

$$V(t) = V_m \cos(\omega t + \theta_v) \Rightarrow \bar{V} = V_m e^{j\theta_v}$$

$$i(t) = I_m \cos(\omega t + \theta_i) \Rightarrow \bar{I} = I_m e^{j\theta_i}$$

$$p(t) = p(t, \bar{V}, \bar{I})$$

$$V(t) = \frac{V_m e^{j(\omega t + \theta_v)} + V_m e^{-j(\omega t + \theta_v)}}{2}$$

$$V(t) = \frac{\bar{V} e^{j\omega t} + \bar{V}^* e^{-j\omega t}}{2}$$

$$i(t) = \frac{\bar{I} e^{j\omega t} + \bar{I}^* e^{-j\omega t}}{2}$$

non dipende dal tempo

$$p(t, \bar{V}, \bar{I}) = \frac{1}{4} \left\{ \underbrace{\bar{V} \bar{I}^*}_a + \underbrace{\bar{V}^* \bar{I}}_{a^*} \right\} + \frac{1}{4} \left\{ \underbrace{\bar{V} \bar{I} e^{j2\omega t}}_b + \underbrace{\bar{V}^* \bar{I}^* e^{-j2\omega t}}_{b^*} \right\}$$

POTENZA MEDIA

$$p(t, \bar{V}, \bar{I}) = \frac{1}{2} \operatorname{Re} \{ \bar{V} \bar{I}^* \} + \frac{1}{2} \operatorname{Re} \{ \bar{V} \bar{I} e^{j2\omega t} \}$$

$$\bar{I}^* = \bar{I} e^{-j2\theta_i} \Rightarrow \bar{I} = \bar{I}^* e^{j2\theta_i}$$



$$\bar{I} = I_m e^{j\theta_i}$$

$$p(t) = \underbrace{\left(\frac{1}{2}\right) \operatorname{Re}\{\bar{V}\bar{I}^*\}}_{\substack{\text{POT. MEDIA} \\ \text{POT. ATTIVA}}} + \left(\frac{1}{2}\right) \operatorname{Re}\{\underbrace{\bar{V}\bar{I}^*}_{\bar{S}}\} e^{j(2\omega t + 2\theta_i)}$$

$$\bar{S} = \frac{1}{2} \bar{V}\bar{I}^*$$

$$\frac{1}{2} |\bar{V}| |\bar{I}| \cos(\theta_v - \theta_i)$$

$$\operatorname{Re}\left\{ \underbrace{a}_{\in \mathbb{C}} \cdot \underbrace{b}_{\in \mathbb{C}} \right\}$$

$$\frac{1}{2} V_m I_m \cos(\theta_v - \theta_i)$$

$$+ \frac{1}{2} \operatorname{Re}\{\bar{V}\bar{I}^*\} \cos(2\omega t + 2\theta_i)$$

$$\frac{1}{2} V_m I_m \underbrace{\cos(\phi)}_{\substack{\text{fattore di} \\ \text{potenza}}}$$

$$- \frac{1}{2} I_m \{\bar{V}\bar{I}^*\} \sin(2\omega t + 2\theta_i)$$

$$p(t) = \frac{1}{2} \operatorname{Re}\{\bar{V}\bar{I}^*\} + \frac{1}{2} \operatorname{Re}\{\bar{V}\bar{I}^*\} \cos(2\omega t + 2\theta_i) - \frac{1}{2} \operatorname{Im}\{\bar{V}\bar{I}^*\} \sin(2\omega t + 2\theta_i)$$

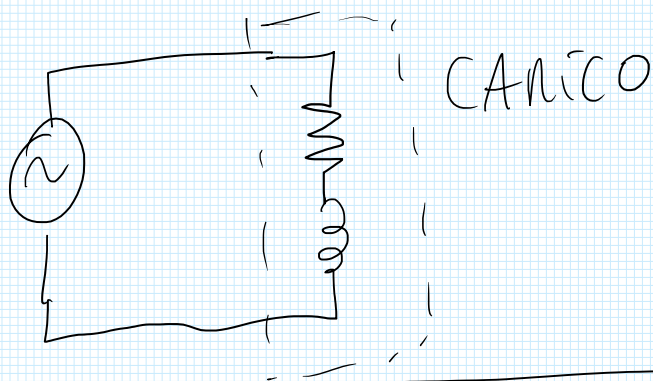
$$\underbrace{\operatorname{Re}\{\bar{S}\} + \operatorname{Re}\{\bar{S}\} \cos(2\omega t + 2\theta_i)}_{\text{RESISTIVA}} - \underbrace{\operatorname{Im}\{\bar{S}\} \sin(2\omega t + 2\theta_i)}_{\text{REATTIVA}}$$

$$\bar{S} = \frac{1}{2} V_m I_m e^{j(\theta_v - \theta_i)}$$

se  $\theta_v = \theta_i$   $\bar{S} \in \mathbb{R}$  e il carico è resistivo

$\theta_i$ )

$$\text{se } \theta_v - \theta_i = \pm \frac{\pi}{2} \quad \bar{S} = \pm j \frac{V_m I_m}{2}$$



$$P = R i^2 \quad P = \frac{V^2}{R}$$

$$R \rightarrow Z, Y$$

$$\bar{V} = Z \cdot \bar{I} \quad \bar{S} = \frac{1}{2} Z \cdot \bar{I} \cdot \bar{I}^* = \frac{1}{2} Z |\bar{I}|^2 = \frac{1}{2} Z I_m^2$$

$$\bar{I} = Y \cdot \bar{V} \quad \bar{S} = \frac{1}{2} \bar{V} \cdot Y^* \bar{V}^* = \frac{1}{2} Y^* |\bar{V}|^2 = \frac{1}{2} Y^* V_m^2$$

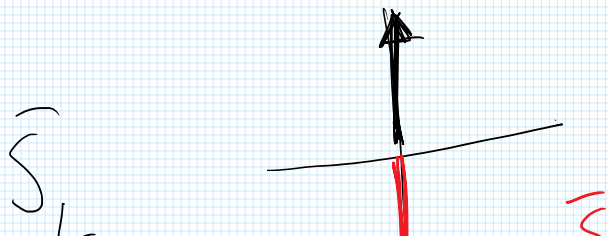
$$\bar{S}_R = \left( \frac{1}{2} \right) R I_m^2 = \left( + \frac{1}{2} \right) \frac{V_m^2}{R} \in \mathbb{R}$$

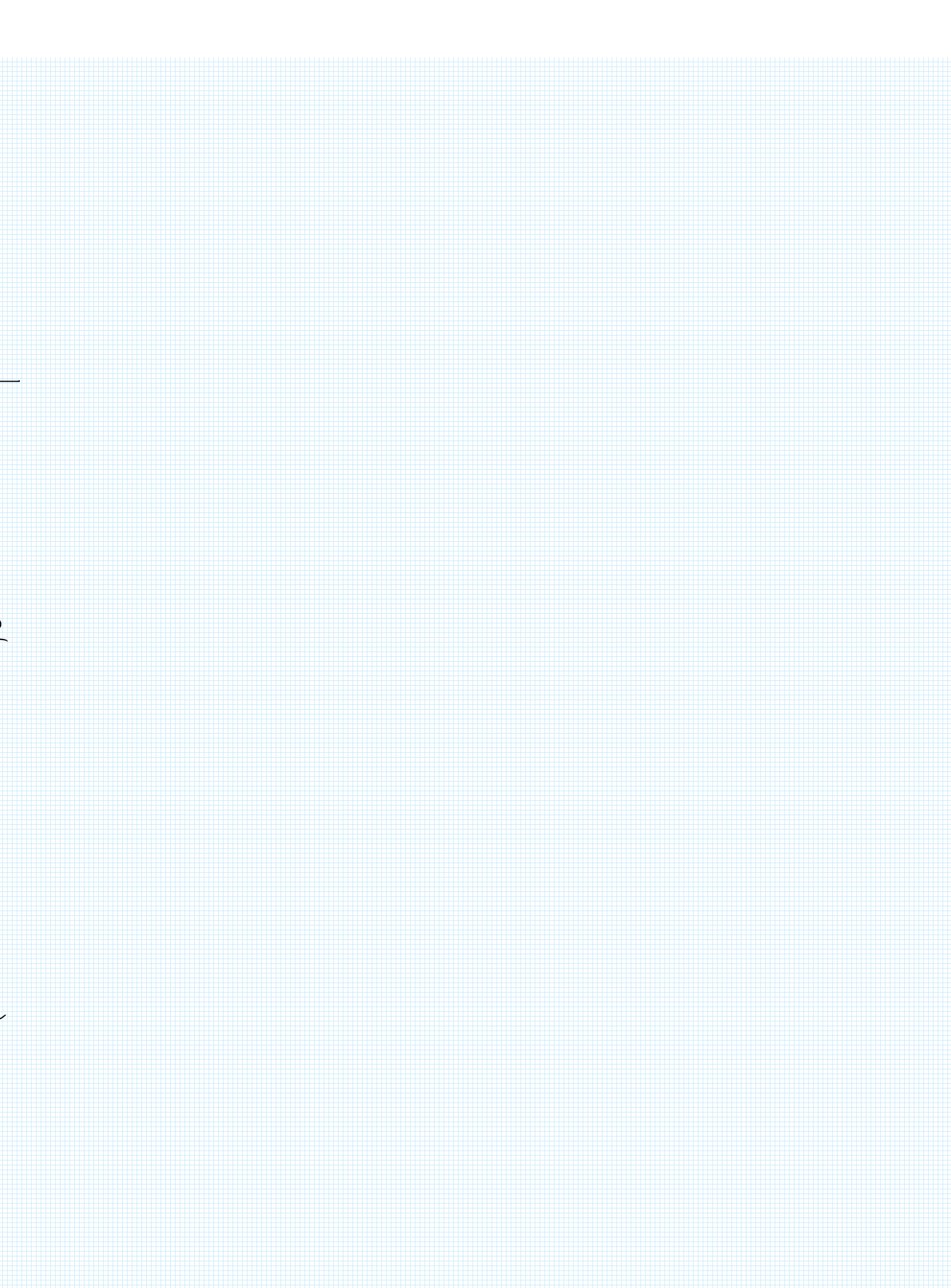
$$\bar{S}_L = \frac{1}{2} j \omega L I_m^2 = j \frac{\omega L}{2} I_m^2$$

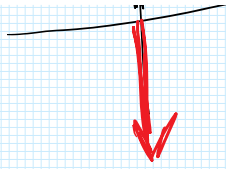
$$Y_C = j \omega C$$

$$Y_C^* = -j \omega C$$

$$\bar{S}_C = \frac{1}{2} -j \omega C V_m^2 = -j \frac{\omega C}{2} V_m^2$$



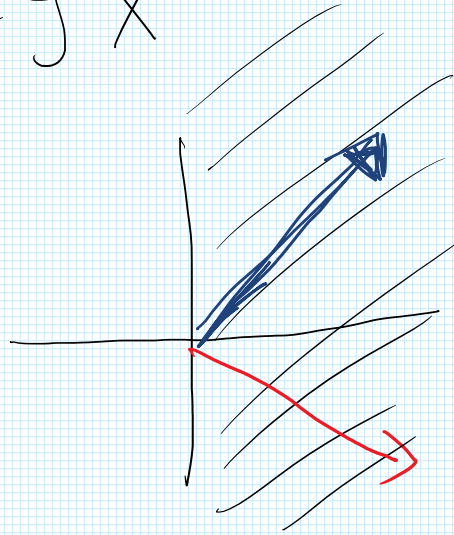


$S_L$  $\bar{S}_0$ 

$$X \begin{matrix} \geq \\ \leq \end{matrix} 0$$

$$Z_{Bip} = R + jX$$

$$\bar{S}_{Bip} =$$



CARICO CON  
COMP. INDUTTIVA

CARICO CON  
COMP. CAPACITIVA

$$\sum \bar{S} = 0$$

$$\sum \text{Re}\{\bar{S}\} = 0$$

$$\sum \text{Im}\{\bar{S}\} = 0$$

$$\sum \text{pot. media} = 0$$

$$\sum \text{pot. reattive} = 0$$

$$\text{Im}\{\bar{S}\} = \text{Im}\left\{\frac{1}{2} \bar{V} \bar{I}^*\right\} = \text{pot. reattive}$$

$$P_n = R i^2$$

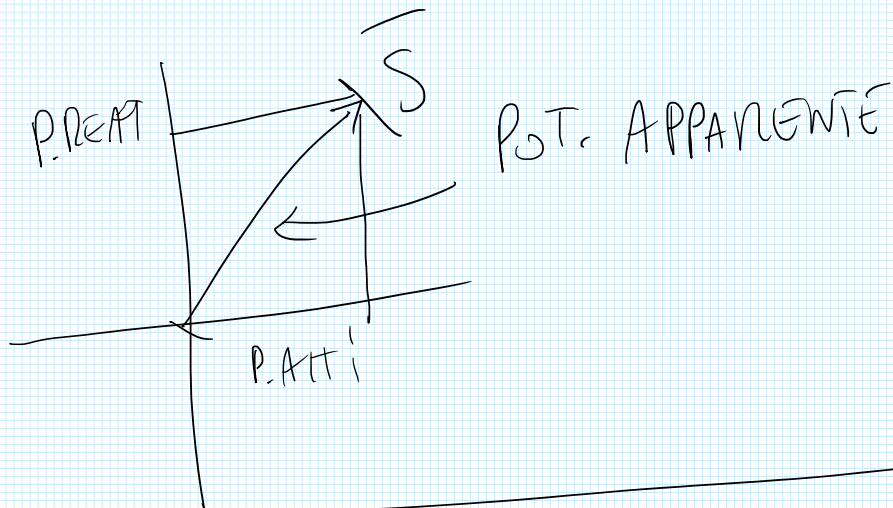
$$\bar{S}_P = \frac{1}{2} R \left( \bar{I}_m \right)^2 \rightarrow \text{VALORE DI PICCO}$$

$$\frac{1}{T} \int_0^T \cos^2(\omega t) dt = \frac{1}{2}$$

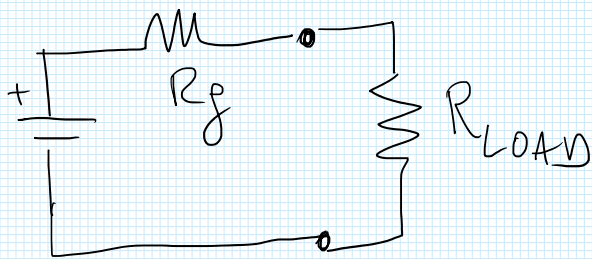
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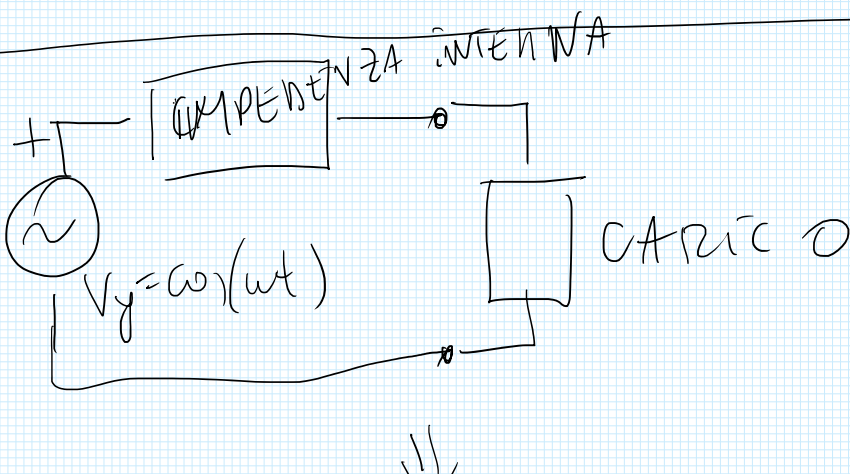
$$\frac{1}{T} \int_0^T \cos^2(\omega t) dt = \frac{1}{2}$$



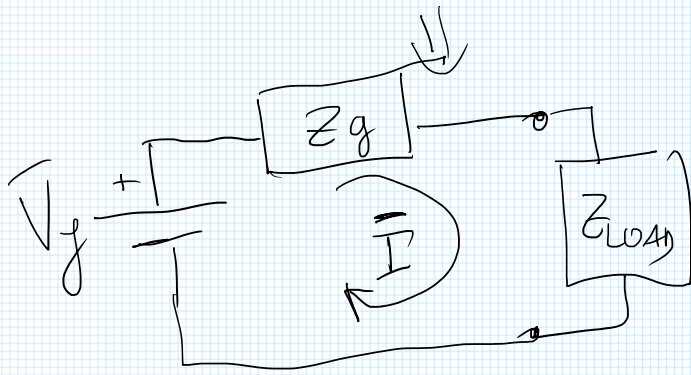
MAX TRASF DI POTENZA ATTIVA



$P_{R_{LOAD}}$  è massima  
quando  $R_{LOAD} = R_g$   
 $\hat{=} R_{TH}$







$P_{ATT}^{LOAD} \rightarrow \text{MAX?}$

$$\overline{I} = \frac{\overline{V}_g}{Z_g + Z_L}$$

$$P_{ATTIVA} = \text{Re} \{ \overline{S} \} = \text{Re} \left\{ \frac{1}{2} Z_{LOAD} \cdot |\overline{I}|^2 \right\}$$

$$= \frac{1}{2} |\overline{I}|^2 \text{Re} \{ Z_{LOAD} \}$$

$$P_{ATTIVA}^{LOAD} = \frac{1}{2} \frac{|\overline{V}_g|^2}{|Z_g + Z_L|^2} \cdot \underbrace{\text{Re} \{ Z_L \}}_{R_{LOAD}}$$

$$Z_g = R_g + jX_g \quad Z_{LOAD} = R_{LOAD} + jX_{LOAD}$$

$$P_{ATT}^{LOAD} = \frac{|\overline{V}_g|^2}{2} \cdot \frac{R_{LOAD}}{[(R_g + R_{LOAD})^2 + (X_g + X_{LOAD})^2]}$$



$$I_{ATT} = \frac{1}{2} \cdot \frac{1}{\left[ (R_g + R_{LOAD})^2 + (X_g + X_{LOAD})^2 \right]}$$

$$\frac{\partial P_{ATT}^{LOAD}}{\partial R_{LOAD}} = \frac{1 \cdot \left[ (R_g + R_L)^2 \right] - 2 R_{LOAD} \cdot (R_g + R_{LOAD})}{\left[ \right]^2}$$

$$\frac{\partial P_{ATT}^{LOAD}}{\partial X_{LOAD}} = \frac{|V_g|^2}{2} \cdot R_{LOAD} \cdot \frac{-2(X_g + X_{LOAD})}{\left[ \right]^2} \stackrel{!}{=} 0$$

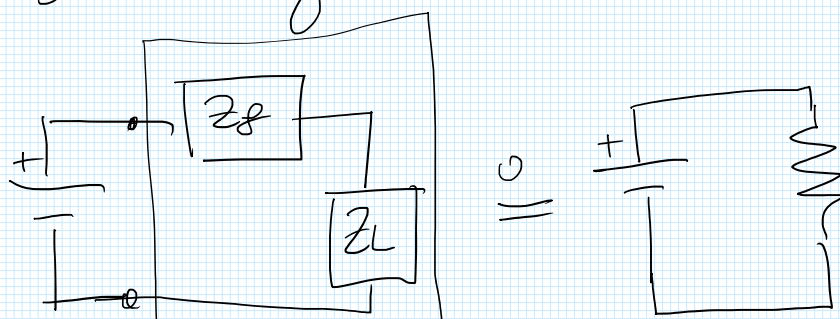
$$\frac{\partial P_{ATT}}{\partial X_{LOAD}} = 0 \quad X_{LOAD} = -X_g$$

$$R_g^2 + R_L^2 + 2R_g R_L - 2R_g R_L - 2R_L^2$$

$$R_g^2 - R_L^2 = 0$$

$$R_g = R_L$$

$$Z_{LOAD} = Z_g^*$$



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