# **Probabilistic Programming Languages**

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Guillaume BAUDART (guillaume.baudart@ens.fr)
Christine TASSON (christine.tasson@lip6.fr)

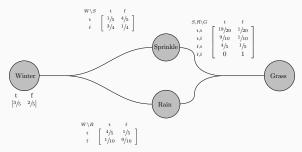
# **Semantics of Probabilistic Programming**

Discrete probability

# **Bayesian Networks**

# **Bayseian Network - Introduction**

#### **Example**



**Purpose :** compact representation of the joint distribution  $\mathbb{P}(G,S,R,W)$ 

Variables X and their sample sets (or carrier or web)  $\left|X\right|$ 

Conditional Probability Tables :  $|\mathtt{Pa}(X)| imes |X| o \mathbb{R}^+$ 

Dependancy to parents Pa(X) and independacy to other variables.

The function mass  $\mathbb{P}(G = g, S = s, R = r, W = w)$  has dimension  $2^4$ !

# **Bayesian Network - Introduction**

**Definition** A bayesian network is given by

A DAG

Labeled by variables and conditional probability tables (CPT)

#### **Dependance and Independance**

Parents :  $Pa(G) = \{S, R\}$  and Pa(S) = W

The probability of X given variables depends only on Pa(X).

## Joint distribution from conditional probability tables

$$\mathbb{P}(G, R, S, W) = \mathbb{P}(G|S, R)\mathbb{P}(S|W)\mathbb{P}(R|W)\mathbb{P}(W)$$

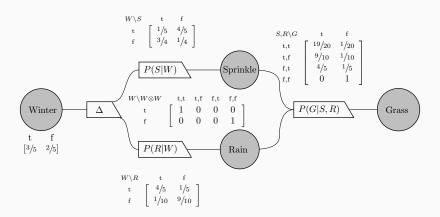
#### Conditional probability

$$\mathbb{P}(G, R, S, W) = \mathbb{P}(G|S, R, W)\mathbb{P}(S, R, W)$$

#### Chain Rule

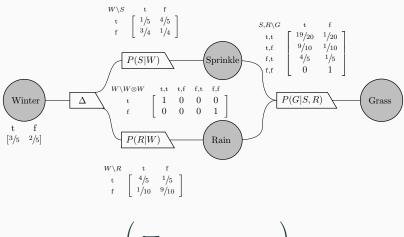
$$\mathbb{P}(G,R,S,W) = \mathbb{P}(G|S,R,W)\mathbb{P}(S|R,W)\mathbb{P}(R|W)\mathbb{P}(W)$$

**Dependance** 
$$\mathbb{P}(G|S,R,W) = \mathbb{P}(G|S,R)$$

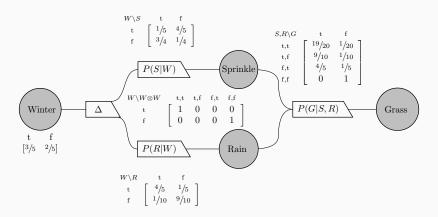


# Compute $\mathbb{P}(G)$ using :

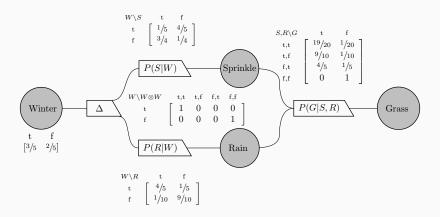
Joint dist. 
$$\mathbb{P}(G, R, S, W) = \mathbb{P}(G|S, R) \mathbb{P}(S|W) \mathbb{P}(R|W) \mathbb{P}(W)$$
  
Marginal  $\mathbb{P}(G) = \sum_{(r,s,w)\in |R|\times |S|\times |W|} \mathbb{P}(G, R, S, W)$ 



$$p(S) = \left(\sum_{a \in \{t,f\}} P(S|W)_{a,b} \cdot p(W)_a\right)_{b \in \{t,f\}}$$



$$p(W)$$
  $P(S|W) = p(S)$   
 $p(W)$   $P(R|W) = p(R)$  and  $(p(S) \otimes p(R))$   $P(G|S,R) = p(G)$ 



$$p(W) \triangle (P(S|W) \otimes P(R|W)) P(G|S,R) = p(G)$$

# **Semantics of Functional Programming**

Operational and Denotational

# PCF, Programming Computable Functions (a functional typed programming language)

(D. Scott : A Type-Theoretical Alternative to ISWIM, CUCH, OWHY. Theor. Comput. Sci., 1993)

(G. Plotkin : LCF Considered as a Programming Language. Theor. Comput. Sci., 1977)

#### **Syntax**

$$M, N, P := \underbrace{x \mid \lambda x \, M \mid (M) \, N \mid (M, N)}_{\lambda \text{-calculus}} \mid \underbrace{\text{fix} \, M}_{\text{Recursion}}$$
$$\mid \underbrace{0 \mid \text{succ} \, M}_{\text{Arithmetics}} \mid \underbrace{\text{true} \mid \text{false} \mid \text{if} \, M \, \text{then} \, N \, \text{else} \, P}_{\text{Conditionnal}}$$

#### **Semantics**

**Operational :**  $M \to M'$  **Denotational :**  $\llbracket \Gamma \vdash M : A \rrbracket : \llbracket \Gamma \rrbracket \to \llbracket A \rrbracket$ 

Wanted

**Soundeness**: If  $M \to M'$ , then  $\llbracket \Gamma \vdash M : A \rrbracket = \llbracket \Gamma \vdash M' : A \rrbracket$ .

**Adequation Lemma :** For every n, if  $[\![M]\!] = n$  then  $M \to^* n$ .

# PCF - Typing system

#### Types and contexts

$$A, B ::= \mathtt{unit} \mid \mathtt{int} \mid \mathtt{bool} \mid A \to B$$
  $\Gamma ::= \top \mid \Gamma, x : A$ 

#### **Rules**

```
\Gamma, x : A \vdash x : A \qquad \Gamma \vdash () : unit
if \Gamma, x : A \vdash M : B then \Gamma \vdash \lambda x.M : A \rightarrow B
if \Gamma \vdash M : A \rightarrow B and \Gamma \vdash N : A then \Gamma \vdash (M)N : B
if \Gamma \vdash M : A \rightarrow A then \Gamma \vdash \text{fix } M : A
\Gamma \vdash \text{true} : \text{bool} \text{ and } \Gamma \vdash \text{false} : \text{bool}
if \Gamma \vdash M: bool and \Gamma \vdash N : A and \Gamma \vdash P : A
then \Gamma \vdash \text{if } M \text{ then } N \text{ else } P : A
\Gamma \vdash 0 : nat
if \Gamma \vdash M: nat then \Gamma \vdash \operatorname{succ} M: nat
```

# **PCF** - Operational Semantics

#### Call-by-name

$$\frac{M \to M'}{(\lambda x \, M) \, N \to M \, [N/x]} \qquad \frac{M \to M'}{(M) \, N \to (M') \, N}$$

$$\overline{\text{fix } M \to (M) (\text{fix} M)}$$

$$\overline{\text{if true then } N \, \text{else} \, P \to N} \qquad \overline{\text{if false then } N \, \text{else} \, P \to P}$$

$$\frac{M \to M'}{\overline{\text{if } M \, \text{then } N \, \text{else} \, P \to \text{if } M' \, \text{then } N \, \text{else} \, P}}$$

 $\llbracket A \rrbracket$  is an object

 $\llbracket G \vdash e : t \rrbracket$  is a morphism in  $\mathcal{C}(\llbracket G \rrbracket, \llbracket t \rrbracket)$ 

```
Category \mathcal C SET, REL, MREL Sets, sets, sets Morphisms (\mathcal C(A,B),id_A,\circ) function, relations, multirelations Interpretation of types :
```

$$\textbf{Cartesian} \; (\mathcal{C}, \&, \top) \qquad \qquad (\mathsf{SET}, \; \{*\}, \; \times), \; (\mathsf{REL}, \; \emptyset, \; \uplus), \; (\mathsf{MREL}, \; \emptyset, \; \uplus)$$

**Terminal object**  $\top$  such that there is a unique  $A \to \top$ **Cartesian product** A & B together with projections  $A \& B \to A$  and  $A \& B \to B$  such that for any  $f: Z \to A$  and  $g: Z \to B$ , there is a unique  $(A \otimes B) = (A \otimes B) =$ 

#### Interpretation of contexts:

$$\llbracket \text{unit} \rrbracket = \top$$
$$\llbracket x_1 : t_1, \dots, x_k : t_k \rrbracket = \llbracket t_1 \rrbracket \times \dots \times \llbracket t_k \rrbracket$$

#### Interpretation of terms:

$$\left[ \left[ \frac{G \vdash e_1 : t_1 \qquad G \vdash e_2 : t_2}{G \vdash (e_1, e_2) : t_1 \times t_2} \right] = \langle \llbracket G \vdash e_1 : t_1 \rrbracket, \llbracket G \vdash e_2 : t_2 \rrbracket \rangle$$

#### Closed $A \Rightarrow B$

$$B^A$$
,  $\stackrel{*}{\blacktriangle}$ ,  $\mathcal{M}_{fin}A \times B$ 

**Evaluation**  $ev: (A \Rightarrow B) \times A \rightarrow B$ 

**Curryfing** if  $f: C \times A \rightarrow B$  then there is a unique  $\Lambda f: C \rightarrow A \Rightarrow B$  compatible with the evaluation.

#### Interpretation of terms:

$$\left[ \frac{G, x : t_1 \vdash e : t_2}{G \vdash \lambda x.e : t_1 \rightarrow t_2} \right] = \Lambda(\llbracket G, x : t_1 \vdash e : t_2 \rrbracket)$$

$$\left[\!\!\left[\frac{G\vdash e_1:t_1\to t_2 \qquad G\vdash e_2:t_1}{G\vdash (e_1)e_2:t_2}\right]\!\!\right]=\operatorname{evo}\langle\left[\!\!\left[G\vdash e_1:t_1\to t_2\right]\!\!\right],\left[\!\!\left[G\vdash e_2:t_2\right]\!\!\right]\rangle$$

#### **CPO**-enriched:

CPO, REL, MREL

 $\mathcal{C}(A,B)$  is a complete partial order and  $\circ$  is continuous.

$$\left[ \frac{G \vdash e : t \to t}{G \vdash \text{fixe} : t} \right] = \sup F^n \text{ with } \begin{cases} F^0 = \bot \in \mathcal{C}(G, t) \\ F^{n+1} = \text{ev} \circ \langle \llbracket G \vdash e : t \to t \rrbracket, F^n \rangle \end{cases}$$

**Theorem :** Every cartesian closed category is a model of the  $\lambda$ -calculus.

Example : Compute  $\llbracket \Gamma, x : A \vdash x : A \rrbracket$  and  $\llbracket \Gamma \vdash (M)N : B \rrbracket$ 

**Theorem**: Every cartesian closed category CPO-enriched with booleans and natural objects is a model of PCF

Example : Compute  $[\![\Gamma \vdash \mathtt{fix}\ M : A]\!]$ 

**Theorem**: MREL is an adequate model of PCF.

Example : Compute  $\llbracket \Gamma \vdash \text{if } M \text{ then } N \text{ else } P : A \rrbracket$ 

# **Probabilistic PCF**

Syntax and Semantics

#### Probabilistic PCF

#### **Syntax**

$$M, N, P := \underbrace{x \mid \lambda x \ M \mid (M) \ N \mid (M, N)}_{\lambda\text{-calculus}} \mid \underbrace{\text{fix} \ M}_{\text{Recursion}}$$

$$\mid \underbrace{0 \mid \text{succ} \ M \mid}_{A\text{rithmetics}} \mid \underbrace{\text{true} \mid \text{false} \mid \text{if} \ M \text{ then } N \text{ else} \ P}_{\text{Conditionnal}}$$

$$\mid \underbrace{\text{let} \ x = \text{sample}(\text{bernoulli} \ p) \text{ in} \ M}_{P\text{robability}} \forall p \in [0, 1]$$

$$Types$$

$$\underbrace{\Gamma, x : \text{bool} \vdash M : A}_{\Gamma \vdash \text{let} \ x = \text{sample}(\text{bernoulli} \ p) \text{ in} \ M : B}$$

#### **Semantics**

**Operational :** 
$$M \stackrel{p}{\to} M'$$
 **Denotational :**  $\llbracket \Gamma \vdash M : A \rrbracket : \llbracket \Gamma \rrbracket \to \llbracket A \rrbracket$ 

#### Wanted

**Soundeness**: 
$$\llbracket \Gamma \vdash M : A \rrbracket = \sum_{M' \mid M \xrightarrow{P} M'} \llbracket \Gamma \vdash M' : A \rrbracket$$
.

# **Operational Semantics**

$$\frac{M \stackrel{p}{\rightarrow} M'}{(NN)^{\frac{1}{2}} M[N/x]} \frac{M \stackrel{p}{\rightarrow} M'}{(M)^{\frac{p}{2}} (M')^{\frac{p}{2}}} \frac{M \stackrel{p}{\rightarrow} M'}{\text{fix } M \stackrel{1}{\rightarrow} (M)(\text{fix}M)}$$

$$\frac{M \stackrel{p}{\rightarrow} M'}{\text{succ } M \stackrel{p}{\rightarrow} \text{succ } M'}$$

$$\frac{M \stackrel{p}{\rightarrow} M'}{\text{if } M \text{ then } N \text{ else } P \stackrel{p}{\rightarrow} \text{ if } M' \text{ then } N \text{ else } P}$$

$$\frac{M \stackrel{p}{\rightarrow} M'}{\text{sample(bernoulli } p) \stackrel{p}{\rightarrow} \text{ true}} \frac{M \stackrel{p}{\rightarrow} M'}{\text{sample(bernoulli } p) \stackrel{1-p}{\rightarrow} \text{ false}}$$

$$\frac{M \stackrel{p}{\rightarrow} M'}{\text{let } x = M \text{ in } N \stackrel{p}{\rightarrow} \text{ let } x = M' \text{ in } N} \frac{\text{v is a constant}}{\text{let } x = v \text{ in } N \stackrel{p}{\rightarrow} M[v/x]}$$

# **Operational Semantics**

#### **Transition Matrix:**

$$\mathbf{Proba}(M, M') = \begin{cases} p & \text{if } M \stackrel{p}{\rightarrow} M' \\ 1 & \text{if } M \text{ normal and } M = M' \\ 0 & \text{otherwise.} \end{cases}$$

#### **Iterated Transition Matrix:**

**Proba**<sup>k</sup>(M, N) is the probability that M reduces to N in at most k steps.

**Proba** $^{\infty}(M, N)$  when N is normal is the probability that M reduces to N in any number of steps

**Adequation Lemma (wanted) :** If M closed term of type nat, then for every n,  $-if [M] = n \text{ then } M \to^* n$ .  $[M]_n = \mathbf{Proba}^{\infty}(M, \underline{n})$ 

# **Examples: Compute the operational semantics**

# Bernoulli: 1 let a = sample(bernoulli 0.5) in 2 let b = sample(bernoulli 0.5) in 3 let c = sample(bernoulli 0.5) in 4 a+b+c Fixpoint: 1 fix lambda b: bool 2 let x = sample(bernoulli p) in

```
fix lambda b:bool

let x = sample(bernoulli p) in

let y = sample(bernoulli p) in

if x then (if y then b else true)

else (if y then false else b)
```

```
Geometric:

fix lambda f:bool->unit lambda d:bool
```

```
let x = sample(d) in
if x then (f)d else ()
```

# **Examples: Compute the operational semantics**

#### Count - while

#### Count - fix

```
fix lambda f:bool->bool
lambda c:bool
let y = (sample bernoulli p) in
if y then c else f(c+1)
```

#### **Probabilistic PCF - Denotational Semantics**

#### The category of Probabilistic Coherent spaces - Pcoh

**Object**: (|A|, P(A)) with |A| a set and  $P(A) \subset (\mathbb{R}^+)^{|A|}$  set of functions from web to positive reals.

#### **Examples**

```
\begin{aligned} &|\text{unit}| = \{*\} \\ &\text{P(unit)} = [0,1] \\ &|\text{int}| = \mathbb{N} \\ &\text{P(int)} = \{(x_n)|\sum x_i \leq n\} \\ &|\text{bool}| = \{\text{true, false}\} \\ &\text{P(bool)} = \{(x_{\text{true}}, x_{\text{false}}) \mid x_{\text{true}} + x_{\text{false}} \leq 1 \\ &|A \& B| = |A| \uplus |B| \\ &\text{P(}A \& B) = \{(x_i)_{i \in A \uplus B} \mid (x_i)_{i \in A} \in \text{P(}A) \text{, } (x_i)_{i \in B} \in \text{P(}B) \} \end{aligned}
```

#### **Probabilistic PCF - Denotational Semantics**

(Vincent Danos, Thomas Ehrhard, On probabilistic coherence spaces, 2011) **The** category of Probabilistic Coherence spaces - Pcoh

**Object**: (|A|, P(A)) with |A| a set and  $P(A) \subset (\mathbb{R}^+)^{|A|}$  set of functions from |A| to  $\mathbb{R}^+$ **Morphism**:  $f: (|A|, P(A)) \to (|B|, P(B))$  a matrix  $(f_{(m,b)})$  indexed by  $\mathcal{M}_{fin}(A) \times B$  such that  $\forall x \in P(A), f \cdot x : b \mapsto \sum_{m \in \mathcal{M}_{fin}(A)} \prod_{a \in m} x(a)^{m(a)} f_{m,b} \in P(B)$ 

#### **Examples**

$$\begin{split} f: \llbracket \mathit{unit} \rrbracket \to \llbracket \mathit{unit} \rrbracket \text{ such that } \forall x \in [0,1], \ f \cdot x = \sum_n f_n x^n \in [0,1] \\ f: \llbracket \mathit{bool} \rrbracket \to \llbracket \mathit{bool} \rrbracket \text{ such that } f = \begin{bmatrix} w \backslash S & \text{t} & \text{f} \\ \frac{1}{5} & \frac{4}{5} \\ \frac{3}{4} & \frac{1}{4} \end{bmatrix} \\ f: \llbracket \mathit{bool} \rrbracket \to \llbracket \mathit{unit} \rrbracket \text{ such that } f_{([\mathtt{true}^n, *], \mathtt{true})} = 1 \text{ otherwise } f_{m, *} = 0, \\ \text{then } f \cdot (p, 1-p) = \sum_n p^n (1-p) \text{ and } f \cdot (1,0) = 0. \end{split}$$

#### **Probabilistic PCF - Denotational Semantics**

#### A sound model

*Pcoh* is a cartesian closed category, CPO-enriched, hence a model of PCF, which is also a model of probabilistic PCF.

#### Interpretation of terms

$$\boxed{ \boxed{ \textit{$G \vdash $\mathsf{bernoulli}(p) : \mathsf{bool \ dist}$} } : \begin{cases} (\gamma, \mathsf{true}) \mapsto p \\ (\gamma, \mathsf{false}) \mapsto 1 - p \end{cases}$$

$$\left[\!\!\left[\begin{array}{ccc} G \vdash d \ : \ t_1 \ \mathrm{dist} & G,x : t_1 \vdash e : t_2 \\ \hline G \vdash \mathrm{let} \, x = d \ \mathrm{in} \, e \ : \ t_2 \end{array}\right] : (\gamma, \mathsf{a}_2) \mapsto \sum_{\mathsf{a}} \llbracket e \rrbracket (\gamma, \mathsf{a}, \mathsf{a}_2)$$

$$\llbracket \overline{\textit{G} \vdash \textit{true} : \textit{bool}} \rrbracket : egin{cases} (\gamma, \mathtt{true}) \mapsto 1 \\ (\gamma, \mathtt{false}) \mapsto 0 \end{cases}$$

$$\llbracket \texttt{if } M \texttt{ then } N \texttt{ else } P \rrbracket (\gamma, a) = \llbracket M \rrbracket (\gamma, \texttt{true}) \llbracket N \rrbracket (\gamma, a) + \llbracket M \rrbracket (\gamma, \texttt{false}) \llbracket P \rrbracket (\gamma, a)$$

#### Bernoulli:

```
let a = sample(bernoulli 0.5) in
let b = sample(bernoulli 0.5) in
let c = sample(bernoulli 0.5) in
a+b+c
```

#### **Fixpoint:**

```
fix lambda b:bool
let x = sample(bernoulli p) in
let y = sample(bernoulli p) in
if x then (if y then b else true)
else (if y then false else b)
```

#### Geometric:

```
fix lambda f:bool->unit lambda d:bool
let x = sample(d) in
if x then (f)d else ()
```

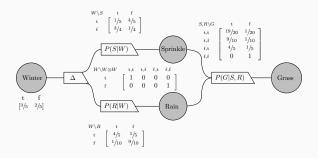
#### Count - while

#### Count - fix

```
fix lambda f:bool—>bool
lambda c:bool
let y = (sample bernoulli p) in
if y then c else f(c+1)
```

# **Example of a Bayesian Network**

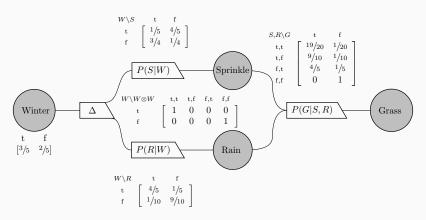
**Definition** A bayesian network is given by a DAG whose nodes are labeled by types (variables) and edges by morphisms (CPT).



**Tensor** 
$$[\![A \otimes B]\!]$$
 with  $|A \otimes B| = |A| \times |B|$  and 
$$P(A \otimes B) = \{f : A \times B \to \mathbb{R}^+ \mid a \mapsto \sum_a f_{a,b} \in P(A), \\ b \mapsto \sum_b f_{a,b} \in P(B)\}.$$

# **Examples - Compute the semantics**

A bayesian network is given by a DAG whose nodes are labeled by types (variables) and edges by morphisms (CPT).



$$p(G) = P(G|S,R) \cdot (P(S|W) \otimes P(R|W)) \cdot \Delta \cdot p(W)$$

# **Examples - Compute the semantics**

#### Funny Bernoulli by rejection sampling:

```
fix lambda f:bool
let a = sample(bernoulli 0.5) in
let b = sample(bernoulli 0.5) in
let c = sample(bernoulli 0.5) in
if (a==0 or b==0) then a+b+c
else f
```

# **Examples - Compute the semantics**

#### Funny Bernoulli:

```
let FB =
let a = sample(bernoulli 0.5) in
let b = sample(bernoulli 0.5) in
let c = sample(bernoulli 0.5) in
sassume(a==0 or b==0);
a+b+c
```

Reminder on enumeration algorithm.

# **Probabilistic Language - Type and Semantics**

$$\llbracket \textit{G} \vdash \textit{e} \; : \; \textit{t} \rrbracket : \llbracket \textit{G} \rrbracket \times \llbracket \textit{t} \rrbracket \rightarrow \mathbb{R}^+ \; \text{and} \; \llbracket \textit{G} \vdash \textit{e} \; : \; \textit{t} \; \text{dist} \rrbracket (\gamma, \texttt{a}) \in \mathrm{P} \left( \texttt{G} \rightarrow \texttt{t} \right)$$

$$\boxed{ \boxed{ \textit{$G \vdash $\mathsf{bernoulli}(p) : \mathsf{bool \ dist}$} } : \begin{cases} (\gamma, \mathsf{true}) \mapsto p \\ (\gamma, \mathsf{false}) \mapsto 1-p \end{cases}$$

$$\left[\!\!\left[\begin{array}{ccc} G \vdash d \ : \ t_1 \ \mathrm{dist} & G, x : t_1 \vdash e : t_2 \\ \hline G \vdash \mathrm{let} \ x = d \ \mathrm{in} \ e \ : \ t_2 \end{array}\right] : (\gamma, \mathsf{a}_2) \mapsto \sum_{\mathsf{a}} \llbracket e \rrbracket (\gamma, \mathsf{a}, \mathsf{a}_2)$$

$$\boxed{ \frac{\textit{G} \vdash \textit{e} \; : \; \textit{t}}{\textit{G} \vdash \mathsf{infer}(\textit{e}) \; : \; \textit{t} \; \mathsf{dist} } } \left( \gamma, \textit{a} \right) = \frac{ [\![\textit{G} \vdash \textit{e} \; : \; \textit{t}]\!] (\gamma, \textit{a})}{ \sum_{\textit{a} \in |\textit{t}|} [\![\textit{G} \vdash \textit{e} \; : \; \textit{t}]\!] (\gamma, \textit{a})}$$

#### **Examples**

#### Dice:

#### Cannabis:

#### Take home

# Semantics for (discrete) probabilistic programs

operational semantics and denotational semantics

Probabilistic coherent spaces (be able to compute semantics)

a model of Bayesian Networks

Probabilistic PCF

First Order Probabilistic language with conditionning

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