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Task 2

## Raport

I have solved a given task to me using C++ and MPI.  
I have implemented 2 given algorithms, and one mine.

My algorithm:

That algorithm is simple. We divided data over processes in equal number. To do so,  $i$ -th process gets stars  $i + k * PROCESSES\_NUMBER$ . In that case split is „equal”, but we need to provide all processes with all initial data.

Bottleneck of algorithms:

All algorithms have their own bottle neck which is redistributing data. The longest one is first, initial distribution.

Algorithm 1) and 3) need all data, so that takes a long time.

Algorithm 2) needs only 9 pieces of data. Potentially it can be noting, all or  $9 * DATA\_SIZE / PROCESSES\_NUMBER$ .

Then comes redistributing it back.

Algorithm 1) redistributes its own chunk of data. It can be as big as whole given data, if all stars are in one cell.

Algorithm 2) redistributes its own chunk of data by, first sending information to each process how much after its own iteration there are stars to send to them, and then send these stars. Potentially it should communicate first with all processes, but it sends only list of ints of length

$PROCESSES\_NUMBER$ , then it should send and receive data between up to 8 other processes.

Algorithm 3) redistributes its own data by sending its own chunk to all other processes and receiving their chunks. Size of chunk is fixed, so less connection is needed.

Calculation

Algorithm 1)

Each process can do from 0 to  $n$  stars, but for each star it needs to do calculation for  $n - 1$  other stars.

Algorithm 2)

It calculates data between its chunk and its neighbours. For many processes chunks should be small, data can be corrupted, because important stars nearby will be forgotten.

Algorithm 3)

It has always all data to its own calculation, but calculates only  $1 / PROCESSES\_COUNT$  data.

Here are some results, first on my machine. 4 Cores.

PROVIDED TESTS (alg, test, processes)

(1, one-star, 16) - 1,05s

(2, one-star, 16) - 0,66s

(3, one-star, 16) - 0,47s

(1, fifty-stars, 16) - 0,98s  
(2, fifty-stars, 16) - 0,68s  
(3, fifty-stars, 16) – 0,61s

That case is not very interesting mostly because there are lots of processes, but data is really small. Redistribution takes a lot of time, normally most. You can see algorithm 3 is best, but only some better than algorithm 2

(alg, processes, move, stars) – 10 ITERS

(1, 6, 1000, 2000) - 3.63s  
(2, 6, 1000, 2000) - 3.48s  
(3, 6, 1000, 2000) - 1.10s

(1, 36, 1000, 2000) - 10,75s  
(2, 36, 1000, 2000) - 6,75s  
(3, 36, 1000, 2000) - 4.45s

(1, 64, 1000, 2000) - 15,75s  
(2, 36, 1000, 2000) - 10.68s  
(3, 36, 1000, 2000) - 6.90s

(1, 6, 1, 2000) - 3.62s  
(2, 6, 1, 2000) - 3.71s  
(3, 6, 1, 2000) - 1.15s

(1, 36, 1, 2000) - 8.18s  
(2, 36, 1, 2000) - 6.32s  
(3, 36, 1, 2000) - 4.48s

(1, 64, 1, 2000) - 12.58s  
(2, 64, 1, 2000) - 9.86s  
(3, 64, 1, 2000) - 7.25s

(1, 6, 1, 4050) - 13.86s  
(2, 6, 1, 4050) - 12.96s  
(3, 6, 1, 4050) - 5.04s

(1, 36, 1, 4050) - 33.50s  
(2, 36, 1, 4050) - 18.02s  
(3, 36, 1, 4050) - 17.66s

(1, 64, 1, 4050) - 40.06s  
(2, 64, 1, 4050) - 31.20s  
(3, 64, 1, 4050) – 22.49s

Here also algorithm 3) win, and is sometimes way batter than algorithm 2), always better than 1).

MIMUW LAB - 10 iters

(1, 64, 100, 11250) - 94.38s  
(2, 64, 100, 11250) - 50.54s  
(3, 64, 100, 11250) - 37.42s

Here, for bigger dataset, nearly 3 times bigger, algorithm 3) is about 80% slower only, algorithm 2 only about 60% and algorithm 1) more than 130%. As far as data is about 3 times bigger, if we were doing it on one processor, time should be about 9 times bigger.

Below is bigger example. - 250 iterations, so redistributing initial data is less important

(1, 81, 1, 16422) – 1522.05s  
(2, 81, 1, 16422) – 267.84s  
(3, 81, 1, 16422) – 459.10s

Here is an example where 3) loses with 2). For data very close to itself.

Algorithm 2) should be useless the way it is if the initial galaxies are far away with them.