

Accelerator Triggered Communication

Jim Dinan, NVIDIA Hybrid & Accelerator WG MPI Forum Virtual Meeting February 16, 2022

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MPI FORUM HYBRID & ACCELERATOR WORKING GROUP

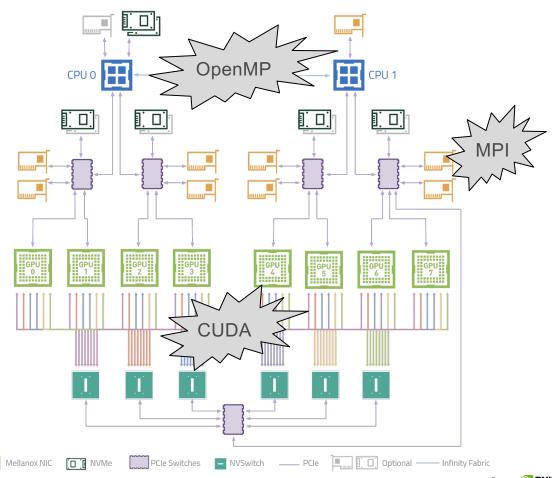
Goal: Integrate MPI communication with accelerator programming models

Why: Modern architectures require MPI + X + Y

- e.g. OpenMP, CUDA, HIP, OpenACC, etc.
- Transitions between programming models incur significant overheads (e.g. synchronization)
- Or expose overheads we want to hide, e.g. loss of pipelining to hide offload overheads

Active integration topics for MPI 4.1:

- 1. Stream and graph triggering
- 2. Kernel triggering using partitioned comms



CPU-INITIATED API CHALLENGES

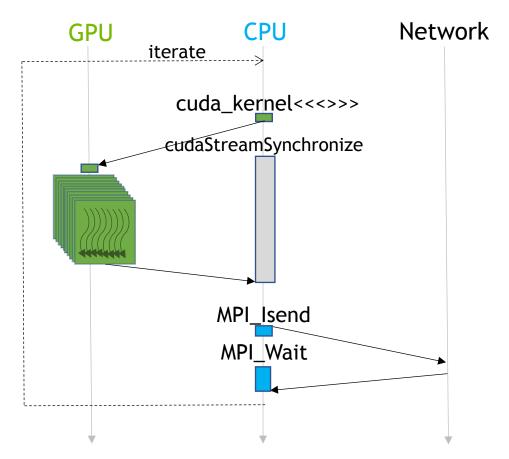
Offloading Overheads and Communication are Exposed

- Compute on GPU
- Communication from CPU
- Synchronization at boundaries

Commonly used model, but -

- Offload latencies in critical path
- Communication is not overlapped

Hiding increases code complexity, Not hiding limits strong scaling



STREAM TRIGGERED COMMUNICATION

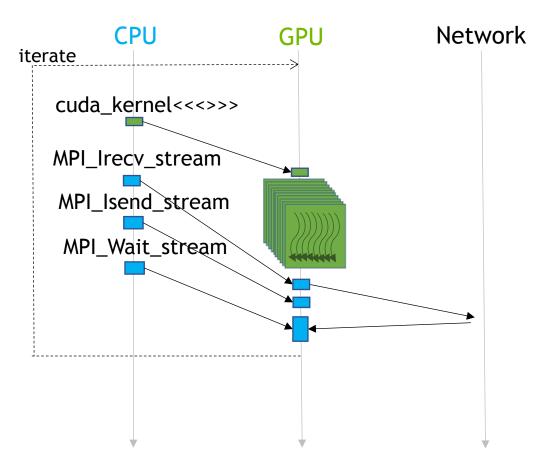
Hides offloading overheads

Eliminates transfer of control between CPU and GPU

"Triggering" avoids running MPI progress engine on the accelerator

Communication on streams can be recorded and embedded in graphs

Computation and communication are distinct tasks, don't naturally overlap



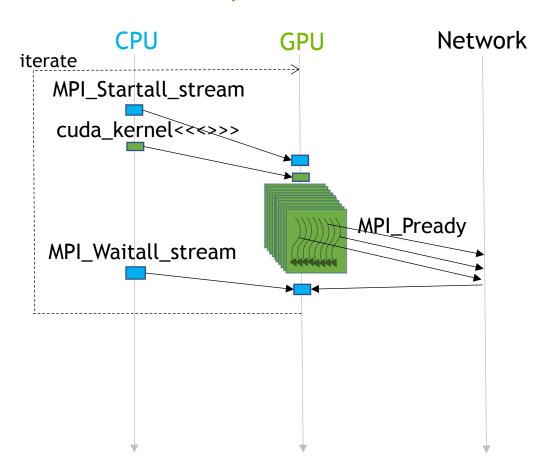
Overlaps Communication and Computation

Use MPI-4 partitioned communication to trigger communication from kernel

Stream-based start/wait eliminates offloading overheads

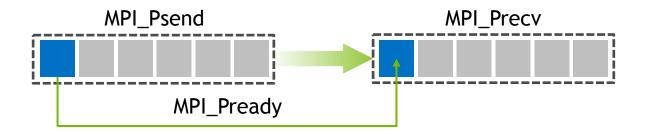
Marking partitions as ready overlaps computation and communication

Communication on streams can be recorded and embedded in graphs



ACCELERATOR TRIGGERED COMMUNICATION

Using the MPI 4.0 Persistent Partitioned Communication API



Send/Recv data buffers are broken into equal-sized partitions

- MPI_Pready: mark partition as ready to send
- MPI_Parrived: query if partition has arrived

Partitioned operations match once in own matching space based on order of init calls

Extending to accelerators: language bindings for accelerator models (unify if possible)

CUDA BINDINGS FOR MPI PARTITIONED APIS

```
int MPI Psend init(const void *buf, int partitions, MPI Count count,
                    MPI Datatype datatype, int dest, int tag, MPI Comm comm, MPI Info info,
                    MPI Request *request)
int MPI Precv init(void *buf, int partitions, MPI Count count,
                    MPI Datatype datatype, int source, int tag, MPI Comm comm, MPI Info info,
                    MPI Request *request)
                                                                                                 Host
int MPI [start,wait][ all](...)
                                                                                           Host + Stream
                                                                                                Device
  device int MPI Pready(int partition, MPI Request request)
  device int MPI Pready range(int partition low, int partition high, MPI Request request)
  device int MPI Pready list(int length, const int array of partitions[], MPI Request request)
 device int MPI Parrived(MPI Request request, int partition, int *flag)
```

Partitioned Neighbor Exchange

Host Code Device Code MPI_Request req[2]; MPI_Prequest preq; MPI Psend init(..., &req[0]); MPI Precv init(..., &req[1]); MPI Prequest create(req[0], MPI INFO NULL, &preq); while (...) { global kernel(..., MPI Prequest preq) { MPI Startall(2, req); int i = my partition(...); kernel<<<..., s>>>(..., preq); // Compute and fill partition i cudaStreamSynchronize(s); // then mark i as ready MPI Waitall(2, req); MPI Pready(i, preq); MPI Prequest free(&preq); MPI Request free(&req[0]); All partitions must be marked ready before calling wait MPI Request free(&req[1]);

MPI REQUEST OBJECTS IN DEVICE CONTEXT

MPI handle must be valid in the device context

Internal MPI state must be accessible by device (e.g. device, pinned host memory)

Option 1: Unified Virtual Memory

- Allocate MPI object in managed memory, accessible to host/device, handle value is unified pointer
 - Pages containing MPI requests migrate on access by host/device, or can set cudaMemAdviseSetPreferredLocation to avoid migration
 - Alternatively, MPI can update requests in start call and then migrate to the device via cudaMemAdviseSetReadMostly

Option 1.5: Unified Virtual Addressing

- - Lives in pinned host memory, which adds PCIe access latency from GPU

Option 2: Export request handle to the device, handle value is device pointer

- Export operation sets up MPI request so it can be accessed by device
- Improves portability
- Can optimize the MPI request object for access from the device

REQUEST EXPORT

```
int MPI_Prequest_create(MPI_Request req, MPI_Info info, MPI_Prequest *preq);
int MPI_Prequest_free(MPI_Prequest *preq);
MPI_PREQUEST_NULL
```

- Prequest object is valid on device in and MPI_Prequest_free
- The MPI Prequest object is created for use by the currently selected device
 - MPI_Request must be in the non-started state
 - Can optionally use the info argument to specify the device
- MPI_Prequest for an MPI_Psend operation may contain:
 - libibverbs: Pointer to list of pre-prepared RDMA write WQEs, pointer to QP (SQ, DBR, DB)
 - libfabric: Reference to event counters with associated triggered send operations
- MPI_Prequest for an MPI_Precv operation may contain:
 - Pointer to flags in device memory
- Starting req also starts any pregs that were created on req
 - E.g. posts triggered operations to the NIC



DEVICE READY

```
__device__ int MPI_Pready(MPI_Prequest prequest, int partition)

__device__ int MPI_Pready_range(int part_low, int part_high, MPI_Prequest prequest)

__device__ int MPI_Pready_list(int length, const int array_of_partitions[], MPI_Prequest prequest)
```

- MPI_Pready operation may involve
 - peer-to-peer: memcpy (e.g. PCle or NVLink)
 - ibverbs: Copy pre-prepared WQE to SQ and ring doorbell
 - libfabric: Increment event counter
- Allow functions to be inlined
- Allow for functions with thread granularity (e.g. warp/block) to optimize memcpy's
- Could replace __device__ with a generic thing like MPI_DEVICE_QUALIFIER

DEVICE ARRIVED

__device__ int MPI_Parrived (MPI_Prequest prequest, int partition, int *flag)

- MPI_Parrived operation may involve
 - peer-to-peer: Checking a flag
 - libibverbs: Polling a CQ
 - libfabric: Checking an event counter
- Allow functions to be inlined
- Allow for functions with thread granularity (e.g. warp/block) to optimize memcpy's
 - E.g., When using a receiver copys protocol
- Q: Should we return an MPI error code?
 - What can the device do with it?
 - Hand it back to the CPU, to be dealt with with the next operation on the request.

Partitioned Neighbor Exchange

Host Code Device Code MPI_Request req[2]; MPI_Prequest preq; MPI Psend init(..., &req[0]); MPI Precv init(..., &req[1]); MPI Prequest create(req[0], MPI INFO NULL, &preq); while (...) { global kernel(..., MPI Prequest preq) { MPI Startall(2, req); int i = my partition(...); kernel<<<..., s>>>(..., preq); // Compute and fill partition i cudaStreamSynchronize(s); // then mark i as ready MPI Waitall(2, req); MPI Pready(i, preq); MPI Prequest free(&preq); MPI Request free(&req[0]); All partitions must be marked ready before calling wait MPI Request free(&req[1]);

Partitioned Neighbor Exchange

Host Code Device Code MPI_Request req[2]; MPI_Prequest preq; MPI Psend init(..., &req[0]); MPI Precv init(..., &req[1]); MPI Prequest create(req[0], MPI_INFO_NULL, &preq); while (...) { global kernel(..., MPI Prequest preq) { MPI Startall_enqueue(2, req, ..., s); int i = my partition(...); kernel<<<..., s>>>(..., preq);-// Compute and fill partition i - cudaStreamSynchronize(s); // then mark i as ready MPI Waitall enqueue(2, req, ..., s); MPI Pready(i, preq); MPI Prequest_free(&preq); MPI Request free(&req[0]); On-stream operations eliminate MPI Request free(&req[1]); stream synchronization

Kernel Calls MPI_Parrived

Host Code

MPI_Request req[2]; MPI_Prequest preq; MPI_Psend_init(..., &req[0]); MPI_Precv_init(..., &req[1]); MPI_Prequest_create(req[0], ..., &preq); while (...) { MPI_Startall_enqueue(2, req, ..., s); sender<<<..., s>>>(..., preq); receiver<<<..., s>>>(..., preq); MPI_Waitall_enqueue(2, req, ..., s); } MPI_Prequest free(&preq);

MPI_Request_free(&req[0]);
MPI Request free(&req[1]);

Device Code

```
global sender(..., MPI Prequest preq) {
 int i = my partition(...);
 sender_compute(..., i);
 MPI_Pready(i, preq);
 global receiver(..., MPI Prequest preq) {
 int arrived;
 int i = my partition(...);
 do {
   MPI_Parrived(preq, i, &arrived);
 } while (!arrived);
 receiver compute(..., i);
```

DISCUSSION

Protocol Challenges With Partitioned API

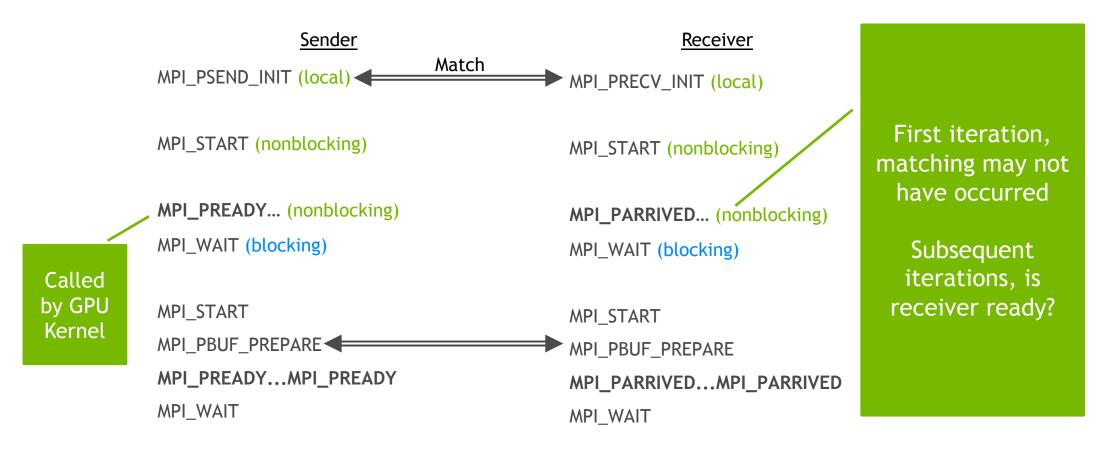
Protocol challenges:

- Establishing the half channel: matching psend with precv
- Determining if receiver is ready

Design goal: Accelerator should not need to interact with the MPI progress engine

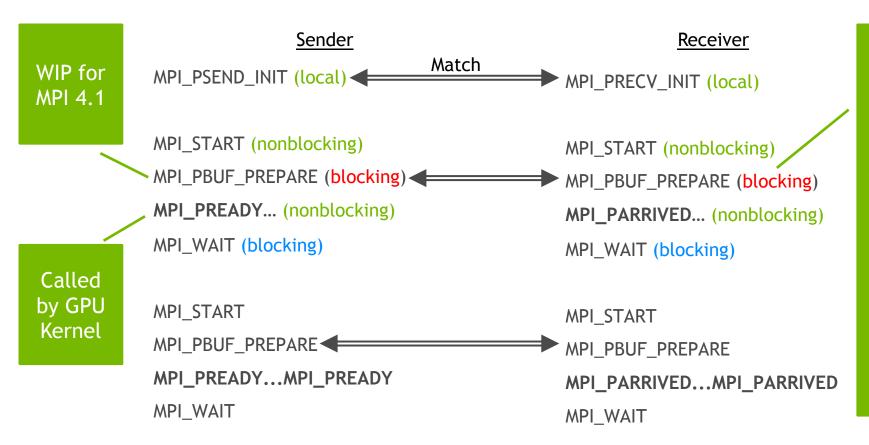
SENDER/RECEIVER INTERACTION

Protocol Challenges



SENDER/RECEIVER INTERACTION

Buffer Preparation Step



First iteration, resolves matching

Subsequent iterations, ensures receiver is ready

Fully resolves control plane, allowing sender GPU to issue RDMA write operations

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Discussion

Partitioned communication API incorporated in MPI 4.0

Partitioned communication provides a path to kernel triggered communication

- CUDA and SYCL language extensions for MPI_Pready and MPI_Parrived
- Proposed partitioned buffer preparation function to advance protocols
 - Collapse send/recv to RDMA and memcpy

Steam/Graph integration is under active discussion

"Greatest Common Denominator" approach

Thank you!

Wednesdays 10-11am US Eastern Time

https://github.com/mpiwg-hybrid/hybrid-issues/wiki