

tesseract_planning
::TaskInfo



```
graph BT; A[tesseract_planning::ProfileSwitchTaskInfo] --> B[tesseract_planning::TaskInfo];
```

The diagram illustrates an inheritance relationship between two classes. At the bottom is a gray box labeled 'tesseract_planning::ProfileSwitchTaskInfo'. A blue arrow points vertically upwards from this box to a white box at the top labeled 'tesseract_planning::TaskInfo'. Both boxes have black borders.

tesseract_planning
::ProfileSwitchTaskInfo