

Software Engineering Is About Tradeoffs

MATEUSZ PUSZ



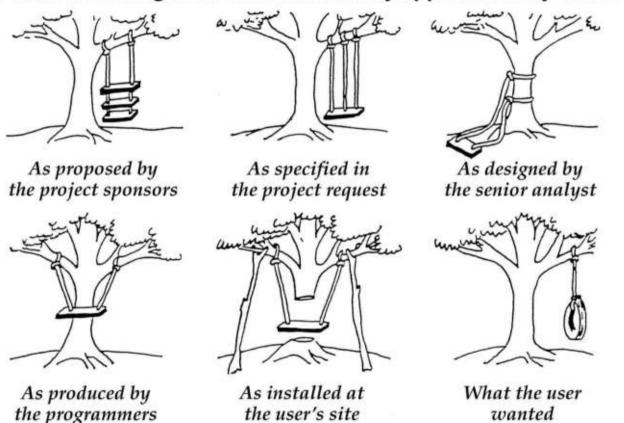


THE ART OF THE SOFTWARE DESIGN

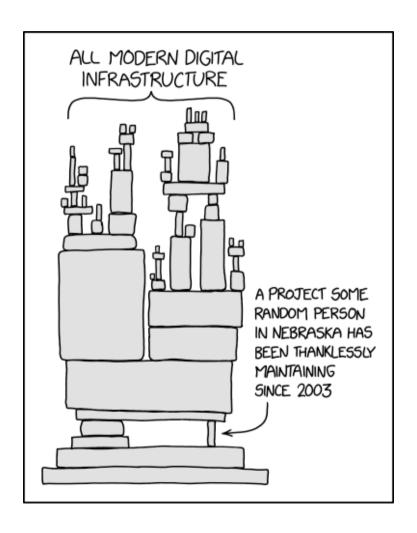


Problem Solving vs. Point Of View

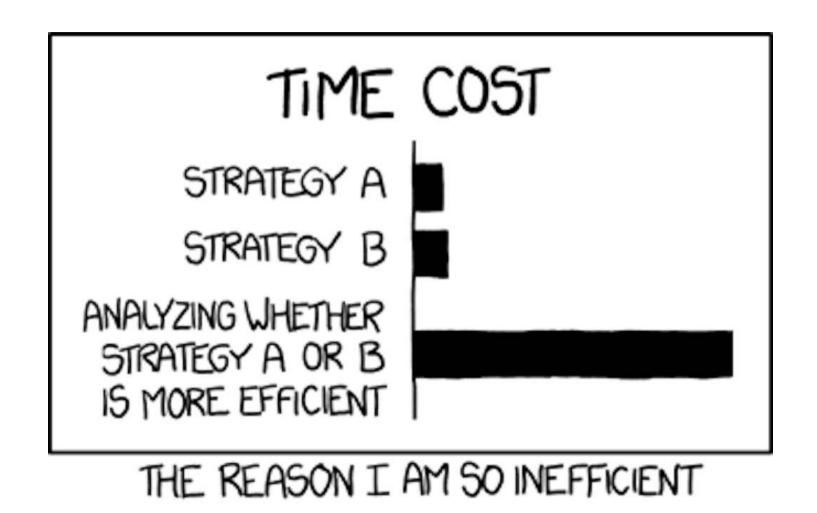
"Problem solving is an art form not fully appreciated by some"



Being Able To See The Whole Picture



The cost of finding the best solution



Let's make some design tradeoffs

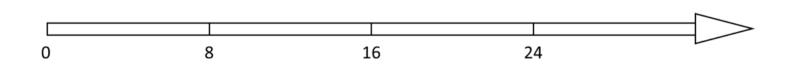
The rest of the talk puts us in the product architect's shoes...

WHAT IS THE BEST STRING?

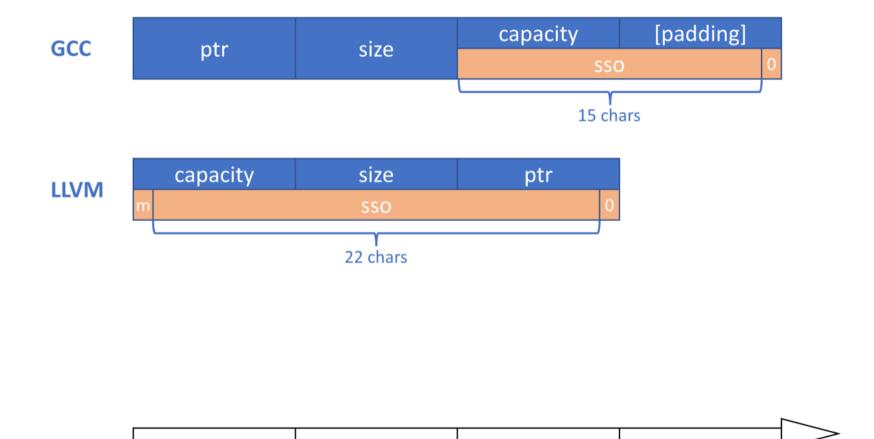


std::string (simplified)





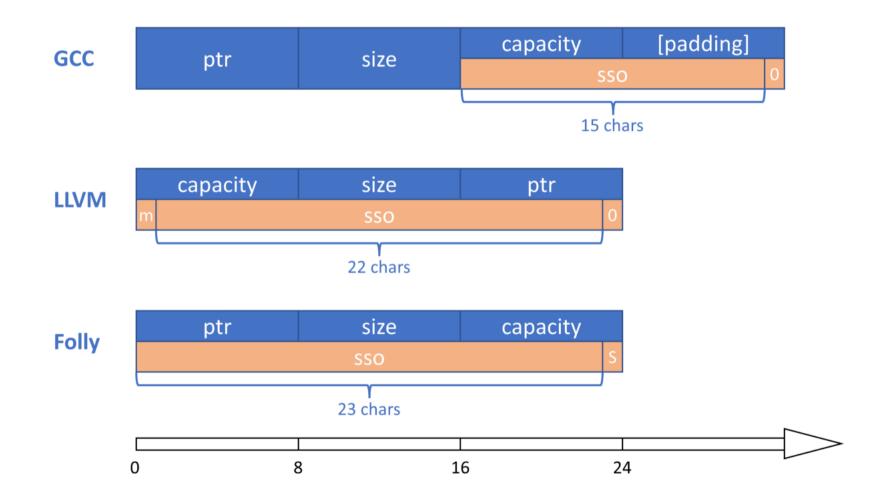
std::string (simplified)



16

24

std::string (simplified)



Small size matters

A major design goal was to minimize **sizeof(string)**, while making the internal buffer as large as possible. The rationale is **to speed move construction and move assignment**. The larger the **sizeof**, the more words you have to move during a move construction or move assignment.

-- Howard Hinnant

22 vs 23 SOO characters

That is clever. However if libc++ adopts <u>it would require libc++ to</u> <u>give up one other characteristic that I like</u> about its **std::string**:

A default constructed string is all 0 bits. That makes <u>default</u>
construction super efficient.

-- Howard Hinnant

Poll: Choose the best solution

FEATURE	GCC	LLVM	FOLLY
Size	32	24	24
SSO size	15	22	23
Move Performance	Slower	Fast	Fast
Branches	capacity() only	Everywhere	Everywhere
Default construct	ptr = SSO data	all zero / fast	S = SSO capacity

DIFFERENT VARIANTS OF EXCEPTION SAFETY GUARANTEES



```
void establish_connections(int first, int last);
int main()
{
   try {
     establish_connections(1, 20);
     // ...
}
   catch(const std::exception& ex) {
     std::cerr << "Unhandled exception: " << ex.what() << "\n";
}
}</pre>
```

```
struct connection {
   explicit connection(int port) : port_(port)
   {
      if(shit_happened())
        throw std::runtime_error("Can't connect!");
   }
   int port() const { return port_; }
   private:
   int port_;
};
```

```
struct connection {
  explicit connection(int port) : port_(port)
  {
    if(shit_happened())
       throw std::runtime_error("Can't connect!");
  }
  int port() const { return port_; }
  private:
    int port_;
};
```

```
std::vector<connection> connections;
```

```
void establish_connections(int first, int last)
 int retry_num = 10;
 while(connections.empty() || connections.back().port() != last) {
    try {
   catch(const std::runtime_error& ex) {
```

```
void establish_connections(int first, int last)
 int retry num = 10;
 while(connections.empty() || connections.back().port() != last) {
    try {
      for(; first<=last; ++first)</pre>
        add_connection(first);
   catch(const std::runtime_error& ex) {
```

```
void establish connections(int first, int last)
  int retry num = 10;
  while(connections.empty() || connections.back().port() != last) {
    try {
      for(; first<=last; ++first)</pre>
        add connection(first);
    catch(const std::runtime_error& ex) {
      if(retry num-- > 0) {
        std::cout << "Exception caught: " << ex.what() << "\n";</pre>
        std::cout << "Retrying...\n";</pre>
      else {
        std::cout << "FAILED\n";</pre>
        throw;
```

```
void add_connection(int port)
{
   connections.emplace_back(port);
}
```



1

When was the last time you reviewed the *exception safety of your algorithm*?

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- 2 How often do you analyse *exception safety of your custom class assignment operator*?

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- 2 How often do you analyse *exception safety of your custom class assignment operator*?
- 3 Which *exception safety the latest library utility* written by you provides?

Exception Safety Guarantees



Exception Safety Guarantees

- 1 Nothrow (or nofail) exception guarantee
- 2 Strong exception guarantee
- 3 Basic exception guarantee
- 4 No exception guarantee

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Only in case of "No exception guarantee" if the function throws an exception, the program may not be in a valid state: resource leaks, memory corruption, or other invariant-destroying errors may have occurred.

The importance of the Exception Safety Guarantees

Even if theoretically known to developers, Exception Safety Guarantees are <u>often ignored in the production code</u>!

Imagine the C++ Standard Library with only Basic Exception Safety Guarantee

Imagine the C++ Standard Library with only Basic Exception Safety Guarantee

```
void add connection(int port)
  if(!connections.empty()) {
    // check if last emplace operation failed
    auto last it = std::prev(connections.end());
    if(connections.dirty(last_it)) {
      // cleanup the container
      connections.erase(last it);
    // insert a new entry
   connections.emplace back(port);
```

What about variant?

std::variant<Types...>::valueless by exception

```
constexpr bool valueless_by_exception() const noexcept; (since C++17)
```

Returns false if and only if the variant holds a value.

Notes

A variant may become valueless in the following situations:

- (guaranteed) an exception is thrown during the move initialization of the contained value from the temporary in copy assignment
- (guaranteed) an exception is thrown during the move initialization of the contained value during move assignment
- (optionally) an exception is thrown when initializing the contained value during a type-changing assignment
- (optionally) an exception is thrown when initializing the contained value during a type-changing emplace

Since variant is never permitted to allocate dynamic memory, previous value cannot be retained in these situations.

This applies even to variants of non-class types:

```
struct S {
    operator int() { throw 42; }
};
std::variant<float, int> v{12.f}; // OK
v.emplace<1>(S()); // v may be valueless
```

Example

```
struct basic_socket {
    // ...
};

struct fast_socket {
    fast_socket() = default;
    fast_socket(const fast_socket&)
    { throw std::runtime_error("Kernel bypass drivers not installed!"); }
    // ...
};

using socket = std::variant<basic_socket, fast_socket>;
```

What about variant?

```
void process(socket& s)
  trv {
    std::cout << "Trying to switch a socket to a fast one\n";</pre>
    s = fast socket{};
  catch(const std::exception&) {
    if(s.valueless_by_exception()) {
      std::cout << "Resetting socket to a basic one\n";</pre>
      s = basic_socket{};
```

"Never-Empty" Guarantee of Boost.Variant



"Never-Empty" Guarantee of Boost.Variant

IN CASE OF A POTENTIALLY THROWING COPY-CONSTRUCTION

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- In the event of failure, copy **backup** to the left-hand side storage
- 5 In the event of success, deallocate the data pointed to by backup

Provides a strong exception safety with the potential cost of a dynamic memory allocation. **boost::variant** does not provide allocator support.

Poll: Choose the best solution



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SOLUTION #1: std::variant

- Basic Exception Safety only
 - invalid state possible
 - manual cleanup may be needed
- Never allocates memory
 - fast
 - can be easily used in an embedded or constrained environment

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SOLUTION #2: boost::variant

- Strong Exception Safety
 - no invalid states
 - no need for a manual cleanup
- Dynamic memory allocations
 - slow
 - may fail
 - no allocator support
 - no-go for some projects (i.e. embedded, safety-critical, hard real-time, ...)

QUANTITY CREATION HELPERS

mp-units



Quantity

Property of a phenomenon, body, or substance, where the property has a magnitude that can be expressed by means of a number and a reference. A reference can be a measurement unit,

• • •

-- ISO 80000

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Property of a phenomenon, body, or substance, where the property has a magnitude that can be expressed by means of a number and a reference. A reference can be a measurement unit,

• • •

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EXAMPLE

- 123 kilometers of length
- 70 kilometers per hour of speed

units::quantity class template

```
template<Dimension D, UnitOf<D> U, Representation Rep = double>
class units::quantity;
```

units::quantity class template

```
template<Dimension D, UnitOf<D> U, Representation Rep = double>
class units::quantity;

units::quantity<units::isq::si::dim_length, units::isq::si::kilometre> d(123);
units::quantity<units::isq::si::dim_speed, units::isq::si::kilometre_per_hour, int> v(70);
```

units::quantity class template

```
template<Dimension D, UnitOf<D> U, Representation Rep = double>
class units::quantity;

units::quantity<units::isq::si::dim_length, units::isq::si::kilometre> d(123);
units::quantity<units::isq::si::dim_speed, units::isq::si::kilometre_per_hour, int> v(70);
```

Above quantity type is verbose to type so some helpers should be provided to improve users experience.

Solution #1: Dimension-Specific Aliases

• Helper aliases provided for *quantities of each dimension*

```
namespace si {

template<Unit U, Representation Rep = double>
using length = quantity<dim_length, U, Rep>;

template<Unit U, Representation Rep = double>
using speed = quantity<dim_speed, U, Rep>;
}
```

Solution #1: Dimension-Specific Aliases: Example

```
units::isq::si::length<units::isq::si::kilometre> d(123);
units::isq::si::speed<units::isq::si::kilometre_per_hour, int> v(70);
```

Solution #1: Dimension-Specific Aliases

PROS

- Cheap to standardize (only one per dimension)
- Fast to compile (alias template)
- Works both for literals and regular variables

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PROS

- Cheap to standardize (only one per dimension)
- Fast to compile (alias template)
- Works both for literals and regular variables

CONS

- Still quite verbose to type
 - i.e. namespace has to be repeated for a unit
- CTAD for alias templates does not work
 - cannot deduce a representation type from the initializer

Solution #2: Unit-Specific Aliases

• Provided for *quantities of each unit in the library*

```
namespace units::aliases::isq::si::inline length {
  template<Representation Rep = double>
  using km = units::isq::si::length<units::isq::si::kilometre, Rep>;
}
namespace units::aliases::isq::si::inline speed {
  template<Representation Rep = double>
  using km_per_h = units::isq::si::speed<units::isq::si::kilometre_per_hour, Rep>;
}
```

Solution #2: Unit-Specific Aliases: Example

```
using namespace units::aliases::isq;
si::length::km<> d(123);
si::speed::km_per_h<int> v(70);
```

Solution #2: Unit-Specific Aliases: Example

```
using namespace units::aliases::isq;
si::length::km<> d(123);
si::speed::km_per_h<int> v(70);
```

With C++20 CTAD for alias templates

```
using namespace units::aliases::isq;
si::length::km d(123.);
si::speed::km_per_h v(70);
```

Solution #2: Unit-Specific Aliases: Example

```
using namespace units::aliases::isq;
si::length::km<> d(123);
si::speed::km_per_h<int> v(70);
```

With C++20 CTAD for alias templates

```
using namespace units::aliases::isq;
si::length::km d(123.);
si::speed::km_per_h v(70);
```

Possibility to be more terse if desired

```
using namespace units::aliases::isq::si;
auto d = km(123.);
auto v = km_per_h(70);
```

Solution #2: Unit-Specific Aliases

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CONS

Expensive to standardize (every unit of every dimension)

Solution #3: Quantity References

Provided for named units only

```
namespace length references {
inline constexpr auto km = reference<dim length, kilometre>{};
  // namespace length references
namespace time references {
inline constexpr auto h = reference<dim time, hour>{};
  // namespace time references
namespace references {
using namespace length references;
using namespace time references;
   // namespace references
```

Solution #3: Quantity References: Example

Solution #3: Quantity References: Example

• It is also possible to easily define custom quantity references from existing ones

```
inline constexpr auto km_per_h = km / h;
auto v = 70 * km_per_h; // si::speed<si::kilometre_per_hour, int>
```

Solution #3: Quantity References

PROS

- Medium effort to standardize as provided only for named units
- Works both for literals and regular variables
- Easy to compose custom references for unnamed derived units

Solution #3: Quantity References

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- Medium effort to standardize as provided only for named units
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- Easy to compose custom references for unnamed derived units

CONS

- Slower to compile (class template instantiation)
- Sometimes awkward to type

```
- 20 * (m / s) / (10 * (m / (s * s)))
```

- Objects with short names often shadow user's local variables (i.e. m, t, N, ...)
- Sometimes hard to understand

```
constexpr Speed auto avg_speed(double d, double t)
{
  return d * m / (t * s);
}
```

Solution #4: User Defined Literals

• Integral and a floating-point version provided for quantity of each unit

```
inline namespace literals {
constexpr auto operator"" q_km(unsigned long long l) {
  return length<kilometre, std::int64 t>(l);
constexpr auto operator"" q km(long double l) {
  return length<kilometre, long double>(l);
constexpr auto operator"" q km per h(unsigned long long l) {
  return speed<kilometre per hour, std::int64 t>(l);
constexpr auto operator"" q_km_per_h(long double l) {
  return speed<kilometre per hour, long double>(l);
     namespace literals
```

Solution #4: User Defined Literals: Example

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PROS

- Compatible with **std::chrono::duration**
- Terse and easy to understand

Solution #4: User Defined Literals: Example

PROS

- Compatible with std::chrono::duration
- Terse and easy to understand

CONS

- The slowest to compile
- The most expensive to standardize (2 instances per every unit)
- Works only for literals (not for common variables)
- No control over the representation type (only std::int64_t or long double)
- Cannot be disambiguated with the namespace name
 - i.e. collisions between **cm** in SI and CGS

Standardization takes time

• We could provide all of the options for standardization...

Standardization takes time

- We could provide all of the options for standardization...
- ... but most probably it would not be accepted

Standardization takes time

- We could provide all of the options for standardization...
- ... but most probably it would not be accepted
- Time needed to
 - discuss in working groups
 - prepare the ISO specification
 - implement in various implementations of the C++ Standard Library
 - teach and learn by the C++ Community



SOLUTION #1: DIMENSION ALIASES

```
si::length<si::kilometre> d(123);
si::speed<si::kilometre_per_hour, int> v(70);
```

SOLUTION #1: DIMENSION ALIASES

```
si::length<si::kilometre> d(123);
si::speed<si::kilometre_per_hour, int> v(70);
```

SOLUTION #2: UNIT ALIASES

```
si::length::km<> d(123);
si::speed::km_per_h<int> v(70);
```

SOLUTION #1: DIMENSION ALIASES

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si::length<si::kilometre> d(123);
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```

SOLUTION #2: UNIT ALIASES

```
si::length::km<> d(123);
si::speed::km_per_h<int> v(70);
auto v = km_per_h(70);
```

SOLUTION #1: DIMENSION ALIASES

```
si::length<si::kilometre> d(123);
si::speed<si::kilometre_per_hour, int> v(70);
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SOLUTION #2: UNIT ALIASES

```
si::length::km<> d(123);
si::speed::km_per_h<int> v(70);
auto d = km(123.);
auto v = km_per_h(70);
```

SOLUTION #3: QUANTITY REFERENCES

```
auto d = 123. * km;
auto v = 70 * (km / h);
```

SOLUTION #1: DIMENSION ALIASES

```
si::length<si::kilometre> d(123);
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SOLUTION #2: UNIT ALIASES

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si::length::km<> d(123);
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auto v = km_per_h(70);
```

SOLUTION #3: QUANTITY REFERENCES

```
auto d = 123. * km;
auto v = 70 * (km / h);
```

SOLUTION #4: UDLS

```
auto d = 123.q_km;
auto v = 70q_km_per_h;
```

Poll: Choose the best solution

FEATURE	#1 DIMENSION ALIASES	#2 UNIT ALIASES	#3 REFERENCES	#4 UDLS
Literals and variables support	Yes	Yes	Yes	Literals only
Preserves user provided representation type	No	Yes	Yes	No
Explicit control over the representation type	Yes	Yes	No	No
Readability	Medium	Good	Medium	Good
Possibility to resolve ambiguity	Yes	Yes	Yes	No
Hard to resolve shadowing issues	No	No	Yes	No
Controlled verbosity	No	Yes	No	No
Easy composition for derived units	No	No	Yes	No
Implementation and standardization effort	Lowest	High	Medium	Highest
Compile-time performance	Fastest	Fast	Medium	Slowest

THE DOWNCASTING FACILITY

mp-units



```
using namespace units::isq;

constexpr Speed auto avg_speed(Length auto d, Time auto t)
{
   const auto s = d / t;
   std::cout << s << "\n";
   return s;
}</pre>
```

```
using namespace units::isq;

constexpr Speed auto avg_speed(Length auto d, Time auto t)
{
  const auto s = d / t;
  std::cout << s << "\n";
  return s;
}</pre>
```

```
using namespace units::isq::si::references;
auto s = avg_speed(140 * km, 2 * h);
```

```
using namespace units::isq;

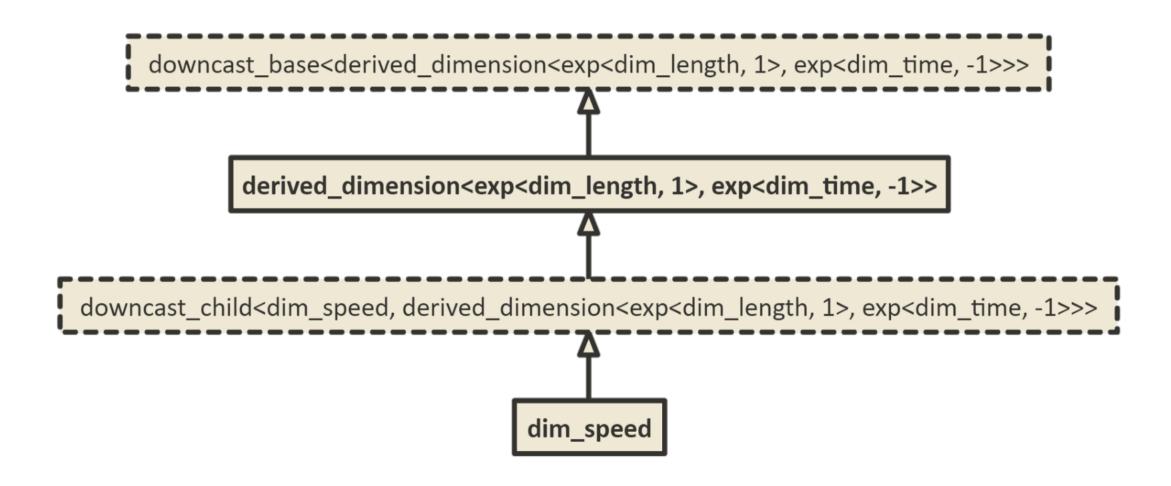
constexpr Speed auto avg_speed(Length auto d, Time auto t)
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  std::cout << s << "\n";
  return s;
}</pre>
```

```
using namespace units::isq::si::references;
auto s = avg_speed(140 * km, 2 * h);
```

70 km/h

```
using namespace units::isq;
constexpr Speed auto avg speed(Length auto d, Time auto t)
  const auto s = d / t;
   std::cout << s << "\n";
   return s:
using namespace units::isq::si::references;
auto s = avg speed(140 * km, 2 * h);
(qdb) ptype s
type = class units::quantity<<mark>units::isq::si::dim speed</mark>, units::isq::si::kilometre per hour, int>
[with D = units::isq::si::dim speed, U = units::isq::si::kilometre per hour, Rep = int] {
```

Downcasting facility (Version 2.0): Overview



One Definition Rule (ODR) - Translation Unit

Only one definition of any variable, function, class type, enumeration type, concept or template is allowed in any one translation unit.

One Definition Rule (ODR) - Program

- One and only one definition of every non-inline function or variable that is odr-used is required to appear in the entire program
- For an inline function or inline variable, a definition is required in every translation unit where it is odrused
- One and only one definition of a class is required to appear in any translation unit where the class is used in a way that requires it to be complete

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but ...

One Definition Rule (ODR) - Program

There can be more than one definition in a program, as long as

- each definition appears in a different translation unit
- each definition *consists of the same sequence of tokens*
- name lookup from within each definition finds the same entities
- overloaded operators, including conversion, allocation, and deallocation functions refer to the same function
- the language *linkage* is the same

If all these requirements are satisfied, the program behaves as if there is only one definition in the entire program. Otherwise, the behavior is undefined.

Problem: One Definition Rule Violation

avg_speed.h

```
constexpr units::isq::Speed auto avg_speed(units::isq::Length auto d, units::isq::Time auto t)
{
  const auto s = d / t;
  std::cout << s << "\n";
  return s;
}</pre>
```

Problem: One Definition Rule Violation

avg_speed.h

```
constexpr units::isq::Speed auto avg_speed(units::isq::Length auto d, units::isq::Time auto t)
{
  const auto s = d / t;
  std::cout << s << "\n";
  return s;
}</pre>
```

file_1.cpp

```
#include "avg_speed.h"
#include <units/isq/si/speed.h>

void foo()
{
   auto s = avg_speed(140 * km, 2 * h);
   // ...
}
```

70 km/h

Problem: One Definition Rule Violation

avg_speed.h

```
constexpr units::isq::Speed auto avg_speed(units::isq::Length auto d, units::isq::Time auto t)
{
  const auto s = d / t;
  std::cout << s << "\n";
  return s;
}</pre>
```

file_1.cpp

```
#include "avg_speed.h"
#include <units/isq/si/speed.h>

void foo()
{
   auto s = avg_speed(140 * km, 2 * h);
   // ...
}
```

70 km/h

file_2.cpp

```
#include "avg_speed.h"

void boo()
{
  auto s = avg_speed(140 * km, 2 * h);
  // ...
}
```

 $70 [1/36 \times 10^{1}] \text{ m/s}$

But this is how some customization points behave...

ab.h

```
struct A { int value; };
struct B { int value; A* a; };
std::ostream& operator<<(std::ostream& os, const B& b)
{ return os << "[" << b.value << ", " << b.a->value << "]"; }</pre>
```

But this is how some customization points behave...

ab.h

```
struct A { int value; };
struct B { int value; A* a; };
std::ostream& operator<<(std::ostream& os, const B& b)
{ return os << "[" << b.value << ", " << b.a->value << "]"; }</pre>
```

file_1.cpp

```
#include "ab.h"

void swap(B& lhs, B& rhs) noexcept
{ std::ranges::swap(lhs.value, rhs.value); }

void foo()
{
    A a1{1}, a2{2};
    B b1{1, &a1}, b2{2, &a2};
    std::ranges::swap(b1, b2);
    std::cout << "b1: " << b1 << ", b2: " << b2 << "\n";
}</pre>
```

b1: [2, 1], b2: [1, 2]

But this is how some customization points behave...

ab.h

```
struct A { int value; };
struct B { int value; A* a; };
std::ostream& operator<<(std::ostream& os, const B& b)
{ return os << "[" << b.value << ", " << b.a->value << "]"; }</pre>
```

file_1.cpp

```
#include "ab.h"

void swap(B& lhs, B& rhs) noexcept
{ std::ranges::swap(lhs.value, rhs.value); }

void foo()
{
    A a1{1}, a2{2};
    B b1{1, &a1}, b2{2, &a2};
    std::ranges::swap(b1, b2);
    std::cout << "b1: " << b1 << ", b2: " << b2 << "\n";
}</pre>
```

b1: [2, 1], b2: [1, 2]

file_2.cpp

```
#include "ab.h"

void boo()
{
    A a1{1}, a2{2};
    B b1{1, &a1}, b2{2, &a2};
    std::ranges::swap(b1, b2);
    std::cout << "b1: " << b1 << ", b2: " << b2 << "\n";
}</pre>
```

b1: [2, 2], b2: [1, 1]

However many will not compile without the definition

ab.h

file_1.cpp

```
#include "ab.h"

void foo()
{
    A a1{1}, a2{2};
    B b1{1, &a1}, b2{2, &a2};
    std::cout << "b1: " << b1 << ", b2: " << b2 << "\n";
}</pre>
```

Solution #1: Keep it as it is

- We get **speed** when such definition is included by the user
 - an unknown_dimension<exp<length, 1>, exp<time, -1>> otherwise
- Document the fact that the same physical system definition (the same set of header files) has to be included in all translation units
- C++20 modules should help
 - i.e. **units.isq.si** module includes definitions of all the SI quantities

Solution #2: Compile-time error when resulting dimension or unit is undefined

- No support for an unknown_dimension<exp<length, 1>, exp<time, -1>> at all
- Everything will have to be predefined
 - even if it is just some partial result of some arithmetic calculation that in the end will result in a known dimension/unit

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```
Speed auto velocity = km_per_h(160);
Speed auto sink_rate = m_per_s(0.7);
auto temp = pow<2>(velocity) + pow<2>(sink_rate); // will not compile
speed::km_per_h s1 = sqrt(temp);
speed::km_per_h s2 = sqrt(pow<2>(velocity) + pow<2>(sink_rate)); // will not compile
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```

May constrain the library too much.

• The user should be responsible for providing a specific type

```
auto s1 = 120 * km / (2 * h);
si::speed<si::kilometre_per_hour> s2 = s1;
std::cout << s2 << "\n";</pre>
```

- s1 always results with an unknown_dimension<exp<length, 1>, exp<time, -1>>
 - the result printed in terms of base units
- s2 has a type explicitly provided by the user and implicitly converts from s1
 - output printed as expected

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Removing the Downcasting Facility simplifies the standardization effort as well.

How to provide a specific type for the following?

```
constexpr units::isq::Speed auto avg_speed(units::isq::Length auto d, units::isq::Time auto t)
{
  const auto s = d / t;
  std::cout << s << "\n";
  return s;
}</pre>
```

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constexpr units::isq::Speed auto avg_speed(units::isq::Length auto d, units::isq::Time auto t)
{
  const auto s = d / t;
  std::cout << s << "\n";
  return s;
}</pre>
```

This is not only about printing the output on the console. Types are affected as well which results with:

- long compilation errors
- poor debugging experience

Poll: Choose the best solution

- 1 Keep it as it is
- 2 Compile-time error when resulting dimension or unit is undefined
- 3 Get rid of the Downcasting Facility

DESIGNING IS HARD



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 - expectations
 - experience
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Please help: https://mpusz.github.io/units!



CAUTION **Programming** is addictive (and too much fun)