

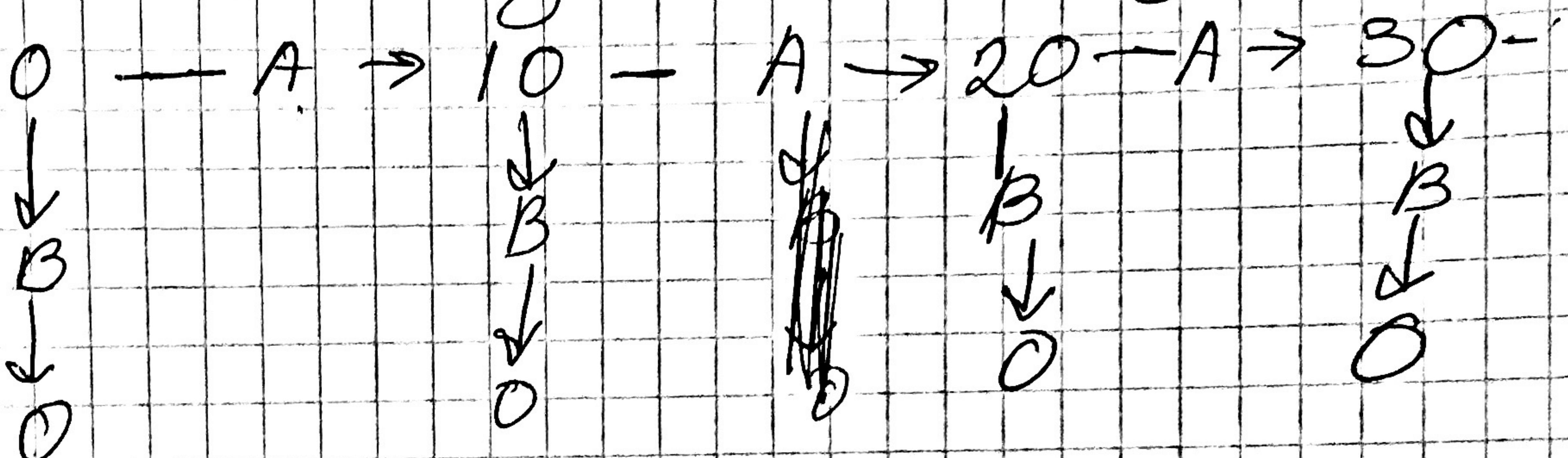
Nod3.HW4 Margarita Prikho do

1. a) Expected A = $P_A \cdot \text{Amount} - \text{Cost to Play}$

$$\text{Expected A} = 0.1 \cdot 20 - 10 = -8$$

$$\begin{aligned} \text{Expected B} &= P_B \cdot \text{Amount} - \text{Cost to Play} \\ &= 0.4 \cdot 30 - 20 = 12 - 20 = -8 \end{aligned}$$

b.) Action Play . MDP diagram



c) All possible policies

$\beta \in [0, 1]$ where β is probability to play on A if you have 20\$
You have 20\$ \rightarrow 2 states

play A or play B

$$\begin{aligned} \text{To play Probability for A} &= \beta \\ \text{To play Probability for B} &= 1 - \beta \end{aligned}$$

For policy π_β

$$\pi(a = A | s = \$20) = \beta$$

$$\pi(a = B | s = \$20) = 1 - \beta$$

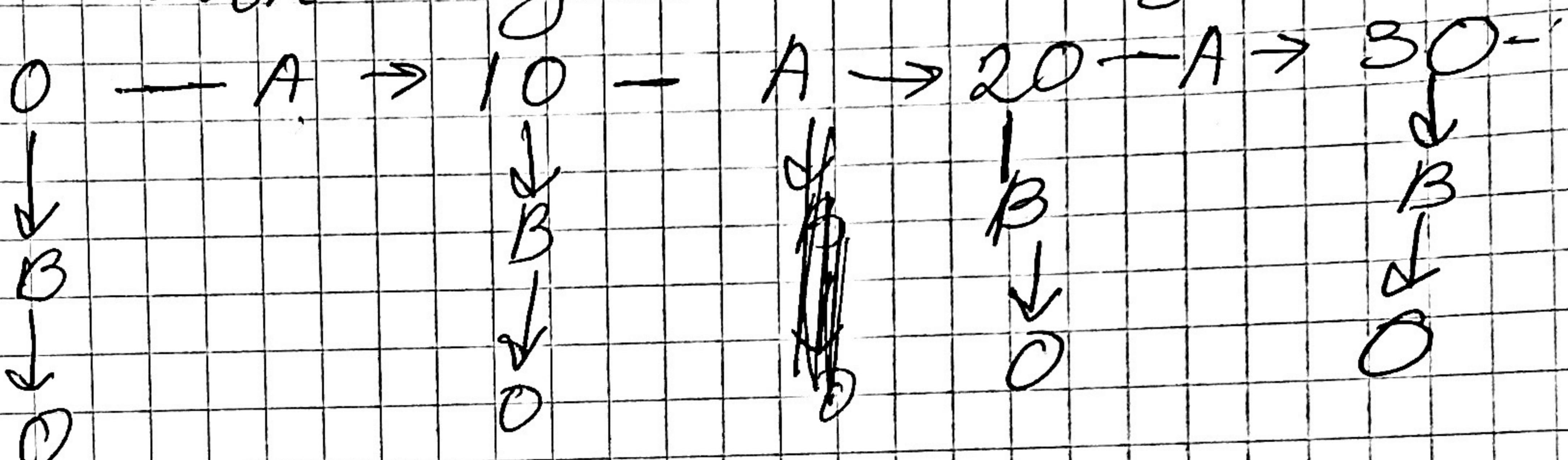
Mod3.HW4 Margarita Priklo dbo

1. a) $\text{Expect. A} = P_A \cdot \text{Amount} - \text{Cost to Play}$

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$\beta \in [0, 1]$ where β is probability to play on A if you have 20\$

You have 20\$ \rightarrow 2 states

play A or play B

To play Probability for A $= \beta$

To play Probability for B $= 1 - \beta$

For policy π_β

$\pi(a=A | s=\$20) = \beta$

$\pi(a=B | s=\$20) = 1 - \beta$

In order to compute $v^{\pi_\beta}(s)$ for all non-terminal states Bellman equation.

$$v^{\pi_\beta}(s) = \sum_{a \in \text{Action}} \pi_\beta(a|s) \cdot$$

• (Reward (s, a)) + $\sum_{s'} p(s'|s, a)$
 $v^{\pi_\beta}(s')$)

$v^{\pi_\beta}(s)$ is value of state
 $\pi_\beta(a|s)$ is the probability
of taking action a in state s
under policy π_β
Reward (s, a) is immediate
reward of taking action a in
state s

$p(s'|s, a)$ is the probability
of transitioning to state s'
from state s under action a

1. For State $S=20$: A state
Reward $(S=20, a=A) = 20$ or 0
win or losses

$$\pi_\beta(a=A|s=20) = \cancel{\text{beta}} = \beta$$

Transition $s=0 / s=30 \rightarrow$ probability

$$\begin{aligned} v_1 &= \\ \text{Reward}(s=0) \cdot 0 + \\ &+ (1-\beta) \cdot \left(\text{Reward}(s=0) \cdot 1 \right) \end{aligned}$$

2. For Action playing. B

$$\pi_\beta(a=B | s = \$20) = 1 - \beta$$

Reward (\$30), $a=B$) = \$30 or \$0
(loses B)

$$v^{\pi_B} = (1-\beta)30 + \text{reward}(s=0) \cdot 0 + \\ + \beta \cdot (\text{Reward}(s=0) \cdot 1)$$

For State \$0, \$10, \$30 similar

$$\text{State } 0 \quad \pi_A^{\pi_B} = \beta(0 + \text{Reward}_1) + (1-\beta)(\text{Reward}_2) = 0$$

$$VB^{\pi\beta} = (1-\alpha) \cancel{(0 + \text{Reward})} + \cancel{(\alpha \beta)} \cdot \text{Reward} = 0$$

For State 910

Finally

State \$20

$$v_{\pi_\beta}(20) = \pi_\beta(A|20) \cdot$$

$$\cdot (0.1(20-10) + 0.9 \cdot 0) + \pi_\beta(B|20) \cdot$$

$$\cdot (0.4 \cdot (30-20) + 0.6) =$$

$$\pi_\beta(A|20) = \beta$$

$$\pi_\beta(B|20) = (1-\beta)$$

$$v_{\pi_\beta} = \beta \cdot 0.1 \cdot \$10 + (1-\beta) 0.4 \cdot$$

$$\cdot (30-20) = 0.1\beta + 0.4(1-\beta) =$$

$$= 0.4 + (-\beta) \cdot 0.3 = 0.4 - 0.3\beta$$

For state \$10

$$v_{\pi_\beta}(\$10) = \pi_\beta(A|\$10) \cdot (0.1 \cdot (\$20 - \$10) + 0.9 \cdot 0) + \pi_\beta(B|\$10) \cdot (0.4 \cdot (30-20) + 0.6 \cdot 0) = 0.1 \cdot \beta + 0.4(1-\beta)$$

For state \$0

$$v_A^{\pi_\beta} = \beta \cdot 0 + \text{Reward. } 0 + (1-\beta) \cdot 0$$

$$v_B^{\pi_\beta} = 0 - \text{Terminal State. } \cancel{0}$$

d.) Expected value for machine B

$$= \frac{1}{2} \cdot \$30 - \frac{1}{2} \cdot \$20 = \$30 - \$20 = \$10$$

Expected for value machine

$$E(A) = \left(1 - \frac{1}{2}\right) \cdot 20 - 10$$

$$E(A) = E(B)$$

$$\frac{1}{2} \cdot \$30 - \frac{1}{2} \cdot \$20 = \left(1 - \frac{1}{2}\right) \cdot 20 - 10$$

$$\frac{1}{2} \cdot \$30 = 20 - 10 + 20 = \$30$$

$$\frac{1}{2} = \frac{30}{50} = 0.6$$

Expected value for machine B

$$= \frac{1}{2} \cdot \$30 - \frac{1}{2} \cdot \$20 = \$30 - \$20 = \$10$$

Expected value machine A

$$E(A) = \left(1 - \frac{1}{2}\right) \cdot 20 - 10$$

$$E(A) = E(B)$$

$$\frac{1}{2} \cdot \$30 - \frac{1}{2} \cdot \$20 = \left(1 - \frac{1}{2}\right) \cdot 20 - 10$$

$$\frac{1}{2} \cdot \$30 - \frac{1}{2} \cdot \$20 = 20 - 10 + 20 = \$30$$

$$\frac{1}{2} = \frac{30}{50} = 0.6$$