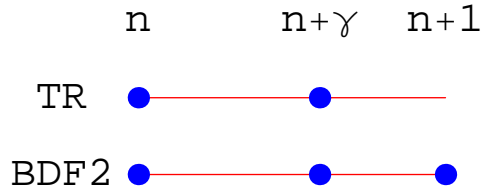


## TRBDF2

R. E. Bank, W. M. Coughran, W. Fichtner, E. H. Grosse, D. J. Rose, and R. K. Smith, “Transient Simulation of Silicon Devices and Circuits,” *IEEE Transactions on Computer-Aided Design*, **CAD-4**, 436–451, 1985.

M. J. Johnson and C. L. Gardner, “An Interface Method for Semiconductor Process Simulation,” in *Semiconductors*, IMA Volumes in Mathematics and its Applications, Volume 58, pp. 33–47. New York: Springer-Verlag, 1993.



To integrate  $du/dt = f(u)$  from  $t = t_n$  to  $t_{n+1} = t_n + \Delta t$ , we first apply the trapezoidal rule (TR) to advance the solution from  $t_n$  to  $t_{n+\gamma} = t_n + \gamma\Delta t$ :

$$u_{n+\gamma} - \gamma \frac{\Delta t}{2} f_{n+\gamma} = u_n + \gamma \frac{\Delta t}{2} f_n, \quad (1)$$

and then use the second-order backward differentiation formula (BDF2)<sup>1</sup> to advance the solution to  $t_{n+1}$ :

$$u_{n+1} - \frac{1-\gamma}{2-\gamma} \Delta t f_{n+1} = \frac{1}{\gamma(2-\gamma)} u_{n+\gamma} - \frac{(1-\gamma)^2}{\gamma(2-\gamma)} u_n. \quad (2)$$

This composite one-step method is second-order accurate and L-stable.

We linearize  $f_{n+1}$  in Eq. (2) (and similarly  $f_{n+\gamma}$  in Eq. (1)) iteratively by setting the new iterative solution to

$$u_{n+1}^{(k+1)} = u_{n+1}^{(k)} + \delta u^{(k)}, \quad u_{n+1}^{(0)} = u_{n+\gamma} \quad (3)$$

and approximating

$$f_{n+1}^{(k+1)} = f_{n+1}^{(k)} + \left( \frac{\partial f}{\partial u} \right)_{n+1}^{(k)} \delta u^{(k)} \quad (4)$$

---

<sup>1</sup>For BDF2,  $e_l \approx -\frac{(1-\gamma)^2}{6(2-\gamma)} \Delta t^3 u'''$ .

where  $k = 0, 1, \dots$  labels the Newton iterations. At each TR or BDF2 partial step, we iterate until the Newton method converges.

The Newton equation for the TR partial step is

$$\left[ I - \gamma \frac{\Delta t}{2} \left( \frac{\partial f}{\partial u} \right)_{n+\gamma}^{(k)} \right] \delta u^{(k)} = - \left( u_{n+\gamma}^{(k)} - u_n \right) + \gamma \frac{\Delta t}{2} \left( f_{n+\gamma}^{(k)} + f_n \right) \equiv -R_{\text{TR}} \quad (5)$$

where  $R_{\text{TR}}$  is the residual for Eq. (1).

The Newton equation for the BDF2 partial step is

$$\begin{aligned} & \left[ I - \frac{1-\gamma}{2-\gamma} \Delta t \left( \frac{\partial f}{\partial u} \right)_{n+1}^{(k)} \right] \delta u^{(k)} = \\ & - \left( u_{n+1}^{(k)} - \frac{1}{\gamma(2-\gamma)} u_{n+\gamma} + \frac{(1-\gamma)^2}{\gamma(2-\gamma)} u_n \right) + \frac{1-\gamma}{2-\gamma} \Delta t f_{n+1}^{(k)} \equiv -R_{\text{BDF2}} \end{aligned} \quad (6)$$

where  $R_{\text{BDF2}}$  is the residual for Eq. (2).

The timestep size  $\Delta t$  is adjusted dynamically within a window  $[\Delta t_{\min}, \Delta t_{\max}]$  by monitoring a divided-difference estimate of the local error  $e_l$ :

$$e_l = k_\gamma \Delta t^3 u''' \quad (7)$$

$$\approx 2k_\gamma \Delta t \left( \frac{1}{\gamma} f_n - \frac{1}{\gamma(1-\gamma)} f_{n+\gamma} + \frac{1}{1-\gamma} f_{n+1} \right), \quad (8)$$

where

$$k_\gamma = \frac{-3\gamma^2 + 4\gamma - 2}{12(2-\gamma)}. \quad (9)$$

The three values of  $f$  employed in Eq. (8) have already been calculated in the most recent TRBDF2 timestep. The  $\|e_l\|$  is minimized for  $\gamma = 2 - \sqrt{2}$ .

## A-stability and L-stability

A time integration method for  $du/dt = au$  ( $\text{Re}\{a\} < 0$ ) is **A-stable** if

$$\frac{\|u_{n+1}\|}{\|u_n\|} = \|G\| \leq 1 \quad (10)$$

for all  $\Delta t > 0$ . A time integration method for  $du/dt = au$  ( $\text{Re}\{a\} < 0$ ) is **L-stable** if it is A-stable and

$$\lim_{\Delta t \rightarrow \infty} \frac{\|u_{n+1}\|}{\|u_n\|} = \lim_{\Delta t \rightarrow \infty} \|G\| = 0. \quad (11)$$

TR is A-stable, but not L-stable. Backward Euler (first- and second-order) and TRBDF2 are L-stable.

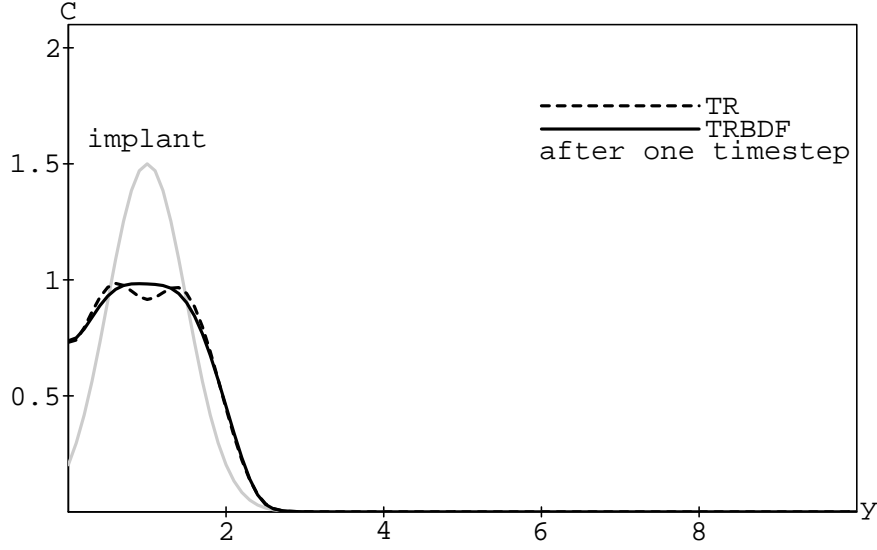


Figure 1: Simulation of nonlinear diffusion in semiconductor processing with a large  $\Delta t$ .

The growth factor  $G$  for TRBDF2 for  $du/dt = -\alpha u$ ,  $\alpha > 0$  is given by ( $\Delta \equiv \gamma\alpha\Delta t > 0$ ):

$$G(\Delta t, \gamma) = \frac{\frac{1 - \frac{\gamma\alpha\Delta t}{2}}{1 + \frac{\gamma\alpha\Delta t}{2}} - (1 - \gamma)^2}{\gamma(2 - \gamma) + \gamma(1 - \gamma)\alpha\Delta t} = \frac{\frac{2 - \Delta}{2 + \Delta} - (1 - \gamma)^2}{\gamma(2 - \gamma) + (1 - \gamma)\Delta}.$$

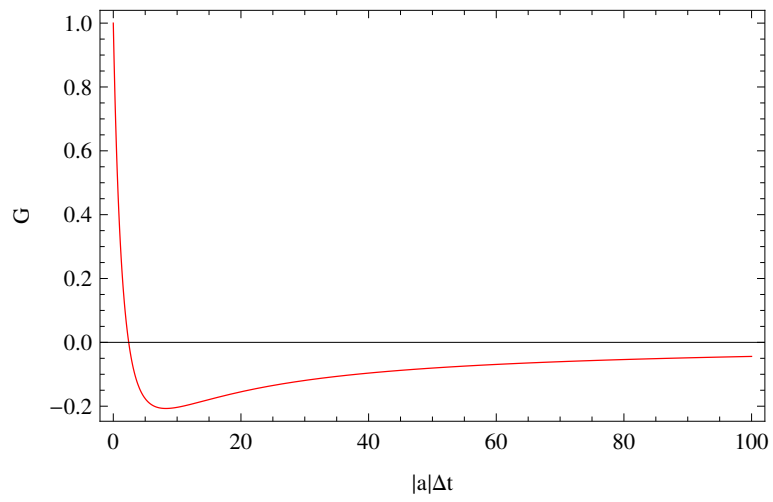


Figure 2:  $G_{TRBDF2}$  as a function of  $|a|\Delta t$  for  $\gamma = 2 - \sqrt{2}$ .