



## Yoshiki Obinata

📍 Tokyo, Japan  
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🔗 <https://github.com/mqcmd196>

Born 3 April 1998

### WORK EXPERIENCE

May 2021 – present

#### Technical Assistant Staff / Parttime

JSK Robotics Lab, The University of Tokyo  
• Developing and maintaining the robot software.

December 2018 – June 2019

#### Software Engineer / Internship

OTOKORO.com  
• Developing of an automated data analysis platform.

August 2017 – present

#### Software Engineer / Parttime

Aidemy  
• Developing the education service of machine-learning-programming.

### EDUCATION

2021 – present

#### Master's degree in Information Science and Technology

Graduate School of Information Science and Technology, The University of Tokyo  
• Major in Mechano-Informatics  
• Belong to JSK Robotics Lab and supervised by Prof.Kei Okada

2017 – 2021

#### Bachelor's degree in Engineering

Faculty of Engineering, The University of Tokyo  
• Department of Mechano-Informatics  
• Belong to JSK Robotics Lab and supervised by Prof.Kei Okada (2020 - 2021)

### SKILLS

**Languages** Japanese, English, Chinese

**Software Skills** Advanced  
• Python(NumPy, PyTorch), LISP(euslisp), ROS, Ubuntu CLI, Raspbian CLI  
Intermediate  
• C++, Shell, CMake  
Basic  
• VHDL

### PUBLICATIONS

Domestic Conference Proceedings

1. Yoshiki Obinata, Naoya Yamaguchi, Koki Shinjo, Kei Okada, Masayuki Inaba, "An indoor and outdoor errand-behavior system based on the coordination of multiple robots (in Japanese)", ROBOMECH2021, 2021
2. Yoshiki Obinata, Naoya Yamaguchi, Shingo Kitagawa, Kei Okada, Masayuki Inaba, "A cooperative system for building facility operation and service robot delivery using smart IoT devices (in Japanese)", ROBOMECH2021, 2021

### ADDITIONAL INFORMATION

**Interests** robotics, machine learning, computer vision, operating system