Dynamic Treatment Regimes and Interference: Recent Developments in Estimation and Implementation

Michael Wallace Associate Professor University of Waterloo

Smoking Cessation

Motivating example:

- Goal: Reduce cigarette dependence.
- o Intervention: e-cigarette use.



Smoking Cessation

Motivating example:

- Goal: Reduce cigarette dependence.
- o Intervention: e-cigarette use.
- Method: Personalized decision-making.
- o Challenge: Interference.



Precision Medicine

A personalized treatment rule example:

"If age ≥ 35 , recommend e-cigarettes, otherwise recommend alternative therapy."

Question: How do we choose the best decision rule?
 Should age cut-off be 25, 35, 45?

The Data

Some hypothetical data:

		e-cigarette	Dependence at
Participant	Age	use?	3 months
1	53	No	57
2	25	Yes	35
3	28	Yes	40
4	41	Yes	21
5	27	No	42

Some hypothetical data:

		e-cigarette	Dependence at
Participant	Age	use?	3 months
1	53	No	57
2	25	Yes	35
3	28	Yes	40
4	41	Yes	21
5	27	No	42



Goal: Identify treatment A that optimizes E[Y|X,A]

$$\underbrace{\mathcal{E}[Y|X,A]}_{\mbox{Expected outcome}} \qquad \qquad A \in \{0,1\}$$
 Expected outcome (to be maximized)

$$\underbrace{E[Y|X,A]}_{\text{Expected outcome}} \qquad A \in \{0,1\}$$

$$\text{Expected outcome}$$
(to be maximized)

We might propose the following model

$$E[Y|X,A;\beta,\psi] = \beta_0 + \beta_1 X + A(\psi_0 + \psi_1 X)$$

$$\underbrace{E[Y|X,A]}_{\text{Expected outcome}} \qquad A \in \{0,1\}$$

$$\text{Expected outcome}$$
(to be maximized)

We might propose the following model

$$E[Y|X, A; \beta, \psi] = \beta_0 + \beta_1 X + A(\psi_0 + \psi_1 X)$$

"Recommend e-cigarettes (A=1) if $\psi_0 + \psi_1 X > 0$ "

$$\underbrace{E[Y|X,A]}_{\text{Expected outcome}} \qquad A \in \{0,1\}$$

$$\text{Expected outcome}$$
(to be maximized)

We might propose the following model

$$E[Y|X, A; \beta, \psi] = \beta_0 + \beta_1 X + A(\psi_0 + \psi_1 X)$$

"Recommend e-cigarettes (A=1) if $\psi_0 + \psi_1 X > 0$ "

More generally:

$$\underbrace{Expected \ \text{outcome}}_{\text{(to be maximized)}} = \underbrace{Impact \ \text{of patient history}}_{\text{in the absence of treatment}} = \underbrace{Impact \ \text{of noutcome}}_{\text{on outcome}} = \underbrace{F[Y|X,A;\beta,\psi]}_{\text{on outcome}} = \underbrace{F[X;X]}_{\text{on outcome}} + \underbrace{F[X;X]}_{\text{on outcome}} = \underbrace{F[X;X]}_{\text{outcome}} = \underbrace{$$

$$\underbrace{E[Y|X,A]}_{\text{Expected outcome}} \qquad A \in \{0,1\}$$

$$\text{Expected outcome}$$
(to be maximized)

We might propose the following model

$$E[Y|X, A; \beta, \psi] = \beta_0 + \beta_1 X + A(\psi_0 + \psi_1 X)$$

"Recommend e-cigarettes (A=1) if $\psi_0 + \psi_1 X > 0$ "

More generally:

Expected outcome (to be maximized)
$$\underbrace{F[Y|X,A;\beta,\psi]}_{\text{Treatment-free}} = \underbrace{F[X,A;\psi]}_{\text{Treatment-free}} + \underbrace{F[X,A;\psi]}_{\text{Treatment-free}}$$

• Simplifies focus: choose A that maximizes $\gamma(X, A; \psi)$.

Suppose the true outcome model is:

$$E[Y|X, A; \beta, \psi] = \beta_0 + \beta_1 X + \beta_2 X^2 + A(\psi_0 + \psi_1 X)$$



Suppose the true outcome model is:

$$E[Y|X, A; \beta, \psi] = \beta_0 + \beta_1 X + \beta_2 X^2 + A(\psi_0 + \psi_1 X)$$

o But we propose:

$$E[Y|X, A; \beta, \psi] = \beta_0 + \beta_1 X + A(\psi_0 + \psi_1 X)$$



Suppose the true outcome model is:

$$E[Y|X, A; \beta, \psi] = \beta_0 + \beta_1 X + \beta_2 X^2 + A(\psi_0 + \psi_1 X)$$

Out we propose:

$$E[Y|X,A;\beta,\psi] = \beta_0 + \beta_1 X + A(\psi_0 + \psi_1 X)$$

 \circ Problem: A depends on $X \implies \psi_0, \psi_1$ mis-estimated.



Suppose the true outcome model is:

$$E[Y|X, A; \beta, \psi] = \beta_0 + \beta_1 X + \beta_2 X^2 + A(\psi_0 + \psi_1 X)$$

o But we propose:

$$E[Y|X, A; \beta, \psi] = \beta_0 + \beta_1 X + A(\psi_0 + \psi_1 X)$$

- \circ Problem: A depends on $X \implies \psi_0, \psi_1$ mis-estimated.
- o Solution: Account for this dependency.



Dynamic WOLS (dWOLS)

$$E[Y|X,A;\beta,\psi] = G(X;\beta) + \gamma(X,A;\psi)$$

- Three models to specify:
 - 1. Treatment-free model: $G(X; \beta)$.
 - 2. Blip model: $\gamma(X, A; \psi)$.
 - 3. Treatment model: $P(A = 1|X; \alpha)$.



Dynamic WOLS (dWOLS)

$$E[Y|X,A;\beta,\psi] = G(X;\beta) + \gamma(X,A;\psi)$$

- o Three models to specify:
 - 1. Treatment-free model: $G(X; \beta)$.
 - 2. Blip model: $\gamma(X, A; \psi)$.
 - 3. Treatment model: $P(A = 1|X; \alpha)$.
- Estimate ψ via WOLS of Y on covariates in blip and treatment-free models, with weights $w = |A P(A = 1|X; \hat{\alpha})| = |A \pi(X)|$.

• Suppose the true outcome model is:

$$E[Y|X, A; \beta, \psi] = \beta_0 + \beta_1 X + \beta_2 X^2 + A(\psi_0 + \psi_1 X)$$



• Suppose the true outcome model is:

$$E[Y|X, A; \beta, \psi] = \beta_0 + \beta_1 X + \beta_2 X^2 + A(\psi_0 + \psi_1 X)$$

Out we propose:

$$E[Y|X, A; \beta, \psi] = \beta_0 + \beta_1 X + A(\psi_0 + \psi_1 X)$$



Suppose the true outcome model is:

$$E[Y|X, A; \beta, \psi] = \beta_0 + \beta_1 X + \beta_2 X^2 + A(\psi_0 + \psi_1 X)$$

o But we propose:

$$E[Y|X, A; \beta, \psi] = \beta_0 + \beta_1 X + A(\psi_0 + \psi_1 X)$$

• WOLS with weights $w = |A - P(A = 1|X; \hat{\alpha})| = |A - \pi(X)|$ will still yield consistent estimators of ψ_0, ψ_1 .



Suppose the true outcome model is:

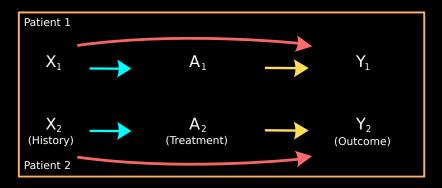
$$E[Y|X, A; \beta, \psi] = \beta_0 + \beta_1 X + \beta_2 X^2 + A(\psi_0 + \psi_1 X)$$

Out we propose:

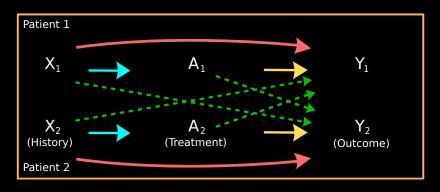
$$E[Y|X, A; \beta, \psi] = \beta_0 + \beta_1 X + A(\psi_0 + \psi_1 X)$$

- WOLS with weights $w = |A P(A = 1|X; \hat{\alpha})| = |A \pi(X)|$ will still yield consistent estimators of ψ_0, ψ_1 .
- Estimators are "doubly robust": consistent if at least one of treatment-free or treatment components correctly specified.
- The blip must always be correct.

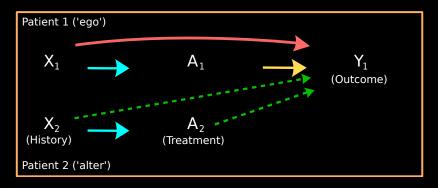




Challenge: Account for others.



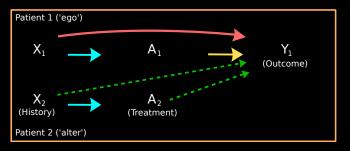
Challenge: Interference between neighbours.



Approach: Identify study unit ('ego') and neighbours ('alters').

We might propose the following model

$$E[Y_1|X_1, X_2, A_1, A_2; \beta, \psi] = \beta_0 + \beta_1 X_1 + \beta_2 A_2 + A_1(\psi_0 + \psi_1 X_1 + \psi_2 A_2)$$



 \circ More generally, let \mathcal{N}_i denote neighbours of ego i.

- \circ More generally, let \mathcal{N}_i denote neighbours of ego i.
- ∘ Let $t(A_{N_i})$ = some function of neighbours' treatments, e.g.:
 - The number or proportion of treated neighbours.
 - The existence of a treated neighbour.

- o More generally, let \mathcal{N}_i denote neighbours of ego i.
- ∘ Let $t(A_{N_i})$ = some function of neighbours' treatments, e.g.:
 - The number or proportion of treated neighbours.
 - The existence of a treated neighbour.
- Then can generalize outcome model to:

$$E[Y_i|\cdot] = \beta_0 + \beta_1 X_i + \beta_2 t(A_{\mathcal{N}_i}) + A_i(\psi_0 + \psi_1 X_i + \psi_2 t(A_{\mathcal{N}_i}))$$

Network Propensity Function

Network propensity function for individual i with neighbours \mathcal{N}_i and treated neighbours $S_{i,A}$:

$$\pi_{i,A_i,S_{i,A}}(X_i,\mathcal{N}_i,X_{\mathcal{N}_i}) = P(A_i \cap S_{i,A}|X_i,\mathcal{N}_i,X_{\mathcal{N}_i})$$

$$= \overbrace{\pi_i(X_i)^{A_i}(1-\pi_i(X_i))^{1-A_i}}^{\text{Individual } i} \cdot \overbrace{\prod_{j \in S_{j,A}} \pi_j(X_j)}^{\text{Treated}} \cdot \overbrace{\prod_{j \in \mathcal{N}_i \setminus S_{i,a}}^{\text{Untreated neighbours}}}^{\text{Untreated neighbours}}$$

Network Propensity Weights

dWOLS may be extended using the network propensity function, for example, WOLS for the outcome model

$$E[Y_i|X_i,X_{\mathcal{N}_i},A_i,A_{\mathcal{N}_i};\beta,\psi] = \beta_0 + \beta_1X_i + \beta_2t(A_{\mathcal{N}_i}) + A_i(\psi_0 + \psi_1X_i + \psi_2A_{\mathcal{N}_i})$$

with weights

Absolute weight for unit
$$i$$

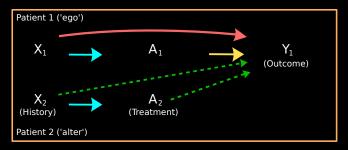
$$w_i = |A_i - P(A_i = 1 | X_i = x_i)| \cdot \prod_{j \in \mathcal{N}_i} |A_j - P(A_j = 1 | X_j)|$$

which retains the double robustness property.

Note: This is not the only viable weight function!

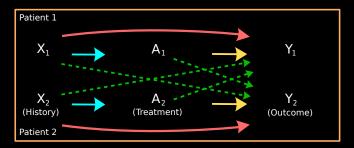
Extension: Simultaneous Optimization

o Limitation: Assumes an 'ego' setup:



Extension: Simultaneous Optimization

 Extension in a dyadic structure: identify and optimize a dyad-health function.



Extension: Ordinal Outcomes

o Limitation: Assumes a continuous outcome.

Extension: Ordinal Outcomes

- o Limitation: Assumes a continuous outcome.
- dWOLS: Extended to numerous other outcome types in the absence of interference.

Extension: Ordinal Outcomes

- Limitation: Assumes a continuous outcome.
- dWOLS: Extended to numerous other outcome types in the absence of interference.
- dWPOM: A dWOLS extension for ordinal outcomes with interference, via proportional odds model.

Extension: Hierarchical Models

Limitation: Only within-group interference assumed.

Neighbourhood A

Household A1

Household A2

Within-group interference

Extension: Hierarchical Models

But: Between-group interference can arise.



Extension: Hierarchical Models

Hierarchical structures of interference can evolve.



Summary

- o Interference an important challenge for precision medicine.
- Progress in addressing interference for continuous, ordinal, and utility-based outcomes.

Summary

- o Interference an important challenge for precision medicine.
- Progress in addressing interference for continuous, ordinal, and utility-based outcomes.
- Methods have been applied to the Population Assessment of Tobacco Heatlh (PATH) Study.

Summary

- o Interference an important challenge for precision medicine.
- Progress in addressing interference for continuous, ordinal, and utility-based outcomes.
- Methods have been applied to the Population Assessment of Tobacco Heatlh (PATH) Study.
- Upcoming work to address hierarchical structures.
- Future work concerns logistical challenges such as cost constraints and implementation of treatment regimes.

Acknowledgments



Cong Jiang cong.jiang@umontreal.ca dWOLS extensions



Marzieh Mussavi Rizi mmussavirizi@uwaterloo.ca Dyad-health function



Alexandra Mossman a2mossman@uwaterloo.ca Hierarchical models



- dWOLS: M. P. Wallace and E. E. M. Moodie (2015). Doubly-robust dynamic treatment regimen estimation via weighted least squares. Biometrics 71(3) 636-644.
- Network Propensity Weights (main result presented): C. Jiang, M. P. Wallace and M. E. Thompson (2023). Dynamic treatment regimes with interference. Canadian Journal of Statistics 51(2) 469-502.
- Ordinal outcomes: C. Jiang, M. E. Thompson, and , M. P. Wallace (2024). Estimating dynamic treatment regimes for ordinal outcomes with household interference: Application in household smoking cessation. arXiv:2306.12865, Statistical Methods in Medical Research (Accepted).
- Dyadic Networks: M. Mussavi Rizi, J. A. Dubin, and M. P. Wallace (2023). Dynamic Treatment Regimes on Dyadic Networks. Statistics in Medicine (in review, please contact me!).

michael.wallace@uwaterloo.ca mpwallace.github.io