



Yoshiki Obinata

📍 Tokyo, Japan
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🔗 <https://github.com/mqcmd196>

Born 3 April 1998

WORK EXPERIENCE

May 2021 – present

Technical Assistant Staff / Parttime

JSK Robotics Lab, The University of Tokyo
• Developing and maintaining the robot software.

October 2019 – March 2020

Software Engineer / Internship

OTOKORO.com
• Developing of an automated data analysis platform.

August 2017 – present

Software Engineer / Parttime

Aidemy
• Developing the education service of machine-learning-programming.

EDUCATION

2021 – present

Master's degree in Information Science and Technology

Graduate School of Information Science and Technology, The University of Tokyo
• Major in Mechano-Informatics
• Belong to JSK Robotics Lab and supervised by Prof.Kei Okada

2017 – 2021

Bachelor's degree in Engineering

Faculty of Engineering, The University of Tokyo
• Department of Mechano-Informatics
• Belong to JSK Robotics Lab and supervised by Prof.Kei Okada (2020 - 2021)

SKILLS

Languages Japanese, English, Chinese

Software Skills Advanced
• Python(NumPy, PyTorch), LISP(euslisp), ROS, Ubuntu CLI, Raspbian CLI
Intermediate
• C++, Shell, CMake
Basic
• VHDL

PUBLICATIONS

Domestic Conference
Proceedings

1. Yoshiki Obinata, Naoya Yamaguchi, Koki Shinjo, Kei Okada, Masayuki Inaba, "An indoor and outdoor errand-behavior system based on the coordination of multiple robots (in Japanese)", ROBOMECH2021, 2021
2. Yoshiki Obinata, Naoya Yamaguchi, Shingo Kitagawa, Kei Okada, Masayuki Inaba, "A cooperative system for building facility operation and service robot delivery using smart IoT devices (in Japanese)", ROBOMECH2021, 2021

ADDITIONAL INFORMATION

Interests robotics, machine learning, computer vision, operating system