ADVANCED MACHINE LEARNING FINAL PROJECT

TOPIC – TensorFlow Digit classification

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SUMMARY

In this project, I would like to elaborate on TensorFlow digit classification. The purpose of this project is to identify and classify handwritten digits. MNIST ("Modified National Institute of Standards and Technology") is the de facto "hello world" dataset of computer vision. Since its release in 1999, this classic dataset of handwritten images has served as the basis for benchmarking classification algorithms. As new machine-learning techniques emerge, MNIST remains a reliable resource for researchers and learners.

The goal is to correctly identify digits from a dataset of tens of thousands of handwritten images by using different techniques like the Sequential model using TensorFlow Keras. Image augmentation, Conv2D, Maxpool2D, Activation Function, Dropouts, Optimizer and Flatten etc. The measuring metric is accuracy.

PROBLEM

Everyone has a unique way of writing skills and how does a machine classify what exactly it is? The machine is trained to read the digits and classify the digits into labels. The goal is to correctly identify digits from a dataset of thousands of handwritten images.

DATA COLLECTION

The data files train.csv and test.csv contain gray-scale images of hand-drawn digits, from zero through nine.

Each image is 28 pixels in height and 28 pixels in width, for a total of 784 pixels in total. Each pixel has a single pixel value associated with it, indicating the lightness or darkness of that pixel, with higher numbers meaning darker. This pixel value is an integer between 0 and 255, inclusive.

The training data set, (train.csv), has 785 columns. The first column, called "label", is the digit that was drawn by the user. The rest of the columns contain the pixel values of the associated image.

Each pixel column in the training set has a name like pixelx, where x is an integer between 0 and 783, inclusive. To locate this pixel on the image, suppose that we have decomposed x as x = i * 28 + j, where i and j are integers between

0 and 27, inclusive. Then pixelx is located on row i and column j of a 28 x 28 matrix, (indexing by zero).

Libraries

Here I have mentioned different libraries used.

NumPy - NumPy is a very popular python library for large multi-dimensional array and matrix processing, with the help of a large collection of high-level mathematical functions. It is very useful for fundamental scientific computations in Machine Learning

Pandas - Pandas are one of the tools in Machine Learning which is used for data cleaning and analysis

Matplotlib - Matplotlib is one of the plotting libraries in python which is however widely in use for machine learning applications with its numerical mathematics extension- NumPy to create static, animated, and interactive visualizations.

TensorFlow - TensorFlow is an open-source library developed by Google primarily for deep learning applications

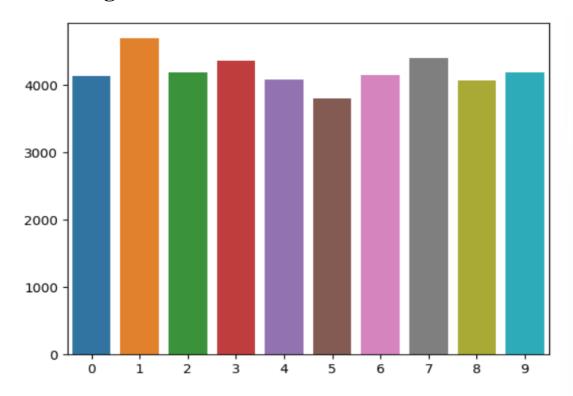
TensorFlow Keras - TensorFlow is an open-sourced end-to-end platform, a library for multiple machine learning tasks, while Keras is a high-level neural network library that runs on top of TensorFlow

Seaborn - Seaborn is a library that uses Matplotlib underneath plot graphs. It will be used to visualize random distributions.

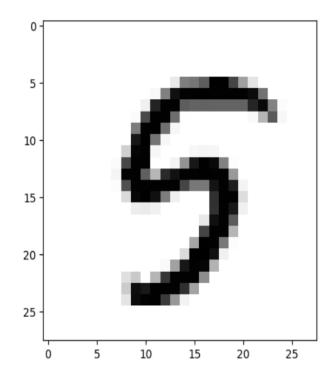
Data preparation and pre-processing

After installing the libraries, we load the data and divide the data into test and train files. Then we check for missing data. We proceed future if there is no missing data.

Data and target class visualizations



As you can see, there is a fairly even class distribution.



Here is an example of one of the digits. It is a 28 x 28 black and white image.

Creating training and validation sets

```
    ★ from sklearn.model_selection import train_test_split

M X_train, X_val, y_train, y_val = train_test_split(X, y, test_size=0.1, random_state=15)
  print(X train.shape, X val.shape, y train.shape, y val.shape)
  (37800, 784) (4200, 784) (37800,) (4200,)
```

Pre-processing pipelines

```
▶ from sklearn.pipeline import Pipeline

  from sklearn.compose import ColumnTransformer
  from sklearn.preprocessing import StandardScaler, MinMaxScaler
▶ from sklearn.base import BaseEstimator, TransformerMixin
def __init__(self):
         pass
      def fit(self, X, y=None):
         return self
      def transform(self, X, y=None):
         X = X.reshape((-1,28,28,1))
▶ features_pipeline = Pipeline(steps=[
      ('Normalize', MinMaxScaler()),
      ('Reshape', ReshapeFunc())
  1)
```

Feature pipeline. Data is scaled between 0 and 1 and then reshaped into input format.

```
X_train = features_pipeline.fit_transform(X_train)

▶ from sklearn.preprocessing import OneHotEncoder

   target_pipeline = Pipeline(steps=[
        ('OneHot', OneHotEncoder())
   ])
```

```
####. One hot encoding is used, as we will be using a softmax activation function in the output node.*
y_train = target_pipeline.fit_transform(y_train.values.reshape(-1,1))
: ▶ y_train = y_train.toarray()
: ▶ print(X_train.shape, y_train.shape)
     (37800, 28, 28, 1) (37800, 10)
: ► X_val = features_pipeline.fit_transform(X_val)
  : M y_val = y_val.toarray()
: ▶ print(X_val.shape, y_val.shape)
     (4200, 28, 28, 1) (4200, 10)
x test = features pipeline.fit transform(df test)
```

```
# Precision (using keras backend)
def precision_metric(y_true, y_pred):
    threshold = 0.5 # Training threshold 0.5
    y_pred_y = K.cast(K.greater(K.clip(y_pred, 0, 1), threshold), K.floatx())
    true_positives = K.sum(K.clip(y_true * y_pred, 0, 1))
    false_negatives = K.sum(K.clip(y_true * (1-y_pred), 0, 1))
    false_positives = K.sum(K.clip((1-y_true) * y_pred, 0, 1))
    true_negatives = K.sum(K.clip((1 - y_true) * (1-y_pred), 0, 1))
    precision = true_positives / (true_positives + false_positives + K.epsilon())
    return precision
# Recall (using keras backend)
def recall_metric(y_true, y_pred):
    threshold = 0.5 #Training threshold 0.5
    y_pred = K.cast(K.greater(K.clip(y_pred, 0, 1), threshold), K.floatx())
    true_positives = K.sum(K.clip(y_true * y_pred, 0, 1))
    false_negatives = K.sum(K.clip(y_true * (1-y_pred), 0, 1))
    false_positives = K.sum(K.clip((1-y_true) * y_pred, 0, 1))
    true_negatives = K.sum(K.clip((1 - y_true) * (1-y_pred), 0, 1))
    recall = true positives / (true positives + false negatives + K.epsilon())
    return recall
# F1-score (using keras backend)
def f1_metric(y_true, y_pred):
    precision = precision_metric(y_true, y_pred)
    recall = recall_metric(y_true, y_pred)
    f1 = 2 * ((precision * recall) / (recall+precision+K.epsilon()))
    return f1
M def build_model():
     inp = keras.Input(shape=(28,28,1))
     x = keras.layers.MaxPool2D(pool_size=(2,2))(x)
x = keras.layers.BatchNormalization()(x)
     x = keras.layers.Dropout(0.25)(x)
     x = keras.layers.Conv2D(filters=64, kernel_size=(5,5), padding='SAME', activation='relu')(x)
     x = keras.layers.MaxPool2D(pool_size=(2,2))(x)
     x = keras.layers.BatchNormalization()(x)
     x = keras.layers.Dropout(0.25)(x)
     x = keras.layers.Flatten()(x)
     x = keras.layers.Dense(256, activation='relu')(x)
     x = keras.layers.Dropout(0.5)(x)
     output = keras.layers.Dense(10, activation='softmax')(x)
     model = keras.Model(inputs=inp, outputs=output)
     model.compile(loss=keras.losses.CategoricalCrossentropy(), optimizer=keras.optimizers.Adam(learning rate=0.0001), r
     return model, inp, output
```

The model is built and compiled using categorical crossentropy and adam optimizer.

TECHNIQUES

Sequential model using TensorFlow keras - A Sequential model is appropriate for a plain stack of layers where each layer has exactly one input tensor and one output tensor. Schematically, the following Sequential model: Define the Sequential model with 3 layers. model = keras.

Image Data Generator for image augmentation, which is a technique of applying different transformations to original images results in multiple transformed copies of the same image.

- Rescale: rescale the image
- Rotation range: value in degrees (0–180) within which to randomly rotate pictures
- Width shift, height shift: ranges within which to randomly translate pictures vertically or horizontally
- Shear range: randomly applying shearing transformations
- Zoom range: randomly zooming inside pictures
- Horizontal flip: randomly flipping half of the images horizontally
- Fill mode: used for filling in newly created pixels after rotation, width, and height shift.

CONV 2D: Applies a 2D convolution over an input signal composed of several input planes. where * is the valid 2D cross-correlation operator, N is the batch size, C denotes the number of channels, H is the height of input planes in pixels, and W is the s width in pixels.

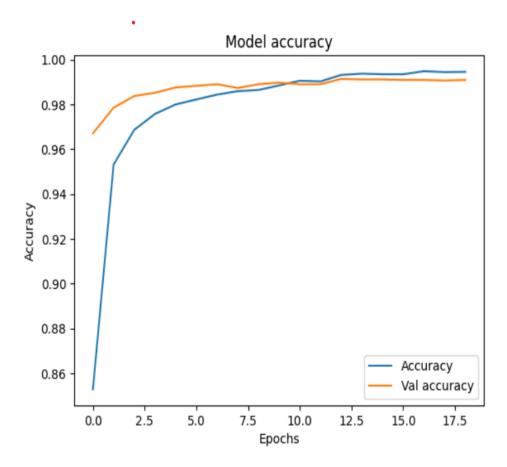
MaxPooling2D - Downsample the input along its spatial dimensions (height and width) by taking the maximum value over an input window (of size defined by pool size) for each channel of the input.

Dropout - The term "dropout" refers to dropping out the nodes (input and hidden layer) in a neural network. All the forward and backward connections with a dropped node are temporarily removed, thus creating a new network architecture out of the parent network.

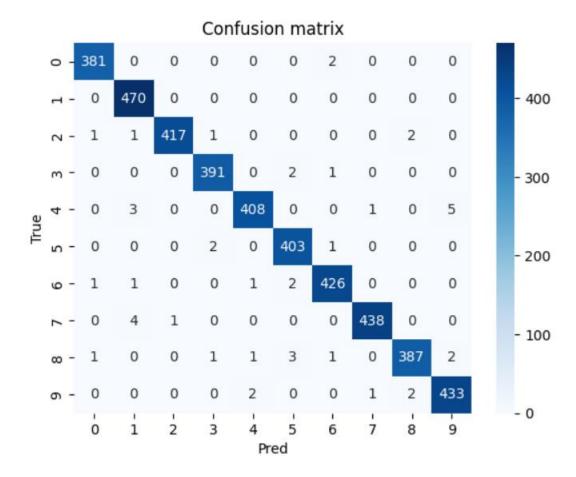
Flatten: Flattens the input. Does not affect the batch size.

Conclusions

The model is built and compiled using categorical cross entropy and adam optimizer.



CONFUSION MATRIX

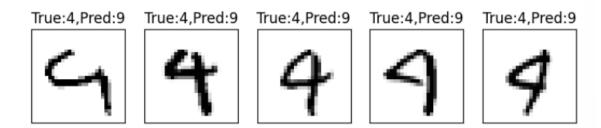


from sklearn.metrics import accuracy_score
accuracy_score(y_val_true, y_val_pred)

0.9890476190476191

The confusion matrix looks really good as well, with lots of predictions along the diagonal which is what we want to see. We got an accuracy of 0.9890476191. This is not bad for our first model! The model has done a pretty good job at classifying each class and is obtaining a high accuracy score. Now we should look at the examples the model is misclassifying. The class with the most confusion is between classes 5 and 6, let's look at the incorrectly predicted examples.

Missclassified examples



Looking at the misclassifications, it's understandable why the model was unable to classify these examples correctly. Some of the examples are quite ambiguous, even a human labeler would probably be unable to clearly label them with good confidence.

However, it does seem that there is room for improvement in some of the examples. With the use of data augmentation and hyper-parameter tuning, we should be able to further improve performance.

Before we try these additional techniques, let's take a quick look at the learned convolutional filters and feature maps, which should give us some insight into how the network is learning.

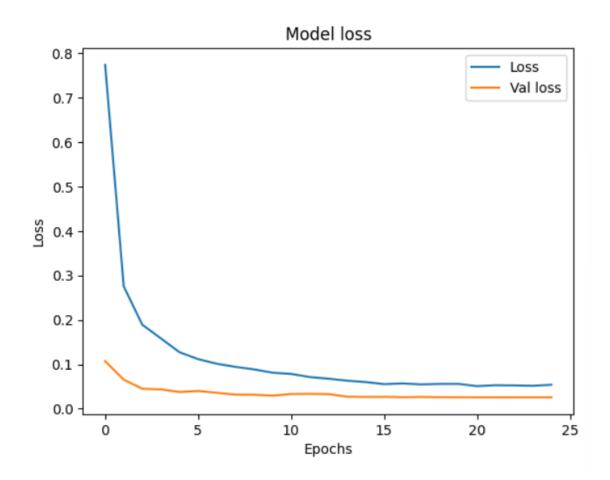
Then we took a test example. I ran it through the network to obtain and visualize the feature maps.

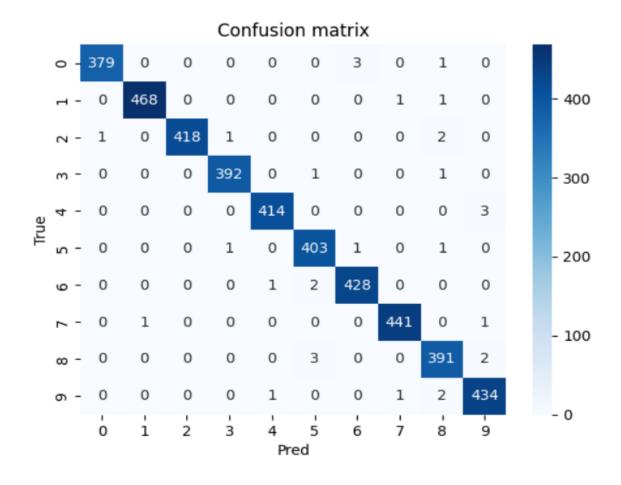
Contributions

To improve the accuracy more than 0.989% I used below technique.

.Data augmentation allows us to generate new images (artificial data) by slightly modifying the images in the training set by applying different transformations. In this notebook, we will use shifting, rotating, and zooming transformations to modify the data and generate new examples.

One of the benefits of data augmentation is it acts as a regularizer and helps to reduce overfitting when training a model. This is because, with more artificially generated images, the model is unable to overfit specific examples and is forced to generalize, thus the model becomes more robust. This generally leads to better overall performance.





accuracy_score(y_val_true, y_val_pred)

0.9923809523809524

We can see using data augmentation has improved our accuracy score by over 0.2%, which is quite a lot considering we are in the top 1% of accuracy score.

Hyper-parameter tuning

Now that we've implemented a data augmentation technique, we need to find the optimal hyper-parameter settings to maximize model performance. We will use the keras-tuner library, which is a hyperparameter optimization framework containing multiple tuning algorithms including Random Search, Hyper Band and Bayesian Optimization.

I tested both Random Search and Hyper Band and found Hyper Band to be much more successful so we will use that.

The accuracy score of our top model is significantly better than our previous model. This shows the importance of hyper-parameter tuning and was worth the time spent tuning.

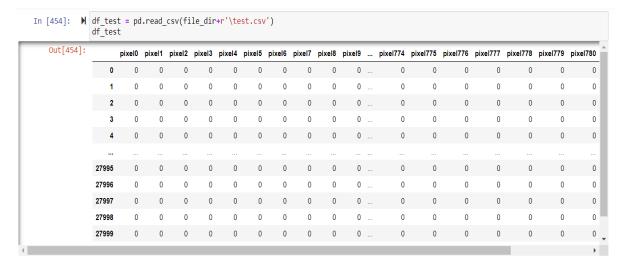
APPENDIX

DIGIT RECOGNITION

Data preparation and pre-processing

Loading data

```
df train
  Out[453]:
                 label pixel0 pixel1 pixel2 pixel3 pixel4 pixel5 pixel6 pixel6 pixel7 pixel8 ... pixel774 pixel775 pixel776 pixel777 pixel777 pixel778 pixel779 pixel780 pix
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            41999
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            42000 rows × 785 columns
df_test
```

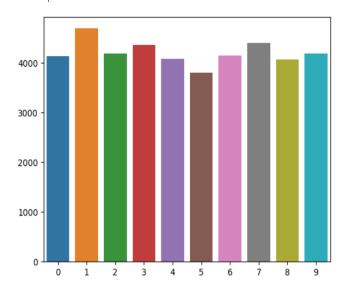


```
Checking for missing values
 Out[112]: count
                      785
             unique
                     False
             top
freq
                      785
             dtype: object
In [113]: M df_test.isna().any().describe()
   Out[113]: count
                     784
            unique
                    False
            top
            freq
                     784
            dtype: object
In [114]: ▶ df_train.info()
            <class 'pandas.core.frame.DataFrame'>
            RangeIndex: 42000 entries, 0 to 41999
           Columns: 785 entries, label to pixel783
            dtypes: int64(785)
            memory usage: 251.5 MB
print(X.shape, y.shape)
            (42000, 784) (42000,)
```

No missing data, let's continue.

Data and target class visualizations

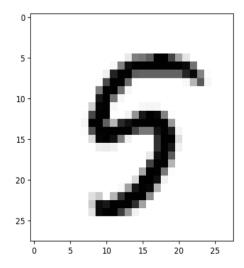
Out[116]: <AxesSubplot: >



As you can see, there is a fairly even class distribution.

```
In [117]: M z = np.reshape(X.iloc[8].values, (28,28))
    print(z.shape)
    plt.imshow(z, cmap='Greys')
```

Out[117]: <matplotlib.image.AxesImage at 0x1b69391a8b0>



```
### Creating training and validation sets
 In [346]: M X_train, X_val, y_train, y_val = train_test_split(X, y, test_size=0.1, random_state=15)
print(X_train.shape, X_val.shape, y_train.shape, y_val.shape)
            (37800, 784) (4200, 784) (37800,) (4200,)
         Pre-processing pipelines
In [347]: ▶ from sklearn.pipeline import Pipeline
            from sklearn.compose import ColumnTransformer
            from sklearn.preprocessing import StandardScaler, MinMaxScaler
In [348]: ▶ from sklearn.base import BaseEstimator, TransformerMixin
pass
                def fit(self, X, y=None):
               return self
def transform(self, X, y=None):
    X = X.reshape((-1,28,28,1))
                   return X
Feature pipeline. Data is scaled between 0 and 1 and then reshaped into input format.
In [351]: M X_train = features_pipeline.fit_transform(X_train)
####. One hot encoding is used, as we will be using a softmax activation function in the output node.*
In [353]:  y_train = target_pipeline.fit_transform(y_train.values.reshape(-1,1))
In [354]:  y_train = y_train.toarray()
In [355]:  print(X_train.shape, y_train.shape)
            (37800, 28, 28, 1) (37800, 10)
In [356]: M X_val = features_pipeline.fit_transform(X_val)
In [357]: M y_val = target_pipeline.fit_transform(y_val.values.reshape(-1, 1))
(4200, 28, 28, 1) (4200, 10)
In [360]: M X_test = features_pipeline.fit_transform(df_test)
```

In [361]: ▶ from keras import backend as K

The model is built and compiled using categorical crossentropy and adam optimizer.

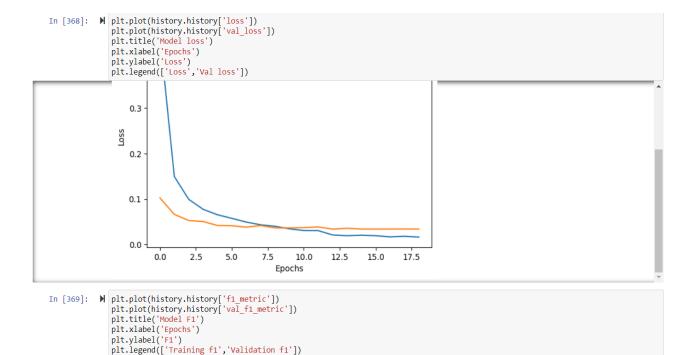
```
In [364]: 
M model, inp, out = build_model()
model.summary()

Model: "model_8"
```

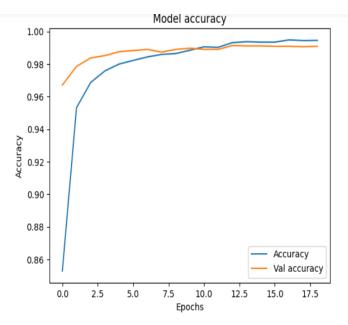
Model: "model_8"

Layer (type)	•	Param #
input_8 (InputLayer)		
conv2d_14 (Conv2D)	(None, 28, 28, 32)	832
<pre>max_pooling2d_14 (MaxPoolin g2D)</pre>	(None, 14, 14, 32)	0
<pre>batch_normalization_14 (Bat chNormalization)</pre>	(None, 14, 14, 32)	128
dropout_21 (Dropout)	(None, 14, 14, 32)	Ø
conv2d_15 (Conv2D)	(None, 14, 14, 64)	51264
<pre>max_pooling2d_15 (MaxPoolin g2D)</pre>	(None, 7, 7, 64)	0
<pre>batch_normalization_15 (Bat chNormalization)</pre>	(None, 7, 7, 64)	256
dropout_22 (Dropout)	(None, 7, 7, 64)	0
flatten_7 (Flatten)	(None, 3136)	0
dense_14 (Dense)	(None, 256)	803072
dropout_23 (Dropout)	(None, 256)	0
dense_15 (Dense)	(None, 10)	2570

Training network

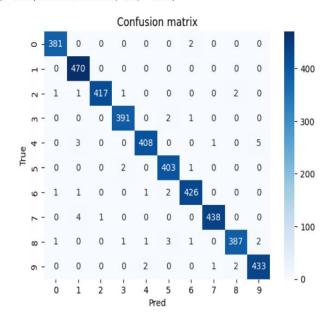


Out[370]: <matplotlib.legend.Legend at 0x1b690c2a640>



Looking at the loss plots, the network is converging well.

Out[373]: Text(50.7222222222214, 0.5, 'True')



Confusion matrix looks really good as well, lots of predictions along the diagonal which is what we want to see.

Ok, not bad for our first model! The model has done a pretty good job at classifying each class and is obtaining a high accuracy score. Now we should take a look at the examples the model is misclassifying.

The class with the most confusions is between class 5 and 6, let's take a look at the incorrectly predicted examples.

Missclassified examples



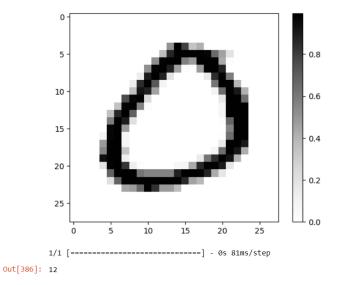
Looking at the missclassifications, its understandable why the model was unable classify these examples correctly. Some of the examples are quite ambiguous, even a human labeller would probably be unable to clearly label them with good confidence.

However, it does seem that there is room for improvement for some of the examples. With the use of data augmentation and hyper-parameter tuning, we should be able to further improve performance.

Before we try these additional techniques, let's take a quick look at the learnt convolutional filters and feature maps, which should give us some insight on how the network is learning.

```
In [381]: ▶ model.layers
    <keras.layers.regularization.dropout.Dropout at 0x1b69449c0d0>,
<keras.layers.convolutional.conv2d.Conv2D at 0x1b6905fc6a0>,
<keras.layers.pooling.max_pooling2d.MaxPooling2D at 0x1b690306e20>,
                 <keras.layers.core.dense.Dense at 0x1b6906219d0>]
In [382]:  M model.layers[1].get_weights()[0].shape
    Out[382]: (5, 5, 1, 32)
In [384]: 

for i in range(len(model.layers)):
    layer = model.layers[i]
    # check for convolutional layer
    if 'conv' not in layer.name:
                    continue
# summarize output shape
                    print(i, layer.name, layer.output.shape)
                1 conv2d_14 (None, 28, 28, 32)
               5 conv2d_15 (None, 14, 14, 64)
In [385]: N
                successive_outputs = [layer.output for layer in model.layers[1:]]
fm_model = keras.Model(inputs=model.input, outputs=successive_outputs)
                successive_outputs
    In [386]:  M test_example = X_train[[9]]
plt.imshow(test_example[0], cmap='Greys')
                plt.colorbar()
                plt.show()
plt.show()
successive_feature_maps = fm_model.predict(test_example)
len(successive_feature_maps) # 12 for 12 layers
```



Now that we have a test example, lets run it through the network to obtain and visualize the feature-maps.

```
In [387]: N
layer_names = [layer.name for layer in model.layers]
for layer_name, feature_map in zip(layer_names, successive_feature_maps):
    print(feature_map.shape)
    print(layer_name)
    if len(feature_map.shape) == 4:
        n_features = feature_map.shape[-1]  # number of features in the feature map
        size = feature_map.shape[-1] # features map shape (1, size, size, n_features)

# We will tile our images in this matrix
    display_grid = np.zeros((size, size * n_features))

# Postprocess the feature to be visually palatable
for i in range(n_features):
        x = feature_map[0, :, :, i]
        x - x . std ()
        x / x . std ()
        x * = 64
        x * = 128
        x = np.clip(x, 0, 255).astype('uint8')
        # Tile each filter into a horizontal grid
        display_grid[:, i * size : (i + 1) * size] = x

# Display the grid
        scale = 20 . / n_features
        plt.figure( figsize=(scale * n_features, scale) )
        plt.title(layer_name)
        plt.grid(False)
        plt.show()

plt.show()

(1, 28, 28, 32)
```

(1, 14, 14, 32) conv2d_14 (1, 14, 14, 32) max_pooling2d_14 (1, 14, 14, 32) batch_normalization_14 (1, 14, 14, 64) dropout_21 (1, 7, 7, 64) conv2d_15 (1, 7, 7, 64) max_pooling2d_15 (1, 7, 7, 64) batch_normalization_15 (1, 3136) dropout_22 (1, 256) dense_14 (1, 10)dropout_23 - 200 - 100 200 1200 100

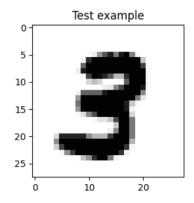
input_8

Creating an ImageDataGenerator

ImageDataGenerator is a brilliant class in keras, which allows us to augment images in real-time while our model is training. This means we can pass it as input to the model, and new augmented images will be generated in batches on the go.

Here is a good explation about the class in more depth: https://deepchecks.com/question/what-is-the-output-of-imagedatagenerator/

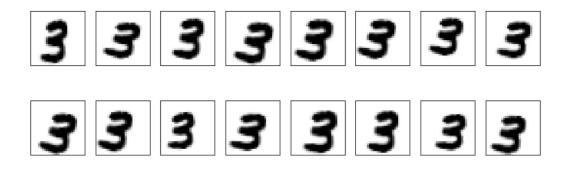
Out[409]: <matplotlib.image.AxesImage at 0x1b6a05e0880>



Lets select a test example for demonstration, and generate some new images using data augmentation.

Augmented images visualized

Augmented images for test example





Here are the artificial images generated. You can see how much variation can be created by slightly modifying just one image.

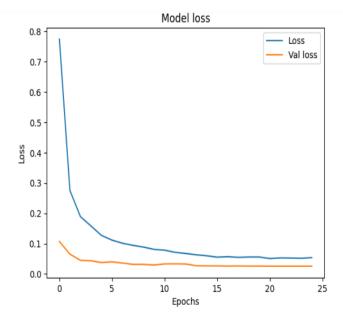
Training network on augmented data

Now we should try training the model again, except this time we will train the model using augmented data.

```
In [423]: M model2, _, _ = build_model()
steps_per_epoch
   Out[425]: 1181
37800 32
 In [427]: ► steps_per_epoch
    Out[427]: 1181
In [428]: M history2 = model2.fit(train_generator, validation_data=(X_val, y_val), epochs=40, steps_per_epoch=steps_per_epoch, callbacks=[keras.callbacks.EarlyStopping(monitor='val_loss',mode='min',patience=10, min_delta=0.005, restore_best_weights=True), keras.callbacks.ReduceLROnPlateau(monitor = 'val_loss', patience = 3)])
             metric: 0.9929 - val_precision_metric: 0.9896 - lr: 1.0000e-06
             Fnoch 23/40
             1181/1181 [==========] - 11s 9ms/step - loss: 0.0517 - accuracy: 0.9844 - f1_metric: 0.9786 - recall_metric: 0.9825 - precision_metric: 0.9747 - val_loss: 0.0257 - val_accuracy: 0.9929 - val_f1_metric: 0.9911 - val_recall_metric: 0.9927 - val_precision_metric: 0.9896 - lr: 1.0000e-06
             Epoch 25/40
```

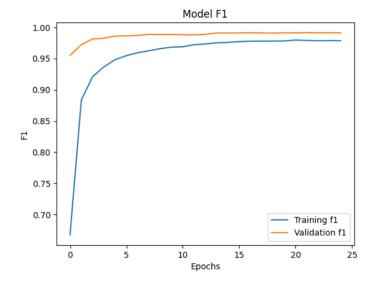
Training the model on augmented data..

```
In [437]: N plt.plot(history2.history['loss'])
    plt.plot(history2.history['val_loss'])
    plt.title('Model loss')
    plt.xlabel('Epochs')
    plt.ylabel('Loss')
    plt.legend(['Loss', 'val loss'])
Out[437]: 
cmatplotlib.legend.Legend at 0x1b695f82fa0>
```



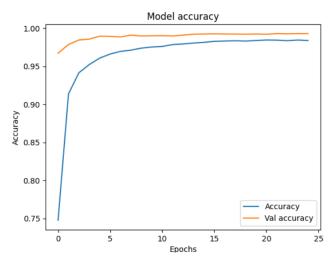
```
In [438]: N plt.plot(history2.history['f1_metric'])
    plt.plot(history2.history['val_f1_metric'])
    plt.title('Model F1')
    plt.xlabel('Epochs')
    plt.ylabel('F1')
    plt.legend(['Training f1','Validation f1'])
```

Out[438]: <matplotlib.legend.Legend at 0x1b696c288b0>

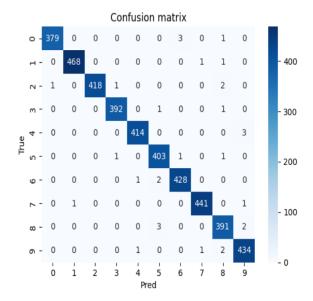


```
In [439]: M plt.plot(history2.history['accuracy'])
    plt.plot(history2.history['val_accuracy'])
    plt.title('Model accuracy')
    plt.xlabel('Epochs')
    plt.ylabel('Accuracy')
    plt.legend(['Accuracy', 'Val accuracy'])
```

Out[439]: <matplotlib.legend.Legend at 0x1b695c41850>



Validation results on augmented data



Hyper-parameter tuning

Now that we've implemented a data augmentation technique, we need find the optimal hyper-parameter settings to maximize model performance. We will use the keras-tuner library, which is a hyperparameter optimization framework containing multiple tuning algorithms including RandomSearch, HyperBand and BayesianOptimization.

```
x = keras.layers.MaxPool2D(pool_size=2)(x)
              x = keras.layers.BatchNormalization()(x)
              x = keras.layers.Dropout(dropout)(x)
x = keras.layers.Flatten()(x)
n_fc_layers = hp.Choice('n_fc_layers', [1,2,3])
fc_choice = hp.Choice('fc_units_combination_choice', [0,1])
fc_combinations_1 = [[128],[256]]
fc_combinations_2 = [[128,64],[256,128]]
fc_combinations_3 = [[512,256,128],[256,128,64]]
if n_fc_layers==1:
               fc_units = fc_combinations_1[fc_choice]
 elif n_fc_layers==2:
fc_units = fc_combinations_2[fc_choice]
elif n fc layers==3:
               fc_units = fc_combinations_3[fc_choice]
for j in range(n_fc_layers):
              x = keras.layers.Dense(fc_units[j], activation='relu')(x)
x = keras.layers.Dropout(hp.Choice('fc_dropout', [0.125,0.25,0.5]))(x)
out = keras.layers.Dense(10, activation='softmax')(x)
model = keras.Model(inputs=inp, outputs=out)
model.compile (loss=keras.losses.CategoricalCrossentropy(), optimizer=keras.optimizers.Adam(learning\_rate=0.0001), optimizer=keras.optimizers.Adam(learning\_rate=0.0001), optimizer=keras.optimizers.Adam(learning\_rate=0.0001), optimizer=keras.optimizers.Adam(learning\_rate=0.0001), optimizer=keras.optimizers.Adam(learning\_rate=0.0001), optimizer=keras.optimizers.Adam(learning\_rate=0.0001), optimizer=keras.optimizers.Adam(learning\_rate=0.0001), optimizer=keras.optimizers.Adam(learning\_rate=0.0001), optimizers.Adam(learning\_rate=0.0001), optimizers.Adam(learnin
                                              metrics=['accuracy', f1_metric, recall_metric, precision_metric])
return model
```

```
{\tt INFO: tensorflow: Reloading\ Oracle\ from\ existing\ project\ .} \\ {\tt hyperband\_results \backslash oracle.json}
             {\tt INFO: tensorflow: Reloading\ Tuner\ from\ .} \\ {\tt hyperband\_results \backslash tuner0.json}
          I tested both RandomSearch and HyperBand, and found HyperBand to be much more successful so we will use that.
 In [126]: H tuner.search_space_summary()
             Search space summary
             Default search space size: 7
             conv block dropout (Choice)
             {'default': 0.125, 'conditions': [], 'values': [0.125, 0.25, 0.375, 0.5], 'ordered': True}
             conv_kernel_size (Choice)
             {'default': 5, 'conditions': [], 'values': [5], 'ordered': True}
             n_conv_blocks (Choice)
              \{ \text{'default': 2, 'conditions': [], 'values': [2, 3, 4], 'ordered': True} \} 
             filter combination choice (Choice)
             {'default': 0, 'conditions': [], 'values': [0, 1, 2, 3], 'ordered': True}
Trial 90 Complete [00h 10m 13s]
             val loss: 0.01791099552065134
             Best val loss So Far: 0.01662298757582903
             Total elapsed time: 05h 29m 10s
             INFO:tensorflow:Oracle triggered exit
          Hyper-parameter results
 dropout_4 (Dropout)
                                      (None, 256)
                                                            0
                                                            2570
              dense 1 (Dense)
                                     (None, 10)
             Total params: 755,914
             Trainable params: 755,146
             Non-trainable params: 768
 In [235]:  y_val_true = np.argmax(y_val,axis=1)
             y_val_pred = np.argmax(top_model.predict(X_val), axis=1) accuracy_score(y_val_true, y_val_pred)
             132/132 [============] - 1s 4ms/step
```

REFERENCES

 $\underline{\text{https://machinelearningmastery.com/how-to-visualize-filters-and-feature-maps-in-convolutional-neural-networks/}$

 $\underline{\text{https://towardsdatascience.com/convolutional-neural-network-feature-map-and-filter-visualization-f75012a5a49c}$

https://www.kaggle.com/code/wonduk/explained-tensorflow-digit-classification