## Network And Circuits Theory Second Assignment 2019-2020

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21-05-2020

### 1 Exercise One

E

1 R1
2 kv 5 R2 6 L2
Fundamental Separation Group
bi

taking into account that

$$i = i_{L2} \tag{1}$$

$$v = E_s - (I_{L1} + I_{L2})R1 (2)$$

From the conservation of current on the fundamental separation group, and from Kirchoffs voltage law across the two fundamental loops we have

$$I_{L1} + I_{L2} = C\dot{V_C} + bI_{L2} \tag{3}$$

$$(E_s - (I_{L1} + I_{L2})R1)(k-1) + I_{L2}(R3 + R2) + L2\dot{I}_{L2} + V_C = 0$$
(4)

$$(E_s - (I_{L1} + I_{L2})R1) + I_{L1}R3 + L1\dot{I}_{L1} + V_C = 0$$
(5)

Organizing matrix format we get

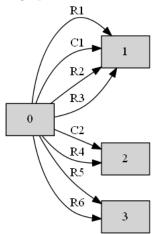
$$\dot{x}(t) = \begin{pmatrix} 0 & \frac{1}{C} & \frac{1-b}{C} \\ -\frac{1}{L2} & \frac{R1-R3}{L1} & \frac{R1}{L1} \\ -\frac{1}{L2} & \frac{(k-1)R1}{L2} & \frac{(k-1)R1-R2-R3}{L2} \end{pmatrix} \begin{pmatrix} x(t) & B \\ V_C(t) \\ I_{L1}(t) \\ I_{L2}(t) \end{pmatrix} + \begin{pmatrix} 0 \\ \frac{-1}{L1} \\ -\frac{(k-1)}{L2} \end{pmatrix} (E_s(t))$$

and

$$y(t) = \begin{pmatrix} C & x(t) \\ 0 & 0 & b \\ 0 & -R1 & -R1 \end{pmatrix} \begin{pmatrix} x(t) \\ V_C(t) \\ I_{L1}(t) \\ I_{L2}(t) \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} E$$

## 2 Exercise Two

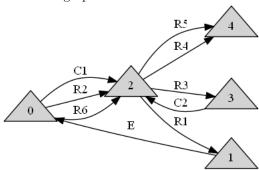
The I graph



Where

$$\begin{array}{c}
\boxed{0} = 0, 1, 3, 5 \\
\boxed{1} = 2 \\
\boxed{2} = 4 \\
\boxed{3} = 6
\end{array} \tag{6}$$

and the V graph



Where the notes correspond to

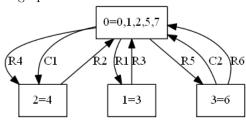
with the output being

$$V_{out} = E_2 \tag{8}$$

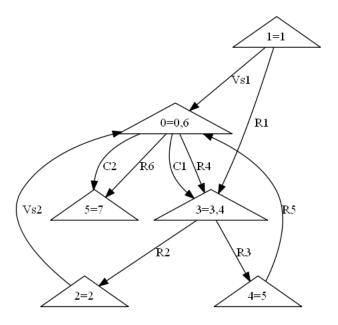
and we arrive at the equations

#### 3 Exercise Three

The I graph



and the V graph



Where the notes correspond to with the output being

$$y = v_{out} = E_5 \tag{9}$$

and we arrive at the equations

As state variables we consider the voltage of the capacitors

$$x = \begin{pmatrix} v_{C1}(t) \\ v_{C2}(t) \end{pmatrix} = \begin{pmatrix} E_3 \\ -E_5 \end{pmatrix}$$

from those equations it must follow

$$sC_1E_3 = -\left(\frac{1}{R4} + \frac{1}{R2}\right)E3 + \frac{V_{s2}}{R2} \tag{10}$$

and

$$sC2E5 = -\frac{1}{R6}E5 + \frac{R3}{R5}\left(-\frac{V_{s1}}{R1} + \left(\frac{1}{R3} + \frac{1}{R1}\right)E3\right)$$
 (11)

So going back to the time domain we obtain

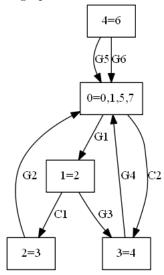
$$\dot{x}(t) = \begin{pmatrix} A & x(t) & B & u(t) \\ -(\frac{1}{R^{4}C1} + \frac{1}{R^{2}C1}) & 0 \\ \frac{R3}{R^{5}C2}(\frac{1}{R^{3}} + \frac{1}{R^{1}}) & -\frac{1}{R^{6}C^{2}} \end{pmatrix} \begin{pmatrix} V_{C1}(t) \\ V_{C2}(t) \end{pmatrix} + \begin{pmatrix} 0 & \frac{1}{C^{1}R^{2}} \\ \frac{R3}{R^{5}R^{1}C^{2}} & 0 \end{pmatrix} \begin{pmatrix} V_{s1}(t) \\ V_{s2}(t) \end{pmatrix}$$

and for the output it must hold

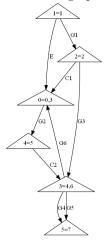
$$y(t) = \begin{pmatrix} C & x(t) & D & u(t) \\ (0 & 1) \begin{pmatrix} V_{C1}(t) \\ V_{C2}(t) \end{pmatrix} + \begin{pmatrix} D & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} V_{s1}(t) \\ V_{s2}(t) \end{pmatrix}$$

# 4 Exercise Four

The I graph



and the V graph



Where the notes correspond to with the output being

$$V_{out} = E_2 (12)$$

and we arrive at the equations