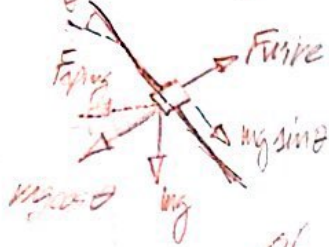


# Bead on a Tilted Wire

## Prefeitura de São Paulo

- In the equilibrium, all forces must be sum zero.



$$F_{wire} = mg \cos \theta \quad \text{negative } \theta = F_{spring, x}$$

$F_{spring} = K(H - L_0)$ , where  $H$  is the hypotenuse

of the triangle as shown

$$H = \sqrt{x^2 + a^2}$$

$$F_{spring, x} = F_{spring} \cos \theta$$

$$\text{then } K = \frac{x}{H} = \frac{x}{\sqrt{x^2 + a^2}} \Rightarrow K \cos \theta = K \frac{x}{\sqrt{x^2 + a^2}} = K \frac{x}{H}$$

$$mg \cos \theta = Kx \left( 1 - \frac{L_0}{\sqrt{x^2 + a^2}} \right) \quad \text{c.g.d.}$$

$$\frac{mg \cos \theta}{Kx} = 1 - \frac{L_0}{\sqrt{x^2 + a^2}} \Rightarrow 1 - \frac{mg \cos \theta}{Kx} = \frac{L_0}{\sqrt{x^2 + a^2}}$$

identifying  $\sqrt{1 + u^2} = \sqrt{x^2 + a^2} \Rightarrow 1 + u^2 = x^2 + a^2 \Rightarrow 1 + u^2 = x^2 + a^2 \Rightarrow x^2 = 1 + u^2 - a^2$  so  $u = \frac{x}{a}$

$$\text{then } \frac{R}{\sqrt{1 + u^2}} = \frac{L_0}{\sqrt{x^2 + a^2}} \Rightarrow \frac{R}{\sqrt{1 + \frac{x^2}{a^2}}} = \frac{L_0}{\sqrt{x^2 + a^2}} \Rightarrow R = L_0 \sqrt{\frac{a^2}{x^2 + a^2}}$$

$$R = L_0 \sqrt{\frac{x^2 + a^2}{a^2(x^2 + a^2)}} \Rightarrow R = \frac{L_0}{a} \quad \text{and finally } \frac{mg \cos \theta}{Kx} = \frac{1}{u}$$

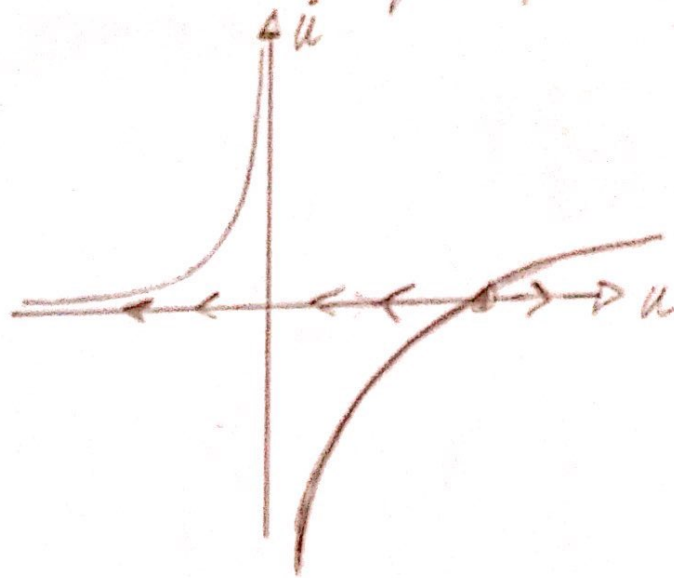
$$\frac{mg \cos \theta}{Kx} = \frac{h}{a} \Rightarrow W = \frac{mg \cos \theta}{a} \quad \text{c.g.d. so:}$$

$$1 - \frac{h}{a} = \frac{R}{\sqrt{1 + u^2}}$$

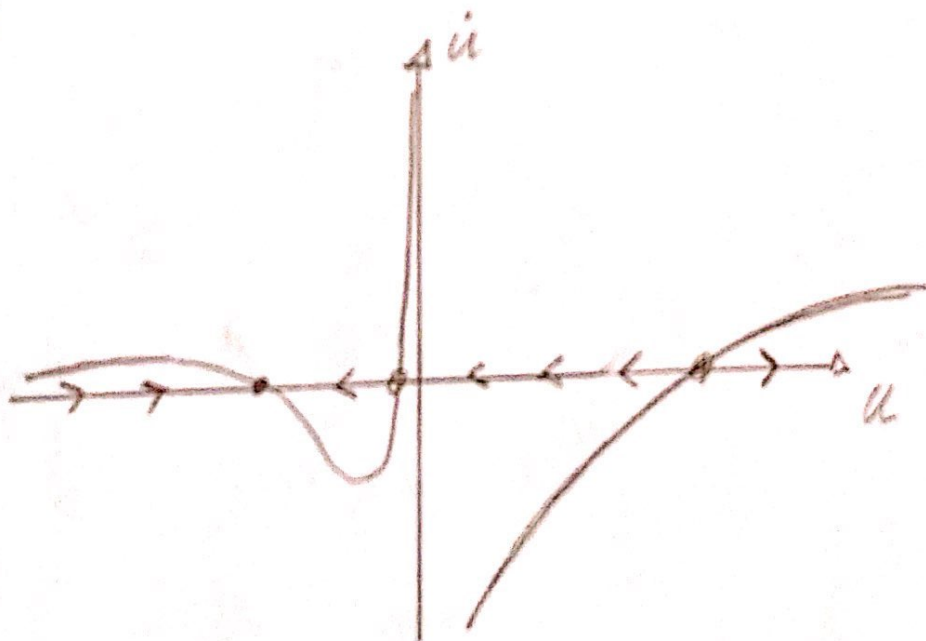
(1)

So  $u$  is the displacement from equilibrium position, the dynamical system is formulated as:  $\ddot{u} = 1 - \frac{h}{u} - \frac{R}{\sqrt{1+u^2}}$   
for simplicity we assume  $h=1$  everywhere,  $R>0$ ;

for  $R < 1$ :



for  $R > 1$ :



$h = R - 1 \Rightarrow 1 - \frac{h}{u} = \frac{u+1}{\sqrt{1+u^2}}$ , using  $\sqrt{1+u^2} \approx 1 + \frac{u^2}{2}$

$$1 - \frac{h}{u} = \frac{u+1}{1 + \frac{u^2}{2}} \Rightarrow (u-h)(1 + \frac{u^2}{2}) = u+1 \Rightarrow u + \frac{u^3}{2} - h - \frac{u^2 h}{2} = u+1$$

$$\Rightarrow h + u h - \frac{u^3}{2} + \frac{u^2 h}{2} = 0 \quad \boxed{h + u h - \frac{u^3}{2} \approx 0} \quad (2)$$

$$\bullet \quad h + ur - \frac{u^3}{2} \approx 0 \rightarrow \frac{d}{du} \left( h + ur - \frac{u^3}{2} \right) = r - \frac{3}{2}u^2 = 0$$

$$\boxed{u^* = \pm \sqrt{\frac{2}{3}r}} \rightarrow h(u^*) = -r + \sqrt{\frac{2}{3}r} + \frac{1}{2} \left( \frac{u^3}{3} \right) \approx h$$

$$\boxed{h(u^*) = \pm \sqrt{\frac{2}{3}r^3}}$$

$$= \pm \sqrt{\frac{2r}{3}} \left( -r + \frac{r}{3} \right) = \pm \sqrt{\frac{2r}{3}} \left( -\frac{2r}{3} \right)$$

•  $h$  is the relative displacement of the head due to its own weight component.  $r$  is the relative displacement of the head to the initial length of the spring. For the approximation to small values of  $h, r, u$  shows a saddle-node bifurcation what means, it is a stable equilibrium to the original position. Being necessary a greater force perpendicular to the wire to take the head off the equilibrium point. Only with higher perpendicular forces the head will move greater in the wire plane.

• Extra Band:

(3)