ACTION_SUBSET` in Fortran, and in C++ should be scoped in the MPI namespace, `MPI::Action_subset`.
3. The names of certain actions have been standardized. In particular, **Create** creates a new object, **Get** retrieves information about an object, **Set** sets this information, **Delete** deletes information, **Is** asks whether or not an object has a certain property.

C and Fortran names for some MPI functions (that were defined during the MPI-1 process) violate these rules in several cases. The most common exceptions are the omission of the **Class** name from the routine and the omission of the **Action** where one can be inferred.

MPI identifiers are limited to 30 characters (31 with the profiling interface). This is done to avoid exceeding the limit on some compilation systems.

## 2.3 Procedure Specification

MPI procedures are specified using a language-independent notation. The arguments of procedure calls are marked as IN, OUT or INOUT. The meanings of these are:

- IN: the call may use the input value but does not update the argument,
- OUT: the call may update the argument but does not use its input value,
- INOUT: the call may both use and update the argument.

There is one special case — if an argument is a handle to an opaque object (these terms are defined in Section 2.5.1), and the object is updated by the procedure call, then the argument is marked INOUT or OUT. It is marked this way even though the handle itself is not modified — we use the INOUT or OUT attribute to denote that what the handle *references* is updated. Thus, in C++, IN arguments are usually either references or pointers to `const` objects.

*Rationale.* The definition of MPI tries to avoid, to the largest possible extent, the use of INOUT arguments, because such use is error-prone, especially for scalar arguments. (*End of rationale.*)

MPI's use of IN, OUT and INOUT is intended to indicate to the user how an argument is to be used, but does not provide a rigorous classification that can be translated directly into all language bindings (e.g., `INTENT` in Fortran 90 bindings or `const` in C bindings). For instance, the “constant” `MPI_BOTTOM` can usually be passed to OUT buffer arguments. Similarly, `MPI_STATUS_IGNORE` can be passed as the OUT status argument (with the `mpi module` or `mpif.h`).

A common occurrence for MPI functions is an argument that is used as IN by some processes and OUT by other processes. Such an argument is, syntactically, an INOUT argument

and is marked as such, although, semantically, it is not used in one call both for input and for output on a single process.

Another frequent situation arises when an argument value is needed only by a subset of the processes. When an argument is not significant at a process then an arbitrary value can be passed as an argument.

Unless specified otherwise, an argument of type OUT or type INOUT cannot be aliased with any other argument passed to an MPI procedure. An example of argument aliasing in C appears below. If we define a C procedure like this,

```
void copyIntBuffer( int *pin, int *pout, int len )
{
    int i;
    for (i=0; i<len; ++i) *pout++ = *pin++;
}
```

then a call to it in the following code fragment has aliased arguments.

```
int a[10];
copyIntBuffer( a, a+3, 7);
```

Although the C language allows this, such usage of MPI procedures is forbidden unless otherwise specified. Note that Fortran prohibits aliasing of arguments.

All MPI functions are first specified in the language-independent notation. Immediately below this, **language dependent bindings follow:**

- The ISO C version of the function.
- The Fortran version of the same function used with `USE mpi` or `INCLUDE 'mpif.h'`
- The Fortran version used with `USE mpi_f08`.
- The C++ binding (which is deprecated).

Fortran in this document refers to Fortran 90 and higher; see Section 2.6.

## 2.4 Semantic Terms

When discussing MPI procedures the following semantic terms are used.

**nonblocking** A procedure is nonblocking if the procedure may return before the operation completes, and before the user is allowed to reuse resources (such as buffers) specified in the call. A nonblocking request is **started** by the call that initiates it, e.g., `MPI_ISEND`. The word complete is used with respect to operations, requests, and communications. An **operation completes** when the user is allowed to reuse resources, and any output buffers have been updated; i.e. a call to `MPI_TEST` will return `flag = true`. A **request is completed** by a call to wait, which returns, or a test or get status call which returns `flag = true`. This completing call has two effects: the status is extracted from the request; in the case of test and wait, if the request was nonpersistent, it is **freed**, and becomes **inactive** if it was persistent. A **communication completes** when all participating operations complete.

**blocking** A procedure is blocking if return from the procedure indicates the user is allowed to reuse resources specified in the call.

**local** A procedure is local if completion of the procedure depends only on the local executing process.

**non-local** A procedure is non-local if completion of the operation may require the execution of some MPI procedure on another process. Such an operation may require communication occurring with another user process.

**collective** A procedure is collective if all processes in a process group need to invoke the procedure. A collective call may or may not be synchronizing. Collective calls over the same communicator must be executed in the same order by all members of the process group.

**predefined** A predefined datatype is a datatype with a predefined (constant) name (such as `MPI_INT`, `MPI_FLOAT_INT`, or `MPI_UB`) or a datatype constructed with `MPI_TYPE_CREATE_F90_INTEGER`, `MPI_TYPE_CREATE_F90_REAL`, or `MPI_TYPE_CREATE_F90_COMPLEX`. The former are **named** whereas the latter are **unnamed**.

**derived** A derived datatype is any datatype that is not predefined.

**portable** A datatype is portable, if it is a predefined datatype, or it is derived from a portable datatype using only the type constructors `MPI_TYPE_CONTIGUOUS`, `MPI_TYPE_VECTOR`, `MPI_TYPE_INDEXED`, `MPI_TYPE_CREATE_INDEXED_BLOCK`, `MPI_TYPE_CREATE_SUBARRAY`, `MPI_TYPE_DUP`, and `MPI_TYPE_CREATE_DARRAY`. Such a datatype is portable because all displacements in the datatype are in terms of extents of one predefined datatype. Therefore, if such a datatype fits a data layout in one memory, it will fit the corresponding data layout in another memory, if the same declarations were used, even if the two systems have different architectures. On the other hand, if a datatype was constructed using `MPI_TYPE_CREATE_HINDEXED`, `MPI_TYPE_CREATE_HVECTOR` or `MPI_TYPE_CREATE_STRUCT`, then the datatype contains explicit byte displacements (e.g., providing padding to meet alignment restrictions). These displacements are unlikely to be chosen correctly if they fit data layout on one memory, but are used for data layouts on another process, running on a processor with a different architecture.

**equivalent** Two datatypes are equivalent if they appear to have been created with the same sequence of calls (and arguments) and thus have the same typemap. Two equivalent datatypes do not necessarily have the same cached attributes or the same names.

## 2.5 Data Types

### 2.5.1 Opaque Objects

MPI manages **system memory** that is used for buffering messages and for storing internal representations of various MPI objects such as groups, communicators, datatypes, etc. This memory is not directly accessible to the user, and objects stored there are **opaque**: their size and shape is not visible to the user. Opaque objects are accessed via **handles**, which exist in user space. MPI procedures that operate on opaque objects are passed handle



arguments to access these objects. In addition to their use by MPI calls for object access, handles can participate in assignments and comparisons.

In Fortran with `USE mpi` or `INCLUDE 'mpif.h'`, all handles have type `INTEGER`. In Fortran with `USE mpi_f08`, and in C and C++, a different handle type is defined for each category of objects. With Fortran `USE mpi_f08`, the handles are defined as Fortran sequenced derived types that consist of only one element `INTEGER :: MPI_VAL`. The internal handle value is identical to the Fortran `INTEGER` value used in the `mpi` module and `mpif.h`. The type names are identical to the names in C, except that they are not case sensitive. For example:

```
TYPE MPI_Comm
  SEQUENCE
  INTEGER :: MPI_VAL
END TYPE MPI_Comm
```

In addition, handles themselves are distinct objects in C++. The C and C++ types must support the use of the assignment and equality operators.

*Advice to implementors.* In Fortran, the handle can be an index into a table of opaque objects in a system table; in C it can be such an index or a pointer to the object. C++ handles can simply “wrap up” a table index or pointer. (*End of advice to implementors.*)

*Rationale.* Due to the sequence attribute in the definition of handles in the `mpi_f08` module, the new Fortran handles are associated with one numerical storage unit; i.e., they can be stored in every application data structure, including common blocks and sequence derived types. They may have the same C binding as the `INTEGER` handles of the `mpi` module. Since the integer values are equivalent, applications can easily convert MPI handles between all three supported Fortran methods. For example, an integer communicator handle `COMM` can be converted directly into an exactly equivalent `mpi_f08` communicator handle named `comm_f08` by `comm_f08%MPI_VAL=COMM`, and vice versa. (*End of rationale.*)

Opaque objects are allocated and deallocated by calls that are specific to each object type. These are listed in the sections where the objects are described. The calls accept a handle argument of matching type. In an allocate call this is an OUT argument that returns a valid reference to the object. In a call to deallocate this is an INOUT argument which returns with an “invalid handle” value. MPI provides an “invalid handle” constant for each object type. Comparisons to this constant are used to test for validity of the handle.

A call to a deallocate routine invalidates the handle and marks the object for deallocation. The object is not accessible to the user after the call. However, MPI need not deallocate the object immediately. Any operation pending (at the time of the deallocate) that involves this object will complete normally; the object will be deallocated afterwards.

An opaque object and its handle are significant only at the process where the object was created and cannot be transferred to another process.

MPI provides certain predefined opaque objects and predefined, static handles to these objects. The user must not free such objects. In C++, this is enforced by declaring the handles to these predefined objects to be `static const`.

*Rationale.* This design hides the internal representation used for MPI data structures, thus allowing similar calls in C, C++, and Fortran. It also avoids conflicts with the typing rules in these languages, and easily allows future extensions of functionality. The mechanism for opaque objects used here loosely follows the POSIX Fortran binding standard.

The explicit separation of handles in user space and objects in system space allows space-reclaiming and deallocation calls to be made at appropriate points in the user program. If the opaque objects were in user space, one would have to be very careful not to go out of scope before any pending operation requiring that object completed. The specified design allows an object to be marked for deallocation, the user program can then go out of scope, and the object itself still persists until any pending operations are complete.

The requirement that handles support assignment/comparison is made since such operations are common. This restricts the domain of possible implementations. The alternative would have been to allow handles to have been an arbitrary, opaque type. This would force the introduction of routines to do assignment and comparison, adding complexity, and was therefore ruled out. (*End of rationale.*)

*Advice to users.* A user may accidentally create a dangling reference by assigning to a handle the value of another handle, and then deallocating the object associated with these handles. Conversely, if a handle variable is deallocated before the associated object is freed, then the object becomes inaccessible (this may occur, for example, if the handle is a local variable within a subroutine, and the subroutine is exited before the associated object is deallocated). It is the user's responsibility to avoid adding or deleting references to opaque objects, except as a result of MPI calls that allocate or deallocate such objects. (*End of advice to users.*)

*Advice to implementors.* The intended semantics of opaque objects is that opaque objects are separate from one another; each call to allocate such an object copies all the information required for the object. Implementations may avoid excessive copying by substituting referencing for copying. For example, a derived datatype may contain references to its components, rather than copies of its components; a call to `MPI_COMM_GROUP` may return a reference to the group associated with the communicator, rather than a copy of this group. In such cases, the implementation must maintain reference counts, and allocate and deallocate objects in such a way that the visible effect is as if the objects were copied. (*End of advice to implementors.*)

## 2.5.2 Array Arguments

An MPI call may need an argument that is an array of opaque objects, or an array of handles. The array-of-handles is a regular array with entries that are handles to objects of the same type in consecutive locations in the array. Whenever such an array is used, an additional `len` argument is required to indicate the number of valid entries (unless this number can be derived otherwise). The valid entries are at the beginning of the array; `len` indicates how many of them there are, and need not be the size of the entire array. The same approach is followed for other array arguments. In some cases `NULL` handles are considered valid entries. When a `NULL` argument is desired for an array of statuses, one uses `MPI_STATUSES_IGNORE`. With the `mpi_f08` module and

the C++ bindings, optional arguments through function overloading are used instead of `MPI_STATUS_IGNORE`, `MPI_STATUSES_IGNORE`, `MPI_ERRCODES_IGNORE`, and `MPI_UNWEIGHTED`. This is done by having two (or four in the case of two such independent arguments) bindings where one has the optional argument and one does not. The constants `MPI_ARGV_NULL` and `MPI_ARGVS_NULL` are not substituted by function overloading.

### 2.5.3 State

MPI procedures use at various places arguments with *state* types. The values of such a data type are all identified by names, and no operation is defined on them. For example, the `MPI_TYPE_CREATE_SUBARRAY` routine has a state argument `order` with values `MPI_ORDER_C` and `MPI_ORDER_FORTRAN`.

### 2.5.4 Named Constants

MPI procedures sometimes assign a special meaning to a special value of a basic type argument; e.g., `tag` is an integer-valued argument of point-to-point communication operations, with a special wild-card value, `MPI_ANY_TAG`. Such arguments will have a range of regular values, which is a proper subrange of the range of values of the corresponding basic type; special values (such as `MPI_ANY_TAG`) will be outside the regular range. The range of regular values, such as `tag`, can be queried using environmental inquiry functions (Chapter 7 of the MPI-1 document). The range of other values, such as `source`, depends on values given by other MPI routines (in the case of `source` it is the communicator size).

MPI also provides predefined named constant handles, such as `MPI_COMM_WORLD`.

All named constants, with the exceptions noted below for Fortran, can be used in initialization expressions or assignments, but not necessarily in array declarations or as labels in C/C++ `switch` or Fortran `select/case` statements. This implies named constants to be link-time but not necessarily compile-time constants. The named constants listed below are required to be compile-time constants in both C/C++ and Fortran. These constants do not change values during execution. Opaque objects accessed by constant handles are defined and do not change value between MPI initialization (`MPI_INIT`) and MPI completion (`MPI_FINALIZE`). The handles themselves are constants and can be also used in initialization expressions or assignments.

The constants that are required to be compile-time constants (and can thus be used for array length declarations and labels in C/C++ `switch` and Fortran `case/select` statements) are:

- `MPI_MAX_PROCESSOR_NAME`
- `MPI_MAX_ERROR_STRING`
- `MPI_MAX_DATAREP_STRING`
- `MPI_MAX_INFO_KEY`
- `MPI_MAX_INFO_VAL`
- `MPI_MAX_OBJECT_NAME`
- `MPI_MAX_PORT_NAME`
- `MPI_STATUS_SIZE` (Fortran only)
- `MPI_ADDRESS_KIND` (Fortran only)
- `MPI_INTEGER_KIND` (Fortran only)
- `MPI_OFFSET_KIND` (Fortran only)

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`MPI_SUBARRAYS` (Fortran only)  
`MPI_SUBARRAYS_SUPPORTED` (Fortran only)  
`MPI_SUBARRAYS_NOT_SUPPORTED` (Fortran only)

and their C++ counterparts where appropriate.

The constants that cannot be used in initialization expressions or assignments in Fortran are:

`MPI_BOTTOM`  
`MPI_STATUS_IGNORE`  
`MPI_STATUSES_IGNORE`  
`MPI_ERRCODES_IGNORE`  
`MPI_IN_PLACE`  
`MPI_ARGV_NULL`  
`MPI_ARGVS_NULL`  
`MPI_UNWEIGHTED`

*Advice to implementors.* In Fortran the implementation of these special constants may require the use of language constructs that are outside the Fortran standard. Using special values for the constants (e.g., by defining them through `PARAMETER` statements) is not possible because an implementation cannot distinguish these values from legal data. Typically, these constants are implemented as predefined static variables (e.g., a variable in an MPI-declared `COMMON` block), relying on the fact that the target compiler passes data by address. Inside the subroutine, this address can be extracted by some mechanism outside the Fortran standard (e.g., by Fortran extensions or by implementing the function in C). (*End of advice to implementors.*)

### 2.5.5 Choice

MPI functions sometimes use arguments with a *choice* (or union) data type. Distinct calls to the same routine may pass by reference actual arguments of different types. The mechanism for providing such arguments will differ from language to language. For Fortran **with the include file `mpif.h` or the `mpi` module**, the document uses `<type>` to represent a choice variable; **with the Fortran `mpi_f08` module, such arguments are declared with the new Fortran syntax `TYPE(*)`, `DIMENSION(..)`**; for C and C++, we use `void *`.

*Advice to implementors.* The implementor can freely choose how to implement choice arguments in the `mpi` module, e.g., with a non-standard compiler-dependent method that has the quality of the call mechanism in the implicit Fortran interfaces, or with the method defined for the `mpi_f08` module. See details in Section 16.2.1 on page 544. (*End of advice to implementors.*)

### 2.5.6 Addresses

Some MPI procedures use *address* arguments that represent an absolute address in the calling program. The datatype of such an argument is `MPI_Aint` in C, `MPI::Aint` in C++ and `INTEGER (KIND=MPI_ADDRESS_KIND)` in Fortran. These types must have the same width and encode address values in the same manner such that address values in one language may be passed directly to another language without conversion. There is the MPI constant `MPI_BOTTOM` to indicate the start of the address range.

### 2.5.7 File Offsets

For I/O there is a need to give the size, displacement, and offset into a file. These quantities can easily be larger than 32 bits which can be the default size of a Fortran integer. To overcome this, these quantities are declared to be `INTEGER (KIND=MPI_OFFSET_KIND)` in Fortran. In C one uses `MPI_Offset` whereas in C++ one uses `MPI::Offset`. These types must have the same width and encode address values in the same manner such that offset values in one language may be passed directly to another language without conversion.

## 2.6 Language Binding

This section defines the rules for MPI language binding in general and for Fortran, ISO C, and C++, in particular. (Note that ANSI C has been replaced by ISO C.) The C++ language bindings have been deprecated. Defined here are various object representations, as well as the naming conventions used for expressing this standard. The actual calling sequences are defined elsewhere.

MPI bindings are for Fortran 90 or later, though they were originally designed to be usable in Fortran 77 environments. With the `mpi_f08` module, two new Fortran features *assumed type* and *assumed rank* are also required, see Section 2.5.5 on page 16.

Since the word `PARAMETER` is a keyword in the Fortran language, we use the word “argument” to denote the arguments to a subroutine. These are normally referred to as parameters in C and C++, however, we expect that C and C++ programmers will understand the word “argument” (which has no specific meaning in C/C++), thus allowing us to avoid unnecessary confusion for Fortran programmers.

Since Fortran is case insensitive, linkers may use either lower case or upper case when resolving Fortran names. Users of case sensitive languages should avoid the “`mpi_`” and “`pmpi_`” prefixes.

### 2.6.1 Deprecated Names and Functions

A number of chapters refer to deprecated or replaced MPI-1 constructs. These are constructs that continue to be part of the MPI standard, as documented in Chapter 15, but that users are recommended not to continue using, since better solutions were provided with MPI-2. For example, the Fortran binding for MPI-1 functions that have address arguments uses `INTEGER`. This is not consistent with the C binding, and causes problems on machines with 32 bit `INTEGER`s and 64 bit addresses. In MPI-2, these functions were given new names with new bindings for the address arguments. The use of the old functions is deprecated. For consistency, here and in a few other cases, new C functions are also provided, even though the new functions are equivalent to the old functions. The old names are deprecated. Another example is provided by the MPI-1 predefined datatypes `MPI_UB` and `MPI_LB`. They are deprecated, since their use is awkward and error-prone. The MPI-2 function `MPI_TYPE_CREATE_RESIZED` provides a more convenient mechanism to achieve the same effect.

Table 2.1 shows a list of all of the deprecated constructs. Note that the constants `MPI_LB` and `MPI_UB` are replaced by the function `MPI_TYPE_CREATE_RESIZED`; this is because their principal use was as input datatypes to `MPI_TYPE_STRUCT` to create resized datatypes. Also note that some C typedefs and Fortran subroutine names are included in this list; they are the types of callback functions.

Deprecated	MPI-2 Replacement
MPI_ADDRESS	MPI_GET_ADDRESS
MPI_TYPE_HINDEXED	MPI_TYPE_CREATE_HINDEXED
MPI_TYPE_HVECTOR	MPI_TYPE_CREATE_HVECTOR
MPI_TYPE_STRUCT	MPI_TYPE_CREATE_STRUCT
MPI_TYPE_EXTENT	MPI_TYPE_GET_EXTENT
MPI_TYPE_UB	MPI_TYPE_GET_EXTENT
MPI_TYPE_LB	MPI_TYPE_GET_EXTENT
MPI_LB	MPI_TYPE_CREATE_RESIZED
MPI_UB	MPI_TYPE_CREATE_RESIZED
MPI_ERRHANDLER_CREATE	MPI_COMM_CREATE_ERRHANDLER
MPI_ERRHANDLER_GET	MPI_COMM_GET_ERRHANDLER
MPI_ERRHANDLER_SET	MPI_COMM_SET_ERRHANDLER
MPI_Handler_function	MPI_Comm_errhandler_function
MPI_KEYVAL_CREATE	MPI_COMM_CREATE_KEYVAL
MPI_KEYVAL_FREE	MPI_COMM_FREE_KEYVAL
MPI_DUP_FN	MPI_COMM_DUP_FN
MPI_NULL_COPY_FN	MPI_COMM_NULL_COPY_FN
MPI_NULL_DELETE_FN	MPI_COMM_NULL_DELETE_FN
MPI_Copy_function	MPI_Comm_copy_attr_function
COPY_FUNCTION	COMM_COPY_ATTR_[ticket250-V.] <b>FUNCTION</b>
MPI_Delete_function	MPI_Comm_delete_attr_function
DELETE_FUNCTION	COMM_DELETE_ATTR_[ticket250-V.] <b>FUNCTION</b>
MPI_ATTR_DELETE	MPI_COMM_DELETE_ATTR
MPI_ATTR_GET	MPI_COMM_GET_ATTR
MPI_ATTR_PUT	MPI_COMM_SET_ATTR

Table 2.1: Deprecated constructs

## 2.6.2 Fortran Binding Issues

Originally, MPI-1.1 provided bindings for Fortran 77. These bindings are retained, but they are now interpreted in the context of the Fortran 90 standard. MPI can still be used with most Fortran 77 compilers, as noted below. When the term Fortran is used it means Fortran 90 or later; it means Fortran 2008 + TR 29113 and later if the `mpi_f08` module is used.

All MPI names have an `MPI_` prefix, and all characters are capitals. Programs must not declare variables, parameters, or functions with names beginning with the prefix `MPI_`. To avoid conflicting with the profiling interface, programs should also avoid functions with the prefix `PMPI_`. This is mandated to avoid possible name collisions.

All MPI Fortran subroutines have a return code in the last argument. With `USE mpi_f08`, this last argument is declared as `OPTIONAL`, except for user-defined callback functions (e.g., `COMM_COPY_ATTR_FUNCTION`) and their predefined callbacks (e.g., `MPI_NULL_COPY_FN`). A few MPI operations which are functions do not have the return code argument. The return code value for successful completion is `MPI_SUCCESS`. Other error codes are implementation dependent; see the error codes in Chapter 8 and Annex A.

*Advice to implementors.* With the `mpi_f08` module, an MPI library may implement the `ierror` argument through function overloading instead of using the



**OPTIONAL** attribute. With function overloading, the branch is implemented at link-time; with the the **OPTIONAL** attribute, it is implemented at run-time. (*End of advice to implementors.*)

Constants representing the maximum length of a string are one smaller in Fortran than in C and C++ as discussed in Section 16.3.9.

Handles are represented in Fortran as **INTEGERs**, or with the **mpi\_f08** module as a **sequence derived type**, see Section 2.5.1 on page 12. Binary-valued variables are of type **LOGICAL**.

Array arguments are indexed from one.

The MPI Fortran bindings are inconsistent with the Fortran standard in several respects. These inconsistencies, such as register optimization problems, have implications for user codes that are discussed in detail in Section 16.2.8.

### 2.6.3 C Binding Issues

We use the ISO C declaration format. All MPI names have an **MPI\_** prefix, defined constants are in all capital letters, and defined types and functions have one capital letter after the prefix. Programs must not declare variables or functions with names beginning with the prefix **MPI\_**. To support the profiling interface, programs should not declare functions with names beginning with the prefix **PMPI\_**.

The definition of named constants, function prototypes, and type definitions must be supplied in an include file **mpi.h**.

Almost all C functions return an error code. The successful return code will be **MPI\_SUCCESS**, but failure return codes are implementation dependent.

Type declarations are provided for handles to each category of opaque objects.

Array arguments are indexed from zero.

Logical flags are integers with value 0 meaning “false” and a non-zero value meaning “true.”

Choice arguments are pointers of type **void \***.

Address arguments are of MPI defined type **MPI\_Aint**. File displacements are of type **MPI\_Offset**. **MPI\_Aint** is defined to be an integer of the size needed to hold any valid address on the target architecture. **MPI\_Offset** is defined to be an integer of the size needed to hold any valid file size on the target architecture.

### 2.6.4 C++ Binding Issues

The C++ language bindings have been deprecated. There are places in the standard that give rules for C and not for C++. In these cases, the C rule should be applied to the C++ case, as appropriate. In particular, the values of constants given in the text are the ones for C and Fortran. A cross index of these with the C++ names is given in Annex A.

We use the ISO C++ declaration format. All MPI names are declared within the scope of a namespace called **MPI** and therefore are referenced with an **MPI::** prefix. Defined constants are in all capital letters, and class names, defined types, and functions have only their first letter capitalized. Programs must not declare variables or functions in the **MPI** namespace. This is mandated to avoid possible name collisions.

The definition of named constants, function prototypes, and type definitions must be supplied in an include file **mpi.h**.

*Advice to implementors.* The file `mpi.h` may contain both the C and C++ definitions. Usually one can simply use the defined value (generally `__cplusplus`, but not required) to see if one is using C++ to protect the C++ definitions. It is possible that a C compiler will require that the source protected this way be legal C code. In this case, all the C++ definitions can be placed in a different include file and the “`#include`” directive can be used to include the necessary C++ definitions in the `mpi.h` file. (*End of advice to implementors.*)

C++ functions that create objects or return information usually place the object or information in the return value. Since the language neutral prototypes of MPI functions include the C++ return value as an OUT parameter, semantic descriptions of MPI functions refer to the C++ return value by that parameter name. The remaining C++ functions return `void`.

In some circumstances, MPI permits users to indicate that they do not want a return value. For example, the user may indicate that the status is not filled in. Unlike C and Fortran where this is achieved through a special input value, in C++ this is done by having two bindings where one has the optional argument and one does not.

C++ functions do not return error codes. If the default error handler has been set to `MPI::ERRORS_THROW_EXCEPTIONS`, the C++ exception mechanism is used to signal an error by throwing an `MPI::Exception` object.

It should be noted that the default error handler (i.e., `MPI::ERRORS_ARE_FATAL`) on a given type has not changed. User error handlers are also permitted. `MPI::ERRORS_RETURN` simply returns control to the calling function; there is no provision for the user to retrieve the error code.

User callback functions that return integer error codes should not throw exceptions; the returned error will be handled by the MPI implementation by invoking the appropriate error handler.

*Advice to users.* C++ programmers that want to handle MPI errors on their own should use the `MPI::ERRORS_THROW_EXCEPTIONS` error handler, rather than `MPI::ERRORS_RETURN`, that is used for that purpose in C. Care should be taken using exceptions in mixed language situations. (*End of advice to users.*)

Opaque object handles must be objects in themselves, and have the assignment and equality operators overridden to perform semantically like their C and Fortran counterparts.

Array arguments are indexed from zero.

Logical flags are of type `bool`.

Choice arguments are pointers of type `void *`.

Address arguments are of MPI-defined integer type `MPI::Aint`, defined to be an integer of the size needed to hold any valid address on the target architecture. Analogously, `MPI::Offset` is an integer to hold file offsets.

Most MPI functions are methods of MPI C++ classes. MPI class names are generated from the language neutral MPI types by dropping the `MPI_` prefix and scoping the type within the MPI namespace. For example, `MPI_DATATYPE` becomes `MPI::Datatype`.

The names of MPI functions generally follow the naming rules given. In some circumstances, the MPI function is related to a function defined already for MPI-1 with a name that does not follow the naming conventions. In this circumstance, the language neutral name is in analogy to the MPI name even though this gives an MPI-2 name that violates the



naming conventions. The C and Fortran names are the same as the language neutral name in this case. However, the C++ names do reflect the naming rules and can differ from the C and Fortran names. Thus, the analogous name in C++ to the MPI name may be different than the language neutral name. This results in the C++ name differing from the language neutral name. An example of this is the language neutral name of MPI\_FINALIZED and a C++ name of MPI::ls\_finalized.

In C++, function `typedefs` are made publicly within appropriate classes. However, these declarations then become somewhat cumbersome, as with the following:

```
{typedef MPI::Grequest::Query_function(); (binding deprecated, see Section 15.2)}
```

would look like the following:

```
namespace MPI {
    class Request {
        // ...
    };

    class Grequest : public MPI::Request {
        // ...
        typedef Query_function(void* extra_state, MPI::Status& status);
    };
};
```

Rather than including this scaffolding when declaring C++ `typedefs`, we use an abbreviated form. In particular, we explicitly indicate the class and namespace scope for the `typedef` of the function. Thus, the example above is shown in the text as follows:

```
typedef int MPI::Grequest::Query_function(void* extra_state,
                                           MPI::Status& status)
```

The C++ bindings presented in Annex A.5 and throughout this document were generated by applying a simple set of name generation rules to the MPI function specifications. While these guidelines may be sufficient in most cases, they may not be suitable for all situations. In cases of ambiguity or where a specific semantic statement is desired, these guidelines may be superseded as the situation dictates.

1. All functions, types, and constants are declared within the scope of a `namespace` called `MPI`.
2. Arrays of MPI handles are always left in the argument list (whether they are IN or OUT arguments).
3. If the argument list of an MPI function contains a scalar IN handle, and it makes sense to define the function as a method of the object corresponding to that handle, the function is made a member function of the corresponding MPI class. The member functions are named according to the corresponding MPI function name, but without the “MPI\_” prefix and without the object name prefix (if applicable). In addition:
  - (a) The scalar IN handle is dropped from the argument list, and `this` corresponds to the dropped argument.

(b) The function is declared `const`.

4. MPI functions are made into class functions (static) when they belong on a class but do not have a unique scalar IN or INOUT parameter of that class.
5. If the argument list contains a single OUT argument that is not of type `MPI_STATUS` (or an array), that argument is dropped from the list and the function returns that value.

**Example 2.1** The C++ binding for `MPI_COMM_SIZE` is  
`int MPI::Comm::Get_size(void) const`.

6. If there are multiple OUT arguments in the argument list, one is chosen as the return value and is removed from the list.
7. If the argument list does not contain any OUT arguments, the function returns `void`.

**Example 2.2** The C++ binding for `MPI_REQUEST_FREE` is  
`void MPI::Request::Free(void)`

8. MPI functions to which the above rules do not apply are not members of any class, but are defined in the `MPI` namespace.

**Example 2.3** The C++ binding for `MPI_BUFFER_ATTACH` is  
`void MPI::Attach_buffer(void* buffer, int size)`.

9. All class names, defined types, and function names have only their first letter capitalized. Defined constants are in all capital letters.
10. Any IN pointer, reference, or array argument must be declared `const`.
11. Handles are passed by reference.
12. Array arguments are denoted with square brackets (`[]`), not pointers, as this is more semantically precise.

### 2.6.5 Functions and Macros

An implementation is allowed to implement `MPI_WTIME`, `MPI_WTICK`, `PMPI_WTIME`, `PMPI_WTICK`, and the handle-conversion functions (`MPI_Group_f2c`, etc.) in Section 16.3.4, and no others, as macros in C.

*Advice to implementors.* Implementors should document which routines are implemented as macros. (*End of advice to implementors.*)

*Advice to users.* If these routines are implemented as macros, they will not work with the MPI profiling interface. (*End of advice to users.*)

## 2.7 Processes

An MPI program consists of autonomous processes, executing their own code, in an MIMD style. The codes executed by each process need not be identical. The processes communicate via calls to MPI communication primitives. Typically, each process executes in its own address space, although shared-memory implementations of MPI are possible.

This document specifies the behavior of a parallel program assuming that only MPI calls are used. The interaction of an MPI program with other possible means of communication, I/O, and process management is not specified. Unless otherwise stated in the specification of the standard, MPI places no requirements on the result of its interaction with external mechanisms that provide similar or equivalent functionality. This includes, but is not limited to, interactions with external mechanisms for process control, shared and remote memory access, file system access and control, interprocess communication, process signaling, and terminal I/O. High quality implementations should strive to make the results of such interactions intuitive to users, and attempt to document restrictions where deemed necessary.

*Advice to implementors.* Implementations that support such additional mechanisms for functionality supported within MPI are expected to document how these interact with MPI. (*End of advice to implementors.*)

The interaction of MPI and threads is defined in Section [12.4](#).

## 2.8 Error Handling

MPI provides the user with reliable message transmission. A message sent is always received correctly, and the user does not need to check for transmission errors, time-outs, or other error conditions. In other words, MPI does not provide mechanisms for dealing with failures in the communication system. If the MPI implementation is built on an unreliable underlying mechanism, then it is the job of the implementor of the MPI subsystem to insulate the user from this unreliability, or to reflect unrecoverable errors as failures. Whenever possible, such failures will be reflected as errors in the relevant communication call. Similarly, MPI itself provides no mechanisms for handling processor failures.

Of course, MPI programs may still be erroneous. A **program error** can occur when an MPI call is made with an incorrect argument (non-existing destination in a send operation, buffer too small in a receive operation, etc.). This type of error would occur in any implementation. In addition, a **resource error** may occur when a program exceeds the amount of available system resources (number of pending messages, system buffers, etc.). The occurrence of this type of error depends on the amount of available resources in the system and the resource allocation mechanism used; this may differ from system to system. A high-quality implementation will provide generous limits on the important resources so as to alleviate the portability problem this represents.

In C and Fortran, almost all MPI calls return a code that indicates successful completion of the operation. Whenever possible, MPI calls return an error code if an error occurred during the call. By default, an error detected during the execution of the MPI library causes the parallel computation to abort, except for file operations. However, MPI provides mechanisms for users to change this default and to handle recoverable errors. The user may specify that no error is fatal, and handle error codes returned by MPI calls by himself

or herself. Also, the user may provide his or her own error-handling routines, which will be invoked whenever an MPI call returns abnormally. The MPI error handling facilities are described in Section 8.3. The return values of C++ functions are not error codes. If the default error handler has been set to `MPI::ERRORS_THROW_EXCEPTIONS`, the C++ exception mechanism is used to signal an error by throwing an `MPI::Exception` object. See also Section 16.1.8 on page 540.

Several factors limit the ability of MPI calls to return with meaningful error codes when an error occurs. MPI may not be able to detect some errors; other errors may be too expensive to detect in normal execution mode; finally some errors may be “catastrophic” and may prevent MPI from returning control to the caller in a consistent state.

Another subtle issue arises because of the nature of asynchronous communications: MPI calls may initiate operations that continue asynchronously after the call returned. Thus, the operation may return with a code indicating successful completion, yet later cause an error exception to be raised. If there is a subsequent call that relates to the same operation (e.g., a call that verifies that an asynchronous operation has completed) then the error argument associated with this call will be used to indicate the nature of the error. In a few cases, the error may occur after all calls that relate to the operation have completed, so that no error value can be used to indicate the nature of the error (e.g., an error on the receiver in a send with the ready mode). Such an error must be treated as fatal, since information cannot be returned for the user to recover from it.

This document does not specify the state of a computation after an erroneous MPI call has occurred. The desired behavior is that a relevant error code be returned, and the effect of the error be localized to the greatest possible extent. E.g., it is highly desirable that an erroneous receive call will not cause any part of the receiver’s memory to be overwritten, beyond the area specified for receiving the message.

Implementations may go beyond this document in supporting in a meaningful manner MPI calls that are defined here to be erroneous. For example, MPI specifies strict type matching rules between matching send and receive operations: it is erroneous to send a floating point variable and receive an integer. Implementations may go beyond these type matching rules, and provide automatic type conversion in such situations. It will be helpful to generate warnings for such non-conforming behavior.

MPI defines a way for users to create new error codes as defined in Section 8.5.

## 2.9 Implementation Issues

There are a number of areas where an MPI implementation may interact with the operating environment and system. While MPI does not mandate that any services (such as signal handling) be provided, it does strongly suggest the behavior to be provided if those services are available. This is an important point in achieving portability across platforms that provide the same set of services.

### 2.9.1 Independence of Basic Runtime Routines

MPI programs require that library routines that are part of the basic language environment (such as `write` in Fortran and `printf` and `malloc` in ISO C) and are executed after `MPI_INIT` and before `MPI_FINALIZE` operate independently and that their *completion* is independent of the action of other processes in an MPI program.

Note that this in no way prevents the creation of library routines that provide parallel services whose operation is collective. However, the following program is expected to complete in an ISO C environment regardless of the size of `MPI_COMM_WORLD` (assuming that `printf` is available at the executing nodes).

```
int rank;
MPI_Init((void *)0, (void *)0);
MPI_Comm_rank(MPI_COMM_WORLD, &rank);
if (rank == 0) printf("Starting program\n");
MPI_Finalize();
```

The corresponding Fortran and C++ programs are also expected to complete.

An example of what is *not* required is any particular ordering of the action of these routines when called by several tasks. For example, MPI makes neither requirements nor recommendations for the output from the following program (again assuming that I/O is available at the executing nodes).

```
MPI_Comm_rank(MPI_COMM_WORLD, &rank);
printf("Output from task rank %d\n", rank);
```

In addition, calls that fail because of resource exhaustion or other error are not considered a violation of the requirements here (however, they are required to complete, just not to complete successfully).

## 2.9.2 Interaction with Signals

MPI does not specify the interaction of processes with signals and does not require that MPI be signal safe. The implementation may reserve some signals for its own use. It is required that the implementation document which signals it uses, and it is strongly recommended that it not use `SIGALRM`, `SIGFPE`, or `SIGIO`. Implementations may also prohibit the use of MPI calls from within signal handlers.

In multithreaded environments, users can avoid conflicts between signals and the MPI library by catching signals only on threads that do not execute MPI calls. High quality single-threaded implementations will be signal safe: an MPI call suspended by a signal will resume and complete normally after the signal is handled.

## 2.10 Examples

The examples in this document are for illustration purposes only. They are not intended to specify the standard. Furthermore, the examples have not been carefully checked or verified.

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## Chapter 3

# Point-to-Point Communication

### 3.1 Introduction

Sending and receiving of messages by processes is the basic MPI communication mechanism. The basic point-to-point communication operations are **send** and **receive**. Their use is illustrated in the example below.

```
#include "mpi.h"
int main( int argc, char **argv )
{
    char message[20];
    int myrank;
    MPI_Status status;
    MPI_Init( &argc, &argv );
    MPI_Comm_rank( MPI_COMM_WORLD, &myrank );
    if (myrank == 0) /* code for process zero */
    {
        strcpy(message, "Hello, there");
        MPI_Send(message, strlen(message)+1, MPI_CHAR, 1, 99, MPI_COMM_WORLD);
    }
    else if (myrank == 1) /* code for process one */
    {
        MPI_Recv(message, 20, MPI_CHAR, 0, 99, MPI_COMM_WORLD, &status);
        printf("received :%s:\n", message);
    }
    MPI_Finalize();
}
```

In this example, process zero (`myrank = 0`) sends a message to process one using the **send** operation `MPI_SEND`. The operation specifies a **send buffer** in the sender memory from which the message data is taken. In the example above, the send buffer consists of the storage containing the variable `message` in the memory of process zero. The location, size and type of the send buffer are specified by the first three parameters of the send operation. The message sent will contain the 13 characters of this variable. In addition, the send operation associates an **envelope** with the message. This envelope specifies the message destination and contains distinguishing information that can be used by the **receive**

operation to select a particular message. The last three parameters of the send operation, along with the rank of the sender, specify the envelope for the message sent. Process one (`myrank = 1`) receives this message with the **receive** operation `MPI_RECV`. The message to be received is selected according to the value of its envelope, and the message data is stored into the **receive buffer**. In the example above, the receive buffer consists of the storage containing the string `message` in the memory of process one. The first three parameters of the receive operation specify the location, size and type of the receive buffer. The next three parameters are used for selecting the incoming message. The last parameter is used to return information on the message just received.

The next sections describe the blocking send and receive operations. We discuss send, receive, blocking communication semantics, type matching requirements, type conversion in heterogeneous environments, and more general communication modes. Nonblocking communication is addressed next, followed by channel-like constructs and send-receive operations. Nonblocking communication is addressed next, followed by channel-like constructs and send-receive operations, ending with a description of the “dummy” process, `MPI_PROC_NULL`.

## 3.2 Blocking Send and Receive Operations

### 3.2.1 Blocking Send

The syntax of the blocking send operation is given below.

`MPI_SEND(buf, count, datatype, dest, tag, comm)`

IN	buf	initial address of send buffer (choice)
IN	count	number of elements in send buffer (non-negative integer)
IN	datatype	datatype of each send buffer element (handle)
IN	dest	rank of destination (integer)
IN	tag	message tag (integer)
IN	comm	communicator (handle)

```
int MPI_Send(void* buf, int count, MPI_Datatype datatype, int dest,
             int tag, MPI_Comm comm)
```

```
MPI_SEND(BUF, COUNT, DATATYPE, DEST, TAG, COMM, IERROR)
```

```
<type> BUF(*)
```

```
INTEGER COUNT, DATATYPE, DEST, TAG, COMM, IERROR
```

```
MPI_Send(buf, count, datatype, dest, tag, comm, ierror)
```

```
TYPE(*), DIMENSION(..) :: buf
```

```
INTEGER, INTENT(IN) :: count, dest, tag
```

```
TYPE(MPI_Datatype), INTENT(IN) :: datatype
```

```
TYPE(MPI_Comm), INTENT(IN) :: comm
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```



```
{void MPI::Comm::Send(const void* buf, int count, const
    MPI::Datatype& datatype, int dest, int tag) const(binding
    deprecated, see Section 15.2) }
```

The blocking semantics of this call are described in Section 3.4.

### 3.2.2 Message Data

The send buffer specified by the `MPI_SEND` operation consists of `count` successive entries of the type indicated by `datatype`, starting with the entry at address `buf`. Note that we specify the message length in terms of number of *elements*, not number of *bytes*. The former is machine independent and closer to the application level.

The data part of the message consists of a sequence of `count` values, each of the type indicated by `datatype`. `count` may be zero, in which case the data part of the message is empty. The basic datatypes that can be specified for message data values correspond to the basic datatypes of the host language. Possible values of this argument for Fortran and the corresponding Fortran types are listed in Table 3.1.

MPI datatype	Fortran datatype
<code>MPI_INTEGER</code>	<code>INTEGER</code>
<code>MPI_REAL</code>	<code>REAL</code>
<code>MPI_DOUBLE_PRECISION</code>	<code>DOUBLE PRECISION</code>
<code>MPI_COMPLEX</code>	<code>COMPLEX</code>
<code>MPI_LOGICAL</code>	<code>LOGICAL</code>
<code>MPI_CHARACTER</code>	<code>CHARACTER(1)</code>
<code>MPI_BYTE</code>	
<code>MPI_PACKED</code>	

Table 3.1: Predefined MPI datatypes corresponding to Fortran datatypes

Possible values for this argument for C and the corresponding C types are listed in Table 3.2.

The datatypes `MPI_BYTE` and `MPI_PACKED` do not correspond to a Fortran or C datatype. A value of type `MPI_BYTE` consists of a byte (8 binary digits). A byte is uninterpreted and is different from a character. Different machines may have different representations for characters, or may use more than one byte to represent characters. On the other hand, a byte has the same binary value on all machines. The use of the type `MPI_PACKED` is explained in Section 4.2.

MPI requires support of these datatypes, which match the basic datatypes of Fortran and ISO C. Additional MPI datatypes should be provided if the host language has additional data types: `MPI_DOUBLE_COMPLEX` for double precision complex in Fortran declared to be of type `DOUBLE COMPLEX`; `MPI_REAL2`, `MPI_REAL4` and `MPI_REAL8` for Fortran reals, declared to be of type `REAL*2`, `REAL*4` and `REAL*8`, respectively; `MPI_INTEGER1`, `MPI_INTEGER2` and `MPI_INTEGER4` for Fortran integers, declared to be of type `INTEGER*1`, `INTEGER*2` and `INTEGER*4`, respectively; etc.

*Rationale.* One goal of the design is to allow for MPI to be implemented as a library, with no need for additional preprocessing or compilation. Thus, one cannot assume that a communication call has information on the datatype of variables in the

MPI datatype	C datatype
MPI_CHAR	char (treated as printable character)
MPI_SHORT	signed short int
MPI_INT	signed int
MPI_LONG	signed long int
MPI_LONG_LONG_INT	signed long long int
MPI_LONG_LONG (as a synonym)	signed long long int
MPI_SIGNED_CHAR	signed char (treated as integral value)
MPI_UNSIGNED_CHAR	unsigned char (treated as integral value)
MPI_UNSIGNED_SHORT	unsigned short int
MPI_UNSIGNED	unsigned int
MPI_UNSIGNED_LONG	unsigned long int
MPI_UNSIGNED_LONG_LONG	unsigned long long int
MPI_FLOAT	float
MPI_DOUBLE	double
MPI_LONG_DOUBLE	long double
MPI_WCHAR	wchar_t (defined in <stddef.h>) (treated as printable character)
MPI_C_BOOL	_Bool
MPI_INT8_T	int8_t
MPI_INT16_T	int16_t
MPI_INT32_T	int32_t
MPI_INT64_T	int64_t
MPI_UINT8_T	uint8_t
MPI_UINT16_T	uint16_t
MPI_UINT32_T	uint32_t
MPI_UINT64_T	uint64_t
MPI_C_COMPLEX	float _Complex
MPI_C_FLOAT_COMPLEX (as a synonym)	float _Complex
MPI_C_DOUBLE_COMPLEX	double _Complex
MPI_C_LONG_DOUBLE_COMPLEX	long double _Complex
MPI_BYTE	
MPI_PACKED	

Table 3.2: Predefined MPI datatypes corresponding to C datatypes

communication buffer; this information must be supplied by an explicit argument. The need for such datatype information will become clear in Section 3.3.2. (*End of rationale.*)

*Rationale.* The datatypes MPI\_C\_BOOL, MPI\_INT8\_T, MPI\_INT16\_T, MPI\_INT32\_T, MPI\_UINT8\_T, MPI\_UINT16\_T, MPI\_UINT32\_T, MPI\_C\_COMPLEX, MPI\_C\_FLOAT\_COMPLEX, MPI\_C\_DOUBLE\_COMPLEX, and

MPI datatype	C datatype	Fortran datatype
MPI_AINT	MPI_Aint	INTEGER (KIND=MPI_ADDRESS_KIND)
MPI_OFFSET	MPI_Offset	INTEGER (KIND=MPI_OFFSET_KIND)

Table 3.3: Predefined MPI datatypes corresponding to both C and Fortran datatypes

MPI\_C\_LONG\_DOUBLE\_COMPLEX have no corresponding C++ bindings. This was intentionally done to avoid potential collisions with the C preprocessor and namespace C++ names. C++ applications can use the C bindings with no loss of functionality. (*End of rationale.*)

The datatypes MPI\_AINT and MPI\_OFFSET correspond to the MPI-defined C types MPI\_Aint and MPI\_Offset and their Fortran equivalents INTEGER (KIND=MPI\_ADDRESS\_KIND) and INTEGER (KIND=MPI\_OFFSET\_KIND). This is described in Table 3.3. See Section 16.3.10 for information on interlanguage communication with these types.

### 3.2.3 Message Envelope

In addition to the data part, messages carry information that can be used to distinguish messages and selectively receive them. This information consists of a fixed number of fields, which we collectively call the **message envelope**. These fields are

source  
destination  
tag  
communicator

The message source is implicitly determined by the identity of the message sender. The other fields are specified by arguments in the send operation.

The message destination is specified by the **dest** argument.

The integer-valued message tag is specified by the **tag** argument. This integer can be used by the program to distinguish different types of messages. The range of valid tag values is 0,...,UB, where the value of UB is implementation dependent. It can be found by querying the value of the attribute MPI\_TAG\_UB, as described in Chapter 8. MPI requires that UB be no less than 32767.

The **comm** argument specifies the **communicator** that is used for the send operation. Communicators are explained in Chapter 6; below is a brief summary of their usage.

A communicator specifies the communication context for a communication operation. Each communication context provides a separate “communication universe:” messages are always received within the context they were sent, and messages sent in different contexts do not interfere.

The communicator also specifies the set of processes that share this communication context. This **process group** is ordered and processes are identified by their rank within this group. Thus, the range of valid values for **dest** is 0, ... , n-1, where n is the number of processes in the group. (If the communicator is an inter-communicator, then destinations are identified by their rank in the remote group. See Chapter 6.)

A predefined communicator `MPI_COMM_WORLD` is provided by MPI. It allows communication with all processes that are accessible after MPI initialization and processes are identified by their rank in the group of `MPI_COMM_WORLD`.

*Advice to users.* Users that are comfortable with the notion of a flat name space for processes, and a single communication context, as offered by most existing communication libraries, need only use the predefined variable `MPI_COMM_WORLD` as the `comm` argument. This will allow communication with all the processes available at initialization time.

Users may define new communicators, as explained in Chapter 6. Communicators provide an important encapsulation mechanism for libraries and modules. They allow modules to have their own disjoint communication universe and their own process numbering scheme. (*End of advice to users.*)

*Advice to implementors.* The message envelope would normally be encoded by a fixed-length message header. However, the actual encoding is implementation dependent. Some of the information (e.g., source or destination) may be implicit, and need not be explicitly carried by messages. Also, processes may be identified by relative ranks, or absolute ids, etc. (*End of advice to implementors.*)

### 3.2.4 Blocking Receive

The syntax of the blocking receive operation is given below.

`MPI_RECV (buf, count, datatype, source, tag, comm, status)`

OUT	buf	initial address of receive buffer (choice)
IN	count	number of elements in receive buffer (non-negative integer)
IN	datatype	datatype of each receive buffer element (handle)
IN	source	rank of source or <code>MPI_ANY_SOURCE</code> (integer)
IN	tag	message tag or <code>MPI_ANY_TAG</code> (integer)
IN	comm	communicator (handle)
OUT	status	status object (Status)

```
int MPI_Recv(void* buf, int count, MPI_Datatype datatype, int source,
            int tag, MPI_Comm comm, MPI_Status *status)
```

```
MPI_RECV(BUF, COUNT, DATATYPE, SOURCE, TAG, COMM, STATUS, IERROR)
<type> BUF(*)
INTEGER COUNT, DATATYPE, SOURCE, TAG, COMM, STATUS(MPI_STATUS_SIZE),
IERROR
```

```
MPI_Recv(buf, count, datatype, source, tag, comm, status, ierror)
TYPE(*), DIMENSION(..) :: buf
INTEGER, INTENT(IN) :: count, source, tag
TYPE(MPI_Datatype), INTENT(IN) :: datatype
```

```

TYPE(MPI_Comm), INTENT(IN) :: comm
TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Comm::Recv(void* buf, int count, const MPI::Datatype& datatype,
    int source, int tag, MPI::Status& status) const(binding
    deprecated, see Section 15.2) }

{void MPI::Comm::Recv(void* buf, int count, const MPI::Datatype& datatype,
    int source, int tag) const(binding deprecated, see Section 15.2) }

```

The blocking semantics of this call are described in Section 3.4.

The receive buffer consists of the storage containing `count` consecutive elements of the type specified by `datatype`, starting at address `buf`. The length of the received message must be less than or equal to the length of the receive buffer. An overflow error occurs if all incoming data does not fit, without truncation, into the receive buffer.

If a message that is shorter than the receive buffer arrives, then only those locations corresponding to the (shorter) message are modified.

*Advice to users.* The `MPI_PROBE` function described in Section 3.8 can be used to receive messages of unknown length. (*End of advice to users.*)

*Advice to implementors.* Even though no specific behavior is mandated by MPI for erroneous programs, the recommended handling of overflow situations is to return in `status` information about the source and tag of the incoming message. The receive operation will return an error code. A quality implementation will also ensure that no memory that is outside the receive buffer will ever be overwritten.

In the case of a message shorter than the receive buffer, MPI is quite strict in that it allows no modification of the other locations. A more lenient statement would allow for some optimizations but this is not allowed. The implementation must be ready to end a copy into the receiver memory exactly at the end of the receive buffer, even if it is an odd address. (*End of advice to implementors.*)

The selection of a message by a receive operation is governed by the value of the message envelope. A message can be received by a receive operation if its envelope matches the `source`, `tag` and `comm` values specified by the receive operation. The receiver may specify a wildcard `MPI_ANY_SOURCE` value for `source`, and/or a wildcard `MPI_ANY_TAG` value for `tag`, indicating that any source and/or tag are acceptable. It cannot specify a wildcard value for `comm`. Thus, a message can be received by a receive operation only if it is addressed to the receiving process, has a matching communicator, has matching source unless `source=MPI_ANY_SOURCE` in the pattern, and has a matching tag unless `tag=MPI_ANY_TAG` in the pattern.

The message tag is specified by the `tag` argument of the receive operation. The argument `source`, if different from `MPI_ANY_SOURCE`, is specified as a rank within the process group associated with that same communicator (remote process group, for intercommunicators). Thus, the range of valid values for the `source` argument is  $\{0, \dots, n-1\} \cup \{\text{MPI\_ANY\_SOURCE}\}$ , where  $n$  is the number of processes in this group.

Note the asymmetry between send and receive operations: A receive operation may accept messages from an arbitrary sender, on the other hand, a send operation must specify

a unique receiver. This matches a “push” communication mechanism, where data transfer is effected by the sender (rather than a “pull” mechanism, where data transfer is effected by the receiver).

Source = destination is allowed, that is, a process can send a message to itself. (However, it is unsafe to do so with the blocking send and receive operations described above, since this may lead to deadlock. See Section 3.5.)

*Advice to implementors.* Message context and other communicator information can be implemented as an additional tag field. It differs from the regular message tag in that wild card matching is not allowed on this field, and that value setting for this field is controlled by communicator manipulation functions. (*End of advice to implementors.*)

### 3.2.5 Return Status

The source or tag of a received message may not be known if wildcard values were used in the receive operation. Also, if multiple requests are completed by a single MPI function (see Section 3.7.5), a distinct error code may need to be returned for each request. The information is returned by the `status` argument of `MPI_RECV`. The type of `status` is MPI-defined. Status variables need to be explicitly allocated by the user, that is, they are not system objects.

In C, `status` is a structure that contains three fields named `MPI_SOURCE`, `MPI_TAG`, and `MPI_ERROR`; the structure may contain additional fields. Thus, `status.MPI_SOURCE`, `status.MPI_TAG` and `status.MPI_ERROR` contain the source, tag, and error code, respectively, of the received message.

In Fortran with `USE mpi` or `INCLUDE 'mpif.h'`, `status` is an array of `INTEGER`s of size `MPI_STATUS_SIZE`. The constants `MPI_SOURCE`, `MPI_TAG` and `MPI_ERROR` are the indices of the entries that store the source, tag and error fields. Thus, `status(MPI_SOURCE)`, `status(MPI_TAG)` and `status(MPI_ERROR)` contain, respectively, the source, tag and error code of the received message.

With Fortran `USE mpi_f08`, `status` is defined as the Fortran sequence derived type `TYPE(MPI_Status)` containing three public fields named `MPI_SOURCE`, `MPI_TAG`, and `MPI_ERROR`. `TYPE(MPI_Status)` may contain additional, implementation-specific fields. Thus, `status%MPI_SOURCE`, `status%MPI_TAG` and `status%MPI_ERROR` contain the source, tag, and error code of a received message respectively. Additionally, within both the `mpi` and the `mpi_f08` modules, the constants `MPI_STATUS_SIZE`, `MPI_SOURCE`, `MPI_TAG`, `MPI_ERROR`, and `TYPE(MPI_Status)` are defined to allow conversion between both `status` representations.

*Rationale.* The Fortran `TYPE(MPI_Status)` is defined as a sequence derived type so that it can be used at any location where the status integer array representation can be used, e.g., in user defined sequence derived types or common blocks. (*End of rationale.*)

*Rationale.* It is allowed to have the same name (e.g., `MPI_SOURCE`) defined as a constant (e.g., Fortran parameter) and as a field of a derived type. (*End of rationale.*)

In C++, the `status` object is handled through the following methods:

```
{int MPI::Status::Get_source() const(binding deprecated, see Section 15.2) }
```

```

{void MPI::Status::Set_source(int source) (binding deprecated, see Section 15.2) }
{int MPI::Status::Get_tag() const (binding deprecated, see Section 15.2) }
{void MPI::Status::Set_tag(int tag) (binding deprecated, see Section 15.2) }
{int MPI::Status::Get_error() const (binding deprecated, see Section 15.2) }
{void MPI::Status::Set_error(int error) (binding deprecated, see Section 15.2) }

```

In general, message-passing calls do not modify the value of the error code field of status variables. This field may be updated only by the functions in Section 3.7.5 which return multiple statuses. The field is updated if and only if such function returns with an error code of MPI\_ERR\_IN\_STATUS.

*Rationale.* The error field in status is not needed for calls that return only one status, such as MPI\_WAIT, since that would only duplicate the information returned by the function itself. The current design avoids the additional overhead of setting it, in such cases. The field is needed for calls that return multiple statuses, since each request may have had a different failure. (*End of rationale.*)

The status argument also returns information on the length of the message received. However, this information is not directly available as a field of the status variable and a call to MPI\_GET\_COUNT is required to “decode” this information.

MPI\_GET\_COUNT(status, datatype, count)

IN	status	return status of receive operation (Status)
IN	datatype	datatype of each receive buffer entry (handle)
OUT	count	number of received entries (integer)

```
int MPI_Get_count(MPI_Status *status, MPI_Datatype datatype, int *count)
```

```
MPI_GET_COUNT(STATUS, DATATYPE, COUNT, IERROR)
```

```
INTEGER STATUS(MPI_STATUS_SIZE), DATATYPE, COUNT, IERROR
```

```
MPI_Get_count(status, datatype, count, ierror)
```

```

TYPE(MPI_Status), INTENT(IN) :: status
TYPE(MPI_Datatype), INTENT(IN) :: datatype
INTEGER, INTENT(OUT) :: count
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{int MPI::Status::Get_count(const MPI::Datatype& datatype) const (binding
    deprecated, see Section 15.2) }

```

Returns the number of entries received. (Again, we count *entries*, each of type *datatype*, not *bytes*.) The *datatype* argument should match the argument provided by the receive call that set the *status* variable. (We shall later see, in Section 4.1.11, that MPI\_GET\_COUNT may return, in certain situations, the value MPI\_UNDEFINED.)

*Rationale.* Some message-passing libraries use INOUT count, tag and source arguments, thus using them both to specify the selection criteria for incoming



messages and return the actual envelope values of the received message. The use of a separate status argument prevents errors that are often attached with INOUT argument (e.g., using the `MPI_ANY_TAG` constant as the tag in a receive). Some libraries use calls that refer implicitly to the “last message received.” This is not thread safe.

The `datatype` argument is passed to `MPI_GET_COUNT` so as to improve performance. A message might be received without counting the number of elements it contains, and the count value is often not needed. Also, this allows the same function to be used after a call to `MPI_PROBE` or `MPI_IProbe`. With a status from `MPI_PROBE` or `MPI_IProbe`, the same datatypes are allowed as in a call to `MPI_RECV` to receive this message. (*End of rationale.*)

The value returned as the `count` argument of `MPI_GET_COUNT` for a datatype of length zero where zero bytes have been transferred is zero. If the number of bytes transferred is greater than zero, `MPI_UNDEFINED` is returned.

*Rationale.* Zero-length datatypes may be created in a number of cases. An important case is `MPI_TYPE_CREATE_DARRAY`, where the definition of the particular darray results in an empty block on some MPI process. Programs written in an SPMD style will not check for this special case and may want to use `MPI_GET_COUNT` to check the status. (*End of rationale.*)

*Advice to users.* The buffer size required for the receive can be affected by data conversions and by the stride of the receive datatype. In most cases, the safest approach is to use the same datatype with `MPI_GET_COUNT` and the receive. (*End of advice to users.*)

All send and receive operations use the `buf`, `count`, `datatype`, `source`, `dest`, `tag`, `comm` and `status` arguments in the same way as the blocking `MPI_SEND` and `MPI_RECV` operations described in this section.

### 3.2.6 Passing `MPI_STATUS_IGNORE` for Status

Every call to `MPI_RECV` includes a `status` argument, wherein the system can return details about the message received. There are also a number of other MPI calls where `status` is returned. An object of type `MPI_STATUS` is not an MPI opaque object; its structure is declared in `mpi.h` and `mpif.h`, and it exists in the user’s program. In many cases, application programs are constructed so that it is unnecessary for them to examine the `status` fields. In these cases, it is a waste for the user to allocate a status object, and it is particularly wasteful for the MPI implementation to fill in fields in this object.

To cope with this problem, there are two predefined constants, `MPI_STATUS_IGNORE` and `MPI_STATUSES_IGNORE` with the C language bindings and the Fortran bindings through the `mpi` module and the `mpif.h` include file, which when passed to a receive, wait, or test function, inform the implementation that the status fields are not to be filled in. Note that `MPI_STATUS_IGNORE` is not a special type of `MPI_STATUS` object; rather, it is a special value for the argument. In C one would expect it to be `NULL`, not the address of a special `MPI_STATUS`.

`MPI_STATUS_IGNORE`, and the array version `MPI_STATUSES_IGNORE`, can be used everywhere a status argument is passed to a receive, wait, or test function. `MPI_STATUS_IGNORE`



cannot be used when status is an IN argument. Note that in Fortran `MPI_STATUS_IGNORE` and `MPI_STATUSES_IGNORE` are objects like `MPI_BOTTOM` (not usable for initialization or assignment). See Section 2.5.4.

In general, this optimization can apply to all functions for which `status` or an array of `statuses` is an OUT argument. Note that this converts `status` into an INOUT argument. The functions that can be passed `MPI_STATUS_IGNORE` are all the various forms of `MPI_RECV`, `MPI_TEST`, and `MPI_WAIT`, as well as `MPI_REQUEST_GET_STATUS`. When an array is passed, as in the `MPI_{TEST|WAIT}{ALL|SOME}` functions, a separate constant, `MPI_STATUSES_IGNORE`, is passed for the array argument. It is possible for an MPI function to return `MPI_ERR_IN_STATUS` even when `MPI_STATUS_IGNORE` or `MPI_STATUSES_IGNORE` has been passed to that function.

`MPI_STATUS_IGNORE` and `MPI_STATUSES_IGNORE` are not required to have the same values in C and Fortran.

It is not allowed to have some of the statuses in an array of statuses for `MPI_{TEST|WAIT}{ALL|SOME}` functions set to `MPI_STATUS_IGNORE`; one either specifies ignoring *all* of the statuses in such a call with `MPI_STATUSES_IGNORE`, or *none* of them by passing normal statuses in all positions in the array of statuses.

With the Fortran bindings through the `mpi_f08` module and the C++ bindings, `MPI_STATUS_IGNORE` and `MPI_STATUSES_IGNORE` do not exist. To allow an OUT or INOUT `TYPE(MPI_Status)` or `MPI::Status` argument to be ignored, all MPI `mpi_f08` or C++ bindings that have OUT or INOUT `TYPE(MPI_Status)` or `MPI::Status` parameters are overloaded with a second version that omits the OUT or INOUT `TYPE(MPI_Status)` or `MPI::Status` parameter.

**Example 3.1** The `mpi_f08` bindings for `MPI_PROBE` (the specific routine names ending with `_with_status` and `_without_status` are implementation dependent):

```

INTERFACE MPI_Probe
  SUBROUTINE MPI_Probe_with_status(source, tag, comm, status, ierror)
    INTEGER, INTENT(IN) :: source, tag
    TYPE(MPI_Comm), INTENT(IN) :: comm
    TYPE(MPI_Status), INTENT(OUT) :: status
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
  END SUBROUTINE
  SUBROUTINE MPI_Probe_without_status(source, tag, comm, ierror)
    INTEGER, INTENT(IN) :: source, tag
    TYPE(MPI_Comm), INTENT(IN) :: comm
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
  END SUBROUTINE
END INTERFACE MPI_Probe

```

**Example 3.2** The C++ bindings for `MPI_PROBE` are:

```

void MPI::Comm::Probe(int source, int tag, MPI::Status& status) const
void MPI::Comm::Probe(int source, int tag) const

```

### 3.3 Data Type Matching and Data Conversion

#### 3.3.1 Type Matching Rules

One can think of message transfer as consisting of the following three phases.

1. Data is pulled out of the send buffer and a message is assembled.
2. A message is transferred from sender to receiver.
3. Data is pulled from the incoming message and disassembled into the receive buffer.

Type matching has to be observed at each of these three phases: The type of each variable in the sender buffer has to match the type specified for that entry by the send operation; the type specified by the send operation has to match the type specified by the receive operation; and the type of each variable in the receive buffer has to match the type specified for that entry by the receive operation. A program that fails to observe these three rules is erroneous.

To define type matching more precisely, we need to deal with two issues: matching of types of the host language with types specified in communication operations; and matching of types at sender and receiver.

The types of a send and receive match (phase two) if both operations use identical names. That is, `MPI_INTEGER` matches `MPI_INTEGER`, `MPI_REAL` matches `MPI_REAL`, and so on. There is one exception to this rule, discussed in Section 4.2, the type `MPI_PACKED` can match any other type.

The type of a variable in a host program matches the type specified in the communication operation if the datatype name used by that operation corresponds to the basic type of the host program variable. For example, an entry with type name `MPI_INTEGER` matches a Fortran variable of type `INTEGER`. A table giving this correspondence for Fortran and C appears in Section 3.2.2. There are two exceptions to this last rule: an entry with type name `MPI_BYTE` or `MPI_PACKED` can be used to match any byte of storage (on a byte-addressable machine), irrespective of the datatype of the variable that contains this byte. The type `MPI_PACKED` is used to send data that has been explicitly packed, or receive data that will be explicitly unpacked, see Section 4.2. The type `MPI_BYTE` allows one to transfer the binary value of a byte in memory unchanged.

To summarize, the type matching rules fall into the three categories below.

- Communication of typed values (e.g., with datatype different from `MPI_BYTE`), where the datatypes of the corresponding entries in the sender program, in the send call, in the receive call and in the receiver program must all match.
- Communication of untyped values (e.g., of datatype `MPI_BYTE`), where both sender and receiver use the datatype `MPI_BYTE`. In this case, there are no requirements on the types of the corresponding entries in the sender and the receiver programs, nor is it required that they be the same.
- Communication involving packed data, where `MPI_PACKED` is used.

The following examples illustrate the first two cases.

**Example 3.3** Sender and receiver specify matching types.

```

CALL MPI_COMM_RANK(comm, rank, ierr)
IF (rank.EQ.0) THEN
    CALL MPI_SEND(a(1), 10, MPI_REAL, 1, tag, comm, ierr)
ELSE IF (rank.EQ.1) THEN
    CALL MPI_RECV(b(1), 15, MPI_REAL, 0, tag, comm, status, ierr)
END IF

```

This code is correct if both **a** and **b** are real arrays of size  $\geq 10$ . (In Fortran, it might be correct to use this code even if **a** or **b** have size  $< 10$ : e.g., when **a**(1) can be equivalenced to an array with ten reals.)

**Example 3.4** Sender and receiver do not specify matching types.

```

CALL MPI_COMM_RANK(comm, rank, ierr)
IF (rank.EQ.0) THEN
    CALL MPI_SEND(a(1), 10, MPI_REAL, 1, tag, comm, ierr)
ELSE IF (rank.EQ.1) THEN
    CALL MPI_RECV(b(1), 40, MPI_BYTE, 0, tag, comm, status, ierr)
END IF

```

This code is erroneous, since sender and receiver do not provide matching datatype arguments.

**Example 3.5** Sender and receiver specify communication of untyped values.

```

CALL MPI_COMM_RANK(comm, rank, ierr)
IF (rank.EQ.0) THEN
    CALL MPI_SEND(a(1), 40, MPI_BYTE, 1, tag, comm, ierr)
ELSE IF (rank.EQ.1) THEN
    CALL MPI_RECV(b(1), 60, MPI_BYTE, 0, tag, comm, status, ierr)
END IF

```

This code is correct, irrespective of the type and size of **a** and **b** (unless this results in an out of bound memory access).

*Advice to users.* If a buffer of type **MPI\_BYTE** is passed as an argument to **MPI\_SEND**, then MPI will send the data stored at contiguous locations, starting from the address indicated by the **buf** argument. This may have unexpected results when the data layout is not as a casual user would expect it to be. For example, some Fortran compilers implement variables of type **CHARACTER** as a structure that contains the character length and a pointer to the actual string. In such an environment, sending and receiving a Fortran **CHARACTER** variable using the **MPI\_BYTE** type will not have the anticipated result of transferring the character string. For this reason, the user is advised to use typed communications whenever possible. (*End of advice to users.*)

#### Type **MPI\_CHARACTER**

The type **MPI\_CHARACTER** matches one character of a Fortran variable of type **CHARACTER**, rather than the entire character string stored in the variable. Fortran variables of type **CHARACTER** or substrings are transferred as if they were arrays of characters. This is illustrated in the example below.

**Example 3.6**

Transfer of Fortran CHARACTERS.

```

CHARACTER*10 a
CHARACTER*10 b

CALL MPI_COMM_RANK(comm, rank, ierr)
IF (rank.EQ.0) THEN
    CALL MPI_SEND(a, 5, MPI_CHARACTER, 1, tag, comm, ierr)
ELSE IF (rank.EQ.1) THEN
    CALL MPI_RECV(b(6:10), 5, MPI_CHARACTER, 0, tag, comm, status, ierr)
END IF

```

The last five characters of string `b` at process 1 are replaced by the first five characters of string `a` at process 0.

*Rationale.* The alternative choice would be for `MPI_CHARACTER` to match a character of arbitrary length. This runs into problems.

A Fortran character variable is a constant length string, with no special termination symbol. There is no fixed convention on how to represent characters, and how to store their length. Some compilers pass a character argument to a routine as a pair of arguments, one holding the address of the string and the other holding the length of string. Consider the case of an MPI communication call that is passed a communication buffer with type defined by a derived datatype (Section 4.1). If this communicator buffer contains variables of type `CHARACTER` then the information on their length will not be passed to the MPI routine.

This problem forces us to provide explicit information on character length with the MPI call. One could add a length parameter to the type `MPI_CHARACTER`, but this does not add much convenience and the same functionality can be achieved by defining a suitable derived datatype. (*End of rationale.*)

*Advice to implementors.* Some compilers pass Fortran `CHARACTER` arguments as a structure with a length and a pointer to the actual string. In such an environment, the MPI call needs to dereference the pointer in order to reach the string. (*End of advice to implementors.*)

### 3.3.2 Data Conversion

One of the goals of MPI is to support parallel computations across heterogeneous environments. Communication in a heterogeneous environment may require data conversions. We use the following terminology.

**type conversion** changes the datatype of a value, e.g., by rounding a `REAL` to an `INTEGER`.

**representation conversion** changes the binary representation of a value, e.g., from Hex floating point to IEEE floating point.

The type matching rules imply that MPI communication never entails type conversion. On the other hand, MPI requires that a representation conversion be performed when a

typed value is transferred across environments that use different representations for the datatype of this value. MPI does not specify rules for representation conversion. Such conversion is expected to preserve integer, logical or character values, and to convert a floating point value to the nearest value that can be represented on the target system.

Overflow and underflow exceptions may occur during floating point conversions. Conversion of integers or characters may also lead to exceptions when a value that can be represented in one system cannot be represented in the other system. An exception occurring during representation conversion results in a failure of the communication. An error occurs either in the send operation, or the receive operation, or both.

If a value sent in a message is untyped (i.e., of type `MPI_BYTE`), then the binary representation of the byte stored at the receiver is identical to the binary representation of the byte loaded at the sender. This holds true, whether sender and receiver run in the same or in distinct environments. No representation conversion is required. (Note that representation conversion may occur when values of type `MPI_CHARACTER` or `MPI_CHAR` are transferred, for example, from an EBCDIC encoding to an ASCII encoding.)

No conversion need occur when an MPI program executes in a homogeneous system, where all processes run in the same environment.

Consider the three examples, 3.3–3.5. The first program is correct, assuming that `a` and `b` are `REAL` arrays of size  $\geq 10$ . If the sender and receiver execute in different environments, then the ten real values that are fetched from the send buffer will be converted to the representation for reals on the receiver site before they are stored in the receive buffer. While the number of real elements fetched from the send buffer equal the number of real elements stored in the receive buffer, the number of bytes stored need not equal the number of bytes loaded. For example, the sender may use a four byte representation and the receiver an eight byte representation for reals.

The second program is erroneous, and its behavior is undefined.

The third program is correct. The exact same sequence of forty bytes that were loaded from the send buffer will be stored in the receive buffer, even if sender and receiver run in a different environment. The message sent has exactly the same length (in bytes) and the same binary representation as the message received. If `a` and `b` are of different types, or if they are of the same type but different data representations are used, then the bits stored in the receive buffer may encode values that are different from the values they encoded in the send buffer.

Data representation conversion also applies to the envelope of a message: source, destination and tag are all integers that may need to be converted.

*Advice to implementors.* The current definition does not require messages to carry data type information. Both sender and receiver provide complete data type information. In a heterogeneous environment, one can either use a machine independent encoding such as XDR, or have the receiver convert from the sender representation to its own, or even have the sender do the conversion.

Additional type information might be added to messages in order to allow the system to detect mismatches between datatype at sender and receiver. This might be particularly useful in a slower but safer debug mode. (*End of advice to implementors.*)

MPI requires support for inter-language communication, i.e., if messages are sent by a C or C++ process and received by a Fortran process, or vice-versa. The behavior is defined in Section 16.3 on page 577.

### 3.4 Communication Modes

The send call described in Section 3.2.1 is **blocking**: it does not return until the message data and envelope have been safely stored away so that the sender is free to modify the send buffer. The message might be copied directly into the matching receive buffer, or it might be copied into a temporary system buffer.

Message buffering decouples the send and receive operations. A blocking send can complete as soon as the message was buffered, even if no matching receive has been executed by the receiver. On the other hand, message buffering can be expensive, as it entails additional memory-to-memory copying, and it requires the allocation of memory for buffering. MPI offers the choice of several communication modes that allow one to control the choice of the communication protocol.

The send call described in Section 3.2.1 uses the **standard** communication mode. In this mode, it is up to MPI to decide whether outgoing messages will be buffered. MPI may buffer outgoing messages. In such a case, the send call may complete before a matching receive is invoked. On the other hand, buffer space may be unavailable, or MPI may choose not to buffer outgoing messages, for performance reasons. In this case, the send call will not complete until a matching receive has been posted, and the data has been moved to the receiver.

Thus, a send in standard mode can be started whether or not a matching receive has been posted. It may complete before a matching receive is posted. The standard mode send is **non-local**: successful completion of the send operation may depend on the occurrence of a matching receive.

*Rationale.* The reluctance of MPI to mandate whether standard sends are buffering or not stems from the desire to achieve portable programs. Since any system will run out of buffer resources as message sizes are increased, and some implementations may want to provide little buffering, MPI takes the position that correct (and therefore, portable) programs do not rely on system buffering in standard mode. Buffering may improve the performance of a correct program, but it doesn't affect the result of the program. If the user wishes to guarantee a certain amount of buffering, the user-provided buffer system of Section 3.6 should be used, along with the buffered-mode send. (*End of rationale.*)

There are three additional communication modes.

A **buffered** mode send operation can be started whether or not a matching receive has been posted. It may complete before a matching receive is posted. However, unlike the standard send, this operation is **local**, and its completion does not depend on the occurrence of a matching receive. Thus, if a send is executed and no matching receive is posted, then MPI must buffer the outgoing message, so as to allow the send call to complete. An error will occur if there is insufficient buffer space. The amount of available buffer space is controlled by the user — see Section 3.6. Buffer allocation by the user may be required for the buffered mode to be effective.

A send that uses the **synchronous** mode can be started whether or not a matching receive was posted. However, the send will complete successfully only if a matching receive is posted, and the receive operation has started to receive the message sent by the synchronous send. Thus, the completion of a synchronous send not only indicates that the send buffer can be reused, but it also indicates that the receiver has reached a certain point in its

execution, namely that it has started executing the matching receive. If both sends and receives are blocking operations then the use of the synchronous mode provides synchronous communication semantics: a communication does not complete at either end before both processes rendezvous at the communication. A send executed in this mode is **non-local**.

A send that uses the **ready** communication mode may be started *only* if the matching receive is already posted. Otherwise, the operation is erroneous and its outcome is undefined. On some systems, this allows the removal of a hand-shake operation that is otherwise required and results in improved performance. The completion of the send operation does not depend on the status of a matching receive, and merely indicates that the send buffer can be reused. A send operation that uses the ready mode has the same semantics as a standard send operation, or a synchronous send operation; it is merely that the sender provides additional information to the system (namely that a matching receive is already posted), that can save some overhead. In a correct program, therefore, a ready send could be replaced by a standard send with no effect on the behavior of the program other than performance.

Three additional send functions are provided for the three additional communication modes. The communication mode is indicated by a one letter prefix: **B** for buffered, **S** for synchronous, and **R** for ready.

MPI\_BSEND (buf, count, datatype, dest, tag, comm)

IN	buf	initial address of send buffer (choice)
IN	count	number of elements in send buffer (non-negative integer)
IN	datatype	datatype of each send buffer element (handle)
IN	dest	rank of destination (integer)
IN	tag	message tag (integer)
IN	comm	communicator (handle)

```
int MPI_Bsend(void* buf, int count, MPI_Datatype datatype, int dest,
              int tag, MPI_Comm comm)
```

```
MPI_BSEND(BUF, COUNT, DATATYPE, DEST, TAG, COMM, IERROR)
```

```
<type> BUF(*)
```

```
INTEGER COUNT, DATATYPE, DEST, TAG, COMM, IERROR
```

```
MPI_Bsend(buf, count, datatype, dest, tag, comm, ierror)
```

```
TYPE(*), DIMENSION(..) :: buf
```

```
INTEGER, INTENT(IN) :: count, dest, tag
```

```
TYPE(MPI_Datatype), INTENT(IN) :: datatype
```

```
TYPE(MPI_Comm), INTENT(IN) :: comm
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Comm::Bsend(const void* buf, int count, const
                      MPI::Datatype& datatype, int dest, int tag) const(binding
                      deprecated, see Section 15.2) }
```

Send in buffered mode.



```

1 MPI_SSEND (buf, count, datatype, dest, tag, comm)
2     IN      buf                initial address of send buffer (choice)
3
4     IN      count              number of elements in send buffer (non-negative inte-
5                                ger)
6
7     IN      datatype           datatype of each send buffer element (handle)
8
9     IN      dest               rank of destination (integer)
10
11    IN      tag                 message tag (integer)
12
13    IN      comm                communicator (handle)

```

```

12 int MPI_Ssend(void* buf, int count, MPI_Datatype datatype, int dest,
13               int tag, MPI_Comm comm)
14

```

```

15 MPI_SSEND(BUF, COUNT, DATATYPE, DEST, TAG, COMM, IERROR)
16     <type> BUF(*)
17     INTEGER COUNT, DATATYPE, DEST, TAG, COMM, IERROR

```

```

18 MPI_Ssend(buf, count, datatype, dest, tag, comm, ierror)
19     TYPE(*), DIMENSION(..) :: buf
20     INTEGER, INTENT(IN) :: count, dest, tag
21     TYPE(MPI_Datatype), INTENT(IN) :: datatype
22     TYPE(MPI_Comm), INTENT(IN) :: comm
23     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
24

```

```

25 {void MPI::Comm::Ssend(const void* buf, int count, const
26                       MPI::Datatype& datatype, int dest, int tag) const(binding
27                               deprecated, see Section 15.2) }
28

```

Send in synchronous mode.

```

31 MPI_RSEND (buf, count, datatype, dest, tag, comm)
32     IN      buf                initial address of send buffer (choice)
33
34     IN      count              number of elements in send buffer (non-negative inte-
35                                ger)
36
37     IN      datatype           datatype of each send buffer element (handle)
38
39     IN      dest               rank of destination (integer)
40
41    IN      tag                 message tag (integer)
42
43    IN      comm                communicator (handle)

```

```

42 int MPI_Rsend(void* buf, int count, MPI_Datatype datatype, int dest,
43               int tag, MPI_Comm comm)
44

```

```

45 MPI_RSEND(BUF, COUNT, DATATYPE, DEST, TAG, COMM, IERROR)
46     <type> BUF(*)
47     INTEGER COUNT, DATATYPE, DEST, TAG, COMM, IERROR

```



```

MPI_Rsend(buf, count, datatype, dest, tag, comm, ierror)
    TYPE(*), DIMENSION(..) :: buf
    INTEGER, INTENT(IN) :: count, dest, tag
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Comm), INTENT(IN) :: comm
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Comm::Rsend(const void* buf, int count, const
    MPI::Datatype& datatype, int dest, int tag) const(binding
    deprecated, see Section 15.2) }
```

Send in ready mode.

There is only one receive operation, but it matches any of the send modes. The receive operation described in the last section is **blocking**: it returns only after the receive buffer contains the newly received message. A receive can complete before the matching send has completed (of course, it can complete only after the matching send has started).

In a multi-threaded implementation of MPI, the system may de-schedule a thread that is blocked on a send or receive operation, and schedule another thread for execution in the same address space. In such a case it is the user's responsibility not to modify a communication buffer until the communication completes. Otherwise, the outcome of the computation is undefined.

*Advice to implementors.* Since a synchronous send cannot complete before a matching receive is posted, one will not normally buffer messages sent by such an operation.

It is recommended to choose buffering over blocking the sender, whenever possible, for standard sends. The programmer can signal his or her preference for blocking the sender until a matching receive occurs by using the synchronous send mode.

A possible communication protocol for the various communication modes is outlined below.

**ready send:** The message is sent as soon as possible.

**synchronous send:** The sender sends a request-to-send message. The receiver stores this request. When a matching receive is posted, the receiver sends back a permission-to-send message, and the sender now sends the message.

**standard send:** First protocol may be used for short messages, and second protocol for long messages.

**buffered send:** The sender copies the message into a buffer and then sends it with a nonblocking send (using the same protocol as for standard send).

Additional control messages might be needed for flow control and error recovery. Of course, there are many other possible protocols.

Ready send can be implemented as a standard send. In this case there will be no performance advantage (or disadvantage) for the use of ready send.

A standard send can be implemented as a synchronous send. In such a case, no data buffering is needed. However, users may expect some buffering.

In a multi-threaded environment, the execution of a blocking communication should block only the executing thread, allowing the thread scheduler to de-schedule this thread and schedule another thread for execution. (*End of advice to implementors.*)

### 3.5 Semantics of Point-to-Point Communication

A valid MPI implementation guarantees certain general properties of point-to-point communication, which are described in this section.

**Order** Messages are *non-overtaking*: If a sender sends two messages in succession to the same destination, and both match the same receive, then this operation cannot receive the second message if the first one is still pending. If a receiver posts two receives in succession, and both match the same message, then the second receive operation cannot be satisfied by this message, if the first one is still pending. This requirement facilitates matching of sends to receives. It guarantees that message-passing code is deterministic, if processes are single-threaded and the wildcard `MPI_ANY_SOURCE` is not used in receives. (Some of the calls described later, such as `MPI_CANCEL` or `MPI_WAITANY`, are additional sources of nondeterminism.)

If a process has a single thread of execution, then any two communications executed by this process are ordered. On the other hand, if the process is multi-threaded, then the semantics of thread execution may not define a relative order between two send operations executed by two distinct threads. The operations are logically concurrent, even if one physically precedes the other. In such a case, the two messages sent can be received in any order. Similarly, if two receive operations that are logically concurrent receive two successively sent messages, then the two messages can match the two receives in either order.

**Example 3.7** An example of non-overtaking messages.

```
CALL MPI_COMM_RANK(comm, rank, ierr)
IF (rank.EQ.0) THEN
    CALL MPI_BSEND(buf1, count, MPI_REAL, 1, tag, comm, ierr)
    CALL MPI_BSEND(buf2, count, MPI_REAL, 1, tag, comm, ierr)
ELSE IF (rank.EQ.1) THEN
    CALL MPI_RECV(buf1, count, MPI_REAL, 0, MPI_ANY_TAG, comm, status, ierr)
    CALL MPI_RECV(buf2, count, MPI_REAL, 0, tag, comm, status, ierr)
END IF
```

The message sent by the first send must be received by the first receive, and the message sent by the second send must be received by the second receive.

**Progress** If a pair of matching send and receives have been initiated on two processes, then at least one of these two operations will complete, independently of other actions in the system: the send operation will complete, unless the receive is satisfied by another message, and completes; the receive operation will complete, unless the message sent is consumed by another matching receive that was posted at the same destination process.

**Example 3.8** An example of two, intertwined matching pairs.

```

CALL MPI_COMM_RANK(comm, rank, ierr)
IF (rank.EQ.0) THEN
    CALL MPI_BSEND(buf1, count, MPI_REAL, 1, tag1, comm, ierr)
    CALL MPI_SSEND(buf2, count, MPI_REAL, 1, tag2, comm, ierr)
ELSE IF (rank.EQ.1) THEN
    CALL MPI_RECV(buf1, count, MPI_REAL, 0, tag2, comm, status, ierr)
    CALL MPI_RECV(buf2, count, MPI_REAL, 0, tag1, comm, status, ierr)
END IF

```

Both processes invoke their first communication call. Since the first send of process zero uses the buffered mode, it must complete, irrespective of the state of process one. Since no matching receive is posted, the message will be copied into buffer space. (If insufficient buffer space is available, then the program will fail.) The second send is then invoked. At that point, a matching pair of send and receive operation is enabled, and both operations must complete. Process one next invokes its second receive call, which will be satisfied by the buffered message. Note that process one received the messages in the reverse order they were sent.

**Fairness** MPI makes no guarantee of *fairness* in the handling of communication. Suppose that a send is posted. Then it is possible that the destination process repeatedly posts a receive that matches this send, yet the message is never received, because it is each time overtaken by another message, sent from another source. Similarly, suppose that a receive was posted by a multi-threaded process. Then it is possible that messages that match this receive are repeatedly received, yet the receive is never satisfied, because it is overtaken by other receives posted at this node (by other executing threads). It is the programmer's responsibility to prevent starvation in such situations.

**Resource limitations** Any pending communication operation consumes system resources that are limited. Errors may occur when lack of resources prevent the execution of an MPI call. A quality implementation will use a (small) fixed amount of resources for each pending send in the ready or synchronous mode and for each pending receive. However, buffer space may be consumed to store messages sent in standard mode, and must be consumed to store messages sent in buffered mode, when no matching receive is available. The amount of space available for buffering will be much smaller than program data memory on many systems. Then, it will be easy to write programs that overrun available buffer space.

MPI allows the user to provide buffer memory for messages sent in the buffered mode. Furthermore, MPI specifies a detailed operational model for the use of this buffer. An MPI implementation is required to do no worse than implied by this model. This allows users to avoid buffer overflows when they use buffered sends. Buffer allocation and use is described in Section 3.6.

A buffered send operation that cannot complete because of a lack of buffer space is erroneous. When such a situation is detected, an error is signalled that may cause the program to terminate abnormally. On the other hand, a standard send operation that cannot complete because of lack of buffer space will merely block, waiting for buffer space to become available or for a matching receive to be posted. This behavior is preferable in many situations. Consider a situation where a producer repeatedly produces new values and sends them to a consumer. Assume that the producer produces new values faster than the consumer can consume them. If buffered sends are used, then a buffer overflow

will result. Additional synchronization has to be added to the program so as to prevent this from occurring. If standard sends are used, then the producer will be automatically throttled, as its send operations will block when buffer space is unavailable.

In some situations, a lack of buffer space leads to deadlock situations. This is illustrated by the examples below.

**Example 3.9** An exchange of messages.

```
CALL MPI_COMM_RANK(comm, rank, ierr)
IF (rank.EQ.0) THEN
    CALL MPI_SEND(sendbuf, count, MPI_REAL, 1, tag, comm, ierr)
    CALL MPI_RECV(recvbuf, count, MPI_REAL, 1, tag, comm, status, ierr)
ELSE IF (rank.EQ.1) THEN
    CALL MPI_RECV(recvbuf, count, MPI_REAL, 0, tag, comm, status, ierr)
    CALL MPI_SEND(sendbuf, count, MPI_REAL, 0, tag, comm, ierr)
END IF
```

This program will succeed even if no buffer space for data is available. The standard send operation can be replaced, in this example, with a synchronous send.

**Example 3.10** An errant attempt to exchange messages.

```
CALL MPI_COMM_RANK(comm, rank, ierr)
IF (rank.EQ.0) THEN
    CALL MPI_RECV(recvbuf, count, MPI_REAL, 1, tag, comm, status, ierr)
    CALL MPI_SEND(sendbuf, count, MPI_REAL, 1, tag, comm, ierr)
ELSE IF (rank.EQ.1) THEN
    CALL MPI_RECV(recvbuf, count, MPI_REAL, 0, tag, comm, status, ierr)
    CALL MPI_SEND(sendbuf, count, MPI_REAL, 0, tag, comm, ierr)
END IF
```

The receive operation of the first process must complete before its send, and can complete only if the matching send of the second processor is executed. The receive operation of the second process must complete before its send and can complete only if the matching send of the first process is executed. This program will always deadlock. The same holds for any other send mode.

**Example 3.11** An exchange that relies on buffering.

```
CALL MPI_COMM_RANK(comm, rank, ierr)
IF (rank.EQ.0) THEN
    CALL MPI_SEND(sendbuf, count, MPI_REAL, 1, tag, comm, ierr)
    CALL MPI_RECV(recvbuf, count, MPI_REAL, 1, tag, comm, status, ierr)
ELSE IF (rank.EQ.1) THEN
    CALL MPI_SEND(sendbuf, count, MPI_REAL, 0, tag, comm, ierr)
    CALL MPI_RECV(recvbuf, count, MPI_REAL, 0, tag, comm, status, ierr)
END IF
```

The message sent by each process has to be copied out before the send operation returns and the receive operation starts. For the program to complete, it is necessary that at least one of the two messages sent be buffered. Thus, this program can succeed only if the communication system can buffer at least count words of data.

*Advice to users.* When standard send operations are used, then a deadlock situation may occur where both processes are blocked because buffer space is not available. The same will certainly happen, if the synchronous mode is used. If the buffered mode is used, and not enough buffer space is available, then the program will not complete either. However, rather than a deadlock situation, we shall have a buffer overflow error.

A program is “safe” if no message buffering is required for the program to complete. One can replace all sends in such program with synchronous sends, and the program will still run correctly. This conservative programming style provides the best portability, since program completion does not depend on the amount of buffer space available or on the communication protocol used.

Many programmers prefer to have more leeway and opt to use the “unsafe” programming style shown in Example 3.11. In such cases, the use of standard sends is likely to provide the best compromise between performance and robustness: quality implementations will provide sufficient buffering so that “common practice” programs will not deadlock. The buffered send mode can be used for programs that require more buffering, or in situations where the programmer wants more control. This mode might also be used for debugging purposes, as buffer overflow conditions are easier to diagnose than deadlock conditions.

Nonblocking message-passing operations, as described in Section 3.7, can be used to avoid the need for buffering outgoing messages. This prevents deadlocks due to lack of buffer space, and improves performance, by allowing overlap of computation and communication, and avoiding the overheads of allocating buffers and copying messages into buffers. (*End of advice to users.*)

## 3.6 Buffer Allocation and Usage

A user may specify a buffer to be used for buffering messages sent in buffered mode. Buffering is done by the sender.

`MPI_BUFFER_ATTACH(buffer, size)`

IN	buffer	initial buffer address (choice)
IN	size	buffer size, in bytes (non-negative integer)

`int MPI_Buffer_attach(void* buffer, int size)`

`MPI_BUFFER_ATTACH(BUFFER, SIZE, IERROR)`

`<type> BUFFER(*)`

`INTEGER SIZE, IERROR`

`MPI_Buffer_attach(buffer, size, ierror)`

`TYPE(*), DIMENSION(..) :: buffer`

`INTEGER, INTENT(IN) :: size`

`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

```

1  {void MPI::Attach_buffer(void* buffer, int size) (binding deprecated, see
2      Section 15.2) }
```

Provides to MPI a buffer in the user's memory to be used for buffering outgoing messages. The buffer is used only by messages sent in buffered mode. Only one buffer can be attached to a process at a time.

```

8  MPI_BUFFER_DETACH(buffer_addr, size)
```

```

9      OUT      buffer_addr          initial buffer address (choice)
```

```

11     OUT      size                  buffer size, in bytes (non-negative integer)
```

```

13  int MPI_Buffer_detach(void* buffer_addr, int* size)
```

```

15  MPI_BUFFER_DETACH(BUFFER_ADDR, SIZE, IERROR)
```

```

16      <type> BUFFER_ADDR(*)
```

```

17      INTEGER SIZE, IERROR
```

```

18  MPI_Buffer_detach(buffer_addr, size, ierror)
```

```

19      TYPE(*), DIMENSION(..)  :: buffer_addr
```

```

20      INTEGER, INTENT(OUT) :: size
```

```

21      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```

23  {int MPI::Detach_buffer(void*& buffer) (binding deprecated, see Section 15.2) }
```

Detach the buffer currently associated with MPI. The call returns the address and the size of the detached buffer. This operation will block until all messages currently in the buffer have been transmitted. Upon return of this function, the user may reuse or deallocate the space taken by the buffer.

**Example 3.12** Calls to attach and detach buffers.

```

31  #define BUFFSIZE 10000
```

```

32  int size;
```

```

33  char *buff;
```

```

34  MPI_Buffer_attach( malloc(BUFFSIZE), BUFFSIZE);
```

```

35  /* a buffer of 10000 bytes can now be used by MPI_Bsend */
```

```

36  MPI_Buffer_detach( &buff, &size);
```

```

37  /* Buffer size reduced to zero */
```

```

38  MPI_Buffer_attach( buff, size);
```

```

39  /* Buffer of 10000 bytes available again */
```

*Advice to users.* Even though the C functions `MPI_Buffer_attach` and `MPI_Buffer_detach` both have a first argument of type `void*`, these arguments are used differently: A pointer to the buffer is passed to `MPI_Buffer_attach`; the address of the pointer is passed to `MPI_Buffer_detach`, so that this call can return the pointer value. (*End of advice to users.*)

*Rationale.* Both arguments are defined to be of type `void*` (rather than `void*` and `void**`, respectively), so as to avoid complex type casts. E.g., in the last

example, `&buff`, which is of type `char**`, can be passed as argument to `MPI_Buffer_detach` without type casting. If the formal parameter had type `void**` then we would need a type cast before and after the call. (*End of rationale.*)

The statements made in this section describe the behavior of MPI for buffered-mode sends. When no buffer is currently associated, MPI behaves as if a zero-sized buffer is associated with the process.

MPI must provide as much buffering for outgoing messages *as if* outgoing message data were buffered by the sending process, in the specified buffer space, using a circular, contiguous-space allocation policy. We outline below a model implementation that defines this policy. MPI may provide more buffering, and may use a better buffer allocation algorithm than described below. On the other hand, MPI may signal an error whenever the simple buffering allocator described below would run out of space. In particular, if no buffer is explicitly associated with the process, then any buffered send may cause an error.

MPI does not provide mechanisms for querying or controlling buffering done by standard mode sends. It is expected that vendors will provide such information for their implementations.

*Rationale.* There is a wide spectrum of possible implementations of buffered communication: buffering can be done at sender, at receiver, or both; buffers can be dedicated to one sender-receiver pair, or be shared by all communications; buffering can be done in real or in virtual memory; it can use dedicated memory, or memory shared by other processes; buffer space may be allocated statically or be changed dynamically; etc. It does not seem feasible to provide a portable mechanism for querying or controlling buffering that would be compatible with all these choices, yet provide meaningful information. (*End of rationale.*)

### 3.6.1 Model Implementation of Buffered Mode

The model implementation uses the packing and unpacking functions described in Section 4.2 and the nonblocking communication functions described in Section 3.7.

We assume that a circular queue of pending message entries (PME) is maintained. Each entry contains a communication request handle that identifies a pending nonblocking send, a pointer to the next entry and the packed message data. The entries are stored in successive locations in the buffer. Free space is available between the queue tail and the queue head.

A buffered send call results in the execution of the following code.

- Traverse sequentially the PME queue from head towards the tail, deleting all entries for communications that have completed, up to the first entry with an uncompleted request; update queue head to point to that entry.
- Compute the number, `n`, of bytes needed to store an entry for the new message. An upper bound on `n` can be computed as follows: A call to the function `MPI_PACK_SIZE(count, datatype, comm, size)`, with the `count`, `datatype` and `comm` arguments used in the `MPI_BSEND` call, returns an upper bound on the amount of space needed to buffer the message data (see Section 4.2). The MPI constant `MPI_BSEND_OVERHEAD` provides an upper bound on the additional space consumed by the entry (e.g., for pointers or envelope information).

- Find the next contiguous empty space of  $n$  bytes in buffer (space following queue tail, or space at start of buffer if queue tail is too close to end of buffer). If space is not found then raise buffer overflow error.
- Append to end of PME queue in contiguous space the new entry that contains request handle, next pointer and packed message data; `MPI_PACK` is used to pack data.
- Post nonblocking send (standard mode) for packed data.
- Return

### 3.7 Nonblocking Communication

One can improve performance on many systems by overlapping communication and computation. This is especially true on systems where communication can be executed autonomously by an intelligent communication controller. Light-weight threads are one mechanism for achieving such overlap. An alternative mechanism that often leads to better performance is to use **nonblocking communication**. A nonblocking **send start** call initiates the send operation, but does not complete it. The send start call can return before the message was copied out of the send buffer. A separate **send complete** call is needed to complete the communication, i.e., to verify that the data has been copied out of the send buffer. With suitable hardware, the transfer of data out of the sender memory may proceed concurrently with computations done at the sender after the send was initiated and before it completed. Similarly, a nonblocking **receive start call** initiates the receive operation, but does not complete it. The call can return before a message is stored into the receive buffer. A separate **receive complete** call is needed to complete the receive operation and verify that the data has been received into the receive buffer. With suitable hardware, the transfer of data into the receiver memory may proceed concurrently with computations done after the receive was initiated and before it completed. The use of nonblocking receives may also avoid system buffering and memory-to-memory copying, as information is provided early on the location of the receive buffer.

Nonblocking send start calls can use the same four modes as blocking sends: **standard**, **buffered**, **synchronous** and **ready**. These carry the same meaning. Sends of all modes, **ready** excepted, can be started whether a matching receive has been posted or not; a nonblocking **ready** send can be started only if a matching receive is posted. In all cases, the send start call is local: it returns immediately, irrespective of the status of other processes. If the call causes some system resource to be exhausted, then it will fail and return an error code. Quality implementations of MPI should ensure that this happens only in “pathological” cases. That is, an MPI implementation should be able to support a large number of pending nonblocking operations.

The send-complete call returns when data has been copied out of the send buffer. It may carry additional meaning, depending on the send mode.

If the send mode is **synchronous**, then the send can complete only if a matching receive has started. That is, a receive has been posted, and has been matched with the send. In this case, the send-complete call is non-local. Note that a synchronous, nonblocking send may complete, if matched by a nonblocking receive, before the receive complete call occurs. (It can complete as soon as the sender “knows” the transfer will complete, but before the receiver “knows” the transfer will complete.)



If the send mode is **buffered** then the message must be buffered if there is no pending receive. In this case, the send-complete call is local, and must succeed irrespective of the status of a matching receive.

If the send mode is **standard** then the send-complete call may return before a matching receive is posted, if the message is buffered. On the other hand, the send-complete may not complete until a matching receive is posted, and the message was copied into the receive buffer.

Nonblocking sends can be matched with blocking receives, and vice-versa.

*Advice to users.* The completion of a send operation may be delayed, for standard mode, and must be delayed, for synchronous mode, until a matching receive is posted. The use of nonblocking sends in these two cases allows the sender to proceed ahead of the receiver, so that the computation is more tolerant of fluctuations in the speeds of the two processes.

Nonblocking sends in the buffered and ready modes have a more limited impact, e.g., the blocking version of buffered send is capable of completing regardless of when a matching receive call is made. However, separating the start from the completion of these sends still gives some opportunity for optimization within the MPI library. For example, starting a buffered send gives an implementation more flexibility in determining if and how the message is buffered. There are also advantages for both nonblocking buffered and ready modes when data copying can be done concurrently with computation.

The message-passing model implies that communication is initiated by the sender. The communication will generally have lower overhead if a receive is already posted when the sender initiates the communication (data can be moved directly to the receive buffer, and there is no need to queue a pending send request). However, a receive operation can complete only after the matching send has occurred. The use of nonblocking receives allows one to achieve lower communication overheads without blocking the receiver while it waits for the send. (*End of advice to users.*)

### 3.7.1 Communication Request Objects

Nonblocking communications use opaque **request** objects to identify communication operations and match the operation that initiates the communication with the operation that terminates it. These are system objects that are accessed via a handle. A request object identifies various properties of a communication operation, such as the send mode, the communication buffer that is associated with it, its context, the tag and destination arguments to be used for a send, or the tag and source arguments to be used for a receive. In addition, this object stores information about the status of the pending communication operation.

### 3.7.2 Communication Initiation

We use the same naming conventions as for blocking communication: a prefix of **B**, **S**, or **R** is used for **buffered**, **synchronous** or **ready** mode. In addition a prefix of **I** (for **immediate**) indicates that the call is nonblocking.

```

1 MPI_ISEND(buf, count, datatype, dest, tag, comm, request)
2     IN      buf                initial address of send buffer (choice)
3
4     IN      count              number of elements in send buffer (non-negative inte-
5                                ger)
6
7     IN      datatype           datatype of each send buffer element (handle)
8
9     IN      dest               rank of destination (integer)
10
11    IN      tag                message tag (integer)
12
13    IN      comm               communicator (handle)
14
15    OUT     request            communication request (handle)

```

```

16 int MPI_Isend(void* buf, int count, MPI_Datatype datatype, int dest,
17               int tag, MPI_Comm comm, MPI_Request *request)

```

```

18 MPI_ISEND(BUF, COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR)
19     <type> BUF(*)
20     INTEGER COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR

```

```

21 MPI_Isend(buf, count, datatype, dest, tag, comm, request, ierror)
22     TYPE(*), DIMENSION(..) :: buf
23     INTEGER, INTENT(IN) :: count, dest, tag
24     TYPE(MPI_Datatype), INTENT(IN) :: datatype
25     TYPE(MPI_Comm), INTENT(IN) :: comm
26     TYPE(MPI_Request), INTENT(OUT) :: request
27     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

28 {MPI::Request MPI::Comm::Isend(const void* buf, int count, const
29                               MPI::Datatype& datatype, int dest, int tag) const(binding
30                               deprecated, see Section 15.2) }

```

Start a standard mode, nonblocking send.

```

33 MPI_IBSEND(buf, count, datatype, dest, tag, comm, request)
34
35     IN      buf                initial address of send buffer (choice)
36
37     IN      count              number of elements in send buffer (non-negative inte-
38                                ger)
39
40     IN      datatype           datatype of each send buffer element (handle)
41
42     IN      dest               rank of destination (integer)
43
44     IN      tag                message tag (integer)
45
46     IN      comm               communicator (handle)
47
48     OUT     request            communication request (handle)

```

```

49 int MPI_Ibsend(void* buf, int count, MPI_Datatype datatype, int dest,
50               int tag, MPI_Comm comm, MPI_Request *request)

```

```
MPI_IBSEND(BUF, COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR)
```

```
<type> BUF(*)
```

```
INTEGER COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR
```

```
MPI_Ibsend(buf, count, datatype, dest, tag, comm, request, ierror)
```

```
TYPE(*), DIMENSION(..) :: buf
```

```
INTEGER, INTENT(IN) :: count, dest, tag
```

```
TYPE(MPI_Datatype), INTENT(IN) :: datatype
```

```
TYPE(MPI_Comm), INTENT(IN) :: comm
```

```
TYPE(MPI_Request), INTENT(OUT) :: request
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{MPI::Request MPI::Comm::Ibsend(const void* buf, int count, const
    MPI::Datatype& datatype, int dest, int tag) const(binding
    deprecated, see Section 15.2) }
```

Start a buffered mode, nonblocking send.

```
MPI_ISSEND(buf, count, datatype, dest, tag, comm, request)
```

```
IN      buf                initial address of send buffer (choice)
```

```
IN      count              number of elements in send buffer (non-negative inte-
                           ger)
```

```
IN      datatype           datatype of each send buffer element (handle)
```

```
IN      dest               rank of destination (integer)
```

```
IN      tag                message tag (integer)
```

```
IN      comm               communicator (handle)
```

```
OUT     request            communication request (handle)
```

```
int MPI_Issend(void* buf, int count, MPI_Datatype datatype, int dest,
    int tag, MPI_Comm comm, MPI_Request *request)
```

```
MPI_ISSEND(BUF, COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR)
```

```
<type> BUF(*)
```

```
INTEGER COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR
```

```
MPI_Issend(buf, count, datatype, dest, tag, comm, request, ierror)
```

```
TYPE(*), DIMENSION(..) :: buf
```

```
INTEGER, INTENT(IN) :: count, dest, tag
```

```
TYPE(MPI_Datatype), INTENT(IN) :: datatype
```

```
TYPE(MPI_Comm), INTENT(IN) :: comm
```

```
TYPE(MPI_Request), INTENT(OUT) :: request
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{MPI::Request MPI::Comm::Issend(const void* buf, int count, const
    MPI::Datatype& datatype, int dest, int tag) const(binding
    deprecated, see Section 15.2) }
```

Start a synchronous mode, nonblocking send.

```

1 MPI_IRSEND(buf, count, datatype, dest, tag, comm, request)
2     IN      buf                initial address of send buffer (choice)
3
4     IN      count              number of elements in send buffer (non-negative integer)
5
6     IN      datatype           datatype of each send buffer element (handle)
7
8     IN      dest               rank of destination (integer)
9
10    IN      tag                message tag (integer)
11
12    IN      comm               communicator (handle)
13
14    OUT     request            communication request (handle)

```

```

14 int MPI_Irsend(void* buf, int count, MPI_Datatype datatype, int dest,
15               int tag, MPI_Comm comm, MPI_Request *request)

```

```

16 MPI_IRSEND(BUF, COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR)
17     <type> BUF(*)
18     INTEGER COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR

```

```

19 MPI_Irsend(buf, count, datatype, dest, tag, comm, request, ierror)
20     TYPE(*), DIMENSION(..) :: buf
21     INTEGER, INTENT(IN) :: count, dest, tag
22     TYPE(MPI_Datatype), INTENT(IN) :: datatype
23     TYPE(MPI_Comm), INTENT(IN) :: comm
24     TYPE(MPI_Request), INTENT(OUT) :: request
25     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

27 {MPI::Request MPI::Comm::Irsend(const void* buf, int count, const
28                               MPI::Datatype& datatype, int dest, int tag) const(binding
29                               deprecated, see Section 15.2) }

```

Start a ready mode nonblocking send.

```

33 MPI_IRECV (buf, count, datatype, source, tag, comm, request)
34
35     OUT     buf                initial address of receive buffer (choice)
36
37     IN      count              number of elements in receive buffer (non-negative integer)
38
39     IN      datatype           datatype of each receive buffer element (handle)
40
41     IN      source             rank of source or MPI_ANY_SOURCE (integer)
42
43     IN      tag                message tag or MPI_ANY_TAG (integer)
44
45     IN      comm               communicator (handle)
46
47     OUT     request            communication request (handle)

```

```

46 int MPI_Irecv(void* buf, int count, MPI_Datatype datatype, int source,
47               int tag, MPI_Comm comm, MPI_Request *request)

```

```

MPI_Irecv(buf, count, datatype, source, tag, comm, request, ierror)
    <type> BUF(*)
    INTEGER COUNT, DATATYPE, SOURCE, TAG, COMM, REQUEST, IERROR
MPI_Irecv(buf, count, datatype, source, tag, comm, request, ierror)
    TYPE(*), DIMENSION(..) :: buf
    INTEGER, INTENT(IN) :: count, source, tag
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Comm), INTENT(IN) :: comm
    TYPE(MPI_Request), INTENT(OUT) :: request
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
{MPI::Request MPI::Comm::Irecv(void* buf, int count, const
    MPI::Datatype& datatype, int source, int tag) const(binding
    deprecated, see Section 15.2) }

```

Start a nonblocking receive.

These calls allocate a communication request object and associate it with the request handle (the argument `request`). The request can be used later to query the status of the communication or wait for its completion.

A nonblocking send call indicates that the system may start copying data out of the send buffer. The sender should not modify any part of the send buffer after a nonblocking send operation is called, until the send completes.

A nonblocking receive call indicates that the system may start writing data into the receive buffer. The receiver should not access any part of the receive buffer after a nonblocking receive operation is called, until the receive completes.

*Advice to users.* To prevent problems with the argument copying and register optimization done by Fortran compilers, please note the hints in Sections 16.2.2-16.2.12, especially in Sections 16.2.4 and 16.2.5 on pages 547-550 about *problems due to data copying and sequence association with subscript triplets and vector subscripts*, and in Sections 16.2.8 to 16.2.11 on pages 551 to 561 about *optimization problems, code movements and register optimization*, and *temporary and permanent data movements*. (End of advice to users.)

### 3.7.3 Communication Completion

The functions `MPI_WAIT` and `MPI_TEST` are used to complete a nonblocking communication. The completion of a send operation indicates that the sender is now free to update the locations in the send buffer (the send operation itself leaves the content of the send buffer unchanged). It does not indicate that the message has been received, rather, it may have been buffered by the communication subsystem. However, if a **synchronous** mode send was used, the completion of the send operation indicates that a matching receive was initiated, and that the message will eventually be received by this matching receive.

The completion of a receive operation indicates that the receive buffer contains the received message, the receiver is now free to access it, and that the status object is set. It does not indicate that the matching send operation has completed (but indicates, of course, that the send was initiated).

We shall use the following terminology: A **null** handle is a handle with value `MPI_REQUEST_NULL`. A persistent request and the handle to it are **inactive** if the request

is not associated with any ongoing communication (see Section 3.9). A handle is **active** if it is neither null nor inactive. An **empty** status is a status which is set to return `tag = MPI_ANY_TAG`, `source = MPI_ANY_SOURCE`, `error = MPI_SUCCESS`, and is also internally configured so that calls to `MPI_GET_COUNT` and `MPI_GET_ELEMENTS` return `count = 0` and `MPI_TEST_CANCELLED` returns false. We set a status variable to empty when the value returned by it is not significant. Status is set in this way so as to prevent errors due to accesses of stale information.

The fields in a **status** object returned by a call to `MPI_WAIT`, `MPI_TEST`, or any of the other derived functions (`MPI_{TEST|WAIT}{ALL|SOME|ANY}`), where the **request** corresponds to a send call, are undefined, with two exceptions: The error status field will contain valid information if the wait or test call returned with `MPI_ERR_IN_STATUS`; and the returned status can be queried by the call `MPI_TEST_CANCELLED`.

Error codes belonging to the error class `MPI_ERR_IN_STATUS` should be returned only by the MPI completion functions that take arrays of `MPI_STATUS`. For the functions `MPI_TEST`, `MPI_TESTANY`, `MPI_WAIT`, and `MPI_WAITANY`, which return a single `MPI_STATUS` value, the normal MPI error return process should be used (not the `MPI_ERROR` field in the `MPI_STATUS` argument).

`MPI_WAIT(request, status)`

INOUT	request	request (handle)
OUT	status	status object (Status)

`int MPI_Wait(MPI_Request *request, MPI_Status *status)`

`MPI_WAIT(REQUEST, STATUS, IERROR)`

INTEGER REQUEST, STATUS(MPI\_STATUS\_SIZE), IERROR

`MPI_Wait(request, status, ierror)`

TYPE(MPI\_Request), INTENT(INOUT) :: request

TYPE(MPI\_Status), INTENT(OUT) :: status ! optional by overloading

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

`{void MPI::Request::Wait(MPI::Status& status) (binding deprecated, see Section 15.2) }`

`{void MPI::Request::Wait() (binding deprecated, see Section 15.2) }`

A call to `MPI_WAIT` returns when the operation identified by **request** is complete. If the communication object associated with this request was created by a nonblocking send or receive call, then the object is deallocated by the call to `MPI_WAIT` and the request handle is set to `MPI_REQUEST_NULL`. `MPI_WAIT` is a non-local operation.

The call returns, in **status**, information on the completed operation. The content of the status object for a receive operation can be accessed as described in Section 3.2.5. The status object for a send operation may be queried by a call to `MPI_TEST_CANCELLED` (see Section 3.8).

One is allowed to call `MPI_WAIT` with a null or inactive **request** argument. In this case the operation returns immediately with empty **status**.

*Advice to users.* Successful return of `MPI_WAIT` after a `MPI_IBSEND` implies that

the user send buffer can be reused — i.e., data has been sent out or copied into a buffer attached with `MPI_BUFFER_ATTACH`. Note that, at this point, we can no longer cancel the send (see Section 3.8). If a matching receive is never posted, then the buffer cannot be freed. This runs somewhat counter to the stated goal of `MPI_CANCEL` (always being able to free program space that was committed to the communication subsystem). (*End of advice to users.*)

*Advice to implementors.* In a multi-threaded environment, a call to `MPI_WAIT` should block only the calling thread, allowing the thread scheduler to schedule another thread for execution. (*End of advice to implementors.*)

`MPI_TEST(request, flag, status)`

INOUT	request	communication request (handle)
OUT	flag	true if operation completed (logical)
OUT	status	status object (Status)

`int MPI_Test(MPI_Request *request, int *flag, MPI_Status *status)`

`MPI_TEST(REQUEST, FLAG, STATUS, IERROR)`

LOGICAL FLAG

INTEGER REQUEST, STATUS(MPI\_STATUS\_SIZE), IERROR

`MPI_Test(request, flag, status, ierror)`

LOGICAL, INTENT(OUT) :: flag

TYPE(MPI\_Request), INTENT(INOUT) :: request

TYPE(MPI\_Status), INTENT(OUT) :: status ! optional by overloading

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

`{bool MPI::Request::Test(MPI::Status& status) (binding deprecated, see Section 15.2) }`

`{bool MPI::Request::Test() (binding deprecated, see Section 15.2) }`

A call to `MPI_TEST` returns `flag = true` if the operation identified by `request` is complete. In such a case, the status object is set to contain information on the completed operation; if the communication object was created by a nonblocking send or receive, then it is deallocated and the request handle is set to `MPI_REQUEST_NULL`. The call returns `flag = false`, otherwise. In this case, the value of the status object is undefined. `MPI_TEST` is a local operation.

The return status object for a receive operation carries information that can be accessed as described in Section 3.2.5. The status object for a send operation carries information that can be accessed by a call to `MPI_TEST_CANCELLED` (see Section 3.8).

One is allowed to call `MPI_TEST` with a null or inactive `request` argument. In such a case the operation returns with `flag = true` and empty `status`.

The functions `MPI_WAIT` and `MPI_TEST` can be used to complete both sends and receives.

*Advice to users.* The use of the nonblocking `MPI_TEST` call allows the user to schedule alternative activities within a single thread of execution. An event-driven thread scheduler can be emulated with periodic calls to `MPI_TEST`. (*End of advice to users.*)

**Example 3.13** Simple usage of nonblocking operations and `MPI_WAIT`.

```
CALL MPI_COMM_RANK(comm, rank, ierr)
IF (rank.EQ.0) THEN
  CALL MPI_ISEND(a(1), 10, MPI_REAL, 1, tag, comm, request, ierr)
  **** do some computation to mask latency ****
  CALL MPI_WAIT(request, status, ierr)
ELSE IF (rank.EQ.1) THEN
  CALL MPI_IRECV(a(1), 15, MPI_REAL, 0, tag, comm, request, ierr)
  **** do some computation to mask latency ****
  CALL MPI_WAIT(request, status, ierr)
END IF
```

A request object can be deallocated without waiting for the associated communication to complete, by using the following operation.

`MPI_REQUEST_FREE(request)`

INOUT      request                                  communication request (handle)

```
int MPI_Request_free(MPI_Request *request)
```

```
MPI_REQUEST_FREE(REQUEST, IERROR)
```

```
INTEGER REQUEST, IERROR
```

```
MPI_Request_free(request, ierror)
```

```
TYPE(MPI_Request), INTENT(INOUT) :: request
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Request::Free() (binding deprecated, see Section 15.2) }
```

Mark the request object for deallocation and set `request` to `MPI_REQUEST_NULL`. An ongoing communication that is associated with the request will be allowed to complete. The request will be deallocated only after its completion.

*Rationale.* The `MPI_REQUEST_FREE` mechanism is provided for reasons of performance and convenience on the sending side. (*End of rationale.*)

*Advice to users.* Once a request is freed by a call to `MPI_REQUEST_FREE`, it is not possible to check for the successful completion of the associated communication with calls to `MPI_WAIT` or `MPI_TEST`. Also, if an error occurs subsequently during the communication, an error code cannot be returned to the user — such an error must be treated as fatal. An active receive request should never be freed as the receiver will have no way to verify that the receive has completed and the receive buffer can be reused. (*End of advice to users.*)



**Example 3.14** An example using MPI\_REQUEST\_FREE.

```

CALL MPI_COMM_RANK(MPI_COMM_WORLD, rank, ierr)
IF (rank.EQ.0) THEN
  DO i=1, n
    CALL MPI_ISEND(outval, 1, MPI_REAL, 1, 0, MPI_COMM_WORLD, req, ierr)
    CALL MPI_REQUEST_FREE(req, ierr)
    CALL MPI_Irecv(inval, 1, MPI_REAL, 1, 0, MPI_COMM_WORLD, req, ierr)
    CALL MPI_WAIT(req, status, ierr)
  END DO
ELSE IF (rank.EQ.1) THEN
  CALL MPI_Irecv(inval, 1, MPI_REAL, 0, 0, MPI_COMM_WORLD, req, ierr)
  CALL MPI_WAIT(req, status, ierr)
  DO I=1, n-1
    CALL MPI_ISEND(outval, 1, MPI_REAL, 0, 0, MPI_COMM_WORLD, req, ierr)
    CALL MPI_REQUEST_FREE(req, ierr)
    CALL MPI_Irecv(inval, 1, MPI_REAL, 0, 0, MPI_COMM_WORLD, req, ierr)
    CALL MPI_WAIT(req, status, ierr)
  END DO
  CALL MPI_ISEND(outval, 1, MPI_REAL, 0, 0, MPI_COMM_WORLD, req, ierr)
  CALL MPI_WAIT(req, status, ierr)
END IF

```

### 3.7.4 Semantics of Nonblocking Communications

The semantics of nonblocking communication is defined by suitably extending the definitions in Section 3.5.

**Order** Nonblocking communication operations are ordered according to the execution order of the calls that initiate the communication. The non-overtaking requirement of Section 3.5 is extended to nonblocking communication, with this definition of order being used.

**Example 3.15** Message ordering for nonblocking operations.

```

CALL MPI_COMM_RANK(comm, rank, ierr)
IF (RANK.EQ.0) THEN
  CALL MPI_ISEND(a, 1, MPI_REAL, 1, 0, comm, r1, ierr)
  CALL MPI_ISEND(b, 1, MPI_REAL, 1, 0, comm, r2, ierr)
ELSE IF (rank.EQ.1) THEN
  CALL MPI_Irecv(a, 1, MPI_REAL, 0, MPI_ANY_TAG, comm, r1, ierr)
  CALL MPI_Irecv(b, 1, MPI_REAL, 0, 0, comm, r2, ierr)
END IF
CALL MPI_WAIT(r1, status, ierr)
CALL MPI_WAIT(r2, status, ierr)

```

The first send of process zero will match the first receive of process one, even if both messages are sent before process one executes either receive.

**Progress** A call to `MPI_WAIT` that completes a receive will eventually terminate and return if a matching send has been started, unless the send is satisfied by another receive. In particular, if the matching send is nonblocking, then the receive should complete even if no call is executed by the sender to complete the send. Similarly, a call to `MPI_WAIT` that completes a send will eventually return if a matching receive has been started, unless the receive is satisfied by another send, and even if no call is executed to complete the receive.

**Example 3.16** An illustration of progress semantics.

```
CALL MPI_COMM_RANK(comm, rank, ierr)
IF (RANK.EQ.0) THEN
    CALL MPI_SSEND(a, 1, MPI_REAL, 1, 0, comm, ierr)
    CALL MPI_SEND(b, 1, MPI_REAL, 1, 1, comm, ierr)
ELSE IF (rank.EQ.1) THEN
    CALL MPI_IRECV(a, 1, MPI_REAL, 0, 0, comm, r, ierr)
    CALL MPI_RECV(b, 1, MPI_REAL, 0, 1, comm, status, ierr)
    CALL MPI_WAIT(r, status, ierr)
END IF
```

This code should not deadlock in a correct MPI implementation. The first synchronous send of process zero must complete after process one posts the matching (nonblocking) receive even if process one has not yet reached the completing wait call. Thus, process zero will continue and execute the second send, allowing process one to complete execution.

If an `MPI_TEST` that completes a receive is repeatedly called with the same arguments, and a matching send has been started, then the call will eventually return `flag = true`, unless the send is satisfied by another receive. If an `MPI_TEST` that completes a send is repeatedly called with the same arguments, and a matching receive has been started, then the call will eventually return `flag = true`, unless the receive is satisfied by another send.

### 3.7.5 Multiple Completions

It is convenient to be able to wait for the completion of any, some, or all the operations in a list, rather than having to wait for a specific message. A call to `MPI_WAITANY` or `MPI_TESTANY` can be used to wait for the completion of one out of several operations. A call to `MPI_WAITALL` or `MPI_TESTALL` can be used to wait for all pending operations in a list. A call to `MPI_WAIT SOME` or `MPI_TEST SOME` can be used to complete all enabled operations in a list.

`MPI_WAITANY (count, array_of_requests, index, status)`

IN	count	list length (non-negative integer)
INOUT	array_of_requests	array of requests (array of handles)
OUT	index	index of handle for operation that completed (integer)
OUT	status	status object (Status)

```
int MPI_Waitany(int count, MPI_Request *array_of_requests, int *index,
               MPI_Status *status)
```

```

MPI_WAITANY(COUNT, ARRAY_OF_REQUESTS, INDEX, STATUS, IERROR)
    INTEGER COUNT, ARRAY_OF_REQUESTS(*), INDEX, STATUS(MPI_STATUS_SIZE),
    IERROR

MPI_Waitany(count, array_of_requests, index, status, ierror)
    INTEGER, INTENT(IN) :: count
    TYPE(MPI_Request), INTENT(OUT) :: array_of_requests(*)
    INTEGER, INTENT(OUT) :: index
    TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{static int MPI::Request::Waitany(int count,
    MPI::Request array_of_requests[], MPI::Status& status) (binding
    deprecated, see Section 15.2) }

{static int MPI::Request::Waitany(int count,
    MPI::Request array_of_requests[]) (binding deprecated, see
    Section 15.2) }

```

Blocks until one of the operations associated with the active requests in the array has completed. If more than one operation is enabled and can terminate, one is arbitrarily chosen. Returns in `index` the index of that request in the array and returns in `status` the status of the completing communication. (The array is indexed from zero in C, and from one in Fortran.) If the request was allocated by a nonblocking communication operation, then it is deallocated and the request handle is set to `MPI_REQUEST_NULL`.

The `array_of_requests` list may contain null or inactive handles. If the list contains no active handles (list has length zero or all entries are null or inactive), then the call returns immediately with `index = MPI_UNDEFINED`, and an empty `status`.

The execution of `MPI_WAITANY(count, array_of_requests, index, status)` has the same effect as the execution of `MPI_WAIT(&array_of_requests[i], status)`, where `i` is the value returned by `index` (unless the value of `index` is `MPI_UNDEFINED`). `MPI_WAITANY` with an array containing one active entry is equivalent to `MPI_WAIT`.

```

MPI_TESTANY(count, array_of_requests, index, flag, status)

```

IN	count	list length (non-negative integer)
INOUT	array_of_requests	array of requests (array of handles)
OUT	index	index of operation that completed, or MPI_UNDEFINED if none completed (integer)
OUT	flag	true if one of the operations is complete (logical)
OUT	status	status object (Status)

```

int MPI_Testany(int count, MPI_Request *array_of_requests, int *index,
    int *flag, MPI_Status *status)

```

```

MPI_TESTANY(COUNT, ARRAY_OF_REQUESTS, INDEX, FLAG, STATUS, IERROR)
    LOGICAL FLAG
    INTEGER COUNT, ARRAY_OF_REQUESTS(*), INDEX, STATUS(MPI_STATUS_SIZE),
    IERROR

```

```

1
ticket-248T. 2 MPI_Testany(count, array_of_requests, index, flag, status, ierror)
3             INTEGER, INTENT(IN) :: count
4             TYPE(MPI_Request), INTENT(INOUT) :: array_of_requests(*)
5             INTEGER, INTENT(OUT) :: index
6             LOGICAL, INTENT(OUT) :: flag
7             TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
8             INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

9
10 {static bool MPI::Request::Testany(int count,
11                                     MPI::Request array_of_requests[], int& index,
12                                     MPI::Status& status) (binding deprecated, see Section 15.2) }
13
14 {static bool MPI::Request::Testany(int count,
15                                     MPI::Request array_of_requests[], int& index) (binding deprecated,
16                                     see Section 15.2) }

```

Tests for completion of either one or none of the operations associated with active handles. In the former case, it returns `flag = true`, returns in `index` the index of this request in the array, and returns in `status` the status of that operation; if the request was allocated by a nonblocking communication call then the request is deallocated and the handle is set to `MPI_REQUEST_NULL`. (The array is indexed from zero in C, and from one in Fortran.) In the latter case (no operation completed), it returns `flag = false`, returns a value of `MPI_UNDEFINED` in `index` and `status` is undefined.

The array may contain null or inactive handles. If the array contains no active handles then the call returns immediately with `flag = true`, `index = MPI_UNDEFINED`, and an empty `status`.

If the array of requests contains active handles then the execution of `MPI_TESTANY(count, array_of_requests, index, status)` has the same effect as the execution of `MPI_TEST(&array_of_requests[i], flag, status)`, for  $i=0, 1, \dots, \text{count}-1$ , in some arbitrary order, until one call returns `flag = true`, or all fail. In the former case, `index` is set to the last value of  $i$ , and in the latter case, it is set to `MPI_UNDEFINED`. `MPI_TESTANY` with an array containing one active entry is equivalent to `MPI_TEST`.

```

33
34 MPI_WAITALL( count, array_of_requests, array_of_statuses)
35
36     IN          count                lists length (non-negative integer)
37     INOUT      array_of_requests      array of requests (array of handles)
38     OUT        array_of_statuses      array of status objects (array of Status)
39

```

```

40
41 int MPI_Waitall(int count, MPI_Request *array_of_requests,
42                MPI_Status *array_of_statuses)
43
44 MPI_WAITALL(COUNT, ARRAY_OF_REQUESTS, ARRAY_OF_STATUSES, IERROR)
45             INTEGER COUNT, ARRAY_OF_REQUESTS(*)
46             INTEGER ARRAY_OF_STATUSES(MPI_STATUS_SIZE,*), IERROR

```

```

47 MPI_Waitall(count, array_of_requests, array_of_statuses, ierror)
48             INTEGER, INTENT(IN) :: count

```

```

    INTEGER, INTENT(INOUT) :: array_of_requests(*)
    TYPE(MPI_Status), INTENT(OUT) :: array_of_statuses(*) ! optional by
    overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{static void MPI::Request::Waitall(int count,
    MPI::Request array_of_requests[],
    MPI::Status array_of_statuses[]) (binding deprecated, see
    Section 15.2) }

{static void MPI::Request::Waitall(int count,
    MPI::Request array_of_requests[]) (binding deprecated, see
    Section 15.2) }

```

Blocks until all communication operations associated with active handles in the list complete, and return the status of all these operations (this includes the case where no handle in the list is active). Both arrays have the same number of valid entries. The *i*-th entry in `array_of_statuses` is set to the return status of the *i*-th operation. Requests that were created by nonblocking communication operations are deallocated and the corresponding handles in the array are set to `MPI_REQUEST_NULL`. The list may contain null or inactive handles. The call sets to empty the status of each such entry.

The error-free execution of `MPI_WAITALL(count, array_of_requests, array_of_statuses)` has the same effect as the execution of `MPI_WAIT(&array_of_request[i], &array_of_statuses[i], for i=0 ..., count-1, in some arbitrary order. MPI_WAITALL with an array of length one is equivalent to MPI_WAIT.`

When one or more of the communications completed by a call to `MPI_WAITALL` fail, it is desirable to return specific information on each communication. The function `MPI_WAITALL` will return in such case the error code `MPI_ERR_IN_STATUS` and will set the error field of each status to a specific error code. This code will be `MPI_SUCCESS`, if the specific communication completed; it will be another specific error code, if it failed; or it can be `MPI_ERR_PENDING` if it has neither failed nor completed. The function `MPI_WAITALL` will return `MPI_SUCCESS` if no request had an error, or will return another error code if it failed for other reasons (such as invalid arguments). In such cases, it will not update the error fields of the statuses.

*Rationale.* This design streamlines error handling in the application. The application code need only test the (single) function result to determine if an error has occurred. It needs to check each individual status only when an error occurred. (*End of rationale.*)

`MPI_TESTALL(count, array_of_requests, flag, array_of_statuses)`

IN	count	lists length (non-negative integer)
INOUT	array_of_requests	array of requests (array of handles)
OUT	flag	(logical)
OUT	array_of_statuses	array of status objects (array of Status)

```

int MPI_Testall(int count, MPI_Request *array_of_requests, int *flag,
    MPI_Status *array_of_statuses)

```

```

1 MPI_TESTALL(COUNT, ARRAY_OF_REQUESTS, FLAG, ARRAY_OF_STATUSES, IERROR)
2     LOGICAL FLAG
3     INTEGER COUNT, ARRAY_OF_REQUESTS(*),
4     ARRAY_OF_STATUSES(MPI_STATUS_SIZE,*), IERROR

```

```

5 MPI_Testall(count, array_of_requests, flag, array_of_statuses, ierror)
6     INTEGER, INTENT(IN) :: count
7     TYPE(MPI_Request), INTENT(INOUT) :: array_of_requests(*)
8     LOGICAL, INTENT(OUT) :: flag
9     TYPE(MPI_Status), INTENT(OUT) :: array_of_statuses(*) ! optional by
10    overloading
11    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

13 {static bool MPI::Request::Testall(int count,
14     MPI::Request array_of_requests[],
15     MPI::Status array_of_statuses[]) (binding deprecated, see
16     Section 15.2) }

```

```

17 {static bool MPI::Request::Testall(int count,
18     MPI::Request array_of_requests[]) (binding deprecated, see
19     Section 15.2) }

```

Returns `flag = true` if all communications associated with active handles in the array have completed (this includes the case where no handle in the list is active). In this case, each status entry that corresponds to an active handle request is set to the status of the corresponding communication; if the request was allocated by a nonblocking communication call then it is deallocated, and the handle is set to `MPI_REQUEST_NULL`. Each status entry that corresponds to a null or inactive handle is set to empty.

Otherwise, `flag = false` is returned, no request is modified and the values of the status entries are undefined. This is a local operation.

Errors that occurred during the execution of `MPI_TESTALL` are handled as errors in `MPI_WAITALL`.

```

33 MPI_WAITSOME(incount, array_of_requests, outcount, array_of_indices, array_of_statuses)

```

IN	incount	length of array_of_requests (non-negative integer)
INOUT	array_of_requests	array of requests (array of handles)
OUT	outcount	number of completed requests (integer)
OUT	array_of_indices	array of indices of operations that completed (array of integers)
OUT	array_of_statuses	array of status objects for operations that completed (array of Status)

```

45 int MPI_Waitsome(int incount, MPI_Request *array_of_requests,
46     int *outcount, int *array_of_indices,
47     MPI_Status *array_of_statuses)

```

```

MPI_WAITSSOME(INCOUNT, ARRAY_OF_REQUESTS, OUTCOUNT, ARRAY_OF_INDICES,
               ARRAY_OF_STATUSES, IERROR)
    INTEGER INCOUNT, ARRAY_OF_REQUESTS(*), OUTCOUNT, ARRAY_OF_INDICES(*),
    ARRAY_OF_STATUSES(MPI_STATUS_SIZE,*), IERROR

```

```

MPI_Waitssome(incount, array_of_requests, outcount, array_of_indices,
               array_of_statuses, ierror)
    INTEGER, INTENT(IN) :: incount
    TYPE(MPI_Request), INTENT(INOUT) :: array_of_requests(*)
    INTEGER, INTENT(OUT) :: outcount, array_of_indices(*)
    TYPE(MPI_Status), INTENT(OUT) :: array_of_statuses(*) ! optional by
    overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{static int MPI::Request::Waitssome(int incount,
    MPI::Request array_of_requests[], int array_of_indices[],
    MPI::Status array_of_statuses[]) (binding deprecated, see
    Section 15.2) }

```

```

{static int MPI::Request::Waitssome(int incount,
    MPI::Request array_of_requests[],
    int array_of_indices[]) (binding deprecated, see Section 15.2) }

```

Waits until at least one of the operations associated with active handles in the list have completed. Returns in `outcount` the number of requests from the list `array_of_requests` that have completed. Returns in the first `outcount` locations of the array `array_of_indices` the indices of these operations (index within the array `array_of_requests`; the array is indexed from zero in C and from one in Fortran). Returns in the first `outcount` locations of the array `array_of_status` the status for these completed operations. If a request that completed was allocated by a nonblocking communication call, then it is deallocated, and the associated handle is set to `MPI_REQUEST_NULL`.

If the list contains no active handles, then the call returns immediately with `outcount = MPI_UNDEFINED`.

When one or more of the communications completed by `MPI_WAITSSOME` fails, then it is desirable to return specific information on each communication. The arguments `outcount`, `array_of_indices` and `array_of_statuses` will be adjusted to indicate completion of all communications that have succeeded or failed. The call will return the error code `MPI_ERR_IN_STATUS` and the error field of each status returned will be set to indicate success or to indicate the specific error that occurred. The call will return `MPI_SUCCESS` if no request resulted in an error, and will return another error code if it failed for other reasons (such as invalid arguments). In such cases, it will not update the error fields of the statuses.

```
1 MPI_TESTSOME(incount, array_of_requests, outcount, array_of_indices, array_of_statuses)
```

```
2
3     IN      incount      length of array_of_requests (non-negative integer)
4
5     INOUT   array_of_requests  array of requests (array of handles)
6
7     OUT     outcount      number of completed requests (integer)
8
9     OUT     array_of_indices  array of indices of operations that completed (array of
10                                integers)
11
12     OUT     array_of_statuses  array of status objects for operations that completed
13                                (array of Status)
```

```
13 int MPI_Testsome(int incount, MPI_Request *array_of_requests,
14                 int *outcount, int *array_of_indices,
15                 MPI_Status *array_of_statuses)
```

```
16 MPI_TESTSOME(INCOUNT, ARRAY_OF_REQUESTS, OUTCOUNT, ARRAY_OF_INDICES,
17             ARRAY_OF_STATUSES, IERROR)
18     INTEGER INCOUNT, ARRAY_OF_REQUESTS(*), OUTCOUNT, ARRAY_OF_INDICES(*),
19     ARRAY_OF_STATUSES(MPI_STATUS_SIZE,*), IERROR
```

```
20 MPI_Testsome(incount, array_of_requests, outcount, array_of_indices,
21             array_of_statuses, ierror)
22     INTEGER, INTENT(IN) :: incount
23     TYPE(MPI_Request), INTENT(INOUT) :: array_of_requests(*)
24     INTEGER, INTENT(OUT) :: outcount, array_of_indices(*)
25     TYPE(MPI_Status), INTENT(OUT) :: array_of_statuses(*) ! optional by
26     overloading
27     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
28 {static int MPI::Request::Testsome(int incount,
29     MPI::Request array_of_requests[], int array_of_indices[],
30     MPI::Status array_of_statuses[]) (binding deprecated, see
31     Section 15.2) }
```

```
32 {static int MPI::Request::Testsome(int incount,
33     MPI::Request array_of_requests[],
34     int array_of_indices[]) (binding deprecated, see Section 15.2) }
```

Behaves like MPI\_WAITSSOME, except that it returns immediately. If no operation has completed it returns outcount = 0. If there is no active handle in the list it returns outcount = MPI\_UNDEFINED.

MPI\_TESTSOME is a local operation, which returns immediately, whereas MPI\_WAITSSOME will block until a communication completes, if it was passed a list that contains at least one active handle. Both calls fulfill a fairness requirement: If a request for a receive repeatedly appears in a list of requests passed to MPI\_WAITSSOME or MPI\_TESTSOME, and a matching send has been posted, then the receive will eventually succeed, unless the send is satisfied by another receive; and similarly for send requests.

Errors that occur during the execution of MPI\_TESTSOME are handled as for MPI\_WAITSSOME.



*Advice to users.* The use of MPI\_TESTSOME is likely to be more efficient than the use of MPI\_TESTANY. The former returns information on all completed communications, with the latter, a new call is required for each communication that completes.

A server with multiple clients can use MPI\_WAIT SOME so as not to starve any client. Clients send messages to the server with service requests. The server calls MPI\_WAIT SOME with one receive request for each client, and then handles all receives that completed. If a call to MPI\_WAIT ANY is used instead, then one client could starve while requests from another client always sneak in first. (*End of advice to users.*)

*Advice to implementors.* MPI\_TESTSOME should complete as many pending communications as possible. (*End of advice to implementors.*)

**Example 3.17** Client-server code (starvation can occur).

```
CALL MPI_COMM_SIZE(comm, size, ierr)
CALL MPI_COMM_RANK(comm, rank, ierr)
IF(rank .GT. 0) THEN          ! client code
  DO WHILE(.TRUE.)
    CALL MPI_ISEND(a, n, MPI_REAL, 0, tag, comm, request, ierr)
    CALL MPI_WAIT(request, status, ierr)
  END DO
ELSE                          ! rank=0 -- server code
  DO i=1, size-1
    CALL MPI_Irecv(a(1,i), n, MPI_REAL, i, tag,
                  comm, request_list(i), ierr)
  END DO
  DO WHILE(.TRUE.)
    CALL MPI_WAITANY(size-1, request_list, index, status, ierr)
    CALL DO_SERVICE(a(1,index)) ! handle one message
    CALL MPI_Irecv(a(1, index), n, MPI_REAL, index, tag,
                  comm, request_list(index), ierr)
  END DO
END IF
```

**Example 3.18** Same code, using MPI\_WAIT SOME.

```
CALL MPI_COMM_SIZE(comm, size, ierr)
CALL MPI_COMM_RANK(comm, rank, ierr)
IF(rank .GT. 0) THEN          ! client code
  DO WHILE(.TRUE.)
    CALL MPI_ISEND(a, n, MPI_REAL, 0, tag, comm, request, ierr)
    CALL MPI_WAIT(request, status, ierr)
  END DO
ELSE                          ! rank=0 -- server code
  DO i=1, size-1
```

```

1      CALL MPI_Irecv(a(1,i), n, MPI_REAL, i, tag,
2                    comm, request_list(i), ierr)
3  END DO
4  DO WHILE(.TRUE.)
5      CALL MPI_WAITsome(size, request_list, numdone,
6                        indices, statuses, ierr)
7      DO i=1, numdone
8          CALL DO_SERVICE(a(1, indices(i)))
9          CALL MPI_Irecv(a(1, indices(i)), n, MPI_REAL, 0, tag,
10                        comm, request_list(indices(i)), ierr)
11      END DO
12  END DO
13 END IF

```

### 3.7.6 Non-destructive Test of status

This call is useful for accessing the information associated with a request, without freeing the request (in case the user is expected to access it later). It allows one to layer libraries more conveniently, since multiple layers of software may access the same completed request and extract from it the status information.

**MPI\_REQUEST\_GET\_STATUS**( request, flag, status )

IN	request	request (handle)
OUT	flag	boolean flag, same as from MPI_TEST (logical)
OUT	status	MPI_STATUS object if flag is true (Status)

```

int MPI_Request_get_status(MPI_Request request, int *flag,
                           MPI_Status *status)

```

```

MPI_REQUEST_GET_STATUS( REQUEST, FLAG, STATUS, IERROR)
  INTEGER REQUEST, STATUS(MPI_STATUS_SIZE), IERROR
  LOGICAL FLAG

```

```

MPI_Request_get_status( request, flag, status, ierror)
  TYPE(MPI_Request), INTENT(IN) :: request
  LOGICAL, INTENT(OUT) :: flag
  TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{bool MPI::Request::Get_status(MPI::Status& status) const(binding deprecated,
  see Section 15.2) }

```

```

{bool MPI::Request::Get_status() const(binding deprecated, see Section 15.2) }

```

Sets flag=true if the operation is complete, and, if so, returns in status the request status. However, unlike test or wait, it does not deallocate or inactivate the request; a subsequent call to test, wait or free should be executed with that request. It sets flag=false if the operation is not complete.

One is allowed to call `MPI_REQUEST_GET_STATUS` with a null or inactive request argument. In such a case the operation returns with `flag=true` and empty status.

### 3.8 Probe and Cancel

The `MPI_PROBE` and `MPI_IPROBE` operations allow incoming messages to be checked for, without actually receiving them. The user can then decide how to receive them, based on the information returned by the probe (basically, the information returned by `status`). In particular, the user may allocate memory for the receive buffer, according to the length of the probed message.

The `MPI_CANCEL` operation allows pending communications to be canceled. This is required for cleanup. Posting a send or a receive ties up user resources (send or receive buffers), and a cancel may be needed to free these resources gracefully.

`MPI_IPROBE(source, tag, comm, flag, status)`

IN	source	rank of source or <code>MPI_ANY_SOURCE</code> (integer)
IN	tag	message tag or <code>MPI_ANY_TAG</code> (integer)
IN	comm	communicator (handle)
OUT	flag	(logical)
OUT	status	status object ( <code>Status</code> )

```
int MPI_Iprobe(int source, int tag, MPI_Comm comm, int *flag,
               MPI_Status *status)
```

```
MPI_IPROBE(SOURCE, TAG, COMM, FLAG, STATUS, IERROR)
```

```
LOGICAL FLAG
```

```
INTEGER SOURCE, TAG, COMM, STATUS(MPI_STATUS_SIZE), IERROR
```

```
MPI_Iprobe(source, tag, comm, flag, status, ierror)
```

```
INTEGER, INTENT(IN) :: source, tag
```

```
TYPE(MPI_Comm), INTENT(IN) :: comm
```

```
LOGICAL, INTENT(OUT) :: flag
```

```
TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{bool MPI::Comm::Iprobe(int source, int tag, MPI::Status& status)
    const(binding deprecated, see Section 15.2) }
```

```
{bool MPI::Comm::Iprobe(int source, int tag) const(binding deprecated, see
    Section 15.2) }
```

`MPI_IPROBE(source, tag, comm, flag, status)` returns `flag = true` if there is a message that can be received and that matches the pattern specified by the arguments `source`, `tag`, and `comm`. The call matches the same message that would have been received by a call to `MPI_RECV(..., source, tag, comm, status)` executed at the same point in the program, and returns in `status` the same value that would have been returned by `MPI_RECV()`. Otherwise, the call returns `flag = false`, and leaves `status` undefined.

If `MPI_Iprobe` returns `flag = true`, then the content of the status object can be subsequently accessed as described in Section 3.2.5 to find the source, tag and length of the probed message.

A subsequent receive executed with the same communicator, and the source and tag returned in status by `MPI_Iprobe` will receive the message that was matched by the probe, if no other intervening receive occurs after the probe, and the send is not successfully cancelled before the receive. If the receiving process is multi-threaded, it is the user's responsibility to ensure that the last condition holds.

The source argument of `MPI_Probe` can be `MPI_ANY_SOURCE`, and the tag argument can be `MPI_ANY_TAG`, so that one can probe for messages from an arbitrary source and/or with an arbitrary tag. However, a specific communication context must be provided with the `comm` argument.

It is not necessary to receive a message immediately after it has been probed for, and the same message may be probed for several times before it is received.

`MPI_Probe(source, tag, comm, status)`

IN	source	rank of source or <code>MPI_ANY_SOURCE</code> (integer)
IN	tag	message tag or <code>MPI_ANY_TAG</code> (integer)
IN	comm	communicator (handle)
OUT	status	status object ( <code>Status</code> )

`int MPI_Probe(int source, int tag, MPI_Comm comm, MPI_Status *status)`

`MPI_Probe(SOURCE, TAG, COMM, STATUS, IERROR)`

`INTEGER SOURCE, TAG, COMM, STATUS(MPI_STATUS_SIZE), IERROR`

`MPI_Probe(source, tag, comm, status, ierror)`

`INTEGER, INTENT(IN) :: source, tag`

`TYPE(MPI_Comm), INTENT(IN) :: comm`

`TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading`

`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{void MPI::Comm::Probe(int source, int tag, MPI::Status& status)`

`const(binding deprecated, see Section 15.2) }`

`{void MPI::Comm::Probe(int source, int tag) const(binding deprecated, see`

`Section 15.2) }`

`MPI_Probe` behaves like `MPI_Iprobe` except that it is a blocking call that returns only after a matching message has been found.

The MPI implementation of `MPI_Probe` and `MPI_Iprobe` needs to guarantee progress: if a call to `MPI_Probe` has been issued by a process, and a send that matches the probe has been initiated by some process, then the call to `MPI_Probe` will return, unless the message is received by another concurrent receive operation (that is executed by another thread at the probing process). Similarly, if a process busy waits with `MPI_Iprobe` and a matching message has been issued, then the call to `MPI_Iprobe` will eventually return `flag = true` unless the message is received by another concurrent receive operation.

**Example 3.19**

Use blocking probe to wait for an incoming message.

```

CALL MPI_COMM_RANK(comm, rank, ierr)
IF (rank.EQ.0) THEN
    CALL MPI_SEND(i, 1, MPI_INTEGER, 2, 0, comm, ierr)
ELSE IF (rank.EQ.1) THEN
    CALL MPI_SEND(x, 1, MPI_REAL, 2, 0, comm, ierr)
ELSE IF (rank.EQ.2) THEN
    DO i=1, 2
        CALL MPI_PROBE(MPI_ANY_SOURCE, 0,
                        comm, status, ierr)
        IF (status(MPI_SOURCE) .EQ. 0) THEN
100      CALL MPI_RECV(i, 1, MPI_INTEGER, 0, 0, comm, status, ierr)
        ELSE
200      CALL MPI_RECV(x, 1, MPI_REAL, 1, 0, comm, status, ierr)
        END IF
    END DO
END IF

```

Each message is received with the right type.

**Example 3.20** A similar program to the previous example, but now it has a problem.

```

CALL MPI_COMM_RANK(comm, rank, ierr)
IF (rank.EQ.0) THEN
    CALL MPI_SEND(i, 1, MPI_INTEGER, 2, 0, comm, ierr)
ELSE IF (rank.EQ.1) THEN
    CALL MPI_SEND(x, 1, MPI_REAL, 2, 0, comm, ierr)
ELSE IF (rank.EQ.2) THEN
    DO i=1, 2
        CALL MPI_PROBE(MPI_ANY_SOURCE, 0,
                        comm, status, ierr)
        IF (status(MPI_SOURCE) .EQ. 0) THEN
100      CALL MPI_RECV(i, 1, MPI_INTEGER, MPI_ANY_SOURCE,
                        0, comm, status, ierr)
        ELSE
200      CALL MPI_RECV(x, 1, MPI_REAL, MPI_ANY_SOURCE,
                        0, comm, status, ierr)
        END IF
    END DO
END IF

```

We slightly modified Example 3.19, using `MPI_ANY_SOURCE` as the `source` argument in the two receive calls in statements labeled 100 and 200. The program is now incorrect: the receive operation may receive a message that is distinct from the message probed by the preceding call to `MPI_PROBE`.

*Advice to implementors.* A call to `MPI_PROBE(source, tag, comm, status)` will match the message that would have been received by a call to `MPI_RECV(..., source, tag,`

comm, status) executed at the same point. Suppose that this message has source *s*, tag *t* and communicator *c*. If the tag argument in the probe call has value MPI\_ANY\_TAG then the message probed will be the earliest pending message from source *s* with communicator *c* and any tag; in any case, the message probed will be the earliest pending message from source *s* with tag *t* and communicator *c* (this is the message that would have been received, so as to preserve message order). This message continues as the earliest pending message from source *s* with tag *t* and communicator *c*, until it is received. A receive operation subsequent to the probe that uses the same communicator as the probe and uses the tag and source values returned by the probe, must receive this message, unless it has already been received by another receive operation. (*End of advice to implementors.*)

MPI\_CANCEL(request)

IN request communication request (handle)

int MPI\_Cancel(MPI\_Request \*request)

MPI\_CANCEL(REQUEST, IERROR)

INTEGER REQUEST, IERROR

MPI\_Cancel(request, ierror)

TYPE(MPI\_Request), INTENT(IN) :: request

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Request::Cancel() const(*binding deprecated, see Section 15.2*) }

A call to MPI\_CANCEL marks for cancellation a pending, nonblocking communication operation (send or receive). The cancel call is local. It returns immediately, possibly before the communication is actually canceled. It is still necessary to complete a communication that has been marked for cancellation, using a call to MPI\_REQUEST\_FREE, MPI\_WAIT or MPI\_TEST (or any of the derived operations).

If a communication is marked for cancellation, then a MPI\_WAIT call for that communication is guaranteed to return, irrespective of the activities of other processes (i.e., MPI\_WAIT behaves as a local function); similarly if MPI\_TEST is repeatedly called in a busy wait loop for a canceled communication, then MPI\_TEST will eventually be successful.

MPI\_CANCEL can be used to cancel a communication that uses a persistent request (see Section 3.9), in the same way it is used for nonpersistent requests. A successful cancellation cancels the active communication, but not the request itself. After the call to MPI\_CANCEL and the subsequent call to MPI\_WAIT or MPI\_TEST, the request becomes inactive and can be activated for a new communication.

The successful cancellation of a buffered send frees the buffer space occupied by the pending message.

Either the cancellation succeeds, or the communication succeeds, but not both. If a send is marked for cancellation, then it must be the case that either the send completes normally, in which case the message sent was received at the destination process, or that the send is successfully canceled, in which case no part of the message was received at the destination. Then, any matching receive has to be satisfied by another send. If a receive is

marked for cancellation, then it must be the case that either the receive completes normally, or that the receive is successfully canceled, in which case no part of the receive buffer is altered. Then, any matching send has to be satisfied by another receive.

If the operation has been canceled, then information to that effect will be returned in the status argument of the operation that completes the communication.

*Rationale.* Although the IN request handle parameter should not need to be passed by reference, the C binding has listed the argument type as `MPI_Request*` since MPI-1.0. This function signature therefore cannot be changed without breaking existing MPI applications. (*End of rationale.*)

`MPI_TEST_CANCELLED(status, flag)`

IN	status	status object (Status)
OUT	flag	(logical)

`int MPI_Test_cancelled(MPI_Status *status, int *flag)`

`MPI_TEST_CANCELLED(STATUS, FLAG, IERROR)`  
`LOGICAL FLAG`  
`INTEGER STATUS(MPI_STATUS_SIZE), IERROR`

`MPI_Test_cancelled(status, flag, ierror)`  
`TYPE(MPI_Status), INTENT(IN) :: status`  
`LOGICAL, INTENT(OUT) :: flag`  
`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{bool MPI::Status::Is_cancelled() const(binding deprecated, see Section 15.2) }`

Returns `flag = true` if the communication associated with the status object was canceled successfully. In such a case, all other fields of `status` (such as `count` or `tag`) are undefined. Returns `flag = false`, otherwise. If a receive operation might be canceled then one should call `MPI_TEST_CANCELLED` first, to check whether the operation was canceled, before checking on the other fields of the return status.

*Advice to users.* Cancel can be an expensive operation that should be used only exceptionally. (*End of advice to users.*)

*Advice to implementors.* If a send operation uses an “eager” protocol (data is transferred to the receiver before a matching receive is posted), then the cancellation of this send may require communication with the intended receiver in order to free allocated buffers. On some systems this may require an interrupt to the intended receiver. Note that, while communication may be needed to implement `MPI_CANCEL`, this is still a local operation, since its completion does not depend on the code executed by other processes. If processing is required on another process, this should be transparent to the application (hence the need for an interrupt and an interrupt handler). (*End of advice to implementors.*)

### 3.9 Persistent Communication Requests

Often a communication with the same argument list is repeatedly executed within the inner loop of a parallel computation. In such a situation, it may be possible to optimize the communication by binding the list of communication arguments to a **persistent** communication request once and, then, repeatedly using the request to initiate and complete messages. The persistent request thus created can be thought of as a communication port or a “half-channel.” It does not provide the full functionality of a conventional channel, since there is no binding of the send port to the receive port. This construct allows reduction of the overhead for communication between the process and communication controller, but not of the overhead for communication between one communication controller and another. It is not necessary that messages sent with a persistent request be received by a receive operation using a persistent request, or vice versa.

A persistent communication request is created using one of the five following calls. These calls involve no communication.

`MPI_SEND_INIT(buf, count, datatype, dest, tag, comm, request)`

IN	buf	initial address of send buffer (choice)
IN	count	number of elements sent (non-negative integer)
IN	datatype	type of each element (handle)
IN	dest	rank of destination (integer)
IN	tag	message tag (integer)
IN	comm	communicator (handle)
OUT	request	communication request (handle)

```
int MPI_Send_init(void* buf, int count, MPI_Datatype datatype, int dest,
                 int tag, MPI_Comm comm, MPI_Request *request)
```

```
MPI_SEND_INIT(BUF, COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR)
```

```
<type> BUF(*)
```

```
INTEGER COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR
```

```
MPI_Send_init(buf, count, datatype, dest, tag, comm, request, ierror)
```

```
TYPE(*), DIMENSION(..) :: buf
```

```
INTEGER, INTENT(IN) :: count, dest, tag
```

```
TYPE(MPI_Datatype), INTENT(IN) :: datatype
```

```
TYPE(MPI_Comm), INTENT(IN) :: comm
```

```
TYPE(MPI_Request), INTENT(OUT) :: request
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{MPI::Prequest MPI::Comm::Send_init(const void* buf, int count, const
MPI::Datatype& datatype, int dest, int tag) const(binding
deprecated, see Section 15.2) }
```

Creates a persistent communication request for a standard mode send operation, and binds to it all the arguments of a send operation.



```

MPI_BSEND_INIT(buf, count, datatype, dest, tag, comm, request)
    IN      buf                initial address of send buffer (choice)
    IN      count              number of elements sent (non-negative integer)
    IN      datatype           type of each element (handle)
    IN      dest               rank of destination (integer)
    IN      tag                message tag (integer)
    IN      comm               communicator (handle)
    OUT     request            communication request (handle)

int MPI_Bsend_init(void* buf, int count, MPI_Datatype datatype, int dest,
                  int tag, MPI_Comm comm, MPI_Request *request)

MPI_BSEND_INIT(BUF, COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR)
    <type> BUF(*)
    INTEGER COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR

MPI_Bsend_init(buf, count, datatype, dest, tag, comm, request, ierror)
    TYPE(*), DIMENSION(..) :: buf
    INTEGER, INTENT(IN) :: count, dest, tag
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Comm), INTENT(IN) :: comm
    TYPE(MPI_Request), INTENT(OUT) :: request
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{MPI::Prequest MPI::Comm::Bsend_init(const void* buf, int count, const
    MPI::Datatype& datatype, int dest, int tag) const(binding
    deprecated, see Section 15.2) }

    Creates a persistent communication request for a buffered mode send.

MPI_SSEND_INIT(buf, count, datatype, dest, tag, comm, request)
    IN      buf                initial address of send buffer (choice)
    IN      count              number of elements sent (non-negative integer)
    IN      datatype           type of each element (handle)
    IN      dest               rank of destination (integer)
    IN      tag                message tag (integer)
    IN      comm               communicator (handle)
    OUT     request            communication request (handle)

int MPI_Ssend_init(void* buf, int count, MPI_Datatype datatype, int dest,
                  int tag, MPI_Comm comm, MPI_Request *request)

MPI_SSEND_INIT(BUF, COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR)
    <type> BUF(*)

```

```

1      INTEGER COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR
ticket-248T. 2
3      MPI_Ssend_init(buf, count, datatype, dest, tag, comm, request, ierror)
4      TYPE(*), DIMENSION(..) :: buf
5      INTEGER, INTENT(IN) :: count, dest, tag
6      TYPE(MPI_Datatype), INTENT(IN) :: datatype
7      TYPE(MPI_Comm), INTENT(IN) :: comm
8      TYPE(MPI_Request), INTENT(OUT) :: request
9      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
10
11      {MPI::Prequest MPI::Comm::Ssend_init(const void* buf, int count, const
12      MPI::Datatype& datatype, int dest, int tag) const(binding
13      deprecated, see Section 15.2) }
14
15      Creates a persistent communication object for a synchronous mode send operation.
16
17      MPI_RSEND_INIT(buf, count, datatype, dest, tag, comm, request)
18
19      IN      buf                initial address of send buffer (choice)
20      IN      count              number of elements sent (non-negative integer)
21      IN      datatype           type of each element (handle)
22      IN      dest               rank of destination (integer)
23      IN      tag                message tag (integer)
24      IN      comm               communicator (handle)
25      OUT     request            communication request (handle)
26
27
28      int MPI_Rsend_init(void* buf, int count, MPI_Datatype datatype, int dest,
29      int tag, MPI_Comm comm, MPI_Request *request)
30
31      MPI_RSEND_INIT(BUF, COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR)
32      <type> BUF(*)
33      INTEGER COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR
ticket-248T. 34
35      MPI_Rsend_init(buf, count, datatype, dest, tag, comm, request, ierror)
36      TYPE(*), DIMENSION(..) :: buf
37      INTEGER, INTENT(IN) :: count, dest, tag
38      TYPE(MPI_Datatype), INTENT(IN) :: datatype
39      TYPE(MPI_Comm), INTENT(IN) :: comm
40      TYPE(MPI_Request), INTENT(OUT) :: request
41      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
42
43      {MPI::Prequest MPI::Comm::Rsend_init(const void* buf, int count, const
44      MPI::Datatype& datatype, int dest, int tag) const(binding
45      deprecated, see Section 15.2) }
46
47      Creates a persistent communication object for a ready mode send operation.
48

```

MPI\_RECV\_INIT(buf, count, datatype, source, tag, comm, request)

OUT	buf	initial address of receive buffer (choice)
IN	count	number of elements received (non-negative integer)
IN	datatype	type of each element (handle)
IN	source	rank of source or MPI_ANY_SOURCE (integer)
IN	tag	message tag or MPI_ANY_TAG (integer)
IN	comm	communicator (handle)
OUT	request	communication request (handle)

```
int MPI_Recv_init(void* buf, int count, MPI_Datatype datatype, int source,
                 int tag, MPI_Comm comm, MPI_Request *request)
```

```
MPI_RECV_INIT(BUF, COUNT, DATATYPE, SOURCE, TAG, COMM, REQUEST, IERROR)
<type> BUF(*)
INTEGER COUNT, DATATYPE, SOURCE, TAG, COMM, REQUEST, IERROR
```

```
MPI_Recv_init(buf, count, datatype, source, tag, comm, request, ierror)
  TYPE(*), DIMENSION(..) :: buf
  INTEGER, INTENT(IN) :: count, source, tag
  TYPE(MPI_Datatype), INTENT(IN) :: datatype
  TYPE(MPI_Comm), INTENT(IN) :: comm
  TYPE(MPI_Request), INTENT(OUT) :: request
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{MPI::Prequest MPI::Comm::Recv_init(void* buf, int count, const
  MPI::Datatype& datatype, int source, int tag) const(binding
  deprecated, see Section 15.2) }
```

Creates a persistent communication request for a receive operation. The argument `buf` is marked as OUT because the user gives permission to write on the receive buffer by passing the argument to `MPI_RECV_INIT`.

A persistent communication request is inactive after it was created — no active communication is attached to the request.

A communication (send or receive) that uses a persistent request is initiated by the function `MPI_START`.

MPI\_START(request)

INOUT	request	communication request (handle)
-------	---------	--------------------------------

```
int MPI_Start(MPI_Request *request)
```

```
MPI_START(REQUEST, IERROR)
INTEGER REQUEST, IERROR
```

```
MPI_Start(request, ierror)
  TYPE(MPI_Request), INTENT(INOUT) :: request
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
1 {void MPI::Prequest::Start() (binding deprecated, see Section 15.2) }
```

2 The argument, `request`, is a handle returned by one of the previous five calls. The associated request should be inactive. The request becomes active once the call is made.

3 If the request is for a send with ready mode, then a matching receive should be posted before the call is made. The communication buffer should not be modified after the call, and until the operation completes.

4 The call is local, with similar semantics to the nonblocking communication operations described in Section 3.7. That is, a call to `MPI_START` with a request created by `MPI_SEND_INIT` starts a communication in the same manner as a call to `MPI_ISEND`; a call to `MPI_START` with a request created by `MPI_BSEND_INIT` starts a communication in the same manner as a call to `MPI_IBSEND`; and so on.

```
13 MPI_STARTALL(count, array_of_requests)
```

```
14 IN count list length (non-negative integer)
```

```
15 INOUT array_of_requests array of requests (array of handle)
```

```
16 int MPI_Startall(int count, MPI_Request *array_of_requests)
```

```
17 MPI_STARTALL(COUNT, ARRAY_OF_REQUESTS, IERROR)
```

```
18 INTEGER COUNT, ARRAY_OF_REQUESTS(*), IERROR
```

```
19 MPI_Startall(count, array_of_requests, ierror)
```

```
20 INTEGER, INTENT(IN) :: count
```

```
21 TYPE(MPI_Request), INTENT(INOUT) :: array_of_requests(*)
```

```
22 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
23 {static void MPI::Prequest::Startall(int count,  
24 MPI::Prequest array_of_requests[]) (binding deprecated, see  
25 Section 15.2) }
```

26 Start all communications associated with requests in `array_of_requests`. A call to `MPI_STARTALL(count, array_of_requests)` has the same effect as calls to `MPI_START (&array_of_requests[i])`, executed for  $i=0, \dots, \text{count}-1$ , in some arbitrary order.

27 A communication started with a call to `MPI_START` or `MPI_STARTALL` is completed by a call to `MPI_WAIT`, `MPI_TEST`, or one of the derived functions described in Section 3.7.5. The request becomes inactive after successful completion of such call. The request is not deallocated and it can be activated anew by an `MPI_START` or `MPI_STARTALL` call.

28 A persistent request is deallocated by a call to `MPI_REQUEST_FREE` (Section 3.7.3).

29 The call to `MPI_REQUEST_FREE` can occur at any point in the program after the persistent request was created. However, the request will be deallocated only after it becomes inactive. Active receive requests should not be freed. Otherwise, it will not be possible to check that the receive has completed. It is preferable, in general, to free requests when they are inactive. If this rule is followed, then the functions described in this section will be invoked in a sequence of the form,

```
30 Create (Start Complete)* Free
```

where \* indicates zero or more repetitions. If the same communication object is used in several concurrent threads, it is the user's responsibility to coordinate calls so that the correct sequence is obeyed.

A send operation initiated with MPI\_START can be matched with any receive operation and, likewise, a receive operation initiated with MPI\_START can receive messages generated by any send operation.

*Advice to users.* To prevent problems with the argument copying and register optimization done by Fortran compilers, please note the hints in [Sections 16.2.2-16.2.12](#), especially in [Sections 16.2.4 and 16.2.5](#) on pages 547-550 about *problems due to data copying and sequence association with subscript triplets and vector subscripts*, and in [Sections 16.2.8 to 16.2.11](#) on pages 551 to 561 about *optimization problems, code movements and register optimization*, and *temporary and permanent data movements*. (*End of advice to users.*)

### 3.10 Send-Receive

The **send-receive** operations combine in one call the sending of a message to one destination and the receiving of another message, from another process. The two (source and destination) are possibly the same. A send-receive operation is very useful for executing a shift operation across a chain of processes. If blocking sends and receives are used for such a shift, then one needs to order the sends and receives correctly (for example, even processes send, then receive, odd processes receive first, then send) so as to prevent cyclic dependencies that may lead to deadlock. When a send-receive operation is used, the communication subsystem takes care of these issues. The send-receive operation can be used in conjunction with the functions described in [Chapter 7](#) in order to perform shifts on various logical topologies. Also, a send-receive operation is useful for implementing remote procedure calls.

A message sent by a send-receive operation can be received by a regular receive operation or probed by a probe operation; a send-receive operation can receive a message sent by a regular send operation.

```

1  MPI_SENDRECV(sendbuf, sendcount, sendtype, dest, sendtag, recvbuf, recvcount, recvtype,
2      source, recvtage, comm, status)
3
4      IN      sendbuf      initial address of send buffer (choice)
5      IN      sendcount    number of elements in send buffer (non-negative integer)
6
7      IN      sendtype     type of elements in send buffer (handle)
8      IN      dest         rank of destination (integer)
9      IN      sendtag      send tag (integer)
10
11     OUT     recvbuf      initial address of receive buffer (choice)
12     IN      recvcount    number of elements in receive buffer (non-negative integer)
13
14     IN      recvtype     type of elements in receive buffer (handle)
15     IN      source       rank of source or MPI_ANY_SOURCE (integer)
16     IN      recvtage     receive tag or MPI_ANY_TAG (integer)
17     IN      comm         communicator (handle)
18     OUT     status       status object (Status)
19
20
21
22  int MPI_Sendrecv(void *sendbuf, int sendcount, MPI_Datatype sendtype,
23      int dest, int sendtag, void *recvbuf, int recvcount,
24      MPI_Datatype recvtype, int source, int recvtage, MPI_Comm comm,
25      MPI_Status *status)
26
27  MPI_SENDRECV(SENDBUF, SENDCOUNT, SENDTYPE, DEST, SENDTAG, RECVBUF,
28      RECVCOUNT, RECVTYPE, SOURCE, RECVTAG, COMM, STATUS, IERROR)
29  <type> SENDBUF(*), RECVBUF(*)
30  INTEGER SENDCOUNT, SENDTYPE, DEST, SENDTAG, RECVCOUNT, RECVTYPE,
31  SOURCE, RECVTAG, COMM, STATUS(MPI_STATUS_SIZE), IERROR
32
33  MPI_Sendrecv(sendbuf, sendcount, sendtype, dest, sendtag, recvbuf,
34      recvcount, recvtype, source, recvtage, comm, status, ierror)
35  TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
36  INTEGER, INTENT(IN) :: sendcount, dest, sendtag, recvcount, source,
37      recvtage
38  TYPE(MPI_Datatype), INTENT(IN) :: sendtype, recvtype
39  TYPE(MPI_Comm), INTENT(IN) :: comm
40  TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
41  INTEGER, OPTIONAL, INTENT(OUT) :: ierror
42
43  {void MPI::Comm::Sendrecv(const void *sendbuf, int sendcount, const
44      MPI::Datatype& sendtype, int dest, int sendtag, void *recvbuf,
45      int recvcount, const MPI::Datatype& recvtype, int source,
46      int recvtage, MPI::Status& status) const(binding deprecated, see
47      Section 15.2) }
48
49  {void MPI::Comm::Sendrecv(const void *sendbuf, int sendcount, const
50      MPI::Datatype& sendtype, int dest, int sendtag, void *recvbuf,

```

```
int recvcount, const MPI::Datatype& recvtype, int source,
int recvtag) const(binding deprecated, see Section 15.2) }
```

Execute a blocking send and receive operation. Both send and receive use the same communicator, but possibly different tags. The send buffer and receive buffers must be disjoint, and may have different lengths and datatypes.

The semantics of a send-receive operation is what would be obtained if the caller forked two concurrent threads, one to execute the send, and one to execute the receive, followed by a join of these two threads.

**MPI\_SENDRECV\_REPLACE**(buf, count, datatype, dest, sendtag, source, recvtag, comm, status)

INOUT	buf	initial address of send and receive buffer (choice)
IN	count	number of elements in send and receive buffer (non-negative integer)
IN	datatype	type of elements in send and receive buffer (handle)
IN	dest	rank of destination (integer)
IN	sendtag	send message tag (integer)
IN	source	rank of source or MPI_ANY_SOURCE (integer)
IN	recvtag	receive message tag or MPI_ANY_TAG (integer)
IN	comm	communicator (handle)
OUT	status	status object (Status)

```
int MPI_Sendrecv_replace(void* buf, int count, MPI_Datatype datatype,
int dest, int sendtag, int source, int recvtag, MPI_Comm comm,
MPI_Status *status)
```

```
MPI_SENDRECV_REPLACE(BUF, COUNT, DATATYPE, DEST, SENDTAG, SOURCE, RECVTAG,
COMM, STATUS, IERROR)
<type> BUF(*)
INTEGER COUNT, DATATYPE, DEST, SENDTAG, SOURCE, RECVTAG, COMM,
STATUS(MPI_STATUS_SIZE), IERROR
```

```
MPI_Sendrecv_replace(buf, count, datatype, dest, sendtag, source, recvtag,
comm, status, ierror)
TYPE(*), DIMENSION(..) :: buf
INTEGER, INTENT(IN) :: count, dest, sendtag, source, recvtag
TYPE(MPI_Datatype), INTENT(IN) :: datatype
TYPE(MPI_Comm), INTENT(IN) :: comm
TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Comm::Sendrecv_replace(void* buf, int count, const
MPI::Datatype& datatype, int dest, int sendtag, int source,
int recvtag, MPI::Status& status) const(binding deprecated, see
Section 15.2) }
```

```

1 {void MPI::Comm::Sendrecv_replace(void* buf, int count, const
2     MPI::Datatype& datatype, int dest, int sendtag, int source,
3     int recvtag) const(binding deprecated, see Section 15.2) }

```

Execute a blocking send and receive. The same buffer is used both for the send and for the receive, so that the message sent is replaced by the message received.

*Advice to implementors.* Additional intermediate buffering is needed for the “replace” variant. (*End of advice to implementors.*)

### 3.11 Null Processes

In many instances, it is convenient to specify a “dummy” source or destination for communication. This simplifies the code that is needed for dealing with boundaries, for example, in the case of a non-circular shift done with calls to send-receive.

The special value `MPI_PROC_NULL` can be used instead of a rank wherever a source or a destination argument is required in a call. A communication with process `MPI_PROC_NULL` has no effect. A send to `MPI_PROC_NULL` succeeds and returns as soon as possible. A receive from `MPI_PROC_NULL` succeeds and returns as soon as possible with no modifications to the receive buffer. When a receive with `source = MPI_PROC_NULL` is executed then the status object returns `source = MPI_PROC_NULL`, `tag = MPI_ANY_TAG` and `count = 0`.



# Chapter 4

## Datatypes

Basic datatypes were introduced in Section 3.2.2 Message Data on page 29 and in Section 3.3 Data Type Matching and Data Conversion on page 38. In this chapter, this model is extended to describe any data layout. We consider general datatypes that allow one to transfer efficiently heterogeneous and noncontiguous data. We conclude with the description of calls for explicit packing and unpacking of messages.

### 4.1 Derived Datatypes

Up to here, all point to point communication have involved only buffers containing a sequence of identical basic datatypes. This is too constraining on two accounts. One often wants to pass messages that contain values with different datatypes (e.g., an integer count, followed by a sequence of real numbers); and one often wants to send noncontiguous data (e.g., a sub-block of a matrix). One solution is to pack noncontiguous data into a contiguous buffer at the sender site and unpack it at the receiver site. This has the disadvantage of requiring additional memory-to-memory copy operations at both sites, even when the communication subsystem has scatter-gather capabilities. Instead, MPI provides mechanisms to specify more general, mixed, and noncontiguous communication buffers. It is up to the implementation to decide whether data should be first packed in a contiguous buffer before being transmitted, or whether it can be collected directly from where it resides.

The general mechanisms provided here allow one to transfer directly, without copying, objects of various shape and size. It is not assumed that the MPI library is cognizant of the objects declared in the host language. Thus, if one wants to transfer a structure, or an array section, it will be necessary to provide in MPI a definition of a communication buffer that mimics the definition of the structure or array section in question. These facilities can be used by library designers to define communication functions that can transfer objects defined in the host language — by decoding their definitions as available in a symbol table or a dope vector. Such higher-level communication functions are not part of MPI.

More general communication buffers are specified by replacing the basic datatypes that have been used so far with derived datatypes that are constructed from basic datatypes using the constructors described in this section. These methods of constructing derived datatypes can be applied recursively.

A **general datatype** is an opaque object that specifies two things:

- A sequence of basic datatypes

- A sequence of integer (byte) displacements

The displacements are not required to be positive, distinct, or in increasing order. Therefore, the order of items need not coincide with their order in store, and an item may appear more than once. We call such a pair of sequences (or sequence of pairs) a **type map**. The sequence of basic datatypes (displacements ignored) is the **type signature** of the datatype.

Let

$$Typemap = \{(type_0, disp_0), \dots, (type_{n-1}, disp_{n-1})\},$$

be such a type map, where  $type_i$  are basic types, and  $disp_i$  are displacements. Let

$$Typesig = \{type_0, \dots, type_{n-1}\}$$

be the associated type signature. This type map, together with a base address  $buf$ , specifies a communication buffer: the communication buffer that consists of  $n$  entries, where the  $i$ -th entry is at address  $buf + disp_i$  and has type  $type_i$ . A message assembled from such a communication buffer will consist of  $n$  values, of the types defined by  $Typesig$ .

Most datatype constructors have replication count or block length arguments. Allowed values are non-negative integers. If the value is zero, no elements are generated in the type map and there is no effect on datatype bounds or extent.

We can use a handle to a general datatype as an argument in a send or receive operation, instead of a basic datatype argument. The operation `MPI_SEND(buf, 1, datatype,...)` will use the send buffer defined by the base address `buf` and the general datatype associated with `datatype`; it will generate a message with the type signature determined by the `datatype` argument. `MPI_RECV(buf, 1, datatype,...)` will use the receive buffer defined by the base address `buf` and the general datatype associated with `datatype`.

General datatypes can be used in all send and receive operations. We discuss, in Section 4.1.11, the case where the second argument `count` has value  $> 1$ .

The basic datatypes presented in Section 3.2.2 are particular cases of a general datatype, and are predefined. Thus, `MPI_INT` is a predefined handle to a datatype with type map  $\{(int, 0)\}$ , with one entry of type `int` and displacement zero. The other basic datatypes are similar.

The **extent** of a datatype is defined to be the span from the first byte to the last byte occupied by entries in this datatype, rounded up to satisfy alignment requirements. That is, if

$$Typemap = \{(type_0, disp_0), \dots, (type_{n-1}, disp_{n-1})\},$$

then

$$\begin{aligned} lb(Typemap) &= \min_j disp_j, \\ ub(Typemap) &= \max_j (disp_j + sizeof(type_j)) + \epsilon, \text{ and} \\ extent(Typemap) &= ub(Typemap) - lb(Typemap). \end{aligned} \tag{4.1}$$

If  $type_i$  requires alignment to a byte address that is a multiple of  $k_i$ , then  $\epsilon$  is the least non-negative increment needed to round  $extent(Typemap)$  to the next multiple of  $\max_i k_i$ . The complete definition of **extent** is given on page 106.

**Example 4.1** Assume that  $Type = \{(double, 0), (char, 8)\}$  (a double at displacement zero, followed by a char at displacement eight). Assume, furthermore, that doubles have to be strictly aligned at addresses that are multiples of eight. Then, the extent of this datatype is 16 (9 rounded to the next multiple of 8). A datatype that consists of a character immediately followed by a double will also have an extent of 16.

*Rationale.* The definition of extent is motivated by the assumption that the amount of padding added at the end of each structure in an array of structures is the least needed to fulfill alignment constraints. More explicit control of the extent is provided in Section 4.1.6. Such explicit control is needed in cases where the assumption does not hold, for example, where union types are used. (*End of rationale.*)

#### 4.1.1 Type Constructors with Explicit Addresses

In Fortran, the functions `MPI_TYPE_CREATE_HVECTOR`, `MPI_TYPE_CREATE_HINDEXED`, `MPI_TYPE_CREATE_STRUCT`, and `MPI_GET_ADDRESS` accept arguments of type `INTEGER(KIND=MPI_ADDRESS_KIND)`, wherever arguments of type `MPI_Aint` and `MPI::Aint` are used in C and C++. On Fortran 77 systems that do not support the Fortran 90 `KIND` notation, and where addresses are 64 bits whereas default `INTEGER`s are 32 bits, these arguments will be of type `INTEGER*8`.

#### 4.1.2 Datatype Constructors

**Contiguous** The simplest datatype constructor is `MPI_TYPE_CONTIGUOUS` which allows replication of a datatype into contiguous locations.

`MPI_TYPE_CONTIGUOUS(count, oldtype, newtype)`

IN	count	replication count (non-negative integer)
IN	oldtype	old datatype (handle)
OUT	newtype	new datatype (handle)

```
int MPI_Type_contiguous(int count, MPI_Datatype oldtype,
                        MPI_Datatype *newtype)
```

```
MPI_TYPE_CONTIGUOUS(COUNT, OLDTYPE, NEWTYPE, IERROR)
INTEGER COUNT, OLDTYPE, NEWTYPE, IERROR
```

```
MPI_Type_contiguous(count, oldtype, newtype, ierror)
  INTEGER, INTENT(IN) :: count
  TYPE(MPI_Datatype), INTENT(IN) :: oldtype
  TYPE(MPI_Datatype), INTENT(OUT) :: newtype
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{MPI::Datatype MPI::Datatype::Create_contiguous(int count) const(binding
  deprecated, see Section 15.2) }
```

`newtype` is the datatype obtained by concatenating `count` copies of `oldtype`. Concatenation is defined using *extent* as the size of the concatenated copies.

**Example 4.2** Let `oldtype` have type map  $\{(\text{double}, 0), (\text{char}, 8)\}$ , with extent 16, and let `count` = 3. The type map of the datatype returned by `newtype` is

$$\{(\text{double}, 0), (\text{char}, 8), (\text{double}, 16), (\text{char}, 24), (\text{double}, 32), (\text{char}, 40)\};$$

i.e., alternating `double` and `char` elements, with displacements 0, 8, 16, 24, 32, 40.

In general, assume that the type map of `oldtype` is

$$\{(type_0, disp_0), \dots, (type_{n-1}, disp_{n-1})\},$$

with extent `ex`. Then `newtype` has a type map with `count · n` entries defined by:

$$\{(type_0, disp_0), \dots, (type_{n-1}, disp_{n-1}), (type_0, disp_0 + ex), \dots, (type_{n-1}, disp_{n-1} + ex), \\ \dots, (type_0, disp_0 + ex \cdot (\text{count} - 1)), \dots, (type_{n-1}, disp_{n-1} + ex \cdot (\text{count} - 1))\}.$$

**Vector** The function `MPI_TYPE_VECTOR` is a more general constructor that allows replication of a datatype into locations that consist of equally spaced blocks. Each block is obtained by concatenating the same number of copies of the old datatype. The spacing between blocks is a multiple of the extent of the old datatype.

`MPI_TYPE_VECTOR( count, blocklength, stride, oldtype, newtype)`

IN	count	number of blocks (non-negative integer)
IN	blocklength	number of elements in each block (non-negative integer)
IN	stride	number of elements between start of each block (integer)
IN	oldtype	old datatype (handle)
OUT	newtype	new datatype (handle)

```
int MPI_Type_vector(int count, int blocklength, int stride,
    MPI_Datatype oldtype, MPI_Datatype *newtype)
```

```
MPI_TYPE_VECTOR(COUNT, BLOCKLENGTH, STRIDE, OLDTYPE, NEWTYPE, IERROR)
INTEGER COUNT, BLOCKLENGTH, STRIDE, OLDTYPE, NEWTYPE, IERROR
```

```
MPI_Type_vector(count, blocklength, stride, oldtype, newtype, ierror)
INTEGER, INTENT(IN) :: count, blocklength, stride
TYPE(MPI_Datatype), INTENT(IN) :: oldtype
TYPE(MPI_Datatype), INTENT(OUT) :: newtype
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{MPI::Datatype MPI::Datatype::Create_vector(int count, int blocklength,
    int stride) const(binding deprecated, see Section 15.2) }
```

**Example 4.3** Assume, again, that `oldtype` has type map  $\{(\text{double}, 0), (\text{char}, 8)\}$ , with extent 16. A call to `MPI_TYPE_VECTOR( 2, 3, 4, oldtype, newtype)` will create the datatype with type map,

$$\{(\text{double}, 0), (\text{char}, 8), (\text{double}, 16), (\text{char}, 24), (\text{double}, 32), (\text{char}, 40), \\ (\text{double}, 64), (\text{char}, 72), (\text{double}, 80), (\text{char}, 88), (\text{double}, 96), (\text{char}, 104)\}.$$

That is, two blocks with three copies each of the old type, with a stride of 4 elements ( $4 \cdot 16$  bytes) between the blocks.

**Example 4.4** A call to `MPI_TYPE_VECTOR(3, 1, -2, oldtype, newtype)` will create the datatype,

$$\{(\text{double}, 0), (\text{char}, 8), (\text{double}, -32), (\text{char}, -24), (\text{double}, -64), (\text{char}, -56)\}.$$

In general, assume that `oldtype` has type map,

$$\{(type_0, disp_0), \dots, (type_{n-1}, disp_{n-1})\},$$

with extent  $ex$ . Let  $bl$  be the blocklength. The newly created datatype has a type map with  $count \cdot bl \cdot n$  entries:

$$\{(type_0, disp_0), \dots, (type_{n-1}, disp_{n-1}), \\ (type_0, disp_0 + ex), \dots, (type_{n-1}, disp_{n-1} + ex), \dots, \\ (type_0, disp_0 + (bl - 1) \cdot ex), \dots, (type_{n-1}, disp_{n-1} + (bl - 1) \cdot ex), \\ (type_0, disp_0 + stride \cdot ex), \dots, (type_{n-1}, disp_{n-1} + stride \cdot ex), \dots, \\ (type_0, disp_0 + (stride + bl - 1) \cdot ex), \dots, (type_{n-1}, disp_{n-1} + (stride + bl - 1) \cdot ex), \dots, \\ (type_0, disp_0 + stride \cdot (count - 1) \cdot ex), \dots, \\ (type_{n-1}, disp_{n-1} + stride \cdot (count - 1) \cdot ex), \dots, \\ (type_0, disp_0 + (stride \cdot (count - 1) + bl - 1) \cdot ex), \dots, \\ (type_{n-1}, disp_{n-1} + (stride \cdot (count - 1) + bl - 1) \cdot ex)\}.$$

A call to `MPI_TYPE_CONTIGUOUS(count, oldtype, newtype)` is equivalent to a call to `MPI_TYPE_VECTOR(count, 1, 1, oldtype, newtype)`, or to a call to `MPI_TYPE_VECTOR(1, count, n, oldtype, newtype)`,  $n$  arbitrary.

Hvector The function `MPI_TYPE_CREATE_HVECTOR` is identical to `MPI_TYPE_VECTOR`, except that `stride` is given in bytes, rather than in elements. The use for both types of vector constructors is illustrated in Section 4.1.14. (H stands for “heterogeneous”).

`MPI_TYPE_CREATE_HVECTOR( count, blocklength, stride, oldtype, newtype)`

IN	count	number of blocks (non-negative integer)
IN	blocklength	number of elements in each block (non-negative integer)
IN	stride	number of bytes between start of each block (integer)
IN	oldtype	old datatype (handle)
OUT	newtype	new datatype (handle)

`int MPI_Type_create_hvector(int count, int blocklength, MPI_Aint stride, MPI_Datatype oldtype, MPI_Datatype *newtype)`

`MPI_TYPE_CREATE_HVECTOR(COUNT, BLOCKLENGTH, STRIDE, OLDTYPE, NEWTYPE, IERROR)`

`INTEGER COUNT, BLOCKLENGTH, OLDTYPE, NEWTYPE, IERROR`  
`INTEGER(KIND=MPI_ADDRESS_KIND) STRIDE`

`MPI_Type_create_hvector(count, blocklength, stride, oldtype, newtype, ierror)`  
`INTEGER, INTENT(IN) :: count, blocklength`  
`INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: stride`  
`TYPE(MPI_Datatype), INTENT(IN) :: oldtype`  
`TYPE(MPI_Datatype), INTENT(OUT) :: newtype`  
`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{MPI::Datatype MPI::Datatype::Create_hvector(int count, int blocklength, MPI::Aint stride) const(binding deprecated, see Section 15.2) }`

This function replaces `MPI_TYPE_HVECTOR`, whose use is deprecated. See also Chapter 15.

Assume that `oldtype` has type map,

$$\{(type_0, disp_0), \dots, (type_{n-1}, disp_{n-1})\},$$

with extent  $ex$ . Let `bl` be the `blocklength`. The newly created datatype has a type map with `count · bl · n` entries:

$$\{(type_0, disp_0), \dots, (type_{n-1}, disp_{n-1}),$$

$$(type_0, disp_0 + ex), \dots, (type_{n-1}, disp_{n-1} + ex), \dots,$$

$$(type_0, disp_0 + (bl - 1) \cdot ex), \dots, (type_{n-1}, disp_{n-1} + (bl - 1) \cdot ex),$$

$$(type_0, disp_0 + stride), \dots, (type_{n-1}, disp_{n-1} + stride), \dots,$$

$$\begin{aligned}
& (type_0, disp_0 + stride + (bl - 1) \cdot ex), \dots, \\
& (type_{n-1}, disp_{n-1} + stride + (bl - 1) \cdot ex), \dots, \\
& (type_0, disp_0 + stride \cdot (count - 1)), \dots, (type_{n-1}, disp_{n-1} + stride \cdot (count - 1)), \dots, \\
& (type_0, disp_0 + stride \cdot (count - 1) + (bl - 1) \cdot ex), \dots, \\
& (type_{n-1}, disp_{n-1} + stride \cdot (count - 1) + (bl - 1) \cdot ex)\}.
\end{aligned}$$

**Indexed** The function `MPI_TYPE_INDEXED` allows replication of an old datatype into a sequence of blocks (each block is a concatenation of the old datatype), where each block can contain a different number of copies and have a different displacement. All block displacements are multiples of the old type extent.

`MPI_TYPE_INDEXED( count, array_of_blocklengths, array_of_displacements, oldtype, newtype)`

IN	count	number of blocks – also number of entries in array_of_displacements and array_of_blocklengths (non-negative integer)
IN	array_of_blocklengths	number of elements per block (array of non-negative integers)
IN	array_of_displacements	displacement for each block, in multiples of oldtype extent (array of integer)
IN	oldtype	old datatype (handle)
OUT	newtype	new datatype (handle)

```

int MPI_Type_indexed(int count, int *array_of_blocklengths,
                    int *array_of_displacements, MPI_Datatype oldtype,
                    MPI_Datatype *newtype)

```

```

MPI_TYPE_INDEXED(COUNT, ARRAY_OF_BLOCKLENGTHS, ARRAY_OF_DISPLACEMENTS,
                OLDTYPE, NEWTYPE, IERROR)
INTEGER COUNT, ARRAY_OF_BLOCKLENGTHS(*), ARRAY_OF_DISPLACEMENTS(*),
OLDTYPE, NEWTYPE, IERROR

```

```

MPI_Type_indexed(count, array_of_blocklengths, array_of_displacements,
                oldtype, newtype, ierror)
INTEGER, INTENT(IN) :: count, array_of_blocklengths(*),
array_of_displacements(*)
TYPE(MPI_Datatype), INTENT(IN) :: oldtype
TYPE(MPI_Datatype), INTENT(OUT) :: newtype
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

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```

1 {MPI::Datatype MPI::Datatype::Create_indexed(int count,
2         const int array_of_blocklengths[],
3         const int array_of_displacements[]) const(binding deprecated, see
4         Section 15.2) }
5
6

```

### Example 4.5

Let `oldtype` have type map  $\{(\text{double}, 0), (\text{char}, 8)\}$ , with extent 16. Let  $B = (3, 1)$  and let  $D = (4, 0)$ . A call to `MPI_TYPE_INDEXED(2, B, D, oldtype, newtype)` returns a datatype with type map,

$$\{(\text{double}, 64), (\text{char}, 72), (\text{double}, 80), (\text{char}, 88), (\text{double}, 96), (\text{char}, 104),$$

$$(\text{double}, 0), (\text{char}, 8)\}.$$

That is, three copies of the old type starting at displacement 64, and one copy starting at displacement 0.

In general, assume that `oldtype` has type map,

$$\{(type_0, disp_0), \dots, (type_{n-1}, disp_{n-1})\},$$

with extent  $ex$ . Let  $B$  be the `array_of_blocklength` argument and  $D$  be the `array_of_displacements` argument. The newly created datatype has  $n \cdot \sum_{i=0}^{\text{count}-1} B[i]$  entries:

$$\{(type_0, disp_0 + D[0] \cdot ex), \dots, (type_{n-1}, disp_{n-1} + D[0] \cdot ex), \dots,$$

$$(type_0, disp_0 + (D[0] + B[0] - 1) \cdot ex), \dots, (type_{n-1}, disp_{n-1} + (D[0] + B[0] - 1) \cdot ex), \dots,$$

$$(type_0, disp_0 + D[\text{count}-1] \cdot ex), \dots, (type_{n-1}, disp_{n-1} + D[\text{count}-1] \cdot ex), \dots,$$

$$(type_0, disp_0 + (D[\text{count}-1] + B[\text{count}-1] - 1) \cdot ex), \dots,$$

$$(type_{n-1}, disp_{n-1} + (D[\text{count}-1] + B[\text{count}-1] - 1) \cdot ex)\}.$$

A call to `MPI_TYPE_VECTOR(count, blocklength, stride, oldtype, newtype)` is equivalent to a call to `MPI_TYPE_INDEXED(count, B, D, oldtype, newtype)` where

$$D[j] = j \cdot \text{stride}, \quad j = 0, \dots, \text{count} - 1,$$

and

$$B[j] = \text{blocklength}, \quad j = 0, \dots, \text{count} - 1.$$



**Hindexed** The function `MPI_TYPE_CREATE_HINDEXED` is identical to `MPI_TYPE_INDEXED`, except that block displacements in `array_of_displacements` are specified in bytes, rather than in multiples of the `oldtype` extent.

`MPI_TYPE_CREATE_HINDEXED( count, array_of_blocklengths, array_of_displacements, oldtype, newtype)`

IN	count	number of blocks — also number of entries in <code>array_of_displacements</code> and <code>array_of_blocklengths</code> (non-negative integer)
IN	array_of_blocklengths	number of elements in each block (array of non-negative integers)
IN	array_of_displacements	byte displacement of each block (array of integer)
IN	oldtype	old datatype (handle)
OUT	newtype	new datatype (handle)

```
int MPI_Type_create_hindexed(int count, int array_of_blocklengths[],
                             MPI_Aint array_of_displacements[], MPI_Datatype oldtype,
                             MPI_Datatype *newtype)
```

```
MPI_TYPE_CREATE_HINDEXED(COUNT, ARRAY_OF_BLOCKLENGTHS,
                          ARRAY_OF_DISPLACEMENTS, OLDTYPE, NEWTYPE, IERROR)
INTEGER COUNT, ARRAY_OF_BLOCKLENGTHS(*), OLDTYPE, NEWTYPE, IERROR
INTEGER(KIND=MPI_ADDRESS_KIND) ARRAY_OF_DISPLACEMENTS(*)
```

```
MPI_Type_create_hindexed(count, array_of_blocklengths,
                          array_of_displacements, oldtype, newtype, ierror)
INTEGER, INTENT(IN) :: count, array_of_blocklengths(*)
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) ::
array_of_displacements(*)
TYPE(MPI_Datatype), INTENT(IN) :: oldtype
TYPE(MPI_Datatype), INTENT(OUT) :: newtype
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{MPI::Datatype MPI::Datatype::Create_hindexed(int count,
        const int array_of_blocklengths[],
        const MPI::Aint array_of_displacements[]) const(binding
        deprecated, see Section 15.2) }
```

This function replaces `MPI_TYPE_HINDEXED`, whose use is deprecated. See also Chapter 15.

Assume that `oldtype` has type map,

$$\{(type_0, disp_0), \dots, (type_{n-1}, disp_{n-1})\},$$

with extent *ex*. Let `B` be the `array_of_blocklength` argument and `D` be the `array_of_displacements` argument. The newly created datatype has a type map with  $n \cdot$

$\sum_{i=0}^{\text{count}-1} B[i]$  entries:

$\{(type_0, disp_0 + D[0]), \dots, (type_{n-1}, disp_{n-1} + D[0]), \dots,$   
 $(type_0, disp_0 + D[0] + (B[0] - 1) \cdot ex), \dots,$   
 $(type_{n-1}, disp_{n-1} + D[0] + (B[0] - 1) \cdot ex), \dots,$   
 $(type_0, disp_0 + D[\text{count}-1]), \dots, (type_{n-1}, disp_{n-1} + D[\text{count}-1]), \dots,$   
 $(type_0, disp_0 + D[\text{count}-1] + (B[\text{count}-1] - 1) \cdot ex), \dots,$   
 $(type_{n-1}, disp_{n-1} + D[\text{count}-1] + (B[\text{count}-1] - 1) \cdot ex)\}.$

**Indexed\_block** This function is the same as `MPI_TYPE_INDEXED` except that the block-length is the same for all blocks. There are many codes using indirect addressing arising from unstructured grids where the blocksize is always 1 (gather/scatter). The following convenience function allows for constant blocksize and arbitrary displacements.

`MPI_TYPE_CREATE_INDEXED_BLOCK(count, blocklength, array_of_displacements, oldtype, newtype)`

IN	count	length of array of displacements (non-negative integer)
IN	blocklength	size of block (non-negative integer)
IN	array_of_displacements	array of displacements (array of integer)
IN	oldtype	old datatype (handle)
OUT	newtype	new datatype (handle)

`int MPI_Type_create_indexed_block(int count, int blocklength,  
int array_of_displacements[], MPI_Datatype oldtype,  
MPI_Datatype *newtype)`

`MPI_TYPE_CREATE_INDEXED_BLOCK(COUNT, BLOCKLENGTH, ARRAY_OF_DISPLACEMENTS,  
OLDTYPE, NEWTYPE, IERROR)  
INTEGER COUNT, BLOCKLENGTH, ARRAY_OF_DISPLACEMENTS(*), OLDTYPE,  
NEWTYPE, IERROR`

`MPI_Type_create_indexed_block(count, blocklength, array_of_displacements,  
oldtype, newtype, ierror)  
INTEGER, INTENT(IN) :: count, blocklength, array_of_displacements(*)  
TYPE(MPI_Datatype), INTENT(IN) :: oldtype  
TYPE(MPI_Datatype), INTENT(OUT) :: newtype  
INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{MPI::Datatype MPI::Datatype::Create_indexed_block(int count,  
int blocklength,  
const int array_of_displacements[]) const (binding deprecated, see  
Section 15.2) }`

Struct `MPI_TYPE_STRUCT` is the most general type constructor. It further generalizes `MPI_TYPE_CREATE_HINDEXED` in that it allows each block to consist of replications of different datatypes.

`MPI_TYPE_CREATE_STRUCT(count, array_of_blocklengths, array_of_displacements, array_of_types, newtype)`

IN	count	number of blocks (non-negative integer) — also number of entries in arrays <code>array_of_types</code> , <code>array_of_displacements</code> and <code>array_of_blocklengths</code>
IN	array_of_blocklength	number of elements in each block (array of non-negative integer)
IN	array_of_displacements	byte displacement of each block (array of integer)
IN	array_of_types	type of elements in each block (array of handles to datatype objects)
OUT	newtype	new datatype (handle)

```
int MPI_Type_create_struct(int count, int array_of_blocklengths[],
                          MPI_Aint array_of_displacements[],
                          MPI_Datatype array_of_types[], MPI_Datatype *newtype)
```

```
MPI_TYPE_CREATE_STRUCT(COUNT, ARRAY_OF_BLOCKLENGTHS,
                       ARRAY_OF_DISPLACEMENTS, ARRAY_OF_TYPES, NEWTYPE, IERROR)
INTEGER COUNT, ARRAY_OF_BLOCKLENGTHS(*), ARRAY_OF_TYPES(*), NEWTYPE,
IERROR
INTEGER(KIND=MPI_ADDRESS_KIND) ARRAY_OF_DISPLACEMENTS(*)
```

```
MPI_Type_create_struct(count, array_of_blocklengths,
                      array_of_displacements, array_of_types, newtype, ierror)
INTEGER, INTENT(IN) :: count, array_of_blocklengths(*)
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) ::
array_of_displacements(*)
TYPE(MPI_Datatype), INTENT(IN) :: array_of_types(*)
TYPE(MPI_Datatype), INTENT(OUT) :: newtype
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{static MPI::Datatype MPI::Datatype::Create_struct(int count,
            const int array_of_blocklengths[], const MPI::Aint
            array_of_displacements[],
            const MPI::Datatype array_of_types[]) (binding deprecated, see
            Section 15.2) }
```

This function replaces `MPI_TYPE_STRUCT`, whose use is deprecated. See also Chapter 15.

**Example 4.6** Let `type1` have type map,

```
{(double, 0), (char, 8)},
```

with extent 16. Let  $B = (2, 1, 3)$ ,  $D = (0, 16, 26)$ , and  $T = (\text{MPI\_FLOAT}, \text{type1}, \text{MPI\_CHAR})$ . Then a call to `MPI_TYPE_STRUCT(3, B, D, T, newtype)` returns a datatype with type map,

$$\{(\text{float}, 0), (\text{float}, 4), (\text{double}, 16), (\text{char}, 24), (\text{char}, 26), (\text{char}, 27), (\text{char}, 28)\}.$$

That is, two copies of `MPI_FLOAT` starting at 0, followed by one copy of `type1` starting at 16, followed by three copies of `MPI_CHAR`, starting at 26. (We assume that a float occupies four bytes.)

In general, let  $T$  be the `array_of_types` argument, where  $T[i]$  is a handle to,

$$\text{typemap}_i = \{(\text{type}_0^i, \text{disp}_0^i), \dots, (\text{type}_{n_i-1}^i, \text{disp}_{n_i-1}^i)\},$$

with extent  $ex_i$ . Let  $B$  be the `array_of_blocklength` argument and  $D$  be the `array_of_displacements` argument. Let  $c$  be the `count` argument. Then the newly created datatype has a type map with  $\sum_{i=0}^{c-1} B[i] \cdot n_i$  entries:

$$\begin{aligned} &\{(\text{type}_0^0, \text{disp}_0^0 + D[0]), \dots, (\text{type}_{n_0}^0, \text{disp}_{n_0}^0 + D[0]), \dots, \\ &(\text{type}_0^0, \text{disp}_0^0 + D[0] + (B[0] - 1) \cdot ex_0), \dots, (\text{type}_{n_0}^0, \text{disp}_{n_0}^0 + D[0] + (B[0]-1) \cdot ex_0), \dots, \\ &(\text{type}_0^{c-1}, \text{disp}_0^{c-1} + D[c-1]), \dots, (\text{type}_{n_{c-1}-1}^{c-1}, \text{disp}_{n_{c-1}-1}^{c-1} + D[c-1]), \dots, \\ &(\text{type}_0^{c-1}, \text{disp}_0^{c-1} + D[c-1] + (B[c-1] - 1) \cdot ex_{c-1}), \dots, \\ &(\text{type}_{n_{c-1}-1}^{c-1}, \text{disp}_{n_{c-1}-1}^{c-1} + D[c-1] + (B[c-1]-1) \cdot ex_{c-1})\}. \end{aligned}$$

A call to `MPI_TYPE_CREATE_HINDEXED(count, B, D, oldtype, newtype)` is equivalent to a call to `MPI_TYPE_CREATE_STRUCT(count, B, D, T, newtype)`, where each entry of  $T$  is equal to `oldtype`.

### 4.1.3 Subarray Datatype Constructor

`MPI_TYPE_CREATE_SUBARRAY(ndims, array_of_sizes, array_of_subsizes, array_of_starts, order, oldtype, newtype)`

IN	ndims	number of array dimensions (positive integer)
IN	array_of_sizes	number of elements of type <code>oldtype</code> in each dimension of the full array (array of positive integers)
IN	array_of_subsizes	number of elements of type <code>oldtype</code> in each dimension of the subarray (array of positive integers)
IN	array_of_starts	starting coordinates of the subarray in each dimension (array of non-negative integers)
IN	order	array storage order flag (state)
IN	oldtype	array element datatype (handle)
OUT	newtype	new datatype (handle)

```
int MPI_Type_create_subarray(int ndims, int array_of_sizes[],
                           int array_of_subsizes[], int array_of_starts[], int order,
```

```

MPI_Datatype oldtype, MPI_Datatype *newtype)
MPI_TYPE_CREATE_SUBARRAY(NDIMS, ARRAY_OF_SIZES, ARRAY_OF_SUBSIZES,
    ARRAY_OF_STARTS, ORDER, OLDTYPE, NEWTYPE, IERROR)
INTEGER NDIMS, ARRAY_OF_SIZES(*), ARRAY_OF_SUBSIZES(*),
    ARRAY_OF_STARTS(*), ORDER, OLDTYPE, NEWTYPE, IERROR
MPI_Type_create_subarray(ndims, array_of_sizes, array_of_subsizes,
    array_of_starts, order, oldtype, newtype, ierror)
INTEGER, INTENT(IN) :: ndims, array_of_sizes(*), array_of_subsizes(*),
    array_of_starts(*), order
TYPE(MPI_Datatype), INTENT(IN) :: oldtype
TYPE(MPI_Datatype), INTENT(OUT) :: newtype
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
{MPI::Datatype MPI::Datatype::Create_subarray(int ndims,
    const int array_of_sizes[], const int array_of_subsizes[],
    const int array_of_starts[], int order) const(binding deprecated,
    see Section 15.2) }
```

The subarray type constructor creates an MPI datatype describing an  $n$ -dimensional subarray of an  $n$ -dimensional array. The subarray may be situated anywhere within the full array, and may be of any nonzero size up to the size of the larger array as long as it is confined within this array. This type constructor facilitates creating filetypes to access arrays distributed in blocks among processes to a single file that contains the global array, see MPI I/O, especially Section 13.1.1 on page 445.

This type constructor can handle arrays with an arbitrary number of dimensions and works for both C and Fortran ordered matrices (i.e., row-major or column-major). Note that a C program may use Fortran order and a Fortran program may use C order.

The `ndims` parameter specifies the number of dimensions in the full data array and gives the number of elements in `array_of_sizes`, `array_of_subsizes`, and `array_of_starts`.

The number of elements of type `oldtype` in each dimension of the  $n$ -dimensional array and the requested subarray are specified by `array_of_sizes` and `array_of_subsizes`, respectively. For any dimension  $i$ , it is erroneous to specify `array_of_subsizes[i] < 1` or `array_of_subsizes[i] > array_of_sizes[i]`.

The `array_of_starts` contains the starting coordinates of each dimension of the subarray. Arrays are assumed to be indexed starting from zero. For any dimension  $i$ , it is erroneous to specify `array_of_starts[i] < 0` or `array_of_starts[i] > (array_of_sizes[i] - array_of_subsizes[i])`.

*Advice to users.* In a Fortran program with arrays indexed starting from 1, if the starting coordinate of a particular dimension of the subarray is  $n$ , then the entry in `array_of_starts` for that dimension is  $n-1$ . (*End of advice to users.*)

The `order` argument specifies the storage order for the subarray as well as the full array. It must be set to one of the following:

**MPI\_ORDER\_C** The ordering used by C arrays, (i.e., row-major order)

**MPI\_ORDER\_FORTRAN** The ordering used by Fortran arrays, (i.e., column-major order)

A  $ndims$ -dimensional subarray (*newtype*) with no extra padding can be defined by the function `Subarray()` as follows:

```
newtype = Subarray(ndims, {size0, size1, ..., sizendims-1},
                  {subsize0, subsize1, ..., subsizendims-1},
                  {start0, start1, ..., startndims-1}, oldtype)
```

Let the *typemap* of *oldtype* have the form:

$$\{(type_0, disp_0), (type_1, disp_1), \dots, (type_{n-1}, disp_{n-1})\}$$

where  $type_i$  is a predefined MPI datatype, and let  $ex$  be the extent of *oldtype*. Then we define the `Subarray()` function recursively using the following three equations. Equation 4.2 defines the base step. Equation 4.3 defines the recursion step when `order = MPI_ORDER_FORTRAN`, and Equation 4.4 defines the recursion step when `order = MPI_ORDER_C`.

$$\text{Subarray}(1, \{size_0\}, \{subsize_0\}, \{start_0\}, \quad (4.2)$$

$$\{(type_0, disp_0), (type_1, disp_1), \dots, (type_{n-1}, disp_{n-1})\})$$

$$= \{(MPI\_LB, 0),$$

$$(type_0, disp_0 + start_0 \times ex), \dots, (type_{n-1}, disp_{n-1} + start_0 \times ex),$$

$$(type_0, disp_0 + (start_0 + 1) \times ex), \dots, (type_{n-1},$$

$$disp_{n-1} + (start_0 + 1) \times ex), \dots,$$

$$(type_0, disp_0 + (start_0 + subsize_0 - 1) \times ex), \dots,$$

$$(type_{n-1}, disp_{n-1} + (start_0 + subsize_0 - 1) \times ex),$$

$$(MPI\_UB, size_0 \times ex)\}$$

$$\text{Subarray}(ndims, \{size_0, size_1, \dots, size_{ndims-1}\}, \quad (4.3)$$

$$\{subsize_0, subsize_1, \dots, subsize_{ndims-1}\},$$

$$\{start_0, start_1, \dots, start_{ndims-1}\}, oldtype)$$

$$= \text{Subarray}(ndims - 1, \{size_1, size_2, \dots, size_{ndims-1}\},$$

$$\{subsize_1, subsize_2, \dots, subsize_{ndims-1}\},$$

$$\{start_1, start_2, \dots, start_{ndims-1}\},$$

$$\text{Subarray}(1, \{size_0\}, \{subsize_0\}, \{start_0\}, oldtype))$$

$$\text{Subarray}(ndims, \{size_0, size_1, \dots, size_{ndims-1}\}, \quad (4.4)$$

$$\{subsize_0, subsize_1, \dots, subsize_{ndims-1}\},$$

$$\{start_0, start_1, \dots, start_{ndims-1}\}, oldtype)$$

$$= \text{Subarray}(ndims - 1, \{size_0, size_1, \dots, size_{ndims-2}\},$$

$$\{subsize_0, subsize_1, \dots, subsize_{ndims-2}\},$$

$$\{start_0, start_1, \dots, start_{ndims-2}\},$$

$$\text{Subarray}(1, \{size_{ndims-1}\}, \{subsize_{ndims-1}\}, \{start_{ndims-1}\}, oldtype))$$

For an example use of `MPI_TYPE_CREATE_SUBARRAY` in the context of I/O see Section 13.9.2.

## 4.1.4 Distributed Array Datatype Constructor

The distributed array type constructor supports HPF-like [37] data distributions. However, unlike in HPF, the storage order may be specified for C arrays as well as for Fortran arrays.

*Advice to users.* One can create an HPF-like file view using this type constructor as follows. Complementary filetypes are created by having every process of a group call this constructor with identical arguments (with the exception of `rank` which should be set appropriately). These filetypes (along with identical `disp` and `etype`) are then used to define the view (via `MPI_FILE_SET_VIEW`), see MPI I/O, especially Section 13.1.1 on page 445 and Section 13.3 on page 458. Using this view, a collective data access operation (with identical offsets) will yield an HPF-like distribution pattern. (*End of advice to users.*)

```
MPI_TYPE_CREATE_DARRAY(size, rank, ndims, array_of_gsizes, array_of_distribs,
                        array_of_dargs, array_of_psize, order, oldtype, newtype)
```

IN	size	size of process group (positive integer)
IN	rank	rank in process group (non-negative integer)
IN	ndims	number of array dimensions as well as process grid dimensions (positive integer)
IN	array_of_gsizes	number of elements of type <code>oldtype</code> in each dimension of global array (array of positive integers)
IN	array_of_distribs	distribution of array in each dimension (array of state)
IN	array_of_dargs	distribution argument in each dimension (array of positive integers)
IN	array_of_psize	size of process grid in each dimension (array of positive integers)
IN	order	array storage order flag (state)
IN	oldtype	old datatype (handle)
OUT	newtype	new datatype (handle)

```
int MPI_Type_create_darray(int size, int rank, int ndims,
                           int array_of_gsizes[], int array_of_distribs[], int
                           array_of_dargs[], int array_of_psize[], int order,
                           MPI_Datatype oldtype, MPI_Datatype *newtype)
```

```
MPI_TYPE_CREATE_DARRAY(SIZE, RANK, NDIMS, ARRAY_OF_GSIZES,
                        ARRAY_OF_DISTRIBS, ARRAY_OF_DARGS, ARRAY_OF_PSIZE, ORDER,
                        OLDTYPE, NEWTYPE, IERROR)
INTEGER SIZE, RANK, NDIMS, ARRAY_OF_GSIZES(*), ARRAY_OF_DISTRIBS(*),
ARRAY_OF_DARGS(*), ARRAY_OF_PSIZE(*), ORDER, OLDTYPE, NEWTYPE, IERROR
```

```
MPI_Type_create_darray(size, rank, ndims, array_of_gsizes,
                        array_of_distribs, array_of_dargs, array_of_psize, order,
                        oldtype, newtype, ierror)
```

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```

1  INTEGER, INTENT(IN) :: size, rank, ndims, array_of_gsizes(*),
2  array_of_distribs(*), array_of_dargs(*), array_of_psize(*), order
3  TYPE(MPI_Datatype), INTENT(IN) :: oldtype
4  TYPE(MPI_Datatype), INTENT(OUT) :: newtype
5  INTEGER, OPTIONAL, INTENT(OUT) :: ierror
6
7  {MPI::Datatype MPI::Datatype::Create_darray(int size, int rank, int ndims,
8      const int array_of_gsizes[], const int array_of_distribs[],
9      const int array_of_dargs[], const int array_of_psize[],
10     int order) const(binding deprecated, see Section 15.2) }

```

MPI\_TYPE\_CREATE\_DARRAY can be used to generate the datatypes corresponding to the distribution of an  $ndims$ -dimensional array of `oldtype` elements onto an  $ndims$ -dimensional grid of logical processes. Unused dimensions of `array_of_psize` should be set to 1. (See Example 4.7, page 103.) For a call to MPI\_TYPE\_CREATE\_DARRAY to be correct, the equation  $\prod_{i=0}^{ndims-1} array\_of\_psize[i] = size$  must be satisfied. The ordering of processes in the process grid is assumed to be row-major, as in the case of virtual Cartesian process topologies.

*Advice to users.* For both Fortran and C arrays, the ordering of processes in the process grid is assumed to be row-major. This is consistent with the ordering used in virtual Cartesian process topologies in MPI. To create such virtual process topologies, or to find the coordinates of a process in the process grid, etc., users may use the corresponding process topology functions, see Chapter 7 on page 289. (*End of advice to users.*)

Each dimension of the array can be distributed in one of three ways:

- MPI\_DISTRIBUTE\_BLOCK - Block distribution
- MPI\_DISTRIBUTE\_CYCLIC - Cyclic distribution
- MPI\_DISTRIBUTE\_NONE - Dimension not distributed.

The constant MPI\_DISTRIBUTE\_DFLT\_DARG specifies a default distribution argument. The distribution argument for a dimension that is not distributed is ignored. For any dimension  $i$  in which the distribution is MPI\_DISTRIBUTE\_BLOCK, it is erroneous to specify `array_of_dargs[i] * array_of_psize[i] < array_of_gsize[i]`.

For example, the HPF layout `ARRAY(CYCLIC(15))` corresponds to MPI\_DISTRIBUTE\_CYCLIC with a distribution argument of 15, and the HPF layout `ARRAY(BLOCK)` corresponds to MPI\_DISTRIBUTE\_BLOCK with a distribution argument of MPI\_DISTRIBUTE\_DFLT\_DARG.

The `order` argument is used as in MPI\_TYPE\_CREATE\_SUBARRAY to specify the storage order. Therefore, arrays described by this type constructor may be stored in Fortran (column-major) or C (row-major) order. Valid values for `order` are MPI\_ORDER\_FORTRAN and MPI\_ORDER\_C.

This routine creates a new MPI datatype with a typemap defined in terms of a function called “cyclic()” (see below).



Without loss of generality, it suffices to define the typemap for the MPI\_DISTRIBUTE\_CYCLIC case where MPI\_DISTRIBUTE\_DFLT\_DARG is not used.

MPI\_DISTRIBUTE\_BLOCK and MPI\_DISTRIBUTE\_NONE can be reduced to the MPI\_DISTRIBUTE\_CYCLIC case for dimension  $i$  as follows.

MPI\_DISTRIBUTE\_BLOCK with `array_of_dargs[i]` equal to MPI\_DISTRIBUTE\_DFLT\_DARG is equivalent to MPI\_DISTRIBUTE\_CYCLIC with `array_of_dargs[i]` set to

$$(\text{array\_of\_gsizes}[i] + \text{array\_of\_psizes}[i] - 1) / \text{array\_of\_psizes}[i].$$

If `array_of_dargs[i]` is not MPI\_DISTRIBUTE\_DFLT\_DARG, then MPI\_DISTRIBUTE\_BLOCK and MPI\_DISTRIBUTE\_CYCLIC are equivalent.

MPI\_DISTRIBUTE\_NONE is equivalent to MPI\_DISTRIBUTE\_CYCLIC with `array_of_dargs[i]` set to `array_of_gsizes[i]`.

Finally, MPI\_DISTRIBUTE\_CYCLIC with `array_of_dargs[i]` equal to MPI\_DISTRIBUTE\_DFLT\_DARG is equivalent to MPI\_DISTRIBUTE\_CYCLIC with `array_of_dargs[i]` set to 1.

For MPI\_ORDER\_FORTRAN, an `ndims`-dimensional distributed array (`newtype`) is defined by the following code fragment:

```
oldtype[0] = oldtype;
for ( i = 0; i < ndims; i++ ) {
    oldtype[i+1] = cyclic(array_of_dargs[i],
                        array_of_gsizes[i],
                        r[i],
                        array_of_psizes[i],
                        oldtype[i]);
}
newtype = oldtype[ndims];
```

For MPI\_ORDER\_C, the code is:

```
oldtype[0] = oldtype;
for ( i = 0; i < ndims; i++ ) {
    oldtype[i + 1] = cyclic(array_of_dargs[ndims - i - 1],
                        array_of_gsizes[ndims - i - 1],
                        r[ndims - i - 1],
                        array_of_psizes[ndims - i - 1],
                        oldtype[i]);
}
newtype = oldtype[ndims];
```

where  $r[i]$  is the position of the process (with rank `rank`) in the process grid at dimension  $i$ . The values of  $r[i]$  are given by the following code fragment:

```
t_rank = rank;
t_size = 1;
for ( i = 0; i < ndims; i++ )
    t_size *= array_of_psizes[i];
```

```

1      for (i = 0; i < ndims; i++) {
2          t_size = t_size / array_of_psize[i];
3          r[i] = t_rank / t_size;
4          t_rank = t_rank % t_size;
5      }

```

Let the typemap of oldtype have the form:

$$\{(type_0, disp_0), (type_1, disp_1), \dots, (type_{n-1}, disp_{n-1})\}$$

where  $type_i$  is a predefined MPI datatype, and let  $ex$  be the extent of oldtype.

Given the above, the function `cyclic()` is defined as follows:

```

12      cyclic(darg, gsize, r, psize, oldtype)
13      =  {(MPI_LB, 0),
14          (type_0, disp_0 + r × darg × ex), ...,
15          (type_{n-1}, disp_{n-1} + r × darg × ex),
16          (type_0, disp_0 + (r × darg + 1) × ex), ...,
17          (type_{n-1}, disp_{n-1} + (r × darg + 1) × ex),
18          ...
19          (type_0, disp_0 + ((r + 1) × darg - 1) × ex), ...,
20          (type_{n-1}, disp_{n-1} + ((r + 1) × darg - 1) × ex),
21          ...
22          (type_0, disp_0 + r × darg × ex + psize × darg × ex), ...,
23          (type_{n-1}, disp_{n-1} + r × darg × ex + psize × darg × ex),
24          (type_0, disp_0 + (r × darg + 1) × ex + psize × darg × ex), ...,
25          (type_{n-1}, disp_{n-1} + (r × darg + 1) × ex + psize × darg × ex),
26          ...
27          (type_0, disp_0 + ((r + 1) × darg - 1) × ex + psize × darg × ex), ...,
28          (type_{n-1}, disp_{n-1} + ((r + 1) × darg - 1) × ex + psize × darg × ex),
29          ...
30          (type_0, disp_0 + r × darg × ex + psize × darg × ex × (count - 1)), ...,
31          (type_{n-1}, disp_{n-1} + r × darg × ex + psize × darg × ex × (count - 1)),
32          (type_0, disp_0 + (r × darg + 1) × ex + psize × darg × ex × (count - 1)), ...,
33          (type_{n-1}, disp_{n-1} + (r × darg + 1) × ex
34              + psize × darg × ex × (count - 1)),
35          ...
36          (type_0, disp_0 + (r × darg + darg_{last} - 1) × ex
37              + psize × darg × ex × (count - 1)), ...,
38          (type_{n-1}, disp_{n-1} + (r × darg + darg_{last} - 1) × ex
39              + psize × darg × ex × (count - 1)),
40          (MPI_UB, gsize × ex)}

```

where  $count$  is defined by this code fragment:

```

nblocks = (gsize + (darg - 1)) / darg;
count = nblocks / psize;
left_over = nblocks - count * psize;
if (r < left_over)
    count = count + 1;

```

Here, *nblocks* is the number of blocks that must be distributed among the processors. Finally, *darg<sub>last</sub>* is defined by this code fragment:

```

if ((num_in_last_cyclic = gsize % (psize * darg)) == 0)
    darg_last = darg;
else
    darg_last = num_in_last_cyclic - darg * r;
    if (darg_last > darg)
        darg_last = darg;
    if (darg_last <= 0)
        darg_last = darg;

```

**Example 4.7** Consider generating the filetypes corresponding to the HPF distribution:

```

<oldtype> FILEARRAY(100, 200, 300)
!HPF$ PROCESSORS PROCESSES(2, 3)
!HPF$ DISTRIBUTE FILEARRAY(CYCLIC(10), *, BLOCK) ONTO PROCESSES

```

This can be achieved by the following Fortran code, assuming there will be six processes attached to the run:

```

ndims = 3
array_of_gsizes(1) = 100
array_of_distrib(1) = MPI_DISTRIBUTE_CYCLIC
array_of_dargs(1) = 10
array_of_gsizes(2) = 200
array_of_distrib(2) = MPI_DISTRIBUTE_NONE
array_of_dargs(2) = 0
array_of_gsizes(3) = 300
array_of_distrib(3) = MPI_DISTRIBUTE_BLOCK
array_of_dargs(3) = MPI_DISTRIBUTE_DFLT_DARG
array_of_psize(1) = 2
array_of_psize(2) = 1
array_of_psize(3) = 3
call MPI_COMM_SIZE(MPI_COMM_WORLD, size, ierr)
call MPI_COMM_RANK(MPI_COMM_WORLD, rank, ierr)
call MPI_TYPE_CREATE_DARRAY(size, rank, ndims, array_of_gsizes, &
    array_of_distrib, array_of_dargs, array_of_psize, &
    MPI_ORDER_FORTRAN, oldtype, newtype, ierr)

```

#### 4.1.5 Address and Size Functions

The displacements in a general datatype are relative to some initial buffer address. **Absolute addresses** can be substituted for these displacements: we treat them as displacements

relative to “address zero,” the start of the address space. This initial address zero is indicated by the constant `MPI_BOTTOM`. Thus, a datatype can specify the absolute address of the entries in the communication buffer, in which case the `buf` argument is passed the value `MPI_BOTTOM`.

The address of a location in memory can be found by invoking the function `MPI_GET_ADDRESS`.

`MPI_GET_ADDRESS(location, address)`

IN	location	location in caller memory (choice)
OUT	address	address of location (integer)

`int MPI_Get_address(void *location, MPI_Aint *address)`

`MPI_GET_ADDRESS(LOCATION, ADDRESS, IERROR)`

`<type> LOCATION(*)`

`INTEGER IERROR`

`INTEGER(KIND=MPI_ADDRESS_KIND) ADDRESS`

`MPI_Get_address(location, address, ierror)`

`TYPE(*), DIMENSION(..) :: location`

`INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: address`

`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{MPI::Aint MPI::Get_address(void* location) (binding deprecated, see Section 15.2)}`

This function replaces `MPI_ADDRESS`, whose use is deprecated. See also Chapter 15. Returns the (byte) address of location.

*Advice to users.* Current Fortran MPI codes will run unmodified, and will port to any system. However, they may fail if addresses larger than  $2^{32} - 1$  are used in the program. New codes should be written so that they use the new functions. This provides compatibility with C/C++ and avoids errors on 64 bit architectures. However, such newly written codes may need to be (slightly) rewritten to port to old Fortran 77 environments that do not support `KIND` declarations. (*End of advice to users.*)

**Example 4.8** Using `MPI_GET_ADDRESS` for an array.

```
REAL A(100,100)
INTEGER(KIND=MPI_ADDRESS_KIND) I1, I2, DIFF
CALL MPI_GET_ADDRESS(A(1,1), I1, IERROR)
CALL MPI_GET_ADDRESS(A(10,10), I2, IERROR)
DIFF = I2 - I1
! The value of DIFF is 909*sizeofreal; the values of I1 and I2 are
! implementation dependent.
```

*Advice to users.* C users may be tempted to avoid the usage of `MPI_GET_ADDRESS` and rely on the availability of the address operator `&`. Note, however, that `& cast-expression` is a pointer, not an address. ISO C does not require that the value of a pointer (or the pointer cast to `int`) be the absolute address of the object pointed at — although this is commonly the case. Furthermore, referencing may not have a unique definition on machines with a segmented address space. The use of `MPI_GET_ADDRESS` to “reference” C variables guarantees portability to such machines as well. (*End of advice to users.*)

*Advice to users.* To prevent problems with the argument copying and register optimization done by Fortran compilers, please note the hints in [Sections 16.2.2-16.2.12](#), especially in [Sections 16.2.4 and 16.2.5](#) on pages 547-550 about *problems due to data copying and sequence association with subscript triplets and vector subscripts*, and in [Sections 16.2.8 to 16.2.11](#) on pages 551 to 561 about *optimization problems, code movements and register optimization*, and *temporary and permanent data movements*. (*End of advice to users.*)

The following auxiliary function provides useful information on derived datatypes.

`MPI_TYPE_SIZE(datatype, size)`

IN	datatype	datatype (handle)
OUT	size	datatype size (integer)

`int MPI_Type_size(MPI_Datatype datatype, int *size)`

`MPI_TYPE_SIZE(DATATYPE, SIZE, IERROR)`

`INTEGER DATATYPE, SIZE, IERROR`

`MPI_Type_size(datatype, size, ierror)`

`TYPE(MPI_Datatype), INTENT(IN) :: datatype`

`INTEGER, INTENT(OUT) :: size`

`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{int MPI::Datatype::Get_size() const(binding deprecated, see Section 15.2) }`

`MPI_TYPE_SIZE` returns the total size, in bytes, of the entries in the type signature associated with `datatype`; i.e., the total size of the data in a message that would be created with this datatype. Entries that occur multiple times in the datatype are counted with their multiplicity.

#### 4.1.6 Lower-Bound and Upper-Bound Markers

It is often convenient to define explicitly the lower bound and upper bound of a type map, and override the definition given on page 106. This allows one to define a datatype that has “holes” at its beginning or its end, or a datatype with entries that extend above the upper bound or below the lower bound. Examples of such usage are provided in [Section 4.1.14](#). Also, the user may want to override the alignment rules that are used to compute upper bounds and extents. E.g., a C compiler may allow the user to override default alignment

rules for some of the structures within a program. The user has to specify explicitly the bounds of the datatypes that match these structures.

To achieve this, we add two additional “pseudo-datatypes,” `MPI_LB` and `MPI_UB`, that can be used, respectively, to mark the lower bound or the upper bound of a datatype. These pseudo-datatypes occupy no space ( $\text{extent}(\text{MPI\_LB}) = \text{extent}(\text{MPI\_UB}) = 0$ ). They do not affect the size or count of a datatype, and do not affect the content of a message created with this datatype. However, they do affect the definition of the extent of a datatype and, therefore, affect the outcome of a replication of this datatype by a datatype constructor.

**Example 4.9** Let  $D = (-3, 0, 6)$ ;  $T = (\text{MPI\_LB}, \text{MPI\_INT}, \text{MPI\_UB})$ , and  $B = (1, 1, 1)$ . Then a call to `MPI_TYPE_STRUCT(3, B, D, T, type1)` creates a new datatype that has an extent of 9 (from -3 to 5, 5 included), and contains an integer at displacement 0. This is the datatype defined by the sequence  $\{(\text{lb}, -3), (\text{int}, 0), (\text{ub}, 6)\}$ . If this type is replicated twice by a call to `MPI_TYPE_CONTIGUOUS(2, type1, type2)` then the newly created type can be described by the sequence  $\{(\text{lb}, -3), (\text{int}, 0), (\text{int}, 9), (\text{ub}, 15)\}$ . (An entry of type `ub` can be deleted if there is another entry of type `ub` with a higher displacement; an entry of type `lb` can be deleted if there is another entry of type `lb` with a lower displacement.)

In general, if

$$\text{Typemap} = \{(\text{type}_0, \text{disp}_0), \dots, (\text{type}_{n-1}, \text{disp}_{n-1})\},$$

then the **lower bound** of *Typemap* is defined to be

$$\text{lb}(\text{Typemap}) = \begin{cases} \min_j \text{disp}_j & \text{if no entry has basic type lb} \\ \min_j \{\text{disp}_j \text{ such that } \text{type}_j = \text{lb}\} & \text{otherwise} \end{cases}$$

Similarly, the **upper bound** of *Typemap* is defined to be

$$\text{ub}(\text{Typemap}) = \begin{cases} \max_j \text{disp}_j + \text{sizeof}(\text{type}_j) + \epsilon & \text{if no entry has basic type ub} \\ \max_j \{\text{disp}_j \text{ such that } \text{type}_j = \text{ub}\} & \text{otherwise} \end{cases}$$

Then

$$\text{extent}(\text{Typemap}) = \text{ub}(\text{Typemap}) - \text{lb}(\text{Typemap})$$

If  $\text{type}_i$  requires alignment to a byte address that is a multiple of  $k_i$ , then  $\epsilon$  is the least non-negative increment needed to round  $\text{extent}(\text{Typemap})$  to the next multiple of  $\max_i k_i$ .

The formal definitions given for the various datatype constructors apply now, with the amended definition of **extent**.

#### 4.1.7 Extent and Bounds of Datatypes

The following function replaces the three functions `MPI_TYPE_UB`, `MPI_TYPE_LB` and `MPI_TYPE_EXTENT`. It also returns address sized integers, in the Fortran binding. The use of `MPI_TYPE_UB`, `MPI_TYPE_LB` and `MPI_TYPE_EXTENT` is deprecated.

`MPI_TYPE_GET_EXTENT(datatype, lb, extent)`

IN	datatype	datatype to get information on (handle)
OUT	lb	lower bound of datatype (integer)
OUT	extent	extent of datatype (integer)

```

int MPI_Type_get_extent(MPI_Datatype datatype, MPI_Aint *lb,
                        MPI_Aint *extent)
MPI_TYPE_GET_EXTENT(DATATYPE, LB, EXTENT, IERROR)
    INTEGER DATATYPE, IERROR
    INTEGER(KIND = MPI_ADDRESS_KIND) LB, EXTENT
MPI_Type_get_extent(datatype, lb, extent, ierror)
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: lb, extent
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
{void MPI::Datatype::Get_extent(MPI::Aint& lb, MPI::Aint& extent)
    const(binding deprecated, see Section 15.2) }
```

Returns the lower bound and the extent of `datatype` (as defined in Section 4.1.6 on page 105).

MPI allows one to change the extent of a datatype, using lower bound and upper bound markers (`MPI_LB` and `MPI_UB`). This is useful, as it allows to control the stride of successive datatypes that are replicated by datatype constructors, or are replicated by the `count` argument in a send or receive call. However, the current mechanism for achieving it is painful; also it is restrictive. `MPI_LB` and `MPI_UB` are “sticky”: once present in a datatype, they cannot be overridden (e.g., the upper bound can be moved up, by adding a new `MPI_UB` marker, but cannot be moved down below an existing `MPI_UB` marker). A new type constructor is provided to facilitate these changes. The use of `MPI_LB` and `MPI_UB` is deprecated.

```

MPI_TYPE_CREATE_RESIZED(oldtype, lb, extent, newtype)
    IN      oldtype      input datatype (handle)
    IN      lb           new lower bound of datatype (integer)
    IN      extent       new extent of datatype (integer)
    OUT     newtype      output datatype (handle)
int MPI_Type_create_resized(MPI_Datatype oldtype, MPI_Aint lb, MPI_Aint
                           extent, MPI_Datatype *newtype)
MPI_TYPE_CREATE_RESIZED(OLDTYPE, LB, EXTENT, NEWTYPE, IERROR)
    INTEGER OLDTYPE, NEWTYPE, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) LB, EXTENT
MPI_Type_create_resized(oldtype, lb, extent, newtype, ierror)
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: lb, extent
    TYPE(MPI_Datatype), INTENT(IN) :: oldtype
    TYPE(MPI_Datatype), INTENT(OUT) :: newtype
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
{MPI::Datatype MPI::Datatype::Create_resized(const MPI::Aint lb,
                                              const MPI::Aint extent) const(binding deprecated, see Section 15.2) }
```

Returns in `newtype` a handle to a new datatype that is identical to `oldtype`, except that the lower bound of this new datatype is set to be `lb`, and its upper bound is set to be `lb + extent`. Any previous `lb` and `ub` markers are erased, and a new pair of lower bound and upper bound markers are put in the positions indicated by the `lb` and `extent` arguments. This affects the behavior of the datatype when used in communication operations, with `count > 1`, and when used in the construction of new derived datatypes.

*Advice to users.* It is strongly recommended that users use these two new functions, rather than the old MPI-1 functions to set and access lower bound, upper bound and extent of datatypes. (*End of advice to users.*)

#### 4.1.8 True Extent of Datatypes

Suppose we implement gather (see also Section 5.5 on page 151) as a spanning tree implemented on top of point-to-point routines. Since the receive buffer is only valid on the root process, one will need to allocate some temporary space for receiving data on intermediate nodes. However, the datatype extent cannot be used as an estimate of the amount of space that needs to be allocated, if the user has modified the extent using the `MPI_UB` and `MPI_LB` values. A function is provided which returns the true extent of the datatype.

`MPI_TYPE_GET_TRUE_EXTENT(datatype, true_lb, true_extent)`

IN	<code>datatype</code>	datatype to get information on (handle)
OUT	<code>true_lb</code>	true lower bound of datatype (integer)
OUT	<code>true_extent</code>	true size of datatype (integer)

```
int MPI_Type_get_true_extent(MPI_Datatype datatype, MPI_Aint *true_lb,
                             MPI_Aint *true_extent)
```

```
MPI_TYPE_GET_TRUE_EXTENT(DATATYPE, TRUE_LB, TRUE_EXTENT, IERROR)
    INTEGER DATATYPE, IERROR
    INTEGER(KIND = MPI_ADDRESS_KIND) TRUE_LB, TRUE_EXTENT
```

```
MPI_Type_get_true_extent(datatype, true_lb, true_extent, ierror)
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: true_lb, true_extent
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Datatype::Get_true_extent(MPI::Aint& true_lb,
    MPI::Aint& true_extent) const(binding deprecated, see Section 15.2) }
```

`true_lb` returns the offset of the lowest unit of store which is addressed by the datatype, i.e., the lower bound of the corresponding typemap, ignoring `MPI_LB` markers. `true_extent` returns the true size of the datatype, i.e., the extent of the corresponding typemap, ignoring `MPI_LB` and `MPI_UB` markers, and performing no rounding for alignment. If the typemap associated with `datatype` is

$$Typemap = \{(type_0, disp_0), \dots, (type_{n-1}, disp_{n-1})\}$$



Then

$$\text{true\_lb}(\text{Typemap}) = \min_j \{ \text{disp}_j : \text{type}_j \neq \text{lb}, \text{ub} \},$$

$$\text{true\_ub}(\text{Typemap}) = \max_j \{ \text{disp}_j + \text{sizeof}(\text{type}_j) : \text{type}_j \neq \text{lb}, \text{ub} \},$$

and

$$\text{true\_extent}(\text{Typemap}) = \text{true\_ub}(\text{Typemap}) - \text{true\_lb}(\text{typemap}).$$

(Readers should compare this with the definitions in Section 4.1.6 on page 105 and Section 4.1.7 on page 106, which describe the function `MPI_TYPE_GET_EXTENT`.)

The `true_extent` is the minimum number of bytes of memory necessary to hold a datatype, uncompressed.

#### 4.1.9 Commit and Free

A datatype object has to be **committed** before it can be used in a communication. As an argument in datatype constructors, uncommitted and also committed datatypes can be used. There is no need to commit basic datatypes. They are “pre-committed.”

`MPI_TYPE_COMMIT(datatype)`

INOUT      datatype                      datatype that is committed (handle)

`int MPI_Type_commit(MPI_Datatype *datatype)`

`MPI_TYPE_COMMIT(DATATYPE, IERROR)`

INTEGER DATATYPE, IERROR

`MPI_Type_commit(datatype, ierror)`

TYPE(MPI\_Datatype), INTENT(INOUT) :: datatype

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

`{void MPI::Datatype::Commit() (binding deprecated, see Section 15.2) }`

The commit operation commits the datatype, that is, the formal description of a communication buffer, not the content of that buffer. Thus, after a datatype has been committed, it can be repeatedly reused to communicate the changing content of a buffer or, indeed, the content of different buffers, with different starting addresses.

*Advice to implementors.* The system may “compile” at commit time an internal representation for the datatype that facilitates communication, e.g. change from a compacted representation to a flat representation of the datatype, and select the most convenient transfer mechanism. (*End of advice to implementors.*)

`MPI_TYPE_COMMIT` will accept a committed datatype; in this case, it is equivalent to a no-op.

**Example 4.10** The following code fragment gives examples of using `MPI_TYPE_COMMIT`.

```

1  INTEGER type1, type2
2  CALL MPI_TYPE_CONTIGUOUS(5, MPI_REAL, type1, ierr)
3      ! new type object created
4  CALL MPI_TYPE_COMMIT(type1, ierr)
5      ! now type1 can be used for communication
6  type2 = type1
7      ! type2 can be used for communication
8      ! (it is a handle to same object as type1)
9  CALL MPI_TYPE_VECTOR(3, 5, 4, MPI_REAL, type1, ierr)
10     ! new uncommitted type object created
11  CALL MPI_TYPE_COMMIT(type1, ierr)
12     ! now type1 can be used anew for communication

```

```

13
14
15  MPI_TYPE_FREE(datatype)

```

```

16      INOUT      datatype                datatype that is freed (handle)

```

```

17
18
19  int MPI_Type_free(MPI_Datatype *datatype)

```

```

20  MPI_TYPE_FREE(DATATYPE, IERROR)

```

```

21      INTEGER DATATYPE, IERROR

```

```

22  MPI_Type_free(datatype, ierror)

```

```

23      TYPE(MPI_Datatype), INTENT(INOUT) :: datatype

```

```

24      INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

25
26  {void MPI::Datatype::Free() (binding deprecated, see Section 15.2) }

```

Marks the datatype object associated with `datatype` for deallocation and sets `datatype` to `MPI_DATATYPE_NULL`. Any communication that is currently using this datatype will complete normally. Freeing a datatype does not affect any other datatype that was built from the freed datatype. The system behaves as if input datatype arguments to derived datatype constructors are passed by value.

*Advice to implementors.* The implementation may keep a reference count of active communications that use the datatype, in order to decide when to free it. Also, one may implement constructors of derived datatypes so that they keep pointers to their datatype arguments, rather than copying them. In this case, one needs to keep track of active datatype definition references in order to know when a datatype object can be freed. (*End of advice to implementors.*)

## 4.1.10 Duplicating a Datatype

`MPI_TYPE_DUP`(`oldtype`, `newtype`)

IN	type	datatype (handle)
OUT	newtype	copy of <code>oldtype</code> (handle)

```
int MPI_Type_dup(MPI_Datatype oldtype, MPI_Datatype *newtype)
```

```
MPI_TYPE_DUP(OLDTYPE, NEWTYPE, IERROR)
    INTEGER OLDTYPE, NEWTYPE, IERROR
```

```
MPI_Type_dup(oldtype, newtype, ierror)
    TYPE(MPI_Datatype), INTENT(IN) :: oldtype
    TYPE(MPI_Datatype), INTENT(OUT) :: newtype
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{MPI::Datatype MPI::Datatype::Dup() const(binding deprecated, see Section 15.2) }
```

`MPI_TYPE_DUP` is a type constructor which duplicates the existing type with associated key values. For each key value, the respective copy callback function determines the attribute value associated with this key in the new communicator; one particular action that a copy callback may take is to delete the attribute from the new datatype. Returns in `newtype` a new datatype with exactly the same properties as `oldtype` and any copied cached information, see Section 6.7.4 on page 276. The new datatype has identical upper bound and lower bound and yields the same net result when fully decoded with the functions in Section 4.1.13. The `newtype` has the same committed state as the old `oldtype`.

## 4.1.11 Use of General Datatypes in Communication

Handles to derived datatypes can be passed to a communication call wherever a datatype argument is required. A call of the form `MPI_SEND(buf, count, datatype, ...)`, where `count > 1`, is interpreted as if the call was passed a new datatype which is the concatenation of `count` copies of `datatype`. Thus, `MPI_SEND(buf, count, datatype, dest, tag, comm)` is equivalent to,

```
MPI_TYPE_CONTIGUOUS(count, datatype, newtype)
MPI_TYPE_COMMIT(newtype)
MPI_SEND(buf, 1, newtype, dest, tag, comm).
```

Similar statements apply to all other communication functions that have a `count` and `datatype` argument.

Suppose that a send operation `MPI_SEND(buf, count, datatype, dest, tag, comm)` is executed, where `datatype` has type map,

$$\{(type_0, disp_0), \dots, (type_{n-1}, disp_{n-1})\},$$

and extent `extent`. (Empty entries of “pseudo-type” `MPI_UB` and `MPI_LB` are not listed in the type map, but they affect the value of `extent`.) The send operation sends  $n \cdot \text{count}$

entries, where entry  $i \cdot n + j$  is at location  $addr_{i,j} = \text{buf} + \text{extent} \cdot i + \text{disp}_j$  and has type  $type_j$ , for  $i = 0, \dots, \text{count} - 1$  and  $j = 0, \dots, n - 1$ . These entries need not be contiguous, nor distinct; their order can be arbitrary.

The variable stored at address  $addr_{i,j}$  in the calling program should be of a type that matches  $type_j$ , where type matching is defined as in Section 3.3.1. The message sent contains  $n \cdot \text{count}$  entries, where entry  $i \cdot n + j$  has type  $type_j$ .

Similarly, suppose that a receive operation `MPI_RECV(buf, count, datatype, source, tag, comm, status)` is executed, where `datatype` has type map,

$$\{(type_0, disp_0), \dots, (type_{n-1}, disp_{n-1})\},$$

with extent  $extent$ . (Again, empty entries of “pseudo-type” `MPI_UB` and `MPI_LB` are not listed in the type map, but they affect the value of  $extent$ .) This receive operation receives  $n \cdot \text{count}$  entries, where entry  $i \cdot n + j$  is at location  $\text{buf} + \text{extent} \cdot i + \text{disp}_j$  and has type  $type_j$ . If the incoming message consists of  $k$  elements, then we must have  $k \leq n \cdot \text{count}$ ; the  $i \cdot n + j$ -th element of the message should have a type that matches  $type_j$ .

Type matching is defined according to the type signature of the corresponding datatypes, that is, the sequence of basic type components. Type matching does not depend on some aspects of the datatype definition, such as the displacements (layout in memory) or the intermediate types used.

**Example 4.11** This example shows that type matching is defined in terms of the basic types that a derived type consists of.

```
...
CALL MPI_TYPE_CONTIGUOUS( 2, MPI_REAL, type2, ...)
CALL MPI_TYPE_CONTIGUOUS( 4, MPI_REAL, type4, ...)
CALL MPI_TYPE_CONTIGUOUS( 2, type2, type22, ...)
...
CALL MPI_SEND( a, 4, MPI_REAL, ...)
CALL MPI_SEND( a, 2, type2, ...)
CALL MPI_SEND( a, 1, type22, ...)
CALL MPI_SEND( a, 1, type4, ...)
...
CALL MPI_RECV( a, 4, MPI_REAL, ...)
CALL MPI_RECV( a, 2, type2, ...)
CALL MPI_RECV( a, 1, type22, ...)
CALL MPI_RECV( a, 1, type4, ...)
```

Each of the sends matches any of the receives.

A datatype may specify overlapping entries. The use of such a datatype in a receive operation is erroneous. (This is erroneous even if the actual message received is short enough not to write any entry more than once.)

Suppose that `MPI_RECV(buf, count, datatype, dest, tag, comm, status)` is executed, where `datatype` has type map,

$$\{(type_0, disp_0), \dots, (type_{n-1}, disp_{n-1})\}.$$

The received message need not fill all the receive buffer, nor does it need to fill a number of locations which is a multiple of  $n$ . Any number,  $k$ , of basic elements can be received, where

$0 \leq k \leq \text{count} \cdot n$ . The number of basic elements received can be retrieved from **status** using the query function **MPI\_GET\_ELEMENTS**.

**MPI\_GET\_ELEMENTS**( **status**, **datatype**, **count**)

IN	<b>status</b>	return status of receive operation ( <b>Status</b> )
IN	<b>datatype</b>	datatype used by receive operation ( <b>handle</b> )
OUT	<b>count</b>	number of received basic elements ( <b>integer</b> )

```
int MPI_Get_elements(MPI_Status *status, MPI_Datatype datatype, int *count)
```

```
MPI_GET_ELEMENTS(STATUS, DATATYPE, COUNT, IERROR)
    INTEGER STATUS(MPI_STATUS_SIZE), DATATYPE, COUNT, IERROR
```

```
MPI_Get_elements(status, datatype, count, ierror)
    TYPE(MPI_Status), INTENT(IN) :: status
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    INTEGER, INTENT(OUT) :: count
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{int MPI::Status::Get_elements(const MPI::Datatype& datatype) const(binding
    deprecated, see Section 15.2) }
```

The previously defined function, **MPI\_GET\_COUNT** (Section 3.2.5), has a different behavior. It returns the number of “top-level entries” received, i.e. the number of “copies” of type **datatype**. In the previous example, **MPI\_GET\_COUNT** may return any integer value  $k$ , where  $0 \leq k \leq \text{count}$ . If **MPI\_GET\_COUNT** returns  $k$ , then the number of basic elements received (and the value returned by **MPI\_GET\_ELEMENTS**) is  $n \cdot k$ . If the number of basic elements received is not a multiple of  $n$ , that is, if the receive operation has not received an integral number of **datatype** “copies,” then **MPI\_GET\_COUNT** returns the value **MPI\_UNDEFINED**. The **datatype** argument should match the argument provided by the receive call that set the **status** variable.

**Example 4.12** Usage of **MPI\_GET\_COUNT** and **MPI\_GET\_ELEMENTS**.

```
...
CALL MPI_TYPE_CONTIGUOUS(2, MPI_REAL, Type2, ierr)
CALL MPI_TYPE_COMMIT(Type2, ierr)
...
CALL MPI_COMM_RANK(comm, rank, ierr)
IF (rank.EQ.0) THEN
    CALL MPI_SEND(a, 2, MPI_REAL, 1, 0, comm, ierr)
    CALL MPI_SEND(a, 3, MPI_REAL, 1, 0, comm, ierr)
ELSE IF (rank.EQ.1) THEN
    CALL MPI_RECV(a, 2, Type2, 0, 0, comm, stat, ierr)
    CALL MPI_GET_COUNT(stat, Type2, i, ierr)      ! returns i=1
    CALL MPI_GET_ELEMENTS(stat, Type2, i, ierr)   ! returns i=2
    CALL MPI_RECV(a, 2, Type2, 0, 0, comm, stat, ierr)
    CALL MPI_GET_COUNT(stat, Type2, i, ierr)      ! returns i=MPI_UNDEFINED
```

```

1      CALL MPI_GET_ELEMENTS(stat, Type2, i, ierr)  ! returns i=3
2  END IF

```

The function `MPI_GET_ELEMENTS` can also be used after a probe to find the number of elements in the probed message. Note that the two functions `MPI_GET_COUNT` and `MPI_GET_ELEMENTS` return the same values when they are used with basic datatypes.

*Rationale.* The extension given to the definition of `MPI_GET_COUNT` seems natural: one would expect this function to return the value of the `count` argument, when the receive buffer is filled. Sometimes `datatype` represents a basic unit of data one wants to transfer, for example, a record in an array of records (structures). One should be able to find out how many components were received without bothering to divide by the number of elements in each component. However, on other occasions, `datatype` is used to define a complex layout of data in the receiver memory, and does not represent a basic unit of data for transfers. In such cases, one needs to use the function `MPI_GET_ELEMENTS`. (*End of rationale.*)

*Advice to implementors.* The definition implies that a receive cannot change the value of storage outside the entries defined to compose the communication buffer. In particular, the definition implies that padding space in a structure should not be modified when such a structure is copied from one process to another. This would prevent the obvious optimization of copying the structure, together with the padding, as one contiguous block. The implementation is free to do this optimization when it does not impact the outcome of the computation. The user can “force” this optimization by explicitly including padding as part of the message. (*End of advice to implementors.*)

#### 4.1.12 Correct Use of Addresses

Successively declared variables in C or Fortran are not necessarily stored at contiguous locations. Thus, care must be exercised that displacements do not cross from one variable to another. Also, in machines with a segmented address space, addresses are not unique and address arithmetic has some peculiar properties. Thus, the use of **addresses**, that is, displacements relative to the start address `MPI_BOTTOM`, has to be restricted.

Variables belong to the same **sequential storage** if they belong to the same array, to the same `COMMON` block in Fortran, or to the same structure in C. Valid addresses are defined recursively as follows:

1. The function `MPI_GET_ADDRESS` returns a valid address, when passed as argument a variable of the calling program.
2. The `buf` argument of a communication function evaluates to a valid address, when passed as argument a variable of the calling program.
3. If `v` is a valid address, and `i` is an integer, then `v+i` is a valid address, provided `v` and `v+i` are in the same sequential storage.
4. If `v` is a valid address then `MPI_BOTTOM + v` is a valid address.

A correct program uses only valid addresses to identify the locations of entries in communication buffers. Furthermore, if `u` and `v` are two valid addresses, then the (integer)

difference  $u - v$  can be computed only if both  $u$  and  $v$  are in the same sequential storage. No other arithmetic operations can be meaningfully executed on addresses.

The rules above impose no constraints on the use of derived datatypes, as long as they are used to define a communication buffer that is wholly contained within the same sequential storage. However, the construction of a communication buffer that contains variables that are not within the same sequential storage must obey certain restrictions. Basically, a communication buffer with variables that are not within the same sequential storage can be used only by specifying in the communication call `buf = MPI_BOTTOM`, `count = 1`, and using a `datatype` argument where all displacements are valid (absolute) addresses.

*Advice to users.* It is not expected that MPI implementations will be able to detect erroneous, “out of bound” displacements — unless those overflow the user address space — since the MPI call may not know the extent of the arrays and records in the host program. (*End of advice to users.*)

*Advice to implementors.* There is no need to distinguish (absolute) addresses and (relative) displacements on a machine with contiguous address space: `MPI_BOTTOM` is zero, and both addresses and displacements are integers. On machines where the distinction is required, addresses are recognized as expressions that involve `MPI_BOTTOM`. (*End of advice to implementors.*)

#### 4.1.13 Decoding a Datatype

MPI datatype objects allow users to specify an arbitrary layout of data in memory. There are several cases where accessing the layout information in opaque datatype objects would be useful. The opaque datatype object has found a number of uses outside MPI. Furthermore, a number of tools wish to display internal information about a datatype. To achieve this, datatype decoding functions are provided. The two functions in this section are used together to decode datatypes to recreate the calling sequence used in their initial definition. These can be used to allow a user to determine the type map and type signature of a datatype.

`MPI_TYPE_GET_ENVELOPE(datatype, num_integers, num_addresses, num_datatypes, combiner)`

IN	<code>datatype</code>	datatype to access (handle)
OUT	<code>num_integers</code>	number of input integers used in the call constructing combiner (non-negative integer)
OUT	<code>num_addresses</code>	number of input addresses used in the call constructing combiner (non-negative integer)
OUT	<code>num_datatypes</code>	number of input datatypes used in the call constructing combiner (non-negative integer)
OUT	<code>combiner</code>	combiner (state)

```
int MPI_Type_get_envelope(MPI_Datatype datatype, int *num_integers,
                          int *num_addresses, int *num_datatypes, int *combiner)
```

```

1 MPI_TYPE_GET_ENVELOPE(DATATYPE, NUM_INTEGERS, NUM_ADDRESSES, NUM_DATATYPES,
2     COMBINER, IERROR)
3     INTEGER DATATYPE, NUM_INTEGERS, NUM_ADDRESSES, NUM_DATATYPES, COMBINER,
4     IERROR
5
6 MPI_Type_get_envelope(datatype, num_integers, num_addresses, num_datatypes,
7     combiner, ierror)
8     TYPE(MPI_Datatype), INTENT(IN) :: datatype
9     INTEGER, INTENT(OUT) :: num_integers, num_addresses, num_datatypes,
10    combiner
11    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
12
13 {void MPI::Datatype::Get_envelope(int& num_integers, int& num_addresses,
14     int& num_datatypes, int& combiner) const(binding deprecated, see
15     Section 15.2) }

```

For the given `datatype`, `MPI_TYPE_GET_ENVELOPE` returns information on the number and type of input arguments used in the call that created the `datatype`. The number-of-arguments values returned can be used to provide sufficiently large arrays in the decoding routine `MPI_TYPE_GET_CONTENTS`. This call and the meaning of the returned values is described below. The `combiner` reflects the MPI datatype constructor call that was used in creating `datatype`.

*Rationale.* By requiring that the `combiner` reflect the constructor used in the creation of the `datatype`, the decoded information can be used to effectively recreate the calling sequence used in the original creation. One call is effectively the same as another when the information obtained from `MPI_TYPE_GET_CONTENTS` may be used with either to produce the same outcome. C calls `MPI_Type_hindexed` and `MPI_Type_create_hindexed` are always effectively the same while the Fortran call `MPI_TYPE_HINDEXED` will be different than either of these in some MPI implementations. This is the most useful information and was felt to be reasonable even though it constrains implementations to remember the original constructor sequence even if the internal representation is different.

The decoded information keeps track of datatype duplications. This is important as one needs to distinguish between a predefined datatype and a dup of a predefined datatype. The former is a constant object that cannot be freed, while the latter is a derived datatype that can be freed. (*End of rationale.*)

The list below has the values that can be returned in `combiner` on the left and the call associated with them on the right.

If `combiner` is `MPI_COMBINER_NAMED` then `datatype` is a named predefined datatype.

For deprecated calls with address arguments, we sometimes need to differentiate whether the call used an integer or an address size argument. For example, there are two combiners for `hvector`: `MPI_COMBINER_HVECTOR_INTEGER` and `MPI_COMBINER_HVECTOR`. The former is used if it was the MPI-1 call from Fortran, and the latter is used if it was the MPI-1 call from C or C++. However, on systems where `MPI_ADDRESS_KIND = MPI_INTEGER_KIND` (i.e., where integer arguments and address size arguments are the same), the combiner `MPI_COMBINER_HVECTOR` may be returned for a datatype constructed by a call to `MPI_TYPE_HVECTOR` from Fortran. Similarly, `MPI_COMBINER_HINDEXED` may



MPI_COMBINER_NAMED	a named predefined datatype
MPI_COMBINER_DUP	MPI_TYPE_DUP
MPI_COMBINER_CONTIGUOUS	MPI_TYPE_CONTIGUOUS
MPI_COMBINER_VECTOR	MPI_TYPE_VECTOR
MPI_COMBINER_HVECTOR_INTEGER	MPI_TYPE_HVECTOR from Fortran
MPI_COMBINER_HVECTOR	MPI_TYPE_HVECTOR from C or C++ and in some case Fortran or MPI_TYPE_CREATE_HVECTOR
MPI_COMBINER_INDEXED	MPI_TYPE_INDEXED
MPI_COMBINER_HINDEXED_INTEGER	MPI_TYPE_HINDEXED from Fortran
MPI_COMBINER_HINDEXED	MPI_TYPE_HINDEXED from C or C++ and in some case Fortran or MPI_TYPE_CREATE_HINDEXED
MPI_COMBINER_INDEXED_BLOCK	MPI_TYPE_CREATE_INDEXED_BLOCK
MPI_COMBINER_STRUCT_INTEGER	MPI_TYPE_STRUCT from Fortran
MPI_COMBINER_STRUCT	MPI_TYPE_STRUCT from C or C++ and in some case Fortran or MPI_TYPE_CREATE_STRUCT
MPI_COMBINER_SUBARRAY	MPI_TYPE_CREATE_SUBARRAY
MPI_COMBINER_DARRAY	MPI_TYPE_CREATE_DARRAY
MPI_COMBINER_F90_REAL	MPI_TYPE_CREATE_F90_REAL
MPI_COMBINER_F90_COMPLEX	MPI_TYPE_CREATE_F90_COMPLEX
MPI_COMBINER_F90_INTEGER	MPI_TYPE_CREATE_F90_INTEGER
MPI_COMBINER_RESIZED	MPI_TYPE_CREATE_RESIZED

Table 4.1: combiner values returned from MPI\_TYPE\_GET\_ENVELOPE

be returned for a datatype constructed by a call to MPI\_TYPE\_HINDEXED from Fortran, and MPI\_COMBINER\_STRUCT may be returned for a datatype constructed by a call to MPI\_TYPE\_STRUCT from Fortran. On such systems, one need not differentiate constructors that take address size arguments from constructors that take integer arguments, since these are the same. The preferred calls all use address sized arguments so two combiners are not required for them.

*Rationale.* For recreating the original call, it is important to know if address information may have been truncated. The deprecated calls from Fortran for a few routines could be subject to truncation in the case where the default `INTEGER` size is smaller than the size of an address. (*End of rationale.*)

The actual arguments used in the creation call for a datatype can be obtained from the call:

```

1 MPI_TYPE_GET_CONTENTS(datatype, max_integers, max_addresses, max_datatypes, ar-
2   ray_of_integers, array_of_addresses, array_of_datatypes)
3
4   IN      datatype      datatype to access (handle)
5
6   IN      max_integers   number of elements in array_of_integers (non-negative
7                           integer)
8
9   IN      max_addresses  number of elements in array_of_addresses (non-negative
10                          integer)
11
12   IN      max_datatypes  number of elements in array_of_datatypes (non-negative
13                          integer)
14
15   OUT     array_of_integers contains integer arguments used in constructing
16                          datatype (array of integers)
17
18   OUT     array_of_addresses contains address arguments used in constructing
19                          datatype (array of integers)
20
21   OUT     array_of_datatypes contains datatype arguments used in constructing
22                          datatype (array of handles)
23
24
25
26
27
28
29
30

```

```

31 int MPI_Type_get_contents(MPI_Datatype datatype, int max_integers,
32                           int max_addresses, int max_datatypes, int array_of_integers[],
33                           MPI_Aint array_of_addresses[],
34                           MPI_Datatype array_of_datatypes[])
35
36 MPI_TYPE_GET_CONTENTS(DATATYPE, MAX_INTEGERS, MAX_ADDRESSES, MAX_DATATYPES,
37   ARRAY_OF_INTEGERS, ARRAY_OF_ADDRESSES, ARRAY_OF_DATATYPES,
38   IERROR)
39
40   INTEGER DATATYPE, MAX_INTEGERS, MAX_ADDRESSES, MAX_DATATYPES,
41   ARRAY_OF_INTEGERS(*), ARRAY_OF_DATATYPES(*), IERROR
42   INTEGER(KIND=MPI_ADDRESS_KIND) ARRAY_OF_ADDRESSES(*)
43
44
45
46
47
48

```

```

49 MPI_TYPE_GET_CONTENTS(DATATYPE, MAX_INTEGERS, MAX_ADDRESSES, MAX_DATATYPES,
50   ARRAY_OF_INTEGERS, ARRAY_OF_ADDRESSES, ARRAY_OF_DATATYPES,
51   IERROR)
52
53   INTEGER DATATYPE, MAX_INTEGERS, MAX_ADDRESSES, MAX_DATATYPES,
54   ARRAY_OF_INTEGERS(*), ARRAY_OF_DATATYPES(*), IERROR
55   INTEGER(KIND=MPI_ADDRESS_KIND) ARRAY_OF_ADDRESSES(*)
56
57
58
59
60
61

```

```

62 MPI_Type_get_contents(datatype, max_integers, max_addresses, max_datatypes,
63   array_of_integers, array_of_addresses, array_of_datatypes,
64   ierror)
65
66   TYPE(MPI_Datatype), INTENT(IN) :: datatype
67   INTEGER, INTENT(IN) :: max_integers, max_addresses, max_datatypes
68   INTEGER, INTENT(OUT) :: array_of_integers(*)
69   INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: array_of_addresses(*)
70   TYPE(MPI_Datatype), INTENT(OUT) :: array_of_datatypes(*)
71   INTEGER, OPTIONAL, INTENT(OUT) :: ierror
72
73
74
75
76
77

```

```

78 MPI_Type_get_contents(datatype, max_integers, max_addresses, max_datatypes,
79   array_of_integers, array_of_addresses, array_of_datatypes,
80   ierror)
81
82   TYPE(MPI_Datatype), INTENT(IN) :: datatype
83   INTEGER, INTENT(IN) :: max_integers, max_addresses, max_datatypes
84   INTEGER, INTENT(OUT) :: array_of_integers(*)
85   INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: array_of_addresses(*)
86   TYPE(MPI_Datatype), INTENT(OUT) :: array_of_datatypes(*)
87   INTEGER, OPTIONAL, INTENT(OUT) :: ierror
88
89
90
91
92
93

```

```

94 MPI_Type_get_contents(datatype, max_integers, max_addresses, max_datatypes,
95   array_of_integers, array_of_addresses, array_of_datatypes,
96   ierror)
97
98   TYPE(MPI_Datatype), INTENT(IN) :: datatype
99   INTEGER, INTENT(IN) :: max_integers, max_addresses, max_datatypes
100  INTEGER, INTENT(OUT) :: array_of_integers(*)
101  INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: array_of_addresses(*)
102  TYPE(MPI_Datatype), INTENT(OUT) :: array_of_datatypes(*)
103  INTEGER, OPTIONAL, INTENT(OUT) :: ierror
104
105
106
107
108
109

```

```

110 {void MPI::Datatype::Get_contents(int max_integers, int max_addresses,
111   int max_datatypes, int array_of_integers[],
112   MPI::Aint array_of_addresses[],
113   MPI::Datatype array_of_datatypes[]) const(binding deprecated, see
114   Section 15.2) }
115
116
117
118
119
120

```

datatype must be a predefined unnamed or a derived datatype; the call is erroneous if datatype is a predefined named datatype.

The values given for `max_integers`, `max_addresses`, and `max_datatypes` must be at least as large as the value returned in `num_integers`, `num_addresses`, and `num_datatypes`, respectively, in the call `MPI_TYPE_GET_ENVELOPE` for the same `datatype` argument.

*Rationale.* The arguments `max_integers`, `max_addresses`, and `max_datatypes` allow for error checking in the call. (*End of rationale.*)

The datatypes returned in `array_of_datatypes` are handles to datatype objects that are equivalent to the datatypes used in the original construction call. If these were derived datatypes, then the returned datatypes are new datatype objects, and the user is responsible for freeing these datatypes with `MPI_TYPE_FREE`. If these were predefined datatypes, then the returned datatype is equal to that (constant) predefined datatype and cannot be freed.

The committed state of returned derived datatypes is undefined, i.e., the datatypes may or may not be committed. Furthermore, the content of attributes of returned datatypes is undefined.

Note that `MPI_TYPE_GET_CONTENTS` can be invoked with a `datatype` argument that was constructed using `MPI_TYPE_CREATE_F90_REAL`, `MPI_TYPE_CREATE_F90_INTEGER`, or `MPI_TYPE_CREATE_F90_COMPLEX` (an unnamed predefined datatype). In such a case, an empty `array_of_datatypes` is returned.

*Rationale.* The definition of datatype equivalence implies that equivalent predefined datatypes are equal. By requiring the same handle for named predefined datatypes, it is possible to use the `==` or `.EQ.` comparison operator to determine the datatype involved. (*End of rationale.*)

*Advice to implementors.* The datatypes returned in `array_of_datatypes` must appear to the user as if each is an equivalent copy of the datatype used in the type constructor call. Whether this is done by creating a new datatype or via another mechanism such as a reference count mechanism is up to the implementation as long as the semantics are preserved. (*End of advice to implementors.*)

*Rationale.* The committed state and attributes of the returned datatype is deliberately left vague. The datatype used in the original construction may have been modified since its use in the constructor call. Attributes can be added, removed, or modified as well as having the datatype committed. The semantics given allow for a reference count implementation without having to track these changes. (*End of rationale.*)

In the deprecated datatype constructor calls, the address arguments in Fortran are of type `INTEGER`. In the preferred calls, the address arguments are of type `INTEGER(KIND=MPI_ADDRESS_KIND)`. The call `MPI_TYPE_GET_CONTENTS` returns all addresses in an argument of type `INTEGER(KIND=MPI_ADDRESS_KIND)`. This is true even if the deprecated calls were used. Thus, the location of values returned can be thought of as being returned by the C bindings. It can also be determined by examining the preferred calls for datatype constructors for the deprecated calls that involve addresses.

*Rationale.* By having all address arguments returned in the `array_of_addresses` argument, the result from a C and Fortran decoding of a `datatype` gives the result in the same argument. It is assumed that an integer of type

INTEGER(KIND=MPI\_ADDRESS\_KIND) will be at least as large as the INTEGER argument used in datatype construction with the old MPI-1 calls so no loss of information will occur. (*End of rationale.*)

The following defines what values are placed in each entry of the returned arrays depending on the datatype constructor used for `datatype`. It also specifies the size of the arrays needed which is the values returned by `MPI_TYPE_GET_ENVELOPE`. In Fortran, the following calls were made:

```

    PARAMETER (LARGE = 1000)
    INTEGER TYPE, NI, NA, ND, COMBINER, I(LARGE), D(LARGE), IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) A(LARGE)
    ! CONSTRUCT DATATYPE TYPE (NOT SHOWN)
    CALL MPI_TYPE_GET_ENVELOPE(TYPE, NI, NA, ND, COMBINER, IERROR)
    IF ((NI .GT. LARGE) .OR. (NA .GT. LARGE) .OR. (ND .GT. LARGE)) THEN
        WRITE (*, *) "NI, NA, OR ND = ", NI, NA, ND, &
            " RETURNED BY MPI_TYPE_GET_ENVELOPE IS LARGER THAN LARGE = ", LARGE
        CALL MPI_ABORT(MPI_COMM_WORLD, 99, IERROR)
    ENDIF
    CALL MPI_TYPE_GET_CONTENTS(TYPE, NI, NA, ND, I, A, D, IERROR)

```

or in C the analogous calls of:

```

#define LARGE 1000
int ni, na, nd, combiner, i[LARGE];
MPI_Aint a[LARGE];
MPI_Datatype type, d[LARGE];
/* construct datatype type (not shown) */
MPI_Type_get_envelope(type, &ni, &na, &nd, &combiner);
if ((ni > LARGE) || (na > LARGE) || (nd > LARGE)) {
    fprintf(stderr, "ni, na, or nd = %d %d %d returned by ", ni, na, nd);
    fprintf(stderr, "MPI_Type_get_envelope is larger than LARGE = %d\n",
        LARGE);
    MPI_Abort(MPI_COMM_WORLD, 99);
};
MPI_Type_get_contents(type, ni, na, nd, i, a, d);

```

The C++ code is in analogy to the C code above with the same values returned.

In the descriptions that follow, the lower case name of arguments is used.

If combiner is `MPI_COMBINER_NAMED` then it is erroneous to call

`MPI_TYPE_GET_CONTENTS`.

If combiner is `MPI_COMBINER_DUP` then

Constructor argument	C & C++ location	Fortran location
oldtype	d[0]	D(1)

and `ni = 0`, `na = 0`, `nd = 1`.

If combiner is `MPI_COMBINER_CONTIGUOUS` then

Constructor argument	C & C++ location	Fortran location
count	i[0]	I(1)
oldtype	d[0]	D(1)

and ni = 1, na = 0, nd = 1.

If combiner is MPI\_COMBINER\_VECTOR then

Constructor argument	C & C++ location	Fortran location
count	i[0]	I(1)
blocklength	i[1]	I(2)
stride	i[2]	I(3)
oldtype	d[0]	D(1)

and ni = 3, na = 0, nd = 1.

If combiner is MPI\_COMBINER\_HVECTOR\_INTEGER or MPI\_COMBINER\_HVECTOR then

Constructor argument	C & C++ location	Fortran location
count	i[0]	I(1)
blocklength	i[1]	I(2)
stride	a[0]	A(1)
oldtype	d[0]	D(1)

and ni = 2, na = 1, nd = 1.

If combiner is MPI\_COMBINER\_INDEXED then

Constructor argument	C & C++ location	Fortran location
count	i[0]	I(1)
array_of_blocklengths	i[1] to i[i[0]]	I(2) to I(I(1)+1)
array_of_displacements	i[i[0]+1] to i[2*i[0]]	I(I(1)+2) to I(2*I(1)+1)
oldtype	d[0]	D(1)

and ni = 2\*count+1, na = 0, nd = 1.

If combiner is MPI\_COMBINER\_HINDEXED\_INTEGER or MPI\_COMBINER\_HINDEXED then

Constructor argument	C & C++ location	Fortran location
count	i[0]	I(1)
array_of_blocklengths	i[1] to i[i[0]]	I(2) to I(I(1)+1)
array_of_displacements	a[0] to a[i[0]-1]	A(1) to A(I(1))
oldtype	d[0]	D(1)

and ni = count+1, na = count, nd = 1.

If combiner is MPI\_COMBINER\_INDEXED\_BLOCK then

Constructor argument	C & C++ location	Fortran location
count	i[0]	I(1)
blocklength	i[1]	I(2)
array_of_displacements	i[2] to i[i[0]+1]	I(3) to I(I(1)+2)
oldtype	d[0]	D(1)

and ni = count+2, na = 0, nd = 1.

If combiner is MPI\_COMBINER\_STRUCT\_INTEGER or MPI\_COMBINER\_STRUCT then

Constructor argument	C & C++ location	Fortran location
count	i[0]	I(1)
array_of_blocklengths	i[1] to i[i[0]]	I(2) to I(I(1)+1)
array_of_displacements	a[0] to a[i[0]-1]	A(1) to A(I(1))
array_of_types	d[0] to d[i[0]-1]	D(1) to D(I(1))

and ni = count+1, na = count, nd = count.

If combiner is MPI\_COMBINER\_SUBARRAY then

Constructor argument	C & C++ location	Fortran location
ndims	i[0]	I(1)
array_of_sizes	i[1] to i[i[0]]	I(2) to I(I(1)+1)
array_of_subsizes	i[i[0]+1] to i[2*i[0]]	I(I(1)+2) to I(2*I(1)+1)
array_of_starts	i[2*i[0]+1] to i[3*i[0]]	I(2*I(1)+2) to I(3*I(1)+1)
order	i[3*i[0]+1]	I(3*I(1)+2)
oldtype	d[0]	D(1)

and ni = 3\*ndims+2, na = 0, nd = 1.

If combiner is MPI\_COMBINER\_DARRAY then

Constructor argument	C & C++ location	Fortran location
size	i[0]	I(1)
rank	i[1]	I(2)
ndims	i[2]	I(3)
array_of_gsizes	i[3] to i[i[2]+2]	I(4) to I(I(3)+3)
array_of_distribs	i[i[2]+3] to i[2*i[2]+2]	I(I(3)+4) to I(2*I(3)+3)
array_of_dargs	i[2*i[2]+3] to i[3*i[2]+2]	I(2*I(3)+4) to I(3*I(3)+3)
array_of_psize	i[3*i[2]+3] to i[4*i[2]+2]	I(3*I(3)+4) to I(4*I(3)+3)
order	i[4*i[2]+3]	I(4*I(3)+4)
oldtype	d[0]	D(1)

and ni = 4\*ndims+4, na = 0, nd = 1.

If combiner is MPI\_COMBINER\_F90\_REAL then

Constructor argument	C & C++ location	Fortran location
p	i[0]	I(1)
r	i[1]	I(2)

and ni = 2, na = 0, nd = 0.

If combiner is MPI\_COMBINER\_F90\_COMPLEX then

Constructor argument	C & C++ location	Fortran location
p	i[0]	I(1)
r	i[1]	I(2)

and ni = 2, na = 0, nd = 0.

If combiner is MPI\_COMBINER\_F90\_INTEGER then

Constructor argument	C & C++ location	Fortran location
r	i[0]	I(1)

and ni = 1, na = 0, nd = 0.

If combiner is MPI\_COMBINER\_RESIZED then

Constructor argument	C & C++ location	Fortran location
lb	a[0]	A(1)
extent	a[1]	A(2)
oldtype	d[0]	D(1)

and ni = 0, na = 2, nd = 1.

#### 4.1.14 Examples

The following examples illustrate the use of derived datatypes.

**Example 4.13** Send and receive a section of a 3D array.

```

REAL a(100,100,100), e(9,9,9)
INTEGER oneslice, twoslice, threeslice, sizeofreal, myrank, ierr
INTEGER status(MPI_STATUS_SIZE)

C      extract the section a(1:17:2, 3:11, 2:10)
C      and store it in e(:, :, :).

CALL MPI_COMM_RANK(MPI_COMM_WORLD, myrank, ierr)

CALL MPI_TYPE_EXTENT( MPI_REAL, sizeofreal, ierr)

C      create datatype for a 1D section
CALL MPI_TYPE_VECTOR( 9, 1, 2, MPI_REAL, oneslice, ierr)

C      create datatype for a 2D section
CALL MPI_TYPE_HVECTOR(9, 1, 100*sizeofreal, oneslice, twoslice, ierr)

C      create datatype for the entire section
CALL MPI_TYPE_HVECTOR( 9, 1, 100*100*sizeofreal, twoslice,
                      threeslice, ierr)

CALL MPI_TYPE_COMMIT( threeslice, ierr)
CALL MPI_SENDRECV(a(1,3,2), 1, threeslice, myrank, 0, e, 9*9*9,
                  MPI_REAL, myrank, 0, MPI_COMM_WORLD, status, ierr)

```

**Example 4.14** Copy the (strictly) lower triangular part of a matrix.

```

REAL a(100,100), b(100,100)
INTEGER disp(100), blocklen(100), ltype, myrank, ierr
INTEGER status(MPI_STATUS_SIZE)

C      copy lower triangular part of array a
C      onto lower triangular part of array b

CALL MPI_COMM_RANK(MPI_COMM_WORLD, myrank, ierr)

C      compute start and size of each column
DO i=1, 100
    disp(i) = 100*(i-1) + i
    blocklen(i) = 100-i
END DO

C      create datatype for lower triangular part
CALL MPI_TYPE_INDEXED( 100, blocklen, disp, MPI_REAL, ltype, ierr)

CALL MPI_TYPE_COMMIT(ltype, ierr)

```

```

1      CALL MPI_SENDRECV( a, 1, ltype, myrank, 0, b, 1,
2                          ltype, myrank, 0, MPI_COMM_WORLD, status, ierr)
3
4

```

**Example 4.15** Transpose a matrix.

```

6      REAL a(100,100), b(100,100)
7      INTEGER row, xpose, sizeofreal, myrank, ierr
8      INTEGER status(MPI_STATUS_SIZE)
9
10     C      transpose matrix a onto b
11
12     CALL MPI_COMM_RANK(MPI_COMM_WORLD, myrank, ierr)
13
14     CALL MPI_TYPE_EXTENT( MPI_REAL, sizeofreal, ierr)
15
16     C      create datatype for one row
17     CALL MPI_TYPE_VECTOR( 100, 1, 100, MPI_REAL, row, ierr)
18
19     C      create datatype for matrix in row-major order
20     CALL MPI_TYPE_HVECTOR( 100, 1, sizeofreal, row, xpose, ierr)
21
22     CALL MPI_TYPE_COMMIT( xpose, ierr)
23
24     C      send matrix in row-major order and receive in column major order
25     CALL MPI_SENDRECV( a, 1, xpose, myrank, 0, b, 100*100,
26                         MPI_REAL, myrank, 0, MPI_COMM_WORLD, status, ierr)
27
28

```

**Example 4.16** Another approach to the transpose problem:

```

31     REAL a(100,100), b(100,100)
32     INTEGER disp(2), blocklen(2), type(2), row, row1, sizeofreal
33     INTEGER myrank, ierr
34     INTEGER status(MPI_STATUS_SIZE)
35
36     CALL MPI_COMM_RANK(MPI_COMM_WORLD, myrank, ierr)
37
38     C      transpose matrix a onto b
39
40     CALL MPI_TYPE_EXTENT( MPI_REAL, sizeofreal, ierr)
41
42     C      create datatype for one row
43     CALL MPI_TYPE_VECTOR( 100, 1, 100, MPI_REAL, row, ierr)
44
45     C      create datatype for one row, with the extent of one real number
46     disp(1) = 0
47     disp(2) = sizeofreal
48     type(1) = row

```



```

        type(2) = MPI_UB
        blocklen(1) = 1
        blocklen(2) = 1
        CALL MPI_TYPE_STRUCT( 2, blocklen, disp, type, row1, ierr)

        CALL MPI_TYPE_COMMIT( row1, ierr)

C      send 100 rows and receive in column major order
        CALL MPI_SENDRECV( a, 100, row1, myrank, 0, b, 100*100,
                          MPI_REAL, myrank, 0, MPI_COMM_WORLD, status, ierr)

```

**Example 4.17** We manipulate an array of structures.

```

struct Partstruct
{
    int    class; /* particle class */
    double d[6]; /* particle coordinates */
    char   b[7]; /* some additional information */
};

struct Partstruct    particle[1000];

int                i, dest, rank, tag;
MPI_Comm           comm;

/* build datatype describing structure */

MPI_Datatype Particletype;
MPI_Datatype type[3] = {MPI_INT, MPI_DOUBLE, MPI_CHAR};
int          blocklen[3] = {1, 6, 7};
MPI_Aint     disp[3];
MPI_Aint     base;

/* compute displacements of structure components */

MPI_Address( particle, disp);
MPI_Address( particle[0].d, disp+1);
MPI_Address( particle[0].b, disp+2);
base = disp[0];
for (i=0; i < 3; i++) disp[i] -= base;

MPI_Type_struct( 3, blocklen, disp, type, &Particletype);

/* If compiler does padding in mysterious ways,
the following may be safer */

```

```

1  MPI_Datatype type1[4] = {MPI_INT, MPI_DOUBLE, MPI_CHAR, MPI_UB};
2  int          blocklen1[4] = {1, 6, 7, 1};
3  MPI_Aint     disp1[4];
4
5  /* compute displacements of structure components */
6
7  MPI_Address( particle, disp1);
8  MPI_Address( particle[0].d, disp1+1);
9  MPI_Address( particle[0].b, disp1+2);
10 MPI_Address( particle+1, disp1+3);
11 base = disp1[0];
12 for (i=0; i < 4; i++) disp1[i] -= base;
13
14 /* build datatype describing structure */
15
16 MPI_Type_struct( 4, blocklen1, disp1, type1, &Particletype);
17
18
19          /* 4.1:
20          send the entire array */
21
22 MPI_Type_commit( &Particletype);
23 MPI_Send( particle, 1000, Particletype, dest, tag, comm);
24
25
26          /* 4.2:
27          send only the entries of class zero particles,
28          preceded by the number of such entries */
29
30 MPI_Datatype Zparticles; /* datatype describing all particles
31                          with class zero (needs to be recomputed
32                          if classes change) */
33 MPI_Datatype Ztype;
34
35 MPI_Aint     zdisp[1000];
36 int          zblock[1000], j, k;
37 int          zzblock[2] = {1,1};
38 MPI_Aint     zzdisp[2];
39 MPI_Datatype zztype[2];
40
41 /* compute displacements of class zero particles */
42 j = 0;
43 for(i=0; i < 1000; i++)
44     if (particle[i].class == 0)
45     {
46         zdisp[j] = i;
47         zblock[j] = 1;
48         j++;

```

```

    }
1
2
/* create datatype for class zero particles */
3
MPI_Type_indexed( j, zblock, zdisp, Particletype, &Zparticles);
4
5
/* prepend particle count */
6
MPI_Address(&j, zzdisp);
7
MPI_Address(particle, zzdisp+1);
8
zztype[0] = MPI_INT;
9
zztype[1] = Zparticles;
10
MPI_Type_struct(2, zblock, zzdisp, zztype, &Ztype);
11
12
MPI_Type_commit( &Ztype);
13
MPI_Send( MPI_BOTTOM, 1, Ztype, dest, tag, comm);
14
15
16
/* A probably more efficient way of defining Zparticles */
17
18
/* consecutive particles with index zero are handled as one block */
19
j=0;
20
for (i=0; i < 1000; i++)
21
    if (particle[i].index == 0)
22
        {
23
            for (k=i+1; (k < 1000)&&(particle[k].index == 0) ; k++);
24
            zdisp[j] = i;
25
            zblock[j] = k-i;
26
            j++;
27
            i = k;
28
        }
29
MPI_Type_indexed( j, zblock, zdisp, Particletype, &Zparticles);
30
31
32
/* 4.3:
33
    send the first two coordinates of all entries */
34
35
MPI_Datatype Allpairs;      /* datatype for all pairs of coordinates */
36
37
MPI_Aint sizeofentry;
38
39
MPI_Type_extent( Particletype, &sizeofentry);
40
41
/* sizeofentry can also be computed by subtracting the address
42
    of particle[0] from the address of particle[1] */
43
44
MPI_Type_hvector( 1000, 2, sizeofentry, MPI_DOUBLE, &Allpairs);
45
MPI_Type_commit( &Allpairs);
46
MPI_Send( particle[0].d, 1, Allpairs, dest, tag, comm);
47
48

```

```

1      /* an alternative solution to 4.3 */
2
3      MPI_Datatype Onepair;    /* datatype for one pair of coordinates, with
4                               the extent of one particle entry */
5      MPI_Aint disp2[3];
6      MPI_Datatype type2[3] = {MPI_LB, MPI_DOUBLE, MPI_UB};
7      int blocklen2[3] = {1, 2, 1};
8
9      MPI_Address( particle, disp2);
10     MPI_Address( particle[0].d, disp2+1);
11     MPI_Address( particle+1, disp2+2);
12     base = disp2[0];
13     for (i=0; i<2; i++) disp2[i] -= base;
14
15     MPI_Type_struct( 3, blocklen2, disp2, type2, &Onepair);
16     MPI_Type_commit( &Onepair);
17     MPI_Send( particle[0].d, 1000, Onepair, dest, tag, comm);
18
19
20
21 Example 4.18 The same manipulations as in the previous example, but use absolute
22 addresses in datatypes.
23
24     struct Partstruct
25     {
26         int class;
27         double d[6];
28         char b[7];
29     };
30
31     struct Partstruct particle[1000];
32
33     /* build datatype describing first array entry */
34
35     MPI_Datatype Particletype;
36     MPI_Datatype type[3] = {MPI_INT, MPI_DOUBLE, MPI_CHAR};
37     int          block[3] = {1, 6, 7};
38     MPI_Aint      disp[3];
39
40     MPI_Address( particle, disp);
41     MPI_Address( particle[0].d, disp+1);
42     MPI_Address( particle[0].b, disp+2);
43     MPI_Type_struct( 3, block, disp, type, &Particletype);
44
45     /* Particletype describes first array entry -- using absolute
46        addresses */
47
48     /* 5.1:

```

```

        send the entire array */
1
2
MPI_Type_commit( &Particletype);
3
MPI_Send( MPI_BOTTOM, 1000, Particletype, dest, tag, comm);
4
5
6
        /* 5.2:
        send the entries of class zero,
        preceded by the number of such entries */
7
8
9
10
MPI_Datatype Zparticles, Ztype;
11
12
MPI_Aint      zdisp[1000];
13
int           zblock[1000], i, j, k;
14
int           zzblock[2] = {1,1};
15
MPI_Datatype  zztype[2];
16
MPI_Aint      zzdisp[2];
17
18
j=0;
19
for (i=0; i < 1000; i++)
20
    if (particle[i].index == 0)
21
        {
22
            for (k=i+1; (k < 1000)&&(particle[k].index == 0) ; k++);
23
            zdisp[j] = i;
24
            zblock[j] = k-i;
25
            j++;
26
            i = k;
27
        }
28
MPI_Type_indexed( j, zblock, zdisp, Particletype, &Zparticles);
29
/* Zparticles describe particles with class zero, using
30
   their absolute addresses*/
31
32
/* prepend particle count */
33
MPI_Address(&j, zzdisp);
34
zzdisp[1] = MPI_BOTTOM;
35
zztype[0] = MPI_INT;
36
zztype[1] = Zparticles;
37
MPI_Type_struct(2, zzblock, zzdisp, zztype, &Ztype);
38
39
MPI_Type_commit( &Ztype);
40
MPI_Send( MPI_BOTTOM, 1, Ztype, dest, tag, comm);
41
42
43
44

```

**Example 4.19** Handling of unions.

```

union {
    int    ival;
45
46
47
48

```

```

1      float    fval;
2      } u[1000];
3
4      int      utype;
5
6      /* All entries of u have identical type; variable
7         utype keeps track of their current type */
8
9      MPI_Datatype  type[2];
10     int           blocklen[2] = {1,1};
11     MPI_Aint      disp[2];
12     MPI_Datatype  mpi_utype[2];
13     MPI_Aint      i,j;
14
15     /* compute an MPI datatype for each possible union type;
16        assume values are left-aligned in union storage. */
17
18     MPI_Address( u, &i);
19     MPI_Address( u+1, &j);
20     disp[0] = 0; disp[1] = j-i;
21     type[1] = MPI_UB;
22
23     type[0] = MPI_INT;
24     MPI_Type_struct(2, blocklen, disp, type, &mpi_utype[0]);
25
26     type[0] = MPI_FLOAT;
27     MPI_Type_struct(2, blocklen, disp, type, &mpi_utype[1]);
28
29     for(i=0; i<2; i++) MPI_Type_commit(&mpi_utype[i]);
30
31     /* actual communication */
32
33     MPI_Send(u, 1000, mpi_utype[utype], dest, tag, comm);
34
35     Example 4.20 This example shows how a datatype can be decoded. The routine
36     printdatatype prints out the elements of the datatype. Note the use of MPI_Type_free for
37     datatypes that are not predefined.
38
39     /*
40        Example of decoding a datatype.
41
42        Returns 0 if the datatype is predefined, 1 otherwise
43        */
44     #include <stdio.h>
45     #include <stdlib.h>
46     #include "mpi.h"
47     int printdatatype( MPI_Datatype datatype )
48     {

```

```

int *array_of_ints;
MPI_Aint *array_of_adds;
MPI_Datatype *array_of_dtypes;
int num_ints, num_adds, num_dtypes, combiner;
int i;

MPI_Type_get_envelope( datatype,
                      &num_ints, &num_adds, &num_dtypes, &combiner );
switch (combiner) {
case MPI_COMBINER_NAMED:
    printf( "Datatype is named:" );
    /* To print the specific type, we can match against the
       predefined forms. We can NOT use a switch statement here
       We could also use MPI_TYPE_GET_NAME if we preferred to use
       names that the user may have changed.
    */
    if (datatype == MPI_INT)    printf( "MPI_INT\n" );
    else if (datatype == MPI_DOUBLE) printf( "MPI_DOUBLE\n" );
    ... else test for other types ...
    return 0;
    break;
case MPI_COMBINER_STRUCT:
case MPI_COMBINER_STRUCT_INTEGER:
    printf( "Datatype is struct containing" );
    array_of_ints = (int *)malloc( num_ints * sizeof(int) );
    array_of_adds =
        (MPI_Aint *) malloc( num_adds * sizeof(MPI_Aint) );
    array_of_dtypes = (MPI_Datatype *)
        malloc( num_dtypes * sizeof(MPI_Datatype) );
    MPI_Type_get_contents( datatype, num_ints, num_adds, num_dtypes,
                          array_of_ints, array_of_adds, array_of_dtypes );
    printf( " %d datatypes:\n", array_of_ints[0] );
    for (i=0; i<array_of_ints[0]; i++) {
        printf( "blocklength %d, displacement %ld, type:\n",
                array_of_ints[i+1], array_of_adds[i] );
        if (printdatatype( array_of_dtypes[i] )) {
            /* Note that we free the type ONLY if it
               is not predefined */
            MPI_Type_free( &array_of_dtypes[i] );
        }
    }
    free( array_of_ints );
    free( array_of_adds );
    free( array_of_dtypes );
    break;
    ... other combiner values ...
default:
    printf( "Unrecognized combiner type\n" );

```

```

1      }
2      return 1;
3  }

```

## 4.2 Pack and Unpack

Some existing communication libraries provide pack/unpack functions for sending noncontiguous data. In these, the user explicitly packs data into a contiguous buffer before sending it, and unpacks it from a contiguous buffer after receiving it. Derived datatypes, which are described in Section 4.1, allow one, in most cases, to avoid explicit packing and unpacking. The user specifies the layout of the data to be sent or received, and the communication library directly accesses a noncontiguous buffer. The pack/unpack routines are provided for compatibility with previous libraries. Also, they provide some functionality that is not otherwise available in MPI. For instance, a message can be received in several parts, where the receive operation done on a later part may depend on the content of a former part. Another use is that outgoing messages may be explicitly buffered in user supplied space, thus overriding the system buffering policy. Finally, the availability of pack and unpack operations facilitates the development of additional communication libraries layered on top of MPI.

**MPI\_PACK**(inbuf, incount, datatype, outbuf, outsize, position, comm)

IN	inbuf	input buffer start (choice)
IN	incount	number of input data items (non-negative integer)
IN	datatype	datatype of each input data item (handle)
OUT	outbuf	output buffer start (choice)
IN	outsize	output buffer size, in bytes (non-negative integer)
INOUT	position	current position in buffer, in bytes (integer)
IN	comm	communicator for packed message (handle)

```

int MPI_Pack(void* inbuf, int incount, MPI_Datatype datatype, void *outbuf,
            int outsize, int *position, MPI_Comm comm)

```

```

MPI_PACK(INBUF, INCOUNT, DATATYPE, OUTBUF, OUTSIZE, POSITION, COMM, IERROR)
<type> INBUF(*), OUTBUF(*)
INTEGER INCOUNT, DATATYPE, OUTSIZE, POSITION, COMM, IERROR

```

```

MPI_Pack(inbuf, incount, datatype, outbuf, outsize, position, comm, ierror)
TYPE(*), DIMENSION(..) :: inbuf, outbuf
INTEGER, INTENT(IN) :: incount, outsize
TYPE(MPI_Datatype), INTENT(IN) :: datatype
INTEGER, INTENT(INOUT) :: position
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```



```
{void MPI::Datatype::Pack(const void* inbuf, int incout, void *outbuf,
                          int outsize, int& position, const MPI::Comm &comm)
                          const(binding deprecated, see Section 15.2) }
```

Packs the message in the send buffer specified by `inbuf`, `incout`, `datatype` into the buffer space specified by `outbuf` and `outsize`. The input buffer can be any communication buffer allowed in `MPI_SEND`. The output buffer is a contiguous storage area containing `outsize` bytes, starting at the address `outbuf` (length is counted in bytes, not elements, as if it were a communication buffer for a message of type `MPI_PACKED`).

The input value of `position` is the first location in the output buffer to be used for packing. `position` is incremented by the size of the packed message, and the output value of `position` is the first location in the output buffer following the locations occupied by the packed message. The `comm` argument is the communicator that will be subsequently used for sending the packed message.

```
MPI_UNPACK(inbuf, insize, position, outbuf, outcount, datatype, comm)
```

IN	inbuf	input buffer start (choice)
IN	insize	size of input buffer, in bytes (non-negative integer)
INOUT	position	current position in bytes (integer)
OUT	outbuf	output buffer start (choice)
IN	outcount	number of items to be unpacked (integer)
IN	datatype	datatype of each output data item (handle)
IN	comm	communicator for packed message (handle)

```
int MPI_Unpack(void* inbuf, int insize, int *position, void *outbuf,
               int outcount, MPI_Datatype datatype, MPI_Comm comm)
```

```
MPI_UNPACK(INBUF, INSIZE, POSITION, OUTBUF, OUTCOUNT, DATATYPE, COMM,
            IERROR)
```

```
<type> INBUF(*), OUTBUF(*)
```

```
INTEGER INSIZE, POSITION, OUTCOUNT, DATATYPE, COMM, IERROR
```

```
MPI_Unpack(inbuf, insize, position, outbuf, outcount, datatype, comm,
            ierror)
```

```
TYPE(*), DIMENSION(..) :: inbuf, outbuf
```

```
INTEGER, INTENT(IN) :: insize, outcount
```

```
INTEGER, INTENT(INOUT) :: position
```

```
TYPE(MPI_Datatype), INTENT(IN) :: datatype
```

```
TYPE(MPI_Comm), INTENT(IN) :: comm
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Datatype::Unpack(const void* inbuf, int insize, void *outbuf,
                           int outcount, int& position, const MPI::Comm& comm)
                           const(binding deprecated, see Section 15.2) }
```

Unpacks a message into the receive buffer specified by `outbuf`, `outcount`, `datatype` from the buffer space specified by `inbuf` and `insize`. The output buffer can be any communication

buffer allowed in `MPI_RECV`. The input buffer is a contiguous storage area containing `insize` bytes, starting at address `inbuf`. The input value of `position` is the first location in the input buffer occupied by the packed message. `position` is incremented by the size of the packed message, so that the output value of `position` is the first location in the input buffer after the locations occupied by the message that was unpacked. `comm` is the communicator used to receive the packed message.

*Advice to users.* Note the difference between `MPI_RECV` and `MPI_UNPACK`: in `MPI_RECV`, the `count` argument specifies the maximum number of items that can be received. The actual number of items received is determined by the length of the incoming message. In `MPI_UNPACK`, the `count` argument specifies the actual number of items that are unpacked; the “size” of the corresponding message is the increment in `position`. The reason for this change is that the “incoming message size” is not predetermined since the user decides how much to unpack; nor is it easy to determine the “message size” from the number of items to be unpacked. In fact, in a heterogeneous system, this number may not be determined *a priori*. (*End of advice to users.*)

To understand the behavior of pack and unpack, it is convenient to think of the data part of a message as being the sequence obtained by concatenating the successive values sent in that message. The pack operation stores this sequence in the buffer space, as if sending the message to that buffer. The unpack operation retrieves this sequence from buffer space, as if receiving a message from that buffer. (It is helpful to think of internal Fortran files or `sscanf` in C, for a similar function.)

Several messages can be successively packed into one **packing unit**. This is effected by several successive **related** calls to `MPI_PACK`, where the first call provides `position = 0`, and each successive call inputs the value of `position` that was output by the previous call, and the same values for `outbuf`, `outcount` and `comm`. This packing unit now contains the equivalent information that would have been stored in a message by one send call with a send buffer that is the “concatenation” of the individual send buffers.

A packing unit can be sent using type `MPI_PACKED`. Any point to point or collective communication function can be used to move the sequence of bytes that forms the packing unit from one process to another. This packing unit can now be received using any receive operation, with any datatype: the type matching rules are relaxed for messages sent with type `MPI_PACKED`.

A message sent with any type (including `MPI_PACKED`) can be received using the type `MPI_PACKED`. Such a message can then be unpacked by calls to `MPI_UNPACK`.

A packing unit (or a message created by a regular, “typed” send) can be unpacked into several successive messages. This is effected by several successive related calls to `MPI_UNPACK`, where the first call provides `position = 0`, and each successive call inputs the value of `position` that was output by the previous call, and the same values for `inbuf`, `insize` and `comm`.

The concatenation of two packing units is not necessarily a packing unit; nor is a substring of a packing unit necessarily a packing unit. Thus, one cannot concatenate two packing units and then unpack the result as one packing unit; nor can one unpack a substring of a packing unit as a separate packing unit. Each packing unit, that was created by a related sequence of pack calls, or by a regular send, must be unpacked as a unit, by a sequence of related unpack calls.

*Rationale.* The restriction on “atomic” packing and unpacking of packing units allows the implementation to add at the head of packing units additional information, such as a description of the sender architecture (to be used for type conversion, in a heterogeneous environment) (*End of rationale.*)

The following call allows the user to find out how much space is needed to pack a message and, thus, manage space allocation for buffers.

`MPI_PACK_SIZE`(`incount`, `datatype`, `comm`, `size`)

IN	<code>incount</code>	count argument to packing call (non-negative integer)
IN	<code>datatype</code>	datatype argument to packing call (handle)
IN	<code>comm</code>	communicator argument to packing call (handle)
OUT	<code>size</code>	upper bound on size of packed message, in bytes (non-negative integer)

```
int MPI_Pack_size(int incount, MPI_Datatype datatype, MPI_Comm comm,
                  int *size)
```

```
MPI_PACK_SIZE(INCOUNT, DATATYPE, COMM, SIZE, IERROR)
INTEGER INCOUNT, DATATYPE, COMM, SIZE, IERROR
```

```
MPI_Pack_size(incount, datatype, comm, size, ierror)
  INTEGER, INTENT(IN) :: incount
  TYPE(MPI_Datatype), INTENT(IN) :: datatype
  TYPE(MPI_Comm), INTENT(IN) :: comm
  INTEGER, INTENT(OUT) :: size
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{int MPI::Datatype::Pack_size(int incount, const MPI::Comm& comm)
  const(binding deprecated, see Section 15.2) }
```

A call to `MPI_PACK_SIZE`(`incount`, `datatype`, `comm`, `size`) returns in `size` an upper bound on the increment in position that is effected by a call to `MPI_PACK`(`inbuf`, `incount`, `datatype`, `outbuf`, `outcount`, `position`, `comm`).

*Rationale.* The call returns an upper bound, rather than an exact bound, since the exact amount of space needed to pack the message may depend on the context (e.g., first message packed in a packing unit may take more space). (*End of rationale.*)

**Example 4.21** An example using `MPI_PACK`.

```

1  int      position, i, j, a[2];
2  char      buff[1000];
3
4  MPI_Comm_rank(MPI_COMM_WORLD, &myrank);
5  if (myrank == 0)
6  {
7      /* SENDER CODE */
8
9      position = 0;
10     MPI_Pack(&i, 1, MPI_INT, buff, 1000, &position, MPI_COMM_WORLD);
11     MPI_Pack(&j, 1, MPI_INT, buff, 1000, &position, MPI_COMM_WORLD);
12     MPI_Send( buff, position, MPI_PACKED, 1, 0, MPI_COMM_WORLD);
13 }
14 else /* RECEIVER CODE */
15     MPI_Recv( a, 2, MPI_INT, 0, 0, MPI_COMM_WORLD);
16
17

```

**Example 4.22** An elaborate example.

```

19  int  position, i;
20  float a[1000];
21  char  buff[1000];
22
23  MPI_Comm_rank(MPI_Comm_world, &myrank);
24  if (myrank == 0)
25  {
26      /* SENDER CODE */
27
28      int len[2];
29      MPI_Aint disp[2];
30      MPI_Datatype type[2], newtype;
31
32      /* build datatype for i followed by a[0]...a[i-1] */
33
34      len[0] = 1;
35      len[1] = i;
36      MPI_Address( &i, disp);
37      MPI_Address( a, disp+1);
38      type[0] = MPI_INT;
39      type[1] = MPI_FLOAT;
40      MPI_Type_struct( 2, len, disp, type, &newtype);
41      MPI_Type_commit( &newtype);
42
43      /* Pack i followed by a[0]...a[i-1]*/
44
45      position = 0;
46      MPI_Pack( MPI_BOTTOM, 1, newtype, buff, 1000, &position, MPI_COMM_WORLD);
47
48      /* Send */

```

```

MPI_Send( buff, position, MPI_PACKED, 1, 0,
          MPI_COMM_WORLD);

/* *****
   One can replace the last three lines with
   MPI_Send( MPI_BOTTOM, 1, newtype, 1, 0, MPI_COMM_WORLD);
   ***** */
}
else if (myrank == 1)
{
    /* RECEIVER CODE */

    MPI_Status status;

    /* Receive */

    MPI_Recv( buff, 1000, MPI_PACKED, 0, 0, MPI_COMM_WORLD, &status);

    /* Unpack i */

    position = 0;
    MPI_Unpack(buff, 1000, &position, &i, 1, MPI_INT, MPI_COMM_WORLD);

    /* Unpack a[0]...a[i-1] */
    MPI_Unpack(buff, 1000, &position, a, i, MPI_FLOAT, MPI_COMM_WORLD);
}

```

**Example 4.23** Each process sends a count, followed by count characters to the root; the root concatenates all characters into one string.

```

int  count, gsize, counts[64], totalcount, k1, k2, k,
     displs[64], position, concat_pos;
char chr[100], *lbuf, *rbuf, *cbuf;

MPI_Comm_size(comm, &gsize);
MPI_Comm_rank(comm, &myrank);

    /* allocate local pack buffer */
MPI_Pack_size(1, MPI_INT, comm, &k1);
MPI_Pack_size(count, MPI_CHAR, comm, &k2);
k = k1+k2;
lbuf = (char *)malloc(k);

    /* pack count, followed by count characters */
position = 0;
MPI_Pack(&count, 1, MPI_INT, lbuf, k, &position, comm);
MPI_Pack(chr, count, MPI_CHAR, lbuf, k, &position, comm);

```

```

1
2 if (myrank != root) {
3     /* gather at root sizes of all packed messages */
4     MPI_Gather( &position, 1, MPI_INT, NULL, 0,
5               MPI_DATATYPE_NULL, root, comm);
6
7     /* gather at root packed messages */
8     MPI_Gatherv( lbuf, position, MPI_PACKED, NULL,
9                 NULL, NULL, NULL, root, comm);
10
11 } else { /* root code */
12     /* gather sizes of all packed messages */
13     MPI_Gather( &position, 1, MPI_INT, counts, 1,
14               MPI_INT, root, comm);
15
16     /* gather all packed messages */
17     displs[0] = 0;
18     for (i=1; i < gsize; i++)
19         displs[i] = displs[i-1] + counts[i-1];
20     totalcount = displs[gsiz-1] + counts[gsiz-1];
21     rbuf = (char *)malloc(totalcount);
22     cbuf = (char *)malloc(totalcount);
23     MPI_Gatherv( lbuf, position, MPI_PACKED, rbuf,
24                 counts, displs, MPI_PACKED, root, comm);
25
26     /* unpack all messages and concatenate strings */
27     concat_pos = 0;
28     for (i=0; i < gsize; i++) {
29         position = 0;
30         MPI_Unpack( rbuf+displs[i], totalcount-displs[i],
31                   &position, &count, 1, MPI_INT, comm);
32         MPI_Unpack( rbuf+displs[i], totalcount-displs[i],
33                   &position, cbuf+concat_pos, count, MPI_CHAR, comm);
34         concat_pos += count;
35     }
36     cbuf[concat_pos] = '\0';
37 }
38
39
40

```

### 4.3 Canonical MPI\_PACK and MPI\_UNPACK

These functions read/write data to/from the buffer in the “external32” data format specified in Section 13.5.2, and calculate the size needed for packing. Their first arguments specify the data format, for future extensibility, but currently the only valid value of the `datarep` argument is “external32.”

*Advice to users.* These functions could be used, for example, to send typed data in a portable format from one MPI implementation to another. (*End of advice to users.*)

The buffer will contain exactly the packed data, without headers. MPI\_BYTE should be used to send and receive data that is packed using MPI\_PACK\_EXTERNAL.

*Rationale.* MPI\_PACK\_EXTERNAL specifies that there is no header on the message and further specifies the exact format of the data. Since MPI\_PACK may (and is allowed to) use a header, the datatype MPI\_PACKED cannot be used for data packed with MPI\_PACK\_EXTERNAL. (*End of rationale.*)

MPI\_PACK\_EXTERNAL(datarep, inbuf, incout, datatype, outbuf, outsize, position )

IN	datarep	data representation (string)
IN	inbuf	input buffer start (choice)
IN	incout	number of input data items (integer)
IN	datatype	datatype of each input data item (handle)
OUT	outbuf	output buffer start (choice)
IN	outsize	output buffer size, in bytes (integer)
INOUT	position	current position in buffer, in bytes (integer)

```
int MPI_Pack_external(char *datarep, void *inbuf, int incout,
                     MPI_Datatype datatype, void *outbuf, MPI_Aint outsize,
                     MPI_Aint *position)
```

```
MPI_PACK_EXTERNAL(DATAREP, INBUF, INCOUNT, DATATYPE, OUTBUF, OUTSIZE,
                  POSITION, IERROR)
INTEGER INCOUNT, DATATYPE, IERROR
INTEGER(KIND=MPI_ADDRESS_KIND) OUTSIZE, POSITION
CHARACTER*(*) DATAREP
<type> INBUF(*), OUTBUF(*)
```

```
MPI_Pack_external(datarep, inbuf, incout, datatype, outbuf, outsize,
                  position, ierror)
```

```
CHARACTER(LEN=*), INTENT(IN) :: datarep
TYPE(*), DIMENSION(..) :: inbuf, outbuf
INTEGER, INTENT(IN) :: incout
TYPE(MPI_Datatype), INTENT(IN) :: datatype
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: outsize
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(INOUT) :: position
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Datatype::Pack_external(const char* datarep, const void* inbuf,
int incout, void* outbuf, MPI::Aint outsize,
MPI::Aint& position) const(binding deprecated, see Section 15.2) }
```

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```

1 MPI_UNPACK_EXTERNAL(datarep, inbuf, insize, position, outbuf, outsize, position )
2
3     IN      datarep      data representation (string)
4     IN      inbuf       input buffer start (choice)
5     IN      insize      input buffer size, in bytes (integer)
6     INOUT   position    current position in buffer, in bytes (integer)
7     OUT     outbuf      output buffer start (choice)
8     IN      outcount    number of output data items (integer)
9     IN      datatype    datatype of output data item (handle)
10
11
12
13 int MPI_Unpack_external(char *datarep, void *inbuf, MPI_Aint insize,
14                        MPI_Aint *position, void *outbuf, int outcount,
15                        MPI_Datatype datatype)
16
17 MPI_UNPACK_EXTERNAL(DATAREP, INBUF, INSIZE, POSITION, OUTBUF, OUTCOUNT,
18                    DATATYPE, IERROR)
19
20 INTEGER OUTCOUNT, DATATYPE, IERROR
21 INTEGER(KIND=MPI_ADDRESS_KIND) INSIZE, POSITION
22 CHARACTER*(*) DATAREP
23 <type> INBUF(*), OUTBUF(*)
24
25 MPI_Unpack_external(datarep, inbuf, insize, position, outbuf, outcount,
26                    datatype, ierror)
27
28 CHARACTER(LEN=*), INTENT(IN) :: datarep
29 TYPE(*), DIMENSION(..) :: inbuf, outbuf
30 INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: insize
31 INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(INOUT) :: position
32 INTEGER, INTENT(IN) :: outcount
33 TYPE(MPI_Datatype), INTENT(IN) :: datatype
34 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
35
36 {void MPI::Datatype::Unpack_external(const char* datarep,
37                                     const void* inbuf, MPI::Aint insize, MPI::Aint& position,
38                                     void* outbuf, int outcount) const (binding deprecated, see
39                                     Section 15.2) }
40
41 MPI_PACK_EXTERNAL_SIZE( datarep, incount, datatype, size )
42
43     IN      datarep      data representation (string)
44     IN      incount      number of input data items (integer)
45     IN      datatype    datatype of each input data item (handle)
46     OUT     size        output buffer size, in bytes (integer)
47
48
49 int MPI_Pack_external_size(char *datarep, int incount,
50                           MPI_Datatype datatype, MPI_Aint *size)

```



```

MPI_PACK_EXTERNAL_SIZE(DATAREP, INCOUNT, DATATYPE, SIZE, IERROR)
    INTEGER INCOUNT, DATATYPE, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) SIZE
    CHARACTER*(*) DATAREP

```

```

MPI_Pack_external_size(datarep, incount, datatype, size, ierror)
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    INTEGER, INTENT(IN) :: incount
    CHARACTER(LEN=*), INTENT(IN) :: datarep
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: size
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{MPI::Aint MPI::Datatype::Pack_external_size(const char* datarep,
    int incount) const(binding deprecated, see Section 15.2) }

```

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# Chapter 5

## Collective Communication

### 5.1 Introduction and Overview

Collective communication is defined as communication that involves a group or groups of processes. The functions of this type provided by MPI are the following:

- **MPI\_BARRIER**, **MPI\_IBARRIER**: Barrier synchronization across all members of a group (Section 5.3 and Section 5.12.1).
- **MPI\_BCAST**, **MPI\_IBCAST**: Broadcast from one member to all members of a group (Section 5.4 and Section 5.12.2). This is shown as “broadcast” in Figure 5.1.
- **MPI\_GATHER**, **MPI\_IGATHER**, **MPI\_GATHERV**, **MPI\_IGATHERV**: Gather data from all members of a group to one member (Section 5.5 and Section 5.12.3). This is shown as “gather” in Figure 5.1.
- **MPI\_SCATTER**, **MPI\_ISCATTER**, **MPI\_SCATTERV**, **MPI\_ISCATTERV**: Scatter data from one member to all members of a group (Section 5.6 and Section 5.12.4). This is shown as “scatter” in Figure 5.1.
- **MPI\_ALLGATHER**, **MPI\_IALLGATHER**, **MPI\_ALLGATHERV**, **MPI\_IALLGATHERV**: A variation on Gather where all members of a group receive the result (Section 5.7 and Section 5.12.5). This is shown as “allgather” in Figure 5.1.
- **MPI\_ALLTOALL**, **MPI\_IALLTOALL**, **MPI\_ALLTOALLV**, **MPI\_IALLTOALLV**, **MPI\_ALLTOALLW**, **MPI\_IALLTOALLW**: Scatter/Gather data from all members to all members of a group (also called complete exchange) (Section 5.8 and Section 5.12.6). This is shown as “complete exchange” in Figure 5.1.
- **MPI\_ALLREDUCE**, **MPI\_IALLREDUCE**, **MPI\_REDUCE**, **MPI\_IREDUCE**: Global reduction operations such as sum, max, min, or user-defined functions, where the result is returned to all members of a group (Section 5.9.6 and Section 5.12.8) and a variation where the result is returned to only one member (Section 5.9 and Section 5.12.7).
- **MPI\_REDUCE\_SCATTER**, **MPI\_IREDUCE\_SCATTER**, **MPI\_REDUCE\_SCATTER\_BLOCK**, **MPI\_IREDUCE\_SCATTER\_BLOCK**: A combined reduction and scatter operation (Section 5.10 and Section 5.12.10).

- `MPI_SCAN`, `MPI_ISCAN`, `MPI_EXSCAN`, `MPI_IEXSCAN`: Scan across all members of a group (also called prefix) (Section 5.11, Section 5.11.2, Section 5.12.11, and Section 5.12.12).

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One of the key arguments in a call to a collective routine is a communicator that defines the group or groups of participating processes and provides a context for the operation. This is discussed further in Section 5.2. The syntax and semantics of the collective operations are defined to be consistent with the syntax and semantics of the point-to-point operations. Thus, general datatypes are allowed and must match between sending and receiving processes as specified in Chapter 4. Several collective routines such as broadcast and gather have a single originating or receiving process. Such a process is called the *root*. Some arguments in the collective functions are specified as “significant only at root,” and are ignored for all participants except the root. The reader is referred to Chapter 4 for information concerning communication buffers, general datatypes and type matching rules, and to Chapter 6 for information on how to define groups and create communicators.

The type-matching conditions for the collective operations are more strict than the corresponding conditions between sender and receiver in point-to-point. Namely, for collective operations, the amount of data sent must exactly match the amount of data specified by the receiver. Different type maps (the layout in memory, see Section 4.1) between sender and receiver are still allowed.

Collective operations can (but are not required to) complete as soon as the caller’s participation in the collective communication is finished. A blocking operation is complete as soon as the call returns. A nonblocking (immediate) call requires a separate completion call (cf. Section 3.7). The completion of a collective operation indicates that the caller is free to modify locations in the communication buffer. It does not indicate that other processes in the group have completed or even started the operation (unless otherwise implied by the description of the operation). Thus, a collective communication function may, or may not, have the effect of synchronizing all calling processes. This statement excludes, of course, the barrier operation.

Collective communication calls may use the same communicators as point-to-point communication; MPI guarantees that messages generated on behalf of collective communication calls will not be confused with messages generated by point-to-point communication. The collective operations do not have a message tag argument. A more detailed discussion of correct use of collective routines is found in Section 5.13.

*Rationale.* The equal-data restriction (on type matching) was made so as to avoid the complexity of providing a facility analogous to the status argument of `MPI_RECV` for discovering the amount of data sent. Some of the collective routines would require an array of status values.

The statements about synchronization are made so as to allow a variety of implementations of the collective functions.

(End of rationale.)

*Advice to users.* It is dangerous to rely on synchronization side-effects of the collective operations for program correctness. For example, even though a particular implementation may provide a broadcast routine with a side-effect of synchronization, the standard does not require this, and a program that relies on this will not be portable.

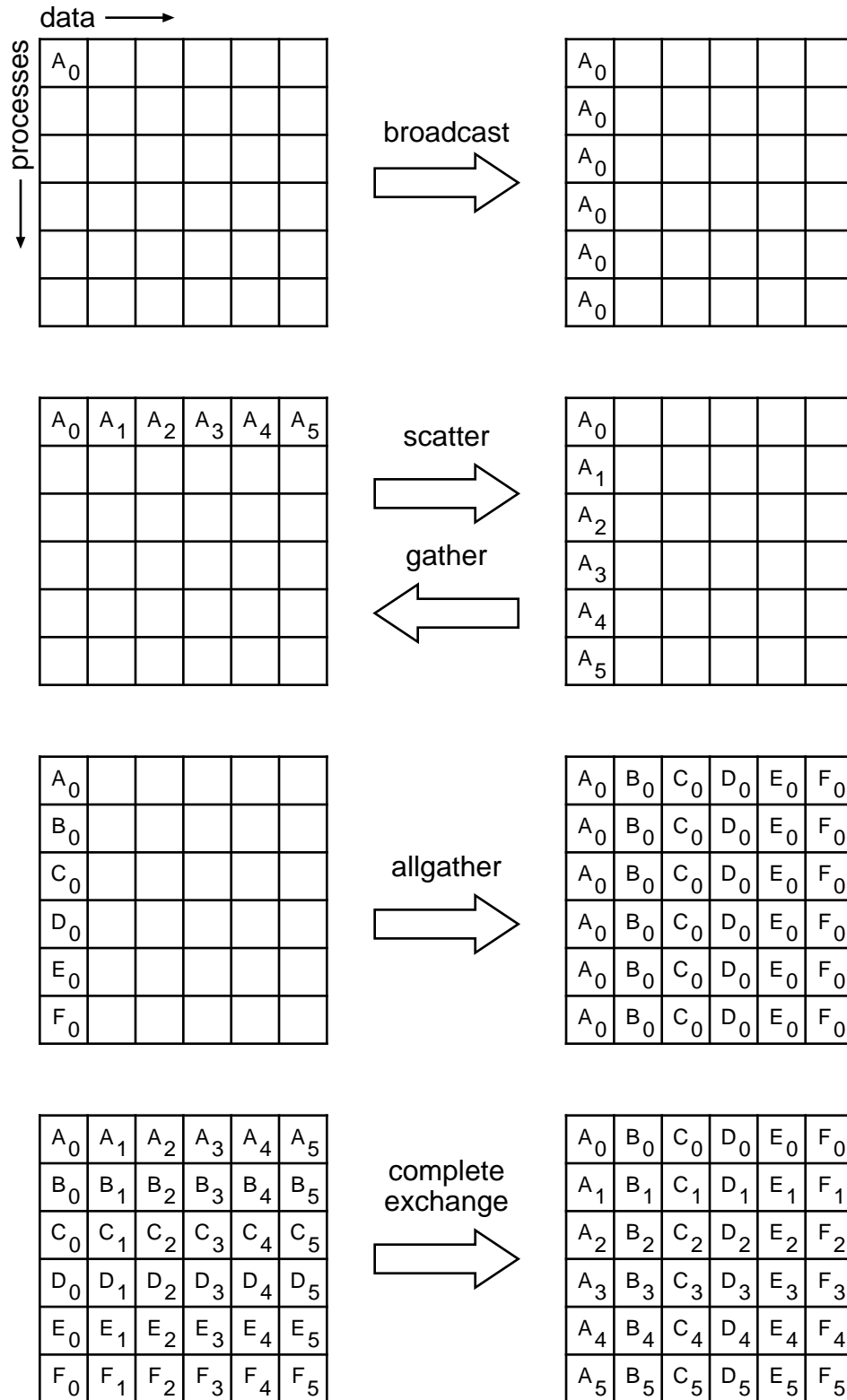


Figure 5.1: Collective move functions illustrated for a group of six processes. In each case, each row of boxes represents data locations in one process. Thus, in the broadcast, initially just the first process contains the data  $A_0$ , but after the broadcast all processes contain it.

On the other hand, a correct, portable program must allow for the fact that a collective call *may* be synchronizing. Though one cannot rely on any synchronization side-effect, one must program so as to allow it. These issues are discussed further in Section 5.13. (*End of advice to users.*)

*Advice to implementors.* While vendors may write optimized collective routines matched to their architectures, a complete library of the collective communication routines can be written entirely using the MPI point-to-point communication functions and a few auxiliary functions. If implementing on top of point-to-point, a hidden, special communicator might be created for the collective operation so as to avoid interference with any on-going point-to-point communication at the time of the collective call. This is discussed further in Section 5.13. (*End of advice to implementors.*)

Many of the descriptions of the collective routines provide illustrations in terms of blocking MPI point-to-point routines. These are intended solely to indicate what data is sent or received by what process. Many of these examples are *not* correct MPI programs; for purposes of simplicity, they often assume infinite buffering.

## 5.2 Communicator Argument

The key concept of the collective functions is to have a group or groups of participating processes. The routines do not have group identifiers as explicit arguments. Instead, there is a communicator argument. Groups and communicators are discussed in full detail in Chapter 6. For the purposes of this chapter, it is sufficient to know that there are two types of communicators: *intra-communicators* and *inter-communicators*. An intracommunicator can be thought of as an identifier for a single group of processes linked with a context. An intercommunicator identifies two distinct groups of processes linked with a context.

### 5.2.1 Specifics for Intracommunicator Collective Operations

All processes in the group identified by the intracommunicator must call the collective routine.

In many cases, collective communication can occur “in place” for intracommunicators, with the output buffer being identical to the input buffer. This is specified by providing a special argument value, `MPI_IN_PLACE`, instead of the send buffer or the receive buffer argument, depending on the operation performed.

*Rationale.* The “in place” operations are provided to reduce unnecessary memory motion by both the MPI implementation and by the user. Note that while the simple check of testing whether the send and receive buffers have the same address will work for some cases (e.g., `MPI_ALLREDUCE`), they are inadequate in others (e.g., `MPI_GATHER`, with root not equal to zero). Further, Fortran explicitly prohibits aliasing of arguments; the approach of using a special value to denote “in place” operation eliminates that difficulty. (*End of rationale.*)

*Advice to users.* By allowing the “in place” option, the receive buffer in many of the collective calls becomes a send-and-receive buffer. For this reason, a Fortran binding that includes `INTENT` must mark these as `INOUT`, not `OUT`.

Note that `MPI_IN_PLACE` is a special kind of value; it has the same restrictions on its use that `MPI_BOTTOM` has. (*End of advice to users.*)

### 5.2.2 Applying Collective Operations to Intercommunicators

To understand how collective operations apply to intercommunicators, we can view most MPI intracommunicator collective operations as fitting one of the following categories (see, for instance, [51]):

**All-To-All** All processes contribute to the result. All processes receive the result.

- `MPI_ALLGATHER`, `MPI_IALLGATHER`, `MPI_ALLGATHERV`, `MPI_IALLGATHERV`
- `MPI_ALLTOALL`, `MPI_IALLTOALL`, `MPI_ALLTOALLV`, `MPI_IALLTOALLV`, `MPI_ALLTOALLW`, `MPI_IALLTOALLW`
- `MPI_ALLREDUCE`, `MPI_IALLREDUCE`, `MPI_REDUCE_SCATTER`, `MPI_IREDUCE_SCATTER`, `MPI_REDUCE_SCATTER_BLOCK`, `MPI_IREDUCE_SCATTER_BLOCK`
- `MPI_BARRIER`, `MPI_IBARRIER`

**All-To-One** All processes contribute to the result. One process receives the result.

- `MPI_GATHER`, `MPI_IGATHER`, `MPI_GATHERV`, `MPI_IGATHERV`
- `MPI_REDUCE`, `MPI_IREDUCE`

**One-To-All** One process contributes to the result. All processes receive the result.

- `MPI_BCAST`, `MPI_IBCAST`
- `MPI_SCATTER`, `MPI_ISCATTER`, `MPI_SCATTERV`, `MPI_ISCATTERV`

**Other** Collective operations that do not fit into one of the above categories.

- `MPI_SCAN`, `MPI_ISCAN`, `MPI_EXSCAN`, `MPI_IEXSCAN`

The data movement patterns of `MPI_SCAN`, `MPI_ISCAN`, `MPI_EXSCAN`, and `MPI_IEXSCAN` do not fit this taxonomy.

The application of collective communication to intercommunicators is best described in terms of two groups. For example, an all-to-all `MPI_ALLGATHER` operation can be described as collecting data from all members of one group with the result appearing in all members of the other group (see Figure 5.2). As another example, a one-to-all `MPI_BCAST` operation sends data from one member of one group to all members of the other group. Collective computation operations such as `MPI_REDUCE_SCATTER` have a similar interpretation (see Figure 5.3). For intracommunicators, these two groups are the same. For intercommunicators, these two groups are distinct. For the all-to-all operations, each such operation is described in two phases, so that it has a symmetric, full-duplex behavior.

The following collective operations also apply to intercommunicators:

- `MPI_BARRIER`, `MPI_IBARRIER`
- `MPI_BCAST`, `MPI_IBCAST`

- MPI\_GATHER, MPI\_IGATHER, MPI\_GATHERV, MPI\_IGATHERV,
- MPI\_SCATTER, MPI\_ISCATTER, MPI\_SCATTERV, MPI\_ISCATTERV,
- MPI\_ALLGATHER, MPI\_IALLGATHER, MPI\_ALLGATHERV, MPI\_IALLGATHERV,
- MPI\_ALLTOALL, MPI\_IALLTOALL, MPI\_ALLTOALLV, MPI\_IALLTOALLV,  
MPI\_ALLTOALLW, MPI\_IALLTOALLW,
- MPI\_ALLREDUCE, MPI\_IALLREDUCE, MPI\_REDUCE, MPI\_IREDUCE,
- MPI\_REDUCE\_SCATTER, MPI\_IREDUCE\_SCATTER, MPI\_REDUCE\_SCATTER\_BLOCK,  
MPI\_IREDUCE\_SCATTER\_BLOCK.

In C++, the bindings for these functions are in the `MPI::Comm` class. However, since the collective operations do not make sense on a C++ `MPI::Comm` (as it is neither an intercommunicator nor an intracommunicator), the functions are all pure virtual.

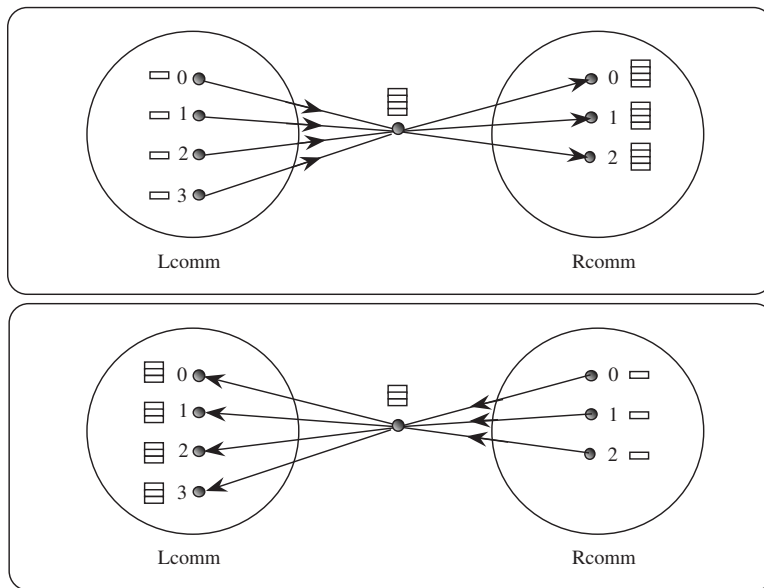


Figure 5.2: Intercommunicator allgather. The focus of data to one process is represented, not mandated by the semantics. The two phases do allgathers in both directions.

### 5.2.3 Specifics for Intercommunicator Collective Operations

All processes in both groups identified by the intercommunicator must call the collective routine.

Note that the “in place” option for intracommunicators does not apply to intercommunicators since in the intercommunicator case there is no communication from a process to itself.

For intercommunicator collective communication, if the operation is in the All-To-One or One-To-All categories, then the transfer is unidirectional. The direction of the transfer is indicated by a special value of the root argument. In this case, for the group containing the root process, all processes in the group must call the routine using a special argument for



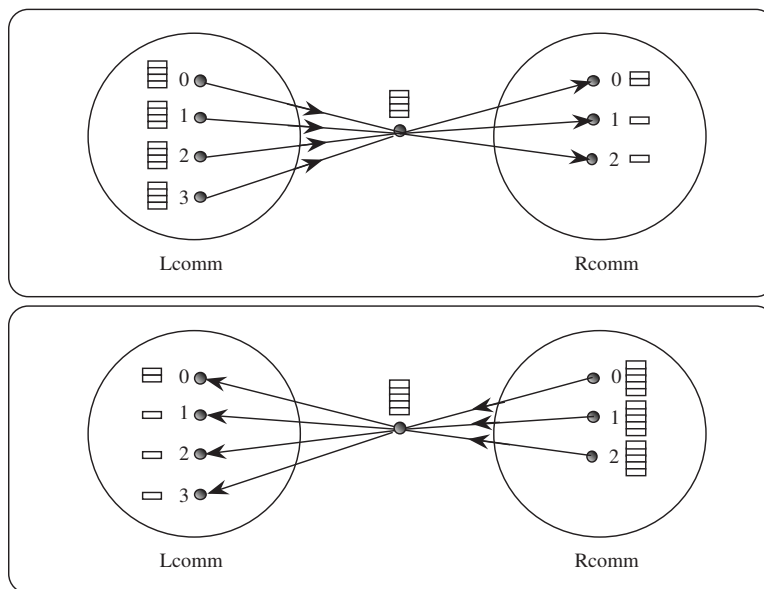


Figure 5.3: Intercommunicator reduce-scatter. The focus of data to one process is represented, not mandated by the semantics. The two phases do reduce-scatters in both directions.

the root. For this, the root process uses the special root value `MPI_ROOT`; all other processes in the same group as the root use `MPI_PROC_NULL`. All processes in the other group (the group that is the remote group relative to the root process) must call the collective routine and provide the rank of the root. If the operation is in the All-To-All category, then the transfer is bidirectional.

*Rationale.* Operations in the All-To-One and One-To-All categories are unidirectional by nature, and there is a clear way of specifying direction. Operations in the All-To-All category will often occur as part of an exchange, where it makes sense to communicate in both directions at once. (*End of rationale.*)

### 5.3 Barrier Synchronization

`MPI_BARRIER(comm)`

IN            comm                            communicator (handle)

`int MPI_Barrier(MPI_Comm comm)`

`MPI_BARRIER(COMM, IERROR)`  
 INTEGER COMM, IERROR

`MPI_Barrier(comm, ierror)`  
 TYPE(MPI\_Comm), INTENT(IN) :: comm  
 INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```
{void MPI::Comm::Barrier() const = 0(binding deprecated, see Section 15.2) }
```

If `comm` is an intracommunicator, `MPI_BARRIER` blocks the caller until all group members have called it. The call returns at any process only after all group members have entered the call.

If `comm` is an intercommunicator, `MPI_BARRIER` involves two groups. The call returns at processes in one group (group A) of the intercommunicator only after all members of the other group (group B) have entered the call (and vice versa). A process may return from the call before all processes in its own group have entered the call.

## 5.4 Broadcast

```
MPI_BCAST(buffer, count, datatype, root, comm)
```

INOUT	buffer	starting address of buffer (choice)
IN	count	number of entries in buffer (non-negative integer)
IN	datatype	data type of buffer (handle)
IN	root	rank of broadcast root (integer)
IN	comm	communicator (handle)

```
int MPI_Bcast(void* buffer, int count, MPI_Datatype datatype, int root,
              MPI_Comm comm)
```

```
MPI_BCAST(BUFFER, COUNT, DATATYPE, ROOT, COMM, IERROR)
<type> BUFFER(*)
INTEGER COUNT, DATATYPE, ROOT, COMM, IERROR
```

```
MPI_Bcast(buffer, count, datatype, root, comm, ierror)
TYPE(*), DIMENSION(..) :: buffer
INTEGER, INTENT(IN) :: count, root
TYPE(MPI_Datatype), INTENT(IN) :: datatype
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Comm::Bcast(void* buffer, int count,
                       const MPI::Datatype& datatype, int root) const = 0(binding
deprecated, see Section 15.2) }
```

If `comm` is an intracommunicator, `MPI_BCAST` broadcasts a message from the process with rank `root` to all processes of the group, itself included. It is called by all members of the group using the same arguments for `comm` and `root`. On return, the content of `root`'s buffer is copied to all other processes.

General, derived datatypes are allowed for `datatype`. The type signature of `count`, `datatype` on any process must be equal to the type signature of `count`, `datatype` at the root. This implies that the amount of data sent must be equal to the amount received, pairwise between each process and the root. `MPI_BCAST` and all other data-movement collective

routines make this restriction. Distinct type maps between sender and receiver are still allowed.

The “in place” option is not meaningful here.

If `comm` is an intercommunicator, then the call involves all processes in the intercommunicator, but with one group (group A) defining the root process. All processes in the other group (group B) pass the same value in argument `root`, which is the rank of the root in group A. The root passes the value `MPI_ROOT` in `root`. All other processes in group A pass the value `MPI_PROC_NULL` in `root`. Data is broadcast from the root to all processes in group B. The buffer arguments of the processes in group B must be consistent with the buffer argument of the root.

#### 5.4.1 Example using MPI\_BCAST

The examples in this section use intracommunicators.

##### Example 5.1

Broadcast 100 ints from process 0 to every process in the group.

```
MPI_Comm comm;
int array[100];
int root=0;
...
MPI_Bcast(array, 100, MPI_INT, root, comm);
```

As in many of our example code fragments, we assume that some of the variables (such as `comm` in the above) have been assigned appropriate values.

## 5.5 Gather

`MPI_GATHER(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, root, comm)`

IN	sendbuf	starting address of send buffer (choice)
IN	sendcount	number of elements in send buffer (non-negative integer)
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice, significant only at root)
IN	recvcount	number of elements for any single receive (non-negative integer, significant only at root)
IN	recvtype	data type of recv buffer elements (significant only at root) (handle)
IN	root	rank of receiving process (integer)
IN	comm	communicator (handle)

```
int MPI_Gather(void* sendbuf, int sendcount, MPI_Datatype sendtype,
              void* recvbuf, int recvcount, MPI_Datatype recvtype, int root,
```

```

1      MPI_Comm comm)
2
3  MPI_GATHER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, REVCOUNT, RECVTYPE,
4            ROOT, COMM, IERROR)
5      <type> SENDBUF(*), RECVBUF(*)
6      INTEGER SENDCOUNT, SENDTYPE, REVCOUNT, RECVTYPE, ROOT, COMM, IERROR
7
8  MPI_Gather(sendbuf, sendcount, sendtype, recvbuf, recvcnt, recvtpe,
9            root, comm, ierror)
10     TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
11     INTEGER, INTENT(IN) :: sendcount, recvcnt, root
12     TYPE(MPI_Datatype), INTENT(IN) :: sendtype
13     TYPE(MPI_Datatype), INTENT(IN) :: recvtpe
14     TYPE(MPI_Comm), INTENT(IN) :: comm
15     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
16
17 {void MPI::Comm::Gather(const void* sendbuf, int sendcount, const
18     MPI::Datatype& sendtype, void* recvbuf, int recvcnt,
19     const MPI::Datatype& recvtpe, int root) const = 0(binding
20     deprecated, see Section 15.2) }
```

If `comm` is an intracommunicator, each process (root process included) sends the contents of its send buffer to the root process. The root process receives the messages and stores them in rank order. The outcome is *as if* each of the `n` processes in the group (including the root process) had executed a call to

```
MPI_Send(sendbuf, sendcount, sendtype, root, ...),
```

and the root had executed `n` calls to

```
MPI_Recv(recvbuf + i · recvcnt · extent(recvtpe), recvcnt, recvtpe, i, ...),
```

where `extent(recvtpe)` is the type extent obtained from a call to `MPI_Type_get_extent()`.

An alternative description is that the `n` messages sent by the processes in the group are concatenated in rank order, and the resulting message is received by the root as if by a call to `MPI_RECV(recvbuf, recvcnt·n, recvtpe, ...)`.

The receive buffer is ignored for all non-root processes.

General, derived datatypes are allowed for both `sendtype` and `recvtpe`. The type signature of `sendcount`, `sendtype` on each process must be equal to the type signature of `recvcnt`, `recvtpe` at the root. This implies that the amount of data sent must be equal to the amount of data received, pairwise between each process and the root. Distinct type maps between sender and receiver are still allowed.

All arguments to the function are significant on process `root`, while on other processes, only arguments `sendbuf`, `sendcount`, `sendtype`, `root`, and `comm` are significant. The arguments `root` and `comm` must have identical values on all processes.

The specification of counts and types should not cause any location on the root to be written more than once. Such a call is erroneous.

Note that the `recvcnt` argument at the root indicates the number of items it receives from *each* process, not the total number of items it receives.

The “in place” option for intracommunicators is specified by passing `MPI_IN_PLACE` as the value of `sendbuf` at the root. In such a case, `sendcount` and `sendtype` are ignored, and

the contribution of the root to the gathered vector is assumed to be already in the correct place in the receive buffer.

If `comm` is an intercommunicator, then the call involves all processes in the intercommunicator, but with one group (group A) defining the root process. All processes in the other group (group B) pass the same value in argument `root`, which is the rank of the root in group A. The root passes the value `MPI_ROOT` in `root`. All other processes in group A pass the value `MPI_PROC_NULL` in `root`. Data is gathered from all processes in group B to the root. The send buffer arguments of the processes in group B must be consistent with the receive buffer argument of the root.

`MPI_GATHERV(sendbuf, sendcount, sendtype, recvbuf, recvcunts, displs, recvtype, root, comm)`

IN	sendbuf	starting address of send buffer (choice)
IN	sendcount	number of elements in send buffer (non-negative integer)
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice, significant only at root)
IN	recvcunts	non-negative integer array (of length group size) containing the number of elements that are received from each process (significant only at root)
IN	displs	integer array (of length group size). Entry <code>i</code> specifies the displacement relative to <code>recvbuf</code> at which to place the incoming data from process <code>i</code> (significant only at root)
IN	recvtype	data type of recv buffer elements (significant only at root) (handle)
IN	root	rank of receiving process (integer)
IN	comm	communicator (handle)

```
int MPI_Gatherv(void* sendbuf, int sendcount, MPI_Datatype sendtype,
               void* recvbuf, int recvcunts[], int displs[],
               MPI_Datatype recvtype, int root, MPI_Comm comm)
```

```
MPI_GATHERV(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNTS, DISPLS,
            RECVTYPE, ROOT, COMM, IERROR)
```

```
<type> SENDBUF(*), RECVBUF(*)
INTEGER SENDCOUNT, SENDTYPE, RECVCOUNTS(*), DISPLS(*), RECVTYPE, ROOT,
COMM, IERROR
```

```
MPI_Gatherv(sendbuf, sendcount, sendtype, recvbuf, recvcunts, displs,
            recvtype, root, comm, ierror)
```

```
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
INTEGER, INTENT(IN) :: sendcount, recvcunts(*), displs(*), root
TYPE(MPI_Datatype), INTENT(IN) :: sendtype
```

```

1      TYPE(MPI_Datatype), INTENT(IN) :: recvtype
2      TYPE(MPI_Comm), INTENT(IN) :: comm
3      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
4
5      {void MPI::Comm::Gatherv(const void* sendbuf, int sendcount, const
6          MPI::Datatype& sendtype, void* recvbuf,
7          const int recvcnts[], const int displs[],
8          const MPI::Datatype& recvtype, int root) const = 0(binding
9          deprecated, see Section 15.2) }

```

MPI\_GATHERV extends the functionality of MPI\_GATHER by allowing a varying count of data from each process, since `recvcnts` is now an array. It also allows more flexibility as to where the data is placed on the root, by providing the new argument, `displs`.

If `comm` is an intracommunicator, the outcome is *as if* each process, including the root process, sends a message to the root,

```
MPI_Send(sendbuf, sendcount, sendtype, root, ...),
```

and the root executes `n` receives,

```
MPI_Recv(recvbuf + displs[j] * extent(recvtype), recvcnts[j], recvtype, i, ...).
```

The data received from process `j` is placed into `recvbuf` of the root process beginning at offset `displs[j]` elements (in terms of the `recvtype`).

The receive buffer is ignored for all non-root processes.

The type signature implied by `sendcount`, `sendtype` on process `i` must be equal to the type signature implied by `recvcnts[i]`, `recvtype` at the root. This implies that the amount of data sent must be equal to the amount of data received, pairwise between each process and the root. Distinct type maps between sender and receiver are still allowed, as illustrated in Example 5.6.

All arguments to the function are significant on process `root`, while on other processes, only arguments `sendbuf`, `sendcount`, `sendtype`, `root`, and `comm` are significant. The arguments `root` and `comm` must have identical values on all processes.

The specification of counts, types, and displacements should not cause any location on the root to be written more than once. Such a call is erroneous.

The “in place” option for intracommunicators is specified by passing `MPI_IN_PLACE` as the value of `sendbuf` at the root. In such a case, `sendcount` and `sendtype` are ignored, and the contribution of the root to the gathered vector is assumed to be already in the correct place in the receive buffer.

If `comm` is an intercommunicator, then the call involves all processes in the intercommunicator, but with one group (group A) defining the root process. All processes in the other group (group B) pass the same value in argument `root`, which is the rank of the root in group A. The root passes the value `MPI_ROOT` in `root`. All other processes in group A pass the value `MPI_PROC_NULL` in `root`. Data is gathered from all processes in group B to the root. The send buffer arguments of the processes in group B must be consistent with the receive buffer argument of the root.

### 5.5.1 Examples using MPI\_GATHER, MPI\_GATHERV

The examples in this section use intracommunicators.

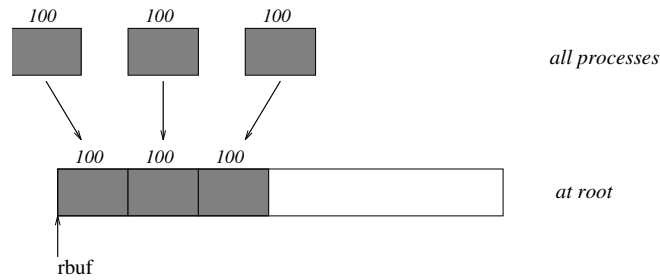


Figure 5.4: The root process gathers 100 ints from each process in the group.

### Example 5.2

Gather 100 ints from every process in group to root. See Figure 5.4.

```
MPI_Comm comm;
int gsize, sendarray[100];
int root, *rbuf;
...
MPI_Comm_size(comm, &gsize);
rbuf = (int *)malloc(gsize*100*sizeof(int));
MPI_Gather(sendarray, 100, MPI_INT, rbuf, 100, MPI_INT, root, comm);
```

### Example 5.3

Previous example modified – only the root allocates memory for the receive buffer.

```
MPI_Comm comm;
int gsize, sendarray[100];
int root, myrank, *rbuf;
...
MPI_Comm_rank(comm, &myrank);
if (myrank == root) {
    MPI_Comm_size(comm, &gsize);
    rbuf = (int *)malloc(gsize*100*sizeof(int));
}
MPI_Gather(sendarray, 100, MPI_INT, rbuf, 100, MPI_INT, root, comm);
```

### Example 5.4

Do the same as the previous example, but use a derived datatype. Note that the type cannot be the entire set of `gsize*100` ints since type matching is defined pairwise between the root and each process in the gather.

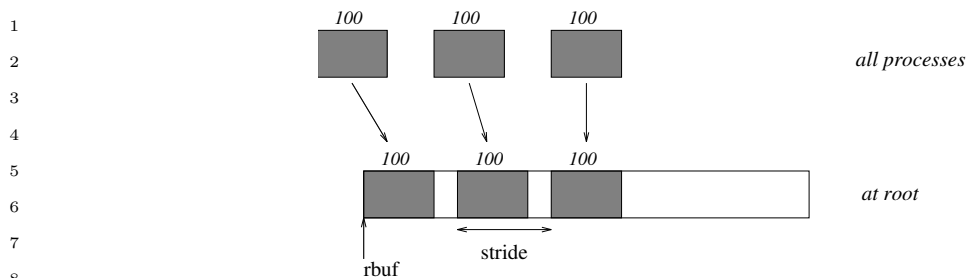


Figure 5.5: The root process gathers 100 ints from each process in the group, each set is placed `stride` ints apart.

```

13 MPI_Comm comm;
14 int gsize, sendarray[100];
15 int root, *rbuf;
16 MPI_Datatype rtype;
17 ...
18 MPI_Comm_size(comm, &gsize);
19 MPI_Type_contiguous(100, MPI_INT, &rtype);
20 MPI_Type_commit(&rtype);
21 rbuf = (int *)malloc(gsize*100*sizeof(int));
22 MPI_Gather(sendarray, 100, MPI_INT, rbuf, 1, rtype, root, comm);

```

### Example 5.5

Now have each process send 100 ints to root, but place each set (of 100) `stride` ints apart at receiving end. Use `MPI_GATHERV` and the `displs` argument to achieve this effect. Assume  $stride \geq 100$ . See Figure 5.5.

```

29 MPI_Comm comm;
30 int gsize, sendarray[100];
31 int root, *rbuf, stride;
32 int *displs, i, *rcounts;
33 ...
34 ...
35 ...
36 MPI_Comm_size(comm, &gsize);
37 rbuf = (int *)malloc(gsize*stride*sizeof(int));
38 displs = (int *)malloc(gsize*sizeof(int));
39 rcounts = (int *)malloc(gsize*sizeof(int));
40 for (i=0; i<gsize; ++i) {
41     displs[i] = i*stride;
42     rcounts[i] = 100;
43 }
44 MPI_Gatherv(sendarray, 100, MPI_INT, rbuf, rcounts, displs, MPI_INT,
45                                                     root, comm);

```

Note that the program is erroneous if  $stride < 100$ .



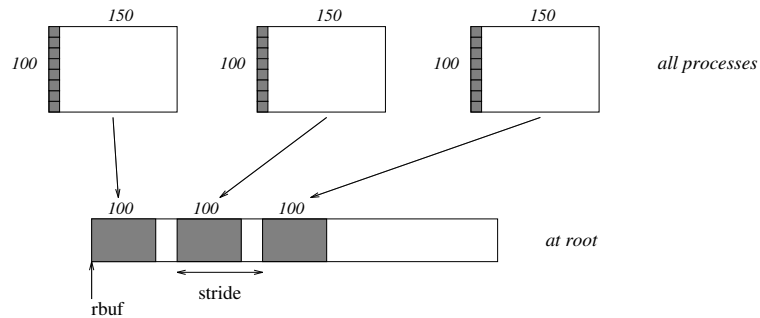


Figure 5.6: The root process gathers column 0 of a 100×150 C array, and each set is placed `stride` ints apart.

### Example 5.6

Same as Example 5.5 on the receiving side, but send the 100 ints from the 0th column of a 100×150 int array, in C. See Figure 5.6.

```

MPI_Comm comm;
int gsize, sendarray[100][150];
int root, *rbuf, stride;
MPI_Datatype stype;
int *displs, i, *rcounts;

...

MPI_Comm_size(comm, &gsize);
rbuf = (int *)malloc(gsize*stride*sizeof(int));
displs = (int *)malloc(gsize*sizeof(int));
rcounts = (int *)malloc(gsize*sizeof(int));
for (i=0; i<gsize; ++i) {
    displs[i] = i*stride;
    rcounts[i] = 100;
}
/* Create datatype for 1 column of array
 */
MPI_Type_vector(100, 1, 150, MPI_INT, &stype);
MPI_Type_commit(&stype);
MPI_Gatherv(sendarray, 1, stype, rbuf, rcounts, displs, MPI_INT,
            root, comm);

```

### Example 5.7

Process `i` sends  $(100-i)$  ints from the `i`-th column of a  $100 \times 150$  int array, in C. It is received into a buffer with stride, as in the previous two examples. See Figure 5.7.

```

MPI_Comm comm;
int gsize, sendarray[100][150], *sptr;
int root, *rbuf, stride, myrank;
MPI_Datatype stype;

```

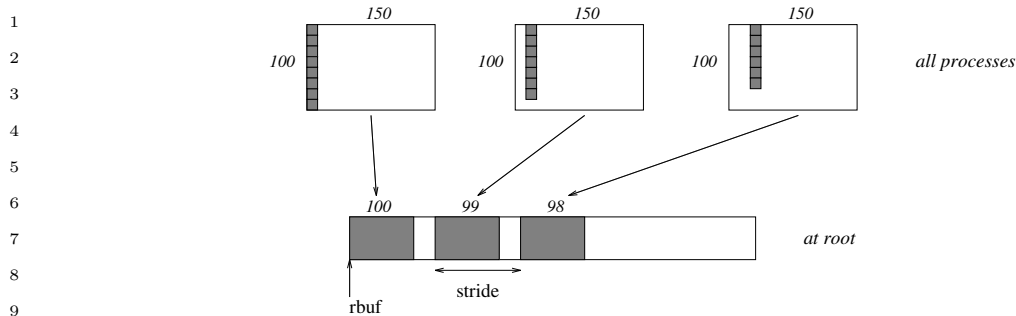


Figure 5.7: The root process gathers  $100-i$  ints from column  $i$  of a  $100 \times 150$  C array, and each set is placed `stride` ints apart.

```

14  int *displs,i,*rcounts;
15
16  ...
17
18  MPI_Comm_size(comm, &gsize);
19  MPI_Comm_rank(comm, &myrank);
20  rbuf = (int *)malloc(gsize*stride*sizeof(int));
21  displs = (int *)malloc(gsize*sizeof(int));
22  rcounts = (int *)malloc(gsize*sizeof(int));
23  for (i=0; i<gsize; ++i) {
24      displs[i] = i*stride;
25      rcounts[i] = 100-i;      /* note change from previous example */
26  }
27  /* Create datatype for the column we are sending
28   */
29  MPI_Type_vector(100-myrank, 1, 150, MPI_INT, &stype);
30  MPI_Type_commit(&stype);
31  /* sptr is the address of start of "myrank" column
32   */
33  sptr = &sendarray[0][myrank];
34  MPI_Gatherv(sptr, 1, stype, rbuf, rcounts, displs, MPI_INT,
35              root, comm);

```

Note that a different amount of data is received from each process.

### Example 5.8

Same as Example 5.7, but done in a different way at the sending end. We create a datatype that causes the correct striding at the sending end so that we read a column of a C array. A similar thing was done in Example 4.16, Section 4.1.14.

```

43  MPI_Comm comm;
44  int gsize,sendarray[100][150],*sptr;
45  int root,*rbuf, stride, myrank, disp[2], blocklen[2];
46  MPI_Datatype stype,type[2];
47  int *displs,i,*rcounts;
48

```

```

...
MPI_Comm_size(comm, &gsize);
MPI_Comm_rank(comm, &myrank);
rbuf = (int *)malloc(gsize*stride*sizeof(int));
displs = (int *)malloc(gsize*sizeof(int));
rcounts = (int *)malloc(gsize*sizeof(int));
for (i=0; i<gsize; ++i) {
    displs[i] = i*stride;
    rcounts[i] = 100-i;
}
/* Create datatype for one int, with extent of entire row
*/
disp[0] = 0;      disp[1] = 150*sizeof(int);
type[0] = MPI_INT; type[1] = MPI_UB;
blocklen[0] = 1;  blocklen[1] = 1;
MPI_Type_create_struct(2, blocklen, disp, type, &stype);
MPI_Type_commit(&stype);
sptr = &sendarray[0][myrank];
MPI_Gatherv(sptr, 100-myrank, stype, rbuf, rcounts, displs, MPI_INT,
                                                    root, comm);

```

### Example 5.9

Same as Example 5.7 at sending side, but at receiving side we make the stride between received blocks vary from block to block. See Figure 5.8.

```

MPI_Comm comm;
int gsize, sendarray[100][150], *sptr;
int root, *rbuf, *stride, myrank, bufsize;
MPI_Datatype stype;
int *displs, i, *rcounts, offset;

...

MPI_Comm_size(comm, &gsize);
MPI_Comm_rank(comm, &myrank);

stride = (int *)malloc(gsize*sizeof(int));
...
/* stride[i] for i = 0 to gsize-1 is set somehow
*/

/* set up displs and rcounts vectors first
*/
displs = (int *)malloc(gsize*sizeof(int));
rcounts = (int *)malloc(gsize*sizeof(int));
offset = 0;

```

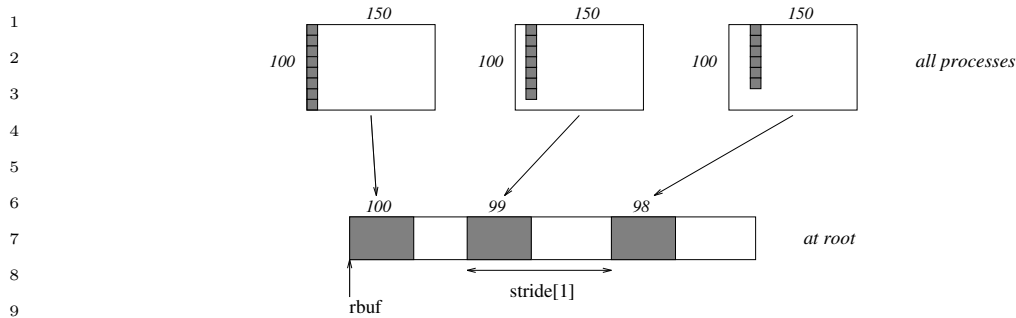


Figure 5.8: The root process gathers 100- $i$  ints from column  $i$  of a 100 $\times$ 150 C array, and each set is placed  $\text{stride}[i]$  ints apart (a varying stride).

```

14     for (i=0; i<gsize; ++i) {
15         displs[i] = offset;
16         offset += stride[i];
17         rcounts[i] = 100-i;
18     }
19     /* the required buffer size for rbuf is now easily obtained
20     */
21     bufsize = displs[gsize-1]+rcounts[gsize-1];
22     rbuf = (int *)malloc(bufsize*sizeof(int));
23     /* Create datatype for the column we are sending
24     */
25     MPI_Type_vector(100-myrank, 1, 150, MPI_INT, &stype);
26     MPI_Type_commit(&stype);
27     sptr = &sendarray[0][myrank];
28     MPI_Gatherv(sptr, 1, stype, rbuf, rcounts, displs, MPI_INT,
29                root, comm);

```

### Example 5.10

Process  $i$  sends  $\text{num}$  ints from the  $i$ -th column of a  $100 \times 150$  int array, in C. The complicating factor is that the various values of  $\text{num}$  are not known to root, so a separate gather must first be run to find these out. The data is placed contiguously at the receiving end.

```

37     MPI_Comm comm;
38     int gsize, sendarray[100][150], *sptr;
39     int root, *rbuf, myrank, disp[2], blocklen[2];
40     MPI_Datatype stype, type[2];
41     int *displs, i, *rcounts, num;
42
43     ...
44
45     MPI_Comm_size(comm, &gsize);
46     MPI_Comm_rank(comm, &myrank);
47
48     /* First, gather nums to root

```

```

    */
    rcounts = (int *)malloc(gsize*sizeof(int));
    MPI_Gather(&num, 1, MPI_INT, rcounts, 1, MPI_INT, root, comm);
    /* root now has correct rcounts, using these we set displs[] so
     * that data is placed contiguously (or concatenated) at receive end
     */
    displs = (int *)malloc(gsize*sizeof(int));
    displs[0] = 0;
    for (i=1; i<gsize; ++i) {
        displs[i] = displs[i-1]+rcounts[i-1];
    }
    /* And, create receive buffer
     */
    rbuf = (int *)malloc(gsize*(displs[gsize-1]+rcounts[gsize-1])
                        *sizeof(int));

    /* Create datatype for one int, with extent of entire row
     */
    disp[0] = 0;      disp[1] = 150*sizeof(int);
    type[0] = MPI_INT; type[1] = MPI_UB;
    blocklen[0] = 1;  blocklen[1] = 1;
    MPI_Type_create_struct( 2, blocklen, disp, type, &stype );
    MPI_Type_commit(&stype);
    sptr = &sendarray[0][myrank];
    MPI_Gatherv(sptr, num, stype, rbuf, rcounts, displs, MPI_INT,
                root, comm);

```

## 5.6 Scatter

**MPI\_SCATTER**(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, root, comm)

IN	sendbuf	address of send buffer (choice, significant only at root)
IN	sendcount	number of elements sent to each process (non-negative integer, significant only at root)
IN	sendtype	data type of send buffer elements (significant only at root) (handle)
OUT	recvbuf	address of receive buffer (choice)
IN	recvcount	number of elements in receive buffer (non-negative integer)
IN	recvtype	data type of receive buffer elements (handle)
IN	root	rank of sending process (integer)
IN	comm	communicator (handle)

```

int MPI_Scatter(void* sendbuf, int sendcount, MPI_Datatype sendtype,
               void* recvbuf, int recvcount, MPI_Datatype recvtype, int root,

```

```

1      MPI_Comm comm)
2
3  MPI_SCATTER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, REVCOUNT, RECVTYPE,
4             ROOT, COMM, IERROR)
5      <type> SENDBUF(*), RECVBUF(*)
6      INTEGER SENDCOUNT, SENDTYPE, REVCOUNT, RECVTYPE, ROOT, COMM, IERROR
7  MPI_Scatter(sendbuf, sendcount, sendtype, recvbuf, recvcnt, recvtpe,
8             root, comm, ierror)
9      TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
10     INTEGER, INTENT(IN) :: sendcount, recvcnt, root
11     TYPE(MPI_Datatype), INTENT(IN) :: sendtype
12     TYPE(MPI_Datatype), INTENT(IN) :: recvtpe
13     TYPE(MPI_Comm), INTENT(IN) :: comm
14     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
15
16 {void MPI::Comm::Scatter(const void* sendbuf, int sendcount, const
17     MPI::Datatype& sendtype, void* recvbuf, int recvcnt,
18     const MPI::Datatype& recvtpe, int root) const = 0(binding
19     deprecated, see Section 15.2) }

```

MPI\_SCATTER is the inverse operation to MPI\_GATHER.

If comm is an intracommunicator, the outcome is *as if* the root executed n send operations,

```
MPI_Send(sendbuf + i · sendcount · extent(sendtype), sendcount, sendtype, i, ...),
```

and each process executed a receive,

```
MPI_Recv(recvbuf, recvcnt, recvtpe, i, ...).
```

An alternative description is that the root sends a message with MPI\_Send(sendbuf, sendcount·n, sendtype, ...). This message is split into n equal segments, the *i*-th segment is sent to the *i*-th process in the group, and each process receives this message as above.

The send buffer is ignored for all non-root processes.

The type signature associated with sendcount, sendtype at the root must be equal to the type signature associated with recvcnt, recvtpe at all processes (however, the type maps may be different). This implies that the amount of data sent must be equal to the amount of data received, pairwise between each process and the root. Distinct type maps between sender and receiver are still allowed.

All arguments to the function are significant on process root, while on other processes, only arguments recvbuf, recvcnt, recvtpe, root, and comm are significant. The arguments root and comm must have identical values on all processes.

The specification of counts and types should not cause any location on the root to be read more than once.

*Rationale.* Though not needed, the last restriction is imposed so as to achieve symmetry with MPI\_GATHER, where the corresponding restriction (a multiple-write restriction) is necessary. (*End of rationale.*)

The “in place” option for intracommunicators is specified by passing MPI\_IN\_PLACE as the value of recvbuf at the root. In such a case, recvcnt and recvtpe are ignored, and

root “sends” no data to itself. The scattered vector is still assumed to contain  $n$  segments, where  $n$  is the group size; the *root*-th segment, which root should “send to itself,” is not moved.

If *comm* is an intercommunicator, then the call involves all processes in the intercommunicator, but with one group (group A) defining the root process. All processes in the other group (group B) pass the same value in argument *root*, which is the rank of the root in group A. The root passes the value `MPI_ROOT` in *root*. All other processes in group A pass the value `MPI_PROC_NULL` in *root*. Data is scattered from the root to all processes in group B. The receive buffer arguments of the processes in group B must be consistent with the send buffer argument of the root.

`MPI_SCATTERV(sendbuf, sendcounts, displs, sendtype, recvbuf, recvcount, recvtype, root, comm)`

IN	<code>sendbuf</code>	address of send buffer (choice, significant only at root)
IN	<code>sendcounts</code>	non-negative integer array (of length group size) specifying the number of elements to send to each processor
IN	<code>displs</code>	integer array (of length group size). Entry <i>i</i> specifies the displacement (relative to <code>sendbuf</code> ) from which to take the outgoing data to process <i>i</i>
IN	<code>sendtype</code>	data type of send buffer elements (handle)
OUT	<code>recvbuf</code>	address of receive buffer (choice)
IN	<code>recvcount</code>	number of elements in receive buffer (non-negative integer)
IN	<code>recvtype</code>	data type of receive buffer elements (handle)
IN	<code>root</code>	rank of sending process (integer)
IN	<code>comm</code>	communicator (handle)

```
int MPI_Scatterv(void* sendbuf, int sendcounts[], int displs[],
                MPI_Datatype sendtype, void* recvbuf, int recvcount,
                MPI_Datatype recvtype, int root, MPI_Comm comm)
```

```
MPI_SCATTERV(SENDBUF, SENDCOUNTS, DISPLS, SENDTYPE, RECVBUF, REVCOUNT,
             RECVTYPE, ROOT, COMM, IERROR)
<type> SENDBUF(*), RECVBUF(*)
INTEGER SENDCOUNTS(*), DISPLS(*), SENDTYPE, REVCOUNT, RECVTYPE, ROOT,
COMM, IERROR
```

```
MPI_Scatterv(sendbuf, sendcounts, displs, sendtype, recvbuf, recvcount,
             recvtype, root, comm, ierror)
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
INTEGER, INTENT(IN) :: sendcounts(*), displs(*), recvcount, root
TYPE(MPI_Datatype), INTENT(IN) :: sendtype
TYPE(MPI_Datatype), INTENT(IN) :: recvtype
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```

1 {void MPI::Comm::Scatterv(const void* sendbuf, const int sendcounts[],
2     const int displs[], const MPI::Datatype& sendtype,
3     void* recvbuf, int recvcount, const MPI::Datatype& recvttype,
4     int root) const = 0(binding deprecated, see Section 15.2) }

```

MPI\_SCATTERV is the inverse operation to MPI\_GATHERV.

MPI\_SCATTERV extends the functionality of MPI\_SCATTER by allowing a varying count of data to be sent to each process, since `sendcounts` is now an array. It also allows more flexibility as to where the data is taken from on the root, by providing an additional argument, `displs`.

If `comm` is an intracommunicator, the outcome is as if the root executed `n` send operations,

```
MPI_Send(sendbuf + displs[i] * extent(sendtype), sendcounts[i], sendtype, i, ...),
```

and each process executed a receive,

```
MPI_Recv(recvbuf, recvcount, recvttype, i, ...).
```

The send buffer is ignored for all non-root processes.

The type signature implied by `sendcount[i]`, `sendtype` at the root must be equal to the type signature implied by `recvcount`, `recvttype` at process `i` (however, the type maps may be different). This implies that the amount of data sent must be equal to the amount of data received, pairwise between each process and the root. Distinct type maps between sender and receiver are still allowed.

All arguments to the function are significant on process `root`, while on other processes, only arguments `recvbuf`, `recvcount`, `recvttype`, `root`, and `comm` are significant. The arguments `root` and `comm` must have identical values on all processes.

The specification of counts, types, and displacements should not cause any location on the root to be read more than once.

The “in place” option for intracommunicators is specified by passing `MPI_IN_PLACE` as the value of `recvbuf` at the root. In such a case, `recvcount` and `recvttype` are ignored, and root “sends” no data to itself. The scattered vector is still assumed to contain  $n$  segments, where  $n$  is the group size; the *root*-th segment, which root should “send to itself,” is not moved.

If `comm` is an intercommunicator, then the call involves all processes in the intercommunicator, but with one group (group A) defining the root process. All processes in the other group (group B) pass the same value in argument `root`, which is the rank of the root in group A. The root passes the value `MPI_ROOT` in `root`. All other processes in group A pass the value `MPI_PROC_NULL` in `root`. Data is scattered from the root to all processes in group B. The receive buffer arguments of the processes in group B must be consistent with the send buffer argument of the root.

### 5.6.1 Examples using MPI\_SCATTER, MPI\_SCATTERV

The examples in this section use intracommunicators.

#### Example 5.11

The reverse of Example 5.2. Scatter sets of 100 ints from the root to each process in the group. See Figure 5.9.



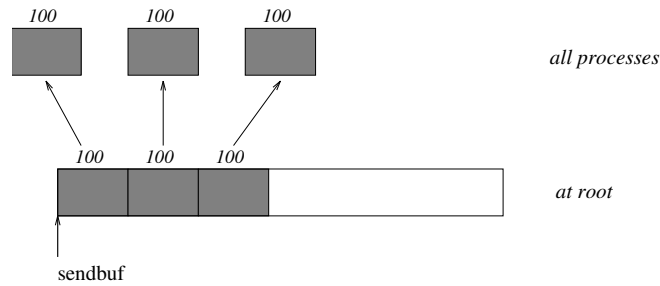


Figure 5.9: The root process scatters sets of 100 ints to each process in the group.

```

MPI_Comm comm;
int gsize,*sendbuf;
int root, rbuf[100];
...
MPI_Comm_size(comm, &gsize);
sendbuf = (int *)malloc(gsize*100*sizeof(int));
...
MPI_Scatter(sendbuf, 100, MPI_INT, rbuf, 100, MPI_INT, root, comm);

```

### Example 5.12

The reverse of Example 5.5. The root process scatters sets of 100 ints to the other processes, but the sets of 100 are *stride ints* apart in the sending buffer. Requires use of MPI\_SCATTERV. Assume  $stride \geq 100$ . See Figure 5.10.

```

MPI_Comm comm;
int gsize,*sendbuf;
int root, rbuf[100], i, *displs, *scounts;
...

MPI_Comm_size(comm, &gsize);
sendbuf = (int *)malloc(gsize*stride*sizeof(int));
...
displs = (int *)malloc(gsize*sizeof(int));
scounts = (int *)malloc(gsize*sizeof(int));
for (i=0; i<gsize; ++i) {
    displs[i] = i*stride;
    scounts[i] = 100;
}
MPI_Scatterv(sendbuf, scounts, displs, MPI_INT, rbuf, 100, MPI_INT,
             root, comm);

```

### Example 5.13

The reverse of Example 5.9. We have a varying stride between blocks at sending (root) side, at the receiving side we receive into the  $i$ -th column of a  $100 \times 150$  C array. See Figure 5.11.

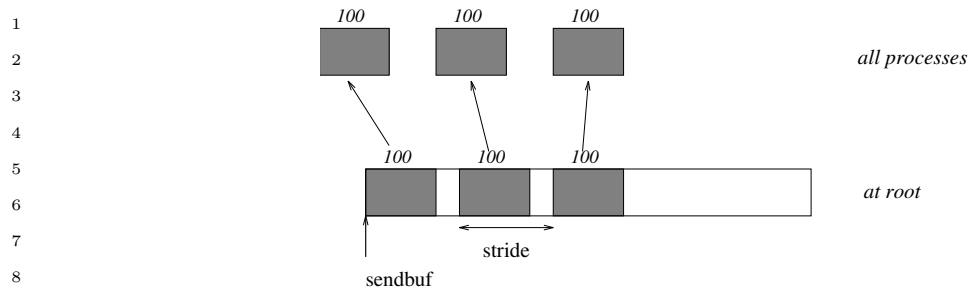


Figure 5.10: The root process scatters sets of 100 ints, moving by `stride` ints from send to send in the scatter.

```

13 MPI_Comm comm;
14 int gsize, recvarray[100][150], *rptr;
15 int root, *sendbuf, myrank, *stride;
16 MPI_Datatype rtype;
17 int i, *displs, *scounts, offset;
18 ...
19 MPI_Comm_size(comm, &gsize);
20 MPI_Comm_rank(comm, &myrank);
21
22 stride = (int *)malloc(gsize*sizeof(int));
23 ...
24 /* stride[i] for i = 0 to gsize-1 is set somehow
25  * sendbuf comes from elsewhere
26  */
27 ...
28 displs = (int *)malloc(gsize*sizeof(int));
29 scounts = (int *)malloc(gsize*sizeof(int));
30 offset = 0;
31 for (i=0; i<gsize; ++i) {
32     displs[i] = offset;
33     offset += stride[i];
34     scounts[i] = 100 - i;
35 }
36 /* Create datatype for the column we are receiving
37  */
38 MPI_Type_vector(100-myrank, 1, 150, MPI_INT, &rtype);
39 MPI_Type_commit(&rtype);
40 rptr = &recvarray[0][myrank];
41 MPI_Scatterv(sendbuf, scounts, displs, MPI_INT, rptr, 1, rtype,
42             root, comm);

```

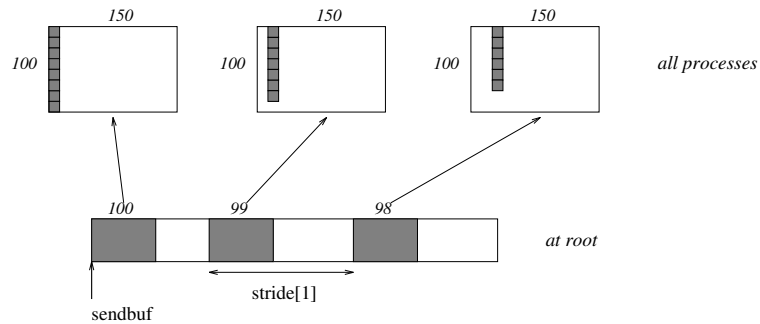


Figure 5.11: The root scatters blocks of  $100-i$  ints into column  $i$  of a  $100 \times 150$  C array. At the sending side, the blocks are `stride[i]` ints apart.

## 5.7 Gather-to-all

<code>MPI_ALLGATHER(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, comm)</code>		
IN	<code>sendbuf</code>	starting address of send buffer (choice)
IN	<code>sendcount</code>	number of elements in send buffer (non-negative integer)
IN	<code>sendtype</code>	data type of send buffer elements (handle)
OUT	<code>recvbuf</code>	address of receive buffer (choice)
IN	<code>recvcount</code>	number of elements received from any process (non-negative integer)
IN	<code>recvtype</code>	data type of receive buffer elements (handle)
IN	<code>comm</code>	communicator (handle)

```
int MPI_Allgather(void* sendbuf, int sendcount, MPI_Datatype sendtype,
                 void* recvbuf, int recvcount, MPI_Datatype recvtype,
                 MPI_Comm comm)
```

```
MPI_ALLGATHER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, REVCOUNT, RECVTYPE,
              COMM, IERROR)
```

```
<type> SENDBUF(*), RECVBUF(*)
```

```
INTEGER SENDCOUNT, SENDTYPE, REVCOUNT, RECVTYPE, COMM, IERROR
```

```
MPI_Allgather(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype,
              comm, ierror)
```

```
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
```

```
INTEGER, INTENT(IN) :: sendcount, recvcount
```

```
TYPE(MPI_Datatype), INTENT(IN) :: sendtype
```

```
TYPE(MPI_Datatype), INTENT(IN) :: recvtype
```

```
TYPE(MPI_Comm), INTENT(IN) :: comm
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

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```

1 {void MPI::Comm::Allgather(const void* sendbuf, int sendcount, const
2     MPI::Datatype& sendtype, void* recvbuf, int recvcount,
3     const MPI::Datatype& recvttype) const = 0(binding deprecated, see
4     Section 15.2) }

```

MPI\_ALLGATHER can be thought of as MPI\_GATHER, but where all processes receive the result, instead of just the root. The block of data sent from the  $j$ -th process is received by every process and placed in the  $j$ -th block of the buffer `recvbuf`.

The type signature associated with `sendcount`, `sendtype`, at a process must be equal to the type signature associated with `recvcount`, `recvttype` at any other process.

If `comm` is an intracommunicator, the outcome of a call to `MPI_ALLGATHER(...)` is as if all processes executed `n` calls to

```

13 MPI_Gather(sendbuf, sendcount, sendtype, recvbuf, recvcount,
14           recvttype, root, comm)
15

```

for `root = 0, ..., n-1`. The rules for correct usage of `MPI_ALLGATHER` are easily found from the corresponding rules for `MPI_GATHER`.

The “in place” option for intracommunicators is specified by passing the value `MPI_IN_PLACE` to the argument `sendbuf` at all processes. `sendcount` and `sendtype` are ignored. Then the input data of each process is assumed to be in the area where that process would receive its own contribution to the receive buffer.

If `comm` is an intercommunicator, then each process of one group (group A) contributes `sendcount` data items; these data are concatenated and the result is stored at each process in the other group (group B). Conversely the concatenation of the contributions of the processes in group B is stored at each process in group A. The send buffer arguments in group A must be consistent with the receive buffer arguments in group B, and vice versa.

*Advice to users.* The communication pattern of `MPI_ALLGATHER` executed on an intercommunication domain need not be symmetric. The number of items sent by processes in group A (as specified by the arguments `sendcount`, `sendtype` in group A and the arguments `recvcount`, `recvttype` in group B), need not equal the number of items sent by processes in group B (as specified by the arguments `sendcount`, `sendtype` in group B and the arguments `recvcount`, `recvttype` in group A). In particular, one can move data in only one direction by specifying `sendcount = 0` for the communication in the reverse direction.

*(End of advice to users.)*

`MPI_ALLGATHERV(sendbuf, sendcount, sendtype, recvbuf, recvcunts, displs, recvtype, comm)`

IN	sendbuf	starting address of send buffer (choice)
IN	sendcount	number of elements in send buffer (non-negative integer)
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice)
IN	recvcunts	non-negative integer array (of length group size) containing the number of elements that are received from each process
IN	displs	integer array (of length group size). Entry <i>i</i> specifies the displacement (relative to <code>recvbuf</code> ) at which to place the incoming data from process <i>i</i>
IN	recvtype	data type of receive buffer elements (handle)
IN	comm	communicator (handle)

```
int MPI_Allgatherv(void* sendbuf, int sendcount, MPI_Datatype sendtype,
                  void* recvbuf, int recvcunts[], int displs[],
                  MPI_Datatype recvtype, MPI_Comm comm)
```

```
MPI_ALLGATHERV(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNTS, DISPLS,
               RECVTYPE, COMM, IERROR)
<type> SENDBUF(*), RECVBUF(*)
INTEGER SENDCOUNT, SENDTYPE, RECVCOUNTS(*), DISPLS(*), RECVTYPE, COMM,
IERROR
```

```
MPI_Allgatherv(sendbuf, sendcount, sendtype, recvbuf, recvcunts, displs,
               recvtype, comm, ierror)
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
INTEGER, INTENT(IN) :: sendcount, recvcunts(*), displs(*)
TYPE(MPI_Datatype), INTENT(IN) :: sendtype
TYPE(MPI_Datatype), INTENT(IN) :: recvtype
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Comm::Allgatherv(const void* sendbuf, int sendcount, const
                          MPI::Datatype& sendtype, void* recvbuf,
                          const int recvcunts[], const int displs[],
                          const MPI::Datatype& recvtype) const = 0(binding deprecated, see
                          Section 15.2) }
```

`MPI_ALLGATHERV` can be thought of as `MPI_GATHERV`, but where all processes receive the result, instead of just the root. The block of data sent from the *j*-th process is received by every process and placed in the *j*-th block of the buffer `recvbuf`. These blocks need not all be the same size.

The type signature associated with `sendcount`, `sendtype`, at process *j* must be equal to the type signature associated with `recvcunts[j]`, `recvtype` at any other process.

If `comm` is an intracommunicator, the outcome is as if all processes executed calls to

```
MPI_GATHERV(sendbuf, sendcount, sendtype, recvbuf, recvcnts, displs,
            recvtype, root, comm),
```

for `root = 0, ..., n-1`. The rules for correct usage of `MPI_ALLGATHERV` are easily found from the corresponding rules for `MPI_GATHERV`.

The “in place” option for intracommunicators is specified by passing the value `MPI_IN_PLACE` to the argument `sendbuf` at all processes. In such a case, `sendcount` and `sendtype` are ignored, and the input data of each process is assumed to be in the area where that process would receive its own contribution to the receive buffer.

If `comm` is an intercommunicator, then each process of one group (group A) contributes `sendcount` data items; these data are concatenated and the result is stored at each process in the other group (group B). Conversely the concatenation of the contributions of the processes in group B is stored at each process in group A. The send buffer arguments in group A must be consistent with the receive buffer arguments in group B, and vice versa.

### 5.7.1 Example using `MPI_ALLGATHER`

The example in this section uses intracommunicators.

#### Example 5.14

The all-gather version of Example 5.2. Using `MPI_ALLGATHER`, we will gather 100 `ints` from every process in the group to every process.

```
MPI_Comm comm;
int gsize, sendarray[100];
int *rbuf;
...
MPI_Comm_size(comm, &gsize);
rbuf = (int *)malloc(gsize*100*sizeof(int));
MPI_Allgather(sendarray, 100, MPI_INT, rbuf, 100, MPI_INT, comm);
```

After the call, every process has the group-wide concatenation of the sets of data.

## 5.8 All-to-All Scatter/Gather

```
MPI_ALLTOALL(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, comm)
```

IN	sendbuf	starting address of send buffer (choice)
IN	sendcount	number of elements sent to each process (non-negative integer)
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice)
IN	recvcount	number of elements received from any process (non-negative integer)
IN	recvtype	data type of receive buffer elements (handle)
IN	comm	communicator (handle)

```
int MPI_Alltoall(void* sendbuf, int sendcount, MPI_Datatype sendtype,
                void* recvbuf, int recvcount, MPI_Datatype recvtype,
                MPI_Comm comm)
```

```
MPI_ALLTOALL(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, REVCOUNT, RECVTYPE,
              COMM, IERROR)
```

```
<type> SENDBUF(*), RECVBUF(*)
```

```
INTEGER SENDCOUNT, SENDTYPE, REVCOUNT, RECVTYPE, COMM, IERROR
```

```
MPI_Alltoall(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype,
              comm, ierror)
```

```
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
```

```
INTEGER, INTENT(IN) :: sendcount, recvcount
```

```
TYPE(MPI_Datatype), INTENT(IN) :: sendtype
```

```
TYPE(MPI_Datatype), INTENT(IN) :: recvtype
```

```
TYPE(MPI_Comm), INTENT(IN) :: comm
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Comm::Alltoall(const void* sendbuf, int sendcount, const
                          MPI::Datatype& sendtype, void* recvbuf, int recvcount,
                          const MPI::Datatype& recvtype) const = 0 (binding deprecated, see
                          Section 15.2) }
```

MPI\_ALLTOALL is an extension of MPI\_ALLGATHER to the case where each process sends distinct data to each of the receivers. The  $j$ -th block sent from process  $i$  is received by process  $j$  and is placed in the  $i$ -th block of `recvbuf`.

The type signature associated with `sendcount`, `sendtype`, at a process must be equal to the type signature associated with `recvcount`, `recvtype` at any other process. This implies that the amount of data sent must be equal to the amount of data received, pairwise between every pair of processes. As usual, however, the type maps may be different.

If `comm` is an intracommunicator, the outcome is as if each process executed a send to each process (itself included) with a call to,

```
MPI_Send(sendbuf + i · sendcount · extent(sendtype), sendcount, sendtype, i, ...),
```

and a receive from every other process with a call to,

```
MPI_Recv(recvbuf + i · recvcount · extent(recvtype), recvcount, recvtype, i, ...).
```

All arguments on all processes are significant. The argument `comm` must have identical values on all processes.

The “in place” option for intracommunicators is specified by passing `MPI_IN_PLACE` to the argument `sendbuf` at *all* processes. In such a case, `sendcount` and `sendtype` are ignored. The data to be sent is taken from the `recvbuf` and replaced by the received data. Data sent and received must have the same type map as specified by `recvcount` and `recvtype`.

*Rationale.* For large `MPI_ALLTOALL` instances, allocating both send and receive buffers may consume too much memory. The “in place” option effectively halves the application memory consumption and is useful in situations where the data to be sent will not be used by the sending process after the `MPI_ALLTOALL` exchange (e.g., in parallel Fast Fourier Transforms). (*End of rationale.*)

*Advice to implementors.* Users may opt to use the “in place” option in order to conserve memory. Quality MPI implementations should thus strive to minimize system buffering. (*End of advice to implementors.*)

If `comm` is an intercommunicator, then the outcome is as if each process in group A sends a message to each process in group B, and vice versa. The *j*-th send buffer of process *i* in group A should be consistent with the *i*-th receive buffer of process *j* in group B, and vice versa.

*Advice to users.* When a complete exchange is executed on an intercommunication domain, then the number of data items sent from processes in group A to processes in group B need not equal the number of items sent in the reverse direction. In particular, one can have unidirectional communication by specifying `sendcount = 0` in the reverse direction.

(*End of advice to users.*)



MPI\_ALLTOALLV(sendbuf, sendcounts, sdispls, sendtype, recvbuf, recvcoun-  
ts, rdispls, recv-  
type, comm)

IN	sendbuf	starting address of send buffer (choice)
IN	sendcounts	non-negative integer array (of length group size) specifying the number of elements to send to each processor
IN	sdispls	integer array (of length group size). Entry j specifies the displacement (relative to <b>sendbuf</b> ) from which to take the outgoing data destined for process j
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice)
IN	recvcoun- ts	non-negative integer array (of length group size) specifying the number of elements that can be received from each processor
IN	rdispls	integer array (of length group size). Entry i specifies the displacement (relative to <b>recvbuf</b> ) at which to place the incoming data from process i
IN	recvtype	data type of receive buffer elements (handle)
IN	comm	communicator (handle)

```
int MPI_Alltoallv(void* sendbuf, int sendcounts[], int sdispls[],
MPI_Datatype sendtype, void* recvbuf, int recvcoun-
ts[], int rdispls[], MPI_Datatype recvtype, MPI_Comm comm)
MPI_ALLTOALLV(SENDBUF, SENDCOUNTS, SDISPLS, SENDTYPE, RECVBUF, RECVCOUNTS,
RDISPLS, RECVTYPE, COMM, IERROR)
<type> SENDBUF(*), RECVBUF(*)
INTEGER SENDCOUNTS(*), SDISPLS(*), SENDTYPE, REVCOUNTS(*), RDISPLS(*),
RECVTYPE, COMM, IERROR
```

```
MPI_Alltoallv(sendbuf, sendcounts, sdispls, sendtype, recvbuf, recvcoun-
ts, rdispls, recvtype, comm, ierror)
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
INTEGER, INTENT(IN) :: sendcounts(*), sdispls(*), recvcoun-
ts(*), rdispls(*)
TYPE(MPI_Datatype), INTENT(IN) :: sendtype
TYPE(MPI_Datatype), INTENT(IN) :: recvtype
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Comm::Alltoallv(const void* sendbuf, const int sendcounts[],
const int sdispls[], const MPI::Datatype& sendtype,
void* recvbuf, const int recvcoun-
ts[], const int rdispls[],
const MPI::Datatype& recvtype) const = 0(binding deprecated, see
Section 15.2) }
```

MPI\_ALLTOALLV adds flexibility to MPI\_ALLTOALL in that the location of data for the send is specified by **sdispls** and the location of the placement of the data on the receive

side is specified by `rdispls`.

If `comm` is an intracommunicator, then the  $j$ -th block sent from process  $i$  is received by process  $j$  and is placed in the  $i$ -th block of `recvbuf`. These blocks need not all have the same size.

The type signature associated with `sendcounts[j]`, `sendtype` at process  $i$  must be equal to the type signature associated with `recvcounts[i]`, `recvtype` at process  $j$ . This implies that the amount of data sent must be equal to the amount of data received, pairwise between every pair of processes. Distinct type maps between sender and receiver are still allowed.

The outcome is as if each process sent a message to every other process with,

```
MPI_Send(sendbuf + sdispls[i] · extent(sendtype), sendcounts[i], sendtype, i, ...),
```

and received a message from every other process with a call to

```
MPI_Recv(recvbuf + rdispls[i] · extent(recvtype), recvcounts[i], recvtype, i, ...).
```

All arguments on all processes are significant. The argument `comm` must have identical values on all processes.

The “in place” option for intracommunicators is specified by passing `MPI_IN_PLACE` to the argument `sendbuf` at *all* processes. In such a case, `sendcounts`, `sdispls` and `sendtype` are ignored. The data to be sent is taken from the `recvbuf` and replaced by the received data. Data sent and received must have the same type map as specified by the `recvcounts` array and the `recvtype`, and is taken from the locations of the receive buffer specified by `rdispls`.

*Advice to users.* Specifying the “in place” option (which must be given on all processes) implies that the same amount and type of data is sent and received between any two processes in the group of the communicator. Different pairs of processes can exchange different amounts of data. Users must ensure that `recvcounts[j]` and `recvtype` on process  $i$  match `recvcounts[i]` and `recvtype` on process  $j$ . This symmetric exchange can be useful in applications where the data to be sent will not be used by the sending process after the `MPI_ALLTOALLV` exchange. (*End of advice to users.*)

If `comm` is an intercommunicator, then the outcome is as if each process in group A sends a message to each process in group B, and vice versa. The  $j$ -th send buffer of process  $i$  in group A should be consistent with the  $i$ -th receive buffer of process  $j$  in group B, and vice versa.

*Rationale.* The definitions of `MPI_ALLTOALL` and `MPI_ALLTOALLV` give as much flexibility as one would achieve by specifying  $n$  independent, point-to-point communications, with two exceptions: all messages use the same datatype, and messages are scattered from (or gathered to) sequential storage. (*End of rationale.*)

*Advice to implementors.* Although the discussion of collective communication in terms of point-to-point operation implies that each message is transferred directly from sender to receiver, implementations may use a tree communication pattern. Messages can be forwarded by intermediate nodes where they are split (for scatter) or concatenated (for gather), if this is more efficient. (*End of advice to implementors.*)

MPI_ALLTOALLW(sendbuf, sendcounts, sdispls, sendtypes, recvbuf, recvcoun-			1
types, comm)			2
IN	sendbuf	starting address of send buffer (choice)	3
IN	sendcounts	non-negative integer array (of length group size) speci-	4
		fying the number of elements to send to each processor	5
IN	sdispls	integer array (of length group size). Entry j specifies	6
		the displacement in bytes (relative to sendbuf) from	7
		which to take the outgoing data destined for process	8
		j (array of integers)	9
IN	sendtypes	array of datatypes (of length group size). Entry j	10
		specifies the type of data to send to process j (array	11
		of handles)	12
OUT	recvbuf	address of receive buffer (choice)	13
IN	recvcoun-	non-negative integer array (of length group size) spec-	14
		ifying the number of elements that can be received	15
		from each processor	16
IN	rdispls	integer array (of length group size). Entry i specifies	17
		the displacement in bytes (relative to recvbuf) at which	18
		to place the incoming data from process i (array of	19
		integers)	20
IN	recvtypes	array of datatypes (of length group size). Entry i	21
		specifies the type of data received from process i (ar-	22
		ray of handles)	23
IN	comm	communicator (handle)	24
			25
			26
			27
			28
int MPI_Alltoallw(void* sendbuf, int sendcounts[], int sdispls[],			29
MPI_Datatype sendtypes[], void* recvbuf, int recvcoun-			30
int rdispls[], MPI_Datatype recvtypes[], MPI_Comm comm)			31
			32
MPI_ALLTOALLW(SENDBUF, SENDCOUNTS, SDISPLS, SENDTYPES, RECVBUF, RECVCOUNTS,			33
RDISPLS, RECVTYPES, COMM, IERROR)			34
<type> SENDBUF(*), RECVBUF(*)			35
INTEGER SENDCOUNTS(*), SDISPLS(*), SENDTYPES(*), RECVCOUNTS(*),			36
RDISPLS(*), RECVTYPES(*), COMM, IERROR			37
			38
MPI_Alltoallw(sendbuf, sendcounts, sdispls, sendtypes, recvbuf, recvcoun-			39
rdispls, recvtypes, comm, ierror)			40
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf			41
INTEGER, INTENT(IN) :: sendcounts(*), sdispls(*), recvcoun-			42
rdispls(*)			43
TYPE(MPI_Datatype), INTENT(IN) :: sendtypes(*)			44
TYPE(MPI_Datatype), INTENT(IN) :: recvtypes(*)			45
TYPE(MPI_Comm), INTENT(IN) :: comm			46
INTEGER, OPTIONAL, INTENT(OUT) :: ierror			47
			48

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```

1 {void MPI::Comm::Alltoallw(const void* sendbuf, const int sendcounts[],
2     const int sdispls[], const MPI::Datatype sendtypes[], void*
3     recvbuf, const int recvcounst[], const int rdispls[], const
4     MPI::Datatype recvtypes[]) const = 0(binding deprecated, see
5     Section 15.2) }

```

MPI\_ALLTOALLW is the most general form of complete exchange. Like MPI\_TYPE\_CREATE\_STRUCT, the most general type constructor, MPI\_ALLTOALLW allows separate specification of count, displacement and datatype. In addition, to allow maximum flexibility, the displacement of blocks within the send and receive buffers is specified in bytes.

If `comm` is an intracommunicator, then the  $j$ -th block sent from process  $i$  is received by process  $j$  and is placed in the  $i$ -th block of `recvbuf`. These blocks need not all have the same size.

The type signature associated with `sendcounts[j]`, `sendtypes[j]` at process  $i$  must be equal to the type signature associated with `recvcounst[i]`, `recvtypes[i]` at process  $j$ . This implies that the amount of data sent must be equal to the amount of data received, pairwise between every pair of processes. Distinct type maps between sender and receiver are still allowed.

The outcome is as if each process sent a message to every other process with

```
MPI_Send(sendbuf + sdispls[i], sendcounts[i], sendtypes[i], i, ...),
```

and received a message from every other process with a call to

```
MPI_Recv(recvbuf + rdispls[i], recvcounst[i], recvtypes[i], i, ...).
```

All arguments on all processes are significant. The argument `comm` must describe the same communicator on all processes.

Like for MPI\_ALLTOALLV, the “in place” option for intracommunicators is specified by passing MPI\_IN\_PLACE to the argument `sendbuf` at *all* processes. In such a case, `sendcounts`, `sdispls` and `sendtypes` are ignored. The data to be sent is taken from the `recvbuf` and replaced by the received data. Data sent and received must have the same type map as specified by the `recvcounst` and `recvtypes` arrays, and is taken from the locations of the receive buffer specified by `rdispls`.

If `comm` is an intercommunicator, then the outcome is as if each process in group A sends a message to each process in group B, and vice versa. The  $j$ -th send buffer of process  $i$  in group A should be consistent with the  $i$ -th receive buffer of process  $j$  in group B, and vice versa.

*Rationale.* The MPI\_ALLTOALLW function generalizes several MPI functions by carefully selecting the input arguments. For example, by making all but one process have `sendcounts[i] = 0`, this achieves an MPI\_SCATTERW function. (*End of rationale.*)

## 5.9 Global Reduction Operations

The functions in this section perform a global reduce operation (for example sum, maximum, and logical and) across all members of a group. The reduction operation can be either one of a predefined list of operations, or a user-defined operation. The global reduction functions come in several flavors: a reduce that returns the result of the reduction to one member of a group, an all-reduce that returns this result to all members of a group, and two scan (parallel

prefix) operations. In addition, a reduce-scatter operation combines the functionality of a reduce and of a scatter operation.

### 5.9.1 Reduce

**MPI\_REDUCE**(sendbuf, recvbuf, count, datatype, op, root, comm)

IN	sendbuf	address of send buffer (choice)
OUT	recvbuf	address of receive buffer (choice, significant only at root)
IN	count	number of elements in send buffer (non-negative integer)
IN	datatype	data type of elements of send buffer (handle)
IN	op	reduce operation (handle)
IN	root	rank of root process (integer)
IN	comm	communicator (handle)

```
int MPI_Reduce(void* sendbuf, void* recvbuf, int count,
               MPI_Datatype datatype, MPI_Op op, int root, MPI_Comm comm)
```

```
MPI_REDUCE(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, ROOT, COMM, IERROR)
<type> SENDBUF(*), RECVBUF(*)
INTEGER COUNT, DATATYPE, OP, ROOT, COMM, IERROR
```

```
MPI_Reduce(sendbuf, recvbuf, count, datatype, op, root, comm, ierror)
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
INTEGER, INTENT(IN) :: count, root
TYPE(MPI_Datatype), INTENT(IN) :: datatype
TYPE(MPI_Op), INTENT(IN) :: op
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Comm::Reduce(const void* sendbuf, void* recvbuf, int count,
                        const MPI::Datatype& datatype, const MPI::Op& op, int root)
  const = 0(binding deprecated, see Section 15.2) }
```

If `comm` is an intracommunicator, **MPI\_REDUCE** combines the elements provided in the input buffer of each process in the group, using the operation `op`, and returns the combined value in the output buffer of the process with rank `root`. The input buffer is defined by the arguments `sendbuf`, `count` and `datatype`; the output buffer is defined by the arguments `recvbuf`, `count` and `datatype`; both have the same number of elements, with the same type. The routine is called by all group members using the same arguments for `count`, `datatype`, `op`, `root` and `comm`. Thus, all processes provide input buffers and output buffers of the same length, with elements of the same type. Each process can provide one element, or a sequence of elements, in which case the combine operation is executed element-wise on each entry of the sequence. For example, if the operation is **MPI\_MAX** and the send buffer contains two

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elements that are floating point numbers (`count = 2` and `datatype = MPI_FLOAT`), then `recvbuf(1) = global max(sendbuf(1))` and `recvbuf(2) = global max(sendbuf(2))`.

Section 5.9.2, lists the set of predefined operations provided by MPI. That section also enumerates the datatypes to which each operation can be applied.

In addition, users may define their own operations that can be overloaded to operate on several datatypes, either basic or derived. This is further explained in Section 5.9.5.

The operation `op` is always assumed to be associative. All predefined operations are also assumed to be commutative. Users may define operations that are assumed to be associative, but not commutative. The “canonical” evaluation order of a reduction is determined by the ranks of the processes in the group. However, the implementation can take advantage of associativity, or associativity and commutativity in order to change the order of evaluation. This may change the result of the reduction for operations that are not strictly associative and commutative, such as floating point addition.

*Advice to implementors.* It is strongly recommended that `MPI_REDUCE` be implemented so that the same result be obtained whenever the function is applied on the same arguments, appearing in the same order. Note that this may prevent optimizations that take advantage of the physical location of processors. (*End of advice to implementors.*)

*Advice to users.* Some applications may not be able to ignore the non-associative nature of floating-point operations or may use user-defined operations (see Section 5.9.5) that require a special reduction order and cannot be treated as associative. Such applications should enforce the order of evaluation explicitly. For example, in the case of operations that require a strict left-to-right (or right-to-left) evaluation order, this could be done by gathering all operands at a single process (e.g., with `MPI_GATHER`), applying the reduction operation in the desired order (e.g., with `MPI_REDUCE_LOCAL`), and if needed, broadcast or scatter the result to the other processes (e.g., with `MPI_BCAST`). (*End of advice to users.*)

The `datatype` argument of `MPI_REDUCE` must be compatible with `op`. Predefined operators work only with the MPI types listed in Section 5.9.2 and Section 5.9.4. Furthermore, the `datatype` and `op` given for predefined operators must be the same on all processes.

Note that it is possible for users to supply different user-defined operations to `MPI_REDUCE` in each process. MPI does not define which operations are used on which operands in this case. User-defined operators may operate on general, derived datatypes. In this case, each argument that the reduce operation is applied to is one element described by such a datatype, which may contain several basic values. This is further explained in Section 5.9.5.

*Advice to users.* Users should make no assumptions about how `MPI_REDUCE` is implemented. It is safest to ensure that the same function is passed to `MPI_REDUCE` by each process. (*End of advice to users.*)

Overlapping datatypes are permitted in “send” buffers. Overlapping datatypes in “receive” buffers are erroneous and may give unpredictable results.

The “in place” option for intracommunicators is specified by passing the value `MPI_IN_PLACE` to the argument `sendbuf` at the root. In such a case, the input data is taken at the root from the receive buffer, where it will be replaced by the output data.

If `comm` is an intercommunicator, then the call involves all processes in the intercommunicator, but with one group (group A) defining the root process. All processes in the other group (group B) pass the same value in argument `root`, which is the rank of the root in group A. The root passes the value `MPI_ROOT` in `root`. All other processes in group A pass the value `MPI_PROC_NULL` in `root`. Only send buffer arguments are significant in group B and only receive buffer arguments are significant at the root.

### 5.9.2 Predefined Reduction Operations

The following predefined operations are supplied for `MPI_REDUCE` and related functions `MPI_ALLREDUCE`, `MPI_REDUCE_SCATTER`, `MPI_SCAN`, and `MPI_EXSCAN`. These operations are invoked by placing the following in `op`.

Name	Meaning
<code>MPI_MAX</code>	maximum
<code>MPI_MIN</code>	minimum
<code>MPI_SUM</code>	sum
<code>MPI_PROD</code>	product
<code>MPI_LAND</code>	logical and
<code>MPI_BAND</code>	bit-wise and
<code>MPI_LOR</code>	logical or
<code>MPI BOR</code>	bit-wise or
<code>MPI_LXOR</code>	logical exclusive or (xor)
<code>MPI_BXOR</code>	bit-wise exclusive or (xor)
<code>MPI_MAXLOC</code>	max value and location
<code>MPI_MINLOC</code>	min value and location

The two operations `MPI_MINLOC` and `MPI_MAXLOC` are discussed separately in Section 5.9.4. For the other predefined operations, we enumerate below the allowed combinations of `op` and `datatype` arguments. First, define groups of MPI basic datatypes in the following way.

C integer:	<code>MPI_INT</code> , <code>MPI_LONG</code> , <code>MPI_SHORT</code> , <code>MPI_UNSIGNED_SHORT</code> , <code>MPI_UNSIGNED</code> , <code>MPI_UNSIGNED_LONG</code> , <code>MPI_LONG_LONG_INT</code> , <code>MPI_LONG_LONG</code> (as synonym), <code>MPI_UNSIGNED_LONG_LONG</code> , <code>MPI_SIGNED_CHAR</code> , <code>MPI_UNSIGNED_CHAR</code> , <code>MPI_INT8_T</code> , <code>MPI_INT16_T</code> , <code>MPI_INT32_T</code> , <code>MPI_INT64_T</code> , <code>MPI_UINT8_T</code> , <code>MPI_UINT16_T</code> , <code>MPI_UINT32_T</code> , <code>MPI_UINT64_T</code>
Fortran integer:	<code>MPI_INTEGER</code> , <code>MPI_AINT</code> , <code>MPI_OFFSET</code> , and handles returned from <code>MPI_TYPE_CREATE_F90_INTEGER</code> ,

and if available: MPI\_INTEGER1,  
 MPI\_INTEGER2, MPI\_INTEGER4,  
 MPI\_INTEGER8, MPI\_INTEGER16  
 Floating point: MPI\_FLOAT, MPI\_DOUBLE, MPI\_REAL,  
 MPI\_DOUBLE\_PRECISION  
 MPI\_LONG\_DOUBLE  
 and handles returned from  
 MPI\_TYPE\_CREATE\_F90\_REAL,  
 and if available: MPI\_REAL2,  
 MPI\_REAL4, MPI\_REAL8, MPI\_REAL16  
 Logical: MPI\_LOGICAL, MPI\_C\_BOOL  
 Complex: MPI\_COMPLEX,  
 MPI\_C\_FLOAT\_COMPLEX,  
 MPI\_C\_DOUBLE\_COMPLEX,  
 MPI\_C\_LONG\_DOUBLE\_COMPLEX,  
 and handles returned from  
 MPI\_TYPE\_CREATE\_F90\_COMPLEX,  
 and if available: MPI\_DOUBLE\_COMPLEX,  
 MPI\_COMPLEX4, MPI\_COMPLEX8,  
 MPI\_COMPLEX16, MPI\_COMPLEX32  
 Byte: MPI\_BYTE

Now, the valid datatypes for each option is specified below.

Op	Allowed Types
MPI_MAX, MPI_MIN	C integer, Fortran integer, Floating point
MPI_SUM, MPI_PROD	C integer, Fortran integer, Floating point, Complex
MPI_LAND, MPI_LOR, MPI_LXOR	C integer, Logical
MPI_BAND, MPI_BOR, MPI_BXOR	C integer, Fortran integer, Byte

The following examples use intracommunicators.

### Example 5.15

A routine that computes the dot product of two vectors that are distributed across a group of processes and returns the answer at node zero.



```

SUBROUTINE PAR_BLAS1(m, a, b, c, comm)
REAL a(m), b(m)      ! local slice of array
REAL c                ! result (at node zero)
REAL sum
INTEGER m, comm, i, ierr

! local sum
sum = 0.0
DO i = 1, m
    sum = sum + a(i)*b(i)
END DO

! global sum
CALL MPI_REDUCE(sum, c, 1, MPI_REAL, MPI_SUM, 0, comm, ierr)
RETURN

```

**Example 5.16**

A routine that computes the product of a vector and an array that are distributed across a group of processes and returns the answer at node zero.

```

SUBROUTINE PAR_BLAS2(m, n, a, b, c, comm)
REAL a(m), b(m,n)    ! local slice of array
REAL c(n)            ! result
REAL sum(n)
INTEGER n, comm, i, j, ierr

! local sum
DO j= 1, n
    sum(j) = 0.0
    DO i = 1, m
        sum(j) = sum(j) + a(i)*b(i,j)
    END DO
END DO

! global sum
CALL MPI_REDUCE(sum, c, n, MPI_REAL, MPI_SUM, 0, comm, ierr)

! return result at node zero (and garbage at the other nodes)
RETURN

```

**5.9.3 Signed Characters and Reductions**

The types `MPI_SIGNED_CHAR` and `MPI_UNSIGNED_CHAR` can be used in reduction operations. `MPI_CHAR`, `MPI_WCHAR`, and `MPI_CHARACTER` (which represent printable characters) cannot be used in reduction operations. In a heterogeneous environment, `MPI_CHAR`, `MPI_WCHAR`, and `MPI_CHARACTER` will be translated so as to preserve the printable character, whereas `MPI_SIGNED_CHAR` and `MPI_UNSIGNED_CHAR` will be translated so as to preserve the integer value.

*Advice to users.* The types `MPI_CHAR`, `MPI_WCHAR`, and `MPI_CHARACTER` are intended for characters, and so will be translated to preserve the printable representation, rather than the integer value, if sent between machines with different character codes. The types `MPI_SIGNED_CHAR` and `MPI_UNSIGNED_CHAR` should be used in C if the integer value should be preserved. (*End of advice to users.*)

#### 5.9.4 MINLOC and MAXLOC

The operator `MPI_MINLOC` is used to compute a global minimum and also an index attached to the minimum value. `MPI_MAXLOC` similarly computes a global maximum and index. One application of these is to compute a global minimum (maximum) and the rank of the process containing this value.

The operation that defines `MPI_MAXLOC` is:

$$\begin{pmatrix} u \\ i \end{pmatrix} \circ \begin{pmatrix} v \\ j \end{pmatrix} = \begin{pmatrix} w \\ k \end{pmatrix}$$

where

$$w = \max(u, v)$$

and

$$k = \begin{cases} i & \text{if } u > v \\ \min(i, j) & \text{if } u = v \\ j & \text{if } u < v \end{cases}$$

`MPI_MINLOC` is defined similarly:

$$\begin{pmatrix} u \\ i \end{pmatrix} \circ \begin{pmatrix} v \\ j \end{pmatrix} = \begin{pmatrix} w \\ k \end{pmatrix}$$

where

$$w = \min(u, v)$$

and

$$k = \begin{cases} i & \text{if } u < v \\ \min(i, j) & \text{if } u = v \\ j & \text{if } u > v \end{cases}$$

Both operations are associative and commutative. Note that if `MPI_MAXLOC` is applied to reduce a sequence of pairs  $(u_0, 0), (u_1, 1), \dots, (u_{n-1}, n-1)$ , then the value returned is  $(u, r)$ , where  $u = \max_i u_i$  and  $r$  is the index of the first global maximum in the sequence. Thus, if each process supplies a value and its rank within the group, then a reduce operation with `op = MPI_MAXLOC` will return the maximum value and the rank of the first process with that value. Similarly, `MPI_MINLOC` can be used to return a minimum and its index. More generally, `MPI_MINLOC` computes a *lexicographic minimum*, where elements are ordered according to the first component of each pair, and ties are resolved according to the second component.

The reduce operation is defined to operate on arguments that consist of a pair: value and index. For both Fortran and C, types are provided to describe the pair. The potentially mixed-type nature of such arguments is a problem in Fortran. The problem is circumvented, for Fortran, by having the MPI-provided type consist of a pair of the same type as value, and coercing the index to this type also. In C, the MPI-provided pair type has distinct types and the index is an `int`.

In order to use `MPI_MINLOC` and `MPI_MAXLOC` in a reduce operation, one must provide a `datatype` argument that represents a pair (value and index). MPI provides nine such predefined datatypes. The operations `MPI_MAXLOC` and `MPI_MINLOC` can be used with each of the following datatypes.

Fortran:

Name	Description
<code>MPI_2REAL</code>	pair of <code>REAL</code> s
<code>MPI_2DOUBLE_PRECISION</code>	pair of <code>DOUBLE PRECISION</code> variables
<code>MPI_2INTEGER</code>	pair of <code>INTEGER</code> s

C:

Name	Description
<code>MPI_FLOAT_INT</code>	float and <code>int</code>
<code>MPI_DOUBLE_INT</code>	double and <code>int</code>
<code>MPI_LONG_INT</code>	long and <code>int</code>
<code>MPI_2INT</code>	pair of <code>int</code>
<code>MPI_SHORT_INT</code>	short and <code>int</code>
<code>MPI_LONG_DOUBLE_INT</code>	long double and <code>int</code>

The datatype `MPI_2REAL` is *as if* defined by the following (see Section 4.1).

```
MPI_TYPE_CONTIGUOUS(2, MPI_REAL, MPI_2REAL)
```

Similar statements apply for `MPI_2INTEGER`, `MPI_2DOUBLE_PRECISION`, and `MPI_2INT`.

The datatype `MPI_FLOAT_INT` is *as if* defined by the following sequence of instructions.

```
type[0] = MPI_FLOAT
type[1] = MPI_INT
disp[0] = 0
disp[1] = sizeof(float)
block[0] = 1
block[1] = 1
MPI_TYPE_CREATE_STRUCT(2, block, disp, type, MPI_FLOAT_INT)
```

Similar statements apply for `MPI_LONG_INT` and `MPI_DOUBLE_INT`.

The following examples use intracommunicators.

#### Example 5.17

Each process has an array of 30 `doubles`, in C. For each of the 30 locations, compute the value and rank of the process containing the largest value.

```

1      ...
2      /* each process has an array of 30 double: ain[30]
3      */
4      double ain[30], aout[30];
5      int ind[30];
6      struct {
7          double val;
8          int rank;
9      } in[30], out[30];
10     int i, myrank, root;
11
12     MPI_Comm_rank(comm, &myrank);
13     for (i=0; i<30; ++i) {
14         in[i].val = ain[i];
15         in[i].rank = myrank;
16     }
17     MPI_Reduce(in, out, 30, MPI_DOUBLE_INT, MPI_MAXLOC, root, comm);
18     /* At this point, the answer resides on process root
19     */
20     if (myrank == root) {
21         /* read ranks out
22         */
23         for (i=0; i<30; ++i) {
24             aout[i] = out[i].val;
25             ind[i] = out[i].rank;
26         }
27     }

```

**Example 5.18**

Same example, in Fortran.

```

33     ...
34     ! each process has an array of 30 double: ain(30)
35
36     DOUBLE PRECISION ain(30), aout(30)
37     INTEGER ind(30)
38     DOUBLE PRECISION in(2,30), out(2,30)
39     INTEGER i, myrank, root, ierr
40
41     CALL MPI_COMM_RANK(comm, myrank, ierr)
42     DO I=1, 30
43         in(1,i) = ain(i)
44         in(2,i) = myrank      ! myrank is coerced to a double
45     END DO
46
47     CALL MPI_REDUCE(in, out, 30, MPI_2DOUBLE_PRECISION, MPI_MAXLOC, root,
48                     comm, ierr)

```

```

! At this point, the answer resides on process root
1
2
IF (myrank .EQ. root) THEN
3
! read ranks out
4
DO I= 1, 30
5
aout(i) = out(1,i)
6
ind(i) = out(2,i) ! rank is coerced back to an integer
7
END DO
8
END IF
9
10
11

```

**Example 5.19**

Each process has a non-empty array of values. Find the minimum global value, the rank of the process that holds it and its index on this process.

```

12
13
14
#define LEN 1000
15
16
float val[LEN]; /* local array of values */
17
int count; /* local number of values */
18
int myrank, minrank, minindex;
19
float minval;
20
21
struct {
22
float value;
23
int index;
24
} in, out;
25
26
/* local minloc */
27
in.value = val[0];
28
in.index = 0;
29
for (i=1; i < count; i++)
30
if (in.value > val[i]) {
31
in.value = val[i];
32
in.index = i;
33
}
34
35
/* global minloc */
36
MPI_Comm_rank(comm, &myrank);
37
in.index = myrank*LEN + in.index;
38
MPI_Reduce( &in, &out, 1, MPI_FLOAT_INT, MPI_MINLOC, root, comm );
39
/* At this point, the answer resides on process root
40
*/
41
if (myrank == root) {
42
/* read answer out
43
*/
44
minval = out.value;
45
minrank = out.index / LEN;
46
minindex = out.index % LEN;
47
}
48

```

*Rationale.* The definition of MPI\_MINLOC and MPI\_MAXLOC given here has the advantage that it does not require any special-case handling of these two operations: they are handled like any other reduce operation. A programmer can provide his or her own definition of MPI\_MAXLOC and MPI\_MINLOC, if so desired. The disadvantage is that values and indices have to be first interleaved, and that indices and values have to be coerced to the same type, in Fortran. (*End of rationale.*)

### 5.9.5 User-Defined Reduction Operations

MPI\_OP\_CREATE(*user\_fn*, *commute*, *op*)

IN	[ <i>ticket252-W.</i> ] <i>user_fn</i>	user defined function (function)
IN	<i>commute</i>	true if commutative; false otherwise.
OUT	<i>op</i>	operation (handle)

int MPI\_Op\_create(MPI\_User\_function\* *user\_fn*, int *commute*, MPI\_Op\* *op*)

MPI\_OP\_CREATE( *USER\_FN*, COMMUTE, OP, IERROR)

EXTERNAL *USER\_FN*  
 LOGICAL COMMUTE  
 INTEGER OP, IERROR

*MPI\_Op\_create*(*user\_fn*, *commute*, *op*, *ierror*)  
 EXTERNAL :: *user\_fn*  
 LOGICAL, INTENT(IN) :: *commute*  
 TYPE(MPI\_Op), INTENT(OUT) :: *op*  
 INTEGER, OPTIONAL, INTENT(OUT) :: *ierror*

{void MPI::Op::Init(MPI::User\_function\* *user\_fn*, bool *commute*) (*binding deprecated, see Section 15.2*) }

MPI\_OP\_CREATE binds a user-defined reduction operation to an *op* handle that can subsequently be used in MPI\_REDUCE, MPI\_ALLREDUCE, MPI\_REDUCE\_SCATTER, MPI\_SCAN, and MPI\_EXSCAN. The user-defined operation is assumed to be associative. If *commute* = true, then the operation should be both commutative and associative. If *commute* = false, then the order of operands is fixed and is defined to be in ascending, process rank order, beginning with process zero. The order of evaluation can be changed, taking advantage of the associativity of the operation. If *commute* = true then the order of evaluation can be changed, taking advantage of commutativity and associativity.

The argument *user\_fn* is the user-defined function, which must have the following four arguments: *invec*, *inoutvec*, *len* and *datatype*.

The ISO C prototype for the function is the following.

```
typedef void MPI_User_function(void* invec, void* inoutvec, int* len,
                               MPI_Datatype* datatype);
```

The Fortran declaration of the user-defined function *user\_fn* appears below. To reduce problems with the choice buffer arguments, implicit interfaces are used with all three Fortran

support methods; the first one with the `mpi` module or `mpif.h`, the second one with `mpi_f08`.

```
SUBROUTINE USER_FUNCTION(INVEC, INOUTVEC, LEN, DATATYPE)
  <type> INVEC(LEN), INOUTVEC(LEN)
  INTEGER LEN, DATATYPE
```

```
SUBROUTINE USER_FUNCTION(invec, inoutvec, len, datatype)
  <type> :: invec(len), inoutvec(len)
  INTEGER :: len
  TYPE(MPI_Datatype) :: datatype
```

The C++ declaration of the user-defined function appears below.

```
{typedef void MPI::User_function(const void* invec, void* inoutvec, int
    len, const Datatype& datatype); (binding deprecated, see
    Section 15.2)}
```

The `datatype` argument is a handle to the data type that was passed into the call to `MPI_REDUCE`. The user reduce function should be written such that the following holds: Let `u[0], ... , u[len-1]` be the `len` elements in the communication buffer described by the arguments `invec`, `len` and `datatype` when the function is invoked; let `v[0], ... , v[len-1]` be `len` elements in the communication buffer described by the arguments `inoutvec`, `len` and `datatype` when the function is invoked; let `w[0], ... , w[len-1]` be `len` elements in the communication buffer described by the arguments `inoutvec`, `len` and `datatype` when the function returns; then `w[i] = u[i] ◦ v[i]`, for `i=0, ... , len-1`, where `◦` is the reduce operation that the function computes.

Informally, we can think of `invec` and `inoutvec` as arrays of `len` elements that `user_fn` is combining. The result of the reduction over-writes values in `inoutvec`, hence the name. Each invocation of the function results in the pointwise evaluation of the reduce operator on `len` elements: i.e., the function returns in `inoutvec[i]` the value `invec[i] ◦ inoutvec[i]`, for `i = 0, ... , count - 1`, where `◦` is the combining operation computed by the function.

*Rationale.* The `len` argument allows `MPI_REDUCE` to avoid calling the function for each element in the input buffer. Rather, the system can choose to apply the function to chunks of input. In C, it is passed in as a reference for reasons of compatibility with Fortran.

By internally comparing the value of the `datatype` argument to known, global handles, it is possible to overload the use of a single user-defined function for several, different data types. (*End of rationale.*)

General datatypes may be passed to the user function. However, use of datatypes that are not contiguous is likely to lead to inefficiencies.

No MPI communication function may be called inside the user function. `MPI_ABORT` may be called inside the function in case of an error.

*Advice to users.* Suppose one defines a library of user-defined reduce functions that are overloaded: the `datatype` argument is used to select the right execution path at each invocation, according to the types of the operands. The user-defined reduce function cannot “decode” the `datatype` argument that it is passed, and cannot identify, by itself, the correspondence between the datatype handles and the datatype they represent.

This correspondence was established when the datatypes were created. Before the library is used, a library initialization preamble must be executed. This preamble code will define the datatypes that are used by the library, and store handles to these datatypes in global, static variables that are shared by the user code and the library code.

The Fortran version of `MPI_REDUCE` will invoke a user-defined reduce function using the Fortran calling conventions and will pass a Fortran-type datatype argument; the C version will use C calling convention and the C representation of a datatype handle. Users who plan to mix languages should define their reduction functions accordingly. (*End of advice to users.*)

*Advice to implementors.* We outline below a naive and inefficient implementation of `MPI_REDUCE` not supporting the “in place” option.

```

MPI_Comm_size(comm, &groupsize);
MPI_Comm_rank(comm, &rank);
if (rank > 0) {
    MPI_Recv(tempbuf, count, datatype, rank-1,...);
    User_reduce(tempbuf, sendbuf, count, datatype);
}
if (rank < groupsize-1) {
    MPI_Send(sendbuf, count, datatype, rank+1, ...);
}
/* answer now resides in process groupsize-1 ... now send to root
*/
if (rank == root) {
    MPI_Irecv(recvbuf, count, datatype, groupsize-1,..., &req);
}
if (rank == groupsize-1) {
    MPI_Send(sendbuf, count, datatype, root, ...);
}
if (rank == root) {
    MPI_Wait(&req, &status);
}

```

The reduction computation proceeds, sequentially, from process 0 to process `groupsize-1`. This order is chosen so as to respect the order of a possibly non-commutative operator defined by the function `User_reduce()`. A more efficient implementation is achieved by taking advantage of associativity and using a logarithmic tree reduction. Commutativity can be used to advantage, for those cases in which the `commute` argument to `MPI_OP_CREATE` is true. Also, the amount of temporary buffer required can be reduced, and communication can be pipelined with computation, by transferring and reducing the elements in chunks of size `len < count`.

The predefined reduce operations can be implemented as a library of user-defined operations. However, better performance might be achieved if `MPI_REDUCE` handles these functions as a special case. (*End of advice to implementors.*)



MPI\_OP\_FREE(op)

INOUT op operation (handle)

int MPI\_op\_free(MPI\_Op \*op)

MPI\_OP\_FREE(OP, IERROR)

INTEGER OP, IERROR

MPI\_Op\_free(op, ierror)

TYPE(MPI\_Op), INTENT(INOUT) :: op

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Op::Free() *(binding deprecated, see Section 15.2)* }

Marks a user-defined reduction operation for deallocation and sets op to MPI\_OP\_NULL.

Example of User-defined Reduce

It is time for an example of user-defined reduction. The example in this section uses an intracommunicator.

**Example 5.20** Compute the product of an array of complex numbers, in C.

```
typedef struct {
    double real,imag;
} Complex;
```

```
/* the user-defined function
*/
```

```
void myProd(Complex *in, Complex *inout, int *len, MPI_Datatype *dptr)
{
    int i;
    Complex c;

    for (i=0; i< *len; ++i) {
        c.real = inout->real*in->real -
                inout->imag*in->imag;
        c.imag = inout->real*in->imag +
                inout->imag*in->real;
        *inout = c;
        in++; inout++;
    }
}
```

```
/* and, to call it...
```

```
*/
```

```
...
```

```
/* each process has an array of 100 Complexes
```

```
*/
```

```

1      Complex a[100], answer[100];
2      MPI_Op myOp;
3      MPI_Datatype ctype;
4
5      /* explain to MPI how type Complex is defined
6       */
7      MPI_Type_contiguous(2, MPI_DOUBLE, &ctype);
8      MPI_Type_commit(&ctype);
9      /* create the complex-product user-op
10     */
11     MPI_Op_create( myProd, 1, &myOp );
12
13     MPI_Reduce(a, answer, 100, ctype, myOp, root, comm);
14
15     /* At this point, the answer, which consists of 100 Complexes,
16      * resides on process root
17      */
18

```

### 5.9.6 All-Reduce

MPI includes a variant of the reduce operations where the result is returned to all processes in a group. MPI requires that all processes from the same group participating in these operations receive identical results.

`MPI_ALLREDUCE(sendbuf, recvbuf, count, datatype, op, comm)`

IN	sendbuf	starting address of send buffer (choice)
OUT	recvbuf	starting address of receive buffer (choice)
IN	count	number of elements in send buffer (non-negative integer)
IN	datatype	data type of elements of send buffer (handle)
IN	op	operation (handle)
IN	comm	communicator (handle)

```

int MPI_Allreduce(void* sendbuf, void* recvbuf, int count,
                  MPI_Datatype datatype, MPI_Op op, MPI_Comm comm)
MPI_ALLREDUCE(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, IERROR)
<type> SENDBUF(*), RECVBUF(*)
INTEGER COUNT, DATATYPE, OP, COMM, IERROR

```

```

MPI_Allreduce(sendbuf, recvbuf, count, datatype, op, comm, ierror)
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
INTEGER, INTENT(IN) :: count
TYPE(MPI_Datatype), INTENT(IN) :: datatype
TYPE(MPI_Op), INTENT(IN) :: op
TYPE(MPI_Comm), INTENT(IN) :: comm

```

**INTEGER, OPTIONAL, INTENT(OUT) :: ierror**

```
{void MPI::Comm::Allreduce(const void* sendbuf, void* recvbuf, int count,
    const MPI::Datatype& datatype, const MPI::Op& op)
    const = 0(binding deprecated, see Section 15.2) }
```

If `comm` is an intracommunicator, `MPI_ALLREDUCE` behaves the same as `MPI_REDUCE` except that the result appears in the receive buffer of all the group members.

*Advice to implementors.* The all-reduce operations can be implemented as a reduce, followed by a broadcast. However, a direct implementation can lead to better performance. (*End of advice to implementors.*)

The “in place” option for intracommunicators is specified by passing the value `MPI_IN_PLACE` to the argument `sendbuf` at all processes. In this case, the input data is taken at each process from the receive buffer, where it will be replaced by the output data.

If `comm` is an intercommunicator, then the result of the reduction of the data provided by processes in group A is stored at each process in group B, and vice versa. Both groups should provide `count` and `datatype` arguments that specify the same type signature.

The following example uses an intracommunicator.

#### Example 5.21

A routine that computes the product of a vector and an array that are distributed across a group of processes and returns the answer at all nodes (see also Example 5.16).

```
SUBROUTINE PAR_BLAS2(m, n, a, b, c, comm)
REAL a(m), b(m,n)      ! local slice of array
REAL c(n)              ! result
REAL sum(n)
INTEGER n, comm, i, j, ierr

! local sum
DO j= 1, n
    sum(j) = 0.0
    DO i = 1, m
        sum(j) = sum(j) + a(i)*b(i,j)
    END DO
END DO

! global sum
CALL MPI_ALLREDUCE(sum, c, n, MPI_REAL, MPI_SUM, comm, ierr)

! return result at all nodes
RETURN
```

#### 5.9.7 Process-local reduction

The functions in this section are of importance to library implementors who may want to implement special reduction patterns that are otherwise not easily covered by the standard MPI operations.

The following function applies a reduction operator to local arguments.

```

1  MPI_REDUCE_LOCAL( inbuf, inoutbuf, count, datatype, op)
2
3
4  IN      inbuf      input buffer (choice)
5
6  INOUT   inoutbuf   combined input and output buffer (choice)
7
8  IN      count      number of elements in inbuf and inoutbuf buffers (non-
9                      negative integer)
10
11  IN      datatype   data type of elements of inbuf and inoutbuf buffers
12                      (handle)
13
14  IN      op         operation (handle)
15
16  int MPI_Reduce_local(void* inbuf, void* inoutbuf, int count,
17                      MPI_Datatype datatype, MPI_Op op)
18
19  MPI_REDUCE_LOCAL(INBUF, INOUTBUF, COUNT, DATATYPE, OP, IERROR)
20  <type> INBUF(*), INOUTBUF(*)
21  INTEGER COUNT, DATATYPE, OP, IERROR
22
23  MPI_Reduce_local(inbuf, inoutbuf, count, datatype, op, ierror)
24  TYPE(*), DIMENSION(..) :: inbuf, inoutbuf
25  INTEGER, INTENT(IN) :: count
26  TYPE(MPI_Datatype), INTENT(IN) :: datatype
27  TYPE(MPI_Op), INTENT(IN) :: op
28  INTEGER, OPTIONAL, INTENT(OUT) :: ierror
29
30  {void MPI::Op::Reduce_local(const void* inbuf, void* inoutbuf, int count,
31                          const MPI::Datatype& datatype) const(binding deprecated, see
32                          Section 15.2) }
```

The function applies the operation given by `op` element-wise to the elements of `inbuf` and `inoutbuf` with the result stored element-wise in `inoutbuf`, as explained for user-defined operations in Section 5.9.5. Both `inbuf` and `inoutbuf` (input as well as result) have the same number of elements given by `count` and the same datatype given by `datatype`. The `MPI_IN_PLACE` option is not allowed.

Reduction operations can be queried for their commutativity.

```

38  MPI_OP_COMMUTATIVE( op, commute)
39
40  IN      op         operation (handle)
41
42  OUT     commute     true if op is commutative, false otherwise (logical)
43
44  int MPI_Op_commutative(MPI_Op op, int *commute)
45
46  MPI_OP_COMMUTATIVE(OP, COMMUTE, IERROR)
47  LOGICAL COMMUTE
48  INTEGER OP, IERROR
```

```

MPI_Op_commutative(op, commute, ierror)
    TYPE(MPI_Op), INTENT(IN) :: op
    LOGICAL, INTENT(OUT) :: commute
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{bool MPI::Op::Is_commutative() const(binding deprecated, see Section 15.2) }

```

## 5.10 Reduce-Scatter

MPI includes variants of the reduce operations where the result is scattered to all processes in a group on return. One variant scatters equal-sized blocks to all processes, while another variant scatters blocks that may vary in size for each process.

### 5.10.1 MPI\_REDUCE\_SCATTER\_BLOCK

```

MPI_REDUCE_SCATTER_BLOCK( sendbuf, recvbuf, recvcnt, datatype, op, comm)

IN      sendbuf      starting address of send buffer (choice)
OUT     recvbuf      starting address of receive buffer (choice)
IN      recvcnt      element count per block (non-negative integer)
IN      datatype     data type of elements of send and receive buffers (handle)
IN      op           operation (handle)
IN      comm         communicator (handle)

int MPI_Reduce_scatter_block(void* sendbuf, void* recvbuf, int recvcnt,
    MPI_Datatype datatype, MPI_Op op, MPI_Comm comm)

MPI_REDUCE_SCATTER_BLOCK(SENDBUF, RECVBUF, RECVCOUNT, DATATYPE, OP, COMM,
    IERROR)
    <type> SENDBUF(*), RECVBUF(*)
    INTEGER REVCOUNT, DATATYPE, OP, COMM, IERROR

MPI_Reduce_scatter_block(sendbuf, recvbuf, recvcnt, datatype, op, comm,
    ierror)
    TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
    INTEGER, INTENT(IN) :: recvcnt
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Op), INTENT(IN) :: op
    TYPE(MPI_Comm), INTENT(IN) :: comm
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Comm::Reduce_scatter_block(const void* sendbuf, void* recvbuf,
    int recvcnt, const MPI::Datatype& datatype,
    const MPI::Op& op) const = 0(binding deprecated, see Section 15.2) }

```

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If `comm` is an intracommunicator, `MPI_REDUCE_SCATTER_BLOCK` first performs a global, element-wise reduction on vectors of `count = n*recvcount` elements in the send buffers defined by `sendbuf`, `count` and `datatype`, using the operation `op`, where `n` is the number of processes in the group of `comm`. The routine is called by all group members using the same arguments for `recvcount`, `datatype`, `op` and `comm`. The resulting vector is treated as `n` consecutive blocks of `recvcount` elements that are scattered to the processes of the group. The `i`-th block is sent to process `i` and stored in the receive buffer defined by `recvbuf`, `recvcount`, and `datatype`.

*Advice to implementors.* The `MPI_REDUCE_SCATTER_BLOCK` routine is functionally equivalent to: an `MPI_REDUCE` collective operation with `count` equal to `recvcount*n`, followed by an `MPI_SCATTER` with `sendcount` equal to `recvcount`. However, a direct implementation may run faster. (*End of advice to implementors.*)

The “in place” option for intracommunicators is specified by passing `MPI_IN_PLACE` in the `sendbuf` argument on *all* processes. In this case, the input data is taken from the receive buffer.

If `comm` is an intercommunicator, then the result of the reduction of the data provided by processes in one group (group A) is scattered among processes in the other group (group B) and vice versa. Within each group, all processes provide the same value for the `recvcount` argument, and provide input vectors of `count = n*recvcount` elements stored in the send buffers, where `n` is the size of the group. The number of elements `count` must be the same for the two groups. The resulting vector from the other group is scattered in blocks of `recvcount` elements among the processes in the group.

*Rationale.* The last restriction is needed so that the length of the send buffer of one group can be determined by the local `recvcount` argument of the other group. Otherwise, a communication is needed to figure out how many elements are reduced. (*End of rationale.*)

### 5.10.2 MPI\_REDUCE\_SCATTER

`MPI_REDUCE_SCATTER` extends the functionality of `MPI_REDUCE_SCATTER_BLOCK` such that the scattered blocks can vary in size. Block sizes are determined by the `recvcounts` array, such that the `i`-th block contains `recvcounts[i]` elements.

`MPI_REDUCE_SCATTER( sendbuf, recvbuf, recvcounts, datatype, op, comm)`

IN	sendbuf	starting address of send buffer (choice)
OUT	recvbuf	starting address of receive buffer (choice)
IN	recvcounts	non-negative integer array (of length group size) specifying the number of elements of the result distributed to each process.
IN	datatype	data type of elements of send and receive buffers (handle)
IN	op	operation (handle)
IN	comm	communicator (handle)

```

int MPI_Reduce_scatter(void* sendbuf, void* recvbuf, int recvcunts[],
                      MPI_Datatype datatype, MPI_Op op, MPI_Comm comm)
MPI_REDUCE_SCATTER(SENDBUF, RECVBUFF, RECVCOUNTS, DATATYPE, OP, COMM,
                  IERROR)
<type> SENDBUF(*), RECVBUFF(*)
INTEGER RECVCOUNTS(*), DATATYPE, OP, COMM, IERROR
MPI_Reduce_scatter(sendbuf, recvbuf, recvcunts, datatype, op, comm,
                  ierror)
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
INTEGER, INTENT(IN) :: recvcunts(*)
TYPE(MPI_Datatype), INTENT(IN) :: datatype
TYPE(MPI_Op), INTENT(IN) :: op
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
{void MPI::Comm::Reduce_scatter(const void* sendbuf, void* recvbuf,
                              int recvcunts[], const MPI::Datatype& datatype,
                              const MPI::Op& op) const = 0(binding deprecated, see Section 15.2) }

```

If `comm` is an intracommunicator, `MPI_REDUCE_SCATTER` first performs a global, element-wise reduction on vectors of  $\text{count} = \sum_{i=0}^{n-1} \text{recvcunts}[i]$  elements in the send buffers defined by `sendbuf`, `count` and `datatype`, using the operation `op`, where `n` is the number of processes in the group of `comm`. The routine is called by all group members using the same arguments for `recvcunts`, `datatype`, `op` and `comm`. The resulting vector is treated as `n` consecutive blocks where the number of elements of the `i`-th block is `recvcunts[i]`. The blocks are scattered to the processes of the group. The `i`-th block is sent to process `i` and stored in the receive buffer defined by `recvbuf`, `recvcunts[i]` and `datatype`.

*Advice to implementors.* The `MPI_REDUCE_SCATTER` routine is functionally equivalent to: an `MPI_REDUCE` collective operation with `count` equal to the sum of `recvcunts[i]` followed by `MPI_SCATTERV` with `sendcounts` equal to `recvcunts`. However, a direct implementation may run faster. (*End of advice to implementors.*)

The “in place” option for intracommunicators is specified by passing `MPI_IN_PLACE` in the `sendbuf` argument. In this case, the input data is taken from the receive buffer. It is not required to specify the “in place” option on all processes, since the processes for which `recvcunts[i]==0` may not have allocated a receive buffer.

If `comm` is an intercommunicator, then the result of the reduction of the data provided by processes in one group (group A) is scattered among processes in the other group (group B), and vice versa. Within each group, all processes provide the same `recvcunts` argument, and provide input vectors of  $\text{count} = \sum_{i=0}^{n-1} \text{recvcunts}[i]$  elements stored in the send buffers, where `n` is the size of the group. The resulting vector from the other group is scattered in blocks of `recvcunts[i]` elements among the processes in the group. The number of elements `count` must be the same for the two groups.

*Rationale.* The last restriction is needed so that the length of the send buffer can be determined by the sum of the local `recvcunts` entries. Otherwise, a communication is needed to figure out how many elements are reduced. (*End of rationale.*)

## 5.11 Scan

### 5.11.1 Inclusive Scan

`MPI_SCAN(sendbuf, recvbuf, count, datatype, op, comm)`

IN	<code>sendbuf</code>	starting address of send buffer (choice)
OUT	<code>recvbuf</code>	starting address of receive buffer (choice)
IN	<code>count</code>	number of elements in input buffer (non-negative integer)
IN	<code>datatype</code>	data type of elements of input buffer (handle)
IN	<code>op</code>	operation (handle)
IN	<code>comm</code>	communicator (handle)

```
int MPI_Scan(void* sendbuf, void* recvbuf, int count,
             MPI_Datatype datatype, MPI_Op op, MPI_Comm comm)
```

```
MPI_SCAN(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, IERROR)
<type> SENDBUF(*), RECVBUF(*)
INTEGER COUNT, DATATYPE, OP, COMM, IERROR
```

```
MPI_Scan(sendbuf, recvbuf, count, datatype, op, comm, ierror)
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
INTEGER, INTENT(IN) :: count
TYPE(MPI_Datatype), INTENT(IN) :: datatype
TYPE(MPI_Op), INTENT(IN) :: op
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Intracomm::Scan(const void* sendbuf, void* recvbuf, int count,
                           const MPI::Datatype& datatype, const MPI::Op& op) const(binding
depreacted, see Section 15.2) }
```

If `comm` is an intracommunicator, `MPI_SCAN` is used to perform a prefix reduction on data distributed across the group. The operation returns, in the receive buffer of the process with rank `i`, the reduction of the values in the send buffers of processes with ranks `0, ..., i` (inclusive). The type of operations supported, their semantics, and the constraints on send and receive buffers are as for `MPI_REDUCE`.

The “in place” option for intracommunicators is specified by passing `MPI_IN_PLACE` in the `sendbuf` argument. In this case, the input data is taken from the receive buffer, and replaced by the output data.

This operation is invalid for intercommunicators.



## 5.11.2 Exclusive Scan

`MPI_EXSCAN(sendbuf, recvbuf, count, datatype, op, comm)`

IN	<code>sendbuf</code>	starting address of send buffer (choice)
OUT	<code>recvbuf</code>	starting address of receive buffer (choice)
IN	<code>count</code>	number of elements in input buffer (non-negative integer)
IN	<code>datatype</code>	data type of elements of input buffer (handle)
IN	<code>op</code>	operation (handle)
IN	<code>comm</code>	intracommunicator (handle)

```
int MPI_Exscan(void* sendbuf, void* recvbuf, int count,
               MPI_Datatype datatype, MPI_Op op, MPI_Comm comm)
```

```
MPI_EXSCAN(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, IERROR)
<type> SENDBUF(*), RECVBUF(*)
INTEGER COUNT, DATATYPE, OP, COMM, IERROR
```

```
MPI_Exscan(sendbuf, recvbuf, count, datatype, op, comm, ierror)
  TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
  INTEGER, INTENT(IN) :: count
  TYPE(MPI_Datatype), INTENT(IN) :: datatype
  TYPE(MPI_Op), INTENT(IN) :: op
  TYPE(MPI_Comm), INTENT(IN) :: comm
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Intracomm::Exscan(const void* sendbuf, void* recvbuf, int count,
                             const MPI::Datatype& datatype, const MPI::Op& op) const(binding
                             deprecated, see Section 15.2) }
```

If `comm` is an intracommunicator, `MPI_EXSCAN` is used to perform a prefix reduction on data distributed across the group. The value in `recvbuf` on the process with rank 0 is undefined, and `recvbuf` is not significant on process 0. The value in `recvbuf` on the process with rank 1 is defined as the value in `sendbuf` on the process with rank 0. For processes with rank  $i > 1$ , the operation returns, in the receive buffer of the process with rank  $i$ , the reduction of the values in the send buffers of processes with ranks  $0, \dots, i - 1$  (inclusive). The type of operations supported, their semantics, and the constraints on send and receive buffers, are as for `MPI_REDUCE`.

The “in place” option for intracommunicators is specified by passing `MPI_IN_PLACE` in the `sendbuf` argument. In this case, the input data is taken from the receive buffer, and replaced by the output data. The receive buffer on rank 0 is not changed by this operation.

This operation is invalid for intercommunicators.

*Rationale.* The exclusive scan is more general than the inclusive scan. Any inclusive scan operation can be achieved by using the exclusive scan and then locally combining the local contribution. Note that for non-invertable operations such as `MPI_MAX`, the exclusive scan cannot be computed with the inclusive scan. (*End of rationale.*)

### 5.11.3 Example using MPI\_SCAN

The example in this section uses an intracommunicator.

#### Example 5.22

This example uses a user-defined operation to produce a *segmented scan*. A segmented scan takes, as input, a set of values and a set of logicals, and the logicals delineate the various segments of the scan. For example:

<i>values</i>	$v_1$	$v_2$	$v_3$	$v_4$	$v_5$	$v_6$	$v_7$	$v_8$
<i>logicals</i>	0	0	1	1	1	0	0	1
<i>result</i>	$v_1$	$v_1 + v_2$	$v_3$	$v_3 + v_4$	$v_3 + v_4 + v_5$	$v_6$	$v_6 + v_7$	$v_8$

The operator that produces this effect is,

$$\begin{pmatrix} u \\ i \end{pmatrix} \circ \begin{pmatrix} v \\ j \end{pmatrix} = \begin{pmatrix} w \\ j \end{pmatrix},$$

where,

$$w = \begin{cases} u + v & \text{if } i = j \\ v & \text{if } i \neq j \end{cases}.$$

Note that this is a non-commutative operator. C code that implements it is given below.

```

typedef struct {
    double val;
    int log;
} SegScanPair;

/* the user-defined function
*/
void segScan(SegScanPair *in, SegScanPair *inout, int *len,
             MPI_Datatype *dptr)
{
    int i;
    SegScanPair c;

    for (i=0; i< *len; ++i) {
        if (in->log == inout->log)
            c.val = in->val + inout->val;
        else
            c.val = inout->val;
        c.log = inout->log;
        *inout = c;
        in++; inout++;
    }
}

```

Note that the `inout` argument to the user-defined function corresponds to the right-hand operand of the operator. When using this operator, we must be careful to specify that it is non-commutative, as in the following.

```

int i,base;
SegScanPair  a, answer;
MPI_Op      myOp;
MPI_Datatype type[2] = {MPI_DOUBLE, MPI_INT};
MPI_Aint     disp[2];
int          blocklen[2] = { 1, 1};
MPI_Datatype sspair;

/* explain to MPI how type SegScanPair is defined
 */
MPI_Get_address( a, disp);
MPI_Get_address( a.log, disp+1);
base = disp[0];
for (i=0; i<2; ++i) disp[i] -= base;
MPI_Type_create_struct( 2, blocklen, disp, type, &sspair );
MPI_Type_commit( &sspair );
/* create the segmented-scan user-op
 */
MPI_Op_create(segScan, 0, &myOp);
...
MPI_Scan( &a, &answer, 1, sspair, myOp, comm );

```

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## 5.12 Nonblocking Collective Operations

As described in Section 3.7, performance of many applications can be improved by overlapping communication and computation, and many systems enable this. Nonblocking collective operations combine the potential benefits of nonblocking point-to-point operations, to exploit overlap and to avoid synchronization, with the optimized implementation and message scheduling provided by collective operations [27, 30]. One way of doing this would be to perform a blocking collective operation in a separate thread. An alternative mechanism that often leads to better performance (e.g., avoids context switching, scheduler overheads, and thread management) is to use nonblocking collective communication [28].

The nonblocking collective communication model is similar to the model used for nonblocking point-to-point communication. A nonblocking call initiates a collective operation, which must be completed in a separate completion call. Once initiated, the operation may progress independently of any computation or other communication at participating processes. In this manner, nonblocking collective operations can mitigate possible synchronizing effects of collective operations by running them in the “background.” In addition to enabling communication-computation overlap, nonblocking collective operations can perform collective operations on overlapping communicators, which would lead to deadlocks with blocking operations. Their semantic advantages can also be useful in combination with point-to-point communication.

As in the nonblocking point-to-point case, all calls are local and return immediately, irrespective of the status of other processes. The call initiates the operation, which indicates

that the system may start to copy data out of the send buffer and into the receive buffer. Once initiated, all associated send buffers and buffers associated with input arguments (such as arrays of counts, displacements, or datatypes in the vector versions of the collectives) should not be modified, and all associated receive buffers should not be accessed, until the collective operation completes. The call returns a request handle, which must be passed to a completion call.

All completion calls (e.g., `MPI_WAIT`) described in Section 3.7.3 are supported for nonblocking collective operations. Similarly to the blocking case, nonblocking collective operations are considered to be complete when the local part of the operation is finished, i.e., for the caller, the semantics of the operation are guaranteed and all buffers can be safely accessed and modified. Completion does not indicate that other processes have completed or even started the operation (unless otherwise implied by the description of the operation). Completion of a particular nonblocking collective operation also does not indicate completion of any other posted nonblocking collective (or send-receive) operations, whether they are posted before or after the completed operation.

*Advice to users.* Users should be aware that implementations are allowed, but not required (with exception of `MPI_IBARRIER`), to synchronize processes during the completion of a nonblocking collective operation. (*End of advice to users.*)

Upon returning from a completion call in which a nonblocking collective operation completes, the `MPI_ERROR` field in the associated status object is set appropriately. The values of the `MPI_SOURCE` and `MPI_TAG` fields are undefined. It is valid to mix different request types (i.e., any combination of collective requests, I/O requests, generalized requests, or point-to-point requests) in functions that enable multiple completions (e.g., `MPI_WAITALL`). It is erroneous to call `MPI_REQUEST_FREE` or `MPI_CANCEL` for a request associated with a nonblocking collective operation. Nonblocking collective requests are not persistent.

*Rationale.* Freeing an active nonblocking collective request could cause similar problems as discussed for point-to-point requests (see Section 3.7.3). Cancelling a request is not supported because the semantics of this operation are not well-defined. (*End of rationale.*)

Multiple nonblocking collective operations can be outstanding on a single communicator. If the nonblocking call causes some system resource to be exhausted, then it will fail and generate an MPI exception. Quality implementations of MPI should ensure that this happens only in pathological cases. That is, an MPI implementation should be able to support a large number of pending nonblocking operations.

Unlike point-to-point operations, nonblocking collective operations do not match with blocking collective operations, and collective operations do not have a tag argument. All processes must call collective operations (blocking and nonblocking) in the same order per communicator. In particular, once a process calls a collective operation, all other processes in the communicator must eventually call the same collective operation, and no other collective operation with the same communicator in between. This is consistent with the ordering rules for blocking collective operations in threaded environments.

*Rationale.* Matching blocking and nonblocking collective operations is not allowed because the implementation might use different communication algorithms for the two

cases. Blocking collective operations may be optimized for minimal time to completion, while nonblocking collective operations may balance time to completion with CPU overhead and asynchronous progression.

The use of tags for collective operations can prevent certain hardware optimizations. (*End of rationale.*)

*Advice to users.* If program semantics require matching blocking and nonblocking collective operations, then a nonblocking collective operation can be initiated and immediately completed with a blocking wait to emulate blocking behavior. (*End of advice to users.*)

In terms of data movements, each nonblocking collective operation has the same effect as its blocking counterpart for intracommunicators and intercommunicators after completion. Likewise, upon completion, nonblocking collective reduction operations have the same effect as their blocking counterparts, and the same restrictions and recommendations on reduction orders apply.

The use of the “in place” option is allowed exactly as described for the corresponding blocking collective operations. When using the “in place” option, message buffers function as both send and receive buffers. Such buffers should not be modified or accessed until the operation completes.

Progression rules for nonblocking collective operations are similar to progression of nonblocking point-to-point operations, refer to Section 3.7.4.

*Advice to implementors.* Nonblocking collective operations can be implemented with local execution schedules [29] using nonblocking point-to-point communication and a reserved tag-space. (*End of advice to implementors.*)

### 5.12.1 Nonblocking Barrier Synchronization

`MPI_IBARRIER(comm , request)`

IN	<code>comm</code>	communicator (handle)
OUT	<code>request</code>	communication request (handle)

`int MPI_Ibarrier(MPI_Comm comm, MPI_Request* request)`

`MPI_IBARRIER(COMM, REQUEST, IERROR)`  
`INTEGER COMM, REQUEST, IERROR`

`MPI_Ibarrier( -- Fortran 2008 -- to be done -- )`

`{MPI::Request MPI::Comm::Ibarrier() const = 0 (binding deprecated, see`  
`Section 15.2) }`

`MPI_IBARRIER` is a nonblocking version of `MPI_BARRIER`. By calling `MPI_IBARRIER`, a process notifies that it has reached the barrier. The call returns immediately, independent of whether other processes have called `MPI_IBARRIER`. The usual barrier semantics are enforced at the corresponding completion operation (test or wait), which in the intra-communicator case will complete only after all other processes in the communicator have

called `MPI_IBARRIER`. In the intercommunicator case, it will complete when all processes in the remote group have called `MPI_IBARRIER`.

*Advice to users.* A nonblocking barrier can be used to hide latency. Moving independent computations between the `MPI_IBARRIER` and the subsequent completion call can overlap the barrier latency and therefore shorten possible waiting times. The semantic properties are also useful when mixing collective operations and point-to-point messages. (*End of advice to users.*)

### 5.12.2 Nonblocking Broadcast

`MPI_IBCAST(buffer, count, datatype, root, comm, request)`

INOUT	buffer	starting address of buffer (choice)
IN	count	number of entries in buffer (non-negative integer)
IN	datatype	data type of buffer (handle)
IN	root	rank of broadcast root (integer)
IN	comm	communicator (handle)
OUT	request	communication request (handle)

```
int MPI_Ibcast(void* buffer, int count, MPI_Datatype datatype, int root,
               MPI_Comm comm, MPI_Request* request)
```

```
MPI_IBCAST(BUFFER, COUNT, DATATYPE, ROOT, COMM, REQUEST, IERROR)
```

```
<type> BUFFER(*)
```

```
INTEGER COUNT, DATATYPE, ROOT, COMM, REQUEST, IERROR
```

```
MPI_Ibcast( -- Fortran 2008 -- to be done -- )
```

```
{MPI::Request MPI::Comm::Ibcast(void* buffer, int count,
                                const MPI::Datatype& datatype, int root) const = 0(binding
                                deprecated, see Section 15.2) }
```

This call starts a nonblocking variant of `MPI_BCAST` (see Section 5.4).

#### Example using `MPI_IBCAST`

The example in this section uses intracommunicators.

#### Example 5.23

Start a broadcast of 100 ints from process 0 to every process in the group, perform some computation on independent data, and then complete the outstanding broadcast operation.

```

MPI_Comm comm;
int array1[100], array2[100];
int root=0;
MPI_Request req;
...
MPI_Ibcast(array1, 100, MPI_INT, root, comm, &req);
compute(array2, 100);
MPI_Wait(&req, MPI_STATUS_IGNORE);

```

### 5.12.3 Nonblocking Gather

`MPI_IGATHER`(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, root, comm, request)

IN	sendbuf	starting address of send buffer (choice)
IN	sendcount	number of elements in send buffer (non-negative integer)
IN	sendtype	data type of send buffer elements (handle)
OUT	recvbuf	address of receive buffer (choice, significant only at root)
IN	recvcount	number of elements for any single receive (non-negative integer, significant only at root)
IN	recvtype	data type of recv buffer elements (significant only at root) (handle)
IN	root	rank of receiving process (integer)
IN	comm	communicator (handle)
OUT	request	communication request (handle)

```

int MPI_Igather(void* sendbuf, int sendcount, MPI_Datatype sendtype,
               void* recvbuf, int recvcount, MPI_Datatype recvtype, int root,
               MPI_Comm comm, MPI_Request* request)

```

```

MPI_IGATHER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE,
            ROOT, COMM, REQUEST, IERROR)
<type> SENDBUF(*), RECVBUF(*)
INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, ROOT, COMM, REQUEST,
IERROR

```

`MPI_Igather`( -- Fortran 2008 -- to be done -- )

```

{MPI::Request MPI::Comm::Igather(const void* sendbuf, int sendcount, const
MPI::Datatype& sendtype, void* recvbuf, int recvcount,
const MPI::Datatype& recvtype, int root) const = 0(binding
deprecated, see Section 15.2) }

```

This call starts a nonblocking variant of `MPI_GATHER` (see Section 5.5).

ticket-248T.

```

1 MPI_IGATHERV(sendbuf, sendcount, sendtype, recvbuf, recvcoun-
2               comm, request)

```

3	IN	sendbuf	starting address of send buffer (choice)
4	IN	sendcount	number of elements in send buffer (non-negative integer)
5	IN	sendtype	data type of send buffer elements (handle)
6	OUT	recvbuf	address of receive buffer (choice, significant only at root)
7	IN	recvcoun-	non-negative integer array (of length group size) con-
8			taining the number of elements that are received from
9			each process (significant only at root)
10	IN	displs	integer array (of length group size). Entry i specifies
11			the displacement relative to <code>recvbuf</code> at which to place
12			the incoming data from process i (significant only at
13			root)
14	IN	recvtype	data type of recv buffer elements (significant only at
15			root) (handle)
16	IN	root	rank of receiving process (integer)
17	IN	comm	communicator (handle)
18	OUT	request	communication request (handle)

```

25 int MPI_Igatherv(void* sendbuf, int sendcount, MPI_Datatype sendtype,
26                 void* recvbuf, int recvcoun-
27                 MPI_Datatype recvtype, int root, MPI_Comm comm,
28                 MPI_Request* request)
29
30 MPI_IGATHERV(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNTS, DISPLS,
31              RECVTYPE, ROOT, COMM, REQUEST, IERROR)
32
33 <type> SENDBUF(*), RECVBUF(*)
34 INTEGER SENDCOUNT, SENDTYPE, RECVCOUNTS(*), DISPLS(*), RECVTYPE, ROOT,
35 COMM, REQUEST, IERROR

```

```

36 MPI_Igatherv( -- Fortran 2008 -- to be done -- )
37
38 {MPI::Request MPI::Comm::Igatherv(const void* sendbuf, int sendcount, const
39 MPI::Datatype& sendtype, void* recvbuf,
40 const int recvcoun-
41 const MPI::Datatype& recvtype, int root) const = 0(binding
42 deprecated, see Section 15.2) }

```

This call starts a nonblocking variant of `MPI_GATHERV` (see Section 5.5).



## 5.12.4 Nonblocking Scatter

`MPI_ISCATTER(sendbuf, sendcount, sendtype, recvbuf, recvcoun, recvtype, root, comm, request)`

IN	sendbuf	address of send buffer (choice, significant only at root)
IN	sendcount	number of elements sent to each process (non-negative integer, significant only at root)
IN	sendtype	data type of send buffer elements (significant only at root) (handle)
OUT	recvbuf	address of receive buffer (choice)
IN	recvcoun	number of elements in receive buffer (non-negative integer)
IN	recvtype	data type of receive buffer elements (handle)
IN	root	rank of sending process (integer)
IN	comm	communicator (handle)
OUT	request	communication request (handle)

```
int MPI_Iscatter(void* sendbuf, int sendcount, MPI_Datatype sendtype,
               void* recvbuf, int recvcoun, MPI_Datatype recvtype, int root,
               MPI_Comm comm, MPI_Request* request)
```

```
MPI_ISCATTER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE,
             ROOT, COMM, REQUEST, IERROR)
    <type> SENDBUF(*), RECVBUF(*)
    INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, ROOT, COMM, REQUEST,
    IERROR
```

```
MPI_Iscatter( -- Fortran 2008 -- to be done -- )
```

```
{MPI::Request MPI::Comm::Iscatter(const void* sendbuf, int sendcount, const
    MPI::Datatype& sendtype, void* recvbuf, int recvcoun,
    const MPI::Datatype& recvtype, int root) const = 0(binding
    deprecated, see Section 15.2) }
```

This call starts a nonblocking variant of `MPI_SCATTER` (see Section 5.6).

ticket-248T.

```
1 MPI_ISCATTERV(sendbuf, sendcounts, displs, sendtype, recvbuf, recvcoun, recvtype, root,
2               comm, request)
```

3	IN	sendbuf	address of send buffer (choice, significant only at root)
4	IN	sendcounts	non-negative integer array (of length group size) specifying the number of elements to send to each processor
5			
6			
7	IN	displs	integer array (of length group size). Entry <i>i</i> specifies the displacement (relative to <code>sendbuf</code> ) from which to take the outgoing data to process <i>i</i>
8			
9			
10	IN	sendtype	data type of send buffer elements (handle)
11	OUT	recvbuf	address of receive buffer (choice)
12	IN	recvcoun	number of elements in receive buffer (non-negative integer)
13			
14			
15	IN	recvtype	data type of receive buffer elements (handle)
16			
17	IN	root	rank of sending process (integer)
18	IN	comm	communicator (handle)
19	OUT	request	communication request (handle)
20			

```
21
ticket0. 22 int MPI_Iscatterv(void* sendbuf, int sendcounts[], int displs[],
ticket0. 23     MPI_Datatype sendtype, void* recvbuf, int recvcoun,
ticket0. 24     MPI_Datatype recvtype, int root, MPI_Comm comm,
ticket0. 25     MPI_Request* request)
26 MPI_ISCATTERV(SENDBUF, SENDCOUNTS, DISPLS, SENDTYPE, RECVBUF, REVCOUNT,
27               RECVTYPE, ROOT, COMM, REQUEST, IERROR)
28 <type> SENDBUF(*), RECVBUF(*)
29 INTEGER SENDCOUNTS(*), DISPLS(*), SENDTYPE, REVCOUNT, RECVTYPE, ROOT,
30 COMM, REQUEST, IERROR
ticket-248T. 31 MPI_Iscatterv( -- Fortran 2008 -- to be done -- )
32
33 {MPI::Request MPI::Comm::Iscatterv(const void* sendbuf,
34     const int sendcounts[], const int displs[],
35     const MPI::Datatype& sendtype, void* recvbuf, int recvcoun,
36     const MPI::Datatype& recvtype, int root) const = 0(binding
37     deprecated, see Section 15.2) }
```

This call starts a nonblocking variant of `MPI_SCATTERV` (see Section 5.6).

## 5.12.5 Nonblocking Gather-to-all

`MPI_IALLGATHER(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, comm, request)`

IN	<code>sendbuf</code>	starting address of send buffer (choice)
IN	<code>sendcount</code>	number of elements in send buffer (non-negative integer)
IN	<code>sendtype</code>	data type of send buffer elements (handle)
OUT	<code>recvbuf</code>	address of receive buffer (choice)
IN	<code>recvcount</code>	number of elements received from any process (non-negative integer)
IN	<code>recvtype</code>	data type of receive buffer elements (handle)
IN	<code>comm</code>	communicator (handle)
OUT	<code>request</code>	communication request (handle)

```
int MPI_Iallgather(void* sendbuf, int sendcount, MPI_Datatype sendtype,
                  void* recvbuf, int recvcount, MPI_Datatype recvtype,
                  MPI_Comm comm, MPI_Request* request)
```

```
MPI_IALLGATHER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, REVCOUNT, RECVTYPE,
               COMM, REQUEST, IERROR)
<type> SENDBUF(*), RECVBUF(*)
INTEGER SENDCOUNT, SENDTYPE, REVCOUNT, RECVTYPE, COMM, REQUEST, IERROR
```

```
MPI_Iallgather( -- Fortran 2008 -- to be done -- )
```

```
{MPI::Request MPI::Comm::Iallgather(const void* sendbuf, int sendcount,
                                     const MPI::Datatype& sendtype, void* recvbuf, int recvcount,
                                     const MPI::Datatype& recvtype) const = 0 (binding deprecated, see
                                     Section 15.2) }
```

This call starts a nonblocking variant of `MPI_ALLGATHER` (see Section 5.7).

ticket-248T.

```

1 MPI_IALLGATHERV(sendbuf, sendcount, sendtype, recvbuf, recvcoun-
2                 request)

```

3	IN	sendbuf	starting address of send buffer (choice)
4	IN	sendcount	number of elements in send buffer (non-negative integer)
5			
6			
7	IN	sendtype	data type of send buffer elements (handle)
8	OUT	recvbuf	address of receive buffer (choice)
9			
10	IN	recvcoun-	non-negative integer array (of length group size) con-
11			taining the number of elements that are received from
12			each process
13	IN	displs	integer array (of length group size). Entry <i>i</i> specifies
14			the displacement (relative to <i>recvbuf</i> ) at which to place
15			the incoming data from process <i>i</i>
16	IN	recvtype	data type of receive buffer elements (handle)
17	IN	comm	communicator (handle)
18	OUT	request	communication request (handle)
19			
20			

```

21 int MPI_Iallgatherv(void* sendbuf, int sendcount, MPI_Datatype sendtype,
22                   void* recvbuf, int recvcoun-
23                   MPI_Datatype recvtype, MPI_Comm comm, MPI_Request* request)
24 MPI_IALLGATHERV(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNTS, DISPLS,
25                 RECVTYPE, COMM, REQUEST, IERROR)
26 <type> SENDBUF(*), RECVBUF(*)
27 INTEGER SENDCOUNT, SENDTYPE, REVCOUNTS(*), DISPLS(*), RECVTYPE, COMM,
28 REQUEST, IERROR

```

```

29 MPI_Iallgatherv( -- Fortran 2008 -- to be done -- )

```

```

30 {MPI::Request MPI::Comm::Iallgatherv(const void* sendbuf, int sendcount,
31                                     const MPI::Datatype& sendtype, void* recvbuf,
32                                     const int recvcoun-
33                                     const int displs[],
34                                     const MPI::Datatype& recvtype) const = 0(binding deprecated, see
35                                     Section 15.2) }

```

This call starts a nonblocking variant of MPI\_ALLGATHERV (see Section 5.7).

## 5.12.6 Nonblocking All-to-All Scatter/Gather

`MPI_IALLTOALL(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, comm, request)`

IN	<code>sendbuf</code>	starting address of send buffer (choice)
IN	<code>sendcount</code>	number of elements sent to each process (non-negative integer)
IN	<code>sendtype</code>	data type of send buffer elements (handle)
OUT	<code>recvbuf</code>	address of receive buffer (choice)
IN	<code>recvcount</code>	number of elements received from any process (non-negative integer)
IN	<code>recvtype</code>	data type of receive buffer elements (handle)
IN	<code>comm</code>	communicator (handle)
OUT	<code>request</code>	communication request (handle)

```
int MPI_Ialltoall(void* sendbuf, int sendcount, MPI_Datatype sendtype,
                 void* recvbuf, int recvcount, MPI_Datatype recvtype,
                 MPI_Comm comm, MPI_Request* request)
```

```
MPI_IALLTOALL(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE,
              COMM, REQUEST, IERROR)
    <type> SENDBUF(*), RECVBUF(*)
    INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, COMM, REQUEST, IERROR
```

```
MPI_Ialltoall( -- Fortran 2008 -- to be done -- )
```

```
{MPI::Request MPI::Comm::Ialltoall(const void* sendbuf, int sendcount,
    const MPI::Datatype& sendtype, void* recvbuf, int recvcount,
    const MPI::Datatype& recvtype) const = 0(binding deprecated, see
    Section 15.2) }
```

This call starts a nonblocking variant of `MPI_ALLTOALL` (see Section 5.8).

ticket-248T.

```

1  MPI_IALLTOALLV(sendbuf, sendcounts, sdispls, sendtype, recvbuf, recvcoun-
2      type, comm, request)
3
4      IN      sendbuf      starting address of send buffer (choice)
5
6      IN      sendcounts   non-negative integer array (of length group size) speci-
7                          fying the number of elements to send to each processor
8
9      IN      sdispls      integer array (of length group size). Entry j specifies
10                      the displacement (relative to sendbuf) from which to
11                      take the outgoing data destined for process j
12
13      IN      sendtype     data type of send buffer elements (handle)
14
15      OUT     recvbuf      address of receive buffer (choice)
16
17      IN      recvcoun-    non-negative integer array (of length group size) speci-
18                      fying the number of elements that can be received
19                      from each processor
20
21      IN      rdispls      integer array (of length group size). Entry i specifies
22                      the displacement (relative to recvbuf) at which to place
23                      the incoming data from process i
24
25      IN      recvtype     data type of receive buffer elements (handle)
26
27      IN      comm         communicator (handle)
28
29      OUT     request      communication request (handle)

```

```

ticket0. 25  int MPI_Ialltoallv(void* sendbuf, int sendcounts[], int sdispls[],
ticket0. 26      MPI_Datatype sendtype, void* recvbuf, int recvcoun-
ticket0. 27      int rdispls[], MPI_Datatype recvtype, MPI_Comm comm,
ticket0. 28      MPI_Request* request)
ticket0. 29
ticket0. 30  MPI_IALLTOALLV(SENDBUF, SENDCOUNTS, SDISPLS, SENDTYPE, RECVBUF, RECVCOUNTS,
ticket0. 31      RDISPLS, RECVTYPE, COMM, REQUEST, IERROR)
ticket0. 32      <type> SENDBUF(*), RECVBUF(*)
ticket0. 33      INTEGER SENDCOUNTS(*), SDISPLS(*), SENDTYPE, REVCOUNTS(*), RDISPLS(*),
ticket0. 34      RECVTYPE, COMM, REQUEST, IERROR

```

```

ticket-248T. 35  MPI_Ialltoallv( -- Fortran 2008 -- to be done -- )
36
37  {MPI::Request MPI::Comm::Ialltoallv(const void* sendbuf,
38      const int sendcounts[], const int sdispls[],
39      const MPI::Datatype& sendtype, void* recvbuf,
40      const int recvcoun- counts[], const int rdispls[],
41      const MPI::Datatype& recvtype) const = 0(binding deprecated, see
42      Section 15.2) }

```

This call starts a nonblocking variant of MPI\_ALLTOALLV (see Section 5.8).

```
MPI_IALLTOALLW(sendbuf, sendcounts, sdispls, sendtypes, recvbuf, recvcoun- 1
                types, comm, request) 2
```

IN	sendbuf	starting address of send buffer (choice)	3
IN	sendcounts	integer array (of length group size) specifying the num- 4 ber of elements to send to each processor (array of 5 non-negative integers) 6	7
IN	sdispls	integer array (of length group size). Entry j specifies 8 the displacement in bytes (relative to sendbuf) from 9 which to take the outgoing data destined for process 10 j (array of integers) 11	12
IN	sendtypes	array of datatypes (of length group size). Entry j 12 specifies the type of data to send to process j (array 13 of handles) 14	15
OUT	recvbuf	address of receive buffer (choice)	16
IN	recvcoun-	integer array (of length group size) specifying the num- 17 ber of elements that can be received from each proces- 18 sor (array of non-negative integers) 19	20
IN	rdispls	integer array (of length group size). Entry i specifies 20 the displacement in bytes (relative to recvbuf) at which 21 to place the incoming data from process i (array of 22 integers) 23	24
IN	recvtypes	array of datatypes (of length group size). Entry i 24 specifies the type of data received from process i (ar- 25 ray of handles) 26	27
IN	comm	communicator (handle)	28
OUT	request	communication request (handle)	29

```
int MPI_Ialltoallw(void* sendbuf, int sendcounts[], int sdispls[], 31
                  MPI_Datatype sendtypes[], void* recvbuf, int recvcoun- 32
                  ts[], MPI_Datatype recvtypes[], MPI_Comm comm, 33
                  MPI_Request* request) 34
```

```
MPI_IALLTOALLW(SENDBUF, SENDCOUNTS, SDISPLS, SENDTYPES, RECVBUF, 35
                RECVCOUNTS, RDISPLS, RECVTYPES, COMM, REQUEST, IERROR) 36
<type> SENDBUF(*), RECVBUF(*) 37
INTEGER SENDCOUNTS(*), SDISPLS(*), SENDTYPES(*), RECVCOUNTS(*), 38
RDISPLS(*), RECVTYPES(*), COMM, REQUEST, IERROR 39
```

```
MPI_Ialltoallw( -- Fortran 2008 -- to be done -- ) 40
```

```
{MPI::Request MPI::Comm::Ialltoallw(const void* sendbuf, const int 41
    sendcounts[], const int sdispls[], const MPI::Datatype 42
    sendtypes[], void* recvbuf, const int recvcoun- 43
    ts[], const MPI::Datatype recvtypes[]) const = 0(binding 44
    deprecated, see Section 15.2) } 45
```

This call starts a nonblocking variant of MPI\_ALLTOALLW (see Section 5.8). 46

## 5.12.7 Nonblocking Reduce

`MPI_IREDUCE(sendbuf, recvbuf, count, datatype, op, root, comm, request)`

IN	<code>sendbuf</code>	address of send buffer (choice)
OUT	<code>recvbuf</code>	address of receive buffer (choice, significant only at root)
IN	<code>count</code>	number of elements in send buffer (non-negative integer)
IN	<code>datatype</code>	data type of elements of send buffer (handle)
IN	<code>op</code>	reduce operation (handle)
IN	<code>root</code>	rank of root process (integer)
IN	<code>comm</code>	communicator (handle)
OUT	<code>request</code>	communication request (handle)

```
int MPI_Ireduce(void* sendbuf, void* recvbuf, int count,
               MPI_Datatype datatype, MPI_Op op, int root, MPI_Comm comm,
               MPI_Request* request)
```

```
MPI_IREDUCE(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, ROOT, COMM, REQUEST,
            IERROR)
    <type> SENDBUF(*), RECVBUF(*)
    INTEGER COUNT, DATATYPE, OP, ROOT, COMM, REQUEST, IERROR
```

```
MPI_Ireduce( -- Fortran 2008 -- to be done -- )
```

```
{MPI::Request MPI::Comm::Ireduce(const void* sendbuf, void* recvbuf,
    int count, const MPI::Datatype& datatype, const MPI::Op& op,
    int root) const = 0(binding deprecated, see Section 15.2) }
```

This call starts a nonblocking variant of `MPI_REDUCE` (see Section 5.9.1).

*Advice to implementors.* The implementation is explicitly allowed to use different algorithms for blocking and nonblocking reduction operations that might change the order of evaluation of the operations. However, as for `MPI_REDUCE`, it is strongly recommended that `MPI_IREDUCE` be implemented so that the same result be obtained whenever the function is applied on the same arguments, appearing in the same order. Note that this may prevent optimizations that take advantage of the physical location of processes. (*End of advice to implementors.*)

*Advice to users.* For operations which are not truly associative, the result delivered upon completion of the nonblocking reduction may not exactly equal the result delivered by the blocking reduction, even when specifying the same arguments in the same order. (*End of advice to users.*)



## 5.12.8 Nonblocking All-Reduce

`MPI_IALLREDUCE(sendbuf, recvbuf, count, datatype, op, comm, request)`

IN	sendbuf	starting address of send buffer (choice)
OUT	recvbuf	starting address of receive buffer (choice)
IN	count	number of elements in send buffer (non-negative integer)
IN	datatype	data type of elements of send buffer (handle)
IN	op	operation (handle)
IN	comm	communicator (handle)
OUT	request	communication request (handle)

```
int MPI_Iallreduce(void* sendbuf, void* recvbuf, int count,
                  MPI_Datatype datatype, MPI_Op op, MPI_Comm comm,
                  MPI_Request* request)
```

```
MPI_IALLREDUCE(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, REQUEST,
               IERROR)
```

```
<type> SENDBUF(*), RECVBUF(*)
```

```
INTEGER COUNT, DATATYPE, OP, COMM, REQUEST, IERROR
```

```
MPI_Iallreduce( -- Fortran 2008 -- to be done -- )
```

```
{MPI::Request MPI::Comm::Iallreduce(const void* sendbuf, void* recvbuf,
int count, const MPI::Datatype& datatype, const MPI::Op& op)
const = 0(binding deprecated, see Section 15.2) }
```

This call starts a nonblocking variant of `MPI_ALLREDUCE` (see Section 5.9.6).

## 5.12.9 Nonblocking Reduce-Scatter with Equal Blocks

`MPI_IREDUCE_SCATTER_BLOCK(sendbuf, recvbuf, recvcount, datatype, op, comm, request)`

IN	sendbuf	starting address of send buffer (choice)
OUT	recvbuf	starting address of receive buffer (choice)
IN	recvcount	element count per block (non-negative integer)
IN	datatype	data type of elements of send and receive buffers (handle)
IN	op	operation (handle)
IN	comm	communicator (handle)
OUT	request	communication request (handle)

```

1  int MPI_Ireduce_scatter_block(void* sendbuf, void* recvbuf, int recvcnt,
2                               MPI_Datatype datatype, MPI_Op op, MPI_Comm comm,
3                               MPI_Request* request)

```

```

4  MPI_IREDUCE_SCATTER_BLOCK(SENDBUF, RECVBUF, RECVCOUNT, DATATYPE, OP, COMM,
5                             REQUEST, IERROR)

```

```

6  <type> SENDBUF(*), RECVBUF(*)

```

```

7  INTEGER RECVCOUNT, DATATYPE, OP, COMM, REQUEST, IERROR

```

```

8  MPI_Ireduce_scatter_block( -- Fortran 2008 -- to be done -- )

```

```

9  {MPI::Request MPI::Comm::Ireduce_scatter_block(const void* sendbuf,
10 void* recvbuf, int recvcnt, const MPI::Datatype& datatype,
11 const MPI::Op& op) const = 0(binding deprecated, see Section 15.2) }

```

This call starts a nonblocking variant of MPI\_REDUCE\_SCATTER\_BLOCK (see Section 5.10.1).

### 5.12.10 Nonblocking Reduce-Scatter

```

17  MPI_IREDUCE_SCATTER(sendbuf, recvbuf, recvcnts, datatype, op, comm, request)

```

```

18  IN      sendbuf      starting address of send buffer (choice)

```

```

19  OUT     recvbuf      starting address of receive buffer (choice)

```

```

20  IN      recvcnts      non-negative integer array specifying the number of
21                      elements in result distributed to each process. Array
22                      must be identical on all calling processes.

```

```

23  IN      datatype      data type of elements of input buffer (handle)

```

```

24  IN      op            operation (handle)

```

```

25  IN      comm          communicator (handle)

```

```

26  OUT     request       communication request (handle)

```

```

27  int MPI_Ireduce_scatter(void* sendbuf, void* recvbuf, int recvcnts[],
28                          MPI_Datatype datatype, MPI_Op op, MPI_Comm comm,
29                          MPI_Request* request)

```

```

30  MPI_IREDUCE_SCATTER(SENDBUF, RECVBUF, RECVCOUNTS, DATATYPE, OP, COMM,
31                      REQUEST, IERROR)

```

```

32  <type> SENDBUF(*), RECVBUF(*)

```

```

33  INTEGER RECVCOUNTS(*), DATATYPE, OP, COMM, REQUEST, IERROR

```

```

34  MPI_Ireduce_scatter( -- Fortran 2008 -- to be done -- )

```

```

35  {MPI::Request MPI::Comm::Ireduce_scatter(const void* sendbuf,
36 void* recvbuf, int recvcnts[],
37 const MPI::Datatype& datatype, const MPI::Op& op)
38 const = 0(binding deprecated, see Section 15.2) }

```

This call starts a nonblocking variant of MPI\_REDUCE\_SCATTER (see Section 5.10.2).

## 5.12.11 Nonblocking Inclusive Scan

```
MPI_ISCAN(sendbuf, recvbuf, count, datatype, op, comm, request)
```

IN	sendbuf	starting address of send buffer (choice)
OUT	recvbuf	starting address of receive buffer (choice)
IN	count	number of elements in input buffer (non-negative integer)
IN	datatype	data type of elements of input buffer (handle)
IN	op	operation (handle)
IN	comm	communicator (handle)
OUT	request	communication request (handle)

```
int MPI_Iscan(void* sendbuf, void* recvbuf, int count,
              MPI_Datatype datatype, MPI_Op op, MPI_Comm comm,
              MPI_Request* request)
```

```
MPI_ISCAN(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, REQUEST, IERROR)
<type> SENDBUF(*), RECVBUF(*)
INTEGER COUNT, DATATYPE, OP, COMM, REQUEST, IERROR
```

```
MPI_Iscan( -- Fortran 2008 -- to be done -- )
```

```
{MPI::Request MPI::Intracomm::Iscale(const void* sendbuf, void* recvbuf,
int count, const MPI::Datatype& datatype, const MPI::Op& op)
const(binding deprecated, see Section 15.2) }
```

This call starts a nonblocking variant of MPI\_SCAN (see Section 5.11).

## 5.12.12 Nonblocking Exclusive Scan

```
MPI_IEXSCAN(sendbuf, recvbuf, count, datatype, op, comm, request)
```

IN	sendbuf	starting address of send buffer (choice)
OUT	recvbuf	starting address of receive buffer (choice)
IN	count	number of elements in input buffer (non-negative integer)
IN	datatype	data type of elements of input buffer (handle)
IN	op	operation (handle)
IN	comm	intracommunicator (handle)
OUT	request	communication request (handle)

```

1  int MPI_Iexscan(void* sendbuf, void* recvbuf, int count,
2                  MPI_Datatype datatype, MPI_Op op, MPI_Comm comm,
3                  MPI_Request* request)
4
5  MPI_IEXSCAN(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, REQUEST, IERROR)
6      <type> SENDBUF(*), RECVBUF(*)
7      INTEGER COUNT, DATATYPE, OP, COMM, REQUEST, IERROR
8
9  MPI_Iexscan( -- Fortran 2008 -- to be done -- )
10
11  {MPI::Request MPI::Intracomm::Iexscan(const void* sendbuf, void* recvbuf,
12      int count, const MPI::Datatype& datatype, const MPI::Op& op)
13      const(binding deprecated, see Section 15.2) }

```

This call starts a nonblocking variant of MPI\_EXSCAN (see Section 5.11.2).

### 5.13 Correctness

A correct, portable program must invoke collective communications so that deadlock will not occur, whether collective communications are synchronizing or not. The following examples illustrate dangerous use of collective routines on intracommunicators.

#### Example 5.24

The following is erroneous.

```

24  switch(rank) {
25      case 0:
26          MPI_Bcast(buf1, count, type, 0, comm);
27          MPI_Bcast(buf2, count, type, 1, comm);
28          break;
29      case 1:
30          MPI_Bcast(buf2, count, type, 1, comm);
31          MPI_Bcast(buf1, count, type, 0, comm);
32          break;
33  }

```

We assume that the group of `comm` is `{0,1}`. Two processes execute two broadcast operations in reverse order. If the operation is synchronizing then a deadlock will occur.

Collective operations must be executed in the same order at all members of the communication group.

#### Example 5.25

The following is erroneous.

```

switch(rank) {
    case 0:
        MPI_Bcast(buf1, count, type, 0, comm0);
        MPI_Bcast(buf2, count, type, 2, comm2);
        break;
    case 1:
        MPI_Bcast(buf1, count, type, 1, comm1);
        MPI_Bcast(buf2, count, type, 0, comm0);
        break;
    case 2:
        MPI_Bcast(buf1, count, type, 2, comm2);
        MPI_Bcast(buf2, count, type, 1, comm1);
        break;
}

```

Assume that the group of `comm0` is  $\{0,1\}$ , of `comm1` is  $\{1, 2\}$  and of `comm2` is  $\{2,0\}$ . If the broadcast is a synchronizing operation, then there is a cyclic dependency: the broadcast in `comm2` completes only after the broadcast in `comm0`; the broadcast in `comm0` completes only after the broadcast in `comm1`; and the broadcast in `comm1` completes only after the broadcast in `comm2`. Thus, the code will deadlock.

Collective operations must be executed in an order so that no cyclic dependencies occur. Nonblocking collective operations can alleviate this issue.

#### Example 5.26

The following is erroneous.

```

switch(rank) {
    case 0:
        MPI_Bcast(buf1, count, type, 0, comm);
        MPI_Send(buf2, count, type, 1, tag, comm);
        break;
    case 1:
        MPI_Recv(buf2, count, type, 0, tag, comm, status);
        MPI_Bcast(buf1, count, type, 0, comm);
        break;
}

```

Process zero executes a broadcast, followed by a blocking send operation. Process one first executes a blocking receive that matches the send, followed by broadcast call that matches the broadcast of process zero. This program may deadlock. The broadcast call on process zero *may* block until process one executes the matching broadcast call, so that the send is not executed. Process one will definitely block on the receive and so, in this case, never executes the broadcast.

The relative order of execution of collective operations and point-to-point operations should be such, so that even if the collective operations and the point-to-point operations are synchronizing, no deadlock will occur.

#### Example 5.27

An unsafe, non-deterministic program.

```

1  switch(rank) {
2      case 0:
3          MPI_Bcast(buf1, count, type, 0, comm);
4          MPI_Send(buf2, count, type, 1, tag, comm);
5          break;
6      case 1:
7          MPI_Recv(buf2, count, type, MPI_ANY_SOURCE, tag, comm, status);
8          MPI_Bcast(buf1, count, type, 0, comm);
9          MPI_Recv(buf2, count, type, MPI_ANY_SOURCE, tag, comm, status);
10         break;
11     case 2:
12         MPI_Send(buf2, count, type, 1, tag, comm);
13         MPI_Bcast(buf1, count, type, 0, comm);
14         break;
15 }

```

All three processes participate in a broadcast. Process 0 sends a message to process 1 after the broadcast, and process 2 sends a message to process 1 before the broadcast. Process 1 receives before and after the broadcast, with a wildcard source argument.

Two possible executions of this program, with different matchings of sends and receives, are illustrated in Figure 5.12. Note that the second execution has the peculiar effect that a send executed after the broadcast is received at another node before the broadcast. This example illustrates the fact that one should not rely on collective communication functions to have particular synchronization effects. A program that works correctly only when the first execution occurs (only when broadcast is synchronizing) is erroneous.

Finally, in multithreaded implementations, one can have more than one, concurrently executing, collective communication call at a process. In these situations, it is the user's responsibility to ensure that the same communicator is not used concurrently by two different collective communication calls at the same process.

*Advice to implementors.* Assume that broadcast is implemented using point-to-point MPI communication. Suppose the following two rules are followed.

1. All receives specify their source explicitly (no wildcards).
2. Each process sends all messages that pertain to one collective call before sending any message that pertain to a subsequent collective call.

Then, messages belonging to successive broadcasts cannot be confused, as the order of point-to-point messages is preserved.

It is the implementor's responsibility to ensure that point-to-point messages are not confused with collective messages. One way to accomplish this is, whenever a communicator is created, to also create a "hidden communicator" for collective communication. One could achieve a similar effect more cheaply, for example, by using a hidden tag or context bit to indicate whether the communicator is used for point-to-point or collective communication. (*End of advice to implementors.*)

### Example 5.28

Blocking and nonblocking collective operations can be interleaved, i.e., a blocking collective operation can be posted even if there is a nonblocking collective operation outstanding.

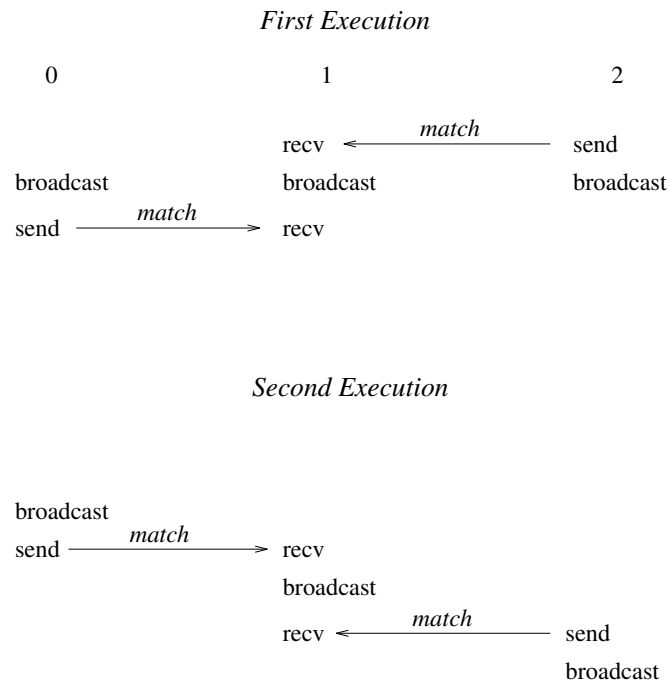


Figure 5.12: A race condition causes non-deterministic matching of sends and receives. One cannot rely on synchronization from a broadcast to make the program deterministic.

```
MPI_Request req;
```

```
MPI_Ibarrier(comm, &req);
```

```
MPI_Bcast(buf1, count, type, 0, comm);
```

```
MPI_Wait(&req, MPI_STATUS_IGNORE);
```

Each process starts a nonblocking barrier operation, participates in a blocking broadcast and then waits until every other process started the barrier operation. This effectively turns the broadcast into a synchronizing broadcast with possible communication/communication overlap (MPI\_Bcast is allowed, but not required to synchronize).

### Example 5.29

The starting order of collective operations on a particular communicator defines their matching. The following example shows an erroneous matching of different collective operations on the same communicator.

```
MPI_Request req;
```

```
switch(rank) {
```

```
    case 0:
```

```
        /* erroneous matching */
```

```
        MPI_Ibarrier(comm, &req);
```

```
        MPI_Bcast(buf1, count, type, 0, comm);
```

```
        MPI_Wait(&req, MPI_STATUS_IGNORE);
```

```
        break;
```

```
    case 1:
```

```

1      /* erroneous matching */
2      MPI_Bcast(buf1, count, type, 0, comm);
3      MPI_Ibarrier(comm, &req);
4      MPI_Wait(&req, MPI_STATUS_IGNORE);
5      break;
6  }

```

This ordering would match `MPI_Ibarrier` on rank 0 with `MPI_Bcast` on rank 1 which is erroneous and the program behavior is undefined. However, if such an order is required, the user must create different duplicate communicators and perform the operations on them. If started with two processes, the following program would be correct:

```

12
13 MPI_Request req;
14 MPI_Comm dupcomm;
15 MPI_Comm_dup(comm, &dupcomm);
16 switch(rank) {
17     case 0:
18         MPI_Ibarrier(comm, &req);
19         MPI_Bcast(buf1, count, type, 0, dupcomm);
20         MPI_Wait(&req, MPI_STATUS_IGNORE);
21         break;
22     case 1:
23         MPI_Bcast(buf1, count, type, 0, dupcomm);
24         MPI_Ibarrier(comm, &req);
25         MPI_Wait(&req, MPI_STATUS_IGNORE);
26         break;
27 }

```

*Advice to users.* The use of different communicators offers some flexibility regarding the matching of nonblocking collective operations. In this sense, communicators could be used as an equivalent to tags. However, communicator construction might induce overheads so that this should be used carefully. (*End of advice to users.*)

### Example 5.30

Nonblocking collective operations can rely on the same progression rules as nonblocking point-to-point messages. Thus, if started with two processes, the following program is a valid MPI program and is guaranteed to terminate:

```

39 MPI_Request req;
40
41 switch(rank) {
42     case 0:
43         MPI_Ibarrier(comm, &req);
44         MPI_Wait(&req, MPI_STATUS_IGNORE);
45         MPI_Send(buf, count, dtype, 1, tag, comm);
46         break;
47     case 1:
48         MPI_Ibarrier(comm, &req);

```



```

    MPI_Recv(buf, count, dtype, 0, tag, comm, MPI_STATUS_IGNORE);
    MPI_Wait(&req, MPI_STATUS_IGNORE);
    break;
}

```

The MPI library must progress the barrier in the MPI\_Recv call. Thus, the MPI\_Wait call in rank 0 will eventually complete, which enables the matching MPI\_Send so all calls eventually return.

### Example 5.31

Blocking and nonblocking collective operations do not match. The following example is erroneous.

```

MPI_Request req;

switch(rank) {
    case 0:
        /* erroneous false matching of Alltoall and Ialltoall */
        MPI_Ialltoall(sbuf, scnt, stype, rbuf, rcnt, rtype, comm, &req);
        MPI_Wait(&req, MPI_STATUS_IGNORE);
        break;
    case 1:
        /* erroneous false matching of Alltoall and Ialltoall */
        MPI_Alltoall(sbuf, scnt, stype, rbuf, rcnt, rtype, comm);
        break;
}

```

### Example 5.32

Collective and point-to-point requests can be mixed in functions that enable multiple completions. If started with two processes, the following program is valid.

```

MPI_Request reqs[2];

switch(rank) {
    case 0:
        MPI_Ibarrier(comm, &reqs[0]);
        MPI_Send(buf, count, dtype, 1, tag, comm);
        MPI_Wait(&reqs[0], MPI_STATUS_IGNORE);
        break;
    case 1:
        MPI_Irecv(buf, count, dtype, 0, tag, comm, &reqs[0]);
        MPI_Ibarrier(comm, &reqs[1]);
        MPI_Waitall(2, reqs, MPI_STATUSES_IGNORE);
        break;
}

```

The Waitall call returns only after the barrier and the receive completed.

### Example 5.33

Multiple nonblocking collective operations can be outstanding on a single communicator and match in order.

```

MPI_Request reqs[3];

compute(buf1);
MPI_Ibcast(buf1, count, type, 0, comm, &reqs[0]);
compute(buf2);
MPI_Ibcast(buf2, count, type, 0, comm, &reqs[1]);
compute(buf3);
MPI_Ibcast(buf3, count, type, 0, comm, &reqs[2]);
MPI_Waitall(3, reqs, MPI_STATUSES_IGNORE);

```

*Advice to users.* Pipelining and double-buffering techniques can efficiently be used to overlap computation and communication. However, having too many outstanding requests might have a negative impact on performance. (*End of advice to users.*)

*Advice to implementors.* The use of pipelining may generate many outstanding requests. A high-quality hardware-supported implementation with limited resources should be able to fall back to a software implementation if its resources are exhausted. In this way, the implementation could limit the number of outstanding requests only by the available memory. (*End of advice to implementors.*)

### Example 5.34

Nonblocking collective operations can also be used to enable simultaneous collective operations on multiple overlapping communicators (see Figure 5.13). The following example is started with three processes and three communicators. The first communicator `comm1` includes ranks 0 and 1, `comm2` includes ranks 1 and 2 and `comm3` spans ranks 0 and 2. It is not possible to perform a blocking collective operation on all communicators because there exists no deadlock-free order to invoke them. However, nonblocking collective operations can easily be used to achieve this task.

```

MPI_Request reqs[2];

switch(rank) {
    case 0:
        MPI_Iallreduce(sbuf1, rbuf1, count, dtype, MPI_SUM, comm1, &reqs[0]);
        MPI_Iallreduce(sbuf3, rbuf3, count, dtype, MPI_SUM, comm3, &reqs[1]);
        break;
    case 1:
        MPI_Iallreduce(sbuf1, rbuf1, count, dtype, MPI_SUM, comm1, &reqs[0]);
        MPI_Iallreduce(sbuf2, rbuf2, count, dtype, MPI_SUM, comm2, &reqs[1]);
        break;
    case 2:
        MPI_Iallreduce(sbuf2, rbuf2, count, dtype, MPI_SUM, comm2, &reqs[0]);
        MPI_Iallreduce(sbuf3, rbuf3, count, dtype, MPI_SUM, comm3, &reqs[1]);
        break;
}
MPI_Waitall(2, reqs, MPI_STATUSES_IGNORE);

```

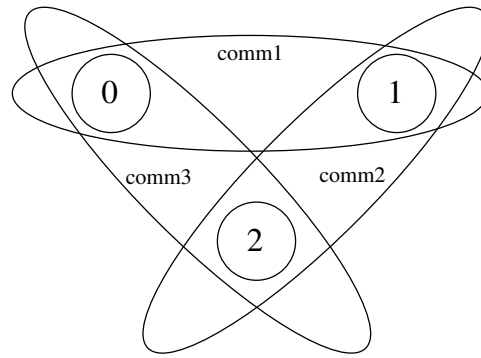


Figure 5.13: Example with overlapping communicators.

*Advice to users.* This method can be useful if overlapping neighboring regions (halo or ghost zones) are used in collective operations. The sequence of the two calls in each process is irrelevant because the two nonblocking operations are performed on different communicators. (*End of advice to users.*)

### Example 5.35

The progress of multiple outstanding nonblocking collective operations is completely independent.

```
MPI_Request reqs[2];

compute(buf1);
MPI_Ibcast(buf1, count, type, 0, comm, &reqs[0]);
compute(buf2);
MPI_Ibcast(buf2, count, type, 0, comm, &reqs[1]);
MPI_Wait(&reqs[1], MPI_STATUS_IGNORE);
/* nothing is known about the status of the first bcast here */
MPI_Wait(&reqs[0], MPI_STATUS_IGNORE);
```

Finishing the second `MPI_IBCAST` is completely independent of the first one. This means that it is not guaranteed that the first broadcast operation is finished or even started after the second one is completed via `reqs[1]`.

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## Chapter 6

# Groups, Contexts, Communicators, and Caching

### 6.1 Introduction

This chapter introduces MPI features that support the development of parallel libraries. Parallel libraries are needed to encapsulate the distracting complications inherent in parallel implementations of key algorithms. They help to ensure consistent correctness of such procedures, and provide a “higher level” of portability than MPI itself can provide. As such, libraries prevent each programmer from repeating the work of defining consistent data structures, data layouts, and methods that implement key algorithms (such as matrix operations). Since the best libraries come with several variations on parallel systems (different data layouts, different strategies depending on the size of the system or problem, or type of floating point), this too needs to be hidden from the user.

We refer the reader to [50] and [3] for further information on writing libraries in MPI, using the features described in this chapter.

#### 6.1.1 Features Needed to Support Libraries

The key features needed to support the creation of robust parallel libraries are as follows:

- Safe communication space, that guarantees that libraries can communicate as they need to, without conflicting with communication extraneous to the library,
- Group scope for collective operations, that allow libraries to avoid unnecessarily synchronizing uninvolved processes (potentially running unrelated code),
- Abstract process naming to allow libraries to describe their communication in terms suitable to their own data structures and algorithms,
- The ability to “adorn” a set of communicating processes with additional user-defined attributes, such as extra collective operations. This mechanism should provide a means for the user or library writer effectively to extend a message-passing notation.

In addition, a unified mechanism or object is needed for conveniently denoting communication context, the group of communicating processes, to house abstract process naming, and to store adornments.

### 6.1.2 MPI's Support for Libraries

The corresponding concepts that MPI provides, specifically to support robust libraries, are as follows:

- **Contexts** of communication,
- **Groups** of processes,
- **Virtual topologies**,
- **Attribute caching**,
- **Communicators**.

**Communicators** (see [19, 48, 53]) encapsulate all of these ideas in order to provide the appropriate scope for all communication operations in MPI. Communicators are divided into two kinds: intra-communicators for operations within a single group of processes and inter-communicators for operations between two groups of processes.

**Caching.** Communicators (see below) provide a “caching” mechanism that allows one to associate new attributes with communicators, on a par with MPI built-in features. This can be used by advanced users to adorn communicators further, and by MPI to implement some communicator functions. For example, the virtual-topology functions described in Chapter 7 are likely to be supported this way.

**Groups.** Groups define an ordered collection of processes, each with a rank, and it is this group that defines the low-level names for inter-process communication (ranks are used for sending and receiving). Thus, groups define a scope for process names in point-to-point communication. In addition, groups define the scope of collective operations. Groups may be manipulated separately from communicators in MPI, but only communicators can be used in communication operations.

**Intra-communicators.** The most commonly used means for message passing in MPI is via intra-communicators. Intra-communicators contain an instance of a group, contexts of communication for both point-to-point and collective communication, and the ability to include virtual topology and other attributes. These features work as follows:

- **Contexts** provide the ability to have separate safe “universes” of message-passing in MPI. A context is akin to an additional tag that differentiates messages. The system manages this differentiation process. The use of separate communication contexts by distinct libraries (or distinct library invocations) insulates communication internal to the library execution from external communication. This allows the invocation of the library even if there are pending communications on “other” communicators, and avoids the need to synchronize entry or exit into library code. Pending point-to-point communications are also guaranteed not to interfere with collective communications within a single communicator.
- **Groups** define the participants in the communication (see above) of a communicator.

- A **virtual topology** defines a special mapping of the ranks in a group to and from a topology. Special constructors for communicators are defined in Chapter 7 to provide this feature. Intra-communicators as described in this chapter do not have topologies.
- **Attributes** define the local information that the user or library has added to a communicator for later reference.

*Advice to users.* The practice in many communication libraries is that there is a unique, predefined communication universe that includes all processes available when the parallel program is initiated; the processes are assigned consecutive ranks. Participants in a point-to-point communication are identified by their rank; a collective communication (such as broadcast) always involves all processes. This practice can be followed in MPI by using the predefined communicator `MPI_COMM_WORLD`. *Users who are satisfied with this practice can plug in `MPI_COMM_WORLD` wherever a communicator argument is required, and can consequently disregard the rest of this chapter. (End of advice to users.)*

**Inter-communicators.** The discussion has dealt so far with **intra-communication**: communication within a group. MPI also supports **inter-communication**: communication between two non-overlapping groups. When an application is built by composing several parallel modules, it is convenient to allow one module to communicate with another using local ranks for addressing within the second module. This is especially convenient in a client-server computing paradigm, where either client or server are parallel. The support of inter-communication also provides a mechanism for the extension of MPI to a dynamic model where not all processes are preallocated at initialization time. In such a situation, it becomes necessary to support communication across “universes.” Inter-communication is supported by objects called **inter-communicators**. These objects bind two groups together with communication contexts shared by both groups. For inter-communicators, these features work as follows:

- **Contexts** provide the ability to have a separate safe “universe” of message-passing between the two groups. A send in the local group is always a receive in the remote group, and vice versa. The system manages this differentiation process. The use of separate communication contexts by distinct libraries (or distinct library invocations) insulates communication internal to the library execution from external communication. This allows the invocation of the library even if there are pending communications on “other” communicators, and avoids the need to synchronize entry or exit into library code.
- A local and remote group specify the recipients and destinations for an inter-communicator.
- Virtual topology is undefined for an inter-communicator.
- As before, attributes cache defines the local information that the user or library has added to a communicator for later reference.

MPI provides mechanisms for creating and manipulating inter-communicators. They are used for point-to-point and collective communication in an related manner to intra-communicators. Users who do not need inter-communication in their applications can safely

ignore this extension. Users who require inter-communication between overlapping groups must layer this capability on top of MPI.

## 6.2 Basic Concepts

In this section, we turn to a more formal definition of the concepts introduced above.

### 6.2.1 Groups

A **group** is an ordered set of process identifiers (henceforth processes); processes are implementation-dependent objects. Each process in a group is associated with an integer **rank**. Ranks are contiguous and start from zero. Groups are represented by opaque **group objects**, and hence cannot be directly transferred from one process to another. A group is used within a communicator to describe the participants in a communication “universe” and to rank such participants (thus giving them unique names within that “universe” of communication).

There is a special pre-defined group: `MPI_GROUP_EMPTY`, which is a group with no members. The predefined constant `MPI_GROUP_NULL` is the value used for invalid group handles.

*Advice to users.* `MPI_GROUP_EMPTY`, which is a valid handle to an empty group, should not be confused with `MPI_GROUP_NULL`, which in turn is an invalid handle. The former may be used as an argument to group operations; the latter, which is returned when a group is freed, is not a valid argument. (*End of advice to users.*)

*Advice to implementors.* A group may be represented by a virtual-to-real process-address-translation table. Each communicator object (see below) would have a pointer to such a table.

Simple implementations of MPI will enumerate groups, such as in a table. However, more advanced data structures make sense in order to improve scalability and memory usage with large numbers of processes. Such implementations are possible with MPI. (*End of advice to implementors.*)

### 6.2.2 Contexts

A **context** is a property of communicators (defined next) that allows partitioning of the communication space. A message sent in one context cannot be received in another context. Furthermore, where permitted, collective operations are independent of pending point-to-point operations. Contexts are not explicit MPI objects; they appear only as part of the realization of communicators (below).

*Advice to implementors.* Distinct communicators in the same process have distinct contexts. A context is essentially a system-managed tag (or tags) needed to make a communicator safe for point-to-point and MPI-defined collective communication. Safety means that collective and point-to-point communication within one communicator do not interfere, and that communication over distinct communicators don’t interfere.



A possible implementation for a context is as a supplemental tag attached to messages on send and matched on receive. Each intra-communicator stores the value of its two tags (one for point-to-point and one for collective communication). Communicator-generating functions use a collective communication to agree on a new group-wide unique context.

Analogously, in inter-communication, two context tags are stored per communicator, one used by group A to send and group B to receive, and a second used by group B to send and for group A to receive.

Since contexts are not explicit objects, other implementations are also possible. (*End of advice to implementors.*)

### 6.2.3 Intra-Communicators

Intra-communicators bring together the concepts of group and context. To support implementation-specific optimizations, and application topologies (defined in the next chapter, Chapter 7), communicators may also “cache” additional information (see Section 6.7). MPI communication operations reference communicators to determine the scope and the “communication universe” in which a point-to-point or collective operation is to operate.

Each communicator contains a group of valid participants; this group always includes the local process. The source and destination of a message is identified by process rank within that group.

For collective communication, the intra-communicator specifies the set of processes that participate in the collective operation (and their order, when significant). Thus, the communicator restricts the “spatial” scope of communication, and provides machine-independent process addressing through ranks.

Intra-communicators are represented by opaque **intra-communicator objects**, and hence cannot be directly transferred from one process to another.

### 6.2.4 Predefined Intra-Communicators

An initial intra-communicator `MPI_COMM_WORLD` of all processes the local process can communicate with after initialization (itself included) is defined once `MPI_INIT` or `MPI_INIT_THREAD` has been called. In addition, the communicator `MPI_COMM_SELF` is provided, which includes only the process itself.

The predefined constant `MPI_COMM_NULL` is the value used for invalid communicator handles.

In a static-process-model implementation of MPI, all processes that participate in the computation are available after MPI is initialized. For this case, `MPI_COMM_WORLD` is a communicator of all processes available for the computation; this communicator has the same value in all processes. In an implementation of MPI where processes can dynamically join an MPI execution, it may be the case that a process starts an MPI computation without having access to all other processes. In such situations, `MPI_COMM_WORLD` is a communicator incorporating all processes with which the joining process can immediately communicate. Therefore, `MPI_COMM_WORLD` may simultaneously represent disjoint groups in different processes.

All MPI implementations are required to provide the `MPI_COMM_WORLD` communicator. It cannot be deallocated during the life of a process. The group corresponding to this communicator does not appear as a pre-defined constant, but it may be accessed using

MPI\_COMM\_GROUP (see below). MPI does not specify the correspondence between the process rank in MPI\_COMM\_WORLD and its (machine-dependent) absolute address. Neither does MPI specify the function of the host process, if any. Other implementation-dependent, predefined communicators may also be provided.

## 6.3 Group Management

This section describes the manipulation of process groups in MPI. These operations are local and their execution does not require interprocess communication.

### 6.3.1 Group Accessors

MPI\_GROUP\_SIZE(group, size)

IN	group	group (handle)
OUT	size	number of processes in the group (integer)

int MPI\_Group\_size(MPI\_Group group, int \*size)

MPI\_GROUP\_SIZE(GROUP, SIZE, IERROR)

INTEGER GROUP, SIZE, IERROR

MPI\_Group\_size(group, size, ierror)

TYPE(MPI\_Group), INTENT(IN) :: group

INTEGER, INTENT(OUT) :: size

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{int MPI::Group::Get\_size() const(*binding deprecated, see Section 15.2*) }

MPI\_GROUP\_RANK(group, rank)

IN	group	group (handle)
OUT	rank	rank of the calling process in group, or MPI_UNDEFINED if the process is not a member (integer)

int MPI\_Group\_rank(MPI\_Group group, int \*rank)

MPI\_GROUP\_RANK(GROUP, RANK, IERROR)

INTEGER GROUP, RANK, IERROR

MPI\_Group\_rank(group, rank, ierror)

TYPE(MPI\_Group), INTENT(IN) :: group

INTEGER, INTENT(OUT) :: rank

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{int MPI::Group::Get\_rank() const(*binding deprecated, see Section 15.2*) }

```

MPI_GROUP_TRANSLATE_RANKS (group1, n, ranks1, group2, ranks2)
    IN      group1          group1 (handle)
    IN      n                number of ranks in ranks1 and ranks2 arrays (integer)
    IN      ranks1          array of zero or more valid ranks in group1
    IN      group2          group2 (handle)
    OUT     ranks2          array of corresponding ranks in group2,
                           MPI_UNDEFINED when no correspondence exists.

```

```

int MPI_Group_translate_ranks (MPI_Group group1, int n, int *ranks1,
                             MPI_Group group2, int *ranks2)

```

```

MPI_GROUP_TRANSLATE_RANKS(GROUP1, N, RANKS1, GROUP2, RANKS2, IERROR)
    INTEGER GROUP1, N, RANKS1(*), GROUP2, RANKS2(*), IERROR

```

```

MPI_Group_translate_ranks(group1, n, ranks1, group2, ranks2, ierror)
    TYPE(MPI_Group), INTENT(IN) :: group1, group2
    INTEGER, INTENT(IN) :: n, ranks1(*)
    INTEGER, INTENT(OUT) :: ranks2(*)
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{static void MPI::Group::Translate_ranks (const MPI::Group& group1, int n,
    const int ranks1[], const MPI::Group& group2,
    int ranks2[]) (binding deprecated, see Section 15.2) }

```

This function is important for determining the relative numbering of the same processes in two different groups. For instance, if one knows the ranks of certain processes in the group of MPI\_COMM\_WORLD, one might want to know their ranks in a subset of that group.

MPI\_PROC\_NULL is a valid rank for input to MPI\_GROUP\_TRANSLATE\_RANKS, which returns MPI\_PROC\_NULL as the translated rank.

```

MPI_GROUP_COMPARE(group1, group2, result)

```

```

    IN      group1          first group (handle)
    IN      group2          second group (handle)
    OUT     result          result (integer)

```

```

int MPI_Group_compare(MPI_Group group1, MPI_Group group2, int *result)

```

```

MPI_GROUP_COMPARE(GROUP1, GROUP2, RESULT, IERROR)
    INTEGER GROUP1, GROUP2, RESULT, IERROR

```

```

MPI_Group_compare(group1, group2, result, ierror)
    TYPE(MPI_Group), INTENT(IN) :: group1, group2
    INTEGER, INTENT(OUT) :: result
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{static int MPI::Group::Compare(const MPI::Group& group1,
    const MPI::Group& group2) (binding deprecated, see Section 15.2) }

```

MPI\_IDENT results if the group members and group order is exactly the same in both groups. This happens for instance if `group1` and `group2` are the same handle. MPI\_SIMILAR results if the group members are the same but the order is different. MPI\_UNEQUAL results otherwise.

### 6.3.2 Group Constructors

Group constructors are used to subset and superset existing groups. These constructors construct new groups from existing groups. These are local operations, and distinct groups may be defined on different processes; a process may also define a group that does not include itself. Consistent definitions are required when groups are used as arguments in communicator-building functions. MPI does not provide a mechanism to build a group from scratch, but only from other, previously defined groups. The base group, upon which all other groups are defined, is the group associated with the initial communicator MPI\_COMM\_WORLD (accessible through the function MPI\_COMM\_GROUP).

*Rationale.* In what follows, there is no group duplication function analogous to MPI\_COMM\_DUP, defined later in this chapter. There is no need for a group duplicator. A group, once created, can have several references to it by making copies of the handle. The following constructors address the need for subsets and supersets of existing groups. (*End of rationale.*)

*Advice to implementors.* Each group constructor behaves as if it returned a new group object. When this new group is a copy of an existing group, then one can avoid creating such new objects, using a reference-count mechanism. (*End of advice to implementors.*)

MPI\_COMM\_GROUP(comm, group)

IN	comm	communicator (handle)
OUT	group	group corresponding to comm (handle)

int MPI\_Comm\_group(MPI\_Comm comm, MPI\_Group \*group)

MPI\_COMM\_GROUP(COMM, GROUP, IERROR)

INTEGER COMM, GROUP, IERROR

MPI\_Comm\_group(comm, group, ierror)

TYPE(MPI\_Comm), INTENT(IN) :: comm

TYPE(MPI\_Group), INTENT(OUT) :: group

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{MPI::Group MPI::Comm::Get\_group() const(*binding deprecated, see Section 15.2*) }

MPI\_COMM\_GROUP returns in group a handle to the group of comm.

```

MPI_GROUP_UNION(group1, group2, newgroup)
    IN      group1      first group (handle)
    IN      group2      second group (handle)
    OUT     newgroup     union group (handle)

int MPI_Group_union(MPI_Group group1, MPI_Group group2,
                    MPI_Group *newgroup)

MPI_GROUP_UNION(GROUP1, GROUP2, NEWGROUP, IERROR)
    INTEGER GROUP1, GROUP2, NEWGROUP, IERROR

MPI_Group_union(group1, group2, newgroup, ierror)
    TYPE(MPI_Group), INTENT(IN) :: group1, group2
    TYPE(MPI_Group), INTENT(OUT) :: newgroup
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{static MPI::Group MPI::Group::Union(const MPI::Group& group1,
    const MPI::Group& group2) (binding deprecated, see Section 15.2) }

MPI_GROUP_INTERSECTION(group1, group2, newgroup)
    IN      group1      first group (handle)
    IN      group2      second group (handle)
    OUT     newgroup     intersection group (handle)

int MPI_Group_intersection(MPI_Group group1, MPI_Group group2,
                           MPI_Group *newgroup)

MPI_GROUP_INTERSECTION(GROUP1, GROUP2, NEWGROUP, IERROR)
    INTEGER GROUP1, GROUP2, NEWGROUP, IERROR

MPI_Group_intersection(group1, group2, newgroup, ierror)
    TYPE(MPI_Group), INTENT(IN) :: group1, group2
    TYPE(MPI_Group), INTENT(OUT) :: newgroup
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{static MPI::Group MPI::Group::Intersect(const MPI::Group& group1,
    const MPI::Group& group2) (binding deprecated, see Section 15.2) }

MPI_GROUP_DIFFERENCE(group1, group2, newgroup)
    IN      group1      first group (handle)
    IN      group2      second group (handle)
    OUT     newgroup     difference group (handle)

int MPI_Group_difference(MPI_Group group1, MPI_Group group2,
                        MPI_Group *newgroup)

```

```

1 MPI_GROUP_DIFFERENCE(GROUP1, GROUP2, NEWGROUP, IERROR)
2     INTEGER GROUP1, GROUP2, NEWGROUP, IERROR
3
4 MPI_Group_difference(group1, group2, newgroup, ierror)
5     TYPE(MPI_Group), INTENT(IN) :: group1, group2
6     TYPE(MPI_Group), INTENT(OUT) :: newgroup
7     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
8
9 {static MPI::Group MPI::Group::Difference(const MPI::Group& group1,
10     const MPI::Group& group2) (binding deprecated, see Section 15.2) }

```

The set-like operations are defined as follows:

**union** All elements of the first group (*group1*), followed by all elements of second group (*group2*) not in first.

**intersect** all elements of the first group that are also in the second group, ordered as in first group.

**difference** all elements of the first group that are not in the second group, ordered as in the first group.

Note that for these operations the order of processes in the output group is determined primarily by order in the first group (if possible) and then, if necessary, by order in the second group. Neither union nor intersection are commutative, but both are associative.

The new group can be empty, that is, equal to `MPI_GROUP_EMPTY`.

```

26 MPI_GROUP_INCL(group, n, ranks, newgroup)
27
28     IN      group      group (handle)
29
30     IN      n          number of elements in array ranks (and size of
31                      newgroup) (integer)
32
33     IN      ranks      ranks of processes in group to appear in
34                      newgroup (array of integers)
35
36     OUT     newgroup    new group derived from above, in the order defined by
37                      ranks (handle)

```

```

36 int MPI_Group_incl(MPI_Group group, int n, int *ranks, MPI_Group *newgroup)

```

```

38 MPI_GROUP_INCL(GROUP, N, RANKS, NEWGROUP, IERROR)
39     INTEGER GROUP, N, RANKS(*), NEWGROUP, IERROR

```

```

40 MPI_Group_incl(group, n, ranks, newgroup, ierror)
41     INTEGER, INTENT(IN) :: n, ranks(*)
42     TYPE(MPI_Group), INTENT(IN) :: group
43     TYPE(MPI_Group), INTENT(OUT) :: newgroup
44     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
45
46 {MPI::Group MPI::Group::Incl(int n, const int ranks[]) const (binding
47     deprecated, see Section 15.2) }

```

The function `MPI_GROUP_INCL` creates a group `newgroup` that consists of the `n` processes in `group` with ranks `rank[0], ..., rank[n-1]`; the process with rank `i` in `newgroup` is the process with rank `ranks[i]` in `group`. Each of the `n` elements of `ranks` must be a valid rank in `group` and all elements must be distinct, or else the program is erroneous. If `n = 0`, then `newgroup` is `MPI_GROUP_EMPTY`. This function can, for instance, be used to reorder the elements of a group. See also `MPI_GROUP_COMPARE`.

`MPI_GROUP_EXCL(group, n, ranks, newgroup)`

IN	group	group (handle)
IN	n	number of elements in array <code>ranks</code> (integer)
IN	ranks	array of integer ranks in <code>group</code> not to appear in <code>newgroup</code>
OUT	newgroup	new group derived from above, preserving the order defined by <code>group</code> (handle)

`int MPI_Group_excl(MPI_Group group, int n, int *ranks, MPI_Group *newgroup)`

`MPI_GROUP_EXCL(GROUP, N, RANKS, NEWGROUP, IERROR)`

`INTEGER GROUP, N, RANKS(*), NEWGROUP, IERROR`

`MPI_Group_excl(group, n, ranks, newgroup, ierror)`

`TYPE(MPI_Group), INTENT(IN) :: group`

`INTEGER, INTENT(IN) :: n, ranks(*)`

`TYPE(MPI_Group), INTENT(OUT) :: newgroup`

`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{MPI::Group MPI::Group::Excl(int n, const int ranks[]) const` *(binding deprecated, see Section 15.2)* `}`

The function `MPI_GROUP_EXCL` creates a group of processes `newgroup` that is obtained by deleting from `group` those processes with ranks `ranks[0] ... ranks[n-1]`. The ordering of processes in `newgroup` is identical to the ordering in `group`. Each of the `n` elements of `ranks` must be a valid rank in `group` and all elements must be distinct; otherwise, the program is erroneous. If `n = 0`, then `newgroup` is identical to `group`.

`MPI_GROUP_RANGE_INCL(group, n, ranges, newgroup)`

IN	group	group (handle)
IN	n	number of triplets in array <code>ranges</code> (integer)
IN	ranges	a one-dimensional array of integer triplets, of the form (first rank, last rank, stride) indicating ranks in <code>group</code> of processes to be included in <code>newgroup</code>
OUT	newgroup	new group derived from above, in the order defined by <code>ranges</code> (handle)

```

1  int MPI_Group_range_incl(MPI_Group group, int n, int ranges[][3],
2      MPI_Group *newgroup)
3
4  MPI_GROUP_RANGE_INCL(GROUP, N, RANGES, NEWGROUP, IERROR)
5  INTEGER GROUP, N, RANGES(3,*), NEWGROUP, IERROR
6
7  MPI_Group_range_incl(group, n, ranges, newgroup, ierror)
8  TYPE(MPI_Group), INTENT(IN) :: group
9  INTEGER, INTENT(IN) :: n, ranges(3,*)
10 TYPE(MPI_Group), INTENT(OUT) :: newgroup
11 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
12
13 {MPI::Group MPI::Group::Range_incl(int n, const int ranges[][3])
14     const(binding deprecated, see Section 15.2) }

```

If `ranges` consist of the triplets

$$(first_1, last_1, stride_1), \dots, (first_n, last_n, stride_n)$$

then `newgroup` consists of the sequence of processes in `group` with ranks

$$first_1, first_1 + stride_1, \dots, first_1 + \left\lfloor \frac{last_1 - first_1}{stride_1} \right\rfloor stride_1, \dots$$

$$first_n, first_n + stride_n, \dots, first_n + \left\lfloor \frac{last_n - first_n}{stride_n} \right\rfloor stride_n.$$

Each computed rank must be a valid rank in `group` and all computed ranks must be distinct, or else the program is erroneous. Note that we may have  $first_i > last_i$ , and  $stride_i$  may be negative, but cannot be zero.

The functionality of this routine is specified to be equivalent to expanding the array of ranges to an array of the included ranks and passing the resulting array of ranks and other arguments to `MPI_GROUP_INCL`. A call to `MPI_GROUP_INCL` is equivalent to a call to `MPI_GROUP_RANGE_INCL` with each rank `i` in `ranks` replaced by the triplet `(i,i,1)` in the argument `ranges`.

```

34 MPI_GROUP_RANGE_EXCL(group, n, ranges, newgroup)

```

IN	group	group (handle)
IN	n	number of elements in array ranges (integer)
IN	ranges	a one-dimensional array of integer triplets of the form (first rank, last rank, stride), indicating the ranks in group of processes to be excluded from the output group <code>newgroup</code> .
OUT	newgroup	new group derived from above, preserving the order in group (handle)

```

45 int MPI_Group_range_excl(MPI_Group group, int n, int ranges[][3],
46     MPI_Group *newgroup)
47
48 MPI_GROUP_RANGE_EXCL(GROUP, N, RANGES, NEWGROUP, IERROR)

```



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```

INTEGER GROUP, N, RANGES(3,*), NEWGROUP, IERROR
MPI_Group_range_excl(group, n, ranges, newgroup, ierror)
  TYPE(MPI_Group), INTENT(IN) :: group
  INTEGER, INTENT(IN) :: n, ranges(3,*)
  TYPE(MPI_Group), INTENT(OUT) :: newgroup
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{MPI::Group MPI::Group::Range_excl(int n, const int ranges[] [3])
  const(binding deprecated, see Section 15.2) }
```

Each computed rank must be a valid rank in `group` and all computed ranks must be distinct, or else the program is erroneous.

The functionality of this routine is specified to be equivalent to expanding the array of `ranges` to an array of the excluded ranks and passing the resulting array of ranks and other arguments to `MPI_GROUP_EXCL`. A call to `MPI_GROUP_EXCL` is equivalent to a call to `MPI_GROUP_RANGE_EXCL` with each rank `i` in `ranks` replaced by the triplet `(i,i,1)` in the argument `ranges`.

*Advice to users.* The range operations do not explicitly enumerate ranks, and therefore are more scalable if implemented efficiently. Hence, we recommend MPI programmers to use them whenever possible, as high-quality implementations will take advantage of this fact. (*End of advice to users.*)

*Advice to implementors.* The range operations should be implemented, if possible, without enumerating the group members, in order to obtain better scalability (time and space). (*End of advice to implementors.*)

### 6.3.3 Group Destructors

```

MPI_GROUP_FREE(group)
  INOUT    group                group (handle)

int MPI_Group_free(MPI_Group *group)

MPI_GROUP_FREE(GROUP, IERROR)
  INTEGER GROUP, IERROR

MPI_Group_free(group, ierror)
  TYPE(MPI_Group), INTENT(INOUT) :: group
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Group::Free() (binding deprecated, see Section 15.2) }
```

This operation marks a group object for deallocation. The handle `group` is set to `MPI_GROUP_NULL` by the call. Any on-going operation using this group will complete normally.

*Advice to implementors.* One can keep a reference count that is incremented for each call to `MPI_COMM_GROUP`, `MPI_COMM_CREATE` and `MPI_COMM_DUP`, and

decremented for each call to `MPI_GROUP_FREE` or `MPI_COMM_FREE`; the group object is ultimately deallocated when the reference count drops to zero. (*End of advice to implementors.*)

## 6.4 Communicator Management

This section describes the manipulation of communicators in MPI. Operations that access communicators are local and their execution does not require interprocess communication. Operations that create communicators are collective and may require interprocess communication.

*Advice to implementors.* High-quality implementations should amortize the overheads associated with the creation of communicators (for the same group, or subsets thereof) over several calls, by allocating multiple contexts with one collective communication. (*End of advice to implementors.*)

### 6.4.1 Communicator Accessors

The following are all local operations.

`MPI_COMM_SIZE(comm, size)`

IN	comm	communicator (handle)
OUT	size	number of processes in the group of comm (integer)

`int MPI_Comm_size(MPI_Comm comm, int *size)`

`MPI_COMM_SIZE(COMM, SIZE, IERROR)`

INTEGER COMM, SIZE, IERROR

`MPI_Comm_size(comm, size, ierror)`

TYPE(MPI\_Comm), INTENT(IN) :: comm

INTEGER, INTENT(OUT) :: size

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

`{int MPI::Comm::Get_size() const(binding deprecated, see Section 15.2) }`

*Rationale.* This function is equivalent to accessing the communicator's group with `MPI_COMM_GROUP` (see above), computing the size using `MPI_GROUP_SIZE`, and then freeing the temporary group via `MPI_GROUP_FREE`. However, this function is so commonly used, that this shortcut was introduced. (*End of rationale.*)

*Advice to users.* This function indicates the number of processes involved in a communicator. For `MPI_COMM_WORLD`, it indicates the total number of processes available (for this version of MPI, there is no standard way to change the number of processes once initialization has taken place).

This call is often used with the next call to determine the amount of concurrency available for a specific library or program. The following call, `MPI_COMM_RANK`

indicates the rank of the process that calls it in the range from 0...size-1, where size is the return value of MPI\_COMM\_SIZE. (*End of advice to users.*)

MPI\_COMM\_RANK(comm, rank)

IN	comm	communicator (handle)
OUT	rank	rank of the calling process in group of comm (integer)

```
int MPI_Comm_rank(MPI_Comm comm, int *rank)
```

```
MPI_COMM_RANK(COMM, RANK, IERROR)
```

```
INTEGER COMM, RANK, IERROR
```

```
MPI_Comm_rank(comm, rank, ierror)
```

```
TYPE(MPI_Comm), INTENT(IN) :: comm
```

```
INTEGER, INTENT(OUT) :: rank
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{int MPI::Comm::Get_rank() const(binding deprecated, see Section 15.2) }
```

*Rationale.* This function is equivalent to accessing the communicator's group with MPI\_COMM\_GROUP (see above), computing the rank using MPI\_GROUP\_RANK, and then freeing the temporary group via MPI\_GROUP\_FREE. However, this function is so commonly used, that this shortcut was introduced. (*End of rationale.*)

*Advice to users.* This function gives the rank of the process in the particular communicator's group. It is useful, as noted above, in conjunction with MPI\_COMM\_SIZE.

Many programs will be written with the master-slave model, where one process (such as the rank-zero process) will play a supervisory role, and the other processes will serve as compute nodes. In this framework, the two preceding calls are useful for determining the roles of the various processes of a communicator. (*End of advice to users.*)

MPI\_COMM\_COMPARE(comm1, comm2, result)

IN	comm1	first communicator (handle)
IN	comm2	second communicator (handle)
OUT	result	result (integer)

```
int MPI_Comm_compare(MPI_Comm comm1, MPI_Comm comm2, int *result)
```

```
MPI_COMM_COMPARE(COMM1, COMM2, RESULT, IERROR)
```

```
INTEGER COMM1, COMM2, RESULT, IERROR
```

```
MPI_Comm_compare(comm1, comm2, result, ierror)
```

```
TYPE(MPI_Comm), INTENT(IN) :: comm1
```

```

1      TYPE(MPI_Comm), INTENT(IN) :: comm2
2      INTEGER, INTENT(OUT) :: result
3      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
4
5      {static int MPI::Comm::Compare(const MPI::Comm& comm1,
6          const MPI::Comm& comm2) (binding deprecated, see Section 15.2) }
7
8      MPI_IDENT results if and only if comm1 and comm2 are handles for the same object (identical
9      groups and same contexts). MPI_CONGRUENT results if the underlying groups are identical
10     in constituents and rank order; these communicators differ only by context. MPI_SIMILAR
11     results if the group members of both communicators are the same but the rank order differs.
12     MPI_UNEQUAL results otherwise.

```

### 6.4.2 Communicator Constructors

The following are collective functions that are invoked by all processes in the group or groups associated with `comm`.

*Rationale.* Note that there is a chicken-and-egg aspect to MPI in that a communicator is needed to create a new communicator. The base communicator for all MPI communicators is predefined outside of MPI, and is `MPI_COMM_WORLD`. This model was arrived at after considerable debate, and was chosen to increase “safety” of programs written in MPI. (*End of rationale.*)

The MPI interface provides four communicator construction routines that apply to both intracommunicators and intercommunicators. The construction routine `MPI_INTERCOMM_CREATE` (discussed later) applies only to intercommunicators.

An intracommunicator involves a single group while an intercommunicator involves two groups. Where the following discussions address intercommunicator semantics, the two groups in an intercommunicator are called the *left* and *right* groups. A process in an intercommunicator is a member of either the left or the right group. From the point of view of that process, the group that the process is a member of is called the *local* group; the other group (relative to that process) is the *remote* group. The left and right group labels give us a way to describe the two groups in an intercommunicator that is not relative to any particular process (as the local and remote groups are).

`MPI_COMM_DUP(comm, newcomm)`

IN	<code>comm</code>	communicator (handle)
OUT	<code>newcomm</code>	copy of <code>comm</code> (handle)

```
int MPI_Comm_dup(MPI_Comm comm, MPI_Comm *newcomm)
```

```
MPI_COMM_DUP(COMM, NEWCOMM, IERROR)
```

```
INTEGER COMM, NEWCOMM, IERROR
```

```
MPI_Comm_dup(comm, newcomm, ierror)
```

```
TYPE(MPI_Comm), INTENT(IN) :: comm
```

```
TYPE(MPI_Comm), INTENT(OUT) :: newcomm
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```

{MPI::Intracomm MPI::Intracomm::Dup() const(binding deprecated, see Section 15.2)
    }
{MPI::Intercomm MPI::Intercomm::Dup() const(binding deprecated, see Section 15.2)
    }
{MPI::Cartcomm MPI::Cartcomm::Dup() const(binding deprecated, see Section 15.2) }
{MPI::Graphcomm MPI::Graphcomm::Dup() const(binding deprecated, see Section 15.2)
    }
{MPI::Distgraphcomm MPI::Distgraphcomm::Dup() const(binding deprecated, see
    Section 15.2) }
{MPI::Comm& MPI::Comm::Clone() const = 0(binding deprecated, see Section 15.2) }
{MPI::Intracomm& MPI::Intracomm::Clone() const(binding deprecated, see
    Section 15.2) }
{MPI::Intercomm& MPI::Intercomm::Clone() const(binding deprecated, see
    Section 15.2) }
{MPI::Cartcomm& MPI::Cartcomm::Clone() const(binding deprecated, see Section 15.2)
    }
{MPI::Graphcomm& MPI::Graphcomm::Clone() const(binding deprecated, see
    Section 15.2) }
{MPI::Distgraphcomm& MPI::Distgraphcomm::Clone() const(binding deprecated, see
    Section 15.2) }

```

**MPI\_COMM\_DUP** Duplicates the existing communicator `comm` with associated key values. For each key value, the respective copy callback function determines the attribute value associated with this key in the new communicator; one particular action that a copy callback may take is to delete the attribute from the new communicator. Returns in `newcomm` a new communicator with the same group or groups, any copied cached information, but a new context (see Section 6.7.1). Please see Section 16.1.7 on page 538 for further discussion about the C++ bindings for `Dup()` and `Clone()`.

*Advice to users.* This operation is used to provide a parallel library call with a duplicate communication space that has the same properties as the original communicator. This includes any attributes (see below), and topologies (see Chapter 7). This call is valid even if there are pending point-to-point communications involving the communicator `comm`. A typical call might involve a `MPI_COMM_DUP` at the beginning of the parallel call, and an `MPI_COMM_FREE` of that duplicated communicator at the end of the call. Other models of communicator management are also possible.

This call applies to both intra- and inter-communicators. (*End of advice to users.*)

*Advice to implementors.* One need not actually copy the group information, but only add a new reference and increment the reference count. Copy on write can be used for the cached information. (*End of advice to implementors.*)

```

1 MPI_COMM_CREATE(comm, group, newcomm)
2     IN      comm      communicator (handle)
3     IN      group      Group, which is a subset of the group of
4                      comm (handle)
5     OUT     newcomm    new communicator (handle)
6
7
8 int MPI_Comm_create(MPI_Comm comm, MPI_Group group, MPI_Comm *newcomm)
9
10 MPI_COMM_CREATE(COMM, GROUP, NEWCOMM, IERROR)
11     INTEGER COMM, GROUP, NEWCOMM, IERROR
12
13 MPI_Comm_create(comm, group, newcomm, ierror)
14     TYPE(MPI_Comm), INTENT(IN) :: comm
15     TYPE(MPI_Group), INTENT(IN) :: group
16     TYPE(MPI_Comm), INTENT(OUT) :: newcomm
17     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
18
19 {MPI::Intercomm MPI::Intercomm::Create(const MPI::Group& group)
20     const(binding deprecated, see Section 15.2) }
21
22 {MPI::Intracomm MPI::Intracomm::Create(const MPI::Group& group)
23     const(binding deprecated, see Section 15.2) }

```

If `comm` is an intracommunicator, this function returns a new communicator `newcomm` with communication group defined by the `group` argument. No cached information propagates from `comm` to `newcomm`. Each process must call with a `group` argument that is a subgroup of the `group` associated with `comm`; this could be `MPI_GROUP_EMPTY`. The processes may specify different values for the `group` argument. If a process calls with a non-empty `group` then all processes in that `group` must call the function with the same `group` as argument, that is the same processes in the same order. Otherwise the call is erroneous. This implies that the set of groups specified across the processes must be disjoint. If the calling process is a member of the group given as `group` argument, then `newcomm` is a communicator with `group` as its associated group. In the case that a process calls with a `group` to which it does not belong, e.g., `MPI_GROUP_EMPTY`, then `MPI_COMM_NULL` is returned as `newcomm`. The function is collective and must be called by all processes in the group of `comm`.

*Rationale.* The interface supports the original mechanism from MPI-1.1, which required the same `group` in all processes of `comm`. It was extended in MPI-2.2 to allow the use of disjoint subgroups in order to allow implementations to eliminate unnecessary communication that `MPI_COMM_SPLIT` would incur when the user already knows the membership of the disjoint subgroups. (*End of rationale.*)

*Rationale.* The requirement that the entire group of `comm` participate in the call stems from the following considerations:

- It allows the implementation to layer `MPI_COMM_CREATE` on top of regular collective communications.
- It provides additional safety, in particular in the case where partially overlapping groups are used to create new communicators.

- It permits implementations sometimes to avoid communication related to context creation.

(*End of rationale.*)

*Advice to users.* MPI\_COMM\_CREATE provides a means to subset a group of processes for the purpose of separate MIMD computation, with separate communication space. newcomm, which emerges from MPI\_COMM\_CREATE can be used in subsequent calls to MPI\_COMM\_CREATE (or other communicator constructors) further to subdivide a computation into parallel sub-computations. A more general service is provided by MPI\_COMM\_SPLIT, below. (*End of advice to users.*)

*Advice to implementors.* When calling MPI\_COMM\_DUP, all processes call with the same group (the group associated with the communicator). When calling MPI\_COMM\_CREATE, the processes provide the same group or disjoint subgroups. For both calls, it is theoretically possible to agree on a group-wide unique context with no communication. However, local execution of these functions requires use of a larger context name space and reduces error checking. Implementations may strike various compromises between these conflicting goals, such as bulk allocation of multiple contexts in one collective operation.

Important: If new communicators are created without synchronizing the processes involved then the communication system should be able to cope with messages arriving in a context that has not yet been allocated at the receiving process. (*End of advice to implementors.*)

If comm is an intercommunicator, then the output communicator is also an intercommunicator where the local group consists only of those processes contained in group (see Figure 6.1). The group argument should only contain those processes in the local group of the input intercommunicator that are to be a part of newcomm. All processes in the same local group of comm must specify the same value for group, i.e., the same members in the same order. If either group does not specify at least one process in the local group of the intercommunicator, or if the calling process is not included in the group, MPI\_COMM\_NULL is returned.

*Rationale.* In the case where either the left or right group is empty, a null communicator is returned instead of an intercommunicator with MPI\_GROUP\_EMPTY because the side with the empty group must return MPI\_COMM\_NULL. (*End of rationale.*)

**Example 6.1** The following example illustrates how the first node in the left side of an intercommunicator could be joined with all members on the right side of an intercommunicator to form a new intercommunicator.

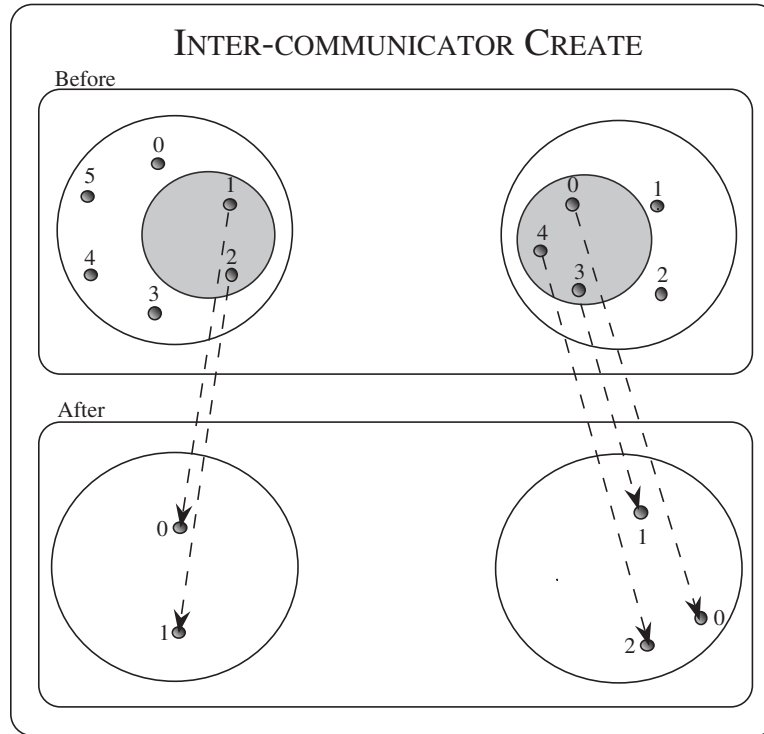


Figure 6.1: Intercommunicator create using `MPI_COMM_CREATE` extended to intercommunicators. The input groups are those in the grey circle.

```

MPI_Comm inter_comm, new_inter_comm;
MPI_Group local_group, group;
int      rank = 0; /* rank on left side to include in
                    new inter-comm */

/* Construct the original intercommunicator: "inter_comm" */
...

/* Construct the group of processes to be in new
intercommunicator */
if (/* I'm on the left side of the intercommunicator */) {
    MPI_Comm_group ( inter_comm, &local_group );
    MPI_Group_incl ( local_group, 1, &rank, &group );
    MPI_Group_free ( &local_group );
}
else
    MPI_Comm_group ( inter_comm, &group );

MPI_Comm_create ( inter_comm, group, &new_inter_comm );
MPI_Group_free( &group );

```



MPI\_COMM\_SPLIT(comm, color, key, newcomm)

IN	comm	communicator (handle)
IN	color	control of subset assignment (integer)
IN	key	control of rank assignment (integer)
OUT	newcomm	new communicator (handle)

```
int MPI_Comm_split(MPI_Comm comm, int color, int key, MPI_Comm *newcomm)
```

```
MPI_COMM_SPLIT(COMM, COLOR, KEY, NEWCOMM, IERROR)
    INTEGER COMM, COLOR, KEY, NEWCOMM, IERROR
```

```
MPI_Comm_split(comm, color, key, newcomm, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm
    INTEGER, INTENT(IN) :: color, key
    TYPE(MPI_Comm), INTENT(OUT) :: newcomm
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{MPI::Intercomm MPI::Intercomm::Split(int color, int key) const(binding
    deprecated, see Section 15.2) }
```

```
{MPI::Intracomm MPI::Intracomm::Split(int color, int key) const(binding
    deprecated, see Section 15.2) }
```

This function partitions the group associated with `comm` into disjoint subgroups, one for each value of `color`. Each subgroup contains all processes of the same color. Within each subgroup, the processes are ranked in the order defined by the value of the argument `key`, with ties broken according to their rank in the old group. A new communicator is created for each subgroup and returned in `newcomm`. A process may supply the color value `MPI_UNDEFINED`, in which case `newcomm` returns `MPI_COMM_NULL`. This is a collective call, but each process is permitted to provide different values for `color` and `key`.

With an intracommunicator `comm`, a call to `MPI_COMM_CREATE(comm, group, newcomm)` is equivalent to a call to `MPI_COMM_SPLIT(comm, color, key, newcomm)`, where processes that are members of their `group` argument provide `color = number of the group` (based on a unique numbering of all disjoint groups) and `key = rank in group`, and all processes that are not members of their `group` argument provide `color = MPI_UNDEFINED`.

The value of `color` must be non-negative.

*Advice to users.* This is an extremely powerful mechanism for dividing a single communicating group of processes into  $k$  subgroups, with  $k$  chosen implicitly by the user (by the number of colors asserted over all the processes). Each resulting communicator will be non-overlapping. Such a division could be useful for defining a hierarchy of computations, such as for multigrid, or linear algebra. For intracommunicators, `MPI_COMM_SPLIT` provides similar capability as `MPI_COMM_CREATE` to split a communicating group into disjoint subgroups. `MPI_COMM_SPLIT` is useful when some processes do not have complete information of the other members in their group, but all processes know (the color of) the group to which they belong. In this case, the MPI implementation discovers the other group members via communication. `MPI_COMM_CREATE` is useful when all processes have complete information

of the members of their group. In this case, MPI can avoid the extra communication required to discover group membership.

Multiple calls to `MPI_COMM_SPLIT` can be used to overcome the requirement that any call have no overlap of the resulting communicators (each process is of only one color per call). In this way, multiple overlapping communication structures can be created. Creative use of the `color` and `key` in such splitting operations is encouraged.

Note that, for a fixed color, the keys need not be unique. It is `MPI_COMM_SPLIT`'s responsibility to sort processes in ascending order according to this key, and to break ties in a consistent way. If all the keys are specified in the same way, then all the processes in a given color will have the relative rank order as they did in their parent group.

Essentially, making the key value zero for all processes of a given color means that one doesn't really care about the rank-order of the processes in the new communicator. (*End of advice to users.*)

*Rationale.* `color` is restricted to be non-negative, so as not to conflict with the value assigned to `MPI_UNDEFINED`. (*End of rationale.*)

The result of `MPI_COMM_SPLIT` on an intercommunicator is that those processes on the left with the same color as those processes on the right combine to create a new intercommunicator. The `key` argument describes the relative rank of processes on each side of the intercommunicator (see Figure 6.2). For those colors that are specified only on one side of the intercommunicator, `MPI_COMM_NULL` is returned. `MPI_COMM_NULL` is also returned to those processes that specify `MPI_UNDEFINED` as the color.

*Advice to users.* For intercommunicators, `MPI_COMM_SPLIT` is more general than `MPI_COMM_CREATE`. A single call to `MPI_COMM_SPLIT` can create a set of disjoint intercommunicators, while a call to `MPI_COMM_CREATE` creates only one. (*End of advice to users.*)

**Example 6.2** (Parallel client-server model). The following client code illustrates how clients on the left side of an intercommunicator could be assigned to a single server from a pool of servers on the right side of an intercommunicator.

```

/* Client code */
MPI_Comm multiple_server_comm;
MPI_Comm single_server_comm;
int      color, rank, num_servers;

/* Create intercommunicator with clients and servers:
   multiple_server_comm */
...

/* Find out the number of servers available */
MPI_Comm_remote_size ( multiple_server_comm, &num_servers );

/* Determine my color */
MPI_Comm_rank ( multiple_server_comm, &rank );

```

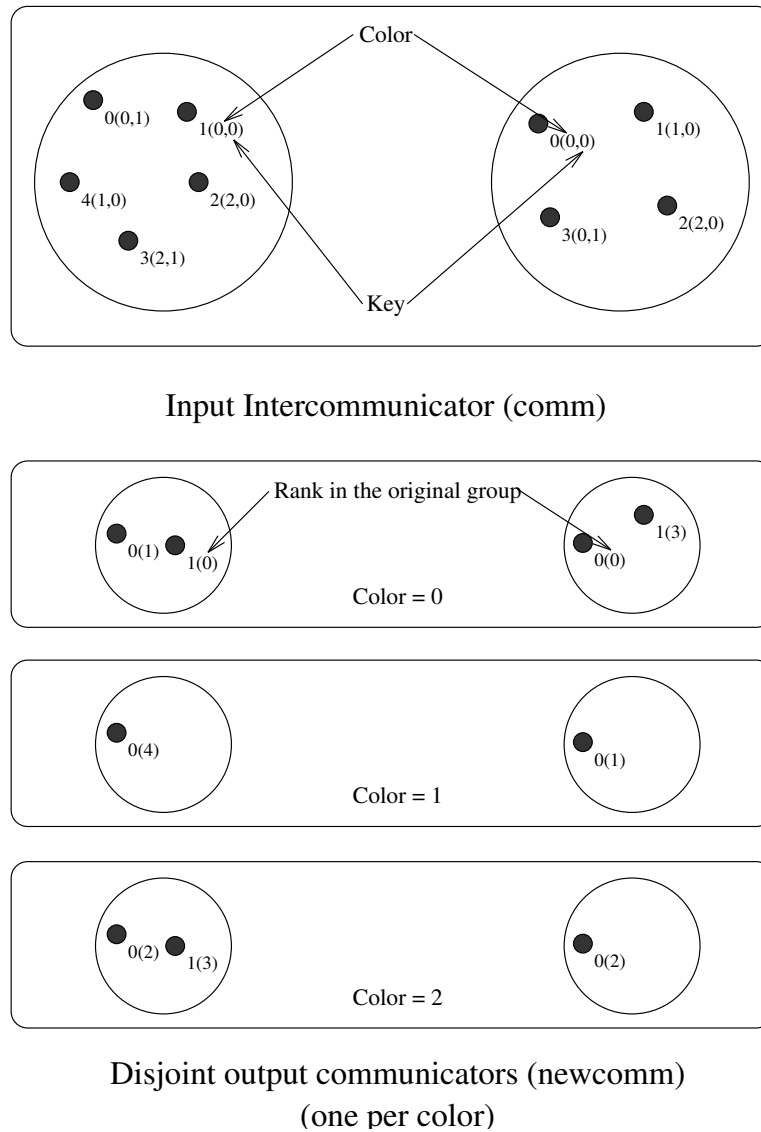


Figure 6.2: Intercommunicator construction achieved by splitting an existing intercommunicator with `MPI_COMM_SPLIT` extended to intercommunicators.

```

1      color = rank % num_servers;
2
3      /* Split the intercommunicator */
4      MPI_Comm_split ( multiple_server_comm, color, rank,
5                      &single_server_comm );
6

```

The following is the corresponding server code:

```

8      /* Server code */
9      MPI_Comm  multiple_client_comm;
10     MPI_Comm  single_server_comm;
11     int       rank;
12
13     /* Create intercommunicator with clients and servers:
14        multiple_client_comm */
15     ...
16
17     /* Split the intercommunicator for a single server per group
18        of clients */
19     MPI_Comm_rank ( multiple_client_comm, &rank );
20     MPI_Comm_split ( multiple_client_comm, rank, 0,
21                     &single_server_comm );
22

```

### 6.4.3 Communicator Destructors

**MPI\_COMM\_FREE(comm)**

INOUT     comm                             communicator to be destroyed (handle)

**int MPI\_Comm\_free(MPI\_Comm \*comm)**

**MPI\_COMM\_FREE(COMM, IERROR)**

INTEGER COMM, IERROR

**MPI\_Comm\_free(comm, ierror)**

TYPE(MPI\_Comm), INTENT(INOUT) :: comm

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Comm::Free() (*binding deprecated, see Section 15.2*) }

This collective operation marks the communication object for deallocation. The handle is set to MPI\_COMM\_NULL. Any pending operations that use this communicator will complete normally; the object is actually deallocated only if there are no other active references to it. This call applies to intra- and inter-communicators. The delete callback functions for all cached attributes (see Section 6.7) are called in arbitrary order.

*Advice to implementors.* A reference-count mechanism may be used: the reference count is incremented by each call to MPI\_COMM\_DUP, and decremented by each call to MPI\_COMM\_FREE. The object is ultimately deallocated when the count reaches zero.

Though collective, it is anticipated that this operation will normally be implemented to be local, though a debugging version of an MPI library might choose to synchronize. (*End of advice to implementors.*)

## 6.5 Motivating Examples

### 6.5.1 Current Practice #1

Example #1a:

```
int main(int argc, char **argv)
{
    int me, size;
    ...
    MPI_Init ( &argc, &argv );
    MPI_Comm_rank (MPI_COMM_WORLD, &me);
    MPI_Comm_size (MPI_COMM_WORLD, &size);

    (void)printf ("Process %d size %d\n", me, size);
    ...
    MPI_Finalize();
}
```

Example #1a is a do-nothing program that initializes itself legally, and refers to the “all” communicator, and prints a message. It terminates itself legally too. This example does not imply that MPI supports `printf`-like communication itself.

Example #1b (supposing that `size` is even):

```
int main(int argc, char **argv)
{
    int me, size;
    int SOME_TAG = 0;
    ...
    MPI_Init(&argc, &argv);

    MPI_Comm_rank(MPI_COMM_WORLD, &me); /* local */
    MPI_Comm_size(MPI_COMM_WORLD, &size); /* local */

    if((me % 2) == 0)
    {
        /* send unless highest-numbered process */
        if((me + 1) < size)
            MPI_Send(..., me + 1, SOME_TAG, MPI_COMM_WORLD);
    }
    else
        MPI_Recv(..., me - 1, SOME_TAG, MPI_COMM_WORLD, &status);

    ...
    MPI_Finalize();
}
```

Example #1b schematically illustrates message exchanges between “even” and “odd” processes in the “all” communicator.

### 6.5.2 Current Practice #2

```

1  int main(int argc, char **argv)
2  {
3      int me, count;
4      void *data;
5      ...
6
7      MPI_Init(&argc, &argv);
8      MPI_Comm_rank(MPI_COMM_WORLD, &me);
9
10     if(me == 0)
11     {
12         /* get input, create buffer “data” */
13         ...
14     }
15
16     MPI_Bcast(data, count, MPI_BYTE, 0, MPI_COMM_WORLD);
17
18     ...
19
20     MPI_Finalize();
21 }

```

This example illustrates the use of a collective communication.

### 6.5.3 (Approximate) Current Practice #3

```

31 int main(int argc, char **argv)
32 {
33     int me, count, count2;
34     void *send_buf, *recv_buf, *send_buf2, *recv_buf2;
35     MPI_Group MPI_GROUP_WORLD, grprem;
36     MPI_Comm commslave;
37     static int ranks[] = {0};
38     ...
39     MPI_Init(&argc, &argv);
40     MPI_Comm_group(MPI_COMM_WORLD, &MPI_GROUP_WORLD);
41     MPI_Comm_rank(MPI_COMM_WORLD, &me); /* local */
42
43     MPI_Group_excl(MPI_GROUP_WORLD, 1, ranks, &grprem); /* local */
44     MPI_Comm_create(MPI_COMM_WORLD, grprem, &commslave);
45
46     if(me != 0)
47     {
48         /* compute on slave */

```

```

...
MPI_Reduce(send_buf,recv_buff,count, MPI_INT, MPI_SUM, 1, commslave);
...
MPI_Comm_free(&commslave);
}
/* zero falls through immediately to this reduce, others do later... */
MPI_Reduce(send_buf2, recv_buff2, count2,
           MPI_INT, MPI_SUM, 0, MPI_COMM_WORLD);

MPI_Group_free(&MPI_GROUP_WORLD);
MPI_Group_free(&grpem);
MPI_Finalize();
}

```

This example illustrates how a group consisting of all but the zeroth process of the “all” group is created, and then how a communicator is formed (`commslave`) for that new group. The new communicator is used in a collective call, and all processes execute a collective call in the `MPI_COMM_WORLD` context. This example illustrates how the two communicators (that inherently possess distinct contexts) protect communication. That is, communication in `MPI_COMM_WORLD` is insulated from communication in `commslave`, and vice versa.

In summary, “group safety” is achieved via communicators because distinct contexts within communicators are enforced to be unique on any process.

#### 6.5.4 Example #4

The following example is meant to illustrate “safety” between point-to-point and collective communication. MPI guarantees that a single communicator can do safe point-to-point and collective communication.

```

#define TAG_ARBITRARY 12345
#define SOME_COUNT    50

int main(int argc, char **argv)
{
    int me;
    MPI_Request request[2];
    MPI_Status status[2];
    MPI_Group MPI_GROUP_WORLD, subgroup;
    int ranks[] = {2, 4, 6, 8};
    MPI_Comm the_comm;
    ...
    MPI_Init(&argc, &argv);
    MPI_Comm_group(MPI_COMM_WORLD, &MPI_GROUP_WORLD);

    MPI_Group_incl(MPI_GROUP_WORLD, 4, ranks, &subgroup); /* local */
    MPI_Group_rank(subgroup, &me); /* local */

    MPI_Comm_create(MPI_COMM_WORLD, subgroup, &the_comm);
}

```

```

1      if(me != MPI_UNDEFINED)
2      {
3          MPI_Irecv(buff1, count, MPI_DOUBLE, MPI_ANY_SOURCE, TAG_ARBITRARY,
4                  the_comm, request);
5          MPI_Isend(buff2, count, MPI_DOUBLE, (me+1)%4, TAG_ARBITRARY,
6                  the_comm, request+1);
7          for(i = 0; i < SOME_COUNT, i++)
8              MPI_Reduce(..., the_comm);
9          MPI_Waitall(2, request, status);
10
11         MPI_Comm_free(&the_comm);
12     }
13
14     MPI_Group_free(&MPI_GROUP_WORLD);
15     MPI_Group_free(&subgroup);
16     MPI_Finalize();
17 }

```

### 6.5.5 Library Example #1

The main program:

```

22     int main(int argc, char **argv)
23     {
24         int done = 0;
25         user_lib_t *libh_a, *libh_b;
26         void *dataset1, *dataset2;
27         ...
28         MPI_Init(&argc, &argv);
29         ...
30         init_user_lib(MPI_COMM_WORLD, &libh_a);
31         init_user_lib(MPI_COMM_WORLD, &libh_b);
32         ...
33         user_start_op(libh_a, dataset1);
34         user_start_op(libh_b, dataset2);
35         ...
36         while(!done)
37         {
38             /* work */
39             ...
40             MPI_Reduce(..., MPI_COMM_WORLD);
41             ...
42             /* see if done */
43             ...
44         }
45         user_end_op(libh_a);
46         user_end_op(libh_b);
47
48

```



```

    uninit_user_lib(libh_a);
    uninit_user_lib(libh_b);
    MPI_Finalize();
}

```

The user library initialization code:

```

void init_user_lib(MPI_Comm comm, user_lib_t **handle)
{
    user_lib_t *save;

    user_lib_initsave(&save); /* local */
    MPI_Comm_dup(comm, &(save -> comm));

    /* other inits */
    ...

    *handle = save;
}

```

User start-up code:

```

void user_start_op(user_lib_t *handle, void *data)
{
    MPI_Irecv( ..., handle->comm, &(handle -> irecv_handle) );
    MPI_Isend( ..., handle->comm, &(handle -> isend_handle) );
}

```

User communication clean-up code:

```

void user_end_op(user_lib_t *handle)
{
    MPI_Status status;
    MPI_Wait(handle -> isend_handle, &status);
    MPI_Wait(handle -> irecv_handle, &status);
}

```

User object clean-up code:

```

void uninit_user_lib(user_lib_t *handle)
{
    MPI_Comm_free(&(handle -> comm));
    free(handle);
}

```

### 6.5.6 Library Example #2

The main program:

```

int main(int argc, char **argv)
{

```

```

1      int ma, mb;
2      MPI_Group MPI_GROUP_WORLD, group_a, group_b;
3      MPI_Comm comm_a, comm_b;
4
5      static int list_a[] = {0, 1};
6  #if defined(EXAMPLE_2B) | defined(EXAMPLE_2C)
7      static int list_b[] = {0, 2, 3};
8  #else/* EXAMPLE_2A */
9      static int list_b[] = {0, 2};
10 #endif
11     int size_list_a = sizeof(list_a)/sizeof(int);
12     int size_list_b = sizeof(list_b)/sizeof(int);
13
14     ...
15     MPI_Init(&argc, &argv);
16     MPI_Comm_group(MPI_COMM_WORLD, &MPI_GROUP_WORLD);
17
18     MPI_Group_incl(MPI_GROUP_WORLD, size_list_a, list_a, &group_a);
19     MPI_Group_incl(MPI_GROUP_WORLD, size_list_b, list_b, &group_b);
20
21     MPI_Comm_create(MPI_COMM_WORLD, group_a, &comm_a);
22     MPI_Comm_create(MPI_COMM_WORLD, group_b, &comm_b);
23
24     if(comm_a != MPI_COMM_NULL)
25         MPI_Comm_rank(comm_a, &ma);
26     if(comm_b != MPI_COMM_NULL)
27         MPI_Comm_rank(comm_b, &mb);
28
29     if(comm_a != MPI_COMM_NULL)
30         lib_call(comm_a);
31
32     if(comm_b != MPI_COMM_NULL)
33     {
34         lib_call(comm_b);
35         lib_call(comm_b);
36     }
37
38     if(comm_a != MPI_COMM_NULL)
39         MPI_Comm_free(&comm_a);
40     if(comm_b != MPI_COMM_NULL)
41         MPI_Comm_free(&comm_b);
42     MPI_Group_free(&group_a);
43     MPI_Group_free(&group_b);
44     MPI_Group_free(&MPI_GROUP_WORLD);
45     MPI_Finalize();
46 }

```

The library:

```

void lib_call(MPI_Comm comm)
{
    int me, done = 0;
    MPI_Status status;
    MPI_Comm_rank(comm, &me);
    if(me == 0)
        while(!done)
        {
            MPI_Recv(..., MPI_ANY_SOURCE, MPI_ANY_TAG, comm, &status);
            ...
        }
    else
    {
        /* work */
        MPI_Send(..., 0, ARBITRARY_TAG, comm);
        ....
    }
#ifdef EXAMPLE_2C
    /* include (resp, exclude) for safety (resp, no safety): */
    MPI_Barrier(comm);
#endif
}

```

The above example is really three examples, depending on whether or not one includes rank 3 in `list_b`, and whether or not a synchronize is included in `lib_call`. This example illustrates that, despite contexts, subsequent calls to `lib_call` with the same context need not be safe from one another (colloquially, “back-masking”). Safety is realized if the `MPI_Barrier` is added. What this demonstrates is that libraries have to be written carefully, even with contexts. When rank 3 is excluded, then the synchronize is not needed to get safety from back masking.

Algorithms like “reduce” and “allreduce” have strong enough source selectivity properties so that they are inherently okay (no backmasking), provided that MPI provides basic guarantees. So are multiple calls to a typical tree-broadcast algorithm with the same root or different roots (see [53]). Here we rely on two guarantees of MPI: pairwise ordering of messages between processes in the same context, and source selectivity — deleting either feature removes the guarantee that backmasking cannot be required.

Algorithms that try to do non-deterministic broadcasts or other calls that include wildcard operations will not generally have the good properties of the deterministic implementations of “reduce,” “allreduce,” and “broadcast.” Such algorithms would have to utilize the monotonically increasing tags (within a communicator scope) to keep things straight.

All of the foregoing is a supposition of “collective calls” implemented with point-to-point operations. MPI implementations may or may not implement collective calls using point-to-point operations. These algorithms are used to illustrate the issues of correctness and safety, independent of how MPI implements its collective calls. See also Section 6.9.

## 6.6 Inter-Communication

This section introduces the concept of inter-communication and describes the portions of MPI that support it. It describes support for writing programs that contain user-level servers.

All communication described thus far has involved communication between processes that are members of the same group. This type of communication is called “intra-communication” and the communicator used is called an “intra-communicator,” as we have noted earlier in the chapter.

In modular and multi-disciplinary applications, different process groups execute distinct modules and processes within different modules communicate with one another in a pipeline or a more general module graph. In these applications, the most natural way for a process to specify a target process is by the rank of the target process within the target group. In applications that contain internal user-level servers, each server may be a process group that provides services to one or more clients, and each client may be a process group that uses the services of one or more servers. It is again most natural to specify the target process by rank within the target group in these applications. This type of communication is called “inter-communication” and the communicator used is called an “inter-communicator,” as introduced earlier.

An inter-communication is a point-to-point communication between processes in different groups. The group containing a process that initiates an inter-communication operation is called the “local group,” that is, the sender in a send and the receiver in a receive. The group containing the target process is called the “remote group,” that is, the receiver in a send and the sender in a receive. As in intra-communication, the target process is specified using a (communicator, rank) pair. Unlike intra-communication, the rank is relative to a second, remote group.

All inter-communicator constructors are blocking and require that the local and remote groups be disjoint.

*Advice to users.* The groups must be disjoint for several reasons. Primarily, this is the intent of the intercommunicators — to provide a communicator for communication between disjoint groups. This is reflected in the definition of `MPI_INTERCOMM_MERGE`, which allows the user to control the ranking of the processes in the created intracommunicator; this ranking makes little sense if the groups are not disjoint. In addition, the natural extension of collective operations to inter-communicators makes the most sense when the groups are disjoint. (*End of advice to users.*)

Here is a summary of the properties of inter-communication and inter-communicators:

- The syntax of point-to-point and collective communication is the same for both inter- and intra-communication. The same communicator can be used both for send and for receive operations.
- A target process is addressed by its rank in the remote group, both for sends and for receives.
- Communications using an inter-communicator are guaranteed not to conflict with any communications that use a different communicator.
- A communicator will provide either intra- or inter-communication, never both.

The routine `MPI_COMM_TEST_INTER` may be used to determine if a communicator is an inter- or intra-communicator. Inter-communicators can be used as arguments to some of the other communicator access routines. Inter-communicators cannot be used as input to some of the constructor routines for intra-communicators (for instance, `MPI_CART_CREATE`).

*Advice to implementors.* For the purpose of point-to-point communication, communicators can be represented in each process by a tuple consisting of:

**group**  
**send\_context**  
**receive\_context**  
**source**

For inter-communicators, **group** describes the remote group, and **source** is the rank of the process in the local group. For intra-communicators, **group** is the communicator group (remote=local), **source** is the rank of the process in this group, and **send context** and **receive context** are identical. A group can be represented by a rank-to-absolute-address translation table.

The inter-communicator cannot be discussed sensibly without considering processes in both the local and remote groups. Imagine a process **P** in group  $\mathcal{P}$ , which has an inter-communicator  $C_{\mathcal{P}}$ , and a process **Q** in group  $\mathcal{Q}$ , which has an inter-communicator  $C_{\mathcal{Q}}$ . Then

- $C_{\mathcal{P}}.\text{group}$  describes the group  $\mathcal{Q}$  and  $C_{\mathcal{Q}}.\text{group}$  describes the group  $\mathcal{P}$ .
- $C_{\mathcal{P}}.\text{send\_context} = C_{\mathcal{Q}}.\text{receive\_context}$  and the context is unique in  $\mathcal{Q}$ ;  
 $C_{\mathcal{P}}.\text{receive\_context} = C_{\mathcal{Q}}.\text{send\_context}$  and this context is unique in  $\mathcal{P}$ .
- $C_{\mathcal{P}}.\text{source}$  is rank of **P** in  $\mathcal{P}$  and  $C_{\mathcal{Q}}.\text{source}$  is rank of **Q** in  $\mathcal{Q}$ .

Assume that **P** sends a message to **Q** using the inter-communicator. Then **P** uses the **group** table to find the absolute address of **Q**; **source** and **send\_context** are appended to the message.

Assume that **Q** posts a receive with an explicit source argument using the inter-communicator. Then **Q** matches **receive\_context** to the message context and source argument to the message source.

The same algorithm is appropriate for intra-communicators as well.

In order to support inter-communicator accessors and constructors, it is necessary to supplement this model with additional structures, that store information about the local communication group, and additional safe contexts. (*End of advice to implementors.*)

### 6.6.1 Inter-communicator Accessors

`MPI_COMM_TEST_INTER(comm, flag)`

IN	<code>comm</code>	communicator (handle)
OUT	<code>flag</code>	(logical)

```
1 int MPI_Comm_test_inter(MPI_Comm comm, int *flag)
2
3 MPI_COMM_TEST_INTER(COMM, FLAG, IERROR)
4     INTEGER COMM, IERROR
5     LOGICAL FLAG
6
7 MPI_Comm_test_inter(comm, flag, ierror)
8     TYPE(MPI_Comm), INTENT(IN) :: comm
9     LOGICAL, INTENT(OUT) :: flag
10    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
11
12 {bool MPI::Comm::Is_inter() const(binding deprecated, see Section 15.2) }
```

This local routine allows the calling process to determine if a communicator is an inter-communicator or an intra-communicator. It returns true if it is an inter-communicator, otherwise false.

When an inter-communicator is used as an input argument to the communicator accessors described above under intra-communication, the following table describes behavior.

MPI_COMM_SIZE	returns the size of the local group.
MPI_COMM_GROUP	returns the local group.
MPI_COMM_RANK	returns the rank in the local group

Table 6.1: MPI\_COMM\_\* Function Behavior (in Inter-Communication Mode)

Furthermore, the operation MPI\_COMM\_COMPARE is valid for inter-communicators. Both communicators must be either intra- or inter-communicators, or else MPI\_UNEQUAL results. Both corresponding local and remote groups must compare correctly to get the results MPI\_CONGRUENT and MPI\_SIMILAR. In particular, it is possible for MPI\_SIMILAR to result because either the local or remote groups were similar but not identical.

The following accessors provide consistent access to the remote group of an inter-communicator:

The following are all local operations.

```
34 MPI_COMM_REMOTE_SIZE(comm, size)
35
36 IN      comm      inter-communicator (handle)
37
38 OUT     size      number of processes in the remote group of comm
39                      (integer)
```

```
40
41 int MPI_Comm_remote_size(MPI_Comm comm, int *size)
42
43 MPI_COMM_REMOTE_SIZE(COMM, SIZE, IERROR)
44     INTEGER COMM, SIZE, IERROR
45
46 MPI_Comm_remote_size(comm, size, ierror)
47     TYPE(MPI_Comm), INTENT(IN) :: comm
48     INTEGER, INTENT(OUT) :: size
49     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{int MPI::Intercomm::Get_remote_size() const(binding deprecated, see Section 15.2)
    }
```

```
MPI_COMM_REMOTE_GROUP(comm, group)
```

```
IN      comm      inter-communicator (handle)
OUT     group      remote group corresponding to comm (handle)
```

```
int MPI_Comm_remote_group(MPI_Comm comm, MPI_Group *group)
```

```
MPI_COMM_REMOTE_GROUP(COMM, GROUP, IERROR)
    INTEGER COMM, GROUP, IERROR
```

```
MPI_Comm_remote_group(comm, group, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm
    TYPE(MPI_Group), INTENT(OUT) :: group
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{MPI::Group MPI::Intercomm::Get_remote_group() const(binding deprecated, see
    Section 15.2) }
```

*Rationale.* Symmetric access to both the local and remote groups of an inter-communicator is important, so this function, as well as `MPI_COMM_REMOTE_SIZE` have been provided. (*End of rationale.*)

## 6.6.2 Inter-communicator Operations

This section introduces four blocking inter-communicator operations.

`MPI_INTERCOMM_CREATE` is used to bind two intra-communicators into an inter-communicator; the function `MPI_INTERCOMM_MERGE` creates an intra-communicator by merging the local and remote groups of an inter-communicator. The functions `MPI_COMM_DUP` and `MPI_COMM_FREE`, introduced previously, duplicate and free an inter-communicator, respectively.

Overlap of local and remote groups that are bound into an inter-communicator is prohibited. If there is overlap, then the program is erroneous and is likely to deadlock. (If a process is multithreaded, and MPI calls block only a thread, rather than a process, then “dual membership” can be supported. It is then the user’s responsibility to make sure that calls on behalf of the two “roles” of a process are executed by two independent threads.)

The function `MPI_INTERCOMM_CREATE` can be used to create an inter-communicator from two existing intra-communicators, in the following situation: At least one selected member from each group (the “group leader”) has the ability to communicate with the selected member from the other group; that is, a “peer” communicator exists to which both leaders belong, and each leader knows the rank of the other leader in this peer communicator. Furthermore, members of each group know the rank of their leader.

Construction of an inter-communicator from two intra-communicators requires separate collective operations in the local group and in the remote group, as well as a point-to-point communication between a process in the local group and a process in the remote group.

In standard MPI implementations (with static process allocation at initialization), the `MPI_COMM_WORLD` communicator (or preferably a dedicated duplicate thereof) can be this peer communicator. For applications that have used `spawn` or `join`, it may be necessary to first create an intracommunicator to be used as peer.

The application topology functions described in Chapter 7 do not apply to inter-communicators. Users that require this capability should utilize `MPI_INTERCOMM_MERGE` to build an intra-communicator, then apply the graph or cartesian topology capabilities to that intra-communicator, creating an appropriate topology-oriented intra-communicator. Alternatively, it may be reasonable to devise one’s own application topology mechanisms for this case, without loss of generality.

```
MPI_INTERCOMM_CREATE(local_comm, local_leader, peer_comm, remote_leader, tag,
                      newintercomm)
```

IN	<code>local_comm</code>	local intra-communicator (handle)
IN	<code>local_leader</code>	rank of local group leader in <code>local_comm</code> (integer)
IN	<code>peer_comm</code>	“peer” communicator; significant only at the <code>local_leader</code> (handle)
IN	<code>remote_leader</code>	rank of remote group leader in <code>peer_comm</code> ; significant only at the <code>local_leader</code> (integer)
IN	<code>tag</code>	“safe” tag (integer)
OUT	<code>newintercomm</code>	new inter-communicator (handle)

```
int MPI_Intercomm_create(MPI_Comm local_comm, int local_leader,
                        MPI_Comm peer_comm, int remote_leader, int tag,
                        MPI_Comm *newintercomm)
```

```
MPI_INTERCOMM_CREATE(LOCAL_COMM, LOCAL_LEADER, PEER_COMM, REMOTE_LEADER,
                     TAG, NEWINTERCOMM, IERROR)
INTEGER LOCAL_COMM, LOCAL_LEADER, PEER_COMM, REMOTE_LEADER, TAG,
NEWINTERCOMM, IERROR
```

```
MPI_Intercomm_create(local_comm, local_leader, peer_comm, remote_leader,
                    tag, newintercomm, ierror)
TYPE(MPI_Comm), INTENT(IN) :: local_comm, peer_comm
INTEGER, INTENT(IN) :: local_leader, remote_leader, tag
TYPE(MPI_Comm), INTENT(OUT) :: newintercomm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{MPI::Intercomm MPI::Intracomm::Create_intercomm(int local_leader, const
MPI::Comm& peer_comm, int remote_leader, int tag) const(binding
deprecated, see Section 15.2) }
```

This call creates an inter-communicator. It is collective over the union of the local and remote groups. Processes should provide identical `local_comm` and `local_leader` arguments within each group. Wildcards are not permitted for `remote_leader`, `local_leader`, and `tag`.

This call uses point-to-point communication with communicator `peer_comm`, and with tag `tag` between the leaders. Thus, care must be taken that there be



no pending communication on `peer_comm` that could interfere with this communication.

*Advice to users.* We recommend using a dedicated peer communicator, such as a duplicate of `MPI_COMM_WORLD`, to avoid trouble with peer communicators. (*End of advice to users.*)

`MPI_INTERCOMM_MERGE(intercomm, high, newintracomm)`

IN	intercomm	Inter-Communicator (handle)
IN	high	(logical)
OUT	newintracomm	new intra-communicator (handle)

```
int MPI_Intercomm_merge(MPI_Comm intercomm, int high,
                        MPI_Comm *newintracomm)
```

```
MPI_INTERCOMM_MERGE(INTERCOMM, HIGH, NEWINTRACOMM, IERROR)
    INTEGER NEWINTERCOMM, INTRACOMM, IERROR
    LOGICAL HIGH
```

```
MPI_Intercomm_merge(intercomm, high, newintracomm, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: intercomm
    LOGICAL, INTENT(IN) :: high
    TYPE(MPI_Comm), INTENT(OUT) :: newintracomm
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{MPI::Intracomm MPI::Intercomm::Merge(bool high) const(binding deprecated, see
    Section 15.2) }
```

This function creates an intra-communicator from the union of the two groups that are associated with `intercomm`. All processes should provide the same `high` value within each of the two groups. If processes in one group provided the value `high = false` and processes in the other group provided the value `high = true` then the union orders the “low” group before the “high” group. If all processes provided the same `high` argument then the order of the union is arbitrary. This call is blocking and collective within the union of the two groups.

The error handler on the new intercommunicator in each process is inherited from the communicator that contributes the local group. Note that this can result in different processes in the same communicator having different error handlers.

*Advice to implementors.* The implementation of `MPI_INTERCOMM_MERGE`, `MPI_COMM_FREE` and `MPI_COMM_DUP` are similar to the implementation of `MPI_INTERCOMM_CREATE`, except that contexts private to the input inter-communicator are used for communication between group leaders rather than contexts inside a bridge communicator. (*End of advice to implementors.*)

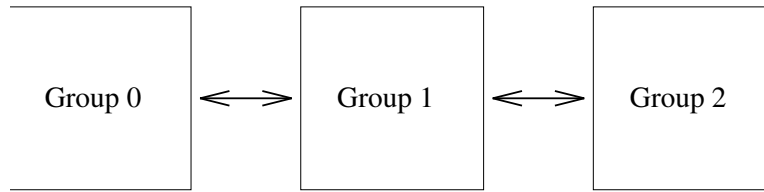


Figure 6.3: Three-group pipeline[ticket0.]

### 6.6.3 Inter-Communication Examples

#### Example 1: Three-Group “Pipeline”

Groups 0 and 1 communicate. Groups 1 and 2 communicate. Therefore, group 0 requires one inter-communicator, group 1 requires two inter-communicators, and group 2 requires 1 inter-communicator.

```

int main(int argc, char **argv)
{
    MPI_Comm    myComm;          /* intra-communicator of local sub-group */
    MPI_Comm    myFirstComm;     /* inter-communicator */
    MPI_Comm    mySecondComm;   /* second inter-communicator (group 1 only) */
    int membershipKey;
    int rank;

    MPI_Init(&argc, &argv);
    MPI_Comm_rank(MPI_COMM_WORLD, &rank);

    /* User code must generate membershipKey in the range [0, 1, 2] */
    membershipKey = rank % 3;

    /* Build intra-communicator for local sub-group */
    MPI_Comm_split(MPI_COMM_WORLD, membershipKey, rank, &myComm);

    /* Build inter-communicators. Tags are hard-coded. */
    if (membershipKey == 0)
    {
        /* Group 0 communicates with group 1. */
        MPI_Intercomm_create( myComm, 0, MPI_COMM_WORLD, 1,
                             1, &myFirstComm);
    }
    else if (membershipKey == 1)
    {
        /* Group 1 communicates with groups 0 and 2. */
        MPI_Intercomm_create( myComm, 0, MPI_COMM_WORLD, 0,
                             1, &myFirstComm);
        MPI_Intercomm_create( myComm, 0, MPI_COMM_WORLD, 2,
                             12, &mySecondComm);
    }
    else if (membershipKey == 2)
    {
        /* Group 2 communicates with group 1. */
    }
}

```

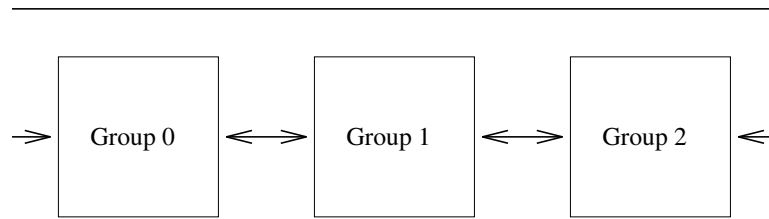


Figure 6.4: Three-group ring[ticket0.]

```

MPI_Intercomm_create( myComm, 0, MPI_COMM_WORLD, 1,
                      12, &myFirstComm);
}

/* Do work ... */

switch(membershipKey) /* free communicators appropriately */
{
case 1:
    MPI_Comm_free(&mySecondComm);
case 0:
case 2:
    MPI_Comm_free(&myFirstComm);
    break;
}

MPI_Finalize();
}

```

## Example 2: Three-Group “Ring”

Groups 0 and 1 communicate. Groups 1 and 2 communicate. Groups 0 and 2 communicate. Therefore, each requires two inter-communicators.

```

int main(int argc, char **argv)
{
    MPI_Comm  myComm;      /* intra-communicator of local sub-group */
    MPI_Comm  myFirstComm; /* inter-communicators */
    MPI_Comm  mySecondComm;
    MPI_Status status;
    int membershipKey;
    int rank;

    MPI_Init(&argc, &argv);
    MPI_Comm_rank(MPI_COMM_WORLD, &rank);
    ...

    /* User code must generate membershipKey in the range [0, 1, 2] */
    membershipKey = rank % 3;
}

```

```

1
2  /* Build intra-communicator for local sub-group */
3  MPI_Comm_split(MPI_COMM_WORLD, membershipKey, rank, &myComm);
4
5  /* Build inter-communicators.  Tags are hard-coded. */
6  if (membershipKey == 0)
7  {
8      /* Group 0 communicates with groups 1 and 2. */
9      MPI_Intercomm_create( myComm, 0, MPI_COMM_WORLD, 1,
10                          1, &myFirstComm);
11      MPI_Intercomm_create( myComm, 0, MPI_COMM_WORLD, 2,
12                          2, &mySecondComm);
13  }
14  else if (membershipKey == 1)
15  {
16      /* Group 1 communicates with groups 0 and 2. */
17      MPI_Intercomm_create( myComm, 0, MPI_COMM_WORLD, 0,
18                          1, &myFirstComm);
19      MPI_Intercomm_create( myComm, 0, MPI_COMM_WORLD, 2,
20                          12, &mySecondComm);
21  }
22  else if (membershipKey == 2)
23  {
24      /* Group 2 communicates with groups 0 and 1. */
25      MPI_Intercomm_create( myComm, 0, MPI_COMM_WORLD, 0,
26                          2, &myFirstComm);
27      MPI_Intercomm_create( myComm, 0, MPI_COMM_WORLD, 1,
28                          12, &mySecondComm);
29  }
30
31  /* Do some work ... */
32
33  /* Then free communicators before terminating... */
34  MPI_Comm_free(&myFirstComm);
35  MPI_Comm_free(&mySecondComm);
36  MPI_Comm_free(&myComm);
37  MPI_Finalize();
38  }
39

```

## 6.7 Caching

MPI provides a “caching” facility that allows an application to attach arbitrary pieces of information, called **attributes**, to three kinds of MPI objects, communicators, windows and datatypes. More precisely, the caching facility allows a portable library to do the following:

- pass information between calls by associating it with an MPI intra- or inter-communicator, window or datatype,
- quickly retrieve that information, and
- be guaranteed that out-of-date information is never retrieved, even if the object is freed and its handle subsequently reused by MPI.

The caching capabilities, in some form, are required by built-in MPI routines such as collective communication and application topology. Defining an interface to these capabilities as part of the MPI standard is valuable because it permits routines like collective communication and application topologies to be implemented as portable code, and also because it makes MPI more extensible by allowing user-written routines to use standard MPI calling sequences.

*Advice to users.* The communicator `MPI_COMM_SELF` is a suitable choice for posting process-local attributes, via this attributing-caching mechanism. (*End of advice to users.*)

*Rationale.* In one extreme one can allow caching on all opaque handles. The other extreme is to only allow it on communicators. Caching has a cost associated with it and should only be allowed when it is clearly needed and the increased cost is modest. This is the reason that windows and datatypes were added but not other handles. (*End of rationale.*)

One difficulty is the potential for size differences between Fortran integers and C pointers. To overcome this problem with attribute caching on communicators, functions are also given for this case. The functions to cache on datatypes and windows also address this issue. For a general discussion of the address size problem, see Section 16.3.6.

*Advice to implementors.* High-quality implementations should raise an error when a keyval that was created by a call to `MPI_XXX_CREATE_KEYVAL` is used with an object of the wrong type with a call to `MPI_YYY_GET_ATTR`, `MPI_YYY_SET_ATTR`, `MPI_YYY_DELETE_ATTR`, or `MPI_YYY_FREE_KEYVAL`. To do so, it is necessary to maintain, with each keyval, information on the type of the associated user function. (*End of advice to implementors.*)

### 6.7.1 Functionality

Attributes can be attached to communicators, windows, and datatypes. Attributes are local to the process and specific to the communicator to which they are attached. Attributes are not propagated by MPI from one communicator to another except when the communicator is duplicated using `MPI_COMM_DUP` (and even then the application must give specific permission through callback functions for the attribute to be copied).

*Advice to users.* Attributes in C are of type `void *`. Typically, such an attribute will be a pointer to a structure that contains further information, or a handle to an MPI object. In Fortran, attributes are of type `INTEGER`. Such attribute can be a handle to an MPI object, or just an integer-valued attribute. (*End of advice to users.*)

*Advice to implementors.* Attributes are scalar values, equal in size to, or larger than a C-language pointer. Attributes can always hold an MPI handle. (*End of advice to implementors.*)

The caching interface defined here requires that attributes be stored by MPI opaquely within a communicator, window, and datatype. Accessor functions include the following:

- obtain a key value (used to identify an attribute); the user specifies “callback” functions by which MPI informs the application when the communicator is destroyed or copied.
- store and retrieve the value of an attribute;

*Advice to implementors.* Caching and callback functions are only called synchronously, in response to explicit application requests. This avoids problems that result from repeated crossings between user and system space. (This synchronous calling rule is a general property of MPI.)

The choice of key values is under control of MPI. This allows MPI to optimize its implementation of attribute sets. It also avoids conflict between independent modules caching information on the same communicators.

A much smaller interface, consisting of just a callback facility, would allow the entire caching facility to be implemented by portable code. However, with the minimal callback interface, some form of table searching is implied by the need to handle arbitrary communicators. In contrast, the more complete interface defined here permits rapid access to attributes through the use of pointers in communicators (to find the attribute table) and cleverly chosen key values (to retrieve individual attributes). In light of the efficiency “hit” inherent in the minimal interface, the more complete interface defined here is seen to be superior. (*End of advice to implementors.*)

MPI provides the following services related to caching. They are all process local.

### 6.7.2 Communicators

Functions for caching on communicators are:

`MPI_COMM_CREATE_KEYVAL(comm_copy_attr_fn, comm_delete_attr_fn, comm_keyval, extra_state)`

IN	<code>comm_copy_attr_fn</code>	copy callback function for <code>comm_keyval</code> (function)
IN	<code>comm_delete_attr_fn</code>	delete callback function for <code>comm_keyval</code> (function)
OUT	<code>comm_keyval</code>	key value for future access (integer)
IN	<code>extra_state</code>	extra state for callback functions

```
int MPI_Comm_create_keyval(MPI_Comm_copy_attr_function *comm_copy_attr_fn,
                           MPI_Comm_delete_attr_function *comm_delete_attr_fn,
                           int *comm_keyval, void *extra_state)
```

```
MPI_COMM_CREATE_KEYVAL(COMM_COPY_ATTR_FN, COMM_DELETE_ATTR_FN, COMM_KEYVAL,
                        EXTRA_STATE, IERROR)
EXTERNAL COMM_COPY_ATTR_FN, COMM_DELETE_ATTR_FN
INTEGER COMM_KEYVAL, IERROR
INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE
```

```
MPI_Comm_create_keyval(comm_copy_attr_fn, comm_delete_attr_fn, comm_keyval,
                        extra_state, ierror)
```

```

PROCEDURE(MPI_Comm_copy_attr_function) :: comm_copy_attr_fn
PROCEDURE(MPI_Comm_delete_attr_function) :: comm_delete_attr_fn
INTEGER, INTENT(OUT) :: comm_keyval
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: extra_state
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{static int MPI::Comm::Create_keyval(MPI::Comm::Copy_attr_function*
    comm_copy_attr_fn,
    MPI::Comm::Delete_attr_function* comm_delete_attr_fn,
    void* extra_state) (binding deprecated, see Section 15.2) }
```

Generates a new attribute key. Keys are locally unique in a process, and opaque to user, though they are explicitly stored in integers. Once allocated, the key value can be used to associate attributes and access them on any locally defined communicator.

This function replaces MPI\_KEYVAL\_CREATE, whose use is deprecated. The C binding is identical. The Fortran binding differs in that `extra_state` is an address-sized integer. Also, the copy and delete callback functions have Fortran bindings that are consistent with address-sized attributes.

The C callback functions are:

```

typedef int MPI_Comm_copy_attr_function(MPI_Comm oldcomm, int comm_keyval,
    void *extra_state, void *attribute_val_in,
    void *attribute_val_out, int *flag);
```

and

```

typedef int MPI_Comm_delete_attr_function(MPI_Comm comm, int comm_keyval,
    void *attribute_val, void *extra_state);
```

which are the same as the MPI-1.1 calls but with a new name. The old names are deprecated.

With the `mpi` module and `mpif.h`, the Fortran callback functions are:

```

SUBROUTINE COMM_COPY_ATTR_FUNCTION(OLDCOMM, COMM_KEYVAL, EXTRA_STATE,
    ATTRIBUTE_VAL_IN, ATTRIBUTE_VAL_OUT, FLAG, IERROR)
    INTEGER OLDCOMM, COMM_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE, ATTRIBUTE_VAL_IN,
    ATTRIBUTE_VAL_OUT
    LOGICAL FLAG
```

and

```

SUBROUTINE COMM_DELETE_ATTR_FUNCTION(COMM, COMM_KEYVAL, ATTRIBUTE_VAL,
    EXTRA_STATE, IERROR)
    INTEGER COMM, COMM_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL, EXTRA_STATE
```

With the `mpi_f08` module, the Fortran callback functions are:

```

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    SUBROUTINE MPI_Comm_copy_attr_function(oldcomm, comm_keyval, extra_state,
    attribute_val_in, attribute_val_out, flag, ierror)
        TYPE(MPI_Comm) :: oldcomm
        INTEGER :: comm_keyval, ierror
```

```

1      INTEGER(KIND=MPI_ADDRESS_KIND) ::  extra_state, attribute_val_in,
2      attribute_val_out
3      LOGICAL flag

```

and

```

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```

```

7      SUBROUTINE MPI_Comm_delete_attr_function(comm, comm_keyval,
8      attribute_val, extra_state, ierror)
9      TYPE(MPI_Comm) ::  comm
10     INTEGER ::  comm_keyval, ierror
11     INTEGER(KIND=MPI_ADDRESS_KIND) ::  attribute_val, extra_state

```

The C++ callbacks are:

```

14 {typedef int MPI::Comm::Copy_attr_function(const MPI::Comm& oldcomm,
15      int comm_keyval, void* extra_state, void* attribute_val_in,
16      void* attribute_val_out, bool& flag); (binding deprecated, see
17      Section 15.2)}

```

and

```

19 {typedef int MPI::Comm::Delete_attr_function(MPI::Comm& comm,
20      int comm_keyval, void* attribute_val, void* extra_state);
21      (binding deprecated, see Section 15.2)}

```

The `comm_copy_attr_fn` function is invoked when a communicator is duplicated by `MPI_COMM_DUP`. `comm_copy_attr_fn` should be of type `MPI_Comm_copy_attr_function`. The copy callback function is invoked for each key value in `oldcomm` in arbitrary order. Each call to the copy callback is made with a key value and its corresponding attribute. If it returns `flag = 0`, then the attribute is deleted in the duplicated communicator. Otherwise (`flag = 1`), the new attribute value is set to the value returned in `attribute_val_out`. The function returns `MPI_SUCCESS` on success and an error code on failure (in which case `MPI_COMM_DUP` will fail).

The argument `comm_copy_attr_fn` may be specified as `MPI_COMM_NULL_COPY_FN` or `MPI_COMM_DUP_FN` from either C, C++, or Fortran. `MPI_COMM_NULL_COPY_FN` is a function that does nothing other than returning `flag = 0` and `MPI_SUCCESS`.

`MPI_COMM_DUP_FN` is a simple-minded copy function that sets `flag = 1`, returns the value of `attribute_val_in` in `attribute_val_out`, and returns `MPI_SUCCESS`. These replace the MPI-1 predefined callbacks `MPI_NULL_COPY_FN` and `MPI_DUP_FN`, whose use is deprecated.

*Advice to users.* Even though both formal arguments `attribute_val_in` and `attribute_val_out` are of type `void *`, their usage differs. The C copy function is passed by MPI in `attribute_val_in` the *value* of the attribute, and in `attribute_val_out` the *address* of the attribute, so as to allow the function to return the (new) attribute value. The use of type `void *` for both is to avoid messy type casts.

A valid copy function is one that completely duplicates the information by making a full duplicate copy of the data structures implied by an attribute; another might just make another reference to that data structure, while using a reference-count mechanism. Other types of attributes might not copy at all (they might be specific to `oldcomm` only). (*End of advice to users.*)



*Advice to implementors.* A C interface should be assumed for copy and delete functions associated with key values created in C; a Fortran calling interface should be assumed for key values created in Fortran. (*End of advice to implementors.*)

Analogous to `comm_copy_attr_fn` is a callback deletion function, defined as follows. The `comm_delete_attr_fn` function is invoked when a communicator is deleted by `MPI_COMM_FREE` or when a call is made explicitly to `MPI_COMM_DELETE_ATTR`. `comm_delete_attr_fn` should be of type `MPI_Comm_delete_attr_function`.

This function is called by `MPI_COMM_FREE`, `MPI_COMM_DELETE_ATTR`, and `MPI_COMM_SET_ATTR` to do whatever is needed to remove an attribute. The function returns `MPI_SUCCESS` on success and an error code on failure (in which case `MPI_COMM_FREE` will fail).

The argument `comm_delete_attr_fn` may be specified as `MPI_COMM_NULL_DELETE_FN` from either C, C++, or Fortran. `MPI_COMM_NULL_DELETE_FN` is a function that does nothing, other than returning `MPI_SUCCESS`. `MPI_COMM_NULL_DELETE_FN` replaces `MPI_NULL_DELETE_FN`, whose use is deprecated.

If an attribute copy function or attribute delete function returns other than `MPI_SUCCESS`, then the call that caused it to be invoked (for example, `MPI_COMM_FREE`), is erroneous.

The special key value `MPI_KEYVAL_INVALID` is never returned by `MPI_KEYVAL_CREATE`. Therefore, it can be used for static initialization of key values.

*Advice to implementors.* To be able to use the predefined C functions `MPI_COMM_NULL_COPY_FN` or `MPI_COMM_DUP_FN` as `comm_copy_attr_fn` argument and/or `MPI_COMM_NULL_DELETE_FN` as the `comm_delete_attr_fn` argument in a call to the C++ routine `MPI::Comm::Create_keyval`, this routine may be overloaded with 3 additional routines that accept the C functions as the first, the second, or both input arguments (instead of an argument that matches the C++ prototype). (*End of advice to implementors.*)

*Advice to users.* If a user wants to write a “wrapper” routine that internally calls `MPI::Comm::Create_keyval` and `comm_copy_attr_fn` and/or `comm_delete_attr_fn` are arguments of this wrapper routine, and if this wrapper routine should be callable with both user-defined C++ copy and delete functions and with the predefined C functions, then the same overloading as described above in the advice to implementors may be necessary. (*End of advice to users.*)

*Advice to implementors.* The predefined Fortran functions `MPI_COMM_NULL_COPY_FN`, `MPI_COMM_DUP_FN`, and `MPI_COMM_NULL_DELETE_FN` are defined in the `mpi` module (and `mpif.h`) and the `mpi_f08` module with a different interface. Each function can coexist twice with the same name in the same MPI library, one routine as an implicit interface outside of the `mpi` module, i.e., declared as `EXTERNAL`, and the other routine within `mpi_f08` declared with `CONTAINS`. (*End of advice to implementors.*)

*Advice to users.* One should not pass the predefined Fortran functions `MPI_COMM_NULL_COPY_FN`, `MPI_COMM_DUP_FN`, and `MPI_COMM_NULL_DELETE_FN` from one application routine that uses the `mpi_f08`

module to another application routine that uses the `mpi` module or `mpif.h`, and vice versa. (*End of advice to users.*)

`MPI_COMM_FREE_KEYVAL(comm_keyval)`

INOUT      `comm_keyval`                      key value (integer)

`int MPI_Comm_free_keyval(int *comm_keyval)`

`MPI_COMM_FREE_KEYVAL(COMM_KEYVAL, IERROR)`

INTEGER `COMM_KEYVAL`, `IERROR`

`MPI_Comm_free_keyval(comm_keyval, ierror)`

INTEGER, INTENT(INOUT) :: `comm_keyval`

INTEGER, OPTIONAL, INTENT(OUT) :: `ierror`

`{static void MPI::Comm::Free_keyval(int& comm_keyval) (binding deprecated, see Section 15.2) }`

Frees an extant attribute key. This function sets the value of `keyval` to `MPI_KEYVAL_INVALID`. Note that it is not erroneous to free an attribute key that is in use, because the actual free does not transpire until after all references (in other communicators on the process) to the key have been freed. These references need to be explicitly freed by the program, either via calls to `MPI_COMM_DELETE_ATTR` that free one attribute instance, or by calls to `MPI_COMM_FREE` that free all attribute instances associated with the freed communicator.

This call is identical to the MPI-1 call `MPI_KEYVAL_FREE` but is needed to match the new communicator-specific creation function. The use of `MPI_KEYVAL_FREE` is deprecated.

`MPI_COMM_SET_ATTR(comm, comm_keyval, attribute_val)`

INOUT      `comm`                      communicator from which attribute will be attached (handle)

IN          `comm_keyval`                      key value (integer)

IN          `attribute_val`                      attribute value

`int MPI_Comm_set_attr(MPI_Comm comm, int comm_keyval, void *attribute_val)`

`MPI_COMM_SET_ATTR(COMM, COMM_KEYVAL, ATTRIBUTE_VAL, IERROR)`

INTEGER `COMM`, `COMM_KEYVAL`, `IERROR`

INTEGER(`KIND=MPI_ADDRESS_KIND`) `ATTRIBUTE_VAL`

`MPI_Comm_set_attr(comm, comm_keyval, attribute_val, ierror)`

TYPE(`MPI_Comm`), INTENT(IN) :: `comm`

INTEGER, INTENT(IN) :: `comm_keyval`

INTEGER(`KIND=MPI_ADDRESS_KIND`), INTENT(IN) :: `attribute_val`

INTEGER, OPTIONAL, INTENT(OUT) :: `ierror`

```
{void MPI::Comm::Set_attr(int comm_keyval, const void* attribute_val)
    const(binding deprecated, see Section 15.2) }
```

This function stores the stipulated attribute value `attribute_val` for subsequent retrieval by `MPI_COMM_GET_ATTR`. If the value is already present, then the outcome is as if `MPI_COMM_DELETE_ATTR` was first called to delete the previous value (and the callback function `comm_delete_attr_fn` was executed), and a new value was next stored. The call is erroneous if there is no key with value `keyval`; in particular `MPI_KEYVAL_INVALID` is an erroneous key value. The call will fail if the `comm_delete_attr_fn` function returned an error code other than `MPI_SUCCESS`.

This function replaces `MPI_ATTR_PUT`, whose use is deprecated. The C binding is identical. The Fortran binding differs in that `attribute_val` is an address-sized integer.

```
MPI_COMM_GET_ATTR(comm, comm_keyval, attribute_val, flag)
```

IN	comm	communicator to which the attribute is attached (handle)
IN	comm_keyval	key value (integer)
OUT	attribute_val	attribute value, unless <code>flag = false</code>
OUT	flag	false if no attribute is associated with the key (logical)

```
int MPI_Comm_get_attr(MPI_Comm comm, int comm_keyval, void *attribute_val,
    int *flag)
```

```
MPI_COMM_GET_ATTR(COMM, COMM_KEYVAL, ATTRIBUTE_VAL, FLAG, IERROR)
    INTEGER COMM, COMM_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL
    LOGICAL FLAG
```

```
MPI_Comm_get_attr(comm, comm_keyval, attribute_val, flag, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm
    INTEGER, INTENT(IN) :: comm_keyval
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: attribute_val
    LOGICAL, INTENT(OUT) :: flag
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{bool MPI::Comm::Get_attr(int comm_keyval, void* attribute_val)
    const(binding deprecated, see Section 15.2) }
```

Retrieves attribute value by key. The call is erroneous if there is no key with value `keyval`. On the other hand, the call is correct if the key value exists, but no attribute is attached on `comm` for that key; in such case, the call returns `flag = false`. In particular `MPI_KEYVAL_INVALID` is an erroneous key value.

*Advice to users.* The call to `MPI_Comm_set_attr` passes in `attribute_val` the *value* of the attribute; the call to `MPI_Comm_get_attr` passes in `attribute_val` the *address* of the location where the attribute value is to be returned. Thus, if the attribute value itself is a pointer of type `void*`, then the actual `attribute_val` parameter to `MPI_Comm_set_attr`

will be of type `void*` and the actual `attribute_val` parameter to `MPI_Comm_get_attr` will be of type `void**`. (*End of advice to users.*)

*Rationale.* The use of a formal parameter `attribute_val` or type `void*` (rather than `void**`) avoids the messy type casting that would be needed if the attribute value is declared with a type other than `void*`. (*End of rationale.*)

This function replaces `MPI_ATTR_GET`, whose use is deprecated. The C binding is identical. The Fortran binding differs in that `attribute_val` is an address-sized integer.

`MPI_COMM_DELETE_ATTR(comm, comm_keyval)`

INOUT	comm	communicator from which the attribute is deleted (handle)
IN	comm_keyval	key value (integer)

`int MPI_Comm_delete_attr(MPI_Comm comm, int comm_keyval)`

`MPI_COMM_DELETE_ATTR(COMM, COMM_KEYVAL, IERROR)`

`INTEGER COMM, COMM_KEYVAL, IERROR`

`MPI_Comm_delete_attr(comm, comm_keyval, ierror)`

`TYPE(MPI_Comm), INTENT(IN) :: comm`

`INTEGER, INTENT(IN) :: comm_keyval`

`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{void MPI::Comm::Delete_attr(int comm_keyval) (binding deprecated, see Section 15.2) }`

Delete attribute from cache by key. This function invokes the attribute delete function `comm_delete_attr_fn` specified when the `keyval` was created. The call will fail if the `comm_delete_attr_fn` function returns an error code other than `MPI_SUCCESS`.

Whenever a communicator is replicated using the function `MPI_COMM_DUP`, all callback copy functions for attributes that are currently set are invoked (in arbitrary order). Whenever a communicator is deleted using the function `MPI_COMM_FREE` all callback delete functions for attributes that are currently set are invoked.

This function is the same as `MPI_ATTR_DELETE` but is needed to match the new communicator specific functions. The use of `MPI_ATTR_DELETE` is deprecated.

### 6.7.3 Windows

The new functions for caching on windows are:

MPI\_WIN\_CREATE\_KEYVAL(win\_copy\_attr\_fn, win\_delete\_attr\_fn, win\_keyval, extra\_state)

IN	win_copy_attr_fn	copy callback function for win_keyval (function)
IN	win_delete_attr_fn	delete callback function for win_keyval (function)
OUT	win_keyval	key value for future access (integer)
IN	extra_state	extra state for callback functions

```
int MPI_Win_create_keyval(MPI_Win_copy_attr_function *win_copy_attr_fn,
                          MPI_Win_delete_attr_function *win_delete_attr_fn,
                          int *win_keyval, void *extra_state)
```

```
MPI_WIN_CREATE_KEYVAL(WIN_COPY_ATTR_FN, WIN_DELETE_ATTR_FN, WIN_KEYVAL,
                      EXTRA_STATE, IERROR)
EXTERNAL WIN_COPY_ATTR_FN, WIN_DELETE_ATTR_FN
INTEGER WIN_KEYVAL, IERROR
INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE
```

```
MPI_Win_create_keyval(win_copy_attr_fn, win_delete_attr_fn, win_keyval,
                      extra_state, ierror)
PROCEDURE(MPI_Win_copy_attr_function) :: win_copy_attr_fn
PROCEDURE(MPI_Win_delete_attr_function) :: win_delete_attr_fn
INTEGER, INTENT(OUT) :: win_keyval
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: extra_state
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{static int MPI::Win::Create_keyval(MPI::Win::Copy_attr_function*
    win_copy_attr_fn,
    MPI::Win::Delete_attr_function* win_delete_attr_fn,
    void* extra_state) (binding deprecated, see Section 15.2) }
```

The argument win\_copy\_attr\_fn may be specified as MPI\_WIN\_NULL\_COPY\_FN or MPI\_WIN\_DUP\_FN from either C, C++, or Fortran. MPI\_WIN\_NULL\_COPY\_FN is a function that does nothing other than returning flag = 0 and MPI\_SUCCESS. MPI\_WIN\_DUP\_FN is a simple-minded copy function that sets flag = 1, returns the value of attribute\_val\_in in attribute\_val\_out, and returns MPI\_SUCCESS.

The argument win\_delete\_attr\_fn may be specified as MPI\_WIN\_NULL\_DELETE\_FN from either C, C++, or Fortran. MPI\_WIN\_NULL\_DELETE\_FN is a function that does nothing, other than returning MPI\_SUCCESS.

The C callback functions are:

```
typedef int MPI_Win_copy_attr_function(MPI_Win oldwin, int win_keyval,
    void *extra_state, void *attribute_val_in,
    void *attribute_val_out, int *flag);
```

and

```
typedef int MPI_Win_delete_attr_function(MPI_Win win, int win_keyval,
    void *attribute_val, void *extra_state);
```

With the mpi module and mpif.h, the Fortran callback functions are:

```

ticket250-V. 1 SUBROUTINE WIN_COPY_ATTR_FUNCTION(OLDWIN, WIN_KEYVAL, EXTRA_STATE,
2             ATTRIBUTE_VAL_IN, ATTRIBUTE_VAL_OUT, FLAG, IERROR)
3             INTEGER OLDWIN, WIN_KEYVAL, IERROR
4             INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE, ATTRIBUTE_VAL_IN,
5             ATTRIBUTE_VAL_OUT
6             LOGICAL FLAG
7
8 and
ticket250-V. 9 SUBROUTINE WIN_DELETE_ATTR_FUNCTION(WIN, WIN_KEYVAL, ATTRIBUTE_VAL,
10             EXTRA_STATE, IERROR)
11             INTEGER WIN, WIN_KEYVAL, IERROR
12             INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL, EXTRA_STATE
13
14 With the mpi_f08 module, the Fortran callback functions are:
ticket230-B.
ticket-248T. 15 ABSTRACT INTERFACE
16             SUBROUTINE MPI_Win_copy_attr_function(oldwin, win_keyval, extra_state,
17             attribute_val_in, attribute_val_out, flag, ierror)
18             TYPE(MPI_Win) :: oldwin
19             INTEGER :: win_keyval, ierror
20             INTEGER(KIND=MPI_ADDRESS_KIND) :: extra_state, attribute_val_in,
21             attribute_val_out
22             LOGICAL flag
23
24 and
ticket230-B.
ticket-248T. 25 ABSTRACT INTERFACE
26             SUBROUTINE MPI_Win_delete_attr_function(win, win_keyval, attribute_val,
27             extra_state, ierror)
28             TYPE(MPI_Win) :: win
29             INTEGER :: win_keyval, ierror
30             INTEGER(KIND=MPI_ADDRESS_KIND) :: attribute_val, extra_state
31
32 The C++ callbacks are:
33 {typedef int MPI::Win::Copy_attr_function(const MPI::Win& oldwin,
34             int win_keyval, void* extra_state, void* attribute_val_in,
35             void* attribute_val_out, bool& flag); (binding deprecated, see
36             Section 15.2)}
37
38 and
39 {typedef int MPI::Win::Delete_attr_function(MPI::Win& win, int win_keyval,
40             void* attribute_val, void* extra_state); (binding deprecated, see
41             Section 15.2)}
42
43 If an attribute copy function or attribute delete function returns other than
44 MPI_SUCCESS, then the call that caused it to be invoked (for example, MPI_WIN_FREE), is
45 erroneous.
46
47
48

```

```

MPI_WIN_FREE_KEYVAL(win_keyval)
    INOUT    win_keyval                key value (integer)

int MPI_Win_free_keyval(int *win_keyval)

MPI_WIN_FREE_KEYVAL(WIN_KEYVAL, IERROR)
    INTEGER WIN_KEYVAL, IERROR

MPI_Win_free_keyval(win_keyval, ierror)
    INTEGER, INTENT(INOUT) :: win_keyval
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{static void MPI::Win::Free_keyval(int& win_keyval) (binding deprecated, see
    Section 15.2) }

MPI_WIN_SET_ATTR(win, win_keyval, attribute_val)
    INOUT    win                        window to which attribute will be attached (handle)
    IN       win_keyval                key value (integer)
    IN       attribute_val             attribute value

int MPI_Win_set_attr(MPI_Win win, int win_keyval, void *attribute_val)

MPI_WIN_SET_ATTR(WIN, WIN_KEYVAL, ATTRIBUTE_VAL, IERROR)
    INTEGER WIN, WIN_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL

MPI_Win_set_attr(win, win_keyval, attribute_val, ierror)
    TYPE(MPI_Win), INTENT(IN) :: win
    INTEGER, INTENT(IN) :: win_keyval
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: attribute_val
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Win::Set_attr(int win_keyval, const void* attribute_val) (binding
    deprecated, see Section 15.2) }

MPI_WIN_GET_ATTR(win, win_keyval, attribute_val, flag)
    IN       win                        window to which the attribute is attached (handle)
    IN       win_keyval                key value (integer)
    OUT      attribute_val             attribute value, unless flag = false
    OUT      flag                      false if no attribute is associated with the key (logical)

int MPI_Win_get_attr(MPI_Win win, int win_keyval, void *attribute_val,
    int *flag)

MPI_WIN_GET_ATTR(WIN, WIN_KEYVAL, ATTRIBUTE_VAL, FLAG, IERROR)

```

```

1      INTEGER WIN, WIN_KEYVAL, IERROR
2      INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL
3      LOGICAL FLAG
4
5      MPI_Win_get_attr(win, win_keyval, attribute_val, flag, ierror)
6          TYPE(MPI_Win), INTENT(IN) :: win
7          INTEGER, INTENT(IN) :: win_keyval
8          INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: attribute_val
9          LOGICAL, INTENT(OUT) :: flag
10         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
11
12     {bool MPI::Win::Get_attr(int win_keyval, void* attribute_val) const(binding
13         deprecated, see Section 15.2) }
14
15     MPI_WIN_DELETE_ATTR(win, win_keyval)
16
17     INOUT    win                window from which the attribute is deleted (handle)
18     IN       win_keyval         key value (integer)
19
20     int MPI_Win_delete_attr(MPI_Win win, int win_keyval)
21
22     MPI_WIN_DELETE_ATTR(WIN, WIN_KEYVAL, IERROR)
23         INTEGER WIN, WIN_KEYVAL, IERROR
24
25     MPI_Win_delete_attr(win, win_keyval, ierror)
26         TYPE(MPI_Win), INTENT(IN) :: win
27         INTEGER, INTENT(IN) :: win_keyval
28         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
29
30     {void MPI::Win::Delete_attr(int win_keyval)(binding deprecated, see Section 15.2)
31         }
32
33
34
35
36
37
38
39
40
41
42
43
44
45
46
47
48

```

#### 6.7.4 Datatypes

The new functions for caching on datatypes are:

```

37     MPI_TYPE_CREATE_KEYVAL(type_copy_attr_fn, type_delete_attr_fn, type_keyval, extra_state)
38
39     IN          type_copy_attr_fn        copy callback function for type_keyval (function)
40     IN          type_delete_attr_fn      delete callback function for type_keyval (function)
41     OUT         type_keyval              key value for future access (integer)
42     IN          extra_state               extra state for callback functions
43
44
45     int MPI_Type_create_keyval(MPI_Type_copy_attr_function *type_copy_attr_fn,
46         MPI_Type_delete_attr_function *type_delete_attr_fn,
47         int *type_keyval, void *extra_state)
48

```



```

MPI_TYPE_CREATE_KEYVAL(TYPE_COPY_ATTR_FN, TYPE_DELETE_ATTR_FN, TYPE_KEYVAL,
    EXTRA_STATE, IERROR)
    EXTERNAL TYPE_COPY_ATTR_FN, TYPE_DELETE_ATTR_FN
    INTEGER TYPE_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE

```

```

MPI_Type_create_keyval(type_copy_attr_fn, type_delete_attr_fn, type_keyval,
    extra_state, ierror)
    PROCEDURE(MPI_Type_copy_attr_function) :: type_copy_attr_fn
    PROCEDURE(MPI_Type_delete_attr_function) :: type_delete_attr_fn
    INTEGER, INTENT(OUT) :: type_keyval
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: extra_state
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{static int MPI::Datatype::Create_keyval(MPI::Datatype::Copy_attr_function*
    type_copy_attr_fn, MPI::Datatype::Delete_attr_function*
    type_delete_attr_fn, void* extra_state) (binding deprecated, see
    Section 15.2) }

```

The argument `type_copy_attr_fn` may be specified as `MPI_TYPE_NULL_COPY_FN` or `MPI_TYPE_DUP_FN` from either C, C++, or Fortran. `MPI_TYPE_NULL_COPY_FN` is a function that does nothing other than returning `flag = 0` and `MPI_SUCCESS`. `MPI_TYPE_DUP_FN` is a simple-minded copy function that sets `flag = 1`, returns the value of `attribute_val_in` in `attribute_val_out`, and returns `MPI_SUCCESS`.

The argument `type_delete_attr_fn` may be specified as `MPI_TYPE_NULL_DELETE_FN` from either C, C++, or Fortran. `MPI_TYPE_NULL_DELETE_FN` is a function that does nothing, other than returning `MPI_SUCCESS`.

The C callback functions are:

```

typedef int MPI_Type_copy_attr_function(MPI_Datatype oldtype,
    int type_keyval, void *extra_state, void *attribute_val_in,
    void *attribute_val_out, int *flag);

```

and

```

typedef int MPI_Type_delete_attr_function(MPI_Datatype datatype,
    int type_keyval, void *attribute_val, void *extra_state);

```

With the `mpi` module and `mpif.h`, the Fortran callback functions are:

```

SUBROUTINE TYPE_COPY_ATTR_FUNCTION(OLDTYPE, TYPE_KEYVAL, EXTRA_STATE,
    ATTRIBUTE_VAL_IN, ATTRIBUTE_VAL_OUT, FLAG, IERROR)
    INTEGER OLDTYPE, TYPE_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE,
        ATTRIBUTE_VAL_IN, ATTRIBUTE_VAL_OUT
    LOGICAL FLAG

```

and

```

SUBROUTINE TYPE_DELETE_ATTR_FUNCTION(DATATYPE, TYPE_KEYVAL, ATTRIBUTE_VAL,
    EXTRA_STATE, IERROR)
    INTEGER DATATYPE, TYPE_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL, EXTRA_STATE

```

ticket230-B. <sup>1</sup> With the `mpi_f08` module, the Fortran callback functions are:

ticket-248T. <sup>2</sup>

```

3 ABSTRACT INTERFACE
4   SUBROUTINE MPI_Type_copy_attr_function(oldtype, type_keyval, extra_state,
5     attribute_val_in, attribute_val_out, flag, ierror)
6     TYPE(MPI_Datatype) :: oldtype
7     INTEGER :: type_keyval, ierror
8     INTEGER(KIND=MPI_ADDRESS_KIND) :: extra_state, attribute_val_in,
9     attribute_val_out
10    LOGICAL flag

```

ticket230-B. <sup>11</sup> and

ticket-248T. <sup>12</sup>

```

13 ABSTRACT INTERFACE
14   SUBROUTINE MPI_Type_delete_attr_function(datatype, type_keyval,
15     attribute_val, extra_state, ierror)
16     TYPE(MPI_Datatype) :: datatype
17     INTEGER :: type_keyval, ierror
18     INTEGER(KIND=MPI_ADDRESS_KIND) :: attribute_val, extra_state

```

<sup>19</sup> The C++ callbacks are:

```

20 {typedef int
21
22     MPI::Datatype::Copy_attr_function(const MPI::Datatype& oldtype,
23     int type_keyval, void* extra_state,
24     const void* attribute_val_in, void* attribute_val_out,
25     bool& flag); (binding deprecated, see Section 15.2)}

```

<sup>26</sup> and

ticket252-W. <sup>27</sup>

```

28 {typedef int MPI::Datatype::Delete_attr_function(MPI::Datatype& datatype,
29     int type_keyval, void* attribute_val, void* extra_state);
30     (binding deprecated, see Section 15.2)}

```

<sup>31</sup> If an attribute copy function or attribute delete function returns other than

<sup>32</sup> `MPI_SUCCESS`, then the call that caused it to be invoked (for example, `MPI_TYPE_FREE`),

<sup>33</sup> is erroneous.

<sup>34</sup>

```

35 MPI_TYPE_FREE_KEYVAL(type_keyval)
36
37     INOUT    type_keyval                key value (integer)

```

<sup>38</sup>

```

39 int MPI_Type_free_keyval(int *type_keyval)
40
41 MPI_TYPE_FREE_KEYVAL(TYPE_KEYVAL, IERROR)
42     INTEGER TYPE_KEYVAL, IERROR

```

ticket-248T. <sup>43</sup>

```

44 MPI_Type_free_keyval(type_keyval, ierror)
45     INTEGER, INTENT(INOUT) :: type_keyval
46     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

<sup>47</sup> {static void MPI::Datatype::Free\_keyval(int& type\_keyval) (*binding deprecated,*

<sup>48</sup> *see Section 15.2*) }

```

MPI_TYPE_SET_ATTR(datatype, type_keyval, attribute_val)
    INOUT    [ticket252-W.]datatype      datatype to which attribute will be attached (handle)
    IN       type_keyval                  key value (integer)
    IN       attribute_val                attribute value

```

```

int MPI_Type_set_attr(MPI_Datatype datatype, int type_keyval,
    void *attribute_val)

```

```

MPI_TYPE_SET_ATTR(DATATYPE, TYPE_KEYVAL, ATTRIBUTE_VAL, IERROR)
    INTEGER DATATYPE, TYPE_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL

```

```

MPI_Type_set_attr(datatype, type_keyval, attribute_val, ierror)
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    INTEGER, INTENT(IN) :: type_keyval
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: attribute_val
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{void MPI::Datatype::Set_attr(int type_keyval, const void*
    attribute_val) (binding deprecated, see Section 15.2) }

```

```

MPI_TYPE_GET_ATTR(datatype, type_keyval, attribute_val, flag)
    IN      [ticket252-W.]datatype      datatype to which the attribute is attached (handle)
    IN      type_keyval                  key value (integer)
    OUT     attribute_val                attribute value, unless flag = false
    OUT     flag                         false if no attribute is associated with the key (logical)

```

```

int MPI_Type_get_attr(MPI_Datatype datatype, int type_keyval, void
    *attribute_val, int *flag)

```

```

MPI_TYPE_GET_ATTR(DATATYPE, TYPE_KEYVAL, ATTRIBUTE_VAL, FLAG, IERROR)
    INTEGER DATATYPE, TYPE_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL
    LOGICAL FLAG

```

```

MPI_Type_get_attr(datatype, type_keyval, attribute_val, flag, ierror)
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    INTEGER, INTENT(IN) :: type_keyval
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: attribute_val
    LOGICAL, INTENT(OUT) :: flag
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{bool MPI::Datatype::Get_attr(int type_keyval, void* attribute_val)
    const (binding deprecated, see Section 15.2) }

```

```

ticket252-W. 1 MPI_TYPE_DELETE_ATTR(datatype, type_keyval)
2
3 INOUT [ticket252-W.]datatype datatype from which the attribute is deleted (handle)
4 IN type_keyval key value (integer)
5

```

```

ticket252-W. 6 int MPI_Type_delete_attr(MPI_Datatype datatype, int type_keyval)
7

```

```

ticket252-W. 8 MPI_TYPE_DELETE_ATTR(DATATYPE, TYPE_KEYVAL, IERROR)
9

```

```

ticket252-W. 9 INTEGER DATATYPE, TYPE_KEYVAL, IERROR
10

```

```

ticket-248T. 10 MPI_Type_delete_attr(datatype, type_keyval, ierror)
11

```

```

11 TYPE(MPI_Datatype), INTENT(IN) :: datatype
12

```

```

12 INTEGER, INTENT(IN) :: type_keyval
13

```

```

13 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
14

```

```

14 {void MPI::Datatype::Delete_attr(int type_keyval) (binding deprecated, see
15 Section 15.2) }
16

```

### 6.7.5 Error Class for Invalid Keyval

Key values for attributes are system-allocated, by `MPI_{TYPE,COMM,WIN}_CREATE_KEYVAL`. Only such values can be passed to the functions that use key values as input arguments. In order to signal that an erroneous key value has been passed to one of these functions, there is a new MPI error class: `MPI_ERR_KEYVAL`. It can be returned by `MPI_ATTR_PUT`, `MPI_ATTR_GET`, `MPI_ATTR_DELETE`, `MPI_KEYVAL_FREE`, `MPI_{TYPE,COMM,WIN}_DELETE_ATTR`, `MPI_{TYPE,COMM,WIN}_SET_ATTR`, `MPI_{TYPE,COMM,WIN}_GET_ATTR`, `MPI_{TYPE,COMM,WIN}_FREE_KEYVAL`, `MPI_COMM_DUP`, `MPI_COMM_DISCONNECT`, and `MPI_COMM_FREE`. The last three are included because `keyval` is an argument to the copy and delete functions for attributes.

### 6.7.6 Attributes Example

*Advice to users.* This example shows how to write a collective communication operation that uses caching to be more efficient after the first call. The coding style assumes that MPI function results return only error statuses. (*End of advice to users.*)

```

35 /* key for this module's stuff: */
36 static int gop_key = MPI_KEYVAL_INVALID;
37
38 typedef struct
39 {
40     int ref_count;          /* reference count */
41     /* other stuff, whatever else we want */
42 } gop_stuff_type;
43
44 Efficient_Collective_Op (comm, ...)
45 MPI_Comm comm;
46 {
47     gop_stuff_type *gop_stuff;
48     MPI_Group      group;

```

```

int                foundflag;
1
2
MPI_Comm_group(comm, &group);
3
4
if (gop_key == MPI_KEYVAL_INVALID) /* get a key on first call ever */
5
{
6
    if ( ! MPI_Comm_create_keyval( gop_stuff_copier,
7
                                   gop_stuff_destructor,
8
                                   &gop_key, (void *)0));
9
    /* get the key while assigning its copy and delete callback
10
       behavior. */
11
12
    MPI_Abort (comm, 99);
13
}
14
15
MPI_Comm_get_attr (comm, gop_key, &gop_stuff, &foundflag);
16
if (foundflag)
17
{ /* This module has executed in this group before.
18
   We will use the cached information */
19
}
20
else
21
{ /* This is a group that we have not yet cached anything in.
22
   We will now do so.
23
   */
24
25
    /* First, allocate storage for the stuff we want,
26
       and initialize the reference count */
27
28
    gop_stuff = (gop_stuff_type *) malloc (sizeof(gop_stuff_type));
29
    if (gop_stuff == NULL) { /* abort on out-of-memory error */ }
30
31
    gop_stuff -> ref_count = 1;
32
33
    /* Second, fill in *gop_stuff with whatever we want.
34
       This part isn't shown here */
35
36
    /* Third, store gop_stuff as the attribute value */
37
    MPI_Comm_set_attr ( comm, gop_key, gop_stuff);
38
}
39
/* Then, in any case, use contents of *gop_stuff
40
   to do the global op ... */
41
}
42
43
/* The following routine is called by MPI when a group is freed */
44
45
gop_stuff_destructor (comm, keyval, gop_stuff, extra)
46
MPI_Comm comm;
47
int keyval;
48

```

```

1      gop_stuff_type *gop_stuff;
2      void *extra;
3      {
4          if (keyval != gop_key) { /* abort -- programming error */ }
5
6          /* The group's being freed removes one reference to gop_stuff */
7          gop_stuff -> ref_count -= 1;
8
9          /* If no references remain, then free the storage */
10         if (gop_stuff -> ref_count == 0) {
11             free((void *)gop_stuff);
12         }
13     }
14
15     /* The following routine is called by MPI when a group is copied */
16     gop_stuff_copier (comm, keyval, extra, gop_stuff_in, gop_stuff_out, flag)
17     MPI_Comm comm;
18     int keyval;
19     gop_stuff_type *gop_stuff_in, *gop_stuff_out;
20     void *extra;
21     {
22         if (keyval != gop_key) { /* abort -- programming error */ }
23
24         /* The new group adds one reference to this gop_stuff */
25         gop_stuff -> ref_count += 1;
26         gop_stuff_out = gop_stuff_in;
27     }
28
29
30

```

## 6.8 Naming Objects

There are many occasions on which it would be useful to allow a user to associate a printable identifier with an MPI communicator, window, or datatype, for instance error reporting, debugging, and profiling. The names attached to opaque objects do not propagate when the object is duplicated or copied by MPI routines. For communicators this can be achieved using the following two functions.

**MPI\_COMM\_SET\_NAME** (comm, comm\_name)

INOUT	comm	communicator whose identifier is to be set (handle)
IN	comm_name	the character string which is remembered as the name (string)

int MPI\_Comm\_set\_name(MPI\_Comm comm, char \*comm\_name)

MPI\_COMM\_SET\_NAME(COMM, COMM\_NAME, IERROR)

INTEGER COMM, IERROR

CHARACTER\*(\*) COMM\_NAME

ticket-248T.

```

MPI_Comm_set_name(comm, comm_name, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm
    CHARACTER(LEN=*), INTENT(IN) :: comm_name
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{void MPI::Comm::Set_name(const char* comm_name) (binding deprecated, see
    Section 15.2) }

```

MPI\_COMM\_SET\_NAME allows a user to associate a name string with a communicator. The character string which is passed to MPI\_COMM\_SET\_NAME will be saved inside the MPI library (so it can be freed by the caller immediately after the call, or allocated on the stack). Leading spaces in name are significant but trailing ones are not.

MPI\_COMM\_SET\_NAME is a local (non-collective) operation, which only affects the name of the communicator as seen in the process which made the MPI\_COMM\_SET\_NAME call. There is no requirement that the same (or any) name be assigned to a communicator in every process where it exists.

*Advice to users.* Since MPI\_COMM\_SET\_NAME is provided to help debug code, it is sensible to give the same name to a communicator in all of the processes where it exists, to avoid confusion. (*End of advice to users.*)

The length of the name which can be stored is limited to the value of MPI\_MAX\_OBJECT\_NAME in Fortran and MPI\_MAX\_OBJECT\_NAME-1 in C and C++ to allow for the null terminator. Attempts to put names longer than this will result in truncation of the name. MPI\_MAX\_OBJECT\_NAME must have a value of at least 64.

*Advice to users.* Under circumstances of store exhaustion an attempt to put a name of any length could fail, therefore the value of MPI\_MAX\_OBJECT\_NAME should be viewed only as a strict upper bound on the name length, not a guarantee that setting names of less than this length will always succeed. (*End of advice to users.*)

*Advice to implementors.* Implementations which pre-allocate a fixed size space for a name should use the length of that allocation as the value of MPI\_MAX\_OBJECT\_NAME. Implementations which allocate space for the name from the heap should still define MPI\_MAX\_OBJECT\_NAME to be a relatively small value, since the user has to allocate space for a string of up to this size when calling MPI\_COMM\_GET\_NAME. (*End of advice to implementors.*)

```

MPI_COMM_GET_NAME (comm, comm_name, resultlen)

```

IN	comm	communicator whose name is to be returned (handle)
OUT	comm_name	the name previously stored on the communicator, or an empty string if no such name exists (string)
OUT	resultlen	length of returned name (integer)

```

int MPI_Comm_get_name(MPI_Comm comm, char *comm_name, int *resultlen)

```

```

MPI_COMM_GET_NAME(COMM, COMM_NAME, RESULTLEN, IERROR)

```

```

1      INTEGER COMM, RESULTLEN, IERROR
2      CHARACTER*(*) COMM_NAME
3
4      MPI_Comm_get_name(comm, comm_name, resultlen, ierror)
5      TYPE(MPI_Comm), INTENT(IN) :: comm
6      CHARACTER(LEN=*), INTENT(OUT) :: comm_name
7      INTEGER, INTENT(OUT) :: resultlen
8      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
9
10     {void MPI::Comm::Get_name(char* comm_name, int& resultlen) const(binding
11                                     deprecated, see Section 15.2) }

```

MPI\_COMM\_GET\_NAME returns the last name which has previously been associated with the given communicator. The name may be set and got from any language. The same name will be returned independent of the language used. `name` should be allocated so that it can hold a resulting string of length MPI\_MAX\_OBJECT\_NAME characters.

MPI\_COMM\_GET\_NAME returns a copy of the set name in `name`.

In C, a null character is additionally stored at `name[resultlen]`. `resultlen` cannot be larger than MPI\_MAX\_OBJECT\_NAME-1. In Fortran, `name` is padded on the right with blank characters. `resultlen` cannot be larger than MPI\_MAX\_OBJECT\_NAME.

If the user has not associated a name with a communicator, or an error occurs, MPI\_COMM\_GET\_NAME will return an empty string (all spaces in Fortran, "" in C and C++). The three predefined communicators will have predefined names associated with them. Thus, the names of MPI\_COMM\_WORLD, MPI\_COMM\_SELF, and the communicator returned by MPI\_COMM\_GET\_PARENT (if not MPI\_COMM\_NULL) will have the default of MPI\_COMM\_WORLD, MPI\_COMM\_SELF, and MPI\_COMM\_PARENT. The fact that the system may have chosen to give a default name to a communicator does not prevent the user from setting a name on the same communicator; doing this removes the old name and assigns the new one.

*Rationale.* We provide separate functions for setting and getting the name of a communicator, rather than simply providing a predefined attribute key for the following reasons:

- It is not, in general, possible to store a string as an attribute from Fortran.
- It is not easy to set up the delete function for a string attribute unless it is known to have been allocated from the heap.
- To make the attribute key useful additional code to call `strdup` is necessary. If this is not standardized then users have to write it. This is extra unneeded work which we can easily eliminate.
- The Fortran binding is not trivial to write (it will depend on details of the Fortran compilation system), and will not be portable. Therefore it should be in the library rather than in user code.

*(End of rationale.)*

*Advice to users.* The above definition means that it is safe simply to print the string returned by MPI\_COMM\_GET\_NAME, as it is always a valid string even if there was no name.



Note that associating a name with a communicator has no effect on the semantics of an MPI program, and will (necessarily) increase the store requirement of the program, since the names must be saved. Therefore there is no requirement that users use these functions to associate names with communicators. However debugging and profiling MPI applications may be made easier if names are associated with communicators, since the debugger or profiler should then be able to present information in a less cryptic manner. (*End of advice to users.*)

The following functions are used for setting and getting names of datatypes.

**MPI\_TYPE\_SET\_NAME** (*datatype*, *type\_name*)

INOUT	[ticket252-W.] <i>datatype</i>	datatype whose identifier is to be set (handle)
IN	<i>type_name</i>	the character string which is remembered as the name (string)

int MPI\_Type\_set\_name(MPI\_Datatype *datatype*, char \**type\_name*)

MPI\_TYPE\_SET\_NAME(DATATYPE, TYPE\_NAME, IERROR)

INTEGER DATATYPE, IERROR

CHARACTER\*(\*) TYPE\_NAME

*MPI\_Type\_set\_name(datatype, type\_name, ierror)*  
*TYPE(MPI\_Datatype), INTENT(IN) :: datatype*  
*CHARACTER(LEN=\*), INTENT(IN) :: type\_name*  
*INTEGER, OPTIONAL, INTENT(OUT) :: ierror*

{void MPI::Datatype::Set\_name(const char\* *type\_name*) (*binding deprecated, see Section 15.2*) }

**MPI\_TYPE\_GET\_NAME** (*datatype*, *type\_name*, *resultlen*)

IN	[ticket252-W.] <i>datatype</i>	datatype whose name is to be returned (handle)
OUT	<i>type_name</i>	the name previously stored on the datatype, or a empty string if no such name exists (string)
OUT	<i>resultlen</i>	length of returned name (integer)

int MPI\_Type\_get\_name(MPI\_Datatype *datatype*, char \**type\_name*, int \**resultlen*)

MPI\_TYPE\_GET\_NAME(DATATYPE, TYPE\_NAME, RESULTLEN, IERROR)

INTEGER DATATYPE, RESULTLEN, IERROR

CHARACTER\*(\*) TYPE\_NAME

*MPI\_Type\_get\_name(datatype, type\_name, resultlen, ierror)*  
*TYPE(MPI\_Datatype), INTENT(IN) :: datatype*  
*CHARACTER(LEN=\*), INTENT(OUT) :: type\_name*  
*INTEGER, INTENT(OUT) :: resultlen*

```

1      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
2
3      {void MPI::Datatype::Get_name(char* type_name, int& resultlen) const(binding
4          deprecated, see Section 15.2) }
```

Named predefined datatypes have the default names of the datatype name. For example, MPI\_WCHAR has the default name of MPI\_WCHAR.

The following functions are used for setting and getting names of windows.

MPI\_WIN\_SET\_NAME (win, win\_name)

INOUT	win	window whose identifier is to be set (handle)
IN	win_name	the character string which is remembered as the name (string)

```
int MPI_Win_set_name(MPI_Win win, char *win_name)
```

```
MPI_WIN_SET_NAME(WIN, WIN_NAME, IERROR)
```

```
    INTEGER WIN, IERROR
```

```
    CHARACTER*(*) WIN_NAME
```

```
MPI_Win_set_name(win, win_name, ierror)
```

```
    TYPE(MPI_Win), INTENT(IN) :: win
```

```
    CHARACTER(LEN=*), INTENT(IN) :: win_name
```

```
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```

{void MPI::Win::Set_name(const char* win_name) (binding deprecated, see
    Section 15.2) }
```

MPI\_WIN\_GET\_NAME (win, win\_name, resultlen)

IN	win	window whose name is to be returned (handle)
OUT	win_name	the name previously stored on the window, or a empty string if no such name exists (string)
OUT	resultlen	length of returned name (integer)

```
int MPI_Win_get_name(MPI_Win win, char *win_name, int *resultlen)
```

```
MPI_WIN_GET_NAME(WIN, WIN_NAME, RESULTLEN, IERROR)
```

```
    INTEGER WIN, RESULTLEN, IERROR
```

```
    CHARACTER*(*) WIN_NAME
```

```
MPI_Win_get_name(win, win_name, resultlen, ierror)
```

```
    TYPE(MPI_Win), INTENT(IN) :: win
```

```
    CHARACTER(LEN=*), INTENT(OUT) :: win_name
```

```
    INTEGER, INTENT(OUT) :: resultlen
```

```
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Win::Get_name(char* win_name, int& resultlen) const(binding
    deprecated, see Section 15.2) }
```

## 6.9 Formalizing the Loosely Synchronous Model

In this section, we make further statements about the loosely synchronous model, with particular attention to intra-communication.

### 6.9.1 Basic Statements

When a caller passes a communicator (that contains a context and group) to a callee, that communicator must be free of side effects throughout execution of the subprogram: there should be no active operations on that communicator that might involve the process. This provides one model in which libraries can be written, and work “safely.” For libraries so designated, the callee has permission to do whatever communication it likes with the communicator, and under the above guarantee knows that no other communications will interfere. Since we permit good implementations to create new communicators without synchronization (such as by preallocated contexts on communicators), this does not impose a significant overhead.

This form of safety is analogous to other common computer-science usages, such as passing a descriptor of an array to a library routine. The library routine has every right to expect such a descriptor to be valid and modifiable.

### 6.9.2 Models of Execution

In the loosely synchronous model, transfer of control to a **parallel procedure** is effected by having each executing process invoke the procedure. The invocation is a collective operation: it is executed by all processes in the execution group, and invocations are similarly ordered at all processes. However, the invocation need not be synchronized.

We say that a parallel procedure is *active* in a process if the process belongs to a group that may collectively execute the procedure, and some member of that group is currently executing the procedure code. If a parallel procedure is active in a process, then this process may be receiving messages pertaining to this procedure, even if it does not currently execute the code of this procedure.

#### Static communicator allocation

This covers the case where, at any point in time, at most one invocation of a parallel procedure can be active at any process, and the group of executing processes is fixed. For example, all invocations of parallel procedures involve all processes, processes are single-threaded, and there are no recursive invocations.

In such a case, a communicator can be statically allocated to each procedure. The static allocation can be done in a preamble, as part of initialization code. If the parallel procedures can be organized into libraries, so that only one procedure of each library can be concurrently active in each processor, then it is sufficient to allocate one communicator per library.

## Dynamic communicator allocation

Calls of parallel procedures are well-nested if a new parallel procedure is always invoked in a subset of a group executing the same parallel procedure. Thus, processes that execute the same parallel procedure have the same execution stack.

In such a case, a new communicator needs to be dynamically allocated for each new invocation of a parallel procedure. The allocation is done by the caller. A new communicator can be generated by a call to `MPI_COMM_DUP`, if the callee execution group is identical to the caller execution group, or by a call to `MPI_COMM_SPLIT` if the caller execution group is split into several subgroups executing distinct parallel routines. The new communicator is passed as an argument to the invoked routine.

The need for generating a new communicator at each invocation can be alleviated or avoided altogether in some cases: If the execution group is not split, then one can allocate a stack of communicators in a preamble, and next manage the stack in a way that mimics the stack of recursive calls.

One can also take advantage of the well-ordering property of communication to avoid confusing caller and callee communication, even if both use the same communicator. To do so, one needs to abide by the following two rules:

- messages sent before a procedure call (or before a return from the procedure) are also received before the matching call (or return) at the receiving end;
- messages are always selected by source (no use is made of `MPI_ANY_SOURCE`).

## The General Case

In the general case, there may be multiple concurrently active invocations of the same parallel procedure within the same group; invocations may not be well-nested. A new communicator needs to be created for each invocation. It is the user's responsibility to make sure that, should two distinct parallel procedures be invoked concurrently on overlapping sets of processes, then communicator creation be properly coordinated.

# Chapter 7

## Process Topologies

### 7.1 Introduction

This chapter discusses the MPI topology mechanism. A topology is an extra, optional attribute that one can give to an intra-communicator; topologies cannot be added to inter-communicators. A topology can provide a convenient naming mechanism for the processes of a group (within a communicator), and additionally, may assist the runtime system in mapping the processes onto hardware.

As stated in Chapter 6, a process group in MPI is a collection of  $n$  processes. Each process in the group is assigned a rank between 0 and  $n-1$ . In many parallel applications a linear ranking of processes does not adequately reflect the logical communication pattern of the processes (which is usually determined by the underlying problem geometry and the numerical algorithm used). Often the processes are arranged in topological patterns such as two- or three-dimensional grids. More generally, the logical process arrangement is described by a graph. In this chapter we will refer to this logical process arrangement as the “virtual topology.”

A clear distinction must be made between the virtual process topology and the topology of the underlying, physical hardware. The virtual topology can be exploited by the system in the assignment of processes to physical processors, if this helps to improve the communication performance on a given machine. How this mapping is done, however, is outside the scope of MPI. The description of the virtual topology, on the other hand, depends only on the application, and is machine-independent. The functions that are described in this chapter deal only with machine-independent mapping.

*Rationale.* Though physical mapping is not discussed, the existence of the virtual topology information may be used as advice by the runtime system. There are well-known techniques for mapping grid/torus structures to hardware topologies such as hypercubes or grids. For more complicated graph structures good heuristics often yield nearly optimal results [39]. On the other hand, if there is no way for the user to specify the logical process arrangement as a “virtual topology,” a random mapping is most likely to result. On some machines, this will lead to unnecessary contention in the interconnection network. Some details about predicted and measured performance improvements that result from good process-to-processor mapping on modern wormhole-routing architectures can be found in [10, 11].

Besides possible performance benefits, the virtual topology can function as a convenient, process-naming structure, with significant benefits for program readability and

notational power in message-passing programming. (*End of rationale.*)

## 7.2 Virtual Topologies

The communication pattern of a set of processes can be represented by a graph. The nodes represent processes, and the edges connect processes that communicate with each other. MPI provides message-passing between any pair of processes in a group. There is no requirement for opening a channel explicitly. Therefore, a “missing link” in the user-defined process graph does not prevent the corresponding processes from exchanging messages. It means rather that this connection is neglected in the virtual topology. This strategy implies that the topology gives no convenient way of naming this pathway of communication. Another possible consequence is that an automatic mapping tool (if one exists for the runtime environment) will not take account of this edge when mapping.

Specifying the virtual topology in terms of a graph is sufficient for all applications. However, in many applications the graph structure is regular, and the detailed set-up of the graph would be inconvenient for the user and might be less efficient at run time. A large fraction of all parallel applications use process topologies like rings, two- or higher-dimensional grids, or tori. These structures are completely defined by the number of dimensions and the numbers of processes in each coordinate direction. Also, the mapping of grids and tori is generally an easier problem than that of general graphs. Thus, it is desirable to address these cases explicitly.

Process coordinates in a Cartesian structure begin their numbering at 0. Row-major numbering is always used for the processes in a Cartesian structure. This means that, for example, the relation between group rank and coordinates for four processes in a  $(2 \times 2)$  grid is as follows.

```
coord (0,0):  rank 0
coord (0,1):  rank 1
coord (1,0):  rank 2
coord (1,1):  rank 3
```

## 7.3 Embedding in MPI

The support for virtual topologies as defined in this chapter is consistent with other parts of MPI, and, whenever possible, makes use of functions that are defined elsewhere. Topology information is associated with communicators. It is added to communicators using the caching mechanism described in Chapter 6.

## 7.4 Overview of the Functions

The functions `MPI_GRAPH_CREATE`, `MPI_DIST_GRAPH_CREATE_ADJACENT`, `MPI_DIST_GRAPH_CREATE` and `MPI_CART_CREATE` are used to create general (graph) virtual topologies and Cartesian topologies, respectively. These topology creation functions are collective. As with other collective calls, the program must be written to work correctly, whether the call synchronizes or not.

The topology creation functions take as input an existing communicator `comm_old`, which defines the set of processes on which the topology is to be mapped. For

MPI\_GRAPH\_CREATE and MPI\_CART\_CREATE, all input arguments must have identical values on all processes of the group of `comm_old`. For MPI\_DIST\_GRAPH\_CREATE\_ADJACENT and MPI\_DIST\_GRAPH\_CREATE the input communication graph is distributed across the calling processes. Therefore the processes provide different values for the arguments specifying the graph. However, all processes must give the same value for `reorder` and the `info` argument. In all cases, a new communicator `comm_topol` is created that carries the topological structure as cached information (see Chapter 6). In analogy to function MPI\_COMM\_CREATE, no cached information propagates from `comm_old` to `comm_topol`.

MPI\_CART\_CREATE can be used to describe Cartesian structures of arbitrary dimension. For each coordinate direction one specifies whether the process structure is periodic or not. Note that an  $n$ -dimensional hypercube is an  $n$ -dimensional torus with 2 processes per coordinate direction. Thus, special support for hypercube structures is not necessary. The local auxiliary function MPI\_DIMS\_CREATE can be used to compute a balanced distribution of processes among a given number of dimensions.

*Rationale.* Similar functions are contained in EXPRESS [12] and PARMACS. (*End of rationale.*)

The function MPI\_TOPO\_TEST can be used to inquire about the topology associated with a communicator. The topological information can be extracted from the communicator using the functions MPI\_GRAPHDIMS\_GET and MPI\_GRAPH\_GET, for general graphs, and MPI\_CARTDIM\_GET and MPI\_CART\_GET, for Cartesian topologies. Several additional functions are provided to manipulate Cartesian topologies: the functions MPI\_CART\_RANK and MPI\_CART\_COORDS translate Cartesian coordinates into a group rank, and vice-versa; the function MPI\_CART\_SUB can be used to extract a Cartesian subspace (analogous to MPI\_COMM\_SPLIT). The function MPI\_CART\_SHIFT provides the information needed to communicate with neighbors in a Cartesian dimension. The two functions MPI\_GRAPH\_NEIGHBORS\_COUNT and MPI\_GRAPH\_NEIGHBORS can be used to extract the neighbors of a node in a graph. For distributed graphs, the functions MPI\_DIST\_NEIGHBORS\_COUNT and MPI\_DIST\_NEIGHBORS can be used to extract the neighbors of the calling node. The function MPI\_CART\_SUB is collective over the input communicator's group; all other functions are local.

Two additional functions, MPI\_GRAPH\_MAP and MPI\_CART\_MAP are presented in the last section. In general these functions are not called by the user directly. However, together with the communicator manipulation functions presented in Chapter 6, they are sufficient to implement all other topology functions. Section 7.5.8 outlines such an implementation.

## 7.5 Topology Constructors

### 7.5.1 Cartesian Constructor

```

MPI_CART_CREATE(comm_old, ndims, dims, periods, reorder, comm_cart)

    IN      comm_old      input communicator (handle)
    IN      ndims         number of dimensions of Cartesian grid (integer)
    IN      dims          integer array of size ndims specifying the number of
                           processes in each dimension
    IN      periods       logical array of size ndims specifying whether the grid
                           is periodic (true) or not (false) in each dimension
    IN      reorder       ranking may be reordered (true) or not (false) (logical)
    OUT     comm_cart     communicator with new Cartesian topology (handle)

```

```

int MPI_Cart_create(MPI_Comm comm_old, int ndims, int *dims, int *periods,
                   int reorder, MPI_Comm *comm_cart)

```

```

MPI_CART_CREATE(COMM_OLD, NDIMS, DIMS, PERIODS, REORDER, COMM_CART, IERROR)
    INTEGER COMM_OLD, NDIMS, DIMS(*), COMM_CART, IERROR
    LOGICAL PERIODS(*), REORDER

```

```

MPI_Cart_create(comm_old, ndims, dims, periods, reorder, comm_cart, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm_old
    INTEGER, INTENT(IN) :: ndims, dims(*)
    LOGICAL, INTENT(IN) :: periods(*), reorder
    TYPE(MPI_Comm), INTENT(OUT) :: comm_cart
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{MPI::Cartcomm MPI::Intracomm::Create_cart(int ndims, const int dims[],
      const bool periods[], bool reorder) const (binding deprecated, see
      Section 15.2) }

```

MPI\_CART\_CREATE returns a handle to a new communicator to which the Cartesian topology information is attached. If `reorder = false` then the rank of each process in the new group is identical to its rank in the old group. Otherwise, the function may reorder the processes (possibly so as to choose a good embedding of the virtual topology onto the physical machine). If the total size of the Cartesian grid is smaller than the size of the group of `comm`, then some processes are returned MPI\_COMM\_NULL, in analogy to MPI\_COMM\_SPLIT. If `ndims` is zero then a zero-dimensional Cartesian topology is created. The call is erroneous if it specifies a grid that is larger than the group size or if `ndims` is negative.

### 7.5.2 Cartesian Convenience Function: MPI\_DIMS\_CREATE

For Cartesian topologies, the function MPI\_DIMS\_CREATE helps the user select a balanced distribution of processes per coordinate direction, depending on the number of processes in the group to be balanced and optional constraints that can be specified by the user.



One use is to partition all the processes (the size of MPI\_COMM\_WORLD's group) into an  $n$ -dimensional topology.

**MPI\_DIMS\_CREATE**(nnodes, ndims, dims)

IN        nnodes                      number of nodes in a grid (integer)  
 IN        ndims                      number of Cartesian dimensions (integer)  
 INOUT    dims                      integer array of size **ndims** specifying the number of  
    nodes in each dimension

int MPI\_Dims\_create(int nnodes, int ndims, int \*dims)

MPI\_DIMS\_CREATE(NNODES, NDIMS, DIMS, IERROR)

INTEGER NNODES, NDIMS, DIMS(\*), IERROR

**MPI\_Dims\_create**(nnodes, ndims, dims, ierror)

INTEGER, INTENT(IN) :: nnodes, ndims

INTEGER, INTENT(INOUT) :: dims(\*)

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Compute\_dims(int nnodes, int ndims, int dims[]) (*binding deprecated,*  
    *see Section 15.2*) }

The entries in the array **dims** are set to describe a Cartesian grid with **ndims** dimensions and a total of **nnodes** nodes. The dimensions are set to be as close to each other as possible, using an appropriate divisibility algorithm. The caller may further constrain the operation of this routine by specifying elements of array **dims**. If **dims[i]** is set to a positive number, the routine will not modify the number of nodes in dimension **i**; only those entries where **dims[i] = 0** are modified by the call.

Negative input values of **dims[i]** are erroneous. An error will occur if **nnodes** is not a multiple of  $\prod_{i, \text{dims}[i] \neq 0} \text{dims}[i]$ .

For **dims[i]** set by the call, **dims[i]** will be ordered in non-increasing order. Array **dims** is suitable for use as input to routine **MPI\_CART\_CREATE**. **MPI\_DIMS\_CREATE** is local.

#### Example 7.1

dims before call	function call	dims on return
(0,0)	MPI_DIMS_CREATE(6, 2, dims)	(3,2)
(0,0)	MPI_DIMS_CREATE(7, 2, dims)	(7,1)
(0,3,0)	MPI_DIMS_CREATE(6, 3, dims)	(2,3,1)
(0,3,0)	MPI_DIMS_CREATE(7, 3, dims)	erroneous call

### 7.5.3 General (Graph) Constructor

```

MPI_GRAPH_CREATE(comm_old, nnodes, index, edges, reorder, comm_graph)

    IN      comm_old      input communicator (handle)
    IN      nnodes        number of nodes in graph (integer)
    IN      index          array of integers describing node degrees (see below)
    IN      edges          array of integers describing graph edges (see below)
    IN      reorder        ranking may be reordered (true) or not (false) (logical)
    OUT     comm_graph     communicator with graph topology added (handle)

int MPI_Graph_create(MPI_Comm comm_old, int nnodes, int *index, int *edges,
                    int reorder, MPI_Comm *comm_graph)

MPI_GRAPH_CREATE(COMM_OLD, NNODES, INDEX, EDGES, REORDER, COMM_GRAPH,
                IERROR)
    INTEGER COMM_OLD, NNODES, INDEX(*), EDGES(*), COMM_GRAPH, IERROR
    LOGICAL REORDER

MPI_Graph_create(comm_old, nnodes, index, edges, reorder, comm_graph,
                ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm_old
    INTEGER, INTENT(IN) :: nnodes, index(*), edges(*)
    LOGICAL, INTENT(IN) :: reorder
    TYPE(MPI_Comm), INTENT(OUT) :: comm_graph
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{MPI::Graphcomm MPI::Intracomm::Create_graph(int nnodes, const int index[],
    const int edges[], bool reorder) const(binding deprecated, see
    Section 15.2) }
```

MPI\_GRAPH\_CREATE returns a handle to a new communicator to which the graph topology information is attached. If `reorder = false` then the rank of each process in the new group is identical to its rank in the old group. Otherwise, the function may reorder the processes. If the size, `nnodes`, of the graph is smaller than the size of the group of `comm`, then some processes are returned `MPI_COMM_NULL`, in analogy to `MPI_CART_CREATE` and `MPI_COMM_SPLIT`. If the graph is empty, i.e., `nnodes == 0`, then `MPI_COMM_NULL` is returned in all processes. The call is erroneous if it specifies a graph that is larger than the group size of the input communicator.

The three parameters `nnodes`, `index` and `edges` define the graph structure. `nnodes` is the number of nodes of the graph. The nodes are numbered from 0 to `nnodes-1`. The `i`-th entry of array `index` stores the total number of neighbors of the first `i` graph nodes. The lists of neighbors of nodes 0, 1, ..., `nnodes-1` are stored in consecutive locations in array `edges`. The array `edges` is a flattened representation of the edge lists. The total number of entries in `index` is `nnodes` and the total number of entries in `edges` is equal to the number of graph edges.

The definitions of the arguments `nnodes`, `index`, and `edges` are illustrated with the following simple example.

### Example 7.2

Assume there are four processes 0, 1, 2, 3 with the following adjacency matrix:

process	neighbors
0	1, 3
1	0
2	3
3	0, 2

Then, the input arguments are:

```
nnodes = 4
index = 2, 3, 4, 6
edges = 1, 3, 0, 3, 0, 2
```

Thus, in C, `index[0]` is the degree of node zero, and `index[i] - index[i-1]` is the degree of node `i`, `i=1, ..., nnodes-1`; the list of neighbors of node zero is stored in `edges[j]`, for  $0 \leq j \leq \text{index}[0] - 1$  and the list of neighbors of node `i`,  $i > 0$ , is stored in `edges[j]`,  $\text{index}[i-1] \leq j \leq \text{index}[i] - 1$ .

In Fortran, `index(1)` is the degree of node zero, and `index(i+1) - index(i)` is the degree of node `i`, `i=1, ..., nnodes-1`; the list of neighbors of node zero is stored in `edges(j)`, for  $1 \leq j \leq \text{index}(1)$  and the list of neighbors of node `i`,  $i > 0$ , is stored in `edges(j)`,  $\text{index}(i) + 1 \leq j \leq \text{index}(i + 1)$ .

A single process is allowed to be defined multiple times in the list of neighbors of a process (i.e., there may be multiple edges between two processes). A process is also allowed to be a neighbor to itself (i.e., a self loop in the graph). The adjacency matrix is allowed to be non-symmetric.

*Advice to users.* Performance implications of using multiple edges or a non-symmetric adjacency matrix are not defined. The definition of a node-neighbor edge does not imply a direction of the communication. (*End of advice to users.*)

*Advice to implementors.* The following topology information is likely to be stored with a communicator:

- Type of topology (Cartesian/graph),
- For a Cartesian topology:
  1. `ndims` (number of dimensions),
  2. `dims` (numbers of processes per coordinate direction),
  3. `periods` (periodicity information),
  4. `own_position` (own position in grid, could also be computed from rank and `dims`)
- For a graph topology:
  1. `index`,
  2. `edges`,

which are the vectors defining the graph structure.

For a graph structure the number of nodes is equal to the number of processes in the group. Therefore, the number of nodes does not have to be stored explicitly. An additional zero entry at the start of array `index` simplifies access to the topology information. (*End of advice to implementors.*)

#### 7.5.4 Distributed (Graph) Constructor

The general graph constructor assumes that each process passes the full (global) communication graph to the call. This limits the scalability of this constructor. With the distributed graph interface, the communication graph is specified in a fully distributed fashion. Each process specifies only the part of the communication graph of which it is aware. Typically, this could be the set of processes from which the process will eventually receive or get data, or the set of processes to which the process will send or put data, or some combination of such edges. Two different interfaces can be used to create a distributed graph topology. `MPI_DIST_GRAPH_CREATE_ADJACENT` creates a distributed graph communicator with each process specifying all of its incoming and outgoing (adjacent) edges in the logical communication graph and thus requires minimal communication during creation. `MPI_DIST_GRAPH_CREATE` provides full flexibility, and processes can indicate that communication will occur between other pairs of processes.

To provide better possibilities for optimization by the MPI library, the distributed graph constructors permit weighted communication edges and take an `info` argument that can further influence process reordering or other optimizations performed by the MPI library. For example, hints can be provided on how edge weights are to be interpreted, the quality of the reordering, and/or the time permitted for the MPI library to process the graph.

```
MPI_DIST_GRAPH_CREATE_ADJACENT(comm_old, indegree, sources, sourceweights, out-
    degree, destinations, destweights, info, reorder, comm_dist_graph)
```

IN	comm_old	input communicator (handle)
IN	indegree	size of sources and sourceweights arrays (non-negative integer)
IN	sources	ranks of processes for which the calling process is a destination (array of non-negative integers)
IN	sourceweights	weights of the edges into the calling process (array of non-negative integers)
IN	outdegree	size of destinations and destweights arrays (non-negative integer)
IN	destinations	ranks of processes for which the calling process is a source (array of non-negative integers)
IN	destweights	weights of the edges out of the calling process (array of non-negative integers)
IN	info	hints on optimization and interpretation of weights (handle)
IN	reorder	the ranks may be reordered (true) or not (false) (logical)
OUT	comm_dist_graph	communicator with distributed graph topology (handle)

```
int MPI_Dist_graph_create_adjacent(MPI_Comm comm_old, int indegree,
    int sources[], int sourceweights[], int outdegree,
    int destinations[], int destweights[], MPI_Info info,
    int reorder, MPI_Comm *comm_dist_graph)
```

```
MPI_DIST_GRAPH_CREATE_ADJACENT(COMM_OLD, INDEGREE, SOURCES, SOURCEWEIGHTS,
    OUTDEGREE, DESTINATIONS, DESTWEIGHTS, INFO, REORDER,
    COMM_DIST_GRAPH, IERROR)
```

```
INTEGER COMM_OLD, INDEGREE, SOURCES(*), SOURCEWEIGHTS(*), OUTDEGREE,
    DESTINATIONS(*), DESTWEIGHTS(*), INFO, COMM_DIST_GRAPH, IERROR
LOGICAL REORDER
```

```
MPI_Dist_graph_create_adjacent(comm_old, indegree, sources, sourceweights,
    outdegree, destinations, destweights, info, reorder,
    comm_dist_graph, ierror)
```

```
TYPE(MPI_Comm), INTENT(IN) :: comm_old
INTEGER, INTENT(IN) :: indegree, sources(*), outdegree,
destinations(*)
INTEGER, INTENT(IN) :: sourceweights(*) ! optional by overloading
INTEGER, INTENT(IN) :: destweights(*) ! optional by overloading
TYPE(MPI_Info), INTENT(IN) :: info
LOGICAL, INTENT(IN) :: reorder
TYPE(MPI_Comm), INTENT(OUT) :: comm_dist_graph
```

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```

1      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
2
3      {MPI::Distgraphcomm MPI::Intracomm::Dist_graph_create_adjacent(int
4          indegree, const int sources[], const int sourceweights[],
5          int outdegree, const int destinations[],
6          const int destweights[], const MPI::Info& info, bool reorder)
7          const(binding deprecated, see Section 15.2) }
8
9      {MPI::Distgraphcomm
10          MPI::Intracomm::Dist_graph_create_adjacent(int indegree,
11              const int sources[], int outdegree, const int destinations[],
12              const MPI::Info& info, bool reorder) const(binding deprecated, see
13                  Section 15.2) }

```

MPI\_DIST\_GRAPH\_CREATE\_ADJACENT returns a handle to a new communicator to which the distributed graph topology information is attached. Each process passes all information about the edges to its neighbors in the virtual distributed graph topology. The calling processes must ensure that each edge of the graph is described in the source and in the destination process with the same weights. If there are multiple edges for a given (source,dest) pair, then the sequence of the weights of these edges does not matter. The complete communication topology is the combination of all edges shown in the sources arrays of all processes in comm\_old, which must be identical to the combination of all edges shown in the destinations arrays. Source and destination ranks must be process ranks of comm\_old. This allows a fully distributed specification of the communication graph. Isolated processes (i.e., processes with no outgoing or incoming edges, that is, processes that have specified indegree and outdegree as zero and that thus do not occur as source or destination rank in the graph specification) are allowed.

The call creates a new communicator comm\_dist\_graph of distributed graph topology type to which topology information has been attached. The number of processes in comm\_dist\_graph is identical to the number of processes in comm\_old. The call to MPI\_DIST\_GRAPH\_CREATE\_ADJACENT is collective.

Weights are specified as non-negative integers and can be used to influence the process remapping strategy and other internal MPI optimizations. For instance, approximate count arguments of later communication calls along specific edges could be used as their edge weights. Multiplicity of edges can likewise indicate more intense communication between pairs of processes. However, the exact meaning of edge weights is not specified by the MPI standard and is left to the implementation. In C or in the Fortran **mpi module** or **mpif.h include file**, an application can supply the special value MPI\_UNWEIGHTED for the weight array to indicate that all edges have the same (effectively no) weight. In the Fortran **mpi\_f08 module** or in C++, this constant does not exist and the weight arguments may be omitted from the argument list.<sup>1</sup> It is erroneous to supply MPI\_UNWEIGHTED, or in **mpi\_f08** or C++ to omit the weight arrays, for some but not all processes of comm\_old. Note that MPI\_UNWEIGHTED is not a special weight value; rather it is a special value for the total array argument. In C, one would expect it to be NULL. In Fortran, MPI\_UNWEIGHTED is an object like MPI\_BOTTOM (not usable for initialization or assignment). See Section 2.5.4.

The meaning of the info and reorder arguments is defined in the description of the following routine.

---

<sup>1</sup>The Fortran generic interface must contain four specific routines with none, both, or only the sourceweight or destweight array is omitted, although in the C++ binding only two of them are provided.

```

MPI_DIST_GRAPH_CREATE(comm_old, n, sources, degrees, destinations, weights, info, re-
    order, comm_dist_graph)
IN      comm_old      input communicator (handle)
IN      n              number of source nodes for which this process specifies
                        edges (non-negative integer)
IN      sources        array containing the n source nodes for which this pro-
                        cess specifies edges (array of non-negative integers)
IN      degrees        array specifying the number of destinations for each
                        source node in the source node array (array of non-
                        negative integers)
IN      destinations   destination nodes for the source nodes in the source
                        node array (array of non-negative integers)
IN      weights        weights for source to destination edges (array of non-
                        negative integers)
IN      info           hints on optimization and interpretation of weights
                        (handle)
IN      reorder        the process may be reordered (true) or not (false) (log-
                        ical)
OUT     comm_dist_graph communicator with distributed graph topology added
                        (handle)

```

```

int MPI_Dist_graph_create(MPI_Comm comm_old, int n, int sources[],
    int degrees[], int destinations[], int weights[],
    MPI_Info info, int reorder, MPI_Comm *comm_dist_graph)

```

```

MPI_DIST_GRAPH_CREATE(COMM_OLD, N, SOURCES, DEGREES, DESTINATIONS, WEIGHTS,
    INFO, REORDER, COMM_DIST_GRAPH, IERROR)
INTEGER COMM_OLD, N, SOURCES(*), DEGREES(*), DESTINATIONS(*),
WEIGHTS(*), INFO, COMM_DIST_GRAPH, IERROR
LOGICAL REORDER

```

```

MPI_Dist_graph_create(comm_old, n, sources, degrees, destinations, weights,
    info, reorder, comm_dist_graph, ierror)
TYPE(MPI_Comm), INTENT(IN) :: comm_old
INTEGER, INTENT(IN) :: n, sources(*), degrees(*), destinations(*)
INTEGER, INTENT(IN) :: weights(*) ! optional by overloading
TYPE(MPI_Info), INTENT(IN) :: info
LOGICAL, INTENT(IN) :: reorder
TYPE(MPI_Comm), INTENT(OUT) :: comm_dist_graph
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{MPI::Distgraphcomm MPI::Intracomm::Dist_graph_create(int n,
    const int sources[], const int degrees[], const int
    destinations[], const int weights[], const MPI::Info& info,
    bool reorder) const(binding deprecated, see Section 15.2) }

```

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```

1 {MPI::Distgraphcomm MPI::Intracomm::Dist_graph_create(int n,
2               const int sources[], const int degrees[],
3               const int destinations[], const MPI::Info& info, bool reorder)
4               const(binding deprecated, see Section 15.2) }

```

MPI\_DIST\_GRAPH\_CREATE returns a handle to a new communicator to which the distributed graph topology information is attached. Concretely, each process calls the constructor with a set of directed (source,destination) communication edges as described below. Every process passes an array of *n* source nodes in the *sources* array. For each source node, a non-negative number of destination nodes is specified in the *degrees* array. The destination nodes are stored in the corresponding consecutive segment of the *destinations* array. More precisely, if the *i*-th node in *sources* is *s*, this specifies *degrees[i]* edges (*s,d*) with *d* of the *j*-th such edge stored in *destinations[degrees[0]+...+degrees[i-1]+j]*. The weight of this edge is stored in *weights[degrees[0]+...+degrees[i-1]+j]*. Both the *sources* and the *destinations* arrays may contain the same node more than once, and the order in which nodes are listed as destinations or sources is not significant. Similarly, different processes may specify edges with the same source and destination nodes. Source and destination nodes must be process ranks of *comm\_old*. Different processes may specify different numbers of source and destination nodes, as well as different source to destination edges. This allows a fully distributed specification of the communication graph. Isolated processes (i.e., processes with no outgoing or incoming edges, that is, processes that do not occur as source or destination node in the graph specification) are allowed.

The call creates a new communicator *comm\_dist\_graph* of distributed graph topology type to which topology information has been attached. The number of processes in *comm\_dist\_graph* is identical to the number of processes in *comm\_old*. The call to *MPI\_Dist\_graph\_create* is collective.

If *reorder = false*, all processes will have the same rank in *comm\_dist\_graph* as in *comm\_old*. If *reorder = true* then the MPI library is free to remap to other processes (of *comm\_old*) in order to improve communication on the edges of the communication graph. The weight associated with each edge is a hint to the MPI library about the amount or intensity of communication on that edge, and may be used to compute a “best” reordering.

Weights are specified as non-negative integers and can be used to influence the process remapping strategy and other internal MPI optimizations. For instance, approximate count arguments of later communication calls along specific edges could be used as their edge weights. Multiplicity of edges can likewise indicate more intense communication between pairs of processes. However, the exact meaning of edge weights is not specified by the MPI standard and is left to the implementation. In C or in the Fortran *mpi module* or *mpif.h include file*, an application can supply the special value *MPI\_UNWEIGHTED* for the weight array to indicate that all edges have the same (effectively no) weight. In the Fortran *mpi\_f08 module* or in C++, this constant does not exist and the weights argument may be omitted from the argument list. It is erroneous to supply *MPI\_UNWEIGHTED*, or in *mpi\_f08* or C++ omit the weight arrays, for some but not all processes of *comm\_old*. Note that *MPI\_UNWEIGHTED* is not a special weight value; rather it is a special value for the total array argument. In C, one would expect it to be *NULL*. In Fortran, *MPI\_UNWEIGHTED* is an object like *MPI\_BOTTOM* (not usable for initialization or assignment). See Section 2.5.4

The meaning of the *weights* argument can be influenced by the *info* argument. *Info* arguments can be used to guide the mapping; possible options include minimizing the maximum number of edges between processes on different SMP nodes, or minimizing the



sum of all such edges. An MPI implementation is not obliged to follow specific hints, and it is valid for an MPI implementation not to do any reordering. An MPI implementation may specify more info key-value pairs. All processes must specify the same set of key-value info pairs.

*Advice to implementors.* MPI implementations must document any additionally supported key-value info pairs. MPI\_INFO\_NULL is always valid, and may indicate the default creation of the distributed graph topology to the MPI library.

An implementation does not explicitly need to construct the topology from its distributed parts. However, all processes can construct the full topology from the distributed specification and use this in a call to MPI\_GRAPH\_CREATE to create the topology. This may serve as a reference implementation of the functionality, and may be acceptable for small communicators. However, a scalable high-quality implementation would save the topology graph in a distributed way. (*End of advice to implementors.*)

**Example 7.3** As for Example 7.2, assume there are four processes 0, 1, 2, 3 with the following adjacency matrix and unit edge weights:

process	neighbors
0	1, 3
1	0
2	3
3	0, 2

With MPI\_DIST\_GRAPH\_CREATE, this graph could be constructed in many different ways. One way would be that each process specifies its outgoing edges. The arguments per process would be:

process	n	sources	degrees	destinations	weights
0	1	0	2	1,3	1,1
1	1	1	1	0	1
2	1	2	1	3	1
3	1	3	2	0,2	1,1

Another way would be to pass the whole graph on process 0, which could be done with the following arguments per process:

process	n	sources	degrees	destinations	weights
0	4	0,1,2,3	2,1,1,2	1,3,0,3,0,2	1,1,1,1,1,1
1	0	-	-	-	-
2	0	-	-	-	-
3	0	-	-	-	-

In both cases above, the application could supply MPI\_UNWEIGHTED or in mpi\_f08 or C++ omit the weights instead of explicitly providing identical weights.

MPI\_DIST\_GRAPH\_CREATE\_ADJACENT could be used to specify this graph using the following arguments:

process	indegree	sources	sourceweights	outdegree	destinations	destweights
0	2	1,3	1,1	2	1,3	1,1
1	1	0	1	1	0	1
2	1	3	1	1	3	1
3	2	0,2	1,1	2	0,2	1,1

**Example 7.4** A two-dimensional  $P \times Q$  torus where all processes communicate along the dimensions and along the diagonal edges. This cannot be modelled with Cartesian topologies, but can easily be captured with `MPI_DIST_GRAPH_CREATE` as shown in the following code. In this example, the communication along the dimensions is twice as heavy as the communication along the diagonals:

```

/*
Input:      dimensions P, Q
Condition:  number of processes equal to P*Q; otherwise only
            ranks smaller than P*Q participate
*/
int rank, x, y;
int sources[1], degrees[1];
int destinations[8], weights[8];

MPI_Comm_rank(MPI_COMM_WORLD, &rank);

/* get x and y dimension */
y=rank/P; x=rank%P;

/* get my communication partners along x dimension */
destinations[0] = P*y+(x+1)%P; weights[0] = 2;
destinations[1] = P*y+(P+x-1)%P; weights[1] = 2;

/* get my communication partners along y dimension */
destinations[2] = P*((y+1)%Q)+x; weights[2] = 2;
destinations[3] = P*((Q+y-1)%Q)+x; weights[3] = 2;

/* get my communication partners along diagonals */
destinations[4] = P*((y+1)%Q)+(x+1)%P; weights[4] = 1;
destinations[5] = P*((Q+y-1)%Q)+(x+1)%P; weights[5] = 1;
destinations[6] = P*((y+1)%Q)+(P+x-1)%P; weights[6] = 1;
destinations[7] = P*((Q+y-1)%Q)+(P+x-1)%P; weights[7] = 1;

sources[0] = rank;
degrees[0] = 8;
MPI_Dist_graph_create(MPI_COMM_WORLD, 1, sources, degrees, destinations,
                      weights, MPI_INFO_NULL, 1, comm_dist_graph)

```

## 7.5.5 Topology Inquiry Functions

If a topology has been defined with one of the above functions, then the topology information can be looked up using inquiry functions. They all are local calls.

**MPI\_TOPO\_TEST(comm, status)**

IN	comm	communicator (handle)
OUT	status	topology type of communicator comm (state)

**int MPI\_Topo\_test(MPI\_Comm comm, int \*status)**

**MPI\_TOPO\_TEST(COMM, STATUS, IERROR)**

INTEGER COMM, STATUS, IERROR

**MPI\_Topo\_test(comm, status, ierror)**

TYPE(MPI\_Comm), INTENT(IN) :: comm

INTEGER, INTENT(OUT) :: status

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{**int MPI::Comm::Get\_topology()** *const(binding deprecated, see Section 15.2)* }

The function **MPI\_TOPO\_TEST** returns the type of topology that is assigned to a communicator.

The output value **status** is one of the following:

<b>MPI_GRAPH</b>	graph topology
<b>MPI_CART</b>	Cartesian topology
<b>MPI_DIST_GRAPH</b>	distributed graph topology
<b>MPI_UNDEFINED</b>	no topology

**MPI\_GRAPHDIMS\_GET(comm, nnodes, nedges)**

IN	comm	communicator for group with graph structure (handle)
OUT	nnodes	number of nodes in graph (integer) (same as number of processes in the group)
OUT	nedges	number of edges in graph (integer)

**int MPI\_Graphdims\_get(MPI\_Comm comm, int \*nnodes, int \*nedges)**

**MPI\_GRAPHDIMS\_GET(COMM, NNODES, NEDGES, IERROR)**

INTEGER COMM, NNODES, NEDGES, IERROR

**MPI\_Graphdims\_get(comm, nnodes, nedges, ierror)**

TYPE(MPI\_Comm), INTENT(IN) :: comm

INTEGER, INTENT(OUT) :: nnodes, nedges

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{**void MPI::Graphcomm::Get\_dims(int nnodes[], int nedges[])** *const(binding deprecated, see Section 15.2)* }

Functions `MPI_GRAPHDIMS_GET` and `MPI_GRAPH_GET` retrieve the graph-topology information that was associated with a communicator by `MPI_GRAPH_CREATE`.

The information provided by `MPI_GRAPHDIMS_GET` can be used to dimension the vectors `index` and `edges` correctly for the following call to `MPI_GRAPH_GET`.

`MPI_GRAPH_GET(comm, maxindex, maxedges, index, edges)`

IN	<code>comm</code>	communicator with graph structure (handle)
IN	<code>maxindex</code>	length of vector <code>index</code> in the calling program (integer)
IN	<code>maxedges</code>	length of vector <code>edges</code> in the calling program (integer)
OUT	<code>index</code>	array of integers containing the graph structure (for details see the definition of <code>MPI_GRAPH_CREATE</code> )
OUT	<code>edges</code>	array of integers containing the graph structure

```
int MPI_Graph_get(MPI_Comm comm, int maxindex, int maxedges, int *index,
                  int *edges)
```

```
MPI_GRAPH_GET(COMM, MAXINDEX, MAXEDGES, INDEX, EDGES, IERROR)
INTEGER COMM, MAXINDEX, MAXEDGES, INDEX(*), EDGES(*), IERROR
```

```
MPI_Graph_get(comm, maxindex, maxedges, index, edges, ierror)
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, INTENT(IN) :: maxindex, maxedges
INTEGER, INTENT(OUT) :: index(*), edges(*)
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Graphcomm::Get_topo(int maxindex, int maxedges, int index[],
                               int edges[]) const(binding deprecated, see Section 15.2) }
```

`MPI_CARTDIM_GET(comm, ndims)`

IN	<code>comm</code>	communicator with Cartesian structure (handle)
OUT	<code>ndims</code>	number of dimensions of the Cartesian structure (integer)

```
int MPI_Cartdim_get(MPI_Comm comm, int *ndims)
```

```
MPI_CARTDIM_GET(COMM, NDIMS, IERROR)
INTEGER COMM, NDIMS, IERROR
```

```
MPI_Cartdim_get(comm, ndims, ierror)
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, INTENT(OUT) :: ndims
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{int MPI::Cartcomm::Get_dim() const(binding deprecated, see Section 15.2) }
```

The functions `MPI_CARTDIM_GET` and `MPI_CART_GET` return the Cartesian topology information that was associated with a communicator by `MPI_CART_CREATE`. If `comm` is associated with a zero-dimensional Cartesian topology, `MPI_CARTDIM_GET` returns `ndims=0` and `MPI_CART_GET` will keep all output arguments unchanged.

`MPI_CART_GET(comm, maxdims, dims, periods, coords)`

IN	<code>comm</code>	communicator with Cartesian structure (handle)
IN	<code>maxdims</code>	length of vectors <code>dims</code> , <code>periods</code> , and <code>coords</code> in the calling program (integer)
OUT	<code>dims</code>	number of processes for each Cartesian dimension (array of integer)
OUT	<code>periods</code>	periodicity ( <code>true/false</code> ) for each Cartesian dimension (array of logical)
OUT	<code>coords</code>	coordinates of calling process in Cartesian structure (array of integer)

```
int MPI_Cart_get(MPI_Comm comm, int maxdims, int *dims, int *periods,
                int *coords)
```

```
MPI_CART_GET(COMM, MAXDIMS, DIMS, PERIODS, COORDS, IERROR)
    INTEGER COMM, MAXDIMS, DIMS(*), COORDS(*), IERROR
    LOGICAL PERIODS(*)
```

```
MPI_Cart_get(comm, maxdims, dims, periods, coords, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm
    INTEGER, INTENT(IN) :: maxdims
    INTEGER, INTENT(OUT) :: dims(*), coords(*)
    LOGICAL, INTENT(OUT) :: periods(*)
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Cartcomm::Get_topo(int maxdims, int dims[], bool periods[],
    int coords[]) const(binding deprecated, see Section 15.2) }
```

`MPI_CART_RANK(comm, coords, rank)`

IN	<code>comm</code>	communicator with Cartesian structure (handle)
IN	<code>coords</code>	integer array (of size <code>ndims</code> ) specifying the Cartesian coordinates of a process
OUT	<code>rank</code>	rank of specified process (integer)

```
int MPI_Cart_rank(MPI_Comm comm, int *coords, int *rank)
```

```
MPI_CART_RANK(COMM, COORDS, RANK, IERROR)
    INTEGER COMM, COORDS(*), RANK, IERROR
```

```
MPI_Cart_rank(comm, coords, rank, ierror)
```

```

1      TYPE(MPI_Comm), INTENT(IN) :: comm
2      INTEGER, INTENT(IN) :: coords(*)
3      INTEGER, INTENT(OUT) :: rank
4      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
5
6  {int MPI::Cartcomm::Get_cart_rank(const int coords[]) const(binding
7      deprecated, see Section 15.2) }

```

For a process group with Cartesian structure, the function `MPI_CART_RANK` translates the logical process coordinates to process ranks as they are used by the point-to-point routines.

For dimension `i` with `periods(i) = true`, if the coordinate, `coords(i)`, is out of range, that is, `coords(i) < 0` or `coords(i) ≥ dims(i)`, it is shifted back to the interval  $0 \leq \text{coords}(i) < \text{dims}(i)$  automatically. Out-of-range coordinates are erroneous for non-periodic dimensions.

If `comm` is associated with a zero-dimensional Cartesian topology, `coords` is not significant and 0 is returned in `rank`.

`MPI_CART_COORDS(comm, rank, maxdims, coords)`

IN	<code>comm</code>	communicator with Cartesian structure (handle)
IN	<code>rank</code>	rank of a process within group of <code>comm</code> (integer)
IN	<code>maxdims</code>	length of vector <code>coords</code> in the calling program (integer)
OUT	<code>coords</code>	integer array (of size <code>ndims</code> ) containing the Cartesian coordinates of specified process (array of integers)

```

28 int MPI_Cart_coords(MPI_Comm comm, int rank, int maxdims, int *coords)
29
30 MPI_CART_COORDS(COMM, RANK, MAXDIMS, COORDS, IERROR)
31     INTEGER COMM, RANK, MAXDIMS, COORDS(*), IERROR

```

```

32 MPI_Cart_coords(comm, rank, maxdims, coords, ierror)

```

```

33     TYPE(MPI_Comm), INTENT(IN) :: comm
34     INTEGER, INTENT(IN) :: rank, maxdims
35     INTEGER, INTENT(OUT) :: coords(*)
36     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
37

```

```

38 {void MPI::Cartcomm::Get_coords(int rank, int maxdims, int coords[])
39     const(binding deprecated, see Section 15.2) }

```

The inverse mapping, rank-to-coordinates translation is provided by `MPI_CART_COORDS`.

If `comm` is associated with a zero-dimensional Cartesian topology, `coords` will be unchanged.

```

MPI_GRAPH_NEIGHBORS_COUNT(comm, rank, nneighbors)
    IN      comm      communicator with graph topology (handle)
    IN      rank      rank of process in group of comm (integer)
    OUT     nneighbors  number of neighbors of specified process (integer)

int MPI_Graph_neighbors_count(MPI_Comm comm, int rank, int *nneighbors)

MPI_GRAPH_NEIGHBORS_COUNT(COMM, RANK, NNEIGHBORS, IERROR)
    INTEGER COMM, RANK, NNEIGHBORS, IERROR

MPI_Graph_neighbors_count(comm, rank, nneighbors, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm
    INTEGER, INTENT(IN) :: rank
    INTEGER, INTENT(OUT) :: nneighbors
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{int MPI::Graphcomm::Get_neighbors_count(int rank) const(binding deprecated,
    see Section 15.2) }

MPI_GRAPH_NEIGHBORS(comm, rank, maxneighbors, neighbors)
    IN      comm      communicator with graph topology (handle)
    IN      rank      rank of process in group of comm (integer)
    IN      maxneighbors  size of array neighbors (integer)
    OUT     neighbors  ranks of processes that are neighbors to specified pro-
                        cess (array of integer)

int MPI_Graph_neighbors(MPI_Comm comm, int rank, int maxneighbors,
    int *neighbors)

MPI_GRAPH_NEIGHBORS(COMM, RANK, MAXNEIGHBORS, NEIGHBORS, IERROR)
    INTEGER COMM, RANK, MAXNEIGHBORS, NEIGHBORS(*), IERROR

MPI_Graph_neighbors(comm, rank, maxneighbors, neighbors, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm
    INTEGER, INTENT(IN) :: rank, maxneighbors
    INTEGER, INTENT(OUT) :: neighbors(*)
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Graphcomm::Get_neighbors(int rank, int maxneighbors, int
    neighbors[]) const(binding deprecated, see Section 15.2) }

    MPI_GRAPH_NEIGHBORS_COUNT and MPI_GRAPH_NEIGHBORS provide adjacency
    information for a general graph topology. The returned count and array of neighbors for
    the queried rank will both include all neighbors and reflect the same edge ordering as
    was specified by the original call to MPI_GRAPH_CREATE. Specifically,
    MPI_GRAPH_NEIGHBORS_COUNT and MPI_GRAPH_NEIGHBORS will return values based

```

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on the original `index` and `edges` array passed to `MPI_GRAPH_CREATE` (assuming that `index[-1]` effectively equals zero):

- The `count` returned from `MPI_GRAPH_NEIGHBORS_COUNT` will be  $(\text{index}[\text{rank}] - \text{index}[\text{rank}-1])$ .
- The `neighbors` array returned from `MPI_GRAPH_NEIGHBORS` will be `edges[index[rank-1]]` through `edges[index[rank]-1]`.

### Example 7.5

Assume there are four processes 0, 1, 2, 3 with the following adjacency matrix (note that some neighbors are listed multiple times):

process	neighbors
0	1, 1, 3
1	0, 0
2	3
3	0, 2, 2

Thus, the input arguments to `MPI_GRAPH_CREATE` are:

```
nnodes = 4
index = 3, 5, 6, 9
edges = 1, 1, 3, 0, 0, 3, 0, 2, 2
```

Therefore, calling `MPI_GRAPH_NEIGHBORS_COUNT` and `MPI_GRAPH_NEIGHBORS` for each of the 4 processes will return:

Input rank	Count	Neighbors
0	3	1, 1, 3
1	2	0, 0
2	1	3
3	3	0, 2, 2

### Example 7.6

Suppose that `comm` is a communicator with a shuffle-exchange topology. The group has  $2^n$  members. Each process is labeled by  $a_1, \dots, a_n$  with  $a_i \in \{0, 1\}$ , and has three neighbors:  $\text{exchange}(a_1, \dots, a_n) = a_1, \dots, a_{n-1}, \bar{a}_n$  ( $\bar{a} = 1 - a$ ),  $\text{shuffle}(a_1, \dots, a_n) = a_2, \dots, a_n, a_1$ , and  $\text{unshuffle}(a_1, \dots, a_n) = a_n, a_1, \dots, a_{n-1}$ . The graph adjacency list is illustrated below for  $n = 3$ .



node	exchange neighbors(1)	shuffle neighbors(2)	unshuffle neighbors(3)
0 (000)	1	0	0
1 (001)	0	2	4
2 (010)	3	4	1
3 (011)	2	6	5
4 (100)	5	1	2
5 (101)	4	3	6
6 (110)	7	5	3
7 (111)	6	7	7

Suppose that the communicator `comm` has this topology associated with it. The following code fragment cycles through the three types of neighbors and performs an appropriate permutation for each.

```

C  assume: each process has stored a real number A.
C  extract neighborhood information
    CALL MPI_COMM_RANK(comm, myrank, ierr)
    CALL MPI_GRAPH_NEIGHBORS(comm, myrank, 3, neighbors, ierr)
C  perform exchange permutation
    CALL MPI_SENDRECV_REPLACE(A, 1, MPI_REAL, neighbors(1), 0,
+    neighbors(1), 0, comm, status, ierr)
C  perform shuffle permutation
    CALL MPI_SENDRECV_REPLACE(A, 1, MPI_REAL, neighbors(2), 0,
+    neighbors(3), 0, comm, status, ierr)
C  perform unshuffle permutation
    CALL MPI_SENDRECV_REPLACE(A, 1, MPI_REAL, neighbors(3), 0,
+    neighbors(2), 0, comm, status, ierr)

```

`MPI_DIST_GRAPH_NEIGHBORS_COUNT` and `MPI_DIST_GRAPH_NEIGHBORS` provide adjacency information for a distributed graph topology.

`MPI_DIST_GRAPH_NEIGHBORS_COUNT(comm, indegree, outdegree, weighted)`

IN	comm	communicator with distributed graph topology (handle)
OUT	indegree	number of edges into this process (non-negative integer)
OUT	outdegree	number of edges out of this process (non-negative integer)
OUT	weighted	false if <code>MPI_UNWEIGHTED</code> was supplied or the weights were omitted during creation, true otherwise (logical)

```

int MPI_Dist_graph_neighbors_count(MPI_Comm comm, int *indegree,
    int *outdegree, int *weighted)

```

`MPI_DIST_GRAPH_NEIGHBORS_COUNT(COMM, INDEGREE, OUTDEGREE, WEIGHTED, IERROR)`

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```

1      INTEGER COMM, INDEGREE, OUTDEGREE, IERROR
2      LOGICAL WEIGHTED
3
4      MPI_Dist_graph_neighbors_count(comm, indegree, outdegree, weighted, ierror)
5      TYPE(MPI_Comm), INTENT(IN) :: comm
6      INTEGER, INTENT(OUT) :: indegree, outdegree
7      LOGICAL, INTENT(OUT) :: weighted
8      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
9
10     {void MPI::Distgraphcomm::Get_dist_neighbors_count(int rank,
11               int indegree[], int outdegree[], bool& weighted) const(binding
12               deprecated, see Section 15.2) }
13
14     MPI_DIST_GRAPH_NEIGHBORS(comm, maxindegree, sources, sourceweights, maxoutdegree,
15                               destinations, destweights)
16
17     IN      comm      communicator with distributed graph topology (han-
18                   dle)
19     IN      maxindegree      size of sources and sourceweights arrays (non-negative
20                   integer)
21     OUT     sources      processes for which the calling process is a destination
22                   (array of non-negative integers)
23     OUT     sourceweights      weights of the edges into the calling process (array of
24                   non-negative integers)
25
26     IN      maxoutdegree      size of destinations and destweights arrays (non-negative
27                   integer)
28     OUT     destinations      processes for which the calling process is a source (ar-
29                   ray of non-negative integers)
30
31     OUT     destweights      weights of the edges out of the calling process (array
32                   of non-negative integers)
33
34     int MPI_Dist_graph_neighbors(MPI_Comm comm, int maxindegree, int sources[],
35               int sourceweights[], int maxoutdegree, int destinations[],
36               int destweights[])
37
38     MPI_DIST_GRAPH_NEIGHBORS(COMM, MAXINDEGREE, SOURCES, SOURCEWEIGHTS,
39                               MAXOUTDEGREE, DESTINATIONS, DESTWEIGHTS, IERROR)
40     INTEGER COMM, MAXINDEGREE, SOURCES(*), SOURCEWEIGHTS(*), MAXOUTDEGREE,
41     DESTINATIONS(*), DESTWEIGHTS(*), IERROR
42
43     MPI_Dist_graph_neighbors(comm, maxindegree, sources, sourceweights,
44                               maxoutdegree, destinations, destweights, ierror)
45     TYPE(MPI_Comm), INTENT(IN) :: comm
46     INTEGER, INTENT(IN) :: maxindegree, maxoutdegree
47     INTEGER, INTENT(OUT) :: sources(*), destinations(*)
48     INTEGER, INTENT(OUT) :: sourceweights(*), destweights(*) ! optional
49     by overloading

```

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```

    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
{void MPI::Distgraphcomm::Get_dist_neighbors(int maxindegree,
      int sources[], int sourceweights[], int maxoutdegree,
      int destinations[], int destweights[]) (binding deprecated, see
      Section 15.2) }
```

These calls are local. The number of edges into and out of the process returned by MPI\_DIST\_GRAPH\_NEIGHBORS\_COUNT are the total number of such edges given in the call to MPI\_DIST\_GRAPH\_CREATE\_ADJACENT or MPI\_DIST\_GRAPH\_CREATE (potentially by processes other than the calling process in the case of MPI\_DIST\_GRAPH\_CREATE). Multiply defined edges are all counted and returned by MPI\_DIST\_GRAPH\_NEIGHBORS in some order. If MPI\_UNWEIGHTED is supplied (in C or the mpi module or mpif.h) or the argument is omitted (in mpi\_f08) for sourceweights or destweights or both,<sup>2</sup> or if MPI\_UNWEIGHTED was supplied or the weights were omitted during the construction of the graph then no weight information is returned in that array or those arrays. The only requirement on the order of values in sources and destinations is that two calls to the routine with same input argument comm will return the same sequence of edges. If maxindegree or maxoutdegree is smaller than the numbers returned by MPI\_DIST\_GRAPH\_NEIGHBOR\_COUNT, then only the first part of the full list is returned. Note, that the order of returned edges does need not to be identical to the order that was provided in the creation of comm for the case that MPI\_DIST\_GRAPH\_CREATE\_ADJACENT was used.

*Advice to implementors.* Since the query calls are defined to be local, each process needs to store the list of its neighbors with incoming and outgoing edges. Communication is required at the collective MPI\_DIST\_GRAPH\_CREATE call in order to compute the neighbor lists for each process from the distributed graph specification. (*End of advice to implementors.*)

### 7.5.6 Cartesian Shift Coordinates

If the process topology is a Cartesian structure, an MPI\_SENDRECV operation is likely to be used along a coordinate direction to perform a shift of data. As input, MPI\_SENDRECV takes the rank of a source process for the receive, and the rank of a destination process for the send. If the function MPI\_CART\_SHIFT is called for a Cartesian process group, it provides the calling process with the above identifiers, which then can be passed to MPI\_SENDRECV. The user specifies the coordinate direction and the size of the step (positive or negative). The function is local.

---

<sup>2</sup>The generic Fortran interface must contain 4 specific routines.

```

1 MPI_CART_SHIFT(comm, direction, disp, rank_source, rank_dest)
2     IN          comm          communicator with Cartesian structure (handle)
3
4     IN          direction      coordinate dimension of shift (integer)
5
6     IN          disp           displacement (> 0: upwards shift, < 0: downwards
7                                shift) (integer)
8
9     OUT         rank_source     rank of source process (integer)
10
11    OUT         rank_dest       rank of destination process (integer)

```

```

12 int MPI_Cart_shift(MPI_Comm comm, int direction, int disp,
13                   int *rank_source, int *rank_dest)
14 MPI_CART_SHIFT(COMM, DIRECTION, DISP, RANK_SOURCE, RANK_DEST, IERROR)
15 INTEGER COMM, DIRECTION, DISP, RANK_SOURCE, RANK_DEST, IERROR
16 MPI_Cart_shift(comm, direction, disp, rank_source, rank_dest, ierror)
17 TYPE(MPI_Comm), INTENT(IN) :: comm
18 INTEGER, INTENT(IN) :: direction, disp
19 INTEGER, INTENT(OUT) :: rank_source, rank_dest
20 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
21
22 {void MPI::Cartcomm::Shift(int direction, int disp, int& rank_source,
23                           int& rank_dest) const(binding deprecated, see Section 15.2) }

```

The direction argument indicates the coordinate dimension to be traversed by the shift. The dimensions are numbered from 0 to `ndims-1`, where `ndims` is the number of dimensions.

Depending on the periodicity of the Cartesian group in the specified coordinate direction, `MPI_CART_SHIFT` provides the identifiers for a circular or an end-off shift. In the case of an end-off shift, the value `MPI_PROC_NULL` may be returned in `rank_source` or `rank_dest`, indicating that the source or the destination for the shift is out of range.

It is erroneous to call `MPI_CART_SHIFT` with a direction that is either negative or greater than or equal to the number of dimensions in the Cartesian communicator. This implies that it is erroneous to call `MPI_CART_SHIFT` with a `comm` that is associated with a zero-dimensional Cartesian topology.

### Example 7.7

The communicator, `comm`, has a two-dimensional, periodic, Cartesian topology associated with it. A two-dimensional array of `REALs` is stored one element per process, in variable `A`. One wishes to skew this array, by shifting column `i` (vertically, i.e., along the column) by `i` steps.

```

40 ....
41
42 C find process rank
43     CALL MPI_COMM_RANK(comm, rank, ierr)
44 C find Cartesian coordinates
45     CALL MPI_CART_COORDS(comm, rank, maxdims, coords, ierr)
46 C compute shift source and destination
47     CALL MPI_CART_SHIFT(comm, 0, coords(2), source, dest, ierr)
48 C skew array

```

```
CALL MPI_SENDRECV_REPLACE(A, 1, MPI_REAL, dest, 0, source, 0, comm,
+                          status, ierr)
```

*Advice to users.* In Fortran, the dimension indicated by `DIRECTION = i` has `DIMS(i+1)` nodes, where `DIMS` is the array that was used to create the grid. In C, the dimension indicated by `direction = i` is the dimension specified by `dims[i]`. (*End of advice to users.*)

### 7.5.7 Partitioning of Cartesian Structures

`MPI_CART_SUB(comm, remain_dims, newcomm)`

IN	<code>comm</code>	communicator with Cartesian structure (handle)
IN	<code>remain_dims</code>	the <i>i</i> -th entry of <code>remain_dims</code> specifies whether the <i>i</i> -th dimension is kept in the subgrid ( <code>true</code> ) or is dropped ( <code>false</code> ) (logical vector)
OUT	<code>newcomm</code>	communicator containing the subgrid that includes the calling process (handle)

```
int MPI_Cart_sub(MPI_Comm comm, int *remain_dims, MPI_Comm *newcomm)
```

```
MPI_CART_SUB(COMM, REMAIN_DIMS, NEWCOMM, IERROR)
```

```
INTEGER COMM, NEWCOMM, IERROR
```

```
LOGICAL REMAIN_DIMS(*)
```

```
MPI_Cart_sub(comm, remain_dims, newcomm, ierror)
```

```
TYPE(MPI_Comm), INTENT(IN) :: comm
```

```
LOGICAL, INTENT(IN) :: remain_dims(*)
```

```
TYPE(MPI_Comm), INTENT(OUT) :: newcomm
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{MPI::Cartcomm MPI::Cartcomm::Sub(const bool remain_dims[]) const(binding
deprecated, see Section 15.2) }
```

If a Cartesian topology has been created with `MPI_CART_CREATE`, the function `MPI_CART_SUB` can be used to partition the communicator group into subgroups that form lower-dimensional Cartesian subgrids, and to build for each subgroup a communicator with the associated subgrid Cartesian topology. If all entries in `remain_dims` are false or `comm` is already associated with a zero-dimensional Cartesian topology then `newcomm` is associated with a zero-dimensional Cartesian topology. (This function is closely related to `MPI_COMM_SPLIT`.)

#### Example 7.8

Assume that `MPI_CART_CREATE(..., comm)` has defined a  $(2 \times 3 \times 4)$  grid. Let `remain_dims = (true, false, true)`. Then a call to,

```
MPI_CART_SUB(comm, remain_dims, comm_new),
```

will create three communicators each with eight processes in a  $2 \times 4$  Cartesian topology. If `remain_dims = (false, false, true)` then the call to `MPI_CART_SUB(comm, remain_dims, comm_new)` will create six non-overlapping communicators, each with four processes, in a one-dimensional Cartesian topology.

### 7.5.8 Low-Level Topology Functions

The two additional functions introduced in this section can be used to implement all other topology functions. In general they will not be called by the user directly, unless he or she is creating additional virtual topology capability other than that provided by MPI.

`MPI_CART_MAP(comm, ndims, dims, periods, newrank)`

IN	<code>comm</code>	input communicator (handle)
IN	<code>ndims</code>	number of dimensions of Cartesian structure (integer)
IN	<code>dims</code>	integer array of size <code>ndims</code> specifying the number of processes in each coordinate direction
IN	<code>periods</code>	logical array of size <code>ndims</code> specifying the periodicity specification in each coordinate direction
OUT	<code>newrank</code>	reordered rank of the calling process; MPI_UNDEFINED if calling process does not belong to grid (integer)

```
int MPI_Cart_map(MPI_Comm comm, int ndims, int *dims, int *periods,
                 int *newrank)
```

```
MPI_CART_MAP(COMM, NDIMS, DIMS, PERIODS, NEWRANK, IERROR)
  INTEGER COMM, NDIMS, DIMS(*), NEWRANK, IERROR
  LOGICAL PERIODS(*)
```

```
MPI_Cart_map(comm, ndims, dims, periods, newrank, ierror)
  TYPE(MPI_Comm), INTENT(IN) :: comm
  INTEGER, INTENT(IN) :: ndims, dims(*)
  LOGICAL, INTENT(IN) :: periods(*)
  INTEGER, INTENT(OUT) :: newrank
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{int MPI::Cartcomm::Map(int ndims, const int dims[], const bool periods[])
  const(binding deprecated, see Section 15.2) }
```

`MPI_CART_MAP` computes an “optimal” placement for the calling process on the physical machine. A possible implementation of this function is to always return the rank of the calling process, that is, not to perform any reordering.

*Advice to implementors.* The function `MPI_CART_CREATE(comm, ndims, dims, periods, reorder, comm_cart)`, with `reorder = true` can be implemented by calling `MPI_CART_MAP(comm, ndims, dims, periods, newrank)`, then calling `MPI_COMM_SPLIT(comm, color, key, comm_cart)`, with `color = 0` if `newrank`  $\neq$  `MPI_UNDEFINED`, `color = MPI_UNDEFINED` otherwise, and `key = newrank`.

The function `MPI_CART_SUB(comm, remain_dims, comm_new)` can be implemented by a call to `MPI_COMM_SPLIT(comm, color, key, comm_new)`, using a single number encoding of the lost dimensions as `color` and a single number encoding of the preserved dimensions as `key`.

All other Cartesian topology functions can be implemented locally, using the topology information that is cached with the communicator. (*End of advice to implementors.*)

The corresponding new function for general graph structures is as follows.

`MPI_GRAPH_MAP(comm, nnodes, index, edges, newrank)`

IN	<code>comm</code>	input communicator (handle)
IN	<code>nnodes</code>	number of graph nodes (integer)
IN	<code>index</code>	integer array specifying the graph structure, see <code>MPI_GRAPH_CREATE</code>
IN	<code>edges</code>	integer array specifying the graph structure
OUT	<code>newrank</code>	reordered rank of the calling process; <code>MPI_UNDEFINED</code> if the calling process does not belong to graph (integer)

```
int MPI_Graph_map(MPI_Comm comm, int nnodes, int *index, int *edges,
                  int *newrank)
```

```
MPI_GRAPH_MAP(COMM, NNODES, INDEX, EDGES, NEWRANK, IERROR)
    INTEGER COMM, NNODES, INDEX(*), EDGES(*), NEWRANK, IERROR
```

```
MPI_Graph_map(comm, nnodes, index, edges, newrank, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm
    INTEGER, INTENT(IN) :: nnodes, index(*), edges(*)
    INTEGER, INTENT(OUT) :: newrank
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{int MPI::Graphcomm::Map(int nnodes, const int index[], const int edges[])
    const(binding deprecated, see Section 15.2) }
```

*Advice to implementors.* The function `MPI_GRAPH_CREATE(comm, nnodes, index, edges, reorder, comm_graph)`, with `reorder = true` can be implemented by calling `MPI_GRAPH_MAP(comm, nnodes, index, edges, newrank)`, then calling `MPI_COMM_SPLIT(comm, color, key, comm_graph)`, with `color = 0` if `newrank ≠ MPI_UNDEFINED`, `color = MPI_UNDEFINED` otherwise, and `key = newrank`.

All other graph topology functions can be implemented locally, using the topology information that is cached with the communicator. (*End of advice to implementors.*)

## 7.6 An Application Example

### Example 7.9

The example in Figure 7.1 shows how the grid definition and inquiry functions can be used in an application program. A partial differential equation, for instance the Poisson equation, is to be solved on a rectangular domain. First, the processes organize themselves in a two-dimensional structure. Each process then inquires about the ranks of its neighbors in the four directions (up, down, right, left). The numerical problem is solved by an iterative method, the details of which are hidden in the subroutine `relax`.

In each relaxation step each process computes new values for the solution grid function at all points owned by the process. Then the values at inter-process boundaries have to be exchanged with neighboring processes. For example, the exchange subroutine might contain a call like `MPI_SEND(...,neigh_rank(1),...)` to send updated values to the left-hand neighbor (`i-1,j`).



```

integer ndims, num_neigh
logical reorder
parameter (ndims=2, num_neigh=4, reorder=.true.)
integer comm, comm_cart, dims(ndims), neigh_def(ndims), ierr
integer neigh_rank(num_neigh), own_position(ndims), i, j
logical periods(ndims)
real*8 u(0:101,0:101), f(0:101,0:101)
data dims / ndims * 0 /
comm = MPI_COMM_WORLD
C   Set process grid size and periodicity
call MPI_DIMS_CREATE(comm, ndims, dims,ierr)
periods(1) = .TRUE.
periods(2) = .TRUE.
C   Create a grid structure in WORLD group and inquire about own position
call MPI_CART_CREATE (comm, ndims, dims, periods, reorder, comm_cart,ierr)
call MPI_CART_GET (comm_cart, ndims, dims, periods, own_position,ierr)
C   Look up the ranks for the neighbors. Own process coordinates are (i,j).
C   Neighbors are (i-1,j), (i+1,j), (i,j-1), (i,j+1)
i = own_position(1)
j = own_position(2)
neigh_def(1) = i-1
neigh_def(2) = j
call MPI_CART_RANK (comm_cart, neigh_def, neigh_rank(1),ierr)
neigh_def(1) = i+1
neigh_def(2) = j
call MPI_CART_RANK (comm_cart, neigh_def, neigh_rank(2),ierr)
neigh_def(1) = i
neigh_def(2) = j-1
call MPI_CART_RANK (comm_cart, neigh_def, neigh_rank(3),ierr)
neigh_def(1) = i
neigh_def(2) = j+1
call MPI_CART_RANK (comm_cart, neigh_def, neigh_rank(4),ierr)
C   Initialize the grid functions and start the iteration
call init (u, f)
do 10 it=1,100
    call relax (u, f)
C   Exchange data with neighbor processes
    call exchange (u, comm_cart, neigh_rank, num_neigh)
10 continue
call output (u)
end

```

Figure 7.1: Set-up of process structure for two-dimensional parallel Poisson solver.

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## Chapter 8

# MPI Environmental Management

This chapter discusses routines for getting and, where appropriate, setting various parameters that relate to the MPI implementation and the execution environment (such as error handling). The procedures for entering and leaving the MPI execution environment are also described here.

### 8.1 Implementation Information

#### 8.1.1 Version Inquiries

In order to cope with changes to the MPI Standard, there are both compile-time and run-time ways to determine which version of the standard is in use in the environment one is using.

The “version” will be represented by two separate integers, for the version and subversion: In C and C++,

```
#define MPI_VERSION    2
#define MPI_SUBVERSION 2
```

in Fortran,

```
INTEGER [ticket240-L.] :: MPI_VERSION, MPI_SUBVERSION
PARAMETER (MPI_VERSION    = 2)
PARAMETER (MPI_SUBVERSION = 2)
```

For runtime determination,

`MPI_GET_VERSION( version, subversion )`

OUT	version	version number (integer)
OUT	subversion	subversion number (integer)

```
int MPI_Get_version(int *version, int *subversion)
```

```
MPI_GET_VERSION(VERSION, SUBVERSION, IERROR)
```

```
INTEGER VERSION, SUBVERSION, IERROR
```

```
MPI_Get_version(version, subversion, ierror)
```

ticket-248T.

```

1      INTEGER, INTENT(OUT) :: version, subversion
2      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
3
4      {void MPI::Get_version(int& version, int& subversion) (binding deprecated, see
5          Section 15.2) }

```

MPI\_GET\_VERSION is one of the few functions that can be called before MPI\_INIT and after MPI\_FINALIZE. Valid (MPI\_VERSION, MPI\_SUBVERSION) pairs in this and previous versions of the MPI standard are (2,2), (2,1), (2,0), and (1,2).

### 8.1.2 Environmental Inquiries

A set of attributes that describe the execution environment are attached to the communicator MPI\_COMM\_WORLD when MPI is initialized. The value of these attributes can be inquired by using the function MPI\_COMM\_GET\_ATTR described in Chapter 6. It is erroneous to delete these attributes, free their keys, or change their values.

The list of predefined attribute keys include

**MPI\_TAG\_UB** Upper bound for tag value.

**MPI\_HOST** Host process rank, if such exists, MPI\_PROC\_NULL, otherwise.

**MPI\_IO** rank of a node that has regular I/O facilities (possibly myrank). Nodes in the same communicator may return different values for this parameter.

**MPI\_WTIME\_IS\_GLOBAL** Boolean variable that indicates whether clocks are synchronized.

Vendors may add implementation specific parameters (such as node number, real memory size, virtual memory size, etc.)

These predefined attributes do not change value between MPI initialization (MPI\_INIT and MPI completion (MPI\_FINALIZE), and cannot be updated or deleted by users.

*Advice to users.* Note that in the C binding, the value returned by these attributes is a *pointer* to an `int` containing the requested value. (*End of advice to users.*)

The required parameter values are discussed in more detail below:

#### Tag Values

Tag values range from 0 to the value returned for MPI\_TAG\_UB inclusive. These values are guaranteed to be unchanging during the execution of an MPI program. In addition, the tag upper bound value must be *at least* 32767. An MPI implementation is free to make the value of MPI\_TAG\_UB larger than this; for example, the value  $2^{30} - 1$  is also a legal value for MPI\_TAG\_UB.

The attribute MPI\_TAG\_UB has the same value on all processes of MPI\_COMM\_WORLD.

#### Host Rank

The value returned for MPI\_HOST gets the rank of the HOST process in the group associated with communicator MPI\_COMM\_WORLD, if there is such. MPI\_PROC\_NULL is returned if there is no host. MPI does not specify what it means for a process to be a HOST, nor does it requires that a HOST exists.

The attribute MPI\_HOST has the same value on all processes of MPI\_COMM\_WORLD.

## IO Rank

The value returned for `MPI_IO` is the rank of a processor that can provide language-standard I/O facilities. For Fortran, this means that all of the Fortran I/O operations are supported (e.g., `OPEN`, `REWIND`, `WRITE`). For C and C++, this means that all of the ISO C and C++, I/O operations are supported (e.g., `fopen`, `fprintf`, `lseek`).

If every process can provide language-standard I/O, then the value `MPI_ANY_SOURCE` will be returned. Otherwise, if the calling process can provide language-standard I/O, then its rank will be returned. Otherwise, if some process can provide language-standard I/O then the rank of one such process will be returned. The same value need not be returned by all processes. If no process can provide language-standard I/O, then the value `MPI_PROC_NULL` will be returned.

*Advice to users.* Note that input is not collective, and this attribute does *not* indicate which process can or does provide input. (*End of advice to users.*)

## Clock Synchronization

The value returned for `MPI_WTIME_IS_GLOBAL` is 1 if clocks at all processes in `MPI_COMM_WORLD` are synchronized, 0 otherwise. A collection of clocks is considered synchronized if explicit effort has been taken to synchronize them. The expectation is that the variation in time, as measured by calls to `MPI_WTIME`, will be less than one half the round-trip time for an MPI message of length zero. If time is measured at a process just before a send and at another process just after a matching receive, the second time should be always higher than the first one.

The attribute `MPI_WTIME_IS_GLOBAL` need not be present when the clocks are not synchronized (however, the attribute key `MPI_WTIME_IS_GLOBAL` is always valid). This attribute may be associated with communicators other than `MPI_COMM_WORLD`.

The attribute `MPI_WTIME_IS_GLOBAL` has the same value on all processes of `MPI_COMM_WORLD`.

`MPI_GET_PROCESSOR_NAME( name, resultlen )`

OUT	name	A unique specifier for the actual (as opposed to virtual) node.
OUT	resultlen	Length (in printable characters) of the result returned in name

```
int MPI_Get_processor_name(char *name, int *resultlen)
```

```
MPI_GET_PROCESSOR_NAME( NAME, RESULTLEN, IERROR)
```

```
CHARACTER*(*) NAME
```

```
INTEGER RESULTLEN, IERROR
```

```
MPI_Get_processor_name( name, resultlen, ierror)
```

```
CHARACTER(LEN=*), INTENT(OUT) :: name
```

```
INTEGER, INTENT(OUT) :: resultlen
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```

1 {void MPI::Get_processor_name(char* name, int& resultlen) (binding deprecated,
2 see Section 15.2) }
```

This routine returns the name of the processor on which it was called at the moment of the call. The name is a character string for maximum flexibility. From this value it must be possible to identify a specific piece of hardware; possible values include “processor 9 in rack 4 of mpp.cs.org” and “231” (where 231 is the actual processor number in the running homogeneous system). The argument `name` must represent storage that is at least `MPI_MAX_PROCESSOR_NAME` characters long. `MPI_GET_PROCESSOR_NAME` may write up to this many characters into `name`.

The number of characters actually written is returned in the output argument, `resultlen`. In C, a null character is additionally stored at `name[resultlen]`. The `resultlen` cannot be larger than `MPI_MAX_PROCESSOR_NAME-1`. In Fortran, `name` is padded on the right with blank characters. The `resultlen` cannot be larger than `MPI_MAX_PROCESSOR_NAME`.

*Rationale.* This function allows MPI implementations that do process migration to return the current processor. Note that nothing in MPI *requires* or defines process migration; this definition of `MPI_GET_PROCESSOR_NAME` simply allows such an implementation. (*End of rationale.*)

*Advice to users.* The user must provide at least `MPI_MAX_PROCESSOR_NAME` space to write the processor name — processor names can be this long. The user should examine the output argument, `resultlen`, to determine the actual length of the name. (*End of advice to users.*)

The constant `MPI_BSEND_OVERHEAD` provides an upper bound on the fixed overhead per message buffered by a call to `MPI_BSEND` (see Section 3.6.1).

## 8.2 Memory Allocation

In some systems, message-passing and remote-memory-access (RMA) operations run faster when accessing specially allocated memory (e.g., memory that is shared by the other processes in the communicating group on an SMP). MPI provides a mechanism for allocating and freeing such special memory. The use of such memory for message-passing or RMA is not mandatory, and this memory can be used without restrictions as any other dynamically allocated memory. However, implementations may restrict the use of the `MPI_WIN_LOCK` and `MPI_WIN_UNLOCK` functions to windows allocated in such memory (see Section 11.4.3.)

```

39 MPI_ALLOC_MEM(size, info, baseptr)
```

41	IN	size	size of memory segment in bytes (non-negative integer)
43	IN	info	info argument (handle)
44	OUT	baseptr	pointer to beginning of memory segment allocated

```

46 int MPI_Alloc_mem(MPI_Aint size, MPI_Info info, void *baseptr)
```

```

48 MPI_ALLOC_MEM(SIZE, INFO, BASEPTR, IERROR)
```

ticket245-Q.

```

USE, INTRINSIC :: ISO_C_BINDING
INTEGER :: INFO, IERROR
INTEGER(KIND=MPI_ADDRESS_KIND) :: SIZE
TYPE(C_PTR) :: BASEPTR !overloaded with following...
INTEGER(KIND=MPI_ADDRESS_KIND) BASEPTR ! ...type

MPI_Alloc_mem(size, info, baseptr, ierror)
USE, INTRINSIC :: ISO_C_BINDING
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: size
TYPE(MPI_Info), INTENT(IN) :: info
TYPE(C_PTR), INTENT(OUT) :: baseptr !overloaded with following...
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: baseptr ! ...type
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void* MPI::Alloc_mem(MPI::Aint size, const MPI::Info& info) (binding
    deprecated, see Section 15.2) }

```

The `info` argument can be used to provide directives that control the desired location of the allocated memory. Such a directive does not affect the semantics of the call. Valid `info` values are implementation-dependent; a null directive value of `info = MPI_INFO_NULL` is always valid.

The function `MPI_ALLOC_MEM` may return an error code of class `MPI_ERR_NO_MEM` to indicate it failed because memory is exhausted.

With Fortran `mpif.h`, only the `INTEGER(KIND=MPI_ADDRESS_KIND)` `BASEPTR` is required; with the `mpi` and `mpi_f08` modules, the overloaded interfaces are required.

```

MPI_FREE_MEM(base)
    IN          base          initial address of memory segment allocated by
                                MPI_ALLOC_MEM (choice)

int MPI_Free_mem(void *base)

MPI_FREE_MEM(BASE, IERROR)
    <type> BASE(*)
    INTEGER IERROR

MPI_Free_mem(base, ierror)
    TYPE(*), DIMENSION(..) :: base
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Free_mem(void *base) (binding deprecated, see Section 15.2) }

```

The function `MPI_FREE_MEM` may return an error code of class `MPI_ERR_BASE` to indicate an invalid `base` argument.

*Rationale.* The C and C++ bindings of `MPI_ALLOC_MEM` and `MPI_FREE_MEM` are similar to the bindings for the `malloc` and `free` C library calls: a call to `MPI_Alloc_mem(..., &base)` should be paired with a call to `MPI_Free_mem(base)` (one less level of indirection). Both arguments are declared to be of same type `void*` so

as to facilitate type casting. The Fortran binding is consistent with the C and C++ bindings: the Fortran `MPI_ALLOC_MEM` call returns in `baseptr` the (integer valued) address **the `TYPE(C_PTR)` pointer** of the allocated memory. The `base` argument of `MPI_FREE_MEM` is a choice argument, which passes (a reference to) the variable stored at that location. (*End of rationale.*)

*Advice to implementors.* If `MPI_ALLOC_MEM` allocates special memory, then a design similar to the design of C `malloc` and `free` functions has to be used, in order to find out the size of a memory segment, when the segment is freed. If no special memory is used, `MPI_ALLOC_MEM` simply invokes `malloc`, and `MPI_FREE_MEM` invokes `free`.

A call to `MPI_ALLOC_MEM` can be used in shared memory systems to allocate memory in a shared memory segment. (*End of advice to implementors.*)

**Example 8.1** Example of use of `MPI_ALLOC_MEM`, in Fortran with `TYPE(C_PTR)` pointers. We assume 4-byte REALs.

```
USE mpi_f08      ! or USE mpi      (not guaranteed with INCLUDE 'mpif.h')
USE, INTRINSIC :: ISO_C_BINDING
TYPE(C_PTR) :: p
REAL, DIMENSION(:, :), POINTER :: a      ! no memory is allocated
INTEGER, DIMENSION(2) :: shape
INTEGER(KIND=MPI_ADDRESS_KIND) :: size
shape = (/100,100/)
size = 4 * shape(1) * shape(2)           ! assuming 4 bytes per REAL
CALL MPI_Alloc_mem(size, MPI_INFO_NULL, p, ierr) ! memory is allocated and
CALL C_F_POINTER(p, a, shape)           ! now accessible through a
...
A(3,5) = 2.71;
...
CALL MPI_Free_mem(a, ierr)              ! memory is freed
```

**Example 8.2** Example of use of `MPI_ALLOC_MEM`, in Fortran with **non-standard Cray-pointer**. We assume 4-byte REALs, and assume that **these** pointers are address-sized.

```
REAL A
POINTER (P, A(100,100)) ! no memory is allocated
[ticket245-Q.]INTEGER(KIND=MPI_ADDRESS_KIND) SIZE
[ticket245-Q.]SIZE = 4*100*100
CALL MPI_ALLOC_MEM([ticket245-Q.]SIZE, MPI_INFO_NULL, P, IERR)
! memory is allocated
...
A(3,5) = 2.71;
...
CALL MPI_FREE_MEM(A, IERR) ! memory is freed
```

**This** code is not Fortran 77 or Fortran 90 code. Some compilers **may** not support this code **or need a special option, e.g., the GNU compiler needs `-fcray-pointer`**.



*Advice to implementors.* Some compilers map Cray-pointer to address-sized integers, some to `TYPE(C_PTR)` pointers (e.g., Cray Fortran, version 7.3.3). From the user's viewpoint, this mapping is irrelevant because Examples 8.2 should work correctly with an MPI-3.0 (or later) library if Cray-pointer are available. (*End of advice to implementors.*)

**Example 8.3** Same example, in C

```
float  (* f)[100][100] ;
/* no memory is allocated */
MPI_Alloc_mem(sizeof(float)*100*100, MPI_INFO_NULL, &f);
/* memory allocated */
...
(*f)[5][3] = 2.71;
...
MPI_Free_mem(f);
```

### 8.3 Error Handling

An MPI implementation cannot or may choose not to handle some errors that occur during MPI calls. These can include errors that generate exceptions or traps, such as floating point errors or access violations. The set of errors that are handled by MPI is implementation-dependent. Each such error generates an **MPI exception**.

The above text takes precedence over any text on error handling within this document. Specifically, text that states that errors *will* be handled should be read as *may* be handled.

A user can associate error handlers to three types of objects: communicators, windows, and files. The specified error handling routine will be used for any MPI exception that occurs during a call to MPI for the respective object. MPI calls that are not related to any objects are considered to be attached to the communicator `MPI_COMM_WORLD`. The attachment of error handlers to objects is purely local: different processes may attach different error handlers to corresponding objects.

Several predefined error handlers are available in MPI:

**MPI\_ERRORS\_ARE\_FATAL** The handler, when called, causes the program to abort on all executing processes. This has the same effect as if `MPI_ABORT` was called by the process that invoked the handler.

**MPI\_ERRORS\_RETURN** The handler has no effect other than returning the error code to the user.

Implementations may provide additional predefined error handlers and programmers can code their own error handlers.

The error handler `MPI_ERRORS_ARE_FATAL` is associated by default with `MPI_COMM_WORLD` after initialization. Thus, if the user chooses not to control error handling, every error that MPI handles is treated as fatal. Since (almost) all MPI calls return an error code, a user may choose to handle errors in its main code, by testing the return code of MPI calls and executing a suitable recovery code when the call was not successful. In this case, the error handler `MPI_ERRORS_RETURN` will be used. Usually it is more convenient and more

efficient not to test for errors after each MPI call, and have such error handled by a non trivial MPI error handler.

After an error is detected, the state of MPI is undefined. That is, using a user-defined error handler, or `MPI_ERRORS_RETURN`, does *not* necessarily allow the user to continue to use MPI after an error is detected. The purpose of these error handlers is to allow a user to issue user-defined error messages and to take actions unrelated to MPI (such as flushing I/O buffers) before a program exits. An MPI implementation is free to allow MPI to continue after an error but is not required to do so.

*Advice to implementors.* A good quality implementation will, to the greatest possible extent, circumscribe the impact of an error, so that normal processing can continue after an error handler was invoked. The implementation documentation will provide information on the possible effect of each class of errors. (*End of advice to implementors.*)

An MPI error handler is an opaque object, which is accessed by a handle. MPI calls are provided to create new error handlers, to associate error handlers with objects, and to test which error handler is associated with an object. C and C++ have distinct typedefs for user defined error handling callback functions that accept communicator, file, and window arguments. In Fortran there are three user routines.

An error handler object is created by a call to `MPI_XXX_CREATE_ERRHANDLER(function, errhandler)`, where XXX is, respectively, `COMM`, `WIN`, or `FILE`.

An error handler is attached to a communicator, window, or file by a call to `MPI_XXX_SET_ERRHANDLER`. The error handler must be either a predefined error handler, or an error handler that was created by a call to `MPI_XXX_CREATE_ERRHANDLER`, with matching XXX. The predefined error handlers `MPI_ERRORS_RETURN` and `MPI_ERRORS_ARE_FATAL` can be attached to communicators, windows, and files. In C++, the predefined error handler `MPI::ERRORS_THROW_EXCEPTIONS` can also be attached to communicators, windows, and files.

The error handler currently associated with a communicator, window, or file can be retrieved by a call to `MPI_XXX_GET_ERRHANDLER`.

The MPI function `MPI_ERRHANDLER_FREE` can be used to free an error handler that was created by a call to `MPI_XXX_CREATE_ERRHANDLER`.

`MPI_{COMM,WIN,FILE}_GET_ERRHANDLER` behave as if a new error handler object is created. That is, once the error handler is no longer needed, `MPI_ERRHANDLER_FREE` should be called with the error handler returned from `MPI_ERRHANDLER_GET` or `MPI_{COMM,WIN,FILE}_GET_ERRHANDLER` to mark the error handler for deallocation. This provides behavior similar to that of `MPI_COMM_GROUP` and `MPI_GROUP_FREE`.

*Advice to implementors.* High-quality implementation should raise an error when an error handler that was created by a call to `MPI_XXX_CREATE_ERRHANDLER` is attached to an object of the wrong type with a call to `MPI_YYY_SET_ERRHANDLER`. To do so, it is necessary to maintain, with each error handler, information on the typedef of the associated user function. (*End of advice to implementors.*)

The syntax for these calls is given below.

## 8.3.1 Error Handlers for Communicators

`MPI_COMM_CREATE_ERRHANDLER(comm_errhandler_fn, errhandler)`

IN [ticket252-W.] `comm_errhandler_fn` user defined error handling procedure (function)

OUT `errhandler` MPI error handler (handle)

```
int MPI_Comm_create_errhandler(MPI_Comm_errhandler_function
                               *comm_errhandler_fn, MPI_Errhandler *errhandler)
```

`MPI_COMM_CREATE_ERRHANDLER(COMM_ERRHANDLER_FN, ERRHANDLER, IERROR)`

EXTERNAL `COMM_ERRHANDLER_FN`

INTEGER `ERRHANDLER`, `IERROR`

```
MPI_Comm_create_errhandler(comm_errhandler_fn, errhandler, ierror)
PROCEDURE(MPI_Comm_errhandler_function) :: comm_errhandler_fn
TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{static MPI::Errhandler
    MPI::Comm::Create_errhandler(MPI::Comm::Errhandler_function*
    comm_errhandler_fn) (binding deprecated, see Section 15.2) }
```

Creates an error handler that can be attached to communicators. This function is identical to `MPI_ERRHANDLER_CREATE`, whose use is deprecated.

The user routine should be, in C, a function of type `MPI_Comm_errhandler_function`, which is defined as

```
typedef void MPI_Comm_errhandler_function(MPI_Comm *, int *, ...);
```

The first argument is the communicator in use. The second is the error code to be returned by the MPI routine that raised the error. If the routine would have returned `MPI_ERR_IN_STATUS`, it is the error code returned in the status for the request that caused the error handler to be invoked. The remaining arguments are “`stdargs`” arguments whose number and meaning is implementation-dependent. An implementation should clearly document these arguments. Addresses are used so that the handler may be written in Fortran. This typedef replaces `MPI_Handler_function`, whose use is deprecated.

With the Fortran `mpi` module and `mpif.h`, the user routine `COMM_ERRHANDLER_FN` should be of the form:

```
SUBROUTINE COMM_ERRHANDLER_FUNCTION(COMM, ERROR_CODE)
    INTEGER COMM, ERROR_CODE
```

With the Fortran `mpi_f08` module, the user routine `comm_errhandler_fn` should be of the form:

```
ABSTRACT INTERFACE
    SUBROUTINE MPI_Comm_errhandler_function(comm, error_code)
        TYPE(MPI_Comm) :: comm
        INTEGER :: error_code
```

In C++, the user routine should be of the form:

```
{typedef void MPI::Comm::Errhandler_function(MPI::Comm &, int *, ...);
    (binding deprecated, see Section 15.2)}
```

*Rationale.* The variable argument list is provided because it provides an ISO-standard hook for providing additional information to the error handler; without this hook, ISO C prohibits additional arguments. (*End of rationale.*)

*Advice to users.* A newly created communicator inherits the error handler that is associated with the “parent” communicator. In particular, the user can specify a “global” error handler for all communicators by associating this handler with the communicator MPI\_COMM\_WORLD immediately after initialization. (*End of advice to users.*)

MPI\_COMM\_SET\_ERRHANDLER(comm, errhandler)

INOUT comm communicator (handle)

IN errhandler new error handler for communicator (handle)

int MPI\_Comm\_set\_errhandler(MPI\_Comm comm, MPI\_Errhandler errhandler)

MPI\_COMM\_SET\_ERRHANDLER(COMM, ERRHANDLER, IERROR)

INTEGER COMM, ERRHANDLER, IERROR

MPI\_Comm\_set\_errhandler(comm, errhandler, ierror)

TYPE(MPI\_Comm), INTENT(IN) :: comm

TYPE(MPI\_Errhandler), INTENT(IN) :: errhandler

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```
{void MPI::Comm::Set_errhandler(const MPI::Errhandler& errhandler) (binding
    deprecated, see Section 15.2) }
```

Attaches a new error handler to a communicator. The error handler must be either a predefined error handler, or an error handler created by a call to MPI\_COMM\_CREATE\_ERRHANDLER. This call is identical to MPI\_ERRHANDLER\_SET, whose use is deprecated.

MPI\_COMM\_GET\_ERRHANDLER(comm, errhandler)

IN comm communicator (handle)

OUT errhandler error handler currently associated with communicator (handle)

int MPI\_Comm\_get\_errhandler(MPI\_Comm comm, MPI\_Errhandler \*errhandler)

MPI\_COMM\_GET\_ERRHANDLER(COMM, ERRHANDLER, IERROR)

INTEGER COMM, ERRHANDLER, IERROR

```

MPI_Comm_get_errhandler(comm, errhandler, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm
    TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{MPI::Errhandler MPI::Comm::Get_errhandler() const(binding deprecated, see
    Section 15.2) }

```

Retrieves the error handler currently associated with a communicator. This call is identical to MPI\_ERRHANDLER\_GET, whose use is deprecated.

Example: A library function may register at its entry point the current error handler for a communicator, set its own private error handler for this communicator, and restore before exiting the previous error handler.

### 8.3.2 Error Handlers for Windows

```

MPI_WIN_CREATE_ERRHANDLER(win_errhandler_fn, errhandler)

```

IN [ticket252-W.] **win\_errhandler\_fn** user defined error handling procedure (function)

OUT errhandler MPI error handler (handle)

```

int MPI_Win_create_errhandler(MPI_Win_errhandler_function
    *win_errhandler_fn, MPI_Errhandler *errhandler)

```

```

MPI_WIN_CREATE_ERRHANDLER(WIN_ERRHANDLER_FN, ERRHANDLER, IERROR)
    EXTERNAL WIN_ERRHANDLER_FN
    INTEGER ERRHANDLER, IERROR

```

```

MPI_Win_create_errhandler(win_errhandler_fn, errhandler, ierror)
    PROCEDURE(MPI_Win_errhandler_function) :: win_errhandler_fn
    TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{static MPI::Errhandler
    MPI::Win::Create_errhandler(MPI::Win::Errhandler_function*
    win_errhandler_fn) (binding deprecated, see Section 15.2) }

```

Creates an error handler that can be attached to a window object. The user routine should be, in C, a function of type MPI\_Win\_errhandler\_function which is defined as

```
typedef void MPI_Win_errhandler_function(MPI_Win *, int *, ...);
```

The first argument is the window in use, the second is the error code to be returned.

With the Fortran **mpi** module and **mpif.h**, the user routine **WIN\_ERRHANDLER\_FN** should be of the form:

```

SUBROUTINE WIN_ERRHANDLER_FUNCTION(WIN, ERROR_CODE)
    INTEGER WIN, ERROR_CODE

```

With the Fortran **mpi\_f08** module, the user routine **win\_errhandler\_fn** should be of the form:

## 1 ABSTRACT INTERFACE

```
2 SUBROUTINE MPI_Win_errhandler_function(win, error_code)
3 TYPE(MPI_Win) :: win
4 INTEGER :: error_code
```

6 In C++, the user routine should be of the form:

```
7 {typedef void MPI::Win::Errhandler_function(MPI::Win &, int *, ...);
8   (binding deprecated, see Section 15.2)}
```

```
11 MPI_WIN_SET_ERRHANDLER(win, errhandler)
```

```
13 INOUT win window (handle)
14 IN errhandler new error handler for window (handle)
```

```
16 int MPI_Win_set_errhandler(MPI_Win win, MPI_Errhandler errhandler)
```

```
18 MPI_WIN_SET_ERRHANDLER(WIN, ERRHANDLER, IERROR)
19 INTEGER WIN, ERRHANDLER, IERROR
```

```
21 MPI_Win_set_errhandler(win, errhandler, ierror)
22 TYPE(MPI_Win), INTENT(IN) :: win
23 TYPE(MPI_Errhandler), INTENT(IN) :: errhandler
24 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
25 {void MPI::Win::Set_errhandler(const MPI::Errhandler& errhandler) (binding
26   deprecated, see Section 15.2) }
```

28 Attaches a new error handler to a window. The error handler must be either a pre-  
29 defined error handler, or an error handler created by a call to  
30 MPI\_WIN\_CREATE\_ERRHANDLER.

```
32 MPI_WIN_GET_ERRHANDLER(win, errhandler)
```

```
34 IN win window (handle)
35 OUT errhandler error handler currently associated with window (han-
36 dle)
```

```
38 int MPI_Win_get_errhandler(MPI_Win win, MPI_Errhandler *errhandler)
```

```
39 MPI_WIN_GET_ERRHANDLER(WIN, ERRHANDLER, IERROR)
40 INTEGER WIN, ERRHANDLER, IERROR
```

```
42 MPI_Win_get_errhandler(win, errhandler, ierror)
43 TYPE(MPI_Win), INTENT(IN) :: win
44 TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
45 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
47 {MPI::Errhandler MPI::Win::Get_errhandler() const (binding deprecated, see
48   Section 15.2) }
```

Retrieves the error handler currently associated with a window.

### 8.3.3 Error Handlers for Files

`MPI_FILE_CREATE_ERRHANDLER(file_errhandler_fn, errhandler)`

IN [ticket252-W.] `file_errhandler_fn` user defined error handling procedure (function)  
OUT `errhandler` MPI error handler (handle)

```
int MPI_File_create_errhandler(MPI_File_errhandler_function
                             *file_errhandler_fn, MPI_Errhandler *errhandler)
```

```
MPI_FILE_CREATE_ERRHANDLER(FILE_ERRHANDLER_FN, ERRHANDLER, IERROR)
EXTERNAL FILE_ERRHANDLER_FN
INTEGER ERRHANDLER, IERROR
```

```
MPI_File_create_errhandler(file_errhandler_fn, errhandler, ierror)
PROCEDURE(MPI_File_errhandler_function) :: file_errhandler_fn
TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{static MPI::Errhandler
    MPI::File::Create_errhandler(MPI::File::Errhandler_function*
    file_errhandler_fn) (binding deprecated, see Section 15.2) }
```

Creates an error handler that can be attached to a file object. The user routine should be, in C, a function of type `MPI_File_errhandler_function`, which is defined as

```
typedef void MPI_File_errhandler_function(MPI_File *, int *, ...);
```

The first argument is the file in use, the second is the error code to be returned.

With the Fortran `mpi` module and `mpif.h`, the user routine `FILE_ERRHANDLER_FN` should be of the form:

```
SUBROUTINE FILE_ERRHANDLER_FUNCTION(FILE, ERROR_CODE)
    INTEGER FILE, ERROR_CODE
```

With the Fortran `mpi_f08` module, the user routine `file_errhandler_fn` should be of the form:

```
ABSTRACT INTERFACE
    SUBROUTINE MPI_File_errhandler_function(file, error_code)
        TYPE(MPI_File) :: file
        INTEGER :: error_code
```

In C++, the user routine should be of the form:

```
{typedef void MPI::File::Errhandler_function(MPI::File &, int *, ...);
    (binding deprecated, see Section 15.2)}
```

1 MPI\_FILE\_SET\_ERRHANDLER(file, errhandler)

2 INOUT file file (handle)

3 IN errhandler new error handler for file (handle)

4  
5  
6 int MPI\_File\_set\_errhandler(MPI\_File file, MPI\_Errhandler errhandler)

7 MPI\_FILE\_SET\_ERRHANDLER(FILE, ERRHANDLER, IERROR)

8 INTEGER FILE, ERRHANDLER, IERROR

9 MPI\_File\_set\_errhandler(file, errhandler, ierror)

10 TYPE(MPI\_File), INTENT(IN) :: file

11 TYPE(MPI\_Errhandler), INTENT(IN) :: errhandler

12 INTEGER, OPTIONAL, INTENT(OUT) :: ierror

13  
14 {void MPI::File::Set\_errhandler(const MPI::Errhandler& errhandler) (*binding*  
15 *deprecated, see Section 15.2*) }

16  
17 Attaches a new error handler to a file. The error handler must be either a predefined  
18 error handler, or an error handler created by a call to MPI\_FILE\_CREATE\_ERRHANDLER.  
19

20  
21 MPI\_FILE\_GET\_ERRHANDLER(file, errhandler)

22 IN file file (handle)

23 OUT errhandler error handler currently associated with file (handle)

24  
25  
26 int MPI\_File\_get\_errhandler(MPI\_File file, MPI\_Errhandler \*errhandler)

27 MPI\_FILE\_GET\_ERRHANDLER(FILE, ERRHANDLER, IERROR)

28 INTEGER FILE, ERRHANDLER, IERROR

29 MPI\_File\_get\_errhandler(file, errhandler, ierror)

30 TYPE(MPI\_File), INTENT(IN) :: file

31 TYPE(MPI\_Errhandler), INTENT(OUT) :: errhandler

32 INTEGER, OPTIONAL, INTENT(OUT) :: ierror

33  
34 {MPI::Errhandler MPI::File::Get\_errhandler() const (*binding deprecated, see*  
35 *Section 15.2*) }

36  
37 Retrieves the error handler currently associated with a file.  
38

### 39 8.3.4 Freeing Errorhandlers and Retrieving Error Strings

40  
41  
42 MPI\_ERRHANDLER\_FREE( errhandler )

43 INOUT errhandler MPI error handler (handle)

44  
45  
46 int MPI\_Errhandler\_free(MPI\_Errhandler \*errhandler)

47 MPI\_ERRHANDLER\_FREE(ERRHANDLER, IERROR)



```

INTEGER ERRHANDLER, IERROR
MPI_Errhandler_free(errhandler, ierror)
  TYPE(MPI_Errhandler), INTENT(INOUT) :: errhandler
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```
{void MPI::Errhandler::Free() (binding deprecated, see Section 15.2) }
```

Marks the error handler associated with `errhandler` for deallocation and sets `errhandler` to `MPI_ERRHANDLER_NULL`. The error handler will be deallocated after all the objects associated with it (communicator, window, or file) have been deallocated.

```
MPI_ERROR_STRING( errorcode, string, resultlen )
```

IN	errorcode	Error code returned by an MPI routine
OUT	string	Text that corresponds to the errorcode
OUT	resultlen	Length (in printable characters) of the result returned in string

```
int MPI_Error_string(int errorcode, char *string, int *resultlen)
```

```
MPI_ERROR_STRING(ERRORCODE, STRING, RESULTLEN, IERROR)
```

```
  INTEGER ERRORCODE, RESULTLEN, IERROR
  CHARACTER*(*) STRING
```

```
MPI_Error_string(errorcode, string, resultlen, ierror)
```

```
  INTEGER, INTENT(IN) :: errorcode
  CHARACTER(LEN=*), INTENT(OUT) :: string
  INTEGER, INTENT(OUT) :: resultlen
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Get_error_string(int errorcode, char* name,
  int& resultlen) (binding deprecated, see Section 15.2) }
```

Returns the error string associated with an error code or class. The argument `string` must represent storage that is at least `MPI_MAX_ERROR_STRING` characters long.

The number of characters actually written is returned in the output argument, `resultlen`.

*Rationale.* The form of this function was chosen to make the Fortran and C bindings similar. A version that returns a pointer to a string has two difficulties. First, the return string must be statically allocated and different for each error message (allowing the pointers returned by successive calls to `MPI_ERROR_STRING` to point to the correct message). Second, in Fortran, a function declared as returning `CHARACTER*(*)` can not be referenced in, for example, a `PRINT` statement. (*End of rationale.*)

## 8.4 Error Codes and Classes

The error codes returned by MPI are left entirely to the implementation (with the exception of `MPI_SUCCESS`). This is done to allow an implementation to provide as much information as possible in the error code (for use with `MPI_ERROR_STRING`).

To make it possible for an application to interpret an error code, the routine `MPI_ERROR_CLASS` converts any error code into one of a small set of standard error codes, called *error classes*. Valid error classes are shown in Table 8.1 and Table 8.2.

The error classes are a subset of the error codes: an MPI function may return an error class number; and the function `MPI_ERROR_STRING` can be used to compute the error string associated with an error class. An MPI error class is a valid MPI error code. Specifically, the values defined for MPI error classes are valid MPI error codes.

The error codes satisfy,

$$0 = \text{MPI\_SUCCESS} < \text{MPI\_ERR\_...} \leq \text{MPI\_ERR\_LASTCODE}.$$

*Rationale.* The difference between `MPI_ERR_UNKNOWN` and `MPI_ERR_OTHER` is that `MPI_ERROR_STRING` can return useful information about `MPI_ERR_OTHER`.

Note that `MPI_SUCCESS = 0` is necessary to be consistent with C practice; the separation of error classes and error codes allows us to define the error classes this way. Having a known `LASTCODE` is often a nice sanity check as well. (*End of rationale.*)

`MPI_ERROR_CLASS( errorcode, errorclass )`

IN	errorcode	Error code returned by an MPI routine
OUT	errorclass	Error class associated with errorcode

`int MPI_Error_class(int errorcode, int *errorclass)`

`MPI_ERROR_CLASS(ERRORCODE, ERRORCLASS, IERROR)`  
`INTEGER ERRORCODE, ERRORCLASS, IERROR`

`MPI_Error_class(errorcode, errorclass, ierror)`  
`INTEGER, INTENT(IN) :: errorcode`  
`INTEGER, INTENT(OUT) :: errorclass`  
`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{int MPI::Get_error_class(int errorcode) (binding deprecated, see Section 15.2) }`

The function `MPI_ERROR_CLASS` maps each standard error code (error class) onto itself.

## 8.5 Error Classes, Error Codes, and Error Handlers

Users may want to write a layered library on top of an existing MPI implementation, and this library may have its own set of error codes and classes. An example of such a library is an I/O library based on MPI, see Chapter 13 on page 445. For this purpose, functions are needed to:

1. add a new error class to the ones an MPI implementation already knows.
2. associate error codes with this error class, so that `MPI_ERROR_CLASS` works.
3. associate strings with these error codes, so that `MPI_ERROR_STRING` works.

MPI_SUCCESS	No error
MPI_ERR_BUFFER	Invalid buffer pointer
MPI_ERR_COUNT	Invalid count argument
MPI_ERR_TYPE	Invalid datatype argument
MPI_ERR_TAG	Invalid tag argument
MPI_ERR_COMM	Invalid communicator
MPI_ERR_RANK	Invalid rank
MPI_ERR_REQUEST	Invalid request (handle)
MPI_ERR_ROOT	Invalid root
MPI_ERR_GROUP	Invalid group
MPI_ERR_OP	Invalid operation
MPI_ERR_TOPOLOGY	Invalid topology
MPI_ERR_DIMS	Invalid dimension argument
MPI_ERR_ARG	Invalid argument of some other kind
MPI_ERR_UNKNOWN	Unknown error
MPI_ERR_TRUNCATE	Message truncated on receive
MPI_ERR_OTHER	Known error not in this list
MPI_ERR_INTERN	Internal MPI (implementation) error
MPI_ERR_IN_STATUS	Error code is in status
MPI_ERR_PENDING	Pending request
MPI_ERR_KEYVAL	Invalid keyval has been passed
MPI_ERR_NO_MEM	MPI_ALLOC_MEM failed because memory is exhausted
MPI_ERR_BASE	Invalid base passed to MPI_FREE_MEM
MPI_ERR_INFO_KEY	Key longer than MPI_MAX_INFO_KEY
MPI_ERR_INFO_VALUE	Value longer than MPI_MAX_INFO_VAL
MPI_ERR_INFO_NOKEY	Invalid key passed to MPI_INFO_DELETE
MPI_ERR_SPAWN	Error in spawning processes
MPI_ERR_PORT	Invalid port name passed to MPI_COMM_CONNECT
MPI_ERR_SERVICE	Invalid service name passed to MPI_UNPUBLISH_NAME
MPI_ERR_NAME	Invalid service name passed to MPI_LOOKUP_NAME
MPI_ERR_WIN	Invalid win argument
MPI_ERR_SIZE	Invalid size argument
MPI_ERR_DISP	Invalid disp argument
MPI_ERR_INFO	Invalid info argument
MPI_ERR_LOCKTYPE	Invalid locktype argument
MPI_ERR_ASSERT	Invalid assert argument
MPI_ERR_RMA_CONFLICT	Conflicting accesses to window
MPI_ERR_RMA_SYNC	Wrong synchronization of RMA calls

Table 8.1: Error classes (Part 1)

1	MPI_ERR_FILE	Invalid file handle
2	MPI_ERR_NOT_SAME	Collective argument not identical on all
3		processes, or collective routines called in
4		a different order by different processes
5	MPI_ERR_AMODE	Error related to the <code>amode</code> passed to
6		<code>MPI_FILE_OPEN</code>
7	MPI_ERR_UNSUPPORTED_DATAREP	Unsupported <code>datarep</code> passed to
8		<code>MPI_FILE_SET_VIEW</code>
9	MPI_ERR_UNSUPPORTED_OPERATION	Unsupported operation, such as seeking on
10		a file which supports sequential access only
11	MPI_ERR_NO_SUCH_FILE	File does not exist
12	MPI_ERR_FILE_EXISTS	File exists
13	MPI_ERR_BAD_FILE	Invalid file name (e.g., path name too long)
14	MPI_ERR_ACCESS	Permission denied
15	MPI_ERR_NO_SPACE	Not enough space
16	MPI_ERR_QUOTA	Quota exceeded
17	MPI_ERR_READ_ONLY	Read-only file or file system
18	MPI_ERR_FILE_IN_USE	File operation could not be completed, as
19		the file is currently open by some process
20	MPI_ERR_DUP_DATAREP	Conversion functions could not be regis-
21		tered because a data representation identi-
22		fier that was already defined was passed to
23		<code>MPI_REGISTER_DATAREP</code>
24	MPI_ERR_CONVERSION	An error occurred in a user supplied data
25		conversion function.
26	MPI_ERR_IO	Other I/O error
27	MPI_ERR_LASTCODE	Last error code

Table 8.2: Error classes (Part 2)

4. invoke the error handler associated with a communicator, window, or object.

Several functions are provided to do this. They are all local. No functions are provided to free error classes or codes: it is not expected that an application will generate them in significant numbers.

`MPI_ADD_ERROR_CLASS(errorclass)`

OUT      errorclass      value for the new error class (integer)

`int MPI_Add_error_class(int *errorclass)`

`MPI_ADD_ERROR_CLASS(ERRORCLASS, IERROR)`

INTEGER ERRORCLASS, IERROR

`MPI_Add_error_class(errorclass, ierror)`

INTEGER, INTENT(OUT) :: errorclass

```

    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
{int MPI::Add_error_class() (binding deprecated, see Section 15.2) }

```

Creates a new error class and returns the value for it.

*Rationale.* To avoid conflicts with existing error codes and classes, the value is set by the implementation and not by the user. (*End of rationale.*)

*Advice to implementors.* A high-quality implementation will return the value for a new `errorclass` in the same deterministic way on all processes. (*End of advice to implementors.*)

*Advice to users.* Since a call to `MPI_ADD_ERROR_CLASS` is local, the same `errorclass` may not be returned on all processes that make this call. Thus, it is not safe to assume that registering a new error on a set of processes at the same time will yield the same `errorclass` on all of the processes. However, if an implementation returns the new `errorclass` in a deterministic way, and they are always generated in the same order on the same set of processes (for example, all processes), then the value will be the same. However, even if a deterministic algorithm is used, the value can vary across processes. This can happen, for example, if different but overlapping groups of processes make a series of calls. As a result of these issues, getting the “same” error on multiple processes may not cause the same value of error code to be generated. (*End of advice to users.*)

The value of `MPI_ERR_LASTCODE` is a constant value and is not affected by new user-defined error codes and classes. Instead, a predefined attribute key `MPI_LASTUSED` is associated with `MPI_COMM_WORLD`. The attribute value corresponding to this key is the current maximum error class including the user-defined ones. This is a local value and may be different on different processes. The value returned by this key is always greater than or equal to `MPI_ERR_LASTCODE`.

*Advice to users.* The value returned by the key `MPI_LASTUSED` will not change unless the user calls a function to explicitly add an error class/code. In a multi-threaded environment, the user must take extra care in assuming this value has not changed. Note that error codes and error classes are not necessarily dense. A user may not assume that each error class below `MPI_LASTUSED` is valid. (*End of advice to users.*)

```

MPI_ADD_ERROR_CODE(errorclass, errorcode)

```

IN	errorclass	error class (integer)
OUT	errorcode	new error code to associated with errorclass (integer)

```

int MPI_Add_error_code(int errorclass, int *errorcode)

```

```

MPI_ADD_ERROR_CODE(ERRORCLASS, ERRORCODE, IERROR)
    INTEGER ERRORCLASS, ERRORCODE, IERROR

```

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```

1 MPI_Add_error_code(errorclass, errorcode, ierror)
2     INTEGER, INTENT(IN) :: errorclass
3     INTEGER, INTENT(OUT) :: errorcode
4     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
5
6 {int MPI::Add_error_code(int errorclass) (binding deprecated, see Section 15.2) }
```

Creates new error code associated with `errorclass` and returns its value in `errorcode`.

*Rationale.* To avoid conflicts with existing error codes and classes, the value of the new error code is set by the implementation and not by the user. (*End of rationale.*)

*Advice to implementors.* A high-quality implementation will return the value for a new `errorcode` in the same deterministic way on all processes. (*End of advice to implementors.*)

```

17 MPI_ADD_ERROR_STRING(errorcode, string)
18
19     IN          errorcode          error code or class (integer)
20     IN          string             text corresponding to errorcode (string)
```

```

22 int MPI_Add_error_string(int errorcode, char *string)
```

```

24 MPI_ADD_ERROR_STRING(ERRORCODE, STRING, IERROR)
25     INTEGER ERRORCODE, IERROR
26     CHARACTER*(*) STRING
```

```

27 MPI_Add_error_string(errorcode, string, ierror)
28     INTEGER, INTENT(IN) :: errorcode
29     CHARACTER(LEN=*), INTENT(IN) :: string
30     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```

32 {void MPI::Add_error_string(int errorcode, const char* string) (binding
33     deprecated, see Section 15.2) }
```

Associates an error string with an error code or class. The string must be no more than `MPI_MAX_ERROR_STRING` characters long. The length of the string is as defined in the calling language. The length of the string does not include the null terminator in C or C++. Trailing blanks will be stripped in Fortran. Calling `MPI_ADD_ERROR_STRING` for an `errorcode` that already has a string will replace the old string with the new string. It is erroneous to call `MPI_ADD_ERROR_STRING` for an error code or class with a value  $\leq$  `MPI_ERR_LASTCODE`.

If `MPI_ERROR_STRING` is called when no string has been set, it will return a empty string (all spaces in Fortran, "" in C and C++).

Section 8.3 on page 325 describes the methods for creating and associating error handlers with communicators, files, and windows.

MPI\_COMM\_CALL\_ERRHANDLER (comm, errorcode)

IN        comm                            communicator with error handler (handle)  
IN        errorcode                      error code (integer)

int MPI\_Comm\_call\_errhandler(MPI\_Comm comm, int errorcode)

MPI\_COMM\_CALL\_ERRHANDLER(COMM, ERRORCODE, IERROR)

INTEGER COMM, ERRORCODE, IERROR

MPI\_Comm\_call\_errhandler(comm, errorcode, ierror)

TYPE(MPI\_Comm), INTENT(IN) :: comm

INTEGER, INTENT(IN) :: errorcode

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Comm::Call\_errhandler(int errorcode) const(*binding deprecated, see  
Section 15.2*) }

This function invokes the error handler assigned to the communicator with the error code supplied. This function returns MPI\_SUCCESS in C and C++ and the same value in IERROR if the error handler was successfully called (assuming the process is not aborted and the error handler returns).

*Advice to users.* Users should note that the default error handler is MPI\_ERRORS\_ARE\_FATAL. Thus, calling MPI\_COMM\_CALL\_ERRHANDLER will abort the comm processes if the default error handler has not been changed for this communicator or on the parent before the communicator was created. (*End of advice to users.*)

MPI\_WIN\_CALL\_ERRHANDLER (win, errorcode)

IN        win                            window with error handler (handle)  
IN        errorcode                      error code (integer)

int MPI\_Win\_call\_errhandler(MPI\_Win win, int errorcode)

MPI\_WIN\_CALL\_ERRHANDLER(WIN, ERRORCODE, IERROR)

INTEGER WIN, ERRORCODE, IERROR

MPI\_Win\_call\_errhandler(win, errorcode, ierror)

TYPE(MPI\_Win), INTENT(IN) :: win

INTEGER, INTENT(IN) :: errorcode

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Win::Call\_errhandler(int errorcode) const(*binding deprecated, see  
Section 15.2*) }

This function invokes the error handler assigned to the window with the error code supplied. This function returns MPI\_SUCCESS in C and C++ and the same value in IERROR if the error handler was successfully called (assuming the process is not aborted and the error handler returns).

*Advice to users.* As with communicators, the default error handler for windows is MPI\_ERRORS\_ARE\_FATAL. (*End of advice to users.*)

MPI\_FILE\_CALL\_ERRHANDLER (fh, errorcode)

IN fh file with error handler (handle)

IN errorcode error code (integer)

int MPI\_File\_call\_errhandler(MPI\_File fh, int errorcode)

MPI\_FILE\_CALL\_ERRHANDLER(FH, ERRORCODE, IERROR)

INTEGER FH, ERRORCODE, IERROR

MPI\_File\_call\_errhandler(fh, errorcode, ierror)

TYPE(MPI\_File), INTENT(IN) :: fh

INTEGER, INTENT(IN) :: errorcode

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::File::Call\_errhandler(int errorcode) const(*binding deprecated, see Section 15.2*) }

This function invokes the error handler assigned to the file with the error code supplied. This function returns MPI\_SUCCESS in C and C++ and the same value in IERROR if the error handler was successfully called (assuming the process is not aborted and the error handler returns).

*Advice to users.* Unlike errors on communicators and windows, the default behavior for files is to have MPI\_ERRORS\_RETURN. (*End of advice to users.*)

*Advice to users.* Users are warned that handlers should not be called recursively with MPI\_COMM\_CALL\_ERRHANDLER, MPI\_FILE\_CALL\_ERRHANDLER, or MPI\_WIN\_CALL\_ERRHANDLER. Doing this can create a situation where an infinite recursion is created. This can occur if MPI\_COMM\_CALL\_ERRHANDLER, MPI\_FILE\_CALL\_ERRHANDLER, or MPI\_WIN\_CALL\_ERRHANDLER is called inside an error handler.

Error codes and classes are associated with a process. As a result, they may be used in any error handler. Error handlers should be prepared to deal with any error code they are given. Furthermore, it is good practice to only call an error handler with the appropriate error codes. For example, file errors would normally be sent to the file error handler. (*End of advice to users.*)

## 8.6 Timers and Synchronization

MPI defines a timer. A timer is specified even though it is not “message-passing,” because timing parallel programs is important in “performance debugging” and because existing timers (both in POSIX 1003.1-1988 and 1003.4D 14.1 and in Fortran 90) are either inconvenient or do not provide adequate access to high-resolution timers. See also Section 2.6.5 on page 22.



MPI\_WTIME()

```
double MPI_Wtime(void)
```

```
DOUBLE PRECISION MPI_WTIME()
```

```
DOUBLE PRECISION MPI_Wtime()
```

```
{double MPI::Wtime() (binding deprecated, see Section 15.2) }
```

MPI\_WTIME returns a floating-point number of seconds, representing elapsed wall-clock time since some time in the past.

The “time in the past” is guaranteed not to change during the life of the process. The user is responsible for converting large numbers of seconds to other units if they are preferred.

This function is portable (it returns seconds, not “ticks”), it allows high-resolution, and carries no unnecessary baggage. One would use it like this:

```
{
    double starttime, endtime;
    starttime = MPI_Wtime();
    .... stuff to be timed ...
    endtime   = MPI_Wtime();
    printf("That took %f seconds\n",endtime-starttime);
}
```

The times returned are local to the node that called them. There is no requirement that different nodes return “the same time.” (But see also the discussion of MPI\_WTIME\_IS\_GLOBAL).

MPI\_WTICK()

```
double MPI_Wtick(void)
```

```
DOUBLE PRECISION MPI_WTICK()
```

```
DOUBLE PRECISION MPI_Wtick()
```

```
{double MPI::Wtick() (binding deprecated, see Section 15.2) }
```

MPI\_WTICK returns the resolution of MPI\_WTIME in seconds. That is, it returns, as a double precision value, the number of seconds between successive clock ticks. For example, if the clock is implemented by the hardware as a counter that is incremented every millisecond, the value returned by MPI\_WTICK should be  $10^{-3}$ .

## 8.7 Startup

One goal of MPI is to achieve *source code portability*. By this we mean that a program written using MPI and complying with the relevant language standards is portable as written, and must not require any source code changes when moved from one system to another. This explicitly does *not* say anything about how an MPI program is started or launched from

the command line, nor what the user must do to set up the environment in which an MPI program will run. However, an implementation may require some setup to be performed before other MPI routines may be called. To provide for this, MPI includes an initialization routine `MPI_INIT`.

`MPI_INIT()`

`int MPI_Init(int *argc, char ***argv)`

`MPI_INIT(IERROR)`

`INTEGER IERROR`

`MPI_Init(ierr)`

`INTEGER, OPTIONAL, INTENT(OUT) :: ierr`

`{void MPI::Init(int& argc, char**& argv) (binding deprecated, see Section 15.2) }`

`{void MPI::Init() (binding deprecated, see Section 15.2) }`

All MPI programs must contain exactly one call to an MPI initialization routine: `MPI_INIT` or `MPI_INIT_THREAD`. Subsequent calls to any initialization routines are erroneous. The only MPI functions that may be invoked before the MPI initialization routines are called are `MPI_GET_VERSION`, `MPI_INITIALIZED`, and `MPI_FINALIZED`. The version for ISO C accepts the `argc` and `argv` that are provided by the arguments to `main` or `NULL`:

`int main(int argc, char **argv)`

`{`

`MPI_Init(&argc, &argv);`

`/* parse arguments */`

`/* main program */`

`MPI_Finalize();     /* see below */`

`}`

The Fortran version takes only `IERROR`.

Conforming implementations of MPI are required to allow applications to pass `NULL` for both the `argc` and `argv` arguments of `main` in C and C++. In C++, there is an alternative binding for `MPI::Init` that does not have these arguments at all.

*Rationale.* In some applications, libraries may be making the call to `MPI_Init`, and may not have access to `argc` and `argv` from `main`. It is anticipated that applications requiring special information about the environment or information supplied by `mpiexec` can get that information from environment variables. (*End of rationale.*)

`MPI_FINALIZE()`

`int MPI_Finalize(void)`

```
MPI_FINALIZE(IERROR)
```

```
    INTEGER IERROR
```

```
MPI_Finalize(ierr)
```

```
    INTEGER, OPTIONAL, INTENT(OUT) :: ierr
```

```
{void MPI::Finalize() (binding deprecated, see Section 15.2) }
```

This routine cleans up all MPI state. Each process must call `MPI_FINALIZE` before it exits. Unless there has been a call to `MPI_ABORT`, each process must ensure that all pending nonblocking communications are (locally) complete before calling `MPI_FINALIZE`. Further, at the instant at which the last process calls `MPI_FINALIZE`, all pending sends must be matched by a receive, and all pending receives must be matched by a send.

For example, the following program is correct:

Process 0	Process 1
-----	-----
<code>MPI_Init();</code>	<code>MPI_Init();</code>
<code>MPI_Send(dest=1);</code>	<code>MPI_Recv(src=0);</code>
<code>MPI_Finalize();</code>	<code>MPI_Finalize();</code>

Without the matching receive, the program is erroneous:

Process 0	Process 1
-----	-----
<code>MPI_Init();</code>	<code>MPI_Init();</code>
<code>MPI_Send (dest=1);</code>	
<code>MPI_Finalize();</code>	<code>MPI_Finalize();</code>

A successful return from a blocking communication operation or from `MPI_WAIT` or `MPI_TEST` tells the user that the buffer can be reused and means that the communication is completed by the user, but does not guarantee that the local process has no more work to do. A successful return from `MPI_REQUEST_FREE` with a request handle generated by an `MPI_ISEND` nullifies the handle but provides no assurance of operation completion. The `MPI_ISEND` is complete only when it is known by some means that a matching receive has completed. `MPI_FINALIZE` guarantees that all local actions required by communications the user has completed will, in fact, occur before it returns.

`MPI_FINALIZE` guarantees nothing about pending communications that have not been completed (completion is assured only by `MPI_WAIT`, `MPI_TEST`, or `MPI_REQUEST_FREE` combined with some other verification of completion).

**Example 8.4** This program is correct:

rank 0	rank 1
=====	=====
...	...
<code>MPI_Isend();</code>	<code>MPI_Recv();</code>
<code>MPI_Request_free();</code>	<code>MPI_Barrier();</code>
<code>MPI_Barrier();</code>	<code>MPI_Finalize();</code>
<code>MPI_Finalize();</code>	<code>exit();</code>
<code>exit();</code>	

**Example 8.5** This program is erroneous and its behavior is undefined:

```

rank 0                                rank 1
=====
...                                  ...
MPI_Isend();                          MPI_Recv();
MPI_Request_free();                   MPI_Finalize();
MPI_Finalize();                       exit();
exit();

```

If no `MPI_BUFFER_DETACH` occurs between an `MPI_BSEND` (or other buffered send) and `MPI_FINALIZE`, the `MPI_FINALIZE` implicitly supplies the `MPI_BUFFER_DETACH`.

**Example 8.6** This program is correct, and after the `MPI_Finalize`, it is as if the buffer had been detached.

```

rank 0                                rank 1
=====
...                                  ...
buffer = malloc(1000000);             MPI_Recv();
MPI_Buffer_attach();                  MPI_Finalize();
MPI_Bsend();                          exit();
MPI_Finalize();
free(buffer);
exit();

```

**Example 8.7** In this example, `MPI_Iprobe()` must return a `FALSE` flag. `MPI_Test_cancelled()` must return a `TRUE` flag, independent of the relative order of execution of `MPI_Cancel()` in process 0 and `MPI_Finalize()` in process 1.

The `MPI_Iprobe()` call is there to make sure the implementation knows that the “tag1” message exists at the destination, without being able to claim that the user knows about it.

```

rank 0                                rank 1
=====
MPI_Init();                          MPI_Init();
MPI_Isend(tag1);                      MPI_Barrier();
MPI_Barrier();                       MPI_Iprobe(tag2);
MPI_Barrier();                       MPI_Barrier();
MPI_Finalize();                      MPI_Finalize();
exit();
MPI_Cancel();
MPI_Wait();
MPI_Test_cancelled();
MPI_Finalize();
exit();

```

*Advice to implementors.* An implementation may need to delay the return from MPI\_FINALIZE until all potential future message cancellations have been processed. One possible solution is to place a barrier inside MPI\_FINALIZE (*End of advice to implementors.*)

Once MPI\_FINALIZE returns, no MPI routine (not even MPI\_INIT) may be called, except for MPI\_GET\_VERSION, MPI\_INITIALIZED, and MPI\_FINALIZED. Each process must complete any pending communication it initiated before it calls MPI\_FINALIZE. If the call returns, each process may continue local computations, or exit, without participating in further MPI communication with other processes. MPI\_FINALIZE is collective over all connected processes. If no processes were spawned, accepted or connected then this means over MPI\_COMM\_WORLD; otherwise it is collective over the union of all processes that have been and continue to be connected, as explained in Section 10.5.4 on page 384.

*Advice to implementors.* Even though a process has completed all the communication it initiated, such communication may not yet be completed from the viewpoint of the underlying MPI system. E.g., a blocking send may have completed, even though the data is still buffered at the sender. The MPI implementation must ensure that a process has completed any involvement in MPI communication before MPI\_FINALIZE returns. Thus, if a process exits after the call to MPI\_FINALIZE, this will not cause an ongoing communication to fail. (*End of advice to implementors.*)

Although it is not required that all processes return from MPI\_FINALIZE, it is required that at least process 0 in MPI\_COMM\_WORLD return, so that users can know that the MPI portion of the computation is over. In addition, in a POSIX environment, they may desire to supply an exit code for each process that returns from MPI\_FINALIZE.

**Example 8.8** The following illustrates the use of requiring that at least one process return and that it be known that process 0 is one of the processes that return. One wants code like the following to work no matter how many processes return.

```
...
MPI_Comm_rank(MPI_COMM_WORLD, &myrank);
...
MPI_Finalize();
if (myrank == 0) {
    resultfile = fopen("outfile","w");
    dump_results(resultfile);
    fclose(resultfile);
}
exit(0);
```

MPI\_INITIALIZED( flag )

OUT	flag	Flag is true if MPI_INIT has been called and false otherwise.
-----	------	---

int MPI\_Initialized(int \*flag)

1 MPI\_INITIALIZED(FLAG, IERROR)

2 LOGICAL FLAG

3 INTEGER IERROR

4 MPI\_Initialized(flag, ierror)

5 LOGICAL, INTENT(OUT) :: flag

6 INTEGER, OPTIONAL, INTENT(OUT) :: ierror

7 {bool MPI::Is\_initialized() *(binding deprecated, see Section 15.2)* }

8 This routine may be used to determine whether MPI\_INIT has been called.  
 9 MPI\_INITIALIZED returns true if the calling process has called MPI\_INIT. Whether  
 10 MPI\_FINALIZE has been called does not affect the behavior of MPI\_INITIALIZED. It is one  
 11 of the few routines that may be called before MPI\_INIT is called.

12 MPI\_ABORT( comm, errorcode )

13 IN comm communicator of tasks to abort

14 IN errorcode error code to return to invoking environment

15 int MPI\_Abort(MPI\_Comm comm, int errorcode)

16 MPI\_ABORT(COMM, ERRORCODE, IERROR)

17 INTEGER COMM, ERRORCODE, IERROR

18 MPI\_Abort(comm, errorcode, ierror)

19 TYPE(MPI\_Comm), INTENT(IN) :: comm

20 INTEGER, INTENT(IN) :: errorcode

21 INTEGER, OPTIONAL, INTENT(OUT) :: ierror

22 {void MPI::Comm::Abort(int errorcode) *(binding deprecated, see Section 15.2)* }

23 This routine makes a “best attempt” to abort all tasks in the group of comm. This  
 24 function does not require that the invoking environment take any action with the error  
 25 code. However, a Unix or POSIX environment should handle this as a **return errorcode**  
 26 from the main program.

27 It may not be possible for an MPI implementation to abort only the processes repre-  
 28 sented by comm if this is a subset of the processes. In this case, the MPI implementation  
 29 should attempt to abort all the connected processes but should not abort any unconnected  
 30 processes. If no processes were spawned, accepted or connected then this has the effect of  
 31 aborting all the processes associated with MPI\_COMM\_WORLD.

32 *Rationale.* The communicator argument is provided to allow for future extensions of  
 33 MPI to environments with, for example, dynamic process management. In particular,  
 34 it allows but does not require an MPI implementation to abort a subset of  
 35 MPI\_COMM\_WORLD. *(End of rationale.)*

36 *Advice to users.* Whether the errorcode is returned from the executable or from the  
 37 MPI process startup mechanism (e.g., `mpiexec`), is an aspect of quality of the MPI  
 38 library but not mandatory. *(End of advice to users.)*

*Advice to implementors.* Where possible, a high-quality implementation will try to return the errorcode from the MPI process startup mechanism (e.g. `mpirexec` or `singleton init`). (*End of advice to implementors.*)

### 8.7.1 Allowing User Functions at Process Termination

There are times in which it would be convenient to have actions happen when an MPI process finishes. For example, a routine may do initializations that are useful until the MPI job (or that part of the job that being terminated in the case of dynamically created processes) is finished. This can be accomplished in MPI by attaching an attribute to `MPI_COMM_SELF` with a callback function. When `MPI_FINALIZE` is called, it will first execute the equivalent of an `MPI_COMM_FREE` on `MPI_COMM_SELF`. This will cause the delete callback function to be executed on all keys associated with `MPI_COMM_SELF`, in the reverse order that they were set on `MPI_COMM_SELF`. If no key has been attached to `MPI_COMM_SELF`, then no callback is invoked. The “freeing” of `MPI_COMM_SELF` occurs before any other parts of MPI are affected. Thus, for example, calling `MPI_FINALIZED` will return `false` in any of these callback functions. Once done with `MPI_COMM_SELF`, the order and rest of the actions taken by `MPI_FINALIZE` is not specified.

*Advice to implementors.* Since attributes can be added from any supported language, the MPI implementation needs to remember the creating language so the correct callback is made. Implementations that use the attribute delete callback on MPI\_COMM\_SELF internally should register their internal callbacks before returning from MPI\_INIT / MPI\_INIT\_THREAD, so that libraries or applications will not have portions of the MPI implementation shut down before the application-level callbacks are made. (*End of advice to implementors.*)

### 8.7.2 Determining Whether MPI Has Finished

One of the goals of MPI was to allow for layered libraries. In order for a library to do this cleanly, it needs to know if MPI is active. In MPI the function `MPI_INITIALIZED` was provided to tell if MPI had been initialized. The problem arises in knowing if MPI has been finalized. Once MPI has been finalized it is no longer active and cannot be restarted. A library needs to be able to determine this to act accordingly. To achieve this the following function is needed:

MPI\_FINALIZED(flag)

OUT	flag	true if MPI was finalized (logical)
-----	------	-------------------------------------

```
int MPI_Finalized(int *flag)
```

MPI\_FINALIZED(FLAG, IERROR)

LOGICAL FLAG

INTEGER IERROR

```
MPI_Finalized(flag, ierror)
```

```
LOGICAL, INTENT(OUT) :: flag
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

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```
1 {bool MPI::Is_finalized() (binding deprecated, see Section 15.2) }
```

```
2
3 This routine returns true if MPI_FINALIZE has completed. It is legal to call
4 MPI_FINALIZED before MPI_INIT and after MPI_FINALIZE.
```

```
5
6 Advice to users. MPI is “active” and it is thus safe to call MPI functions if MPI_INIT
7 has completed and MPI_FINALIZE has not completed. If a library has no other
8 way of knowing whether MPI is active or not, then it can use MPI_INITIALIZED and
9 MPI_FINALIZED to determine this. For example, MPI is “active” in callback functions
10 that are invoked during MPI_FINALIZE. (End of advice to users.)
```

## 12 8.8 Portable MPI Process Startup

```
13
14 A number of implementations of MPI provide a startup command for MPI programs that
15 is of the form
```

```
16      mpirun <mpirun arguments> <program> <program arguments>
```

```
17
18 Separating the command to start the program from the program itself provides flexibility,
19 particularly for network and heterogeneous implementations. For example, the startup
20 script need not run on one of the machines that will be executing the MPI program itself.
```

```
21 Having a standard startup mechanism also extends the portability of MPI programs one
22 step further, to the command lines and scripts that manage them. For example, a validation
23 suite script that runs hundreds of programs can be a portable script if it is written using such
24 a standard startup mechanism. In order that the “standard” command not be confused with
25 existing practice, which is not standard and not portable among implementations, instead
26 of mpirun MPI specifies mpiexec.
```

```
27 While a standardized startup mechanism improves the usability of MPI, the range of
28 environments is so diverse (e.g., there may not even be a command line interface) that MPI
29 cannot mandate such a mechanism. Instead, MPI specifies an mpiexec startup command
30 and recommends but does not require it, as advice to implementors. However, if an im-
31 plementation does provide a command called mpiexec, it must be of the form described
32 below.
```

```
33 It is suggested that
```

```
34
35      mpiexec -n <numprocs> <program>
```

```
36
37 be at least one way to start <program> with an initial MPI_COMM_WORLD whose group
38 contains <numprocs> processes. Other arguments to mpiexec may be implementation-
39 dependent.
```

```
40 Advice to implementors. Implementors, if they do provide a special startup command
41 for MPI programs, are advised to give it the following form. The syntax is chosen in
42 order that mpiexec be able to be viewed as a command-line version of
43 MPI_COMM_SPAWN (See Section 10.3.4).
```

```
44 Analogous to MPI_COMM_SPAWN, we have
```

```
45
46
47      mpiexec -n      <maxprocs>
48              -soft  <      >
```



```

-host <      >
-arch <      >
-wdir <      >
-path <      >
-file <      >
...
<command line>

```

for the case where a single command line for the application program and its arguments will suffice. See Section 10.3.4 for the meanings of these arguments. For the case corresponding to MPI\_COMM\_SPAWN\_MULTIPLE there are two possible formats:

Form A:

```
mpiexec { <above arguments> } : { ... } : { ... } : ... : { ... }
```

As with MPI\_COMM\_SPAWN, all the arguments are optional. (Even the `-n x` argument is optional; the default is implementation dependent. It might be 1, it might be taken from an environment variable, or it might be specified at compile time.) The names and meanings of the arguments are taken from the keys in the `info` argument to MPI\_COMM\_SPAWN. There may be other, implementation-dependent arguments as well.

Note that Form A, though convenient to type, prevents colons from being program arguments. Therefore an alternate, file-based form is allowed:

Form B:

```
mpiexec -configfile <filename>
```

where the lines of `<filename>` are of the form separated by the colons in Form A. Lines beginning with `#` are comments, and lines may be continued by terminating the partial line with `\`.

**Example 8.9** Start 16 instances of `myprog` on the current or default machine:

```
mpiexec -n 16 myprog
```

**Example 8.10** Start 10 processes on the machine called `ferrari`:

```
mpiexec -n 10 -host ferrari myprog
```

**Example 8.11** Start three copies of the same program with different command-line arguments:

```
mpiexec myprog infile1 : myprog infile2 : myprog infile3
```

**Example 8.12** Start the `ocean` program on five Suns and the `atmos` program on 10 RS/6000's:

```
mpiexec -n 5 -arch sun ocean : -n 10 -arch rs6000 atmos
```

It is assumed that the implementation in this case has a method for choosing hosts of the appropriate type. Their ranks are in the order specified.

**Example 8.13** Start the `ocean` program on five Suns and the `atmos` program on 10 RS/6000's (Form B):

```
mpiexec -configfile myfile
```

where `myfile` contains

```
-n 5 -arch sun    ocean
-n 10 -arch rs6000 atmos
```

*(End of advice to implementors.)*

# Chapter 9

## The Info Object

Many of the routines in MPI take an argument `info`. `info` is an opaque object with a handle of type `MPI_Info` in C and Fortran with the `mpi_f08` module, `MPI::Info` in C++, and `INTEGER` in Fortran with the `mpi` module or the include file `mpif.h`. It stores an unordered set of (key,value) pairs (both key and value are strings). A key can have only one value. MPI reserves several keys and requires that if an implementation uses a reserved key, it must provide the specified functionality. An implementation is not required to support these keys and may support any others not reserved by MPI.

An implementation must support info objects as caches for arbitrary (key, value) pairs, regardless of whether it recognizes the key. Each function that takes hints in the form of an `MPI_Info` must be prepared to ignore any key it does not recognize. This description of info objects does not attempt to define how a particular function should react if it recognizes a key but not the associated value. `MPI_INFO_GET_NKEYS`, `MPI_INFO_GET_NTHKEY`, `MPI_INFO_GET_VALUELEN`, and `MPI_INFO_GET` must retain all (key,value) pairs so that layered functionality can also use the `Info` object.

Keys have an implementation-defined maximum length of `MPI_MAX_INFO_KEY`, which is at least 32 and at most 255. Values have an implementation-defined maximum length of `MPI_MAX_INFO_VAL`. In Fortran, leading and trailing spaces are stripped from both. Returned values will never be larger than these maximum lengths. Both key and value are case sensitive.

*Rationale.* Keys have a maximum length because the set of known keys will always be finite and known to the implementation and because there is no reason for keys to be complex. The small maximum size allows applications to declare keys of size `MPI_MAX_INFO_KEY`. The limitation on value sizes is so that an implementation is not forced to deal with arbitrarily long strings. (*End of rationale.*)

*Advice to users.* `MPI_MAX_INFO_VAL` might be very large, so it might not be wise to declare a string of that size. (*End of advice to users.*)

When it is an argument to a nonblocking routine, `info` is parsed before that routine returns, so that it may be modified or freed immediately after return.

When the descriptions refer to a key or value as being a boolean, an integer, or a list, they mean the string representation of these types. An implementation may define its own rules for how info value strings are converted to other types, but to ensure portability, every implementation must support the following representations. Legal values for a boolean must

include the strings “true” and “false” (all lowercase). For integers, legal values must include string representations of decimal values of integers that are within the range of a standard integer type in the program. (However it is possible that not every legal integer is a legal value for a given key.) On positive numbers, + signs are optional. No space may appear between a + or – sign and the leading digit of a number. For comma separated lists, the string must contain legal elements separated by commas. Leading and trailing spaces are stripped automatically from the types of info values described above and for each element of a comma separated list. These rules apply to all info values of these types. Implementations are free to specify a different interpretation for values of other info keys.

**MPI\_INFO\_CREATE**(info)

OUT      info                                  info object created (handle)

int MPI\_Info\_create(MPI\_Info \*info)

MPI\_INFO\_CREATE(INFO, IERROR)

INTEGER INFO, IERROR

**MPI\_Info\_create**(info, ierror)

TYPE(MPI\_Info), INTENT(OUT) :: info

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{static MPI::Info MPI::Info::Create() (*binding deprecated, see Section 15.2*) }

MPI\_INFO\_CREATE creates a new info object. The newly created object contains no key/value pairs.

**MPI\_INFO\_SET**(info, key, value)

INOUT    info                                  info object (handle)

IN        key                                  key (string)

IN        value                                value (string)

int MPI\_Info\_set(MPI\_Info info, char \*key, char \*value)

MPI\_INFO\_SET(INFO, KEY, VALUE, IERROR)

INTEGER INFO, IERROR

CHARACTER\*(\*) KEY, VALUE

**MPI\_Info\_set**(info, key, value, ierror)

TYPE(MPI\_Info), INTENT(IN) :: info

CHARACTER(LEN=\*), INTENT(IN) :: key, value

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Info::Set(const char\* key, const char\* value) (*binding deprecated, see Section 15.2*) }

MPI\_INFO\_SET adds the (key,value) pair to info, and overrides the value if a value for the same key was previously set. key and value are null-terminated strings in C. In Fortran,

leading and trailing spaces in key and value are stripped. If either key or value are larger than the allowed maximums, the errors MPI\_ERR\_INFO\_KEY or MPI\_ERR\_INFO\_VALUE are raised, respectively.

MPI\_INFO\_DELETE(info, key)

INOUT	info	info object (handle)
IN	key	key (string)

int MPI\_Info\_delete(MPI\_Info info, char \*key)

MPI\_INFO\_DELETE(INFO, KEY, IERROR)

INTEGER INFO, IERROR

CHARACTER\*(\*) KEY

MPI\_Info\_delete(info, key, ierror)

TYPE(MPI\_Info), INTENT(IN) :: info

CHARACTER(LEN=\*), INTENT(IN) :: key

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Info::Delete(const char\* key) (*binding deprecated, see Section 15.2*) }

MPI\_INFO\_DELETE deletes a (key,value) pair from info. If key is not defined in info, the call raises an error of class MPI\_ERR\_INFO\_NOKEY.

MPI\_INFO\_GET(info, key, valuelen, value, flag)

IN	info	info object (handle)
IN	key	key (string)
IN	valuelen	length of value arg (integer)
OUT	value	value (string)
OUT	flag	true if key defined, false if not (boolean)

int MPI\_Info\_get(MPI\_Info info, char \*key, int valuelen, char \*value, int \*flag)

MPI\_INFO\_GET(INFO, KEY, VALUELEN, VALUE, FLAG, IERROR)

INTEGER INFO, VALUELEN, IERROR

CHARACTER\*(\*) KEY, VALUE

LOGICAL FLAG

MPI\_Info\_get(info, key, valuelen, value, flag, ierror)

TYPE(MPI\_Info), INTENT(IN) :: info

CHARACTER(LEN=\*), INTENT(IN) :: key

INTEGER, INTENT(IN) :: valuelen

CHARACTER(LEN=\*), INTENT(OUT) :: value

LOGICAL, INTENT(OUT) :: flag

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

1  {bool MPI::Info::Get(const char* key, int valuelen, char* value)
2      const(binding deprecated, see Section 15.2) }
3

```

This function retrieves the value associated with key in a previous call to MPI\_INFO\_SET. If such a key exists, it sets flag to true and returns the value in value, otherwise it sets flag to false and leaves value unchanged. valuelen is the number of characters available in value. If it is less than the actual size of the value, the value is truncated. In C, valuelen should be one less than the amount of allocated space to allow for the null terminator.

If key is larger than MPI\_MAX\_INFO\_KEY, the call is erroneous.

```

12 MPI_INFO_GET_VALUELEN(info, key, valuelen, flag)
13

```

14	IN	info	info object (handle)
15	IN	key	key (string)
16	OUT	valuelen	length of value arg (integer)
17	OUT	flag	true if key defined, false if not (boolean)

```

19
20 int MPI_Info_get_valuelen(MPI_Info info, char *key, int *valuelen,
21                          int *flag)
22

```

```

23 MPI_INFO_GET_VALUELEN(INFO, KEY, VALUELEN, FLAG, IERROR)
24     INTEGER INFO, VALUELEN, IERROR
25     LOGICAL FLAG
26     CHARACTER*(*) KEY

```

```

27 MPI_Info_get_valuelen(info, key, valuelen, flag, ierror)
28     TYPE(MPI_Info), INTENT(IN) :: info
29     CHARACTER(LEN=*), INTENT(IN) :: key
30     INTEGER, INTENT(OUT) :: valuelen
31     LOGICAL, INTENT(OUT) :: flag
32     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

33 {bool MPI::Info::Get_valuelen(const char* key, int& valuelen) const(binding
34     deprecated, see Section 15.2) }
35

```

Retrieves the length of the value associated with key. If key is defined, valuelen is set to the length of its associated value and flag is set to true. If key is not defined, valuelen is not touched and flag is set to false. The length returned in C or C++ does not include the end-of-string character.

If key is larger than MPI\_MAX\_INFO\_KEY, the call is erroneous.

```

42 MPI_INFO_GET_NKEYS(info, nkeys)
43

```

44	IN	info	info object (handle)
45	OUT	nkeys	number of defined keys (integer)

```

47 int MPI_Info_get_nkeys(MPI_Info info, int *nkeys)
48

```

```
MPI_INFO_GET_NKEYS(INFO, NKEYS, IERROR)
    INTEGER INFO, NKEYS, IERROR
```

```
MPI_Info_get_nkeys(info, nkeys, ierror)
    TYPE(MPI_Info), INTENT(IN) :: info
    INTEGER, INTENT(OUT) :: nkeys
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{int MPI::Info::Get_nkeys() const(binding deprecated, see Section 15.2) }
```

MPI\_INFO\_GET\_NKEYS returns the number of currently defined keys in info.

```
MPI_INFO_GET_NTHKEY(info, n, key)
```

IN	info	info object (handle)
IN	n	key number (integer)
OUT	key	key (string)

```
int MPI_Info_get_nthkey(MPI_Info info, int n, char *key)
```

```
MPI_INFO_GET_NTHKEY(INFO, N, KEY, IERROR)
    INTEGER INFO, N, IERROR
    CHARACTER*(*) KEY
```

```
MPI_Info_get_nthkey(info, n, key, ierror)
    TYPE(MPI_Info), INTENT(IN) :: info
    INTEGER, INTENT(IN) :: n
    CHARACTER(LEN=*), INTENT(OUT) :: key
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Info::Get_nthkey(int n, char* key) const(binding deprecated, see
    Section 15.2) }
```

This function returns the *n*th defined key in info. Keys are numbered  $0 \dots N - 1$  where *N* is the value returned by MPI\_INFO\_GET\_NKEYS. All keys between 0 and  $N - 1$  are guaranteed to be defined. The number of a given key does not change as long as info is not modified with MPI\_INFO\_SET or MPI\_INFO\_DELETE.

```
MPI_INFO_DUP(info, newinfo)
```

IN	info	info object (handle)
OUT	newinfo	info object (handle)

```
int MPI_Info_dup(MPI_Info info, MPI_Info *newinfo)
```

```
MPI_INFO_DUP(INFO, NEWINFO, IERROR)
    INTEGER INFO, NEWINFO, IERROR
```

```
MPI_Info_dup(info, newinfo, ierror)
    TYPE(MPI_Info), INTENT(IN) :: info
```

```

1      TYPE(MPI_Info), INTENT(OUT) :: newinfo
2      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
3
4      {MPI::Info MPI::Info::Dup() const(binding deprecated, see Section 15.2) }
5
6      MPI_INFO_DUP duplicates an existing info object, creating a new object, with the
7      same (key,value) pairs and the same ordering of keys.
8
9      MPI_INFO_FREE(info)
10     INOUT    info                      info object (handle)
11
12     int MPI_Info_free(MPI_Info *info)
13
14     MPI_INFO_FREE(INFO, IERROR)
15     INTEGER INFO, IERROR
16
17     MPI_Info_free(info, ierror)
18     TYPE(MPI_Info), INTENT(INOUT) :: info
19     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
20
21     {void MPI::Info::Free() (binding deprecated, see Section 15.2) }

```

This function frees info and sets it to MPI\_INFO\_NULL. The value of an info argument is interpreted each time the info is passed to a routine. Changes to an info after return from a routine do not affect that interpretation.



# Chapter 10

## Process Creation and Management

### 10.1 Introduction

MPI is primarily concerned with communication rather than process or resource management. However, it is necessary to address these issues to some degree in order to define a useful framework for communication. This chapter presents a set of MPI interfaces that allow for a variety of approaches to process management while placing minimal restrictions on the execution environment.

The MPI model for process creation allows both the creation of an initial set of processes related by their membership in a common MPI\_COMM\_WORLD and the creation and management of processes after an MPI application has been started. A major impetus for the later form of process creation comes from the PVM [23] research effort. This work has provided a wealth of experience with process management and resource control that illustrates their benefits and potential pitfalls.

The MPI Forum decided not to address resource control because it was not able to design a portable interface that would be appropriate for the broad spectrum of existing and potential resource and process controllers. Resource control can encompass a wide range of abilities, including adding and deleting nodes from a virtual parallel machine, reserving and scheduling resources, managing compute partitions of an MPP, and returning information about available resources. assumes that resource control is provided externally — probably by computer vendors, in the case of tightly coupled systems, or by a third party software package when the environment is a cluster of workstations.

The reasons for including process management in MPI are both technical and practical. Important classes of message-passing applications require process control. These include task farms, serial applications with parallel modules, and problems that require a run-time assessment of the number and type of processes that should be started. On the practical side, users of workstation clusters who are migrating from PVM to MPI may be accustomed to using PVM's capabilities for process and resource management. The lack of these features would be a practical stumbling block to migration.

The following goals are central to the design of MPI process management:

- The MPI process model must apply to the vast majority of current parallel environments. These include everything from tightly integrated MPPs to heterogeneous networks of workstations.
- MPI must not take over operating system responsibilities. It should instead provide a

clean interface between an application and system software.

- MPI must guarantee communication determinism in the presense of dynamic processes, i.e., dynamic process management must not introduce unavoidable race conditions.
- MPI must not contain features that compromise performance.

The process management model addresses these issues in two ways. First, MPI remains primarily a communication library. It does not manage the parallel environment in which a parallel program executes, though it provides a minimal interface between an application and external resource and process managers.

Second, MPI maintains a consistent concept of a communicator, regardless of how its members came into existence. A communicator is never changed once created, and it is always created using deterministic collective operations.

## 10.2 The Dynamic Process Model

The dynamic process model allows for the creation and cooperative termination of processes after an MPI application has started. It provides a mechanism to establish communication between the newly created processes and the existing MPI application. It also provides a mechanism to establish communication between two existing MPI applications, even when one did not “start” the other.

### 10.2.1 Starting Processes

MPI applications may start new processes through an interface to an external process manager.

MPI\_COMM\_SPAWN starts MPI processes and establishes communication with them, returning an intercommunicator. MPI\_COMM\_SPAWN\_MULTIPLE starts several different binaries (or the same binary with different arguments), placing them in the same MPI\_COMM\_WORLD and returning an intercommunicator.

MPI uses the existing group abstraction to represent processes. A process is identified by a (group, rank) pair.

### 10.2.2 The Runtime Environment

The MPI\_COMM\_SPAWN and MPI\_COMM\_SPAWN\_MULTIPLE routines provide an interface between MPI and the *runtime environment* of an MPI application. The difficulty is that there is an enormous range of runtime environments and application requirements, and MPI must not be tailored to any particular one. Examples of such environments are:

- **MPP managed by a batch queueing system.** Batch queueing systems generally allocate resources before an application begins, enforce limits on resource use (CPU time, memory use, etc.), and do not allow a change in resource allocation after a job begins. Moreover, many MPPs have special limitations or extensions, such as a limit on the number of processes that may run on one processor, or the ability to gang-schedule processes of a parallel application.

- **Network of workstations with PVM.** PVM (Parallel Virtual Machine) allows a user to create a “virtual machine” out of a network of workstations. An application may extend the virtual machine or manage processes (create, kill, redirect output, etc.) through the PVM library. Requests to manage the machine or processes may be intercepted and handled by an external resource manager.
- **Network of workstations managed by a load balancing system.** A load balancing system may choose the location of spawned processes based on dynamic quantities, such as load average. It may transparently migrate processes from one machine to another when a resource becomes unavailable.
- **Large SMP with Unix.** Applications are run directly by the user. They are scheduled at a low level by the operating system. Processes may have special scheduling characteristics (gang-scheduling, processor affinity, deadline scheduling, processor locking, etc.) and be subject to OS resource limits (number of processes, amount of memory, etc.).

MPI assumes, implicitly, the existence of an environment in which an application runs. It does not provide “operating system” services, such as a general ability to query what processes are running, to kill arbitrary processes, to find out properties of the runtime environment (how many processors, how much memory, etc.).

Complex interaction of an MPI application with its runtime environment should be done through an environment-specific API. An example of such an API would be the PVM task and machine management routines — `pvm_addhosts`, `pvm_config`, `pvm_tasks`, etc., possibly modified to return an MPI (group,rank) when possible. A Condor or PBS API would be another possibility.

At some low level, obviously, MPI must be able to interact with the runtime system, but the interaction is not visible at the application level and the details of the interaction are not specified by the MPI standard.

In many cases, it is impossible to keep environment-specific information out of the MPI interface without seriously compromising MPI functionality. To permit applications to take advantage of environment-specific functionality, many MPI routines take an `info` argument that allows an application to specify environment-specific information. There is a tradeoff between functionality and portability: applications that make use of `info` are not portable.

MPI does not require the existence of an underlying “virtual machine” model, in which there is a consistent global view of an MPI application and an implicit “operating system” managing resources and processes. For instance, processes spawned by one task may not be visible to another; additional hosts added to the runtime environment by one process may not be visible in another process; tasks spawned by different processes may not be automatically distributed over available resources.

Interaction between MPI and the runtime environment is limited to the following areas:

- A process may start new processes with `MPI_COMM_SPAWN` and `MPI_COMM_SPAWN_MULTIPLE`.
- When a process spawns a child process, it may optionally use an `info` argument to tell the runtime environment where or how to start the process. This extra information may be opaque to MPI.

- An attribute `MPI_UNIVERSE_SIZE` on `MPI_COMM_WORLD` tells a program how “large” the initial runtime environment is, namely how many processes can usefully be started in all. One can subtract the size of `MPI_COMM_WORLD` from this value to find out how many processes might usefully be started in addition to those already running.

## 10.3 Process Manager Interface

### 10.3.1 Processes in MPI

A process is represented in MPI by a (group, rank) pair. A (group, rank) pair specifies a unique process but a process does not determine a unique (group, rank) pair, since a process may belong to several groups.

### 10.3.2 Starting Processes and Establishing Communication

The following routine starts a number of MPI processes and establishes communication with them, returning an intercommunicator.

*Advice to users.* It is possible in MPI to start a static SPMD or MPMD application by starting first one process and having that process start its siblings with `MPI_COMM_SPAWN`. This practice is discouraged primarily for reasons of performance. If possible, it is preferable to start all processes at once, as a single MPI application. (*End of advice to users.*)

`MPI_COMM_SPAWN(command, argv, maxprocs, info, root, comm, intercomm,  
array_of_errcodes)`

IN	command	name of program to be spawned (string, significant only at root)
IN	argv	arguments to <code>command</code> (array of strings, significant only at root)
IN	maxprocs	maximum number of processes to start (integer, significant only at root)
IN	info	a set of key-value pairs telling the runtime system where and how to start the processes (handle, significant only at root)
IN	root	rank of process in which previous arguments are examined (integer)
IN	comm	intracommunicator containing group of spawning processes (handle)
OUT	intercomm	intercommunicator between original group and the newly spawned group (handle)
OUT	array_of_errcodes	one code per process (array of integer)

```

int MPI_Comm_spawn(char *command, char *argv[], int maxprocs, MPI_Info
                    info, int root, MPI_Comm comm, MPI_Comm *intercomm,
                    int array_of_errcodes[])
MPI_COMM_SPAWN(COMMAND, ARGV, MAXPROCS, INFO, ROOT, COMM, INTERCOMM,
                ARRAY_OF_ERRCODES, IERROR)
CHARACTER*(*) COMMAND, ARGV(*)
INTEGER INFO, MAXPROCS, ROOT, COMM, INTERCOMM, ARRAY_OF_ERRCODES(*),
IERROR
MPI_Comm_spawn(command, argv, maxprocs, info, root, comm, intercomm,
                array_of_errcodes, ierror)
CHARACTER(LEN=*), INTENT(IN) :: command, argv(*)
INTEGER, INTENT(IN) :: maxprocs, root
TYPE(MPI_Info), INTENT(IN) :: info
TYPE(MPI_Comm), INTENT(IN) :: comm
TYPE(MPI_Comm), INTENT(OUT) :: intercomm
INTEGER, INTENT(OUT) :: array_of_errcodes(*) ! optional by
overloading
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
{MPI::Intercomm MPI::Intracomm::Spawn(const char* command,
const char* argv[], int maxprocs, const MPI::Info& info,
int root, int array_of_errcodes[]) const(binding deprecated, see
Section 15.2) }
{MPI::Intercomm MPI::Intracomm::Spawn(const char* command,
const char* argv[], int maxprocs, const MPI::Info& info,
int root) const(binding deprecated, see Section 15.2) }

```

MPI\_COMM\_SPAWN tries to start maxprocs identical copies of the MPI program specified by command, establishing communication with them and returning an intercommunicator. The spawned processes are referred to as children. The children have their own MPI\_COMM\_WORLD, which is separate from that of the parents. MPI\_COMM\_SPAWN is collective over comm, and also may not return until MPI\_INIT has been called in the children. Similarly, MPI\_INIT in the children may not return until all parents have called MPI\_COMM\_SPAWN. In this sense, MPI\_COMM\_SPAWN in the parents and MPI\_INIT in the children form a collective operation over the union of parent and child processes. The intercommunicator returned by MPI\_COMM\_SPAWN contains the parent processes in the local group and the child processes in the remote group. The ordering of processes in the local and remote groups is the same as the ordering of the group of the comm in the parents and of MPI\_COMM\_WORLD of the children, respectively. This intercommunicator can be obtained in the children through the function MPI\_COMM\_GET\_PARENT.

*Advice to users.* An implementation may automatically establish communication before MPI\_INIT is called by the children. Thus, completion of MPI\_COMM\_SPAWN in the parent does not necessarily mean that MPI\_INIT has been called in the children (although the returned intercommunicator can be used immediately). (*End of advice to users.*)

The `command` argument The `command` argument is a string containing the name of a program to be spawned. The string is null-terminated in C. In Fortran, leading and trailing spaces are stripped. MPI does not specify how to find the executable or how the working directory is determined. These rules are implementation-dependent and should be appropriate for the runtime environment.

*Advice to implementors.* The implementation should use a natural rule for finding executables and determining working directories. For instance, a homogeneous system with a global file system might look first in the working directory of the spawning process, or might search the directories in a `PATH` environment variable as do Unix shells. An implementation on top of PVM would use PVM's rules for finding executables (usually in `$HOME/pvm3/bin/$PVM_ARCH`). An MPI implementation running under POE on an IBM SP would use POE's method of finding executables. An implementation should document its rules for finding executables and determining working directories, and a high-quality implementation should give the user some control over these rules. (*End of advice to implementors.*)

If the program named in `command` does not call `MPI_INIT`, but instead forks a process that calls `MPI_INIT`, the results are undefined. Implementations may allow this case to work but are not required to.

*Advice to users.* MPI does not say what happens if the program you start is a shell script and that shell script starts a program that calls `MPI_INIT`. Though some implementations may allow you to do this, they may also have restrictions, such as requiring that arguments supplied to the shell script be supplied to the program, or requiring that certain parts of the environment not be changed. (*End of advice to users.*)

The `argv` argument `argv` is an array of strings containing arguments that are passed to the program. The first element of `argv` is the first argument passed to `command`, not, as is conventional in some contexts, the command itself. The argument list is terminated by `NULL` in C and C++ and an empty string in Fortran. In Fortran, leading and trailing spaces are always stripped, so that a string consisting of all spaces is considered an empty string. The constant `MPI_ARGV_NULL` may be used in C, C++ and Fortran to indicate an empty argument list. In C and C++, this constant is the same as `NULL`.

#### Example 10.1 Examples of `argv` in C and Fortran

To run the program "ocean" with arguments "-gridfile" and "ocean1.grd" in C:

```
char command[] = "ocean";
char *argv[] = {"-gridfile", "ocean1.grd", NULL};
MPI_Comm_spawn(command, argv, ...);
```

or, if not everything is known at compile time:

```

char *command;
char **argv;
command = "ocean";
argv=(char **)malloc(3 * sizeof(char *));
argv[0] = "-gridfile";
argv[1] = "ocean1.grd";
argv[2] = NULL;
MPI_Comm_spawn(command, argv, ...);

```

In Fortran:

```

CHARACTER*25 command, argv(3)
command = ' ocean '
argv(1) = ' -gridfile '
argv(2) = ' ocean1.grd'
argv(3) = ' '
call MPI_COMM_SPAWN(command, argv, ...)

```

Arguments are supplied to the program if this is allowed by the operating system. In C, the `MPI_COMM_SPAWN` argument `argv` differs from the `argv` argument of `main` in two respects. First, it is shifted by one element. Specifically, `argv[0]` of `main` is provided by the implementation and conventionally contains the name of the program (given by `command`). `argv[1]` of `main` corresponds to `argv[0]` in `MPI_COMM_SPAWN`, `argv[2]` of `main` to `argv[1]` of `MPI_COMM_SPAWN`, etc. Second, `argv` of `MPI_COMM_SPAWN` must be null-terminated, so that its length can be determined. Passing an `argv` of `MPI_ARGV_NULL` to `MPI_COMM_SPAWN` results in `main` receiving `argc` of 1 and an `argv` whose element 0 is (conventionally) the name of the program.

If a Fortran implementation supplies routines that allow a program to obtain its arguments, the arguments may be available through that mechanism. In C, if the operating system does not support arguments appearing in `argv` of `main()`, the MPI implementation may add the arguments to the `argv` that is passed to `MPI_INIT`.

The `maxprocs` argument MPI tries to spawn `maxprocs` processes. If it is unable to spawn `maxprocs` processes, it raises an error of class `MPI_ERR_SPAWN`.

An implementation may allow the `info` argument to change the default behavior, such that if the implementation is unable to spawn all `maxprocs` processes, it may spawn a smaller number of processes instead of raising an error. In principle, the `info` argument may specify an arbitrary set  $\{m_i : 0 \leq m_i \leq \text{maxprocs}\}$  of allowed values for the number of processes spawned. The set  $\{m_i\}$  does not necessarily include the value `maxprocs`. If an implementation is able to spawn one of these allowed numbers of processes, `MPI_COMM_SPAWN` returns successfully and the number of spawned processes,  $m$ , is given by the size of the remote group of `intercomm`. If  $m$  is less than `maxproc`, reasons why the other processes were not spawned are given in `array_of_errcodes` as described below. If it is not possible to spawn one of the allowed numbers of processes, `MPI_COMM_SPAWN` raises an error of class `MPI_ERR_SPAWN`.

A spawn call with the default behavior is called *hard*. A spawn call for which fewer than `maxprocs` processes may be returned is called *soft*. See Section 10.3.4 on page 368 for more information on the `soft` key for `info`.

*Advice to users.* By default, requests are hard and MPI errors are fatal. This means that by default there will be a fatal error if MPI cannot spawn all the requested processes. If you want the behavior “spawn as many processes as possible, up to  $N$ ,” you should do a soft spawn, where the set of allowed values  $\{m_i\}$  is  $\{0 \dots N\}$ . However, this is not completely portable, as implementations are not required to support soft spawning. (*End of advice to users.*)

**The info argument** The info argument to all of the routines in this chapter is an opaque handle of type `MPI_Info` in C and Fortran with the `mpi_f08` module, `MPI::Info` in C++ and `INTEGER` in Fortran with the `mpi` module or the include file `mpif.h`. It is a container for a number of user-specified (key,value) pairs. key and value are strings (null-terminated `char*` in C, `character(*)` in Fortran). Routines to create and manipulate the info argument are described in Section 9 on page 351.

For the `SPAWN` calls, info provides additional (and possibly implementation-dependent) instructions to MPI and the runtime system on how to start processes. An application may pass `MPI_INFO_NULL` in C or Fortran. Portable programs not requiring detailed control over process locations should use `MPI_INFO_NULL`.

MPI does not specify the content of the info argument, except to reserve a number of special key values (see Section 10.3.4 on page 368). The info argument is quite flexible and could even be used, for example, to specify the executable and its command-line arguments. In this case the `command` argument to `MPI_COMM_SPAWN` could be empty. The ability to do this follows from the fact that MPI does not specify how an executable is found, and the info argument can tell the runtime system where to “find” the executable “” (empty string). Of course a program that does this will not be portable across MPI implementations.

**The root argument** All arguments before the root argument are examined only on the process whose rank in `comm` is equal to `root`. The value of these arguments on other processes is ignored.

**The array\_of\_errcodes argument** The `array_of_errcodes` is an array of length `maxprocs` in which MPI reports the status of each process that MPI was requested to start. If all `maxprocs` processes were spawned, `array_of_errcodes` is filled in with the value `MPI_SUCCESS`. If only  $m$  ( $0 \leq m < \text{maxprocs}$ ) processes are spawned,  $m$  of the entries will contain `MPI_SUCCESS` and the rest will contain an implementation-specific error code indicating the reason MPI could not start the process. MPI does not specify which entries correspond to failed processes. An implementation may, for instance, fill in error codes in one-to-one correspondence with a detailed specification in the info argument. These error codes all belong to the error class `MPI_ERR_SPAWN` if there was no error in the argument list. In C or in the Fortran `mpi` module or `mpif.h` include file, an application may pass `MPI_ERRCODES_IGNORE` if it is not interested in the error codes. In the Fortran `mpi_f08` module or in C++ this constant does not exist, and the `array_of_errcodes` argument may be omitted from the argument list.

*Advice to implementors.* In the Fortran `mpi` module or `mpif.h` include file, `MPI_ERRCODES_IGNORE` is a special type of constant, like `MPI_BOTTOM`. See the discussion in Section 2.5.4 on page 15. In the Fortran `mpi_f08` module, the optional argument has to be implemented through function overloading. See the discussion in Section 2.5.2 on page 14. (*End of advice to implementors.*)



MPI\_COMM\_GET\_PARENT(parent)

OUT      parent                      the parent communicator (handle)

int MPI\_Comm\_get\_parent(MPI\_Comm \*parent)

MPI\_COMM\_GET\_PARENT(PARENT, IERROR)

INTEGER PARENT, IERROR

MPI\_Comm\_get\_parent(parent, ierror)

TYPE(MPI\_Comm), INTENT(OUT) :: parent

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{static MPI::Intercomm MPI::Comm::Get\_parent() (*binding deprecated, see*  
*Section 15.2*) }

If a process was started with MPI\_COMM\_SPAWN or MPI\_COMM\_SPAWN\_MULTIPLE, MPI\_COMM\_GET\_PARENT returns the “parent” intercommunicator of the current process. This parent intercommunicator is created implicitly inside of MPI\_INIT and is the same intercommunicator returned by SPAWN in the parents.

If the process was not spawned, MPI\_COMM\_GET\_PARENT returns MPI\_COMM\_NULL.

After the parent communicator is freed or disconnected, MPI\_COMM\_GET\_PARENT returns MPI\_COMM\_NULL.

*Advice to users.* MPI\_COMM\_GET\_PARENT returns a handle to a single intercommunicator. Calling MPI\_COMM\_GET\_PARENT a second time returns a handle to the same intercommunicator. Freeing the handle with MPI\_COMM\_DISCONNECT or MPI\_COMM\_FREE will cause other references to the intercommunicator to become invalid (dangling). Note that calling MPI\_COMM\_FREE on the parent communicator is not useful. (*End of advice to users.*)

*Rationale.* The desire of the Forum was to create a constant MPI\_COMM\_PARENT similar to MPI\_COMM\_WORLD. Unfortunately such a constant cannot be used (syntactically) as an argument to MPI\_COMM\_DISCONNECT, which is explicitly allowed. (*End of rationale.*)

### 10.3.3 Starting Multiple Executables and Establishing Communication

While MPI\_COMM\_SPAWN is sufficient for most cases, it does not allow the spawning of multiple binaries, or of the same binary with multiple sets of arguments. The following routine spawns multiple binaries or the same binary with multiple sets of arguments, establishing communication with them and placing them in the same MPI\_COMM\_WORLD.

```

1 MPI_COMM_SPAWN_MULTIPLE(count, array_of_commands, array_of_argv, array_of_maxprocs,
2   array_of_info, root, comm, intercomm, array_of_errcodes)

```

3	IN	count	number of commands (positive integer, significant to MPI only at root — see advice to users)
4			
5			
6	IN	array_of_commands	programs to be executed (array of strings, significant only at root)
7			
8	IN	array_of_argv	arguments for commands (array of array of strings, significant only at root)
9			
10	IN	array_of_maxprocs	maximum number of processes to start for each command (array of integer, significant only at root)
11			
12			
13	IN	array_of_info	info objects telling the runtime system where and how to start processes (array of handles, significant only at root)
14			
15			
16	IN	root	rank of process in which previous arguments are examined (integer)
17			
18	IN	comm	intracommunicator containing group of spawning processes (handle)
19			
20			
21	OUT	intercomm	intercommunicator between original group and newly spawned group (handle)
22			
23	OUT	array_of_errcodes	one error code per process (array of integer)
24			

```

25 int MPI_Comm_spawn_multiple(int count, char *array_of_commands[],
26   char **array_of_argv[], int array_of_maxprocs[],
27   MPI_Info array_of_info[], int root, MPI_Comm comm,
28   MPI_Comm *intercomm, int array_of_errcodes[])
29

```

```

30 MPI_COMM_SPAWN_MULTIPLE(COUNT, ARRAY_OF_COMMANDS, ARRAY_OF_ARGV,
31   ARRAY_OF_MAXPROCS, ARRAY_OF_INFO, ROOT, COMM, INTERCOMM,
32   ARRAY_OF_ERRCODES, IERROR)
33 INTEGER COUNT, ARRAY_OF_INFO(*), ARRAY_OF_MAXPROCS(*), ROOT, COMM,
34 INTERCOMM, ARRAY_OF_ERRCODES(*), IERROR
35 CHARACTER*(*) ARRAY_OF_COMMANDS(*), ARRAY_OF_ARGV(COUNT, *)

```

```

36 MPI_Comm_spawn_multiple(count, array_of_commands, array_of_argv,
37   array_of_maxprocs, array_of_info, root, comm, intercomm,
38   array_of_errcodes, ierror)
39 INTEGER, INTENT(IN) :: count, array_of_maxprocs(*), root
40 CHARACTER(LEN=*), INTENT(IN) :: array_of_commands(*),
41 array_of_argv(count, *)
42 TYPE(MPI_Info), INTENT(IN) :: array_of_info(*)
43 TYPE(MPI_Comm), INTENT(IN) :: comm
44 TYPE(MPI_Comm), INTENT(OUT) :: intercomm
45 INTEGER, INTENT(OUT) :: array_of_errcodes(*) ! optional by
46 overloading
47 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
48

```

```

{MPI::Intercomm MPI::Intracomm::Spawn_multiple(int count,
    const char* array_of_commands[], const char** array_of_argv[],
    const int array_of_maxprocs[],
    const MPI::Info array_of_info[], int root,
    int array_of_errcodes[]) (binding deprecated, see Section 15.2) }
{MPI::Intercomm MPI::Intracomm::Spawn_multiple(int count,
    const char* array_of_commands[], const char** array_of_argv[],
    const int array_of_maxprocs[],
    const MPI::Info array_of_info[], int root) (binding deprecated, see
    Section 15.2) }

```

MPI\_COMM\_SPAWN\_MULTIPLE is identical to MPI\_COMM\_SPAWN except that there are multiple executable specifications. The first argument, `count`, gives the number of specifications. Each of the next four arguments are simply arrays of the corresponding arguments in MPI\_COMM\_SPAWN. For the Fortran version of `array_of_argv`, the element `array_of_argv(i,j)` is the  $j$ -th argument to command number  $i$ .

*Rationale.* This may seem backwards to Fortran programmers who are familiar with Fortran's column-major ordering. However, it is necessary to do it this way to allow MPI\_COMM\_SPAWN to sort out arguments. Note that the leading dimension of `array_of_argv` *must* be the same as `count`. (*End of rationale.*)

*Advice to users.* The argument `count` is interpreted by MPI only at the root, as is `array_of_argv`. Since the leading dimension of `array_of_argv` is `count`, a non-positive value of `count` at a non-root node could theoretically cause a runtime bounds check error, even though `array_of_argv` should be ignored by the subroutine. If this happens, you should explicitly supply a reasonable value of `count` on the non-root nodes. (*End of advice to users.*)

In any language, an application may use the constant MPI\_ARGVS\_NULL (which is likely to be `(char ***)0` in C) to specify that no arguments should be passed to any commands. The effect of setting individual elements of `array_of_argv` to MPI\_ARGV\_NULL is not defined. To specify arguments for some commands but not others, the commands without arguments should have a corresponding `argv` whose first element is null (`(char *)0` in C and empty string in Fortran).

All of the spawned processes have the same MPI\_COMM\_WORLD. Their ranks in MPI\_COMM\_WORLD correspond directly to the order in which the commands are specified in MPI\_COMM\_SPAWN\_MULTIPLE. Assume that  $m_1$  processes are generated by the first command,  $m_2$  by the second, etc. The processes corresponding to the first command have ranks  $0, 1, \dots, m_1 - 1$ . The processes in the second command have ranks  $m_1, m_1 + 1, \dots, m_1 + m_2 - 1$ . The processes in the third have ranks  $m_1 + m_2, m_1 + m_2 + 1, \dots, m_1 + m_2 + m_3 - 1$ , etc.

*Advice to users.* Calling MPI\_COMM\_SPAWN multiple times would create many sets of children with different MPI\_COMM\_WORLDS whereas MPI\_COMM\_SPAWN\_MULTIPLE creates children with a single MPI\_COMM\_WORLD, so the two methods are not completely equivalent. There are also two performance-related reasons why, if you need to spawn multiple executables, you may want to use MPI\_COMM\_SPAWN\_MULTIPLE instead of calling MPI\_COMM\_SPAWN several

times. First, spawning several things at once may be faster than spawning them sequentially. Second, in some implementations, communication between processes spawned at the same time may be faster than communication between processes spawned separately. (*End of advice to users.*)

The `array_of_errcodes` argument is a 1-dimensional array of size  $\sum_{i=1}^{count} n_i$ , where  $n_i$  is the  $i$ -th element of `array_of_maxprocs`. Command number  $i$  corresponds to the  $n_i$  contiguous slots in this array from element  $\sum_{j=1}^{i-1} n_j$  to  $\left[\sum_{j=1}^i n_j\right] - 1$ . Error codes are treated as for `MPI_COMM_SPAWN`.

### Example 10.2 Examples of `array_of_argv` in C and Fortran

To run the program “ocean” with arguments “-gridfile” and “ocean1.grd” and the program “atmos” with argument “atmos.grd” in C:

```
char *array_of_commands[2] = {"ocean", "atmos"};
char **array_of_argv[2];
char *argv0[] = {"-gridfile", "ocean1.grd", (char *)0};
char *argv1[] = {"atmos.grd", (char *)0};
array_of_argv[0] = argv0;
array_of_argv[1] = argv1;
MPI_Comm_spawn_multiple(2, array_of_commands, array_of_argv, ...);
```

Here’s how you do it in Fortran:

```
CHARACTER*25 commands(2), array_of_argv(2, 3)
commands(1) = ' ocean '
array_of_argv(1, 1) = ' -gridfile '
array_of_argv(1, 2) = ' ocean1.grd'
array_of_argv(1, 3) = ' '

commands(2) = ' atmos '
array_of_argv(2, 1) = ' atmos.grd '
array_of_argv(2, 2) = ' '

call MPI_COMM_SPAWN_MULTIPLE(2, commands, array_of_argv, ...)
```

### 10.3.4 Reserved Keys

The following keys are reserved. An implementation is not required to interpret these keys, but if it does interpret the key, it must provide the functionality described.

**host** Value is a hostname. The format of the hostname is determined by the implementation.

**arch** Value is an architecture name. Valid architecture names and what they mean are determined by the implementation.

**wdir** Value is the name of a directory on a machine on which the spawned process(es) execute(s). This directory is made the working directory of the executing process(es). The format of the directory name is determined by the implementation.

path Value is a directory or set of directories where the implementation should look for the executable. The format of path is determined by the implementation.

file Value is the name of a file in which additional information is specified. The format of the filename and internal format of the file are determined by the implementation.

soft Value specifies a set of numbers which are allowed values for the number of processes that MPI\_COMM\_SPAWN (et al.) may create. The format of the value is a comma-separated list of Fortran-90 triplets each of which specifies a set of integers and which together specify the set formed by the union of these sets. Negative values in this set and values greater than maxprocs are ignored. MPI will spawn the largest number of processes it can, consistent with some number in the set. The order in which triplets are given is not significant.

By Fortran-90 triplets, we mean:

1.  $a$  means  $a$
2.  $a:b$  means  $a, a+1, a+2, \dots, b$
3.  $a:b:c$  means  $a, a+c, a+2c, \dots, a+ck$ , where for  $c > 0$ ,  $k$  is the largest integer for which  $a+ck \leq b$  and for  $c < 0$ ,  $k$  is the largest integer for which  $a+ck \geq b$ . If  $b > a$  then  $c$  must be positive. If  $b < a$  then  $c$  must be negative.

Examples:

1.  $a:b$  gives a range between  $a$  and  $b$
2.  $0:N$  gives full “soft” functionality
3.  $1,2,4,8,16,32,64,128,256,512,1024,2048,4096$  allows power-of-two number of processes.
4.  $2:10000:2$  allows even number of processes.
5.  $2:10:2,7$  allows 2, 4, 6, 7, 8, or 10 processes.

### 10.3.5 Spawn Example

Manager-worker Example Using MPI\_COMM\_SPAWN.

```
/* manager */
#include "mpi.h"
int main(int argc, char *argv[])
{
    int world_size, universe_size, *universe_sizep, flag;
    MPI_Comm everyone;          /* intercommunicator */
    char worker_program[100];

    MPI_Init(&argc, &argv);
    MPI_Comm_size(MPI_COMM_WORLD, &world_size);

    if (world_size != 1)    error("Top heavy with management");

    MPI_Comm_get_attr(MPI_COMM_WORLD, MPI_UNIVERSE_SIZE,
```

ticket0.

```

1          &universe_sizep, &flag);
2      if (!flag) {
3          printf("This MPI does not support UNIVERSE_SIZE. How many\n\
4 processes total?");
5          scanf("%d", &universe_size);
6      } else universe_size = *universe_sizep;
7      if (universe_size == 1) error("No room to start workers");
8
9      /*
10     * Now spawn the workers. Note that there is a run-time determination
11     * of what type of worker to spawn, and presumably this calculation must
12     * be done at run time and cannot be calculated before starting
13     * the program. If everything is known when the application is
14     * first started, it is generally better to start them all at once
15     * in a single MPI_COMM_WORLD.
16     */
17
18     choose_worker_program(worker_program);
19     MPI_Comm_spawn(worker_program, MPI_ARGV_NULL, universe_size-1,
20                   MPI_INFO_NULL, 0, MPI_COMM_SELF, &everyone,
21                   MPI_ERRCODES_IGNORE);
22
23     /*
24     * Parallel code here. The communicator "everyone" can be used
25     * to communicate with the spawned processes, which have ranks 0,..
26     * MPI_UNIVERSE_SIZE-1 in the remote group of the intercommunicator
27     * "everyone".
28     */
29
30     MPI_Finalize();
31     return 0;
32 }
33
34 /* worker */
35
36 #include "mpi.h"
37 int main(int argc, char *argv[])
38 {
39     int size;
40     MPI_Comm parent;
41     MPI_Init(&argc, &argv);
42     MPI_Comm_get_parent(&parent);
43     if (parent == MPI_COMM_NULL) error("No parent!");
44     MPI_Comm_remote_size(parent, &size);
45     if (size != 1) error("Something's wrong with the parent");
46
47     /*
48     * Parallel code here.
49     * The manager is represented as the process with rank 0 in (the remote

```

```

    * group of) the parent communicator.  If the workers need to communicate
    * among themselves, they can use MPI_COMM_WORLD.
    */

    MPI_Finalize();
    return 0;
}

```

## 10.4 Establishing Communication

This section provides functions that establish communication between two sets of MPI processes that do not share a communicator.

Some situations in which these functions are useful are:

1. Two parts of an application that are started independently need to communicate.
2. A visualization tool wants to attach to a running process.
3. A server wants to accept connections from multiple clients. Both clients and server may be parallel programs.

In each of these situations, MPI must establish communication channels where none existed before, and there is no parent/child relationship. The routines described in this section establish communication between the two sets of processes by creating an MPI intercommunicator, where the two groups of the intercommunicator are the original sets of processes.

Establishing contact between two groups of processes that do not share an existing communicator is a collective but asymmetric process. One group of processes indicates its willingness to accept connections from other groups of processes. We will call this group the (parallel) *server*, even if this is not a client/server type of application. The other group connects to the server; we will call it the *client*.

*Advice to users.* While the names *client* and *server* are used throughout this section, MPI does not guarantee the traditional robustness of client server systems. The functionality described in this section is intended to allow two cooperating parts of the same application to communicate with one another. For instance, a client that gets a segmentation fault and dies, or one that doesn't participate in a collective operation may cause a server to crash or hang. (*End of advice to users.*)

### 10.4.1 Names, Addresses, Ports, and All That

Almost all of the complexity in MPI client/server routines addresses the question “how does the client find out how to contact the server?” The difficulty, of course, is that there is no existing communication channel between them, yet they must somehow agree on a rendezvous point where they will establish communication.

Agreeing on a rendezvous point always involves a third party. The third party may itself provide the rendezvous point or may communicate rendezvous information from server to client. Complicating matters might be the fact that a client doesn't really care what server it contacts, only that it be able to get in touch with one that can handle its request.

Ideally, MPI can accommodate a wide variety of run-time systems while retaining the ability to write simple portable code. The following should be compatible with MPI:

- The server resides at a well-known internet address host:port.
- The server prints out an address to the terminal, the user gives this address to the client program.
- The server places the address information on a nameserver, where it can be retrieved with an agreed-upon name.
- The server to which the client connects is actually a broker, acting as a middleman between the client and the real server.

MPI does not require a nameserver, so not all implementations will be able to support all of the above scenarios. However, MPI provides an optional nameserver interface, and is compatible with external name servers.

A `port_name` is a *system-supplied* string that encodes a low-level network address at which a server can be contacted. Typically this is an IP address and a port number, but an implementation is free to use any protocol. The server establishes a `port_name` with the `MPI_OPEN_PORT` routine. It accepts a connection to a given port with `MPI_COMM_ACCEPT`. A client uses `port_name` to connect to the server.

By itself, the `port_name` mechanism is completely portable, but it may be clumsy to use because of the necessity to communicate `port_name` to the client. It would be more convenient if a server could specify that it be known by an *application-supplied* `service_name` so that the client could connect to that `service_name` without knowing the `port_name`.

An MPI implementation may allow the server to publish a (`port_name`, `service_name`) pair with `MPI_PUBLISH_NAME` and the client to retrieve the port name from the service name with `MPI_LOOKUP_NAME`. This allows three levels of portability, with increasing levels of functionality.

1. Applications that do not rely on the ability to publish names are the most portable. Typically the `port_name` must be transferred “by hand” from server to client.
2. Applications that use the `MPI_PUBLISH_NAME` mechanism are completely portable among implementations that provide this service. To be portable among all implementations, these applications should have a fall-back mechanism that can be used when names are not published.
3. Applications may ignore MPI’s name publishing functionality and use their own mechanism (possibly system-supplied) to publish names. This allows arbitrary flexibility but is not portable.

#### 10.4.2 Server Routines

A server makes itself available with two routines. First it must call `MPI_OPEN_PORT` to establish a port at which it may be contacted. Secondly it must call `MPI_COMM_ACCEPT` to accept connections from clients.



MPI\_OPEN\_PORT(info, port\_name)

IN	info	implementation-specific information on how to establish an address (handle)
OUT	port_name	newly established port (string)

int MPI\_Open\_port(MPI\_Info info, char \*port\_name)

MPI\_OPEN\_PORT(INFO, PORT\_NAME, IERROR)  
 CHARACTER\*(\*) PORT\_NAME  
 INTEGER INFO, IERROR

MPI\_Open\_port(info, port\_name, ierror)  
 TYPE(MPI\_Info), INTENT(IN) :: info  
 CHARACTER(LEN=\*), INTENT(OUT) :: port\_name  
 INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Open\_port(const MPI::Info& info, char\* port\_name) (*binding deprecated, see Section 15.2*) }

This function establishes a network address, encoded in the `port_name` string, at which the server will be able to accept connections from clients. `port_name` is supplied by the system, possibly using information in the `info` argument.

MPI copies a system-supplied port name into `port_name`. `port_name` identifies the newly opened port and can be used by a client to contact the server. The maximum size string that may be supplied by the system is `MPI_MAX_PORT_NAME`.

*Advice to users.* The system copies the port name into `port_name`. The application must pass a buffer of sufficient size to hold this value. (*End of advice to users.*)

`port_name` is essentially a network address. It is unique within the communication universe to which it belongs (determined by the implementation), and may be used by any client within that communication universe. For instance, if it is an internet (host:port) address, it will be unique on the internet. If it is a low level switch address on an IBM SP, it will be unique to that SP.

*Advice to implementors.* These examples are not meant to constrain implementations. A `port_name` could, for instance, contain a user name or the name of a batch job, as long as it is unique within some well-defined communication domain. The larger the communication domain, the more useful MPI's client/server functionality will be. (*End of advice to implementors.*)

The precise form of the address is implementation-defined. For instance, an internet address may be a host name or IP address, or anything that the implementation can decode into an IP address. A port name may be reused after it is freed with `MPI_CLOSE_PORT` and released by the system.

*Advice to implementors.* Since the user may type in `port_name` by hand, it is useful to choose a form that is easily readable and does not have embedded spaces. (*End of advice to implementors.*)

info may be used to tell the implementation how to establish the address. It may, and usually will, be MPI\_INFO\_NULL in order to get the implementation defaults.

MPI\_CLOSE\_PORT(port\_name)

IN port\_name a port (string)

int MPI\_Close\_port(char \*port\_name)

MPI\_CLOSE\_PORT(PORT\_NAME, IERROR)

CHARACTER\*(\*) PORT\_NAME

INTEGER IERROR

MPI\_Close\_port(port\_name, ierror)

CHARACTER(LEN=\*), INTENT(IN) :: port\_name

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Close\_port(const char\* port\_name) (*binding deprecated, see Section 15.2*)  
}

This function releases the network address represented by port\_name.

MPI\_COMM\_ACCEPT(port\_name, info, root, comm, newcomm)

IN port\_name port name (string, used only on root)

IN info implementation-dependent information (handle, used only on root)

IN root rank in comm of root node (integer)

IN comm intracommunicator over which call is collective (handle)

OUT newcomm intercommunicator with client as remote group (handle)

int MPI\_Comm\_accept(char \*port\_name, MPI\_Info info, int root,  
MPI\_Comm comm, MPI\_Comm \*newcomm)

MPI\_COMM\_ACCEPT(PORT\_NAME, INFO, ROOT, COMM, NEWCOMM, IERROR)

CHARACTER\*(\*) PORT\_NAME

INTEGER INFO, ROOT, COMM, NEWCOMM, IERROR

MPI\_Comm\_accept(port\_name, info, root, comm, newcomm, ierror)

CHARACTER(LEN=\*), INTENT(IN) :: port\_name

TYPE(MPI\_Info), INTENT(IN) :: info

INTEGER, INTENT(IN) :: root

TYPE(MPI\_Comm), INTENT(IN) :: comm

TYPE(MPI\_Comm), INTENT(OUT) :: newcomm

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```
{MPI::Intercomm MPI::Intracomm::Accept(const char* port_name,
    const MPI::Info& info, int root) const(binding deprecated, see
    Section 15.2) }
```

MPI\_COMM\_ACCEPT establishes communication with a client. It is collective over the calling communicator. It returns an intercommunicator that allows communication with the client.

The `port_name` must have been established through a call to MPI\_OPEN\_PORT.

`info` is a implementation-defined string that may allow fine control over the ACCEPT call.

### 10.4.3 Client Routines

There is only one routine on the client side.

MPI\_COMM\_CONNECT(`port_name`, `info`, `root`, `comm`, `newcomm`)

IN	<code>port_name</code>	network address (string, used only on root)
IN	<code>info</code>	implementation-dependent information (handle, used only on root)
IN	<code>root</code>	rank in <code>comm</code> of root node (integer)
IN	<code>comm</code>	intracommunicator over which call is collective (handle)
OUT	<code>newcomm</code>	intercommunicator with server as remote group (handle)

```
int MPI_Comm_connect(char *port_name, MPI_Info info, int root,
    MPI_Comm comm, MPI_Comm *newcomm)
```

```
MPI_COMM_CONNECT(PORT_NAME, INFO, ROOT, COMM, NEWCOMM, IERROR)
    CHARACTER(*) PORT_NAME
    INTEGER INFO, ROOT, COMM, NEWCOMM, IERROR
```

```
MPI_Comm_connect(port_name, info, root, comm, newcomm, ierror)
    CHARACTER(LEN=*), INTENT(IN) :: port_name
    TYPE(MPI_Info), INTENT(IN) :: info
    INTEGER, INTENT(IN) :: root
    TYPE(MPI_Comm), INTENT(IN) :: comm
    TYPE(MPI_Comm), INTENT(OUT) :: newcomm
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{MPI::Intercomm MPI::Intracomm::Connect(const char* port_name,
    const MPI::Info& info, int root) const(binding deprecated, see
    Section 15.2) }
```

This routine establishes communication with a server specified by `port_name`. It is collective over the calling communicator and returns an intercommunicator in which the remote group participated in an MPI\_COMM\_ACCEPT.

If the named port does not exist (or has been closed), `MPI_COMM_CONNECT` raises an error of class `MPI_ERR_PORT`.

If the port exists, but does not have a pending `MPI_COMM_ACCEPT`, the connection attempt will eventually time out after an implementation-defined time, or succeed when the server calls `MPI_COMM_ACCEPT`. In the case of a time out, `MPI_COMM_CONNECT` raises an error of class `MPI_ERR_PORT`.

*Advice to implementors.* The time out period may be arbitrarily short or long. However, a high quality implementation will try to queue connection attempts so that a server can handle simultaneous requests from several clients. A high quality implementation may also provide a mechanism, through the `info` arguments to `MPI_OPEN_PORT`, `MPI_COMM_ACCEPT` and/or `MPI_COMM_CONNECT`, for the user to control timeout and queuing behavior. (*End of advice to implementors.*)

MPI provides no guarantee of fairness in servicing connection attempts. That is, connection attempts are not necessarily satisfied in the order they were initiated and competition from other connection attempts may prevent a particular connection attempt from being satisfied.

`port_name` is the address of the server. It must be the same as the name returned by `MPI_OPEN_PORT` on the server. Some freedom is allowed here. If there are equivalent forms of `port_name`, an implementation may accept them as well. For instance, if `port_name` is (hostname:port), an implementation may accept (ip\_address:port) as well.

#### 10.4.4 Name Publishing

The routines in this section provide a mechanism for publishing names. A (`service_name`, `port_name`) pair is published by the server, and may be retrieved by a client using the `service_name` only. An MPI implementation defines the *scope* of the `service_name`, that is, the domain over which the `service_name` can be retrieved. If the domain is the empty set, that is, if no client can retrieve the information, then we say that name publishing is not supported. Implementations should document how the scope is determined. High-quality implementations will give some control to users through the `info` arguments to name publishing functions. Examples are given in the descriptions of individual functions.

`MPI_PUBLISH_NAME(service_name, info, port_name)`

IN	<code>service_name</code>	a service name to associate with the port (string)
IN	<code>info</code>	implementation-specific information (handle)
IN	<code>port_name</code>	a port name (string)

`int MPI_Publish_name(char *service_name, MPI_Info info, char *port_name)`

`MPI_PUBLISH_NAME(SERVICE_NAME, INFO, PORT_NAME, IERROR)`

INTEGER `INFO`, `IERROR`

CHARACTER\*(\*) `SERVICE_NAME`, `PORT_NAME`

`MPI_Publish_name(service_name, info, port_name, ierror)`

TYPE(`MPI_Info`), `INTENT(IN) :: info`

```

    CHARACTER(LEN=*), INTENT(IN) :: service_name, port_name
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Publish_name(const char* service_name, const MPI::Info& info,
    const char* port_name) (binding deprecated, see Section 15.2) }
```

This routine publishes the pair (port\_name, service\_name) so that an application may retrieve a system-supplied port\_name using a well-known service\_name.

The implementation must define the *scope* of a published service name, that is, the domain over which the service name is unique, and conversely, the domain over which the (port name, service name) pair may be retrieved. For instance, a service name may be unique to a job (where job is defined by a distributed operating system or batch scheduler), unique to a machine, or unique to a Kerberos realm. The scope may depend on the info argument to MPI\_PUBLISH\_NAME.

MPI permits publishing more than one service\_name for a single port\_name. On the other hand, if service\_name has already been published within the scope determined by info, the behavior of MPI\_PUBLISH\_NAME is undefined. An MPI implementation may, through a mechanism in the info argument to MPI\_PUBLISH\_NAME, provide a way to allow multiple servers with the same service in the same scope. In this case, an implementation-defined policy will determine which of several port names is returned by MPI\_LOOKUP\_NAME.

Note that while service\_name has a limited scope, determined by the implementation, port\_name always has global scope within the communication universe used by the implementation (i.e., it is globally unique).

port\_name should be the name of a port established by MPI\_OPEN\_PORT and not yet deleted by MPI\_CLOSE\_PORT. If it is not, the result is undefined.

*Advice to implementors.* In some cases, an MPI implementation may use a name service that a user can also access directly. In this case, a name published by MPI could easily conflict with a name published by a user. In order to avoid such conflicts, MPI implementations should mangle service names so that they are unlikely to conflict with user code that makes use of the same service. Such name mangling will of course be completely transparent to the user.

The following situation is problematic but unavoidable, if we want to allow implementations to use nameservers. Suppose there are multiple instances of “ocean” running on a machine. If the scope of a service name is confined to a job, then multiple oceans can coexist. If an implementation provides site-wide scope, however, multiple instances are not possible as all calls to MPI\_PUBLISH\_NAME after the first may fail. There is no universal solution to this.

To handle these situations, a high-quality implementation should make it possible to limit the domain over which names are published. (*End of advice to implementors.*)

```
MPI_UNPUBLISH_NAME(service_name, info, port_name)
```

IN	service_name	a service name (string)
IN	info	implementation-specific information (handle)
IN	port_name	a port name (string)

```

1  int MPI_Unpublish_name(char *service_name, MPI_Info info, char *port_name)
2
3  MPI_UNPUBLISH_NAME(SERVICE_NAME, INFO, PORT_NAME, IERROR)
4      INTEGER INFO, IERROR
5      CHARACTER*(*) SERVICE_NAME, PORT_NAME

```

```

6  MPI_Unpublish_name(service_name, info, port_name, ierror)
7      CHARACTER(LEN=*), INTENT(IN) :: service_name, port_name
8      TYPE(MPI_Info), INTENT(IN) :: info
9      INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

10
11 {void MPI::Unpublish_name(const char* service_name, const MPI::Info& info,
12     const char* port_name) (binding deprecated, see Section 15.2) }

```

This routine unpublishes a service name that has been previously published. Attempting to unpublish a name that has not been published or has already been unpublished is erroneous and is indicated by the error class `MPI_ERR_SERVICE`.

All published names must be unpublished before the corresponding port is closed and before the publishing process exits. The behavior of `MPI_UNPUBLISH_NAME` is implementation dependent when a process tries to unpublish a name that it did not publish.

If the `info` argument was used with `MPI_PUBLISH_NAME` to tell the implementation how to publish names, the implementation may require that `info` passed to `MPI_UNPUBLISH_NAME` contain information to tell the implementation how to unpublish a name.

```

24
25 MPI_LOOKUP_NAME(service_name, info, port_name)

```

26	IN	service_name	a service name (string)
27			
28	IN	info	implementation-specific information (handle)
29	OUT	port_name	a port name (string)

```

30
31 int MPI_Lookup_name(char *service_name, MPI_Info info, char *port_name)
32
33 MPI_LOOKUP_NAME(SERVICE_NAME, INFO, PORT_NAME, IERROR)
34     CHARACTER*(*) SERVICE_NAME, PORT_NAME
35     INTEGER INFO, IERROR

```

```

36 MPI_Lookup_name(service_name, info, port_name, ierror)
37     CHARACTER(LEN=*), INTENT(IN) :: service_name
38     TYPE(MPI_Info), INTENT(IN) :: info
39     CHARACTER(LEN=*), INTENT(OUT) :: port_name
40     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

41
42 {void MPI::Lookup_name(const char* service_name, const MPI::Info& info,
43     char* port_name) (binding deprecated, see Section 15.2) }

```

This function retrieves a `port_name` published by `MPI_PUBLISH_NAME` with `service_name`. If `service_name` has not been published, it raises an error in the error class `MPI_ERR_NAME`. The application must supply a `port_name` buffer large enough to hold the largest possible port name (see discussion above under `MPI_OPEN_PORT`).

If an implementation allows multiple entries with the same `service_name` within the same scope, a particular `port_name` is chosen in a way determined by the implementation.

If the `info` argument was used with `MPI_PUBLISH_NAME` to tell the implementation how to publish names, a similar `info` argument may be required for `MPI_LOOKUP_NAME`.

#### 10.4.5 Reserved Key Values

The following key values are reserved. An implementation is not required to interpret these key values, but if it does interpret the key value, it must provide the functionality described.

`ip_port` Value contains IP port number at which to establish a `port`. (Reserved for `MPI_OPEN_PORT` only).

`ip_address` Value contains IP address at which to establish a `port`. If the address is not a valid IP address of the host on which the `MPI_OPEN_PORT` call is made, the results are undefined. (Reserved for `MPI_OPEN_PORT` only).

#### 10.4.6 Client/Server Examples

##### Simplest Example — Completely Portable.

The following example shows the simplest way to use the client/server interface. It does not use service names at all.

On the server side:

```
char myport[MPI_MAX_PORT_NAME];
MPI_Comm intercomm;
/* ... */
MPI_Open_port(MPI_INFO_NULL, myport);
printf("port name is: %s\n", myport);

MPI_Comm_accept(myport, MPI_INFO_NULL, 0, MPI_COMM_SELF, &intercomm);
/* do something with intercomm */
```

The server prints out the port name to the terminal and the user must type it in when starting up the client (assuming the MPI implementation supports stdin such that this works). On the client side:

```
MPI_Comm intercomm;
char name[MPI_MAX_PORT_NAME];
printf("enter port name: ");
gets(name);
MPI_Comm_connect(name, MPI_INFO_NULL, 0, MPI_COMM_SELF, &intercomm);
```

##### Ocean/Atmosphere - Relies on Name Publishing

In this example, the “ocean” application is the “server” side of a coupled ocean-atmosphere climate model. It assumes that the MPI implementation publishes names.

```

1
2 MPI_Open_port(MPI_INFO_NULL, port_name);
3 MPI_Publish_name("ocean", MPI_INFO_NULL, port_name);
4
5 MPI_Comm_accept(port_name, MPI_INFO_NULL, 0, MPI_COMM_SELF, &intercomm);
6 /* do something with intercomm */
7 MPI_Unpublish_name("ocean", MPI_INFO_NULL, port_name);
8
9

```

On the client side:

```

11 MPI_Lookup_name("ocean", MPI_INFO_NULL, port_name);
12 MPI_Comm_connect( port_name, MPI_INFO_NULL, 0, MPI_COMM_SELF,
13                  &intercomm);
14
15

```

### Simple Client-Server Example.

This is a simple example; the server accepts only a single connection at a time and serves that connection until the client requests to be disconnected. The server is a single process.

Here is the server. It accepts a single connection and then processes data until it receives a message with tag 1. A message with tag 0 tells the server to exit.

```

22 #include "mpi.h"
23 int main( int argc, char **argv )
24 {
25     MPI_Comm client;
26     MPI_Status status;
27     char port_name[MPI_MAX_PORT_NAME];
28     double buf[MAX_DATA];
29     int    size, again;
30
31     MPI_Init( &argc, &argv );
32     MPI_Comm_size(MPI_COMM_WORLD, &size);
33     if (size != 1) error(FATAL, "Server too big");
34     MPI_Open_port(MPI_INFO_NULL, port_name);
35     printf("server available at %s\n",port_name);
36     while (1) {
37         MPI_Comm_accept( port_name, MPI_INFO_NULL, 0, MPI_COMM_WORLD,
38                         &client );
39         again = 1;
40         while (again) {
41             MPI_Recv( buf, MAX_DATA, MPI_DOUBLE,
42                      MPI_ANY_SOURCE, MPI_ANY_TAG, client, &status );
43             switch (status.MPI_TAG) {
44                 case 0: MPI_Comm_free( &client );
45                         MPI_Close_port(port_name);
46                         MPI_Finalize();
47                         return 0;
48                 case 1: MPI_Comm_disconnect( &client );

```



```

        again = 0;
        break;
    case 2: /* do something */
        ...
    default:
        /* Unexpected message type */
        MPI_Abort( MPI_COMM_WORLD, 1 );
    }
}
}

```

Here is the client.

```

#include "mpi.h"
int main( int argc, char **argv )
{
    MPI_Comm server;
    double buf[MAX_DATA];
    char port_name[MPI_MAX_PORT_NAME];

    MPI_Init( &argc, &argv );
    strcpy(port_name, argv[1] ); /* assume server's name is cmd-line arg */

    MPI_Comm_connect( port_name, MPI_INFO_NULL, 0, MPI_COMM_WORLD,
                      &server );

    while (!done) {
        tag = 2; /* Action to perform */
        MPI_Send( buf, n, MPI_DOUBLE, 0, tag, server );
        /* etc */
    }
    MPI_Send( buf, 0, MPI_DOUBLE, 0, 1, server );
    MPI_Comm_disconnect( &server );
    MPI_Finalize();
    return 0;
}

```

## 10.5 Other Functionality

### 10.5.1 Universe Size

Many “dynamic” MPI applications are expected to exist in a static runtime environment, in which resources have been allocated before the application is run. When a user (or possibly a batch system) runs one of these quasi-static applications, she will usually specify a number of processes to start and a total number of processes that are expected. An application simply needs to know how many slots there are, i.e., how many processes it should spawn.

MPI provides an attribute on `MPI_COMM_WORLD`, `MPI_UNIVERSE_SIZE`, that allows the application to obtain this information in a portable manner. This attribute indicates the total number of processes that are expected. In Fortran, the attribute is the integer value. In C, the attribute is a pointer to the integer value. An application typically subtracts the size of `MPI_COMM_WORLD` from `MPI_UNIVERSE_SIZE` to find out how many processes it should spawn. `MPI_UNIVERSE_SIZE` is initialized in `MPI_INIT` and is not changed by MPI. If defined, it has the same value on all processes of `MPI_COMM_WORLD`. `MPI_UNIVERSE_SIZE` is determined by the application startup mechanism in a way not specified by MPI. (The size of `MPI_COMM_WORLD` is another example of such a parameter.)

Possibilities for how `MPI_UNIVERSE_SIZE` might be set include

- A `-universe_size` argument to a program that starts MPI processes.
- Automatic interaction with a batch scheduler to figure out how many processors have been allocated to an application.
- An environment variable set by the user.
- Extra information passed to `MPI_COMM_SPAWN` through the `info` argument.

An implementation must document how `MPI_UNIVERSE_SIZE` is set. An implementation may not support the ability to set `MPI_UNIVERSE_SIZE`, in which case the attribute `MPI_UNIVERSE_SIZE` is not set.

`MPI_UNIVERSE_SIZE` is a recommendation, not necessarily a hard limit. For instance, some implementations may allow an application to spawn 50 processes per processor, if they are requested. However, it is likely that the user only wants to spawn one process per processor.

`MPI_UNIVERSE_SIZE` is assumed to have been specified when an application was started, and is in essence a portable mechanism to allow the user to pass to the application (through the MPI process startup mechanism, such as `mpiexec`) a piece of critical runtime information. Note that no interaction with the runtime environment is required. If the runtime environment changes size while an application is running, `MPI_UNIVERSE_SIZE` is not updated, and the application must find out about the change through direct communication with the runtime system.

## 10.5.2 Singleton `MPI_INIT`

A high-quality implementation will allow any process (including those not started with a “parallel application” mechanism) to become an MPI process by calling `MPI_INIT`. Such a process can then connect to other MPI processes using the `MPI_COMM_ACCEPT` and `MPI_COMM_CONNECT` routines, or spawn other MPI processes. MPI does not mandate this behavior, but strongly encourages it where technically feasible.

*Advice to implementors.* To start MPI processes belonging to the same `MPI_COMM_WORLD` requires some special coordination. The processes must be started at the “same” time, they must have a mechanism to establish communication, etc. Either the user or the operating system must take special steps beyond simply starting processes.

When an application enters `MPI_INIT`, clearly it must be able to determine if these special steps were taken. If a process enters `MPI_INIT` and determines that no

special steps were taken (i.e., it has not been given the information to form an MPI\_COMM\_WORLD with other processes) it succeeds and forms a singleton MPI program, that is, one in which MPI\_COMM\_WORLD has size 1.

In some implementations, MPI may not be able to function without an “MPI environment.” For example, MPI may require that daemons be running or MPI may not be able to work at all on the front-end of an MPP. In this case, an MPI implementation may either

1. Create the environment (e.g., start a daemon) or
2. Raise an error if it cannot create the environment and the environment has not been started independently.

A high-quality implementation will try to create a singleton MPI process and not raise an error.

*(End of advice to implementors.)*

### 10.5.3 MPI\_APPNUM

There is a predefined attribute MPI\_APPNUM of MPI\_COMM\_WORLD. In Fortran, the attribute is an integer value. In C, the attribute is a pointer to an integer value. If a process was spawned with MPI\_COMM\_SPAWN\_MULTIPLE, MPI\_APPNUM is the command number that generated the current process. Numbering starts from zero. If a process was spawned with MPI\_COMM\_SPAWN, it will have MPI\_APPNUM equal to zero.

Additionally, if the process was not started by a spawn call, but by an implementation-specific startup mechanism that can handle multiple process specifications, MPI\_APPNUM should be set to the number of the corresponding process specification. In particular, if it is started with

```
mpiexec spec0 [: spec1 : spec2 : ...]
```

MPI\_APPNUM should be set to the number of the corresponding specification.

If an application was not spawned with MPI\_COMM\_SPAWN or MPI\_COMM\_SPAWN\_MULTIPLE, and MPI\_APPNUM doesn’t make sense in the context of the implementation-specific startup mechanism, MPI\_APPNUM is not set.

MPI implementations may optionally provide a mechanism to override the value of MPI\_APPNUM through the info argument. MPI reserves the following key for all SPAWN calls.

**appnum** Value contains an integer that overrides the default value for MPI\_APPNUM in the child.

*Rationale.* When a single application is started, it is able to figure out how many processes there are by looking at the size of MPI\_COMM\_WORLD. An application consisting of multiple SPMD sub-applications has no way to find out how many sub-applications there are and to which sub-application the process belongs. While there are ways to figure it out in special cases, there is no general mechanism. MPI\_APPNUM provides such a general mechanism. *(End of rationale.)*

### 10.5.4 Releasing Connections

Before a client and server connect, they are independent MPI applications. An error in one does not affect the other. After establishing a connection with `MPI_COMM_CONNECT` and `MPI_COMM_ACCEPT`, an error in one may affect the other. It is desirable for a client and server to be able to disconnect, so that an error in one will not affect the other. Similarly, it might be desirable for a parent and child to disconnect, so that errors in the child do not affect the parent, or vice-versa.

- Two processes are **connected** if there is a communication path (direct or indirect) between them. More precisely:
  1. Two processes are connected if
    - (a) they both belong to the same communicator (inter- or intra-, including `MPI_COMM_WORLD`) *or*
    - (b) they have previously belonged to a communicator that was freed with `MPI_COMM_FREE` instead of `MPI_COMM_DISCONNECT` *or*
    - (c) they both belong to the group of the same window or filehandle.
  2. If A is connected to B and B to C, then A is connected to C.
- Two processes are **disconnected** (also **independent**) if they are not connected.
- By the above definitions, connectivity is a transitive property, and divides the universe of MPI processes into disconnected (independent) sets (equivalence classes) of processes.
- Processes which are connected, but don't share the same `MPI_COMM_WORLD` may become disconnected (independent) if the communication path between them is broken by using `MPI_COMM_DISCONNECT`.

The following additional rules apply to MPI routines in other chapters:

- `MPI_FINALIZE` is collective over a set of connected processes.
- `MPI_ABORT` does not abort independent processes. It may abort all processes in the caller's `MPI_COMM_WORLD` (ignoring its `comm` argument). Additionally, it may abort connected processes as well, though it makes a "best attempt" to abort only the processes in `comm`.
- If a process terminates without calling `MPI_FINALIZE`, independent processes are not affected but the effect on connected processes is not defined.

`MPI_COMM_DISCONNECT(comm)`

INOUT    `comm`                                    communicator (handle)

`int MPI_Comm_disconnect(MPI_Comm *comm)`

`MPI_COMM_DISCONNECT(COMM, IERROR)`

INTEGER `COMM`, `IERROR`

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```

MPI_Comm_disconnect(comm, ierror)
    TYPE(MPI_Comm), INTENT(INOUT) :: comm
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{void MPI::Comm::Disconnect() (binding deprecated, see Section 15.2) }

```

This function waits for all pending communication on `comm` to complete internally, deallocates the communicator object, and sets the handle to `MPI_COMM_NULL`. It is a collective operation.

It may not be called with the communicator `MPI_COMM_WORLD` or `MPI_COMM_SELF`.

`MPI_COMM_DISCONNECT` may be called only if all communication is complete and matched, so that buffered data can be delivered to its destination. This requirement is the same as for `MPI_FINALIZE`.

`MPI_COMM_DISCONNECT` has the same action as `MPI_COMM_FREE`, except that it waits for pending communication to finish internally and enables the guarantee about the behavior of disconnected processes.

*Advice to users.* To disconnect two processes you may need to call `MPI_COMM_DISCONNECT`, `MPI_WIN_FREE` and `MPI_FILE_CLOSE` to remove all communication paths between the two processes. Notes that it may be necessary to disconnect several communicators (or to free several windows or files) before two processes are completely independent. (*End of advice to users.*)

*Rationale.* It would be nice to be able to use `MPI_COMM_FREE` instead, but that function explicitly does not wait for pending communication to complete. (*End of rationale.*)

### 10.5.5 Another Way to Establish MPI Communication

```

MPI_COMM_JOIN(fd, intercomm)

```

IN	fd	socket file descriptor
OUT	intercomm	new intercommunicator (handle)

```

int MPI_Comm_join(int fd, MPI_Comm *intercomm)

```

```

MPI_COMM_JOIN(FD, INTERCOMM, IERROR)
    INTEGER FD, INTERCOMM, IERROR

```

```

MPI_Comm_join(fd, intercomm, ierror)
    INTEGER, INTENT(IN) :: fd
    TYPE(MPI_Comm), INTENT(OUT) :: intercomm
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{static MPI::Intercomm MPI::Comm::Join(const int fd) (binding deprecated, see
    Section 15.2) }

```

`MPI_COMM_JOIN` is intended for MPI implementations that exist in an environment supporting the Berkeley Socket interface [40, 44]. Implementations that exist in an environ-

ment not supporting Berkeley Sockets should provide the entry point for `MPI_COMM_JOIN` and should return `MPI_COMM_NULL`.

This call creates an intercommunicator from the union of two MPI processes which are connected by a socket. `MPI_COMM_JOIN` should normally succeed if the local and remote processes have access to the same implementation-defined MPI communication universe.

*Advice to users.* An MPI implementation may require a specific communication medium for MPI communication, such as a shared memory segment or a special switch. In this case, it may not be possible for two processes to successfully join even if there is a socket connecting them and they are using the same MPI implementation. (*End of advice to users.*)

*Advice to implementors.* A high-quality implementation will attempt to establish communication over a slow medium if its preferred one is not available. If implementations do not do this, they must document why they cannot do MPI communication over the medium used by the socket (especially if the socket is a TCP connection). (*End of advice to implementors.*)

`fd` is a file descriptor representing a socket of type `SOCK_STREAM` (a two-way reliable byte-stream connection). Nonblocking I/O and asynchronous notification via `SIGIO` must not be enabled for the socket. The socket must be in a connected state. The socket must be quiescent when `MPI_COMM_JOIN` is called (see below). It is the responsibility of the application to create the socket using standard socket API calls.

`MPI_COMM_JOIN` must be called by the process at each end of the socket. It does not return until both processes have called `MPI_COMM_JOIN`. The two processes are referred to as the local and remote processes.

MPI uses the socket to bootstrap creation of the intercommunicator, and for nothing else. Upon return from `MPI_COMM_JOIN`, the file descriptor will be open and quiescent (see below).

If MPI is unable to create an intercommunicator, but is able to leave the socket in its original state, with no pending communication, it succeeds and sets `intercomm` to `MPI_COMM_NULL`.

The socket must be quiescent before `MPI_COMM_JOIN` is called and after `MPI_COMM_JOIN` returns. More specifically, on entry to `MPI_COMM_JOIN`, a `read` on the socket will not read any data that was written to the socket before the remote process called `MPI_COMM_JOIN`. On exit from `MPI_COMM_JOIN`, a `read` will not read any data that was written to the socket before the remote process returned from `MPI_COMM_JOIN`. It is the responsibility of the application to ensure the first condition, and the responsibility of the MPI implementation to ensure the second. In a multithreaded application, the application must ensure that one thread does not access the socket while another is calling `MPI_COMM_JOIN`, or call `MPI_COMM_JOIN` concurrently.

*Advice to implementors.* MPI is free to use any available communication path(s) for MPI messages in the new communicator; the socket is only used for the initial handshaking. (*End of advice to implementors.*)

`MPI_COMM_JOIN` uses non-MPI communication to do its work. The interaction of non-MPI communication with pending MPI communication is not defined. Therefore, the result

of calling `MPI_COMM_JOIN` on two connected processes (see Section 10.5.4 on page 384 for the definition of connected) is undefined.

The returned communicator may be used to establish MPI communication with additional processes, through the usual MPI communicator creation mechanisms.

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# Chapter 11

## One-Sided Communications

### 11.1 Introduction

Remote Memory Access (RMA) extends the communication mechanisms of MPI by allowing one process to specify all communication parameters, both for the sending side and for the receiving side. This mode of communication facilitates the coding of some applications with dynamically changing data access patterns where the data distribution is fixed or slowly changing. In such a case, each process can compute what data it needs to access or update at other processes. However, processes may not know which data in their own memory need to be accessed or updated by remote processes, and may not even know the identity of these processes. Thus, the transfer parameters are all available only on one side. Regular send/receive communication requires matching operations by sender and receiver. In order to issue the matching operations, an application needs to distribute the transfer parameters. This may require all processes to participate in a time consuming global computation, or to periodically poll for potential communication requests to receive and act upon. The use of RMA communication mechanisms avoids the need for global computations or explicit polling. A generic example of this nature is the execution of an assignment of the form  $A = B(\text{map})$ , where  $\text{map}$  is a permutation vector, and  $A$ ,  $B$  and  $\text{map}$  are distributed in the same manner.

Message-passing communication achieves two effects: *communication* of data from sender to receiver; and *synchronization* of sender with receiver. The RMA design separates these two functions. Three communication calls are provided: `MPI_PUT` (remote write), `MPI_GET` (remote read) and `MPI_ACCUMULATE` (remote update). A larger number of synchronization calls are provided that support different synchronization styles. The design is similar to that of weakly coherent memory systems: correct ordering of memory accesses has to be imposed by the user, using synchronization calls; the implementation can delay communication operations until the synchronization calls occur, for efficiency.

The design of the RMA functions allows implementors to take advantage, in many cases, of fast communication mechanisms provided by various platforms, such as coherent or noncoherent shared memory, DMA engines, hardware-supported put/get operations, communication coprocessors, etc. The most frequently used RMA communication mechanisms can be layered on top of message-passing. However, support for asynchronous communication agents (handlers, threads, etc.) is needed, for certain RMA functions, in a distributed memory environment.

We shall denote by **origin** the process that performs the call, and by **target** the

process in which the memory is accessed. Thus, in a put operation, source=origin and destination=target; in a get operation, source=target and destination=origin.

## 11.2 Initialization

### 11.2.1 Window Creation

The initialization operation allows each process in an intracommunicator group to specify, in a collective operation, a “window” in its memory that is made accessible to accesses by remote processes. The call returns an opaque object that represents the group of processes that own and access the set of windows, and the attributes of each window, as specified by the initialization call.

`MPI_WIN_CREATE(base, size, disp_unit, info, comm, win)`

IN	base	initial address of window (choice)
IN	size	size of window in bytes (non-negative integer)
IN	disp_unit	local unit size for displacements, in bytes (positive integer)
IN	info	info argument (handle)
IN	comm	communicator (handle)
OUT	win	window object returned by the call (handle)

```
int MPI_Win_create(void *base, MPI_Aint size, int disp_unit, MPI_Info info,
                  MPI_Comm comm, MPI_Win *win)
```

```
MPI_WIN_CREATE(BASE, SIZE, DISP_UNIT, INFO, COMM, WIN, IERROR)
```

```
<type> BASE(*)
INTEGER(KIND=MPI_ADDRESS_KIND) SIZE
INTEGER DISP_UNIT, INFO, COMM, WIN, IERROR
```

```
MPI_Win_create(base, size, disp_unit, info, comm, win, ierror)
```

```
TYPE(*), DIMENSION(..) :: base
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: size
INTEGER, INTENT(IN) :: disp_unit
TYPE(MPI_Info), INTENT(IN) :: info
TYPE(MPI_Comm), INTENT(IN) :: comm
TYPE(MPI_Win), INTENT(OUT) :: win
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{static MPI::Win MPI::Win::Create(const void* base, MPI::Aint size, int
                                disp_unit, const MPI::Info& info, const MPI::Intracomm&
                                comm) (binding deprecated, see Section 15.2) }
```

This is a collective call executed by all processes in the group of comm. It returns a window object that can be used by these processes to perform RMA operations. Each process specifies a window of existing memory that it exposes to RMA accesses by the

processes in the group of `comm`. The window consists of `size` bytes, starting at address `base`. A process may elect to expose no memory by specifying `size = 0`.

The displacement unit argument is provided to facilitate address arithmetic in RMA operations: the target displacement argument of an RMA operation is scaled by the factor `disp_unit` specified by the target process, at window creation.

*Rationale.* The window size is specified using an address sized integer, so as to allow windows that span more than 4 GB of address space. (Even if the physical memory size is less than 4 GB, the address range may be larger than 4 GB, if addresses are not contiguous.) (*End of rationale.*)

*Advice to users.* Common choices for `disp_unit` are 1 (no scaling), and (in C syntax) `sizeof(type)`, for a window that consists of an array of elements of type `type`. The later choice will allow one to use array indices in RMA calls, and have those scaled correctly to byte displacements, even in a heterogeneous environment. (*End of advice to users.*)

The `info` argument provides optimization hints to the runtime about the expected usage pattern of the window. The following info key is predefined:

`no_locks` — if set to true, then the implementation may assume that the local window is never locked (by a call to `MPI_WIN_LOCK`). This implies that this window is not used for 3-party communication, and RMA can be implemented with no (less) asynchronous agent activity at this process.

The various processes in the group of `comm` may specify completely different target windows, in location, size, displacement units and info arguments. As long as all the get, put and accumulate accesses to a particular process fit their specific target window this should pose no problem. The same area in memory may appear in multiple windows, each associated with a different window object. However, concurrent communications to distinct, overlapping windows may lead to erroneous results.

*Advice to users.* A window can be created in any part of the process memory. However, on some systems, the performance of windows in memory allocated by `MPI_ALLOC_MEM` (Section 8.2, page 322) will be better. Also, on some systems, performance is improved when window boundaries are aligned at “natural” boundaries (word, double-word, cache line, page frame, etc.). (*End of advice to users.*)

*Advice to implementors.* In cases where RMA operations use different mechanisms in different memory areas (e.g., load/store in a shared memory segment, and an asynchronous handler in private memory), the `MPI_WIN_CREATE` call needs to figure out which type of memory is used for the window. To do so, MPI maintains, internally, the list of memory segments allocated by `MPI_ALLOC_MEM`, or by other, implementation specific, mechanisms, together with information on the type of memory segment allocated. When a call to `MPI_WIN_CREATE` occurs, then MPI checks which segment contains each window, and decides, accordingly, which mechanism to use for RMA operations.

Vendors may provide additional, implementation-specific mechanisms to allocate or to specify memory regions that are preferable for use in one-sided communication. In

particular, such mechanisms can be used to place static variables into such preferred regions.

Implementors should document any performance impact of window alignment. (*End of advice to implementors.*)

**MPI\_WIN\_FREE(win)**

INOUT     win                             window object (handle)

**int MPI\_Win\_free(MPI\_Win \*win)**

**MPI\_WIN\_FREE(WIN, IERROR)**

INTEGER WIN, IERROR

**MPI\_Win\_free(win, ierror)**

TYPE(MPI\_Win), INTENT(INOUT) :: win

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Win::Free() (*binding deprecated, see Section 15.2*) }

Frees the window object win and returns a null handle (equal to MPI\_WIN\_NULL). This is a collective call executed by all processes in the group associated with win. MPI\_WIN\_FREE(win) can be invoked by a process only after it has completed its involvement in RMA communications on window win: i.e., the process has called MPI\_WIN\_FENCE, or called MPI\_WIN\_WAIT to match a previous call to MPI\_WIN\_POST or called MPI\_WIN\_COMPLETE to match a previous call to MPI\_WIN\_START or called MPI\_WIN\_UNLOCK to match a previous call to MPI\_WIN\_LOCK. When the call returns, the window memory can be freed.

*Advice to implementors.* MPI\_WIN\_FREE requires a barrier synchronization: no process can return from free until all processes in the group of win called free. This, to ensure that no process will attempt to access a remote window (e.g., with lock/unlock) after it was freed. (*End of advice to implementors.*)

## 11.2.2 Window Attributes

The following three attributes are cached with a window, when the window is created.

MPI\_WIN\_BASE                             window base address.

MPI\_WIN\_SIZE                             window size, in bytes.

MPI\_WIN\_DISP\_UNIT                        displacement unit associated with the window.

In C, calls to MPI\_Win\_get\_attr(win, MPI\_WIN\_BASE, &base, &flag), MPI\_Win\_get\_attr(win, MPI\_WIN\_SIZE, &size, &flag) and MPI\_Win\_get\_attr(win, MPI\_WIN\_DISP\_UNIT, &disp\_unit, &flag) will return in base a pointer to the start of the window win, and will return in size and disp\_unit pointers to the size and displacement unit of the window, respectively. And similarly, in C++.

In Fortran, calls to MPI\_WIN\_GET\_ATTR(win, MPI\_WIN\_BASE, base, flag, ierror), MPI\_WIN\_GET\_ATTR(win, MPI\_WIN\_SIZE, size, flag, ierror) and

`MPI_WIN_GET_ATTR(win, MPI_WIN_DISP_UNIT, disp_unit, flag, ierror)` will return in `base`, `size` and `disp_unit` the (integer representation of) the base address, the size and the displacement unit of the window `win`, respectively. (The window attribute access functions are defined in Section 6.7.3, page 272.)

The other “window attribute,” namely the group of processes attached to the window, can be retrieved using the call below.

`MPI_WIN_GET_GROUP(win, group)`

IN	<code>win</code>	window object (handle)
OUT	<code>group</code>	group of processes which share access to the window (handle)

`int MPI_Win_get_group(MPI_Win win, MPI_Group *group)`

`MPI_WIN_GET_GROUP(WIN, GROUP, IERROR)`  
`INTEGER WIN, GROUP, IERROR`

`MPI_Win_get_group(win, group, ierror)`  
`TYPE(MPI_Win), INTENT(IN) :: win`  
`TYPE(MPI_Group), INTENT(OUT) :: group`  
`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{MPI::Group MPI::Win::Get_group() const(binding deprecated, see Section 15.2) }`

`MPI_WIN_GET_GROUP` returns a duplicate of the group of the communicator used to create the window associated with `win`. The group is returned in `group`.

## 11.3 Communication Calls

MPI supports three RMA communication calls: `MPI_PUT` transfers data from the caller memory (origin) to the target memory; `MPI_GET` transfers data from the target memory to the caller memory; and `MPI_ACCUMULATE` updates locations in the target memory, e.g. by adding to these locations values sent from the caller memory. These operations are *nonblocking*: the call initiates the transfer, but the transfer may continue after the call returns. The transfer is completed, both at the origin and at the target, when a subsequent *synchronization* call is issued by the caller on the involved window object. These synchronization calls are described in Section 11.4, page 402.

The local communication buffer of an RMA call should not be updated, and the local communication buffer of a get call should not be accessed after the RMA call, until the subsequent synchronization call completes.

It is erroneous to have concurrent conflicting accesses to the same memory location in a window; if a location is updated by a put or accumulate operation, then this location cannot be accessed by a load or another RMA operation until the updating operation has completed at the target. There is one exception to this rule; namely, the same location can be updated by several concurrent accumulate calls, the outcome being as if these updates occurred in some order. In addition, a window cannot concurrently be updated by a put or accumulate operation and by a local store operation. This, even if these two updates access different locations in the window. The last restriction enables more efficient implementations of RMA

operations on many systems. These restrictions are described in more detail in Section 11.7, page 419.

The calls use general datatype arguments to specify communication buffers at the origin and at the target. Thus, a transfer operation may also gather data at the source and scatter it at the destination. However, all arguments specifying both communication buffers are provided by the caller.

For all three calls, the target process may be identical with the origin process; i.e., a process may use an RMA operation to move data in its memory.

*Rationale.* The choice of supporting “self-communication” is the same as for message-passing. It simplifies some coding, and is very useful with accumulate operations, to allow atomic updates of local variables. (*End of rationale.*)

MPI\_PROC\_NULL is a valid target rank in the MPI RMA calls MPI\_ACCUMULATE, MPI\_GET, and MPI\_PUT. The effect is the same as for MPI\_PROC\_NULL in MPI point-to-point communication. After any RMA operation with rank MPI\_PROC\_NULL, it is still necessary to finish the RMA epoch with the synchronization method that started the epoch.

### 11.3.1 Put

The execution of a put operation is similar to the execution of a send by the origin process and a matching receive by the target process. The obvious difference is that all arguments are provided by one call — the call executed by the origin process.

MPI\_PUT(origin\_addr, origin\_count, origin\_datatype, target\_rank, target\_disp, target\_count, target\_datatype, win)

IN	origin_addr	initial address of origin buffer (choice)
IN	origin_count	number of entries in origin buffer (non-negative integer)
IN	origin_datatype	datatype of each entry in origin buffer (handle)
IN	target_rank	rank of target (non-negative integer)
IN	target_disp	displacement from start of window to target buffer (non-negative integer)
IN	target_count	number of entries in target buffer (non-negative integer)
IN	target_datatype	datatype of each entry in target buffer (handle)
IN	win	window object used for communication (handle)

```
int MPI_Put(void *origin_addr, int origin_count, MPI_Datatype
            origin_datatype, int target_rank, MPI_Aint target_disp, int
            target_count, MPI_Datatype target_datatype, MPI_Win win)
MPI_PUT(ORIGIN_ADDR, ORIGIN_COUNT, ORIGIN_DATATYPE, TARGET_RANK,
        TARGET_DISP, TARGET_COUNT, TARGET_DATATYPE, WIN, IERROR)
<type> ORIGIN_ADDR(*)
```

```

INTEGER(KIND=MPI_ADDRESS_KIND) TARGET_DISP
INTEGER ORIGIN_COUNT, ORIGIN_DATATYPE, TARGET_RANK, TARGET_COUNT,
TARGET_DATATYPE, WIN, IERROR
MPI_Put(origin_addr, origin_count, origin_datatype, target_rank,
        target_disp, target_count, target_datatype, win, ierror)
TYPE(*), DIMENSION(..) :: origin_addr
INTEGER, INTENT(IN) :: origin_count, target_rank, target_count
TYPE(MPI_Datatype), INTENT(IN) :: origin_datatype
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: target_disp
TYPE(MPI_Datatype), INTENT(IN) :: target_datatype
TYPE(MPI_Win), INTENT(IN) :: win
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
{void MPI::Win::Put(const void* origin_addr, int origin_count, const
    MPI::Datatype& origin_datatype, int target_rank, MPI::Aint
    target_disp, int target_count, const MPI::Datatype&
    target_datatype) const(binding deprecated, see Section 15.2) }
```

Transfers `origin_count` successive entries of the type specified by the `origin_datatype`, starting at address `origin_addr` on the origin node to the target node specified by the `win`, `target_rank` pair. The data are written in the target buffer at address `target_addr = window_base + target_disp × disp_unit`, where `window_base` and `disp_unit` are the base address and window displacement unit specified at window initialization, by the target process.

The target buffer is specified by the arguments `target_count` and `target_datatype`.

The data transfer is the same as that which would occur if the origin process executed a send operation with arguments `origin_addr`, `origin_count`, `origin_datatype`, `target_rank`, `tag`, `comm`, and the target process executed a receive operation with arguments `target_addr`, `target_count`, `target_datatype`, `source`, `tag`, `comm`, where `target_addr` is the target buffer address computed as explained above, and `comm` is a communicator for the group of `win`.

The communication must satisfy the same constraints as for a similar message-passing communication. The `target_datatype` may not specify overlapping entries in the target buffer. The message sent must fit, without truncation, in the target buffer. Furthermore, the target buffer must fit in the target window.

The `target_datatype` argument is a handle to a datatype object defined at the origin process. However, this object is interpreted at the target process: the outcome is as if the target datatype object was defined at the target process, by the same sequence of calls used to define it at the origin process. The target datatype must contain only relative displacements, not absolute addresses. The same holds for `get` and `accumulate`.

*Advice to users.* The `target_datatype` argument is a handle to a datatype object that is defined at the origin process, even though it defines a data layout in the target process memory. This causes no problems in a homogeneous environment, or in a heterogeneous environment, if only portable datatypes are used (portable datatypes are defined in Section 2.4, page 11).

The performance of a `put` transfer can be significantly affected, on some systems, from the choice of window location and the shape and location of the origin and target buffer: transfers to a target window in memory allocated by `MPI_ALLOC_MEM` may be much faster on shared memory systems; transfers from contiguous buffers will be

faster on most, if not all, systems; the alignment of the communication buffers may also impact performance. (*End of advice to users.*)

*Advice to implementors.* A high-quality implementation will attempt to prevent remote accesses to memory outside the window that was exposed by the process. This, both for debugging purposes, and for protection with client-server codes that use RMA. I.e., a high-quality implementation will check, if possible, window bounds on each RMA call, and raise an MPI exception at the origin call if an out-of-bound situation occurred. Note that the condition can be checked at the origin. Of course, the added safety achieved by such checks has to be weighed against the added cost of such checks. (*End of advice to implementors.*)

### 11.3.2 Get

`MPI_GET(origin_addr, origin_count, origin_datatype, target_rank, target_disp, target_count, target_datatype, win)`

OUT	origin_addr	initial address of origin buffer (choice)
IN	origin_count	number of entries in origin buffer (non-negative integer)
IN	origin_datatype	datatype of each entry in origin buffer (handle)
IN	target_rank	rank of target (non-negative integer)
IN	target_disp	displacement from window start to the beginning of the target buffer (non-negative integer)
IN	target_count	number of entries in target buffer (non-negative integer)
IN	target_datatype	datatype of each entry in target buffer (handle)
IN	win	window object used for communication (handle)

```
int MPI_Get(void *origin_addr, int origin_count, MPI_Datatype
            origin_datatype, int target_rank, MPI_Aint target_disp, int
            target_count, MPI_Datatype target_datatype, MPI_Win win)
```

```
MPI_GET(ORIGIN_ADDR, ORIGIN_COUNT, ORIGIN_DATATYPE, TARGET_RANK,
        TARGET_DISP, TARGET_COUNT, TARGET_DATATYPE, WIN, IERROR)
<type> ORIGIN_ADDR(*)
INTEGER(KIND=MPI_ADDRESS_KIND) TARGET_DISP
INTEGER ORIGIN_COUNT, ORIGIN_DATATYPE, TARGET_RANK, TARGET_COUNT,
TARGET_DATATYPE, WIN, IERROR
```

```
MPI_Get(origin_addr, origin_count, origin_datatype, target_rank,
        target_disp, target_count, target_datatype, win, ierror)
TYPE(*), DIMENSION(..) :: origin_addr
INTEGER, INTENT(IN) :: origin_count, target_rank, target_count
TYPE(MPI_Datatype), INTENT(IN) :: origin_datatype
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: target_disp
```



```

TYPE(MPI_Datatype), INTENT(IN) :: target_datatype
TYPE(MPI_Win), INTENT(IN) :: win
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Win::Get(void *origin_addr, int origin_count, const
    MPI::Datatype& origin_datatype, int target_rank, MPI::Aint
    target_disp, int target_count, const MPI::Datatype&
    target_datatype) const(binding deprecated, see Section 15.2) }
```

Similar to MPI\_PUT, except that the direction of data transfer is reversed. Data are copied from the target memory to the origin. The `origin_datatype` may not specify overlapping entries in the origin buffer. The target buffer must be contained within the target window, and the copied data must fit, without truncation, in the origin buffer.

### 11.3.3 Examples

**Example 11.1** We show how to implement the generic indirect assignment `A = B(map)`, where `A`, `B` and `map` have the same distribution, and `map` is a permutation. To simplify, we assume a block distribution with equal size blocks.

```

SUBROUTINE MAPVALS(A, B, map, m, comm, p)
USE MPI
INTEGER m, map(m), comm, p
REAL A(m), B(m)

INTEGER otype(p), oindex(m),    & ! used to construct origin datatypes
      ttype(p), tindex(m),      & ! used to construct target datatypes
      count(p), total(p),       &
      win, ierr
INTEGER (KIND=MPI_ADDRESS_KIND) lowerbound, sizeofreal

! This part does the work that depends on the locations of B.
! Can be reused while this does not change

CALL MPI_TYPE_GET_EXTENT(MPI_REAL, lowerbound, sizeofreal, ierr)
CALL MPI_WIN_CREATE(B, m*sizeofreal, sizeofreal, MPI_INFO_NULL, &
      comm, win, ierr)

! This part does the work that depends on the value of map and
! the locations of the arrays.
! Can be reused while these do not change

! Compute number of entries to be received from each process

DO i=1,p
  count(i) = 0
END DO
DO i=1,m
```

```

1      j = map(i)/m+1
2      count(j) = count(j)+1
3  END DO
4
5  total(1) = 0
6  DO i=2,p
7      total(i) = total(i-1) + count(i-1)
8  END DO
9
10 DO i=1,p
11     count(i) = 0
12 END DO
13
14 ! compute origin and target indices of entries.
15 ! entry i at current process is received from location
16 ! k at process (j-1), where map(i) = (j-1)*m + (k-1),
17 ! j = 1..p and k = 1..m
18
19 DO i=1,m
20     j = map(i)/m+1
21     k = MOD(map(i),m)+1
22     count(j) = count(j)+1
23     oindex(total(j) + count(j)) = i
24     tindex(total(j) + count(j)) = k
25 END DO
26
27 ! create origin and target datatypes for each get operation
28 DO i=1,p
29     CALL MPI_TYPE_CREATE_INDEXED_BLOCK(count(i), 1, oindex(total(i)+1), &
30                                         MPI_REAL, otype(i), ierr)
31     CALL MPI_TYPE_COMMIT(otype(i), ierr)
32     CALL MPI_TYPE_CREATE_INDEXED_BLOCK(count(i), 1, tindex(total(i)+1), &
33                                         MPI_REAL, ttype(i), ierr)
34     CALL MPI_TYPE_COMMIT(ttype(i), ierr)
35 END DO
36
37 ! this part does the assignment itself
38 CALL MPI_WIN_FENCE(0, win, ierr)
39 DO i=1,p
40     CALL MPI_GET(A, 1, otype(i), i-1, 0, 1, ttype(i), win, ierr)
41 END DO
42 CALL MPI_WIN_FENCE(0, win, ierr)
43
44 CALL MPI_WIN_FREE(win, ierr)
45 DO i=1,p
46     CALL MPI_TYPE_FREE(otype(i), ierr)
47     CALL MPI_TYPE_FREE(ttype(i), ierr)
48 END DO

```

```

RETURN
END

```

### Example 11.2

A simpler version can be written that does not require that a datatype be built for the target buffer. But, one then needs a separate get call for each entry, as illustrated below. This code is much simpler, but usually much less efficient, for large arrays.

```

SUBROUTINE MAPVALS(A, B, map, m, comm, p)
USE MPI
INTEGER m, map(m), comm, p
REAL A(m), B(m)
INTEGER win, ierr
INTEGER (KIND=MPI_ADDRESS_KIND) lowerbound, sizeofreal

CALL MPI_TYPE_GET_EXTENT(MPI_REAL, lowerbound, sizeofreal, ierr)
CALL MPI_WIN_CREATE(B, m*sizeofreal, sizeofreal, MPI_INFO_NULL, &
                   comm, win, ierr)

CALL MPI_WIN_FENCE(0, win, ierr)
DO i=1,m
  j = map(i)/m
  k = MOD(map(i),m)
  CALL MPI_GET(A(i), 1, MPI_REAL, j, k, 1, MPI_REAL, win, ierr)
END DO
CALL MPI_WIN_FENCE(0, win, ierr)
CALL MPI_WIN_FREE(win, ierr)
RETURN
END

```

#### 11.3.4 Accumulate Functions

It is often useful in a put operation to combine the data moved to the target process with the data that resides at that process, rather than replacing the data there. This will allow, for example, the accumulation of a sum by having all involved processes add their contribution to the sum variable in the memory of one process.

```

1 MPI_ACCUMULATE(origin_addr, origin_count, origin_datatype, target_rank, target_disp,
2               target_count, target_datatype, op, win)

```

3	IN	origin_addr	initial address of buffer (choice)
4			
5	IN	origin_count	number of entries in buffer (non-negative integer)
6	IN	origin_datatype	datatype of each buffer entry (handle)
7	IN	target_rank	rank of target (non-negative integer)
8			
9	IN	target_disp	displacement from start of window to beginning of target buffer (non-negative integer)
10			
11	IN	target_count	number of entries in target buffer (non-negative integer)
12			
13	IN	target_datatype	datatype of each entry in target buffer (handle)
14	IN	op	reduce operation (handle)
15	IN	win	window object (handle)

```

17
18 int MPI_Accumulate(void *origin_addr, int origin_count,
19                  MPI_Datatype origin_datatype, int target_rank,
20                  MPI_Aint target_disp, int target_count,
21                  MPI_Datatype target_datatype, MPI_Op op, MPI_Win win)
22

```

```

23 MPI_ACCUMULATE(ORIGIN_ADDR, ORIGIN_COUNT, ORIGIN_DATATYPE, TARGET_RANK,
24               TARGET_DISP, TARGET_COUNT, TARGET_DATATYPE, OP, WIN, IERROR)
25 <type> ORIGIN_ADDR(*)
26 INTEGER(KIND=MPI_ADDRESS_KIND) TARGET_DISP
27 INTEGER ORIGIN_COUNT, ORIGIN_DATATYPE, TARGET_RANK, TARGET_COUNT,
28 TARGET_DATATYPE, OP, WIN, IERROR

```

```

29 MPI_Accumulate(origin_addr, origin_count, origin_datatype, target_rank,
30               target_disp, target_count, target_datatype, op, win, ierror)
31 TYPE(*), DIMENSION(..) :: origin_addr
32 INTEGER, INTENT(IN) :: origin_count, target_rank, target_count
33 TYPE(MPI_Datatype), INTENT(IN) :: origin_datatype
34 INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: target_disp
35 TYPE(MPI_Datatype), INTENT(IN) :: target_datatype
36 TYPE(MPI_Op), INTENT(IN) :: op
37 TYPE(MPI_Win), INTENT(IN) :: win
38 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
39

```

```

40 {void MPI::Win::Accumulate(const void* origin_addr, int origin_count, const
41                          MPI::Datatype& origin_datatype, int target_rank, MPI::Aint
42                          target_disp, int target_count, const MPI::Datatype&
43                          target_datatype, const MPI::Op& op) const(binding deprecated, see
44                          Section 15.2) }
45

```

Accumulate the contents of the origin buffer (as defined by `origin_addr`, `origin_count` and `origin_datatype`) to the buffer specified by arguments `target_count` and `target_datatype`, at offset `target_disp`, in the target window specified by `target_rank` and `win`, using the operation

op. This is like MPI\_PUT except that data is combined into the target area instead of overwriting it.

Any of the predefined operations for MPI\_REDUCE can be used. User-defined functions cannot be used. For example, if op is MPI\_SUM, each element of the origin buffer is added to the corresponding element in the target, replacing the former value in the target.

Each datatype argument must be a predefined datatype or a derived datatype, where all basic components are of the same predefined datatype. Both datatype arguments must be constructed from the same predefined datatype. The operation op applies to elements of that predefined type. target\_datatype must not specify overlapping entries, and the target buffer must fit in the target window.

A new predefined operation, MPI\_REPLACE, is defined. It corresponds to the associative function  $f(a, b) = b$ ; i.e., the current value in the target memory is replaced by the value supplied by the origin.

MPI\_REPLACE can be used only in MPI\_ACCUMULATE, not in collective reduction operations, such as MPI\_REDUCE and others.

*Advice to users.* MPI\_PUT is a special case of MPI\_ACCUMULATE, with the operation MPI\_REPLACE. Note, however, that MPI\_PUT and MPI\_ACCUMULATE have different constraints on concurrent updates. (*End of advice to users.*)

**Example 11.3** We want to compute  $B(j) = \sum_{\text{map}(i)=j} A(i)$ . The arrays A, B and map are distributed in the same manner. We write the simple version.

```

SUBROUTINE SUM(A, B, map, m, comm, p)
USE MPI
INTEGER m, map(m), comm, p, win, ierr
REAL A(m), B(m)
INTEGER (KIND=MPI_ADDRESS_KIND) lowerbound, sizeofreal

CALL MPI_TYPE_GET_EXTENT(MPI_REAL, lowerbound, sizeofreal, ierr)
CALL MPI_WIN_CREATE(B, m*sizeofreal, sizeofreal, MPI_INFO_NULL, &
                    comm, win, ierr)

CALL MPI_WIN_FENCE(0, win, ierr)
DO i=1,m
  j = map(i)/m
  k = MOD(map(i),m)
  CALL MPI_ACCUMULATE(A(i), 1, MPI_REAL, j, k, 1, MPI_REAL, &
                     MPI_SUM, win, ierr)
END DO
CALL MPI_WIN_FENCE(0, win, ierr)

CALL MPI_WIN_FREE(win, ierr)
RETURN
END

```

This code is identical to the code in Example 11.2, page 399, except that a call to get has been replaced by a call to accumulate. (Note that, if map is one-to-one, then the

code computes  $B = A(\text{map}^{-1})$ , which is the reverse assignment to the one computed in that previous example.) In a similar manner, we can replace in Example 11.1, page 397, the call to `get` by a call to `accumulate`, thus performing the computation with only one communication between any two processes.

## 11.4 Synchronization Calls

RMA communications fall in two categories:

- **active target** communication, where data is moved from the memory of one process to the memory of another, and both are explicitly involved in the communication. This communication pattern is similar to message passing, except that all the data transfer arguments are provided by one process, and the second process only participates in the synchronization.
- **passive target** communication, where data is moved from the memory of one process to the memory of another, and only the origin process is explicitly involved in the transfer. Thus, two origin processes may communicate by accessing the same location in a target window. The process that owns the target window may be distinct from the two communicating processes, in which case it does not participate explicitly in the communication. This communication paradigm is closest to a shared memory model, where shared data can be accessed by all processes, irrespective of location.

RMA communication calls with argument `win` must occur at a process only within an **access epoch** for `win`. Such an epoch starts with an RMA synchronization call on `win`; it proceeds with zero or more RMA communication calls (`MPI_PUT`, `MPI_GET` or `MPI_ACCUMULATE`) on `win`; it completes with another synchronization call on `win`. This allows users to amortize one synchronization with multiple data transfers and provide implementors more flexibility in the implementation of RMA operations.

Distinct access epochs for `win` at the same process must be disjoint. On the other hand, epochs pertaining to different `win` arguments may overlap. Local operations or other MPI calls may also occur during an epoch.

In active target communication, a target window can be accessed by RMA operations only within an **exposure epoch**. Such an epoch is started and completed by RMA synchronization calls executed by the target process. Distinct exposure epochs at a process on the same window must be disjoint, but such an exposure epoch may overlap with exposure epochs on other windows or with access epochs for the same or other `win` arguments. There is a one-to-one matching between access epochs at origin processes and exposure epochs on target processes: RMA operations issued by an origin process for a target window will access that target window during the same exposure epoch if and only if they were issued during the same access epoch.

In passive target communication the target process does not execute RMA synchronization calls, and there is no concept of an exposure epoch.

MPI provides three synchronization mechanisms:

1. The `MPI_WIN_FENCE` collective synchronization call supports a simple synchronization pattern that is often used in parallel computations: namely a loosely-synchronous model, where global computation phases alternate with global communication phases. This mechanism is most useful for loosely synchronous algorithms where the graph

of communicating processes changes very frequently, or where each process communicates with many others.

This call is used for active target communication. An access epoch at an origin process or an exposure epoch at a target process are started and completed by calls to `MPI_WIN_FENCE`. A process can access windows at all processes in the group of `win` during such an access epoch, and the local window can be accessed by all processes in the group of `win` during such an exposure epoch.

2. The four functions `MPI_WIN_START`, `MPI_WIN_COMPLETE`, `MPI_WIN_POST` and `MPI_WIN_WAIT` can be used to restrict synchronization to the minimum: only pairs of communicating processes synchronize, and they do so only when a synchronization is needed to order correctly RMA accesses to a window with respect to local accesses to that same window. This mechanism may be more efficient when each process communicates with few (logical) neighbors, and the communication graph is fixed or changes infrequently.

These calls are used for active target communication. An access epoch is started at the origin process by a call to `MPI_WIN_START` and is terminated by a call to `MPI_WIN_COMPLETE`. The start call has a group argument that specifies the group of target processes for that epoch. An exposure epoch is started at the target process by a call to `MPI_WIN_POST` and is completed by a call to `MPI_WIN_WAIT`. The post call has a group argument that specifies the set of origin processes for that epoch.

3. Finally, shared and exclusive locks are provided by the two functions `MPI_WIN_LOCK` and `MPI_WIN_UNLOCK`. Lock synchronization is useful for MPI applications that emulate a shared memory model via MPI calls; e.g., in a “billboard” model, where processes can, at random times, access or update different parts of the billboard.

These two calls provide passive target communication. An access epoch is started by a call to `MPI_WIN_LOCK` and terminated by a call to `MPI_WIN_UNLOCK`. Only one target window can be accessed during that epoch with `win`.

Figure 11.1 illustrates the general synchronization pattern for active target communication. The synchronization between `post` and `start` ensures that the put call of the origin process does not start until the target process exposes the window (with the `post` call); the target process will expose the window only after preceding local accesses to the window have completed. The synchronization between `complete` and `wait` ensures that the put call of the origin process completes before the window is unexposed (with the `wait` call). The target process will execute following local accesses to the target window only after the `wait` returned.

Figure 11.1 shows operations occurring in the natural temporal order implied by the synchronizations: the `post` occurs before the matching `start`, and `complete` occurs before the matching `wait`. However, such **strong** synchronization is more than needed for correct ordering of window accesses. The semantics of MPI calls allow **weak** synchronization, as illustrated in Figure 11.2. The access to the target window is delayed until the window is exposed, after the `post`. However the `start` may complete earlier; the put and `complete` may also terminate earlier, if put data is buffered by the implementation. The synchronization calls order correctly window accesses, but do not necessarily synchronize other operations. This weaker synchronization semantic allows for more efficient implementations.

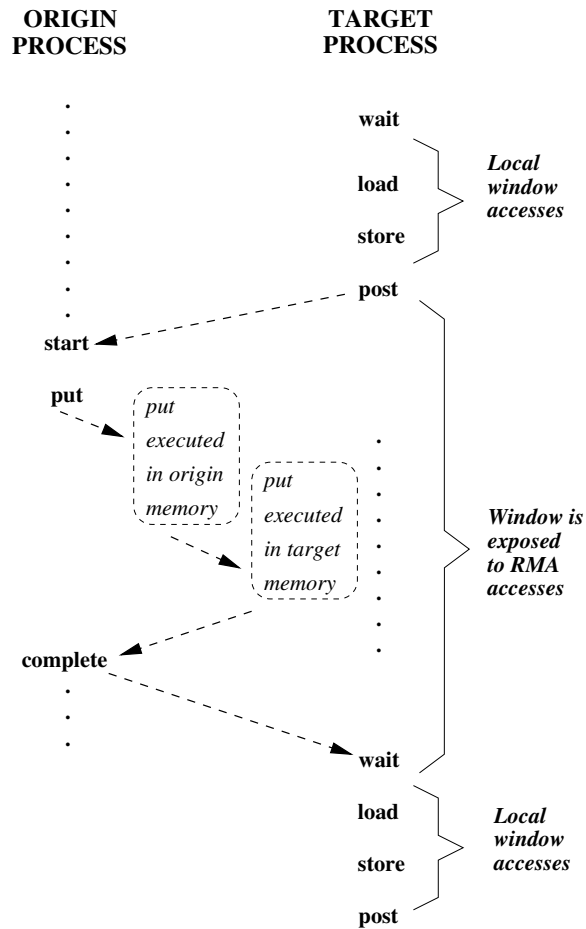


Figure 11.1: Active target communication. Dashed arrows represent synchronizations (ordering of events).



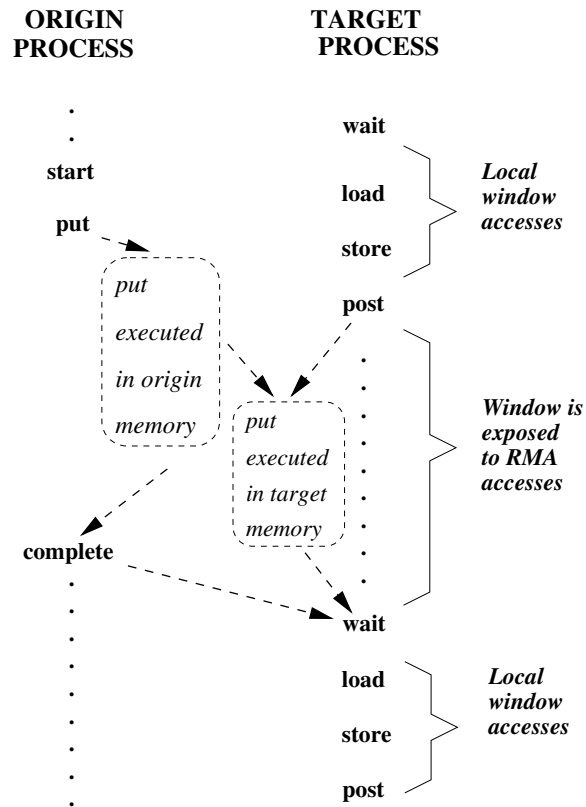


Figure 11.2: Active target communication, with weak synchronization. Dashed arrows represent synchronizations (ordering of events)

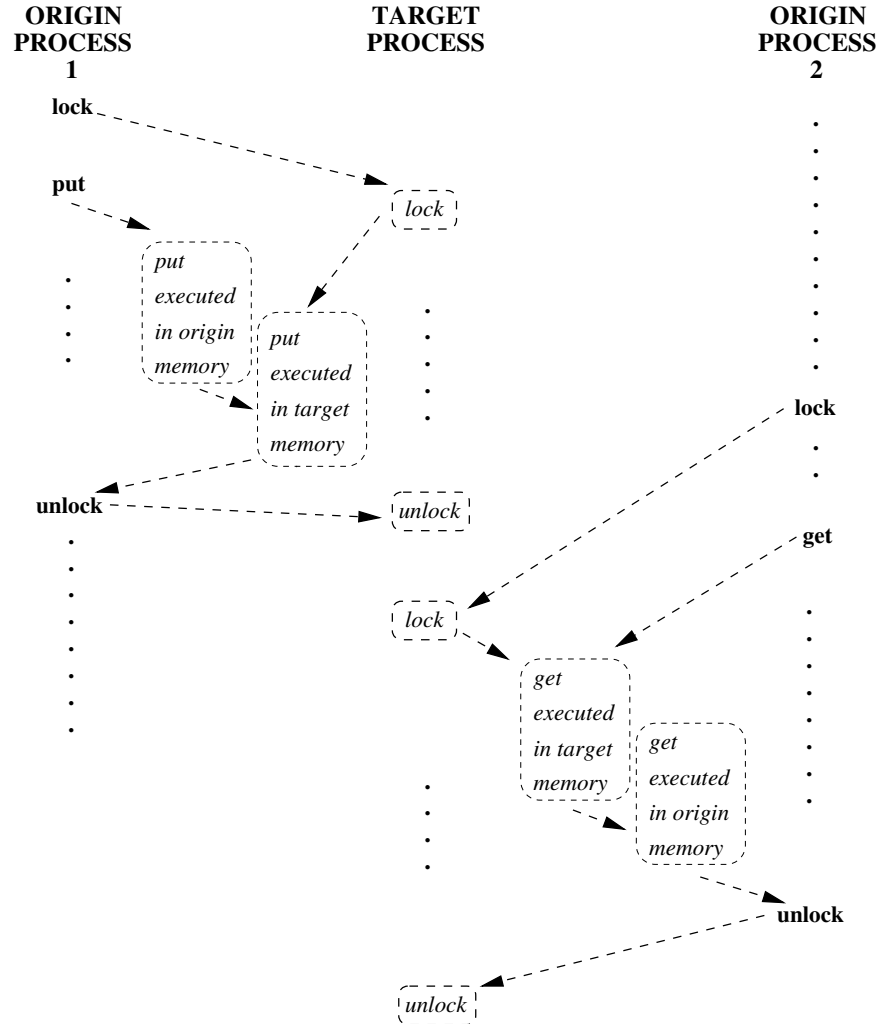


Figure 11.3: Passive target communication. Dashed arrows represent synchronizations (ordering of events).

Figure 11.3 illustrates the general synchronization pattern for passive target communication. The first origin process communicates data to the second origin process, through the memory of the target process; the target process is not explicitly involved in the communication. The **lock** and **unlock** calls ensure that the two RMA accesses do not occur concurrently. However, they do *not* ensure that the **put** by origin 1 will precede the **get** by origin 2.

## 11.4.1 Fence

MPI\_WIN\_FENCE(assert, win)

IN            assert                            program assertion (integer)  
IN            win                                window object (handle)

int MPI\_Win\_fence(int assert, MPI\_Win win)

MPI\_WIN\_FENCE(ASSERT, WIN, IERROR)  
INTEGER ASSERT, WIN, IERROR

MPI\_Win\_fence(assert, win, ierror)  
INTEGER, INTENT(IN) :: assert  
TYPE(MPI\_Win), INTENT(IN) :: win  
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Win::Fence(int assert) const(*binding deprecated, see Section 15.2*) }

The MPI call MPI\_WIN\_FENCE(assert, win) synchronizes RMA calls on win. The call is collective on the group of win. All RMA operations on win originating at a given process and started before the fence call will complete at that process before the fence call returns. They will be completed at their target before the fence call returns at the target. RMA operations on win started by a process after the fence call returns will access their target window only after MPI\_WIN\_FENCE has been called by the target process.

The call completes an RMA access epoch if it was preceded by another fence call and the local process issued RMA communication calls on win between these two calls. The call completes an RMA exposure epoch if it was preceded by another fence call and the local window was the target of RMA accesses between these two calls. The call starts an RMA access epoch if it is followed by another fence call and by RMA communication calls issued between these two fence calls. The call starts an exposure epoch if it is followed by another fence call and the local window is the target of RMA accesses between these two fence calls. Thus, the fence call is equivalent to calls to a subset of **post**, **start**, **complete**, **wait**.

A fence call usually entails a barrier synchronization: a process completes a call to MPI\_WIN\_FENCE only after all other processes in the group entered their matching call. However, a call to MPI\_WIN\_FENCE that is known not to end any epoch (in particular, a call with `assert = MPI_MODE_NOPRECEDE`) does not necessarily act as a barrier.

The `assert` argument is used to provide assertions on the context of the call that may be used for various optimizations. This is described in Section 11.4.4. A value of `assert = 0` is always valid.

*Advice to users.* Calls to MPI\_WIN\_FENCE should both precede and follow calls to **put**, **get** or **accumulate** that are synchronized with fence calls. (*End of advice to users.*)

## 11.4.2 General Active Target Synchronization

MPI\_WIN\_START(group, assert, win)

IN	group	group of target processes (handle)
IN	assert	program assertion (integer)
IN	win	window object (handle)

int MPI\_Win\_start(MPI\_Group group, int assert, MPI\_Win win)

MPI\_WIN\_START(GROUP, ASSERT, WIN, IERROR)

INTEGER GROUP, ASSERT, WIN, IERROR

MPI\_Win\_start(group, assert, win, ierror)

TYPE(MPI\_Group), INTENT(IN) :: group

INTEGER, INTENT(IN) :: assert

TYPE(MPI\_Win), INTENT(IN) :: win

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Win::Start(const MPI::Group& group, int assert) const(*binding deprecated, see Section 15.2*) }

Starts an RMA access epoch for win. RMA calls issued on win during this epoch must access only windows at processes in group. Each process in group must issue a matching call to MPI\_WIN\_POST. RMA accesses to each target window will be delayed, if necessary, until the target process executed the matching call to MPI\_WIN\_POST. MPI\_WIN\_START is allowed to block until the corresponding MPI\_WIN\_POST calls are executed, but is not required to.

The assert argument is used to provide assertions on the context of the call that may be used for various optimizations. This is described in Section 11.4.4. A value of assert = 0 is always valid.

MPI\_WIN\_COMPLETE(win)

IN	win	window object (handle)
----	-----	------------------------

int MPI\_Win\_complete(MPI\_Win win)

MPI\_WIN\_COMPLETE(WIN, IERROR)

INTEGER WIN, IERROR

MPI\_Win\_complete(win, ierror)

TYPE(MPI\_Win), INTENT(IN) :: win

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Win::Complete() const(*binding deprecated, see Section 15.2*) }

Completes an RMA access epoch on win started by a call to MPI\_WIN\_START. All RMA communication calls issued on win during this epoch will have completed at the origin

when the call returns.

`MPI_WIN_COMPLETE` enforces completion of preceding RMA calls at the origin, but not at the target. A put or accumulate call may not have completed at the target when it has completed at the origin.

Consider the sequence of calls in the example below.

#### Example 11.4

```
MPI_Win_start(group, flag, win);
MPI_Put(...,win);
MPI_Win_complete(win);
```

The call to `MPI_WIN_COMPLETE` does not return until the put call has completed at the origin; and the target window will be accessed by the put operation only after the call to `MPI_WIN_START` has matched a call to `MPI_WIN_POST` by the target process. This still leaves much choice to implementors. The call to `MPI_WIN_START` can block until the matching call to `MPI_WIN_POST` occurs at all target processes. One can also have implementations where the call to `MPI_WIN_START` is nonblocking, but the call to `MPI_PUT` blocks until the matching call to `MPI_WIN_POST` occurred; or implementations where the first two calls are nonblocking, but the call to `MPI_WIN_COMPLETE` blocks until the call to `MPI_WIN_POST` occurred; or even implementations where all three calls can complete before any target process called `MPI_WIN_POST` — the data put must be buffered, in this last case, so as to allow the put to complete at the origin ahead of its completion at the target. However, once the call to `MPI_WIN_POST` is issued, the sequence above must complete, without further dependencies.

`MPI_WIN_POST(group, assert, win)`

IN	group	group of origin processes (handle)
IN	assert	program assertion (integer)
IN	win	window object (handle)

```
int MPI_Win_post(MPI_Group group, int assert, MPI_Win win)
```

```
MPI_WIN_POST(GROUP, ASSERT, WIN, IERROR)
```

```
INTEGER GROUP, ASSERT, WIN, IERROR
```

```
MPI_Win_post(group, assert, win, ierror)
```

```
TYPE(MPI_Group), INTENT(IN) :: group
```

```
INTEGER, INTENT(IN) :: assert
```

```
TYPE(MPI_Win), INTENT(IN) :: win
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Win::Post(const MPI::Group& group, int assert) const(binding
    deprecated, see Section 15.2) }
```

Starts an RMA exposure epoch for the local window associated with `win`. Only processes in `group` should access the window with RMA calls on `win` during this epoch. Each process in `group` must issue a matching call to `MPI_WIN_START`. `MPI_WIN_POST` does not block.

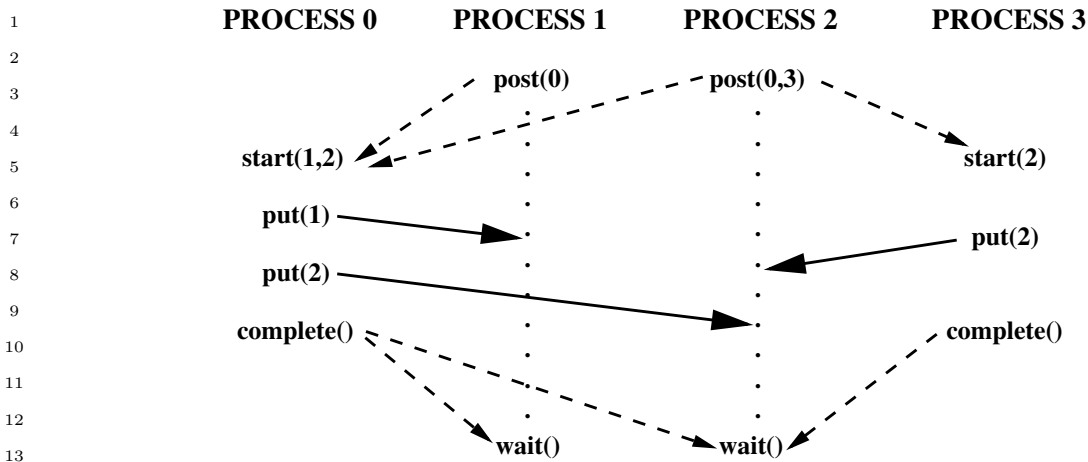


Figure 11.4: Active target communication. Dashed arrows represent synchronizations and solid arrows represent data transfer.

`MPI_WIN_WAIT(win)`

IN win window object (handle)

`int MPI_Win_wait(MPI_Win win)`

`MPI_WIN_WAIT(WIN, IERROR)`

INTEGER WIN, IERROR

`MPI_Win_wait(win, ierror)`

TYPE(MPI\_Win), INTENT(IN) :: win

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

`{void MPI::Win::Wait() const(binding deprecated, see Section 15.2) }`

Completes an RMA exposure epoch started by a call to `MPI_WIN_POST` on win. This call matches calls to `MPI_WIN_COMPLETE(win)` issued by each of the origin processes that were granted access to the window during this epoch. The call to `MPI_WIN_WAIT` will block until all matching calls to `MPI_WIN_COMPLETE` have occurred. This guarantees that all these origin processes have completed their RMA accesses to the local window. When the call returns, all these RMA accesses will have completed at the target window.

Figure 11.4 illustrates the use of these four functions. Process 0 puts data in the windows of processes 1 and 2 and process 3 puts data in the window of process 2. Each start call lists the ranks of the processes whose windows will be accessed; each post call lists the ranks of the processes that access the local window. The figure illustrates a possible timing for the events, assuming strong synchronization; in a weak synchronization, the start, put or complete calls may occur ahead of the matching post calls.

**MPI\_WIN\_TEST**(win, flag)

IN	win	window object (handle)
OUT	flag	success flag (logical)

int MPI\_Win\_test(MPI\_Win win, int \*flag)

MPI\_WIN\_TEST(WIN, FLAG, IERROR)

INTEGER WIN, IERROR  
LOGICAL FLAG

**MPI\_Win\_test**(win, flag, ierror)

LOGICAL, INTENT(OUT) :: flag  
TYPE(MPI\_Win), INTENT(IN) :: win  
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{bool MPI::Win::Test() const(*binding deprecated, see Section 15.2*) }

This is the nonblocking version of MPI\_WIN\_WAIT. It returns `flag = true` if all accesses to the local window by the group to which it was exposed by the corresponding MPI\_WIN\_POST call have been completed as signalled by matching MPI\_WIN\_COMPLETE calls, and `flag = false` otherwise. In the former case MPI\_WIN\_WAIT would have returned immediately. The effect of return of MPI\_WIN\_TEST with `flag = true` is the same as the effect of a return of MPI\_WIN\_WAIT. If `flag = false` is returned, then the call has no visible effect.

MPI\_WIN\_TEST should be invoked only where MPI\_WIN\_WAIT can be invoked. Once the call has returned `flag = true`, it must not be invoked anew, until the window is posted anew.

Assume that window `win` is associated with a “hidden” communicator `wincomm`, used for communication by the processes of `win`. The rules for matching of post and start calls and for matching complete and wait call can be derived from the rules for matching sends and receives, by considering the following (partial) model implementation.

**MPI\_WIN\_POST(group,0,win)** initiate a nonblocking send with tag `tag0` to each process in `group`, using `wincomm`. No need to wait for the completion of these sends.

**MPI\_WIN\_START(group,0,win)** initiate a nonblocking receive with tag `tag0` from each process in `group`, using `wincomm`. An RMA access to a window in target process `i` is delayed until the receive from `i` is completed.

**MPI\_WIN\_COMPLETE(win)** initiate a nonblocking send with tag `tag1` to each process in the group of the preceding start call. No need to wait for the completion of these sends.

**MPI\_WIN\_WAIT(win)** initiate a nonblocking receive with tag `tag1` from each process in the group of the preceding post call. Wait for the completion of all receives.

No races can occur in a correct program: each of the sends matches a unique receive, and vice-versa.

*Rationale.* The design for general active target synchronization requires the user to provide complete information on the communication pattern, at each end of a communication link: each origin specifies a list of targets, and each target specifies a list of origins. This provides maximum flexibility (hence, efficiency) for the implementor: each synchronization can be initiated by either side, since each “knows” the identity of the other. This also provides maximum protection from possible races. On the other hand, the design requires more information than RMA needs, in general: in general, it is sufficient for the origin to know the rank of the target, but not vice versa. Users that want more “anonymous” communication will be required to use the fence or lock mechanisms. (*End of rationale.*)

*Advice to users.* Assume a communication pattern that is represented by a directed graph  $G = \langle V, E \rangle$ , where  $V = \{0, \dots, n-1\}$  and  $ij \in E$  if origin process  $i$  accesses the window at target process  $j$ . Then each process  $i$  issues a call to `MPI_WIN_POST(ingroupi, ...)`, followed by a call to `MPI_WIN_START(outgroupi, ...)`, where  $outgroup_i = \{j : ij \in E\}$  and  $ingroup_i = \{j : ji \in E\}$ . A call is a noop, and can be skipped, if the group argument is empty. After the communications calls, each process that issued a start will issue a complete. Finally, each process that issued a post will issue a wait.

Note that each process may call with a group argument that has different members. (*End of advice to users.*)

### 11.4.3 Lock

`MPI_WIN_LOCK(lock_type, rank, assert, win)`

IN	lock_type	either <code>MPI_LOCK_EXCLUSIVE</code> or <code>MPI_LOCK_SHARED</code> (state)
IN	rank	rank of locked window (non-negative integer)
IN	assert	program assertion (integer)
IN	win	window object (handle)

`int MPI_Win_lock(int lock_type, int rank, int assert, MPI_Win win)`

`MPI_WIN_LOCK(LOCK_TYPE, RANK, ASSERT, WIN, IERROR)`

`INTEGER LOCK_TYPE, RANK, ASSERT, WIN, IERROR`

`MPI_Win_lock(lock_type, rank, assert, win, ierror)`  
`INTEGER, INTENT(IN) :: lock_type, rank, assert`  
`TYPE(MPI_Win), INTENT(IN) :: win`  
`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{void MPI::Win::Lock(int lock_type, int rank, int assert) const(binding deprecated, see Section 15.2) }`

Starts an RMA access epoch. Only the window at the process with rank `rank` can be accessed by RMA operations on `win` during that epoch.



MPI\_WIN\_UNLOCK(rank, win)

IN	rank	rank of window (non-negative integer)
IN	win	window object (handle)

int MPI\_Win\_unlock(int rank, MPI\_Win win)

MPI\_WIN\_UNLOCK(RANK, WIN, IERROR)

INTEGER RANK, WIN, IERROR

MPI\_Win\_unlock(rank, win, ierror)

INTEGER, INTENT(IN) :: rank

TYPE(MPI\_Win), INTENT(IN) :: win

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::Win::Unlock(int rank) const(*binding deprecated, see Section 15.2*) }

Completes an RMA access epoch started by a call to MPI\_WIN\_LOCK(...,win). RMA operations issued during this period will have completed both at the origin and at the target when the call returns.

Locks are used to protect accesses to the locked target window effected by RMA calls issued between the lock and unlock call, and to protect local load/store accesses to a locked local window executed between the lock and unlock call. Accesses that are protected by an exclusive lock will not be concurrent at the window site with other accesses to the same window that are lock protected. Accesses that are protected by a shared lock will not be concurrent at the window site with accesses protected by an exclusive lock to the same window.

It is erroneous to have a window locked and exposed (in an exposure epoch) concurrently. I.e., a process may not call MPI\_WIN\_LOCK to lock a target window if the target process has called MPI\_WIN\_POST and has not yet called MPI\_WIN\_WAIT; it is erroneous to call MPI\_WIN\_POST while the local window is locked.

*Rationale.* An alternative is to require MPI to enforce mutual exclusion between exposure epochs and locking periods. But this would entail additional overheads when locks or active target synchronization do not interact in support of those rare interactions between the two mechanisms. The programming style that we encourage here is that a set of windows is used with only one synchronization mechanism at a time, with shifts from one mechanism to another being rare and involving global synchronization. (*End of rationale.*)

*Advice to users.* Users need to use explicit synchronization code in order to enforce mutual exclusion between locking periods and exposure epochs on a window. (*End of advice to users.*)

Implementors may restrict the use of RMA communication that is synchronized by lock calls to windows in memory allocated by MPI\_ALLOC\_MEM (Section 8.2, page 322). Locks can be used portably only in such memory.

*Rationale.* The implementation of passive target communication when memory is not shared requires an asynchronous agent. Such an agent can be implemented more

easily, and can achieve better performance, if restricted to specially allocated memory. It can be avoided altogether if shared memory is used. It seems natural to impose restrictions that allows one to use shared memory for 3-rd party communication in shared memory machines.

The downside of this decision is that passive target communication cannot be used without taking advantage of nonstandard Fortran features: namely, the availability of C-like pointers; these are not supported by some Fortran compilers (g77 and Windows/NT compilers, at the time of writing). Also, passive target communication cannot be portably targeted to `COMMON` blocks, or other statically declared Fortran arrays. (*End of rationale.*)

Consider the sequence of calls in the example below.

#### Example 11.5

```
MPI_Win_lock(MPI_LOCK_EXCLUSIVE, rank, assert, win)
MPI_Put(..., rank, ..., win)
MPI_Win_unlock(rank, win)
```

The call to `MPI_WIN_UNLOCK` will not return until the put transfer has completed at the origin and at the target. This still leaves much freedom to implementors. The call to `MPI_WIN_LOCK` may block until an exclusive lock on the window is acquired; or, the call `MPI_WIN_LOCK` may not block, while the call to `MPI_PUT` blocks until a lock is acquired; or, the first two calls may not block, while `MPI_WIN_UNLOCK` blocks until a lock is acquired — the update of the target window is then postponed until the call to `MPI_WIN_UNLOCK` occurs. However, if the call to `MPI_WIN_LOCK` is used to lock a local window, then the call must block until the lock is acquired, since the lock may protect local load/store accesses to the window issued after the lock call returns.

#### 11.4.4 Assertions

The `assert` argument in the calls `MPI_WIN_POST`, `MPI_WIN_START`, `MPI_WIN_FENCE` and `MPI_WIN_LOCK` is used to provide assertions on the context of the call that may be used to optimize performance. The `assert` argument does not change program semantics if it provides correct information on the program — it is erroneous to provides incorrect information. Users may always provide `assert = 0` to indicate a general case, where no guarantees are made.

*Advice to users.* Many implementations may not take advantage of the information in `assert`; some of the information is relevant only for noncoherent, shared memory machines. Users should consult their implementation manual to find which information is useful on each system. On the other hand, applications that provide correct assertions whenever applicable are portable and will take advantage of assertion specific optimizations, whenever available. (*End of advice to users.*)

*Advice to implementors.* Implementations can always ignore the `assert` argument. Implementors should document which `assert` values are significant on their implementation. (*End of advice to implementors.*)

`assert` is the bit-vector OR of zero or more of the following integer constants: `MPI_MODE_NOCHECK`, `MPI_MODE_NOSTORE`, `MPI_MODE_NOPUT`, `MPI_MODE_NOPRECEDE` and `MPI_MODE_NOSUCCEED`. The significant options are listed below, for each call.

*Advice to users.* C/C++ users can use bit vector or (`|`) to combine these constants; Fortran 90 users can use the bit-vector `IOR` intrinsic. Fortran 77 users can use (non-portably) bit vector `IOR` on systems that support it. Alternatively, Fortran users can portably use integer addition to OR the constants (each constant should appear at most once in the addition!). (*End of advice to users.*)

#### **MPI\_WIN\_START:**

`MPI_MODE_NOCHECK` — the matching calls to `MPI_WIN_POST` have already completed on all target processes when the call to `MPI_WIN_START` is made. The `nocheck` option can be specified in a start call if and only if it is specified in each matching post call. This is similar to the optimization of “ready-send” that may save a handshake when the handshake is implicit in the code. (However, ready-send is matched by a regular receive, whereas both start and post must specify the `nocheck` option.)

#### **MPI\_WIN\_POST:**

`MPI_MODE_NOCHECK` — the matching calls to `MPI_WIN_START` have not yet occurred on any origin processes when the call to `MPI_WIN_POST` is made. The `nocheck` option can be specified by a post call if and only if it is specified by each matching start call.

`MPI_MODE_NOSTORE` — the local window was not updated by local stores (or local get or receive calls) since last synchronization. This may avoid the need for cache synchronization at the post call.

`MPI_MODE_NOPUT` — the local window will not be updated by put or accumulate calls after the post call, until the ensuing (wait) synchronization. This may avoid the need for cache synchronization at the wait call.

#### **MPI\_WIN\_FENCE:**

`MPI_MODE_NOSTORE` — the local window was not updated by local stores (or local get or receive calls) since last synchronization.

`MPI_MODE_NOPUT` — the local window will not be updated by put or accumulate calls after the fence call, until the ensuing (fence) synchronization.

`MPI_MODE_NOPRECEDE` — the fence does not complete any sequence of locally issued RMA calls. If this assertion is given by any process in the window group, then it must be given by all processes in the group.

**MPI\_MODE\_NOSUCCEED** — the fence does not start any sequence of locally issued RMA calls. If the assertion is given by any process in the window group, then it must be given by all processes in the group.

#### **MPI\_WIN\_LOCK:**

`MPI_MODE_NOCHECK` — no other process holds, or will attempt to acquire a conflicting lock, while the caller holds the window lock. This is useful when mutual exclusion is achieved by other means, but the coherence operations that may be attached to the lock and unlock calls are still required.

*Advice to users.* Note that the `nostore` and `noprecede` flags provide information on what happened *before* the call; the `noput` and `nosucceed` flags provide information on what will happen *after* the call. (*End of advice to users.*)

#### 11.4.5 Miscellaneous Clarifications

Once an RMA routine completes, it is safe to free any opaque objects passed as argument to that routine. For example, the `datatype` argument of a `MPI_PUT` call can be freed as soon as the call returns, even though the communication may not be complete.

As in message-passing, datatypes must be committed before they can be used in RMA communication.

### 11.5 Examples

**Example 11.6** The following example shows a generic loosely synchronous, iterative code, using fence synchronization. The window at each process consists of array `A`, which contains the origin and target buffers of the put calls.

```
...
while(!converged(A)){
    update(A);
    MPI_Win_fence(MPI_MODE_NOPRECEDE, win);
    for(i=0; i < toneighbors; i++)
        MPI_Put(&frombuf[i], 1, fromtype[i], toneighbor[i],
                todisp[i], 1, totype[i], win);
    MPI_Win_fence((MPI_MODE_NOSTORE | MPI_MODE_NOSUCCEED), win);
}
```

The same code could be written with `get` rather than `put`. Note that, during the communication phase, each window is concurrently read (as origin buffer of puts) and written (as target buffer of puts). This is OK, provided that there is no overlap between the target buffer of a put and another communication buffer.

**Example 11.7** Same generic example, with more computation/communication overlap. We assume that the update phase is broken in two subphases: the first, where the “boundary,” which is involved in communication, is updated, and the second, where the “core,” which neither use nor provide communicated data, is updated.

```

...
while(!converged(A)){
    update_boundary(A);
    MPI_Win_fence((MPI_MODE_NOPUT | MPI_MODE_NOPRECEDE), win);
    for(i=0; i < fromneighbors; i++)
        MPI_Get(&tobuf[i], 1, totype[i], fromneighbor[i],
                fromdisp[i], 1, fromtype[i], win);
    update_core(A);
    MPI_Win_fence(MPI_MODE_NOSUCCEED, win);
}

```

The get communication can be concurrent with the core update, since they do not access the same locations, and the local update of the origin buffer by the get call can be concurrent with the local update of the core by the `update_core` call. In order to get similar overlap with put communication we would need to use separate windows for the core and for the boundary. This is required because we do not allow local stores to be concurrent with puts on the same, or on overlapping, windows.

**Example 11.8** Same code as in Example 11.6, rewritten using post-start-complete-wait.

```

...
while(!converged(A)){
    update(A);
    MPI_Win_post(fromgroup, 0, win);
    MPI_Win_start(togroup, 0, win);
    for(i=0; i < toneighbors; i++)
        MPI_Put(&frombuf[i], 1, fromtype[i], toneighbor[i],
                todisp[i], 1, totype[i], win);
    MPI_Win_complete(win);
    MPI_Win_wait(win);
}

```

**Example 11.9** Same example, with split phases, as in Example 11.7.

```

...
while(!converged(A)){
    update_boundary(A);
    MPI_Win_post(togroup, MPI_MODE_NOPUT, win);
    MPI_Win_start(fromgroup, 0, win);
    for(i=0; i < fromneighbors; i++)
        MPI_Get(&tobuf[i], 1, totype[i], fromneighbor[i],
                fromdisp[i], 1, fromtype[i], win);
    update_core(A);
    MPI_Win_complete(win);
    MPI_Win_wait(win);
}

```

**Example 11.10** A checkerboard, or double buffer communication pattern, that allows more computation/communication overlap. Array `A0` is updated using values of array `A1`, and vice versa. We assume that communication is symmetric: if process A gets data from process B, then process B gets data from process A. Window `win0` consists of array `Ai`.

```

...
if (!converged(A0,A1))
    MPI_Win_post(neighbors, (MPI_MODE_NOCHECK | MPI_MODE_NOPUT), win0);
MPI_Barrier(comm0);
/* the barrier is needed because the start call inside the
loop uses the nocheck option */
while(!converged(A0, A1)){
    /* communication on A0 and computation on A1 */
    update2(A1, A0); /* local update of A1 that depends on A0 (and A1) */
    MPI_Win_start(neighbors, MPI_MODE_NOCHECK, win0);
    for(i=0; i < neighbors; i++)
        MPI_Get(&tobuf0[i], 1, totype0[i], neighbor[i],
                fromdisp0[i], 1, fromtype0[i], win0);
    update1(A1); /* local update of A1 that is
                  concurrent with communication that updates A0 */
    MPI_Win_post(neighbors, (MPI_MODE_NOCHECK | MPI_MODE_NOPUT), win1);
    MPI_Win_complete(win0);
    MPI_Win_wait(win0);

    /* communication on A1 and computation on A0 */
    update2(A0, A1); /* local update of A0 that depends on A1 (and A0)*/
    MPI_Win_start(neighbors, MPI_MODE_NOCHECK, win1);
    for(i=0; i < neighbors; i++)
        MPI_Get(&tobuf1[i], 1, totype1[i], neighbor[i],
                fromdisp1[i], 1, fromtype1[i], win1);
    update1(A0); /* local update of A0 that depends on A0 only,
                  concurrent with communication that updates A1 */
    if (!converged(A0,A1))
        MPI_Win_post(neighbors, (MPI_MODE_NOCHECK | MPI_MODE_NOPUT), win0);
    MPI_Win_complete(win1);
    MPI_Win_wait(win1);
}

```

A process posts the local window associated with `win0` before it completes RMA accesses to the remote windows associated with `win1`. When the `wait(win1)` call returns, then all neighbors of the calling process have posted the windows associated with `win0`. Conversely, when the `wait(win0)` call returns, then all neighbors of the calling process have posted the windows associated with `win1`. Therefore, the `nocheck` option can be used with the calls to `MPI_WIN_START`.

Put calls can be used, instead of get calls, if the area of array `A0` (resp. `A1`) used by the `update(A1, A0)` (resp. `update(A0, A1)`) call is disjoint from the area modified by the RMA communication. On some systems, a put call may be more efficient than a get call, as it requires information exchange only in one direction.

## 11.6 Error Handling

### 11.6.1 Error Handlers

Errors occurring during calls to `MPI_WIN_CREATE(...,comm,...)` cause the error handler currently associated with `comm` to be invoked. All other RMA calls have an input `win` argument. When an error occurs during such a call, the error handler currently associated with `win` is invoked.

The default error handler associated with `win` is `MPI_ERRORS_ARE_FATAL`. Users may change this default by explicitly associating a new error handler with `win` (see Section 8.3, page 325).

### 11.6.2 Error Classes

The following error classes for one-sided communication are defined

<code>MPI_ERR_WIN</code>	invalid <code>win</code> argument
<code>MPI_ERR_BASE</code>	invalid <code>base</code> argument
<code>MPI_ERR_SIZE</code>	invalid <code>size</code> argument
<code>MPI_ERR_DISP</code>	invalid <code>disp</code> argument
<code>MPI_ERR_LOCKTYPE</code>	invalid <code>locktype</code> argument
<code>MPI_ERR_ASSERT</code>	invalid <code>assert</code> argument
<code>MPI_ERR_RMA_CONFLICT</code>	conflicting accesses to window
<code>MPI_ERR_RMA_SYNC</code>	wrong synchronization of RMA calls

Table 11.1: Error classes in one-sided communication routines

## 11.7 Semantics and Correctness

The semantics of RMA operations is best understood by assuming that the system maintains a separate *public* copy of each window, in addition to the original location in process memory (the *private* window copy). There is only one instance of each variable in process memory, but a distinct *public* copy of the variable for each window that contains it. A load accesses the instance in process memory (this includes MPI sends). A store accesses and updates the instance in process memory (this includes MPI receives), but the update may affect other public copies of the same locations. A get on a window accesses the public copy of that window. A put or accumulate on a window accesses and updates the public copy of that window, but the update may affect the private copy of the same locations in process memory, and public copies of other overlapping windows. This is illustrated in Figure 11.5.

The following rules specify the latest time at which an operation must complete at the origin or the target. The update performed by a get call in the origin process memory is visible when the get operation is complete at the origin (or earlier); the update performed by a put or accumulate call in the public copy of the target window is visible when the put or accumulate has completed at the target (or earlier). The rules also specify the latest time at which an update of one window copy becomes visible in another overlapping copy.

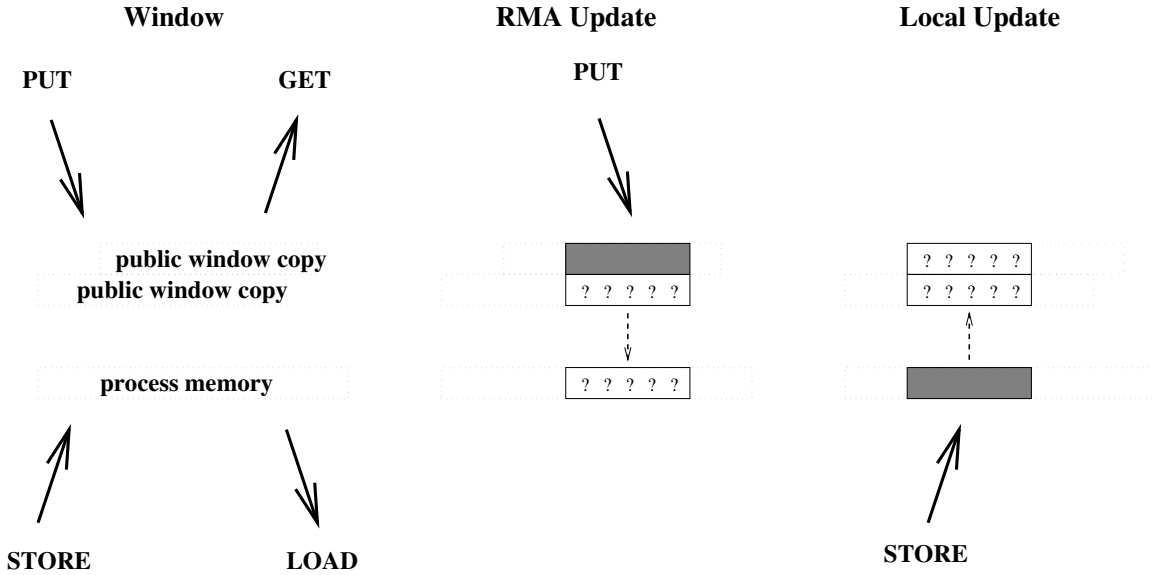


Figure 11.5: Schematic description of window

1. An RMA operation is completed at the origin by the ensuing call to `MPI_WIN_COMPLETE`, `MPI_WIN_FENCE` or `MPI_WIN_UNLOCK` that synchronizes this access at the origin.
2. If an RMA operation is completed at the origin by a call to `MPI_WIN_FENCE` then the operation is completed at the target by the matching call to `MPI_WIN_FENCE` by the target process.
3. If an RMA operation is completed at the origin by a call to `MPI_WIN_COMPLETE` then the operation is completed at the target by the matching call to `MPI_WIN_WAIT` by the target process.
4. If an RMA operation is completed at the origin by a call to `MPI_WIN_UNLOCK` then the operation is completed at the target by that same call to `MPI_WIN_UNLOCK`.
5. An update of a location in a private window copy in process memory becomes visible in the public window copy at latest when an ensuing call to `MPI_WIN_POST`, `MPI_WIN_FENCE`, or `MPI_WIN_UNLOCK` is executed on that window by the window owner.
6. An update by a put or accumulate call to a public window copy becomes visible in the private copy in process memory at latest when an ensuing call to `MPI_WIN_WAIT`, `MPI_WIN_FENCE`, or `MPI_WIN_LOCK` is executed on that window by the window owner.

The `MPI_WIN_FENCE` or `MPI_WIN_WAIT` call that completes the transfer from public copy to private copy (6) is the same call that completes the put or accumulate operation in the window copy (2, 3). If a put or accumulate access was synchronized with a lock, then the update of the public window copy is complete as soon as the updating process executed `MPI_WIN_UNLOCK`. On the other hand, the update of private copy in the process memory may be delayed until the target process executes a synchronization call on that window



(6). Thus, updates to process memory can always be delayed until the process executes a suitable synchronization call. Updates to a public window copy can also be delayed until the window owner executes a synchronization call, if fences or post-start-complete-wait synchronization is used. Only when lock synchronization is used does it become necessary to update the public window copy, even if the window owner does not execute any related synchronization call.

The rules above also define, by implication, when an update to a public window copy becomes visible in another overlapping public window copy. Consider, for example, two overlapping windows, win1 and win2. A call to `MPI_WIN_FENCE(0, win1)` by the window owner makes visible in the process memory previous updates to window win1 by remote processes. A subsequent call to `MPI_WIN_FENCE(0, win2)` makes these updates visible in the public copy of win2.

A correct program must obey the following rules.

1. A location in a window must not be accessed locally once an update to that location has started, until the update becomes visible in the private window copy in process memory.
2. A location in a window must not be accessed as a target of an RMA operation once an update to that location has started, until the update becomes visible in the public window copy. There is one exception to this rule, in the case where the same variable is updated by two concurrent accumulates that use the same operation, with the same predefined datatype, on the same window.
3. A put or accumulate must not access a target window once a local update or a put or accumulate update to another (overlapping) target window have started on a location in the target window, until the update becomes visible in the public copy of the window. Conversely, a local update in process memory to a location in a window must not start once a put or accumulate update to that target window has started, until the put or accumulate update becomes visible in process memory. In both cases, the restriction applies to operations even if they access disjoint locations in the window.

A program is erroneous if it violates these rules.

*Rationale.* The last constraint on correct RMA accesses may seem unduly restrictive, as it forbids concurrent accesses to nonoverlapping locations in a window. The reason for this constraint is that, on some architectures, explicit coherence restoring operations may be needed at synchronization points. A different operation may be needed for locations that were locally updated by stores and for locations that were remotely updated by put or accumulate operations. Without this constraint, the MPI library will have to track precisely which locations in a window were updated by a put or accumulate call. The additional overhead of maintaining such information is considered prohibitive. (*End of rationale.*)

*Advice to users.* A user can write correct programs by following the following rules:

**fence:** During each period between fence calls, each window is either updated by put or accumulate calls, or updated by local stores, but not both. Locations updated by put or accumulate calls should not be accessed during the same period (with



**Example 11.12** Rule 6:

Process A:                      Process B:  
                                  window location X

```

MPI_Win_lock(EXCLUSIVE,B)
MPI_Put(X) /* update to public window */
MPI_Win_unlock(B)

MPI_Barrier                      MPI_Barrier

                                 MPI_Win_lock(EXCLUSIVE,B)
                                 /* now visible in private copy of B */
                                 load X
                                 MPI_Win_unlock(B)

```

Note that the private copy of X has not necessarily been updated after the barrier, so omitting the lock-unlock at process B may lead to the load returning an obsolete value.

**Example 11.13** The rules do *not* guarantee that process A in the following sequence will see the value of X as updated by the local store by B before the lock.

```

Process A:                      Process B:
                                 window location X

                                 store X /* update to private copy of B */
                                 MPI_Win_lock(SHARED,B)
MPI_Barrier                      MPI_Barrier

MPI_Win_lock(SHARED,B)
MPI_Get(X) /* X may not be in public window copy */
MPI_Win_unlock(B)

                                 MPI_Win_unlock(B)
                                 /* update on X now visible in public window */

```

**Example 11.14** In the following sequence

```

Process A:                      Process B:
window location X
window location Y

store Y
MPI_Win_post(A,B) /* Y visible in public window */
MPI_Win_start(A)                      MPI_Win_start(A)

store X /* update to private window */

MPI_Win_complete                      MPI_Win_complete
MPI_Win_wait

```

```

1  /* update on X may not yet visible in public window */
2
3  MPI_Barrier                MPI_Barrier
4
5                          MPI_Win_lock(EXCLUSIVE,A)
6                          MPI_Get(X) /* may return an obsolete value */
7                          MPI_Get(Y)
8                          MPI_Win_unlock(A)
9

```

it is *not* guaranteed that process B reads the value of X as per the local update by process A, because neither `MPI_WIN_WAIT` nor `MPI_WIN_COMPLETE` calls by process A ensure visibility in the public window copy. To allow B to read the value of X stored by A the local store must be replaced by a local `MPI_PUT` that updates the public window copy. Note that by this replacement X may become visible in the private copy in process memory of A only after the `MPI_WIN_WAIT` call in process A. The update on Y made before the `MPI_WIN_POST` call is visible in the public window after the `MPI_WIN_POST` call and therefore correctly gotten by process B. The `MPI_GET(Y)` call could be moved to the epoch started by the `MPI_WIN_START` operation, and process B would still get the value stored by A.

**Example 11.15** Finally, in the following sequence

```

22 Process A:                Process B:
23                               window location X
24
25 MPI_Win_lock(EXCLUSIVE,B)
26 MPI_Put(X) /* update to public window */
27 MPI_Win_unlock(B)
28
29 MPI_Barrier                MPI_Barrier
30
31                               MPI_Win_post(B)
32                               MPI_Win_start(B)
33
34                               load X /* access to private window */
35                               /* may return an obsolete value */
36
37                               MPI_Win_complete
38                               MPI_Win_wait
39

```

rules (5,6) do *not* guarantee that the private copy of X at B has been updated before the load takes place. To ensure that the value put by process A is read, the local load must be replaced with a local `MPI_GET` operation, or must be placed after the call to `MPI_WIN_WAIT`.

### 11.7.1 Atomicity

The outcome of concurrent accumulates to the same location, with the same operation and predefined datatype, is as if the accumulates were done at that location in some serial

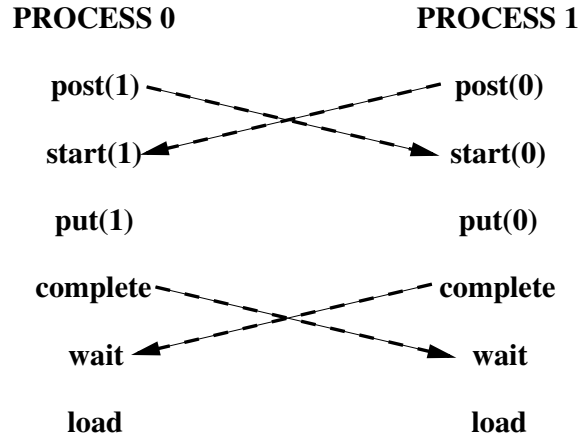


Figure 11.6: Symmetric communication

order. On the other hand, if two locations are both updated by two accumulate calls, then the updates may occur in reverse order at the two locations. Thus, there is no guarantee that the entire call to `MPI_ACCUMULATE` is executed atomically. The effect of this lack of atomicity is limited: The previous correctness conditions imply that a location updated by a call to `MPI_ACCUMULATE`, cannot be accessed by load or an RMA call other than accumulate, until the `MPI_ACCUMULATE` call has completed (at the target). Different interleavings can lead to different results only to the extent that computer arithmetics are not truly associative or commutative.

### 11.7.2 Progress

One-sided communication has the same progress requirements as point-to-point communication: once a communication is enabled, then it is guaranteed to complete. RMA calls must have local semantics, except when required for synchronization with other RMA calls.

There is some fuzziness in the definition of the time when a RMA communication becomes enabled. This fuzziness provides to the implementor more flexibility than with point-to-point communication. Access to a target window becomes enabled once the corresponding synchronization (such as `MPI_WIN_FENCE` or `MPI_WIN_POST`) has executed. On the origin process, an RMA communication may become enabled as soon as the corresponding put, get or accumulate call has executed, or as late as when the ensuing synchronization call is issued. Once the communication is enabled both at the origin and at the target, the communication must complete.

Consider the code fragment in Example 11.4, on page 409. Some of the calls may block if the target window is not posted. However, if the target window is posted, then the code fragment must complete. The data transfer may start as soon as the put call occur, but may be delayed until the ensuing complete call occurs.

Consider the code fragment in Example 11.5, on page 414. Some of the calls may block if another process holds a conflicting lock. However, if no conflicting lock is held, then the code fragment must complete.

Consider the code illustrated in Figure 11.6. Each process updates the window of the other process using a put operation, then accesses its own window. The post calls are nonblocking, and should complete. Once the post calls occur, RMA access to the windows is enabled, so that each process should complete the sequence of calls start-put-complete. Once

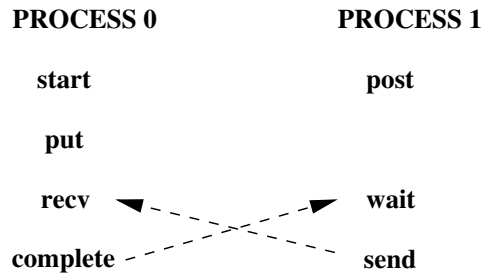


Figure 11.7: Deadlock situation

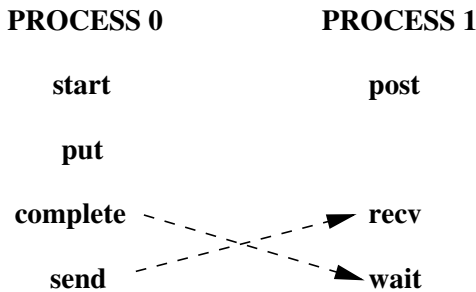


Figure 11.8: No deadlock

these are done, the wait calls should complete at both processes. Thus, this communication should not deadlock, irrespective of the amount of data transferred.

Assume, in the last example, that the order of the post and start calls is reversed, at each process. Then, the code may deadlock, as each process may block on the start call, waiting for the matching post to occur. Similarly, the program will deadlock, if the order of the complete and wait calls is reversed, at each process.

The following two examples illustrate the fact that the synchronization between complete and wait is not symmetric: the wait call blocks until the complete executes, but not vice-versa. Consider the code illustrated in Figure 11.7. This code will deadlock: the wait of process 1 blocks until process 0 calls complete, and the receive of process 0 blocks until process 1 calls send. Consider, on the other hand, the code illustrated in Figure 11.8. This code will not deadlock. Once process 1 calls post, then the sequence start, put, complete on process 0 can proceed to completion. Process 0 will reach the send call, allowing the receive call of process 1 to complete.

*Rationale.* MPI implementations must guarantee that a process makes progress on all enabled communications it participates in, while blocked on an MPI call. This is true for send-receive communication and applies to RMA communication as well. Thus, in the example in Figure 11.8, the put and complete calls of process 0 should complete while process 1 is blocked on the receive call. This may require the involvement of process 1, e.g., to transfer the data put, while it is blocked on the receive call.

A similar issue is whether such progress must occur while a process is busy computing, or blocked in a non-MPI call. Suppose that in the last example the send-receive pair is replaced by a write-to-socket/read-from-socket pair. Then MPI does not specify whether deadlock is avoided. Suppose that the blocking receive of process 1 is replaced by a very long compute loop. Then, according to one interpretation of the

MPI standard, process 0 must return from the complete call after a bounded delay, even if process 1 does not reach any MPI call in this period of time. According to another interpretation, the complete call may block until process 1 reaches the wait call, or reaches another MPI call. The qualitative behavior is the same, under both interpretations, unless a process is caught in an infinite compute loop, in which case the difference may not matter. However, the quantitative expectations are different. Different MPI implementations reflect these different interpretations. While this ambiguity is unfortunate, it does not seem to affect many real codes. The MPI forum decided not to decide which interpretation of the standard is the correct one, since the issue is very contentious, and a decision would have much impact on implementors but less impact on users. (*End of rationale.*)

### 11.7.3 Registers and Compiler Optimizations

*Advice to users.* All the material in this section is an advice to users. (*End of advice to users.*)

A coherence problem exists between variables kept in registers and the memory value of these variables. An RMA call may access a variable in memory (or cache), while the up-to-date value of this variable is in register. A get will not return the latest variable value, and a put may be overwritten when the register is stored back in memory.

The problem is illustrated by the following code:

Source of Process 1	Source of Process 2	Executed in Process 2
bbbb = 777	buff = 999	reg_A:=999
call MPI_WIN_FENCE	call MPI_WIN_FENCE	
call MPI_PUT(bbbb		stop appl.thread
into buff of process 2)		buff:=777 in PUT handler
		continue appl.thread
call MPI_WIN_FENCE	call MPI_WIN_FENCE	
	ccc = buff	ccc:=reg_A

In this example, variable `buff` is allocated in the register `reg_A` and therefore `ccc` will have the old value of `buff` and not the new value 777.

This problem, which also afflicts in some cases send/receive communication, is discussed more at length in Section 16.2.8.

MPI implementations will avoid this problem for standard conforming C programs. Many Fortran compilers will avoid this problem, without disabling compiler optimizations. However, in order to avoid register coherence problems in a completely portable manner, users should restrict their use of RMA windows to variables stored in **in modules or COMMON blocks**. To prevent problems with the argument copying and register optimization done by Fortran compilers, please note the hints in Sections 16.2.2-16.2.12, especially in Sections 16.2.4 and 16.2.5 on pages 547-550 about *problems due to data copying and sequence association with subscript triplets and vector subscripts*, and in Sections 16.2.8 to 16.2.11 on pages 551 to 561 about *optimization problems, code movements and register optimization*, and *temporary and permanent data movements*. Sections “Solutions” to “VOLATILE” on pages 555-558 discuss several solutions for the problem in this example.

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# Chapter 12

## External Interfaces

### 12.1 Introduction

This chapter begins with calls used to create **generalized requests**, which allow users to create new nonblocking operations with an interface similar to what is present in MPI. This can be used to layer new functionality on top of MPI. Next, Section 12.3 deals with setting the information found in `status`. **This functionality is** needed for generalized requests.

The chapter continues, in Section 12.4, with a discussion of how threads are to be handled in MPI. Although thread compliance is not required, the standard specifies how threads are to work if they are provided.

### 12.2 Generalized Requests

The goal of generalized requests is to allow users to define new nonblocking operations. Such an outstanding nonblocking operation is represented by a (generalized) request. A fundamental property of nonblocking operations is that progress toward the completion of this operation occurs asynchronously, i.e., concurrently with normal program execution. Typically, this requires execution of code concurrently with the execution of the user code, e.g., in a separate thread or in a signal handler. Operating systems provide a variety of mechanisms in support of concurrent execution. MPI does not attempt to standardize or replace these mechanisms: it is assumed programmers who wish to define new asynchronous operations will use the mechanisms provided by the underlying operating system. Thus, the calls in this section only provide a means for defining the effect of MPI calls such as `MPI_WAIT` or `MPI_CANCEL` when they apply to generalized requests, and for signaling to MPI the completion of a generalized operation.

*Rationale.* It is tempting to also define an MPI standard mechanism for achieving concurrent execution of user-defined nonblocking operations. However, it is very difficult to define such a mechanism without consideration of the specific mechanisms used in the operating system. The Forum feels that concurrency mechanisms are a proper part of the underlying operating system and should not be standardized by MPI; the MPI standard should only deal with the interaction of such mechanisms with MPI. (*End of rationale.*)

For a regular request, the operation associated with the request is performed by the MPI implementation, and the operation completes without intervention by the application.

For a generalized request, the operation associated with the request is performed by the application; therefore, the application must notify MPI when the operation completes. This is done by making a call to `MPI_GREQUEST_COMPLETE`. MPI maintains the “completion” status of generalized requests. Any other request state has to be maintained by the user.

A new generalized request is started with

`MPI_GREQUEST_START(query_fn, free_fn, cancel_fn, extra_state, request)`

IN	query_fn	callback function invoked when request status is queried (function)
IN	free_fn	callback function invoked when request is freed (function)
IN	cancel_fn	callback function invoked when request is cancelled (function)
IN	extra_state	extra state
OUT	request	generalized request (handle)

```
int MPI_Grequest_start(MPI_Grequest_query_function *query_fn,
                      MPI_Grequest_free_function *free_fn,
                      MPI_Grequest_cancel_function *cancel_fn, void *extra_state,
                      MPI_Request *request)
```

```
MPI_GREQUEST_START(QUERY_FN, FREE_FN, CANCEL_FN, EXTRA_STATE, REQUEST,
                  IERROR)
```

```
INTEGER REQUEST, IERROR
EXTERNAL QUERY_FN, FREE_FN, CANCEL_FN
INTEGER (KIND=MPI_ADDRESS_KIND) EXTRA_STATE
```

```
MPI_Grequest_start(query_fn, free_fn, cancel_fn, extra_state, request,
                  ierror)
```

```
PROCEDURE(MPI_Grequest_query_function) :: query_fn
PROCEDURE(MPI_Grequest_free_function) :: free_fn
PROCEDURE(MPI_Grequest_cancel_function) :: cancel_fn
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: extra_state
TYPE(MPI_Request), INTENT(OUT) :: request
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{static MPI::Grequest
```

```
    MPI::Grequest::Start(const MPI::Grequest::Query_function*
                        query_fn, const MPI::Grequest::Free_function* free_fn,
                        const MPI::Grequest::Cancel_function* cancel_fn,
                        void *extra_state) (binding deprecated, see Section 15.2) }
```

*Advice to users.* Note that a generalized request belongs, in C++, to the class `MPI::Grequest`, which is a derived class of `MPI::Request`. It is of the same type as regular requests, in C and Fortran. (*End of advice to users.*)

The call starts a generalized request and returns a handle to it in `request`.

The syntax and meaning of the callback functions are listed below. All callback functions are passed the `extra_state` argument that was associated with the request by the starting call `MPI_GREQUEST_START`; `extra_state` can be used to maintain user-defined state for the request.

In C, the query function is

```
typedef int MPI_Grequest_query_function(void *extra_state,
                                       MPI_Status *status);
```

in Fortran with the `mpi` module and `mpif.h`

```
SUBROUTINE GREQUEST_QUERY_FUNCTION(EXTRA_STATE, STATUS, IERROR)
  INTEGER STATUS(MPI_STATUS_SIZE), IERROR
  INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE
```

in Fortran with the `mpi_f08` module

```
ABSTRACT INTERFACE
  SUBROUTINE MPI_Grequest_query_function(extra_state, status, ierror)
    TYPE(MPI_Status) :: status
    INTEGER :: ierror
    INTEGER(KIND=MPI_ADDRESS_KIND) :: extra_state
```

and in C++

```
{typedef int MPI::Grequest::Query_function(void* extra_state,
      MPI::Status& status); (binding deprecated, see Section 15.2)}
```

The `query_fn` function computes the status that should be returned for the generalized request. The status also includes information about successful/unsuccessful cancellation of the request (result to be returned by `MPI_TEST_CANCELLED`).

The `query_fn` callback is invoked by the `MPI_{WAIT|TEST}{ANY|SOME|ALL}` call that completed the generalized request associated with this callback. The callback function is also invoked by calls to `MPI_REQUEST_GET_STATUS`, if the request is complete when the call occurs. In both cases, the callback is passed a reference to the corresponding status variable passed by the user to the MPI call; the status set by the callback function is returned by the MPI call. If the user provided `MPI_STATUS_IGNORE` or `MPI_STATUSES_IGNORE` to the MPI function that causes `query_fn` to be called or has omitted the status argument (with the `mpi_f08` Fortran module or C++), then MPI will pass a valid status object to `query_fn`, and this status will be ignored upon return of the callback function. Note that `query_fn` is invoked only after `MPI_GREQUEST_COMPLETE` is called on the request; it may be invoked several times for the same generalized request, e.g., if the user calls `MPI_REQUEST_GET_STATUS` several times for this request. Note also that a call to `MPI_{WAIT|TEST}{SOME|ALL}` may cause multiple invocations of `query_fn` callback functions, one for each generalized request that is completed by the MPI call. The order of these invocations is not specified by MPI.

In C, the free function is

```
typedef int MPI_Grequest_free_function(void *extra_state);
```

in Fortran with the `mpi` module and `mpif.h`

```
SUBROUTINE GREQUEST_FREE_FUNCTION(EXTRA_STATE, IERROR)
  INTEGER IERROR
  INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE
```

ticket230-B. 1 in Fortran with the `mpi_f08` module  
 ticket-248T. 2 **ABSTRACT INTERFACE**  
 3 **SUBROUTINE MPI\_Grequest\_free\_function(extra\_state, ierror)**  
 4 **INTEGER :: ierror**  
 5 **INTEGER(KIND=MPI\_ADDRESS\_KIND) :: extra\_state**  
 6  
 7 and in C++  
 8 **{typedef int MPI::Grequest::Free\_function(void\* extra\_state);** (*binding*  
 9 *deprecated, see Section 15.2*)  
 10  
 ticket0. 11 **The `free_fn` function** is invoked to clean up user-allocated resources when the generalized  
 ticket0. 12 request is freed.  
 13 **The `free_fn` callback** is invoked by the `MPI_{WAIT|TEST}_{ANY|SOME|ALL}` call that  
 14 completed the generalized request associated with this callback. `free_fn` is invoked after  
 15 the call to `query_fn` for the same request. However, if the MPI call completed multiple  
 16 generalized requests, the order in which `free_fn` callback functions are invoked is not specified  
 ticket0. 17 by MPI.  
 18 **The `free_fn` callback** is also invoked for generalized requests that are freed by a call  
 19 to `MPI_REQUEST_FREE` (no call to `WAIT_{WAIT|TEST}_{ANY|SOME|ALL}` will occur for  
 20 such a request). In this case, the callback function will be called either in the MPI call  
 21 `MPI_REQUEST_FREE(request)`, or in the MPI call `MPI_GREQUEST_COMPLETE(request)`,  
 22 whichever happens last, i.e., in this case the actual freeing code is executed as soon as both  
 23 calls `MPI_REQUEST_FREE` and `MPI_GREQUEST_COMPLETE` have occurred. The `request`  
 24 is not deallocated until after `free_fn` completes. Note that `free_fn` will be invoked only once  
 25 per request by a correct program.  
 26  
 27 *Advice to users.* Calling `MPI_REQUEST_FREE(request)` will cause the `request` handle  
 28 to be set to `MPI_REQUEST_NULL`. This handle to the generalized request is no longer  
 29 valid. However, user copies of this handle are valid until after `free_fn` completes since  
 30 MPI does not deallocate the object until then. Since `free_fn` is not called until after  
 31 `MPI_GREQUEST_COMPLETE`, the user copy of the handle can be used to make this  
 32 call. Users should note that MPI will deallocate the object after `free_fn` executes. At  
 33 this point, user copies of the `request` handle no longer point to a valid request. MPI will  
 34 not set user copies to `MPI_REQUEST_NULL` in this case, so it is up to the user to avoid  
 ticket0. 35 accessing this stale handle. This is a special case **in which** MPI defers deallocating the  
 36 object until a later time that is known by the user. (*End of advice to users.*)  
 37  
 38 In C, the cancel function is  
 39 **typedef int MPI\_Grequest\_cancel\_function(void \*extra\_state, int complete);**  
 40  
 ticket230-B. 41 in Fortran **with the `mpi` module and `mpif.h`**  
 42 **SUBROUTINE GREQUEST\_CANCEL\_FUNCTION(EXTRA\_STATE, COMPLETE, IERROR)**  
 43 **INTEGER IERROR**  
 44 **INTEGER(KIND=MPI\_ADDRESS\_KIND) EXTRA\_STATE**  
 45 **LOGICAL COMPLETE**  
 46  
 ticket230-B. 47 in Fortran with the `mpi_f08` module  
 ticket-248T. 48 **ABSTRACT INTERFACE**

```

SUBROUTINE MPI_Grequest_cancel_function(extra_state, complete, ierror)
  INTEGER :: ierror
  INTEGER(KIND=MPI_ADDRESS_KIND) :: extra_state
  LOGICAL complete

```

and in C++

```
{typedef int MPI::Grequest::Cancel_function(void* extra_state,
      bool complete); (binding deprecated, see Section 15.2)}
```

The `cancel_fn` function is invoked to start the cancelation of a generalized request. It is called by `MPI_CANCEL(request)`. MPI passes `complete=true` to the callback function if `MPI_GREQUEST_COMPLETE` was already called on the request, and `complete=false` otherwise.

All callback functions return an error code. The code is passed back and dealt with as appropriate for the error code by the MPI function that invoked the callback function. For example, if error codes are returned then the error code returned by the callback function will be returned by the MPI function that invoked the callback function. In the case of an MPI\_{WAIT|TEST}{ANY} call that invokes both query\_fn and free\_fn, the MPI call will return the error code returned by the last callback, namely free\_fn. If one or more of the requests in a call to MPI\_{WAIT|TEST}{SOME|ALL} failed, then the MPI call will return MPI\_ERR\_IN\_STATUS. In such a case, if the MPI call was passed an array of statuses, then MPI will return in each of the statuses that correspond to a completed generalized request the error code returned by the corresponding invocation of its free\_fn callback function. However, if the MPI function was passed MPI\_STATUSES\_IGNORE or the status argument was omitted, then the individual error codes returned by each callback functions will be lost.

*Advice to users.* `query_fn` must **not** set the error field of `status` since `query_fn` may be called by `MPI_WAIT` or `MPI_TEST`, in which case the error field of `status` should not change. The MPI library knows the “context” in which `query_fn` is invoked and can decide correctly when to put in the error field of `status` the returned error code. (*End of advice to users.*)

MPI\_GREQUEST\_COMPLETE(request)

INOUT	request	generalized request (handle)
-------	---------	------------------------------

```
int MPI_Grequest_complete(MPI_Request request)
```

```
MPI_GREQUEST_COMPLETE(REQUEST, IERROR)
    INTEGER REQUEST, IERROR
```

```
MPI_Grequest_complete(request, ierror)
    TYPE(MPI_Request), INTENT(IN) :: request
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Grequest::Complete() (binding deprecated, see Section 15.2) }
```

The call informs MPI that the operations represented by the generalized request `request` are complete (see definitions in Section 2.4). A call to `MPI_WAIT(request, status)` will

return and a call to `MPI_TEST(request, flag, status)` will return `flag=true` only after a call to `MPI_GREQUEST_COMPLETE` has declared that these operations are complete.

MPI imposes no restrictions on the code executed by the callback functions. However, new nonblocking operations should be defined so that the general semantic rules about MPI calls such as `MPI_TEST`, `MPI_REQUEST_FREE`, or `MPI_CANCEL` still hold. For example, all these calls are supposed to be local and nonblocking. Therefore, the callback functions `query_fn`, `free_fn`, or `cancel_fn` should invoke blocking MPI communication calls only if the context is such that these calls are guaranteed to return in finite time. Once `MPI_CANCEL` is invoked, the cancelled operation should complete in finite time, irrespective of the state of other processes (the operation has acquired “local” semantics). It should either succeed, or fail without side-effects. The user should guarantee these same properties for newly defined operations.

*Advice to implementors.* A call to `MPI_GREQUEST_COMPLETE` may unblock a blocked user process/thread. The MPI library should ensure that the blocked user computation will resume. (*End of advice to implementors.*)

### 12.2.1 Examples

**Example 12.1** This example shows the code for a user-defined reduce operation on an `int` using a binary tree: each non-root node receives two messages, sums them, and sends them up. We assume that no status is returned and that the operation cannot be cancelled.

```
typedef struct {
    MPI_Comm comm;
    int tag;
    int root;
    int valin;
    int *valout;
    MPI_Request request;
} ARGS;

int myreduce(MPI_Comm comm, int tag, int root,
             int valin, int *valout, MPI_Request *request)
{
    ARGS *args;
    pthread_t thread;

    /* start request */
    MPI_Grequest_start(query_fn, free_fn, cancel_fn, NULL, request);

    args = (ARGS*)malloc(sizeof(ARGS));
    args->comm = comm;
    args->tag = tag;
    args->root = root;
    args->valin = valin;
    args->valout = valout;
```

```

    args->request = *request;
1
2
    /* spawn thread to handle request */
3
    /* The availability of the pthread_create call is system dependent */
4
    pthread_create(&thread, NULL, reduce_thread, args);
5
6
    return MPI_SUCCESS;
7
}
8
9
/* thread code */
10
void* reduce_thread(void *ptr)
11
{
12
    int lchild, rchild, parent, lval, rval, val;
13
    MPI_Request req[2];
14
    ARGS *args;
15
16
    args = (ARGS*)ptr;
17
18
    /* compute left,right child and parent in tree; set
        to MPI_PROC_NULL if does not exist */
19
20
    /* code not shown */
21
    ...
22
23
    MPI_Irecv(&lval, 1, MPI_INT, lchild, args->tag, args->comm, &req[0]);
24
    MPI_Irecv(&rval, 1, MPI_INT, rchild, args->tag, args->comm, &req[1]);
25
    MPI_Waitall(2, req, MPI_STATUSES_IGNORE);
26
    val = lval + args->valin + rval;
27
    MPI_Send( &val, 1, MPI_INT, parent, args->tag, args->comm );
28
    if (parent == MPI_PROC_NULL) *(args->valout) = val;
29
    MPI_Grequest_complete((args->request));
30
    free(ptr);
31
    return(NULL);
32
}
33
34
int query_fn(void *extra_state, MPI_Status *status)
35
{
36
    /* always send just one int */
37
    MPI_Status_set_elements(status, MPI_INT, 1);
38
    /* can never cancel so always true */
39
    MPI_Status_set_cancelled(status, 0);
40
    /* choose not to return a value for this */
41
    status->MPI_SOURCE = MPI_UNDEFINED;
42
    /* tag has no meaning for this generalized request */
43
    status->MPI_TAG = MPI_UNDEFINED;
44
    /* this generalized request never fails */
45
    return MPI_SUCCESS;
46
}
47
48

```

```

1
2 int free_fn(void *extra_state)
3 {
4     /* this generalized request does not need to do any freeing */
5     /* as a result it never fails here */
6     return MPI_SUCCESS;
7 }
8
9
10 int cancel_fn(void *extra_state, int complete)
11 {
12     /* This generalized request does not support cancelling.
13        Abort if not already done. If done then treat as if cancel failed.*/
14     if (!complete) {
15         fprintf(stderr,
16             "Cannot cancel generalized request - aborting program\n");
17         MPI_Abort(MPI_COMM_WORLD, 99);
18     }
19     return MPI_SUCCESS;
20 }
21
22
23

```

### 12.3 Associating Information with Status

MPI supports several different types of requests besides those for point-to-point operations. These range from MPI calls for I/O to generalized requests. It is desirable to allow these calls to use the same request mechanism, which allows one to wait or test on different types of requests. However, `MPI_{TEST|WAIT}{ANY|SOME|ALL}` returns a status with information about the request. With the generalization of requests, one needs to define what information will be returned in the status object.

Each MPI call fills in the appropriate fields in the status object. Any unused fields will have undefined values. A call to `MPI_{TEST|WAIT}{ANY|SOME|ALL}` can modify any of the fields in the status object. Specifically, it can modify fields that are undefined. The fields with meaningful values for a given request are defined in the sections with the new request.

Generalized requests raise additional considerations. Here, the user provides the functions to deal with the request. Unlike other MPI calls, the user needs to provide the information to be returned in status. The status argument is provided directly to the callback function where the status needs to be set. Users can directly set the values in 3 of the 5 status values. The count and cancel fields are opaque. To overcome this, these calls are provided:



MPI\_STATUS\_SET\_ELEMENTS(status, datatype, count)

INOUT	status	status with which to associate count (Status)
IN	datatype	datatype associated with count (handle)
IN	count	number of elements to associate with status (integer)

```
int MPI_Status_set_elements(MPI_Status *status, MPI_Datatype datatype,
                           int count)
```

```
MPI_STATUS_SET_ELEMENTS(STATUS, DATATYPE, COUNT, IERROR)
    INTEGER STATUS(MPI_STATUS_SIZE), DATATYPE, COUNT, IERROR
```

```
MPI_Status_set_elements(status, datatype, count, ierror)
    TYPE(MPI_Status), INTENT(INOUT) :: status
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    INTEGER, INTENT(IN) :: count
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::Status::Set_elements(const MPI::Datatype& datatype, int
                               count) (binding deprecated, see Section 15.2) }
```

This call modifies the opaque part of status so that a call to MPI\_GET\_ELEMENTS will return count. MPI\_GET\_COUNT will return a compatible value.

*Rationale.* The number of elements is set instead of the count because the former can deal with a nonintegral number of datatypes. (*End of rationale.*)

A subsequent call to MPI\_GET\_COUNT(status, datatype, count) or to MPI\_GET\_ELEMENTS(status, datatype, count) must use a datatype argument that has the same type signature as the datatype argument that was used in the call to MPI\_STATUS\_SET\_ELEMENTS.

*Rationale.* The requirement of matching type signatures for these calls is similar to the restriction that holds when count is set by a receive operation: in that case, the calls to MPI\_GET\_COUNT and MPI\_GET\_ELEMENTS must use a datatype with the same signature as the datatype used in the receive call. (*End of rationale.*)

MPI\_STATUS\_SET\_CANCELLED(status, flag)

INOUT	status	status with which to associate cancel flag (Status)
IN	flag	if true indicates request was cancelled (logical)

```
int MPI_Status_set_cancelled(MPI_Status *status, int flag)
```

```
MPI_STATUS_SET_CANCELLED(STATUS, FLAG, IERROR)
    INTEGER STATUS(MPI_STATUS_SIZE), IERROR
    LOGICAL FLAG
```

```
MPI_Status_set_cancelled(status, flag, ierror)
```

```

1      TYPE(MPI_Status), INTENT(INOUT) :: status
2      LOGICAL, INTENT(OUT) :: flag
3      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
4
5      {void MPI::Status::Set_cancelled(bool flag) (binding deprecated, see Section 15.2)
6          }

```

If `flag` is set to `true` then a subsequent call to `MPI_TEST_CANCELLED(status, flag)` will also return `flag = true`, otherwise it will return `false`.

*Advice to users.* Users are advised not to reuse the status fields for values other than those for which they were intended. Doing so may lead to unexpected results when using the status object. For example, calling `MPI_GET_ELEMENTS` may cause an error if the value is out of range or it may be impossible to detect such an error. The `extra_state` argument provided with a generalized request can be used to return information that does not logically belong in status. Furthermore, modifying the values in a status set internally by MPI, e.g., `MPI_RECV`, may lead to unpredictable results and is strongly discouraged. (*End of advice to users.*)

## 12.4 MPI and Threads

This section specifies the interaction between MPI calls and threads. The section lists minimal requirements for **thread compliant** MPI implementations and defines functions that can be used for initializing the thread environment. MPI may be implemented in environments where threads are not supported or perform poorly. Therefore, it is not required that all MPI implementations fulfill all the requirements specified in this section.

This section generally assumes a thread package similar to POSIX threads [33], but the syntax and semantics of thread calls are not specified here — these are beyond the scope of this document.

### 12.4.1 General

In a thread-compliant implementation, an MPI process is a process that may be multi-threaded. Each thread can issue MPI calls; however, threads are not separately addressable: a rank in a send or receive call identifies a process, not a thread. A message sent to a process can be received by any thread in this process.

*Rationale.* This model corresponds to the POSIX model of interprocess communication: the fact that a process is multi-threaded, rather than single-threaded, does not affect the external interface of this process. MPI implementations in which MPI ‘processes’ are POSIX threads inside a single POSIX process are not thread-compliant by this definition (indeed, their “processes” are single-threaded). (*End of rationale.*)

*Advice to users.* It is the user’s responsibility to prevent races when threads within the same application post conflicting communication calls. The user can make sure that two threads in the same process will not issue conflicting communication calls by using distinct communicators at each thread. (*End of advice to users.*)

The two main requirements for a thread-compliant implementation are listed below.

1. All MPI calls are *thread-safe*, i.e., two concurrently running threads may make MPI calls and the outcome will be as if the calls executed in some order, even if their execution is interleaved.
2. Blocking MPI calls will block the calling thread only, allowing another thread to execute, if available. The calling thread will be blocked until the event on which it is waiting occurs. Once the blocked communication is enabled and can proceed, then the call will complete and the thread will be marked runnable, within a finite time. A blocked thread will not prevent progress of other runnable threads on the same process, and will not prevent them from executing MPI calls.

**Example 12.2** Process 0 consists of two threads. The first thread executes a blocking send call `MPI_Send(buff1, count, type, 0, 0, comm)`, whereas the second thread executes a blocking receive call `MPI_Recv(buff2, count, type, 0, 0, comm, &status)`, i.e., the first thread sends a message that is received by the second thread. This communication should always succeed. According to the first requirement, the execution will correspond to some interleaving of the two calls. According to the second requirement, a call can only block the calling thread and cannot prevent progress of the other thread. If the send call went ahead of the receive call, then the sending thread may block, but this will not prevent the receiving thread from executing. Thus, the receive call will occur. Once both calls occur, the communication is enabled and both calls will complete. On the other hand, a single-threaded process that posts a send, followed by a matching receive, may deadlock. The progress requirement for multithreaded implementations is stronger, as a blocked call cannot prevent progress in other threads.

*Advice to implementors.* MPI calls can be made thread-safe by executing only one at a time, e.g., by protecting MPI code with one process-global lock. However, blocked operations cannot hold the lock, as this would prevent progress of other threads in the process. The lock is held only for the duration of an atomic, locally-completing suboperation such as posting a send or completing a send, and is released in between. Finer locks can provide more concurrency, at the expense of higher locking overheads. Concurrency can also be achieved by having some of the MPI protocol executed by separate server threads. (*End of advice to implementors.*)

#### 12.4.2 Clarifications

**Initialization and Completion** The call to `MPI_FINALIZE` should occur on the same thread that initialized MPI. We call this thread the **main thread**. The call should occur only after all the process threads have completed their MPI calls, and have no pending communications or I/O operations.

*Rationale.* This constraint simplifies implementation. (*End of rationale.*)

**Multiple threads completing the same request.** A program where two threads block, waiting on the same request, is erroneous. Similarly, the same request cannot appear in the array of requests of two concurrent `MPI_{WAIT|TEST}{ANY|SOME|ALL}` calls. In MPI, a request can only be completed once. Any combination of wait or test **that** violates this rule is erroneous.

*Rationale.* This restriction is consistent with the view that a multithreaded execution corresponds to an interleaving of the MPI calls. In a single threaded implementation, once a wait is posted on a request the request handle will be nullified before it is possible to post a second wait on the same handle. With threads, an MPI\_WAIT{ANY|SOME|ALL} may be blocked without having nullified its request(s) so it becomes the user's responsibility to avoid using the same request in an MPI\_WAIT on another thread. This constraint also simplifies implementation, as only one thread will be blocked on any communication or I/O event. (*End of rationale.*)

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**Probe** A receive call that uses source and tag values returned by a preceding call to MPI\_PROBE or MPI\_IProbe will receive the message matched by the probe call only if there was no other matching receive after the probe and before that receive. In a multi-threaded environment, it is up to the user to enforce this condition using suitable mutual exclusion logic. This can be enforced by making sure that each communicator is used by only one thread on each process.

**Collective calls** Matching of collective calls on a communicator, window, or file handle is done according to the order in which the calls are issued at each process. If concurrent threads issue such calls on the same communicator, window or file handle, it is up to the user to make sure the calls are correctly ordered, using interthread synchronization.

*Advice to users.* With three concurrent threads in each MPI process of a communicator comm, it is allowed that thread A in each MPI process calls a collective operation on comm, thread B calls a file operation on an existing filehandle that was formerly opened on comm, and thread C invokes one-sided operations on an existing window handle that was also formerly created on comm. (*End of advice to users.*)

*Rationale.* As already specified in MPI\_FILE\_OPEN and MPI\_WIN\_CREATE, a file handle and a window handle inherit only the group of processes of the underlying communicator, but not the communicator itself. Accesses to communicators, window handles and file handles cannot affect one another. (*End of rationale.*)

ticket0. *Advice to implementors.* If the implementation of file or window operations internally uses MPI communication then a duplicated communicator may be cached on the file or window object. (*End of advice to implementors.*)

**Exception handlers** An exception handler does not necessarily execute in the context of the thread that made the exception-raising MPI call; the exception handler may be executed by a thread that is distinct from the thread that will return the error code.

*Rationale.* The MPI implementation may be multithreaded, so that part of the communication protocol may execute on a thread that is distinct from the thread that made the MPI call. The design allows the exception handler to be executed on the thread where the exception occurred. (*End of rationale.*)

**Interaction with signals and cancellations** The outcome is undefined if a thread that executes an MPI call is cancelled (by another thread), or if a thread catches a signal while executing an MPI call. However, a thread of an MPI process may terminate, and may catch signals or be cancelled by another thread when not executing MPI calls.

*Rationale.* Few C library functions are signal safe, and many have cancellation points — points **at which** the thread executing them may be cancelled. The above restriction simplifies implementation (no need for the MPI library to be “async-cancel-safe” or “async-signal-safe”). (*End of rationale.*)

*Advice to users.* Users can catch signals in separate, non-MPI threads (e.g., by masking signals on MPI calling threads, and unmasking them in one or more non-MPI threads). A good programming practice is to have a distinct thread blocked in a call to `sigwait` for each user expected signal that may occur. Users must not catch signals used by the MPI implementation; as each MPI implementation is required to document the signals used internally, users can avoid these signals. (*End of advice to users.*)

*Advice to implementors.* The MPI library should not invoke library calls that are not thread safe, if multiple threads execute. (*End of advice to implementors.*)

### 12.4.3 Initialization

The following function may be used to initialize MPI, and initialize the MPI thread environment, instead of `MPI_INIT`.

`MPI_INIT_THREAD(required, provided)`

IN	required	desired level of thread support (integer)
OUT	provided	provided level of thread support (integer)

```
int MPI_Init_thread(int *argc, char *((*argv)[]), int required,
                   int *provided)
```

```
MPI_INIT_THREAD(REQUIRED, PROVIDED, IERROR)
INTEGER REQUIRED, PROVIDED, IERROR
```

```
MPI_Init_thread(required, provided, ierror)
    INTEGER, INTENT(IN) :: required
    INTEGER, INTENT(OUT) :: provided
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{int MPI::Init_thread(int& argc, char**& argv, int required) (binding
    deprecated, see Section 15.2) }
```

```
{int MPI::Init_thread(int required) (binding deprecated, see Section 15.2) }
```

*Advice to users.* In C and C++, the passing of `argc` and `argv` is **optional**, as with `MPI_INIT` as discussed in Section 8.7. In C, **null pointers may be passed in their place**. In C++, **two separate bindings support this choice**. (*End of advice to users.*)

This call initializes MPI in the same way that a call to `MPI_INIT` would. In addition, it initializes the thread environment. The argument `required` is used to specify the desired level of thread support. The possible values are listed in increasing order of thread support.

**MPI\_THREAD\_SINGLE** Only one thread will execute.

**MPI\_THREAD\_FUNNELED** The process may be multi-threaded, but the application must ensure that only the main thread makes MPI calls (for the definition of main thread, see `MPI_IS_THREAD_MAIN` on page 443).

**MPI\_THREAD\_SERIALIZED** The process may be multi-threaded, and multiple threads may make MPI calls, but only one at a time: MPI calls are not made concurrently from two distinct threads (all MPI calls are “serialized”).

**MPI\_THREAD\_MULTIPLE** Multiple threads may call MPI, with no restrictions.

These values are monotonic; i.e., `MPI_THREAD_SINGLE` < `MPI_THREAD_FUNNELED` < `MPI_THREAD_SERIALIZED` < `MPI_THREAD_MULTIPLE`.

Different processes in `MPI_COMM_WORLD` may require different levels of thread support.

The call returns in `provided` information about the actual level of thread support that will be provided by MPI. It can be one of the four values listed above.

The level(s) of thread support that can be provided by `MPI_INIT_THREAD` will depend on the implementation, and may depend on information provided by the user before the program started to execute (e.g., with arguments to `mpiexec`). If possible, the call will return `provided = required`. Failing this, the call will return the least supported level such that `provided > required` (thus providing a stronger level of support than required by the user). Finally, if the user requirement cannot be satisfied, then the call will return in `provided` the highest supported level.

A **thread compliant** MPI implementation will be able to return `provided = MPI_THREAD_MULTIPLE`. Such an implementation may always return `provided = MPI_THREAD_MULTIPLE`, irrespective of the value of `required`. At the other extreme, an MPI library that is not thread compliant may always return `provided = MPI_THREAD_SINGLE`, irrespective of the value of `required`.

A call to `MPI_INIT` has the same effect as a call to `MPI_INIT_THREAD` with a `required = MPI_THREAD_SINGLE`.

Vendors may provide (implementation dependent) means to specify the level(s) of thread support available when the MPI program is started, e.g., with arguments to `mpiexec`. This will affect the outcome of calls to `MPI_INIT` and `MPI_INIT_THREAD`. Suppose, for example, that an MPI program has been started so that only `MPI_THREAD_MULTIPLE` is available. Then `MPI_INIT_THREAD` will return `provided = MPI_THREAD_MULTIPLE`, irrespective of the value of `required`; a call to `MPI_INIT` will also initialize the MPI thread support level to `MPI_THREAD_MULTIPLE`. Suppose, on the other hand, that an MPI program has been started so that all four levels of thread support are available. Then, a call to `MPI_INIT_THREAD` will return `provided = required`; on the other hand, a call to `MPI_INIT` will initialize the MPI thread support level to `MPI_THREAD_SINGLE`.

*Rationale.* Various optimizations are possible when MPI code is executed single-threaded, or is executed on multiple threads, but not concurrently: mutual exclusion code may be omitted. Furthermore, if only one thread executes, then the MPI library can use library functions that are not thread safe, without risking conflicts with user threads. Also, the model of one communication thread, multiple computation threads fits many applications well, e.g., if the process code is a sequential Fortran/C/C++

program with MPI calls that has been parallelized by a compiler for execution on an SMP node, in a cluster of SMPs, then the process computation is multi-threaded, but MPI calls will likely execute on a single thread.

The design accommodates a static specification of the thread support level, for environments that require static binding of libraries, and for compatibility for current multi-threaded MPI codes. (*End of rationale.*)

*Advice to implementors.* If `provided` is not `MPI_THREAD_SINGLE` then the MPI library should not invoke C/ C++/Fortran library calls that are not thread safe, e.g., in an environment where `malloc` is not thread safe, then `malloc` should not be used by the MPI library.

Some implementors may want to use different MPI libraries for different levels of thread support. They can do so using dynamic linking and selecting which library will be linked when `MPI_INIT_THREAD` is invoked. If this is not possible, then optimizations for lower levels of thread support will occur only when the level of thread support required is specified at link time. (*End of advice to implementors.*)

The following function can be used to query the current level of thread support.

MPI\_QUERY\_THREAD(provided)

OUT	provided	provided level of thread support (integer)
-----	----------	--

```
int MPI_Query_thread(int *provided)
```

```
MPI_QUERY_THREAD( PROVIDED, IERROR)
    INTEGER PROVIDED, IERROR
```

```
MPI_Query_thread(provided, ierror)
    INTEGER, INTENT(OUT) :: provided
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{int MPI::Query_thread() (binding deprecated, see Section 15.2) }
```

The call returns in `provided` the current level of thread **support**, which will be the value returned in `provided` by `MPI_INIT_THREAD`, if MPI was initialized by a call to `MPI_INIT_THREAD()`.

MPI\_IS\_THREAD\_MAIN(flag)

OUT	flag	true if calling thread is main thread, false otherwise (logical)
-----	------	--

```
int MPI_Is_thread_main(int *flag)
```

```
MPI_IS_THREAD_MAIN(FLAG, IERROR)
    LOGICAL FLAG
    INTEGER IERROR
```

```
MPI_Is_thread_main(flag, ierror)
```



```

1      LOGICAL, INTENT(OUT) :: flag
2      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
3
4      {bool MPI::Is_thread_main() (binding deprecated, see Section 15.2) }
```

This function can be called by a thread to **determine if** it is the main thread (the thread that called MPI\_INIT or MPI\_INIT\_THREAD).

All routines listed in this section must be supported by all MPI implementations.

*Rationale.* MPI libraries are required to provide these calls even if they do not support threads, so that portable code that contains invocations to these functions **can** link correctly. MPI\_INIT continues to be supported so as to provide compatibility with current MPI codes. (*End of rationale.*)

*Advice to users.* It is possible to spawn threads before MPI is initialized, but no MPI call other than MPI\_INITIALIZED should be executed by these threads, until MPI\_INIT\_THREAD is invoked by one thread (which, thereby, becomes the main thread). In particular, it is possible to enter the MPI execution with a multi-threaded process.

The level of thread support provided is a global property of the MPI process that can be specified only once, when MPI is initialized on that process (or before). Portable third party libraries have to be written so as to accommodate any provided level of thread support. Otherwise, their usage will be restricted to specific level(s) of thread support. If such a library can run only with specific level(s) of thread support, e.g., only with MPI\_THREAD\_MULTIPLE, then MPI\_QUERY\_THREAD can be used to check whether the user initialized MPI to the correct level of thread support and, if not, raise an exception. (*End of advice to users.*)



# Chapter 13

## I/O

### 13.1 Introduction

POSIX provides a model of a widely portable file system, but the portability and optimization needed for parallel I/O cannot be achieved with the POSIX interface.

The significant optimizations required for efficiency (e.g., grouping [42], collective buffering [6, 13, 43, 47, 54], and disk-directed I/O [38]) can only be implemented if the parallel I/O system provides a high-level interface supporting partitioning of file data among processes and a collective interface supporting complete transfers of global data structures between process memories and files. In addition, further efficiencies can be gained via support for asynchronous I/O, strided accesses, and control over physical file layout on storage devices (disks). The I/O environment described in this chapter provides these facilities.

Instead of defining I/O access modes to express the common patterns for accessing a shared file (broadcast, reduction, scatter, gather), we chose another approach in which data partitioning is expressed using derived datatypes. Compared to a limited set of predefined access patterns, this approach has the advantage of added flexibility and expressiveness.

#### 13.1.1 Definitions

**file** An MPI file is an ordered collection of typed data items. MPI supports random or sequential access to any integral set of these items. A file is opened collectively by a group of processes. All collective I/O calls on a file are collective over this group.

**displacement** A file *displacement* is an absolute byte position relative to the beginning of a file. The displacement defines the location where a *view* begins. Note that a “file displacement” is distinct from a “typemap displacement.”

**etype** An *etype* (*elementary* datatype) is the unit of data access and positioning. It can be any MPI predefined or derived datatype. Derived etypes can be constructed using any of the MPI datatype constructor routines, provided all resulting typemap displacements are non-negative and monotonically nondecreasing. Data access is performed in etype units, reading or writing whole data items of type etype. Offsets are expressed as a count of etypes; file pointers point to the beginning of etypes. Depending on context, the term “etype” is used to describe one of three aspects of an elementary datatype: a particular MPI type, a data item of that type, or the extent of that type.

**filetype** A *filetype* is the basis for partitioning a file among processes and defines a template for accessing the file. A filetype is either a single etype or a derived MPI datatype constructed from multiple instances of the same etype. In addition, the extent of any hole in the filetype must be a multiple of the etype's extent. The displacements in the typemap of the filetype are not required to be distinct, but they must be non-negative and monotonically nondecreasing.

**view** A *view* defines the current set of data visible and accessible from an open file as an ordered set of etypes. Each process has its own view of the file, defined by three quantities: a displacement, an etype, and a filetype. The pattern described by a filetype is repeated, beginning at the displacement, to define the view. The pattern of repetition is defined to be the same pattern that `MPI_TYPE_CONTIGUOUS` would produce if it were passed the filetype and an arbitrarily large count. Figure 13.1 shows how the tiling works; note that the filetype in this example must have explicit lower and upper bounds set in order for the initial and final holes to be repeated in the view. Views can be changed by the user during program execution. The default view is a linear byte stream (displacement is zero, etype and filetype equal to `MPI_BYTE`).

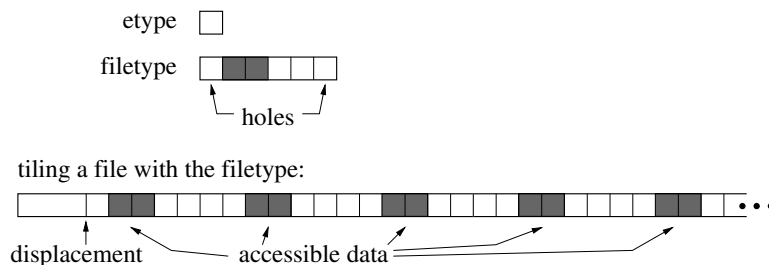


Figure 13.1: Etypes and filetypes

A group of processes can use complementary views to achieve a global data distribution such as a scatter/gather pattern (see Figure 13.2).

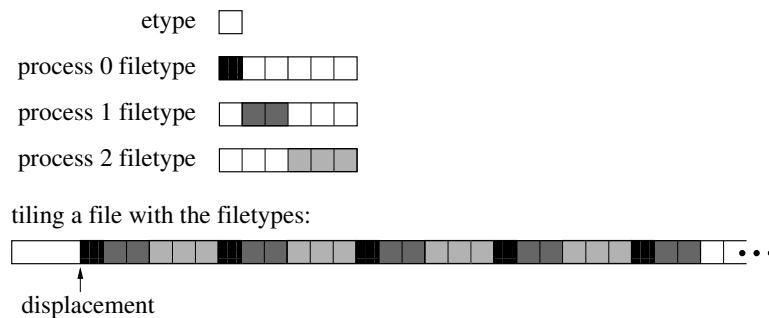


Figure 13.2: Partitioning a file among parallel processes

**offset** An *offset* is a position in the file relative to the current view, expressed as a count of etypes. Holes in the view's filetype are skipped when calculating this position. Offset 0 is the location of the first etype visible in the view (after skipping the displacement and any initial holes in the view). For example, an offset of 2 for process 1 in Figure 13.2 is the position of the 8th etype in the file after the displacement. An “explicit offset” is an offset that is used as a formal parameter in explicit data access routines.

**file size and end of file** The *size* of an MPI file is measured in bytes from the beginning of the file. A newly created file has a size of zero bytes. Using the size as an absolute displacement gives the position of the byte immediately following the last byte in the file. For any given view, the *end of file* is the offset of the first etype accessible in the current view starting after the last byte in the file.

**file pointer** A *file pointer* is an implicit offset maintained by MPI. “Individual file pointers” are file pointers that are local to each process that opened the file. A “shared file pointer” is a file pointer that is shared by the group of processes that opened the file.

**file handle** A *file handle* is an opaque object created by `MPI_FILE_OPEN` and freed by `MPI_FILE_CLOSE`. All operations on an open file reference the file through the file handle.

## 13.2 File Manipulation

### 13.2.1 Opening a File

`MPI_FILE_OPEN(comm, filename, amode, info, fh)`

IN	comm	communicator (handle)
IN	filename	name of file to open (string)
IN	amode	file access mode (integer)
IN	info	info object (handle)
OUT	fh	new file handle (handle)

```
int MPI_File_open(MPI_Comm comm, char *filename, int amode, MPI_Info info,
                  MPI_File *fh)
```

```
MPI_FILE_OPEN(COMM, FILENAME, AMODE, INFO, FH, IERROR)
CHARACTER*(*) FILENAME
INTEGER COMM, AMODE, INFO, FH, IERROR
```

```
MPI_File_open(comm, filename, amode, info, fh, ierror)
TYPE(MPI_Comm), INTENT(IN) :: comm
CHARACTER(LEN=*), INTENT(IN) :: filename
INTEGER, INTENT(IN) :: amode
TYPE(MPI_Info), INTENT(IN) :: info
TYPE(MPI_File), INTENT(OUT) :: fh
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{static MPI::File MPI::File::Open(const MPI::Intracomm& comm,
    const char* filename, int amode, const MPI::Info& info) (binding
    deprecated, see Section 15.2) }
```

`MPI_FILE_OPEN` opens the file identified by the file name `filename` on all processes in the `comm` communicator group. `MPI_FILE_OPEN` is a collective routine: all processes must provide the same value for `amode`, and all processes must provide filenames that reference

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the same file. (Values for `info` may vary.) `comm` must be an intracommunicator; it is erroneous to pass an intercommunicator to `MPI_FILE_OPEN`. Errors in `MPI_FILE_OPEN` are raised using the default file error handler (see Section 13.7, page 510). A process can open a file independently of other processes by using the `MPI_COMM_SELF` communicator. The file handle returned, `fh`, can be subsequently used to access the file until the file is closed using `MPI_FILE_CLOSE`. Before calling `MPI_FINALIZE`, the user is required to close (via `MPI_FILE_CLOSE`) all files that were opened with `MPI_FILE_OPEN`. Note that the communicator `comm` is unaffected by `MPI_FILE_OPEN` and continues to be usable in all MPI routines (e.g., `MPI_SEND`). Furthermore, the use of `comm` will not interfere with I/O behavior.

The format for specifying the file name in the `filename` argument is implementation dependent and must be documented by the implementation.

*Advice to implementors.* An implementation may require that `filename` include a string or strings specifying additional information about the file. Examples include the type of filesystem (e.g., a prefix of `ufs:`), a remote hostname (e.g., a prefix of `machine.univ.edu:`), or a file password (e.g., a suffix of `/PASSWORD=SECRET`). (*End of advice to implementors.*)

*Advice to users.* On some implementations of MPI, the file namespace may not be identical from all processes of all applications. For example, `"/tmp/foo"` may denote different files on different processes, or a single file may have many names, dependent on process location. The user is responsible for ensuring that a single file is referenced by the `filename` argument, as it may be impossible for an implementation to detect this type of namespace error. (*End of advice to users.*)

Initially, all processes view the file as a linear byte stream, and each process views data in its own native representation (no data representation conversion is performed). (POSIX files are linear byte streams in the native representation.) The file view can be changed via the `MPI_FILE_SET_VIEW` routine.

The following access modes are supported (specified in `amode`, a bit vector OR of the following integer constants):

- `MPI_MODE_RDONLY` — read only,
- `MPI_MODE_RDWR` — reading and writing,
- `MPI_MODE_WRONLY` — write only,
- `MPI_MODE_CREATE` — create the file if it does not exist,
- `MPI_MODE_EXCL` — error if creating file that already exists,
- `MPI_MODE_DELETE_ON_CLOSE` — delete file on close,
- `MPI_MODE_UNIQUE_OPEN` — file will not be concurrently opened elsewhere,
- `MPI_MODE_SEQUENTIAL` — file will only be accessed sequentially,
- `MPI_MODE_APPEND` — set initial position of all file pointers to end of file.

*Advice to users.* C/C++ users can use bit vector OR (|) to combine these constants; Fortran 90 users can use the bit vector IOR intrinsic. Fortran 77 users can use (non-portably) bit vector IOR on systems that support it. Alternatively, Fortran users can portably use integer addition to OR the constants (each constant should appear at most once in the addition.). (*End of advice to users.*)

*Advice to implementors.* The values of these constants must be defined such that the bitwise OR and the sum of any distinct set of these constants is equivalent. (*End of advice to implementors.*)

The modes MPI\_MODE\_RDONLY, MPI\_MODE\_RDWR, MPI\_MODE\_WRONLY, MPI\_MODE\_CREATE, and MPI\_MODE\_EXCL have identical semantics to their POSIX counterparts [33]. Exactly one of MPI\_MODE\_RDONLY, MPI\_MODE\_RDWR, or MPI\_MODE\_WRONLY, must be specified. It is erroneous to specify MPI\_MODE\_CREATE or MPI\_MODE\_EXCL in conjunction with MPI\_MODE\_RDONLY; it is erroneous to specify MPI\_MODE\_SEQUENTIAL together with MPI\_MODE\_RDWR.

The MPI\_MODE\_DELETE\_ON\_CLOSE mode causes the file to be deleted (equivalent to performing an MPI\_FILE\_DELETE) when the file is closed.

The MPI\_MODE\_UNIQUE\_OPEN mode allows an implementation to optimize access by eliminating the overhead of file locking. It is erroneous to open a file in this mode unless the file will not be concurrently opened elsewhere.

*Advice to users.* For MPI\_MODE\_UNIQUE\_OPEN, *not opened elsewhere* includes both inside and outside the MPI environment. In particular, one needs to be aware of potential external events which may open files (e.g., automated backup facilities). When MPI\_MODE\_UNIQUE\_OPEN is specified, the user is responsible for ensuring that no such external events take place. (*End of advice to users.*)

The MPI\_MODE\_SEQUENTIAL mode allows an implementation to optimize access to some sequential devices (tapes and network streams). It is erroneous to attempt nonsequential access to a file that has been opened in this mode.

Specifying MPI\_MODE\_APPEND only guarantees that all shared and individual file pointers are positioned at the initial end of file when MPI\_FILE\_OPEN returns. Subsequent positioning of file pointers is application dependent. In particular, the implementation does not ensure that all writes are appended.

Errors related to the access mode are raised in the class MPI\_ERR\_AMODE.

The info argument is used to provide information regarding file access patterns and file system specifics (see Section 13.2.8, page 455). The constant MPI\_INFO\_NULL can be used when no info needs to be specified.

*Advice to users.* Some file attributes are inherently implementation dependent (e.g., file permissions). These attributes must be set using either the info argument or facilities outside the scope of MPI. (*End of advice to users.*)

Files are opened by default using nonatomic mode file consistency semantics (see Section 13.6.1, page 500). The more stringent atomic mode consistency semantics, required for atomicity of conflicting accesses, can be set using MPI\_FILE\_SET\_ATOMICITY.

### 13.2.2 Closing a File

#### MPI\_FILE\_CLOSE(fh)

INOUT fh file handle (handle)

```
int MPI_File_close(MPI_File *fh)
```

```
MPI_FILE_CLOSE(FH, IERROR)
```

```
INTEGER FH, IERROR
```

```
MPI_File_close(fh, ierror)
```

```
TYPE(MPI_File), INTENT(INOUT) :: fh
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::File::Close() (binding deprecated, see Section 15.2) }
```

MPI\_FILE\_CLOSE first synchronizes file state (equivalent to performing an MPI\_FILE\_SYNC), then closes the file associated with fh. The file is deleted if it was opened with access mode MPI\_MODE\_DELETE\_ON\_CLOSE (equivalent to performing an MPI\_FILE\_DELETE). MPI\_FILE\_CLOSE is a collective routine.

*Advice to users.* If the file is deleted on close, and there are other processes currently accessing the file, the status of the file and the behavior of future accesses by these processes are implementation dependent. (*End of advice to users.*)

The user is responsible for ensuring that all outstanding nonblocking requests and split collective operations associated with fh made by a process have completed before that process calls MPI\_FILE\_CLOSE.

The MPI\_FILE\_CLOSE routine deallocates the file handle object and sets fh to MPI\_FILE\_NULL.

### 13.2.3 Deleting a File

#### MPI\_FILE\_DELETE(filename, info)

IN filename name of file to delete (string)

IN info info object (handle)

```
int MPI_File_delete(char *filename, MPI_Info info)
```

```
MPI_FILE_DELETE(FILENAME, INFO, IERROR)
```

```
CHARACTER*(*) FILENAME
```

```
INTEGER INFO, IERROR
```

```
MPI_File_delete(filename, info, ierror)
```

```
CHARACTER(LEN=*), INTENT(IN) :: filename
```

```
TYPE(MPI_Info), INTENT(IN) :: info
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{static void MPI::File::Delete(const char* filename,
                               const MPI::Info& info) (binding deprecated, see Section 15.2) }
```

MPI\_FILE\_DELETE deletes the file identified by the file name `filename`. If the file does not exist, MPI\_FILE\_DELETE raises an error in the class MPI\_ERR\_NO\_SUCH\_FILE.

The `info` argument can be used to provide information regarding file system specifics (see Section 13.2.8, page 455). The constant MPI\_INFO\_NULL refers to the null info, and can be used when no info needs to be specified.

If a process currently has the file open, the behavior of any access to the file (as well as the behavior of any outstanding accesses) is implementation dependent. In addition, whether an open file is deleted or not is also implementation dependent. If the file is not deleted, an error in the class MPI\_ERR\_FILE\_IN\_USE or MPI\_ERR\_ACCESS will be raised. Errors are raised using the default error handler (see Section 13.7, page 510).

### 13.2.4 Resizing a File

MPI\_FILE\_SET\_SIZE(fh, size)

INOUT	fh	file handle (handle)
IN	size	size to truncate or expand file (integer)

```
int MPI_File_set_size(MPI_File fh, MPI_Offset size)
```

```
MPI_FILE_SET_SIZE(FH, SIZE, IERROR)
    INTEGER FH, IERROR
    INTEGER(KIND=MPI_OFFSET_KIND) SIZE
```

```
MPI_File_set_size(fh, size, ierror)
    TYPE(MPI_File), INTENT(IN) :: fh
    INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: size
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::File::Set_size(MPI::Offset size) (binding deprecated, see Section 15.2)
}
```

MPI\_FILE\_SET\_SIZE resizes the file associated with the file handle `fh`. `size` is measured in bytes from the beginning of the file. MPI\_FILE\_SET\_SIZE is collective; all processes in the group must pass identical values for `size`.

If `size` is smaller than the current file size, the file is truncated at the position defined by `size`. The implementation is free to deallocate file blocks located beyond this position.

If `size` is larger than the current file size, the file size becomes `size`. Regions of the file that have been previously written are unaffected. The values of data in the new regions in the file (those locations with displacements between old file size and `size`) are undefined. It is implementation dependent whether the MPI\_FILE\_SET\_SIZE routine allocates file space—use MPI\_FILE\_PREALLOCATE to force file space to be reserved.

MPI\_FILE\_SET\_SIZE does not affect the individual file pointers or the shared file pointer. If MPI\_MODE\_SEQUENTIAL mode was specified when the file was opened, it is erroneous to call this routine.

*Advice to users.* It is possible for the file pointers to point beyond the end of file after a `MPI_FILE_SET_SIZE` operation truncates a file. This is legal, and equivalent to seeking beyond the current end of file. (*End of advice to users.*)

All nonblocking requests and split collective operations on `fh` must be completed before calling `MPI_FILE_SET_SIZE`. Otherwise, calling `MPI_FILE_SET_SIZE` is erroneous. As far as consistency semantics are concerned, `MPI_FILE_SET_SIZE` is a write operation that conflicts with operations that access bytes at displacements between the old and new file sizes (see Section 13.6.1, page 500).

### 13.2.5 Preallocating Space for a File

`MPI_FILE_PREALLOCATE(fh, size)`

INOUT	<code>fh</code>	file handle (handle)
IN	<code>size</code>	size to preallocate file (integer)

`int MPI_File_preallocate(MPI_File fh, MPI_Offset size)`

`MPI_FILE_PREALLOCATE(FH, SIZE, IERROR)`

`INTEGER FH, IERROR`

`INTEGER(KIND=MPI_OFFSET_KIND) SIZE`

`MPI_File_preallocate(fh, size, ierror)`

`TYPE(MPI_File), INTENT(IN) :: fh`

`INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: size`

`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{void MPI::File::Preallocate(MPI::Offset size) (binding deprecated, see Section 15.2) }`

`MPI_FILE_PREALLOCATE` ensures that storage space is allocated for the first `size` bytes of the file associated with `fh`. `MPI_FILE_PREALLOCATE` is collective; all processes in the group must pass identical values for `size`. Regions of the file that have previously been written are unaffected. For newly allocated regions of the file, `MPI_FILE_PREALLOCATE` has the same effect as writing undefined data. If `size` is larger than the current file size, the file size increases to `size`. If `size` is less than or equal to the current file size, the file size is unchanged.

The treatment of file pointers, pending nonblocking accesses, and file consistency is the same as with `MPI_FILE_SET_SIZE`. If `MPI_MODE_SEQUENTIAL` mode was specified when the file was opened, it is erroneous to call this routine.

*Advice to users.* In some implementations, file preallocation may be expensive. (*End of advice to users.*)



## 13.2.6 Querying the Size of a File

`MPI_FILE_GET_SIZE(fh, size)`

IN	fh	file handle (handle)
OUT	size	size of the file in bytes (integer)

`int MPI_File_get_size(MPI_File fh, MPI_Offset *size)`

`MPI_FILE_GET_SIZE(FH, SIZE, IERROR)`  
`INTEGER FH, IERROR`  
`INTEGER(KIND=MPI_OFFSET_KIND) SIZE`

`MPI_File_get_size(fh, size, ierror)`  
`TYPE(MPI_File), INTENT(IN) :: fh`  
`INTEGER(KIND=MPI_OFFSET_KIND), INTENT(OUT) :: size`  
`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{MPI::Offset MPI::File::Get_size() const}` (*binding deprecated, see Section 15.2*)

`MPI_FILE_GET_SIZE` returns, in `size`, the current size in bytes of the file associated with the file handle `fh`. As far as consistency semantics are concerned, `MPI_FILE_GET_SIZE` is a data access operation (see Section 13.6.1, page 500).

## 13.2.7 Querying File Parameters

`MPI_FILE_GET_GROUP(fh, group)`

IN	fh	file handle (handle)
OUT	group	group which opened the file (handle)

`int MPI_File_get_group(MPI_File fh, MPI_Group *group)`

`MPI_FILE_GET_GROUP(FH, GROUP, IERROR)`  
`INTEGER FH, GROUP, IERROR`

`MPI_File_get_group(fh, group, ierror)`  
`TYPE(MPI_File), INTENT(IN) :: fh`  
`TYPE(MPI_Group), INTENT(OUT) :: group`  
`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{MPI::Group MPI::File::Get_group() const}` (*binding deprecated, see Section 15.2*)

`MPI_FILE_GET_GROUP` returns a duplicate of the group of the communicator used to open the file associated with `fh`. The group is returned in `group`. The user is responsible for freeing `group`.

1 MPI\_FILE\_GET\_AMODE(fh, amode)

2     IN         fh                             file handle (handle)

3     OUT        amode                        file access mode used to open the file (integer)

4     5  
6 int MPI\_File\_get\_amode(MPI\_File fh, int \*amode)

7 MPI\_FILE\_GET\_AMODE(FH, AMODE, IERROR)

8     INTEGER FH, AMODE, IERROR

9     10 MPI\_File\_get\_amode(fh, amode, ierror)

11     TYPE(MPI\_File), INTENT(IN) :: fh

12     INTEGER, INTENT(OUT) :: amode

13     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

14     15 {int MPI::File::Get\_amode() const(*binding deprecated, see Section 15.2*) }

16     MPI\_FILE\_GET\_AMODE returns, in amode, the access mode of the file associated with  
17 fh.

18  
19 **Example 13.1** In Fortran 77, decoding an amode bit vector will require a routine such as  
20 the following:

21     22         SUBROUTINE BIT\_QUERY(TEST\_BIT, MAX\_BIT, AMODE, BIT\_FOUND)

23     !

24     ! TEST IF THE INPUT TEST\_BIT IS SET IN THE INPUT AMODE

25     ! IF SET, RETURN 1 IN BIT\_FOUND, 0 OTHERWISE

26     !

27         INTEGER TEST\_BIT, AMODE, BIT\_FOUND, CP\_AMODE, HIFOUND

28         BIT\_FOUND = 0

29         CP\_AMODE = AMODE

30     100 CONTINUE

31         LBIT = 0

32         HIFOUND = 0

33         DO 20 L = MAX\_BIT, 0, -1

34             MATCHER = 2\*\*L

35             IF (CP\_AMODE .GE. MATCHER .AND. HIFOUND .EQ. 0) THEN

36                 HIFOUND = 1

37                 LBIT = MATCHER

38                 CP\_AMODE = CP\_AMODE - MATCHER

39             END IF

40     20 CONTINUE

41         IF (HIFOUND .EQ. 1 .AND. LBIT .EQ. TEST\_BIT) BIT\_FOUND = 1

42         IF (BIT\_FOUND .EQ. 0 .AND. HIFOUND .EQ. 1 .AND. &

43             CP\_AMODE .GT. 0) GO TO 100

44     END

45  
46     This routine could be called successively to decode amode, one bit at a time. For  
47 example, the following code fragment would check for MPI\_MODE\_RDONLY.

```

CALL BIT_QUERY(MPI_MODE_RDONLY, 30, AMODE, BIT_FOUND)
IF (BIT_FOUND .EQ. 1) THEN
    PRINT *, ' FOUND READ-ONLY BIT IN AMODE=', AMODE
ELSE
    PRINT *, ' READ-ONLY BIT NOT FOUND IN AMODE=', AMODE
END IF

```

### 13.2.8 File Info

Hints specified via info (see Section 9, page 351) allow a user to provide information such as file access patterns and file system specifics to direct optimization. Providing hints may enable an implementation to deliver increased I/O performance or minimize the use of system resources. However, hints do not change the semantics of any of the I/O interfaces. In other words, an implementation is free to ignore all hints. Hints are specified on a per file basis, in `MPI_FILE_OPEN`, `MPI_FILE_DELETE`, `MPI_FILE_SET_VIEW`, and `MPI_FILE_SET_INFO`, via the opaque info object. When an info object that specifies a subset of valid hints is passed to `MPI_FILE_SET_VIEW` or `MPI_FILE_SET_INFO`, there will be no effect on previously set or defaulted hints that the info does not specify.

*Advice to implementors.* It may happen that a program is coded with hints for one system, and later executes on another system that does not support these hints. In general, unsupported hints should simply be ignored. Needless to say, no hint can be mandatory. However, for each hint used by a specific implementation, a default value must be provided when the user does not specify a value for this hint. (*End of advice to implementors.*)

`MPI_FILE_SET_INFO(fh, info)`

INOUT	fh	file handle (handle)
IN	info	info object (handle)

`int MPI_File_set_info(MPI_File fh, MPI_Info info)`

`MPI_FILE_SET_INFO(FH, INFO, IERROR)`

`INTEGER FH, INFO, IERROR`

`MPI_File_set_info(fh, info, ierror)`

`TYPE(MPI_File), INTENT(IN) :: fh`

`TYPE(MPI_Info), INTENT(IN) :: info`

`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{void MPI::File::Set_info(const MPI::Info& info) (binding deprecated, see Section 15.2) }`

`MPI_FILE_SET_INFO` sets new values for the hints of the file associated with `fh`. `MPI_FILE_SET_INFO` is a collective routine. The info object may be different on each process, but any info entries that an implementation requires to be the same on all processes must appear with the same value in each process's info object.

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*Advice to users.* Many info items that an implementation can use when it creates or opens a file cannot easily be changed once the file has been created or opened. Thus, an implementation may ignore hints issued in this call that it would have accepted in an open call. (*End of advice to users.*)

`MPI_FILE_GET_INFO(fh, info_used)`

IN	fh	file handle (handle)
OUT	info_used	new info object (handle)

`int MPI_File_get_info(MPI_File fh, MPI_Info *info_used)`

`MPI_FILE_GET_INFO(FH, INFO_USED, IERROR)`

`INTEGER FH, INFO_USED, IERROR`

`MPI_File_get_info(fh, info_used, ierror)`

`TYPE(MPI_File), INTENT(IN) :: fh`

`TYPE(MPI_Info), INTENT(OUT) :: info_used`

`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{MPI::Info MPI::File::Get_info() const(binding deprecated, see Section 15.2)}`

`MPI_FILE_GET_INFO` returns a new info object containing the hints of the file associated with `fh`. The current setting of all hints actually used by the system related to this open file is returned in `info_used`. If no such hints exist, a handle to a newly created info object is returned that contains no key/value pair. The user is responsible for freeing `info_used` via `MPI_INFO_FREE`.

*Advice to users.* The info object returned in `info_used` will contain all hints currently active for this file. This set of hints may be greater or smaller than the set of hints passed in to `MPI_FILE_OPEN`, `MPI_FILE_SET_VIEW`, and `MPI_FILE_SET_INFO`, as the system may not recognize some hints set by the user, and may recognize other hints that the user has not set. (*End of advice to users.*)

## Reserved File Hints

Some potentially useful hints (info key values) are outlined below. The following key values are reserved. An implementation is not required to interpret these key values, but if it does interpret the key value, it must provide the functionality described. (For more details on “info,” see Section 9, page 351.)

These hints mainly affect access patterns and the layout of data on parallel I/O devices. For each hint name introduced, we describe the purpose of the hint, and the type of the hint value. The “[**SAME**]” annotation specifies that the hint values provided by all participating processes must be identical; otherwise the program is erroneous. In addition, some hints are context dependent, and are only used by an implementation at specific times (e.g., `file_perm` is only useful during file creation).

**access\_style (comma separated list of strings):** This hint specifies the manner in which the file will be accessed until the file is closed or until the `access_style` key value is

altered. The hint value is a comma separated list of the following: `read_once`, `write_once`, `read_mostly`, `write_mostly`, `sequential`, `reverse_sequential`, and `random`.

**collective\_buffering (boolean) [SAME]:** This hint specifies whether the application may benefit from collective buffering. Collective buffering is an optimization performed on collective accesses. Accesses to the file are performed on behalf of all processes in the group by a number of target nodes. These target nodes coalesce small requests into large disk accesses. Legal values for this key are `true` and `false`. Collective buffering parameters are further directed via additional hints: `cb_block_size`, `cb_buffer_size`, and `cb_nodes`.

**cb\_block\_size (integer) [SAME]:** This hint specifies the block size to be used for collective buffering file access. *Target nodes* access data in chunks of this size. The chunks are distributed among target nodes in a round-robin (CYCLIC) pattern.

**cb\_buffer\_size (integer) [SAME]:** This hint specifies the total buffer space that can be used for collective buffering on each target node, usually a multiple of `cb_block_size`.

**cb\_nodes (integer) [SAME]:** This hint specifies the number of target nodes to be used for collective buffering.

**chunked (comma separated list of integers) [SAME]:** This hint specifies that the file consists of a multidimensional array that is often accessed by subarrays. The value for this hint is a comma separated list of array dimensions, starting from the most significant one (for an array stored in row-major order, as in C, the most significant dimension is the first one; for an array stored in column-major order, as in Fortran, the most significant dimension is the last one, and array dimensions should be reversed).

**chunked\_item (comma separated list of integers) [SAME]:** This hint specifies the size of each array entry, in bytes.

**chunked\_size (comma separated list of integers) [SAME]:** This hint specifies the dimensions of the subarrays. This is a comma separated list of array dimensions, starting from the most significant one.

**filename (string):** This hint specifies the file name used when the file was opened. If the implementation is capable of returning the file name of an open file, it will be returned using this key by `MPI_FILE_GET_INFO`. This key is ignored when passed to `MPI_FILE_OPEN`, `MPI_FILE_SET_VIEW`, `MPI_FILE_SET_INFO`, and `MPI_FILE_DELETE`.

**file\_perm (string) [SAME]:** This hint specifies the file permissions to use for file creation. Setting this hint is only useful when passed to `MPI_FILE_OPEN` with an `amode` that includes `MPI_MODE_CREATE`. The set of legal values for this key is implementation dependent.

**io\_node\_list (comma separated list of strings) [SAME]:** This hint specifies the list of I/O devices that should be used to store the file. This hint is most relevant when the file is created.

**nb\_proc (integer) [SAME]:** This hint specifies the number of parallel processes that will typically be assigned to run programs that access this file. This hint is most relevant when the file is created.

**num\_io\_nodes (integer) [SAME]:** This hint specifies the number of I/O devices in the system. This hint is most relevant when the file is created.

**striping\_factor (integer) [SAME]:** This hint specifies the number of I/O devices that the file should be striped across, and is relevant only when the file is created.

**striping\_unit (integer) [SAME]:** This hint specifies the suggested striping unit to be used for this file. The striping unit is the amount of consecutive data assigned to one I/O device before progressing to the next device, when striping across a number of devices. It is expressed in bytes. This hint is relevant only when the file is created.

### 13.3 File Views

**MPI\_FILE\_SET\_VIEW(fh, disp, etype, filetype, datarep, info)**

INOUT	fh	file handle (handle)
IN	disp	displacement (integer)
IN	etype	elementary datatype (handle)
IN	filetype	filetype (handle)
IN	datarep	data representation (string)
IN	info	info object (handle)

**int MPI\_File\_set\_view(MPI\_File fh, MPI\_Offset disp, MPI\_Datatype etype, MPI\_Datatype filetype, char \*datarep, MPI\_Info info)**

**MPI\_FILE\_SET\_VIEW(FH, DISP, ETYPE, FILETYPE, DATAREP, INFO, IERROR)**

INTEGER FH, ETYPE, FILETYPE, INFO, IERROR  
 CHARACTER\*(\*) DATAREP  
 INTEGER(KIND=MPI\_OFFSET\_KIND) DISP

**MPI\_File\_set\_view(fh, disp, etype, filetype, datarep, info, ierror)**

TYPE(MPI\_File), INTENT(IN) :: fh  
 INTEGER(KIND=MPI\_OFFSET\_KIND), INTENT(IN) :: disp  
 TYPE(MPI\_Datatype), INTENT(IN) :: etype  
 TYPE(MPI\_Datatype), INTENT(IN) :: filetype  
 CHARACTER(LEN=\*), INTENT(IN) :: datarep  
 TYPE(MPI\_Info), INTENT(IN) :: info  
 INTEGER, OPTIONAL, INTENT(OUT) :: ierror

**{void MPI::File::Set\_view(MPI::Offset disp, const MPI::Datatype& etype, const MPI::Datatype& filetype, const char\* datarep, const MPI::Info& info) (binding deprecated, see Section 15.2) }**

The **MPI\_FILE\_SET\_VIEW** routine changes the process's view of the data in the file. The start of the view is set to **disp**; the type of data is set to **etype**; the distribution of data to processes is set to **filetype**; and the representation of data in the file is set to **datarep**. In addition, **MPI\_FILE\_SET\_VIEW** resets the individual file pointers and the shared file

pointer to zero. `MPI_FILE_SET_VIEW` is collective; the values for `datarep` and the extents of `etype` in the file data representation must be identical on all processes in the group; values for `disp`, `filetype`, and `info` may vary. The datatypes passed in `etype` and `filetype` must be committed.

The `etype` always specifies the data layout in the file. If `etype` is a portable datatype (see Section 2.4, page 11), the extent of `etype` is computed by scaling any displacements in the datatype to match the file data representation. If `etype` is not a portable datatype, no scaling is done when computing the extent of `etype`. The user must be careful when using nonportable `etypes` in heterogeneous environments; see Section 13.5.1, page 492 for further details.

If `MPI_MODE_SEQUENTIAL` mode was specified when the file was opened, the special displacement `MPI_DISPLACEMENT_CURRENT` must be passed in `disp`. This sets the displacement to the current position of the shared file pointer. `MPI_DISPLACEMENT_CURRENT` is invalid unless the amode for the file has `MPI_MODE_SEQUENTIAL` set.

*Rationale.* For some sequential files, such as those corresponding to magnetic tapes or streaming network connections, the *displacement* may not be meaningful. `MPI_DISPLACEMENT_CURRENT` allows the view to be changed for these types of files. (*End of rationale.*)

*Advice to implementors.* It is expected that a call to `MPI_FILE_SET_VIEW` will immediately follow `MPI_FILE_OPEN` in numerous instances. A high-quality implementation will ensure that this behavior is efficient. (*End of advice to implementors.*)

The `disp` displacement argument specifies the position (absolute offset in bytes from the beginning of the file) where the view begins.

*Advice to users.* `disp` can be used to skip headers or when the file includes a sequence of data segments that are to be accessed in different patterns (see Figure 13.3). Separate views, each using a different displacement and `filetype`, can be used to access each segment.

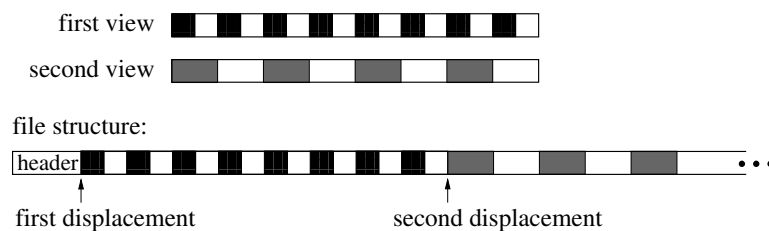


Figure 13.3: Displacements

(*End of advice to users.*)

An *etype* (*elementary* datatype) is the unit of data access and positioning. It can be any MPI predefined or derived datatype. Derived `etypes` can be constructed by using any of the MPI datatype constructor routines, provided all resulting typemap displacements are non-negative and monotonically nondecreasing. Data access is performed in `etype` units, reading or writing whole data items of type `etype`. Offsets are expressed as a count of `etypes`; file pointers point to the beginning of `etypes`.

*Advice to users.* In order to ensure interoperability in a heterogeneous environment, additional restrictions must be observed when constructing the **etype** (see Section 13.5, page 490). (*End of advice to users.*)

A filetype is either a single etype or a derived MPI datatype constructed from multiple instances of the same etype. In addition, the extent of any hole in the filetype must be a multiple of the etype’s extent. These displacements are not required to be distinct, but they cannot be negative, and they must be monotonically nondecreasing.

If the file is opened for writing, neither the **etype** nor the **filetype** is permitted to contain overlapping regions. This restriction is equivalent to the “datatype used in a receive cannot specify overlapping regions” restriction for communication. Note that filetypes from different processes may still overlap each other.

If filetype has holes in it, then the data in the holes is inaccessible to the calling process. However, the **disp**, **etype** and **filetype** arguments can be changed via future calls to **MPI\_FILE\_SET\_VIEW** to access a different part of the file.

It is erroneous to use absolute addresses in the construction of the **etype** and **filetype**.

The **info** argument is used to provide information regarding file access patterns and file system specifics to direct optimization (see Section 13.2.8, page 455). The constant **MPI\_INFO\_NULL** refers to the null info and can be used when no info needs to be specified.

The **datarep** argument is a string that specifies the representation of data in the file. See the file interoperability section (Section 13.5, page 490) for details and a discussion of valid values.

The user is responsible for ensuring that all nonblocking requests and split collective operations on **fh** have been completed before calling **MPI\_FILE\_SET\_VIEW**—otherwise, the call to **MPI\_FILE\_SET\_VIEW** is erroneous.

**MPI\_FILE\_GET\_VIEW**(**fh**, **disp**, **etype**, **filetype**, **datarep**)

IN	<b>fh</b>	file handle (handle)
OUT	<b>disp</b>	displacement (integer)
OUT	<b>etype</b>	elementary datatype (handle)
OUT	<b>filetype</b>	filetype (handle)
OUT	<b>datarep</b>	data representation (string)

```
int MPI_File_get_view(MPI_File fh, MPI_Offset *disp, MPI_Datatype *etype,
                     MPI_Datatype *filetype, char *datarep)
```

```
MPI_FILE_GET_VIEW(FH, DISP, ETYPE, FILETYPE, DATAREP, IERROR)
```

```
INTEGER FH, ETYPE, FILETYPE, IERROR
```

```
CHARACTER*(*) DATAREP
```

```
INTEGER(KIND=MPI_OFFSET_KIND) DISP
```

```
MPI_File_get_view(fh, disp, etype, filetype, datarep, ierror)
```

```
TYPE(MPI_File), INTENT(IN) :: fh
```

```
INTEGER(KIND=MPI_OFFSET_KIND), INTENT(OUT) :: disp
```

```
TYPE(MPI_Datatype), INTENT(OUT) :: etype
```

```
TYPE(MPI_Datatype), INTENT(OUT) :: filetype
```



```

    CHARACTER(LEN=*), INTENT(OUT) :: datarep
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::File::Get_view(MPI::Offset& disp, MPI::Datatype& etype,
    MPI::Datatype& filetype, char* datarep) const(binding deprecated,
    see Section 15.2) }
```

MPI\_FILE\_GET\_VIEW returns the process's view of the data in the file. The current value of the displacement is returned in `disp`. The `etype` and `filetype` are new datatypes with typemaps equal to the typemaps of the current `etype` and `filetype`, respectively.

The data representation is returned in `datarep`. The user is responsible for ensuring that `datarep` is large enough to hold the returned data representation string. The length of a data representation string is limited to the value of `MPI_MAX_DATAREP_STRING`.

In addition, if a portable datatype was used to set the current view, then the corresponding datatype returned by `MPI_FILE_GET_VIEW` is also a portable datatype. If `etype` or `filetype` are derived datatypes, the user is responsible for freeing them. The `etype` and `filetype` returned are both in a committed state.

## 13.4 Data Access

### 13.4.1 Data Access Routines

Data is moved between files and processes by issuing read and write calls. There are three orthogonal aspects to data access: positioning (explicit offset *vs.* implicit file pointer), synchronism (blocking *vs.* nonblocking and split collective), and coordination (noncollective *vs.* collective). The following combinations of these data access routines, including two types of file pointers (individual and shared) are provided in Table 13.1.

positioning	synchronism	coordination	
		<i>noncollective</i>	<i>collective</i>
<i>explicit offsets</i>	<i>blocking</i>	MPI_FILE_READ_AT MPI_FILE_WRITE_AT	MPI_FILE_READ_AT_ALL MPI_FILE_WRITE_AT_ALL
	<i>nonblocking &amp; split collective</i>	MPI_FILE_IREAD_AT	MPI_FILE_READ_AT_ALL_BEGIN MPI_FILE_READ_AT_ALL_END
		MPI_FILE_IWRITE_AT	MPI_FILE_WRITE_AT_ALL_BEGIN MPI_FILE_WRITE_AT_ALL_END
<i>individual file pointers</i>	<i>blocking</i>	MPI_FILE_READ MPI_FILE_WRITE	MPI_FILE_READ_ALL MPI_FILE_WRITE_ALL
	<i>nonblocking &amp; split collective</i>	MPI_FILE_IREAD	MPI_FILE_READ_ALL_BEGIN MPI_FILE_READ_ALL_END
		MPI_FILE_IWRITE	MPI_FILE_WRITE_ALL_BEGIN MPI_FILE_WRITE_ALL_END
<i>shared file pointer</i>	<i>blocking</i>	MPI_FILE_READ_SHARED MPI_FILE_WRITE_SHARED	MPI_FILE_READ_ORDERED MPI_FILE_WRITE_ORDERED
	<i>nonblocking &amp; split collective</i>	MPI_FILE_IREAD_SHARED	MPI_FILE_READ_ORDERED_BEGIN MPI_FILE_READ_ORDERED_END
		MPI_FILE_IWRITE_SHARED	MPI_FILE_WRITE_ORDERED_BEGIN MPI_FILE_WRITE_ORDERED_END

Table 13.1: Data access routines

POSIX `read()/fread()` and `write()/fwrite()` are blocking, noncollective operations and use individual file pointers. The MPI equivalents are `MPI_FILE_READ` and `MPI_FILE_WRITE`.

Implementations of data access routines may buffer data to improve performance. This does not affect reads, as the data is always available in the user’s buffer after a read operation completes. For writes, however, the `MPI_FILE_SYNC` routine provides the only guarantee that data has been transferred to the storage device.

## Positioning

MPI provides three types of positioning for data access routines: explicit offsets, individual file pointers, and shared file pointers. The different positioning methods may be mixed within the same program and do not affect each other.

The data access routines that accept explicit offsets contain `_AT` in their name (e.g., `MPI_FILE_WRITE_AT`). Explicit offset operations perform data access at the file position given directly as an argument—no file pointer is used nor updated. Note that this is not equivalent to an atomic seek-and-read or seek-and-write operation, as no “seek” is issued. Operations with explicit offsets are described in Section 13.4.2, page 464.

The names of the individual file pointer routines contain no positional qualifier (e.g., `MPI_FILE_WRITE`). Operations with individual file pointers are described in Section 13.4.3, page 468. The data access routines that use shared file pointers contain `_SHARED` or `_ORDERED` in their name (e.g., `MPI_FILE_WRITE_SHARED`). Operations with shared file pointers are described in Section 13.4.4, page 476.

The main semantic issues with MPI-maintained file pointers are how and when they are updated by I/O operations. In general, each I/O operation leaves the file pointer pointing to the next data item after the last one that is accessed by the operation. In a nonblocking or split collective operation, the pointer is updated by the call that initiates the I/O, possibly before the access completes.

More formally,

$$new\_file\_offset = old\_file\_offset + \frac{elements(datatype)}{elements(etype)} \times count$$

where *count* is the number of *datatype* items to be accessed, *elements(X)* is the number of predefined datatypes in the typemap of *X*, and *old\_file\_offset* is the value of the implicit offset before the call. The file position, *new\_file\_offset*, is in terms of a count of etypes relative to the current view.

## Synchronism

MPI supports blocking and nonblocking I/O routines.

A *blocking* I/O call will not return until the I/O request is completed.

A *nonblocking* I/O call initiates an I/O operation, but does not wait for it to complete. Given suitable hardware, this allows the transfer of data out/in the user’s buffer to proceed concurrently with computation. A separate *request complete* call (`MPI_WAIT`, `MPI_TEST`, or any of their variants) is needed to complete the I/O request, i.e., to confirm that the data has been read or written and that it is safe for the user to reuse the buffer. The nonblocking versions of the routines are named `MPI_FILE_IXXX`, where the *I* stands for immediate.

It is erroneous to access the local buffer of a nonblocking data access operation, or to use that buffer as the source or target of other communications, between the initiation and completion of the operation.

The split collective routines support a restricted form of “nonblocking” operations for collective data access (see Section 13.4.5, page 482).

#### Coordination

Every noncollective data access routine `MPI_FILE_XXX` has a collective counterpart. For most routines, this counterpart is `MPI_FILE_XXX_ALL` or a pair of `MPI_FILE_XXX_BEGIN` and `MPI_FILE_XXX_END`. The counterparts to the `MPI_FILE_XXX_SHARED` routines are `MPI_FILE_XXX_ORDERED`.

The completion of a noncollective call only depends on the activity of the calling process. However, the completion of a collective call (which must be called by all members of the process group) may depend on the activity of the other processes participating in the collective call. See Section 13.6.4, page 504, for rules on semantics of collective calls.

Collective operations may perform much better than their noncollective counterparts, as global data accesses have significant potential for automatic optimization.

#### Data Access Conventions

Data is moved between files and processes by calling read and write routines. Read routines move data from a file into memory. Write routines move data from memory into a file. The file is designated by a file handle, `fh`. The location of the file data is specified by an offset into the current view. The data in memory is specified by a triple: `buf`, `count`, and `datatype`. Upon completion, the amount of data accessed by the calling process is returned in a `status`.

An offset designates the starting position in the file for an access. The offset is always in etype units relative to the current view. Explicit offset routines pass `offset` as an argument (negative values are erroneous). The file pointer routines use implicit offsets maintained by MPI.

A data access routine attempts to transfer (read or write) `count` data items of type `datatype` between the user’s buffer `buf` and the file. The `datatype` passed to the routine must be a committed datatype. The layout of data in memory corresponding to `buf`, `count`, `datatype` is interpreted the same way as in MPI communication functions; see Section 3.2.2 on page 29 and Section 4.1.11 on page 111. The data is accessed from those parts of the file specified by the current view (Section 13.3, page 458). The type signature of `datatype` must match the type signature of some number of contiguous copies of the `etype` of the current view. As in a receive, it is erroneous to specify a `datatype` for reading that contains overlapping regions (areas of memory which would be stored into more than once).

The nonblocking data access routines indicate that MPI can start a data access and associate a request handle, `request`, with the I/O operation. Nonblocking operations are completed via `MPI_TEST`, `MPI_WAIT`, or any of their variants.

Data access operations, when completed, return the amount of data accessed in `status`.

*Advice to users.* To prevent problems with the argument copying and register optimization done by Fortran compilers, please note the hints in — Sections 16.2.2-16.2.12, especially in Sections 16.2.4 and 16.2.5 on pages 547-550 about *problems due to data copying and sequence association with subscript triplets and vector subscripts*, and in Sections 16.2.8 to 16.2.11 on pages 551 to 561 about *optimization problems, code*

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ticket236-H.  
ticket238-J.

*movements and register optimization, and temporary and permanent data movements.*  
*(End of advice to users.)*

For blocking routines, `status` is returned directly. For nonblocking routines and split collective routines, `status` is returned when the operation is completed. The number of `datatype` entries and predefined elements accessed by the calling process can be extracted from `status` by using `MPI_GET_COUNT` and `MPI_GET_ELEMENTS`, respectively. The interpretation of the `MPI_ERROR` field is the same as for other operations — normally undefined, but meaningful if an MPI routine returns `MPI_ERR_IN_STATUS`. The user can pass (in C and *with the Fortran `mpi module` or `mpif.h` include file*) `MPI_STATUS_IGNORE` in the `status` argument if the return value of this argument is not needed. *With the Fortran `mpi_f08 module` or in C++*, the `status` argument is optional. The `status` can be passed to `MPI_TEST_CANCELLED` to determine if the operation was cancelled. All other fields of `status` are undefined.

When reading, a program can detect the end of file by noting that the amount of data read is less than the amount requested. Writing past the end of file increases the file size. The amount of data accessed will be the amount requested, unless an error is raised (or a read reaches the end of file).

### 13.4.2 Data Access with Explicit Offsets

If `MPI_MODE_SEQUENTIAL` mode was specified when the file was opened, it is erroneous to call the routines in this section.

`MPI_FILE_READ_AT(fh, offset, buf, count, datatype, status)`

IN	fh	file handle (handle)
IN	offset	file offset (integer)
OUT	buf	initial address of buffer (choice)
IN	count	number of elements in buffer (integer)
IN	datatype	datatype of each buffer element (handle)
OUT	status	status object (Status)

```
int MPI_File_read_at(MPI_File fh, MPI_Offset offset, void *buf, int count,
                    MPI_Datatype datatype, MPI_Status *status)
```

```
MPI_FILE_READ_AT(FH, OFFSET, BUF, COUNT, DATATYPE, STATUS, IERROR)
  <type> BUF(*)
  INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
  INTEGER(KIND=MPI_OFFSET_KIND) OFFSET
```

```
MPI_File_read_at(fh, offset, buf, count, datatype, status, ierror)
  TYPE(MPI_File), INTENT(IN) :: fh
  INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
  TYPE(*), DIMENSION(..) :: buf
  INTEGER, INTENT(IN) :: count
  TYPE(MPI_Datatype), INTENT(IN) :: datatype
  TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
```

```

    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
{void MPI::File::Read_at(MPI::Offset offset, void* buf, int count,
    const MPI::Datatype& datatype, MPI::Status& status) (binding
    deprecated, see Section 15.2) }
{void MPI::File::Read_at(MPI::Offset offset, void* buf, int count,
    const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
}
```

MPI\_FILE\_READ\_AT reads a file beginning at the position specified by offset.

MPI\_FILE\_READ\_AT\_ALL(fh, offset, buf, count, datatype, status)

IN	fh	file handle (handle)
IN	offset	file offset (integer)
OUT	buf	initial address of buffer (choice)
IN	count	number of elements in buffer (integer)
IN	datatype	datatype of each buffer element (handle)
OUT	status	status object (Status)

```

int MPI_File_read_at_all(MPI_File fh, MPI_Offset offset, void *buf,
    int count, MPI_Datatype datatype, MPI_Status *status)
```

```

MPI_FILE_READ_AT_ALL(FH, OFFSET, BUF, COUNT, DATATYPE, STATUS, IERROR)
    <type> BUF(*)
    INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
    INTEGER(KIND=MPI_OFFSET_KIND) OFFSET
```

```

MPI_File_read_at_all(fh, offset, buf, count, datatype, status, ierror)
    TYPE(MPI_File), INTENT(IN) :: fh
    INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
    TYPE(*), DIMENSION(..) :: buf
    INTEGER, INTENT(IN) :: count
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```

{void MPI::File::Read_at_all(MPI::Offset offset, void* buf, int count,
    const MPI::Datatype& datatype, MPI::Status& status) (binding
    deprecated, see Section 15.2) }
{void MPI::File::Read_at_all(MPI::Offset offset, void* buf, int count,
    const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
}
```

MPI\_FILE\_READ\_AT\_ALL is a collective version of the blocking MPI\_FILE\_READ\_AT interface.

ticket-248T.

```

1  MPI_FILE_WRITE_AT(fh, offset, buf, count, datatype, status)
2
3  INOUT    fh                file handle (handle)
4  IN       offset            file offset (integer)
5  IN       buf               initial address of buffer (choice)
6  IN       count             number of elements in buffer (integer)
7  IN       datatype          datatype of each buffer element (handle)
8  OUT      status            status object (Status)
9
10
11  int MPI_File_write_at(MPI_File fh, MPI_Offset offset, void *buf, int count,
12                        MPI_Datatype datatype, MPI_Status *status)
13
14  MPI_FILE_WRITE_AT(FH, OFFSET, BUF, COUNT, DATATYPE, STATUS, IERROR)
15  <type> BUF(*)
16  INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
17  INTEGER(KIND=MPI_OFFSET_KIND) OFFSET
18
19  MPI_File_write_at(fh, offset, buf, count, datatype, status, ierror)
20  TYPE(MPI_File), INTENT(IN) :: fh
21  INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
22  TYPE(*), DIMENSION(..) :: buf
23  INTEGER, INTENT(IN) :: count
24  TYPE(MPI_Datatype), INTENT(IN) :: datatype
25  TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
26  INTEGER, OPTIONAL, INTENT(OUT) :: ierror
27
28  {void MPI::File::Write_at(MPI::Offset offset, const void* buf, int count,
29                            const MPI::Datatype& datatype, MPI::Status& status) (binding
30                            deprecated, see Section 15.2) }
31
32  {void MPI::File::Write_at(MPI::Offset offset, const void* buf, int count,
33                            const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
34                            }
35
36  MPI_FILE_WRITE_AT writes a file beginning at the position specified by offset.
37
38  MPI_FILE_WRITE_AT_ALL(fh, offset, buf, count, datatype, status)
39
40  INOUT    fh                file handle (handle)
41  IN       offset            file offset (integer)
42  IN       buf               initial address of buffer (choice)
43  IN       count             number of elements in buffer (integer)
44  IN       datatype          datatype of each buffer element (handle)
45  OUT      status            status object (Status)
46
47  int MPI_File_write_at_all(MPI_File fh, MPI_Offset offset, void *buf,
48                            int count, MPI_Datatype datatype, MPI_Status *status)

```

```

MPI_FILE_WRITE_AT_ALL(FH, OFFSET, BUF, COUNT, DATATYPE, STATUS, IERROR)
    <type> BUF(*)
    INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
    INTEGER(KIND=MPI_OFFSET_KIND) OFFSET

MPI_File_write_at_all(fh, offset, buf, count, datatype, status, ierror)
    TYPE(MPI_File), INTENT(IN) :: fh
    INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
    TYPE(*), DIMENSION(..) :: buf
    INTEGER, INTENT(IN) :: count
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::File::Write_at_all(MPI::Offset offset, const void* buf,
    int count, const MPI::Datatype& datatype,
    MPI::Status& status) (binding deprecated, see Section 15.2) }

{void MPI::File::Write_at_all(MPI::Offset offset, const void* buf,
    int count, const MPI::Datatype& datatype) (binding deprecated, see
    Section 15.2) }

    MPI_FILE_WRITE_AT_ALL is a collective version of the blocking
    MPI_FILE_WRITE_AT interface.

```

```

MPI_FILE_IREAD_AT(fh, offset, buf, count, datatype, request)

```

IN	fh	file handle (handle)
IN	offset	file offset (integer)
OUT	buf	initial address of buffer (choice)
IN	count	number of elements in buffer (integer)
IN	datatype	datatype of each buffer element (handle)
OUT	request	request object (handle)

```

int MPI_File_iread_at(MPI_File fh, MPI_Offset offset, void *buf, int count,
    MPI_Datatype datatype, MPI_Request *request)

```

```

MPI_FILE_IREAD_AT(FH, OFFSET, BUF, COUNT, DATATYPE, REQUEST, IERROR)
    <type> BUF(*)
    INTEGER FH, COUNT, DATATYPE, REQUEST, IERROR
    INTEGER(KIND=MPI_OFFSET_KIND) OFFSET

```

```

MPI_File_iread_at(fh, offset, buf, count, datatype, request, ierror)
    TYPE(MPI_File), INTENT(IN) :: fh
    INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
    TYPE(*), DIMENSION(..) :: buf
    INTEGER, INTENT(IN) :: count
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Request), INTENT(OUT) :: request

```



```

1      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
2
3      {MPI::Request MPI::File::Iread_at(MPI::Offset offset, void* buf, int count,
4          const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
5          }

```

MPI\_FILE\_IREAD\_AT is a nonblocking version of the MPI\_FILE\_READ\_AT interface.

```

6      MPI_FILE_IWRITE_AT(fh, offset, buf, count, datatype, request)

```

10	INOUT	fh	file handle (handle)
11	IN	offset	file offset (integer)
12	IN	buf	initial address of buffer (choice)
13	IN	count	number of elements in buffer (integer)
14	IN	datatype	datatype of each buffer element (handle)
15	IN	datatype	datatype of each buffer element (handle)
16	OUT	request	request object (handle)
17			

```

18
19      int MPI_File_iwrite_at(MPI_File fh, MPI_Offset offset, void *buf,
20          int count, MPI_Datatype datatype, MPI_Request *request)

```

```

21      MPI_FILE_IWRITE_AT(FH, OFFSET, BUF, COUNT, DATATYPE, REQUEST, IERROR)
22          <type> BUF(*)
23          INTEGER FH, COUNT, DATATYPE, REQUEST, IERROR
24          INTEGER(KIND=MPI_OFFSET_KIND) OFFSET

```

```

25      MPI_File_iwrite_at(fh, offset, buf, count, datatype, request, ierror)
26          TYPE(MPI_File), INTENT(IN) :: fh
27          INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
28          TYPE(*), DIMENSION(..) :: buf
29          INTEGER, INTENT(IN) :: count
30          TYPE(MPI_Datatype), INTENT(IN) :: datatype
31          TYPE(MPI_Request), INTENT(OUT) :: request
32          INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

33
34      {MPI::Request MPI::File::Iwrite_at(MPI::Offset offset, const void* buf,
35          int count, const MPI::Datatype& datatype) (binding deprecated, see
36          Section 15.2) }

```

MPI\_FILE\_IWRITE\_AT is a nonblocking version of the MPI\_FILE\_WRITE\_AT interface.

### 13.4.3 Data Access with Individual File Pointers

MPI maintains one individual file pointer per process per file handle. The current value of this pointer implicitly specifies the offset in the data access routines described in this section. These routines only use and update the individual file pointers maintained by MPI. The shared file pointer is not used nor updated.

The individual file pointer routines have the same semantics as the data access with explicit offset routines described in Section 13.4.2, page 464, with the following modification:



- the `offset` is defined to be the current value of the MPI-maintained individual file pointer.

After an individual file pointer operation is initiated, the individual file pointer is updated to point to the next etype after the last one that will be accessed. The file pointer is updated relative to the current view of the file.

If `MPI_MODE_SEQUENTIAL` mode was specified when the file was opened, it is erroneous to call the routines in this section, with the exception of `MPI_FILE_GET_BYTE_OFFSET`.

`MPI_FILE_READ(fh, buf, count, datatype, status)`

INOUT	fh	file handle (handle)
OUT	buf	initial address of buffer (choice)
IN	count	number of elements in buffer (integer)
IN	datatype	datatype of each buffer element (handle)
OUT	status	status object (Status)

```
int MPI_File_read(MPI_File fh, void *buf, int count, MPI_Datatype datatype,
                 MPI_Status *status)
```

```
MPI_FILE_READ(FH, BUF, COUNT, DATATYPE, STATUS, IERROR)
```

```
<type> BUF(*)
```

```
INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
```

```
MPI_File_read(fh, buf, count, datatype, status, ierror)
```

```
TYPE(MPI_File), INTENT(IN) :: fh
```

```
TYPE(*), DIMENSION(..) :: buf
```

```
INTEGER, INTENT(IN) :: count
```

```
TYPE(MPI_Datatype), INTENT(IN) :: datatype
```

```
TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::File::Read(void* buf, int count, const MPI::Datatype& datatype,
                     MPI::Status& status) (binding deprecated, see Section 15.2) }
```

```
{void MPI::File::Read(void* buf, int count,
                     const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
}
```

`MPI_FILE_READ` reads a file using the individual file pointer.

**Example 13.2** The following Fortran code fragment is an example of reading a file until the end of file is reached:

```

1  !   Read a preexisting input file until all data has been read.
2  !   Call routine "process_input" if all requested data is read.
3  !   The Fortran 90 "exit" statement exits the loop.
4
5      integer    bufsize, numread, totprocessed, status(MPI_STATUS_SIZE)
6      parameter (bufsize=100)
7      real       localbuffer(bufsize)
8
9      call MPI_FILE_OPEN( MPI_COMM_WORLD, 'myoldfile', &
10                          MPI_MODE_RDONLY, MPI_INFO_NULL, myfh, ierr )
11      call MPI_FILE_SET_VIEW( myfh, 0, MPI_REAL, MPI_REAL, 'native', &
12                              MPI_INFO_NULL, ierr )
13      totprocessed = 0
14      do
15          call MPI_FILE_READ( myfh, localbuffer, bufsize, MPI_REAL, &
16                              status, ierr )
17          call MPI_GET_COUNT( status, MPI_REAL, numread, ierr )
18          call process_input( localbuffer, numread )
19          totprocessed = totprocessed + numread
20          if ( numread < bufsize ) exit
21      enddo
22
23      write(6,1001) numread, bufsize, totprocessed
24 1001 format( "No more data:  read", I3, "and expected", I3, &
25             "Processed total of", I6, "before terminating job." )
26
27      call MPI_FILE_CLOSE( myfh, ierr )
28
29
30
31 MPI_FILE_READ_ALL(fh, buf, count, datatype, status)
32     INOUT    fh                file handle (handle)
33     OUT      buf               initial address of buffer (choice)
34     IN       count             number of elements in buffer (integer)
35     IN       datatype          datatype of each buffer element (handle)
36     OUT      status            status object (Status)
37
38
39
40 int MPI_File_read_all(MPI_File fh, void *buf, int count,
41                      MPI_Datatype datatype, MPI_Status *status)
42
43 MPI_FILE_READ_ALL(FH, BUF, COUNT, DATATYPE, STATUS, IERROR)
44     <type> BUF(*)
45     INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR

```

```

46 MPI_File_read_all(fh, buf, count, datatype, status, ierror)
47     TYPE(MPI_File), INTENT(IN) :: fh
48     TYPE(*), DIMENSION(..) :: buf

```

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```

    INTEGER, INTENT(IN) :: count
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::File::Read_all(void* buf, int count,
    const MPI::Datatype& datatype, MPI::Status& status) (binding
    deprecated, see Section 15.2) }

{void MPI::File::Read_all(void* buf, int count,
    const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
}
```

MPI\_FILE\_READ\_ALL is a collective version of the blocking MPI\_FILE\_READ interface.

MPI\_FILE\_WRITE(fh, buf, count, datatype, status)

INOUT	fh	file handle (handle)
IN	buf	initial address of buffer (choice)
IN	count	number of elements in buffer (integer)
IN	datatype	datatype of each buffer element (handle)
OUT	status	status object (Status)

```

int MPI_File_write(MPI_File fh, void *buf, int count,
    MPI_Datatype datatype, MPI_Status *status)
```

```

MPI_FILE_WRITE(FH, BUF, COUNT, DATATYPE, STATUS, IERROR)
```

```

    <type> BUF(*)
```

```

    INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
```

```

MPI_File_write(fh, buf, count, datatype, status, ierror)
```

```

    TYPE(MPI_File), INTENT(IN) :: fh
    TYPE(*), DIMENSION(..) :: buf
    INTEGER, INTENT(IN) :: count
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```

{void MPI::File::Write(const void* buf, int count,
    const MPI::Datatype& datatype, MPI::Status& status) (binding
    deprecated, see Section 15.2) }
```

```

{void MPI::File::Write(const void* buf, int count,
    const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
}
```

MPI\_FILE\_WRITE writes a file using the individual file pointer.

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```
1 MPI_FILE_WRITE_ALL(fh, buf, count, datatype, status)
```

```
2     INOUT    fh                file handle (handle)
```

```
3     IN      buf                initial address of buffer (choice)
```

```
4     IN      count              number of elements in buffer (integer)
```

```
5     IN      datatype           datatype of each buffer element (handle)
```

```
6     OUT     status             status object (Status)
```

```
7
8
9
10 int MPI_File_write_all(MPI_File fh, void *buf, int count,
11                        MPI_Datatype datatype, MPI_Status *status)
```

```
12 MPI_FILE_WRITE_ALL(FH, BUF, COUNT, DATATYPE, STATUS, IERROR)
```

```
13     <type> BUF(*)
```

```
14     INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
```

```
15 MPI_File_write_all(fh, buf, count, datatype, status, ierror)
```

```
16     TYPE(MPI_File), INTENT(IN) :: fh
```

```
17     TYPE(*), DIMENSION(..) :: buf
```

```
18     INTEGER, INTENT(IN) :: count
```

```
19     TYPE(MPI_Datatype), INTENT(IN) :: datatype
```

```
20     TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
```

```
21     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
22
23 {void MPI::File::Write_all(const void* buf, int count,
24                           const MPI::Datatype& datatype, MPI::Status& status) (binding
25                           deprecated, see Section 15.2) }
```

```
26
27 {void MPI::File::Write_all(const void* buf, int count,
28                           const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
29 }
```

30 MPI\_FILE\_WRITE\_ALL is a collective version of the blocking MPI\_FILE\_WRITE inter-  
31 face.  
32

```
33
34 MPI_FILE_IREAD(fh, buf, count, datatype, request)
```

```
35     INOUT    fh                file handle (handle)
```

```
36     OUT     buf                initial address of buffer (choice)
```

```
37     IN      count              number of elements in buffer (integer)
```

```
38     IN      datatype           datatype of each buffer element (handle)
```

```
39     OUT     request            request object (handle)
```

```
40
41
42
43 int MPI_File_iread(MPI_File fh, void *buf, int count,
44                   MPI_Datatype datatype, MPI_Request *request)
```

```
45 MPI_FILE_IREAD(FH, BUF, COUNT, DATATYPE, REQUEST, IERROR)
```

```
46     <type> BUF(*)
```

```
47     INTEGER FH, COUNT, DATATYPE, REQUEST, IERROR
```

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```

MPI_File_iread(fh, buf, count, datatype, request, ierror)
  TYPE(MPI_File), INTENT(IN) :: fh
  TYPE(*), DIMENSION(..) :: buf
  INTEGER, INTENT(IN) :: count
  TYPE(MPI_Datatype), INTENT(IN) :: datatype
  TYPE(MPI_Request), INTENT(OUT) :: request
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{MPI::Request MPI::File::Iread(void* buf, int count,
  const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
}
```

MPI\_FILE\_IREAD is a nonblocking version of the MPI\_FILE\_READ interface.

**Example 13.3** The following Fortran code fragment illustrates file pointer update semantics:

```

! Read the first twenty real words in a file into two local
! buffers. Note that when the first MPI_FILE_IREAD returns,
! the file pointer has been updated to point to the
! eleventh real word in the file.

integer bufsize, req1, req2
integer, dimension(MPI_STATUS_SIZE) :: status1, status2
parameter (bufsize=10)
real buf1(bufsize), buf2(bufsize)

call MPI_FILE_OPEN( MPI_COMM_WORLD, 'myoldfile', &
  MPI_MODE_RDONLY, MPI_INFO_NULL, myfh, ierr )
call MPI_FILE_SET_VIEW( myfh, 0, MPI_REAL, MPI_REAL, 'native', &
  MPI_INFO_NULL, ierr )
call MPI_FILE_IREAD( myfh, buf1, bufsize, MPI_REAL, &
  req1, ierr )
call MPI_FILE_IREAD( myfh, buf2, bufsize, MPI_REAL, &
  req2, ierr )

call MPI_WAIT( req1, status1, ierr )
call MPI_WAIT( req2, status2, ierr )

call MPI_FILE_CLOSE( myfh, ierr )
```

```
1 MPI_FILE_IWRITE(fh, buf, count, datatype, request)
```

```
2     INOUT    fh                file handle (handle)
3
4     IN       buf              initial address of buffer (choice)
5
6     IN       count            number of elements in buffer (integer)
7
8     IN       datatype          datatype of each buffer element (handle)
9
10    OUT      request           request object (handle)
```

```
10 int MPI_File_iwrite(MPI_File fh, void *buf, int count,
11                    MPI_Datatype datatype, MPI_Request *request)
```

```
12 MPI_FILE_IWRITE(FH, BUF, COUNT, DATATYPE, REQUEST, IERROR)
13 <type> BUF(*)
14 INTEGER FH, COUNT, DATATYPE, REQUEST, IERROR
```

```
15 MPI_File_iwrite(fh, buf, count, datatype, request, ierror)
16 TYPE(MPI_File), INTENT(IN) :: fh
17 TYPE(*), DIMENSION(..) :: buf
18 INTEGER, INTENT(IN) :: count
19 TYPE(MPI_Datatype), INTENT(IN) :: datatype
20 TYPE(MPI_Request), INTENT(OUT) :: request
21 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
22 {MPI::Request MPI::File::Iwrite(const void* buf, int count,
23                                const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
24 }
25
```

26 MPI\_FILE\_IWRITE is a nonblocking version of the MPI\_FILE\_WRITE interface.

```
27
28
29 MPI_FILE_SEEK(fh, offset, whence)
```

```
30
31    INOUT    fh                file handle (handle)
32
33    IN       offset            file offset (integer)
34
35    IN       whence            update mode (state)
```

```
36 int MPI_File_seek(MPI_File fh, MPI_Offset offset, int whence)
```

```
37 MPI_FILE_SEEK(FH, OFFSET, WHENCE, IERROR)
38 INTEGER FH, WHENCE, IERROR
39 INTEGER(KIND=MPI_OFFSET_KIND) OFFSET
```

```
40 MPI_File_seek(fh, offset, whence, ierror)
41 TYPE(MPI_File), INTENT(IN) :: fh
42 INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
43 INTEGER, INTENT(IN) :: whence
44 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
45 {void MPI::File::Seek(MPI::Offset offset, int whence) (binding deprecated, see
46 Section 15.2) }
47
48
```

MPI\_FILE\_SEEK updates the individual file pointer according to *whence*, which has the following possible values:

- MPI\_SEEK\_SET: the pointer is set to *offset*
- MPI\_SEEK\_CUR: the pointer is set to the current pointer position plus *offset*
- MPI\_SEEK\_END: the pointer is set to the end of file plus *offset*

The *offset* can be negative, which allows seeking backwards. It is erroneous to seek to a negative position in the view.

MPI\_FILE\_GET\_POSITION(*fh*, *offset*)

IN	<i>fh</i>	file handle (handle)
OUT	<i>offset</i>	offset of individual pointer (integer)

```
int MPI_File_get_position(MPI_File fh, MPI_Offset *offset)
```

```
MPI_FILE_GET_POSITION(FH, OFFSET, IERROR)
```

```
    INTEGER FH, IERROR
```

```
    INTEGER(KIND=MPI_OFFSET_KIND) OFFSET
```

```
MPI_File_get_position(fh, offset, ierror)
```

```
    TYPE(MPI_File), INTENT(IN) :: fh
```

```
    INTEGER(KIND=MPI_OFFSET_KIND), INTENT(OUT) :: offset
```

```
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{MPI::Offset MPI::File::Get_position() const(binding deprecated, see Section 15.2)
}
```

MPI\_FILE\_GET\_POSITION returns, in *offset*, the current position of the individual file pointer in etype units relative to the current view.

*Advice to users.* The *offset* can be used in a future call to MPI\_FILE\_SEEK using *whence* = MPI\_SEEK\_SET to return to the current position. To set the displacement to the current file pointer position, first convert *offset* into an absolute byte position using MPI\_FILE\_GET\_BYTE\_OFFSET, then call MPI\_FILE\_SET\_VIEW with the resulting displacement. (*End of advice to users.*)

MPI\_FILE\_GET\_BYTE\_OFFSET(*fh*, *offset*, *disp*)

IN	<i>fh</i>	file handle (handle)
IN	<i>offset</i>	offset (integer)
OUT	<i>disp</i>	absolute byte position of offset (integer)

```
int MPI_File_get_byte_offset(MPI_File fh, MPI_Offset offset,
                             MPI_Offset *disp)
```

```
MPI_FILE_GET_BYTE_OFFSET(FH, OFFSET, DISP, IERROR)
```

```

1      INTEGER fh, ierror
2      INTEGER(KIND=MPI_OFFSET_KIND) offset, disp
3
4      MPI_File_get_byte_offset(fh, offset, disp, ierror)
5      TYPE(MPI_File), INTENT(IN) :: fh
6      INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
7      INTEGER(KIND=MPI_OFFSET_KIND), INTENT(OUT) :: disp
8      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
9
10     {MPI::Offset MPI::File::Get_byte_offset(const MPI::Offset disp)
11         const(binding deprecated, see Section 15.2) }

```

MPI\_FILE\_GET\_BYTE\_OFFSET converts a view-relative offset into an absolute byte position. The absolute byte position (from the beginning of the file) of `offset` relative to the current view of `fh` is returned in `disp`.

#### 13.4.4 Data Access with Shared File Pointers

MPI maintains exactly one shared file pointer per collective MPI\_FILE\_OPEN (shared among processes in the communicator group). The current value of this pointer implicitly specifies the offset in the data access routines described in this section. These routines only use and update the shared file pointer maintained by MPI. The individual file pointers are not used nor updated.

The shared file pointer routines have the same semantics as the data access with explicit offset routines described in Section 13.4.2, page 464, with the following modifications:

- the `offset` is defined to be the current value of the MPI-maintained shared file pointer,
- the effect of multiple calls to shared file pointer routines is defined to behave as if the calls were serialized, and
- the use of shared file pointer routines is erroneous unless all processes use the same file view.

For the noncollective shared file pointer routines, the serialization ordering is not deterministic. The user needs to use other synchronization means to enforce a specific order.

After a shared file pointer operation is initiated, the shared file pointer is updated to point to the next etype after the last one that will be accessed. The file pointer is updated relative to the current view of the file.

#### Noncollective Operations

MPI\_FILE\_READ\_SHARED(fh, buf, count, datatype, status)

INOUT	fh	file handle (handle)
OUT	buf	initial address of buffer (choice)
IN	count	number of elements in buffer (integer)
IN	datatype	datatype of each buffer element (handle)
OUT	status	status object (Status)



```

int MPI_File_read_shared(MPI_File fh, void *buf, int count,
                        MPI_Datatype datatype, MPI_Status *status)
MPI_FILE_READ_SHARED(FH, BUF, COUNT, DATATYPE, STATUS, IERROR)
    <type> BUF(*)
    INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
MPI_File_read_shared(fh, buf, count, datatype, status, ierror)
    TYPE(MPI_File), INTENT(IN) :: fh
    TYPE(*), DIMENSION(..) :: buf
    INTEGER, INTENT(IN) :: count
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
{void MPI::File::Read_shared(void* buf, int count,
    const MPI::Datatype& datatype, MPI::Status& status) (binding
    deprecated, see Section 15.2) }
{void MPI::File::Read_shared(void* buf, int count,
    const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
    }

```

MPI\_FILE\_READ\_SHARED reads a file using the shared file pointer.

MPI\_FILE\_WRITE\_SHARED(fh, buf, count, datatype, status)

INOUT	fh	file handle (handle)
IN	buf	initial address of buffer (choice)
IN	count	number of elements in buffer (integer)
IN	datatype	datatype of each buffer element (handle)
OUT	status	status object (Status)

```

int MPI_File_write_shared(MPI_File fh, void *buf, int count,
                        MPI_Datatype datatype, MPI_Status *status)
MPI_FILE_WRITE_SHARED(FH, BUF, COUNT, DATATYPE, STATUS, IERROR)
    <type> BUF(*)
    INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
MPI_File_write_shared(fh, buf, count, datatype, status, ierror)
    TYPE(MPI_File), INTENT(IN) :: fh
    TYPE(*), DIMENSION(..) :: buf
    INTEGER, INTENT(IN) :: count
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
{void MPI::File::Write_shared(const void* buf, int count,
    const MPI::Datatype& datatype, MPI::Status& status) (binding

```

```

1      deprecated, see Section 15.2) }
2
3  {void MPI::File::Write_shared(const void* buf, int count,
4      const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
5      }

```

MPI\_FILE\_WRITE\_SHARED writes a file using the shared file pointer.

```

6
7
8
9  MPI_FILE_IREAD_SHARED(fh, buf, count, datatype, request)

```

INOUT	fh	file handle (handle)
OUT	buf	initial address of buffer (choice)
IN	count	number of elements in buffer (integer)
IN	datatype	datatype of each buffer element (handle)
OUT	request	request object (handle)

```

10
11
12
13
14
15
16
17
18  int MPI_File_iread_shared(MPI_File fh, void *buf, int count,
19      MPI_Datatype datatype, MPI_Request *request)

```

```

20  MPI_FILE_IREAD_SHARED(FH, BUF, COUNT, DATATYPE, REQUEST, IERROR)
21      <type> BUF(*)
22      INTEGER FH, COUNT, DATATYPE, REQUEST, IERROR

```

```

23
24  MPI_File_iread_shared(fh, buf, count, datatype, request, ierror)
25      TYPE(MPI_File), INTENT(IN) :: fh
26      TYPE(*), DIMENSION(..) :: buf
27      INTEGER, INTENT(IN) :: count
28      TYPE(MPI_Datatype), INTENT(IN) :: datatype
29      TYPE(MPI_Request), INTENT(OUT) :: request
30      INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

31  {MPI::Request MPI::File::Iread_shared(void* buf, int count,
32      const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
33      }
34

```

MPI\_FILE\_IREAD\_SHARED is a nonblocking version of the MPI\_FILE\_READ\_SHARED interface.

```

35
36
37
38  MPI_FILE_IWRITE_SHARED(fh, buf, count, datatype, request)

```

INOUT	fh	file handle (handle)
IN	buf	initial address of buffer (choice)
IN	count	number of elements in buffer (integer)
IN	datatype	datatype of each buffer element (handle)
OUT	request	request object (handle)

```

39
40
41
42
43
44
45
46
47  int MPI_File_ fwrite_shared(MPI_File fh, void *buf, int count,
48      MPI_Datatype datatype, MPI_Request *request)

```

```

MPI_FILE_IWRITE_SHARED(FH, BUF, COUNT, DATATYPE, REQUEST, IERROR)
    <type> BUF(*)
    INTEGER FH, COUNT, DATATYPE, REQUEST, IERROR

MPI_File_iwrite_shared(fh, buf, count, datatype, request, ierror)
    TYPE(*), DIMENSION(..) :: buf
    TYPE(MPI_File), INTENT(IN) :: fh
    INTEGER, INTENT(IN) :: count
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Request), INTENT(OUT) :: request
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{MPI::Request MPI::File::Iwrite_shared(const void* buf, int count,
    const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
}
```

MPI\_FILE\_IWRITE\_SHARED is a nonblocking version of the MPI\_FILE\_WRITE\_SHARED interface.

### Collective Operations

The semantics of a collective access using a shared file pointer is that the accesses to the file will be in the order determined by the ranks of the processes within the group. For each process, the location in the file at which data is accessed is the position at which the shared file pointer would be after all processes whose ranks within the group less than that of this process had accessed their data. In addition, in order to prevent subsequent shared offset accesses by the same processes from interfering with this collective access, the call might return only after all the processes within the group have initiated their accesses. When the call returns, the shared file pointer points to the next etype accessible, according to the file view used by all processes, after the last etype requested.

*Advice to users.* There may be some programs in which all processes in the group need to access the file using the shared file pointer, but the program may not *require* that data be accessed in order of process rank. In such programs, using the shared ordered routines (e.g., MPI\_FILE\_WRITE\_ORDERED rather than MPI\_FILE\_WRITE\_SHARED) may enable an implementation to optimize access, improving performance. (*End of advice to users.*)

*Advice to implementors.* Accesses to the data requested by all processes do not have to be serialized. Once all processes have issued their requests, locations within the file for all accesses can be computed, and accesses can proceed independently from each other, possibly in parallel. (*End of advice to implementors.*)

```

1 MPI_FILE_READ_ORDERED(fh, buf, count, datatype, status)
2     INOUT    fh                file handle (handle)
3
4     OUT      buf                initial address of buffer (choice)
5
6     IN       count              number of elements in buffer (integer)
7
8     IN       datatype            datatype of each buffer element (handle)
9
10    OUT      status              status object (Status)
11
12
13 int MPI_File_read_ordered(MPI_File fh, void *buf, int count,
14     MPI_Datatype datatype, MPI_Status *status)
15
16 MPI_FILE_READ_ORDERED(FH, BUF, COUNT, DATATYPE, STATUS, IERROR)
17     <type> BUF(*)
18     INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
19
20 MPI_File_read_ordered(fh, buf, count, datatype, status, ierror)
21     TYPE(MPI_File), INTENT(IN) :: fh
22     TYPE(*), DIMENSION(..) :: buf
23     INTEGER, INTENT(IN) :: count
24     TYPE(MPI_Datatype), INTENT(IN) :: datatype
25     TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
26     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
27
28 {void MPI::File::Read_ordered(void* buf, int count,
29     const MPI::Datatype& datatype, MPI::Status& status) (binding
30     deprecated, see Section 15.2) }
31
32 {void MPI::File::Read_ordered(void* buf, int count,
33     const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
34     }
35
36 MPI_FILE_READ_ORDERED is a collective version of the MPI_FILE_READ_SHARED
37 interface.
38
39 MPI_FILE_WRITE_ORDERED(fh, buf, count, datatype, status)
40
41     INOUT    fh                file handle (handle)
42
43     IN       buf                initial address of buffer (choice)
44
45     IN       count              number of elements in buffer (integer)
46
47     IN       datatype            datatype of each buffer element (handle)
48
49     OUT      status              status object (Status)
50
51
52 int MPI_File_write_ordered(MPI_File fh, void *buf, int count,
53     MPI_Datatype datatype, MPI_Status *status)
54
55 MPI_FILE_WRITE_ORDERED(FH, BUF, COUNT, DATATYPE, STATUS, IERROR)
56     <type> BUF(*)
57     INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR

```

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```

MPI_File_write_ordered(fh, buf, count, datatype, status, ierror)
    TYPE(MPI_File), INTENT(IN) :: fh
    TYPE(*), DIMENSION(..) :: buf
    INTEGER, INTENT(IN) :: count
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::File::Write_ordered(const void* buf, int count,
    const MPI::Datatype& datatype, MPI::Status& status) (binding
    deprecated, see Section 15.2) }

{void MPI::File::Write_ordered(const void* buf, int count,
    const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
}
```

MPI\_FILE\_WRITE\_ORDERED is a collective version of the MPI\_FILE\_WRITE\_SHARED interface.

#### Seek

If MPI\_MODE\_SEQUENTIAL mode was specified when the file was opened, it is erroneous to call the following two routines (MPI\_FILE\_SEEK\_SHARED and MPI\_FILE\_GET\_POSITION\_SHARED).

MPI\_FILE\_SEEK\_SHARED(fh, offset, whence)

INOUT	fh	file handle (handle)
IN	offset	file offset (integer)
IN	whence	update mode (state)

```
int MPI_File_seek_shared(MPI_File fh, MPI_Offset offset, int whence)
```

```
MPI_FILE_SEEK_SHARED(FH, OFFSET, WHENCE, IERROR)
```

```
    INTEGER FH, WHENCE, IERROR
```

```
    INTEGER(KIND=MPI_OFFSET_KIND) OFFSET
```

```
MPI_File_seek_shared(fh, offset, whence, ierror)
```

```
    TYPE(MPI_File), INTENT(IN) :: fh
```

```
    INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
```

```
    INTEGER, INTENT(IN) :: whence
```

```
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::File::Seek_shared(MPI::Offset offset, int whence) (binding
    deprecated, see Section 15.2) }
```

MPI\_FILE\_SEEK\_SHARED updates the shared file pointer according to whence, which has the following possible values:

- MPI\_SEEK\_SET: the pointer is set to offset

- `MPI_SEEK_CUR`: the pointer is set to the current pointer position plus offset
- `MPI_SEEK_END`: the pointer is set to the end of file plus offset

`MPI_FILE_SEEK_SHARED` is collective; all the processes in the communicator group associated with the file handle `fh` must call `MPI_FILE_SEEK_SHARED` with the same values for `offset` and `whence`.

The `offset` can be negative, which allows seeking backwards. It is erroneous to seek to a negative position in the view.

`MPI_FILE_GET_POSITION_SHARED(fh, offset)`

IN	<code>fh</code>	file handle (handle)
OUT	<code>offset</code>	offset of shared pointer (integer)

`int MPI_File_get_position_shared(MPI_File fh, MPI_Offset *offset)`

`MPI_FILE_GET_POSITION_SHARED(FH, OFFSET, IERROR)`

INTEGER FH, IERROR

INTEGER(KIND=MPI\_OFFSET\_KIND) OFFSET

`MPI_File_get_position_shared(fh, offset, ierror)`

TYPE(MPI\_File), INTENT(IN) :: fh

INTEGER(KIND=MPI\_OFFSET\_KIND), INTENT(OUT) :: offset

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{MPI::Offset MPI::File::Get\_position\_shared() const(*binding deprecated, see Section 15.2*) }

`MPI_FILE_GET_POSITION_SHARED` returns, in `offset`, the current position of the shared file pointer in `etype` units relative to the current view.

*Advice to users.* The `offset` can be used in a future call to `MPI_FILE_SEEK_SHARED` using `whence = MPI_SEEK_SET` to return to the current position. To set the displacement to the current file pointer position, first convert `offset` into an absolute byte position using `MPI_FILE_GET_BYTE_OFFSET`, then call `MPI_FILE_SET_VIEW` with the resulting displacement. (*End of advice to users.*)

### 13.4.5 Split Collective Data Access Routines

MPI provides a restricted form of “nonblocking collective” I/O operations for all data accesses using split collective data access routines. These routines are referred to as “split” collective routines because a single collective operation is split in two: a begin routine and an end routine. The begin routine begins the operation, much like a nonblocking data access (e.g., `MPI_FILE_IREAD`). The end routine completes the operation, much like the matching test or wait (e.g., `MPI_WAIT`). As with nonblocking data access operations, the user must not use the buffer passed to a begin routine while the routine is outstanding; the operation must be completed with an end routine before it is safe to free buffers, etc.

Split collective data access operations on a file handle `fh` are subject to the semantic rules given below.

- On any MPI process, each file handle may have at most one active split collective operation at any time.
- Begin calls are collective over the group of processes that participated in the collective open and follow the ordering rules for collective calls.
- End calls are collective over the group of processes that participated in the collective open and follow the ordering rules for collective calls. Each end call matches the preceding begin call for the same collective operation. When an “end” call is made, exactly one unmatched “begin” call for the same operation must precede it.
- An implementation is free to implement any split collective data access routine using the corresponding blocking collective routine when either the begin call (e.g., `MPI_FILE_READ_ALL_BEGIN`) or the end call (e.g., `MPI_FILE_READ_ALL_END`) is issued. The begin and end calls are provided to allow the user and MPI implementation to optimize the collective operation.
- Split collective operations do not match the corresponding regular collective operation. For example, in a single collective read operation, an `MPI_FILE_READ_ALL` on one process does not match an `MPI_FILE_READ_ALL_BEGIN`/`MPI_FILE_READ_ALL_END` pair on another process.
- Split collective routines must specify a buffer in both the begin and end routines. By specifying the buffer that receives data in the end routine, we can avoid the problems described in “A Problem with [Code Movements and Register Optimization](#),” [Section 16.2.9 on page 552](#), but not all of the problems described in [Section 16.2.8 on page 551](#).
- No collective I/O operations are permitted on a file handle concurrently with a split collective access on that file handle (i.e., between the begin and end of the access). That is

```
MPI_File_read_all_begin(fh, ...);
...
MPI_File_read_all(fh, ...);
...
MPI_File_read_all_end(fh, ...);
```

is erroneous.

- In a multithreaded implementation, any split collective begin and end operation called by a process must be called from the same thread. This restriction is made to simplify the implementation in the multithreaded case. (Note that we have already disallowed having two threads begin a split collective operation on the same file handle since only one split collective operation can be active on a file handle at any time.)

The arguments for these routines have the same meaning as for the equivalent collective versions (e.g., the argument definitions for `MPI_FILE_READ_ALL_BEGIN` and `MPI_FILE_READ_ALL_END` are equivalent to the arguments for `MPI_FILE_READ_ALL`). The begin routine (e.g., `MPI_FILE_READ_ALL_BEGIN`) begins a split collective operation

that, when completed with the matching end routine (i.e., `MPI_FILE_READ_ALL_END`) produces the result as defined for the equivalent collective routine (i.e., `MPI_FILE_READ_ALL`).

For the purpose of consistency semantics (Section 13.6.1, page 500), a matched pair of split collective data access operations (e.g., `MPI_FILE_READ_ALL_BEGIN` and `MPI_FILE_READ_ALL_END`) compose a single data access.

`MPI_FILE_READ_AT_ALL_BEGIN(fh, offset, buf, count, datatype)`

IN	fh	file handle (handle)
IN	offset	file offset (integer)
OUT	buf	initial address of buffer (choice)
IN	count	number of elements in buffer (integer)
IN	datatype	datatype of each buffer element (handle)

```
int MPI_File_read_at_all_begin(MPI_File fh, MPI_Offset offset, void *buf,
                              int count, MPI_Datatype datatype)
```

```
MPI_FILE_READ_AT_ALL_BEGIN(FH, OFFSET, BUF, COUNT, DATATYPE, IERROR)
```

```
<type> BUF(*)
INTEGER FH, COUNT, DATATYPE, IERROR
INTEGER(KIND=MPI_OFFSET_KIND) OFFSET
```

```
MPI_File_read_at_all_begin(fh, offset, buf, count, datatype, ierror)
```

```
TYPE(MPI_File), INTENT(IN) :: fh
INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
TYPE(*), DIMENSION(..) :: buf
INTEGER, INTENT(IN) :: count
TYPE(MPI_Datatype), INTENT(IN) :: datatype
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{void MPI::File::Read_at_all_begin(MPI::Offset offset, void* buf,
                                   int count, const MPI::Datatype& datatype) (binding deprecated, see
                                   Section 15.2) }
```

`MPI_FILE_READ_AT_ALL_END(fh, buf, status)`

IN	fh	file handle (handle)
OUT	buf	initial address of buffer (choice)
OUT	status	status object (Status)

```
int MPI_File_read_at_all_end(MPI_File fh, void *buf, MPI_Status *status)
```

```
MPI_FILE_READ_AT_ALL_END(FH, BUF, STATUS, IERROR)
```

```
<type> BUF(*)
INTEGER FH, STATUS(MPI_STATUS_SIZE), IERROR
```



```

MPI_File_read_at_all_end(fh, buf, status, ierror)
    TYPE(MPI_File), INTENT(IN) :: fh
    TYPE(*), DIMENSION(..) :: buf
    TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::File::Read_at_all_end(void* buf, MPI::Status& status) (binding
    deprecated, see Section 15.2) }

{void MPI::File::Read_at_all_end(void* buf) (binding deprecated, see Section 15.2)
    }

```

**MPI\_FILE\_WRITE\_AT\_ALL\_BEGIN(fh, offset, buf, count, datatype)**

INOUT	fh	file handle (handle)
IN	offset	file offset (integer)
IN	buf	initial address of buffer (choice)
IN	count	number of elements in buffer (integer)
IN	datatype	datatype of each buffer element (handle)

```

int MPI_File_write_at_all_begin(MPI_File fh, MPI_Offset offset, void *buf,
    int count, MPI_Datatype datatype)

```

```

MPI_FILE_WRITE_AT_ALL_BEGIN(FH, OFFSET, BUF, COUNT, DATATYPE, IERROR)
    <type> BUF(*)
    INTEGER FH, COUNT, DATATYPE, IERROR
    INTEGER(KIND=MPI_OFFSET_KIND) OFFSET

```

```

MPI_File_write_at_all_begin(fh, offset, buf, count, datatype, ierror)
    TYPE(MPI_File), INTENT(IN) :: fh
    INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
    TYPE(*), DIMENSION(..) :: buf
    INTEGER, INTENT(IN) :: count
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

{void MPI::File::Write_at_all_begin(MPI::Offset offset, const void* buf,
    int count, const MPI::Datatype& datatype) (binding deprecated, see
    Section 15.2) }

```

**MPI\_FILE\_WRITE\_AT\_ALL\_END(fh, buf, status)**

INOUT	fh	file handle (handle)
IN	buf	initial address of buffer (choice)
OUT	status	status object (Status)

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```

1  int MPI_File_write_at_all_end(MPI_File fh, void *buf, MPI_Status *status)
2
3  MPI_FILE_WRITE_AT_ALL_END(FH, BUF, STATUS, IERROR)
4      <type> BUF(*)
5      INTEGER FH, STATUS(MPI_STATUS_SIZE), IERROR
6
7  MPI_File_write_at_all_end(fh, buf, status, ierror)
8      TYPE(MPI_File), INTENT(IN) :: fh
9      TYPE(*), DIMENSION(..) :: buf
10     TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
11     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
12
13 {void MPI::File::Write_at_all_end(const void* buf,
14     MPI::Status& status) (binding deprecated, see Section 15.2) }
15
16 {void MPI::File::Write_at_all_end(const void* buf) (binding deprecated, see
17     Section 15.2) }
18
19 MPI_FILE_READ_ALL_BEGIN(fh, buf, count, datatype)
20     INOUT    fh                file handle (handle)
21     OUT      buf               initial address of buffer (choice)
22     IN       count             number of elements in buffer (integer)
23     IN       datatype          datatype of each buffer element (handle)
24
25
26 int MPI_File_read_all_begin(MPI_File fh, void *buf, int count,
27     MPI_Datatype datatype)
28
29 MPI_FILE_READ_ALL_BEGIN(FH, BUF, COUNT, DATATYPE, IERROR)
30     <type> BUF(*)
31     INTEGER FH, COUNT, DATATYPE, IERROR
32
33 MPI_File_read_all_begin(fh, buf, count, datatype, ierror)
34     TYPE(MPI_File), INTENT(IN) :: fh
35     TYPE(*), DIMENSION(..) :: buf
36     INTEGER, INTENT(IN) :: count
37     TYPE(MPI_Datatype), INTENT(IN) :: datatype
38     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
39
40 {void MPI::File::Read_all_begin(void* buf, int count,
41     const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
42     }
43
44
45
46
47
48

```

MPI\_FILE\_READ\_ALL\_END(fh, buf, status)

INOUT	fh	file handle (handle)
OUT	buf	initial address of buffer (choice)
OUT	status	status object (Status)

int MPI\_File\_read\_all\_end(MPI\_File fh, void \*buf, MPI\_Status \*status)

MPI\_FILE\_READ\_ALL\_END(FH, BUF, STATUS, IERROR)  
 <type> BUF(\*)  
 INTEGER FH, STATUS(MPI\_STATUS\_SIZE), IERROR

MPI\_File\_read\_all\_end(fh, buf, status, ierror)  
 TYPE(MPI\_File), INTENT(IN) :: fh  
 TYPE(\*), DIMENSION(..) :: buf  
 TYPE(MPI\_Status), INTENT(OUT) :: status ! optional by overloading  
 INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::File::Read\_all\_end(void\* buf, MPI::Status& status) (*binding deprecated, see Section 15.2*) }

{void MPI::File::Read\_all\_end(void\* buf) (*binding deprecated, see Section 15.2*) }

MPI\_FILE\_WRITE\_ALL\_BEGIN(fh, buf, count, datatype)

INOUT	fh	file handle (handle)
IN	buf	initial address of buffer (choice)
IN	count	number of elements in buffer (integer)
IN	datatype	datatype of each buffer element (handle)

int MPI\_File\_write\_all\_begin(MPI\_File fh, void \*buf, int count, MPI\_Datatype datatype)

MPI\_FILE\_WRITE\_ALL\_BEGIN(FH, BUF, COUNT, DATATYPE, IERROR)  
 <type> BUF(\*)  
 INTEGER FH, COUNT, DATATYPE, IERROR

MPI\_File\_write\_all\_begin(fh, buf, count, datatype, ierror)  
 TYPE(MPI\_File), INTENT(IN) :: fh  
 TYPE(\*), DIMENSION(..) :: buf  
 INTEGER, INTENT(IN) :: count  
 TYPE(MPI\_Datatype), INTENT(IN) :: datatype  
 INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::File::Write\_all\_begin(const void\* buf, int count, const MPI::Datatype& datatype) (*binding deprecated, see Section 15.2*) }

```

1 MPI_FILE_WRITE_ALL_END(fh, buf, status)
2     INOUT    fh                file handle (handle)
3
4     IN       buf                initial address of buffer (choice)
5
6     OUT      status             status object (Status)
7
8 int MPI_File_write_all_end(MPI_File fh, void *buf, MPI_Status *status)
9 MPI_FILE_WRITE_ALL_END(FH, BUF, STATUS, IERROR)
10    <type> BUF(*)
11    INTEGER FH, STATUS(MPI_STATUS_SIZE), IERROR
12 MPI_File_write_all_end(fh, buf, status, ierror)
13    TYPE(MPI_File), INTENT(IN) :: fh
14    TYPE(*), DIMENSION(..) :: buf
15    TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
16    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
17
18 {void MPI::File::Write_all_end(const void* buf, MPI::Status& status) (binding
19     deprecated, see Section 15.2) }
20
21 {void MPI::File::Write_all_end(const void* buf) (binding deprecated, see
22     Section 15.2) }
23
24 MPI_FILE_READ_ORDERED_BEGIN(fh, buf, count, datatype)
25
26     INOUT    fh                file handle (handle)
27
28     OUT      buf                initial address of buffer (choice)
29
30     IN       count              number of elements in buffer (integer)
31
32     IN       datatype            datatype of each buffer element (handle)
33
34 int MPI_File_read_ordered_begin(MPI_File fh, void *buf, int count,
35     MPI_Datatype datatype)
36 MPI_FILE_READ_ORDERED_BEGIN(FH, BUF, COUNT, DATATYPE, IERROR)
37    <type> BUF(*)
38    INTEGER FH, COUNT, DATATYPE, IERROR
39 MPI_File_read_ordered_begin(fh, buf, count, datatype, ierror)
40    TYPE(MPI_File), INTENT(IN) :: fh
41    TYPE(*), DIMENSION(..) :: buf
42    INTEGER, INTENT(IN) :: count
43    TYPE(MPI_Datatype), INTENT(IN) :: datatype
44    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
45
46 {void MPI::File::Read_ordered_begin(void* buf, int count,
47     const MPI::Datatype& datatype) (binding deprecated, see Section 15.2)
48     }

```

MPI\_FILE\_READ\_ORDERED\_END(fh, buf, status)

INOUT	fh	file handle (handle)
OUT	buf	initial address of buffer (choice)
OUT	status	status object (Status)

int MPI\_File\_read\_ordered\_end(MPI\_File fh, void \*buf, MPI\_Status \*status)

MPI\_FILE\_READ\_ORDERED\_END(FH, BUF, STATUS, IERROR)

<type> BUF(\*)

INTEGER FH, STATUS(MPI\_STATUS\_SIZE), IERROR

MPI\_File\_read\_ordered\_end(fh, buf, status, ierror)

TYPE(MPI\_File), INTENT(IN) :: fh

TYPE(\*), DIMENSION(..) :: buf

TYPE(MPI\_Status), INTENT(OUT) :: status ! optional by overloading

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::File::Read\_ordered\_end(void\* buf, MPI::Status& status) (*binding deprecated, see Section 15.2*) }

{void MPI::File::Read\_ordered\_end(void\* buf) (*binding deprecated, see Section 15.2*) }

MPI\_FILE\_WRITE\_ORDERED\_BEGIN(fh, buf, count, datatype)

INOUT	fh	file handle (handle)
IN	buf	initial address of buffer (choice)
IN	count	number of elements in buffer (integer)
IN	datatype	datatype of each buffer element (handle)

int MPI\_File\_write\_ordered\_begin(MPI\_File fh, void \*buf, int count, MPI\_Datatype datatype)

MPI\_FILE\_WRITE\_ORDERED\_BEGIN(FH, BUF, COUNT, DATATYPE, IERROR)

<type> BUF(\*)

INTEGER FH, COUNT, DATATYPE, IERROR

MPI\_File\_write\_ordered\_begin(fh, buf, count, datatype, ierror)

TYPE(MPI\_File), INTENT(IN) :: fh

TYPE(\*), DIMENSION(..) :: buf

INTEGER, INTENT(IN) :: count

TYPE(MPI\_Datatype), INTENT(IN) :: datatype

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::File::Write\_ordered\_begin(const void\* buf, int count, const MPI::Datatype& datatype) (*binding deprecated, see Section 15.2*) }

```

1 MPI_FILE_WRITE_ORDERED_END(fh, buf, status)
2     INOUT    fh                file handle (handle)
3
4     IN       buf              initial address of buffer (choice)
5
6     OUT      status           status object (Status)
7
8 int MPI_File_write_ordered_end(MPI_File fh, void *buf, MPI_Status *status)
9 MPI_FILE_WRITE_ORDERED_END(FH, BUF, STATUS, IERROR)
10     <type> BUF(*)
11     INTEGER FH, STATUS(MPI_STATUS_SIZE), IERROR
12
13 MPI_File_write_ordered_end(fh, buf, status, ierror)
14     TYPE(MPI_File), INTENT(IN) :: fh
15     TYPE(*), DIMENSION(..) :: buf
16     TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
17     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
18
19 {void MPI::File::Write_ordered_end(const void* buf,
20     MPI::Status& status) (binding deprecated, see Section 15.2) }
21
22 {void MPI::File::Write_ordered_end(const void* buf) (binding deprecated, see
23     Section 15.2) }
24
25
26
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28
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```

## 13.5 File Interoperability

At the most basic level, file interoperability is the ability to read the information previously written to a file—not just the bits of data, but the actual information the bits represent. MPI guarantees full interoperability within a single MPI environment, and supports increased interoperability outside that environment through the external data representation (Section 13.5.2, page 494) as well as the data conversion functions (Section 13.5.3, page 496).

Interoperability within a single MPI environment (which could be considered “operability”) ensures that file data written by one MPI process can be read by any other MPI process, subject to the consistency constraints (see Section 13.6.1, page 500), provided that it would have been possible to start the two processes simultaneously and have them reside in a single MPI\_COMM\_WORLD. Furthermore, both processes must see the same data values at every absolute byte offset in the file for which data was written.

This single environment file interoperability implies that file data is accessible regardless of the number of processes.

There are three aspects to file interoperability:

- transferring the bits,
- converting between different file structures, and
- converting between different machine representations.

The first two aspects of file interoperability are beyond the scope of this standard, as both are highly machine dependent. However, transferring the bits of a file into and out of the MPI environment (e.g., by writing a file to tape) is required to be supported

by all MPI implementations. In particular, an implementation must specify how familiar operations similar to POSIX `cp`, `rm`, and `mv` can be performed on the file. Furthermore, it is expected that the facility provided maintains the correspondence between absolute byte offsets (e.g., after possible file structure conversion, the data bits at byte offset 102 in the MPI environment are at byte offset 102 outside the MPI environment). As an example, a simple off-line conversion utility that transfers and converts files between the native file system and the MPI environment would suffice, provided it maintained the offset coherence mentioned above. In a high-quality implementation of MPI, users will be able to manipulate MPI files using the same or similar tools that the native file system offers for manipulating its files.

The remaining aspect of file interoperability, converting between different machine representations, is supported by the typing information specified in the `etyp` and `filetype`. This facility allows the information in files to be shared between any two applications, regardless of whether they use MPI, and regardless of the machine architectures on which they run.

MPI supports multiple data representations: “native,” “internal,” and “external32.” An implementation may support additional data representations. MPI also supports user-defined data representations (see Section 13.5.3, page 496). The “native” and “internal” data representations are implementation dependent, while the “external32” representation is common to all MPI implementations and facilitates file interoperability. The data representation is specified in the `datarep` argument to `MPI_FILE_SET_VIEW`.

*Advice to users.* MPI is not guaranteed to retain knowledge of what data representation was used when a file is written. Therefore, to correctly retrieve file data, an MPI application is responsible for specifying the same data representation as was used to create the file. (*End of advice to users.*)

**“native”** Data in this representation is stored in a file exactly as it is in memory. The advantage of this data representation is that data precision and I/O performance are not lost in type conversions with a purely homogeneous environment. The disadvantage is the loss of transparent interoperability within a heterogeneous MPI environment.

*Advice to users.* This data representation should only be used in a homogeneous MPI environment, or when the MPI application is capable of performing the data type conversions itself. (*End of advice to users.*)

*Advice to implementors.* When implementing read and write operations on top of MPI message-passing, the message data should be typed as `MPI_BYTE` to ensure that the message routines do not perform any type conversions on the data. (*End of advice to implementors.*)

**“internal”** This data representation can be used for I/O operations in a homogeneous or heterogeneous environment; the implementation will perform type conversions if necessary. The implementation is free to store data in any format of its choice, with the restriction that it will maintain constant extents for all predefined datatypes in any one file. The environment in which the resulting file can be reused is implementation-defined and must be documented by the implementation.

*Rationale.* This data representation allows the implementation to perform I/O efficiently in a heterogeneous environment, though with implementation-defined restrictions on how the file can be reused. (*End of rationale.*)

*Advice to implementors.* Since “external32” is a superset of the functionality provided by “internal,” an implementation may choose to implement “internal” as “external32.” (*End of advice to implementors.*)

**“external32”** This data representation states that read and write operations convert all data from and to the “external32” representation defined in Section 13.5.2, page 494. The data conversion rules for communication also apply to these conversions (see Section 3.3.2, page 25-27, of the MPI-1 document). The data on the storage medium is always in this canonical representation, and the data in memory is always in the local process’s native representation.

This data representation has several advantages. First, all processes reading the file in a heterogeneous MPI environment will automatically have the data converted to their respective native representations. Second, the file can be exported from one MPI environment and imported into any other MPI environment with the guarantee that the second environment will be able to read all the data in the file.

The disadvantage of this data representation is that data precision and I/O performance may be lost in data type conversions.

*Advice to implementors.* When implementing read and write operations on top of MPI message-passing, the message data should be converted to and from the “external32” representation in the client, and sent as type MPI\_BYTE. This will avoid possible double data type conversions and the associated further loss of precision and performance. (*End of advice to implementors.*)

### 13.5.1 Datatypes for File Interoperability

If the file data representation is other than “native,” care must be taken in constructing etypes and filetypes. Any of the datatype constructor functions may be used; however, for those functions that accept displacements in bytes, the displacements must be specified in terms of their values in the file for the file data representation being used. MPI will interpret these byte displacements as is; no scaling will be done. The function MPI\_FILE\_GET\_TYPE\_EXTENT can be used to calculate the extents of datatypes in the file. For etypes and filetypes that are portable datatypes (see Section 2.4, page 11), MPI will scale any displacements in the datatypes to match the file data representation. Datatypes passed as arguments to read/write routines specify the data layout in memory; therefore, they must always be constructed using displacements corresponding to displacements in memory.

*Advice to users.* One can logically think of the file as if it were stored in the memory of a file server. The etype and filetype are interpreted as if they were defined at this file server, by the same sequence of calls used to define them at the calling process. If the data representation is “native,” then this logical file server runs on the same architecture as the calling process, so that these types define the same data layout on the file as they would define in the memory of the calling process. If the etype



and `filetype` are portable datatypes, then the data layout defined in the file is the same as would be defined in the calling process memory, up to a scaling factor. The routine `MPI_FILE_GET_FILE_EXTENT` can be used to calculate this scaling factor. Thus, two equivalent, portable datatypes will define the same data layout in the file, even in a heterogeneous environment with “internal”, “external32”, or user defined data representations. Otherwise, the `etype` and `filetype` must be constructed so that their `typemap` and `extent` are the same on any architecture. This can be achieved if they have an explicit upper bound and lower bound (defined either using `MPI_LB` and `MPI_UB` markers, or using `MPI_TYPE_CREATE_RESIZED`). This condition must also be fulfilled by any datatype that is used in the construction of the `etype` and `filetype`, if this datatype is replicated contiguously, either explicitly, by a call to `MPI_TYPE_CONTIGUOUS`, or implicitly, by a `blocklength` argument that is greater than one. If an `etype` or `filetype` is not portable, and has a `typemap` or `extent` that is architecture dependent, then the data layout specified by it on a file is implementation dependent.

File data representations other than “native” may be different from corresponding data representations in memory. Therefore, for these file data representations, it is important not to use hardwired byte offsets for file positioning, including the initial displacement that specifies the view. When a portable datatype (see Section 2.4, page 11) is used in a data access operation, any holes in the datatype are scaled to match the data representation. However, note that this technique only works when all the processes that created the file view build their etypes from the same predefined datatypes. For example, if one process uses an `etype` built from `MPI_INT` and another uses an `etype` built from `MPI_FLOAT`, the resulting views may be nonportable because the relative sizes of these types may differ from one data representation to another. *(End of advice to users.)*

`MPI_FILE_GET_TYPE_EXTENT(fh, datatype, extent)`

IN	<code>fh</code>	file handle (handle)
IN	<code>datatype</code>	datatype (handle)
OUT	<code>extent</code>	datatype extent (integer)

```
int MPI_File_get_type_extent(MPI_File fh, MPI_Datatype datatype,
                             MPI_Aint *extent)
```

```
MPI_FILE_GET_TYPE_EXTENT(FH, DATATYPE, EXTENT, IERROR)
    INTEGER FH, DATATYPE, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) EXTENT
```

```
MPI_File_get_type_extent(fh, datatype, extent, ierror)
    TYPE(MPI_File), INTENT(IN) :: fh
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: extent
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

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```

1 {MPI::Aint MPI::File::Get_type_extent(const MPI::Datatype& datatype)
2     const(binding deprecated, see Section 15.2) }
3

```

Returns the extent of `datatype` in the file `fh`. This extent will be the same for all processes accessing the file `fh`. If the current view uses a user-defined data representation (see Section 13.5.3, page 496), MPI uses the `dtype_file_extent_fn` callback to calculate the extent.

*Advice to implementors.* In the case of user-defined data representations, the extent of a derived datatype can be calculated by first determining the extents of the predefined datatypes in this derived datatype using `dtype_file_extent_fn` (see Section 13.5.3, page 496). (*End of advice to implementors.*)

### 13.5.2 External Data Representation: “external32”

All MPI implementations are required to support the data representation defined in this section. Support of optional datatypes (e.g., `MPI_INTEGER2`) is not required.

All floating point values are in big-endian IEEE format [31] of the appropriate size. Floating point values are represented by one of three IEEE formats. These are the IEEE “Single,” “Double,” and “Double Extended” formats, requiring 4, 8 and 16 bytes of storage, respectively. For the IEEE “Double Extended” formats, MPI specifies a Format Width of 16 bytes, with 15 exponent bits, bias = +16383, 112 fraction bits, and an encoding analogous to the “Double” format. All integral values are in two’s complement big-endian format. Big-endian means most significant byte at lowest address byte. For C `_Bool`, Fortran `LOGICAL` and C++ `bool`, 0 implies false and nonzero implies true. C `float _Complex`, `double _Complex` and long double `_Complex` as well as Fortran `COMPLEX` and `DOUBLE COMPLEX` are represented by a pair of floating point format values for the real and imaginary components. Characters are in ISO 8859-1 format [32]. Wide characters (of type `MPI_WCHAR`) are in Unicode format [55].

All signed numerals (e.g., `MPI_INT`, `MPI_REAL`) have the sign bit at the most significant bit. `MPI_COMPLEX` and `MPI_DOUBLE_COMPLEX` have the sign bit of the real and imaginary parts at the most significant bit of each part.

According to IEEE specifications [31], the “NaN” (not a number) is system dependent. It should not be interpreted within MPI as anything other than “NaN.”

*Advice to implementors.* The MPI treatment of “NaN” is similar to the approach used in XDR (see <ftp://ds.internic.net/rfc/rfc1832.txt>). (*End of advice to implementors.*)

All data is byte aligned, regardless of type. All data items are stored contiguously in the file (if the file view is contiguous).

*Advice to implementors.* All bytes of `LOGICAL` and `bool` must be checked to determine the value. (*End of advice to implementors.*)

*Advice to users.* The type `MPI_PACKED` is treated as bytes and is not converted. The user should be aware that `MPI_PACK` has the option of placing a header in the beginning of the pack buffer. (*End of advice to users.*)

The size of the predefined datatypes returned from `MPI_TYPE_CREATE_F90_REAL`, `MPI_TYPE_CREATE_F90_COMPLEX`, and `MPI_TYPE_CREATE_F90_INTEGER` are defined in Section 16.2.18, page 573.

Type	Length	Optional Type	Length
MPI_PACKED	1	MPI_INTEGER1	1
MPI_BYTE	1	MPI_INTEGER2	2
MPI_CHAR	1	MPI_INTEGER4	4
MPI_UNSIGNED_CHAR	1	MPI_INTEGER8	8
MPI_SIGNED_CHAR	1	MPI_INTEGER16	16
MPI_WCHAR	2		
MPI_SHORT	2	MPI_REAL2	2
MPI_UNSIGNED_SHORT	2	MPI_REAL4	4
MPI_INT	4	MPI_REAL8	8
MPI_UNSIGNED	4	MPI_REAL16	16
MPI_LONG	4		
MPI_UNSIGNED_LONG	4	MPI_COMPLEX4	2*2
MPI_LONG_LONG_INT	8	MPI_COMPLEX8	2*4
MPI_UNSIGNED_LONG_LONG	8	MPI_COMPLEX16	2*8
MPI_FLOAT	4	MPI_COMPLEX32	2*16
MPI_DOUBLE	8		
MPI_LONG_DOUBLE	16		
MPI_C_BOOL	4		
MPI_INT8_T	1		
MPI_INT16_T	2		
MPI_INT32_T	4		
MPI_INT64_T	8		
MPI_UINT8_T	1		
MPI_UINT16_T	2		
MPI_UINT32_T	4		
MPI_UINT64_T	8		
MPI_AINT	8		
MPI_OFFSET	8		
MPI_C_COMPLEX	2*4		
MPI_C_FLOAT_COMPLEX	2*4		
MPI_C_DOUBLE_COMPLEX	2*8		
MPI_C_LONG_DOUBLE_COMPLEX	2*16		
MPI_CHARACTER	1		
MPI_LOGICAL	4		
MPI_INTEGER	4		
MPI_REAL	4		
MPI_DOUBLE_PRECISION	8		
MPI_COMPLEX	2*4		
MPI_DOUBLE_COMPLEX	2*8		

Table 13.2: “external32” sizes of predefined datatypes

*Advice to implementors.* When converting a larger size integer to a smaller size integer, only the less significant bytes are moved. Care must be taken to preserve the sign bit value. This allows no conversion errors if the data range is within the range of the smaller size integer. (*End of advice to implementors.*)

Table 13.2 specifies the sizes of predefined datatypes in “external32” format.

### 13.5.3 User-Defined Data Representations

There are two situations that cannot be handled by the required representations:

1. a user wants to write a file in a representation unknown to the implementation, and
2. a user wants to read a file written in a representation unknown to the implementation.

User-defined data representations allow the user to insert a third party converter into the I/O stream to do the data representation conversion.

```
MPI_REGISTER_DATAREP(datarep, read_conversion_fn, write_conversion_fn,
                      dtype_file_extent_fn, extra_state)
```

IN	datarep	data representation identifier (string)
IN	read_conversion_fn	function invoked to convert from file representation to native representation (function)
IN	write_conversion_fn	function invoked to convert from native representation to file representation (function)
IN	dtype_file_extent_fn	function invoked to get the extent of a datatype as represented in the file (function)
IN	extra_state	extra state

```
int MPI_Register_datarep(char *datarep,
                        MPI_Datarep_conversion_function *read_conversion_fn,
                        MPI_Datarep_conversion_function *write_conversion_fn,
                        MPI_Datarep_extent_function *dtype_file_extent_fn,
                        void *extra_state)

MPI_REGISTER_DATAREP(DATAREP, READ_CONVERSION_FN, WRITE_CONVERSION_FN,
                     DTYPE_FILE_EXTENT_FN, EXTRA_STATE, IERROR)
CHARACTER*(*) DATAREP
EXTERNAL READ_CONVERSION_FN, WRITE_CONVERSION_FN, DTYPE_FILE_EXTENT_FN
INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE
INTEGER IERROR
```

```
MPI_Register_datarep(datarep, read_conversion_fn, write_conversion_fn,
                     dtype_file_extent_fn, extra_state, ierror)
CHARACTER(LEN=*) INTENT(IN) :: datarep
EXTERNAL :: read_conversion_fn, write_conversion_fn
PROCEDURE(MPI_Datarep_extent_function) :: dtype_file_extent_fn
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: extra_state
```

```

    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
{void MPI::Register_datarep(const char* datarep,
    MPI::Datarep_conversion_function* read_conversion_fn,
    MPI::Datarep_conversion_function* write_conversion_fn,
    MPI::Datarep_extent_function* dtype_file_extent_fn,
    void* extra_state) (binding deprecated, see Section 15.2) }
```

The call associates `read_conversion_fn`, `write_conversion_fn`, and `dtype_file_extent_fn` with the data representation identifier `datarep`. `datarep` can then be used as an argument to `MPI_FILE_SET_VIEW`, causing subsequent data access operations to call the conversion functions to convert all data items accessed between file data representation and native representation. `MPI_REGISTER_DATAREP` is a local operation and only registers the data representation for the calling MPI process. If `datarep` is already defined, an error in the error class `MPI_ERR_DUP_DATAREP` is raised using the default file error handler (see Section 13.7, page 510). The length of a data representation string is limited to the value of `MPI_MAX_DATAREP_STRING`. `MPI_MAX_DATAREP_STRING` must have a value of at least 64. No routines are provided to delete data representations and free the associated resources; it is not expected that an application will generate them in significant numbers.

#### Extent Callback

```

typedef int MPI_Datarep_extent_function(MPI_Datatype datatype,
    MPI_Aint *file_extent, void *extra_state);

SUBROUTINE DATAREP_EXTENT_FUNCTION(DATATYPE, EXTENT, EXTRA_STATE, IERROR)
    INTEGER DATATYPE, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) EXTENT, EXTRA_STATE
```

#### ABSTRACT INTERFACE

```

    SUBROUTINE MPI_Datarep_extent_function(datatype, extent, extra_state,
    ierror)
        TYPE(MPI_Datatype) :: datatype
        INTEGER :: ierror
        INTEGER(KIND=MPI_ADDRESS_KIND) :: extent, extra_state

{typedef void MPI::Datarep_extent_function(const MPI::Datatype& datatype,
    MPI::Aint& file_extent, void* extra_state); (binding deprecated,
    see Section 15.2)}
```

The function `dtype_file_extent_fn` must return, in `file_extent`, the number of bytes required to store `datatype` in the file representation. The function is passed, in `extra_state`, the argument that was passed to the `MPI_REGISTER_DATAREP` call. MPI will only call this routine with predefined datatypes employed by the user.

#### Datarep Conversion Functions

```

typedef int MPI_Datarep_conversion_function(void *userbuf,
    MPI_Datatype datatype, int count, void *filebuf,
    MPI_Offset position, void *extra_state);
```

To reduce problems with the choice buffer arguments, implicit interfaces are used with all three Fortran support methods; the first one with the `mpi` module or `mpif.h`, the second one with `mpi_f08`.

```

SUBROUTINE DATAREP_CONVERSION_FUNCTION(USERBUF, DATATYPE, COUNT, FILEBUF,
    POSITION, EXTRA_STATE, IERROR)
    <TYPE> USERBUF(*), FILEBUF(*)
    INTEGER COUNT, DATATYPE, IERROR
    INTEGER(KIND=MPI_OFFSET_KIND) POSITION
    INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE

SUBROUTINE DATAREP_CONVERSION_FUNCTION(userbuf, datatype, count, filebuf,
    position, extra_state, ierror)
    <TYPE> userbuf(*), filebuf(*)
    TYPE(MPI_Datatype) datatype
    INTEGER count, ierror
    INTEGER(KIND=MPI_OFFSET_KIND) position
    INTEGER(KIND=MPI_ADDRESS_KIND) extra_state

{typedef void MPI::Datarep_conversion_function(void* userbuf,
    MPI::Datatype& datatype, int count, void* filebuf,
    MPI::Offset position, void* extra_state); (binding deprecated, see
    Section 15.2)}

```

The function `read_conversion_fn` must convert from file data representation to native representation. Before calling this routine, MPI allocates and fills `filebuf` with `count` contiguous data items. The type of each data item matches the corresponding entry for the predefined datatype in the type signature of `datatype`. The function is passed, in `extra_state`, the argument that was passed to the `MPI_REGISTER_DATAREP` call. The function must copy all `count` data items from `filebuf` to `userbuf` in the distribution described by `datatype`, converting each data item from file representation to native representation. `datatype` will be equivalent to the datatype that the user passed to the read function. If the size of `datatype` is less than the size of the `count` data items, the conversion function must treat `datatype` as being contiguously tiled over the `userbuf`. The conversion function must begin storing converted data at the location in `userbuf` specified by `position` into the (tiled) `datatype`.

*Advice to users.* Although the conversion functions have similarities to `MPI_PACK` and `MPI_UNPACK`, one should note the differences in the use of the arguments `count` and `position`. In the conversion functions, `count` is a count of data items (i.e., count of typemap entries of `datatype`), and `position` is an index into this typemap. In `MPI_PACK`, `incount` refers to the number of whole datatypes, and `position` is a number of bytes. (*End of advice to users.*)

*Advice to implementors.* A converted read operation could be implemented as follows:

1. Get file extent of all data items
2. Allocate a `filebuf` large enough to hold all `count` data items
3. Read data from file into `filebuf`
4. Call `read_conversion_fn` to convert data and place it into `userbuf`

## 5. Deallocate filebuf

*(End of advice to implementors.)*

If MPI cannot allocate a buffer large enough to hold all the data to be converted from a read operation, it may call the conversion function repeatedly using the same `datatype` and `userbuf`, and reading successive chunks of data to be converted in `filebuf`. For the first call (and in the case when all the data to be converted fits into `filebuf`), MPI will call the function with `position` set to zero. Data converted during this call will be stored in the `userbuf` according to the first `count` data items in `datatype`. Then in subsequent calls to the conversion function, MPI will increment the value in `position` by the `count` of items converted in the previous call, and the `userbuf` pointer will be unchanged.

*Rationale.* Passing the conversion function a position and one datatype for the transfer allows the conversion function to decode the datatype only once and cache an internal representation of it on the datatype. Then on subsequent calls, the conversion function can use the `position` to quickly find its place in the datatype and continue storing converted data where it left off at the end of the previous call. *(End of rationale.)*

*Advice to users.* Although the conversion function may usefully cache an internal representation on the datatype, it should not cache any state information specific to an ongoing conversion operation, since it is possible for the same datatype to be used concurrently in multiple conversion operations. *(End of advice to users.)*

The function `write_conversion_fn` must convert from native representation to file data representation. Before calling this routine, MPI allocates `filebuf` of a size large enough to hold `count` contiguous data items. The type of each data item matches the corresponding entry for the predefined datatype in the type signature of `datatype`. The function must copy `count` data items from `userbuf` in the distribution described by `datatype`, to a contiguous distribution in `filebuf`, converting each data item from native representation to file representation. If the size of `datatype` is less than the size of `count` data items, the conversion function must treat `datatype` as being contiguously tiled over the `userbuf`.

The function must begin copying at the location in `userbuf` specified by `position` into the (tiled) `datatype`. `datatype` will be equivalent to the datatype that the user passed to the write function. The function is passed, in `extra_state`, the argument that was passed to the `MPI_REGISTER_DATAREP` call.

The predefined constant `MPI_CONVERSION_FN_NULL` may be used as either `write_conversion_fn` or `read_conversion_fn`. In that case, MPI will not attempt to invoke `write_conversion_fn` or `read_conversion_fn`, respectively, but will perform the requested data access using the native data representation.

An MPI implementation must ensure that all data accessed is converted, either by using a `filebuf` large enough to hold all the requested data items or else by making repeated calls to the conversion function with the same `datatype` argument and appropriate values for `position`.

An implementation will only invoke the callback routines in this section (`read_conversion_fn`, `write_conversion_fn`, and `dtype_file_extent_fn`) when one of the read or write routines in Section 13.4, page 461, or `MPI_FILE_GET_TYPE_EXTENT` is called by the user. `dtype_file_extent_fn` will only be passed predefined datatypes employed by the



user. The conversion functions will only be passed datatypes equivalent to those that the user has passed to one of the routines noted above.

The conversion functions must be reentrant. User defined data representations are restricted to use byte alignment for all types. Furthermore, it is erroneous for the conversion functions to call any collective routines or to free `datatype`.

The conversion functions should return an error code. If the returned error code has a value other than `MPI_SUCCESS`, the implementation will raise an error in the class `MPI_ERR_CONVERSION`.

### 13.5.4 Matching Data Representations

It is the user's responsibility to ensure that the data representation used to read data from a file is *compatible* with the data representation that was used to write that data to the file.

In general, using the same data representation name when writing and reading a file does not guarantee that the representation is compatible. Similarly, using different representation names on two different implementations may yield compatible representations.

Compatibility can be obtained when "external32" representation is used, although precision may be lost and the performance may be less than when "native" representation is used. Compatibility is guaranteed using "external32" provided at least one of the following conditions is met.

- The data access routines directly use types enumerated in Section 13.5.2, page 494, that are supported by all implementations participating in the I/O. The predefined type used to write a data item must also be used to read a data item.
- In the case of Fortran 90 programs, the programs participating in the data accesses obtain compatible datatypes using MPI routines that specify precision and/or range (Section 16.2.18, page 569).
- For any given data item, the programs participating in the data accesses use compatible predefined types to write and read the data item.

User-defined data representations may be used to provide an implementation compatibility with another implementation's "native" or "internal" representation.

*Advice to users.* Section 16.2.18, page 569, defines routines that support the use of matching datatypes in heterogeneous environments and contains examples illustrating their use. (*End of advice to users.*)

## 13.6 Consistency and Semantics

### 13.6.1 File Consistency

Consistency semantics define the outcome of multiple accesses to a single file. All file accesses in MPI are relative to a specific file handle created from a collective open. MPI provides three levels of consistency: sequential consistency among all accesses using a single file handle, sequential consistency among all accesses using file handles created from a single collective open with atomic mode enabled, and user-imposed consistency among accesses other than the above. Sequential consistency means the behavior of a set of operations will



be as if the operations were performed in some serial order consistent with program order; each access appears atomic, although the exact ordering of accesses is unspecified. User-imposed consistency may be obtained using program order and calls to `MPI_FILE_SYNC`.

Let  $FH_1$  be the set of file handles created from one particular collective open of the file  $FOO$ , and  $FH_2$  be the set of file handles created from a different collective open of  $FOO$ . Note that nothing restrictive is said about  $FH_1$  and  $FH_2$ : the sizes of  $FH_1$  and  $FH_2$  may be different, the groups of processes used for each open may or may not intersect, the file handles in  $FH_1$  may be destroyed before those in  $FH_2$  are created, etc. Consider the following three cases: a single file handle (e.g.,  $fh_1 \in FH_1$ ), two file handles created from a single collective open (e.g.,  $fh_{1a} \in FH_1$  and  $fh_{1b} \in FH_1$ ), and two file handles from different collective opens (e.g.,  $fh_1 \in FH_1$  and  $fh_2 \in FH_2$ ).

For the purpose of consistency semantics, a matched pair (Section 13.4.5, page 482) of split collective data access operations (e.g., `MPI_FILE_READ_ALL_BEGIN` and `MPI_FILE_READ_ALL_END`) compose a single data access operation. Similarly, a non-blocking data access routine (e.g., `MPI_FILE_IREAD`) and the routine which completes the request (e.g., `MPI_WAIT`) also compose a single data access operation. For all cases below, these data access operations are subject to the same constraints as blocking data access operations.

*Advice to users.* For an `MPI_FILE_IREAD` and `MPI_WAIT` pair, the operation begins when `MPI_FILE_IREAD` is called and ends when `MPI_WAIT` returns. (*End of advice to users.*)

Assume that  $A_1$  and  $A_2$  are two data access operations. Let  $D_1$  ( $D_2$ ) be the set of absolute byte displacements of every byte accessed in  $A_1$  ( $A_2$ ). The two data accesses *overlap* if  $D_1 \cap D_2 \neq \emptyset$ . The two data accesses *conflict* if they overlap and at least one is a write access.

Let  $SEQ_{fh}$  be a sequence of file operations on a single file handle, bracketed by `MPI_FILE_SYNC`s on that file handle. (Both opening and closing a file implicitly perform an `MPI_FILE_SYNC`.)  $SEQ_{fh}$  is a “write sequence” if any of the data access operations in the sequence are writes or if any of the file manipulation operations in the sequence change the state of the file (e.g., `MPI_FILE_SET_SIZE` or `MPI_FILE_PREALLOCATE`). Given two sequences,  $SEQ_1$  and  $SEQ_2$ , we say they are not *concurrent* if one sequence is guaranteed to completely precede the other (temporally).

The requirements for guaranteeing sequential consistency among all accesses to a particular file are divided into the three cases given below. If any of these requirements are not met, then the value of all data in that file is implementation dependent.

**Case 1:**  $fh_1 \in FH_1$  All operations on  $fh_1$  are sequentially consistent if atomic mode is set. If nonatomic mode is set, then all operations on  $fh_1$  are sequentially consistent if they are either nonconcurrent, nonconflicting, or both.

**Case 2:**  $fh_{1a} \in FH_1$  and  $fh_{1b} \in FH_1$  Assume  $A_1$  is a data access operation using  $fh_{1a}$ , and  $A_2$  is a data access operation using  $fh_{1b}$ . If for any access  $A_1$ , there is no access  $A_2$  that conflicts with  $A_1$ , then MPI guarantees sequential consistency.

However, unlike POSIX semantics, the default MPI semantics for conflicting accesses do not guarantee sequential consistency. If  $A_1$  and  $A_2$  conflict, sequential consistency can be guaranteed by either enabling atomic mode via the `MPI_FILE_SET_ATOMICITY` routine, or meeting the condition described in Case 3 below.

Case 3:  $fh_1 \in FH_1$  and  $fh_2 \in FH_2$  Consider access to a single file using file handles from distinct collective opens. In order to guarantee sequential consistency, `MPI_FILE_SYNC` must be used (both opening and closing a file implicitly perform an `MPI_FILE_SYNC`).

Sequential consistency is guaranteed among accesses to a single file if for any write sequence  $SEQ_1$  to the file, there is no sequence  $SEQ_2$  to the file which is *concurrent* with  $SEQ_1$ . To guarantee sequential consistency when there are write sequences, `MPI_FILE_SYNC` must be used together with a mechanism that guarantees nonconcurrency of the sequences.

See the examples in Section 13.6.10, page 506, for further clarification of some of these consistency semantics.

`MPI_FILE_SET_ATOMICITY(fh, flag)`

INOUT	fh	file handle (handle)
IN	flag	true to set atomic mode, false to set nonatomic mode (logical)

`int MPI_File_set_atomicity(MPI_File fh, int flag)`

`MPI_FILE_SET_ATOMICITY(FH, FLAG, IERROR)`

INTEGER FH, IERROR

LOGICAL FLAG

`MPI_File_set_atomicity(fh, flag, ierror)`

TYPE(MPI\_File), INTENT(IN) :: fh

LOGICAL, INTENT(IN) :: flag

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

`{void MPI::File::Set_atomicity(bool flag) (binding deprecated, see Section 15.2) }`

Let  $FH$  be the set of file handles created by one collective open. The consistency semantics for data access operations using  $FH$  is set by collectively calling `MPI_FILE_SET_ATOMICITY` on  $FH$ . `MPI_FILE_SET_ATOMICITY` is collective; all processes in the group must pass identical values for `fh` and `flag`. If `flag` is true, atomic mode is set; if `flag` is false, nonatomic mode is set.

Changing the consistency semantics for an open file only affects new data accesses. All completed data accesses are guaranteed to abide by the consistency semantics in effect during their execution. Nonblocking data accesses and split collective operations that have not completed (e.g., via `MPI_WAIT`) are only guaranteed to abide by nonatomic mode consistency semantics.

*Advice to implementors.* Since the semantics guaranteed by atomic mode are stronger than those guaranteed by nonatomic mode, an implementation is free to adhere to the more stringent atomic mode semantics for outstanding requests. (*End of advice to implementors.*)

MPI\_FILE\_GET\_ATOMICITY(fh, flag)

IN fh file handle (handle)  
OUT flag true if atomic mode, false if nonatomic mode (logical)

int MPI\_File\_get\_atomicity(MPI\_File fh, int \*flag)

MPI\_FILE\_GET\_ATOMICITY(FH, FLAG, IERROR)

INTEGER FH, IERROR

LOGICAL FLAG

MPI\_File\_get\_atomicity(fh, flag, ierror)

TYPE(MPI\_File), INTENT(IN) :: fh

LOGICAL, INTENT(OUT) :: flag

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{bool MPI::File::Get\_atomicity() const(*binding deprecated, see Section 15.2*) }

MPI\_FILE\_GET\_ATOMICITY returns the current consistency semantics for data access operations on the set of file handles created by one collective open. If flag is true, atomic mode is enabled; if flag is false, nonatomic mode is enabled.

MPI\_FILE\_SYNC(fh)

INOUT fh file handle (handle)

int MPI\_File\_sync(MPI\_File fh)

MPI\_FILE\_SYNC(FH, IERROR)

INTEGER FH, IERROR

MPI\_File\_sync(fh, ierror)

TYPE(MPI\_File), INTENT(IN) :: fh

INTEGER, OPTIONAL, INTENT(OUT) :: ierror

{void MPI::File::Sync() (*binding deprecated, see Section 15.2*) }

Calling MPI\_FILE\_SYNC with fh causes all previous writes to fh by the calling process to be transferred to the storage device. If other processes have made updates to the storage device, then all such updates become visible to subsequent reads of fh by the calling process. MPI\_FILE\_SYNC may be necessary to ensure sequential consistency in certain cases (see above).

MPI\_FILE\_SYNC is a collective operation.

The user is responsible for ensuring that all nonblocking requests and split collective operations on fh have been completed before calling MPI\_FILE\_SYNC—otherwise, the call to MPI\_FILE\_SYNC is erroneous.

### 13.6.2 Random Access vs. Sequential Files

MPI distinguishes ordinary random access files from sequential stream files, such as pipes and tape files. Sequential stream files must be opened with the MPI\_MODE\_SEQUENTIAL flag set in the amode. For these files, the only permitted data access operations are shared

file pointer reads and writes. Filetypes and etypes with holes are erroneous. In addition, the notion of file pointer is not meaningful; therefore, calls to `MPI_FILE_SEEK_SHARED` and `MPI_FILE_GET_POSITION_SHARED` are erroneous, and the pointer update rules specified for the data access routines do not apply. The amount of data accessed by a data access operation will be the amount requested unless the end of file is reached or an error is raised.

*Rationale.* This implies that reading on a pipe will always wait until the requested amount of data is available or until the process writing to the pipe has issued an end of file. (*End of rationale.*)

Finally, for some sequential files, such as those corresponding to magnetic tapes or streaming network connections, writes to the file may be destructive. In other words, a write may act as a truncate (a `MPI_FILE_SET_SIZE` with size set to the current position) followed by the write.

### 13.6.3 Progress

The progress rules of MPI are both a promise to users and a set of constraints on implementors. In cases where the progress rules restrict possible implementation choices more than the interface specification alone, the progress rules take precedence.

All blocking routines must complete in finite time unless an exceptional condition (such as resource exhaustion) causes an error.

Nonblocking data access routines inherit the following progress rule from nonblocking point to point communication: a nonblocking write is equivalent to a nonblocking send for which a receive is eventually posted, and a nonblocking read is equivalent to a nonblocking receive for which a send is eventually posted.

Finally, an implementation is free to delay progress of collective routines until all processes in the group associated with the collective call have invoked the routine. Once all processes in the group have invoked the routine, the progress rule of the equivalent noncollective routine must be followed.

### 13.6.4 Collective File Operations

Collective file operations are subject to the same restrictions as collective communication operations. For a complete discussion, please refer to the semantics set forth in Section 5.13 on page 216.

Collective file operations are collective over a dup of the communicator used to open the file—this duplicate communicator is implicitly specified via the file handle argument. Different processes can pass different values for other arguments of a collective routine unless specified otherwise.

### 13.6.5 Type Matching

The type matching rules for I/O mimic the type matching rules for communication with one exception: if etype is `MPI_BYTE`, then this matches any datatype in a data access operation. In general, the etype of data items written must match the etype used to read the items, and for each data access operation, the current etype must also match the type declaration of the data access buffer.

*Advice to users.* In most cases, use of MPI\_BYTE as a wild card will defeat the file interoperability features of MPI. File interoperability can only perform automatic conversion between heterogeneous data representations when the exact datatypes accessed are explicitly specified. (*End of advice to users.*)

### 13.6.6 Miscellaneous Clarifications

Once an I/O routine completes, it is safe to free any opaque objects passed as arguments to that routine. For example, the `comm` and `info` used in an `MPI_FILE_OPEN`, or the `etype` and `filetype` used in an `MPI_FILE_SET_VIEW`, can be freed without affecting access to the file. Note that for nonblocking routines and split collective operations, the operation must be completed before it is safe to reuse data buffers passed as arguments.

As in communication, datatypes must be committed before they can be used in file manipulation or data access operations. For example, the `etype` and `filetype` must be committed before calling `MPI_FILE_SET_VIEW`, and the `datatype` must be committed before calling `MPI_FILE_READ` or `MPI_FILE_WRITE`.

### 13.6.7 MPI\_Offset Type

`MPI_Offset` is an integer type of size sufficient to represent the size (in bytes) of the largest file supported by MPI. Displacements and offsets are always specified as values of type `MPI_Offset`.

In Fortran, the corresponding integer is an integer `with kind parameter MPI_OFFSET_KIND`, which is defined in the `mpi_f08` module, the `mpi` module and the `mpif.h` include file.

In Fortran 77 environments that do not support `KIND` parameters, `MPI_Offset` arguments should be declared as an `INTEGER` of suitable size. The language interoperability implications for `MPI_Offset` are similar to those for addresses (see Section 16.3, page 577).

### 13.6.8 Logical vs. Physical File Layout

MPI specifies how the data should be laid out in a virtual file structure (the view), not how that file structure is to be stored on one or more disks. Specification of the physical file structure was avoided because it is expected that the mapping of files to disks will be system specific, and any specific control over file layout would therefore restrict program portability. However, there are still cases where some information may be necessary to optimize file layout. This information can be provided as *hints* specified via *info* when a file is created (see Section 13.2.8, page 455).

### 13.6.9 File Size

The size of a file may be increased by writing to the file after the current end of file. The size may also be changed by calling MPI *size changing* routines, such as `MPI_FILE_SET_SIZE`. A call to a size changing routine does not necessarily change the file size. For example, calling `MPI_FILE_PREALLOCATE` with a size less than the current size does not change the size.

Consider a set of bytes that has been written to a file since the most recent call to a size changing routine, or since `MPI_FILE_OPEN` if no such routine has been called. Let the *high byte* be the byte in that set with the largest displacement. The file size is the larger of

- One plus the displacement of the high byte.
- The size immediately after the size changing routine, or `MPI_FILE_OPEN`, returned.

When applying consistency semantics, calls to `MPI_FILE_SET_SIZE` and `MPI_FILE_PREALLOCATE` are considered writes to the file (which conflict with operations that access bytes at displacements between the old and new file sizes), and `MPI_FILE_GET_SIZE` is considered a read of the file (which overlaps with all accesses to the file).

*Advice to users.* Any sequence of operations containing the collective routines `MPI_FILE_SET_SIZE` and `MPI_FILE_PREALLOCATE` is a write sequence. As such, sequential consistency in nonatomic mode is not guaranteed unless the conditions in Section 13.6.1, page 500, are satisfied. (*End of advice to users.*)

File pointer update semantics (i.e., file pointers are updated by the amount accessed) are only guaranteed if file size changes are sequentially consistent.

*Advice to users.* Consider the following example. Given two operations made by separate processes to a file containing 100 bytes: an `MPI_FILE_READ` of 10 bytes and an `MPI_FILE_SET_SIZE` to 0 bytes. If the user does not enforce sequential consistency between these two operations, the file pointer may be updated by the amount requested (10 bytes) even if the amount accessed is zero bytes. (*End of advice to users.*)

### 13.6.10 Examples

The examples in this section illustrate the application of the MPI consistency and semantics guarantees. These address

- conflicting accesses on file handles obtained from a single collective open, and
- all accesses on file handles obtained from two separate collective opens.

The simplest way to achieve consistency for conflicting accesses is to obtain sequential consistency by setting atomic mode. For the code below, process 1 will read either 0 or 10 integers. If the latter, every element of `b` will be 5. If nonatomic mode is set, the results of the read are undefined.

```
/* Process 0 */
int i, a[10] ;
int TRUE = 1;

for ( i=0;i<10;i++)
    a[i] = 5 ;

MPI_File_open( MPI_COMM_WORLD, "workfile",
               MPI_MODE_RDWR | MPI_MODE_CREATE, MPI_INFO_NULL, &fh0 ) ;
MPI_File_set_view( fh0, 0, MPI_INT, MPI_INT, "native", MPI_INFO_NULL ) ;
MPI_File_set_atomicity( fh0, TRUE ) ;
MPI_File_write_at(fh0, 0, a, 10, MPI_INT, &status) ;
/* MPI_Barrier( MPI_COMM_WORLD ) ; */
```

```

/* Process 1 */
int b[10] ;
int TRUE = 1;
MPI_File_open( MPI_COMM_WORLD, "workfile",
               MPI_MODE_RDWR | MPI_MODE_CREATE, MPI_INFO_NULL, &fh1 ) ;
MPI_File_set_view( fh1, 0, MPI_INT, MPI_INT, "native", MPI_INFO_NULL ) ;
MPI_File_set_atomicity( fh1, TRUE ) ;
/* MPI_Barrier( MPI_COMM_WORLD ) ; */
MPI_File_read_at(fh1, 0, b, 10, MPI_INT, &status) ;

```

A user may guarantee that the write on process 0 precedes the read on process 1 by imposing temporal order with, for example, calls to `MPI_BARRIER`.

*Advice to users.* Routines other than `MPI_BARRIER` may be used to impose temporal order. In the example above, process 0 could use `MPI_SEND` to send a 0 byte message, received by process 1 using `MPI_RECV`. (*End of advice to users.*)

Alternatively, a user can impose consistency with nonatomic mode set:

```

/* Process 0 */
int i, a[10] ;
for ( i=0;i<10;i++)
    a[i] = 5 ;

MPI_File_open( MPI_COMM_WORLD, "workfile",
               MPI_MODE_RDWR | MPI_MODE_CREATE, MPI_INFO_NULL, &fh0 ) ;
MPI_File_set_view( fh0, 0, MPI_INT, MPI_INT, "native", MPI_INFO_NULL ) ;
MPI_File_write_at(fh0, 0, a, 10, MPI_INT, &status ) ;
MPI_File_sync( fh0 ) ;
MPI_Barrier( MPI_COMM_WORLD ) ;
MPI_File_sync( fh0 ) ;

/* Process 1 */
int b[10] ;
MPI_File_open( MPI_COMM_WORLD, "workfile",
               MPI_MODE_RDWR | MPI_MODE_CREATE, MPI_INFO_NULL, &fh1 ) ;
MPI_File_set_view( fh1, 0, MPI_INT, MPI_INT, "native", MPI_INFO_NULL ) ;
MPI_File_sync( fh1 ) ;
MPI_Barrier( MPI_COMM_WORLD ) ;
MPI_File_sync( fh1 ) ;
MPI_File_read_at(fh1, 0, b, 10, MPI_INT, &status ) ;

```

The “sync-barrier-sync” construct is required because:

- The barrier ensures that the write on process 0 occurs before the read on process 1.
- The first sync guarantees that the data written by all processes is transferred to the storage device.
- The second sync guarantees that all data which has been transferred to the storage device is visible to all processes. (This does not affect process 0 in this example.)

The following program represents an erroneous attempt to achieve consistency by eliminating the apparently superfluous second “sync” call for each process.

```

1  /* ----- THIS EXAMPLE IS ERRONEOUS ----- */
2  /* Process 0 */
3  int i, a[10] ;
4  for ( i=0;i<10;i++)
5      a[i] = 5 ;
6
7  MPI_File_open( MPI_COMM_WORLD, "workfile",
8                MPI_MODE_RDWR | MPI_MODE_CREATE, MPI_INFO_NULL, &fh0 ) ;
9  MPI_File_set_view( fh0, 0, MPI_INT, MPI_INT, "native", MPI_INFO_NULL ) ;
10 MPI_File_write_at(fh0, 0, a, 10, MPI_INT, &status ) ;
11 MPI_File_sync( fh0 ) ;
12 MPI_Barrier( MPI_COMM_WORLD ) ;
13
14 /* Process 1 */
15 int b[10] ;
16 MPI_File_open( MPI_COMM_WORLD, "workfile",
17               MPI_MODE_RDWR | MPI_MODE_CREATE, MPI_INFO_NULL, &fh1 ) ;
18 MPI_File_set_view( fh1, 0, MPI_INT, MPI_INT, "native", MPI_INFO_NULL ) ;
19 MPI_Barrier( MPI_COMM_WORLD ) ;
20 MPI_File_sync( fh1 ) ;
21 MPI_File_read_at(fh1, 0, b, 10, MPI_INT, &status ) ;
22
23 /* ----- THIS EXAMPLE IS ERRONEOUS ----- */

```

The above program also violates the MPI rule against out-of-order collective operations and will deadlock for implementations in which MPI\_FILE\_SYNC blocks.

*Advice to users.* Some implementations may choose to implement MPI\_FILE\_SYNC as a temporally synchronizing function. When using such an implementation, the “sync-barrier-sync” construct above can be replaced by a single “sync.” The results of using such code with an implementation for which MPI\_FILE\_SYNC is not temporally synchronizing is undefined. (*End of advice to users.*)

### Asynchronous I/O

The behavior of asynchronous I/O operations is determined by applying the rules specified above for synchronous I/O operations.

The following examples all access a preexisting file “myfile.” Word 10 in myfile initially contains the integer 2. Each example writes and reads word 10.

First consider the following code fragment:

```

43 int a = 4, b, TRUE=1;
44 MPI_File_open( MPI_COMM_WORLD, "myfile",
45               MPI_MODE_RDWR, MPI_INFO_NULL, &fh ) ;
46 MPI_File_set_view( fh, 0, MPI_INT, MPI_INT, "native", MPI_INFO_NULL ) ;
47 /* MPI_File_set_atomicity( fh, TRUE ) ; Use this to set atomic mode. */

```



```

MPI_File_iread_at(fh, 10, &b, 1, MPI_INT, &reqs[1]) ;
MPI_Waitall(2, reqs, statuses) ;

```

For asynchronous data access operations, MPI specifies that the access occurs at any time between the call to the asynchronous data access routine and the return from the corresponding request complete routine. Thus, executing either the read before the write, or the write before the read is consistent with program order. If atomic mode is set, then MPI guarantees sequential consistency, and the program will read either 2 or 4 into b. If atomic mode is not set, then sequential consistency is not guaranteed and the program may read something other than 2 or 4 due to the conflicting data access.

Similarly, the following code fragment does not order file accesses:

```

int a = 4, b;
MPI_File_open( MPI_COMM_WORLD, "myfile",
               MPI_MODE_RDWR, MPI_INFO_NULL, &fh ) ;
MPI_File_set_view( fh, 0, MPI_INT, MPI_INT, "native", MPI_INFO_NULL ) ;
/* MPI_File_set_atomicity( fh, TRUE ) ; Use this to set atomic mode. */
MPI_File_iread_at(fh, 10, &b, 1, MPI_INT, &reqs[1]) ;
MPI_File_iread_at(fh, 10, &b, 1, MPI_INT, &reqs[1]) ;
MPI_Wait(&reqs[0], &status) ;
MPI_Wait(&reqs[1], &status) ;

```

If atomic mode is set, either 2 or 4 will be read into b. Again, MPI does not guarantee sequential consistency in nonatomic mode.

On the other hand, the following code fragment:

```

int a = 4, b;
MPI_File_open( MPI_COMM_WORLD, "myfile",
               MPI_MODE_RDWR, MPI_INFO_NULL, &fh ) ;
MPI_File_set_view( fh, 0, MPI_INT, MPI_INT, "native", MPI_INFO_NULL ) ;
MPI_File_iread_at(fh, 10, &b, 1, MPI_INT, &reqs[1]) ;
MPI_Wait(&reqs[0], &status) ;
MPI_File_iread_at(fh, 10, &b, 1, MPI_INT, &reqs[1]) ;
MPI_Wait(&reqs[1], &status) ;

```

defines the same ordering as:

```

int a = 4, b;
MPI_File_open( MPI_COMM_WORLD, "myfile",
               MPI_MODE_RDWR, MPI_INFO_NULL, &fh ) ;
MPI_File_set_view( fh, 0, MPI_INT, MPI_INT, "native", MPI_INFO_NULL ) ;
MPI_File_write_at(fh, 10, &a, 1, MPI_INT, &status) ;
MPI_File_read_at(fh, 10, &b, 1, MPI_INT, &status) ;

```

Since

- nonconcurrent operations on a single file handle are sequentially consistent, and
- the program fragments specify an order for the operations,

MPI guarantees that both program fragments will read the value 4 into `b`. There is no need to set atomic mode for this example.

Similar considerations apply to conflicting accesses of the form:

```
MPI_File_write_all_begin(fh,...) ;
MPI_File_iread(fh,...) ;
MPI_Wait(fh,...) ;
MPI_File_write_all_end(fh,...) ;
```

Recall that constraints governing consistency and semantics are not relevant to the following:

```
MPI_File_write_all_begin(fh,...) ;
MPI_File_read_all_begin(fh,...) ;
MPI_File_read_all_end(fh,...) ;
MPI_File_write_all_end(fh,...) ;
```

since split collective operations on the same file handle may not overlap (see Section 13.4.5, page 482).

## 13.7 I/O Error Handling

By default, communication errors are fatal—`MPI_ERRORS_ARE_FATAL` is the default error handler associated with `MPI_COMM_WORLD`. I/O errors are usually less catastrophic (e.g., “file not found”) than communication errors, and common practice is to catch these errors and continue executing. For this reason, MPI provides additional error facilities for I/O.

*Advice to users.* MPI does not specify the state of a computation after an erroneous MPI call has occurred. A high-quality implementation will support the I/O error handling facilities, allowing users to write programs using common practice for I/O. (*End of advice to users.*)

Like communicators, each file handle has an error handler associated with it. The MPI I/O error handling routines are defined in Section 8.3, page 325.

When MPI calls a user-defined error handler resulting from an error on a particular file handle, the first two arguments passed to the file error handler are the file handle and the error code. For I/O errors that are not associated with a valid file handle (e.g., in `MPI_FILE_OPEN` or `MPI_FILE_DELETE`), the first argument passed to the error handler is `MPI_FILE_NULL`,

I/O error handling differs from communication error handling in another important aspect. By default, the predefined error handler for file handles is `MPI_ERRORS_RETURN`. The default file error handler has two purposes: when a new file handle is created (by `MPI_FILE_OPEN`), the error handler for the new file handle is initially set to the default error handler, and I/O routines that have no valid file handle on which to raise an error (e.g., `MPI_FILE_OPEN` or `MPI_FILE_DELETE`) use the default file error handler. The default file error handler can be changed by specifying `MPI_FILE_NULL` as the `fh` argument to `MPI_FILE_SET_ERRHANDLER`. The current value of the default file error handler can be determined by passing `MPI_FILE_NULL` as the `fh` argument to `MPI_FILE_GET_ERRHANDLER`.

*Rationale.* For communication, the default error handler is inherited from MPI\_COMM\_WORLD. In I/O, there is no analogous “root” file handle from which default properties can be inherited. Rather than invent a new global file handle, the default file error handler is manipulated as if it were attached to MPI\_FILE\_NULL. (*End of rationale.*)

## 13.8 I/O Error Classes

The implementation dependent error codes returned by the I/O routines can be converted into the error classes defined in Table 13.3.

In addition, calls to routines in this chapter may raise errors in other MPI classes, such as MPI\_ERR\_TYPE.

MPI_ERR_FILE	Invalid file handle
MPI_ERR_NOT_SAME	Collective argument not identical on all processes, or collective routines called in a different order by different processes
MPI_ERR_AMODE	Error related to the <code>amode</code> passed to MPI_FILE_OPEN
MPI_ERR_UNSUPPORTED_DATAREP	Unsupported <code>datarep</code> passed to MPI_FILE_SET_VIEW
MPI_ERR_UNSUPPORTED_OPERATION	Unsupported operation, such as seeking on a file which supports sequential access only
MPI_ERR_NO_SUCH_FILE	File does not exist
MPI_ERR_FILE_EXISTS	File exists
MPI_ERR_BAD_FILE	Invalid file name (e.g., path name too long)
MPI_ERR_ACCESS	Permission denied
MPI_ERR_NO_SPACE	Not enough space
MPI_ERR_QUOTA	Quota exceeded
MPI_ERR_READ_ONLY	Read-only file or file system
MPI_ERR_FILE_IN_USE	File operation could not be completed, as the file is currently open by some process
MPI_ERR_DUP_DATAREP	Conversion functions could not be registered because a data representation identifier that was already defined was passed to MPI_REGISTER_DATAREP
MPI_ERR_CONVERSION	An error occurred in a user supplied data conversion function.
MPI_ERR_IO	Other I/O error

Table 13.3: I/O Error Classes

## 13.9 Examples

### 13.9.1 Double Buffering with Split Collective I/O

This example shows how to overlap computation and output. The computation is performed by the function `compute_buffer()`.

```

/*=====
 *
 * Function:          double_buffer
 *
 * Synopsis:
 * void double_buffer(
 *     MPI_File fh,                ** IN
 *     MPI_Datatype buftype,       ** IN
 *     int bufcount                ** IN
 * )
 *
 * Description:
 *     Performs the steps to overlap computation with a collective write
 *     by using a double-buffering technique.
 *
 * Parameters:
 *     fh                previously opened MPI file handle
 *     buftype           MPI datatype for memory layout
 *                      (Assumes a compatible view has been set on fh)
 *     bufcount          # buftype elements to transfer
 *-----*/

/* this macro switches which buffer "x" is pointing to */
#define TOGGLE_PTR(x) (((x)==(buffer1)) ? (x=buffer2) : (x=buffer1))

void double_buffer( MPI_File fh, MPI_Datatype buftype, int bufcount)
{
    MPI_Status status;          /* status for MPI calls */
    float *buffer1, *buffer2;  /* buffers to hold results */
    float *compute_buf_ptr;    /* destination buffer */
                                /* for computing */
    float *write_buf_ptr;      /* source for writing */
    int done;                  /* determines when to quit */

    /* buffer initialization */
    buffer1 = (float *)
        malloc(bufcount*sizeof(float)) ;
    buffer2 = (float *)
        malloc(bufcount*sizeof(float)) ;
    compute_buf_ptr = buffer1 ; /* initially point to buffer1 */
    write_buf_ptr = buffer1 ;  /* initially point to buffer1 */

```

```

1
2
3  /* DOUBLE-BUFFER prolog:
4     *   compute buffer1; then initiate writing buffer1 to disk
5     */
6  compute_buffer(compute_buf_ptr, bufcount, &done);
7  MPI_File_write_all_begin(fh, write_buf_ptr, bufcount, buftype);
8
9  /* DOUBLE-BUFFER steady state:
10     *   Overlap writing old results from buffer pointed to by write_buf_ptr
11     *   with computing new results into buffer pointed to by compute_buf_ptr.
12     *
13     *   There is always one write-buffer and one compute-buffer in use
14     *   during steady state.
15     */
16  while (!done) {
17      TOGGLE_PTR(compute_buf_ptr);
18      compute_buffer(compute_buf_ptr, bufcount, &done);
19      MPI_File_write_all_end(fh, write_buf_ptr, &status);
20      TOGGLE_PTR(write_buf_ptr);
21      MPI_File_write_all_begin(fh, write_buf_ptr, bufcount, buftype);
22  }
23
24  /* DOUBLE-BUFFER epilog:
25     *   wait for final write to complete.
26     */
27  MPI_File_write_all_end(fh, write_buf_ptr, &status);
28
29
30  /* buffer cleanup */
31  free(buffer1);
32  free(buffer2);
33  }

```

### 13.9.2 Subarray Filetype Constructor

Assume we are writing out a 100x100 2D array of double precision floating point numbers that is distributed among 4 processes such that each process has a block of 25 columns (e.g., process 0 has columns 0-24, process 1 has columns 25-49, etc.; see Figure 13.4). To create the filetypes for each process one could use the following C program (see Section 4.1.3 on page 96):

```

double subarray[100][25];
MPI_Datatype filetype;
int sizes[2], subsizes[2], starts[2];
int rank;

MPI_Comm_rank(MPI_COMM_WORLD, &rank);

```

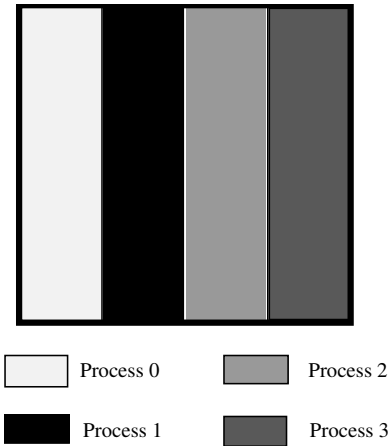


Figure 13.4: Example array file layout

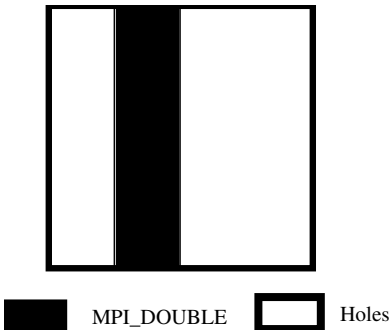


Figure 13.5: Example local array filetype for process 1

```

sizes[0]=100; sizes[1]=100;
subsizes[0]=100; subsizes[1]=25;
starts[0]=0; starts[1]=rank*subsizes[1];

MPI_Type_create_subarray(2, sizes, subsizes, starts, MPI_ORDER_C,
                        MPI_DOUBLE, &filetype);

```

Or, equivalently in Fortran:

```

double precision subarray(100,25)
integer filetype, rank, ierror
integer sizes(2), subsizes(2), starts(2)

call MPI_COMM_RANK(MPI_COMM_WORLD, rank, ierror)
sizes(1)=100
sizes(2)=100
subsizes(1)=100
subsizes(2)=25
starts(1)=0
starts(2)=rank*subsizes(2)

call MPI_TYPE_CREATE_SUBARRAY(2, sizes, subsizes, starts, &
                             MPI_ORDER_FORTRAN, MPI_DOUBLE_PRECISION, &
                             filetype, ierror)

```

The generated filetype will then describe the portion of the file contained within the process's subarray with holes for the space taken by the other processes. Figure 13.5 shows the filetype created for process 1.

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48



# Chapter 14

## Profiling Interface

### 14.1 Requirements

To meet the requirements for the MPI profiling interface, an implementation of the MPI functions *must*

1. provide a mechanism through which all of the MPI defined functions, except those allowed as macros (See Section 2.6.5), may be accessed with a name shift. This requires, in C and Fortran, an alternate entry point name, with the prefix `PMPI_` for each MPI function. The profiling interface in C++ is described in Section 16.1.10. For routines implemented as macros, it is still required that the `PMPI_` version be supplied and work as expected, but it is not possible to replace at link time the `MPI_` version with a user-defined version.
2. ensure that those MPI functions that are not replaced may still be linked into an executable image without causing name clashes.
3. document the implementation of different language bindings of the MPI interface if they are layered on top of each other, so that the profiler developer knows whether she must implement the profile interface for each binding, or can economize by implementing it only for the lowest level routines.
4. where the implementation of different language bindings is done through a layered approach (e.g., the Fortran binding is a set of “wrapper” functions that call the C implementation), ensure that these wrapper functions are separable from the rest of the library.

This separability is necessary to allow a separate profiling library to be correctly implemented, since (at least with Unix linker semantics) the profiling library must contain these wrapper functions if it is to perform as expected. This requirement allows the person who builds the profiling library to extract these functions from the original MPI library and add them into the profiling library without bringing along any other unnecessary code.

5. provide a no-op routine `MPI_PCONTROL` in the MPI library.

## 14.2 Discussion

The objective of the MPI profiling interface is to ensure that it is relatively easy for authors of profiling (and other similar) tools to interface their codes to MPI implementations on different machines.

Since MPI is a machine independent standard with many different implementations, it is unreasonable to expect that the authors of profiling tools for MPI will have access to the source code that implements MPI on any particular machine. It is therefore necessary to provide a mechanism by which the implementors of such tools can collect whatever performance information they wish *without* access to the underlying implementation.

We believe that having such an interface is important if MPI is to be attractive to end users, since the availability of many different tools will be a significant factor in attracting users to the MPI standard.

The profiling interface is just that, an interface. It says *nothing* about the way in which it is used. There is therefore no attempt to lay down what information is collected through the interface, or how the collected information is saved, filtered, or displayed.

While the initial impetus for the development of this interface arose from the desire to permit the implementation of profiling tools, it is clear that an interface like that specified may also prove useful for other purposes, such as “internetworking” multiple MPI implementations. Since all that is defined is an interface, there is no objection to its being used wherever it is useful.

As the issues being addressed here are intimately tied up with the way in which executable images are built, which may differ greatly on different machines, the examples given below should be treated solely as one way of implementing the objective of the MPI profiling interface. The actual requirements made of an implementation are those detailed in the Requirements section above, the whole of the rest of this chapter is only present as justification and discussion of the logic for those requirements.

The examples below show one way in which an implementation could be constructed to meet the requirements on a Unix system (there are doubtless others that would be equally valid).

## 14.3 Logic of the Design

Provided that an MPI implementation meets the requirements above, it is possible for the implementor of the profiling system to intercept all of the MPI calls that are made by the user program. She can then collect whatever information she requires before calling the underlying MPI implementation (through its name shifted entry points) to achieve the desired effects.

### 14.3.1 Miscellaneous Control of Profiling

There is a clear requirement for the user code to be able to control the profiler dynamically at run time. This is normally used for (at least) the purposes of

- Enabling and disabling profiling depending on the state of the calculation.
- Flushing trace buffers at non-critical points in the **calculation**.
- Adding user events to a trace file.

These requirements are met by use of the MPI\_PCONTROL.

MPI\_PCONTROL(level, ...)

IN            level                            Profiling level

int MPI\_Pcontrol(const int level, ...)

MPI\_PCONTROL(LEVEL)

INTEGER LEVEL

MPI\_Pcontrol(level)

INTEGER, INTENT(IN) :: level

{void MPI::Pcontrol(const int level, ...) (*binding deprecated, see Section 15.2*) }

MPI libraries themselves make no use of this routine, and simply return immediately to the user code. However the presence of calls to this routine allows a profiling package to be explicitly called by the user.

Since MPI has no control of the implementation of the profiling code, we are unable to specify precisely the semantics that will be provided by calls to MPI\_PCONTROL. This vagueness extends to the number of arguments to the function, and their datatypes.

However to provide some level of portability of user codes to different profiling libraries, we request the following meanings for certain values of level.

- level==0 Profiling is disabled.
- level==1 Profiling is enabled at a normal default level of detail.
- level==2 Profile buffers are flushed, which may be a no-op in some profilers.
- All other values of level have profile library defined effects and additional arguments.

We also request that the default state after MPI\_INIT has been called is for profiling to be enabled at the normal default level. (i.e. as if MPI\_PCONTROL had just been called with the argument 1). This allows users to link with a profiling library and obtain profile output without having to modify their source code at all.

The provision of MPI\_PCONTROL as a no-op in the standard MPI library supports the collection of more detailed profiling information with source code that can still link against the standard MPI library.

## 14.4 Examples

### 14.4.1 Profiler Implementation

A profiler can accumulate the total amount of data sent by the MPI\_SEND function, along with the total elapsed time spent in the function, as follows:

```
static int totalBytes = 0;
static double totalTime = 0.0;
```

```

1  int MPI_Send(void* buffer, int count, MPI_Datatype datatype,
2              int dest, int tag, MPI_Comm comm)
3  {
4      double tstart = MPI_Wtime();      /* Pass on all the arguments */
5      int extent;
6      int result    = PMPI_Send(buffer, count, datatype, dest, tag, comm);
7
8      MPI_Type_size(datatype, &extent); /* Compute size */
9      totalBytes += count*extent;
10
11     totalTime += MPI_Wtime() - tstart;      /* and time      */
12
13     return result;
14 }

```

#### 14.4.2 MPI Library Implementation

If the MPI library is implemented in C on a Unix system, then there are various options, including the two presented here, for supporting the name-shift requirement. The choice between these two options depends partly on whether the linker and compiler support weak symbols.

##### Systems with Weak Symbols

If the compiler and linker support weak external symbols (e.g., Solaris 2.x, other system V.4 machines), then only a single library is required through the use of `#pragma weak` thus

```

#pragma weak MPI_Example = PMPI_Example

int PMPI_Example(/* appropriate args */)
{
    /* Useful content */
}

```

The effect of this `#pragma` is to define the external symbol `MPI_Example` as a weak definition. This means that the linker will not complain if there is another definition of the symbol (for instance in the profiling library), however if no other definition exists, then the linker will use the weak definition.

##### Systems Without Weak Symbols

In the absence of weak symbols then one possible solution would be to use the C macro pre-processor thus

```

#ifdef PROFILELIB
#   ifdef __STDC__
#       define FUNCTION(name) P##name
#   else
#       define FUNCTION(name) P/**/name

```

```
#    endif
#else
#    define FUNCTION(name) name
#endif
```

Each of the user visible functions in the library would then be declared thus

```
int FUNCTION(MPI_Example)(/* appropriate args */)
{
    /* Useful content */
}
```

The same source file can then be compiled to produce both versions of the library, depending on the state of the `PROFILELIB` macro symbol.

It is required that the standard MPI library be built in such a way that the inclusion of MPI functions can be achieved one at a time. This is a somewhat unpleasant requirement, since it may mean that each external function has to be compiled from a separate file. However this is necessary so that the author of the profiling library need only define those MPI functions that she wishes to intercept, references to any others being fulfilled by the normal MPI library. Therefore the link step can look something like this

```
% cc ... -lmyprof -lpmpi -lmpi
```

Here `libmyprof.a` contains the profiler functions that intercept some of the MPI functions. `libpmpi.a` contains the “name shifted” MPI functions, and `libmpi.a` contains the normal definitions of the MPI functions.

### 14.4.3 Complications

#### Multiple Counting

Since parts of the MPI library may themselves be implemented using more basic MPI functions (e.g., a portable implementation of the collective operations implemented using point to point communications), there is potential for profiling functions to be called from within an MPI function that was called from a profiling function. This could lead to “double counting” of the time spent in the inner routine. Since this effect could actually be useful under some circumstances (e.g., it might allow one to answer the question “How much time is spent in the point to point routines when they’re called from collective functions?”), we have decided not to enforce any restrictions on the author of the MPI library that would overcome this. Therefore the author of the profiling library should be aware of this problem, and guard against it herself. In a single threaded world this is easily achieved through use of a static variable in the profiling code that remembers if you are already inside a profiling routine. It becomes more complex in a multi-threaded environment (as does the meaning of the times recorded).

#### Linker Oddities

The Unix linker traditionally operates in one `pass`: the effect of this is that functions from libraries are only included in the image if they are needed at the time the library is scanned.

When combined with weak symbols, or multiple definitions of the same function, this can cause odd (and unexpected) effects.

Consider, for instance, an implementation of MPI in which the Fortran binding is achieved by using wrapper functions on top of the C implementation. The author of the profile library then assumes that it is reasonable only to provide profile functions for the C binding, since Fortran will eventually call these, and the cost of the wrappers is assumed to be small. However, if the wrapper functions are not in the profiling library, then none of the profiled entry points will be undefined when the profiling library is called. Therefore none of the profiling code will be included in the image. When the standard MPI library is scanned, the Fortran wrappers will be resolved, and will also pull in the base versions of the MPI functions. The overall effect is that the code will link successfully, but will not be profiled.

To overcome this we must ensure that the Fortran wrapper functions are included in the profiling version of the library. We ensure that this is possible by requiring that these be separable from the rest of the base MPI library. This allows them to be aared out of the base library and into the profiling one.

## 14.5 Multiple Levels of Interception

The scheme given here does not directly support the nesting of profiling functions, since it provides only a single alternative name for each MPI function. Consideration was given to an implementation that would allow multiple levels of call interception, however we were unable to construct an implementation of this that did not have the following disadvantages

- assuming a particular implementation language,
- imposing a run time cost even when no profiling was taking place.

Since one of the objectives of MPI is to permit efficient, low latency implementations, and it is not the business of a standard to require a particular implementation language, we decided to accept the scheme outlined above.

Note, however, that it is possible to use the scheme above to implement a multi-level system, since the function called by the user may call many different profiling functions before calling the underlying MPI function. This capability has been demonstrated in the P<sup>N</sup>MPI tool infrastructure [46].

## Chapter 15

# Deprecated Functions

### 15.1 Deprecated since MPI-2.0

The following function is deprecated and is superseded by `MPI_TYPE_CREATE_HVECTOR` in MPI-2.0. The language independent definition and the C binding of the deprecated function is the same as of the new function, except of the function name. Only the Fortran language binding is different.

`MPI_TYPE_HVECTOR( count, blocklength, stride, oldtype, newtype)`

IN	count	number of blocks (non-negative integer)
IN	blocklength	number of elements in each block (non-negative integer)
IN	stride	number of bytes between start of each block (integer)
IN	oldtype	old datatype (handle)
OUT	newtype	new datatype (handle)

```
int MPI_Type_hvector(int count, int blocklength, MPI_Aint stride,  
                    MPI_Datatype oldtype, MPI_Datatype *newtype)
```

```
MPI_TYPE_HVECTOR(COUNT, BLOCKLENGTH, STRIDE, OLDTYPE, NEWTYPE, IERROR)  
    INTEGER COUNT, BLOCKLENGTH, STRIDE, OLDTYPE, NEWTYPE, IERROR
```

The following function is deprecated and is superseded by `MPI_TYPE_CREATE_HINDEXED` in MPI-2.0. The language independent definition and the C binding of the deprecated function is the same as of the new function, except of the function name. Only the Fortran language binding is different.

```

1 MPI_TYPE_HINDEXED( count, array_of_blocklengths, array_of_displacements, oldtype, new-
2     type)
3
4     IN          count          number of blocks – also number of entries in
5                               array_of_displacements and array_of_blocklengths (non-
6                               negative integer)
7
8     IN          array_of_blocklengths  number of elements in each block (array of non-negative
9                               integers)
10
11    IN          array_of_displacements  byte displacement of each block (array of integer)
12
13    IN          oldtype              old datatype (handle)
14
15    OUT         newtype              new datatype (handle)

```

```

16 int MPI_Type_hindexed(int count, int *array_of_blocklengths,
17     MPI_Aint *array_of_displacements, MPI_Datatype oldtype,
18     MPI_Datatype *newtype)
19
20 MPI_TYPE_HINDEXED(COUNT, ARRAY_OF_BLOCKLENGTHS, ARRAY_OF_DISPLACEMENTS,
21     OLDTYPE, NEWTYPE, IERROR)
22
23     INTEGER COUNT, ARRAY_OF_BLOCKLENGTHS(*), ARRAY_OF_DISPLACEMENTS(*),
24     OLDTYPE, NEWTYPE, IERROR

```

The following function is deprecated and is superseded by MPI\_TYPE\_CREATE\_STRUCT in MPI-2.0. The language independent definition and the C binding of the deprecated function is the same as of the new function, except of the function name. Only the Fortran language binding is different.

```

25
26
27 MPI_TYPE_STRUCT(count, array_of_blocklengths, array_of_displacements, array_of_types,
28     newtype)
29
30     IN          count          number of blocks (integer) (non-negative integer) –
31                               also number of entries in arrays array_of_types,
32                               array_of_displacements and array_of_blocklengths
33
34     IN          array_of_blocklength  number of elements in each block (array of non-negative
35                               integer)
36
37     IN          array_of_displacements  byte displacement of each block (array of integer)
38
39     IN          array_of_types        type of elements in each block (array of handles to
40                               datatype objects)
41
42     OUT         newtype              new datatype (handle)
43
44 int MPI_Type_struct(int count, int *array_of_blocklengths,
45     MPI_Aint *array_of_displacements,
46     MPI_Datatype *array_of_types, MPI_Datatype *newtype)
47
48 MPI_TYPE_STRUCT(COUNT, ARRAY_OF_BLOCKLENGTHS, ARRAY_OF_DISPLACEMENTS,
49     ARRAY_OF_TYPES, NEWTYPE, IERROR)
50
51     INTEGER COUNT, ARRAY_OF_BLOCKLENGTHS(*), ARRAY_OF_DISPLACEMENTS(*),
52     ARRAY_OF_TYPES(*), NEWTYPE, IERROR

```



The following function is deprecated and is superseded by `MPI_GET_ADDRESS` in MPI-2.0. The language independent definition and the C binding of the deprecated function is the same as of the new function, except of the function name. Only the Fortran language binding is different.

`MPI_ADDRESS(location, address)`

IN	location	location in caller memory (choice)
OUT	address	address of location (integer)

`int MPI_Address(void* location, MPI_Aint *address)`

`MPI_ADDRESS(LOCATION, ADDRESS, IERROR)`  
`<type> LOCATION(*)`  
`INTEGER ADDRESS, IERROR`

The following functions are deprecated and are superseded by `MPI_TYPE_GET_EXTENT` in MPI-2.0.

`MPI_TYPE_EXTENT(datatype, extent)`

IN	datatype	datatype (handle)
OUT	extent	datatype extent (integer)

`int MPI_Type_extent(MPI_Datatype datatype, MPI_Aint *extent)`

`MPI_TYPE_EXTENT(DATATYPE, EXTENT, IERROR)`  
`INTEGER DATATYPE, EXTENT, IERROR`

Returns the extent of a datatype, where extent is as defined on page 106.

The two functions below can be used for finding the lower bound and the upper bound of a datatype.

`MPI_TYPE_LB( datatype, displacement)`

IN	datatype	datatype (handle)
OUT	displacement	displacement of lower bound from origin, in bytes (integer)

`int MPI_Type_lb(MPI_Datatype datatype, MPI_Aint* displacement)`

`MPI_TYPE_LB( DATATYPE, DISPLACEMENT, IERROR)`  
`INTEGER DATATYPE, DISPLACEMENT, IERROR`

```

1 MPI_TYPE_UB( datatype, displacement)
2     IN          datatype          datatype (handle)
3
4     OUT         displacement      displacement of upper bound from origin, in bytes (in-
5                                     teger)
6

```

```

7 int MPI_Type_ub(MPI_Datatype datatype, MPI_Aint* displacement)
8

```

```

9 MPI_TYPE_UB( DATATYPE, DISPLACEMENT, IERROR)
10    INTEGER DATATYPE, DISPLACEMENT, IERROR
11

```

The following function is deprecated and is superseded by MPI\_COMM\_CREATE\_KEYVAL in MPI-2.0. The language independent definition of the deprecated function is the same as that of the new function, except for the function name and a different behavior in the C/Fortran language interoperability, see Section 16.3.7 on page 587. The language bindings are modified.

```

17 MPI_KEYVAL_CREATE(copy_fn, delete_fn, keyval, extra_state)
18
19     IN          copy_fn           Copy callback function for keyval
20
21     IN          delete_fn        Delete callback function for keyval
22
23     OUT         keyval           key value for future access (integer)
24
25     IN          extra_state      Extra state for callback functions
26
27
28 int MPI_Keyval_create(MPI_Copy_function *copy_fn, MPI_Delete_function
29                      *delete_fn, int *keyval, void* extra_state)
30
31 MPI_KEYVAL_CREATE(COPY_FN, DELETE_FN, KEYVAL, EXTRA_STATE, IERROR)
32    EXTERNAL COPY_FN, DELETE_FN
33    INTEGER KEYVAL, EXTRA_STATE, IERROR
34

```

The copy\_fn function is invoked when a communicator is duplicated by MPI\_COMM\_DUP. copy\_fn should be of type MPI\_Copy\_function, which is defined as follows:

```

35 typedef int MPI_Copy_function(MPI_Comm oldcomm, int keyval,
36                               void *extra_state, void *attribute_val_in,
37                               void *attribute_val_out, int *flag)
38

```

A Fortran declaration for such a function is as follows:

```

39 SUBROUTINE COPY_FUNCTION(OLDCOMM, KEYVAL, EXTRA_STATE, ATTRIBUTE_VAL_IN,
40                          ATTRIBUTE_VAL_OUT, FLAG, IERR)
41    INTEGER OLDCOMM, KEYVAL, EXTRA_STATE, ATTRIBUTE_VAL_IN,
42    ATTRIBUTE_VAL_OUT, IERR
43    LOGICAL FLAG
44

```

copy\_fn may be specified as MPI\_NULL\_COPY\_FN or MPI\_DUP\_FN from either C or FORTRAN; MPI\_NULL\_COPY\_FN is a function that does nothing other than returning flag = 0 and MPI\_SUCCESS. MPI\_DUP\_FN is a simple-minded copy function that sets flag =

1, returns the value of `attribute_val_in` in `attribute_val_out`, and returns `MPI_SUCCESS`. Note that `MPI_NULL_COPY_FN` and `MPI_DUP_FN` are also deprecated.

Analogous to `copy_fn` is a callback deletion function, defined as follows. The `delete_fn` function is invoked when a communicator is deleted by `MPI_COMM_FREE` or when a call is made explicitly to `MPI_ATTR_DELETE`. `delete_fn` should be of type `MPI_Delete_function`, which is defined as follows:

```
typedef int MPI_Delete_function(MPI_Comm comm, int keyval,
void *attribute_val, void *extra_state);
```

A Fortran declaration for such a function is as follows:

```
SUBROUTINE DELETE_FUNCTION(COMM, KEYVAL, ATTRIBUTE_VAL, EXTRA_STATE, IERR)
  INTEGER COMM, KEYVAL, ATTRIBUTE_VAL, EXTRA_STATE, IERR
```

`delete_fn` may be specified as `MPI_NULL_DELETE_FN` from either C or FORTRAN; `MPI_NULL_DELETE_FN` is a function that does nothing, other than returning `MPI_SUCCESS`. Note that `MPI_NULL_DELETE_FN` is also deprecated.

The following function is deprecated and is superseded by `MPI_COMM_FREE_KEYVAL` in MPI-2.0. The language independent definition of the deprecated function is the same as of the new function, except of the function name. The language bindings are modified.

`MPI_KEYVAL_FREE(keyval)`

INOUT	keyval	Frees the integer key value (integer)
-------	--------	---------------------------------------

```
int MPI_Keyval_free(int *keyval)
```

```
MPI_KEYVAL_FREE(KEYVAL, IERROR)
  INTEGER KEYVAL, IERROR
```

The following function is deprecated and is superseded by `MPI_COMM_SET_ATTR` in MPI-2.0. The language independent definition of the deprecated function is the same as of the new function, except of the function name. The language bindings are modified.

`MPI_ATTR_PUT(comm, keyval, attribute_val)`

INOUT	comm	communicator to which attribute will be attached (handle)
IN	keyval	key value, as returned by <code>MPI_KEYVAL_CREATE</code> (integer)
IN	attribute_val	attribute value

```
int MPI_Attr_put(MPI_Comm comm, int keyval, void* attribute_val)
```

```
MPI_ATTR_PUT(COMM, KEYVAL, ATTRIBUTE_VAL, IERROR)
  INTEGER COMM, KEYVAL, ATTRIBUTE_VAL, IERROR
```

The following function is deprecated and is superseded by `MPI_COMM_GET_ATTR` in MPI-2.0. The language independent definition of the deprecated function is the same as of the new function, except of the function name. The language bindings are modified.

1 MPI\_ATTR\_GET(comm, keyval, attribute\_val, flag)

2	IN	comm	communicator to which attribute is attached (handle)
3			
4	IN	keyval	key value (integer)
5	OUT	attribute_val	attribute value, unless flag = false
6	OUT	flag	true if an attribute value was extracted; false if no attribute is associated with the key
7			
8			

9  
10 int MPI\_Attr\_get(MPI\_Comm comm, int keyval, void \*attribute\_val, int \*flag)

11 MPI\_ATTR\_GET(COMM, KEYVAL, ATTRIBUTE\_VAL, FLAG, IERROR)

12 INTEGER COMM, KEYVAL, ATTRIBUTE\_VAL, IERROR

13 LOGICAL FLAG

14  
15 The following function is deprecated and is superseded by MPI\_COMM\_DELETE\_ATTR  
16 in MPI-2.0. The language independent definition of the deprecated function is the same as  
17 of the new function, except of the function name. The language bindings are modified.

18  
19 MPI\_ATTR\_DELETE(comm, keyval)

20	INOUT	comm	communicator to which attribute is attached (handle)
21			
22	IN	keyval	The key value of the deleted attribute (integer)
23			

24 int MPI\_Attr\_delete(MPI\_Comm comm, int keyval)

25  
26 MPI\_ATTR\_DELETE(COMM, KEYVAL, IERROR)

27 INTEGER COMM, KEYVAL, IERROR

28  
29 The following function is deprecated and is superseded by  
30 MPI\_COMM\_CREATE\_ERRHANDLER in MPI-2.0. The language independent definition  
31 of the deprecated function is the same as of the new function, except of the function name.  
32 The language bindings are modified.

33  
34 MPI\_ERRHANDLER\_CREATE( handler\_fn, errhandler )

35	IN	[ticket252-W.]handler_fn	user defined error handling procedure
36			
37	OUT	errhandler	MPI error handler (handle)
38			

39 int MPI\_Errhandler\_create(MPI\_Handler\_function \*handler\_fn,  
40 MPI\_Errhandler \*errhandler)

41 MPI\_ERRHANDLER\_CREATE(HANDLER\_FN, ERRHANDLER, IERROR)

42 EXTERNAL HANDLER\_FN

43 INTEGER ERRHANDLER, IERROR

44  
45 Register the user routine handler\_fn for use as an MPI exception handler. Returns in  
46 errhandler a handle to the registered exception handler.

47 In the C language, the user routine should be a C function of type MPI\_Handler\_function,  
48 which is defined as:

```
typedef void (MPI_Handler_function)(MPI_Comm *, int *, ...);
```

The first argument is the communicator in use, the second is the error code to be returned.

In the Fortran language, the user routine should be of the form:

```
SUBROUTINE HANDLER_FUNCTION(COMM, ERROR_CODE)
  INTEGER COMM, ERROR_CODE
```

The following function is deprecated and is superseded by `MPI_COMM_SET_ERRHANDLER` in MPI-2.0. The language independent definition of the deprecated function is the same as of the new function, except of the function name. The language bindings are modified.

```
MPI_ERRHANDLER_SET( comm, errhandler )
```

INOUT	comm	communicator to set the error handler for (handle)
IN	errhandler	new MPI error handler for communicator (handle)

```
int MPI_Errhandler_set(MPI_Comm comm, MPI_Errhandler errhandler)
```

```
MPI_ERRHANDLER_SET(COMM, ERRHANDLER, IERROR)
  INTEGER COMM, ERRHANDLER, IERROR
```

Associates the new error handler `errorhandler` with communicator `comm` at the calling process. Note that an error handler is always associated with the communicator.

The following function is deprecated and is superseded by `MPI_COMM_GET_ERRHANDLER` in MPI-2.0. The language independent definition of the deprecated function is the same as of the new function, except of the function name. The language bindings are modified.

```
MPI_ERRHANDLER_GET( comm, errhandler )
```

IN	comm	communicator to get the error handler from (handle)
OUT	errhandler	MPI error handler currently associated with communicator (handle)

```
int MPI_Errhandler_get(MPI_Comm comm, MPI_Errhandler *errhandler)
```

```
MPI_ERRHANDLER_GET(COMM, ERRHANDLER, IERROR)
  INTEGER COMM, ERRHANDLER, IERROR
```

Returns in `errhandler` (a handle to) the error handler that is currently associated with communicator `comm`.

## 15.2 Deprecated since MPI-2.2

The entire set of C++ language bindings have been deprecated.

*Rationale.* The C++ bindings add minimal functionality over the C bindings while incurring a significant amount of maintenance to the MPI specification. Since the C++ bindings are effectively a one-to-one mapping of the C bindings, it should be relatively easy to convert existing C++ MPI applications to use the MPI C bindings. Additionally, there are third party packages available that provide C++ class library functionality (i.e., C++-specific functionality layered on top of the MPI C bindings) that are likely more expressive and/or natural to C++ programmers and are not suitable for standardization in this specification. (*End of rationale.*)

The following function typedefs have been deprecated and are superseded by new names. Other than the typedef names, the function signatures are exactly the same; the names were updated to match conventions of other function typedef names.

Deprecated Name	New Name
MPI_Comm_errhandler_fn	MPI_Comm_errhandler_function
MPI::Comm::Errhandler_fn	MPI::Comm::Errhandler_function
MPI_File_errhandler_fn	MPI_File_errhandler_function
MPI::File::Errhandler_fn	MPI::File::Errhandler_function
MPI_Win_errhandler_fn	MPI_Win_errhandler_function
MPI::Win::Errhandler_fn	MPI::Win::Errhandler_function

# Chapter 16

## Language Bindings

### 16.1 C++

#### 16.1.1 Overview

The C++ language bindings have been deprecated.

There are some issues specific to C++ that must be considered in the design of an interface that go beyond the simple description of language bindings. In particular, in C++, we must be concerned with the design of objects and their interfaces, rather than just the design of a language-specific functional interface to MPI. Fortunately, the design of MPI was based on the notion of objects, so a natural set of classes is already part of MPI.

MPI-2 includes C++ bindings as part of its function specifications. In some cases, MPI-2 provides new names for the C bindings of MPI-1 functions. In this case, the C++ binding matches the new C name — there is no binding for the deprecated name.

#### 16.1.2 Design

The C++ language interface for MPI is designed according to the following criteria:

1. The C++ language interface consists of a small set of classes with a lightweight functional interface to MPI. The classes are based upon the fundamental MPI object types (e.g., communicator, group, etc.).
2. The MPI C++ language bindings provide a semantically correct interface to MPI.
3. To the greatest extent possible, the C++ bindings for MPI functions are member functions of MPI classes.

*Rationale.* Providing a lightweight set of MPI objects that correspond to the basic MPI types is the best fit to MPI's implicit object-based design; methods can be supplied for these objects to realize MPI functionality. The existing C bindings can be used in C++ programs, but much of the expressive power of the C++ language is forfeited. On the other hand, while a comprehensive class library would make user programming more elegant, such a library it is not suitable as a language binding for MPI since a binding must provide a direct and unambiguous mapping to the specified functionality of MPI. (*End of rationale.*)

### 16.1.3 C++ Classes for MPI

All MPI classes, constants, and functions are declared within the scope of an MPI `namespace`. Thus, instead of the `MPI_` prefix that is used in C and Fortran, MPI functions essentially have an `MPI::` prefix.

The members of the MPI namespace are those classes corresponding to objects implicitly used by MPI. An abbreviated definition of the MPI namespace and its member classes is as follows:

```
namespace MPI {
    class Comm { ... };
    class Intracomm : public Comm { ... };
    class Graphcomm : public Intracomm { ... };
    class Distgraphcomm : public Intracomm { ... };
    class Cartcomm : public Intracomm { ... };
    class Intercomm : public Comm { ... };
    class Datatype { ... };
    class Errhandler { ... };
    class Exception { ... };
    class File { ... };
    class Group { ... };
    class Info { ... };
    class Op { ... };
    class Request { ... };
    class Prerequest : public Request { ... };
    class Grequest : public Request { ... };
    class Status { ... };
    class Win { ... };
};
```

Note that there are a small number of derived classes, and that virtual inheritance is *not* used.

### 16.1.4 Class Member Functions for MPI

Besides the member functions which constitute the C++ language bindings for MPI, the C++ language interface has additional functions (as required by the C++ language). In particular, the C++ language interface must provide a constructor and destructor, an assignment operator, and comparison operators.

The complete set of C++ language bindings for MPI is presented in Annex A.5. The bindings take advantage of some important C++ features, such as references and `const`. Declarations (which apply to all MPI member classes) for construction, destruction, copying, assignment, comparison, and mixed-language operability are also provided.

Except where indicated, all non-static member functions (except for constructors and the assignment operator) of MPI member classes are virtual functions.

*Rationale.* Providing virtual member functions is an important part of design for inheritance. Virtual functions can be bound at run-time, which allows users of libraries to re-define the behavior of objects already contained in a library. There is a small



performance penalty that must be paid (the virtual function must be looked up before it can be called). However, users concerned about this performance penalty can force compile-time function binding. (*End of rationale.*)

**Example 16.1** Example showing a derived MPI class.

```
class foo_comm : public MPI::Intracomm {
public:
    void Send(const void* buf, int count, const MPI::Datatype& type,
              int dest, int tag) const
    {
        // Class library functionality
        MPI::Intracomm::Send(buf, count, type, dest, tag);
        // More class library functionality
    }
};
```

*Advice to implementors.* Implementors must be careful to avoid unintended side effects from class libraries that use inheritance, especially in layered implementations. For example, if MPI\_BCAST is implemented by repeated calls to MPI\_SEND or MPI\_RECV, the behavior of MPI\_BCAST cannot be changed by derived communicator classes that might redefine MPI\_SEND or MPI\_RECV. The implementation of MPI\_BCAST must explicitly use the MPI\_SEND (or MPI\_RECV) of the base MPI::Comm class. (*End of advice to implementors.*)

### 16.1.5 Semantics

The semantics of the member functions constituting the C++ language binding for MPI are specified by the MPI function description itself. Here, we specify the semantics for those portions of the C++ language interface that are not part of the language binding. In this subsection, functions are prototyped using the type MPI::<CLASS> rather than listing each function for every MPI class; the word <CLASS> can be replaced with any valid MPI class name (e.g., Group), except as noted.

**Construction / Destruction** The default constructor and destructor are prototyped as follows:

```
{ MPI::<CLASS>() (binding deprecated, see Section 15.2) }
{ ~MPI::<CLASS>() (binding deprecated, see Section 15.2) }
```

In terms of construction and destruction, opaque MPI user level objects behave like handles. Default constructors for all MPI objects except MPI::Status create corresponding MPI::\*\_NULL handles. That is, when an MPI object is instantiated, comparing it with its corresponding MPI::\*\_NULL object will return true. The default constructors do not create new MPI opaque objects. Some classes have a member function Create() for this purpose.

**Example 16.2** In the following code fragment, the test will return true and the message will be sent to cout.

```

1 void foo()
2 {
3     MPI::Intracomm bar;
4
5     if (bar == MPI::COMM_NULL)
6         cout << "bar is MPI::COMM_NULL" << endl;
7 }

```

The destructor for each MPI user level object does *not* invoke the corresponding `MPI_*_FREE` function (if it exists).

*Rationale.* `MPI_*_FREE` functions are not automatically invoked for the following reasons:

1. Automatic destruction contradicts the shallow-copy semantics of the MPI classes.
2. The model put forth in MPI makes memory allocation and deallocation the responsibility of the user, not the implementation.
3. Calling `MPI_*_FREE` upon destruction could have unintended side effects, including triggering collective operations (this also affects the copy, assignment, and construction semantics). In the following example, we would want neither `foo_comm` nor `bar_comm` to automatically invoke `MPI_*_FREE` upon exit from the function.

```

23 void example_function()
24 {
25     MPI::Intracomm foo_comm(MPI::COMM_WORLD), bar_comm;
26     bar_comm = MPI::COMM_WORLD.Dup();
27     // rest of function
28 }

```

*(End of rationale.)*

**Copy / Assignment** The copy constructor and assignment operator are prototyped as follows:

```

34 { MPI::<CLASS>(const MPI::<CLASS>& data) (binding deprecated, see Section 15.2) }
35
36 { MPI::<CLASS>& MPI::<CLASS>::operator=(const MPI::<CLASS>& data) (binding
37     deprecated, see Section 15.2) }

```

In terms of copying and assignment, opaque MPI user level objects behave like handles. Copy constructors perform handle-based (shallow) copies. `MPI::Status` objects are exceptions to this rule. These objects perform deep copies for assignment and copy construction.

*Advice to implementors.* Each MPI user level object is likely to contain, by value or by reference, implementation-dependent state information. The assignment and copying of MPI object handles may simply copy this value (or reference). *(End of advice to implementors.)*

**Example 16.3** Example using assignment operator. In this example, `MPI::Intracomm::Dup()` is *not* called for `foo_comm`. The object `foo_comm` is simply an alias for `MPI::COMM_WORLD`. But `bar_comm` is created with a call to `MPI::Intracomm::Dup()` and is therefore a different communicator than `foo_comm` (and thus different from `MPI::COMM_WORLD`). `baz_comm` becomes an alias for `bar_comm`. If one of `bar_comm` or `baz_comm` is freed with `MPI_COMM_FREE` it will be set to `MPI::COMM_NULL`. The state of the other handle will be undefined — it will be invalid, but not necessarily set to `MPI::COMM_NULL`.

```
MPI::Intracomm foo_comm, bar_comm, baz_comm;

foo_comm = MPI::COMM_WORLD;
bar_comm = MPI::COMM_WORLD.Dup();
baz_comm = bar_comm;
```

**Comparison** The comparison operators are prototyped as follows:

```
{bool MPI::<CLASS>::operator==(const MPI::<CLASS>& data) const(binding
    deprecated, see Section 15.2) }

{bool MPI::<CLASS>::operator!=(const MPI::<CLASS>& data) const(binding
    deprecated, see Section 15.2) }
```

The member function `operator==()` returns `true` only when the handles reference the same internal MPI object, `false` otherwise. `operator!=()` returns the boolean complement of `operator==()`. However, since the `Status` class is not a handle to an underlying MPI object, it does not make sense to compare `Status` instances. Therefore, the `operator==()` and `operator!=()` functions are not defined on the `Status` class.

**Constants** Constants are singleton objects and are declared `const`. Note that not all globally defined MPI objects are constant. For example, `MPI::COMM_WORLD` and `MPI::COMM_SELF` are not `const`.

### 16.1.6 C++ Datatypes

Table 16.1 lists all of the C++ predefined MPI datatypes and their corresponding C and C++ datatypes, Table 16.2 lists all of the Fortran predefined MPI datatypes and their corresponding Fortran 77 datatypes. Table 16.3 lists the C++ names for all other MPI datatypes.

`MPI::BYTE` and `MPI::PACKED` conform to the same restrictions as `MPI_BYTE` and `MPI_PACKED`, listed in Sections 3.2.2 on page 29 and Sections 4.2 on page 132, respectively.

The following table defines groups of MPI predefined datatypes:

C integer:	<code>MPI::INT</code> , <code>MPI::LONG</code> , <code>MPI::SHORT</code> , <code>MPI::UNSIGNED_SHORT</code> , <code>MPI::UNSIGNED</code> , <code>MPI::UNSIGNED_LONG</code> , <code>MPI::_LONG_LONG</code> , <code>MPI::UNSIGNED_LONG_LONG</code> , <code>MPI::SIGNED_CHAR</code> , <code>MPI::UNSIGNED_CHAR</code>
Fortran integer:	<code>MPI::INTEGER</code> and handles returned from

MPI datatype	C datatype	C++ datatype
MPI::CHAR	char	char
MPI::SHORT	signed short	signed short
MPI::INT	signed int	signed int
MPI::LONG	signed long	signed long
MPI::LONG_LONG	signed long long	signed long long
MPI::SIGNED_CHAR	signed char	signed char
MPI::UNSIGNED_CHAR	unsigned char	unsigned char
MPI::UNSIGNED_SHORT	unsigned short	unsigned short
MPI::UNSIGNED	unsigned int	unsigned int
MPI::UNSIGNED_LONG	unsigned long	unsigned long int
MPI::UNSIGNED_LONG_LONG	unsigned long long	unsigned long long
MPI::FLOAT	float	float
MPI::DOUBLE	double	double
MPI::LONG_DOUBLE	long double	long double
MPI::BOOL		bool
MPI::COMPLEX		Complex<float>
MPI::DOUBLE_COMPLEX		Complex<double>
MPI::LONG_DOUBLE_COMPLEX		Complex<long double>
MPI::WCHAR	wchar_t	wchar_t
MPI::BYTE		
MPI::PACKED		

Table 16.1: C++ names for the MPI C and C++ predefined datatypes, and their corresponding C/C++ datatypes.

MPI datatype	Fortran datatype
MPI::INTEGER	INTEGER
MPI::REAL	REAL
MPI::DOUBLE_PRECISION	DOUBLE PRECISION
MPI::F_COMPLEX	COMPLEX
MPI::LOGICAL	LOGICAL
MPI::CHARACTER	CHARACTER(1)
MPI::BYTE	
MPI::PACKED	

Table 16.2: C++ names for the MPI Fortran predefined datatypes, and their corresponding Fortran 77 datatypes.

MPI datatype	Description
MPI::FLOAT_INT	C/C++ reduction type
MPI::DOUBLE_INT	C/C++ reduction type
MPI::LONG_INT	C/C++ reduction type
MPI::TWOINT	C/C++ reduction type
MPI::SHORT_INT	C/C++ reduction type
MPI::LONG_DOUBLE_INT	C/C++ reduction type
MPI::TWOREAL	Fortran reduction type
MPI::TWODOUBLE_PRECISION	Fortran reduction type
MPI::TWOINTEGER	Fortran reduction type
MPI::F_DOUBLE_COMPLEX	Optional Fortran type
MPI::INTEGER1	Explicit size type
MPI::INTEGER2	Explicit size type
MPI::INTEGER4	Explicit size type
MPI::INTEGER8	Explicit size type
MPI::INTEGER16	Explicit size type
MPI::REAL2	Explicit size type
MPI::REAL4	Explicit size type
MPI::REAL8	Explicit size type
MPI::REAL16	Explicit size type
MPI::F_COMPLEX4	Explicit size type
MPI::F_COMPLEX8	Explicit size type
MPI::F_COMPLEX16	Explicit size type
MPI::F_COMPLEX32	Explicit size type

Table 16.3: C++ names for other MPI datatypes. Implementations may also define other optional types (e.g., `MPI::INTEGER8`).

```

1      MPI::Datatype::Create_f90_integer,
2      and if available: MPI::INTEGER1,
3      MPI::INTEGER2, MPI::INTEGER4,
4      MPI::INTEGER8, MPI::INTEGER16
5      Floating point: MPI::FLOAT, MPI::DOUBLE, MPI::REAL,
6      MPI::DOUBLE_PRECISION,
7      MPI::LONG_DOUBLE
8      and handles returned from
9      MPI::Datatype::Create_f90_real,
10     and if available: MPI::REAL2,
11     MPI::REAL4, MPI::REAL8, MPI::REAL16
12     Logical: MPI::LOGICAL, MPI::BOOL
13     Complex: MPI::F_COMPLEX, MPI::COMPLEX,
14     MPI::F_DOUBLE_COMPLEX,
15     MPI::DOUBLE_COMPLEX,
16     MPI::LONG_DOUBLE_COMPLEX
17     and handles returned from
18     MPI::Datatype::Create_f90_complex,
19     and if available: MPI::F_DOUBLE_COMPLEX,
20     MPI::F_COMPLEX4, MPI::F_COMPLEX8,
21     MPI::F_COMPLEX16, MPI::F_COMPLEX32
22     Byte: MPI::BYTE

```

Valid datatypes for each reduction operation are specified below in terms of the groups defined above.

Op	Allowed Types
MPI::MAX, MPI::MIN	C integer, Fortran integer, Floating point
MPI::SUM, MPI::PROD	C integer, Fortran integer, Floating point, Complex
MPI::LAND, MPI::LOR, MPI::LXOR	C integer, Logical
MPI::BAND, MPI::BOR, MPI::BXOR	C integer, Fortran integer, Byte

MPI::MINLOC and MPI::MAXLOC perform just as their C and Fortran counterparts; see Section 5.9.4 on page 182.

### 16.1.7 Communicators

The `MPI::Comm` class hierarchy makes explicit the different kinds of communicators implicitly defined by MPI and allows them to be strongly typed. Since the original design of MPI defined only one type of handle for all types of communicators, the following clarifications are provided for the C++ design.

**Types of communicators** There are six different types of communicators: `MPI::Comm`, `MPI::Intercomm`, `MPI::Intracomm`, `MPI::Cartcomm`, `MPI::Graphcomm`, and `MPI::Distgraphcomm`. `MPI::Comm` is the abstract base communicator class, encapsulating the functionality common to all MPI communicators. `MPI::Intercomm` and `MPI::Intracomm` are derived from `MPI::Comm`. `MPI::Cartcomm`, `MPI::Graphcomm`, and `MPI::Distgraphcomm` are derived from `MPI::Intracomm`.

*Advice to users.* Initializing a derived class with an instance of a base class is not legal in C++. For instance, it is not legal to initialize a `Cartcomm` from an `Intracomm`. Moreover, because `MPI::Comm` is an abstract base class, it is non-instantiable, so that it is not possible to have an object of class `MPI::Comm`. However, it is possible to have a reference or a pointer to an `MPI::Comm`.

**Example 16.4** The following code is erroneous.

```
Intracomm intra = MPI::COMM_WORLD.Dup();
Cartcomm cart(intra);           // This is erroneous
```

*(End of advice to users.)*

`MPI::COMM_NULL` The specific type of `MPI::COMM_NULL` is implementation dependent. `MPI::COMM_NULL` must be able to be used in comparisons and initializations with all types of communicators. `MPI::COMM_NULL` must also be able to be passed to a function that expects a communicator argument in the parameter list (provided that `MPI::COMM_NULL` is an allowed value for the communicator argument).

*Rationale.* There are several possibilities for implementation of `MPI::COMM_NULL`. Specifying its required behavior, rather than its realization, provides maximum flexibility to implementors. *(End of rationale.)*

**Example 16.5** The following example demonstrates the behavior of assignment and comparison using `MPI::COMM_NULL`.

```
MPI::Intercomm comm;
comm = MPI::COMM_NULL;           // assign with COMM_NULL
if (comm == MPI::COMM_NULL)      // true
    cout << "comm is NULL" << endl;
if (MPI::COMM_NULL == comm)      // note -- a different function!
    cout << "comm is still NULL" << endl;
```

`Dup()` is not defined as a member function of `MPI::Comm`, but it is defined for the derived classes of `MPI::Comm`. `Dup()` is not virtual and it returns its OUT parameter by value.

`MPI::Comm::Clone()` The C++ language interface for MPI includes a new function `Clone()`. `MPI::Comm::Clone()` is a pure virtual function. For the derived communicator classes, `Clone()` behaves like `Dup()` except that it returns a new object by reference. The `Clone()` functions are prototyped as follows:

```
Comm& Comm::Clone() const = 0

Intracomm& Intracomm::Clone() const

Intercomm& Intercomm::Clone() const

Cartcomm& Cartcomm::Clone() const

Graphcomm& Graphcomm::Clone() const
```

```
1 Distgraphcomm& Distgraphcomm::Clone() const
```

3     *Rationale.* `Clone()` provides the “virtual dup” functionality that is expected by C++  
4 programmers and library writers. Since `Clone()` returns a new object by reference,  
5 users are responsible for eventually deleting the object. A new name is introduced  
6 rather than changing the functionality of `Dup()`. (*End of rationale.*)

8     *Advice to implementors.* Within their class declarations, prototypes for `Clone()` and  
9 `Dup()` would look like the following:

```
11 namespace MPI {
12     class Comm {
13         virtual Comm& Clone() const = 0;
14     };
15     class Intracomm : public Comm {
16         Intracomm Dup() const { ... };
17         virtual Intracomm& Clone() const { ... };
18     };
19     class Intercomm : public Comm {
20         Intercomm Dup() const { ... };
21         virtual Intercomm& Clone() const { ... };
22     };
23     // Cartcomm, Graphcomm,
24     // and Distgraphcomm are similarly defined
25 };
```

26     (*End of advice to implementors.*)

### 28 16.1.8 Exceptions

30 The C++ language interface for MPI includes the predefined error handler  
31 `MPI::ERRORS_THROW_EXCEPTIONS` for use with the `Set_errhandler()` member functions.  
32 `MPI::ERRORS_THROW_EXCEPTIONS` can only be set or retrieved by C++ functions. If a  
33 non-C++ program causes an error that invokes the `MPI::ERRORS_THROW_EXCEPTIONS` error  
34 handler, the exception will pass up the calling stack until C++ code can catch it. If there  
35 is no C++ code to catch it, the behavior is undefined. In a multi-threaded environment  
36 or if a nonblocking MPI call throws an exception while making progress in the background,  
37 the behavior is implementation dependent.

38 The error handler `MPI::ERRORS_THROW_EXCEPTIONS` causes an `MPI::Exception` to be  
39 thrown for any MPI result code other than `MPI::SUCCESS`. The public interface to  
40 `MPI::Exception` class is defined as follows:

```
41
42 namespace MPI {
43     class Exception {
44     public:
45
46         Exception(int error_code);
47
48         int Get_error_code() const;
```



```

int Get_error_class() const;
const char *Get_error_string() const;
};
};

```

*Advice to implementors.*

The exception will be thrown within the body of `MPI::ERRORS_THROW_EXCEPTIONS`. It is expected that control will be returned to the user when the exception is thrown. Some MPI functions specify certain return information in their parameters in the case of an error and `MPI_ERRORS_RETURN` is specified. The same type of return information must be provided when exceptions are thrown.

For example, `MPI_WAITALL` puts an error code for each request in the corresponding entry in the status array and returns `MPI_ERR_IN_STATUS`. When using `MPI::ERRORS_THROW_EXCEPTIONS`, it is expected that the error codes in the status array will be set appropriately before the exception is thrown.

*(End of advice to implementors.)*

### 16.1.9 Mixed-Language Operability

The C++ language interface provides functions listed below for mixed-language operability. These functions provide for a seamless transition between C and C++. For the case where the C++ class corresponding to `<CLASS>` has derived classes, functions are also provided for converting between the derived classes and the C `MPI_<CLASS>`.

```
MPI::<CLASS>& MPI::<CLASS>::operator=(const MPI_<CLASS>& data)
```

```
MPI::<CLASS>(const MPI_<CLASS>& data)
```

```
MPI::<CLASS>::operator MPI_<CLASS>() const
```

These functions are discussed in Section [16.3.4](#).

### 16.1.10 Profiling

This section specifies the requirements of a C++ profiling interface to MPI.

*Advice to implementors.* Since the main goal of profiling is to intercept function calls from user code, it is the implementor's decision how to layer the underlying implementation to allow function calls to be intercepted and profiled. If an implementation of the MPI C++ bindings is layered on top of MPI bindings in another language (such as C), or if the C++ bindings are layered on top of a profiling interface in another language, no extra profiling interface is necessary because the underlying MPI implementation already meets the MPI profiling interface requirements.

Native C++ MPI implementations that do not have access to other profiling interfaces must implement an interface that meets the requirements outlined in this section.

High-quality implementations can implement the interface outlined in this section in order to promote portable C++ profiling libraries. Implementors may wish to provide an option whether to build the C++ profiling interface or not; C++ implementations that are already layered on top of bindings in another language or another profiling

interface will have to insert a third layer to implement the C++ profiling interface.  
(*End of advice to implementors.*)

To meet the requirements of the C++ MPI profiling interface, an implementation of the MPI functions *must*:

1. Provide a mechanism through which all of the MPI defined functions may be accessed with a name shift. Thus all of the MPI functions (which normally start with the prefix “MPI:.”) should also be accessible with the prefix “PMPI:.”
2. Ensure that those MPI functions which are not replaced may still be linked into an executable image without causing name clashes.
3. Document the implementation of different language bindings of the MPI interface if they are layered on top of each other, so that profiler developer knows whether they must implement the profile interface for each binding, or can economize by implementing it only for the lowest level routines.
4. Where the implementation of different language bindings is done through a layered approach (e.g., the C++ binding is a set of “wrapper” functions which call the C implementation), ensure that these wrapper functions are separable from the rest of the library.

This is necessary to allow a separate profiling library to be correctly implemented, since (at least with Unix linker semantics) the profiling library must contain these wrapper functions if it is to perform as expected. This requirement allows the author of the profiling library to extract these functions from the original MPI library and add them into the profiling library without bringing along any other unnecessary code.

5. Provide a no-op routine MPI::Pcontrol in the MPI library.

*Advice to implementors.* There are (at least) two apparent options for implementing the C++ profiling interface: inheritance or caching. An inheritance-based approach may not be attractive because it may require a virtual inheritance implementation of the communicator classes. Thus, it is most likely that implementors will cache PMPI objects on their corresponding MPI objects. The caching scheme is outlined below.

The “real” entry points to each routine can be provided within a namespace PMPI. The non-profiling version can then be provided within a namespace MPI.

Caching instances of PMPI objects in the MPI handles provides the “has a” relationship that is necessary to implement the profiling scheme.

Each instance of an MPI object simply “wraps up” an instance of a PMPI object. MPI objects can then perform profiling actions before invoking the corresponding function in their internal PMPI object.

The key to making the profiling work by simply re-linking programs is by having a header file that *declares* all the MPI functions. The functions must be *defined* elsewhere, and compiled into a library. MPI constants should be declared *extern* in the MPI namespace. For example, the following is an excerpt from a sample `mpi.h` file:

**Example 16.6** Sample `mpi.h` file.

```

namespace PMPI {
    class Comm {
    public:
        int Get_size() const;
    };
    // etc.
};

namespace MPI {
public:
    class Comm {
    public:
        int Get_size() const;

    private:
        PMPI::Comm pmpi_comm;
    };
};

```

Note that all constructors, the assignment operator, and the destructor in the `MPI` class will need to initialize/destroy the internal `PMPI` object as appropriate.

The definitions of the functions must be in separate object files; the `PMPI` class member functions and the non-profiling versions of the `MPI` class member functions can be compiled into `libmpi.a`, while the profiling versions can be compiled into `libpmpi.a`. Note that the `PMPI` class member functions and the `MPI` constants must be in different object files than the non-profiling `MPI` class member functions in the `libmpi.a` library to prevent multiple definitions of `MPI` class member function names when linking both `libmpi.a` and `libpmpi.a`. For example:

**Example 16.7** `pmapi.cc`, to be compiled into `libmpi.a`.

```

int PMPI::Comm::Get_size() const
{
    // Implementation of MPI_COMM_SIZE
}

```

**Example 16.8** `constants.cc`, to be compiled into `libmpi.a`.

```

const MPI::Intracomm MPI::COMM_WORLD;

```

**Example 16.9** `mpi_no_profile.cc`, to be compiled into `libpmpi.a`.

```

int MPI::Comm::Get_size() const
{
    return pmpi_comm.Get_size();
}

```

**Example 16.10** `mpi_profile.cc`, to be compiled into `libmpi.a`.

```
int MPI::Comm::Get_size() const
{
    // Do profiling stuff
    int ret = pmpi_comm.Get_size();
    // More profiling stuff
    return ret;
}
```

*(End of advice to implementors.)*

## 16.2 Fortran Support

### 16.2.1 Overview

The Fortran **MPI** language bindings have been designed to be compatible with the Fortran 90 standard with additional features from Fortran 2003 and Fortran 2008 [34] + TR 29113 [35].

*Rationale.* Fortran 90 contains numerous features designed to make it a more “modern” language than Fortran 77. It seems natural that **MPI** should be able to take advantage of these new features with a set of bindings tailored to Fortran 90. In Fortran 2008 + TR 29113, the major new language features used are assumed-type and assumed-rank dummy arguments. They were defined to allow the definition of choice arguments as part of the Fortran language. Further requirements for compiler support are listed in Section 16.2.16 on page 566. *(End of rationale.)*

**MPI** defines three methods of Fortran support:

1. **INCULDE 'mpif.h'** This method is described in Section 16.2.13. The use of the include file `mpif.h` is strongly discouraged starting with **MPI-3.0**.
2. **USE mpi** This method is described in Section 16.2.14 and requires compile-time argument checking.
3. **USE mpi\_f08** This method is described in Section 16.2.15 and requires compile-time argument checking that also includes unique handle types.

Compliant **MPI-3** implementations providing a Fortran interface must provide all three Fortran support methods.

Application subroutines and functions may use either one of the modules or the `mpif.h` include file. An implementation may require the use of modules to prevent type mismatch errors.

*Advice to users.* Users are advised to utilize one of the **MPI** modules even if `mpif.h` enforces type checking on a particular system. Using a module provides several potential advantages over using an include file. *(End of advice to users.)*

ticket230-B. In a single application, it must be possible to link together routines which `USE mpi_f08`,  
 ticket230-B. `USE mpi` and `INCLUDE mpif.h`.  
 ticket234-F.

The `INTEGER` compile-time constant `MPI_SUBARRAYS` is set to `MPI_SUBARRAYS_SUPPORTED` if all buffer choice arguments are defined in explicit interfaces with assumed-type and assumed-rank [35]; otherwise it is set to `MPI_SUBARRAYS_NOT_SUPPORTED`. This constant exists with each Fortran support method, but not in the C/C++ header files. The value may be different for each Fortran support method.

Section 16.2.2 to 16.2.11 gives an overview and details on known problems when using Fortran together with MPI; Section 16.2.12 compares the Fortran problems with C. Section 16.2.13 to 16.2.15 define the Fortran support methods. Section 16.2.16 summarizes major requirements for valid MPI-3.0 implementations with Fortran support. Section 16.2.17 and Section 16.2.18 describe additional functionality that is part of the Fortran support. `MPI_F_SYNC_REG` is needed for one of the methods to prevent register optimization problems. A set of functions provides additional support for Fortran intrinsic numeric types, including parameterized types: `MPI_SIZEOF`, `MPI_TYPE_MATCH_SIZE`, `MPI_TYPE_CREATE_F90_INTEGER`, `MPI_TYPE_CREATE_F90_REAL` and `MPI_TYPE_CREATE_F90_COMPLEX`. In the context of MPI, parameterized types are Fortran intrinsic types which are specified using `KIND` type parameters.

## 16.2.2 Problems With Fortran Bindings for MPI

This section discusses a number of problems that may arise when using MPI in a Fortran program. It is intended as advice to users, and clarifies how MPI interacts with Fortran. It does not add to the standard, but is intended to clarify the standard.

As noted in the original MPI specification, the interface violates the Fortran standard in several ways. While these may cause few problems for Fortran 77 programs, they become more significant for Fortran 90 programs, so that users must exercise care when using new Fortran 90 features. The violations were originally adopted and have been retained because they are important for the usability of MPI. The rest of this section describes the potential problems in detail.

The following MPI features are inconsistent with Fortran 90 and Fortran 77.

1. An MPI subroutine with a choice argument may be called with different argument types. When using the `mpi_f08` module together with a compiler that supports Fortran 2008 + TR 29113, this problem is resolved.
2. An MPI subroutine with an assumed-size dummy argument may be passed an actual scalar argument.
3. Many MPI routines assume that actual arguments are passed by address and that arguments are not copied on entrance to or exit from the subroutine.
4. An MPI implementation may read or modify user data (e.g., communication buffers used by nonblocking communications) concurrently with a user program that is executing outside of MPI calls.
5. Several named “constants,” such as `MPI_BOTTOM`, `MPI_IN_PLACE`, `MPI_STATUS_IGNORE`, `MPI_STATUSES_IGNORE`, `MPI_ERRCODES_IGNORE`,

MPI\_UNWEIGHTED, MPI\_ARGV\_NULL, and MPI\_ARGVS\_NULL are not ordinary Fortran constants and require a special implementation. See Section 2.5.4 on page 15 for more information.

6. The memory allocation routine MPI\_ALLOC\_MEM can't be usefully used in Fortran 77/90/95 without a language extension that allows the allocated memory to be associated with a Fortran variable. Therefore, address sized integers were used in MPI-2.0 - MPI-2.2. In Fortran 2003, the TYPE(C\_PTR) pointers were added. In MPI-3.0 and later, MPI\_ALLOC\_MEM got an additional, overloaded interface to support this language feature.

Additionally, MPI is inconsistent with Fortran 77 in a number of ways, as noted below.

- MPI identifiers exceed 6 characters.
- MPI identifiers may contain underscores after the first character.
- MPI requires an include file, `mpif.h`. On systems that do not support include files, the implementation should specify the values of named constants.
- Many routines in MPI have KIND-parameterized integers (e.g., MPI\_ADDRESS\_KIND and MPI\_OFFSET\_KIND) that hold address information. On systems that do not support Fortran 90-style parameterized types, `INTEGER*8` or `INTEGER` should be used instead.

MPI-1 contained several routines that take address-sized information as input or return address-sized information as output. In C such arguments were of type `MPI_Aint` and in Fortran of type `INTEGER`. On machines where integers are smaller than addresses, these routines can lose information. In MPI-2 the use of these functions has been deprecated and they have been replaced by routines taking `INTEGER` arguments of `KIND=MPI_ADDRESS_KIND`. A number of new MPI-2 functions also take `INTEGER` arguments of non-default `KIND`. See Section 2.6 on page 17 and Section 4.1.1 on page 87 for more information.

Sections 16.2.3 to 16.2.11 describe in detail several problems between MPI and Fortran and their solutions. Some of these solutions require special capabilities from the compilers. Major requirements are summarized in Section 16.2.16 on page 566.

### 16.2.3 Problems Due to Strong Typing

All MPI functions with choice arguments associate actual arguments of different Fortran datatypes with the same dummy argument. This is not allowed by Fortran 77, and in Fortran 90 is technically only allowed if the function is overloaded with a different function for each type. In C, the use of `void*` formal arguments avoids these problems. Similar to C, with Fortran 2008 + TR 29113 (and later) together with the `mpi_f08` module, the problem is avoided by declaring choice arguments with `TYPE(*)`, `DIMENSION(..)`, i.e., as assumed-type and assumed-rank dummy arguments.

Using `INCLUDE mpif.h`, the following code fragment is technically invalid and may generate a compile-time error.

```
integer i(5)
real    x(5)
...
call mpi_send(x, 5, MPI_REAL, ...)
call mpi_send(i, 5, MPI_INTEGER, ...)
```

In practice, it is rare for compilers to do more than issue a warning. Using the `mpi_f08` or `mpi` module, the problem is usually resolved through the assumed-type and assumed-rank declarations of the dummy arguments, or with a compiler-dependent mechanism that overrides type checking for choice arguments.

It is also technically invalid in Fortran to pass a scalar actual argument to an array dummy argument that is not a choice buffer argument. Thus, when using the `mpi_f08` or `mpi` module, the following code fragment usually generates an error since the `dims` and `periods` arguments to `MPI_CART_CREATE` are declared as assumed size arrays `INTEGER :: DIMS(*)` and `LOGICAL :: PERIODS(*)`.

```
USE mpi_f08      ! or  USE mpi
INTEGER size
CALL MPI_Cart_create( comm_old,1,size,.TRUE.,.TRUE.,comm_cart,ierror )
```

Using `INCLUDE 'mpif.h'`, compiler warnings are not expected (but may occur) unless this include file also uses Fortran explicit interfaces.

#### 16.2.4 Problems Due to Data Copying and Sequence Association with Subscript Triplets

Arrays with subscript **triplets** describe Fortran subarrays with or without strides, e.g.,

```
REAL a(100,100,100)
CALL MPI_Send( a(11:17, 12:99:3, 1:100), 7*30*100, MPI_REAL, ...)
```

The handling of subscript triplets depends on the value of the constant `MPI_SUBARRAYS`:

- If `MPI_SUBARRAYS` equals `MPI_SUBARRAYS_SUPPORTED`:

Choice buffer arguments are declared as `TYPE(*)`, `DIMENSION(..)`. For example, considering the following code fragment:

```
REAL s(100), r(100)
CALL MPI_Isend(s(1:100:5), 3, MPI_REAL, ..., rq, ierror)
CALL MPI_Wait(rq, status, ierror)
CALL MPI_Irecv(r(1:100:5), 3, MPI_REAL, ..., rq, ierror)
CALL MPI_Wait(rq, status, ierror)
```

In this case, the individual elements `s(1)`, `s(6)`, and `s(11)` are sent between the start of `MPI_ISEND` and the end of `MPI_WAIT` even though the compiled code will not copy `s(1:100:5)` to a contiguous temporary scratch buffer. Instead, the compiled code will pass a descriptor to `MPI_ISEND` that allows MPI to operate directly on `s(1)`, `s(6)`, `s(11)`, ..., `s(96)`. The called `MPI_ISEND` routine will take only the first three of these elements due to the type signature “3, `MPI_REAL`”.

All nonblocking MPI functions (e.g., `MPI_ISEND`, `MPI_PUT`, `MPI_FILE_WRITE_ALL_BEGIN`) behave as if *the user-specified elements of choice buffers are copied to a contiguous scratch buffer in the MPI runtime environment*. All datatype descriptions (in the example above, “3, `MPI_REAL`”) read and store data from and to this virtual contiguous scratch buffer. Displacements in MPI derived datatypes are relative to the beginning of this virtual contiguous scratch buffer.

Upon completion of a nonblocking receive operation (e.g., when `MPI_WAIT` on a corresponding `MPI_Request` returns), it is as if the received data has been copied from the virtual contiguous scratch buffer back to the non-contiguous application buffer. In the example above, `r(1)`, `r(6)`, and `r(11)` will be filled with the received data when `MPI_WAIT` returns.

*Advice to implementors.* The Fortran descriptor for `TYPE(*)`, `DIMENSION(..)` arguments contains enough information that the MPI library can make a real contiguous copy of non-contiguous user buffers if desired. Efficient implementations may avoid such additional memory-to-memory data copying. (*End of advice to implementors.*)

*Rationale.* If `MPI_SUBARRAYS` equals `MPI_SUBARRAYS_SUPPORTED`, non-contiguous buffers are handled inside of the MPI library instead of by the compiler through argument association conventions. Therefore the scope of MPI library scratch buffers can be from the beginning of a nonblocking operation until the completion of the operation although beginning and completion are implemented in different routines. If `MPI_SUBARRAYS` equals `MPI_SUBARRAYS_NOT_SUPPORTED`, temporary copies made by the compiler will not exist throughout the duration of the entire nonblocking MPI operation, which is too short for implementing the entire MPI operation. (*End of rationale.*)

- If `MPI_SUBARRAYS` equals `MPI_SUBARRAYS_NOT_SUPPORTED`:

Implicit in MPI is the idea of a contiguous chunk of memory accessible through a linear address space. MPI copies data to and from this memory. An MPI program specifies the location of data by providing memory addresses and offsets. In the C language, sequence association rules plus pointers provide all the necessary low-level structure.

In Fortran 90, user data is not necessarily stored contiguously. For example, the array section `A(1:N:2)` involves only the elements of `A` with indices 1, 3, 5, ... . The same is true for a pointer array whose target is such a section. Most compilers ensure that an array that is a dummy argument is held in contiguous memory if it is declared with an explicit shape (e.g., `B(N)`) or is of assumed size (e.g., `B(*)`). If necessary, they do this by making a copy of the array into contiguous memory.<sup>1</sup>

Because MPI dummy buffer arguments are assumed-size arrays, this leads to a serious problem for a nonblocking call: the compiler copies the temporary array back on return but MPI continues to copy data to the memory that held it. For example, consider the following code fragment:

```
real a(100)
call MPI_Irecv(a(1:100:2), MPI_REAL, 50, ...)
```

Since the first dummy argument to `MPI_Irecv` is an assumed-size array (`<type> buf(*)`), the array section `a(1:100:2)` is copied to a temporary before being passed to `MPI_Irecv`, so that it is contiguous in memory. `MPI_Irecv` returns immediately,

<sup>1</sup>Technically, the Fortran standard is worded to allow non-contiguous storage of any array data, unless the dummy argument has the `CONTIGUOUS` attribute.



and data is copied from the temporary back into the array `a`. Sometime later, MPI may write to the address of the deallocated temporary. Copying is also a problem for `MPI_ISEND` since the temporary array may be deallocated before the data has all been sent from it.

Most Fortran 90 compilers do not make a copy if the actual argument is the whole of an explicit-shape or assumed-size array or is a ‘**simply contiguous**’ section such as `A(1:N)` of such an array. (We define ‘**simply contiguous**’ more fully in the next paragraph.) Also, many compilers treat allocatable arrays the same as they treat explicit-shape arrays in this regard (though we know of one that does not). However, the same is not true for assumed-shape and pointer arrays; since they may be discontinuous, copying is often done. It is this copying that causes problems for MPI as described in the previous paragraph.

Our formal definition of a ‘**simply contiguous**’ array section is

```
name ( [:,]... [<subscript>]:[<subscript>] [,<subscript>]... )
```

That is, there are zero or more dimensions that are selected in full, then one dimension selected without a stride, then zero or more dimensions that are selected with a simple subscript. Examples are

```
A(1:N), A(:,N), A(:,1:N,1), A(1:6,N), A(:, :, 1:N)
```

Because of Fortran’s column-major ordering, where the first index varies fastest, a ‘**simply contiguous**’ section of a contiguous array will also be contiguous.<sup>2</sup>

The same problem can occur with a scalar argument. A compiler **may** make a copy of scalar dummy arguments within a called procedure **when passed as an actual argument to a choice buffer routine**. That this can cause a problem is illustrated by the example

```
[ticket236-H.]real :: a
call user1(a,rq)
call MPI_WAIT(rq,status,ierr)
write (*,*) a

subroutine user1(buf,request)
call MPI_IRecv(buf,...,request,...)
end
```

If `a` is copied, `MPI_IRecv` will alter the copy when it completes the communication and will not alter `a` itself.

Note that copying will almost certainly occur for an argument that is a non-trivial expression (one with at least one operator or function call), a section that does not select a contiguous part of its parent (e.g., `A(1:n:2)`), a pointer whose target is such

<sup>2</sup>To keep the definition of ‘**simply contiguous**’ simple, we have chosen to require all but one of the section subscripts to be without bounds. A colon without bounds makes it obvious both to the compiler and to the reader that the whole of the dimension is selected. It would have been possible to allow cases where the whole dimension is selected with one or two bounds, but this means for the reader that the array declaration or most recent allocation has to be consulted and for the compiler that a run-time check may be required.

a section, or an assumed-shape array that is (directly or indirectly) associated with such a section.

If there is a compiler option that inhibits copying of arguments, in either the calling or called procedure, this should be employed.

If a compiler makes copies in the calling procedure of arguments that are explicit-shape or assumed-size arrays, **simply contiguous** array sections of such arrays, or scalars, and if there is no compiler option to inhibit this, then the compiler cannot be used for applications that use `MPI_GET_ADDRESS`, or any nonblocking MPI routine. If a compiler copies scalar arguments in the called procedure and there is no compiler option to inhibit this, then this compiler cannot be used for applications that use memory references across subroutine calls as in the example above.

## 16.2.5 Problems Due to Data Copying and Sequence Association with Vector Subscripts

Arrays with **vector** subscripts describe in Fortran subarrays containing a possibly irregular set of elements

```
REAL a(100)
CALL MPI_Send( A((/7,9,23,81,82/)), 5, MPI_REAL, ...)
```

Arrays with a vector subscript must not be used as actual choice buffer arguments in any nonblocking or split collective MPI operations; they may be used in blocking MPI operations.

## 16.2.6 Special Constants

MPI requires a number of special “constants” that cannot be implemented as normal Fortran constants, e.g., `MPI_BOTTOM`. The complete list can be found in Section 2.5.4 on page 15. In C, these are implemented as constant pointers, usually as `NULL` and are used where the function prototype calls for a pointer to a variable, not the variable itself.

In Fortran, **using** special values for the constants (e.g., by defining them through **parameter** statements) is not possible because an implementation cannot distinguish these values from legal data. Typically these constants are implemented as predefined static variables (e.g., a variable in an MPI-declared `COMMON` block), relying on the fact that the target compiler passes data by address. Inside the subroutine, **the address of the actual choice buffer argument can be compared with the address of such a predefined static variable.**

With `USE mpi_f08`, the attributes `INTENT(IN)`, `INTENT(OUT)`, and `INTENT(INOUT)` are used in the Fortran interface. In most cases, `INTENT(IN)` is used if the C interface uses call-by-value. For all buffer arguments and for `OUT` and `INOUT` dummy arguments that allow one of these special constants as input, an `INTENT(...)` is not specified.

## 16.2.7 Fortran Derived Types

MPI supports passing Fortran **SEQUENCE** and **BIND(C)** derived types to choice dummy arguments, **but does not support Fortran derived types that neither have the SEQUENCE nor the BIND(C) attribute.**

The following code fragment shows one possible way to send a **sequence** derived type in Fortran. The example assumes that all data is passed by address.

```

type mytype
  [ticket237-I.]SEQUENCE
  integer i
  real x
  double precision d
end type mytype

type(mytype) foo
integer blocklen(3), type(3)
integer(MPI_ADDRESS_KIND) disp(3), base

call MPI_GET_ADDRESS(foo%i, disp(1), ierr)
call MPI_GET_ADDRESS(foo%x, disp(2), ierr)
call MPI_GET_ADDRESS(foo%d, disp(3), ierr)

base = disp(1)
disp(1) = disp(1) - base
disp(2) = disp(2) - base
disp(3) = disp(3) - base

blocklen(1) = 1
blocklen(2) = 1
blocklen(3) = 1

type(1) = MPI_INTEGER
type(2) = MPI_REAL
type(3) = MPI_DOUBLE_PRECISION

call MPI_TYPE_CREATE_STRUCT(3, blocklen, disp, type, newtype, ierr)
call MPI_TYPE_COMMIT(newtype, ierr)

[ticket237-I.]
[ticket237-I.]
  call MPI_SEND(foo%i, 1, newtype, ...)

```

### 16.2.8 Optimization Problems, an Overview

MPI provides operations that may be hidden from the user code and run concurrently with it, accessing the same memory as user code. Examples include the data transfer for an `MPI_IRECV`. The optimizer of a compiler will assume that it can recognize periods when a copy of a variable can be kept in a register without reloading from or storing to memory. When the user code is working with a register copy of some variable while the hidden operation reads or writes the memory copy, problems occur. These problems are independent of the Fortran support method, i.e., they occur with the `mpi_f08` module, the `mpi` module, and the `mpif.h` include file.

This section shows four problematic usage areas (the abbreviations in parentheses are used in the table below):

- Usage of nonblocking routines (*Nonbl.*).
- Usage of one-sided routines (*1-sided*).
- Usage of MPI parallel file I/O split collective operations (*Split*).
- Use of MPI\_BOTTOM together with absolute displacements in MPI datatypes, or relative displacements between two variables in such datatypes (*Bottom*).

The following compiler optimization strategies (valid for serial code) may cause problems in MPI applications:

- Code movement and register optimization problems; see Section 16.2.9 on page 552.
- Temporary data movement and temporary memory modifications; see Section 16.2.10 on page 558.
- Permanent data movement (e.g., through garbage collection); see Section 16.2.11 on page 561.

Table 16.4 shows in which usage areas the optimization problems may only occur.

Optimization ...	... may cause a problem in following usage areas			
	Nonbl.	1-sided	Split	Bottom
Code movement and register optimization	yes	yes	no	yes
Temporary data movement	yes	yes	yes	no
Permanent data movement	yes	yes	yes	yes

Table 16.4: Occurrence of Fortran optimization problems in several usage areas

The solutions in the following sections are based on compromises

- to minimize the burden for the application programmer, e.g., as shown in Sections “Solutions” to “VOLATILE” on pages 555-558,
- to minimize the additional needs in the Fortran standard, e.g., in the Fortran 2008 TR 29113 [35],
- to minimize the drawbacks on compiler based optimization, and
- to minimize the requirements defined in Section 16.2.16 on page 566.

### 16.2.9 Problems with Code Movement and Register Optimization

#### Nonblocking operations

If a variable is local to a Fortran subroutine (i.e., not in a module or a COMMON block), the compiler will assume that it cannot be modified by a called subroutine unless it is an actual argument of the call. In the most common linkage convention, the subroutine is expected

**Example 16.11** Fortran 90 register optimization – extreme.

Source	compiled as	or compiled as
[ticket238-J.] <code>REAL :: buf, b1</code>	<code>REAL :: buf, b1</code>	<code>REAL :: buf, b1</code>
<code>call MPI_Irecv(buf,..req)</code>	<code>call MPI_Irecv(buf,..req)</code>	<code>call MPI_Irecv(buf,..req)</code>
	<code>register = buf</code>	<code>b1 = buf</code>
<code>call MPI_WAIT(req,..)</code>	<code>call MPI_WAIT(req,..)</code>	<code>call MPI_WAIT(req,..)</code>
<code>b1 = buf</code>	<code>b1 = register</code>	

to save and restore certain registers. Thus, the optimizer will assume that a register which held a valid copy of such a variable before the call will still hold a valid copy on return.

Example 16.11 shows extreme, but allowed, possibilities. `MPI_WAIT` on a concurrent thread modifies `buf` between the invocation of `MPI_Irecv` and the finish of `MPI_WAIT`. But the compiler cannot see any possibility that `buf` can be changed after `MPI_Irecv` has returned, and may schedule the load of `buf` earlier than typed in the source. It has no reason to avoid using a register to hold `buf` across the call to `MPI_WAIT`. It also may reorder the instructions as in the case on the right column.

[ticket238-J.]

**Example 16.12** Similar example with `MPI_ISEND`

Source	compiled as	with a possible MPI-internal execution sequence
<code>REAL :: buf, copy</code>	<code>REAL :: buf, copy</code>	<code>REAL :: buf, copy</code>
<code>buf = val</code>	<code>buf = val</code>	<code>buf = val</code>
<code>call MPI_ISEND(buf,..req)</code>	<code>call MPI_ISEND(buf,..req)</code>	<code>addr = &amp;buf</code>
<code>copy = buf</code>	<code>copy = buf</code>	<code>copy = buf</code>
	<code>buf = val_overwrite</code>	<code>buf = val_overwrite</code>
<code>call MPI_WAIT(req,..)</code>	<code>call MPI_WAIT(req,..)</code>	<code>send(*addr) ! within MPI_WAIT</code>
<code>buf = val_overwrite</code>		

Due to valid compiler code movement optimizations in Example 16.12, the content of `buf` may already be overwritten by the compiler when the content of `buf` is sent. The code movement is permitted because the compiler cannot detect a possible access to `buf` in `MPI_WAIT` (or in a second thread between the start of `MPI_ISEND` and the end of `MPI_WAIT`).

Such register optimization is based on moving code; here, the access to `buf` was moved from after `MPI_Wait` to before `MPI_Wait`. Note that code movement may also occur across subroutine boundaries when subroutines or functions are inlined.

This register optimization / code movement problem for nonblocking operations does not occur with MPI parallel file I/O split collective operations, because in the `..._BEGIN` and `..._END` calls, the same buffer has to be provided as an actual argument. The register optimization / code movement problem for `MPI_BOTTOM` and derived MPI datatypes may occur in each blocking and nonblocking communication or parallel file I/O operation.

### One-sided communication

An example with instruction reordering due to register optimization can be found in Section 11.7.3 on page 427.

### MPI\_BOTTOM and combining independent variables in datatypes

This section is only relevant if the MPI program uses a buffer argument to an MPI\_SEND, MPI\_RECV etc., which hides the actual variables involved. MPI\_BOTTOM with an MPI\_Datatype containing absolute addresses is one example. Creating a datatype which uses one variable as an anchor and brings along others by using MPI\_GET\_ADDRESS to determine their offsets from the anchor is another. The anchor variable would be the only one referenced in the call. Also attention must be paid if MPI operations are used that run in parallel with the user's application.

Example 16.13 shows what Fortran compilers are allowed to do.

#### Example 16.13 Fortran 90 register optimization.

This source ...	can be compiled as:
call MPI_GET_ADDRESS(buf,bufaddr, ierror)	call MPI_GET_ADDRESS(buf,...)
call MPI_TYPE_CREATE_STRUCT(1,1, bufaddr, MPI_REAL,type,ierror)	call MPI_TYPE_CREATE_STRUCT(...)
call MPI_TYPE_COMMIT(type,ierror)	call MPI_TYPE_COMMIT(...)
val_old = buf	register = buf
	val_old = register
call MPI_RECV(MPI_BOTTOM,1,type,...)	call MPI_RECV(MPI_BOTTOM,...)
val_new = buf	val_new = register

In Example 16.13, the compiler does not invalidate the register because it cannot see that MPI\_RECV changes the value of buf. The access to buf is hidden by the use of MPI\_GET\_ADDRESS and MPI\_BOTTOM.

[ticket238-J.]

#### Example 16.14 Similar example with MPI\_SEND

This source ...	can be compiled as:
! buf contains val_old	! buf contains val_old
buf = val_new	
call MPI_SEND(MPI_BOTTOM,1,type,...)	call MPI_SEND(...)
! with buf as a displacement in type	! i.e. val_old is sent
	!
	! buf=val_new is moved to here
	! and detected as dead code
	! and therefore removed
	!
buf = val_overwrite	buf = val_overwrite

In Example 16.14, several successive assignments to the same variable buf can be combined in the way, that only the last assignment is executed. Successive means that no interfering load access to this variable occurs between the assignments. The

compiler cannot detect that the call to `MPI_SEND` statement is interfering, because the load access to `buf` is hidden by the usage of `MPI_BOTTOM`.

### Solutions

The following sections show in detail how the problems with code movement and register optimization can be solved in a portable way. Application writers can partially or fully avoid these compiler optimization problems by using one or more of the special Fortran declarations with the send and receive buffers used in nonblocking operations, or in operations in which `MPI_BOTTOM` is used or datatype handles that combine several variables are used:

- Usage of the Fortran `TARGET` attribute.
- Usage of the helper routine `MPI_F_SYNC_REG`, or an equivalent user-written dummy routine.
- Declaring the buffer as a Fortran module variable or within a Fortran common block.
- Usage of the Fortran `VOLATILE` attribute.

Each of these methods solves the problems of code movement and register optimization, however, may involve different degree of performance impact, and may not be usable in every application context. These methods may not be guaranteed by the Fortran standard, but they must be guaranteed by a MPI-3.0 compliant (and later) MPI library and their compiler according to the requirements listed in Section 16.2.16 on page 566. The `VOLATILE` attribute may have the most negative impact on performance. There is one attribute that cannot be used for this purpose:

- The Fortran `ASYNCHRONOUS` attribute may not solve code movement problems in MPI applications.

Table 16.5 shows the usability of each method. Each problem category is described in detail below.

### The Fortran `TARGET` attribute

Declaring a buffer with the Fortran `TARGET` attribute in a scoping unit (or `BLOCK`) tells the compiler that any statement of the scoping unit may be executed while some pointer is associated with the buffer. Calling a library routine (e.g., an MPI routine) may imply that such a pointer is used to modify the buffer.

- The `TARGET` attribute solves problems of instruction reordering, code movement, and register optimization related to nonblocking and one-sided communication, or related to the usage of `MPI_BOTTOM` and derived datatype handles. Declaring `REAL, TARGET :: buf` solves the register optimization problem in Examples 16.11, 16.12, 16.13, and 16.14
- Unfortunately, the `TARGET` attribute does **not** solve problems caused by asynchronous accesses between the start and end of a nonblocking or one-sided communication specifically, problems caused by temporary memory modifications are not solved. Example 16.15 on page 559 can **not** be solved with the `TARGET` attribute.

[ticket238-J.]

	Nonbl.	1-sided	Bottom	Overhead may be
Examples	16.11, 16.12	Section 11.7.3	16.13, 16.14	
TARGET	solved	solved	solved	low - medium
MPI_F_SYNC_REG	solved	solved	solved	low
Module Data	solved	solved	solved	low - medium
VOLATILE	solved	solved	solved	high - huge
ASYNCHRONOUS	NOT solved	NOT solved	NOT solved	medium - high

Table 16.5: Usability of methods to prevent Fortran optimization problems

## Calling MPI\_F\_SYNC\_REG

The compiler may be prevented from moving a reference to a buffer across a call to an MPI subroutine by surrounding the call by calls to an external subroutine with the buffer as an actual argument. The MPI library provides the MPI\_F\_SYNC\_REG routine for this purpose; see Section 16.2.17 on page 568.

- The problems illustrated by the Examples 16.11 and 16.12 can be solved by calling MPI\_F\_SYNC\_REG(buf) once immediately after MPI\_WAIT.

## Example 16.11

can be solved with

call MPI\_Irecv(buf, ..req)

call MPI\_WAIT(req, ..)

call MPI\_F\_SYNC\_REG(buf)

b1 = buf

## Example 16.12

can be solved with

buf = val

call MPI\_Isend(buf, ..req)

copy = buf

call MPI\_WAIT(req, ..)

call MPI\_F\_SYNC\_REG(buf)

buf = val\_overwrite

The call to MPI\_F\_SYNC\_REG(buf) prevents moving the last line before the MPI\_WAIT call. Further calls to MPI\_F\_SYNC\_REG(buf) are not needed because it is still correct if the additional read access copy=buf is moved below MPI\_WAIT and before buf=val\_overwrite.

- The problems illustrated by the Examples 16.13 and 16.14 can be solved with two additional MPI\_F\_SYNC\_REG(buf) statements; one directly before MPI\_RECV/ MPI\_SEND, and one directly after this communication operation.

## Example 16.13

can be solved with

## Example 16.14

can be solved with



```

call MPI_F_SYNC_REG(buf)          call MPI_F_SYNC_REG(buf)
call MPI_RECV(MPI_BOTTOM,...)     call MPI_SEND(MPI_BOTTOM,...)
call MPI_F_SYNC_REG(buf)          call MPI_F_SYNC_REG(buf)

```

The first call to `MPI_F_SYNC_REG(buf)` is needed to finish all load and store references to `buf` prior to `MPI_RECV/MPI_SEND`; the second call is needed to assure that the subsequent access to `buf` are not moved before `MPI_RECV/SEND`.

- In the example in Section 11.7.3 on page 427, two asynchronous accesses must be protected: in Process 1, the access to `bbbb` must be protected similar to Example 16.11, i.e., a call to `MPI_F_SYNC_REG(bbbb)` is needed after the second `MPI_WIN_FENCE` to guarantee that further accesses to `bbbb` are not moved ahead of the call to `MPI_WIN_FENCE`. In Process 2, both calls to `MPI_WIN_FENCE` together act as a communication call with `MPI_BOTTOM` as the buffer, i.e., before the first fence and after the second fence, a call to `MPI_F_SYNC_REG(buff)` is needed to guarantee that accesses to `buff` are not moved after or ahead of the calls to `MPI_WIN_FENCE`. Using `MPI_GET` instead of `MPI_PUT`, the same calls to `MPI_F_SYNC_REG` are necessary.

#### Source of Process 1

```

bbbb = 777

call MPI_WIN_FENCE
call MPI_PUT(bbbb
into buff of process 2)

call MPI_WIN_FENCE
call MPI_F_SYNC_REG(bbbb)

```

#### Source of Process 2

```

buff = 999
call MPI_F_SYNC_REG(buff)
call MPI_WIN_FENCE

call MPI_WIN_FENCE
call MPI_F_SYNC_REG(buff)
ccc = buff

```

- The temporary memory modification problem, i.e., Example 16.15 on page 559, can **not** be solved with this method.

#### A user defined routine instead of `MPI_F_SYNC_REG`

Instead of `MPI_F_SYNC_REG`, one can also use a user defined external subroutine, which is separately compiled:

```

subroutine DD(buf)
  integer buf
end

```

Note that if the intent is declared in an explicit interface for the external subroutine, it must be `OUT` or `INOUT`. The subroutine itself may have an empty body, but the compiler does not know this and has to assume that the buffer may be altered. For example, a call to `MPI_RECV` with `MPI_BOTTOM` as buffer might be replaced by

```

call DD(buf)
call MPI_RECV(MPI_BOTTOM,...)
call DD(buf)

```

ticket238-J.

Such a user-defined routine was introduced in MPI-2.0 and is still included here to document such usage in existing application programs although new applications should prefer `MPI_F_SYNC_REG` or one of the other possibilities. In existing application, calls to such a user-written routine should be substituted by a call to `MPI_F_SYNC_REG` because the user-written routine may not be implemented according to the rules specified in Section 16.2.16 on page 566.

### Module variables and COMMON blocks

An alternative is to put the buffer or variable into a module or a common block and access it through a `USE` or `COMMON` statement in each scope where it is referenced, defined or appears as an actual argument in a call to an MPI routine. The compiler will then have to assume that the MPI procedure may alter the buffer or variable, provided that the compiler cannot infer that the MPI procedure does not reference the module or common block.

- This method solves problems of instruction reordering, code movement, and register optimization related to nonblocking and one-sided communication, or related to the usage of `MPI_BOTTOM` and derived datatype handles.
- Unfortunately, this method does **not** solve problems caused by asynchronous accesses between the start and end of a nonblocking or one-sided communication specifically, problems caused by temporary memory modifications are not solved.

### The (poorly performing) Fortran VOLATILE attribute

The `VOLATILE` attribute, gives the buffer or variable the properties needed, but it may inhibit optimization of any code containing references or definitions of the buffer or variable.

### The Fortran ASYNCHRONOUS attribute

Declaring a buffer with the `ASYNCHRONOUS` Fortran attribute in a scoping unit (or `BLOCK`) tells the compiler that any statement of the scoping unit may be executed while the buffer is affected by a pending asynchronous Fortran input/output operation. Because a Fortran compiler may implement asynchronous Fortran input/output operations with blocking I/O, the `ASYNCHRONOUS` attribute may be totally ignored by such a compiler. Therefore, the `ASYNCHRONOUS` attribute can **not** be used to solve the code movement and register optimization problem in a portable MPI program.

## 16.2.10 Temporary Data Movement and Temporary Memory Modification

The compiler is allowed to temporarily modify data in memory. Normally, this problem may occur only when overlapping communication and computation. Example 16.15 shows a possibility that could be problematic.

In the compiler-generated, possible optimization in Example 16.16, `buf(100,100)` from Example 16.15 is equivalenced with the 1-dimensional array `buf_1dim(10000)`. The nonblocking receive may asynchronously receive the data in the boundary `buf(1,1:100)` while the fused loop is temporarily using this part of the buffer.

[ticket238-J.]

**Example 16.15** Overlapping Communication and Computation.

```

USE mpi_f08
REAL :: buf(100,100)
CALL MPI_Irecv(buf(1,1:100),...req,...)
DO j=1,100
  DO i=2,100
    buf(i,j)=...
  END DO
END DO
CALL MPI_Wait(req,...)

```

[ticket238-J.]

**Example 16.16** The compiler may substitute the nested loops through loop fusion.

```

REAL :: buf(100,100), buf_1dim(10000)
EQUIVALENCE (buf(1,1), buf_1dim(1))
CALL MPI_Irecv(buf(1,1:100),...req,...)
DO h=1,100
  tmp(h)=buf(1,h)
END DO
DO j=1,10000
  buf_1dim(h)=...
END DO
DO h=1,100
  buf(1,h)=tmp(h)
END DO
CALL MPI_Wait(req,...)

```

When the `tmp` data is written back to `buf`, the previous data of `buf(1,1:100)` is restored and the received data is lost. The principle behind this optimization is that the receive buffer data `buf(1,1:100)` was temporarily moved to `tmp`.

Example 16.17 shows a second possible optimization. The whole array is temporarily moved to `local_buf`. When storing `local_buf` back to the original location `buf`, then this includes also an overwriting of the receive buffer part `buf(1,1:100)`, i.e., this storing back may overwrite the asynchronously received data.

Note, that this problem may also occurs:

- With the local buffer at the origin process, between an RMA communication call and the ensuing synchronization call; see Chapter 11 on page 389.
- With the window buffer at the target process between two ensuing RMA synchronization calls,
- With the local buffer in MPI parallel file I/O split collective operations with between the `..._BEGIN` and `..._END` calls; see Section 13.4.5 on page 482.

[ticket238-J.]

**Example 16.17** Another optimization is based on the usage of a separate memory storage area, e.g., in a GPU.

```

REAL :: buf(100,100), local_buf(100:100)
CALL MPI_Irecv(buf(1,1:100),...req,...)
local_buf = buf
DO j=1,100
  DO i=2,100
    local_buf(i,j)=....
  END DO
END DO
buf = local_buf ! may overwrite asynchronously received
                ! data in buf(1,1:100)
CALL MPI_Wait(req,...)

```

Note that such compiler optimization with temporary data movement can **not** be prevented when `buf` is declared with the `ASYNCHRONOUS` Fortran attribute.

*Rationale.* Using the `ASYNCHRONOUS` attribute for a buffer while asynchronous operations are pending, the access is restricted as if the pending operation involves the whole buffer (see the *pending I/O storage sequence affector*, Section 5.3.4 and Section 9.6.4.1 paragraphs 5 and 6 of the Fortran 2008 standard [34]). Thus, it is invalid to use parts of an array in pending nonblocking operations and other parts in numerical computation if the array is declared as `ASYNCHRONOUS`. Due to this reason and also due to the reason in Section *The Fortran ASYNCHRONOUS attribute* on page 558, the `ASYNCHRONOUS` attribute can **not** be used to solve temporary data movement problems even if the meaning of `ASYNCHRONOUS` would be extended within the Fortran standard from Fortran input/output to general nonblocking operation. (*End of rationale.*)

Note also that the methods

- `TARGET` attribute,
- calling `MPI_F_SYNC_REG` (or such a user-defined routine), and
- using module variables and `COMMON` blocks

cannot be used to prevent such temporary data movement. These methods influence compiler optimization when library routines are called. They cannot prevent the optimizations of the numerical code shown in Example 16.15 and 16.16.

Note also that compiler optimization with temporary data movement should **not** be prevented by declaring `buf` as `VOLATILE` because: The `VOLATILE` implies that all accesses to any storage unit (word) of `buf` must be directly done in the main memory exactly in the sequence defined by the application program. The `VOLATILE` attribute prevents every register or cache optimization. Therefore, `VOLATILE` may cause a huge performance degradation.

Instead of solving the problem, it is better to **prevent** the problem, i.e., when overlapping communication and computation, the nonblocking communication (or nonblocking

or split collective IO) and the computation should be executed **on different sets of variables**. In this case, the temporary memory modifications are done only on the variables used in the computation and cannot have any side effect on the data used in the nonblocking MPI operations.

*Rationale.* This is a strong restriction for application programs. To weaken this restriction, a new or modified asynchronous feature in the Fortran language would be necessary, e.g., an asynchronous attribute that can be used on parts of an array and together with asynchronous operations outside the scope of Fortran. If this would be available in a later version of the Fortran standard then this restriction also may be weakened in a later version of the MPI standard. (*End of rationale.*)

### 16.2.11 Permanent Data Movement

A Fortran compiler may implement permanent data movement during the execution of a Fortran program. This would require that pointers to such data are appropriately updated. An automatic garbage collection is a use case. Such permanent data movement is in conflict with MPI in several areas:

- MPI datatype handles with absolute addresses in combination with MPI\_BOTTOM.
- Nonblocking MPI operations (communication, one-sided, I/O) if the internally used pointers to the buffers are not updated by the Fortran runtime, or if within an MPI process, the data movement is executed in parallel to the MPI operation.

This MPI standard requires that the problems with permanent data movement are solved by the MPI library together with the used compiler; see Section 16.2.16 on page 566.

### 16.2.12 Comparison with C

In C, subroutines which modify variables that are not in the argument list will not cause register optimization problems. This is because taking pointers to storage objects by using the & operator and later referencing the objects by way of the pointer is an integral part of the language. A C compiler understands the implications, so that the problem should not occur, in general. However, some compilers do offer optional aggressive optimization levels which may not be safe. Problems due to temporary memory modifications can also occur in C. Also here, the best advice is to avoid the problem specifically, to use different variables for buffers in nonblocking MPI operations and computation that is executed while the nonblocking operations are pending.

### 16.2.13 Fortran Support Through the mpif.h Include File

The use of the `mpif.h` include file is strongly discouraged.

Because Fortran 90 is (for all practical purposes) a superset of Fortran 77, Fortran 90 (and future) programs can use the original Fortran interface. The Fortran bindings are compatible with Fortran 77 implicit-style interfaces in most cases. The include file `mpif.h` must:

- Define all named MPI constants.

- Declare MPI functions that return a value.
- Define all handles as `INTEGER`. This is reflected in the first of the two Fortran interfaces in each MPI function definition throughout this document.
- Be valid and equivalent for both fixed- and free- source form.

For each MPI routine, an implementation can choose to use an implicit or explicit interface. With each MPI routine definition, two Fortran bindings are provided (in deprecated routines, the second one may be omitted). With explicit interfaces, the first of the two must be implemented.

*Advice to users.* Instead of using `mpif.h`, the use of the `mpi_f08` or `mpi` module is strongly encouraged. Reasons are:

- Most `mpif.h` include files do not implement compile-time argument checking.
- Therefore, too many bugs in MPI applications are still undetected:
  - Missing  `ierror` as last additional argument in most Fortran bindings.
  - Declaration of a `status` as an `INTEGER` variable instead of an `INTEGER` array with size `MPI_STATUS_SIZE`.
  - Wrong argument positions, e.g., interchanging the `count` and `datatype` arguments.
  - Passing wrong MPI handles.
- The migration from `mpif.h` to the `mpi` module should be without problems (i.e., substituting `include 'mpif.h'` below an `implicit none` statement by `use mpi` before such `implicit` statement) as long as the application syntax is correct.
- Migrating portable applications to the `mpi` module, it is not expected to experience any compile or runtime problems because an `mpif.h` include file was always allowed to provide explicit Fortran interfaces.

*(End of advice to users.)*

*Rationale.* With MPI-3.0, the `mpif.h` include file was not deprecated because of backward compatibility reasons, and internally `mpif.h` and the `mpi` module can be implemented so that the same library implementation of the MPI routines can be used. *(End of rationale.)*

*Advice to implementors.* To make `mpif.h` compatible with both fixed- and free-source forms, to allow automatic inclusion by preprocessors, and to allow extended fixed-form line length, it is recommended that requirement two be met by constructing `mpif.h` without any continuation lines. This should be possible because `mpif.h` contains only declarations, and because common block declarations can be split among several lines. To support Fortran 77 as well as Fortran 90, it may be necessary to eliminate all comments from `mpif.h`. *(End of advice to implementors.)*

16.2.14 Fortran Support Through the `mpi` Module

An MPI implementation must provide a module named `mpi` that can be used in a Fortran program. This module must:

- Define all named MPI constants
- Declare MPI functions that return a value.
- Provide explicit interfaces based on the first of the two Fortran bindings that are provided for all MPI routines, i.e., this module guarantees compile-time argument checking, and allows positional and keyword-based argument lists.
- Define all handles as `INTEGER`. This is reflected in the first of the two Fortran interfaces in each MPI function definition throughout this document.
- Define all named handle types and `MPI_Status` that are used in the `mpi_f08` module. They are needed only when the application converts old-style `INTEGER` handles into a new-style handles with a named type.

An MPI implementation may provide other features in the `mpi` module that enhance the usability of MPI while maintaining adherence to the standard. For example, it may provide `INTENT` information in these interface blocks.

*Advice to implementors.* The appropriate `INTENT` may be different from what is given in the MPI generic interface. Implementations must choose `INTENT` so that the function adheres to the MPI standard, e.g., by defining the `INTENT` as provided in the `mpi_f08` bindings. (*End of advice to implementors.*)

*Rationale.* The intent given by the MPI generic interface is not precisely defined and does not in all cases correspond to the correct Fortran `INTENT`. For instance, receiving into a buffer specified by a datatype with absolute addresses may require associating `MPI_BOTTOM` with a dummy `OUT` argument. Moreover, “constants” such as `MPI_BOTTOM` and `MPI_STATUS_IGNORE` are not constants as defined by Fortran, but “special addresses” used in a nonstandard way. Finally, the MPI-1 generic intent is changed in several places by MPI-2. For instance, `MPI_IN_PLACE` changes the `intent` of an `OUT` argument to be `INOUT`. (*End of rationale.*)

*Advice to implementors.* Some compilers allow to implement a choice buffer argument in the `mpi` module with the following explicit interface:

```
INTERFACE
  SUBROUTINE MPI...(buf, ...)
    !DEC$ ATTRIBUTES NO_ARG_CHECK :: buf
    !$PRAGMA IGNORE_TKR buf
    !DIR$ IGNORE_TKR buf
    !IBM* IGNORE_TKR buf
    REAL, DIMENSION(*) :: buf
```

In this case, the `INTEGER` compile-time constant `MPI_SUBARRAYS` must be set to `MPI_SUBARRAYS_NOT_SUPPORTED`. Note, however, that it is explicitly allowed that the choice arguments can be implemented in the same way as with the `mpi_f08` module. In the case where the compiler does not provide such functionality, a set of overloaded functions may be used. See the paper of M. Hennecke [26]. (*End of advice to implementors.*)

### 16.2.15 Fortran Support Through the `mpi_f08` Module

An MPI implementation must provide a module named `mpi_f08` that can be used in a Fortran program. With this module, a second Fortran definition is added for each MPI routine, except for routines that are deprecated since MPI-3.0 or earlier. This module must:

- Define all named MPI constants.
- Declare MPI functions that return a value.
- Provide explicit interfaces for the second Fortran interface of all MPI routines, i.e., this module guarantees compile-time argument checking for all arguments which are not `TYPE(*)`.
- Provide explicit interfaces for the first Fortran interface if the second one is omitted; this is only the case in functions that are deprecated since MPI-3.0 or earlier.

*Advice to users.* It is strongly recommended to substitute calls to deprecated routines when changing from `mpif.h` or the `mpi` module to the `mpi_f08` module. (*End of advice to users.*)

- Define all handles with uniquely named handle types (instead of `INTEGER` handles in the `mpi` module). This is reflected in the second of the two Fortran interfaces in each MPI function definition throughout this document.
- Set the `INTEGER` compile-time constant `MPI_SUBARRAYS` to `MPI_SUBARRAYS_SUPPORTED` and declare choice buffers with the Fortran 2008 TR 29113 feature assumed-type and assumed-rank `TYPE(*)`, `DIMENSION(..)` if the underlying Fortran compiler supports it. With this, the use of non-contiguous sub-arrays is valid also in nonblocking routines.
- Set the `MPI_SUBARRAYS` compile-time constant to `MPI_SUBARRAYS_NOT_SUPPORTED` and declare choice buffers with a compiler-dependent mechanism that overrides type checking if the underlying Fortran compiler does not support the Fortran 2008 TR 29113 assumed-type and assumed-rank notation. In this case, the use of non-contiguous sub-arrays in nonblocking calls may be restricted as with the `mpi` module.

*Advice to implementors.* In the `MPI_SUBARRAYS_NOT_SUPPORTED` case, the choice argument may be implemented with an explicit interface with compiler directives, for example:



```

INTERFACE
  SUBROUTINE MPI_...(buf, ...)
    !DEC$ ATTRIBUTES NO_ARG_CHECK :: buf
    !$PRAGMA IGNORE_TKR buf
    !DIR$ IGNORE_TKR buf
    !IBM* IGNORE_TKR buf
    REAL, DIMENSION(*) :: buf

```

(End of advice to implementors.)

- Declare each argument with an `INTENT=IN`, `OUT`, or `INOUT` as defined in this standard.

*Rationale.* For these definitions in the `mpi_f08` bindings, in most cases, `INTENT(IN)` is used if the C interface uses call-by-value. For all buffer arguments and for `OUT` and `INOUT` dummy arguments that allow one of the non-ordinary Fortran constants (see `MPI_BOTTOM`, etc. in Section 2.5.4 on page 15) as input, an `INTENT(...)` is not specified. (End of rationale.)

- Declare all `status` and `array_of_statuses` output arguments as optional through function overloading, instead of using `MPI_STATUS_IGNORE` and `MPI_STATUSES_IGNORE`. For this, two specific bindings are provided in a generic interface where one has the optional argument and one does not.
- Declare all `array_of_errcodes` output arguments as optional through function overloading, instead of using `MPI_ERRCODES_IGNORE`.
- Declare all `sourceweights`, `destweights`, and `weights` arguments as optional through function overloading, instead of using `MPI_UNWEIGHTED`.

*Rationale.* To assure that the correspondence of the optional `ierror` argument can always be established by position, it is necessary that other arguments are not optional through using the `OPTIONAL` attribute. Therefore, function overloading is used for such other arguments. (End of rationale.)

- Declare all `ierror` output arguments as `OPTIONAL`, except for user-defined callback functions (e.g., `COMM_COPY_ATTR_FUNCTION`) and their predefined callbacks (e.g., `MPI_NULL_COPY_FN`).

*Rationale.* For user-defined callback functions (e.g., `COMM_COPY_ATTR_FUNCTION`) and their predefined callbacks (e.g., `MPI_NULL_COPY_FN`), the `ierror` argument is not optional. The MPI library must always call these routines with an actual `ierror` argument. Therefore, these user-defined functions need not to check whether the MPI library calls these routines with or without an actual `ierror` output argument. (End of rationale.)

ticket230-B.

The MPI Fortran bindings in the `mpi_f08` module are designed based on the Fortran 2008 standard [34] together with the Technical Report (TR 29113) on Further Interoperability with C [35] of the ISO/IEC JTC1/SC22/WG5 (Fortran) working group.

*Rationale.* The features in TR 29113 on further interoperability with C were decided on by ISO/IEC JTC1/SC22/WG5 and designed by PL22.3 (formerly J3) to support a higher level of integration between Fortran-specific features and C than provided in the Fortran 2008 standard; part of this design is based on requirements from the MPI Forum to support MPI-3.0. “It is the intention of ISO/IEC JTC1/SC22/WG5 that the semantics and syntax specified by this technical report be included in the next revision of the Fortran International Standard without change unless experience in the implementation and use of this feature identifies errors that need to be corrected, or changes are needed to achieve proper integration, in which case every reasonable effort will be made to minimize the impact of such changes on existing implementations.”<sup>3</sup>

This TR 29113 contains language features that are needed for the MPI bindings in the `mpi_f08` module: assumed-type and assumed-rank. It is important that any possible actual argument can be used for such dummy arguments, e.g., scalars, arrays, assumed-shape arrays, assumed-size arrays, allocatable arrays, and with any element type, e.g., `REAL`, `CHARACTER*5`, `CHARACTER*(*)`, sequence derived types, `BIND(C)` derived types. Especially for backward compatibility reasons, it is important that any possible actual argument in an implicit interface implementation of a choice buffer dummy argument can be used in an implementation with assumed-type and assumed-rank in an explicit interface.

Furthermore, the implementors of the MPI Fortran bindings can freely choose whether the interfaces are declared within a Fortran `INTERFACE` or `CONTAINS` construct, and whether all bindings are defined as native Fortran or a `BIND(C)` interface. The `INTERFACE` construct in combination with `BIND(C)` allows to implement the Fortran `mpi_f08` interface with a single set of portable wrapper routines written in C; to support all desired features in the `mpi_f08` interface, TR 29113 also has a provision for `OPTIONAL` arguments in `BIND(C)` interfaces.

The MPI Forum hereby wishes to acknowledge this important effort by the Fortran PL22.3 and WG5 committee. (*End of rationale.*)

#### 16.2.16 Requirements on Fortran Compilers

The compliance to MPI-3.0 (and later) Fortran bindings is not only a property of the MPI library itself, but is always a property of an MPI library together with the Fortran compiler it is compiled for.

*Advice to users.* Many MPI libraries are shipped together with special compilation scripts (e.g., `mpif90`, `mpicc`). These scripts start the compiler probably together with special options to guarantee this compliance. (*End of advice to users.*)

---

<sup>3</sup>[36] page iv, paragraph 7.

An MPI library is only compliant with MPI-3.0 (and later), as referred by `MPI_GET_VERSION`, if all the solutions described in Sections 16.2.3 to 16.2.11 work correctly. Based on this rule, major requirements for all three Fortran support methods (i.e., the `mpi_f08` and `mpi` modules, and `mpif.h`) are:

- The language features assumed-type and assumed-rank from Fortran 2008 TR 29113 [35] are available. This is required only for `mpi_f08`. As long as this requirement is not supported by the compiler, it is valid to build a preliminary MPI-3.0 (and not later) library, which implements the `mpi_f08` module with `MPI_SUBARRAYS` set to `MPI_SUBARRAYS_NOT_SUPPORTED`.
- Simply contiguous arrays and scalars must be passed to choice buffer dummy arguments with call by reference.
- `SEQUENCE` and `BIND(C)` derived types are valid as actual arguments passed to choice buffer dummy arguments and they are passed with call by reference.
- The `TARGET` attribute (as described in Section *The Fortran TARGET attribute* on page 555) solves the problems described in Section 16.2.9 on page 552 independent of whether the MPI library internally uses Fortran or C pointers to store the location of a buffer between start and completion of a nonblocking operation, and to handle absolute and relative addresses in MPI derived datatype handles.
- Separately compiled empty Fortran routines with implicit interfaces and separately compiled empty C routines with `BIND(C)` Fortran interfaces (as `MPI_F_SYNC_REG` on page 556 and Section 16.2.17 on page 568, and `DD` on page 557) solve the problems described in Section 16.2.9 on page 552.
- The problems with temporary data movement (as described in Section 16.2.10 on page 558) are solved as long as the application uses different sets of variables for the nonblocking communication (or nonblocking or split collective IO) and the computation when overlapping communication and computation.
- Problems caused by automatic and permanent data movement (e.g., within a garbage collection, see Section 16.2.11 on page 561) are resolved **without** any further requirements on the application program, neither on the usage of the buffers, nor on the declaration of application routines that are involved in calling MPI operations.
- All actual arguments that are allowed for a dummy argument in an implicitly defined and separately compiled Fortran routine with the given compiler (e.g., `CHARACTER(LEN=*)` strings and array of strings) must also be valid for choice buffer dummy arguments with all Fortran support methods.
- The handle and status types in `mpi_f08` (i.e., sequence derived types with `INTEGER` elements) are (handle) or can be (status) identical to one numerical storage unit or a sequence of those. These types must be valid at every location where an `INTEGER` and a fixed-size array of `INTEGER`s (i.e., handle and status in the `mpi` module and `mpif.h`) is valid, especially also within `BIND(C)` derived types defined by the application.

*Rationale.* This is not yet part of the draft N1845 of TR 29113 [36], but may be part of the final version of this TR 29113 [35]. It is already implemented in some of the available Fortran compilers (e.g., ifort and pgi).

A contrary definition of handles and statuses would have been BIND(C) derived types. With such definition, it would have been necessary that such BIND(C) derived types could be part of application-defined sequence derived types which is contradictory to the current rules about BIND(C) and Fortran storage units. *(End of rationale.)*

All of these rules are valid independently of whether the MPI routine interfaces in the `mpi_f08` and `mpi` modules are internally defined with an `INTERFACE` or `CONTAINS` construct, and with or without `BIND(C)`, and also when `mpif.h` uses explicit interfaces.

*Advice to implementors.* Some of these rules are already part of the Fortran 2003 standard if the MPI interfaces are defined without BIND(C). Additional compiler support may be necessary if BIND(C) is used. Some of these additional requirements are defined in the Fortran 2008 TR 29113 [35]. Some of these requirements for MPI-3.0 are beyond of TR 29113. (*End of advice to implementors.*)

Further requirements apply if the MPI library internally uses BIND(C) routine interfaces:

- Non-buffer arguments are `INTEGER`, `INTEGER(KIND=...)`, `CHARACTER(LEN=*)`, `LOGICAL`, and sequence derived types (handles and status in `mpi_f08`) variables and arrays, and `EXTERNAL` routines; function results are `DOUBLE PRECISION`. All these types must be valid as dummy arguments in the `BIND(C)` MPI routine interfaces. When compiling an MPI application, the compiler should not issue warnings because these types may not be interoperable with an existing type in C. Some of these types are already valid in `BIND(C)` interfaces since Fortran 2003, some may be valid through TR 29113 (e.g., `CHARACTER*(*)` and sequence derived types (not yet part of draft N1845)).
- `OPTIONAL` dummy arguments are also valid within `BIND(C)` interfaces. This requirements is part of the TR 29113.

### 16.2.17 Additional Support for Fortran Register-Memory-Synchronization

As described in Section 16.2.9 on page 552, a dummy call is needed to tell the compiler that registers are to be flushed for a given buffer or that accesses to a buffer may not be moved across a given point in the sequence of execution. It has only a Fortran binding.

MPI\_F\_SYNC\_REG(buf)

**INOUT**    buf                      initial address of buffer (choice)

MPI\_F\_SYNC\_REG(buf)

```
<type> buf(*)
```

```
MPI_F_sync_reg(buf)
```

```
TYPE(*), DIMENSION(..) :: buf
```

This routine is a no-operation. It must be compiled in the MPI library so that a Fortran compiler cannot detect in the module that the routine has an empty body. It is used only to tell the compiler that a cached register value of a variable or buffer should be flushed, i.e., stored back to the memory (when necessary) or invalidated.

*Rationale.* This function is not available in other languages because it would not be useful. This routine has no `ierror` return argument because there is no operation that can fail. (*End of rationale.*)

*Advice to implementors.* It is recommended to bind this routine to a C routine to minimize the risk that the Fortran compiler can learn that this routine is empty (and that the call to this routine can be removed as part of an optimization). It is explicitly allowed to implement this routine within the `mpi_f08` module according to the definition for the `mpi` module or `mpif.h` to circumvent the overhead of building the internal dope vector to handle the assumed-type, assumed-rank argument. (*End of advice to implementors.*)

*Advice to users.* If only a part of an array (e.g., defined by a subscript triplet) is used in a nonblocking routine, it is recommended to pass the whole array to `MPI_F_SYNC_REG` to minimize the overhead of this no-operation call. (*End of advice to users.*)

### 16.2.18 Additional Support for Fortran Numeric Intrinsic Types

The routines in this section are part of Extended Fortran Support described in Section 16.2.14.

MPI provides a small number of named datatypes that correspond to named intrinsic types supported by C and Fortran. These include `MPI_INTEGER`, `MPI_REAL`, `MPI_INT`, `MPI_DOUBLE`, etc., as well as the optional types `MPI_REAL4`, `MPI_REAL8`, etc. There is a one-to-one correspondence between language declarations and MPI types.

Fortran (starting with Fortran 90) provides so-called KIND-parameterized types. These types are declared using an intrinsic type (one of `INTEGER`, `REAL`, `COMPLEX`, `LOGICAL` and `CHARACTER`) with an optional integer `KIND` parameter that selects from among one or more variants. The specific meaning of different `KIND` values themselves are implementation dependent and not specified by the language. Fortran provides the `KIND` selection functions `selected_real_kind` for `REAL` and `COMPLEX` types, and `selected_int_kind` for `INTEGER` types that allow users to declare variables with a minimum precision or number of digits. These functions provide a portable way to declare `KIND`-parameterized `REAL`, `COMPLEX` and `INTEGER` variables in Fortran. This scheme is backward compatible with Fortran 77. `REAL` and `INTEGER` Fortran variables have a default `KIND` if none is specified. Fortran `DOUBLE PRECISION` variables are of intrinsic type `REAL` with a non-default `KIND`. The following two declarations are equivalent:

```
double precision x
real(KIND(0.0d0)) x
```

MPI provides two orthogonal methods to communicate using numeric intrinsic types. The first method can be used when variables have been declared in a portable way — using default `KIND` or using `KIND` parameters obtained with the `selected_int_kind` or `selected_real_kind` functions. With this method, MPI automatically selects the correct data size (e.g., 4 or 8 bytes) and provides representation conversion in heterogeneous environments. The second method gives the user complete control over communication by exposing machine representations.

## Parameterized Datatypes with Specified Precision and Exponent Range

MPI provides named datatypes corresponding to standard Fortran 77 numeric types — `MPI_INTEGER`, `MPI_COMPLEX`, `MPI_REAL`, `MPI_DOUBLE_PRECISION` and `MPI_DOUBLE_COMPLEX`. MPI automatically selects the correct data size and provides representation conversion in heterogeneous environments. The mechanism described in this section extends this model to support portable parameterized numeric types.

The model for supporting portable parameterized types is as follows. Real variables are declared (perhaps indirectly) using `selected_real_kind(p, r)` to determine the `KIND` parameter, where `p` is decimal digits of precision and `r` is an exponent range. Implicitly MPI maintains a two-dimensional array of predefined MPI datatypes `D(p, r)`. `D(p, r)` is defined for each value of `(p, r)` supported by the compiler, including pairs for which one value is unspecified. Attempting to access an element of the array with an index `(p, r)` not supported by the compiler is erroneous. MPI implicitly maintains a similar array of `COMPLEX` datatypes. For integers, there is a similar implicit array related to `selected_int_kind` and indexed by the requested number of digits `r`. Note that the predefined datatypes contained in these implicit arrays are not the same as the named MPI datatypes `MPI_REAL`, etc., but a new set.

*Advice to implementors.* The above description is for explanatory purposes only. It is not expected that implementations will have such internal arrays. (*End of advice to implementors.*)

*Advice to users.* `selected_real_kind()` maps a large number of `(p,r)` pairs to a much smaller number of `KIND` parameters supported by the compiler. `KIND` parameters are not specified by the language and are not portable. From the language point of view intrinsic types of the same base type and `KIND` parameter are of the same type. In order to allow interoperability in a heterogeneous environment, MPI is more stringent. The corresponding MPI datatypes match if and only if they have the same `(p,r)` value (`REAL` and `COMPLEX`) or `r` value (`INTEGER`). Thus MPI has many more datatypes than there are fundamental language types. (*End of advice to users.*)

```
MPI_TYPE_CREATE_F90_REAL(p, r, newtype)
```

IN	p	precision, in decimal digits (integer)
IN	r	decimal exponent range (integer)
OUT	newtype	the requested MPI datatype (handle)

```
int MPI_Type_create_f90_real(int p, int r, MPI_Datatype *newtype)
```

```
MPI_TYPE_CREATE_F90_REAL(P, R, NEWTYPE, IERROR)
```

```
INTEGER P, R, NEWTYPE, IERROR
```

```
MPI_Type_create_f90_real(p, r, newtype, ierror)
```

```
INTEGER, INTENT(IN) :: p, r
```

```
TYPE(MPI_Datatype), INTENT(OUT) :: newtype
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

ticket-248T.

```
{static MPI::Datatype MPI::Datatype::Create_f90_real(int p, int r) (binding
    deprecated, see Section 15.2) }
```

This function returns a predefined MPI datatype that matches a REAL variable of KIND `selected_real_kind(p, r)`. In the model described above it returns a handle for the element `D(p, r)`. Either `p` or `r` may be omitted from calls to `selected_real_kind(p, r)` (but not both). Analogously, either `p` or `r` may be set to `MPI_UNDEFINED`. In communication, an MPI datatype `A` returned by `MPI_TYPE_CREATE_F90_REAL` matches a datatype `B` if and only if `B` was returned by `MPI_TYPE_CREATE_F90_REAL` called with the same values for `p` and `r` or `B` is a duplicate of such a datatype. Restrictions on using the returned datatype with the “external32” data representation are given on page 573.

It is erroneous to supply values for `p` and `r` not supported by the compiler.

```
MPI_TYPE_CREATE_F90_COMPLEX(p, r, newtype)
```

IN	<code>p</code>	precision, in decimal digits (integer)
IN	<code>r</code>	decimal exponent range (integer)
OUT	<code>newtype</code>	the requested MPI datatype (handle)

```
int MPI_Type_create_f90_complex(int p, int r, MPI_Datatype *newtype)
```

```
MPI_TYPE_CREATE_F90_COMPLEX(P, R, NEWTYPE, IERROR)
```

```
INTEGER P, R, NEWTYPE, IERROR
```

```
MPI_Type_create_f90_complex(p, r, newtype, ierror)
```

```
INTEGER, INTENT(IN) :: p, r
```

```
TYPE(MPI_Datatype), INTENT(OUT) :: newtype
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
{static MPI::Datatype MPI::Datatype::Create_f90_complex(int p,
    int r) (binding deprecated, see Section 15.2) }
```

This function returns a predefined MPI datatype that matches a COMPLEX variable of KIND `selected_real_kind(p, r)`. Either `p` or `r` may be omitted from calls to `selected_real_kind(p, r)` (but not both). Analogously, either `p` or `r` may be set to `MPI_UNDEFINED`. Matching rules for datatypes created by this function are analogous to the matching rules for datatypes created by `MPI_TYPE_CREATE_F90_REAL`. Restrictions on using the returned datatype with the “external32” data representation are given on page 573.

It is erroneous to supply values for `p` and `r` not supported by the compiler.

```
MPI_TYPE_CREATE_F90_INTEGER(r, newtype)
```

IN	<code>r</code>	decimal exponent range, i.e., number of decimal digits (integer)
OUT	<code>newtype</code>	the requested MPI datatype (handle)

```
int MPI_Type_create_f90_integer(int r, MPI_Datatype *newtype)
```



```

1  MPI_TYPE_CREATE_F90_INTEGER(R, NEWTYPE, IERROR)
2      INTEGER R, NEWTYPE, IERROR
3
4  MPI_Type_create_f90_integer(r, newtype, ierror)
5      INTEGER, INTENT(IN) :: r
6      TYPE(MPI_Datatype), INTENT(OUT) :: newtype
7      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
8
9  {static MPI::Datatype MPI::Datatype::Create_f90_integer(int r) (binding
10      deprecated, see Section 15.2) }

```

This function returns a predefined MPI datatype that matches a `INTEGER` variable of `KIND selected_int_kind(r)`. Matching rules for datatypes created by this function are analogous to the matching rules for datatypes created by `MPI_TYPE_CREATE_F90_REAL`. Restrictions on using the returned datatype with the “external32” data representation are given on page 573.

It is erroneous to supply a value for `r` that is not supported by the compiler.

Example:

```

18  integer      longtype, quadtype
19  integer, parameter :: long = selected_int_kind(15)
20  integer(long) ii(10)
21  real(selected_real_kind(30)) x(10)
22  call MPI_TYPE_CREATE_F90_INTEGER(15, longtype, ierror)
23  call MPI_TYPE_CREATE_F90_REAL(30, MPI_UNDEFINED, quadtype, ierror)
24  ...
25
26  call MPI_SEND(ii, 10, longtype, ...)
27  call MPI_SEND(x, 10, quadtype, ...)
28

```

*Advice to users.* The datatypes returned by the above functions are predefined datatypes. They cannot be freed; they do not need to be committed; they can be used with predefined reduction operations. There are two situations in which they behave differently syntactically, but not semantically, from the MPI named predefined datatypes.

1. `MPI_TYPE_GET_ENVELOPE` returns special combinators that allow a program to retrieve the values of `p` and `r`.
2. Because the datatypes are not named, they cannot be used as compile-time initializers or otherwise accessed before a call to one of the `MPI_TYPE_CREATE_F90_` routines.

If a variable was declared specifying a non-default `KIND` value that was not obtained with `selected_real_kind()` or `selected_int_kind()`, the only way to obtain a matching MPI datatype is to use the size-based mechanism described in the next section.

(*End of advice to users.*)

*Advice to implementors.* An application may often repeat a call to `MPI_TYPE_CREATE_F90_XXXX` with the same combination of `(XXXX,p,r)`. The application is not allowed to free the returned predefined, unnamed datatype handles. To



prevent the creation of a potentially huge amount of handles, a high quality MPI implementation should return the same datatype handle for the same (REAL/COMPLEX/INTEGER,p,r) combination. Checking for the combination (p,r) in the preceding call to MPI\_TYPE\_CREATE\_F90\_xxxx and using a hash-table to find formerly generated handles should limit the overhead of finding a previously generated datatype with same combination of (xxxx,p,r). (*End of advice to implementors.*)

*Rationale.* The MPI\_TYPE\_CREATE\_F90\_REAL/COMPLEX/INTEGER interface needs as input the original range and precision values to be able to define useful and compiler-independent external (Section 13.5.2 on page 494) or user-defined (Section 13.5.3 on page 496) data representations, and in order to be able to perform automatic and efficient data conversions in a heterogeneous environment. (*End of rationale.*)

We now specify how the datatypes described in this section behave when used with the “external32” external data representation described in Section 13.5.2 on page 494.

The external32 representation specifies data formats for integer and floating point values. Integer values are represented in two’s complement big-endian format. Floating point values are represented by one of three IEEE formats. These are the IEEE “Single,” “Double” and “Double Extended” formats, requiring 4, 8 and 16 bytes of storage, respectively. For the IEEE “Double Extended” formats, MPI specifies a Format Width of 16 bytes, with 15 exponent bits, bias = +10383, 112 fraction bits, and an encoding analogous to the “Double” format.

The external32 representations of the datatypes returned by MPI\_TYPE\_CREATE\_F90\_REAL/COMPLEX/INTEGER are given by the following rules.

For MPI\_TYPE\_CREATE\_F90\_REAL:

```

if      (p > 33) or (r > 4931) then  external32 representation
                                     is undefined
else if (p > 15) or (r > 307) then  external32_size = 16
else if (p > 6) or (r > 37) then   external32_size = 8
else                                external32_size = 4

```

For MPI\_TYPE\_CREATE\_F90\_COMPLEX: twice the size as for MPI\_TYPE\_CREATE\_F90\_REAL.

For MPI\_TYPE\_CREATE\_F90\_INTEGER:

```

if      (r > 38) then  external32 representation is undefined
else if (r > 18) then  external32_size = 16
else if (r > 9) then   external32_size = 8
else if (r > 4) then   external32_size = 4
else if (r > 2) then   external32_size = 2
else                  external32_size = 1

```

If the external32 representation of a datatype is undefined, the result of using the datatype directly or indirectly (i.e., as part of another datatype or through a duplicated datatype) in operations that require the external32 representation is undefined. These operations include MPI\_PACK\_EXTERNAL, MPI\_UNPACK\_EXTERNAL and many MPI\_FILE functions, when the “external32” data representation is used. The ranges for which the external32 representation is undefined are reserved for future standardization.

## Support for Size-specific MPI Datatypes

MPI provides named datatypes corresponding to optional Fortran 77 numeric types that contain explicit byte lengths — `MPI_REAL4`, `MPI_INTEGER8`, etc. This section describes a mechanism that generalizes this model to support all Fortran numeric intrinsic types.

We assume that for each **typeclass** (integer, real, complex) and each word size there is a unique machine representation. For every pair (**typeclass**, **n**) supported by a compiler, MPI must provide a named size-specific datatype. The name of this datatype is of the form `MPI_<TYPE>n` in C and Fortran and of the form `MPI::<TYPE>n` in C++ where `<TYPE>` is one of `REAL`, `INTEGER` and `COMPLEX`, and **n** is the length in bytes of the machine representation. This datatype locally matches all variables of type (**typeclass**, **n**). The list of names for such types includes:

```
MPI_REAL4
MPI_REAL8
MPI_REAL16
MPI_COMPLEX8
MPI_COMPLEX16
MPI_COMPLEX32
MPI_INTEGER1
MPI_INTEGER2
MPI_INTEGER4
MPI_INTEGER8
MPI_INTEGER16
```

One datatype is required for each representation supported by the compiler. To be backward compatible with the interpretation of these types in MPI-1, we assume that the nonstandard declarations `REAL*n`, `INTEGER*n`, always create a variable whose representation is of size **n**. All these datatypes are predefined.

The following functions allow a user to obtain a size-specific MPI datatype for any intrinsic Fortran type.

```
MPI_SIZEOF(x, size)
```

IN	x	a Fortran variable of numeric intrinsic type (choice)
OUT	size	size of machine representation of that type (integer)

```
MPI_SIZEOF(X, SIZE, IERROR)
```

```
<type> X
```

```
INTEGER SIZE, IERROR
```

```
MPI_Sizeof(x, size, ierror)
```

```
TYPE(*) :: x
```

```
INTEGER, INTENT(OUT) :: size
```

```
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

This function returns the size in bytes of the machine representation of the given variable. It is a generic Fortran routine and has a Fortran binding only.

*Advice to users.* This function is similar to the C and C++ `sizeof` operator but behaves slightly differently. If given an array argument, it returns the size of the base element, not the size of the whole array. (*End of advice to users.*)

*Rationale.* This function is not available in other languages because it would not be useful. (*End of rationale.*)

`MPI_TYPE_MATCH_SIZE(typeclass, size, datatype)`

IN	typeclass	generic type specifier (integer)
IN	size	size, in bytes, of representation (integer)
OUT	[ticket252-W.]datatype	datatype with correct type, size (handle)

`int MPI_Type_match_size(int typeclass, int size, MPI_Datatype *datatype)`

`MPI_TYPE_MATCH_SIZE(TYPECLASS, SIZE, DATATYPE, IERROR)`  
`INTEGER TYPECLASS, SIZE, DATATYPE, IERROR`

`MPI_Type_match_size(typeclass, size, datatype, ierror)`  
`INTEGER, INTENT(IN) :: typeclass, size`  
`TYPE(MPI_Datatype), INTENT(OUT) :: datatype`  
`INTEGER, OPTIONAL, INTENT(OUT) :: ierror`

`{static MPI::Datatype MPI::Datatype::Match_size(int typeclass,`  
`int size)(binding deprecated, see Section 15.2) }`

typeclass is one of `MPI_TYPECLASS_REAL`, `MPI_TYPECLASS_INTEGER` and `MPI_TYPECLASS_COMPLEX`, corresponding to the desired **typeclass**. The function returns an MPI datatype matching a local variable of type (**typeclass**, **size**).

This function returns a reference (handle) to one of the predefined named datatypes, not a duplicate. This type cannot be freed. `MPI_TYPE_MATCH_SIZE` can be used to obtain a size-specific type that matches a Fortran numeric intrinsic type by first calling `MPI_SIZEOF` in order to compute the variable size, and then calling `MPI_TYPE_MATCH_SIZE` to find a suitable datatype. In C and C++, one can use the C function `sizeof()`, instead of `MPI_SIZEOF`. In addition, for variables of default kind the variable's size can be computed by a call to `MPI_TYPE_GET_EXTENT`, if the **typeclass** is known. It is erroneous to specify a size not supported by the compiler.

*Rationale.* This is a convenience function. Without it, it can be tedious to find the correct named type. See note to implementors below. (*End of rationale.*)

*Advice to implementors.* This function could be implemented as a series of tests.

```
int MPI_Type_match_size(int typeclass, int size, MPI_Datatype *rtype)
{
    switch(typeclass) {
        case MPI_TYPECLASS_REAL: switch(size) {
            case 4: *rtype = MPI_REAL4; return MPI_SUCCESS;
            case 8: *rtype = MPI_REAL8; return MPI_SUCCESS;
```

```

1      default: error(...);
2  }
3      case MPI_TYPECLASS_INTEGER: switch(size) {
4          case 4: *rtype = MPI_INTEGER4; return MPI_SUCCESS;
5          case 8: *rtype = MPI_INTEGER8; return MPI_SUCCESS;
6          default: error(...);      }
7      ... etc. ...
8  }
9  }

```

(End of advice to implementors.)

### Communication With Size-specific Types

The usual type matching rules apply to size-specific datatypes: a value sent with datatype `MPI_<TYPE>n` can be received with this same datatype on another process. Most modern computers use 2's complement for integers and IEEE format for floating point. Thus, communication using these size-specific datatypes will not entail loss of precision or truncation errors.

*Advice to users.* Care is required when communicating in a heterogeneous environment. Consider the following code:

```

23      real(selected_real_kind(5)) x(100)
24      call MPI_SIZEOF(x, size, ierror)
25      call MPI_TYPE_MATCH_SIZE(MPI_TYPECLASS_REAL, size, xtype, ierror)
26      if (myrank .eq. 0) then
27          ... initialize x ...
28          call MPI_SEND(x, xtype, 100, 1, ...)
29      else if (myrank .eq. 1) then
30          call MPI_RECV(x, xtype, 100, 0, ...)
31      endif
32

```

This may not work in a heterogeneous environment if the value of `size` is not the same on process 1 and process 0. There should be no problem in a homogeneous environment. To communicate in a heterogeneous environment, there are at least four options. The first is to declare variables of default type and use the MPI datatypes for these types, e.g., declare a variable of type `REAL` and use `MPI_REAL`. The second is to use `selected_real_kind` or `selected_int_kind` and with the functions of the previous section. The third is to declare a variable that is known to be the same size on all architectures (e.g., `selected_real_kind(12)` on almost all compilers will result in an 8-byte representation). The fourth is to carefully check representation size before communication. This may require explicit conversion to a variable of size that can be communicated and handshaking between sender and receiver to agree on a size.

Note finally that using the “external32” representation for I/O requires explicit attention to the representation sizes. Consider the following code:

```

real(selected_real_kind(5)) x(100)
call MPI_SIZEOF(x, size, ierror)
call MPI_TYPE_MATCH_SIZE(MPI_TYPECLASS_REAL, size, xtype, ierror)

if (myrank .eq. 0) then
    call MPI_FILE_OPEN(MPI_COMM_SELF, 'foo',
                      MPI_MODE_CREATE+MPI_MODE_WRONLY,
                      MPI_INFO_NULL, fh, ierror)
    call MPI_FILE_SET_VIEW(fh, 0, xtype, xtype, 'external32',
                          MPI_INFO_NULL, ierror)
    call MPI_FILE_WRITE(fh, x, 100, xtype, status, ierror)
    call MPI_FILE_CLOSE(fh, ierror)
endif

call MPI_BARRIER(MPI_COMM_WORLD, ierror)

if (myrank .eq. 1) then
    call MPI_FILE_OPEN(MPI_COMM_SELF, 'foo', MPI_MODE_RDONLY,
                      MPI_INFO_NULL, fh, ierror)
    call MPI_FILE_SET_VIEW(fh, 0, xtype, xtype, 'external32',
                          MPI_INFO_NULL, ierror)
    call MPI_FILE_WRITE(fh, x, 100, xtype, status, ierror)
    call MPI_FILE_CLOSE(fh, ierror)
endif

```

If processes 0 and 1 are on different machines, this code may not work as expected if the size is different on the two machines. (*End of advice to users.*)

## 16.3 Language Interoperability

### 16.3.1 Introduction

It is not uncommon for library developers to use one language to develop an applications library that may be called by an application program written in a different language. MPI currently supports ISO (previously ANSI) C, C++, and Fortran bindings. It should be possible for applications in any of the supported languages to call MPI-related functions in another language.

Moreover, MPI allows the development of client-server code, with MPI communication used between a parallel client and a parallel server. It should be possible to code the server in one language and the clients in another language. To do so, communications should be possible between applications written in different languages.

There are several issues that need to be addressed in order to achieve interoperability.

**Initialization** We need to specify how the MPI environment is initialized for all languages.

**Interlanguage passing of MPI opaque objects** We need to specify how MPI object handles are passed between languages. We also need to specify what happens when

an MPI object is accessed in one language, to retrieve information (e.g., attributes) set in another language.

**Interlanguage communication** We need to specify how messages sent in one language can be received in another language.

It is highly desirable that the solution for interlanguage interoperability be extendable to new languages, should MPI bindings be defined for such languages.

### 16.3.2 Assumptions

We assume that conventions exist for programs written in one language to call routines written in another language. These conventions specify how to link routines in different languages into one program, how to call functions in a different language, how to pass arguments between languages, and the correspondence between basic data types in different languages. In general, these conventions will be implementation dependent. Furthermore, not every basic datatype may have a matching type in other languages. For example, C/C++ character strings may not be compatible with Fortran `CHARACTER` variables. However, we assume that a Fortran `INTEGER`, as well as a (sequence associated) Fortran array of `INTEGER`s, can be passed to a C or C++ program. We also assume that Fortran, C, and C++ have address-sized integers. This does not mean that the default-size integers are the same size as default-sized pointers, but only that there is some way to hold (and pass) a C address in a Fortran integer. It is also assumed that `INTEGER(KIND=MPI_OFFSET_KIND)` can be passed from Fortran to C as `MPI_Offset`.

### 16.3.3 Initialization

A call to `MPI_INIT` or `MPI_INIT_THREAD`, from any language, initializes MPI for execution in all languages.

*Advice to users.* Certain implementations use the (inout) `argc`, `argv` arguments of the C/C++ version of `MPI_INIT` in order to propagate values for `argc` and `argv` to all executing processes. Use of the Fortran version of `MPI_INIT` to initialize MPI may result in a loss of this ability. (*End of advice to users.*)

The function `MPI_INITIALIZED` returns the same answer in all languages.

The function `MPI_FINALIZE` finalizes the MPI environments for all languages.

The function `MPI_FINALIZED` returns the same answer in all languages.

The function `MPI_ABORT` kills processes, irrespective of the language used by the caller or by the processes killed.

The MPI environment is initialized in the same manner for all languages by `MPI_INIT`. E.g., `MPI_COMM_WORLD` carries the same information regardless of language: same processes, same environmental attributes, same error handlers.

Information can be added to info objects in one language and retrieved in another.

*Advice to users.* The use of several languages in one MPI program may require the use of special options at compile and/or link time. (*End of advice to users.*)

*Advice to implementors.* Implementations may selectively link language specific MPI libraries only to codes that need them, so as not to increase the size of binaries for codes that use only one language. The MPI initialization code need perform initialization for a language only if that language library is loaded. (*End of advice to implementors.*)

## 16.3.4 Transfer of Handles

Handles are passed between Fortran and C or C++ by using an explicit C wrapper to convert Fortran handles to C handles. There is no direct access to C or C++ handles in Fortran. Handles are passed between C and C++ using overloaded C++ operators called from C++ code. There is no direct access to C++ objects from C.

The type definition `MPI_Fint` is provided in C/C++ for an integer of the size that matches a Fortran `INTEGER`; usually, `MPI_Fint` will be equivalent to `int`. With the Fortran `mpi` module or the `mpif.h` include file, a Fortran handle is a Fortran `INTEGER` value that can be used in the following conversion functions. With the Fortran `mpi_f08` module, a Fortran handle is a sequence derived type that contains an `INTEGER` field named `MPI_VAL`. This `INTEGER` value can be used in the following conversion functions.

The following functions are provided in C to convert from a Fortran communicator handle (which is an integer) to a C communicator handle, and vice versa. See also Section 2.6.5 on page 22.

```
MPI_Comm MPI_Comm_f2c(MPI_Fint comm)
```

If `comm` is a valid Fortran handle to a communicator, then `MPI_Comm_f2c` returns a valid C handle to that same communicator; if `comm = MPI_COMM_NULL` (Fortran value), then `MPI_Comm_f2c` returns a null C handle; if `comm` is an invalid Fortran handle, then `MPI_Comm_f2c` returns an invalid C handle.

```
MPI_Fint MPI_Comm_c2f(MPI_Comm comm)
```

The function `MPI_Comm_c2f` translates a C communicator handle into a Fortran handle to the same communicator; it maps a null handle into a null handle and an invalid handle into an invalid handle.

Similar functions are provided for the other types of opaque objects.

```
MPI_Datatype MPI_Type_f2c(MPI_Fint datatype)
```

```
MPI_Fint MPI_Type_c2f(MPI_Datatype datatype)
```

```
MPI_Group MPI_Group_f2c(MPI_Fint group)
```

```
MPI_Fint MPI_Group_c2f(MPI_Group group)
```

```
MPI_Request MPI_Request_f2c(MPI_Fint request)
```

```
MPI_Fint MPI_Request_c2f(MPI_Request request)
```

```
MPI_File MPI_File_f2c(MPI_Fint file)
```

```
MPI_Fint MPI_File_c2f(MPI_File file)
```

```
MPI_Win MPI_Win_f2c(MPI_Fint win)
```

```
MPI_Fint MPI_Win_c2f(MPI_Win win)
```

```
MPI_Op MPI_Op_f2c(MPI_Fint op)
```

```
MPI_Fint MPI_Op_c2f(MPI_Op op)
```

```
MPI_Info MPI_Info_f2c(MPI_Fint info)
```

```
MPI_Fint MPI_Info_c2f(MPI_Info info)
```

```

1 MPI_Errhandler MPI_Errhandler_f2c(MPI_Fint errhandler)
2
3 MPI_Fint MPI_Errhandler_c2f(MPI_Errhandler errhandler)
4

```

**Example 16.18** The example below illustrates how the Fortran MPI function `MPI_TYPE_COMMIT` can be implemented by wrapping the C MPI function `MPI_Type_commit` with a C wrapper to do handle conversions. In this example a Fortran-C interface is assumed where a Fortran function is all upper case when referred to from C and arguments are passed by addresses.

```

10
11 ! FORTRAN PROCEDURE
12 SUBROUTINE MPI_TYPE_COMMIT( DATATYPE, IERR)
13 INTEGER DATATYPE, IERR
14 CALL MPI_X_TYPE_COMMIT(DATATYPE, IERR)
15 RETURN
16 END
17
18 /* C wrapper */
19
20 void MPI_X_TYPE_COMMIT( MPI_Fint *f_handle, MPI_Fint *ierr)
21 {
22     MPI_Datatype datatype;
23
24     datatype = MPI_Type_f2c( *f_handle);
25     *ierr = (MPI_Fint)MPI_Type_commit( &datatype);
26     *f_handle = MPI_Type_c2f(datatype);
27     return;
28 }
29

```

The same approach can be used for all other MPI functions. The call to `MPI_xxx_f2c` (resp. `MPI_xxx_c2f`) can be omitted when the handle is an OUT (resp. IN) argument, rather than INOUT.

*Rationale.* The design here provides a convenient solution for the prevalent case, where a C wrapper is used to allow Fortran code to call a C library, or C code to call a Fortran library. The use of C wrappers is much more likely than the use of Fortran wrappers, because it is much more likely that a variable of type `INTEGER` can be passed to C, than a C handle can be passed to Fortran.

Returning the converted value as a function value rather than through the argument list allows the generation of efficient inlined code when these functions are simple (e.g., the identity). The conversion function in the wrapper does not catch an invalid handle argument. Instead, an invalid handle is passed below to the library function, which, presumably, checks its input arguments. (*End of rationale.*)

**C and C++** The C++ language interface provides the functions listed below for mixed-language interoperability. The token `<CLASS>` is used below to indicate any valid MPI opaque handle name (e.g., `Group`), except where noted. For the case where the C++ class corresponding to `<CLASS>` has derived classes, functions are also provided for converting between the derived classes and the C MPI\_<CLASS>.



The following function allows assignment from a C MPI handle to a C++ MPI handle.

```
MPI::<CLASS>& MPI::<CLASS>::operator=(const MPI_<CLASS>& data)
```

The constructor below creates a C++ MPI object from a C MPI handle. This allows the automatic promotion of a C MPI handle to a C++ MPI handle.

```
MPI::<CLASS>::<CLASS>(const MPI_<CLASS>& data)
```

**Example 16.19** In order for a C program to use a C++ library, the C++ library must export a C interface that provides appropriate conversions before invoking the underlying C++ library call. This example shows a C interface function that invokes a C++ library call with a C communicator; the communicator is automatically promoted to a C++ handle when the underlying C++ function is invoked.

```
// C++ library function prototype
void cpp_lib_call(MPI::Comm cpp_comm);

// Exported C function prototype
extern "C" {
    void c_interface(MPI_Comm c_comm);
}

void c_interface(MPI_Comm c_comm)
{
    // the MPI_Comm (c_comm) is automatically promoted to MPI::Comm
    cpp_lib_call(c_comm);
}
```

The following function allows conversion from C++ objects to C MPI handles. In this case, the casting operator is overloaded to provide the functionality.

```
MPI::<CLASS>::operator MPI_<CLASS>() const
```

**Example 16.20** A C library routine is called from a C++ program. The C library routine is prototyped to take an MPI\_Comm as an argument.

```
// C function prototype
extern "C" {
    void c_lib_call(MPI_Comm c_comm);
}

void cpp_function()
{
    // Create a C++ communicator, and initialize it with a dup of
    // MPI::COMM_WORLD
    MPI::Intracomm cpp_comm(MPI::COMM_WORLD.Dup());
    c_lib_call(cpp_comm);
}
```

*Rationale.* Providing conversion from C to C++ via constructors and from C++ to C via casting allows the compiler to make automatic conversions. Calling C from C++ becomes trivial, as does the provision of a C or Fortran interface to a C++ library. (*End of rationale.*)

*Advice to users.* Note that the casting and promotion operators return new handles by value. Using these new handles as INOUT parameters will affect the internal MPI object, but will *not* affect the original handle from which it was cast. (*End of advice to users.*)

It is important to note that all C++ objects with corresponding C handles can be used interchangeably by an application. For example, an application can cache an attribute on `MPI_COMM_WORLD` and later retrieve it from `MPI::COMM_WORLD`.

### 16.3.5 Status

The following two procedures are provided in C to convert from a Fortran (**with the `mpi module` or `mpif.h`**) status (which is an array of integers) to a C status (which is a structure), and vice versa. The conversion occurs on all the information in status, including that which is hidden. That is, no status information is lost in the conversion.

```
int MPI_Status_f2c(MPI_Fint *f_status, MPI_Status *c_status)
```

If `f_status` is a valid Fortran status, but not the Fortran value of `MPI_STATUS_IGNORE` or `MPI_STATUSES_IGNORE`, then `MPI_Status_f2c` returns in `c_status` a valid C status with the same content. If `f_status` is the Fortran value of `MPI_STATUS_IGNORE` or `MPI_STATUSES_IGNORE`, or if `f_status` is not a valid Fortran status, then the call is erroneous.

The C status has the same source, tag and error code values as the Fortran status, and returns the same answers when queried for count, elements, and cancellation. The conversion function may be called with a Fortran status argument that has an undefined error field, in which case the value of the error field in the C status argument is undefined.

Two global variables of type `MPI_Fint*`, `MPI_F_STATUS_IGNORE` and `MPI_F_STATUSES_IGNORE` are declared in `mpi.h`. They can be used to test, in C, whether `f_status` is the Fortran value of `MPI_STATUS_IGNORE` or `MPI_STATUSES_IGNORE`, respectively. These are global variables, not C constant expressions and cannot be used in places where C requires constant expressions. Their value is defined only between the calls to `MPI_INIT` and `MPI_FINALIZE` and should not be changed by user code.

To do the conversion in the other direction, we have the following:

```
int MPI_Status_c2f(MPI_Status *c_status, MPI_Fint *f_status)
```

This call converts a C status into a Fortran status, and has a behavior similar to `MPI_Status_f2c`. That is, the value of `c_status` must not be either `MPI_STATUS_IGNORE` or `MPI_STATUSES_IGNORE`.

*Advice to users.* There **exists no** separate conversion function for arrays of statuses, since one can simply loop through the array, converting each status. (*End of advice to users.*)

*Rationale.* The handling of `MPI_STATUS_IGNORE` is required in order to layer libraries with only a C wrapper: if the Fortran call has passed `MPI_STATUS_IGNORE`, then the

C wrapper must handle this correctly. Note that this constant need not have the same value in Fortran and C. If `MPI_Status_f2c` were to handle `MPI_STATUS_IGNORE`, then the type of its result would have to be `MPI_Status**`, which was considered an inferior solution. (*End of rationale.*)

Using the `mpi_f08` Fortran module, a status is declared as `TYPE(MPI_Status)`. The C type `MPI_F_status` can be used to pass a Fortran `TYPE(MPI_Status)` argument into a C routine. Figure 16.1 illustrates all status conversion routines. Some are only available in C, some in both C and Fortran.

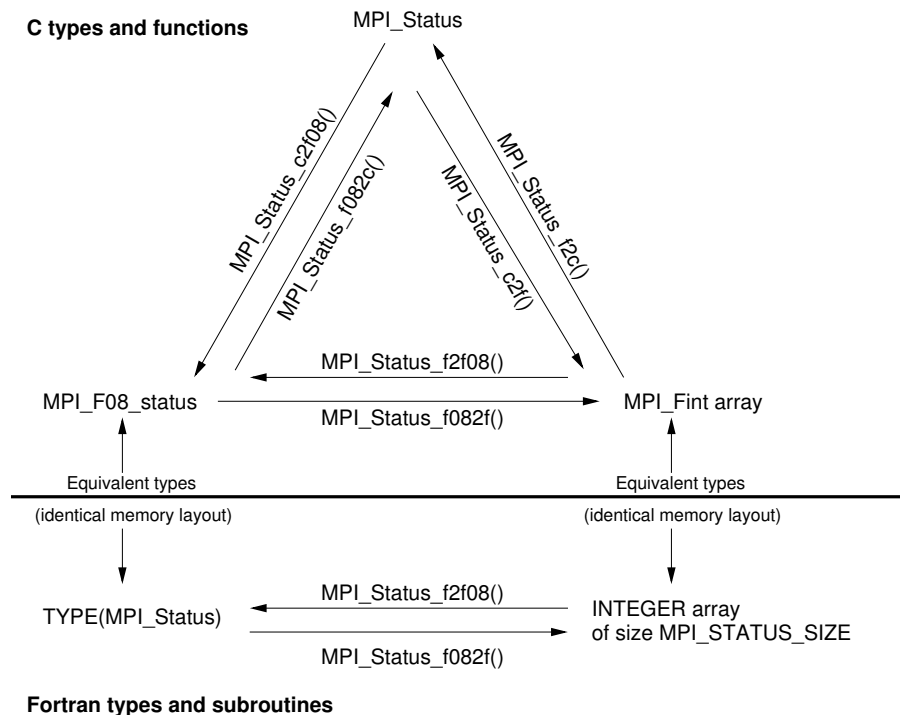


Figure 16.1: Status conversion routines

```
int MPI_Status_f082c(MPI_F_status *f08_status, MPI_Status *c_status)
```

This C routine converts a Fortran `mpi_f08` `TYPE(MPI_Status)` into a C `MPI_Status`.

```
int MPI_Status_c2f08(MPI_Status *c_status, MPI_F_status *f08_status)
```

This C routine converts a C `MPI_Status` into a Fortran `mpi_f08` `TYPE(MPI_Status)`. Conversion between the two Fortran versions of a status can be done with:

```
MPI_STATUS_F2F08(f_status, f08_status)
```

IN	<code>f_status</code>	status object declared as array
OUT	<code>f08_status</code>	status object declared as named type

```
int MPI_Status_f2f08(MPI_Fint *f_status, MPI_F_status *f08_status)
```

```
MPI_STATUS_F2F08(F_STATUS, F08_STATUS, IERROR)
```

```

1      INTEGER :: F_STATUS(MPI_STATUS_SIZE)
2      TYPE(MPI_Status) :: F08_STATUS
3      INTEGER IERROR

```

```

4      MPI_Status_f2f08(f_status, f08_status, ierror)
5      INTEGER, INTENT(IN) :: f_status(MPI_STATUS_SIZE)
6      TYPE(MPI_Status), INTENT(OUT) :: f08_status
7      INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

This routine converts a Fortran `INTEGER, DIMENSION(MPI_STATUS_SIZE)` status array into a Fortran `mpi_f08 TYPE(MPI_Status)`.

```

12      MPI_STATUS_F082F(f08_status, f_status)

```

IN	f08_status	status object declared as named type
OUT	f_status	status object declared as array

```

17      int MPI_Status_f082f(MPI_F_status *f08_status, MPI_Fint *f_status)

```

```

19      MPI_STATUS_F082F(F08_STATUS, F_STATUS, IERROR)
20      TYPE(MPI_Status) :: F08_STATUS
21      INTEGER :: F_STATUS(MPI_STATUS_SIZE)
22      INTEGER IERROR

```

```

23      MPI_Status_f082f(f08_status, f_status, ierror)
24      TYPE(MPI_Status), INTENT(IN) :: f08_status
25      INTEGER, INTENT(OUT) :: f_status(MPI_STATUS_SIZE)
26      INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

This routine converts a Fortran `mpi_f08 TYPE(MPI_Status)` into a Fortran `INTEGER, DIMENSION(MPI_STATUS_SIZE)` status array.

### 16.3.6 MPI Opaque Objects

Unless said otherwise, opaque objects are “the same” in all languages: they carry the same information, and have the same meaning in both languages. The mechanism described in the previous section can be used to pass references to MPI objects from language to language. An object created in one language can be accessed, modified or freed in another language.

We examine below in more detail, issues that arise for each type of MPI object.

#### Datatypes

Datatypes encode the same information in all languages. E.g., a datatype accessor like `MPI_TYPE_GET_EXTENT` will return the same information in all languages. If a datatype defined in one language is used for a communication call in another language, then the message sent will be identical to the message that would be sent from the first language: the same communication buffer is accessed, and the same representation conversion is performed, if needed. All predefined datatypes can be used in datatype constructors in any language. If a datatype is committed, it can be used for communication in any language.

The function `MPI_GET_ADDRESS` returns the same value in all languages. Note that we do not require that the constant `MPI_BOTTOM` have the same value in all languages (see 16.3.9, page 591).

### Example 16.21

```

! FORTRAN CODE
REAL R(5)
INTEGER TYPE, IERR, AOBLN(1), AOTYPE(1)
INTEGER (KIND=MPI_ADDRESS_KIND) AODISP(1)

! create an absolute datatype for array R
AOBLN(1) = 5
CALL MPI_GET_ADDRESS( R, AODISP(1), IERR)
AOTYPE(1) = MPI_REAL
CALL MPI_TYPE_CREATE_STRUCT(1, AOBLN,AODISP,AOTYPE, TYPE, IERR)
CALL C_ROUTINE(TYPE)

/* C code */

void C_ROUTINE(MPI_Fint *ftype)
{
    int count = 5;
    int lens[2] = {1,1};
    MPI_Aint displs[2];
    MPI_Datatype types[2], newtype;

    /* create an absolute datatype for buffer that consists
    /*   of count, followed by R(5)

    MPI_Get_address(&count, &displs[0]);
    displs[1] = 0;
    types[0] = MPI_INT;
    types[1] = MPI_Type_f2c(*ftype);
    MPI_Type_create_struct(2, lens, displs, types, &newtype);
    MPI_Type_commit(&newtype);

    MPI_Send(MPI_BOTTOM, 1, newtype, 1, 0, MPI_COMM_WORLD);
    /* the message sent contains an int count of 5, followed
    /* by the 5 REAL entries of the Fortran array R.

}

```

*Advice to implementors.* The following implementation can be used: MPI addresses, as returned by `MPI_GET_ADDRESS`, will have the same value in all languages. One obvious choice is that MPI addresses be identical to regular addresses. The address is stored in the datatype, when datatypes with absolute addresses are constructed. When a send or receive operation is performed, then addresses stored in a datatype are interpreted as displacements that are all augmented by a base address. This base address is (the address of) `buf`, or zero, if `buf = MPI_BOTTOM`. Thus, if `MPI_BOTTOM`

is zero then a send or receive call with `buf = MPI_BOTTOM` is implemented exactly as a call with a regular buffer argument: in both cases the base address is `buf`. On the other hand, if `MPI_BOTTOM` is not zero, then the implementation has to be slightly different. A test is performed to check whether `buf = MPI_BOTTOM`. If true, then the base address is zero, otherwise it is `buf`. In particular, if `MPI_BOTTOM` does not have the same value in Fortran and C/C++, then an additional test for `buf = MPI_BOTTOM` is needed in at least one of the languages.

It may be desirable to use a value other than zero for `MPI_BOTTOM` even in C/C++, so as to distinguish it from a `NULL` pointer. If `MPI_BOTTOM = c` then one can still avoid the test `buf = MPI_BOTTOM`, by using the displacement from `MPI_BOTTOM`, i.e., the regular address - `c`, as the MPI address returned by `MPI_GET_ADDRESS` and stored in absolute datatypes. (*End of advice to implementors.*)

## Callback Functions

MPI calls may associate callback functions with MPI objects: error handlers are associated with communicators and files, attribute copy and delete functions are associated with attribute keys, reduce operations are associated with operation objects, etc. In a multilanguage environment, a function passed in an MPI call in one language may be invoked by an MPI call in another language. MPI implementations must make sure that such invocation will use the calling convention of the language the function is bound to.

*Advice to implementors.* Callback functions need to have a language tag. This tag is set when the callback function is passed in by the library function (which is presumably different for each language), and is used to generate the right calling sequence when the callback function is invoked. (*End of advice to implementors.*)

## Error Handlers

*Advice to implementors.* Error handlers, have, in C and C++, a “`stdargs`” argument list. It might be useful to provide to the handler information on the language environment where the error occurred. (*End of advice to implementors.*)

## Reduce Operations

*Advice to users.* Reduce operations receive as one of their arguments the datatype of the operands. Thus, one can define “polymorphic” reduce operations that work for C, C++, and Fortran datatypes. (*End of advice to users.*)

## Addresses

Some of the datatype accessors and constructors have arguments of type `MPI_Aint` (in C) or `MPI::Aint` in C++, to hold addresses. The corresponding arguments, in Fortran, have type `INTEGER`. This causes Fortran and C/C++ to be incompatible, in an environment where addresses have 64 bits, but Fortran `INTEGER`s have 32 bits.

This is a problem, irrespective of interlanguage issues. Suppose that a Fortran process has an address space of  $\geq 4$  GB. What should be the value returned in Fortran by `MPI_ADDRESS`, for a variable with an address above  $2^{32}$ ? The design described here addresses this issue, while maintaining compatibility with current Fortran codes.

The constant `MPI_ADDRESS_KIND` is defined so that, in Fortran 90, `INTEGER(KIND=MPI_ADDRESS_KIND)` is an address sized integer type (typically, but not necessarily, the size of an `INTEGER(KIND=MPI_ADDRESS_KIND)` is 4 on 32 bit address machines and 8 on 64 bit address machines). Similarly, the constant `MPI_INTEGER_KIND` is defined so that `INTEGER(KIND=MPI_INTEGER_KIND)` is a default size `INTEGER`.

There are seven functions that have address arguments: `MPI_TYPE_HVECTOR`, `MPI_TYPE_HINDEXED`, `MPI_TYPE_STRUCT`, `MPI_ADDRESS`, `MPI_TYPE_EXTENT`, `MPI_TYPE_LB` and `MPI_TYPE_UB`.

Four new functions are provided to supplement the first four functions in this list. These functions are described in Section 4.1.1 on page 87. The remaining three functions are supplemented by the new function `MPI_TYPE_GET_EXTENT`, described in that same section. The new functions have the same functionality as the old functions in C/C++, or on Fortran systems where default `INTEGER`s are address sized. In Fortran, they accept arguments of type `INTEGER(KIND=MPI_ADDRESS_KIND)`, wherever arguments of type `MPI_Aint` and `MPI::Aint` are used in C and C++. On Fortran 77 systems that do not support the Fortran 90 `KIND` notation, and where addresses are 64 bits whereas default `INTEGER`s are 32 bits, these arguments will be of an appropriate integer type. The old functions will continue to be provided, for backward compatibility. However, users are encouraged to switch to the new functions, in Fortran, so as to avoid problems on systems with an address range  $> 2^{32}$ , and to provide compatibility across languages.

### 16.3.7 Attributes

Attribute keys can be allocated in one language and freed in another. Similarly, attribute values can be set in one language and accessed in another. To achieve this, attribute keys will be allocated in an integer range that is valid all languages. The same holds true for system-defined attribute values (such as `MPI_TAG_UB`, `MPI_WTIME_IS_GLOBAL`, etc.)

Attribute keys declared in one language are associated with copy and delete functions in that language (the functions provided by the `MPI_{TYPE,COMM,WIN}_CREATE_KEYVAL` call). When a communicator is duplicated, for each attribute, the corresponding copy function is called, using the right calling convention for the language of that function; and similarly, for the delete callback function.

*Advice to implementors.* This requires that attributes be tagged either as “C,” “C++” or “Fortran,” and that the language tag be checked in order to use the right calling convention for the callback function. (*End of advice to implementors.*)

The attribute manipulation functions described in Section 6.7 on page 264 define attributes arguments to be of type `void*` in C, and of type `INTEGER`, in Fortran. On some systems, `INTEGER`s will have 32 bits, while C/C++ pointers will have 64 bits. This is a problem if communicator attributes are used to move information from a Fortran caller to a C/C++ callee, or vice-versa.

MPI behaves as if it stores, internally, address sized attributes. If Fortran `INTEGER`s are smaller, then the Fortran function `MPI_ATTR_GET` will return the least significant part of the attribute word; the Fortran function `MPI_ATTR_PUT` will set the least significant part of the attribute word, which will be sign extended to the entire word. (These two functions may be invoked explicitly by user code, or implicitly, by attribute copying callback functions.)

As for addresses, new functions are provided that manipulate Fortran address sized attributes, and have the same functionality as the old functions in C/C++. These functions are described in Section 6.7, page 264. Users are encouraged to use these new functions.

MPI supports two types of attributes: address-valued (pointer) attributes, and integer valued attributes. C and C++ attribute functions put and get address valued attributes. Fortran attribute functions put and get integer valued attributes. When an integer valued attribute is accessed from C or C++, then `MPI_xxx_get_attr` will return the address of (a pointer to) the integer valued attribute, which is a pointer to `MPI_Aint` if the attribute was stored with Fortran `MPI_xxx_SET_ATTR`, and a pointer to `int` if it was stored with the deprecated Fortran `MPI_ATTR_PUT`. When an address valued attribute is accessed from Fortran, then `MPI_xxx_GET_ATTR` will convert the address into an integer and return the result of this conversion. This conversion is lossless if new style attribute functions are used, and an integer of kind `MPI_ADDRESS_KIND` is returned. The conversion may cause truncation if deprecated attribute functions are used. In C, the deprecated routines `MPI_Attr_put` and `MPI_Attr_get` behave identical to `MPI_Comm_set_attr` and `MPI_Comm_get_attr`.

### Example 16.22

A. Setting an attribute value in C

```
int set_val = 3;
struct foo set_struct;

/* Set a value that is a pointer to an int */
MPI_Comm_set_attr(MPI_COMM_WORLD, keyval1, &set_val);
/* Set a value that is a pointer to a struct */
MPI_Comm_set_attr(MPI_COMM_WORLD, keyval2, &set_struct);
/* Set an integer value */
MPI_Comm_set_attr(MPI_COMM_WORLD, keyval3, (void *) 17);
```

B. Reading the attribute value in C

```
int flag, *get_val;
struct foo *get_struct;

/* Upon successful return, get_val == &set_val
   (and therefore *get_val == 3) */
MPI_Comm_get_attr(MPI_COMM_WORLD, keyval1, &get_val, &flag);
/* Upon successful return, get_struct == &set_struct */
MPI_Comm_get_attr(MPI_COMM_WORLD, keyval2, &get_struct, &flag);
/* Upon successful return, get_val == (void*) 17 */
/*      i.e., (MPI_Aint) get_val == 17 */
MPI_Comm_get_attr(MPI_COMM_WORLD, keyval3, &get_val, &flag);
```

C. Reading the attribute value with (deprecated) Fortran MPI-1 calls



```

LOGICAL FLAG
INTEGER IERR, GET_VAL, GET_STRUCT

! Upon successful return, GET_VAL == &set_val, possibly truncated
CALL MPI_ATTR_GET(MPI_COMM_WORLD, KEYVAL1, GET_VAL, FLAG, IERR)
! Upon successful return, GET_STRUCT == &set_struct, possibly truncated
CALL MPI_ATTR_GET(MPI_COMM_WORLD, KEYVAL2, GET_STRUCT, FLAG, IERR)
! Upon successful return, GET_VAL == 17
CALL MPI_ATTR_GET(MPI_COMM_WORLD, KEYVAL3, GET_VAL, FLAG, IERR)

```

D. Reading the attribute value with Fortran MPI-2 calls

```

LOGICAL FLAG
INTEGER IERR
INTEGER (KIND=MPI_ADDRESS_KIND) GET_VAL, GET_STRUCT

! Upon successful return, GET_VAL == &set_val
CALL MPI_COMM_GET_ATTR(MPI_COMM_WORLD, KEYVAL1, GET_VAL, FLAG, IERR)
! Upon successful return, GET_STRUCT == &set_struct
CALL MPI_COMM_GET_ATTR(MPI_COMM_WORLD, KEYVAL2, GET_STRUCT, FLAG, IERR)
! Upon successful return, GET_VAL == 17
CALL MPI_COMM_GET_ATTR(MPI_COMM_WORLD, KEYVAL3, GET_VAL, FLAG, IERR)

```

### Example 16.23

A. Setting an attribute value with the (deprecated) Fortran MPI-1 call

```

INTEGER IERR, VAL
VAL = 7
CALL MPI_ATTR_PUT(MPI_COMM_WORLD, KEYVAL, VAL, IERR)

```

B. Reading the attribute value in C

```

int flag;
int *value;

/* Upon successful return, value points to internal MPI storage and
   *value == (int) 7 */
MPI_Comm_get_attr(MPI_COMM_WORLD, keyval, &value, &flag);

```

C. Reading the attribute value with (deprecated) Fortran MPI-1 calls

```

LOGICAL FLAG
INTEGER IERR, VALUE

! Upon successful return, VALUE == 7
CALL MPI_ATTR_GET(MPI_COMM_WORLD, KEYVAL, VALUE, FLAG, IERR)

```

D. Reading the attribute value with Fortran MPI-2 calls

```

1  LOGICAL FLAG
2  INTEGER IERR
3  INTEGER (KIND=MPI_ADDRESS_KIND) VALUE
4
5  ! Upon successful return, VALUE == 7 (sign extended)
6  CALL MPI_COMM_GET_ATTR(MPI_COMM_WORLD, KEYVAL, VALUE, FLAG, IERR)
7

```

**Example 16.24** A. Setting an attribute value via a Fortran MPI-2 call

```

9
10 INTEGER IERR
11 INTEGER(KIND=MPI_ADDRESS_KIND) VALUE1
12 INTEGER(KIND=MPI_ADDRESS_KIND) VALUE2
13 VALUE1 = 42
14 VALUE2 = INT(2, KIND=MPI_ADDRESS_KIND) ** 40
15
16 CALL MPI_COMM_SET_ATTR(MPI_COMM_WORLD, KEYVAL1, VALUE1, IERR)
17 CALL MPI_COMM_SET_ATTR(MPI_COMM_WORLD, KEYVAL2, VALUE2, IERR)
18

```

B. Reading the attribute value in C

```

19
20 int flag;
21 MPI_Aint *value1, *value2;
22
23 /* Upon successful return, value1 points to internal MPI storage and
24    *value1 == 42 */
25 MPI_Comm_get_attr(MPI_COMM_WORLD, keyval1, &value1, &flag);
26 /* Upon successful return, value2 points to internal MPI storage and
27    *value2 == 2^40 */
28 MPI_Comm_get_attr(MPI_COMM_WORLD, keyval2, &value2, &flag);
29

```

C. Reading the attribute value with (deprecated) Fortran MPI-1 calls

```

30
31 LOGICAL FLAG
32 INTEGER IERR, VALUE1, VALUE2
33
34 ! Upon successful return, VALUE1 == 42
35 CALL MPI_ATTR_GET(MPI_COMM_WORLD, KEYVAL1, VALUE1, FLAG, IERR)
36 ! Upon successful return, VALUE2 == 2^40, or 0 if truncation
37 ! needed (i.e., the least significant part of the attribute word)
38 CALL MPI_ATTR_GET(MPI_COMM_WORLD, KEYVAL2, VALUE2, FLAG, IERR)
39

```

D. Reading the attribute value with Fortran MPI-2 calls

```

40
41 LOGICAL FLAG
42 INTEGER IERR
43 INTEGER (KIND=MPI_ADDRESS_KIND) VALUE1, VALUE2
44
45 ! Upon successful return, VALUE1 == 42
46 CALL MPI_COMM_GET_ATTR(MPI_COMM_WORLD, KEYVAL1, VALUE1, FLAG, IERR)
47 ! Upon successful return, VALUE2 == 2^40
48 CALL MPI_COMM_GET_ATTR(MPI_COMM_WORLD, KEYVAL2, VALUE2, FLAG, IERR)

```

The predefined MPI attributes can be integer valued or address valued. Predefined integer valued attributes, such as `MPI_TAG_UB`, behave as if they were put by a call to the deprecated Fortran routine `MPI_ATTR_PUT`, i.e., in Fortran, `MPI_COMM_GET_ATTR(MPI_COMM_WORLD, MPI_TAG_UB, val, flag, ierr)` will return in `val` the upper bound for tag value; in C, `MPI_Comm_get_attr(MPI_COMM_WORLD, MPI_TAG_UB, &p, &flag)` will return in `p` a pointer to an int containing the upper bound for tag value.

Address valued predefined attributes, such as `MPI_WIN_BASE` behave as if they were put by a C call, i.e., in Fortran, `MPI_WIN_GET_ATTR(win, MPI_WIN_BASE, val, flag, ierror)` will return in `val` the base address of the window, converted to an integer. In C, `MPI_Win_get_attr(win, MPI_WIN_BASE, &p, &flag)` will return in `p` a pointer to the window base, cast to `(void *)`.

*Rationale.* The design is consistent with the behavior specified for predefined attributes, and ensures that no information is lost when attributes are passed from language to language. Because the language interoperability for predefined attributes was defined based on `MPI_ATTR_PUT`, this definition is kept for compatibility reasons although the routine itself is now deprecated. (*End of rationale.*)

*Advice to implementors.* Implementations should tag attributes either as (1) address attributes, (2) as `INTEGER(KIND=MPI_ADDRESS_KIND)` attributes or (3) as `INTEGER` attributes, according to whether they were set in (1) C (with `MPI_Attr_put` or `MPI_Xxx_set_attr`), (2) in Fortran with `MPI_XXX_SET_ATTR` or (3) with the deprecated Fortran routine `MPI_ATTR_PUT`. Thus, the right choice can be made when the attribute is retrieved. (*End of advice to implementors.*)

### 16.3.8 Extra State

Extra-state should not be modified by the copy or delete callback functions. (This is obvious from the C binding, but not obvious from the Fortran binding). However, these functions may update state that is indirectly accessed via extra-state. E.g., in C, extra-state can be a pointer to a data structure that is modified by the copy or callback functions; in Fortran, extra-state can be an index into an entry in a `COMMON` array that is modified by the copy or callback functions. In a multithreaded environment, users should be aware that distinct threads may invoke the same callback function concurrently: if this function modifies state associated with extra-state, then mutual exclusion code must be used to protect updates and accesses to the shared state.

### 16.3.9 Constants

MPI constants have the same value in all languages, unless specified otherwise. This does not apply to constant handles (`MPI_INT`, `MPI_COMM_WORLD`, `MPI_ERRORS_RETURN`, `MPI_SUM`, etc.) These handles need to be converted, as explained in Section 16.3.4. Constants that specify maximum lengths of strings (see Section A.1.1 for a listing) have a value one less in Fortran than C/C++ since in C/C++ the length includes the null terminating character. Thus, these constants represent the amount of space which must be allocated to hold the largest possible such string, rather than the maximum number of printable characters the string could contain.

*Advice to users.* This definition means that it is safe in C/C++ to allocate a buffer to receive a string using a declaration like

```
char name [MPI_MAX_OBJECT_NAME];
```

*(End of advice to users.)*

Also constant “addresses,” i.e., special values for reference arguments that are not handles, such as MPI\_BOTTOM or MPI\_STATUS\_IGNORE may have different values in different languages.

*Rationale.* The current MPI standard specifies that MPI\_BOTTOM can be used in initialization expressions in C, but not in Fortran. Since Fortran does not normally support call by value, then MPI\_BOTTOM must be in Fortran the name of a predefined static variable, e.g., a variable in an MPI declared COMMON block. On the other hand, in C, it is natural to take MPI\_BOTTOM = 0 (Caveat: Defining MPI\_BOTTOM = 0 implies that NULL pointer cannot be distinguished from MPI\_BOTTOM; it may be that MPI\_BOTTOM = 1 is better ...) Requiring that the Fortran and C values be the same will complicate the initialization process. *(End of rationale.)*

### 16.3.10 Interlanguage Communication

The type matching rules for communications in MPI are not changed: the datatype specification for each item sent should match, in type signature, the datatype specification used to receive this item (unless one of the types is MPI\_PACKED). Also, the type of a message item should match the type declaration for the corresponding communication buffer location, unless the type is MPI\_BYTE or MPI\_PACKED. Interlanguage communication is allowed if it complies with these rules.

**Example 16.25** In the example below, a Fortran array is sent from Fortran and received in C.

```
! FORTRAN CODE
REAL R(5)
INTEGER TYPE, IERR, MYRANK, AOBLEN(1), AOTYPE(1)
INTEGER (KIND=MPI_ADDRESS_KIND) AODISP(1)

! create an absolute datatype for array R
AOBLEN(1) = 5
CALL MPI_GET_ADDRESS( R, AODISP(1), IERR)
AOTYPE(1) = MPI_REAL
CALL MPI_TYPE_CREATE_STRUCT(1, AOBLEN,AODISP,AOTYPE, TYPE, IERR)
CALL MPI_TYPE_COMMIT(TYPE, IERR)

CALL MPI_COMM_RANK( MPI_COMM_WORLD, MYRANK, IERR)
IF (MYRANK.EQ.0) THEN
    CALL MPI_SEND( MPI_BOTTOM, 1, TYPE, 1, 0, MPI_COMM_WORLD, IERR)
ELSE
    CALL C_ROUTINE(TYPE)
END IF
```

```
/* C code */
```

```
void C_ROUTINE(MPI_Fint *fhandle)
```

```
{
```

```
    MPI_Datatype type;
```

```
    MPI_Status status;
```

```
    type = MPI_Type_f2c(*fhandle);
```

```
    MPI_Recv( MPI_BOTTOM, 1, type, 0, 0, MPI_COMM_WORLD, &status);
```

```
}
```

MPI implementors may weaken these type matching rules, and allow messages to be sent with Fortran types and received with C types, and vice versa, when those types match. I.e., if the Fortran type `INTEGER` is identical to the C type `int`, then an MPI implementation may allow data to be sent with datatype `MPI_INTEGER` and be received with datatype `MPI_INT`. However, such code is not portable.

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# Annex A

## Language Bindings Summary

In this section we summarize the specific bindings for C, Fortran, and C++. First we present the constants, type definitions, info values and keys. Then we present the routine prototypes separately for each binding. Listings are alphabetical within chapter.

### A.1 Defined Values and Handles

#### A.1.1 Defined Constants

The C and Fortran name is listed in the left column and the C++ name is listed in the middle or right column. Constants with the type `const int` may also be implemented as literal integer constants substituted by the preprocessor.

Return Codes	
C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type: <code>const int</code>
Fortran type: <code>INTEGER</code>	(or unnamed <code>enum</code> )
<code>MPI_SUCCESS</code>	<code>MPI::SUCCESS</code>
<code>MPI_ERR_BUFFER</code>	<code>MPI::ERR_BUFFER</code>
<code>MPI_ERR_COUNT</code>	<code>MPI::ERR_COUNT</code>
<code>MPI_ERR_TYPE</code>	<code>MPI::ERR_TYPE</code>
<code>MPI_ERR_TAG</code>	<code>MPI::ERR_TAG</code>
<code>MPI_ERR_COMM</code>	<code>MPI::ERR_COMM</code>
<code>MPI_ERR_RANK</code>	<code>MPI::ERR_RANK</code>
<code>MPI_ERR_REQUEST</code>	<code>MPI::ERR_REQUEST</code>
<code>MPI_ERR_ROOT</code>	<code>MPI::ERR_ROOT</code>
<code>MPI_ERR_GROUP</code>	<code>MPI::ERR_GROUP</code>
<code>MPI_ERR_OP</code>	<code>MPI::ERR_OP</code>
<code>MPI_ERR_TOPOLOGY</code>	<code>MPI::ERR_TOPOLOGY</code>
<code>MPI_ERR_DIMS</code>	<code>MPI::ERR_DIMS</code>
<code>MPI_ERR_ARG</code>	<code>MPI::ERR_ARG</code>
<code>MPI_ERR_UNKNOWN</code>	<code>MPI::ERR_UNKNOWN</code>
<code>MPI_ERR_TRUNCATE</code>	<code>MPI::ERR_TRUNCATE</code>
<code>MPI_ERR_OTHER</code>	<code>MPI::ERR_OTHER</code>
<code>MPI_ERR_INTERN</code>	<code>MPI::ERR_INTERN</code>
<code>MPI_ERR_PENDING</code>	<code>MPI::ERR_PENDING</code>

(Continued on next page)

**Return Codes (continued)**

MPI_ERR_IN_STATUS	MPI::ERR_IN_STATUS
MPI_ERR_ACCESS	MPI::ERR_ACCESS
MPI_ERR_AMODE	MPI::ERR_AMODE
MPI_ERR_ASSERT	MPI::ERR_ASSERT
MPI_ERR_BAD_FILE	MPI::ERR_BAD_FILE
MPI_ERR_BASE	MPI::ERR_BASE
MPI_ERR_CONVERSION	MPI::ERR_CONVERSION
MPI_ERR_DISP	MPI::ERR_DISP
MPI_ERR_DUP_DATAREP	MPI::ERR_DUP_DATAREP
MPI_ERR_FILE_EXISTS	MPI::ERR_FILE_EXISTS
MPI_ERR_FILE_IN_USE	MPI::ERR_FILE_IN_USE
MPI_ERR_FILE	MPI::ERR_FILE
MPI_ERR_INFO_KEY	MPI::ERR_INFO_VALUE
MPI_ERR_INFO_NOKEY	MPI::ERR_INFO_NOKEY
MPI_ERR_INFO_VALUE	MPI::ERR_INFO_KEY
MPI_ERR_INFO	MPI::ERR_INFO
MPI_ERR_IO	MPI::ERR_IO
MPI_ERR_KEYVAL	MPI::ERR_KEYVAL
MPI_ERR_LOCKTYPE	MPI::ERR_LOCKTYPE
MPI_ERR_NAME	MPI::ERR_NAME
MPI_ERR_NO_MEM	MPI::ERR_NO_MEM
MPI_ERR_NOT_SAME	MPI::ERR_NOT_SAME
MPI_ERR_NO_SPACE	MPI::ERR_NO_SPACE
MPI_ERR_NO_SUCH_FILE	MPI::ERR_NO_SUCH_FILE
MPI_ERR_PORT	MPI::ERR_PORT
MPI_ERR_QUOTA	MPI::ERR_QUOTA
MPI_ERR_READ_ONLY	MPI::ERR_READ_ONLY
MPI_ERR_RMA_CONFLICT	MPI::ERR_RMA_CONFLICT
MPI_ERR_RMA_SYNC	MPI::ERR_RMA_SYNC
MPI_ERR_SERVICE	MPI::ERR_SERVICE
MPI_ERR_SIZE	MPI::ERR_SIZE
MPI_ERR_SPAWN	MPI::ERR_SPAWN
MPI_ERR_UNSUPPORTED_DATAREP	MPI::ERR_UNSUPPORTED_DATAREP
MPI_ERR_UNSUPPORTED_OPERATION	MPI::ERR_UNSUPPORTED_OPERATION
MPI_ERR_WIN	MPI::ERR_WIN
MPI_ERR_LASTCODE	MPI::ERR_LASTCODE

**Buffer Address Constants**

C type: <code>void * const</code>	C++ type:
Fortran type: (predefined memory location)	<code>void * const</code>
MPI_BOTTOM	MPI::BOTTOM
MPI_IN_PLACE	MPI::IN_PLACE



Assorted Constants		1
		2
C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type:	3
Fortran type: <code>INTEGER</code>	<code>const int</code> (or unnamed <code>enum</code> )	4
<code>MPI_PROC_NULL</code>	<code>MPI::PROC_NULL</code>	5
<code>MPI_ANY_SOURCE</code>	<code>MPI::ANY_SOURCE</code>	6
<code>MPI_ANY_TAG</code>	<code>MPI::ANY_TAG</code>	7
<code>MPI_UNDEFINED</code>	<code>MPI::UNDEFINED</code>	8
<code>MPI_BSEND_OVERHEAD</code>	<code>MPI::BSEND_OVERHEAD</code>	9
<code>MPI_KEYVAL_INVALID</code>	<code>MPI::KEYVAL_INVALID</code>	10
<code>MPI_LOCK_EXCLUSIVE</code>	<code>MPI::LOCK_EXCLUSIVE</code>	11
<code>MPI_LOCK_SHARED</code>	<code>MPI::LOCK_SHARED</code>	12
<code>MPI_ROOT</code>	<code>MPI::ROOT</code>	13
[ticket234-F.] <code>MPI_SUBARRAYS</code> (Fortran only)		14
[ticket234-F.] <code>MPI_SUBARRAYS_SUPPORTED</code> (Fortran only)		15
[ticket234-F.] <code>MPI_SUBARRAYS_NOT_SUPPORTED</code> (Fortran only)		16

#### Status size and reserved index values (Fortran only)

Fortran type: <code>INTEGER</code>		17
<code>MPI_STATUS_SIZE</code>	Not defined for C++	18
<code>MPI_SOURCE</code>	Not defined for C++	19
<code>MPI_TAG</code>	Not defined for C++	20
<code>MPI_ERROR</code>	Not defined for C++	21

#### Variable Address Size (Fortran only)

Fortran type: <code>INTEGER</code>		22
<code>MPI_ADDRESS_KIND</code>	Not defined for C++	23
<code>MPI_INTEGER_KIND</code>	Not defined for C++	24
<code>MPI_OFFSET_KIND</code>	Not defined for C++	25

#### Error-handling specifiers

C type: <code>MPI_Errhandler</code>	C++ type: <code>MPI::Errhandler</code>	26
Fortran type: <code>INTEGER</code>		27
[ticket231-C.] <code>or TYPE(MPI_Errhandler)</code>		28
<code>MPI_ERRORS_ARE_FATAL</code>	<code>MPI::ERRORS_ARE_FATAL</code>	29
<code>MPI_ERRORS_RETURN</code>	<code>MPI::ERRORS_RETURN</code>	30
	<code>MPI::ERRORS_THROW_EXCEPTIONS</code>	31

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Maximum Sizes for Strings	
C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER</code>	<code>const int</code> (or unnamed <code>enum</code> )
MPI_MAX_PROCESSOR_NAME	MPI::MAX_PROCESSOR_NAME
MPI_MAX_ERROR_STRING	MPI::MAX_ERROR_STRING
MPI_MAX_DATAREP_STRING	MPI::MAX_DATAREP_STRING
MPI_MAX_INFO_KEY	MPI::MAX_INFO_KEY
MPI_MAX_INFO_VAL	MPI::MAX_INFO_VAL
MPI_MAX_OBJECT_NAME	MPI::MAX_OBJECT_NAME
MPI_MAX_PORT_NAME	MPI::MAX_PORT_NAME

Named Predefined Datatypes		C/C++ types	1
C type: MPI_Datatype	C++ type: MPI::Datatype		2
Fortran type: INTEGER			3
[ticket231-C.]or TYPE(MPI_Datatype)			4
MPI_CHAR	MPI::CHAR	char	5
		(treated as printable	6
		character)	7
MPI_SHORT	MPI::SHORT	signed short int	8
MPI_INT	MPI::INT	signed int	9
MPI_LONG	MPI::LONG	signed long	10
MPI_LONG_LONG_INT	MPI::LONG_LONG_INT	signed long long	11
MPI_LONG_LONG	MPI::LONG_LONG	long long (synonym)	12
MPI_SIGNED_CHAR	MPI::SIGNED_CHAR	signed char	13
		(treated as integral value)	14
MPI_UNSIGNED_CHAR	MPI::UNSIGNED_CHAR	unsigned char	15
		(treated as integral value)	16
MPI_UNSIGNED_SHORT	MPI::UNSIGNED_SHORT	unsigned short	17
MPI_UNSIGNED	MPI::UNSIGNED	unsigned int	18
MPI_UNSIGNED_LONG	MPI::UNSIGNED_LONG	unsigned long	19
MPI_UNSIGNED_LONG_LONG	MPI::UNSIGNED_LONG_LONG	unsigned long long	20
MPI_FLOAT	MPI::FLOAT	float	21
MPI_DOUBLE	MPI::DOUBLE	double	22
MPI_LONG_DOUBLE	MPI::LONG_DOUBLE	long double	23
MPI_WCHAR	MPI::WCHAR	wchar_t	24
		(defined in <stddef.h>)	25
		(treated as printable	26
		character)	27
MPI_C_BOOL	(use C datatype handle)	_Bool	28
MPI_INT8_T	(use C datatype handle)	int8_t	29
MPI_INT16_T	(use C datatype handle)	int16_t	30
MPI_INT32_T	(use C datatype handle)	int32_t	31
MPI_INT64_T	(use C datatype handle)	int64_t	32
MPI_UINT8_T	(use C datatype handle)	uint8_t	33
MPI_UINT16_T	(use C datatype handle)	uint16_t	34
MPI_UINT32_T	(use C datatype handle)	uint32_t	35
MPI_UINT64_T	(use C datatype handle)	uint64_t	36
MPI_AINT	(use C datatype handle)	MPI_Aint	37
MPI_OFFSET	(use C datatype handle)	MPI_Offset	38
MPI_C_COMPLEX	(use C datatype handle)	float _Complex	39
MPI_C_FLOAT_COMPLEX	(use C datatype handle)	float _Complex	40
MPI_C_DOUBLE_COMPLEX	(use C datatype handle)	double _Complex	41
MPI_C_LONG_DOUBLE_COMPLEX	(use C datatype handle)	long double _Complex	42
MPI_BYTE	MPI::BYTE	(any C/C++ type)	43
MPI_PACKED	MPI::PACKED	(any C/C++ type)	44

Named Predefined Datatypes		Fortran types
C type: MPI_Datatype	C++ type: MPI::Datatype	
Fortran type: INTEGER		
[ticket231-C.]or TYPE(MPI_Datatype)		
MPI_INTEGER	MPI::INTEGER	INTEGER
MPI_REAL	MPI::REAL	REAL
MPI_DOUBLE_PRECISION	MPI::DOUBLE_PRECISION	DOUBLE PRECISION
MPI_COMPLEX	MPI::F_COMPLEX	COMPLEX
MPI_LOGICAL	MPI::LOGICAL	LOGICAL
MPI_CHARACTER	MPI::CHARACTER	CHARACTER(1)
MPI_AINT	(use C datatype handle)	INTEGER (KIND=MPI_ADDRESS_KIND)
MPI_OFFSET	(use C datatype handle)	INTEGER (KIND=MPI_OFFSET_KIND)
MPI_BYTE	MPI::BYTE	(any Fortran type)
MPI_PACKED	MPI::PACKED	(any Fortran type)

C++-Only Named Predefined Datatypes	C++ types
C++ type: MPI::Datatype	
MPI::BOOL	bool
MPI::COMPLEX	Complex<float>
MPI::DOUBLE_COMPLEX	Complex<double>
MPI::LONG_DOUBLE_COMPLEX	Complex<long double>

Optional datatypes (Fortran)		Fortran types
C type: MPI_Datatype	C++ type: MPI::Datatype	
Fortran type: INTEGER		
[ticket231-C.]or TYPE(MPI_Datatype)		
MPI_DOUBLE_COMPLEX	MPI::F_DOUBLE_COMPLEX	DOUBLE COMPLEX
MPI_INTEGER1	MPI::INTEGER1	INTEGER*1
MPI_INTEGER2	MPI::INTEGER2	INTEGER*8
MPI_INTEGER4	MPI::INTEGER4	INTEGER*4
MPI_INTEGER8	MPI::INTEGER8	INTEGER*8
MPI_INTEGER16		INTEGER*16
MPI_REAL2	MPI::REAL2	REAL*2
MPI_REAL4	MPI::REAL4	REAL*4
MPI_REAL8	MPI::REAL8	REAL*8
MPI_REAL16		REAL*16
MPI_COMPLEX4		COMPLEX*4
MPI_COMPLEX8		COMPLEX*8
MPI_COMPLEX16		COMPLEX*16
MPI_COMPLEX32		COMPLEX*32

**Datatypes for reduction functions (C and C++)**

C type: MPI_Datatype	C++ type: MPI::Datatype
Fortran type: INTEGER	
[ticket231-C.]or TYPE(MPI_Datatype)	
MPI_FLOAT_INT	MPI::FLOAT_INT
MPI_DOUBLE_INT	MPI::DOUBLE_INT
MPI_LONG_INT	MPI::LONG_INT
MPI_2INT	MPI::TWOINT
MPI_SHORT_INT	MPI::SHORT_INT
MPI_LONG_DOUBLE_INT	MPI::LONG_DOUBLE_INT

**Datatypes for reduction functions (Fortran)**

C type: MPI_Datatype	C++ type: MPI::Datatype
Fortran type: INTEGER	
[ticket231-C.]or TYPE(MPI_Datatype)	
MPI_2REAL	MPI::TWOREAL
MPI_2DOUBLE_PRECISION	MPI::TWODOUBLE_PRECISION
MPI_2INTEGER	MPI::TWOINTEGER

**Special datatypes for constructing derived datatypes**

C type: MPI_Datatype	C++ type: MPI::Datatype
Fortran type: INTEGER	
[ticket231-C.]or TYPE(MPI_Datatype)	
MPI_UB	MPI::UB
MPI_LB	MPI::LB

**Reserved communicators**

C type: MPI_Comm	C++ type: MPI::Intracomm
Fortran type: INTEGER	
[ticket231-C.]or TYPE(MPI_Comm)	
MPI_COMM_WORLD	MPI::COMM_WORLD
MPI_COMM_SELF	MPI::COMM_SELF

**Results of communicator and group comparisons**

C type: const int (or unnamed enum)	C++ type: const int
Fortran type: INTEGER	(or unnamed enum)
MPI_IDENT	MPI::IDENT
MPI_CONGRUENT	MPI::CONGRUENT
MPI_SIMILAR	MPI::SIMILAR
MPI_UNEQUAL	MPI::UNEQUAL

**Environmental inquiry keys**

C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type: <code>const int</code>
Fortran type: <code>INTEGER</code>	(or unnamed <code>enum</code> )
<code>MPI_TAG_UB</code>	<code>MPI::TAG_UB</code>
<code>MPI_IO</code>	<code>MPI::IO</code>
<code>MPI_HOST</code>	<code>MPI::HOST</code>
<code>MPI_WTIME_IS_GLOBAL</code>	<code>MPI::WTIME_IS_GLOBAL</code>

**Collective Operations**

C type: <code>MPI_Op</code>	C++ type: <code>const MPI::Op</code>
Fortran type: <code>INTEGER</code>	
[ticket231-C.] or <code>TYPE(MPI_Op)</code>	
<code>MPI_MAX</code>	<code>MPI::MAX</code>
<code>MPI_MIN</code>	<code>MPI::MIN</code>
<code>MPI_SUM</code>	<code>MPI::SUM</code>
<code>MPI_PROD</code>	<code>MPI::PROD</code>
<code>MPI_MAXLOC</code>	<code>MPI::MAXLOC</code>
<code>MPI_MINLOC</code>	<code>MPI::MINLOC</code>
<code>MPI_BAND</code>	<code>MPI::BAND</code>
<code>MPI_BOR</code>	<code>MPI::BOR</code>
<code>MPI_BXOR</code>	<code>MPI::BXOR</code>
<code>MPI_LAND</code>	<code>MPI::LAND</code>
<code>MPI_LOR</code>	<code>MPI::LOR</code>
<code>MPI_LXOR</code>	<code>MPI::LXOR</code>
<code>MPI_REPLACE</code>	<code>MPI::REPLACE</code>

Null Handles	
C/Fortran name	C++ name
C type / Fortran type	C++ type
MPI_GROUP_NULL	MPI::GROUP_NULL
MPI_Group / INTEGER	const MPI::Group
[ticket231-C.] or TYPE(MPI_Group)	
MPI_COMM_NULL	MPI::COMM_NULL
MPI_Comm / INTEGER	<sup>1)</sup>
[ticket231-C.] or TYPE(MPI_Comm)	
MPI_DATATYPE_NULL	MPI::DATATYPE_NULL
MPI_Datatype / INTEGER	const MPI::Datatype
[ticket231-C.] or TYPE(MPI_Datatype)	
MPI_REQUEST_NULL	MPI::REQUEST_NULL
MPI_Request / INTEGER	const MPI::Request
[ticket231-C.] or TYPE(MPI_Request)	
MPI_OP_NULL	MPI::OP_NULL
MPI_Op / INTEGER	const MPI::Op
[ticket231-C.] or TYPE(MPI_Op)	
MPI_ERRHANDLER_NULL	MPI::ERRHANDLER_NULL
MPI_Errhandler / INTEGER	const MPI::Errhandler
[ticket231-C.] or TYPE(MPI_Errhandler)	
MPI_FILE_NULL	MPI::FILE_NULL
MPI_File / INTEGER	
[ticket231-C.] or TYPE(MPI_File)	
MPI_INFO_NULL	MPI::INFO_NULL
MPI_Info / INTEGER	const MPI::Info
[ticket231-C.] or TYPE(MPI_Info)	
MPI_WIN_NULL	MPI::WIN_NULL
MPI_Win / INTEGER	
[ticket231-C.] or TYPE(MPI_Win)	
<sup>1)</sup> C++ type: See Section 16.1.7 on page 538 regarding class hierarchy and the specific type of MPI::COMM_NULL	

Empty group	
C type: MPI_Group	C++ type: const MPI::Group
Fortran type: INTEGER	
[ticket231-C.] or TYPE(MPI_Group)	
MPI_GROUP_EMPTY	MPI::GROUP_EMPTY

Topologies	
C type: const int (or unnamed enum)	C++ type: const int
Fortran type: INTEGER	(or unnamed enum)
MPI_GRAPH	MPI::GRAPH
MPI_CART	MPI::CART
MPI_DIST_GRAPH	MPI::DIST_GRAPH

Predefined functions	
C/Fortran name	C++ name
C type / Fortran type [ticket230-B.]with <b>mpi module</b> [ticket230-B.]/ <b>Fortran type with mpi_f08 module</b>	C++ type
MPI_COMM_NULL_COPY_FN	MPI_COMM_NULL_COPY_FN
MPI_Comm_copy_attr_function	same as in C <sup>1)</sup>
/ COMM_COPY_ATTR_[ticket250-V.] <b>FUNCTION</b>	
/ [ticket230-B.] <b>PROCEDURE(MPI_Comm_copy_attr_function) <sup>2)</sup></b>	
MPI_COMM_DUP_FN	MPI_COMM_DUP_FN
MPI_Comm_copy_attr_function	same as in C <sup>1)</sup>
/ COMM_COPY_ATTR_[ticket250-V.] <b>FUNCTION</b>	
/ [ticket230-B.] <b>PROCEDURE(MPI_Comm_copy_attr_function) <sup>2)</sup></b>	
MPI_COMM_NULL_DELETE_FN	MPI_COMM_NULL_DELETE_FN
MPI_Comm_delete_attr_function	same as in C <sup>1)</sup>
/ COMM_DELETE_ATTR_[ticket250-V.] <b>FUNCTION</b>	
/ [ticket230-B.] <b>PROCEDURE(MPI_Comm_delete_attr_function) <sup>2)</sup></b>	
MPI_WIN_NULL_COPY_FN	MPI_WIN_NULL_COPY_FN
MPI_Win_copy_attr_function	same as in C <sup>1)</sup>
/ WIN_COPY_ATTR_[ticket250-V.] <b>FUNCTION</b>	
/ [ticket230-B.] <b>PROCEDURE(MPI_Win_copy_attr_function) <sup>2)</sup></b>	
MPI_WIN_DUP_FN	MPI_WIN_DUP_FN
MPI_Win_copy_attr_function	same as in C <sup>1)</sup>
/ WIN_COPY_ATTR_[ticket250-V.] <b>FUNCTION</b>	
/ [ticket230-B.] <b>PROCEDURE(MPI_Win_copy_attr_function) <sup>2)</sup></b>	
MPI_WIN_NULL_DELETE_FN	MPI_WIN_NULL_DELETE_FN
MPI_Win_delete_attr_function	same as in C <sup>1)</sup>
/ WIN_DELETE_ATTR_[ticket250-V.] <b>FUNCTION</b>	
/ [ticket230-B.] <b>PROCEDURE(MPI_Win_delete_attr_function) <sup>2)</sup></b>	
MPI_TYPE_NULL_COPY_FN	MPI_TYPE_NULL_COPY_FN
MPI_Type_copy_attr_function	same as in C <sup>1)</sup>
/ TYPE_COPY_ATTR_[ticket250-V.] <b>FUNCTION</b>	
/ [ticket230-B.] <b>PROCEDURE(MPI_Type_copy_attr_function) <sup>2)</sup></b>	
MPI_TYPE_DUP_FN	MPI_TYPE_DUP_FN
MPI_Type_copy_attr_function	same as in C <sup>1)</sup>
/ TYPE_COPY_ATTR_[ticket250-V.] <b>FUNCTION</b>	
/ [ticket230-B.] <b>PROCEDURE(MPI_Type_copy_attr_function) <sup>2)</sup></b>	
MPI_TYPE_NULL_DELETE_FN	MPI_TYPE_NULL_DELETE_FN
MPI_Type_delete_attr_function	same as in C <sup>1)</sup>
/ TYPE_DELETE_ATTR_[ticket250-V.] <b>FUNCTION</b>	
/ [ticket230-B.] <b>PROCEDURE(MPI_Type_delete_attr_function) <sup>2)</sup></b>	
<sup>1</sup> See the advice to implementors [ticket230-B.](on page 269) and advice to users (on page 269) on [ticket230-B.]the predefined C functions MPI_COMM_NULL_COPY_FN, ... in Section 6.7.2 on page 266	
[ticket230-B.] <sup>2</sup> See the advice to implementors (on page 269) and advice to users (on page 269) [ticket230-B.] on the predefined Fortran functions MPI_COMM_NULL_COPY_FN, ... in [ticket230-B.] Section 6.7.2 on page 266	



**Deprecated predefined functions**

C/Fortran name	C++ name
C type / Fortran type	C++ type
MPI_NULL_COPY_FN	MPI::NULL_COPY_FN
MPI_Copy_function / COPY_FUNCTION	MPI::Copy_function
MPI_DUP_FN	MPI::DUP_FN
MPI_Copy_function / COPY_FUNCTION	MPI::Copy_function
MPI_NULL_DELETE_FN	MPI::NULL_DELETE_FN
MPI_Delete_function / DELETE_FUNCTION	MPI::Delete_function

**Predefined Attribute Keys**

C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER</code>	<code>const int</code> (or unnamed <code>enum</code> )
MPI_APPNUM	MPI::APPNUM
MPI_LASTUSED_CODE	MPI::LASTUSED_CODE
MPI_UNIVERSE_SIZE	MPI::UNIVERSE_SIZE
MPI_WIN_BASE	MPI::WIN_BASE
MPI_WIN_DISP_UNIT	MPI::WIN_DISP_UNIT
MPI_WIN_SIZE	MPI::WIN_SIZE

**Mode Constants**

C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER</code>	<code>const int</code> (or unnamed <code>enum</code> )
MPI_MODE_APPEND	MPI::MODE_APPEND
MPI_MODE_CREATE	MPI::MODE_CREATE
MPI_MODE_DELETE_ON_CLOSE	MPI::MODE_DELETE_ON_CLOSE
MPI_MODE_EXCL	MPI::MODE_EXCL
MPI_MODE_NOCHECK	MPI::MODE_NOCHECK
MPI_MODE_NOPRECEDE	MPI::MODE_NOPRECEDE
MPI_MODE_NOPUT	MPI::MODE_NOPUT
MPI_MODE_NOSTORE	MPI::MODE_NOSTORE
MPI_MODE_NOSUCCEED	MPI::MODE_NOSUCCEED
MPI_MODE_RDONLY	MPI::MODE_RDONLY
MPI_MODE_RDWR	MPI::MODE_RDWR
MPI_MODE_SEQUENTIAL	MPI::MODE_SEQUENTIAL
MPI_MODE_UNIQUE_OPEN	MPI::MODE_UNIQUE_OPEN
MPI_MODE_WRONLY	MPI::MODE_WRONLY

**Datatype Decoding Constants**

C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER</code>	<code>const int</code> (or unnamed <code>enum</code> )
<code>MPI_COMBINER_CONTIGUOUS</code>	<code>MPI::COMBINER_CONTIGUOUS</code>
<code>MPI_COMBINER_DARRAY</code>	<code>MPI::COMBINER_DARRAY</code>
<code>MPI_COMBINER_DUP</code>	<code>MPI::COMBINER_DUP</code>
<code>MPI_COMBINER_F90_COMPLEX</code>	<code>MPI::COMBINER_F90_COMPLEX</code>
<code>MPI_COMBINER_F90_INTEGER</code>	<code>MPI::COMBINER_F90_INTEGER</code>
<code>MPI_COMBINER_F90_REAL</code>	<code>MPI::COMBINER_F90_REAL</code>
<code>MPI_COMBINER_HINDEXED_INTEGER</code>	<code>MPI::COMBINER_HINDEXED_INTEGER</code>
<code>MPI_COMBINER_HINDEXED</code>	<code>MPI::COMBINER_HINDEXED</code>
<code>MPI_COMBINER_HVECTOR_INTEGER</code>	<code>MPI::COMBINER_HVECTOR_INTEGER</code>
<code>MPI_COMBINER_HVECTOR</code>	<code>MPI::COMBINER_HVECTOR</code>
<code>MPI_COMBINER_INDEXED_BLOCK</code>	<code>MPI::COMBINER_INDEXED_BLOCK</code>
<code>MPI_COMBINER_INDEXED</code>	<code>MPI::COMBINER_INDEXED</code>
<code>MPI_COMBINER_NAMED</code>	<code>MPI::COMBINER_NAMED</code>
<code>MPI_COMBINER_RESIZED</code>	<code>MPI::COMBINER_RESIZED</code>
<code>MPI_COMBINER_STRUCT_INTEGER</code>	<code>MPI::COMBINER_STRUCT_INTEGER</code>
<code>MPI_COMBINER_STRUCT</code>	<code>MPI::COMBINER_STRUCT</code>
<code>MPI_COMBINER_SUBARRAY</code>	<code>MPI::COMBINER_SUBARRAY</code>
<code>MPI_COMBINER_VECTOR</code>	<code>MPI::COMBINER_VECTOR</code>

**Threads Constants**

C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER</code>	<code>const int</code> (or unnamed <code>enum</code> )
<code>MPI_THREAD_FUNNELED</code>	<code>MPI::THREAD_FUNNELED</code>
<code>MPI_THREAD_MULTIPLE</code>	<code>MPI::THREAD_MULTIPLE</code>
<code>MPI_THREAD_SERIALIZED</code>	<code>MPI::THREAD_SERIALIZED</code>
<code>MPI_THREAD_SINGLE</code>	<code>MPI::THREAD_SINGLE</code>

**File Operation Constants, Part 1**

C type: <code>const MPI_Offset</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER (KIND=MPI_OFFSET_KIND)</code>	<code>const MPI::Offset</code> (or unnamed <code>enum</code> )
<code>MPI_DISPLACEMENT_CURRENT</code>	<code>MPI::DISPLACEMENT_CURRENT</code>

**File Operation Constants, Part 2**

C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER</code>	<code>const int</code> (or unnamed <code>enum</code> )
<code>MPI_DISTRIBUTE_BLOCK</code>	<code>MPI::DISTRIBUTE_BLOCK</code>
<code>MPI_DISTRIBUTE_CYCLIC</code>	<code>MPI::DISTRIBUTE_CYCLIC</code>
<code>MPI_DISTRIBUTE_DFLT_DARG</code>	<code>MPI::DISTRIBUTE_DFLT_DARG</code>
<code>MPI_DISTRIBUTE_NONE</code>	<code>MPI::DISTRIBUTE_NONE</code>
<code>MPI_ORDER_C</code>	<code>MPI::ORDER_C</code>
<code>MPI_ORDER_FORTRAN</code>	<code>MPI::ORDER_FORTRAN</code>
<code>MPI_SEEK_CUR</code>	<code>MPI::SEEK_CUR</code>
<code>MPI_SEEK_END</code>	<code>MPI::SEEK_END</code>
<code>MPI_SEEK_SET</code>	<code>MPI::SEEK_SET</code>

**F90 Datatype Matching Constants**

C type: <code>const int</code> (or unnamed <code>enum</code> )	C++ type:
Fortran type: <code>INTEGER</code>	<code>const int</code> (or unnamed <code>enum</code> )
<code>MPI_TYPECLASS_COMPLEX</code>	<code>MPI::TYPECLASS_COMPLEX</code>
<code>MPI_TYPECLASS_INTEGER</code>	<code>MPI::TYPECLASS_INTEGER</code>
<code>MPI_TYPECLASS_REAL</code>	<code>MPI::TYPECLASS_REAL</code>

**Constants Specifying Empty or Ignored Input**

C/Fortran name	C++ name
C type / Fortran type [ticket244-P.] <i>with <code>mpi</code> module</i>	C++ type
[ticket244-P.] <i>/ Fortran type with <code>mpi_f08</code> module</i>	
<code>MPI_ARGVS_NULL</code>	<code>MPI::ARGVS_NULL</code>
<code>char***</code> / 2-dim. array of <code>CHARACTER*(*)</code>	<code>const char ***</code>
[ticket244-P.] <i>/ 2-dim. array of <code>CHARACTER*(*)</code></i>	
<code>MPI_ARGV_NULL</code>	<code>MPI::ARGV_NULL</code>
<code>char**</code> / array of <code>CHARACTER*(*)</code>	<code>const char **</code>
[ticket244-P.] <i>/ array of <code>CHARACTER*(*)</code></i>	
<code>MPI_ERRCODES_IGNORE</code>	Not defined for C++
<code>int*</code> / <code>INTEGER</code> array	
[ticket244-P.] <i>/ not defined</i>	
<code>MPI_STATUSES_IGNORE</code>	Not defined for C++
<code>MPI_Status*</code> / <code>INTEGER</code> , <code>DIMENSION(MPI_STATUS_SIZE,*)</code>	
[ticket244-P.] <i>/ not defined</i>	
<code>MPI_STATUS_IGNORE</code>	Not defined for C++
<code>MPI_Status*</code> / <code>INTEGER</code> , <code>DIMENSION(MPI_STATUS_SIZE)</code>	
[ticket244-P.] <i>/ not defined</i>	
<code>MPI_UNWEIGHTED</code>	Not defined for C++
<code>int*</code> / <code>INTEGER</code> array	
[ticket244-P.] <i>/ not defined</i>	

**C Constants Specifying Ignored Input (no C++ or Fortran)**

C type: MPI\_Fint\*

MPI\_F\_STATUSES\_IGNORE

MPI\_F\_STATUS\_IGNORE

**C and C++ preprocessor Constants and Fortran Parameters**

C/C++ type: const int (or unnamed enum)

Fortran type: INTEGER

MPI\_SUBVERSION

MPI\_VERSION

**A.1.2 Types**

The following are defined C type definitions, included in the file `mpi.h`.

/\* C opaque types \*/

MPI\_Aint

MPI\_Fint

MPI\_Offset

MPI\_Status

/\* C handles to assorted structures \*/

MPI\_Comm

MPI\_Datatype

MPI\_Errhandler

MPI\_File

MPI\_Group

MPI\_Info

MPI\_Op

MPI\_Request

MPI\_Win

// C++ opaque types (all within the MPI namespace)

MPI::Aint

MPI::Offset

MPI::Status

// C++ handles to assorted structures (classes,

// all within the MPI namespace)

MPI::Comm

MPI::Intracomm

MPI::Graphcomm

MPI::Distgraphcomm

MPI::Cartcomm

MPI::Intercomm

MPI::Datatype

MPI::Errhandler

MPI::Exception

MPI::File  
 MPI::Group  
 MPI::Info  
 MPI::Op  
 MPI::Request  
 MPI::Prequest  
 MPI::Grequest  
 MPI::Win

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 9 ticket243-O.

The following are defined Fortran type definitions, included in the `mpi_f08` and `mpi` module.

! Fortran opaque types in the `mpi_f08` and `mpi` module  
 TYPE(MPI\_Status)

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 15 ticket231-C.

! Fortran handles in the `mpi_f08` and `mpi` module  
 TYPE(MPI\_Comm)  
 TYPE(MPI\_Datatype)  
 TYPE(MPI\_Errhandler)  
 TYPE(MPI\_File)  
 TYPE(MPI\_Group)  
 TYPE(MPI\_Info)  
 TYPE(MPI\_Op)  
 TYPE(MPI\_Request)  
 TYPE(MPI\_Win)

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### A.1.3 Prototype Definitions

27 ticket0.  
 28 ticket230-B.

#### C Bindings

The following are defined C typedefs for user-defined functions, also included in the file `mpi.h`.

```
/* prototypes for user-defined functions */
typedef void MPI_User_function(void *invec, void *inoutvec, int *len,
                               MPI_Datatype *datatype);

typedef int MPI_Comm_copy_attr_function(MPI_Comm oldcomm,
                                         int comm_keyval, void *extra_state, void *attribute_val_in,
                                         void *attribute_val_out, int*flag);
typedef int MPI_Comm_delete_attr_function(MPI_Comm comm,
                                         int comm_keyval, void *attribute_val, void *extra_state);

typedef int MPI_Win_copy_attr_function(MPI_Win oldwin, int win_keyval,
                                         void *extra_state, void *attribute_val_in,
                                         void *attribute_val_out, int *flag);
typedef int MPI_Win_delete_attr_function(MPI_Win win, int win_keyval,
                                         void *attribute_val, void *extra_state);
```

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```

1  typedef int MPI_Type_copy_attr_function(MPI_Datatype oldtype,
2      int type_keyval, void *extra_state,
3      void *attribute_val_in, void *attribute_val_out, int *flag);
4  typedef int MPI_Type_delete_attr_function(MPI_Datatype [ticket252-W.]datatype,
5      int type_keyval, void *attribute_val, void *extra_state);
6
7  typedef void MPI_Comm_errhandler_function(MPI_Comm *, int *, ...);
8  typedef void MPI_Win_errhandler_function(MPI_Win *, int *, ...);
9  typedef void MPI_File_errhandler_function(MPI_File *, int *, ...);
10
11 typedef int MPI_Grequest_query_function(void *extra_state,
12     MPI_Status *status);
13 typedef int MPI_Grequest_free_function(void *extra_state);
14 typedef int MPI_Grequest_cancel_function(void *extra_state, int complete);
15
16 typedef int MPI_Datarep_extent_function(MPI_Datatype datatype,
17     MPI_Aint *file_extent, void *extra_state);
18 typedef int MPI_Datarep_conversion_function(void *userbuf,
19     MPI_Datatype datatype, int count, void *filebuf,
20     MPI_Offset position, void *extra_state);

```

ticket230-B.

### Fortran Bindings with mpif.h or the mpi Module

ticket230-B.

With the Fortran `mpi` module or `mpif.h`, here are examples of how each of the user-defined subroutines should be declared.

The user-function argument to `MPI_OP_CREATE` should be declared like this:

```

28 SUBROUTINE USER_FUNCTION(INVEC, INOUTVEC, LEN, [ticket252-W.]DATATYPE)
29     <type> INVEC(LEN), INOUTVEC(LEN)
30     INTEGER LEN, [ticket252-W.]DATATYPE

```

The copy and delete function arguments to `MPI_COMM_CREATE_KEYVAL` should be declared like these:

```

34 SUBROUTINE COMM_COPY_ATTR_[ticket250-V.]FUNCTION(OLDCOMM, COMM_KEYVAL, EXTRA_STATE,
35     ATTRIBUTE_VAL_IN, ATTRIBUTE_VAL_OUT, FLAG, IERROR)
36     INTEGER OLDCOMM, COMM_KEYVAL, IERROR
37     INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE, ATTRIBUTE_VAL_IN,
38     ATTRIBUTE_VAL_OUT
39     LOGICAL FLAG
40
41 SUBROUTINE COMM_DELETE_ATTR_[ticket250-V.]FUNCTION(COMM, COMM_KEYVAL, ATTRIBUTE_VAL,
42     EXTRA_STATE, IERROR)
43     INTEGER COMM, COMM_KEYVAL, IERROR
44     INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL, EXTRA_STATE

```

The copy and delete function arguments to `MPI_WIN_CREATE_KEYVAL` should be declared like these:

```

SUBROUTINE WIN_COPY_ATTR_[ticket250-V.]FUNCTION(OLDWIN, WIN_KEYVAL, EXTRA_STATE,
    ATTRIBUTE_VAL_IN, ATTRIBUTE_VAL_OUT, FLAG, IERROR)
    INTEGER OLDWIN, WIN_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE, ATTRIBUTE_VAL_IN,
        ATTRIBUTE_VAL_OUT
    LOGICAL FLAG

```

```

SUBROUTINE WIN_DELETE_ATTR_[ticket250-V.]FUNCTION(WIN, WIN_KEYVAL, ATTRIBUTE_VAL,
    EXTRA_STATE, IERROR)
    INTEGER WIN, WIN_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL, EXTRA_STATE

```

The copy and delete function arguments to MPI\_TYPE\_CREATE\_KEYVAL should be declared like these:

```

SUBROUTINE TYPE_COPY_ATTR_[ticket250-V.]FUNCTION(OLDTYPE, TYPE_KEYVAL, EXTRA_STATE,
    ATTRIBUTE_VAL_IN, ATTRIBUTE_VAL_OUT, FLAG, IERROR)
    INTEGER OLDTYPE, TYPE_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE,
        ATTRIBUTE_VAL_IN, ATTRIBUTE_VAL_OUT
    LOGICAL FLAG

```

```

SUBROUTINE TYPE_DELETE_ATTR_[ticket250-V.]FUNCTION([ticket252-W.]DATATYPE, TYPE_KEYVAL, ATTRIBUTE_VAL,
    EXTRA_STATE, IERROR)
    INTEGER [ticket252-W.]DATATYPE, TYPE_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL, EXTRA_STATE

```

The handler-function argument to MPI\_COMM\_CREATE\_ERRHANDLER should be declared like this:

```

SUBROUTINE COMM_ERRHANDLER_FUNCTION(COMM, ERROR_CODE)
    INTEGER COMM, ERROR_CODE

```

The handler-function argument to MPI\_WIN\_CREATE\_ERRHANDLER should be declared like this:

```

SUBROUTINE WIN_ERRHANDLER_FUNCTION(WIN, ERROR_CODE)
    INTEGER WIN, ERROR_CODE

```

The handler-function argument to MPI\_FILE\_CREATE\_ERRHANDLER should be declared like this:

```

SUBROUTINE FILE_ERRHANDLER_FUNCTION(FILE, ERROR_CODE)
    INTEGER FILE, ERROR_CODE

```

The query, free, and cancel function arguments to MPI\_GREQUEST\_START should be declared like these:

```

1  SUBROUTINE GREQUEST_QUERY_FUNCTION(EXTRA_STATE, STATUS, IERROR)
2      INTEGER STATUS(MPI_STATUS_SIZE), IERROR
3      INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE
4
5  SUBROUTINE GREQUEST_FREE_FUNCTION(EXTRA_STATE, IERROR)
6      INTEGER IERROR
7      INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE
8
9  SUBROUTINE GREQUEST_CANCEL_FUNCTION(EXTRA_STATE, COMPLETE, IERROR)
10     INTEGER IERROR
11     INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE
12     LOGICAL COMPLETE
13

```

The extend and conversion function arguments to MPI\_REGISTER\_DATAREP should be declared like these:

```

16
17 SUBROUTINE DATAREP_EXTENT_FUNCTION(DATATYPE, EXTENT, EXTRA_STATE, IERROR)
18     INTEGER DATATYPE, IERROR
19     INTEGER(KIND=MPI_ADDRESS_KIND) EXTENT, EXTRA_STATE
20
21 SUBROUTINE DATAREP_CONVERSION_FUNCTION(USERBUF, DATATYPE, COUNT, FILEBUF,
22     POSITION, EXTRA_STATE, IERROR)
23     <TYPE> USERBUF(*), FILEBUF(*)
24     INTEGER COUNT, DATATYPE, IERROR
25     INTEGER(KIND=MPI_OFFSET_KIND) POSITION
26     INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE

```

### Fortran 2008 Bindings with the mpi\_f08 Module

With the Fortran `mpi_f08` module, the callback prototypes are:

The user-function argument to `MPI_Op_create` should be declared like this:

```

33     SUBROUTINE USER_FUNCTION(invec, inoutvec, len, datatype)
34     <type> :: invec(len), inoutvec(len)
35     INTEGER :: len
36     TYPE(MPI_Datatype) :: datatype

```

The copy and delete function arguments to `MPI_Comm_create_keyval` should be declared according to:

```

39 ABSTRACT INTERFACE
40     SUBROUTINE MPI_Comm_copy_attr_function(oldcomm, comm_keyval, extra_state,
41     attribute_val_in, attribute_val_out, flag, ierror)
42     TYPE(MPI_Comm) :: oldcomm
43     INTEGER :: comm_keyval, ierror
44     INTEGER(KIND=MPI_ADDRESS_KIND) :: extra_state, attribute_val_in,
45     attribute_val_out
46     LOGICAL flag

```

```

48 ABSTRACT INTERFACE

```



```

SUBROUTINE MPI_Comm_delete_attr_function(comm, comm_keyval,
attribute_val, extra_state, ierror)
    TYPE(MPI_Comm) :: comm
    INTEGER :: comm_keyval, ierror
    INTEGER(KIND=MPI_ADDRESS_KIND) :: attribute_val, extra_state

```

The copy and delete function arguments to MPI\_Win\_create\_keyval should be declared according to:

ABSTRACT INTERFACE

```

SUBROUTINE MPI_Win_copy_attr_function(oldwin, win_keyval, extra_state,
attribute_val_in, attribute_val_out, flag, ierror)
    TYPE(MPI_Win) :: oldwin
    INTEGER :: win_keyval, ierror
    INTEGER(KIND=MPI_ADDRESS_KIND) :: extra_state, attribute_val_in,
attribute_val_out
    LOGICAL flag

```

ABSTRACT INTERFACE

```

SUBROUTINE MPI_Win_delete_attr_function(win, win_keyval, attribute_val,
extra_state, ierror)
    TYPE(MPI_Win) :: win
    INTEGER :: win_keyval, ierror
    INTEGER(KIND=MPI_ADDRESS_KIND) :: attribute_val, extra_state

```

The copy and delete function arguments to MPI\_Type\_create\_keyval should be declared according to:

ABSTRACT INTERFACE

```

SUBROUTINE MPI_Type_copy_attr_function(oldtype, type_keyval, extra_state,
attribute_val_in, attribute_val_out, flag, ierror)
    TYPE(MPI_Datatype) :: oldtype
    INTEGER :: type_keyval, ierror
    INTEGER(KIND=MPI_ADDRESS_KIND) :: extra_state, attribute_val_in,
attribute_val_out
    LOGICAL flag

```

ABSTRACT INTERFACE

```

SUBROUTINE MPI_Type_delete_attr_function(datatype, type_keyval,
attribute_val, extra_state, ierror)
    TYPE(MPI_Datatype) :: datatype
    INTEGER :: type_keyval, ierror
    INTEGER(KIND=MPI_ADDRESS_KIND) :: attribute_val, extra_state

```

The handler-function argument to MPI\_Comm\_create\_errhandler should be declared like this:

ABSTRACT INTERFACE

```

SUBROUTINE MPI_Comm_errhandler_function(comm, error_code)
    TYPE(MPI_Comm) :: comm
    INTEGER :: error_code

```

The handler-function argument to MPI\_Win\_create\_errhandler should be declared like this:

```
ABSTRACT INTERFACE
  SUBROUTINE MPI_Win_errhandler_function(win, error_code)
    TYPE(MPI_Win) :: win
    INTEGER :: error_code
```

The handler-function argument to MPI\_File\_create\_errhandler should be declared like this:

```
ABSTRACT INTERFACE
  SUBROUTINE MPI_File_errhandler_function(file, error_code)
    TYPE(MPI_File) :: file
    INTEGER :: error_code
```

The query, free, and cancel function arguments to MPI\_Grequest\_start should be declared according to:

```
ABSTRACT INTERFACE
  SUBROUTINE MPI_Grequest_query_function(extra_state, status, ierror)
    TYPE(MPI_Status) :: status
    INTEGER :: ierror
    INTEGER(KIND=MPI_ADDRESS_KIND) :: extra_state
```

```
ABSTRACT INTERFACE
  SUBROUTINE MPI_Grequest_free_function(extra_state, ierror)
    INTEGER :: ierror
    INTEGER(KIND=MPI_ADDRESS_KIND) :: extra_state
```

```
ABSTRACT INTERFACE
  SUBROUTINE MPI_Grequest_cancel_function(extra_state, complete, ierror)
    INTEGER :: ierror
    INTEGER(KIND=MPI_ADDRESS_KIND) :: extra_state
    LOGICAL complete
```

The extend and conversion function arguments to MPI\_Register\_datarep should be declared according to:

```
ABSTRACT INTERFACE
  SUBROUTINE MPI_Datarep_extent_function(datatype, extent, extra_state,
    ierror)
    TYPE(MPI_Datatype) :: datatype
    INTEGER :: ierror
    INTEGER(KIND=MPI_ADDRESS_KIND) :: extent, extra_state
```

and like these:

```
SUBROUTINE DATAREP_CONVERSION_FUNCTION(userbuf, datatype, count, filebuf,
    position, extra_state, ierror)
  <TYPE> userbuf(*), filebuf(*)
  TYPE(MPI_Datatype) datatype
  INTEGER count, ierror
  INTEGER(KIND=MPI_OFFSET_KIND) position
  INTEGER(KIND=MPI_ADDRESS_KIND) extra_state
```

**C++ Bindings (deprecated)**

The following are defined C++ typedefs, also included in the file `mpi.h`.

```
namespace MPI {
    typedef void User_function(const void* invec, void *inoutvec,
                              int len, const Datatype& datatype);

    typedef int Comm::Copy_attr_function(const Comm& oldcomm,
                                         int comm_keyval, void* extra_state, void* attribute_val_in,
                                         void* attribute_val_out, bool& flag);
    typedef int Comm::Delete_attr_function(Comm& comm, int
                                         comm_keyval, void* attribute_val, void* extra_state);

    typedef int Win::Copy_attr_function(const Win& oldwin,
                                         int win_keyval, void* extra_state, void* attribute_val_in,
                                         void* attribute_val_out, bool& flag);
    typedef int Win::Delete_attr_function(Win& win, int
                                         win_keyval, void* attribute_val, void* extra_state);

    typedef int Datatype::Copy_attr_function(const Datatype& oldtype,
                                             int type_keyval, void* extra_state,
                                             const void* attribute_val_in, void* attribute_val_out,
                                             bool& flag);
    typedef int Datatype::Delete_attr_function(Datatype& [ticket3.].0){252-W}{data}type,
                                             int type_keyval, void* attribute_val, void* extra_state);

    typedef void Comm::Errhandler_function(Comm &, int *, ...);
    typedef void Win::Errhandler_function(Win &, int *, ...);
    typedef void File::Errhandler_function(File &, int *, ...);

    typedef int Grequest::Query_function(void* extra_state, Status& status);
    typedef int Grequest::Free_function(void* extra_state);
    typedef int Grequest::Cancel_function(void* extra_state, bool complete);

    typedef void Datarep_extent_function(const Datatype& datatype,
                                         Aint& file_extent, void* extra_state);
    typedef void Datarep_conversion_function(void* userbuf,
                                             Datatype& datatype, int count, void* filebuf,
                                             Offset position, void* extra_state);
}
```

**A.1.4 Deprecated Prototype Definitions**

The following are defined C typedefs for deprecated user-defined functions, also included in the file `mpi.h`.

```
/* prototypes for user-defined functions */
typedef int MPI_Copy_function(MPI_Comm oldcomm, int keyval,
                              void *extra_state, void *attribute_val_in,
```

```

1      void *attribute_val_out, int *flag);
2  typedef int MPI_Delete_function(MPI_Comm comm, int keyval,
3      void *attribute_val, void *extra_state);
4  typedef void MPI_Handler_function(MPI_Comm *, int *, ...);

```

The following are deprecated Fortran user-defined callback subroutine prototypes. The deprecated copy and delete function arguments to MPI\_KEYVAL\_CREATE should be declared like these:

```

9  SUBROUTINE COPY_FUNCTION(OLDCOMM, KEYVAL, EXTRA_STATE,
10      ATTRIBUTE_VAL_IN, ATTRIBUTE_VAL_OUT, FLAG, IERR)
11      INTEGER OLDCOMM, KEYVAL, EXTRA_STATE, ATTRIBUTE_VAL_IN,
12      ATTRIBUTE_VAL_OUT, IERR
13      LOGICAL FLAG
14
15  SUBROUTINE DELETE_FUNCTION(COMM, KEYVAL, ATTRIBUTE_VAL, EXTRA_STATE, IERR)
16      INTEGER COMM, KEYVAL, ATTRIBUTE_VAL, EXTRA_STATE, IERR

```

The deprecated handler-function for error handlers should be declared like this:

```

18  SUBROUTINE HANDLER_FUNCTION(COMM, ERROR_CODE)
19      INTEGER COMM, ERROR_CODE

```

#### A.1.5 Info Keys

```

23  access_style
24  appnum
25  arch
26  cb_block_size
27  cb_buffer_size
28  cb_nodes
29  chunked_item
30  chunked_size
31  chunked
32  collective_buffering
33  file_perm
34  filename
35  file
36  host
37  io_node_list
38  ip_address
39  ip_port
40  nb_proc
41  no_locks
42  num_io_nodes
43  path
44  soft
45  striping_factor
46  striping_unit
47  wdir

```

## A.1.6 Info Values

false

random

read\_mostly

read\_once

reverse\_sequential

sequential

true

write\_mostly

write\_once

1  
2  
3  
4  
5  
6  
7  
8  
9  
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48

## A.2 C Bindings

### A.2.1 Point-to-Point Communication C Bindings

```

1  int MPI_Bsend_init(void* buf, int count, MPI_Datatype datatype, int dest,
2      int tag, MPI_Comm comm, MPI_Request *request)
3
4  int MPI_Bsend(void* buf, int count, MPI_Datatype datatype, int dest,
5      int tag, MPI_Comm comm)
6
7  int MPI_Buffer_attach(void* buffer, int size)
8
9  int MPI_Buffer_detach(void* buffer_addr, int* size)
10
11 int MPI_Cancel(MPI_Request *request)
12
13 int MPI_Get_count(MPI_Status *status, MPI_Datatype datatype, int *count)
14
15 int MPI_Ibsend(void* buf, int count, MPI_Datatype datatype, int dest,
16     int tag, MPI_Comm comm, MPI_Request *request)
17
18 int MPI_Iprobe(int source, int tag, MPI_Comm comm, int *flag,
19     MPI_Status *status)
20
21 int MPI_Irecv(void* buf, int count, MPI_Datatype datatype, int source,
22     int tag, MPI_Comm comm, MPI_Request *request)
23
24 int MPI_Irsend(void* buf, int count, MPI_Datatype datatype, int dest,
25     int tag, MPI_Comm comm, MPI_Request *request)
26
27 int MPI_Isend(void* buf, int count, MPI_Datatype datatype, int dest,
28     int tag, MPI_Comm comm, MPI_Request *request)
29
30 int MPI_Issend(void* buf, int count, MPI_Datatype datatype, int dest,
31     int tag, MPI_Comm comm, MPI_Request *request)
32
33 int MPI_Probe(int source, int tag, MPI_Comm comm, MPI_Status *status)
34
35 int MPI_Recv_init(void* buf, int count, MPI_Datatype datatype, int source,
36     int tag, MPI_Comm comm, MPI_Request *request)
37
38 int MPI_Recv(void* buf, int count, MPI_Datatype datatype, int source,
39     int tag, MPI_Comm comm, MPI_Status *status)
40
41 int MPI_Request_free(MPI_Request *request)
42
43 int MPI_Request_get_status(MPI_Request request, int *flag,
44     MPI_Status *status)
45
46 int MPI_Rsend_init(void* buf, int count, MPI_Datatype datatype, int dest,
47     int tag, MPI_Comm comm, MPI_Request *request)
48
49 int MPI_Rsend(void* buf, int count, MPI_Datatype datatype, int dest,
50     int tag, MPI_Comm comm)
51
52 int MPI_Send_init(void* buf, int count, MPI_Datatype datatype, int dest,
53     int tag, MPI_Comm comm, MPI_Request *request)

```

```

int MPI_Sendrecv_replace(void* buf, int count, MPI_Datatype datatype,      1
                        int dest, int sendtag, int source, int recvtag, MPI_Comm comm,
                        MPI_Status *status)                                2
                                                                           3
                                                                           4
int MPI_Sendrecv(void *sendbuf, int sendcount, MPI_Datatype sendtype,      5
                int dest, int sendtag, void *recvbuf, int recvcount,
                MPI_Datatype recvtype, int source, int recvtag, MPI_Comm comm,
                MPI_Status *status)                                        6
                                                                           7
                                                                           8
int MPI_Send(void* buf, int count, MPI_Datatype datatype, int dest,
            int tag, MPI_Comm comm)                                       9
                                                                           10
                                                                           11
int MPI_Ssend_init(void* buf, int count, MPI_Datatype datatype, int dest,
                int tag, MPI_Comm comm, MPI_Request *request)           12
                                                                           13
int MPI_Ssend(void* buf, int count, MPI_Datatype datatype, int dest,
            int tag, MPI_Comm comm)                                       14
                                                                           15
                                                                           16
int MPI_Startall(int count, MPI_Request *array_of_requests)             17
                                                                           18
int MPI_Start(MPI_Request *request)                                       19
                                                                           20
int MPI_Testall(int count, MPI_Request *array_of_requests, int *flag,
                MPI_Status *array_of_statuses)                           21
                                                                           22
int MPI_Testany(int count, MPI_Request *array_of_requests, int *index,
                int *flag, MPI_Status *status)                           23
                                                                           24
int MPI_Test_cancelled(MPI_Status *status, int *flag)                    25
                                                                           26
int MPI_Test(MPI_Request *request, int *flag, MPI_Status *status)         27
                                                                           28
int MPI_Testsome(int incout, MPI_Request *array_of_requests,
                int *outcount, int *array_of_indices,
                MPI_Status *array_of_statuses)                           29
                                                                           30
                                                                           31
int MPI_Waitall(int count, MPI_Request *array_of_requests,
                MPI_Status *array_of_statuses)                           32
                                                                           33
int MPI_Waitany(int count, MPI_Request *array_of_requests, int *index,
                MPI_Status *status)                                       34
                                                                           35
                                                                           36
int MPI_Wait(MPI_Request *request, MPI_Status *status)                   37
                                                                           38
int MPI_Waitsome(int incout, MPI_Request *array_of_requests,
                int *outcount, int *array_of_indices,
                MPI_Status *array_of_statuses)                           39
                                                                           40
                                                                           41
                                                                           42

```

### A.2.2 Datatypes C Bindings

```

int MPI_Get_address(void *location, MPI_Aint *address)                   44
                                                                           45
int MPI_Get_elements(MPI_Status *status, MPI_Datatype datatype, int *count) 46
                                                                           47
int MPI_Pack_external(char *datarep, void *inbuf, int incout,

```

```

1      MPI_Datatype datatype, void *outbuf, MPI_Aint outsize,
2      MPI_Aint *position)
3
4  int MPI_Pack_external_size(char *datarep, int incount,
5      MPI_Datatype datatype, MPI_Aint *size)
6
7  int MPI_Pack_size(int incount, MPI_Datatype datatype, MPI_Comm comm,
8      int *size)
9
10 int MPI_Pack(void* inbuf, int incount, MPI_Datatype datatype, void *outbuf,
11     int outsize, int *position, MPI_Comm comm)
12
13 int MPI_Type_commit(MPI_Datatype *datatype)
14
15 int MPI_Type_contiguous(int count, MPI_Datatype oldtype,
16     MPI_Datatype *newtype)
17
18 int MPI_Type_create_darray(int size, int rank, int ndims,
19     int array_of_gsizes[], int array_of_distrib[], int
20     array_of_dargs[], int array_of_psize[], int order,
21     MPI_Datatype oldtype, MPI_Datatype *newtype)
22
23 int MPI_Type_create_hindexed(int count, int array_of_blocklengths[],
24     MPI_Aint array_of_displacements[], MPI_Datatype oldtype,
25     MPI_Datatype *newtype)
26
27 int MPI_Type_create_hvector(int count, int blocklength, MPI_Aint stride,
28     MPI_Datatype oldtype, MPI_Datatype *newtype)
29
30 int MPI_Type_create_indexed_block(int count, int blocklength,
31     int array_of_displacements[], MPI_Datatype oldtype,
32     MPI_Datatype *newtype)
33
34 int MPI_Type_create_resized(MPI_Datatype oldtype, MPI_Aint lb, MPI_Aint
35     extent, MPI_Datatype *newtype)
36
37 int MPI_Type_create_struct(int count, int array_of_blocklengths[],
38     MPI_Aint array_of_displacements[],
39     MPI_Datatype array_of_types[], MPI_Datatype *newtype)
40
41 int MPI_Type_create_subarray(int ndims, int array_of_sizes[],
42     int array_of_subsizes[], int array_of_starts[], int order,
43     MPI_Datatype oldtype, MPI_Datatype *newtype)
44
45 int MPI_Type_dup(MPI_Datatype oldtype, MPI_Datatype *newtype)
46
47 int MPI_Type_free(MPI_Datatype *datatype)
48
49 int MPI_Type_get_contents(MPI_Datatype datatype, int max_integers,
50     int max_addresses, int max_datatypes, int array_of_integers[],
51     MPI_Aint array_of_addresses[],
52     MPI_Datatype array_of_datatypes[])
53
54 int MPI_Type_get_envelope(MPI_Datatype datatype, int *num_integers,
55     int *num_addresses, int *num_datatypes, int *combiner)

```



```

int MPI_Type_get_extent(MPI_Datatype datatype, MPI_Aint *lb,
                        MPI_Aint *extent)
int MPI_Type_get_true_extent(MPI_Datatype datatype, MPI_Aint *true_lb,
                             MPI_Aint *true_extent)
int MPI_Type_indexed(int count, int *array_of_blocklengths,
                    int *array_of_displacements, MPI_Datatype oldtype,
                    MPI_Datatype *newtype)
int MPI_Type_size(MPI_Datatype datatype, int *size)
int MPI_Type_vector(int count, int blocklength, int stride,
                   MPI_Datatype oldtype, MPI_Datatype *newtype)
int MPI_Unpack_external(char *datarep, void *inbuf, MPI_Aint insize,
                      MPI_Aint *position, void *outbuf, int outcount,
                      MPI_Datatype datatype)
int MPI_Unpack(void* inbuf, int insize, int *position, void *outbuf,
              int outcount, MPI_Datatype datatype, MPI_Comm comm)

A.2.3 Collective Communication C Bindings

int MPI_Allgather(void* sendbuf, int sendcount, MPI_Datatype sendtype,
                void* recvbuf, int recvcount, MPI_Datatype recvtype,
                MPI_Comm comm)
int MPI_Allgatherv(void* sendbuf, int sendcount, MPI_Datatype sendtype,
                 void* recvbuf, int recvcounts[], int displs[],
                 MPI_Datatype recvtype, MPI_Comm comm)
int MPI_Allreduce(void* sendbuf, void* recvbuf, int count,
                 MPI_Datatype datatype, MPI_Op op, MPI_Comm comm)
int MPI_Alltoall(void* sendbuf, int sendcount, MPI_Datatype sendtype,
                void* recvbuf, int recvcount, MPI_Datatype recvtype,
                MPI_Comm comm)
int MPI_Alltoallv(void* sendbuf, int sendcounts[], int sdispls[],
                 MPI_Datatype sendtype, void* recvbuf, int recvcounts[],
                 int rdispls[], MPI_Datatype recvtype, MPI_Comm comm)
int MPI_Alltoallw(void* sendbuf, int sendcounts[], int sdispls[],
                 MPI_Datatype sendtypes[], void* recvbuf, int recvcounts[],
                 int rdispls[], MPI_Datatype recvtypes[], MPI_Comm comm)
int MPI_Barrier(MPI_Comm comm)
int MPI_Bcast(void* buffer, int count, MPI_Datatype datatype, int root,
             MPI_Comm comm)
int MPI_Exscan(void* sendbuf, void* recvbuf, int count,
              MPI_Datatype datatype, MPI_Op op, MPI_Comm comm)

```

```

1  int MPI_Gather(void* sendbuf, int sendcount, MPI_Datatype sendtype,
2                void* recvbuf, int recvcount, MPI_Datatype recvtype, int root,
3                MPI_Comm comm)
4
5  int MPI_Gatherv(void* sendbuf, int sendcount, MPI_Datatype sendtype,
6                void* recvbuf, int recvcounts[], int displs[],
7                MPI_Datatype recvtype, int root, MPI_Comm comm)
8
9  int MPI_Iallgather(void* sendbuf, int sendcount, MPI_Datatype sendtype,
10                   void* recvbuf, int recvcount, MPI_Datatype recvtype,
11                   MPI_Comm comm, MPI_Request* request)
12
13 int MPI_Iallgatherv(void* sendbuf, int sendcount, MPI_Datatype sendtype,
14                   void* recvbuf, int recvcounts[], int displs[],
15                   MPI_Datatype recvtype, MPI_Comm comm, MPI_Request* request)
16
17 int MPI_Iallreduce(void* sendbuf, void* recvbuf, int count,
18                   MPI_Datatype datatype, MPI_Op op, MPI_Comm comm,
19                   MPI_Request* request)
20
21 int MPI_Ialltoall(void* sendbuf, int sendcount, MPI_Datatype sendtype,
22                  void* recvbuf, int recvcount, MPI_Datatype recvtype,
23                  MPI_Comm comm, MPI_Request* request)
24
25 int MPI_Ialltoallv(void* sendbuf, int sendcounts[], int sdispls[],
26                   MPI_Datatype sendtype, void* recvbuf, int recvcounts[],
27                   int rdispls[], MPI_Datatype recvtype, MPI_Comm comm,
28                   MPI_Request* request)
29
30 int MPI_Ialltoallw(void* sendbuf, int sendcounts[], int sdispls[],
31                   MPI_Datatype sendtypes[], void* recvbuf, int recvcounts[],
32                   int rdispls[], MPI_Datatype recvtypes[], MPI_Comm comm,
33                   MPI_Request* request)
34
35 int MPI_Ibarrier(MPI_Comm comm, MPI_Request* request)
36
37 int MPI_Ibcast(void* buffer, int count, MPI_Datatype datatype, int root,
38               MPI_Comm comm, MPI_Request* request)
39
40 int MPI_Iexscan(void* sendbuf, void* recvbuf, int count,
41                MPI_Datatype datatype, MPI_Op op, MPI_Comm comm,
42                MPI_Request* request)
43
44 int MPI_Igather(void* sendbuf, int sendcount, MPI_Datatype sendtype,
45                void* recvbuf, int recvcount, MPI_Datatype recvtype, int root,
46                MPI_Comm comm, MPI_Request* request)
47
48 int MPI_Igatherv(void* sendbuf, int sendcount, MPI_Datatype sendtype,
49                 void* recvbuf, int recvcounts[], int displs[],
50                 MPI_Datatype recvtype, int root, MPI_Comm comm,
51                 MPI_Request* request)
52
53 int MPI_Ireduce_scatter_block(void* sendbuf, void* recvbuf, int recvcount,
54                              MPI_Datatype datatype, MPI_Op op, MPI_Comm comm,

```

```

        MPI_Request* request)
1
2
int MPI_Ireduce_scatter(void* sendbuf, void* recvbuf, int recvcunts[],
3 ticket0.
        MPI_Datatype datatype, MPI_Op op, MPI_Comm comm,
4 ticket0.
        MPI_Request* request)
5
6
int MPI_Ireduce(void* sendbuf, void* recvbuf, int count,
7
        MPI_Datatype datatype, MPI_Op op, int root, MPI_Comm comm,
8
        MPI_Request* request)
9
10
int MPI_Iscan(void* sendbuf, void* recvbuf, int count,
11
        MPI_Datatype datatype, MPI_Op op, MPI_Comm comm,
12
        MPI_Request* request)
13
14
int MPI_Iscatter(void* sendbuf, int sendcount, MPI_Datatype sendtype,
15
        void* recvbuf, int recvcunt, MPI_Datatype recvtype, int root,
16
        MPI_Comm comm, MPI_Request* request)
17
18
int MPI_Iscatterv(void* sendbuf, int sendcounts[], int displs[],
19 ticket0.
        MPI_Datatype sendtype, void* recvbuf, int recvcunt,
20 ticket0.
        MPI_Datatype recvtype, int root, MPI_Comm comm,
21
        MPI_Request* request)
22
23
int MPI_Op_commutative(MPI_Op op, int *commute)
24
25
int MPI_Op_create(MPI_User_function* user_fn, int commute, MPI_Op* op)
26 ticket252-W.
27
28
int MPI_op_free(MPI_Op *op)
29
30
int MPI_Reduce_local(void* inbuf, void* inoutbuf, int count,
31
        MPI_Datatype datatype, MPI_Op op)
32
33
int MPI_Reduce_scatter_block(void* sendbuf, void* recvbuf, int recvcunt,
34
        MPI_Datatype datatype, MPI_Op op, MPI_Comm comm)
35
36
int MPI_Reduce_scatter(void* sendbuf, void* recvbuf, int recvcunts[],
37
        MPI_Datatype datatype, MPI_Op op, MPI_Comm comm)
38
39
int MPI_Reduce(void* sendbuf, void* recvbuf, int count,
40
        MPI_Datatype datatype, MPI_Op op, int root, MPI_Comm comm)
41
42
int MPI_Scan(void* sendbuf, void* recvbuf, int count,
43
        MPI_Datatype datatype, MPI_Op op, MPI_Comm comm)
44
45
int MPI_Scatter(void* sendbuf, int sendcount, MPI_Datatype sendtype,
46
        void* recvbuf, int recvcunt, MPI_Datatype recvtype, int root,
47
        MPI_Comm comm)
48
49
int MPI_Scatterv(void* sendbuf, int sendcounts[], int displs[],
50
        MPI_Datatype sendtype, void* recvbuf, int recvcunt,
51
        MPI_Datatype recvtype, int root, MPI_Comm comm)
52
53

```

## A.2.4 Groups, Contexts, Communicators, and Caching C Bindings

```

1  int MPI_Comm_compare(MPI_Comm comm1, MPI_Comm comm2, int *result)
2
3  int MPI_Comm_create_keyval(MPI_Comm_copy_attr_function *comm_copy_attr_fn,
4                             MPI_Comm_delete_attr_function *comm_delete_attr_fn,
5                             int *comm_keyval, void *extra_state)
6
7  int MPI_Comm_create(MPI_Comm comm, MPI_Group group, MPI_Comm *newcomm)
8
9  int MPI_Comm_delete_attr(MPI_Comm comm, int comm_keyval)
10
11 int MPI_COMM_DUP_FN(MPI_Comm oldcomm, int comm_keyval, void *extra_state,
12                    void *attribute_val_in, void *attribute_val_out, int *flag)
13
14 int MPI_Comm_dup(MPI_Comm comm, MPI_Comm *newcomm)
15
16 int MPI_Comm_free_keyval(int *comm_keyval)
17
18 int MPI_Comm_free(MPI_Comm *comm)
19
20 int MPI_Comm_get_attr(MPI_Comm comm, int comm_keyval, void *attribute_val,
21                      int *flag)
22
23 int MPI_Comm_get_name(MPI_Comm comm, char *comm_name, int *resultlen)
24
25 int MPI_Comm_group(MPI_Comm comm, MPI_Group *group)
26
27 int MPI_COMM_NULL_COPY_FN(MPI_Comm oldcomm, int comm_keyval,
28                           void *extra_state, void *attribute_val_in,
29                           void *attribute_val_out, int *flag)
30
31 int MPI_COMM_NULL_DELETE_FN(MPI_Comm comm, int comm_keyval, void
32                             *attribute_val, void *extra_state)
33
34 int MPI_Comm_rank(MPI_Comm comm, int *rank)
35
36 int MPI_Comm_remote_group(MPI_Comm comm, MPI_Group *group)
37
38 int MPI_Comm_remote_size(MPI_Comm comm, int *size)
39
40 int MPI_Comm_set_attr(MPI_Comm comm, int comm_keyval, void *attribute_val)
41
42 int MPI_Comm_set_name(MPI_Comm comm, char *comm_name)
43
44 int MPI_Comm_size(MPI_Comm comm, int *size)
45
46 int MPI_Comm_split(MPI_Comm comm, int color, int key, MPI_Comm *newcomm)
47
48 int MPI_Comm_test_inter(MPI_Comm comm, int *flag)
49
50 int MPI_Group_compare(MPI_Group group1, MPI_Group group2, int *result)
51
52 int MPI_Group_difference(MPI_Group group1, MPI_Group group2,
53                         MPI_Group *newgroup)
54
55 int MPI_Group_excl(MPI_Group group, int n, int *ranks, MPI_Group *newgroup)
56
57 int MPI_Group_free(MPI_Group *group)

```

```

int MPI_Group_incl(MPI_Group group, int n, int *ranks, MPI_Group *newgroup)
int MPI_Group_intersection(MPI_Group group1, MPI_Group group2,
    MPI_Group *newgroup)
int MPI_Group_range_excl(MPI_Group group, int n, int ranges[][3],
    MPI_Group *newgroup)
int MPI_Group_range_incl(MPI_Group group, int n, int ranges[][3],
    MPI_Group *newgroup)
int MPI_Group_rank(MPI_Group group, int *rank)
int MPI_Group_size(MPI_Group group, int *size)
int MPI_Group_translate_ranks (MPI_Group group1, int n, int *ranks1,
    MPI_Group group2, int *ranks2)
int MPI_Group_union(MPI_Group group1, MPI_Group group2,
    MPI_Group *newgroup)
int MPI_Intercomm_create(MPI_Comm local_comm, int local_leader,
    MPI_Comm peer_comm, int remote_leader, int tag,
    MPI_Comm *newintercomm)
int MPI_Intercomm_merge(MPI_Comm intercomm, int high,
    MPI_Comm *newintracomm)
int MPI_Type_create_keyval(MPI_Type_copy_attr_function *type_copy_attr_fn,
    MPI_Type_delete_attr_function *type_delete_attr_fn,
    int *type_keyval, void *extra_state)
int MPI_Type_delete_attr(MPI_Datatype datatype, int type_keyval)
int MPI_TYPE_DUP_FN(MPI_Datatype oldtype, int type_keyval,
    void *extra_state, void *attribute_val_in,
    void *attribute_val_out, int *flag)
int MPI_Type_free_keyval(int *type_keyval)
int MPI_Type_get_attr(MPI_Datatype datatype, int type_keyval, void
    *attribute_val, int *flag)
int MPI_Type_get_name(MPI_Datatype datatype, char *type_name, int
    *resultlen)
int MPI_TYPE_NULL_COPY_FN(MPI_Datatype oldtype, int type_keyval,
    void *extra_state, void *attribute_val_in,
    void *attribute_val_out, int *flag)
int MPI_TYPE_NULL_DELETE_FN(MPI_Datatype datatype, int type_keyval, void
    *attribute_val, void *extra_state)
int MPI_Type_set_attr(MPI_Datatype datatype, int type_keyval,
    void *attribute_val)

```

```

ticket252-W. 1  int MPI_Type_set_name(MPI_Datatype datatype, char *type_name)
2
3  int MPI_Win_create_keyval(MPI_Win_copy_attr_function *win_copy_attr_fn,
4                          MPI_Win_delete_attr_function *win_delete_attr_fn,
5                          int *win_keyval, void *extra_state)
6
7  int MPI_Win_delete_attr(MPI_Win win, int win_keyval)
8
9  int MPI_WIN_DUP_FN(MPI_Win oldwin, int win_keyval, void *extra_state,
10                     void *attribute_val_in, void *attribute_val_out, int *flag)
11
12 int MPI_Win_free_keyval(int *win_keyval)
13
14 int MPI_Win_get_attr(MPI_Win win, int win_keyval, void *attribute_val,
15                     int *flag)
16
17 int MPI_Win_get_name(MPI_Win win, char *win_name, int *resultlen)
18
19 int MPI_WIN_NULL_COPY_FN(MPI_Win oldwin, int win_keyval, void *extra_state,
20                          void *attribute_val_in, void *attribute_val_out, int *flag)
21
22 int MPI_WIN_NULL_DELETE_FN(MPI_Win win, int win_keyval, void
23                          *attribute_val, void *extra_state)
24
25 int MPI_Win_set_attr(MPI_Win win, int win_keyval, void *attribute_val)
26
27 int MPI_Win_set_name(MPI_Win win, char *win_name)

```

## A.2.5 Process Topologies C Bindings

```

26 int MPI_Cart_coords(MPI_Comm comm, int rank, int maxdims, int *coords)
27
28 int MPI_Cart_create(MPI_Comm comm_old, int ndims, int *dims, int *periods,
29                    int reorder, MPI_Comm *comm_cart)
30
31 int MPI_Cartdim_get(MPI_Comm comm, int *ndims)
32
33 int MPI_Cart_get(MPI_Comm comm, int maxdims, int *dims, int *periods,
34                  int *coords)
35
36 int MPI_Cart_map(MPI_Comm comm, int ndims, int *dims, int *periods,
37                  int *newrank)
38
39 int MPI_Cart_rank(MPI_Comm comm, int *coords, int *rank)
40
41 int MPI_Cart_shift(MPI_Comm comm, int direction, int disp,
42                   int *rank_source, int *rank_dest)
43
44 int MPI_Cart_sub(MPI_Comm comm, int *remain_dims, MPI_Comm *newcomm)
45
46 int MPI_Dims_create(int nnodes, int ndims, int *dims)
47
48 int MPI_Dist_graph_create_adjacent(MPI_Comm comm_old, int indegree,
49                                   int sources[], int sourceweights[], int outdegree,
50                                   int destinations[], int destweights[], MPI_Info info,
51                                   int reorder, MPI_Comm *comm_dist_graph)

```

```

int MPI_Dist_graph_create(MPI_Comm comm_old, int n, int sources[],
                        int degrees[], int destinations[], int weights[],
                        MPI_Info info, int reorder, MPI_Comm *comm_dist_graph)
int MPI_Dist_graph_neighbors_count(MPI_Comm comm, int *indegree,
                                int *outdegree, int *weighted)
int MPI_Dist_graph_neighbors(MPI_Comm comm, int maxindegree, int sources[],
                            int sourceweights[], int maxoutdegree, int destinations[],
                            int destweights[])
int MPI_Graph_create(MPI_Comm comm_old, int nnodes, int *index, int *edges,
                    int reorder, MPI_Comm *comm_graph)
int MPI_Graphdims_get(MPI_Comm comm, int *nnodes, int *nedges)
int MPI_Graph_get(MPI_Comm comm, int maxindex, int maxedges, int *index,
                 int *edges)
int MPI_Graph_map(MPI_Comm comm, int nnodes, int *index, int *edges,
                 int *newrank)
int MPI_Graph_neighbors_count(MPI_Comm comm, int rank, int *nneighbors)
int MPI_Graph_neighbors(MPI_Comm comm, int rank, int maxneighbors,
                        int *neighbors)
int MPI_Topo_test(MPI_Comm comm, int *status)

```

### A.2.6 MPI Environmental Management C Bindings

```

int MPI_Abort(MPI_Comm comm, int errorcode)
int MPI_Add_error_class(int *errorclass)
int MPI_Add_error_code(int errorclass, int *errorcode)
int MPI_Add_error_string(int errorcode, char *string)
int MPI_Alloc_mem(MPI_Aint size, MPI_Info info, void *baseptr)
int MPI_Comm_call_errhandler(MPI_Comm comm, int errorcode)
int MPI_Comm_create_errhandler(MPI_Comm_errhandler_function
                             *comm_errhandler_fn, MPI_Errhandler *errhandler)
int MPI_Comm_get_errhandler(MPI_Comm comm, MPI_Errhandler *errhandler)
int MPI_Comm_set_errhandler(MPI_Comm comm, MPI_Errhandler errhandler)
int MPI_Errhandler_free(MPI_Errhandler *errhandler)
int MPI_Error_class(int errorcode, int *errorclass)
int MPI_Error_string(int errorcode, char *string, int *resultlen)
int MPI_File_call_errhandler(MPI_File fh, int errorcode)

```

ticket252-W.

```

1  int MPI_File_create_errhandler(MPI_File_errhandler_function
ticket252-W. 2      *file_errhandler_fn, MPI_Errhandler *errhandler)
3
4  int MPI_File_get_errhandler(MPI_File file, MPI_Errhandler *errhandler)
5
6  int MPI_File_set_errhandler(MPI_File file, MPI_Errhandler errhandler)
7
8  int MPI_Finalized(int *flag)
9
10 int MPI_Finalize(void)
11
12 int MPI_Get_processor_name(char *name, int *resultlen)
13
14 int MPI_Get_version(int *version, int *subversion)
15
16 int MPI_Initialized(int *flag)
17
18 int MPI_Init(int *argc, char ***argv)
19
20 int MPI_Win_create_errhandler(MPI_Win_errhandler_function
ticket252-W. 21      *win_errhandler_fn, MPI_Errhandler *errhandler)
22
23 int MPI_Win_get_errhandler(MPI_Win win, MPI_Errhandler *errhandler)
24
25 int MPI_Win_set_errhandler(MPI_Win win, MPI_Errhandler errhandler)
26
27 double MPI_Wtick(void)
28
29 double MPI_Wtime(void)

```

### A.2.7 The Info Object C Bindings

```

30 int MPI_Info_create(MPI_Info *info)
31
32 int MPI_Info_delete(MPI_Info info, char *key)
33
34 int MPI_Info_dup(MPI_Info info, MPI_Info *newinfo)
35
36 int MPI_Info_free(MPI_Info *info)
37
38 int MPI_Info_get(MPI_Info info, char *key, int valuelen, char *value,
39                 int *flag)
40
41 int MPI_Info_get_nkeys(MPI_Info info, int *nkeys)
42
43 int MPI_Info_get_nthkey(MPI_Info info, int n, char *key)
44
45 int MPI_Info_get_valuelen(MPI_Info info, char *key, int *valuelen,
46                           int *flag)
47
48 int MPI_Info_set(MPI_Info info, char *key, char *value)

```



## A.2.8 Process Creation and Management C Bindings

```

int MPI_Close_port(char *port_name)
int MPI_Comm_accept(char *port_name, MPI_Info info, int root,
                    MPI_Comm comm, MPI_Comm *newcomm)
int MPI_Comm_connect(char *port_name, MPI_Info info, int root,
                    MPI_Comm comm, MPI_Comm *newcomm)
int MPI_Comm_disconnect(MPI_Comm *comm)
int MPI_Comm_get_parent(MPI_Comm *parent)
int MPI_Comm_join(int fd, MPI_Comm *intercomm)
int MPI_Comm_spawn(char *command, char *argv[], int maxprocs, MPI_Info
                    info, int root, MPI_Comm comm, MPI_Comm *intercomm,
                    int array_of_errcodes[])
int MPI_Comm_spawn_multiple(int count, char *array_of_commands[],
                             char **array_of_argv[], int array_of_maxprocs[],
                             MPI_Info array_of_info[], int root, MPI_Comm comm,
                             MPI_Comm *intercomm, int array_of_errcodes[])
int MPI_Lookup_name(char *service_name, MPI_Info info, char *port_name)
int MPI_Open_port(MPI_Info info, char *port_name)
int MPI_Publish_name(char *service_name, MPI_Info info, char *port_name)
int MPI_Unpublish_name(char *service_name, MPI_Info info, char *port_name)

```

## A.2.9 One-Sided Communications C Bindings

```

int MPI_Accumulate(void *origin_addr, int origin_count,
                  MPI_Datatype origin_datatype, int target_rank,
                  MPI_Aint target_disp, int target_count,
                  MPI_Datatype target_datatype, MPI_Op op, MPI_Win win)
int MPI_Get(void *origin_addr, int origin_count, MPI_Datatype
            origin_datatype, int target_rank, MPI_Aint target_disp, int
            target_count, MPI_Datatype target_datatype, MPI_Win win)
int MPI_Put(void *origin_addr, int origin_count, MPI_Datatype
            origin_datatype, int target_rank, MPI_Aint target_disp, int
            target_count, MPI_Datatype target_datatype, MPI_Win win)
int MPI_Win_complete(MPI_Win win)
int MPI_Win_create(void *base, MPI_Aint size, int disp_unit, MPI_Info info,
                  MPI_Comm comm, MPI_Win *win)
int MPI_Win_fence(int assert, MPI_Win win)
int MPI_Win_free(MPI_Win *win)

```

```

1  int MPI_Win_get_group(MPI_Win win, MPI_Group *group)
2
3  int MPI_Win_lock(int lock_type, int rank, int assert, MPI_Win win)
4
5  int MPI_Win_post(MPI_Group group, int assert, MPI_Win win)
6
7  int MPI_Win_start(MPI_Group group, int assert, MPI_Win win)
8
9  int MPI_Win_test(MPI_Win win, int *flag)
10
11 int MPI_Win_unlock(int rank, MPI_Win win)
12
13 int MPI_Win_wait(MPI_Win win)

```

#### A.2.10 External Interfaces C Bindings

```

14 int MPI_Grequest_complete(MPI_Request request)
15
16 int MPI_Grequest_start(MPI_Grequest_query_function *query_fn,
17                        MPI_Grequest_free_function *free_fn,
18                        MPI_Grequest_cancel_function *cancel_fn, void *extra_state,
19                        MPI_Request *request)
20
21 int MPI_Init_thread(int *argc, char *((*argv)[[]]), int required,
22                    int *provided)
23
24 int MPI_Is_thread_main(int *flag)
25
26 int MPI_Query_thread(int *provided)
27
28 int MPI_Status_set_cancelled(MPI_Status *status, int flag)
29
30 int MPI_Status_set_elements(MPI_Status *status, MPI_Datatype datatype,
31                             int count)

```

#### A.2.11 I/O C Bindings

```

32 int MPI_File_close(MPI_File *fh)
33
34 int MPI_File_delete(char *filename, MPI_Info info)
35
36 int MPI_File_get_amode(MPI_File fh, int *amode)
37
38 int MPI_File_get_atomicity(MPI_File fh, int *flag)
39
40 int MPI_File_get_byte_offset(MPI_File fh, MPI_Offset offset,
41                             MPI_Offset *disp)
42
43 int MPI_File_get_group(MPI_File fh, MPI_Group *group)
44
45 int MPI_File_get_info(MPI_File fh, MPI_Info *info_used)
46
47 int MPI_File_get_position(MPI_File fh, MPI_Offset *offset)
48
49 int MPI_File_get_position_shared(MPI_File fh, MPI_Offset *offset)
50
51 int MPI_File_get_size(MPI_File fh, MPI_Offset *size)

```

```

int MPI_File_get_type_extent(MPI_File fh, MPI_Datatype datatype,      1
                             MPI_Aint *extent)                        2
                                                                    3
int MPI_File_get_view(MPI_File fh, MPI_Offset *disp, MPI_Datatype *etype, 4
                      MPI_Datatype *filetype, char *datarep)          5
                                                                    6
int MPI_File_iread_at(MPI_File fh, MPI_Offset offset, void *buf, int count, 7
                      MPI_Datatype datatype, MPI_Request *request)     8
                                                                    9
int MPI_File_iread(MPI_File fh, void *buf, int count,                  10
                   MPI_Datatype datatype, MPI_Request *request)       11
                                                                    12
int MPI_File_iread_shared(MPI_File fh, void *buf, int count,          13
                          MPI_Datatype datatype, MPI_Request *request) 14
                                                                    15
int MPI_File_iwrite_at(MPI_File fh, MPI_Offset offset, void *buf,      16
                       int count, MPI_Datatype datatype, MPI_Request *request) 17
                                                                    18
int MPI_File_iwrite(MPI_File fh, void *buf, int count,                 19
                    MPI_Datatype datatype, MPI_Request *request)       20
                                                                    21
int MPI_File_iwrite_shared(MPI_File fh, void *buf, int count,          22
                           MPI_Datatype datatype, MPI_Request *request) 23
                                                                    24
int MPI_File_open(MPI_Comm comm, char *filename, int amode, MPI_Info info, 25
                  MPI_File *fh)                                         26
                                                                    27
int MPI_File_preallocate(MPI_File fh, MPI_Offset size)                 28
                                                                    29
int MPI_File_read_all_begin(MPI_File fh, void *buf, int count,         30
                            MPI_Datatype datatype)                     31
                                                                    32
int MPI_File_read_all_end(MPI_File fh, void *buf, MPI_Status *status) 33
                                                                    34
int MPI_File_read_all(MPI_File fh, void *buf, int count,               35
                      MPI_Datatype datatype, MPI_Status *status)       36
                                                                    37
int MPI_File_read_at_all_begin(MPI_File fh, MPI_Offset offset, void *buf, 38
                               int count, MPI_Datatype datatype)       39
                                                                    40
int MPI_File_read_at_all_end(MPI_File fh, void *buf, MPI_Status *status) 41
                                                                    42
int MPI_File_read_at_all(MPI_File fh, MPI_Offset offset, void *buf,    43
                          int count, MPI_Datatype datatype, MPI_Status *status) 44
                                                                    45
int MPI_File_read_at(MPI_File fh, MPI_Offset offset, void *buf, int count, 46
                     MPI_Datatype datatype, MPI_Status *status)        47
                                                                    48
int MPI_File_read(MPI_File fh, void *buf, int count, MPI_Datatype datatype,
                  MPI_Status *status)
int MPI_File_read_ordered_begin(MPI_File fh, void *buf, int count,
                                MPI_Datatype datatype)
int MPI_File_read_ordered_end(MPI_File fh, void *buf, MPI_Status *status)

```

```

1  int MPI_File_read_ordered(MPI_File fh, void *buf, int count,
2      MPI_Datatype datatype, MPI_Status *status)
3
4  int MPI_File_read_shared(MPI_File fh, void *buf, int count,
5      MPI_Datatype datatype, MPI_Status *status)
6
7  int MPI_File_seek(MPI_File fh, MPI_Offset offset, int whence)
8
9  int MPI_File_seek_shared(MPI_File fh, MPI_Offset offset, int whence)
10
11 int MPI_File_set_atomicity(MPI_File fh, int flag)
12
13 int MPI_File_set_info(MPI_File fh, MPI_Info info)
14
15 int MPI_File_set_size(MPI_File fh, MPI_Offset size)
16
17 int MPI_File_set_view(MPI_File fh, MPI_Offset disp, MPI_Datatype etype,
18     MPI_Datatype filetype, char *datarep, MPI_Info info)
19
20 int MPI_File_sync(MPI_File fh)
21
22 int MPI_File_write_all_begin(MPI_File fh, void *buf, int count,
23     MPI_Datatype datatype)
24
25 int MPI_File_write_all_end(MPI_File fh, void *buf, MPI_Status *status)
26
27 int MPI_File_write_all(MPI_File fh, void *buf, int count,
28     MPI_Datatype datatype, MPI_Status *status)
29
30 int MPI_File_write_at_all_begin(MPI_File fh, MPI_Offset offset, void *buf,
31     int count, MPI_Datatype datatype)
32
33 int MPI_File_write_at_all_end(MPI_File fh, void *buf, MPI_Status *status)
34
35 int MPI_File_write_at_all(MPI_File fh, MPI_Offset offset, void *buf,
36     int count, MPI_Datatype datatype, MPI_Status *status)
37
38 int MPI_File_write_at(MPI_File fh, MPI_Offset offset, void *buf, int count,
39     MPI_Datatype datatype, MPI_Status *status)
40
41 int MPI_File_write(MPI_File fh, void *buf, int count,
42     MPI_Datatype datatype, MPI_Status *status)
43
44 int MPI_File_write_ordered_begin(MPI_File fh, void *buf, int count,
45     MPI_Datatype datatype)
46
47 int MPI_File_write_ordered_end(MPI_File fh, void *buf, MPI_Status *status)
48
49 int MPI_File_write_ordered(MPI_File fh, void *buf, int count,
50     MPI_Datatype datatype, MPI_Status *status)
51
52 int MPI_File_write_shared(MPI_File fh, void *buf, int count,
53     MPI_Datatype datatype, MPI_Status *status)
54
55 int MPI_Register_datarep(char *datarep,
56     MPI_Datarep_conversion_function *read_conversion_fn,
57     MPI_Datarep_conversion_function *write_conversion_fn,
58 )

```

```

    MPI_Datarep_extent_function *dtype_file_extent_fn,
    void *extra_state)

```

### A.2.12 Language Bindings C Bindings

```

int MPI_Status_f082f(MPI_F_status *f08_status, MPI_Fint *f_status)
int MPI_Status_f2f08(MPI_Fint *f_status, MPI_F_status *f08_status)
int MPI_Type_create_f90_complex(int p, int r, MPI_Datatype *newtype)
int MPI_Type_create_f90_integer(int r, MPI_Datatype *newtype)
int MPI_Type_create_f90_real(int p, int r, MPI_Datatype *newtype)
int MPI_Type_match_size(int typeclass, int size, MPI_Datatype *datatype)
MPI_Fint MPI_Comm_c2f(MPI_Comm comm)
MPI_Comm MPI_Comm_f2c(MPI_Fint comm)
MPI_Fint MPI_Errhandler_c2f(MPI_Errhandler errhandler)
MPI_Errhandler MPI_Errhandler_f2c(MPI_Fint errhandler)
MPI_Fint MPI_File_c2f(MPI_File file)
MPI_File MPI_File_f2c(MPI_Fint file)
MPI_Fint MPI_Group_c2f(MPI_Group group)
MPI_Group MPI_Group_f2c(MPI_Fint group)
MPI_Fint MPI_Info_c2f(MPI_Info info)
MPI_Info MPI_Info_f2c(MPI_Fint info)
MPI_Fint MPI_Op_c2f(MPI_Op op)
MPI_Op MPI_Op_f2c(MPI_Fint op)
MPI_Fint MPI_Request_c2f(MPI_Request request)
MPI_Request MPI_Request_f2c(MPI_Fint request)
int MPI_Status_c2f08(MPI_Status *c_status, MPI_F_status *f08_status)
int MPI_Status_c2f(MPI_Status *c_status, MPI_Fint *f_status)
int MPI_Status_f082c(MPI_F_status *f08_status, MPI_Status *c_status)
int MPI_Status_f2c(MPI_Fint *f_status, MPI_Status *c_status)
MPI_Fint MPI_Type_c2f(MPI_Datatype datatype)
MPI_Datatype MPI_Type_f2c(MPI_Fint datatype)
MPI_Fint MPI_Win_c2f(MPI_Win win)
MPI_Win MPI_Win_f2c(MPI_Fint win)

```

## A.2.13 Profiling Interface C Bindings

```
int MPI_Pcontrol(const int level, ...)
```

## A.2.14 Deprecated C Bindings

```
int MPI_Address(void* location, MPI_Aint *address)
```

```
int MPI_Attr_delete(MPI_Comm comm, int keyval)
```

```
int MPI_Attr_get(MPI_Comm comm, int keyval, void *attribute_val, int *flag)
```

```
int MPI_Attr_put(MPI_Comm comm, int keyval, void* attribute_val)
```

```
int MPI_DUP_FN(MPI_Comm oldcomm, int keyval, void *extra_state,
               void *attribute_val_in, void *attribute_val_out, int *flag)
```

```
int MPI_Errhandler_create(MPI_Handler_function *handler_fn,
                          MPI_Errhandler *errhandler)
```

```
int MPI_Errhandler_get(MPI_Comm comm, MPI_Errhandler *errhandler)
```

```
int MPI_Errhandler_set(MPI_Comm comm, MPI_Errhandler errhandler)
```

```
int MPI_Keyval_create(MPI_Copy_function *copy_fn, MPI_Delete_function
                     *delete_fn, int *keyval, void* extra_state)
```

```
int MPI_Keyval_free(int *keyval)
```

```
int MPI_NULL_COPY_FN(MPI_Comm oldcomm, int keyval, void *extra_state,
                     void *attribute_val_in, void *attribute_val_out, int *flag)
```

```
int MPI_NULL_DELETE_FN(MPI_Comm comm, int keyval, void *attribute_val,
                       void *extra_state)
```

```
int MPI_Type_extent(MPI_Datatype datatype, MPI_Aint *extent)
```

```
int MPI_Type_hindexed(int count, int *array_of_blocklengths,
                      MPI_Aint *array_of_displacements, MPI_Datatype oldtype,
                      MPI_Datatype *newtype)
```

```
int MPI_Type_hvector(int count, int blocklength, MPI_Aint stride,
                     MPI_Datatype oldtype, MPI_Datatype *newtype)
```

```
int MPI_Type_lb(MPI_Datatype datatype, MPI_Aint* displacement)
```

```
int MPI_Type_struct(int count, int *array_of_blocklengths,
                    MPI_Aint *array_of_displacements,
                    MPI_Datatype *array_of_types, MPI_Datatype *newtype)
```

```
int MPI_Type_ub(MPI_Datatype datatype, MPI_Aint* displacement)
```

## A.3 Fortran Bindings with mpif.h or the mpi Module

### A.3.1 Point-to-Point Communication Fortran Bindings

```

MPI_BSEND(BUF, COUNT, DATATYPE, DEST, TAG, COMM, IERROR)
    <type> BUF(*)
    INTEGER COUNT, DATATYPE, DEST, TAG, COMM, IERROR

MPI_BSEND_INIT(BUF, COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR)
    <type> BUF(*)
    INTEGER COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR

MPI_BUFFER_ATTACH(BUFFER, SIZE, IERROR)
    <type> BUFFER(*)
    INTEGER SIZE, IERROR

MPI_BUFFER_DETACH(BUFFER_ADDR, SIZE, IERROR)
    <type> BUFFER_ADDR(*)
    INTEGER SIZE, IERROR

MPI_CANCEL(REQUEST, IERROR)
    INTEGER REQUEST, IERROR

MPI_GET_COUNT(STATUS, DATATYPE, COUNT, IERROR)
    INTEGER STATUS(MPI_STATUS_SIZE), DATATYPE, COUNT, IERROR

MPI_IBSEND(BUF, COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR)
    <type> BUF(*)
    INTEGER COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR

MPI_IPROBE(SOURCE, TAG, COMM, FLAG, STATUS, IERROR)
    LOGICAL FLAG
    INTEGER SOURCE, TAG, COMM, STATUS(MPI_STATUS_SIZE), IERROR

MPI_IRECV(BUF, COUNT, DATATYPE, SOURCE, TAG, COMM, REQUEST, IERROR)
    <type> BUF(*)
    INTEGER COUNT, DATATYPE, SOURCE, TAG, COMM, REQUEST, IERROR

MPI_IRSEND(BUF, COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR)
    <type> BUF(*)
    INTEGER COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR

MPI_ISEND(BUF, COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR)
    <type> BUF(*)
    INTEGER COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR

MPI_ISSEND(BUF, COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR)
    <type> BUF(*)
    INTEGER COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR

MPI_PROBE(SOURCE, TAG, COMM, STATUS, IERROR)
    INTEGER SOURCE, TAG, COMM, STATUS(MPI_STATUS_SIZE), IERROR

MPI_RECV(BUF, COUNT, DATATYPE, SOURCE, TAG, COMM, STATUS, IERROR)

```

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```

1      <type> BUF(*)
2      INTEGER COUNT, DATATYPE, SOURCE, TAG, COMM, STATUS(MPI_STATUS_SIZE),
3      IERROR
4
5      MPI_RECV_INIT(BUF, COUNT, DATATYPE, SOURCE, TAG, COMM, REQUEST, IERROR)
6      <type> BUF(*)
7      INTEGER COUNT, DATATYPE, SOURCE, TAG, COMM, REQUEST, IERROR
8
9      MPI_REQUEST_FREE(REQUEST, IERROR)
10     INTEGER REQUEST, IERROR
11
12     MPI_REQUEST_GET_STATUS( REQUEST, FLAG, STATUS, IERROR)
13     INTEGER REQUEST, STATUS(MPI_STATUS_SIZE), IERROR
14     LOGICAL FLAG
15
16     MPI_RSEND(BUF, COUNT, DATATYPE, DEST, TAG, COMM, IERROR)
17     <type> BUF(*)
18     INTEGER COUNT, DATATYPE, DEST, TAG, COMM, IERROR
19
20     MPI_RSEND_INIT(BUF, COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR)
21     <type> BUF(*)
22     INTEGER COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR
23
24     MPI_SEND(BUF, COUNT, DATATYPE, DEST, TAG, COMM, IERROR)
25     <type> BUF(*)
26     INTEGER COUNT, DATATYPE, DEST, TAG, COMM, IERROR
27
28     MPI_SEND_INIT(BUF, COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR)
29     <type> BUF(*)
30     INTEGER COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR
31
32     MPI_SENDRECV_REPLACE(BUF, COUNT, DATATYPE, DEST, SENDTAG, SOURCE, RECVTAG,
33     COMM, STATUS, IERROR)
34     <type> BUF(*)
35     INTEGER COUNT, DATATYPE, DEST, SENDTAG, SOURCE, RECVTAG, COMM,
36     STATUS(MPI_STATUS_SIZE), IERROR
37
38     MPI_SENDRECV(SENDBUF, SENDCOUNT, SENDTYPE, DEST, SENDTAG, RECVBUF,
39     RECVCOUNT, RECVTYPE, SOURCE, RECVTAG, COMM, STATUS(MPI_STATUS_SIZE), IERROR)
40     <type> SENDBUF(*), RECVBUF(*)
41     INTEGER SENDCOUNT, SENDTYPE, DEST, SENDTAG, RECVCOUNT, RECVTYPE,
42     SOURCE, RECVTAG, COMM, STATUS(MPI_STATUS_SIZE), IERROR
43
44     MPI_SSEND(BUF, COUNT, DATATYPE, DEST, TAG, COMM, IERROR)
45     <type> BUF(*)
46     INTEGER COUNT, DATATYPE, DEST, TAG, COMM, IERROR
47
48     MPI_SSEND_INIT(BUF, COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR)
49     <type> BUF(*)
50     INTEGER COUNT, DATATYPE, DEST, TAG, COMM, REQUEST, IERROR
51
52     MPI_STARTALL(COUNT, ARRAY_OF_REQUESTS, IERROR)
53     INTEGER COUNT, ARRAY_OF_REQUESTS(*), IERROR

```



```

MPI_START(REQUEST, IERROR)                                1
    INTEGER REQUEST, IERROR                                2
                                                                3
MPI_TESTALL(COUNT, ARRAY_OF_REQUESTS, FLAG, ARRAY_OF_STATUSES, IERROR) 4
    LOGICAL FLAG                                           5
    INTEGER COUNT, ARRAY_OF_REQUESTS(*),                   6
    ARRAY_OF_STATUSES(MPI_STATUS_SIZE,*), IERROR          7
                                                                8
MPI_TESTANY(COUNT, ARRAY_OF_REQUESTS, INDEX, FLAG, STATUS, IERROR) 9
    LOGICAL FLAG                                           9
    INTEGER COUNT, ARRAY_OF_REQUESTS(*), INDEX, STATUS(MPI_STATUS_SIZE), 10
    IERROR                                                  11
                                                                12
MPI_TEST_CANCELLED(STATUS, FLAG, IERROR)                   13
    LOGICAL FLAG                                           14
    INTEGER STATUS(MPI_STATUS_SIZE), IERROR                 15
                                                                16
MPI_TEST(REQUEST, FLAG, STATUS, IERROR)                     17
    LOGICAL FLAG                                           18
    INTEGER REQUEST, STATUS(MPI_STATUS_SIZE), IERROR        19
                                                                20
MPI_TESTSOME(INCOUNT, ARRAY_OF_REQUESTS, OUTCOUNT, ARRAY_OF_INDICES, 21
    ARRAY_OF_STATUSES, IERROR)                             22
    INTEGER INCOUNT, ARRAY_OF_REQUESTS(*), OUTCOUNT, ARRAY_OF_INDICES(*), 23
    ARRAY_OF_STATUSES(MPI_STATUS_SIZE,*), IERROR           24
                                                                25
MPI_WAITALL(COUNT, ARRAY_OF_REQUESTS, ARRAY_OF_STATUSES, IERROR) 26
    INTEGER COUNT, ARRAY_OF_REQUESTS(*)                     27
    INTEGER ARRAY_OF_STATUSES(MPI_STATUS_SIZE,*), IERROR    28
                                                                29
MPI_WAITANY(COUNT, ARRAY_OF_REQUESTS, INDEX, STATUS, IERROR) 30
    INTEGER COUNT, ARRAY_OF_REQUESTS(*), INDEX, STATUS(MPI_STATUS_SIZE), 31
    IERROR                                                  32
                                                                33
MPI_WAIT(REQUEST, STATUS, IERROR)                           34
    INTEGER REQUEST, STATUS(MPI_STATUS_SIZE), IERROR        35
                                                                36
MPI_WAITSOME(INCOUNT, ARRAY_OF_REQUESTS, OUTCOUNT, ARRAY_OF_INDICES, 37
    ARRAY_OF_STATUSES, IERROR)                             38
    INTEGER INCOUNT, ARRAY_OF_REQUESTS(*), OUTCOUNT, ARRAY_OF_INDICES(*), 39
    ARRAY_OF_STATUSES(MPI_STATUS_SIZE,*), IERROR           40
                                                                41

```

### A.3.2 Datatypes Fortran Bindings

```

MPI_GET_ADDRESS(LOCATION, ADDRESS, IERROR)                  41
    <type> LOCATION(*)                                     42
    INTEGER IERROR                                         43
    INTEGER(KIND=MPI_ADDRESS_KIND) ADDRESS                 44
                                                                45
MPI_GET_ELEMENTS(STATUS, DATATYPE, COUNT, IERROR)          46
    INTEGER STATUS(MPI_STATUS_SIZE), DATATYPE, COUNT, IERROR 47
                                                                48

```

```

1  MPI_PACK_EXTERNAL(DATAREP, INBUF, INCOUNT, DATATYPE, OUTBUF, OUTSIZE,
2      POSITION, IERROR)
3      INTEGER INCOUNT, DATATYPE, IERROR
4      INTEGER(KIND=MPI_ADDRESS_KIND) OUTSIZE, POSITION
5      CHARACTER*(*) DATAREP
6      <type> INBUF(*), OUTBUF(*)
7
8  MPI_PACK_EXTERNAL_SIZE(DATAREP, INCOUNT, DATATYPE, SIZE, IERROR)
9      INTEGER INCOUNT, DATATYPE, IERROR
10     INTEGER(KIND=MPI_ADDRESS_KIND) SIZE
11     CHARACTER*(*) DATAREP
12
13 MPI_PACK(INBUF, INCOUNT, DATATYPE, OUTBUF, OUTSIZE, POSITION, COMM, IERROR)
14     <type> INBUF(*), OUTBUF(*)
15     INTEGER INCOUNT, DATATYPE, OUTSIZE, POSITION, COMM, IERROR
16
17 MPI_PACK_SIZE(INCOUNT, DATATYPE, COMM, SIZE, IERROR)
18     INTEGER INCOUNT, DATATYPE, COMM, SIZE, IERROR
19
20 MPI_TYPE_COMMIT(DATATYPE, IERROR)
21     INTEGER DATATYPE, IERROR
22
23 MPI_TYPE_CONTIGUOUS(COUNT, OLDTYPE, NEWTYPE, IERROR)
24     INTEGER COUNT, OLDTYPE, NEWTYPE, IERROR
25
26 MPI_TYPE_CREATE_DARRAY(SIZE, RANK, NDIMS, ARRAY_OF_GSIZES,
27     ARRAY_OF_DISTRIBS, ARRAY_OF_DARGS, ARRAY_OF_PSIZEs, ORDER,
28     OLDTYPE, NEWTYPE, IERROR)
29     INTEGER SIZE, RANK, NDIMS, ARRAY_OF_GSIZES(*), ARRAY_OF_DISTRIBS(*),
30     ARRAY_OF_DARGS(*), ARRAY_OF_PSIZEs(*), ORDER, OLDTYPE, NEWTYPE, IERROR
31
32 MPI_TYPE_CREATE_HINDEXED(COUNT, ARRAY_OF_BLOCKLENGTHS,
33     ARRAY_OF_DISPLACEMENTS, OLDTYPE, NEWTYPE, IERROR)
34     INTEGER COUNT, ARRAY_OF_BLOCKLENGTHS(*), OLDTYPE, NEWTYPE, IERROR
35     INTEGER(KIND=MPI_ADDRESS_KIND) ARRAY_OF_DISPLACEMENTS(*)
36
37 MPI_TYPE_CREATE_HVECTOR(COUNT, BLOCKLENGTH, STRIDE, OLDTYPE, NEWTYPE,
38     IERROR)
39     INTEGER COUNT, BLOCKLENGTH, OLDTYPE, NEWTYPE, IERROR
40     INTEGER(KIND=MPI_ADDRESS_KIND) STRIDE
41
42 MPI_TYPE_CREATE_INDEXED_BLOCK(COUNT, BLOCKLENGTH, ARRAY_OF_DISPLACEMENTS,
43     OLDTYPE, NEWTYPE, IERROR)
44     INTEGER COUNT, BLOCKLENGTH, ARRAY_OF_DISPLACEMENTS(*), OLDTYPE,
45     NEWTYPE, IERROR
46
47 MPI_TYPE_CREATE_RESIZED(OLDTYPE, LB, EXTENT, NEWTYPE, IERROR)
48     INTEGER OLDTYPE, NEWTYPE, IERROR
49     INTEGER(KIND=MPI_ADDRESS_KIND) LB, EXTENT
50
51 MPI_TYPE_CREATE_STRUCT(COUNT, ARRAY_OF_BLOCKLENGTHS,
52     ARRAY_OF_DISPLACEMENTS, ARRAY_OF_TYPES, NEWTYPE, IERROR)
53     INTEGER COUNT, ARRAY_OF_BLOCKLENGTHS(*), ARRAY_OF_TYPES(*), NEWTYPE,

```

```

IERROR 1
INTEGER(KIND=MPI_ADDRESS_KIND) ARRAY_OF_DISPLACEMENTS(*) 2
3
MPI_TYPE_CREATE_SUBARRAY(NDIMS, ARRAY_OF_SIZES, ARRAY_OF_SUBSIZES, 4
    ARRAY_OF_STARTS, ORDER, OLDTYPE, NEWTYPE, IERROR) 5
INTEGER NDIMS, ARRAY_OF_SIZES(*), ARRAY_OF_SUBSIZES(*), 6
    ARRAY_OF_STARTS(*), ORDER, OLDTYPE, NEWTYPE, IERROR 7
MPI_TYPE_DUP(OLDTYPE, NEWTYPE, IERROR) 8 ticket252-W.
INTEGER OLDTYPE, NEWTYPE, IERROR 9 ticket252-W.
10
MPI_TYPE_FREE(DATATYPE, IERROR) 11
INTEGER DATATYPE, IERROR 12
MPI_TYPE_GET_CONTENTS(DATATYPE, MAX_INTEGERS, MAX_ADDRESSES, MAX_DATATYPES, 13
    ARRAY_OF_INTEGERS, ARRAY_OF_ADDRESSES, ARRAY_OF_DATATYPES, 14
    IERROR) 15
INTEGER DATATYPE, MAX_INTEGERS, MAX_ADDRESSES, MAX_DATATYPES, 16
    ARRAY_OF_INTEGERS(*), ARRAY_OF_DATATYPES(*), IERROR 17
INTEGER(KIND=MPI_ADDRESS_KIND) ARRAY_OF_ADDRESSES(*) 18
19
MPI_TYPE_GET_ENVELOPE(DATATYPE, NUM_INTEGERS, NUM_ADDRESSES, NUM_DATATYPES, 20
    COMBINER, IERROR) 21
INTEGER DATATYPE, NUM_INTEGERS, NUM_ADDRESSES, NUM_DATATYPES, COMBINER, 22
    IERROR 23
MPI_TYPE_GET_EXTENT(DATATYPE, LB, EXTENT, IERROR) 24
INTEGER DATATYPE, IERROR 25
INTEGER(KIND = MPI_ADDRESS_KIND) LB, EXTENT 26
27
MPI_TYPE_GET_TRUE_EXTENT(DATATYPE, TRUE_LB, TRUE_EXTENT, IERROR) 28
INTEGER DATATYPE, IERROR 29
INTEGER(KIND = MPI_ADDRESS_KIND) TRUE_LB, TRUE_EXTENT 30
31
MPI_TYPE_INDEXED(COUNT, ARRAY_OF_BLOCKLENGTHS, ARRAY_OF_DISPLACEMENTS, 32
    OLDTYPE, NEWTYPE, IERROR) 33
INTEGER COUNT, ARRAY_OF_BLOCKLENGTHS(*), ARRAY_OF_DISPLACEMENTS(*), 34
    OLDTYPE, NEWTYPE, IERROR 35
MPI_TYPE_SIZE(DATATYPE, SIZE, IERROR) 36
INTEGER DATATYPE, SIZE, IERROR 37
MPI_TYPE_VECTOR(COUNT, BLOCKLENGTH, STRIDE, OLDTYPE, NEWTYPE, IERROR) 38
INTEGER COUNT, BLOCKLENGTH, STRIDE, OLDTYPE, NEWTYPE, IERROR 39
40
MPI_UNPACK_EXTERNAL(DATAREP, INBUF, INSIZE, POSITION, OUTBUF, OUTCOUNT, 41
    DATATYPE, IERROR) 42
INTEGER OUTCOUNT, DATATYPE, IERROR 43
INTEGER(KIND=MPI_ADDRESS_KIND) INSIZE, POSITION 44
CHARACTER*(*) DATAREP 45
<type> INBUF(*), OUTBUF(*) 46
47
MPI_UNPACK(INBUF, INSIZE, POSITION, OUTBUF, OUTCOUNT, DATATYPE, COMM, 48

```

```

1         IERROR)
2         <type> INBUF(*), OUTBUF(*)
3         INTEGER INSIZE, POSITION, OUTCOUNT, DATATYPE, COMM, IERROR
4
5
6 A.3.3 Collective Communication Fortran Bindings
7
8 MPI_ALLGATHER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, REVCOUNT, RECVTYPE,
9             COMM, IERROR)
10        <type> SENDBUF(*), RECVBUF(*)
11        INTEGER SENDCOUNT, SENDTYPE, REVCOUNT, RECVTYPE, COMM, IERROR
12
13 MPI_ALLGATHERV(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, REVCOUNTS, DISPLS,
14             RECVTYPE, COMM, IERROR)
15        <type> SENDBUF(*), RECVBUF(*)
16        INTEGER SENDCOUNT, SENDTYPE, REVCOUNTS(*), DISPLS(*), RECVTYPE, COMM,
17        IERROR
18
19 MPI_ALLREDUCE(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, IERROR)
20        <type> SENDBUF(*), RECVBUF(*)
21        INTEGER COUNT, DATATYPE, OP, COMM, IERROR
22
23 MPI_ALLTOALL(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, REVCOUNT, RECVTYPE,
24             COMM, IERROR)
25        <type> SENDBUF(*), RECVBUF(*)
26        INTEGER SENDCOUNT, SENDTYPE, REVCOUNT, RECVTYPE, COMM, IERROR
27
28 MPI_ALLTOALLV(SENDBUF, SENDCOUNTS, SDISPLS, SENDTYPE, RECVBUF, REVCOUNTS,
29             RDISPLS, RECVTYPE, COMM, IERROR)
30        <type> SENDBUF(*), RECVBUF(*)
31        INTEGER SENDCOUNTS(*), SDISPLS(*), SENDTYPE, REVCOUNTS(*), RDISPLS(*),
32        RECVTYPE, COMM, IERROR
33
34 MPI_ALLTOALLW(SENDBUF, SENDCOUNTS, SDISPLS, SENDTYPES, RECVBUF, REVCOUNTS,
35             RDISPLS, RECVTYPES, COMM, IERROR)
36        <type> SENDBUF(*), RECVBUF(*)
37        INTEGER SENDCOUNTS(*), SDISPLS(*), SENDTYPES(*), REVCOUNTS(*),
38        RDISPLS(*), RECVTYPES(*), COMM, IERROR
39
40 MPI_BARRIER(COMM, IERROR)
41        INTEGER COMM, IERROR
42
43 MPI_BCAST(BUFFER, COUNT, DATATYPE, ROOT, COMM, IERROR)
44        <type> BUFFER(*)
45        INTEGER COUNT, DATATYPE, ROOT, COMM, IERROR
46
47 MPI_EXSCAN(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, IERROR)
48        <type> SENDBUF(*), RECVBUF(*)
49        INTEGER COUNT, DATATYPE, OP, COMM, IERROR
50
51 MPI_GATHER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, REVCOUNT, RECVTYPE,
52             ROOT, COMM, IERROR)
53        <type> SENDBUF(*), RECVBUF(*)

```

```

    INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVMYPE, ROOT, COMM, IERROR
MPI_GATHERV(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNTS, DISPLS,
    RECVMYPE, ROOT, COMM, IERROR)
    <type> SENDBUF(*), RECVBUF(*)
    INTEGER SENDCOUNT, SENDTYPE, RECVCOUNTS(*), DISPLS(*), RECVMYPE, ROOT,
    COMM, IERROR
MPI_IALLGATHER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVMYPE,
    COMM, REQUEST, IERROR)
    <type> SENDBUF(*), RECVBUF(*)
    INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVMYPE, COMM, REQUEST, IERROR
MPI_IALLGATHERV(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNTS, DISPLS,
    RECVMYPE, COMM, REQUEST, IERROR)
    <type> SENDBUF(*), RECVBUF(*)
    INTEGER SENDCOUNT, SENDTYPE, RECVCOUNTS(*), DISPLS(*), RECVMYPE, COMM,
    REQUEST, IERROR
MPI_IALLREDUCE(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, REQUEST,
    IERROR)
    <type> SENDBUF(*), RECVBUF(*)
    INTEGER COUNT, DATATYPE, OP, COMM, REQUEST, IERROR
MPI_IALLTOALL(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVMYPE,
    COMM, REQUEST, IERROR)
    <type> SENDBUF(*), RECVBUF(*)
    INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVMYPE, COMM, REQUEST, IERROR
MPI_IALLTOALLV(SENDBUF, SENDCOUNTS, SDISPLS, SENDTYPE, RECVBUF, RECVCOUNTS,
    RDISPLS, RECVMYPE, COMM, REQUEST, IERROR)
    <type> SENDBUF(*), RECVBUF(*)
    INTEGER SENDCOUNTS(*), SDISPLS(*), SENDTYPE, RECVCOUNTS(*), RDISPLS(*),
    RECVMYPE, COMM, REQUEST, IERROR
MPI_IALLTOALLW(SENDBUF, SENDCOUNTS, SDISPLS, SENDTYPES, RECVBUF,
    RECVCOUNTS, RDISPLS, RECVMYPES, COMM, REQUEST, IERROR)
    <type> SENDBUF(*), RECVBUF(*)
    INTEGER SENDCOUNTS(*), SDISPLS(*), SENDTYPES(*), RECVCOUNTS(*),
    RDISPLS(*), RECVMYPES(*), COMM, REQUEST, IERROR
MPI_IBARRIER(COMM, REQUEST, IERROR)
    INTEGER COMM, REQUEST, IERROR
MPI_IBCAST(BUFFER, COUNT, DATATYPE, ROOT, COMM, REQUEST, IERROR)
    <type> BUFFER(*)
    INTEGER COUNT, DATATYPE, ROOT, COMM, REQUEST, IERROR
MPI_IEXSCAN(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, REQUEST, IERROR)
    <type> SENDBUF(*), RECVBUF(*)
    INTEGER COUNT, DATATYPE, OP, COMM, REQUEST, IERROR
MPI_IGATHER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVMYPE,

```

```

1          ROOT, COMM, REQUEST, IERROR)
2      <type> SENDBUF(*), RECVBUF(*)
3      INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, ROOT, COMM, REQUEST,
4      IERROR
5
6      MPI_IGATHERV(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNTS, DISPLS,
7                  RECVTYPE, ROOT, COMM, REQUEST, IERROR)
8      <type> SENDBUF(*), RECVBUF(*)
9      INTEGER SENDCOUNT, SENDTYPE, RECVCOUNTS(*), DISPLS(*), RECVTYPE, ROOT,
10     COMM, REQUEST, IERROR
11
12     MPI_IREDUCE_SCATTER_BLOCK(SENDBUF, RECVBUF, RECVCOUNT, DATATYPE, OP, COMM,
13                               REQUEST, IERROR)
14     <type> SENDBUF(*), RECVBUF(*)
15     INTEGER RECVCOUNT, DATATYPE, OP, COMM, REQUEST, IERROR
16
17     MPI_IREDUCE_SCATTER(SENDBUF, RECVBUF, RECVCOUNTS, DATATYPE, OP, COMM,
18                         REQUEST, IERROR)
19     <type> SENDBUF(*), RECVBUF(*)
20     INTEGER RECVCOUNTS(*), DATATYPE, OP, COMM, REQUEST, IERROR
21
22     MPI_IREDUCE(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, ROOT, COMM, REQUEST,
23                 IERROR)
24     <type> SENDBUF(*), RECVBUF(*)
25     INTEGER COUNT, DATATYPE, OP, ROOT, COMM, REQUEST, IERROR
26
27     MPI_ISCAN(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, REQUEST, IERROR)
28     <type> SENDBUF(*), RECVBUF(*)
29     INTEGER COUNT, DATATYPE, OP, COMM, REQUEST, IERROR
30
31     MPI_ISCATTER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE,
32                 ROOT, COMM, REQUEST, IERROR)
33     <type> SENDBUF(*), RECVBUF(*)
34     INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, ROOT, COMM, REQUEST,
35     IERROR
36
37     MPI_ISCATTERV(SENDBUF, SENDCOUNTS, DISPLS, SENDTYPE, RECVBUF, RECVCOUNT,
38                  RECVTYPE, ROOT, COMM, REQUEST, IERROR)
39     <type> SENDBUF(*), RECVBUF(*)
40     INTEGER SENDCOUNTS(*), DISPLS(*), SENDTYPE, RECVCOUNT, RECVTYPE, ROOT,
41     COMM, REQUEST, IERROR
42
43     MPI_OP_COMMUTATIVE(OP, COMMUTE, IERROR)
44     LOGICAL COMMUTE
45     INTEGER OP, IERROR
46
47     MPI_OP_CREATE( USER_FN, COMMUTE, OP, IERROR)
48     EXTERNAL USER_FN
49     LOGICAL COMMUTE
50     INTEGER OP, IERROR
51
52     MPI_OP_FREE(OP, IERROR)

```

```

INTEGER OP, IERROR
MPI_REDUCE_LOCAL(INBUF, INOUTBUF, COUNT, DATATYPE, OP, IERROR)
  <type> INBUF(*), INOUTBUF(*)
  INTEGER COUNT, DATATYPE, OP, IERROR
MPI_REDUCE_SCATTER_BLOCK(SENDBUF, RECVBUF, RECVCOUNT, DATATYPE, OP, COMM,
  IERROR)
  <type> SENDBUF(*), RECVBUF(*)
  INTEGER RECVCOUNT, DATATYPE, OP, COMM, IERROR
MPI_REDUCE_SCATTER(SENDBUF, RECVBUF, RECVCOUNTS, DATATYPE, OP, COMM,
  IERROR)
  <type> SENDBUF(*), RECVBUF(*)
  INTEGER RECVCOUNTS(*), DATATYPE, OP, COMM, IERROR
MPI_REDUCE(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, ROOT, COMM, IERROR)
  <type> SENDBUF(*), RECVBUF(*)
  INTEGER COUNT, DATATYPE, OP, ROOT, COMM, IERROR
MPI_SCAN(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, IERROR)
  <type> SENDBUF(*), RECVBUF(*)
  INTEGER COUNT, DATATYPE, OP, COMM, IERROR
MPI_SCATTER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE,
  ROOT, COMM, IERROR)
  <type> SENDBUF(*), RECVBUF(*)
  INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, ROOT, COMM, IERROR
MPI_SCATTERV(SENDBUF, SENDCOUNTS, DISPLS, SENDTYPE, RECVBUF, RECVCOUNT,
  RECVTYPE, ROOT, COMM, IERROR)
  <type> SENDBUF(*), RECVBUF(*)
  INTEGER SENDCOUNTS(*), DISPLS(*), SENDTYPE, RECVCOUNT, RECVTYPE, ROOT,
  COMM, IERROR

```

#### A.3.4 Groups, Contexts, Communicators, and Caching Fortran Bindings

```

MPI_COMM_COMPARE(COMM1, COMM2, RESULT, IERROR)
  INTEGER COMM1, COMM2, RESULT, IERROR
MPI_COMM_CREATE(COMM, GROUP, NEWCOMM, IERROR)
  INTEGER COMM, GROUP, NEWCOMM, IERROR
MPI_COMM_CREATE_KEYVAL(COMM_COPY_ATTR_FN, COMM_DELETE_ATTR_FN, COMM_KEYVAL,
  EXTRA_STATE, IERROR)
  EXTERNAL COMM_COPY_ATTR_FN, COMM_DELETE_ATTR_FN
  INTEGER COMM_KEYVAL, IERROR
  INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE
MPI_COMM_DELETE_ATTR(COMM, COMM_KEYVAL, IERROR)
  INTEGER COMM, COMM_KEYVAL, IERROR
MPI_COMM_DUP(COMM, NEWCOMM, IERROR)

```

```

1      INTEGER COMM, NEWCOMM, IERROR
2
3      MPI_COMM_DUP_FN(OLDCOMM, COMM_KEYVAL, EXTRA_STATE, ATTRIBUTE_VAL_IN,
4          ATTRIBUTE_VAL_OUT, FLAG, IERROR)
5      INTEGER OLDCOMM, COMM_KEYVAL, IERROR
6      INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE, ATTRIBUTE_VAL_IN,
7          ATTRIBUTE_VAL_OUT
8      LOGICAL FLAG
9
10     MPI_COMM_FREE(COMM, IERROR)
11     INTEGER COMM, IERROR
12
13     MPI_COMM_FREE_KEYVAL(COMM_KEYVAL, IERROR)
14     INTEGER COMM_KEYVAL, IERROR
15
16     MPI_COMM_GET_ATTR(COMM, COMM_KEYVAL, ATTRIBUTE_VAL, FLAG, IERROR)
17     INTEGER COMM, COMM_KEYVAL, IERROR
18     INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL
19     LOGICAL FLAG
20
21     MPI_COMM_GET_NAME(COMM, COMM_NAME, RESULTLEN, IERROR)
22     INTEGER COMM, RESULTLEN, IERROR
23     CHARACTER*(*) COMM_NAME
24
25     MPI_COMM_GROUP(COMM, GROUP, IERROR)
26     INTEGER COMM, GROUP, IERROR
27
28     MPI_COMM_NULL_COPY_FN(OLDCOMM, COMM_KEYVAL, EXTRA_STATE, ATTRIBUTE_VAL_IN,
29         ATTRIBUTE_VAL_OUT, FLAG, IERROR)
30     INTEGER OLDCOMM, COMM_KEYVAL, IERROR
31     INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE, ATTRIBUTE_VAL_IN,
32         ATTRIBUTE_VAL_OUT
33     LOGICAL FLAG
34
35     MPI_COMM_NULL_DELETE_FN(COMM, COMM_KEYVAL, ATTRIBUTE_VAL, EXTRA_STATE,
36         IERROR)
37     INTEGER COMM, COMM_KEYVAL, IERROR
38     INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL, EXTRA_STATE
39
40     MPI_COMM_RANK(COMM, RANK, IERROR)
41     INTEGER COMM, RANK, IERROR
42
43     MPI_COMM_REMOTE_GROUP(COMM, GROUP, IERROR)
44     INTEGER COMM, GROUP, IERROR
45
46     MPI_COMM_REMOTE_SIZE(COMM, SIZE, IERROR)
47     INTEGER COMM, SIZE, IERROR
48
49     MPI_COMM_SET_ATTR(COMM, COMM_KEYVAL, ATTRIBUTE_VAL, IERROR)
50     INTEGER COMM, COMM_KEYVAL, IERROR
51     INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL
52
53     MPI_COMM_SET_NAME(COMM, COMM_NAME, IERROR)
54     INTEGER COMM, IERROR

```



```

CHARACTER*(*) COMM_NAME
1
MPI_COMM_SIZE(COMM, SIZE, IERROR)
2
INTEGER COMM, SIZE, IERROR
3
MPI_COMM_SPLIT(COMM, COLOR, KEY, NEWCOMM, IERROR)
4
INTEGER COMM, COLOR, KEY, NEWCOMM, IERROR
5
MPI_COMM_TEST_INTER(COMM, FLAG, IERROR)
6
INTEGER COMM, IERROR
7
LOGICAL FLAG
8
MPI_GROUP_COMPARE(GROUP1, GROUP2, RESULT, IERROR)
9
INTEGER GROUP1, GROUP2, RESULT, IERROR
10
MPI_GROUP_DIFFERENCE(GROUP1, GROUP2, NEWGROUP, IERROR)
11
INTEGER GROUP1, GROUP2, NEWGROUP, IERROR
12
MPI_GROUP_EXCL(GROUP, N, RANKS, NEWGROUP, IERROR)
13
INTEGER GROUP, N, RANKS(*), NEWGROUP, IERROR
14
MPI_GROUP_FREE(GROUP, IERROR)
15
INTEGER GROUP, IERROR
16
MPI_GROUP_INCL(GROUP, N, RANKS, NEWGROUP, IERROR)
17
INTEGER GROUP, N, RANKS(*), NEWGROUP, IERROR
18
MPI_GROUP_INTERSECTION(GROUP1, GROUP2, NEWGROUP, IERROR)
19
INTEGER GROUP1, GROUP2, NEWGROUP, IERROR
20
MPI_GROUP_RANGE_EXCL(GROUP, N, RANGES, NEWGROUP, IERROR)
21
INTEGER GROUP, N, RANGES(3,*), NEWGROUP, IERROR
22
MPI_GROUP_RANGE_INCL(GROUP, N, RANGES, NEWGROUP, IERROR)
23
INTEGER GROUP, N, RANGES(3,*), NEWGROUP, IERROR
24
MPI_GROUP_RANK(GROUP, RANK, IERROR)
25
INTEGER GROUP, RANK, IERROR
26
MPI_GROUP_SIZE(GROUP, SIZE, IERROR)
27
INTEGER GROUP, SIZE, IERROR
28
MPI_GROUP_TRANSLATE_RANKS(GROUP1, N, RANKS1, GROUP2, RANKS2, IERROR)
29
INTEGER GROUP1, N, RANKS1(*), GROUP2, RANKS2(*), IERROR
30
MPI_GROUP_UNION(GROUP1, GROUP2, NEWGROUP, IERROR)
31
INTEGER GROUP1, GROUP2, NEWGROUP, IERROR
32
MPI_INTERCOMM_CREATE(LOCAL_COMM, LOCAL_LEADER, PEER_COMM, REMOTE_LEADER,
33
TAG, NEWINTERCOMM, IERROR)
34
INTEGER LOCAL_COMM, LOCAL_LEADER, PEER_COMM, REMOTE_LEADER, TAG,
35
NEWINTERCOMM, IERROR
36
MPI_INTERCOMM_MERGE(INTERCOMM, HIGH, NEWINTRACOMM, IERROR)
37
INTEGER NEWINTERCOMM, INTRACOMM, IERROR
38
39
40
41
42
43
44
45
46 ticket250-V.
47 ticket250-V.
48

```

```

1      LOGICAL HIGH
2
3      MPI_TYPE_CREATE_KEYVAL(TYPE_COPY_ATTR_FN, TYPE_DELETE_ATTR_FN, TYPE_KEYVAL,
4          EXTRA_STATE, IERROR)
5      EXTERNAL TYPE_COPY_ATTR_FN, TYPE_DELETE_ATTR_FN
6      INTEGER TYPE_KEYVAL, IERROR
7      INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE
8
9      MPI_TYPE_DELETE_ATTR(DATATYPE, TYPE_KEYVAL, IERROR)
10     INTEGER DATATYPE, TYPE_KEYVAL, IERROR
11
12     MPI_TYPE_DUP_FN(OLDTYPE, TYPE_KEYVAL, EXTRA_STATE, ATTRIBUTE_VAL_IN,
13         ATTRIBUTE_VAL_OUT, FLAG, IERROR)
14     INTEGER OLDTYPE, TYPE_KEYVAL, IERROR
15     INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE, ATTRIBUTE_VAL_IN,
16         ATTRIBUTE_VAL_OUT
17     LOGICAL FLAG
18
19     MPI_TYPE_FREE_KEYVAL(TYPE_KEYVAL, IERROR)
20     INTEGER TYPE_KEYVAL, IERROR
21
22     MPI_TYPE_GET_ATTR(DATATYPE, TYPE_KEYVAL, ATTRIBUTE_VAL, FLAG, IERROR)
23     INTEGER DATATYPE, TYPE_KEYVAL, IERROR
24     INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL
25     LOGICAL FLAG
26
27     MPI_TYPE_GET_NAME(DATATYPE, TYPE_NAME, RESULTLEN, IERROR)
28     INTEGER DATATYPE, RESULTLEN, IERROR
29     CHARACTER*(*) TYPE_NAME
30
31     MPI_TYPE_NULL_COPY_FN(OLDTYPE, TYPE_KEYVAL, EXTRA_STATE, ATTRIBUTE_VAL_IN,
32         ATTRIBUTE_VAL_OUT, FLAG, IERROR)
33     INTEGER OLDTYPE, TYPE_KEYVAL, IERROR
34     INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE, ATTRIBUTE_VAL_IN,
35         ATTRIBUTE_VAL_OUT
36     LOGICAL FLAG
37
38     MPI_TYPE_NULL_DELETE_FN(DATATYPE, TYPE_KEYVAL, ATTRIBUTE_VAL, EXTRA_STATE,
39         IERROR)
40     INTEGER DATATYPE, TYPE_KEYVAL, IERROR
41     INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL, EXTRA_STATE
42
43     MPI_TYPE_SET_ATTR(DATATYPE, TYPE_KEYVAL, ATTRIBUTE_VAL, IERROR)
44     INTEGER DATATYPE, TYPE_KEYVAL, IERROR
45     INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL
46
47     MPI_TYPE_SET_NAME(DATATYPE, TYPE_NAME, IERROR)
48     INTEGER DATATYPE, IERROR
49     CHARACTER*(*) TYPE_NAME
50
51     MPI_WIN_CREATE_KEYVAL(WIN_COPY_ATTR_FN, WIN_DELETE_ATTR_FN, WIN_KEYVAL,
52         EXTRA_STATE, IERROR)
53     EXTERNAL WIN_COPY_ATTR_FN, WIN_DELETE_ATTR_FN

```

```

    INTEGER WIN_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE
MPI_WIN_DELETE_ATTR(WIN, WIN_KEYVAL, IERROR)
    INTEGER WIN, WIN_KEYVAL, IERROR
MPI_WIN_DUP_FN(OLDWIN, WIN_KEYVAL, EXTRA_STATE, ATTRIBUTE_VAL_IN,
    ATTRIBUTE_VAL_OUT, FLAG, IERROR)
    INTEGER OLDWIN, WIN_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE, ATTRIBUTE_VAL_IN,
    ATTRIBUTE_VAL_OUT
    LOGICAL FLAG
MPI_WIN_FREE_KEYVAL(WIN_KEYVAL, IERROR)
    INTEGER WIN_KEYVAL, IERROR
MPI_WIN_GET_ATTR(WIN, WIN_KEYVAL, ATTRIBUTE_VAL, FLAG, IERROR)
    INTEGER WIN, WIN_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL
    LOGICAL FLAG
MPI_WIN_GET_NAME(WIN, WIN_NAME, RESULTLEN, IERROR)
    INTEGER WIN, RESULTLEN, IERROR
    CHARACTER*(*) WIN_NAME
MPI_WIN_NULL_COPY_FN(OLDWIN, WIN_KEYVAL, EXTRA_STATE, ATTRIBUTE_VAL_IN,
    ATTRIBUTE_VAL_OUT, FLAG, IERROR)
    INTEGER OLDWIN, WIN_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE, ATTRIBUTE_VAL_IN,
    ATTRIBUTE_VAL_OUT
    LOGICAL FLAG
MPI_WIN_NULL_DELETE_FN(WIN, WIN_KEYVAL, ATTRIBUTE_VAL, EXTRA_STATE, IERROR)
    INTEGER WIN, WIN_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL, EXTRA_STATE
MPI_WIN_SET_ATTR(WIN, WIN_KEYVAL, ATTRIBUTE_VAL, IERROR)
    INTEGER WIN, WIN_KEYVAL, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) ATTRIBUTE_VAL
MPI_WIN_SET_NAME(WIN, WIN_NAME, IERROR)
    INTEGER WIN, IERROR
    CHARACTER*(*) WIN_NAME

```

### A.3.5 Process Topologies Fortran Bindings

```

MPI_CART_COORDS(COMM, RANK, MAXDIMS, COORDS, IERROR)
    INTEGER COMM, RANK, MAXDIMS, COORDS(*), IERROR
MPI_CART_CREATE(COMM_OLD, NDIMS, DIMS, PERIODS, REORDER, COMM_CART, IERROR)
    INTEGER COMM_OLD, NDIMS, DIMS(*), COMM_CART, IERROR
    LOGICAL PERIODS(*), REORDER

```

```

1  MPI_CARTDIM_GET(COMM, NDIMS, IERROR)
2      INTEGER COMM, NDIMS, IERROR
3
4  MPI_CART_GET(COMM, MAXDIMS, DIMS, PERIODS, COORDS, IERROR)
5      INTEGER COMM, MAXDIMS, DIMS(*), COORDS(*), IERROR
6      LOGICAL PERIODS(*)
7
8  MPI_CART_MAP(COMM, NDIMS, DIMS, PERIODS, NEWRANK, IERROR)
9      INTEGER COMM, NDIMS, DIMS(*), NEWRANK, IERROR
10     LOGICAL PERIODS(*)
11
12 MPI_CART_RANK(COMM, COORDS, RANK, IERROR)
13     INTEGER COMM, COORDS(*), RANK, IERROR
14
15 MPI_CART_SHIFT(COMM, DIRECTION, DISP, RANK_SOURCE, RANK_DEST, IERROR)
16     INTEGER COMM, DIRECTION, DISP, RANK_SOURCE, RANK_DEST, IERROR
17
18 MPI_CART_SUB(COMM, REMAIN_DIMS, NEWCOMM, IERROR)
19     INTEGER COMM, NEWCOMM, IERROR
20     LOGICAL REMAIN_DIMS(*)
21
22 MPI_DIMS_CREATE(NNODES, NDIMS, DIMS, IERROR)
23     INTEGER NNODES, NDIMS, DIMS(*), IERROR
24
25 MPI_DIST_GRAPH_CREATE_ADJACENT(COMM_OLD, INDEGREE, SOURCES, SOURCEWEIGHTS,
26     OUTDEGREE, DESTINATIONS, DESTWEIGHTS, INFO, REORDER,
27     COMM_DIST_GRAPH, IERROR)
28     INTEGER COMM_OLD, INDEGREE, SOURCES(*), SOURCEWEIGHTS(*), OUTDEGREE,
29     DESTINATIONS(*), DESTWEIGHTS(*), INFO, COMM_DIST_GRAPH, IERROR
30     LOGICAL REORDER
31
32 MPI_DIST_GRAPH_CREATE(COMM_OLD, N, SOURCES, DEGREES, DESTINATIONS, WEIGHTS,
33     INFO, REORDER, COMM_DIST_GRAPH, IERROR)
34     INTEGER COMM_OLD, N, SOURCES(*), DEGREES(*), DESTINATIONS(*),
35     WEIGHTS(*), INFO, COMM_DIST_GRAPH, IERROR
36     LOGICAL REORDER
37
38 MPI_DIST_GRAPH_NEIGHBORS(COMM, MAXINDEGREE, SOURCES, SOURCEWEIGHTS,
39     MAXOUTDEGREE, DESTINATIONS, DESTWEIGHTS, IERROR)
40     INTEGER COMM, MAXINDEGREE, SOURCES(*), SOURCEWEIGHTS(*), MAXOUTDEGREE,
41     DESTINATIONS(*), DESTWEIGHTS(*), IERROR
42
43 MPI_DIST_GRAPH_NEIGHBORS_COUNT(COMM, INDEGREE, OUTDEGREE, WEIGHTED, IERROR)
44     INTEGER COMM, INDEGREE, OUTDEGREE, IERROR
45     LOGICAL WEIGHTED
46
47 MPI_GRAPH_CREATE(COMM_OLD, NNODES, INDEX, EDGES, REORDER, COMM_GRAPH,
48     IERROR)
49     INTEGER COMM_OLD, NNODES, INDEX(*), EDGES(*), COMM_GRAPH, IERROR
50     LOGICAL REORDER
51
52 MPI_GRAPHDIMS_GET(COMM, NNODES, NEDGES, IERROR)
53     INTEGER COMM, NNODES, NEDGES, IERROR

```

```

MPI_GRAPH_GET(COMM, MAXINDEX, MAXEDGES, INDEX, EDGES, IERROR)
    INTEGER COMM, MAXINDEX, MAXEDGES, INDEX(*), EDGES(*), IERROR
MPI_GRAPH_MAP(COMM, NNODES, INDEX, EDGES, NEWRANK, IERROR)
    INTEGER COMM, NNODES, INDEX(*), EDGES(*), NEWRANK, IERROR
MPI_GRAPH_NEIGHBORS(COMM, RANK, MAXNEIGHBORS, NEIGHBORS, IERROR)
    INTEGER COMM, RANK, MAXNEIGHBORS, NEIGHBORS(*), IERROR
MPI_GRAPH_NEIGHBORS_COUNT(COMM, RANK, NNEIGHBORS, IERROR)
    INTEGER COMM, RANK, NNEIGHBORS, IERROR
MPI_TOPO_TEST(COMM, STATUS, IERROR)
    INTEGER COMM, STATUS, IERROR

```

### A.3.6 MPI Environmental Management Fortran Bindings

```

DOUBLE PRECISION MPI_WTICK()
DOUBLE PRECISION MPI_WTIME()
MPI_ABORT(COMM, ERRORCODE, IERROR)
    INTEGER COMM, ERRORCODE, IERROR
MPI_ADD_ERROR_CLASS(ERRORCLASS, IERROR)
    INTEGER ERRORCLASS, IERROR
MPI_ADD_ERROR_CODE(ERRORCLASS, ERRORCODE, IERROR)
    INTEGER ERRORCLASS, ERRORCODE, IERROR
MPI_ADD_ERROR_STRING(ERRORCODE, STRING, IERROR)
    INTEGER ERRORCODE, IERROR
    CHARACTER*(*) STRING
MPI_ALLOC_MEM(SIZE, INFO, BASEPTR, IERROR)
    USE, INTRINSIC :: ISO_C_BINDING
    INTEGER :: INFO, IERROR
    INTEGER(KIND=MPI_ADDRESS_KIND) :: SIZE
    TYPE(C_PTR) :: BASEPTR !overloaded with following...
    INTEGER(KIND=MPI_ADDRESS_KIND) BASEPTR ! ...type
MPI_COMM_CALL_ERRHANDLER(COMM, ERRORCODE, IERROR)
    INTEGER COMM, ERRORCODE, IERROR
MPI_COMM_CREATE_ERRHANDLER(COMM_ERRHANDLER_FN, ERRHANDLER, IERROR)
    EXTERNAL COMM_ERRHANDLER_FN
    INTEGER ERRHANDLER, IERROR
MPI_COMM_GET_ERRHANDLER(COMM, ERRHANDLER, IERROR)
    INTEGER COMM, ERRHANDLER, IERROR
MPI_COMM_SET_ERRHANDLER(COMM, ERRHANDLER, IERROR)
    INTEGER COMM, ERRHANDLER, IERROR

```

```

1  MPI_ERRHANDLER_FREE(ERRHANDLER, IERROR)
2      INTEGER ERRHANDLER, IERROR
3
4  MPI_ERROR_CLASS(ERRORCODE, ERRORCLASS, IERROR)
5      INTEGER ERRORCODE, ERRORCLASS, IERROR
6
7  MPI_ERROR_STRING(ERRORCODE, STRING, RESULTLEN, IERROR)
8      INTEGER ERRORCODE, RESULTLEN, IERROR
9      CHARACTER*(*) STRING
10
11 MPI_FILE_CALL_ERRHANDLER(FH, ERRORCODE, IERROR)
12     INTEGER FH, ERRORCODE, IERROR
13
14 MPI_FILE_CREATE_ERRHANDLER(FILE_ERRHANDLER_FN, ERRHANDLER, IERROR)
15     EXTERNAL FILE_ERRHANDLER_FN
16     INTEGER ERRHANDLER, IERROR
17
18 MPI_FILE_GET_ERRHANDLER(FILE, ERRHANDLER, IERROR)
19     INTEGER FILE, ERRHANDLER, IERROR
20
21 MPI_FILE_SET_ERRHANDLER(FILE, ERRHANDLER, IERROR)
22     INTEGER FILE, ERRHANDLER, IERROR
23
24 MPI_FINALIZED(FLAG, IERROR)
25     LOGICAL FLAG
26     INTEGER IERROR
27
28 MPI_FINALIZE(IERROR)
29     INTEGER IERROR
30
31 MPI_FREE_MEM(BASE, IERROR)
32     <type> BASE(*)
33     INTEGER IERROR
34
35 MPI_GET_PROCESSOR_NAME( NAME, RESULTLEN, IERROR)
36     CHARACTER*(*) NAME
37     INTEGER RESULTLEN, IERROR
38
39 MPI_GET_VERSION(VERSION, SUBVERSION, IERROR)
40     INTEGER VERSION, SUBVERSION, IERROR
41
42 MPI_INITIALIZED(FLAG, IERROR)
43     LOGICAL FLAG
44     INTEGER IERROR
45
46 MPI_INIT(IERROR)
47     INTEGER IERROR
48
49 MPI_WIN_CALL_ERRHANDLER(WIN, ERRORCODE, IERROR)
50     INTEGER WIN, ERRORCODE, IERROR
51
52 MPI_WIN_CREATE_ERRHANDLER(WIN_ERRHANDLER_FN, ERRHANDLER, IERROR)
53     EXTERNAL WIN_ERRHANDLER_FN
54     INTEGER ERRHANDLER, IERROR
55
56

```

```

MPI_WIN_GET_ERRHANDLER(WIN, ERRHANDLER, IERROR)
    INTEGER WIN, ERRHANDLER, IERROR
MPI_WIN_SET_ERRHANDLER(WIN, ERRHANDLER, IERROR)
    INTEGER WIN, ERRHANDLER, IERROR

```

### A.3.7 The Info Object Fortran Bindings

```

MPI_INFO_CREATE(INFO, IERROR)
    INTEGER INFO, IERROR
MPI_INFO_DELETE(INFO, KEY, IERROR)
    INTEGER INFO, IERROR
    CHARACTER*(*) KEY
MPI_INFO_DUP(INFO, NEWINFO, IERROR)
    INTEGER INFO, NEWINFO, IERROR
MPI_INFO_FREE(INFO, IERROR)
    INTEGER INFO, IERROR
MPI_INFO_GET(INFO, KEY, VALUELEN, VALUE, FLAG, IERROR)
    INTEGER INFO, VALUELEN, IERROR
    CHARACTER*(*) KEY, VALUE
    LOGICAL FLAG
MPI_INFO_GET_NKEYS(INFO, NKEYS, IERROR)
    INTEGER INFO, NKEYS, IERROR
MPI_INFO_GET_NTHKEY(INFO, N, KEY, IERROR)
    INTEGER INFO, N, IERROR
    CHARACTER*(*) KEY
MPI_INFO_GET_VALUELEN(INFO, KEY, VALUELEN, FLAG, IERROR)
    INTEGER INFO, VALUELEN, IERROR
    LOGICAL FLAG
    CHARACTER*(*) KEY
MPI_INFO_SET(INFO, KEY, VALUE, IERROR)
    INTEGER INFO, IERROR
    CHARACTER*(*) KEY, VALUE

```

### A.3.8 Process Creation and Management Fortran Bindings

```

MPI_CLOSE_PORT(PORT_NAME, IERROR)
    CHARACTER*(*) PORT_NAME
    INTEGER IERROR
MPI_COMM_ACCEPT(PORT_NAME, INFO, ROOT, COMM, NEWCOMM, IERROR)
    CHARACTER*(*) PORT_NAME
    INTEGER INFO, ROOT, COMM, NEWCOMM, IERROR

```

```

1  MPI_COMM_CONNECT(PORT_NAME, INFO, ROOT, COMM, NEWCOMM, IERROR)
2      CHARACTER*(*) PORT_NAME
3      INTEGER INFO, ROOT, COMM, NEWCOMM, IERROR
4
5  MPI_COMM_DISCONNECT(COMM, IERROR)
6      INTEGER COMM, IERROR
7
8  MPI_COMM_GET_PARENT(PARENT, IERROR)
9      INTEGER PARENT, IERROR
10
11 MPI_COMM_JOIN(FD, INTERCOMM, IERROR)
12     INTEGER FD, INTERCOMM, IERROR
13
14 MPI_COMM_SPAWN(COMMAND, ARGV, MAXPROCS, INFO, ROOT, COMM, INTERCOMM,
15     ARRAY_OF_ERRCODES, IERROR)
16     CHARACTER*(*) COMMAND, ARGV(*)
17     INTEGER INFO, MAXPROCS, ROOT, COMM, INTERCOMM, ARRAY_OF_ERRCODES(*),
18     IERROR
19
20 MPI_COMM_SPAWN_MULTIPLE(COUNT, ARRAY_OF_COMMANDS, ARRAY_OF_ARGV,
21     ARRAY_OF_MAXPROCS, ARRAY_OF_INFO, ROOT, COMM, INTERCOMM,
22     ARRAY_OF_ERRCODES, IERROR)
23     INTEGER COUNT, ARRAY_OF_INFO(*), ARRAY_OF_MAXPROCS(*), ROOT, COMM,
24     INTERCOMM, ARRAY_OF_ERRCODES(*), IERROR
25     CHARACTER*(*) ARRAY_OF_COMMANDS(*), ARRAY_OF_ARGV(COUNT, *)
26
27 MPI_LOOKUP_NAME(SERVICE_NAME, INFO, PORT_NAME, IERROR)
28     CHARACTER*(*) SERVICE_NAME, PORT_NAME
29     INTEGER INFO, IERROR
30
31 MPI_OPEN_PORT(INFO, PORT_NAME, IERROR)
32     CHARACTER*(*) PORT_NAME
33     INTEGER INFO, IERROR
34
35 MPI_PUBLISH_NAME(SERVICE_NAME, INFO, PORT_NAME, IERROR)
36     INTEGER INFO, IERROR
37     CHARACTER*(*) SERVICE_NAME, PORT_NAME
38
39 MPI_UNPUBLISH_NAME(SERVICE_NAME, INFO, PORT_NAME, IERROR)
40     INTEGER INFO, IERROR
41     CHARACTER*(*) SERVICE_NAME, PORT_NAME
42
43
44
45
46
47
48

```

### A.3.9 One-Sided Communications Fortran Bindings

```

41 MPI_ACCUMULATE(ORIGIN_ADDR, ORIGIN_COUNT, ORIGIN_DATATYPE, TARGET_RANK,
42     TARGET_DISP, TARGET_COUNT, TARGET_DATATYPE, OP, WIN, IERROR)
43     <type> ORIGIN_ADDR(*)
44     INTEGER(KIND=MPI_ADDRESS_KIND) TARGET_DISP
45     INTEGER ORIGIN_COUNT, ORIGIN_DATATYPE, TARGET_RANK, TARGET_COUNT,
46     TARGET_DATATYPE, OP, WIN, IERROR
47
48 MPI_GET(ORIGIN_ADDR, ORIGIN_COUNT, ORIGIN_DATATYPE, TARGET_RANK,

```



```

        TARGET_DISP, TARGET_COUNT, TARGET_DATATYPE, WIN, IERROR)      1
    <type> ORIGIN_ADDR(*)                                              2
    INTEGER(KIND=MPI_ADDRESS_KIND) TARGET_DISP                        3
    INTEGER ORIGIN_COUNT, ORIGIN_DATATYPE, TARGET_RANK, TARGET_COUNT, 4
    TARGET_DATATYPE, WIN, IERROR                                       5
                                                                    6
MPI_PUT(ORIGIN_ADDR, ORIGIN_COUNT, ORIGIN_DATATYPE, TARGET_RANK,      7
        TARGET_DISP, TARGET_COUNT, TARGET_DATATYPE, WIN, IERROR)    8
    <type> ORIGIN_ADDR(*)                                              9
    INTEGER(KIND=MPI_ADDRESS_KIND) TARGET_DISP                       10
    INTEGER ORIGIN_COUNT, ORIGIN_DATATYPE, TARGET_RANK, TARGET_COUNT, 11
    TARGET_DATATYPE, WIN, IERROR                                       12
                                                                    13
MPI_WIN_COMPLETE(WIN, IERROR)                                         14
    INTEGER WIN, IERROR                                               15
                                                                    16
MPI_WIN_CREATE(BASE, SIZE, DISP_UNIT, INFO, COMM, WIN, IERROR)       17
    <type> BASE(*)                                                    18
    INTEGER(KIND=MPI_ADDRESS_KIND) SIZE                              19
    INTEGER DISP_UNIT, INFO, COMM, WIN, IERROR                       20
                                                                    21
MPI_WIN_FENCE(ASSERT, WIN, IERROR)                                    22
    INTEGER ASSERT, WIN, IERROR                                       23
                                                                    24
MPI_WIN_FREE(WIN, IERROR)                                             25
    INTEGER WIN, IERROR                                               26
                                                                    27
MPI_WIN_GET_GROUP(WIN, GROUP, IERROR)                                  28
    INTEGER WIN, GROUP, IERROR                                         29
                                                                    30
MPI_WIN_LOCK(LOCK_TYPE, RANK, ASSERT, WIN, IERROR)                   31
    INTEGER LOCK_TYPE, RANK, ASSERT, WIN, IERROR                     32
                                                                    33
MPI_WIN_POST(GROUP, ASSERT, WIN, IERROR)                              34
    INTEGER GROUP, ASSERT, WIN, IERROR                                 35
                                                                    36
MPI_WIN_START(GROUP, ASSERT, WIN, IERROR)                             37
    INTEGER GROUP, ASSERT, WIN, IERROR                                 38
                                                                    39
MPI_WIN_TEST(WIN, FLAG, IERROR)                                       40
    INTEGER WIN, IERROR                                               41
    LOGICAL FLAG                                                       42
                                                                    43
MPI_WIN_UNLOCK(RANK, WIN, IERROR)                                      44
    INTEGER RANK, WIN, IERROR                                          45
                                                                    46
MPI_WIN_WAIT(WIN, IERROR)                                             47
    INTEGER WIN, IERROR                                               48

```

A.3.10 External Interfaces Fortran Bindings

```

MPI_GREQUEST_COMPLETE(REQUEST, IERROR)
    INTEGER REQUEST, IERROR

```

```

1  MPI_GREQUEST_START(QUERY_FN, FREE_FN, CANCEL_FN, EXTRA_STATE, REQUEST,
2      IERROR)
3      INTEGER REQUEST, IERROR
4      EXTERNAL QUERY_FN, FREE_FN, CANCEL_FN
5      INTEGER (KIND=MPI_ADDRESS_KIND) EXTRA_STATE
6
7  MPI_INIT_THREAD(REQUIRED, PROVIDED, IERROR)
8      INTEGER REQUIRED, PROVIDED, IERROR
9
10 MPI_IS_THREAD_MAIN(FLAG, IERROR)
11     LOGICAL FLAG
12     INTEGER IERROR
13
14 MPI_QUERY_THREAD(PROVIDED, IERROR)
15     INTEGER PROVIDED, IERROR
16
17 MPI_STATUS_SET_CANCELLED(STATUS, FLAG, IERROR)
18     INTEGER STATUS(MPI_STATUS_SIZE), IERROR
19     LOGICAL FLAG
20
21 MPI_STATUS_SET_ELEMENTS(STATUS, DATATYPE, COUNT, IERROR)
22     INTEGER STATUS(MPI_STATUS_SIZE), DATATYPE, COUNT, IERROR

```

### A.3.11 I/O Fortran Bindings

```

23
24 MPI_FILE_CLOSE(FH, IERROR)
25     INTEGER FH, IERROR
26
27 MPI_FILE_DELETE(FILENAME, INFO, IERROR)
28     CHARACTER*(*) FILENAME
29     INTEGER INFO, IERROR
30
31 MPI_FILE_GET_AMODE(FH, AMODE, IERROR)
32     INTEGER FH, AMODE, IERROR
33
34 MPI_FILE_GET_ATOMICITY(FH, FLAG, IERROR)
35     INTEGER FH, IERROR
36     LOGICAL FLAG
37
38 MPI_FILE_GET_BYTE_OFFSET(FH, OFFSET, DISP, IERROR)
39     INTEGER FH, IERROR
40     INTEGER(KIND=MPI_OFFSET_KIND) OFFSET, DISP
41
42 MPI_FILE_GET_GROUP(FH, GROUP, IERROR)
43     INTEGER FH, GROUP, IERROR
44
45 MPI_FILE_GET_INFO(FH, INFO_USED, IERROR)
46     INTEGER FH, INFO_USED, IERROR
47
48 MPI_FILE_GET_POSITION(FH, OFFSET, IERROR)
49     INTEGER FH, IERROR
50     INTEGER(KIND=MPI_OFFSET_KIND) OFFSET

```

MPI_FILE_GET_POSITION_SHARED(FH, OFFSET, IERROR)	1
INTEGER FH, IERROR	2
INTEGER(KIND=MPI_OFFSET_KIND) OFFSET	3
	4
MPI_FILE_GET_SIZE(FH, SIZE, IERROR)	5
INTEGER FH, IERROR	6
INTEGER(KIND=MPI_OFFSET_KIND) SIZE	7
	8
MPI_FILE_GET_TYPE_EXTENT(FH, DATATYPE, EXTENT, IERROR)	9
INTEGER FH, DATATYPE, IERROR	10
INTEGER(KIND=MPI_ADDRESS_KIND) EXTENT	11
	12
MPI_FILE_GET_VIEW(FH, DISP, ETYPE, FILETYPE, DATAREP, IERROR)	13
INTEGER FH, ETYPE, FILETYPE, IERROR	14
CHARACTER*(*) DATAREP	15
INTEGER(KIND=MPI_OFFSET_KIND) DISP	16
	17
MPI_FILE_IREAD_AT(FH, OFFSET, BUF, COUNT, DATATYPE, REQUEST, IERROR)	18
<type> BUF(*)	19
INTEGER FH, COUNT, DATATYPE, REQUEST, IERROR	20
INTEGER(KIND=MPI_OFFSET_KIND) OFFSET	21
	22
MPI_FILE_IREAD(FH, BUF, COUNT, DATATYPE, REQUEST, IERROR)	23
<type> BUF(*)	24
INTEGER FH, COUNT, DATATYPE, REQUEST, IERROR	25
	26
MPI_FILE_IREAD_SHARED(FH, BUF, COUNT, DATATYPE, REQUEST, IERROR)	27
<type> BUF(*)	28
INTEGER FH, COUNT, DATATYPE, REQUEST, IERROR	29
	30
MPI_FILE_IWRITE_AT(FH, OFFSET, BUF, COUNT, DATATYPE, REQUEST, IERROR)	31
<type> BUF(*)	32
INTEGER FH, COUNT, DATATYPE, REQUEST, IERROR	33
INTEGER(KIND=MPI_OFFSET_KIND) OFFSET	34
	35
MPI_FILE_IWRITE(FH, BUF, COUNT, DATATYPE, REQUEST, IERROR)	36
<type> BUF(*)	37
INTEGER FH, COUNT, DATATYPE, REQUEST, IERROR	38
	39
MPI_FILE_IWRITE_SHARED(FH, BUF, COUNT, DATATYPE, REQUEST, IERROR)	40
<type> BUF(*)	41
INTEGER FH, COUNT, DATATYPE, REQUEST, IERROR	42
	43
MPI_FILE_OPEN(COMM, FILENAME, AMODE, INFO, FH, IERROR)	44
CHARACTER*(*) FILENAME	45
INTEGER COMM, AMODE, INFO, FH, IERROR	46
	47
MPI_FILE_PREALLOCATE(FH, SIZE, IERROR)	48
INTEGER FH, IERROR	
INTEGER(KIND=MPI_OFFSET_KIND) SIZE	
MPI_FILE_READ_ALL_BEGIN(FH, BUF, COUNT, DATATYPE, IERROR)	
<type> BUF(*)	

```

1      INTEGER FH, COUNT, DATATYPE, IERROR
2
3      MPI_FILE_READ_ALL_END(FH, BUF, STATUS, IERROR)
4          <type> BUF(*)
5          INTEGER FH, STATUS(MPI_STATUS_SIZE), IERROR
6
7      MPI_FILE_READ_ALL(FH, BUF, COUNT, DATATYPE, STATUS, IERROR)
8          <type> BUF(*)
9          INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
10
11     MPI_FILE_READ_AT_ALL_BEGIN(FH, OFFSET, BUF, COUNT, DATATYPE, IERROR)
12         <type> BUF(*)
13         INTEGER FH, COUNT, DATATYPE, IERROR
14         INTEGER(KIND=MPI_OFFSET_KIND) OFFSET
15
16     MPI_FILE_READ_AT_ALL_END(FH, BUF, STATUS, IERROR)
17         <type> BUF(*)
18         INTEGER FH, STATUS(MPI_STATUS_SIZE), IERROR
19
20     MPI_FILE_READ_AT_ALL(FH, OFFSET, BUF, COUNT, DATATYPE, STATUS, IERROR)
21         <type> BUF(*)
22         INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
23         INTEGER(KIND=MPI_OFFSET_KIND) OFFSET
24
25     MPI_FILE_READ_AT(FH, OFFSET, BUF, COUNT, DATATYPE, STATUS, IERROR)
26         <type> BUF(*)
27         INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
28         INTEGER(KIND=MPI_OFFSET_KIND) OFFSET
29
30     MPI_FILE_READ(FH, BUF, COUNT, DATATYPE, STATUS, IERROR)
31         <type> BUF(*)
32         INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
33
34     MPI_FILE_READ_ORDERED_BEGIN(FH, BUF, COUNT, DATATYPE, IERROR)
35         <type> BUF(*)
36         INTEGER FH, COUNT, DATATYPE, IERROR
37
38     MPI_FILE_READ_ORDERED_END(FH, BUF, STATUS, IERROR)
39         <type> BUF(*)
40         INTEGER FH, STATUS(MPI_STATUS_SIZE), IERROR
41
42     MPI_FILE_READ_ORDERED(FH, BUF, COUNT, DATATYPE, STATUS, IERROR)
43         <type> BUF(*)
44         INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
45
46     MPI_FILE_READ_SHARED(FH, BUF, COUNT, DATATYPE, STATUS, IERROR)
47         <type> BUF(*)
48         INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
49
50     MPI_FILE_SEEK(FH, OFFSET, WHENCE, IERROR)
51         INTEGER FH, WHENCE, IERROR
52         INTEGER(KIND=MPI_OFFSET_KIND) OFFSET
53
54     MPI_FILE_SEEK_SHARED(FH, OFFSET, WHENCE, IERROR)

```

INTEGER FH, WHENCE, IERROR	1
INTEGER(KIND=MPI_OFFSET_KIND) OFFSET	2
	3
MPI_FILE_SET_ATOMICITY(FH, FLAG, IERROR)	4
INTEGER FH, IERROR	5
LOGICAL FLAG	6
	7
MPI_FILE_SET_INFO(FH, INFO, IERROR)	8
INTEGER FH, INFO, IERROR	9
	10
MPI_FILE_SET_SIZE(FH, SIZE, IERROR)	11
INTEGER FH, IERROR	12
INTEGER(KIND=MPI_OFFSET_KIND) SIZE	13
	14
MPI_FILE_SET_VIEW(FH, DISP, ETYPE, FILETYPE, DATAREP, INFO, IERROR)	15
INTEGER FH, ETYPE, FILETYPE, INFO, IERROR	16
CHARACTER*(*) DATAREP	17
INTEGER(KIND=MPI_OFFSET_KIND) DISP	18
	19
MPI_FILE_SYNC(FH, IERROR)	20
INTEGER FH, IERROR	21
	22
MPI_FILE_WRITE_ALL_BEGIN(FH, BUF, COUNT, DATATYPE, IERROR)	23
<type> BUF(*)	24
INTEGER FH, COUNT, DATATYPE, IERROR	25
	26
MPI_FILE_WRITE_ALL_END(FH, BUF, STATUS, IERROR)	27
<type> BUF(*)	28
INTEGER FH, STATUS(MPI_STATUS_SIZE), IERROR	29
	30
MPI_FILE_WRITE_ALL(FH, BUF, COUNT, DATATYPE, STATUS, IERROR)	31
<type> BUF(*)	32
INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR	33
INTEGER(KIND=MPI_OFFSET_KIND) OFFSET	34
	35
MPI_FILE_WRITE_AT_ALL_BEGIN(FH, OFFSET, BUF, COUNT, DATATYPE, IERROR)	36
<type> BUF(*)	37
INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR	38
INTEGER(KIND=MPI_OFFSET_KIND) OFFSET	39
	40
MPI_FILE_WRITE_AT_ALL_END(FH, OFFSET, BUF, COUNT, DATATYPE, STATUS, IERROR)	41
<type> BUF(*)	42
INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR	43
INTEGER(KIND=MPI_OFFSET_KIND) OFFSET	44
	45
MPI_FILE_WRITE_AT(FH, OFFSET, BUF, COUNT, DATATYPE, STATUS, IERROR)	46
<type> BUF(*)	47
INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR	48
INTEGER(KIND=MPI_OFFSET_KIND) OFFSET	
MPI_FILE_WRITE(FH, BUF, COUNT, DATATYPE, STATUS, IERROR)	

```

1      <type> BUF(*)
2      INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
3
4      MPI_FILE_WRITE_ORDERED_BEGIN(FH, BUF, COUNT, DATATYPE, IERROR)
5      <type> BUF(*)
6      INTEGER FH, COUNT, DATATYPE, IERROR
7
8      MPI_FILE_WRITE_ORDERED_END(FH, BUF, STATUS, IERROR)
9      <type> BUF(*)
10     INTEGER FH, STATUS(MPI_STATUS_SIZE), IERROR
11
12     MPI_FILE_WRITE_ORDERED(FH, BUF, COUNT, DATATYPE, STATUS, IERROR)
13     <type> BUF(*)
14     INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
15
16     MPI_FILE_WRITE_SHARED(FH, BUF, COUNT, DATATYPE, STATUS, IERROR)
17     <type> BUF(*)
18     INTEGER FH, COUNT, DATATYPE, STATUS(MPI_STATUS_SIZE), IERROR
19
20     MPI_REGISTER_DATAREP(DATAREP, READ_CONVERSION_FN, WRITE_CONVERSION_FN,
21                          DTYPE_FILE_EXTENT_FN, EXTRA_STATE, IERROR)
22     CHARACTER*(*) DATAREP
23     EXTERNAL READ_CONVERSION_FN, WRITE_CONVERSION_FN, DTYPE_FILE_EXTENT_FN
24     INTEGER(KIND=MPI_ADDRESS_KIND) EXTRA_STATE
25     INTEGER IERROR

```

### A.3.12 Language Bindings Fortran Bindings

```

26
27     MPI_F_SYNC_REG(buf)
28     <type> buf(*)
29
30     MPI_SIZEOF(X, SIZE, IERROR)
31     <type> X
32     INTEGER SIZE, IERROR
33
34     MPI_STATUS_F082F(F08_STATUS, F_STATUS, IERROR)
35     TYPE(MPI_Status) :: F08_STATUS
36     INTEGER :: F_STATUS(MPI_STATUS_SIZE)
37     INTEGER IERROR
38
39     MPI_STATUS_F2F08(F_STATUS, F08_STATUS, IERROR)
40     INTEGER :: F_STATUS(MPI_STATUS_SIZE)
41     TYPE(MPI_Status) :: F08_STATUS
42     INTEGER IERROR
43
44     MPI_TYPE_CREATE_F90_COMPLEX(P, R, NEWTYPE, IERROR)
45     INTEGER P, R, NEWTYPE, IERROR
46
47     MPI_TYPE_CREATE_F90_INTEGER(R, NEWTYPE, IERROR)
48     INTEGER R, NEWTYPE, IERROR
49
50     MPI_TYPE_CREATE_F90_REAL(P, R, NEWTYPE, IERROR)
51     INTEGER P, R, NEWTYPE, IERROR

```

```

MPI_TYPE_MATCH_SIZE(TYPECLASS, SIZE, DATATYPE, IERROR)
    INTEGER TYPECLASS, SIZE, DATATYPE, IERROR

```

1 ticket252-W.

2 ticket252-W.

3

4

### A.3.13 Profiling Interface Fortran Bindings

5

```

MPI_PCONTROL(LEVEL)
    INTEGER LEVEL

```

6

7

8

9

### A.3.14 Deprecated Fortran Bindings

10

```

MPI_ADDRESS(LOCATION, ADDRESS, IERROR)
    <type> LOCATION(*)
    INTEGER ADDRESS, IERROR

```

11

12

13

14

```

MPI_ATTR_DELETE(COMM, KEYVAL, IERROR)
    INTEGER COMM, KEYVAL, IERROR

```

15

16

17

```

MPI_ATTR_GET(COMM, KEYVAL, ATTRIBUTE_VAL, FLAG, IERROR)
    INTEGER COMM, KEYVAL, ATTRIBUTE_VAL, IERROR
    LOGICAL FLAG

```

18

19

20

```

MPI_ATTR_PUT(COMM, KEYVAL, ATTRIBUTE_VAL, IERROR)
    INTEGER COMM, KEYVAL, ATTRIBUTE_VAL, IERROR

```

21

22

23

```

MPI_DUP_FN(OLDCOMM, KEYVAL, EXTRA_STATE, ATTRIBUTE_VAL_IN,
           ATTRIBUTE_VAL_OUT, FLAG, IERR)
    INTEGER OLDCOMM, KEYVAL, EXTRA_STATE, ATTRIBUTE_VAL_IN,
    ATTRIBUTE_VAL_OUT, IERR
    LOGICAL FLAG

```

24

25

26

27

28

```

MPI_ERRHANDLER_CREATE(HANDLER_FN, ERRHANDLER, IERROR)
    EXTERNAL HANDLER_FN
    INTEGER ERRHANDLER, IERROR

```

29 ticket252-W.

30 ticket252-W.

31

32

```

MPI_ERRHANDLER_GET(COMM, ERRHANDLER, IERROR)
    INTEGER COMM, ERRHANDLER, IERROR

```

33

34

```

MPI_ERRHANDLER_SET(COMM, ERRHANDLER, IERROR)
    INTEGER COMM, ERRHANDLER, IERROR

```

35

36

37

```

MPI_KEYVAL_CREATE(COPY_FN, DELETE_FN, KEYVAL, EXTRA_STATE, IERROR)
    EXTERNAL COPY_FN, DELETE_FN
    INTEGER KEYVAL, EXTRA_STATE, IERROR

```

38

39

40

```

MPI_KEYVAL_FREE(KEYVAL, IERROR)
    INTEGER KEYVAL, IERROR

```

41

42

43

```

MPI_NULL_COPY_FN(OLDCOMM, KEYVAL, EXTRA_STATE, ATTRIBUTE_VAL_IN,
                 ATTRIBUTE_VAL_OUT, FLAG, IERR)
    INTEGER OLDCOMM, KEYVAL, EXTRA_STATE, ATTRIBUTE_VAL_IN,
    ATTRIBUTE_VAL_OUT, IERR
    LOGICAL FLAG

```

44

45

46

47

48

```

1  MPI_NULL_DELETE_FN(COMM, KEYVAL, ATTRIBUTE_VAL, EXTRA_STATE, IERROR)
2      INTEGER COMM, KEYVAL, ATTRIBUTE_VAL, EXTRA_STATE, IERROR
3
4  MPI_TYPE_EXTENT(DATATYPE, EXTENT, IERROR)
5      INTEGER DATATYPE, EXTENT, IERROR
6
7  MPI_TYPE_HINDEXED(COUNT, ARRAY_OF_BLOCKLENGTHS, ARRAY_OF_DISPLACEMENTS,
8      OLDTYPE, NEWTYPE, IERROR)
9      INTEGER COUNT, ARRAY_OF_BLOCKLENGTHS(*), ARRAY_OF_DISPLACEMENTS(*),
10     OLDTYPE, NEWTYPE, IERROR
11
12 MPI_TYPE_HVECTOR(COUNT, BLOCKLENGTH, STRIDE, OLDTYPE, NEWTYPE, IERROR)
13     INTEGER COUNT, BLOCKLENGTH, STRIDE, OLDTYPE, NEWTYPE, IERROR
14
15 MPI_TYPE_LB( DATATYPE, DISPLACEMENT, IERROR)
16     INTEGER DATATYPE, DISPLACEMENT, IERROR
17
18 MPI_TYPE_STRUCT(COUNT, ARRAY_OF_BLOCKLENGTHS, ARRAY_OF_DISPLACEMENTS,
19     ARRAY_OF_TYPES, NEWTYPE, IERROR)
20     INTEGER COUNT, ARRAY_OF_BLOCKLENGTHS(*), ARRAY_OF_DISPLACEMENTS(*),
21     ARRAY_OF_TYPES(*), NEWTYPE, IERROR
22
23 MPI_TYPE_UB( DATATYPE, DISPLACEMENT, IERROR)
24     INTEGER DATATYPE, DISPLACEMENT, IERROR
25
26 SUBROUTINE COPY_FUNCTION(OLDCOMM, KEYVAL, EXTRA_STATE, ATTRIBUTE_VAL_IN,
27     ATTRIBUTE_VAL_OUT, FLAG, IERR)
28     INTEGER OLDCOMM, KEYVAL, EXTRA_STATE, ATTRIBUTE_VAL_IN,
29     ATTRIBUTE_VAL_OUT, IERR
30     LOGICAL FLAG
31
32 SUBROUTINE DELETE_FUNCTION(COMM, KEYVAL, ATTRIBUTE_VAL, EXTRA_STATE, IERR)
33     INTEGER COMM, KEYVAL, ATTRIBUTE_VAL, EXTRA_STATE, IERR
34
35
36
37
38
39
40
41
42
43
44
45
46
47
48

```



## A.4 Fortran 2008 Bindings with the mpi\_f08 Module

### A.4.1 Point-to-Point Communication Fortran 2008 Bindings

`MPI_Bsend(buf, count, datatype, dest, tag, comm, ierror)`

```
TYPE(*), DIMENSION(..) :: buf
INTEGER, INTENT(IN) :: count, dest, tag
TYPE(MPI_Datatype), INTENT(IN) :: datatype
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

`MPI_Bsend_init(buf, count, datatype, dest, tag, comm, request, ierror)`

```
TYPE(*), DIMENSION(..) :: buf
INTEGER, INTENT(IN) :: count, dest, tag
TYPE(MPI_Datatype), INTENT(IN) :: datatype
TYPE(MPI_Comm), INTENT(IN) :: comm
TYPE(MPI_Request), INTENT(OUT) :: request
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

`MPI_Buffer_attach(buffer, size, ierror)`

```
TYPE(*), DIMENSION(..) :: buffer
INTEGER, INTENT(IN) :: size
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

`MPI_Buffer_detach(buffer_addr, size, ierror)`

```
TYPE(*), DIMENSION(..) :: buffer_addr
INTEGER, INTENT(OUT) :: size
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

`MPI_Cancel(request, ierror)`

```
TYPE(MPI_Request), INTENT(IN) :: request
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

`MPI_Get_count(status, datatype, count, ierror)`

```
TYPE(MPI_Status), INTENT(IN) :: status
TYPE(MPI_Datatype), INTENT(IN) :: datatype
INTEGER, INTENT(OUT) :: count
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

`MPI_Ibsend(buf, count, datatype, dest, tag, comm, request, ierror)`

```
TYPE(*), DIMENSION(..) :: buf
INTEGER, INTENT(IN) :: count, dest, tag
TYPE(MPI_Datatype), INTENT(IN) :: datatype
TYPE(MPI_Comm), INTENT(IN) :: comm
TYPE(MPI_Request), INTENT(OUT) :: request
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

`MPI_Iprobe(source, tag, comm, flag, status, ierror)`

```
INTEGER, INTENT(IN) :: source, tag
```

```

1      TYPE(MPI_Comm), INTENT(IN) :: comm
2      LOGICAL, INTENT(OUT) :: flag
3      TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
4      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 5
6      MPI_Irecv(buf, count, datatype, source, tag, comm, request, ierror)
7      TYPE(*), DIMENSION(..) :: buf
8      INTEGER, INTENT(IN) :: count, source, tag
9      TYPE(MPI_Datatype), INTENT(IN) :: datatype
10     TYPE(MPI_Comm), INTENT(IN) :: comm
11     TYPE(MPI_Request), INTENT(OUT) :: request
12     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 13
14     MPI_Irsend(buf, count, datatype, dest, tag, comm, request, ierror)
15     TYPE(*), DIMENSION(..) :: buf
16     INTEGER, INTENT(IN) :: count, dest, tag
17     TYPE(MPI_Datatype), INTENT(IN) :: datatype
18     TYPE(MPI_Comm), INTENT(IN) :: comm
19     TYPE(MPI_Request), INTENT(OUT) :: request
20     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 21
22     MPI_Isend(buf, count, datatype, dest, tag, comm, request, ierror)
23     TYPE(*), DIMENSION(..) :: buf
24     INTEGER, INTENT(IN) :: count, dest, tag
25     TYPE(MPI_Datatype), INTENT(IN) :: datatype
26     TYPE(MPI_Comm), INTENT(IN) :: comm
27     TYPE(MPI_Request), INTENT(OUT) :: request
28     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 29
30     MPI_Issend(buf, count, datatype, dest, tag, comm, request, ierror)
31     TYPE(*), DIMENSION(..) :: buf
32     INTEGER, INTENT(IN) :: count, dest, tag
33     TYPE(MPI_Datatype), INTENT(IN) :: datatype
34     TYPE(MPI_Comm), INTENT(IN) :: comm
35     TYPE(MPI_Request), INTENT(OUT) :: request
36     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 37
38     MPI_Probe(source, tag, comm, status, ierror)
39     INTEGER, INTENT(IN) :: source, tag
40     TYPE(MPI_Comm), INTENT(IN) :: comm
41     TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
42     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 43
44     MPI_Recv(buf, count, datatype, source, tag, comm, status, ierror)
45     TYPE(*), DIMENSION(..) :: buf
46     INTEGER, INTENT(IN) :: count, source, tag
47     TYPE(MPI_Datatype), INTENT(IN) :: datatype
48     TYPE(MPI_Comm), INTENT(IN) :: comm
49     TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
50     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

MPI_Recv_init(buf, count, datatype, source, tag, comm, request, ierror)
    TYPE(*), DIMENSION(..) :: buf
    INTEGER, INTENT(IN) :: count, source, tag
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Comm), INTENT(IN) :: comm
    TYPE(MPI_Request), INTENT(OUT) :: request
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Request_free(request, ierror)
    TYPE(MPI_Request), INTENT(INOUT) :: request
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Request_get_status( request, flag, status, ierror)
    TYPE(MPI_Request), INTENT(IN) :: request
    LOGICAL, INTENT(OUT) :: flag
    TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Rsend(buf, count, datatype, dest, tag, comm, ierror)
    TYPE(*), DIMENSION(..) :: buf
    INTEGER, INTENT(IN) :: count, dest, tag
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Comm), INTENT(IN) :: comm
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Rsend_init(buf, count, datatype, dest, tag, comm, request, ierror)
    TYPE(*), DIMENSION(..) :: buf
    INTEGER, INTENT(IN) :: count, dest, tag
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Comm), INTENT(IN) :: comm
    TYPE(MPI_Request), INTENT(OUT) :: request
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Send(buf, count, datatype, dest, tag, comm, ierror)
    TYPE(*), DIMENSION(..) :: buf
    INTEGER, INTENT(IN) :: count, dest, tag
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Comm), INTENT(IN) :: comm
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Send_init(buf, count, datatype, dest, tag, comm, request, ierror)
    TYPE(*), DIMENSION(..) :: buf
    INTEGER, INTENT(IN) :: count, dest, tag
    TYPE(MPI_Datatype), INTENT(IN) :: datatype
    TYPE(MPI_Comm), INTENT(IN) :: comm
    TYPE(MPI_Request), INTENT(OUT) :: request
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Sendrecv_replace(buf, count, datatype, dest, sendtag, source, recvtag,
    comm, status, ierror)
    TYPE(*), DIMENSION(..) :: buf

```

```

1      INTEGER, INTENT(IN) :: count, dest, sendtag, source, recvtag
2      TYPE(MPI_Datatype), INTENT(IN) :: datatype
3      TYPE(MPI_Comm), INTENT(IN) :: comm
4      TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
5      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 6
7      MPI_Sendrecv(sendbuf, sendcount, sendtype, dest, sendtag, recvbuf,
8                  recvcount, recvtype, source, recvtag, comm, status, ierror)
9      TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
10     INTEGER, INTENT(IN) :: sendcount, dest, sendtag, recvcount, source,
11     recvtag
12     TYPE(MPI_Datatype), INTENT(IN) :: sendtype, recvtype
13     TYPE(MPI_Comm), INTENT(IN) :: comm
14     TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
ticket-248T. 15
16     MPI_Ssend(buf, count, datatype, dest, tag, comm, ierror)
17     TYPE(*), DIMENSION(..) :: buf
18     INTEGER, INTENT(IN) :: count, dest, tag
19     TYPE(MPI_Datatype), INTENT(IN) :: datatype
20     TYPE(MPI_Comm), INTENT(IN) :: comm
21     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 22
23     MPI_Ssend_init(buf, count, datatype, dest, tag, comm, request, ierror)
24     TYPE(*), DIMENSION(..) :: buf
25     INTEGER, INTENT(IN) :: count, dest, tag
26     TYPE(MPI_Datatype), INTENT(IN) :: datatype
27     TYPE(MPI_Comm), INTENT(IN) :: comm
28     TYPE(MPI_Request), INTENT(OUT) :: request
ticket-248T. 29
30     MPI_Startall(count, array_of_requests, ierror)
31     INTEGER, INTENT(IN) :: count
32     TYPE(MPI_Request), INTENT(INOUT) :: array_of_requests(*)
33     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 34
35     MPI_Start(request, ierror)
36     TYPE(MPI_Request), INTENT(INOUT) :: request
37     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 38
39     MPI_Testall(count, array_of_requests, flag, array_of_statuses, ierror)
40     INTEGER, INTENT(IN) :: count
41     TYPE(MPI_Request), INTENT(INOUT) :: array_of_requests(*)
42     LOGICAL, INTENT(OUT) :: flag
43     TYPE(MPI_Status), INTENT(OUT) :: array_of_statuses(*) ! optional by
44     overloading
ticket-248T. 45
46     MPI_Testany(count, array_of_requests, index, flag, status, ierror)
47     INTEGER, INTENT(IN) :: count
48     TYPE(MPI_Request), INTENT(INOUT) :: array_of_requests(*)

```

```

    INTEGER, INTENT(OUT) :: index
    LOGICAL, INTENT(OUT) :: flag
    TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Test_cancelled(status, flag, ierror)
    TYPE(MPI_Status), INTENT(IN) :: status
    LOGICAL, INTENT(OUT) :: flag
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Test(request, flag, status, ierror)
    LOGICAL, INTENT(OUT) :: flag
    TYPE(MPI_Request), INTENT(INOUT) :: request
    TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Testsome(incount, array_of_requests, outcount, array_of_indices,
              array_of_statuses, ierror)
    INTEGER, INTENT(IN) :: incount
    TYPE(MPI_Request), INTENT(INOUT) :: array_of_requests(*)
    INTEGER, INTENT(OUT) :: outcount, array_of_indices(*)
    TYPE(MPI_Status), INTENT(OUT) :: array_of_statuses(*) ! optional by
    overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Waitall(count, array_of_requests, array_of_statuses, ierror)
    INTEGER, INTENT(IN) :: count
    INTEGER, INTENT(INOUT) :: array_of_requests(*)
    TYPE(MPI_Status), INTENT(OUT) :: array_of_statuses(*) ! optional by
    overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Waitany(count, array_of_requests, index, status, ierror)
    INTEGER, INTENT(IN) :: count
    TYPE(MPI_Request), INTENT(INOUT) :: array_of_requests(*)
    INTEGER, INTENT(OUT) :: index
    TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Wait(request, status, ierror)
    TYPE(MPI_Request), INTENT(INOUT) :: request
    TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Waitsome(incount, array_of_requests, outcount, array_of_indices,
              array_of_statuses, ierror)
    INTEGER, INTENT(IN) :: incount
    TYPE(MPI_Request), INTENT(INOUT) :: array_of_requests(*)
    INTEGER, INTENT(OUT) :: outcount, array_of_indices(*)
    TYPE(MPI_Status), INTENT(OUT) :: array_of_statuses(*) ! optional by
    overloading

```

```

1      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
2
3

```

#### A.4.2 Datatypes Fortran 2008 Bindings

```

4      MPI_Get_address(location, address, ierror)
5      TYPE(*), DIMENSION(..) :: location
6      INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: address
7      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
8

```

```

9      MPI_Get_elements(status, datatype, count, ierror)
10     TYPE(MPI_Status), INTENT(IN) :: status
11     TYPE(MPI_Datatype), INTENT(IN) :: datatype
12     INTEGER, INTENT(OUT) :: count
13     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
14

```

```

15     MPI_Pack_external(datarep, inbuf, incount, datatype, outbuf, outsize,
16                      position, ierror)
17     CHARACTER(LEN=*), INTENT(IN) :: datarep
18     TYPE(*), DIMENSION(..) :: inbuf, outbuf
19     INTEGER, INTENT(IN) :: incount
20     TYPE(MPI_Datatype), INTENT(IN) :: datatype
21     INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: outsize
22     INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(INOUT) :: position
23     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
24

```

```

25     MPI_Pack_external_size(datarep, incount, datatype, size, ierror)
26     TYPE(MPI_Datatype), INTENT(IN) :: datatype
27     INTEGER, INTENT(IN) :: incount
28     CHARACTER(LEN=*), INTENT(IN) :: datarep
29     INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: size
30     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
31

```

```

32     MPI_Pack(inbuf, incount, datatype, outbuf, outsize, position, comm, ierror)
33     TYPE(*), DIMENSION(..) :: inbuf, outbuf
34     INTEGER, INTENT(IN) :: incount, outsize
35     TYPE(MPI_Datatype), INTENT(IN) :: datatype
36     INTEGER, INTENT(INOUT) :: position
37     TYPE(MPI_Comm), INTENT(IN) :: comm
38     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
39

```

```

40     MPI_Pack_size(incount, datatype, comm, size, ierror)
41     INTEGER, INTENT(IN) :: incount
42     TYPE(MPI_Datatype), INTENT(IN) :: datatype
43     TYPE(MPI_Comm), INTENT(IN) :: comm
44     INTEGER, INTENT(OUT) :: size
45     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
46

```

```

47     MPI_Type_commit(datatype, ierror)
48     TYPE(MPI_Datatype), INTENT(INOUT) :: datatype
49     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
50

```

```

MPI_Type_contiguous(count, oldtype, newtype, ierror)
  INTEGER, INTENT(IN) :: count
  TYPE(MPI_Datatype), INTENT(IN) :: oldtype
  TYPE(MPI_Datatype), INTENT(OUT) :: newtype
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Type_create_darray(size, rank, ndims, array_of_gsizes,
  array_of_distribs, array_of_dargs, array_of_psize, order,
  oldtype, newtype, ierror)
  INTEGER, INTENT(IN) :: size, rank, ndims, array_of_gsize(*),
  array_of_distribs(*), array_of_dargs(*), array_of_psize(*), order
  TYPE(MPI_Datatype), INTENT(IN) :: oldtype
  TYPE(MPI_Datatype), INTENT(OUT) :: newtype
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Type_create_hindexed(count, array_of_blocklengths,
  array_of_displacements, oldtype, newtype, ierror)
  INTEGER, INTENT(IN) :: count, array_of_blocklengths(*)
  INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) ::
  array_of_displacements(*)
  TYPE(MPI_Datatype), INTENT(IN) :: oldtype
  TYPE(MPI_Datatype), INTENT(OUT) :: newtype
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Type_create_hvector(count, blocklength, stride, oldtype, newtype,
  ierror)
  INTEGER, INTENT(IN) :: count, blocklength
  INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: stride
  TYPE(MPI_Datatype), INTENT(IN) :: oldtype
  TYPE(MPI_Datatype), INTENT(OUT) :: newtype
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Type_create_indexed_block(count, blocklength, array_of_displacements,
  oldtype, newtype, ierror)
  INTEGER, INTENT(IN) :: count, blocklength, array_of_displacements(*)
  TYPE(MPI_Datatype), INTENT(IN) :: oldtype
  TYPE(MPI_Datatype), INTENT(OUT) :: newtype
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Type_create_resized(oldtype, lb, extent, newtype, ierror)
  INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: lb, extent
  TYPE(MPI_Datatype), INTENT(IN) :: oldtype
  TYPE(MPI_Datatype), INTENT(OUT) :: newtype
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Type_create_struct(count, array_of_blocklengths,
  array_of_displacements, array_of_types, newtype, ierror)
  INTEGER, INTENT(IN) :: count, array_of_blocklengths(*)
  INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) ::
  array_of_displacements(*)

```

```

1      TYPE(MPI_Datatype), INTENT(IN) :: array_of_types(*)
2      TYPE(MPI_Datatype), INTENT(OUT) :: newtype
3      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 4
5      MPI_Type_create_subarray(ndims, array_of_sizes, array_of_subsizes,
6          array_of_starts, order, oldtype, newtype, ierror)
7      INTEGER, INTENT(IN) :: ndims, array_of_sizes(*), array_of_subsizes(*),
8          array_of_starts(*), order
9      TYPE(MPI_Datatype), INTENT(IN) :: oldtype
10     TYPE(MPI_Datatype), INTENT(OUT) :: newtype
ticket-248T. 11     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
12     MPI_Type_dup(oldtype, newtype, ierror)
13     TYPE(MPI_Datatype), INTENT(IN) :: oldtype
14     TYPE(MPI_Datatype), INTENT(OUT) :: newtype
15     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 16
17     MPI_Type_free(datatype, ierror)
18     TYPE(MPI_Datatype), INTENT(INOUT) :: datatype
19     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 20
21     MPI_Type_get_contents(datatype, max_integers, max_addresses, max_datatypes,
22         array_of_integers, array_of_addresses, array_of_datatypes,
23         ierror)
24     TYPE(MPI_Datatype), INTENT(IN) :: datatype
25     INTEGER, INTENT(IN) :: max_integers, max_addresses, max_datatypes
26     INTEGER, INTENT(OUT) :: array_of_integers(*)
27     INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: array_of_addresses(*)
28     TYPE(MPI_Datatype), INTENT(OUT) :: array_of_datatypes(*)
29     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 30
31     MPI_Type_get_envelope(datatype, num_integers, num_addresses, num_datatypes,
32         combiner, ierror)
33     TYPE(MPI_Datatype), INTENT(IN) :: datatype
34     INTEGER, INTENT(OUT) :: num_integers, num_addresses, num_datatypes,
35         combiner
ticket-248T. 36     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
37     MPI_Type_get_extent(datatype, lb, extent, ierror)
38     TYPE(MPI_Datatype), INTENT(IN) :: datatype
39     INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: lb, extent
40     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 41
42     MPI_Type_get_true_extent(datatype, true_lb, true_extent, ierror)
43     TYPE(MPI_Datatype), INTENT(IN) :: datatype
44     INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: true_lb, true_extent
45     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 46
47     MPI_Type_indexed(count, array_of_blocklengths, array_of_displacements,
48         oldtype, newtype, ierror)
49     INTEGER, INTENT(IN) :: count, array_of_blocklengths(*),

```



```

array_of_displacements(*)
TYPE(MPI_Datatype), INTENT(IN) :: oldtype
TYPE(MPI_Datatype), INTENT(OUT) :: newtype
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Type_size(datatype, size, ierror)
TYPE(MPI_Datatype), INTENT(IN) :: datatype
INTEGER, INTENT(OUT) :: size
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Type_vector(count, blocklength, stride, oldtype, newtype, ierror)
INTEGER, INTENT(IN) :: count, blocklength, stride
TYPE(MPI_Datatype), INTENT(IN) :: oldtype
TYPE(MPI_Datatype), INTENT(OUT) :: newtype
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Unpack_external(datarep, inbuf, insize, position, outbuf, outcount,
    datatype, ierror)
CHARACTER(LEN=*), INTENT(IN) :: datarep
TYPE(*), DIMENSION(..) :: inbuf, outbuf
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: insize
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(INOUT) :: position
INTEGER, INTENT(IN) :: outcount
TYPE(MPI_Datatype), INTENT(IN) :: datatype
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Unpack(inbuf, insize, position, outbuf, outcount, datatype, comm,
    ierror)
TYPE(*), DIMENSION(..) :: inbuf, outbuf
INTEGER, INTENT(IN) :: insize, outcount
INTEGER, INTENT(INOUT) :: position
TYPE(MPI_Datatype), INTENT(IN) :: datatype
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

A.4.3 Collective Communication Fortran 2008 Bindings
MPI_Allgather(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype,
    comm, ierror)
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
INTEGER, INTENT(IN) :: sendcount, recvcount
TYPE(MPI_Datatype), INTENT(IN) :: sendtype
TYPE(MPI_Datatype), INTENT(IN) :: recvtype
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Allgatherv(sendbuf, sendcount, sendtype, recvbuf, recvcounts, displs,
    recvtype, comm, ierror)
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
INTEGER, INTENT(IN) :: sendcount, recvcounts(*), displs(*)

```

```

1      TYPE(MPI_Datatype), INTENT(IN) :: sendtype
2      TYPE(MPI_Datatype), INTENT(IN) :: recvtype
3      TYPE(MPI_Comm), INTENT(IN) :: comm
4      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 5
6      MPI_Allreduce(sendbuf, recvbuf, count, datatype, op, comm, ierror)
7      TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
8      INTEGER, INTENT(IN) :: count
9      TYPE(MPI_Datatype), INTENT(IN) :: datatype
10     TYPE(MPI_Op), INTENT(IN) :: op
11     TYPE(MPI_Comm), INTENT(IN) :: comm
12     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 13
14     MPI_Alltoall(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype,
15                  comm, ierror)
16     TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
17     INTEGER, INTENT(IN) :: sendcount, recvcount
18     TYPE(MPI_Datatype), INTENT(IN) :: sendtype
19     TYPE(MPI_Datatype), INTENT(IN) :: recvtype
20     TYPE(MPI_Comm), INTENT(IN) :: comm
21     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 22
23     MPI_Alltoallv(sendbuf, sendcounts, sdispls, sendtype, recvbuf, recvcounts,
24                  rdispls, recvtype, comm, ierror)
25     TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
26     INTEGER, INTENT(IN) :: sendcounts(*), sdispls(*), recvcounts(*),
27     rdispls(*)
28     TYPE(MPI_Datatype), INTENT(IN) :: sendtype
29     TYPE(MPI_Datatype), INTENT(IN) :: recvtype
30     TYPE(MPI_Comm), INTENT(IN) :: comm
31     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 32
33     MPI_Alltoallw(sendbuf, sendcounts, sdispls, sendtypes, recvbuf, recvcounts,
34                  rdispls, recvtypes, comm, ierror)
35     TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
36     INTEGER, INTENT(IN) :: sendcounts(*), sdispls(*), recvcounts(*),
37     rdispls(*)
38     TYPE(MPI_Datatype), INTENT(IN) :: sendtypes(*)
39     TYPE(MPI_Datatype), INTENT(IN) :: recvtypes(*)
40     TYPE(MPI_Comm), INTENT(IN) :: comm
41     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 42
43     MPI_Barrier(comm, ierror)
44     TYPE(MPI_Comm), INTENT(IN) :: comm
45     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 46
47     MPI_Bcast(buffer, count, datatype, root, comm, ierror)
48     TYPE(*), DIMENSION(..) :: buffer
49     INTEGER, INTENT(IN) :: count, root
50     TYPE(MPI_Datatype), INTENT(IN) :: datatype

```

```

TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Exscan(sendbuf, recvbuf, count, datatype, op, comm, ierror)
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
INTEGER, INTENT(IN) :: count
TYPE(MPI_Datatype), INTENT(IN) :: datatype
TYPE(MPI_Op), INTENT(IN) :: op
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Gather(sendbuf, sendcount, sendtype, recvbuf, recvcnt, recvtpe,
           root, comm, ierror)
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
INTEGER, INTENT(IN) :: sendcount, recvcnt, root
TYPE(MPI_Datatype), INTENT(IN) :: sendtype
TYPE(MPI_Datatype), INTENT(IN) :: recvtpe
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Gatherv(sendbuf, sendcount, sendtype, recvbuf, recvcnts, displs,
            recvtpe, root, comm, ierror)
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
INTEGER, INTENT(IN) :: sendcount, recvcnts(*), displs(*), root
TYPE(MPI_Datatype), INTENT(IN) :: sendtype
TYPE(MPI_Datatype), INTENT(IN) :: recvtpe
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Iallgather( -- Fortran 2008 -- to be done -- )
MPI_Iallgatherv( -- Fortran 2008 -- to be done -- )
MPI_Iallreduce( -- Fortran 2008 -- to be done -- )
MPI_Ialltoall( -- Fortran 2008 -- to be done -- )
MPI_Ialltoallv( -- Fortran 2008 -- to be done -- )
MPI_Ialltoallw( -- Fortran 2008 -- to be done -- )
MPI_Ibarrier( -- Fortran 2008 -- to be done -- )
MPI_Ibcast( -- Fortran 2008 -- to be done -- )
MPI_Iexscan( -- Fortran 2008 -- to be done -- )
MPI_Igather( -- Fortran 2008 -- to be done -- )
MPI_Igatherv( -- Fortran 2008 -- to be done -- )
MPI_Ireduce( -- Fortran 2008 -- to be done -- )
MPI_Ireduce_scatter_block( -- Fortran 2008 -- to be done -- )

```

```

1      MPI_Ireduce_scatter( -- Fortran 2008 -- to be done -- )
ticket-248T. 2
3      MPI_Iscan( -- Fortran 2008 -- to be done -- )
ticket-248T. 3
4      MPI_Iscatter( -- Fortran 2008 -- to be done -- )
ticket-248T. 4
5      MPI_Iscatterv( -- Fortran 2008 -- to be done -- )
ticket-248T. 5
6
7      MPI_Op_commutative(op, commute, ierror)
8          TYPE(MPI_Op), INTENT(IN) :: op
9          LOGICAL, INTENT(OUT) :: commute
10         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 10
11
12     MPI_Op_create(user_fn, commute, op, ierror)
13         EXTERNAL :: user_fn
14         LOGICAL, INTENT(IN) :: commute
15         TYPE(MPI_Op), INTENT(OUT) :: op
16         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 15
17
18     MPI_Op_free(op, ierror)
19         TYPE(MPI_Op), INTENT(INOUT) :: op
20         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 20
21
22     MPI_Reduce_local(inbuf, inoutbuf, count, datatype, op, ierror)
23         TYPE(*), DIMENSION(..) :: inbuf, inoutbuf
24         INTEGER, INTENT(IN) :: count
25         TYPE(MPI_Datatype), INTENT(IN) :: datatype
26         TYPE(MPI_Op), INTENT(IN) :: op
27         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 25
28
29     MPI_Reduce_scatter_block(sendbuf, recvbuf, recvcount, datatype, op, comm,
30                             ierror)
31         TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
32         INTEGER, INTENT(IN) :: recvcount
33         TYPE(MPI_Datatype), INTENT(IN) :: datatype
34         TYPE(MPI_Op), INTENT(IN) :: op
35         TYPE(MPI_Comm), INTENT(IN) :: comm
36         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 35
37
38     MPI_Reduce_scatter(sendbuf, recvbuf, recvcounts, datatype, op, comm,
39                             ierror)
40         TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
41         INTEGER, INTENT(IN) :: recvcounts(*)
42         TYPE(MPI_Datatype), INTENT(IN) :: datatype
43         TYPE(MPI_Op), INTENT(IN) :: op
44         TYPE(MPI_Comm), INTENT(IN) :: comm
45         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 43
46
47     MPI_Reduce(sendbuf, recvbuf, count, datatype, op, root, comm, ierror)
48         TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
49         INTEGER, INTENT(IN) :: count, root
50         TYPE(MPI_Datatype), INTENT(IN) :: datatype

```

```

TYPE(MPI_Op), INTENT(IN) :: op
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Scan(sendbuf, recvbuf, count, datatype, op, comm, ierror)
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
INTEGER, INTENT(IN) :: count
TYPE(MPI_Datatype), INTENT(IN) :: datatype
TYPE(MPI_Op), INTENT(IN) :: op
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Scatter(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvttype,
            root, comm, ierror)
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
INTEGER, INTENT(IN) :: sendcount, recvcount, root
TYPE(MPI_Datatype), INTENT(IN) :: sendtype
TYPE(MPI_Datatype), INTENT(IN) :: recvttype
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Scatterv(sendbuf, sendcounts, displs, sendtype, recvbuf, recvcount,
             recvttype, root, comm, ierror)
TYPE(*), DIMENSION(..) :: sendbuf, recvbuf
INTEGER, INTENT(IN) :: sendcounts(*), displs(*), recvcount, root
TYPE(MPI_Datatype), INTENT(IN) :: sendtype
TYPE(MPI_Datatype), INTENT(IN) :: recvttype
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

A.4.4 Groups, Contexts, Communicators, and Caching Fortran 2008 Bindings

MPI_Comm_compare(comm1, comm2, result, ierror)
TYPE(MPI_Comm), INTENT(IN) :: comm1
TYPE(MPI_Comm), INTENT(IN) :: comm2
INTEGER, INTENT(OUT) :: result
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Comm_create(comm, group, newcomm, ierror)
TYPE(MPI_Comm), INTENT(IN) :: comm
TYPE(MPI_Group), INTENT(IN) :: group
TYPE(MPI_Comm), INTENT(OUT) :: newcomm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Comm_create_keyval(comm_copy_attr_fn, comm_delete_attr_fn, comm_keyval,
                       extra_state, ierror)
PROCEDURE(MPI_Comm_copy_attr_function) :: comm_copy_attr_fn
PROCEDURE(MPI_Comm_delete_attr_function) :: comm_delete_attr_fn
INTEGER, INTENT(OUT) :: comm_keyval
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: extra_state

```

```

1      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 2
3      MPI_Comm_delete_attr(comm, comm_keyval, ierror)
4      TYPE(MPI_Comm), INTENT(IN) :: comm
5      INTEGER, INTENT(IN) :: comm_keyval
6      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 7
8      MPI_Comm_dup(comm, newcomm, ierror)
9      TYPE(MPI_Comm), INTENT(IN) :: comm
10     TYPE(MPI_Comm), INTENT(OUT) :: newcomm
11     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 12
13     MPI_COMM_DUP_FN(oldcomm, comm_keyval, extra_state, attribute_val_in,
14                     attribute_val_out, flag, ierror)
15     TYPE(MPI_Comm), INTENT(IN) :: oldcomm
16     INTEGER, INTENT(IN) :: comm_keyval
17     INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: extra_state,
18     attribute_val_in
19     INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: attribute_val_out
20     LOGICAL, INTENT(OUT) :: flag
21     INTEGER, INTENT(OUT) :: ierror
ticket-248T. 22
23     MPI_Comm_free(comm, ierror)
24     TYPE(MPI_Comm), INTENT(INOUT) :: comm
25     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 26
27     MPI_Comm_free_keyval(comm_keyval, ierror)
28     INTEGER, INTENT(INOUT) :: comm_keyval
29     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 30
31     MPI_Comm_get_attr(comm, comm_keyval, attribute_val, flag, ierror)
32     TYPE(MPI_Comm), INTENT(IN) :: comm
33     INTEGER, INTENT(IN) :: comm_keyval
34     INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: attribute_val
35     LOGICAL, INTENT(OUT) :: flag
36     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 37
38     MPI_Comm_get_name(comm, comm_name, resultlen, ierror)
39     TYPE(MPI_Comm), INTENT(IN) :: comm
40     CHARACTER(LEN=*), INTENT(OUT) :: comm_name
41     INTEGER, INTENT(OUT) :: resultlen
42     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 43
44     MPI_Comm_group(comm, group, ierror)
45     TYPE(MPI_Comm), INTENT(IN) :: comm
46     TYPE(MPI_Group), INTENT(OUT) :: group
47     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 48
49     MPI_COMM_NULL_COPY_FN(oldcomm, comm_keyval, extra_state, attribute_val_in,
50                           attribute_val_out, flag, ierror)
51     TYPE(MPI_Comm), INTENT(IN) :: oldcomm
52     INTEGER, INTENT(IN) :: comm_keyval

```

```

INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: extra_state,
attribute_val_in
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: attribute_val_out
LOGICAL, INTENT(OUT) :: flag
INTEGER, INTENT(OUT) :: ierror
MPI_COMM_NULL_DELETE_FN(comm, comm_keyval, attribute_val, extra_state,
ierror)
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, INTENT(IN) :: comm_keyval
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: attribute_val,
extra_state
INTEGER, INTENT(OUT) :: ierror
MPI_Comm_rank(comm, rank, ierror)
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, INTENT(OUT) :: rank
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Comm_remote_group(comm, group, ierror)
TYPE(MPI_Comm), INTENT(IN) :: comm
TYPE(MPI_Group), INTENT(OUT) :: group
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Comm_remote_size(comm, size, ierror)
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, INTENT(OUT) :: size
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Comm_set_attr(comm, comm_keyval, attribute_val, ierror)
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, INTENT(IN) :: comm_keyval
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: attribute_val
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Comm_set_name(comm, comm_name, ierror)
TYPE(MPI_Comm), INTENT(IN) :: comm
CHARACTER(LEN=*), INTENT(IN) :: comm_name
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Comm_size(comm, size, ierror)
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, INTENT(OUT) :: size
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Comm_split(comm, color, key, newcomm, ierror)
TYPE(MPI_Comm), INTENT(IN) :: comm
INTEGER, INTENT(IN) :: color, key
TYPE(MPI_Comm), INTENT(OUT) :: newcomm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Comm_test_inter(comm, flag, ierror)

```

```

1      TYPE(MPI_Comm), INTENT(IN) :: comm
2      LOGICAL, INTENT(OUT) :: flag
3      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 4
5      MPI_Group_compare(group1, group2, result, ierror)
6      TYPE(MPI_Group), INTENT(IN) :: group1, group2
7      INTEGER, INTENT(OUT) :: result
8      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 9
10     MPI_Group_difference(group1, group2, newgroup, ierror)
11     TYPE(MPI_Group), INTENT(IN) :: group1, group2
12     TYPE(MPI_Group), INTENT(OUT) :: newgroup
13     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 14
15     MPI_Group_excl(group, n, ranks, newgroup, ierror)
16     TYPE(MPI_Group), INTENT(IN) :: group
17     INTEGER, INTENT(IN) :: n, ranks(*)
18     TYPE(MPI_Group), INTENT(OUT) :: newgroup
19     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 20
21     MPI_Group_free(group, ierror)
22     TYPE(MPI_Group), INTENT(INOUT) :: group
23     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 24
25     MPI_Group_incl(group, n, ranks, newgroup, ierror)
26     INTEGER, INTENT(IN) :: n, ranks(*)
27     TYPE(MPI_Group), INTENT(IN) :: group
28     TYPE(MPI_Group), INTENT(OUT) :: newgroup
29     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 30
31     MPI_Group_intersection(group1, group2, newgroup, ierror)
32     TYPE(MPI_Group), INTENT(IN) :: group1, group2
33     TYPE(MPI_Group), INTENT(OUT) :: newgroup
34     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 35
36     MPI_Group_range_excl(group, n, ranges, newgroup, ierror)
37     TYPE(MPI_Group), INTENT(IN) :: group
38     INTEGER, INTENT(IN) :: n, ranges(3,*)
39     TYPE(MPI_Group), INTENT(OUT) :: newgroup
40     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 41
42     MPI_Group_range_incl(group, n, ranges, newgroup, ierror)
43     TYPE(MPI_Group), INTENT(IN) :: group
44     INTEGER, INTENT(IN) :: n, ranges(3,*)
45     TYPE(MPI_Group), INTENT(OUT) :: newgroup
46     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 47
48     MPI_Group_rank(group, rank, ierror)
49     TYPE(MPI_Group), INTENT(IN) :: group
50     INTEGER, INTENT(OUT) :: rank
51     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 52

```



```

MPI_Group_size(group, size, ierror)
  TYPE(MPI_Group), INTENT(IN) :: group
  INTEGER, INTENT(OUT) :: size
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Group_translate_ranks(group1, n, ranks1, group2, ranks2, ierror)
  TYPE(MPI_Group), INTENT(IN) :: group1, group2
  INTEGER, INTENT(IN) :: n, ranks1(*)
  INTEGER, INTENT(OUT) :: ranks2(*)
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Group_union(group1, group2, newgroup, ierror)
  TYPE(MPI_Group), INTENT(IN) :: group1, group2
  TYPE(MPI_Group), INTENT(OUT) :: newgroup
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Intercomm_create(local_comm, local_leader, peer_comm, remote_leader,
  tag, newintercomm, ierror)
  TYPE(MPI_Comm), INTENT(IN) :: local_comm, peer_comm
  INTEGER, INTENT(IN) :: local_leader, remote_leader, tag
  TYPE(MPI_Comm), INTENT(OUT) :: newintercomm
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Intercomm_merge(intercomm, high, newintracomm, ierror)
  TYPE(MPI_Comm), INTENT(IN) :: intercomm
  LOGICAL, INTENT(IN) :: high
  TYPE(MPI_Comm), INTENT(OUT) :: newintracomm
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Type_create_keyval(type_copy_attr_fn, type_delete_attr_fn, type_keyval,
  extra_state, ierror)
  PROCEDURE(MPI_Type_copy_attr_function) :: type_copy_attr_fn
  PROCEDURE(MPI_Type_delete_attr_function) :: type_delete_attr_fn
  INTEGER, INTENT(OUT) :: type_keyval
  INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: extra_state
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Type_delete_attr(datatype, type_keyval, ierror)
  TYPE(MPI_Datatype), INTENT(IN) :: datatype
  INTEGER, INTENT(IN) :: type_keyval
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Type_Dup_FN(oldtype, type_keyval, extra_state, attribute_val_in,
  attribute_val_out, flag, ierror)
  TYPE(MPI_Datatype), INTENT(IN) :: oldtype
  INTEGER, INTENT(IN) :: type_keyval
  INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: extra_state,
  attribute_val_in
  INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: attribute_val_out
  LOGICAL, INTENT(OUT) :: flag
  INTEGER, INTENT(OUT) :: ierror

```

```

1
ticket-248T. 2 MPI_Type_free_keyval(type_keyval, ierror)
3             INTEGER, INTENT(INOUT) :: type_keyval
4             INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 5
6 MPI_Type_get_attr(datatype, type_keyval, attribute_val, flag, ierror)
7             TYPE(MPI_Datatype), INTENT(IN) :: datatype
8             INTEGER, INTENT(IN) :: type_keyval
9             INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: attribute_val
10            LOGICAL, INTENT(OUT) :: flag
ticket-248T. 11            INTEGER, OPTIONAL, INTENT(OUT) :: ierror
12
13 MPI_Type_get_name(datatype, type_name, resultlen, ierror)
14            TYPE(MPI_Datatype), INTENT(IN) :: datatype
15            CHARACTER(LEN=*), INTENT(OUT) :: type_name
16            INTEGER, INTENT(OUT) :: resultlen
ticket-248T. 17            INTEGER, OPTIONAL, INTENT(OUT) :: ierror
18
19 MPI_TYPE_NULL_COPY_FN(oldtype, type_keyval, extra_state, attribute_val_in,
20                       attribute_val_out, flag, ierror)
21            TYPE(MPI_Datatype), INTENT(IN) :: oldtype
22            INTEGER, INTENT(IN) :: type_keyval
23            INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: extra_state,
24            attribute_val_in
25            INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: attribute_val_out
26            LOGICAL, INTENT(OUT) :: flag
ticket-248T. 27            INTEGER, INTENT(OUT) :: ierror
28
29 MPI_TYPE_NULL_DELETE_FN(datatype, type_keyval, attribute_val, extra_state,
30                          ierror)
31            TYPE(MPI_Datatype), INTENT(IN) :: datatype
32            INTEGER, INTENT(IN) :: type_keyval
33            INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: attribute_val,
34            extra_state
ticket-248T. 35            INTEGER, INTENT(OUT) :: ierror
36
37 MPI_Type_set_attr(datatype, type_keyval, attribute_val, ierror)
38            TYPE(MPI_Datatype), INTENT(IN) :: datatype
39            INTEGER, INTENT(IN) :: type_keyval
40            INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: attribute_val
ticket-248T. 41            INTEGER, OPTIONAL, INTENT(OUT) :: ierror
42
43 MPI_Type_set_name(datatype, type_name, ierror)
44            TYPE(MPI_Datatype), INTENT(IN) :: datatype
45            CHARACTER(LEN=*), INTENT(IN) :: type_name
46            INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 47
48 MPI_Win_create_keyval(win_copy_attr_fn, win_delete_attr_fn, win_keyval,
49                      extra_state, ierror)
50            PROCEDURE(MPI_Win_copy_attr_function) :: win_copy_attr_fn
51            PROCEDURE(MPI_Win_delete_attr_function) :: win_delete_attr_fn

```

```

    INTEGER, INTENT(OUT) :: win_keyval
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: extra_state
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Win_delete_attr(win, win_keyval, ierror)
    TYPE(MPI_Win), INTENT(IN) :: win
    INTEGER, INTENT(IN) :: win_keyval
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_WIN_DUP_FN(oldwin, win_keyval, extra_state, attribute_val_in,
               attribute_val_out, flag, ierror)
    INTEGER, INTENT(IN) :: oldwin, win_keyval
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: extra_state,
    attribute_val_in
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: attribute_val_out
    LOGICAL, INTENT(OUT) :: flag
    INTEGER, INTENT(OUT) :: ierror
MPI_Win_free_keyval(win_keyval, ierror)
    INTEGER, INTENT(INOUT) :: win_keyval
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Win_get_attr(win, win_keyval, attribute_val, flag, ierror)
    TYPE(MPI_Win), INTENT(IN) :: win
    INTEGER, INTENT(IN) :: win_keyval
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: attribute_val
    LOGICAL, INTENT(OUT) :: flag
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Win_get_name(win, win_name, resultlen, ierror)
    TYPE(MPI_Win), INTENT(IN) :: win
    CHARACTER(LEN=*), INTENT(OUT) :: win_name
    INTEGER, INTENT(OUT) :: resultlen
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_WIN_NULL_COPY_FN(oldwin, win_keyval, extra_state, attribute_val_in,
                    attribute_val_out, flag, ierror)
    INTEGER, INTENT(IN) :: oldwin, win_keyval
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: extra_state,
    attribute_val_in
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: attribute_val_out
    LOGICAL, INTENT(OUT) :: flag
    INTEGER, INTENT(OUT) :: ierror
MPI_WIN_NULL_DELETE_FN(win, win_keyval, attribute_val, extra_state, ierror)
    TYPE(MPI_Win), INTENT(IN) :: win
    INTEGER, INTENT(IN) :: win_keyval
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: attribute_val,
    extra_state
    INTEGER, INTENT(OUT) :: ierror

```

```

1  MPI_Win_set_attr(win, win_keyval, attribute_val, ierror)
2      TYPE(MPI_Win), INTENT(IN) :: win
3      INTEGER, INTENT(IN) :: win_keyval
4      INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: attribute_val
5      INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

6  MPI_Win_set_name(win, win_name, ierror)
7      TYPE(MPI_Win), INTENT(IN) :: win
8      CHARACTER(LEN=*), INTENT(IN) :: win_name
9      INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

#### A.4.5 Process Topologies Fortran 2008 Bindings

```

14 MPI_Cart_coords(comm, rank, maxdims, coords, ierror)
15     TYPE(MPI_Comm), INTENT(IN) :: comm
16     INTEGER, INTENT(IN) :: rank, maxdims
17     INTEGER, INTENT(OUT) :: coords(*)
18     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

19 MPI_Cart_create(comm_old, ndims, dims, periods, reorder, comm_cart, ierror)
20     TYPE(MPI_Comm), INTENT(IN) :: comm_old
21     INTEGER, INTENT(IN) :: ndims, dims(*)
22     LOGICAL, INTENT(IN) :: periods(*), reorder
23     TYPE(MPI_Comm), INTENT(OUT) :: comm_cart
24     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

26 MPI_Cartdim_get(comm, ndims, ierror)
27     TYPE(MPI_Comm), INTENT(IN) :: comm
28     INTEGER, INTENT(OUT) :: ndims
29     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

30 MPI_Cart_get(comm, maxdims, dims, periods, coords, ierror)
31     TYPE(MPI_Comm), INTENT(IN) :: comm
32     INTEGER, INTENT(IN) :: maxdims
33     INTEGER, INTENT(OUT) :: dims(*), coords(*)
34     LOGICAL, INTENT(OUT) :: periods(*)
35     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

37 MPI_Cart_map(comm, ndims, dims, periods, newrank, ierror)
38     TYPE(MPI_Comm), INTENT(IN) :: comm
39     INTEGER, INTENT(IN) :: ndims, dims(*)
40     LOGICAL, INTENT(IN) :: periods(*)
41     INTEGER, INTENT(OUT) :: newrank
42     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

44 MPI_Cart_rank(comm, coords, rank, ierror)
45     TYPE(MPI_Comm), INTENT(IN) :: comm
46     INTEGER, INTENT(IN) :: coords(*)
47     INTEGER, INTENT(OUT) :: rank
48     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

MPI_Cart_shift(comm, direction, disp, rank_source, rank_dest, ierror)
  TYPE(MPI_Comm), INTENT(IN) :: comm
  INTEGER, INTENT(IN) :: direction, disp
  INTEGER, INTENT(OUT) :: rank_source, rank_dest
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Cart_sub(comm, remain_dims, newcomm, ierror)
  TYPE(MPI_Comm), INTENT(IN) :: comm
  LOGICAL, INTENT(IN) :: remain_dims(*)
  TYPE(MPI_Comm), INTENT(OUT) :: newcomm
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Dims_create(nnodes, ndims, dims, ierror)
  INTEGER, INTENT(IN) :: nnodes, ndims
  INTEGER, INTENT(INOUT) :: dims(*)
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Dist_graph_create_adjacent(comm_old, indegree, sources, sourceweights,
  outdegree, destinations, destweights, info, reorder,
  comm_dist_graph, ierror)
  TYPE(MPI_Comm), INTENT(IN) :: comm_old
  INTEGER, INTENT(IN) :: indegree, sources(*), outdegree,
  destinations(*)
  INTEGER, INTENT(IN) :: sourceweights(*) ! optional by overloading
  INTEGER, INTENT(IN) :: destweights(*) ! optional by overloading
  TYPE(MPI_Info), INTENT(IN) :: info
  LOGICAL, INTENT(IN) :: reorder
  TYPE(MPI_Comm), INTENT(OUT) :: comm_dist_graph
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Dist_graph_create(comm_old, n, sources, degrees, destinations, weights,
  info, reorder, comm_dist_graph, ierror)
  TYPE(MPI_Comm), INTENT(IN) :: comm_old
  INTEGER, INTENT(IN) :: n, sources(*), degrees(*), destinations(*)
  INTEGER, INTENT(IN) :: weights(*) ! optional by overloading
  TYPE(MPI_Info), INTENT(IN) :: info
  LOGICAL, INTENT(IN) :: reorder
  TYPE(MPI_Comm), INTENT(OUT) :: comm_dist_graph
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Dist_graph_neighbors(comm, maxindegree, sources, sourceweights,
  maxoutdegree, destinations, destweights, ierror)
  TYPE(MPI_Comm), INTENT(IN) :: comm
  INTEGER, INTENT(IN) :: maxindegree, maxoutdegree
  INTEGER, INTENT(OUT) :: sources(*), destinations(*)
  INTEGER, INTENT(OUT) :: sourceweights(*), destweights(*) ! optional
  by overloading
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Dist_graph_neighbors_count(comm, indegree, outdegree, weighted, ierror)

```

```

1      TYPE(MPI_Comm), INTENT(IN) :: comm
2      INTEGER, INTENT(OUT) :: indegree, outdegree
3      LOGICAL, INTENT(OUT) :: weighted
4      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 5
6      MPI_Graph_create(comm_old, nnodes, index, edges, reorder, comm_graph,
7                  ierror)
8      TYPE(MPI_Comm), INTENT(IN) :: comm_old
9      INTEGER, INTENT(IN) :: nnodes, index(*), edges(*)
10     LOGICAL, INTENT(IN) :: reorder
11     TYPE(MPI_Comm), INTENT(OUT) :: comm_graph
12     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 13
14     MPI_Graphdims_get(comm, nnodes, nedges, ierror)
15     TYPE(MPI_Comm), INTENT(IN) :: comm
16     INTEGER, INTENT(OUT) :: nnodes, nedges
17     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 18
19     MPI_Graph_get(comm, maxindex, maxedges, index, edges, ierror)
20     TYPE(MPI_Comm), INTENT(IN) :: comm
21     INTEGER, INTENT(IN) :: maxindex, maxedges
22     INTEGER, INTENT(OUT) :: index(*), edges(*)
23     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 24
25     MPI_Graph_map(comm, nnodes, index, edges, newrank, ierror)
26     TYPE(MPI_Comm), INTENT(IN) :: comm
27     INTEGER, INTENT(IN) :: nnodes, index(*), edges(*)
28     INTEGER, INTENT(OUT) :: newrank
29     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 30
31     MPI_Graph_neighbors(comm, rank, maxneighbors, neighbors, ierror)
32     TYPE(MPI_Comm), INTENT(IN) :: comm
33     INTEGER, INTENT(IN) :: rank, maxneighbors
34     INTEGER, INTENT(OUT) :: neighbors(*)
35     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 36
37     MPI_Graph_neighbors_count(comm, rank, nneighbors, ierror)
38     TYPE(MPI_Comm), INTENT(IN) :: comm
39     INTEGER, INTENT(IN) :: rank
40     INTEGER, INTENT(OUT) :: nneighbors
41     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 42
43     MPI_Topo_test(comm, status, ierror)
44     TYPE(MPI_Comm), INTENT(IN) :: comm
45     INTEGER, INTENT(OUT) :: status
46     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
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```

#### A.4.6 MPI Environmental Management Fortran 2008 Bindings

```
DOUBLE PRECISION MPI_Wtick()
```

```

DOUBLE PRECISION MPI_Wtime()
MPI_Abort(comm, errorcode, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm
    INTEGER, INTENT(IN) :: errorcode
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Add_error_class(errorclass, ierror)
    INTEGER, INTENT(OUT) :: errorclass
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Add_error_code(errorclass, errorcode, ierror)
    INTEGER, INTENT(IN) :: errorclass
    INTEGER, INTENT(OUT) :: errorcode
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Add_error_string(errorcode, string, ierror)
    INTEGER, INTENT(IN) :: errorcode
    CHARACTER(LEN=*), INTENT(IN) :: string
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Alloc_mem(size, info, baseptr, ierror)
    USE, INTRINSIC :: ISO_C_BINDING
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: size
    TYPE(MPI_Info), INTENT(IN) :: info
    TYPE(C_PTR), INTENT(OUT) :: baseptr !overloaded with following...
    INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: baseptr ! ...type
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Comm_call_errhandler(comm, errorcode, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm
    INTEGER, INTENT(IN) :: errorcode
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Comm_create_errhandler(comm_errhandler_fn, errhandler, ierror)
    PROCEDURE(MPI_Comm_errhandler_function) :: comm_errhandler_fn
    TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Comm_get_errhandler(comm, errhandler, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm
    TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Comm_set_errhandler(comm, errhandler, ierror)
    TYPE(MPI_Comm), INTENT(IN) :: comm
    TYPE(MPI_Errhandler), INTENT(IN) :: errhandler
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Errhandler_free(errhandler, ierror)
    TYPE(MPI_Errhandler), INTENT(INOUT) :: errhandler
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

1  MPI_Error_class(errorcode, errorclass, ierror)
2      INTEGER, INTENT(IN) :: errorcode
3      INTEGER, INTENT(OUT) :: errorclass
4      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T.
5  MPI_Error_string(errorcode, string, resultlen, ierror)
6      INTEGER, INTENT(IN) :: errorcode
7      CHARACTER(LEN=*), INTENT(OUT) :: string
8      INTEGER, INTENT(OUT) :: resultlen
9      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T.
10 MPI_File_call_errhandler(fh, errorcode, ierror)
11     TYPE(MPI_File), INTENT(IN) :: fh
12     INTEGER, INTENT(IN) :: errorcode
13     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T.
14 MPI_File_create_errhandler(file_errhandler_fn, errhandler, ierror)
15     PROCEDURE(MPI_File_errhandler_function) :: file_errhandler_fn
16     TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
17     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T.
18 MPI_File_get_errhandler(file, errhandler, ierror)
19     TYPE(MPI_File), INTENT(IN) :: file
20     TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
21     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T.
22 MPI_File_set_errhandler(file, errhandler, ierror)
23     TYPE(MPI_File), INTENT(IN) :: file
24     TYPE(MPI_Errhandler), INTENT(IN) :: errhandler
25     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T.
26 MPI_Finalized(flag, ierror)
27     LOGICAL, INTENT(OUT) :: flag
28     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T.
29 MPI_Finalize(ierror)
30     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T.
31 MPI_Free_mem(base, ierror)
32     TYPE(*), DIMENSION(..) :: base
33     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T.
34 MPI_Get_processor_name( name, resultlen, ierror)
35     CHARACTER(LEN=*), INTENT(OUT) :: name
36     INTEGER, INTENT(OUT) :: resultlen
37     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T.
38 MPI_Get_version(version, subversion, ierror)
39     INTEGER, INTENT(OUT) :: version, subversion
40     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T.
41 MPI_Initialized(flag, ierror)
42     LOGICAL, INTENT(OUT) :: flag

```



```

    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Init(ierror)
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Win_call_errhandler(win, errorcode, ierror)
    TYPE(MPI_Win), INTENT(IN) :: win
    INTEGER, INTENT(IN) :: errorcode
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Win_create_errhandler(win_errhandler_fn, errhandler, ierror)
    PROCEDURE(MPI_Win_errhandler_function) :: win_errhandler_fn
    TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Win_get_errhandler(win, errhandler, ierror)
    TYPE(MPI_Win), INTENT(IN) :: win
    TYPE(MPI_Errhandler), INTENT(OUT) :: errhandler
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Win_set_errhandler(win, errhandler, ierror)
    TYPE(MPI_Win), INTENT(IN) :: win
    TYPE(MPI_Errhandler), INTENT(IN) :: errhandler
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

#### A.4.7 The Info Object Fortran 2008 Bindings

```

MPI_Info_create(info, ierror)
    TYPE(MPI_Info), INTENT(OUT) :: info
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Info_delete(info, key, ierror)
    TYPE(MPI_Info), INTENT(IN) :: info
    CHARACTER(LEN=*), INTENT(IN) :: key
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Info_dup(info, newinfo, ierror)
    TYPE(MPI_Info), INTENT(IN) :: info
    TYPE(MPI_Info), INTENT(OUT) :: newinfo
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Info_free(info, ierror)
    TYPE(MPI_Info), INTENT(INOUT) :: info
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Info_get(info, key, valuelen, value, flag, ierror)
    TYPE(MPI_Info), INTENT(IN) :: info
    CHARACTER(LEN=*), INTENT(IN) :: key
    INTEGER, INTENT(IN) :: valuelen
    CHARACTER(LEN=*), INTENT(OUT) :: value
    LOGICAL, INTENT(OUT) :: flag
    INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

1
ticket-248T. 2 MPI_Info_get_nkeys(info, nkeys, ierror)
3 TYPE(MPI_Info), INTENT(IN) :: info
4 INTEGER, INTENT(OUT) :: nkeys
5 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 6
7 MPI_Info_get_nthkey(info, n, key, ierror)
8 TYPE(MPI_Info), INTENT(IN) :: info
9 INTEGER, INTENT(IN) :: n
10 CHARACTER(LEN=*), INTENT(OUT) :: key
11 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 12
13 MPI_Info_get_valuelen(info, key, valuelen, flag, ierror)
14 TYPE(MPI_Info), INTENT(IN) :: info
15 CHARACTER(LEN=*), INTENT(IN) :: key
16 INTEGER, INTENT(OUT) :: valuelen
17 LOGICAL, INTENT(OUT) :: flag
18 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 19
20 MPI_Info_set(info, key, value, ierror)
21 TYPE(MPI_Info), INTENT(IN) :: info
22 CHARACTER(LEN=*), INTENT(IN) :: key, value
23 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
24
25 A.4.8 Process Creation and Management Fortran 2008 Bindings
ticket-248T. 26
27 MPI_Close_port(port_name, ierror)
28 CHARACTER(LEN=*), INTENT(IN) :: port_name
29 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 30
31 MPI_Comm_accept(port_name, info, root, comm, newcomm, ierror)
32 CHARACTER(LEN=*), INTENT(IN) :: port_name
33 TYPE(MPI_Info), INTENT(IN) :: info
34 INTEGER, INTENT(IN) :: root
35 TYPE(MPI_Comm), INTENT(IN) :: comm
36 TYPE(MPI_Comm), INTENT(OUT) :: newcomm
37 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 38
39 MPI_Comm_connect(port_name, info, root, comm, newcomm, ierror)
40 CHARACTER(LEN=*), INTENT(IN) :: port_name
41 TYPE(MPI_Info), INTENT(IN) :: info
42 INTEGER, INTENT(IN) :: root
43 TYPE(MPI_Comm), INTENT(IN) :: comm
44 TYPE(MPI_Comm), INTENT(OUT) :: newcomm
45 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 46
47 MPI_Comm_disconnect(comm, ierror)
48 TYPE(MPI_Comm), INTENT(INOUT) :: comm
49 INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 50
51 MPI_Comm_get_parent(parent, ierror)

```

```

TYPE(MPI_Comm), INTENT(OUT) :: parent
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Comm_join(fd, intercomm, ierror)
INTEGER, INTENT(IN) :: fd
TYPE(MPI_Comm), INTENT(OUT) :: intercomm
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Comm_spawn(command, argv, maxprocs, info, root, comm, intercomm,
               array_of_errcodes, ierror)
CHARACTER(LEN=*), INTENT(IN) :: command, argv(*)
INTEGER, INTENT(IN) :: maxprocs, root
TYPE(MPI_Info), INTENT(IN) :: info
TYPE(MPI_Comm), INTENT(IN) :: comm
TYPE(MPI_Comm), INTENT(OUT) :: intercomm
INTEGER, INTENT(OUT) :: array_of_errcodes(*) ! optional by
overloading
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Comm_spawn_multiple(count, array_of_commands, array_of_argv,
                       array_of_maxprocs, array_of_info, root, comm, intercomm,
                       array_of_errcodes, ierror)
INTEGER, INTENT(IN) :: count, array_of_maxprocs(*), root
CHARACTER(LEN=*), INTENT(IN) :: array_of_commands(*),
array_of_argv(count, *)
TYPE(MPI_Info), INTENT(IN) :: array_of_info(*)
TYPE(MPI_Comm), INTENT(IN) :: comm
TYPE(MPI_Comm), INTENT(OUT) :: intercomm
INTEGER, INTENT(OUT) :: array_of_errcodes(*) ! optional by
overloading
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Lookup_name(service_name, info, port_name, ierror)
CHARACTER(LEN=*), INTENT(IN) :: service_name
TYPE(MPI_Info), INTENT(IN) :: info
CHARACTER(LEN=*), INTENT(OUT) :: port_name
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Open_port(info, port_name, ierror)
TYPE(MPI_Info), INTENT(IN) :: info
CHARACTER(LEN=*), INTENT(OUT) :: port_name
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Publish_name(service_name, info, port_name, ierror)
TYPE(MPI_Info), INTENT(IN) :: info
CHARACTER(LEN=*), INTENT(IN) :: service_name, port_name
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Unpublish_name(service_name, info, port_name, ierror)
CHARACTER(LEN=*), INTENT(IN) :: service_name, port_name
TYPE(MPI_Info), INTENT(IN) :: info

```

```
1      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

#### ticket-248T. 4 A.4.9 One-Sided Communications Fortran 2008 Bindings

```
5      MPI_Accumulate(origin_addr, origin_count, origin_datatype, target_rank,
6                    target_disp, target_count, target_datatype, op, win, ierror)
7      TYPE(*), DIMENSION(..) :: origin_addr
8      INTEGER, INTENT(IN) :: origin_count, target_rank, target_count
9      TYPE(MPI_Datatype), INTENT(IN) :: origin_datatype
10     INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: target_disp
11     TYPE(MPI_Datatype), INTENT(IN) :: target_datatype
12     TYPE(MPI_Op), INTENT(IN) :: op
13     TYPE(MPI_Win), INTENT(IN) :: win
14     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
15     MPI_Get(origin_addr, origin_count, origin_datatype, target_rank,
16            target_disp, target_count, target_datatype, win, ierror)
17     TYPE(*), DIMENSION(..) :: origin_addr
18     INTEGER, INTENT(IN) :: origin_count, target_rank, target_count
19     TYPE(MPI_Datatype), INTENT(IN) :: origin_datatype
20     INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: target_disp
21     TYPE(MPI_Datatype), INTENT(IN) :: target_datatype
22     TYPE(MPI_Win), INTENT(IN) :: win
23     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
24     MPI_Put(origin_addr, origin_count, origin_datatype, target_rank,
25            target_disp, target_count, target_datatype, win, ierror)
26     TYPE(*), DIMENSION(..) :: origin_addr
27     INTEGER, INTENT(IN) :: origin_count, target_rank, target_count
28     TYPE(MPI_Datatype), INTENT(IN) :: origin_datatype
29     INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: target_disp
30     TYPE(MPI_Datatype), INTENT(IN) :: target_datatype
31     TYPE(MPI_Win), INTENT(IN) :: win
32     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
33     MPI_Win_complete(win, ierror)
34     TYPE(MPI_Win), INTENT(IN) :: win
35     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
36     MPI_Win_create(base, size, disp_unit, info, comm, win, ierror)
37     TYPE(*), DIMENSION(..) :: base
38     INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: size
39     INTEGER, INTENT(IN) :: disp_unit
40     TYPE(MPI_Info), INTENT(IN) :: info
41     TYPE(MPI_Comm), INTENT(IN) :: comm
42     TYPE(MPI_Win), INTENT(OUT) :: win
43     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
```

```
44     MPI_Win_fence(assert, win, ierror)
45     INTEGER, INTENT(IN) :: assert
```

```

TYPE(MPI_Win), INTENT(IN) :: win
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Win_free(win, ierror)
TYPE(MPI_Win), INTENT(INOUT) :: win
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Win_get_group(win, group, ierror)
TYPE(MPI_Win), INTENT(IN) :: win
TYPE(MPI_Group), INTENT(OUT) :: group
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Win_lock(lock_type, rank, assert, win, ierror)
INTEGER, INTENT(IN) :: lock_type, rank, assert
TYPE(MPI_Win), INTENT(IN) :: win
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Win_post(group, assert, win, ierror)
TYPE(MPI_Group), INTENT(IN) :: group
INTEGER, INTENT(IN) :: assert
TYPE(MPI_Win), INTENT(IN) :: win
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Win_start(group, assert, win, ierror)
TYPE(MPI_Group), INTENT(IN) :: group
INTEGER, INTENT(IN) :: assert
TYPE(MPI_Win), INTENT(IN) :: win
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Win_test(win, flag, ierror)
LOGICAL, INTENT(OUT) :: flag
TYPE(MPI_Win), INTENT(IN) :: win
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Win_unlock(rank, win, ierror)
INTEGER, INTENT(IN) :: rank
TYPE(MPI_Win), INTENT(IN) :: win
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Win_wait(win, ierror)
TYPE(MPI_Win), INTENT(IN) :: win
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

A.4.10 External Interfaces Fortran 2008 Bindings
MPI_Grequest_complete(request, ierror)
TYPE(MPI_Request), INTENT(IN) :: request
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_Grequest_start(query_fn, free_fn, cancel_fn, extra_state, request,
ierror)
PROCEDURE(MPI_Grequest_query_function) :: query_fn

```

```

1      PROCEDURE(MPI_Grequest_free_function) :: free_fn
2      PROCEDURE(MPI_Grequest_cancel_function) :: cancel_fn
3      INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: extra_state
4      TYPE(MPI_Request), INTENT(OUT) :: request
5      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 6
7      MPI_Init_thread(required, provided, ierror)
8          INTEGER, INTENT(IN) :: required
9          INTEGER, INTENT(OUT) :: provided
10         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 11
12     MPI_Is_thread_main(flag, ierror)
13         LOGICAL, INTENT(OUT) :: flag
14         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 15
16     MPI_Query_thread(provided, ierror)
17         INTEGER, INTENT(OUT) :: provided
18         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 19
20     MPI_Status_set_cancelled(status, flag, ierror)
21         TYPE(MPI_Status), INTENT(INOUT) :: status
22         LOGICAL, INTENT(OUT) :: flag
23         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 24
25     MPI_Status_set_elements(status, datatype, count, ierror)
26         TYPE(MPI_Status), INTENT(INOUT) :: status
27         TYPE(MPI_Datatype), INTENT(IN) :: datatype
28         INTEGER, INTENT(IN) :: count
29         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
30
31     A.4.11 I/O Fortran 2008 Bindings
ticket-248T. 32
33     MPI_File_close(fh, ierror)
34         TYPE(MPI_File), INTENT(INOUT) :: fh
35         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 36
37     MPI_File_delete(filename, info, ierror)
38         CHARACTER(LEN=*), INTENT(IN) :: filename
39         TYPE(MPI_Info), INTENT(IN) :: info
40         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 41
42     MPI_File_get_amode(fh, amode, ierror)
43         TYPE(MPI_File), INTENT(IN) :: fh
44         INTEGER, INTENT(OUT) :: amode
45         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 46
47     MPI_File_get_atomicity(fh, flag, ierror)
48         TYPE(MPI_File), INTENT(IN) :: fh
49         LOGICAL, INTENT(OUT) :: flag
50         INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 51
52     MPI_File_get_byte_offset(fh, offset, disp, ierror)

```

```

TYPE(MPI_File), INTENT(IN) :: fh
INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
INTEGER(KIND=MPI_OFFSET_KIND), INTENT(OUT) :: disp
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_get_group(fh, group, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
TYPE(MPI_Group), INTENT(OUT) :: group
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_get_info(fh, info_used, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
TYPE(MPI_Info), INTENT(OUT) :: info_used
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_get_position(fh, offset, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
INTEGER(KIND=MPI_OFFSET_KIND), INTENT(OUT) :: offset
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_get_position_shared(fh, offset, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
INTEGER(KIND=MPI_OFFSET_KIND), INTENT(OUT) :: offset
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_get_size(fh, size, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
INTEGER(KIND=MPI_OFFSET_KIND), INTENT(OUT) :: size
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_get_type_extent(fh, datatype, extent, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
TYPE(MPI_Datatype), INTENT(IN) :: datatype
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(OUT) :: extent
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_get_view(fh, disp, etype, filetype, datarep, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
INTEGER(KIND=MPI_OFFSET_KIND), INTENT(OUT) :: disp
TYPE(MPI_Datatype), INTENT(OUT) :: etype
TYPE(MPI_Datatype), INTENT(OUT) :: filetype
CHARACTER(LEN=*), INTENT(OUT) :: datarep
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_iread_at(fh, offset, buf, count, datatype, request, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
TYPE(*), DIMENSION(..) :: buf
INTEGER, INTENT(IN) :: count
TYPE(MPI_Datatype), INTENT(IN) :: datatype
TYPE(MPI_Request), INTENT(OUT) :: request

```

```

1      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 2
3      MPI_File_iread(fh, buf, count, datatype, request, ierror)
4      TYPE(MPI_File), INTENT(IN) :: fh
5      TYPE(*), DIMENSION(..) :: buf
6      INTEGER, INTENT(IN) :: count
7      TYPE(MPI_Datatype), INTENT(IN) :: datatype
8      TYPE(MPI_Request), INTENT(OUT) :: request
9      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 10
11     MPI_File_iread_shared(fh, buf, count, datatype, request, ierror)
12     TYPE(MPI_File), INTENT(IN) :: fh
13     TYPE(*), DIMENSION(..) :: buf
14     INTEGER, INTENT(IN) :: count
15     TYPE(MPI_Datatype), INTENT(IN) :: datatype
16     TYPE(MPI_Request), INTENT(OUT) :: request
17     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 18
19     MPI_File_ fwrite_at(fh, offset, buf, count, datatype, request, ierror)
20     TYPE(MPI_File), INTENT(IN) :: fh
21     INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
22     TYPE(*), DIMENSION(..) :: buf
23     INTEGER, INTENT(IN) :: count
24     TYPE(MPI_Datatype), INTENT(IN) :: datatype
25     TYPE(MPI_Request), INTENT(OUT) :: request
26     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 27
28     MPI_File_ fwrite(fh, buf, count, datatype, request, ierror)
29     TYPE(MPI_File), INTENT(IN) :: fh
30     TYPE(*), DIMENSION(..) :: buf
31     INTEGER, INTENT(IN) :: count
32     TYPE(MPI_Datatype), INTENT(IN) :: datatype
33     TYPE(MPI_Request), INTENT(OUT) :: request
34     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 35
36     MPI_File_ fwrite_shared(fh, buf, count, datatype, request, ierror)
37     TYPE(*), DIMENSION(..) :: buf
38     TYPE(MPI_File), INTENT(IN) :: fh
39     INTEGER, INTENT(IN) :: count
40     TYPE(MPI_Datatype), INTENT(IN) :: datatype
41     TYPE(MPI_Request), INTENT(OUT) :: request
42     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 43
44     MPI_File_ fopen(comm, filename, amode, info, fh, ierror)
45     TYPE(MPI_Comm), INTENT(IN) :: comm
46     CHARACTER(LEN=*), INTENT(IN) :: filename
47     INTEGER, INTENT(IN) :: amode
48     TYPE(MPI_Info), INTENT(IN) :: info
49     TYPE(MPI_File), INTENT(OUT) :: fh
50     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```



```

MPI_File_preallocate(fh, size, ierror)
  TYPE(MPI_File), INTENT(IN) :: fh
  INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: size
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_read_all_begin(fh, buf, count, datatype, ierror)
  TYPE(MPI_File), INTENT(IN) :: fh
  TYPE(*), DIMENSION(..) :: buf
  INTEGER, INTENT(IN) :: count
  TYPE(MPI_Datatype), INTENT(IN) :: datatype
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_read_all_end(fh, buf, status, ierror)
  TYPE(MPI_File), INTENT(IN) :: fh
  TYPE(*), DIMENSION(..) :: buf
  TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_read_all(fh, buf, count, datatype, status, ierror)
  TYPE(MPI_File), INTENT(IN) :: fh
  TYPE(*), DIMENSION(..) :: buf
  INTEGER, INTENT(IN) :: count
  TYPE(MPI_Datatype), INTENT(IN) :: datatype
  TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_read_at_all_begin(fh, offset, buf, count, datatype, ierror)
  TYPE(MPI_File), INTENT(IN) :: fh
  INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
  TYPE(*), DIMENSION(..) :: buf
  INTEGER, INTENT(IN) :: count
  TYPE(MPI_Datatype), INTENT(IN) :: datatype
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_read_at_all_end(fh, buf, status, ierror)
  TYPE(MPI_File), INTENT(IN) :: fh
  TYPE(*), DIMENSION(..) :: buf
  TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_read_at_all(fh, offset, buf, count, datatype, status, ierror)
  TYPE(MPI_File), INTENT(IN) :: fh
  INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
  TYPE(*), DIMENSION(..) :: buf
  INTEGER, INTENT(IN) :: count
  TYPE(MPI_Datatype), INTENT(IN) :: datatype
  TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
  INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_read_at(fh, offset, buf, count, datatype, status, ierror)
  TYPE(MPI_File), INTENT(IN) :: fh

```

```

1      INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
2      TYPE(*), DIMENSION(..) :: buf
3      INTEGER, INTENT(IN) :: count
4      TYPE(MPI_Datatype), INTENT(IN) :: datatype
5      TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
6      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 7
8      MPI_File_read(fh, buf, count, datatype, status, ierror)
9      TYPE(MPI_File), INTENT(IN) :: fh
10     TYPE(*), DIMENSION(..) :: buf
11     INTEGER, INTENT(IN) :: count
12     TYPE(MPI_Datatype), INTENT(IN) :: datatype
13     TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
14     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 15
16     MPI_File_read_ordered_begin(fh, buf, count, datatype, ierror)
17     TYPE(MPI_File), INTENT(IN) :: fh
18     TYPE(*), DIMENSION(..) :: buf
19     INTEGER, INTENT(IN) :: count
20     TYPE(MPI_Datatype), INTENT(IN) :: datatype
21     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 22
23     MPI_File_read_ordered_end(fh, buf, status, ierror)
24     TYPE(MPI_File), INTENT(IN) :: fh
25     TYPE(*), DIMENSION(..) :: buf
26     TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
27     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 28
29     MPI_File_read_ordered(fh, buf, count, datatype, status, ierror)
30     TYPE(MPI_File), INTENT(IN) :: fh
31     TYPE(*), DIMENSION(..) :: buf
32     INTEGER, INTENT(IN) :: count
33     TYPE(MPI_Datatype), INTENT(IN) :: datatype
34     TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
35     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 36
37     MPI_File_read_shared(fh, buf, count, datatype, status, ierror)
38     TYPE(MPI_File), INTENT(IN) :: fh
39     TYPE(*), DIMENSION(..) :: buf
40     INTEGER, INTENT(IN) :: count
41     TYPE(MPI_Datatype), INTENT(IN) :: datatype
42     TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
43     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 44
45     MPI_File_seek(fh, offset, whence, ierror)
46     TYPE(MPI_File), INTENT(IN) :: fh
47     INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
48     INTEGER, INTENT(IN) :: whence
49     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
50
51     MPI_File_seek_shared(fh, offset, whence, ierror)

```

```

TYPE(MPI_File), INTENT(IN) :: fh
INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
INTEGER, INTENT(IN) :: whence
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_File_set_atomicity(fh, flag, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
LOGICAL, INTENT(IN) :: flag
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_File_set_info(fh, info, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
TYPE(MPI_Info), INTENT(IN) :: info
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_File_set_size(fh, size, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: size
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_File_set_view(fh, disp, etype, filetype, datarep, info, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: disp
TYPE(MPI_Datatype), INTENT(IN) :: etype
TYPE(MPI_Datatype), INTENT(IN) :: filetype
CHARACTER(LEN=*), INTENT(IN) :: datarep
TYPE(MPI_Info), INTENT(IN) :: info
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_File_sync(fh, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_File_write_all_begin(fh, buf, count, datatype, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
TYPE(*), DIMENSION(..) :: buf
INTEGER, INTENT(IN) :: count
TYPE(MPI_Datatype), INTENT(IN) :: datatype
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_File_write_all_end(fh, buf, status, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
TYPE(*), DIMENSION(..) :: buf
TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
INTEGER, OPTIONAL, INTENT(OUT) :: ierror
MPI_File_write_all(fh, buf, count, datatype, status, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
TYPE(*), DIMENSION(..) :: buf
INTEGER, INTENT(IN) :: count
TYPE(MPI_Datatype), INTENT(IN) :: datatype

```

```

1      TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
2      INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 3
4      MPI_File_write_at_all_begin(fh, offset, buf, count, datatype, ierror)
5      TYPE(MPI_File), INTENT(IN) :: fh
6      INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
7      TYPE(*), DIMENSION(..) :: buf
8      INTEGER, INTENT(IN) :: count
9      TYPE(MPI_Datatype), INTENT(IN) :: datatype
10     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 11
12     MPI_File_write_at_all_end(fh, buf, status, ierror)
13     TYPE(MPI_File), INTENT(IN) :: fh
14     TYPE(*), DIMENSION(..) :: buf
15     TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
16     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 17
18     MPI_File_write_at_all(fh, offset, buf, count, datatype, status, ierror)
19     TYPE(MPI_File), INTENT(IN) :: fh
20     INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
21     TYPE(*), DIMENSION(..) :: buf
22     INTEGER, INTENT(IN) :: count
23     TYPE(MPI_Datatype), INTENT(IN) :: datatype
24     TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
25     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 26
27     MPI_File_write_at(fh, offset, buf, count, datatype, status, ierror)
28     TYPE(MPI_File), INTENT(IN) :: fh
29     INTEGER(KIND=MPI_OFFSET_KIND), INTENT(IN) :: offset
30     TYPE(*), DIMENSION(..) :: buf
31     INTEGER, INTENT(IN) :: count
32     TYPE(MPI_Datatype), INTENT(IN) :: datatype
33     TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
34     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 35
36     MPI_File_write(fh, buf, count, datatype, status, ierror)
37     TYPE(MPI_File), INTENT(IN) :: fh
38     TYPE(*), DIMENSION(..) :: buf
39     INTEGER, INTENT(IN) :: count
40     TYPE(MPI_Datatype), INTENT(IN) :: datatype
41     TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
42     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
ticket-248T. 43
44     MPI_File_write_ordered_begin(fh, buf, count, datatype, ierror)
45     TYPE(MPI_File), INTENT(IN) :: fh
46     TYPE(*), DIMENSION(..) :: buf
47     INTEGER, INTENT(IN) :: count
48     TYPE(MPI_Datatype), INTENT(IN) :: datatype
49     INTEGER, OPTIONAL, INTENT(OUT) :: ierror
50     MPI_File_write_ordered_end(fh, buf, status, ierror)

```

```

TYPE(MPI_File), INTENT(IN) :: fh
TYPE(*), DIMENSION(..) :: buf
TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_write_ordered(fh, buf, count, datatype, status, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
TYPE(*), DIMENSION(..) :: buf
INTEGER, INTENT(IN) :: count
TYPE(MPI_Datatype), INTENT(IN) :: datatype
TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_File_write_shared(fh, buf, count, datatype, status, ierror)
TYPE(MPI_File), INTENT(IN) :: fh
TYPE(*), DIMENSION(..) :: buf
INTEGER, INTENT(IN) :: count
TYPE(MPI_Datatype), INTENT(IN) :: datatype
TYPE(MPI_Status), INTENT(OUT) :: status ! optional by overloading
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Register_datarep(datarep, read_conversion_fn, write_conversion_fn,
    dtype_file_extent_fn, extra_state, ierror)
CHARACTER(LEN=*), INTENT(IN) :: datarep
EXTERNAL :: read_conversion_fn, write_conversion_fn
PROCEDURE(MPI_Datarep_extent_function) :: dtype_file_extent_fn
INTEGER(KIND=MPI_ADDRESS_KIND), INTENT(IN) :: extra_state
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

#### A.4.12 Language Bindings Fortran 2008 Bindings

```

MPI_F_sync_reg(buf)
TYPE(*), DIMENSION(..) :: buf

MPI_Sizeof(x, size, ierror)
TYPE(*) :: x
INTEGER, INTENT(OUT) :: size
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Status_f082f(f08_status, f_status, ierror)
TYPE(MPI_Status), INTENT(IN) :: f08_status
INTEGER, INTENT(OUT) :: f_status(MPI_STATUS_SIZE)
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Status_f2f08(f_status, f08_status, ierror)
INTEGER, INTENT(IN) :: f_status(MPI_STATUS_SIZE)
TYPE(MPI_Status), INTENT(OUT) :: f08_status
INTEGER, OPTIONAL, INTENT(OUT) :: ierror

MPI_Type_create_f90_complex(p, r, newtype, ierror)
INTEGER, INTENT(IN) :: p, r

```

```

1      TYPE(MPI_Datatype), INTENT(OUT) :: newtype
2      INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

4      MPI_Type_create_f90_integer(r, newtype, ierror)
5      INTEGER, INTENT(IN) :: r

```

```

6      TYPE(MPI_Datatype), INTENT(OUT) :: newtype
7      INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

8      MPI_Type_create_f90_real(p, r, newtype, ierror)
9      INTEGER, INTENT(IN) :: p, r

```

```

10     TYPE(MPI_Datatype), INTENT(OUT) :: newtype
11     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

```

13     MPI_Type_match_size(typeclass, size, datatype, ierror)
14     INTEGER, INTENT(IN) :: typeclass, size
15     TYPE(MPI_Datatype), INTENT(OUT) :: datatype
16     INTEGER, OPTIONAL, INTENT(OUT) :: ierror

```

#### A.4.13 Profiling Interface Fortran 2008 Bindings

```

20     MPI_Pcontrol(level)
21     INTEGER, INTENT(IN) :: level

```

#### A.4.14 Deprecated Fortran 2008 Bindings

## A.5 C++ Bindings (deprecated)

### A.5.1 Point-to-Point Communication C++ Bindings

```

namespace MPI {

    {void Attach_buffer(void* buffer, int size) (binding deprecated, see
        Section 15.2) }

    {void Comm::Bsend(const void* buf, int count, const Datatype& datatype,
        int dest, int tag) const (binding deprecated, see Section 15.2) }

    {Prequest Comm::Bsend_init(const void* buf, int count, const
        Datatype& datatype, int dest, int tag) const (binding deprecated,
        see Section 15.2) }

    {void Request::Cancel() const (binding deprecated, see Section 15.2) }

    {int Detach_buffer(void*& buffer) (binding deprecated, see Section 15.2) }

    {void Request::Free() (binding deprecated, see Section 15.2) }

    {int Status::Get_count(const Datatype& datatype) const (binding deprecated,
        see Section 15.2) }

    {int Status::Get_error() const (binding deprecated, see Section 15.2) }

    {int Status::Get_source() const (binding deprecated, see Section 15.2) }

    {bool Request::Get_status() const (binding deprecated, see Section 15.2) }

    {bool Request::Get_status(Status& status) const (binding deprecated, see
        Section 15.2) }

    {int Status::Get_tag() const (binding deprecated, see Section 15.2) }

    {Request Comm::Ibsend(const void* buf, int count, const
        Datatype& datatype, int dest, int tag) const (binding deprecated,
        see Section 15.2) }

    {bool Comm::Iprobe(int source, int tag) const (binding deprecated, see
        Section 15.2) }

    {bool Comm::Iprobe(int source, int tag, Status& status) const (binding
        deprecated, see Section 15.2) }

    {Request Comm::Irecv(void* buf, int count, const Datatype& datatype,
        int source, int tag) const (binding deprecated, see Section 15.2) }

    {Request Comm::Irsend(const void* buf, int count, const
        Datatype& datatype, int dest, int tag) const (binding deprecated,
        see Section 15.2) }

    {bool Status::Is_cancelled() const (binding deprecated, see Section 15.2) }

    {Request Comm::Isend(const void* buf, int count, const
        Datatype& datatype, int dest, int tag) const (binding deprecated,

```

```

1         see Section 15.2) }
2
3     {Request Comm::Issend(const void* buf, int count, const
4         Datatype& datatype, int dest, int tag) const(binding deprecated,
5         see Section 15.2) }
6
7     {void Comm::Probe(int source, int tag) const(binding deprecated, see
8         Section 15.2) }
9
10    {void Comm::Probe(int source, int tag, Status& status) const(binding
11        deprecated, see Section 15.2) }
12
13    {Prequest Comm::Recv_init(void* buf, int count, const Datatype& datatype,
14        int source, int tag) const(binding deprecated, see Section 15.2) }
15
16    {void Comm::Recv(void* buf, int count, const Datatype& datatype,
17        int source, int tag) const(binding deprecated, see Section 15.2) }
18
19    {void Comm::Recv(void* buf, int count, const Datatype& datatype,
20        int source, int tag, Status& status) const(binding deprecated, see
21        Section 15.2) }
22
23    {void Comm::Rsend(const void* buf, int count, const Datatype& datatype,
24        int dest, int tag) const(binding deprecated, see Section 15.2) }
25
26    {Prequest Comm::Rsend_init(const void* buf, int count, const
27        Datatype& datatype, int dest, int tag) const(binding deprecated,
28        see Section 15.2) }
29
30    {void Comm::Send(const void* buf, int count, const Datatype& datatype,
31        int dest, int tag) const(binding deprecated, see Section 15.2) }
32
33    {Prequest Comm::Send_init(const void* buf, int count, const
34        Datatype& datatype, int dest, int tag) const(binding deprecated,
35        see Section 15.2) }
36
37    {void Comm::Sendrecv(const void *sendbuf, int sendcount, const
38        Datatype& sendtype, int dest, int sendtag, void *recvbuf,
39        int recvcount, const Datatype& recvtype, int source,
40        int recvtage) const(binding deprecated, see Section 15.2) }
41
42    {void Comm::Sendrecv(const void *sendbuf, int sendcount, const
43        Datatype& sendtype, int dest, int sendtag, void *recvbuf,
44        int recvcount, const Datatype& recvtype, int source,
45        int recvtage, Status& status) const(binding deprecated, see
46        Section 15.2) }
47
48    {void Comm::Sendrecv_replace(void* buf, int count, const
49        Datatype& datatype, int dest, int sendtag, int source,
50        int recvtage) const(binding deprecated, see Section 15.2) }
51
52    {void Comm::Sendrecv_replace(void* buf, int count, const
53        Datatype& datatype, int dest, int sendtag, int source,
54        int recvtage, Status& status) const(binding deprecated, see
55        Section 15.2) }

```



```

    Section 15.2) }
1
2
3 {void Status::Set_error(int error) (binding deprecated, see Section 15.2) }
4 {void Status::Set_source(int source) (binding deprecated, see Section 15.2) }
5 {void Status::Set_tag(int tag) (binding deprecated, see Section 15.2) }
6 {void Comm::Ssend(const void* buf, int count, const Datatype& datatype,
7     int dest, int tag) const (binding deprecated, see Section 15.2) }
8 {Prequest Comm::Ssend_init(const void* buf, int count, const
9     Datatype& datatype, int dest, int tag) const (binding deprecated,
10     see Section 15.2) }
11 {static void Prequest::Startall(int count,
12     Prequest array_of_requests[]) (binding deprecated, see Section 15.2) }
13 {void Prequest::Start() (binding deprecated, see Section 15.2) }
14 {static bool Request::Testall(int count, Request array_of_requests[],
15     Status array_of_statuses[]) (binding deprecated, see Section 15.2) }
16 {static bool Request::Testall(int count,
17     Request array_of_requests[]) (binding deprecated, see Section 15.2) }
18 {static bool Request::Testany(int count, Request array_of_requests[],
19     int& index, Status& status) (binding deprecated, see Section 15.2) }
20 {static bool Request::Testany(int count, Request array_of_requests[],
21     int& index) (binding deprecated, see Section 15.2) }
22 {static bool Request::Testany(int count, Request array_of_requests[],
23     int& index) (binding deprecated, see Section 15.2) }
24 {static bool Request::Testany(int count, Request array_of_requests[],
25     int& index) (binding deprecated, see Section 15.2) }
26 {bool Request::Test() (binding deprecated, see Section 15.2) }
27 {bool Request::Test(Status& status) (binding deprecated, see Section 15.2) }
28 {static int Request::Testsome(int incount, Request array_of_requests[],
29     int array_of_indices[], Status array_of_statuses[]) (binding
30     deprecated, see Section 15.2) }
31 {static int Request::Testsome(int incount, Request array_of_requests[],
32     int array_of_indices[]) (binding deprecated, see Section 15.2) }
33 {static void Request::Waitall(int count, Request array_of_requests[],
34     Status array_of_statuses[]) (binding deprecated, see Section 15.2) }
35 {static void Request::Waitall(int count,
36     Request array_of_requests[]) (binding deprecated, see Section 15.2) }
37 {static int Request::Waitany(int count, Request array_of_requests[],
38     Status& status) (binding deprecated, see Section 15.2) }
39 {static int Request::Waitany(int count,
40     Request array_of_requests[]) (binding deprecated, see Section 15.2) }
41 {static int Request::Waitany(int count,
42     Request array_of_requests[]) (binding deprecated, see Section 15.2) }
43 {void Request::Wait(Status& status) (binding deprecated, see Section 15.2) }
44
45
46
47
48

```

```

1  {static int Request::Waitsome(int incount, Request array_of_requests[],
2      int array_of_indices[], Status array_of_statuses[]) (binding
3      deprecated, see Section 15.2) }
4
5  {static int Request::Waitsome(int incount, Request array_of_requests[],
6      int array_of_indices[]) (binding deprecated, see Section 15.2) }
7
8  {void Request::Wait() (binding deprecated, see Section 15.2) }
9
10 };

```

## A.5.2 Datatypes C++ Bindings

```

13 namespace MPI {
14
15     {void Datatype::Commit() (binding deprecated, see Section 15.2) }
16
17     {Datatype Datatype::Create_contiguous(int count) const (binding deprecated,
18         see Section 15.2) }
19
20     {Datatype Datatype::Create_darray(int size, int rank, int ndims,
21         const int array_of_gsizes[], const int array_of_distrib[],
22         const int array_of_dargs[], const int array_of_psize[],
23         int order) const (binding deprecated, see Section 15.2) }
24
25     {Datatype Datatype::Create_hindexed(int count,
26         const int array_of_blocklengths[],
27         const Aint array_of_displacements[]) const (binding deprecated, see
28         Section 15.2) }
29
30     {Datatype Datatype::Create_hvector(int count, int blocklength, Aint
31         stride) const (binding deprecated, see Section 15.2) }
32
33     {Datatype Datatype::Create_indexed_block(int count, int blocklength,
34         const int array_of_displacements[]) const (binding deprecated, see
35         Section 15.2) }
36
37     {Datatype Datatype::Create_indexed(int count,
38         const int array_of_blocklengths[],
39         const int array_of_displacements[]) const (binding deprecated, see
40         Section 15.2) }
41
42     {Datatype Datatype::Create_resized(const Aint lb, const Aint extent)
43         const (binding deprecated, see Section 15.2) }
44
45     {static Datatype Datatype::Create_struct(int count,
46         const int array_of_blocklengths[], const Aint
47         array_of_displacements[],
48         const Datatype array_of_types[]) (binding deprecated, see
49         Section 15.2) }
50
51     {Datatype Datatype::Create_subarray(int ndims,
52         const int array_of_sizes[], const int array_of_subsizes[],

```

```

        const int array_of_starts[], int order) const(binding deprecated,
        see Section 15.2) }
    {Datatype Datatype::Create_vector(int count, int blocklength, int stride)
        const(binding deprecated, see Section 15.2) }
    {Datatype Datatype::Dup() const(binding deprecated, see Section 15.2) }
    {void Datatype::Free() (binding deprecated, see Section 15.2) }
    {Aint Get_address(void* location) (binding deprecated, see Section 15.2) }
    {void Datatype::Get_contents(int max_integers, int max_addresses,
        int max_datatypes, int array_of_integers[],
        Aint array_of_addresses[], Datatype array_of_datatypes[])
        const(binding deprecated, see Section 15.2) }
    {int Status::Get_elements(const Datatype& datatype) const(binding deprecated,
        see Section 15.2) }
    {void Datatype::Get_envelope(int& num_integers, int& num_addresses,
        int& num_datatypes, int& combiner) const(binding deprecated, see
        Section 15.2) }
    {void Datatype::Get_extent(Aint& lb, Aint& extent) const(binding deprecated,
        see Section 15.2) }
    {int Datatype::Get_size() const(binding deprecated, see Section 15.2) }
    {void Datatype::Get_true_extent(Aint& true_lb, Aint& true_extent)
        const(binding deprecated, see Section 15.2) }
    {void Datatype::Pack(const void* inbuf, int incount, void *outbuf,
        int outsize, int& position, const Comm &comm) const(binding
        deprecated, see Section 15.2) }
    {void Datatype::Pack_external(const char* datarep, const void* inbuf,
        int incount, void* outbuf, Aint outsize, Aint& position)
        const(binding deprecated, see Section 15.2) }
    {Aint Datatype::Pack_external_size(const char* datarep, int incount)
        const(binding deprecated, see Section 15.2) }
    {int Datatype::Pack_size(int incount, const Comm& comm) const(binding
        deprecated, see Section 15.2) }
    {void Datatype::Unpack(const void* inbuf, int insize, void *outbuf,
        int outcount, int& position, const Comm& comm) const(binding
        deprecated, see Section 15.2) }
    {void Datatype::Unpack_external(const char* datarep, const void* inbuf,
        Aint insize, Aint& position, void* outbuf, int outcount) const
        (binding deprecated, see Section 15.2) }
};

```

## A.5.3 Collective Communication C++ Bindings

```

namespace MPI {

    {void Comm::Allgather(const void* sendbuf, int sendcount, const
        Datatype& sendtype, void* recvbuf, int recvcount,
        const Datatype& recvttype) const = 0(binding deprecated, see
        Section 15.2) }

    {void Comm::Allgatherv(const void* sendbuf, int sendcount, const
        Datatype& sendtype, void* recvbuf, const int recvcounts[],
        const int displs[], const Datatype& recvttype) const = 0(binding
        deprecated, see Section 15.2) }

    {void Comm::Allreduce(const void* sendbuf, void* recvbuf, int count,
        const Datatype& datatype, const Op& op) const = 0(binding
        deprecated, see Section 15.2) }

    {void Comm::Alltoall(const void* sendbuf, int sendcount, const
        Datatype& sendtype, void* recvbuf, int recvcount,
        const Datatype& recvttype) const = 0(binding deprecated, see
        Section 15.2) }

    {void Comm::Alltoallv(const void* sendbuf, const int sendcounts[],
        const int sdispls[], const Datatype& sendtype, void* recvbuf,
        const int recvcounts[], const int rdispls[],
        const Datatype& recvttype) const = 0(binding deprecated, see
        Section 15.2) }

    {void Comm::Alltoallw(const void* sendbuf, const int sendcounts[], const
        int sdispls[], const Datatype sendtypes[], void* recvbuf,
        const int recvcounts[], const int rdispls[], const Datatype
        recvtypes[]) const = 0(binding deprecated, see Section 15.2) }

    {void Comm::Barrier() const = 0(binding deprecated, see Section 15.2) }

    {void Comm::Bcast(void* buffer, int count, const Datatype& datatype,
        int root) const = 0(binding deprecated, see Section 15.2) }

    {void Intracomm::Exscan(const void* sendbuf, void* recvbuf, int count,
        const Datatype& datatype, const Op& op) const(binding deprecated,
        see Section 15.2) }

    {void Op::Free() (binding deprecated, see Section 15.2) }

    {void Comm::Gather(const void* sendbuf, int sendcount, const
        Datatype& sendtype, void* recvbuf, int recvcount,
        const Datatype& recvttype, int root) const = 0(binding deprecated,
        see Section 15.2) }

    {void Comm::Gatherv(const void* sendbuf, int sendcount, const
        Datatype& sendtype, void* recvbuf, const int recvcounts[],
        const int displs[], const Datatype& recvttype, int root)
        const = 0(binding deprecated, see Section 15.2) }

```

```

{Request Comm::Iallgather(const void* sendbuf, int sendcount, const
    Datatype& sendtype, void* recvbuf, int recvcount,
    const Datatype& recvtype) const = 0(binding deprecated, see
    Section 15.2) }

{Request Comm::Iallgatherv(const void* sendbuf, int sendcount, const
    Datatype& sendtype, void* recvbuf, const int recvcounts[],
    const int displs[], const Datatype& recvtype) const = 0(binding
    deprecated, see Section 15.2) }

{Request Comm::Iallreduce(const void* sendbuf, void* recvbuf, int count,
    const Datatype& datatype, const Op& op) const = 0(binding
    deprecated, see Section 15.2) }

{Request Comm::Ialltoall(const void* sendbuf, int sendcount, const
    Datatype& sendtype, void* recvbuf, int recvcount,
    const Datatype& recvtype) const = 0(binding deprecated, see
    Section 15.2) }

{Request Comm::Ialltoallv(const void* sendbuf, const int sendcounts[],
    const int sdispls[], const Datatype& sendtype, void* recvbuf,
    const int recvcounts[], const int rdispls[],
    const Datatype& recvtype) const = 0(binding deprecated, see
    Section 15.2) }

{Request Comm::Ialltoallw(const void* sendbuf, const int sendcounts[],
    const int sdispls[], const Datatype sendtypes[], void*
    recvbuf, const int recvcounts[], const int rdispls[], const
    Datatype recvtypes[]) const = 0(binding deprecated, see
    Section 15.2) }

{Request Comm::Ibarrier() const = 0(binding deprecated, see Section 15.2) }

{Request Comm::Ibcast(void* buffer, int count, const Datatype& datatype,
    int root) const = 0(binding deprecated, see Section 15.2) }

{Request Intracomm::Iexscan(const void* sendbuf, void* recvbuf, int
    count, const Datatype& datatype, const Op& op) const(binding
    deprecated, see Section 15.2) }

{Request Comm::Igather(const void* sendbuf, int sendcount, const
    Datatype& sendtype, void* recvbuf, int recvcount,
    const Datatype& recvtype, int root) const = 0(binding deprecated,
    see Section 15.2) }

{Request Comm::Igatherv(const void* sendbuf, int sendcount, const
    Datatype& sendtype, void* recvbuf, const int recvcounts[],
    const int displs[], const Datatype& recvtype, int root)
    const = 0(binding deprecated, see Section 15.2) }

{void Op::Init(User_function* user_fn, bool commute)(binding deprecated, see
    Section 15.2) }

```

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```

1  {Request Comm::Ireduce(const void* sendbuf, void* recvbuf, int count,
2      const Datatype& datatype, const Op& op, int root)
3      const = 0(binding deprecated, see Section 15.2) }
4
5  {Request Comm::Ireduce_scatter_block(const void* sendbuf, void* recvbuf,
6      int recvcnt, const Datatype& datatype, const Op& op)
7      const = 0(binding deprecated, see Section 15.2) }
8
9  {Request Comm::Ireduce_scatter(const void* sendbuf, void* recvbuf,
10     int recvcnts[], const Datatype& datatype, const Op& op)
11     const = 0(binding deprecated, see Section 15.2) }
12
13 {Request Intracomm::Iscan(const void* sendbuf, void* recvbuf, int count,
14     const Datatype& datatype, const Op& op) const(binding deprecated,
15     see Section 15.2) }
16
17 {Request Comm::Iscatter(const void* sendbuf, int sendcount, const
18     Datatype& sendtype, void* recvbuf, int recvcnt,
19     const Datatype& recvtype, int root) const = 0(binding deprecated,
20     see Section 15.2) }
21
22 {Request Comm::Iscatterv(const void* sendbuf, const int sendcounts[],
23     const int displs[], const Datatype& sendtype, void* recvbuf,
24     int recvcnt, const Datatype& recvtype, int root)
25     const = 0(binding deprecated, see Section 15.2) }
26
27 {bool Op::Is_commutative() const(binding deprecated, see Section 15.2) }
28
29 {void Comm::Reduce(const void* sendbuf, void* recvbuf, int count,
30     const Datatype& datatype, const Op& op, int root)
31     const = 0(binding deprecated, see Section 15.2) }
32
33 {void Op::Reduce_local(const void* inbuf, void* inoutbuf, int count,
34     const Datatype& datatype) const(binding deprecated, see
35     Section 15.2) }
36
37 {void Comm::Reduce_scatter_block(const void* sendbuf, void* recvbuf,
38     int recvcnt, const Datatype& datatype, const Op& op)
39     const = 0(binding deprecated, see Section 15.2) }
40
41 {void Comm::Reduce_scatter(const void* sendbuf, void* recvbuf,
42     int recvcnts[], const Datatype& datatype, const Op& op)
43     const = 0(binding deprecated, see Section 15.2) }
44
45 {void Intracomm::Scan(const void* sendbuf, void* recvbuf, int count,
46     const Datatype& datatype, const Op& op) const(binding deprecated,
47     see Section 15.2) }
48
49 {void Comm::Scatter(const void* sendbuf, int sendcount, const
50     Datatype& sendtype, void* recvbuf, int recvcnt,
51     const Datatype& recvtype, int root) const = 0(binding deprecated,
52     see Section 15.2) }

```

```

{void Comm::Scatterv(const void* sendbuf, const int sendcounts[],
                    const int displs[], const Datatype& sendtype, void* recvbuf,
                    int recvcnt, const Datatype& recvttype, int root)
                    const = 0(binding deprecated, see Section 15.2) }

};

```

#### A.5.4 Groups, Contexts, Communicators, and Caching C++ Bindings

```

namespace MPI {

    {Comm& Comm::Clone() const = 0(binding deprecated, see Section 15.2) }

    {Cartcomm& Cartcomm::Clone() const(binding deprecated, see Section 15.2) }

    {Distgraphcomm& Distgraphcomm::Clone() const(binding deprecated, see
        Section 15.2) }

    {Graphcomm& Graphcomm::Clone() const(binding deprecated, see Section 15.2) }

    {Intercomm& Intercomm::Clone() const(binding deprecated, see Section 15.2) }

    {Intracomm& Intracomm::Clone() const(binding deprecated, see Section 15.2) }

    {static int Comm::Compare(const Comm& comm1, const Comm& comm2)(binding
        deprecated, see Section 15.2) }

    {static int Group::Compare(const Group& group1,
        const Group& group2)(binding deprecated, see Section 15.2) }

    {Intercomm Intercomm::Create(const Group& group) const(binding deprecated,
        see Section 15.2) }

    {Intracomm Intracomm::Create(const Group& group) const(binding deprecated,
        see Section 15.2) }

    {Intercomm Intracomm::Create_intercomm(int local_leader, const
        Comm& peer_comm, int remote_leader, int tag) const(binding
        deprecated, see Section 15.2) }

    {static int Comm::Create_keyval(Comm::Copy_attr_function*
        comm_copy_attr_fn,
        Comm::Delete_attr_function* comm_delete_attr_fn,
        void* extra_state)(binding deprecated, see Section 15.2) }

    {static int Datatype::Create_keyval(Datatype::Copy_attr_function*
        type_copy_attr_fn, Datatype::Delete_attr_function*
        type_delete_attr_fn, void* extra_state)(binding deprecated, see
        Section 15.2) }

    {static int Win::Create_keyval(Win::Copy_attr_function* win_copy_attr_fn,
        Win::Delete_attr_function* win_delete_attr_fn,
        void* extra_state)(binding deprecated, see Section 15.2) }

    {void Comm::Delete_attr(int comm_keyval)(binding deprecated, see Section 15.2) }
}

```



```

1  {void Datatype::Delete_attr(int type_keyval) (binding deprecated, see
2      Section 15.2) }
3
4  {void Win::Delete_attr(int win_keyval) (binding deprecated, see Section 15.2) }
5
6  {static Group Group::Difference(const Group& group1,
7      const Group& group2) (binding deprecated, see Section 15.2) }
8
9  {Cartcomm Cartcomm::Dup() const (binding deprecated, see Section 15.2) }
10
11 {Distgraphcomm Distgraphcomm::Dup() const (binding deprecated, see Section 15.2) }
12
13 {Graphcomm Graphcomm::Dup() const (binding deprecated, see Section 15.2) }
14
15 {Intercomm Intercomm::Dup() const (binding deprecated, see Section 15.2) }
16
17 {Intracomm Intracomm::Dup() const (binding deprecated, see Section 15.2) }
18
19 {Group Group::Excl(int n, const int ranks[]) const (binding deprecated, see
20     Section 15.2) }
21
22 {static void Comm::Free_keyval(int& comm_keyval) (binding deprecated, see
23     Section 15.2) }
24
25 {static void Datatype::Free_keyval(int& type_keyval) (binding deprecated, see
26     Section 15.2) }
27
28 {static void Win::Free_keyval(int& win_keyval) (binding deprecated, see
29     Section 15.2) }
30
31 {void Comm::Free() (binding deprecated, see Section 15.2) }
32
33 {void Group::Free() (binding deprecated, see Section 15.2) }
34
35 {bool Comm::Get_attr(int comm_keyval, void* attribute_val) const (binding
36     deprecated, see Section 15.2) }
37
38 {bool Datatype::Get_attr(int type_keyval, void* attribute_val)
39     const (binding deprecated, see Section 15.2) }
40
41 {bool Win::Get_attr(int win_keyval, void* attribute_val) const (binding
42     deprecated, see Section 15.2) }
43
44 {Group Comm::Get_group() const (binding deprecated, see Section 15.2) }
45
46 {void Comm::Get_name(char* comm_name, int& resultlen) const (binding
47     deprecated, see Section 15.2) }
48
49 {void Datatype::Get_name(char* type_name, int& resultlen) const (binding
50     deprecated, see Section 15.2) }
51
52 {void Win::Get_name(char* win_name, int& resultlen) const (binding deprecated,
53     see Section 15.2) }
54
55 {int Comm::Get_rank() const (binding deprecated, see Section 15.2) }
56
57 {int Group::Get_rank() const (binding deprecated, see Section 15.2) }

```



```

{Group Intercomm::Get_remote_group() const(binding deprecated, see Section 15.2) }
    }
{int Intercomm::Get_remote_size() const(binding deprecated, see Section 15.2) }
{int Comm::Get_size() const(binding deprecated, see Section 15.2) }
{int Group::Get_size() const(binding deprecated, see Section 15.2) }
{Group Group::Incl(int n, const int ranks[]) const(binding deprecated, see
    Section 15.2) }
{static Group Group::Intersect(const Group& group1,
    const Group& group2)(binding deprecated, see Section 15.2) }
{bool Comm::Is_inter() const(binding deprecated, see Section 15.2) }
{Intracomm Intercomm::Merge(bool high) const(binding deprecated, see
    Section 15.2) }
{Group Group::Range_excl(int n, const int ranges[][3]) const(binding
    deprecated, see Section 15.2) }
{Group Group::Range_incl(int n, const int ranges[][3]) const(binding
    deprecated, see Section 15.2) }
{void Comm::Set_attr(int comm_keyval, const void* attribute_val)
    const(binding deprecated, see Section 15.2) }
{void Datatype::Set_attr(int type_keyval, const void*
    attribute_val)(binding deprecated, see Section 15.2) }
{void Win::Set_attr(int win_keyval, const void* attribute_val)(binding
    deprecated, see Section 15.2) }
{void Comm::Set_name(const char* comm_name)(binding deprecated, see
    Section 15.2) }
{void Datatype::Set_name(const char* type_name)(binding deprecated, see
    Section 15.2) }
{void Win::Set_name(const char* win_name)(binding deprecated, see Section 15.2) }
{Intercomm Intercomm::Split(int color, int key) const(binding deprecated, see
    Section 15.2) }
{Intracomm Intracomm::Split(int color, int key) const(binding deprecated, see
    Section 15.2) }
{static void Group::Translate_ranks (const Group& group1, int n,
    const int ranks1[], const Group& group2, int ranks2[])(binding
    deprecated, see Section 15.2) }
{static Group Group::Union(const Group& group1,
    const Group& group2)(binding deprecated, see Section 15.2) }

```

```
1 };
2
```

### 3 A.5.5 Process Topologies C++ Bindings

```
4 namespace MPI {
5
6     {void Compute_dims(int nnodes, int ndims, int dims[]) (binding deprecated, see
7         Section 15.2) }
8
9     {Cartcomm Intracomm::Create_cart(int ndims, const int dims[],
10         const bool periods[], bool reorder) const (binding deprecated, see
11         Section 15.2) }
12
13     {Graphcomm Intracomm::Create_graph(int nnodes, const int index[],
14         const int edges[], bool reorder) const (binding deprecated, see
15         Section 15.2) }
16
17     {Distgraphcomm Intracomm::Dist_graph_create_adjacent(int indegree,
18         const int sources[], const int sourceweights[], int outdegree,
19         const int destinations[], const int destweights[],
20         const Info& info, bool reorder) const (binding deprecated, see
21         Section 15.2) }
22
23     {Distgraphcomm Intracomm::Dist_graph_create_adjacent(int indegree,
24         const int sources[], int outdegree, const int destinations[],
25         const Info& info, bool reorder) const (binding deprecated, see
26         Section 15.2) }
27
28     {Distgraphcomm Intracomm::Dist_graph_create(int n, const int sources[],
29         const int degrees[], const int destinations[],
30         const int weights[], const Info& info, bool reorder)
31         const (binding deprecated, see Section 15.2) }
32
33     {Distgraphcomm Intracomm::Dist_graph_create(int n, const int sources[],
34         const int degrees[], const int destinations[],
35         const Info& info, bool reorder) const (binding deprecated, see
36         Section 15.2) }
37
38     {int Cartcomm::Get_cart_rank(const int coords[]) const (binding deprecated,
39         see Section 15.2) }
40
41     {void Cartcomm::Get_coords(int rank, int maxdims, int coords[])
42         const (binding deprecated, see Section 15.2) }
43
44     {int Cartcomm::Get_dim() const (binding deprecated, see Section 15.2) }
45
46     {void Graphcomm::Get_dims(int nnodes[], int nedges[]) const (binding
47         deprecated, see Section 15.2) }
48
49     {void Distgraphcomm::Get_dist_neighbors_count(int rank, int indegree[],
50         int outdegree[], bool& weighted) const (binding deprecated, see
51         Section 15.2) }
```

```

{void Distgraphcomm::Get_dist_neighbors(int maxindegree, int sources[],
    int sourceweights[], int maxoutdegree, int destinations[],
    int destweights[]) (binding deprecated, see Section 15.2) }
{int Graphcomm::Get_neighbors_count(int rank) const(binding deprecated, see
    Section 15.2) }
{void Graphcomm::Get_neighbors(int rank, int maxneighbors, int
    neighbors[]) const(binding deprecated, see Section 15.2) }
{void Cartcomm::Get_topo(int maxdims, int dims[], bool periods[],
    int coords[]) const(binding deprecated, see Section 15.2) }
{void Graphcomm::Get_topo(int maxindex, int maxedges, int index[],
    int edges[]) const(binding deprecated, see Section 15.2) }
{int Comm::Get_topology() const(binding deprecated, see Section 15.2) }
{int Cartcomm::Map(int ndims, const int dims[], const bool periods[])
    const(binding deprecated, see Section 15.2) }
{int Graphcomm::Map(int nnodes, const int index[], const int edges[])
    const(binding deprecated, see Section 15.2) }
{void Cartcomm::Shift(int direction, int disp, int& rank_source,
    int& rank_dest) const(binding deprecated, see Section 15.2) }
{Cartcomm Cartcomm::Sub(const bool remain_dims[]) const(binding deprecated,
    see Section 15.2) }
};

```

### A.5.6 MPI Environmental Management C++ Bindings

```

namespace MPI {
{void Comm::Abort(int errorcode) (binding deprecated, see Section 15.2) }
{int Add_error_class() (binding deprecated, see Section 15.2) }
{int Add_error_code(int errorclass) (binding deprecated, see Section 15.2) }
{void Add_error_string(int errorcode, const char* string) (binding deprecated,
    see Section 15.2) }
{void* Alloc_mem(Aint size, const Info& info) (binding deprecated, see
    Section 15.2) }
{void Comm::Call_errhandler(int errorcode) const(binding deprecated, see
    Section 15.2) }
{void File::Call_errhandler(int errorcode) const(binding deprecated, see
    Section 15.2) }
{void Win::Call_errhandler(int errorcode) const(binding deprecated, see
    Section 15.2) }
}

```

```

1      {static Errhandler Comm::Create_errhandler(Comm::Errhandler_function*
ticket252-W. 2          comm_errhandler_fn) (binding deprecated, see Section 15.2) }
3
4      {static Errhandler File::Create_errhandler(File::Errhandler_function*
ticket252-W. 5          file_errhandler_fn) (binding deprecated, see Section 15.2) }
6
7      {static Errhandler Win::Create_errhandler(Win::Errhandler_function*
ticket252-W. 8          win_errhandler_fn) (binding deprecated, see Section 15.2) }
9
10     {void Finalize() (binding deprecated, see Section 15.2) }
11
12     {void Free_mem(void *base) (binding deprecated, see Section 15.2) }
13
14     {void Errhandler::Free() (binding deprecated, see Section 15.2) }
15
16     {Errhandler Comm::Get_errhandler() const (binding deprecated, see Section 15.2) }
17
18     {Errhandler File::Get_errhandler() const (binding deprecated, see Section 15.2) }
19
20     {Errhandler Win::Get_errhandler() const (binding deprecated, see Section 15.2) }
21
22     {int Get_error_class(int errorcode) (binding deprecated, see Section 15.2) }
23
24     {void Get_error_string(int errorcode, char* name, int& resultlen) (binding
25         deprecated, see Section 15.2) }
26
27     {void Get_processor_name(char* name, int& resultlen) (binding deprecated, see
28         Section 15.2) }
29
30     {void Get_version(int& version, int& subversion) (binding deprecated, see
31         Section 15.2) }
32
33     {void Init(int& argc, char**& argv) (binding deprecated, see Section 15.2) }
34
35     {void Init() (binding deprecated, see Section 15.2) }
36
37     {bool Is_finalized() (binding deprecated, see Section 15.2) }
38
39     {bool Is_initialized() (binding deprecated, see Section 15.2) }
40
41     {void Comm::Set_errhandler(const Errhandler& errhandler) (binding deprecated,
42         see Section 15.2) }
43
44     {void File::Set_errhandler(const Errhandler& errhandler) (binding deprecated,
45         see Section 15.2) }
46
47     {void Win::Set_errhandler(const Errhandler& errhandler) (binding deprecated,
48         see Section 15.2) }
49
50     {double Wtick() (binding deprecated, see Section 15.2) }
51
52     {double Wtime() (binding deprecated, see Section 15.2) }
53
54 };

```

## A.5.7 The Info Object C++ Bindings

```
namespace MPI {
```

```

{static Info Info::Create() (binding deprecated, see Section 15.2) }
{void Info::Delete(const char* key) (binding deprecated, see Section 15.2) }
{Info Info::Dup() const (binding deprecated, see Section 15.2) }
{void Info::Free() (binding deprecated, see Section 15.2) }
{bool Info::Get(const char* key, int valuelen, char* value) const (binding
    deprecated, see Section 15.2) }
{int Info::Get_nkeys() const (binding deprecated, see Section 15.2) }
{void Info::Get_nthkey(int n, char* key) const (binding deprecated, see
    Section 15.2) }
{bool Info::Get_valuelen(const char* key, int& valuelen) const (binding
    deprecated, see Section 15.2) }
{void Info::Set(const char* key, const char* value) (binding deprecated, see
    Section 15.2) }
};

```

#### A.5.8 Process Creation and Management C++ Bindings

```

namespace MPI {
    {Intercomm Intracomm::Accept(const char* port_name, const Info& info,
        int root) const (binding deprecated, see Section 15.2) }
    {void Close_port(const char* port_name) (binding deprecated, see Section 15.2) }
    {Intercomm Intracomm::Connect(const char* port_name, const Info& info,
        int root) const (binding deprecated, see Section 15.2) }
    {void Comm::Disconnect() (binding deprecated, see Section 15.2) }
    {static Intercomm Comm::Get_parent() (binding deprecated, see Section 15.2) }
    {static Intercomm Comm::Join(const int fd) (binding deprecated, see Section 15.2)
        }
    {void Lookup_name(const char* service_name, const Info& info,
        char* port_name) (binding deprecated, see Section 15.2) }
    {void Open_port(const Info& info, char* port_name) (binding deprecated, see
        Section 15.2) }
    {void Publish_name(const char* service_name, const Info& info,
        const char* port_name) (binding deprecated, see Section 15.2) }
    {Intercomm Intracomm::Spawn(const char* command, const char* argv[],
        int maxprocs, const Info& info, int root) const (binding
        deprecated, see Section 15.2) }
}

```

```

1  {Intercomm Intracomm::Spawn(const char* command, const char* argv[],
2      int maxprocs, const Info& info, int root,
3      int array_of_errcodes[]) const(binding deprecated, see Section 15.2)
4      }
5
6  {Intercomm Intracomm::Spawn_multiple(int count,
7      const char* array_of_commands[], const char** array_of_argv[],
8      const int array_of_maxprocs[], const Info array_of_info[],
9      int root, int array_of_errcodes[])(binding deprecated, see
10     Section 15.2) }
11
12 {Intercomm Intracomm::Spawn_multiple(int count,
13     const char* array_of_commands[], const char** array_of_argv[],
14     const int array_of_maxprocs[], const Info array_of_info[],
15     int root)(binding deprecated, see Section 15.2) }
16
17 {void Unpublish_name(const char* service_name, const Info& info,
18     const char* port_name)(binding deprecated, see Section 15.2) }
19 };
20

```

#### A.5.9 One-Sided Communications C++ Bindings

```

21 namespace MPI {
22
23     {void Win::Accumulate(const void* origin_addr, int origin_count, const
24         Datatype& origin_datatype, int target_rank, Aint target_disp,
25         int target_count, const Datatype& target_datatype, const Op&
26         op) const(binding deprecated, see Section 15.2) }
27
28     {void Win::Complete() const(binding deprecated, see Section 15.2) }
29
30     {static Win Win::Create(const void* base, Aint size, int disp_unit, const
31         Info& info, const Intracomm& comm)(binding deprecated, see
32         Section 15.2) }
33
34     {void Win::Fence(int assert) const(binding deprecated, see Section 15.2) }
35
36     {void Win::Free()(binding deprecated, see Section 15.2) }
37
38     {Group Win::Get_group() const(binding deprecated, see Section 15.2) }
39
40     {void Win::Get(void *origin_addr, int origin_count, const Datatype&
41         origin_datatype, int target_rank, Aint target_disp, int
42         target_count, const Datatype& target_datatype) const(binding
43         deprecated, see Section 15.2) }
44
45     {void Win::Lock(int lock_type, int rank, int assert) const(binding
46         deprecated, see Section 15.2) }
47
48     {void Win::Post(const Group& group, int assert) const(binding deprecated, see
49         Section 15.2) }
50

```

```

{void Win::Put(const void* origin_addr, int origin_count, const Datatype&
    origin_datatype, int target_rank, Aint target_disp, int
    target_count, const Datatype& target_datatype) const(binding
    deprecated, see Section 15.2) }
{void Win::Start(const Group& group, int assert) const(binding deprecated,
    see Section 15.2) }
{bool Win::Test() const(binding deprecated, see Section 15.2) }
{void Win::Unlock(int rank) const(binding deprecated, see Section 15.2) }
{void Win::Wait() const(binding deprecated, see Section 15.2) }
};

```

#### A.5.10 External Interfaces C++ Bindings

```

namespace MPI {
    {void Grequest::Complete() (binding deprecated, see Section 15.2) }
    {int Init_thread(int& argc, char**& argv, int required) (binding deprecated,
        see Section 15.2) }
    {int Init_thread(int required) (binding deprecated, see Section 15.2) }
    {bool Is_thread_main() (binding deprecated, see Section 15.2) }
    {int Query_thread() (binding deprecated, see Section 15.2) }
    {void Status::Set_cancelled(bool flag) (binding deprecated, see Section 15.2) }
    {void Status::Set_elements(const Datatype& datatype, int count) (binding
        deprecated, see Section 15.2) }
    {static Grequest Grequest::Start(const Grequest::Query_function*
        query_fn, const Grequest::Free_function* free_fn,
        const Grequest::Cancel_function* cancel_fn,
        void *extra_state) (binding deprecated, see Section 15.2) }
};

```

#### A.5.11 I/O C++ Bindings

```

namespace MPI {
    {void File::Close() (binding deprecated, see Section 15.2) }
    {static void File::Delete(const char* filename, const Info& info) (binding
        deprecated, see Section 15.2) }
    {int File::Get_amode() const(binding deprecated, see Section 15.2) }
    {bool File::Get_atomicity() const(binding deprecated, see Section 15.2) }
}

```

```

1  {Offset File::Get_byte_offset(const Offset disp) const(binding deprecated,
2      see Section 15.2) }
3
4  {Group File::Get_group() const(binding deprecated, see Section 15.2) }
5
6  {Info File::Get_info() const(binding deprecated, see Section 15.2) }
7
8  {Offset File::Get_position() const(binding deprecated, see Section 15.2) }
9
10 {Offset File::Get_position_shared() const(binding deprecated, see Section 15.2) }
11
12 {Offset File::Get_size() const(binding deprecated, see Section 15.2) }
13
14 {Aint File::Get_type_extent(const Datatype& datatype) const(binding
15     deprecated, see Section 15.2) }
16
17 {void File::Get_view(Offset& disp, Datatype& etype, Datatype& filetype,
18     char* datarep) const(binding deprecated, see Section 15.2) }
19
20 {Request File::Iread_at(Offset offset, void* buf, int count,
21     const Datatype& datatype)(binding deprecated, see Section 15.2) }
22
23 {Request File::Iread_shared(void* buf, int count,
24     const Datatype& datatype)(binding deprecated, see Section 15.2) }
25
26 {Request File::Iread(void* buf, int count,
27     const Datatype& datatype)(binding deprecated, see Section 15.2) }
28
29 {Request File::Iwrite_at(Offset offset, const void* buf, int count,
30     const Datatype& datatype)(binding deprecated, see Section 15.2) }
31
32 {Request File::Iwrite(const void* buf, int count,
33     const Datatype& datatype)(binding deprecated, see Section 15.2) }
34
35 {Request File::Iwrite_shared(const void* buf, int count,
36     const Datatype& datatype)(binding deprecated, see Section 15.2) }
37
38 {static File File::Open(const Intracomm& comm, const char* filename,
39     int amode, const Info& info)(binding deprecated, see Section 15.2) }
40
41 {void File::Preallocate(Offset size)(binding deprecated, see Section 15.2) }
42
43 {void File::Read_all_begin(void* buf, int count,
44     const Datatype& datatype)(binding deprecated, see Section 15.2) }
45
46 {void File::Read_all_end(void* buf, Status& status)(binding deprecated, see
47     Section 15.2) }
48
49 {void File::Read_all_end(void* buf)(binding deprecated, see Section 15.2) }
50
51 {void File::Read_all(void* buf, int count, const Datatype& datatype,
52     Status& status)(binding deprecated, see Section 15.2) }
53
54 {void File::Read_all(void* buf, int count,
55     const Datatype& datatype)(binding deprecated, see Section 15.2) }

```



```

{void File::Read_at_all_begin(Offset offset, void* buf, int count,
    const Datatype& datatype) (binding deprecated, see Section 15.2) }
{void File::Read_at_all_end(void* buf, Status& status) (binding deprecated,
    see Section 15.2) }
{void File::Read_at_all_end(void* buf) (binding deprecated, see Section 15.2) }
{void File::Read_at_all(Offset offset, void* buf, int count,
    const Datatype& datatype, Status& status) (binding deprecated, see
    Section 15.2) }
{void File::Read_at_all(Offset offset, void* buf, int count,
    const Datatype& datatype) (binding deprecated, see Section 15.2) }
{void File::Read_at(Offset offset, void* buf, int count,
    const Datatype& datatype, Status& status) (binding deprecated, see
    Section 15.2) }
{void File::Read_at(Offset offset, void* buf, int count,
    const Datatype& datatype) (binding deprecated, see Section 15.2) }
{void File::Read_ordered_begin(void* buf, int count,
    const Datatype& datatype) (binding deprecated, see Section 15.2) }
{void File::Read_ordered_end(void* buf, Status& status) (binding deprecated,
    see Section 15.2) }
{void File::Read_ordered_end(void* buf) (binding deprecated, see Section 15.2) }
{void File::Read_ordered(void* buf, int count, const Datatype& datatype,
    Status& status) (binding deprecated, see Section 15.2) }
{void File::Read_ordered(void* buf, int count,
    const Datatype& datatype) (binding deprecated, see Section 15.2) }
{void File::Read_shared(void* buf, int count, const Datatype& datatype,
    Status& status) (binding deprecated, see Section 15.2) }
{void File::Read_shared(void* buf, int count,
    const Datatype& datatype) (binding deprecated, see Section 15.2) }
{void File::Read(void* buf, int count, const Datatype& datatype, Status&
    status) (binding deprecated, see Section 15.2) }
{void File::Read(void* buf, int count, const Datatype& datatype) (binding
    deprecated, see Section 15.2) }
{void Register_datarep(const char* datarep,
    Datarep_conversion_function* read_conversion_fn,
    Datarep_conversion_function* write_conversion_fn,
    Datarep_extent_function* dtype_file_extent_fn,
    void* extra_state) (binding deprecated, see Section 15.2) }

```

```

1  {void File::Seek(Offset offset, int whence) (binding deprecated, see
2      Section 15.2) }
3
4  {void File::Seek_shared(Offset offset, int whence) (binding deprecated, see
5      Section 15.2) }
6
7  {void File::Set_atomicity(bool flag) (binding deprecated, see Section 15.2) }
8  {void File::Set_info(const Info& info) (binding deprecated, see Section 15.2) }
9  {void File::Set_size(Offset size) (binding deprecated, see Section 15.2) }
10
11 {void File::Set_view(Offset disp, const Datatype& etype,
12     const Datatype& filetype, const char* datarep,
13     const Info& info) (binding deprecated, see Section 15.2) }
14
15 {void File::Sync() (binding deprecated, see Section 15.2) }
16
17 {void File::Write_all_begin(const void* buf, int count,
18     const Datatype& datatype) (binding deprecated, see Section 15.2) }
19
20 {void File::Write_all(const void* buf, int count,
21     const Datatype& datatype, Status& status) (binding deprecated, see
22     Section 15.2) }
23
24 {void File::Write_all(const void* buf, int count,
25     const Datatype& datatype) (binding deprecated, see Section 15.2) }
26
27 {void File::Write_all_end(const void* buf, Status& status) (binding
28     deprecated, see Section 15.2) }
29
30 {void File::Write_at_all_begin(Offset offset, const void* buf, int count,
31     const Datatype& datatype) (binding deprecated, see Section 15.2) }
32
33 {void File::Write_at_all_end(const void* buf, Status& status) (binding
34     deprecated, see Section 15.2) }
35
36 {void File::Write_at_all_end(const void* buf) (binding deprecated, see
37     Section 15.2) }
38
39 {void File::Write_at_all(Offset offset, const void* buf, int count,
40     const Datatype& datatype, Status& status) (binding deprecated, see
41     Section 15.2) }
42
43 {void File::Write_at_all(Offset offset, const void* buf, int count,
44     const Datatype& datatype) (binding deprecated, see Section 15.2) }
45
46 {void File::Write_at(Offset offset, const void* buf, int count,
47     const Datatype& datatype, Status& status) (binding deprecated, see
48     Section 15.2) }

```

```

{void File::Write(const void* buf, int count, const Datatype& datatype,
                  Status& status) (binding deprecated, see Section 15.2) }
{void File::Write(const void* buf, int count,
                  const Datatype& datatype) (binding deprecated, see Section 15.2) }
{void File::Write_ordered_begin(const void* buf, int count,
                                const Datatype& datatype) (binding deprecated, see Section 15.2) }
{void File::Write_ordered(const void* buf, int count,
                           const Datatype& datatype, Status& status) (binding deprecated, see
                           Section 15.2) }
{void File::Write_ordered(const void* buf, int count,
                           const Datatype& datatype) (binding deprecated, see Section 15.2) }
{void File::Write_ordered_end(const void* buf, Status& status) (binding
                              deprecated, see Section 15.2) }
{void File::Write_ordered_end(const void* buf) (binding deprecated, see
                              Section 15.2) }
{void File::Write_shared(const void* buf, int count,
                          const Datatype& datatype, Status& status) (binding deprecated, see
                          Section 15.2) }
{void File::Write_shared(const void* buf, int count,
                          const Datatype& datatype) (binding deprecated, see Section 15.2) }
};

```

#### A.5.12 Language Bindings C++ Bindings

```

namespace MPI {
    {static Datatype Datatype::Create_f90_complex(int p, int r) (binding
        deprecated, see Section 15.2) }
    {static Datatype Datatype::Create_f90_integer(int r) (binding deprecated, see
        Section 15.2) }
    {static Datatype Datatype::Create_f90_real(int p, int r) (binding deprecated,
        see Section 15.2) }
    Exception::Exception(int error_code)
    {int Exception::Get_error_class() const (binding deprecated, see Section 15.2) }
    {int Exception::Get_error_code() const (binding deprecated, see Section 15.2) }
    {const char* Exception::Get_error_string() const (binding deprecated, see
        Section 15.2) }
    {static Datatype Datatype::Match_size(int typeclass, int size) (binding
        deprecated, see Section 15.2) }
}

```

```
1 };
```

### 3 A.5.13 Profiling Interface C++ Bindings

```
4 namespace MPI {
5
6     {void Pcontrol(const int level, ...) (binding deprecated, see Section 15.2) }
7
8 };
```

ticket11.

### 11 A.5.14 C++ Bindings on all MPI Classes

12 The C++ language requires all classes to have four special functions: a default constructor,  
 13 a copy constructor, a destructor, and an assignment operator. The bindings for these func-  
 14 tions are listed below; their semantics are discussed in Section 16.1.5. The two constructors  
 15 are *not virtual*. The bindings prototype functions are using the type `<CLASS>` rather than  
 16 listing each function for every MPI class. The token `<CLASS>` can be replaced with valid MPI-  
 17 2 class names, such as `Group`, `Datatype`, etc., except when noted. In addition, bindings are  
 18 provided for comparison and inter-language operability from Sections 16.1.5 and 16.1.9.

### 20 A.5.15 Construction / Destruction

```
21 namespace MPI {
22
23     <CLASS>::<CLASS>()
24
25     <CLASS>::~~<CLASS>()
26
27 };
```

### 29 A.5.16 Copy / Assignment

```
30 namespace MPI {
31
32     <CLASS>::<CLASS>(const <CLASS>& data)
33
34     <CLASS>& <CLASS>::operator=(const <CLASS>& data)
35
36 };
```

### 38 A.5.17 Comparison

39 Since `Status` instances are not handles to underlying MPI objects, the `operator==( )` and  
 40 `operator!=( )` functions are not defined on the `Status` class.

```
41 namespace MPI {
42
43     bool <CLASS>::operator==(const <CLASS>& data) const
44
45     bool <CLASS>::operator!=(const <CLASS>& data) const
46
47 };
```

## A.5.18 Inter-language Operability

Since there are no C++ `MPI::STATUS_IGNORE` and `MPI::STATUSES_IGNORE` objects, the result of promoting the C or Fortran handles (`MPI_STATUS_IGNORE` and `MPI_STATUSES_IGNORE`) to C++ is undefined.

```
namespace MPI {
    <CLASS>& <CLASS>::operator=(const MPI_<CLASS>& data)
    <CLASS>::<CLASS>(const MPI_<CLASS>& data)
    <CLASS>::operator MPI_<CLASS>() const
};
```

1  
2  
3  
4  
5  
6  
7  
8  
9  
10  
11  
12  
13  
14  
15  
16  
17  
18  
19  
20  
21  
22  
23  
24  
25  
26  
27  
28  
29  
30  
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47  
48

# Annex B

## Change-Log

This annex summarizes changes from the previous version of the MPI standard to the version presented by this document. Only significant changes (i.e., clarifications and new features) that might either require implementation effort in the MPI libraries or change the understanding of MPI from a user's perspective are presented. Editorial modifications, formatting, typo corrections and minor clarifications are not shown.

### B.1 Changes from Version 2.2 to Version 3.0

1. Section 2.3 on page 10, and Sections 16.2.1, 16.2.15, 16.2.16 on pages 544, 564, and 566.

The new `mpi_08` Fortran module is introduced.

2. Section 2.5.1 on page 12, Section 16.2.14 on page 563, Section 16.2.15 on page 564, and Section 16.2.16 on page 566.

Handles to opaque objects are defined as named types within the `mpi_08` Fortran module. The handle types are also available through the `mpi` Fortran module.

3. Section 2.5.2 on page 14, Section 3.2.6 on page 36, Section 7.5.4 on page 296, Section 7.5.5 on page 303, Section 10.3 on page 360, Section 10.3.3 on page 365, Section 12.2 on page 429, and Section 16.2.15 on page 564.

With the `mpi_f08` module, optional arguments through function overloading are used instead of `MPI_STATUS_IGNORE`, `MPI_STATUSES_IGNORE`, `MPI_ERRCODES_IGNORE`, and `MPI_UNWEIGHTED`.

4. Sections 2.5.4, 2.5.5 on pages 15, 16, Sections 16.2.1, 16.2.2, 16.2.3, 16.2.4, 16.2.5 on pages 544, 545, 546, 547, 550, and Sections 16.2.14, 16.2.15, 16.2.16 on pages 563, 564, 566.

Within the `mpi_08` Fortran module, choice buffers are defined as assumed-type and assumed-rank according to Fortran 2008, TR 29113 [35], and the compile-time constant `MPI_SUBARRAYS` is set to `MPI_SUBARRAYS_SUPPORTED`. With this, Fortran subscript triplets can be used in nonblocking MPI operations; vector subscripts are not supported in nonblocking operations. If the compiler does not support this Fortran TR 29113 feature, the constant is set to `MPI_SUBARRAYS_NOT_SUPPORTED`.

5. Section 2.6.2 on page 18, Section 16.2.15 on page 564, and Section 16.2.16 on page 566. The `ierror` dummy arguments are `OPTIONAL` within the `mpi_08` Fortran module.

ticket243-O.

6. Section 3.2.5 on page 34, Section 16.2.14 on page 563, Section 16.2.15 on page 564, Section 16.2.16 on page 566, and Section 16.3.5 on page 582.

Within the `mpi_08` Fortran module, the status is defined as `TYPE(MPI_Status)`. New conversion routines are added: `MPI_STATUS_F2F08`, `MPI_STATUS_F082F`, `MPI_Status_c2f08`, and `MPI_Status_f082c`,

7. Sections 4.1.10, 5.9.5, 5.9.7, 6.7.4, 6.8, 8.3.1, 8.3.2, 8.3.3, 15.1, 16.2.18 on pages 111, 186, 191, 276, 282, 327, 329, 331, 523, and 569. In some routines, the dummy argument names were changed, because they were identical to the Fortran keywords `TYPE` and `FUNCTION`. The new dummy argument names must be used because the `mpi` and `mpi_08` modules guarantee keyword-based actual argument lists. The argument name `type` was changed into `oldtype` in `MPI_TYPE_DUP`, and into `datatype` in the Fortran `USER_FUNCTION` of `MPI_OP_CREATE`, and in `MPI_TYPE_SET_ATTR`, `MPI_TYPE_GET_ATTR`, `MPI_TYPE_DELETE_ATTR`, `MPI_TYPE_SET_NAME`, `MPI_TYPE_GET_NAME`, `MPI_TYPE_MATCH_SIZE`, in the callback prototype definition `MPI_Type_delete_attr_function`, and the predefined callback function `MPI_TYPE_NULL_DELETE_FN`; function was changed into `user_fn` in `MPI_OP_CREATE`, into `comm_errhandler_fn` in `MPI_COMM_CREATE_ERRHANDLER`, into `win_errhandler_fn` in `MPI_WIN_CREATE_ERRHANDLER`, into `file_errhandler_fn` in `MPI_FILE_CREATE_ERRHANDLER`, into `handler_fn` in `MPI_ERRHANDLER_CREATE`. For consistency reasons, `INOUBUF` was changed into `INOUTBUF` in `MPI_REDUCE_LOCAL`, and `intracomm` into `newintracomm` in `MPI_INTERCOMM_MERGE`.

8. Section 8.2 on page 322.  
In Fortran with the `mpi` and `mpi_f08` modules, `MPI_ALLOC_MEM` now also supports `TYPE(C_PTR)` C-pointer instead of only returning an address-sized integer that may be usable together with non-standard Cray-pointer.

9. Section 16.2.7 on page 550, and Section 16.2.16 on page 566.  
Fortran `SEQUENCE` and `BIND(C)` derived application types can be used as buffers in MPI operations.

10. Section 16.2.8 on page 551 to Section 16.2.11 on page 561, Section 16.2.16 on page 566, and Section 16.2.17 on page 568.

The sections about Fortran optimization problems and their solution is partially rewritten and new methods are added, e.g., the use of the `TARGET` attribute. The Fortran routine `MPI_F_SYNC_REG` is added. To achieve a secure and portable programming interfaces, in Section 16.2.16, several requirements are defined for the combination of an MPI library and a Fortran compiler to be MPI-3.0 compliant.

11. Section 16.2.13 on page 561.

The use of the `mpif.h` Fortran include file is strongly discouraged.

12. Section 16.2.14 on page 563, and Section 16.2.16 on page 566.

The existing `mpi` Fortran module must implement compile-time argument checking.

13. Section 16.2.15 on page 564.

Within the `mpi_08` Fortran module, dummy arguments are declared with `INTENT=IN`, `OUT`, or `INOUT` as defined in the `mpi_08` interfaces.



14. Section 16.2.16 on page 566.  
This new section summarizes requirements that an MPI library together with a Fortran compiler is compliant to the MPI standard.
15. Section A.1.1, Table “*Predefined functions*” on page 604, Section A.1.3 on page 609, and Section A.4.4 on page 673.  
Within the new `mpi_f08` module, all callback prototype definitions are defined with explicit interfaces `PROCEDURE(MPI_...)`, except for the `user_fn` argument in `MPI_OP_CREATE` and for the `read_conversion_fn` and `write_conversion_fn` arguments in `MPI_REGISTER_DATAREP`.
16. Section A.1.3 on page 609.  
In some routines, the Fortran callback prototype names were changed from `..._FN` to `..._FUNCTION` to be consistent with the other language bindings.

## B.2 Changes from Version 2.1 to Version 2.2

1. Section 2.5.4 on page 15.  
It is now guaranteed that predefined named constant handles (as other constants) can be used in initialization expressions or assignments, i.e., also before the call to `MPI_INIT`.
2. Section 2.6 on page 17, Section 2.6.4 on page 19, and Section 16.1 on page 531.  
The C++ language bindings have been deprecated and may be removed in a future version of the MPI specification.
3. Section 3.2.2 on page 29.  
`MPI_CHAR` for printable characters is now defined for C type char (instead of signed char). This change should not have any impact on applications nor on MPI libraries (except some comment lines), because printable characters could and can be stored in any of the C types char, signed char, and unsigned char, and `MPI_CHAR` is not allowed for predefined reduction operations.
4. Section 3.2.2 on page 29.  
`MPI_(U)INT{8,16,32,64}_T`, `MPI_AINT`, `MPI_OFFSET`, `MPI_C_BOOL`, `MPI_C_COMPLEX`, `MPI_C_FLOAT_COMPLEX`, `MPI_C_DOUBLE_COMPLEX`, and `MPI_C_LONG_DOUBLE_COMPLEX` are now valid predefined MPI datatypes.
5. Section 3.4 on page 42, Section 3.7.2 on page 53, Section 3.9 on page 76, and Section 5.1 on page 143.  
The read access restriction on the send buffer for blocking, non blocking and collective API has been lifted. It is permitted to access for read the send buffer while the operation is in progress.
6. Section 3.7 on page 52.  
The Advice to users for `IBSEND` and `IRSEND` was slightly changed.
7. Section 3.7.3 on page 57.  
The advice to free an active request was removed in the Advice to users for `MPI_REQUEST_FREE`.

- 1       8. Section 3.7.6 on page 70.  
2       MPI\_REQUEST\_GET\_STATUS changed to permit inactive or null requests as input.  
3
- 4       9. Section 5.8 on page 171.  
5       “In place” option is added to MPI\_ALLTOALL, MPI\_ALLTOALLV, and  
6       MPI\_ALLTOALLW for intracommunicators.
- 7       10. Section 5.9.2 on page 179.  
8       Predefined parameterized datatypes (e.g., returned by MPI\_TYPE\_CREATE\_F90\_REAL)  
9       and optional named predefined datatypes (e.g. MPI\_REAL8) have been added to the  
10      list of valid datatypes in reduction operations.  
11
- 12      11. Section 5.9.2 on page 179.  
13      MPI\_(U)INT{8,16,32,64}\_T are all considered C integer types for the purposes of the  
14      predefined reduction operators. MPI\_AINT and MPI\_OFFSET are considered Fortran  
15      integer types. MPI\_C\_BOOL is considered a Logical type.  
16      MPI\_C\_COMPLEX, MPI\_C\_FLOAT\_COMPLEX, MPI\_C\_DOUBLE\_COMPLEX, and  
17      MPI\_C\_LONG\_DOUBLE\_COMPLEX are considered Complex types.  
18
- 19      12. Section 5.9.7 on page 191.  
20      The local routines MPI\_REDUCE\_LOCAL and MPI\_OP\_COMMUTATIVE have been  
21      added.
- 22      13. Section 5.10.1 on page 193.  
23      The collective function MPI\_REDUCE\_SCATTER\_BLOCK is added to the MPI stan-  
24      dard.  
25
- 26      14. Section 5.11.2 on page 197.  
27      Added in place argument to MPI\_EXSCAN.
- 28      15. Section 6.4.2 on page 240, and Section 6.6 on page 256.  
29      Implementations that did not implement MPI\_COMM\_CREATE on intercommuni-  
30      cators will need to add that functionality. As the standard described the behav-  
31      ior of this operation on intercommunicators, it is believed that most implementa-  
32      tions already provide this functionality. Note also that the C++ binding for both  
33      MPI\_COMM\_CREATE and MPI\_COMM\_SPLIT explicitly allow Intercomms.  
34
- 35      16. Section 6.4.2 on page 240.  
36      MPI\_COMM\_CREATE is extended to allow several disjoint subgroups as input if comm  
37      is an intracommunicator. If comm is an intercommunicator it was clarified that all  
38      processes in the same local group of comm must specify the same value for group.  
39
- 40      17. Section 7.5.4 on page 296.  
41      New functions for a scalable distributed graph topology interface has been added.  
42      In this section, the functions MPI\_DIST\_GRAPH\_CREATE\_ADJACENT and  
43      MPI\_DIST\_GRAPH\_CREATE, the constants MPI\_UNWEIGHTED, and the derived C++  
44      class Distgraphcomm were added.
- 45      18. Section 7.5.5 on page 303.  
46      For the scalable distributed graph topology interface, the functions  
47      MPI\_DIST\_NEIGHBORS\_COUNT and MPI\_DIST\_NEIGHBORS and the constant  
48      MPI\_DIST\_GRAPH were added.

19. Section 7.5.5 on page 303.  
Remove ambiguity regarding duplicated neighbors with MPI\_GRAPH\_NEIGHBORS and MPI\_GRAPH\_NEIGHBORS\_COUNT.
20. Section 8.1.1 on page 319.  
The subversion number changed from 1 to 2.
21. Section 8.3 on page 325, Section 15.2 on page 529, and Annex A.1.3 on page 609.  
Changed function pointer typedef names MPI\_{Comm,File,Win}\_errhandler\_fn to MPI\_{Comm,File,Win}\_errhandler\_function. Deprecated old “\_fn” names.
22. Section 8.7.1 on page 347.  
Attribute deletion callbacks on MPI\_COMM\_SELF are now called in LIFO order. Implementors must now also register all implementation-internal attribute deletion callbacks on MPI\_COMM\_SELF before returning from MPI\_INIT/MPI\_INIT\_THREAD.
23. Section 11.3.4 on page 399.  
The restriction added in MPI 2.1 that the operation MPI\_REPLACE in MPI\_ACCUMULATE can be used only with predefined datatypes has been removed. MPI\_REPLACE can now be used even with derived datatypes, as it was in MPI 2.0. Also, a clarification has been made that MPI\_REPLACE can be used only in MPI\_ACCUMULATE, not in collective operations that do reductions, such as MPI\_REDUCE and others.
24. Section 12.2 on page 429.  
Add “\*” to the query\_fn, free\_fn, and cancel\_fn arguments to the C++ binding for MPI::Grequest::Start() for consistency with the rest of MPI functions that take function pointer arguments.
25. Section 13.5.2 on page 494, and Table 13.2 on page 495.  
MPI\_(U)INT{8,16,32,64}\_T, MPI\_AINT, MPI\_OFFSET, MPI\_C\_COMPLEX, MPI\_C\_FLOAT\_COMPLEX, MPI\_C\_DOUBLE\_COMPLEX, MPI\_C\_LONG\_DOUBLE\_COMPLEX, and MPI\_C\_BOOL are added as predefined datatypes in the external32 representation.
26. Section 16.3.7 on page 587.  
The description was modified that it only describes how an MPI implementation behaves, but not how MPI stores attributes internally. The erroneous MPI-2.1 Example 16.17 was replaced with three new examples 16.22, 16.23, and 16.24 on pages 588-590 explicitly detailing cross-language attribute behavior. Implementations that matched the behavior of the old example will need to be updated.
27. Annex A.1.1 on page 595.  
Removed type MPI::Fint (compare MPI\_Fint in Section A.1.2 on page 608).
28. Annex A.1.1 on page 595. Table *Named Predefined Datatypes*.  
Added MPI\_(U)INT{8,16,32,64}\_T, MPI\_AINT, MPI\_OFFSET, MPI\_C\_BOOL, MPI\_C\_FLOAT\_COMPLEX, MPI\_C\_COMPLEX, MPI\_C\_DOUBLE\_COMPLEX, and MPI\_C\_LONG\_DOUBLE\_COMPLEX are added as predefined datatypes.

### B.3 Changes from Version 2.0 to Version 2.1

1. Section 3.2.2 on page 29, Section 16.1.6 on page 535, and Annex A.1 on page 595.  
In addition, the MPI\_LONG\_LONG should be added as an optional type; it is a synonym for MPI\_LONG\_LONG\_INT.
2. Section 3.2.2 on page 29, Section 16.1.6 on page 535, and Annex A.1 on page 595.  
MPI\_LONG\_LONG\_INT, MPI\_LONG\_LONG (as synonym), MPI\_UNSIGNED\_LONG\_LONG, MPI\_SIGNED\_CHAR, and MPI\_WCHAR are moved from optional to official and they are therefore defined for all three language bindings.
3. Section 3.2.5 on page 34.  
MPI\_GET\_COUNT with zero-length datatypes: The value returned as the count argument of MPI\_GET\_COUNT for a datatype of length zero where zero bytes have been transferred is zero. If the number of bytes transferred is greater than zero, MPI\_UNDEFINED is returned.
4. Section 4.1 on page 85.  
General rule about derived datatypes: Most datatype constructors have replication count or block length arguments. Allowed values are non-negative integers. If the value is zero, no elements are generated in the type map and there is no effect on datatype bounds or extent.
5. Section 4.3 on page 138.  
MPI\_BYTE should be used to send and receive data that is packed using MPI\_PACK\_EXTERNAL.
6. Section 5.9.6 on page 190.  
If comm is an intercommunicator in MPI\_ALLREDUCE, then both groups should provide count and datatype arguments that specify the same type signature (i.e., it is not necessary that both groups provide the same count value).
7. Section 6.3.1 on page 230.  
MPI\_GROUP\_TRANSLATE\_RANKS and MPI\_PROC\_NULL: MPI\_PROC\_NULL is a valid rank for input to MPI\_GROUP\_TRANSLATE\_RANKS, which returns MPI\_PROC\_NULL as the translated rank.
8. Section 6.7 on page 264.  
About the attribute caching functions:  
  

*Advice to implementors.* High-quality implementations should raise an error when a keyval that was created by a call to MPI\_XXX\_CREATE\_KEYVAL is used with an object of the wrong type with a call to MPI\_YYY\_GET\_ATTR, MPI\_YYY\_SET\_ATTR, MPI\_YYY\_DELETE\_ATTR, or MPI\_YYY\_FREE\_KEYVAL. To do so, it is necessary to maintain, with each keyval, information on the type of the associated user function. (*End of advice to implementors.*)
9. Section 6.8 on page 282.  
In MPI\_COMM\_GET\_NAME: In C, a null character is additionally stored at

name[resultlen]. resultlen cannot be larger than MPI\_MAX\_OBJECT\_NAME-1. In Fortran, name is padded on the right with blank characters. resultlen cannot be larger than MPI\_MAX\_OBJECT\_NAME.

10. Section 7.4 on page 290.  
About MPI\_GRAPH\_CREATE and MPI\_CART\_CREATE: All input arguments must have identical values on all processes of the group of comm\_old.
11. Section 7.5.1 on page 292.  
In MPI\_CART\_CREATE: If ndims is zero then a zero-dimensional Cartesian topology is created. The call is erroneous if it specifies a grid that is larger than the group size or if ndims is negative.
12. Section 7.5.3 on page 294.  
In MPI\_GRAPH\_CREATE: If the graph is empty, i.e., nnodes == 0, then MPI\_COMM\_NULL is returned in all processes.
13. Section 7.5.3 on page 294.  
In MPI\_GRAPH\_CREATE: A single process is allowed to be defined multiple times in the list of neighbors of a process (i.e., there may be multiple edges between two processes). A process is also allowed to be a neighbor to itself (i.e., a self loop in the graph). The adjacency matrix is allowed to be non-symmetric.  
  
*Advice to users.* Performance implications of using multiple edges or a non-symmetric adjacency matrix are not defined. The definition of a node-neighbor edge does not imply a direction of the communication. (*End of advice to users.*)
14. Section 7.5.5 on page 303.  
In MPI\_CARTDIM\_GET and MPI\_CART\_GET: If comm is associated with a zero-dimensional Cartesian topology, MPI\_CARTDIM\_GET returns ndims=0 and MPI\_CART\_GET will keep all output arguments unchanged.
15. Section 7.5.5 on page 303.  
In MPI\_CART\_RANK: If comm is associated with a zero-dimensional Cartesian topology, coord is not significant and 0 is returned in rank.
16. Section 7.5.5 on page 303.  
In MPI\_CART\_COORDS: If comm is associated with a zero-dimensional Cartesian topology, coords will be unchanged.
17. Section 7.5.6 on page 311.  
In MPI\_CART\_SHIFT: It is erroneous to call MPI\_CART\_SHIFT with a direction that is either negative or greater than or equal to the number of dimensions in the Cartesian communicator. This implies that it is erroneous to call MPI\_CART\_SHIFT with a comm that is associated with a zero-dimensional Cartesian topology.
18. Section 7.5.7 on page 313.  
In MPI\_CART\_SUB: If all entries in remain\_dims are false or comm is already associated with a zero-dimensional Cartesian topology then newcomm is associated with a zero-dimensional Cartesian topology.

- 1 18.1. Section 8.1.1 on page 319.  
 2 The subversion number changed from 0 to 1.  
 3
- 4 19. Section 8.1.2 on page 320.  
 5 In MPI\_GET\_PROCESSOR\_NAME: In C, a null character is additionally stored at  
 6 name[resultlen]. resultlen cannot be larger than MPI\_MAX\_PROCESSOR\_NAME-1. In  
 7 Fortran, name is padded on the right with blank characters. resultlen cannot be larger  
 8 than MPI\_MAX\_PROCESSOR\_NAME.  
 9
- 10 20. Section 8.3 on page 325.  
 11 MPI\_{COMM,WIN,FILE}\_GET\_ERRHANDLER behave as if a new error handler object  
 12 is created. That is, once the error handler is no longer needed,  
 13 MPI\_ERRHANDLER\_FREE should be called with the error handler returned from  
 14 MPI\_ERRHANDLER\_GET or MPI\_{COMM,WIN,FILE}\_GET\_ERRHANDLER to mark  
 15 the error handler for deallocation. This provides behavior similar to that of  
 16 MPI\_COMM\_GROUP and MPI\_GROUP\_FREE.  
 17
- 18 21. Section 8.7 on page 341, see explanations to MPI\_FINALIZE.  
 19 MPI\_FINALIZE is collective over all connected processes. If no processes were spawned,  
 20 accepted or connected then this means over MPI\_COMM\_WORLD; otherwise it is col-  
 21 lective over the union of all processes that have been and continue to be connected,  
 22 as explained in Section 10.5.4 on page 384.  
 23
- 24 22. Section 8.7 on page 341.  
 25 About MPI\_ABORT:  
 26 *Advice to users.* Whether the errorcode is returned from the executable or from  
 27 the MPI process startup mechanism (e.g., mpiexec), is an aspect of quality of the  
 28 MPI library but not mandatory. (*End of advice to users.*)  
 29 *Advice to implementors.* Where possible, a high-quality implementation will try  
 30 to return the errorcode from the MPI process startup mechanism (e.g. mpiexec  
 31 or singleton init). (*End of advice to implementors.*)  
 32
- 33 23. Section 9 on page 351.  
 34 An implementation must support info objects as caches for arbitrary (key, value)  
 35 pairs, regardless of whether it recognizes the key. Each function that takes hints in  
 36 the form of an MPI\_Info must be prepared to ignore any key it does not recognize. This  
 37 description of info objects does not attempt to define how a particular function should  
 38 react if it recognizes a key but not the associated value. MPI\_INFO\_GET\_NKEYS,  
 39 MPI\_INFO\_GET\_NTHKEY, MPI\_INFO\_GET\_VALUELEN, and MPI\_INFO\_GET must  
 40 retain all (key,value) pairs so that layered functionality can also use the Info object.  
 41
- 42 24. Section 11.3 on page 393.  
 43 MPI\_PROC\_NULL is a valid target rank in the MPI RMA calls MPI\_ACCUMULATE,  
 44 MPI\_GET, and MPI\_PUT. The effect is the same as for MPI\_PROC\_NULL in MPI point-  
 45 to-point communication. See also item 25 in this list.  
 46
- 47 25. Section 11.3 on page 393.  
 48 After any RMA operation with rank MPI\_PROC\_NULL, it is still necessary to finish

the RMA epoch with the synchronization method that started the epoch. See also item 24 in this list.

26. Section 11.3.4 on page 399.  
MPI\_REPLACE in MPI\_ACCUMULATE, like the other predefined operations, is defined only for the predefined MPI datatypes.
27. Section 13.2.8 on page 455.  
About MPI\_FILE\_SET\_VIEW and MPI\_FILE\_SET\_INFO: When an info object that specifies a subset of valid hints is passed to MPI\_FILE\_SET\_VIEW or MPI\_FILE\_SET\_INFO, there will be no effect on previously set or defaulted hints that the info does not specify.
28. Section 13.2.8 on page 455.  
About MPI\_FILE\_GET\_INFO: If no hint exists for the file associated with fh, a handle to a newly created info object is returned that contains no key/value pair.
29. Section 13.3 on page 458.  
If a file does not have the mode MPI\_MODE\_SEQUENTIAL, then MPI\_DISPLACEMENT\_CURRENT is invalid as disp in MPI\_FILE\_SET\_VIEW.
30. Section 13.5.2 on page 494.  
The bias of 16 byte doubles was defined with 10383. The correct value is 16383.
31. Section 16.1.4 on page 532.  
In the example in this section, the buffer should be declared as `const void* buf`.
32. Section 16.2.18 on page 569.  
About MPI\_TYPE\_CREATE\_F90\_XXXX:  
  

*Advice to implementors.* An application may often repeat a call to MPI\_TYPE\_CREATE\_F90\_XXXX with the same combination of (XXXX,p,r). The application is not allowed to free the returned predefined, unnamed datatype handles. To prevent the creation of a potentially huge amount of handles, the MPI implementation should return the same datatype handle for the same (REAL/COMPLEX/INTEGER,p,r) combination. Checking for the combination (p,r) in the preceding call to MPI\_TYPE\_CREATE\_F90\_XXXX and using a hash-table to find formerly generated handles should limit the overhead of finding a previously generated datatype with same combination of (XXXX,p,r). (*End of advice to implementors.*)
33. Section A.1.1 on page 595.  
MPI\_BOTTOM is defined as `void * const MPI::BOTTOM`.

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# MPI Callback Function Prototype Index

This index lists the C typedef names for callback routines, such as those used with attribute caching or user-defined reduction operations. C++ names for these typedefs and Fortran example prototypes are given near the text of the C name.

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