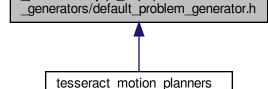
tesseract_motion_planners
/include/tesseract_motion
_planners/trajopt_ifopt/problem
_generators/default_problem_generator.h



/src/trajopt_ifopt/problem _generators/default_problem _generator.cpp