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├── examples/ Example scripts using low- to high-level APIs
├── exercises/ Hands-on exercises for the tutorial
├── openoptics/ Core OpenOptics logic and APIs
│   ├── Toolbox.py Top-level classes and API entry points
│   ├── OpticalTopo.py Functions for topology algorithms
│   ├── OpticalRouting.py Routing algorithms and utilities
├── p4/ P4 programs for ToR and OCS dataplane behavior
├── target/ bmv4 software switch implementation with OpenOptics extensions
│   (e.g., calendar queue, monitoring tools)
├── tests/ Sorry what?
```

`connect(self, node1, port1, node2, port2, time_slice) -> bool:` Connect two node ports at the given time slice by configuring OCS,
if no optical connections haven't been built for both ports.

`deploy_topo(Optional : ciruits)` Convert the pre-defined circuits to OCS schedules
Call after calling connect() or given ciruits (from topology functions in OpticalTopo.py)

`add_time_flow_entry(node_id, entries, routing_mode="Per-hop" or "Source")`

`deploy_routing(Optional : paths, routing_mode="Per-hop" or "Source")`