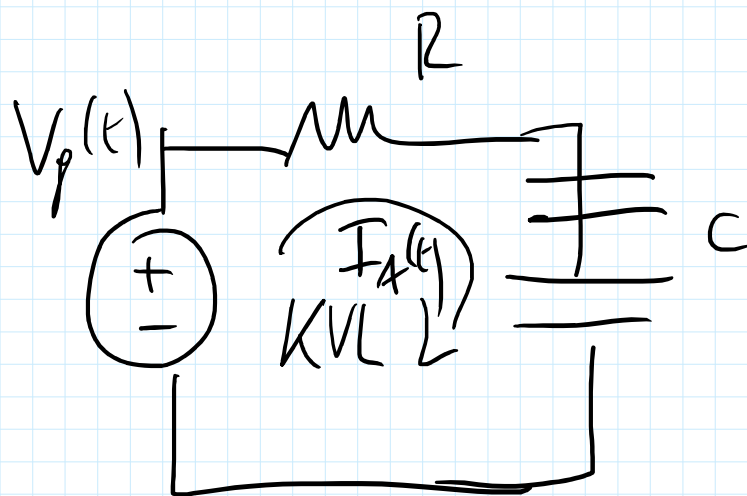


CIRCUITI 1° ORDINE

05 April 2017 15:27

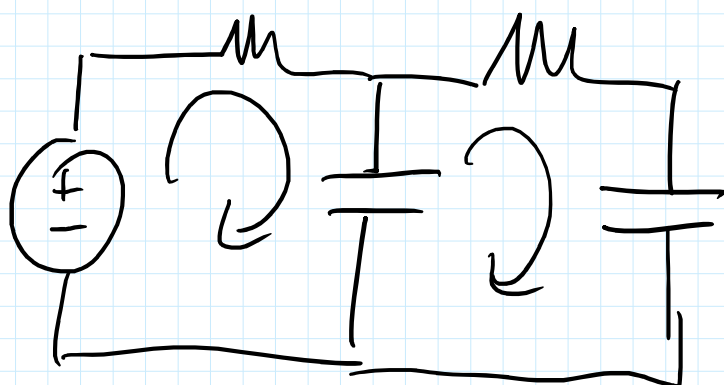
N
 e_p

1° ord. $\dot{X} + X = f$



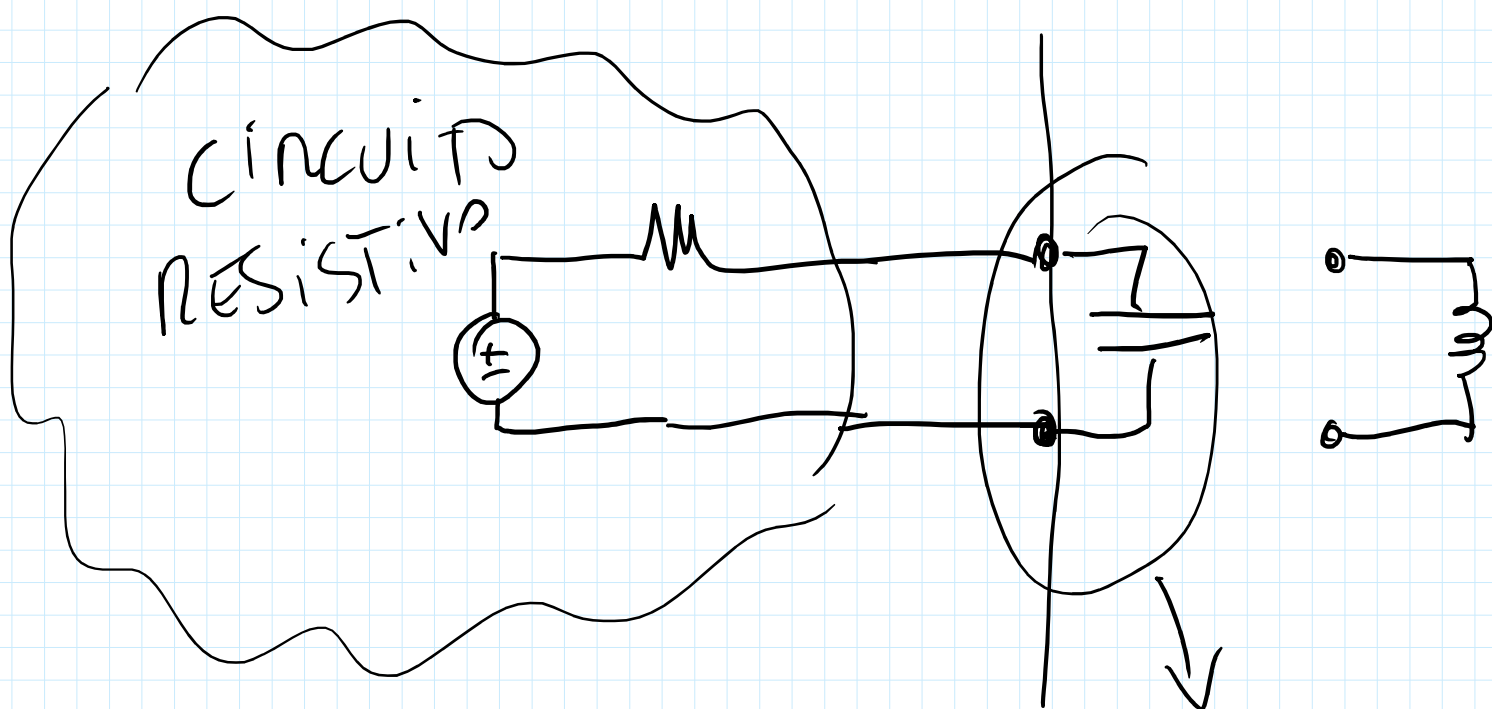
$$V_p(t) = i_A(t) \cdot R + \frac{1}{C} \int_{-\infty}^t i_A(\tau) d\tau$$

$$\dot{V}_p(t) = \dot{i}_A(t) R + \frac{1}{C_{TOT}} i_A(t)$$

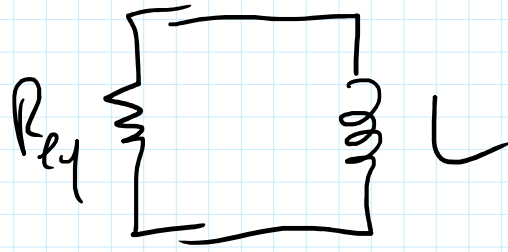
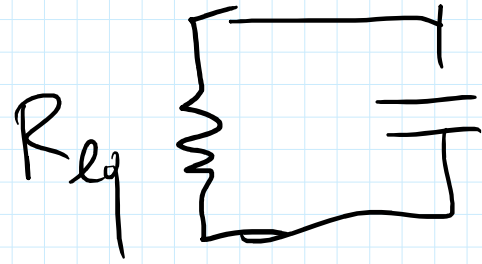
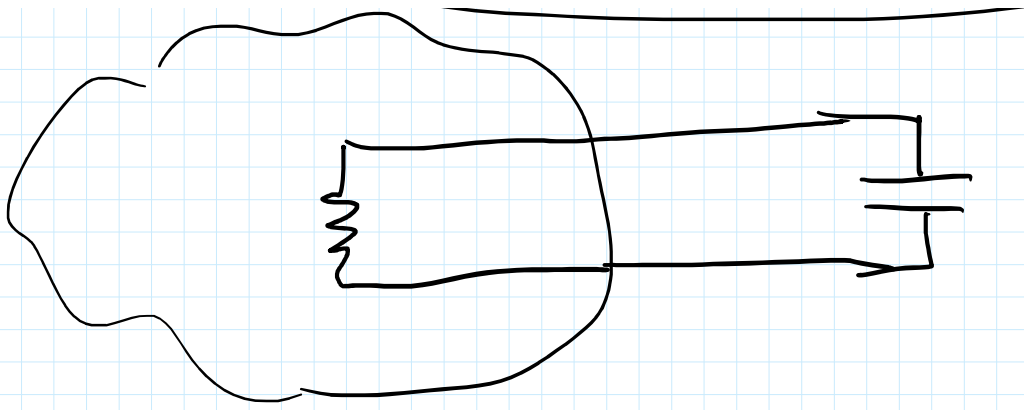


$\left\{ \begin{array}{l} I^o_{out} \\ t^a \end{array} \right\}$

$\Rightarrow \overset{0}{=} 1 \text{ SOLA EQ}$
 2^o ord.

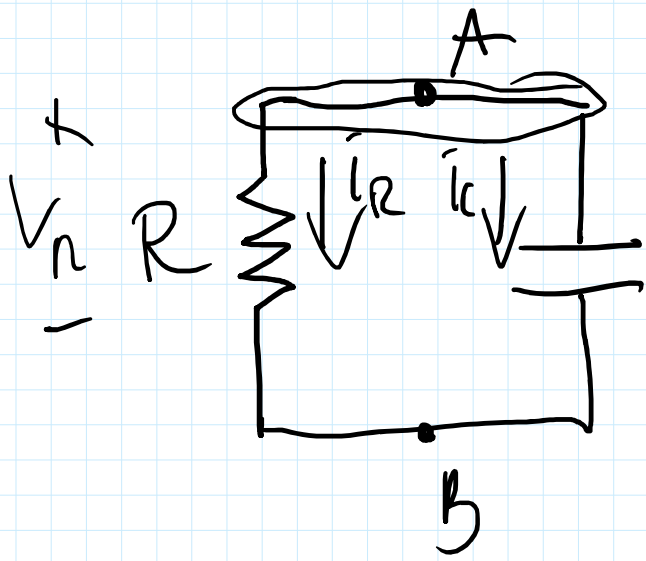


IL TRANSITORIO



RC AUTONOMO

05 April 2017 15:39



$$C \quad V_c \quad V_c(t)$$

$$KCL - \textcircled{A} \rightarrow$$

$$\hat{i}_R + \hat{i}_C = 0$$

$$\frac{V_c}{R} + C \frac{dV_c(t)}{dt} = 0$$

$$\dot{V}_c(t) = \left(-\frac{V_c}{RC} \right) \Rightarrow V_c(t) = A e^{-\frac{t}{RC}}$$

$$\frac{dV_c(t)}{dt} = -\frac{V_c(t)}{RC} \Rightarrow \int_{t_0}^{t'} \frac{dV_c(t)}{V_c(t)} = \int_{t_0}^{t'} -\frac{dt}{RC}$$

$$df(x) = dg(x)$$

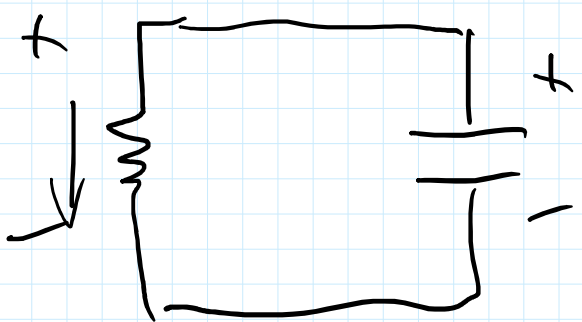
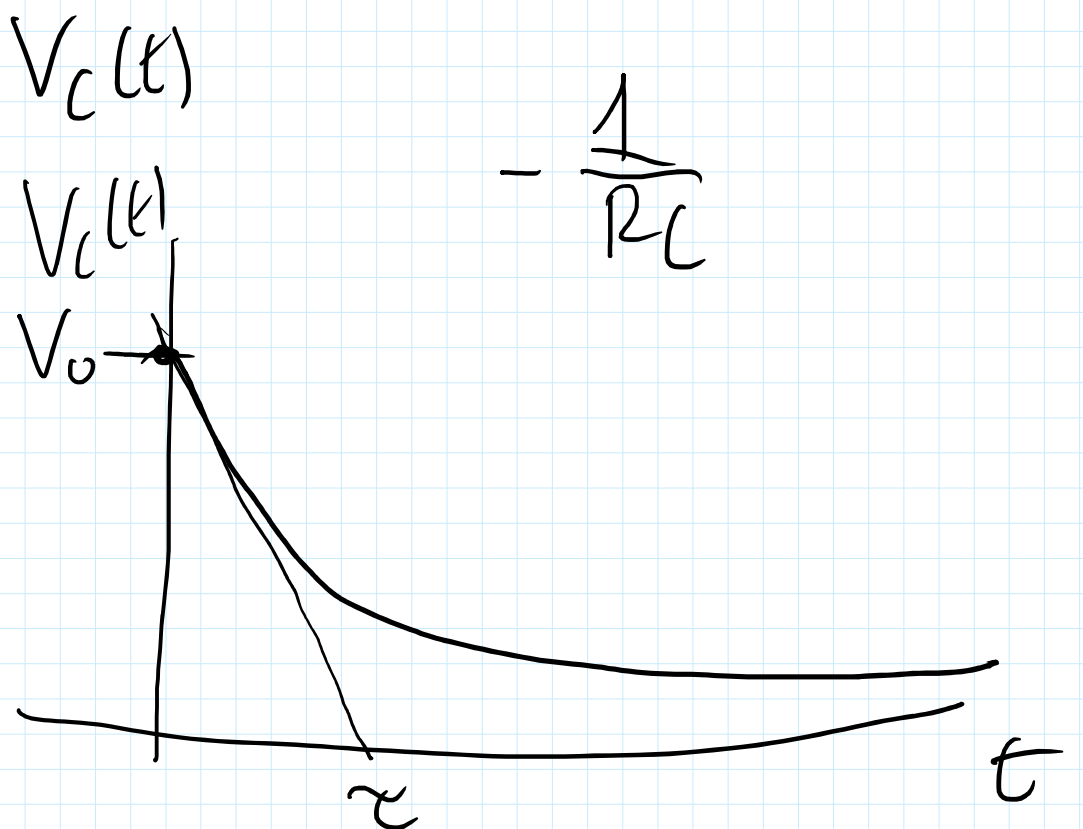
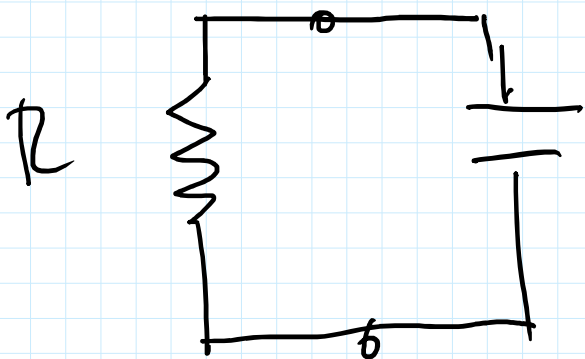
$$\int_{-\infty}^x \frac{dx}{x} = \ln y$$

$$\ln V_c(t) \Big|_{-\infty}^{t'} = -\frac{1}{RC} \int_{-\infty}^t dt$$

$$\ln V_c(t) \Big|_0^t = - \frac{t}{RC}$$

$$V_c(t) = V_0 e^{-\frac{t}{R_c}} = V_0 e^{-\frac{t}{\tau}}$$

$$\tau = RC$$



$$V_C(t) = V_0 e^{-\frac{t}{\tau}}$$

$$\frac{1}{2} C V_c^2(t) = \frac{1}{2} C V_0^2 e^{-\frac{2t}{\tau}}$$

$$P_R(t) = \frac{V_R(t)^2}{R} = \frac{V_0^2 e^{-\frac{2t}{\tau}}}{R}$$

$$v_1(t) = \dots \quad v_2(t) = \dots - \frac{2t}{\tau} \dots$$

$$W_n(t) = \int_0^t P_n(t') dt' = \frac{V_0^2}{R} \int_0^t e^{-\frac{2t'}{\tau}} dt'$$

$$= -\frac{\tau}{2} \frac{V_0^2}{R} e^{-\frac{2t'}{\tau}} \Big|_0^t$$

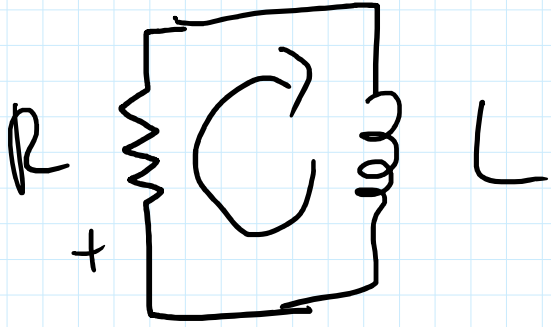
ASSONBIA

$$W_n(t) = \frac{\tau}{2} \frac{V_0^2}{R} \left[e^{-\frac{2t}{\tau}} - 1 \right]$$

$$W_n(t) = \frac{\tau}{2} \frac{V_0^2}{R} \left[1 - e^{-\frac{2t}{\tau}} \right]$$

$$t \rightarrow \infty \quad W_n(+\infty) = \frac{\tau}{2} \frac{V_0^2}{R} \quad \tau = RC$$

$$= \frac{RC}{2} \frac{V_0^2}{R} = \frac{1}{2} C V_0^2$$



$$\hat{i}_L(t)$$

$$\hat{i}_L(t) \cdot R + \underbrace{L \frac{d\hat{i}_L(t)}{dt}}_{V_L(t)} = 0$$

$$\frac{d\hat{i}_L(t)}{dt} = -\left(\frac{R}{L}\right)\hat{i}_L(t) \rightarrow \hat{i}_L(t) = \hat{i}_L(0) e^{-\frac{R}{L}t}$$

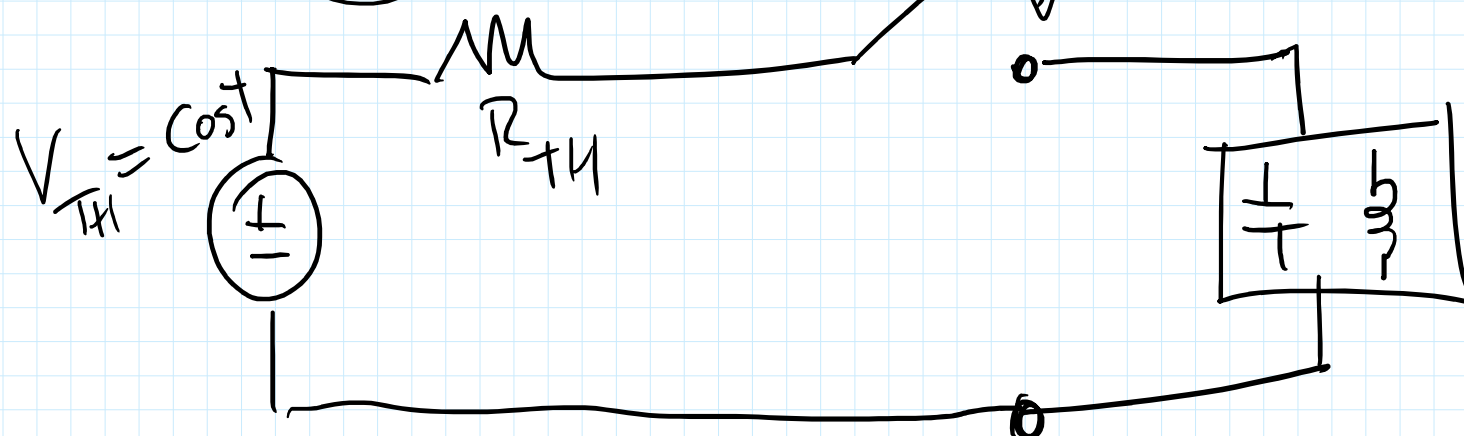
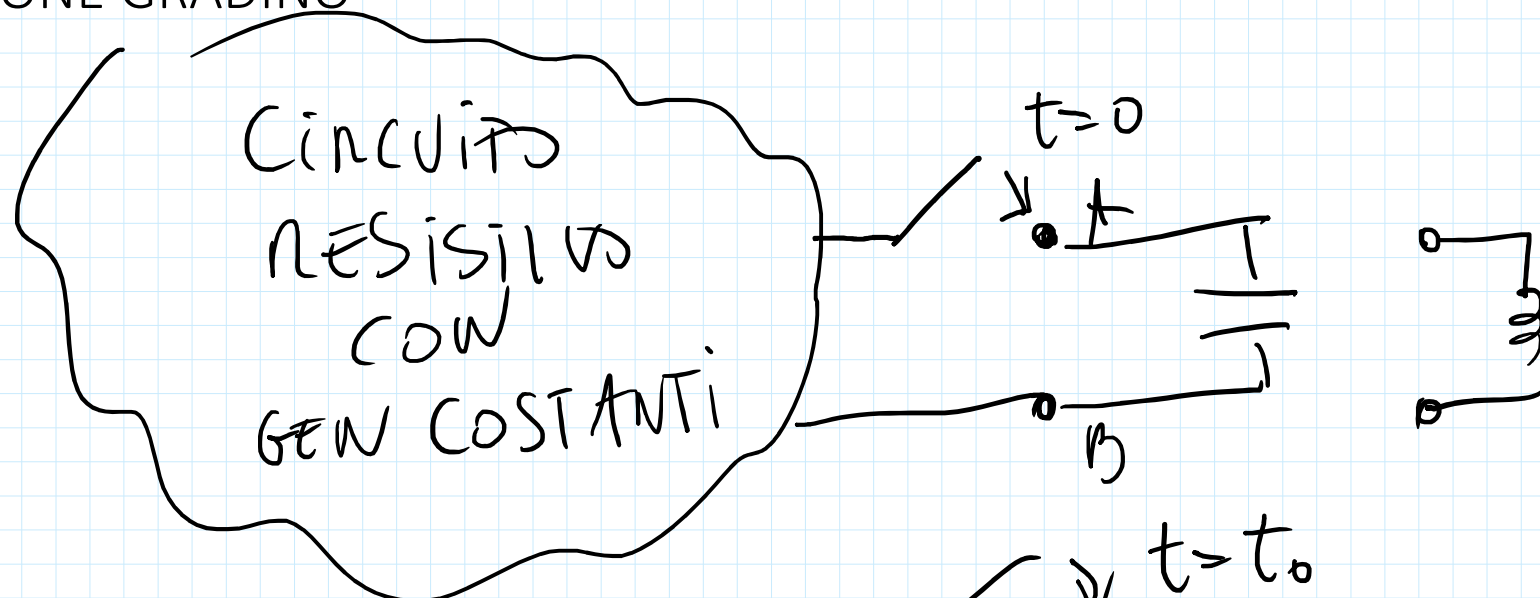
$$\frac{dV_C(t)}{dt} = -\left(\frac{1}{RC}\right)V_C(t) \rightarrow V_C(t) = V_0 e^{-\frac{t}{RC}}$$

$$\hat{i}_L(t) = \hat{i}_L(0) e^{-\frac{t}{\tau}}$$

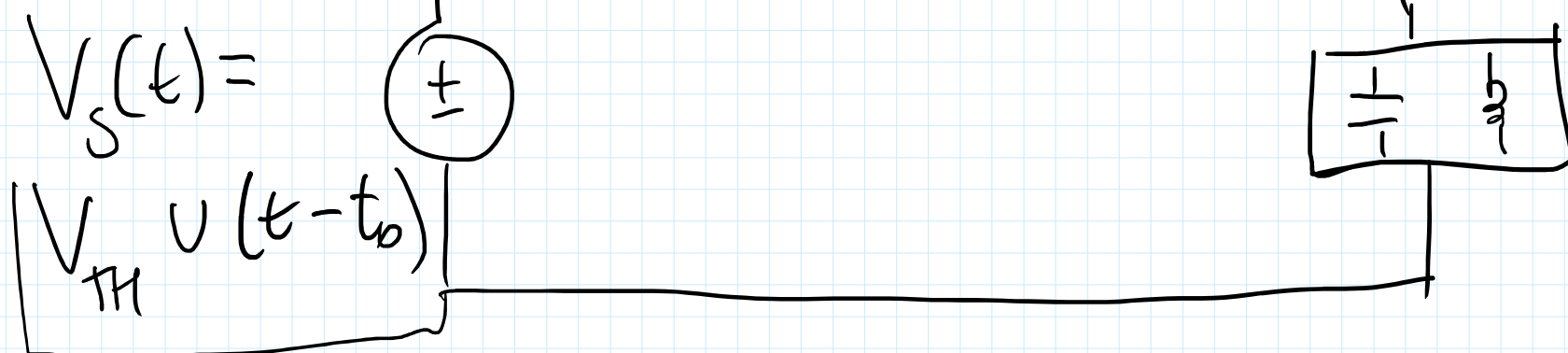
$$\tau = \frac{L}{R}$$

FUNZIONE GRADINO

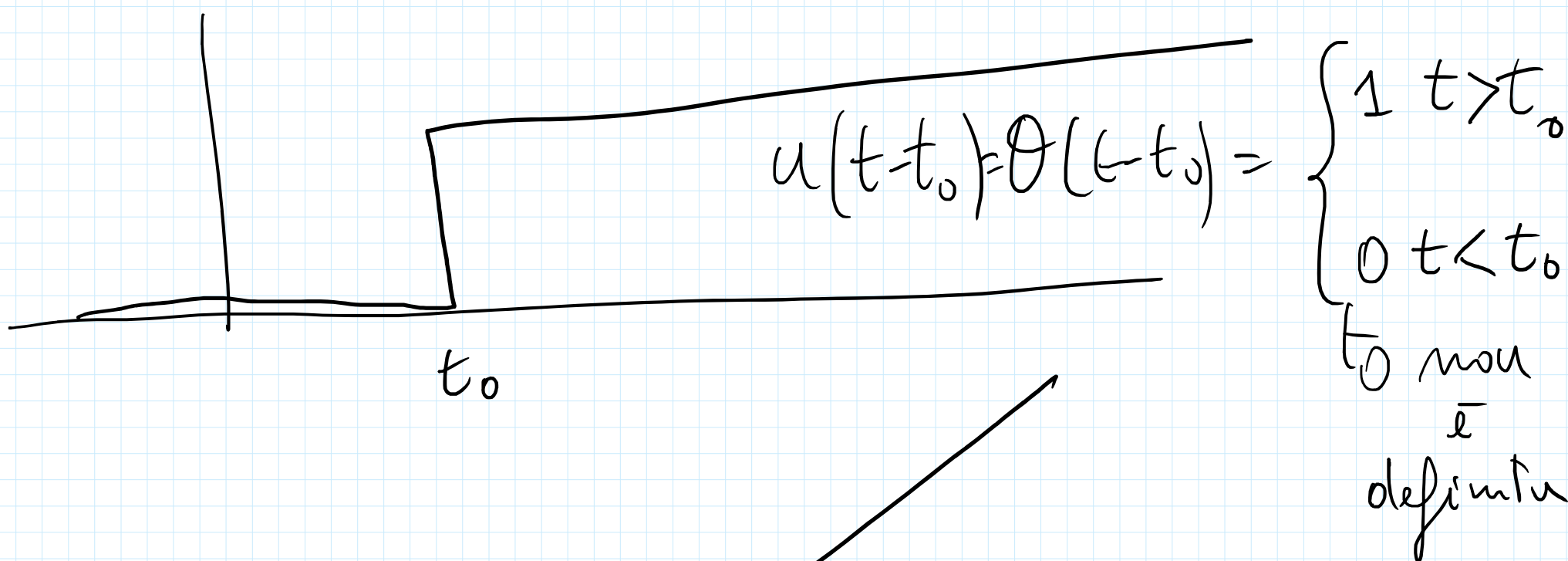
05 April 2017 16:08

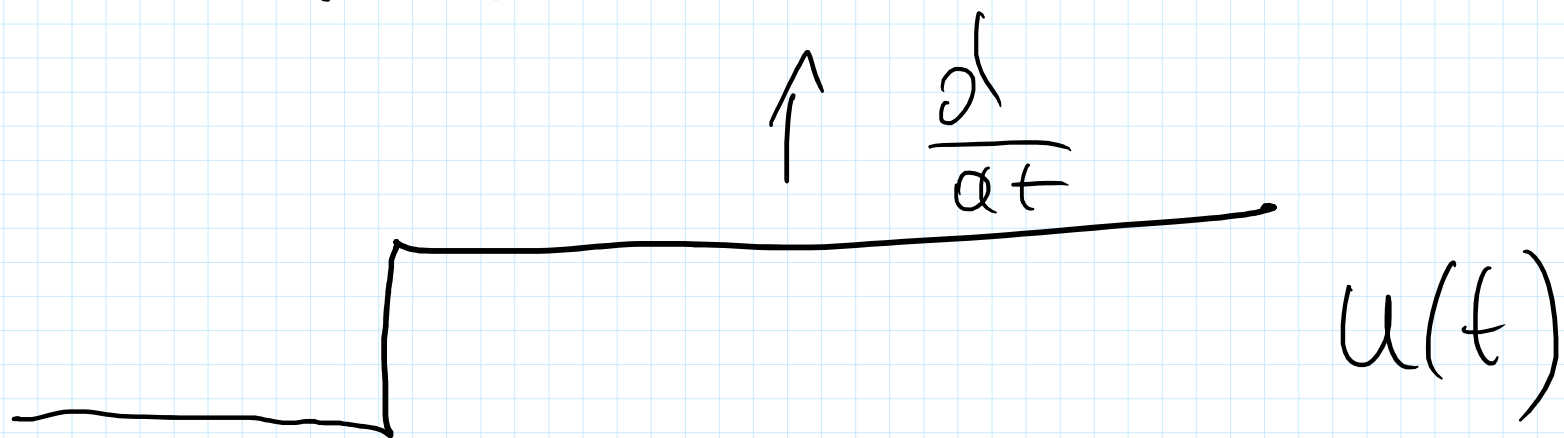
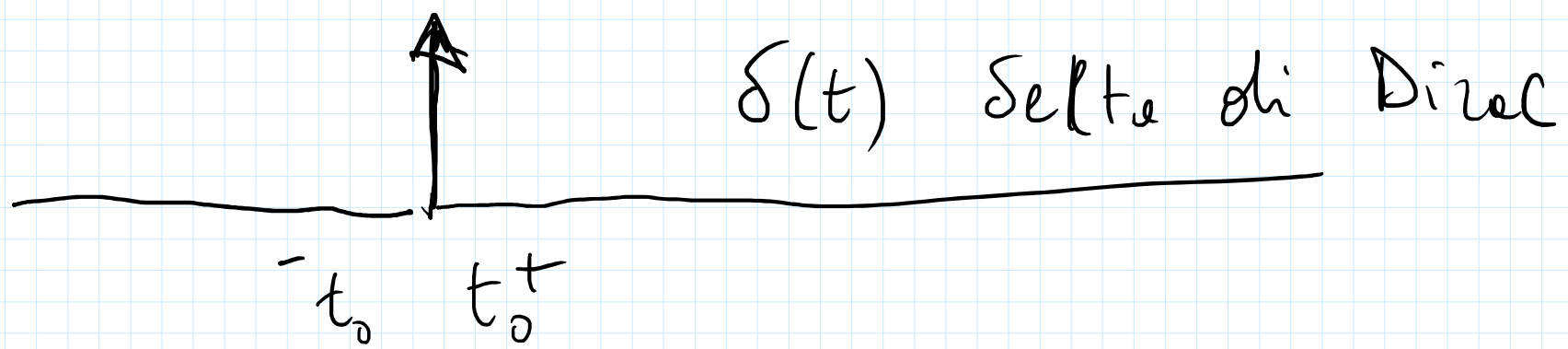


\equiv

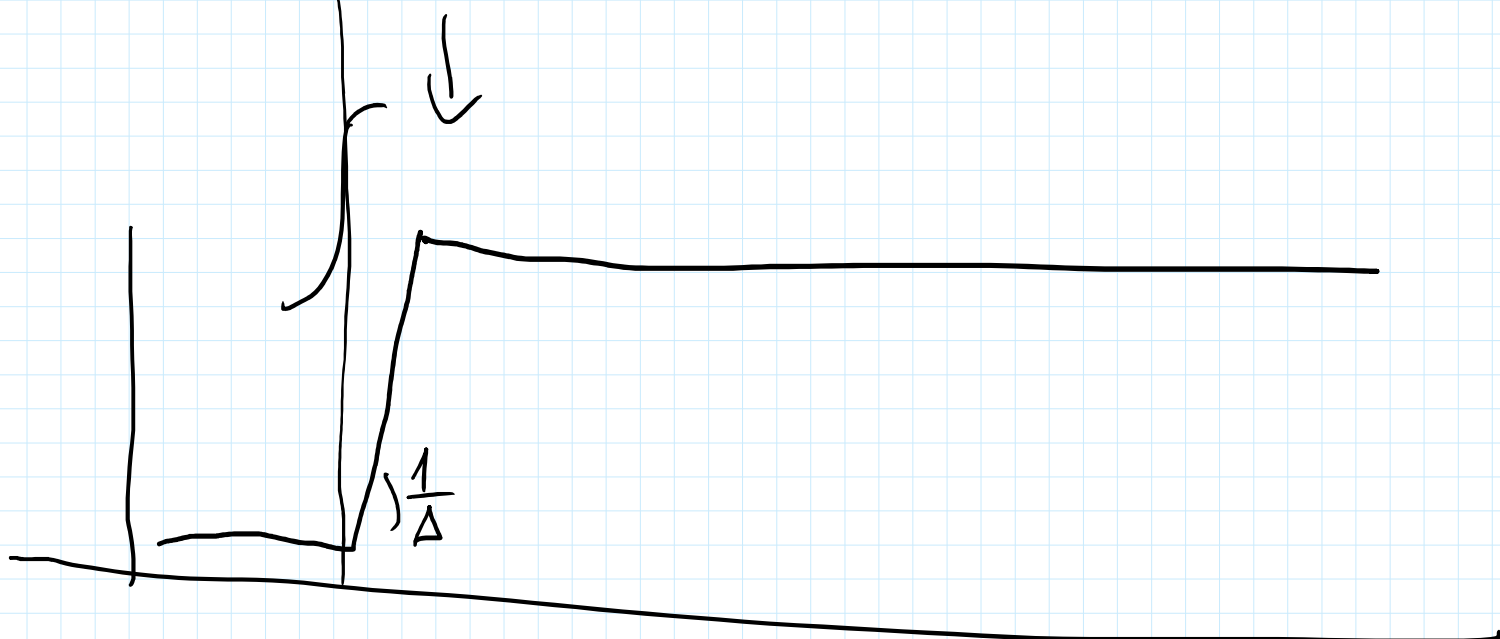
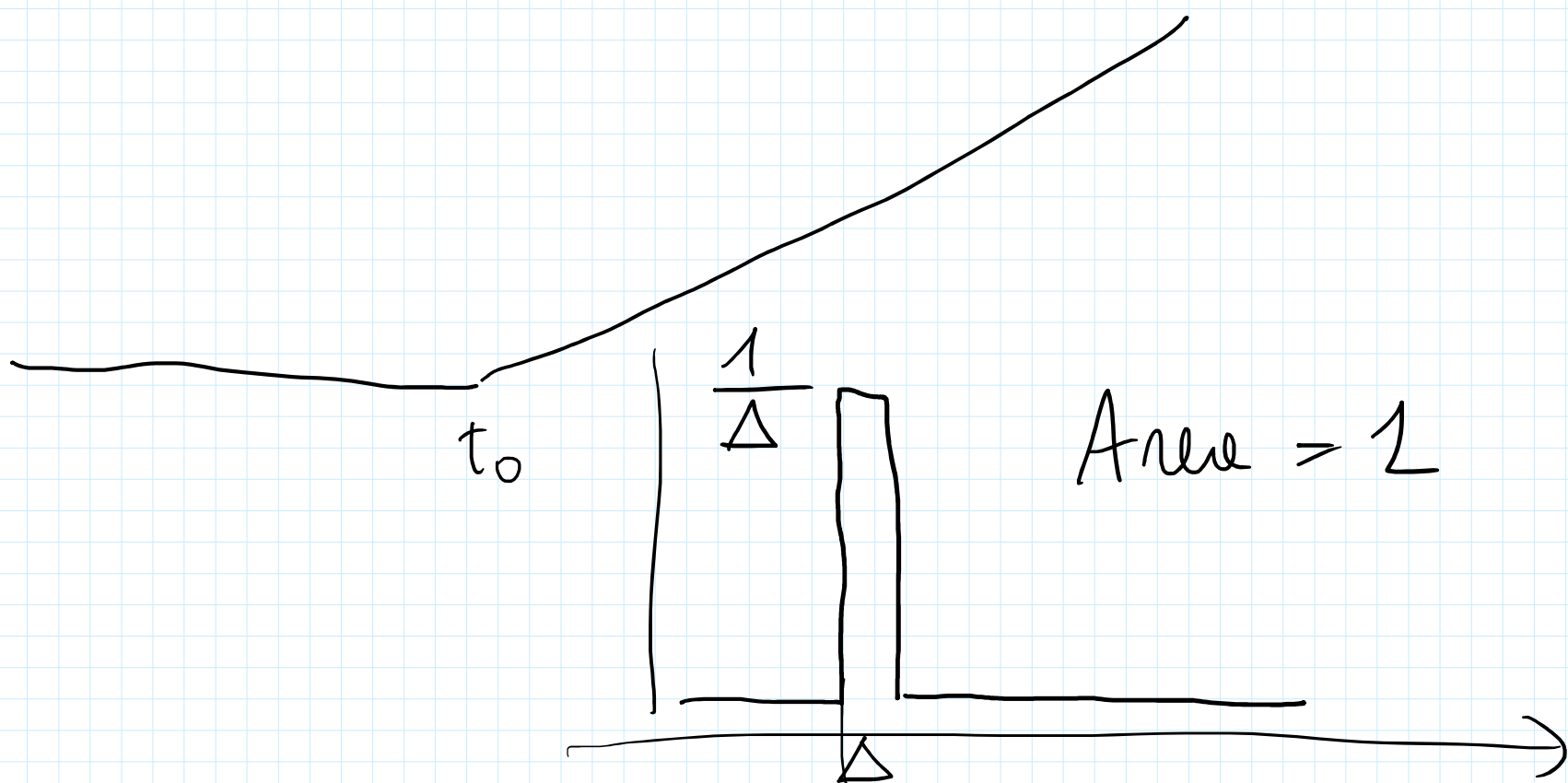


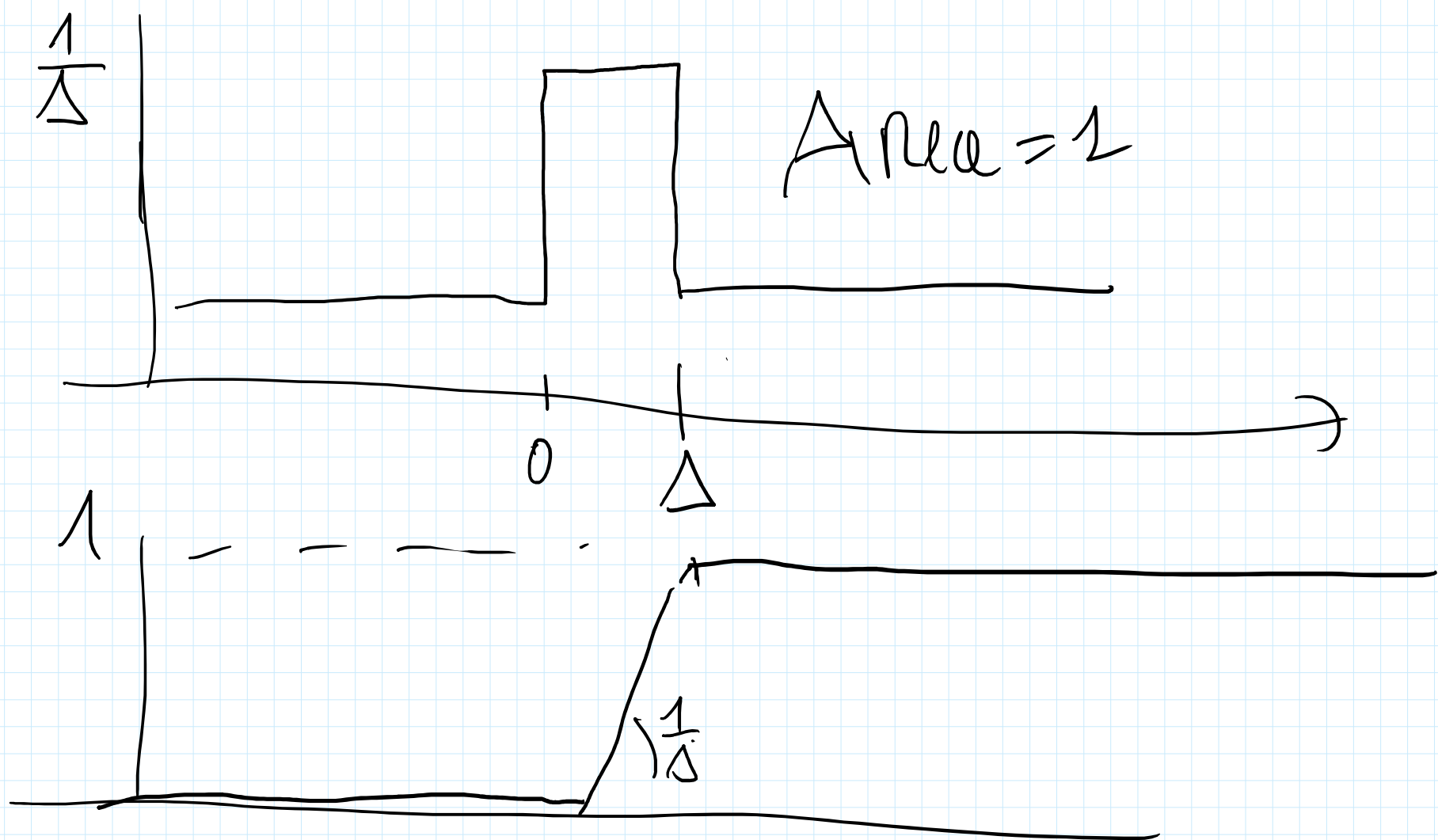
$$u(t) = \theta(t) \text{ Heaviside}$$





↓ \int





$$\lim_{\Delta \rightarrow 0}$$

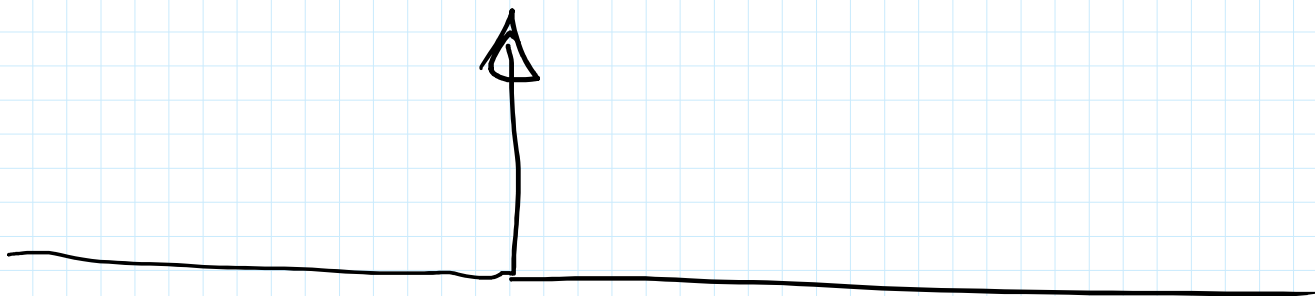
$$\delta(t) = \frac{d u(t)}{d t}$$

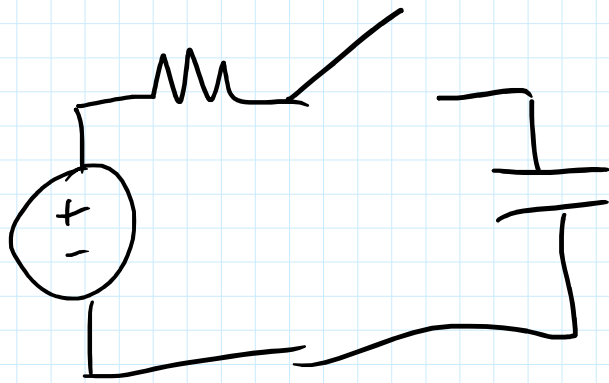
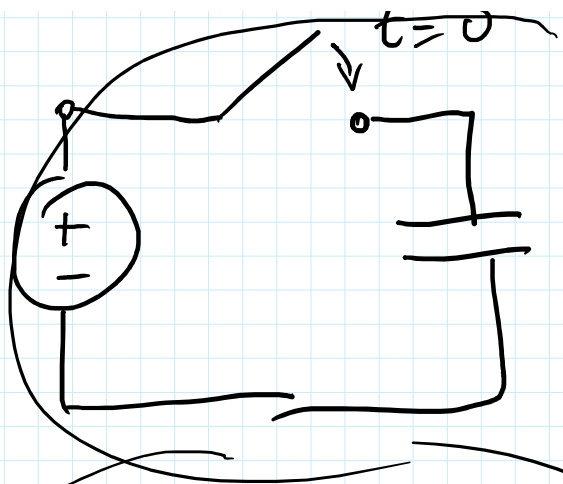
$$V_g(t) = V_0 u(t)$$

$$V_c(t) = u(t)$$

\Downarrow

$$\boxed{i_c(t) = C \frac{d V_c(t)}{d t}}$$





$$i_L(t) = i_g u(t)$$

$$V_L(t) = L \frac{di_L(t)}{dt} = L \delta(t)$$

