





Processor-Sharing Internet of Things Architecture for Large-scale Deployment

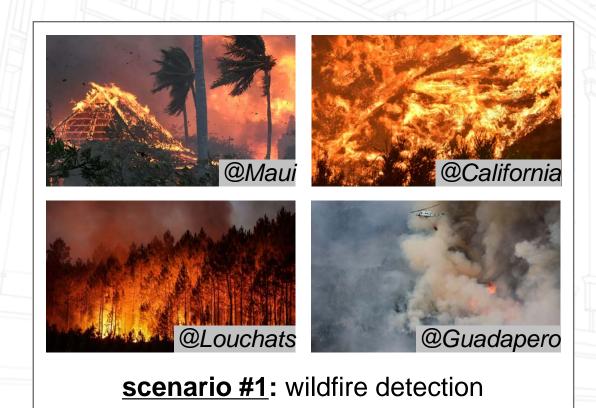
Qianhe Meng¹, Han Wang¹, Chong Zhang^{1,2}, Yihang Song¹, Songfan Li³, Li Lu¹, and Hongzi Zhu⁴

¹University of Electronic Science and Technology of China ²Southwest Petroleum University ³The Hong Kong University of Science and Technology ⁴Shanghai Jiao Tong University

Background



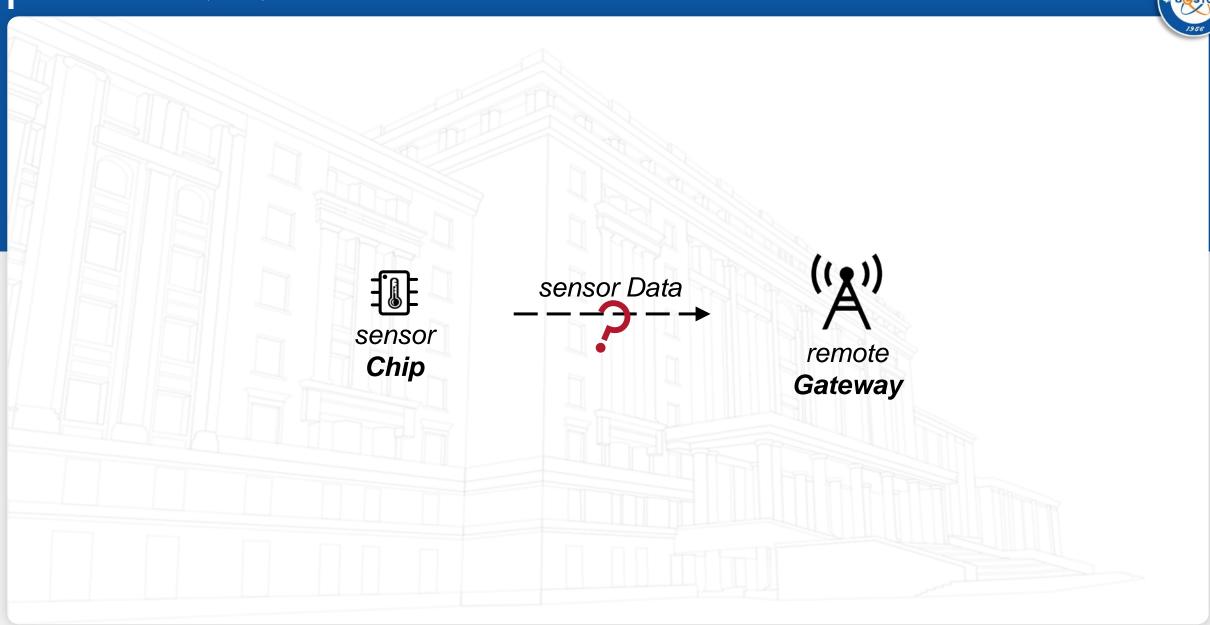
Sensor chips are keen to be deployed at a large-scale.





scenario #2: structural health monitoring

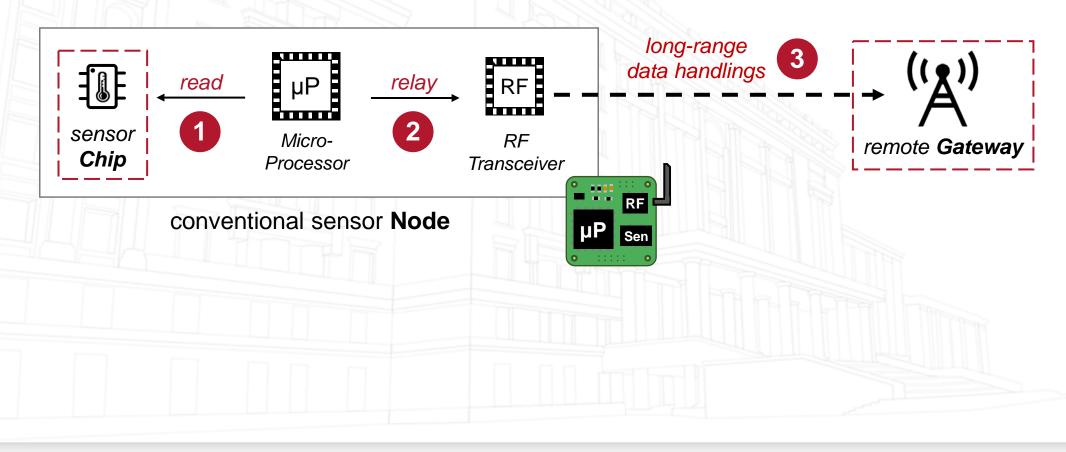
Status Quo (1/3)



Status Quo (2/3)



Embedded Solution: Embedding each sensor chip into a full-fledged embedded device.



Status Quo (3/3)



Nodes are **EXPENSIVE** for large-scale deployment

Unaffordable **Manufacturing** Cost

full-fledged with μP and RF transceiver

→ more than \$10 per node!

Unaffordable **Maintenance** Cost

power-hungry RF components

→ frequent battery changes!

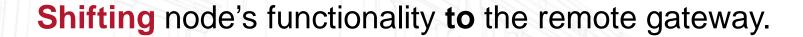
Common Sense



Simplify nodes for the ease of large-scale deployment.

Current Effort (1/4)



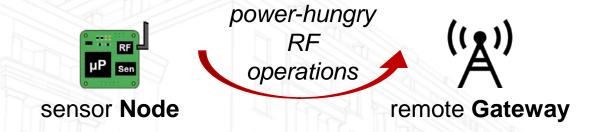




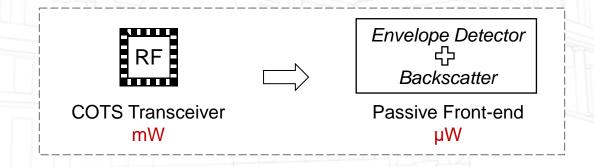
Current Effort (2/4)



Direction #1: communication offload (e.g., backscatter)



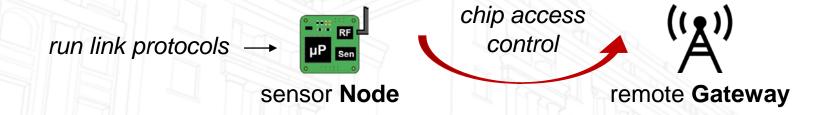
<u>Drawback</u>: Two-way communication range limited to ~30 meters.



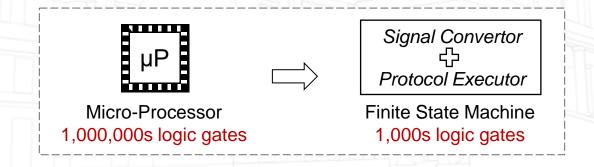
Current Effort (3/4)



Direction #2: computation offload (e.g., processor-free)



Drawback: Comm. overheads increased, thus **network scalability sacrificed**.



Current Effort (4/4)



<u>Insight</u>: Current effort **trades** the network performance **for** the simplicity of sensor nodes.

More gateways to be deployed in trade-off!

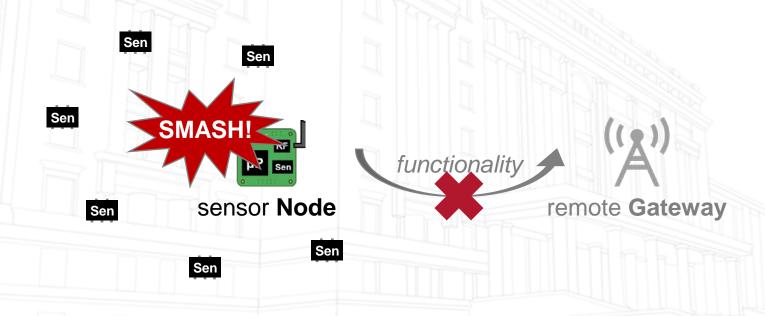


Deployment costs are INCREASED at the SYSTEM-LEVEL!

Motivation (1/2)



Smash a full-fledged sensor node into the AIR for **broader sensor-chip coverage.**

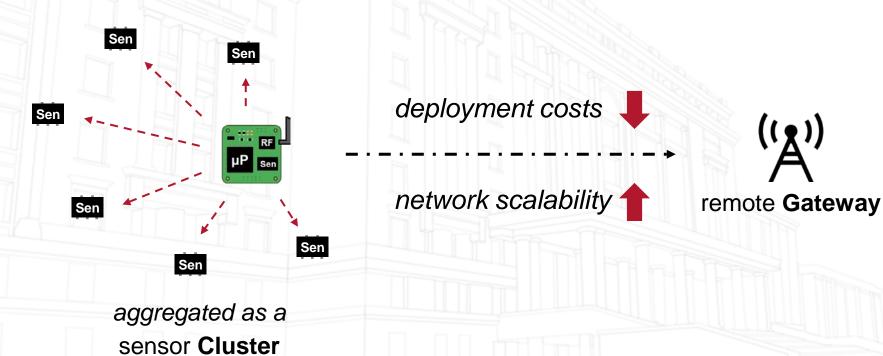


Motivation (2/2)



Could a processor access its **neighboring** sensor **chips** with **negligible** overheads?

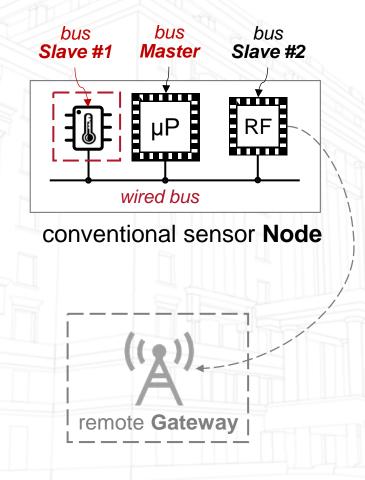




Basic Idea (1/3)



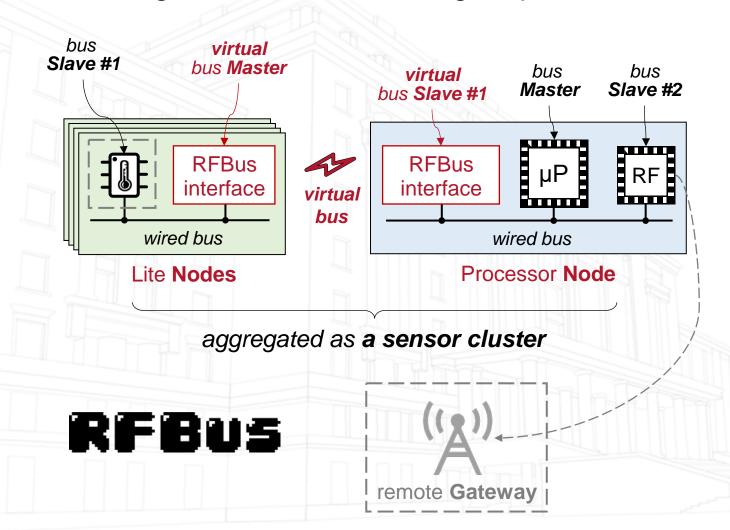
Basic Knowledge: Chips are inter-connect through computer bus.



Basic Idea (2/3)



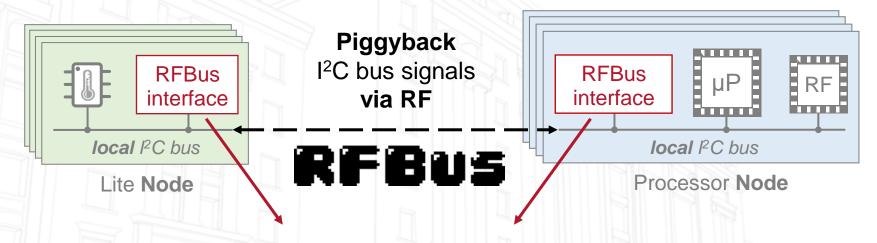
Basic Idea: Constructing a virtual bus among chips.



Basic Idea (3/3)



Sweet Spot: Inherit link-layer services from I²C protocol transparently, including chip address, anti-collision and reliable delivery.



fully backward compatible with the PC specification

A chip-oriented multi-to-multi RF network powered by I²C.

Design > Outline



Design #1: RF Open-Drain (PHY layer)

Design #2: RFBus Front-End (PHY layer)

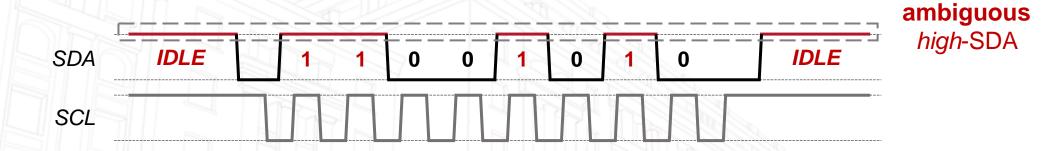
Design #3: Half-duplex RF signaling (link layer)

Design #4: Multi-to-Multi Chip Networking (link layer)

Design > #1 RF Open-Drain (1/2)

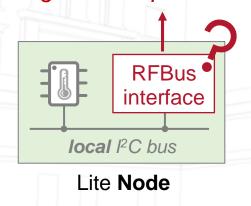


Problem: I²C express **trinary** bus information through **binary** voltage-level.



Lite node asks:

'Does the input high-SDA represents logic '1' or IDLE?'



```
if logic '1'

piggyback it via RF;

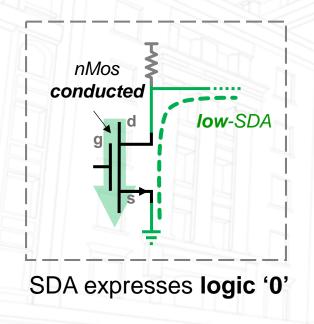
else (IDLE)

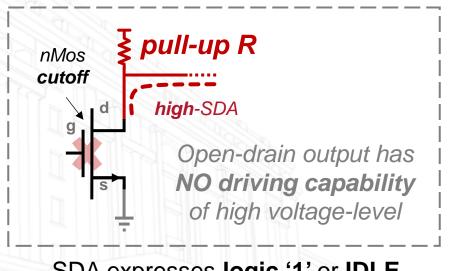
keep silent (release l²C bus);
```

Design > #1 RF Open-Drain (2/2)



Insight: Trinary I²C bus information is expressed by **binary PHY control**.





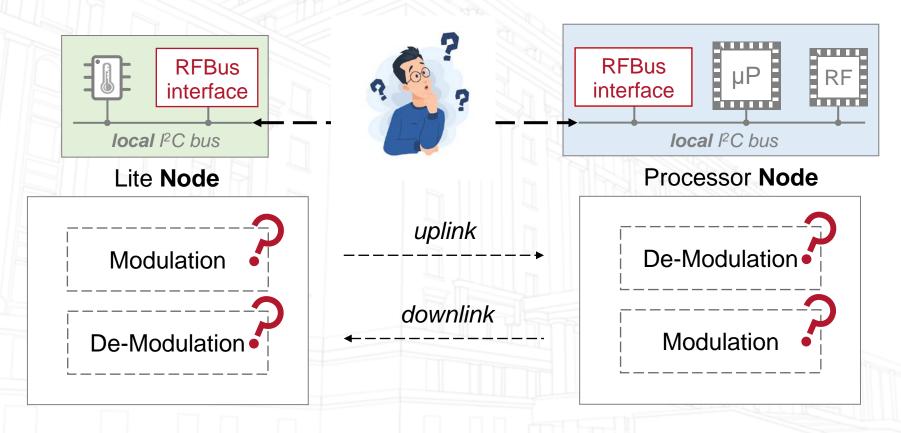
SDA expresses logic '1' or IDLE

Solution: Piggyback low-SDA via RF only.

Design > #2 RFBus Front-End (1/5)



Principle: Inter-node communication with negligible overheads.



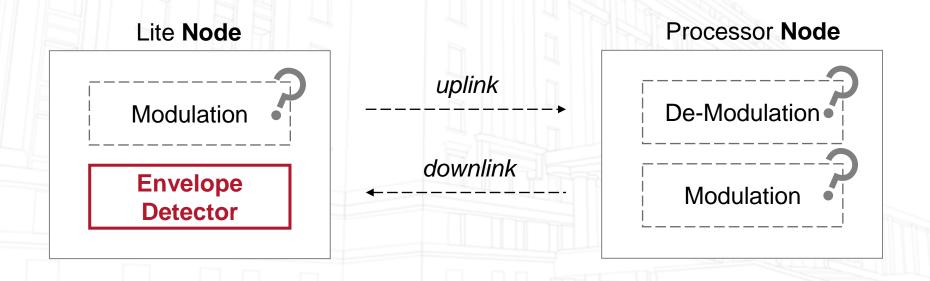
low-cost, low-power & fit-for-purpose performance

Design > #2 RFBus Front-End (2/5)



Design Concern: Lite node must listen to the virtual bus continuously.

Ultra-low power RX at lite node

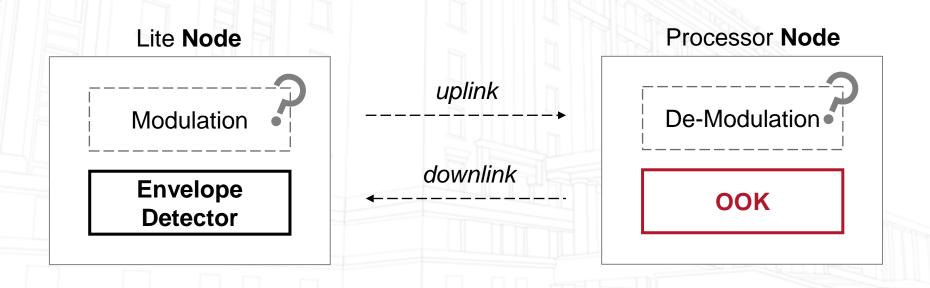


Design > #2 RFBus Front-End (3/5)



Design Concern: Processor node provides amplitude-modulated signals to the envelope detector.

OOK TX at processor node

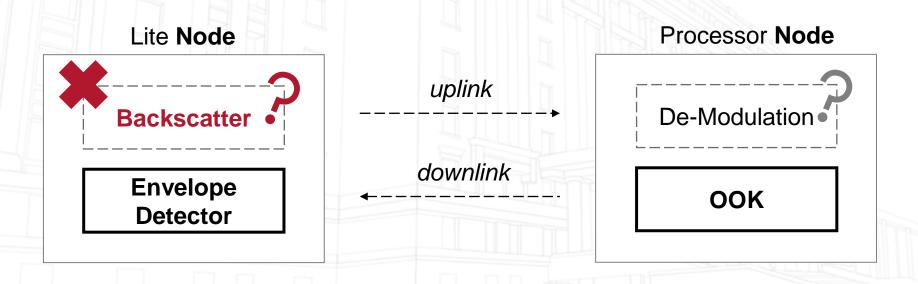


Design > #2 RFBus Front-End (4/5)



Insight: Backscatter is not suitable for RFBus.

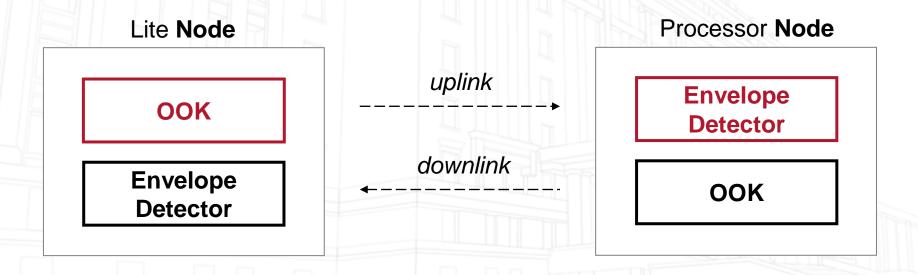
- Backscatter calls for a sensitive RX → deployment costs of processor node increased.
- Backscatter causes unequal two-way communication range → inefficient energy utilization.



Design > #2 RFBus Front-End (5/5)



A symmetric, bidirectional RF chain between the processor and lite nodes.

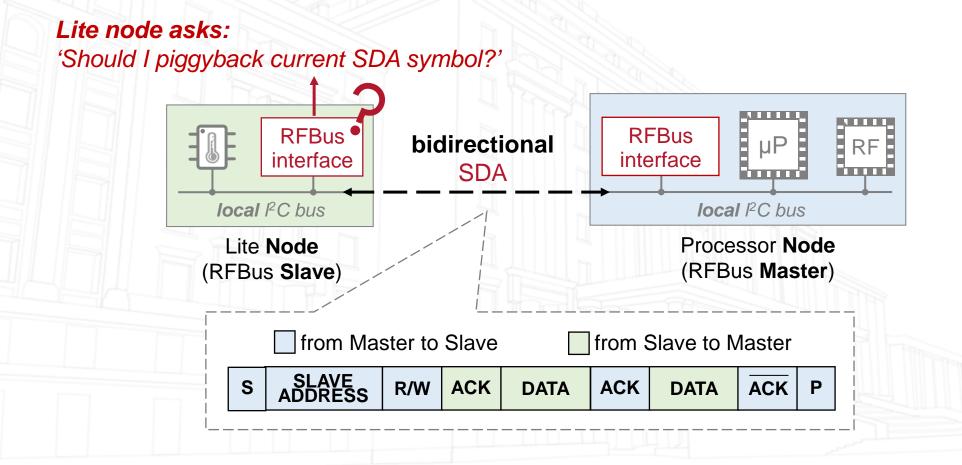


identical two-way communication range

Design > #3 Half-Duplex RF Signaling (1/2)



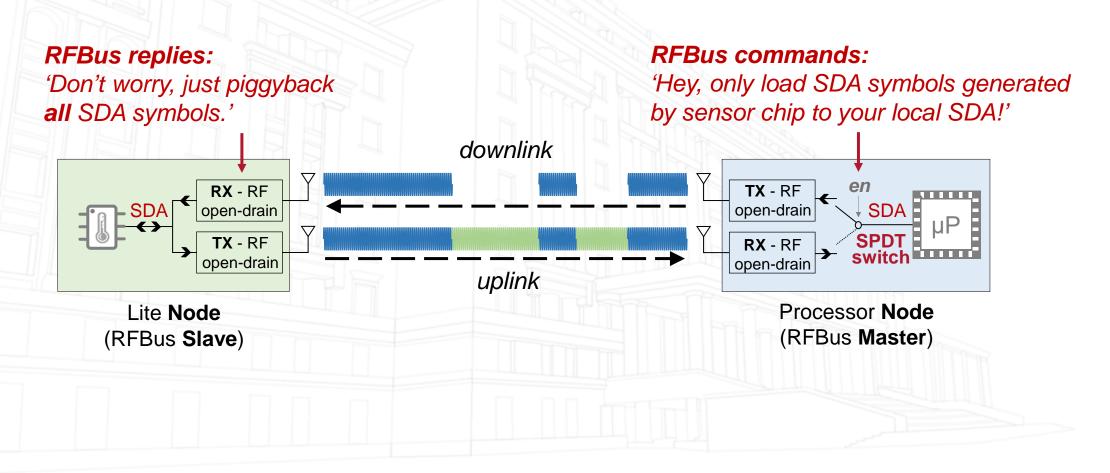
Problem: Rhythm of bidirectional I²C communication is **agnostic** to lite node.



Design > #3 Half-Duplex RF Signaling (2/2)



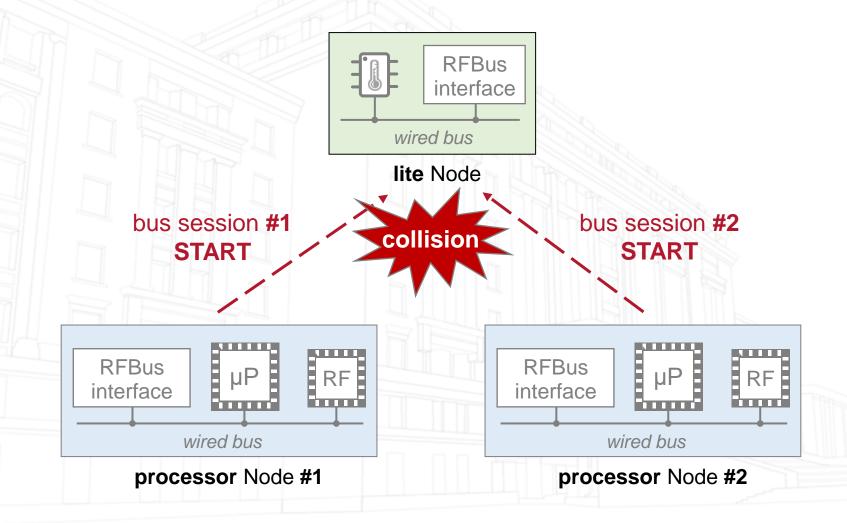
Solution: Frequency division multiplexing without protocol parsing at lite node.



Design > #4 Multi-to-Multi Chip Networking (1/5)



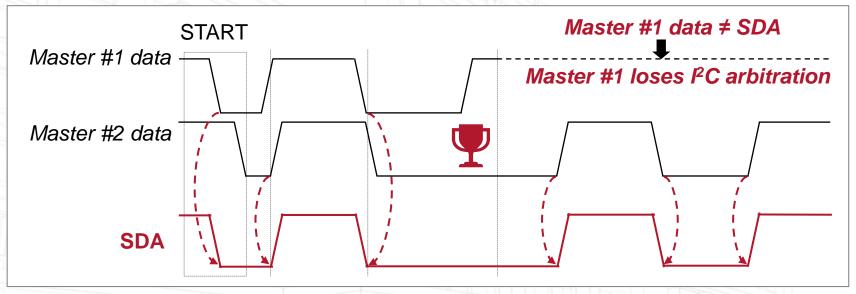
Problem: Bus collisions among multiple processor nodes.



Design > #4 Multi-to-Multi Chip Networking (2/5)



Naturally resolved by I²C arbitration.

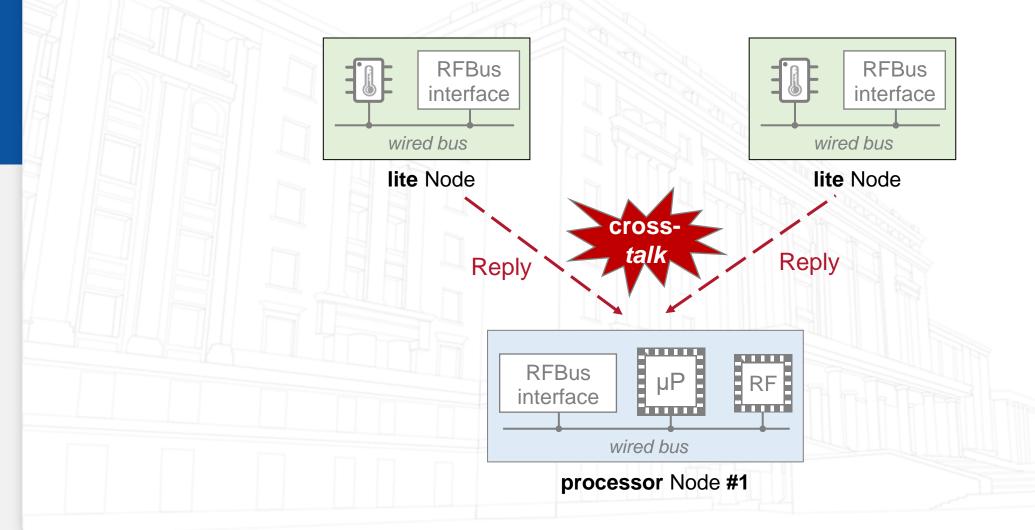


The principle of I²C arbitration shown in a two-master case.

Design > #4 Multi-to-Multi Chip Networking (3/5)



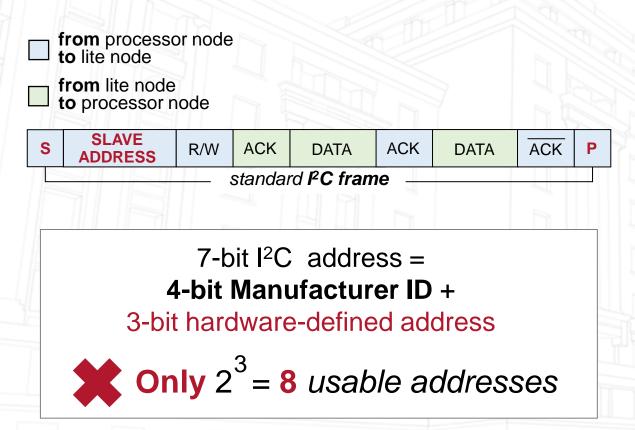
Problem: Cross-talk among multiple lite nodes.

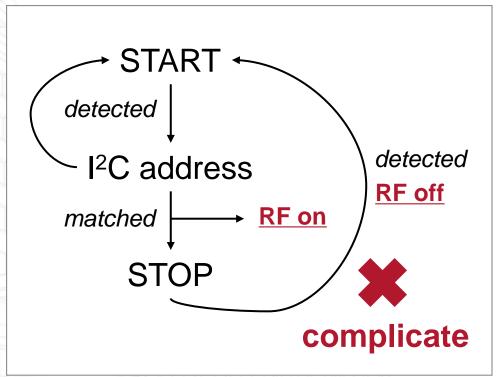


Design > #4 Multi-to-Multi Chip Networking (4/5)



Intuitive Solution: Control lite node's RF by parsing I²C protocol.

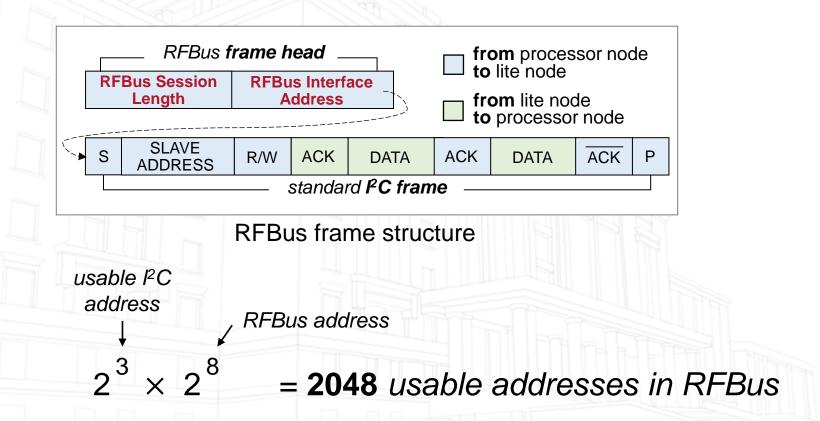




Design > #4 Multi-to-Multi Chip Networking (5/5)



Our Solution: Configure lite node's RFBus interface before each I²C session.

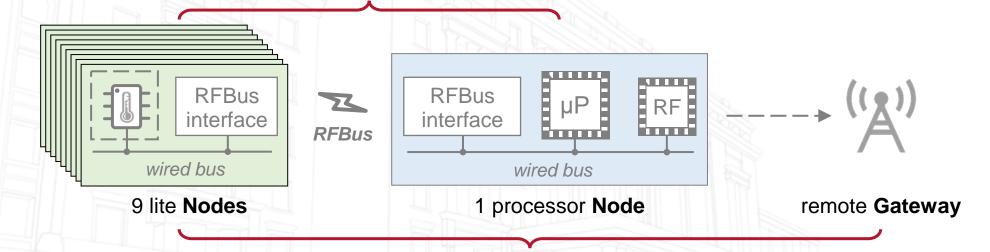


Evaluation > Outline



1 RFBus Network

- > Inter-Node Communication Range
- > Network Throughput
- > Task Throughput



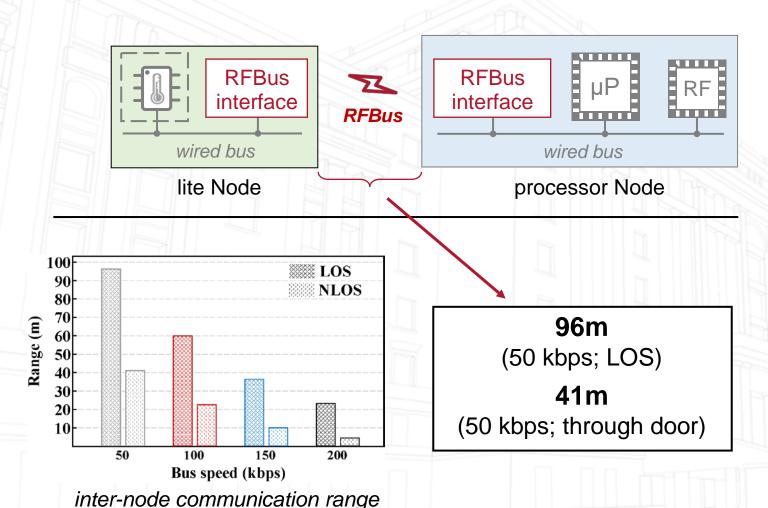
② Processor-Sharing Architecture

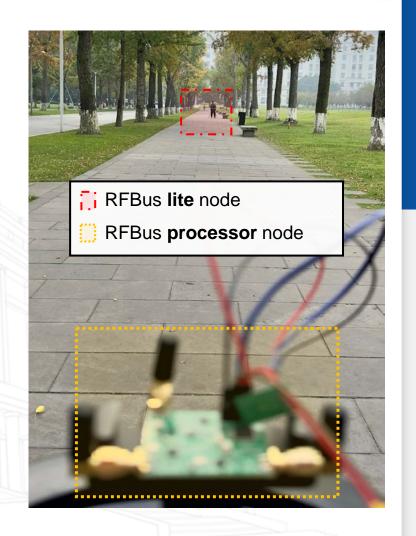
- > Power Consumption
- > Response Time
- > Manufacturing Cost

Evaluation > RFBus Network > Inter-Node Communication Range



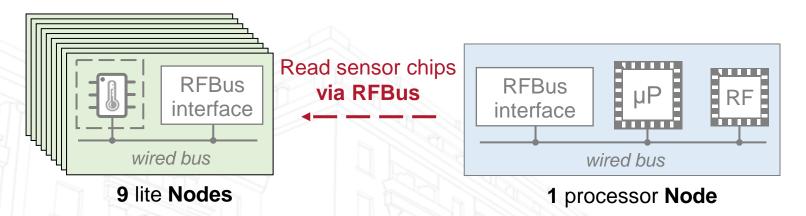
Setup: passive RX + 17dBm TX

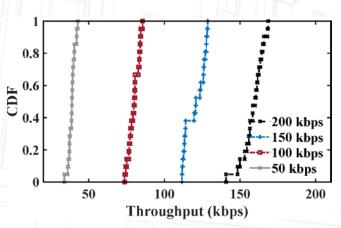




Evaluation > RFBus Network > Network and Task Throughput







Limited by the conducting frequency of RF Schottky diode

168 kbps (max) network throughput

Strategy: querying

169 Hz	339 Hz	452 Hz	678 Hz
50 kbps	100 kbps	150 kbps	200 kbps

Strategy: polling

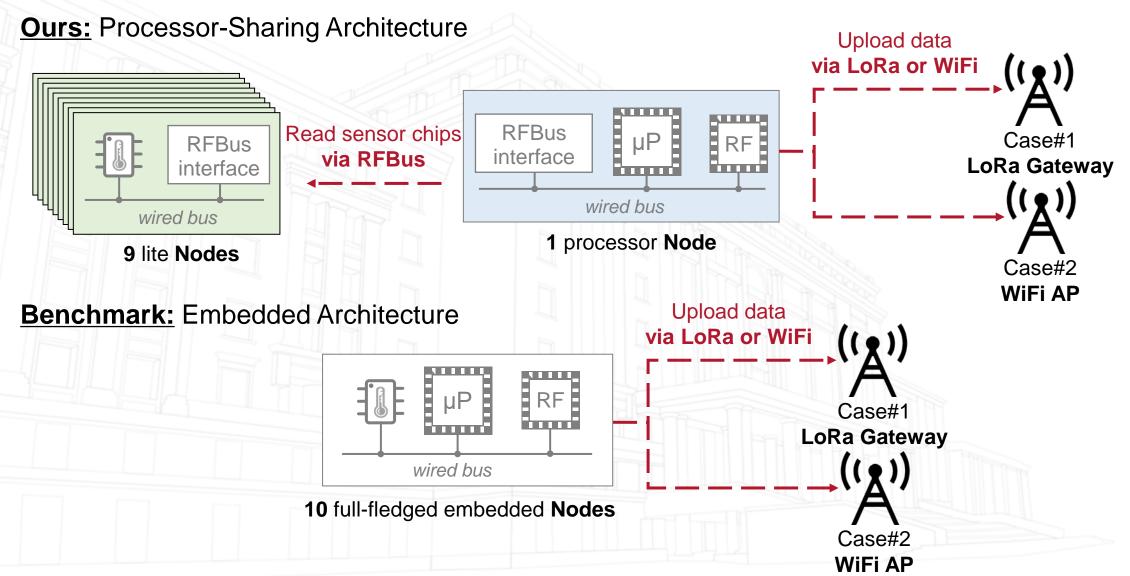
50 kbps	100 kbps	150 kbps	200 kbps
218 Hz	403 Hz	550 Hz	826 Hz

A processor node reads these **30 sensor chips** up to **826 times** in pipeline within **1 second**.

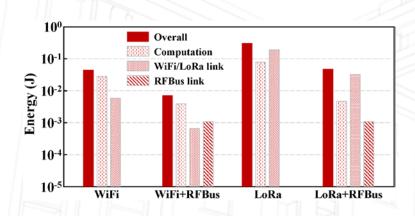
24.8 kHz (max) task throughput

Evaluation > P.S. Architecture





Evaluation > P.S. Architecture > Power, Real-time & Cost

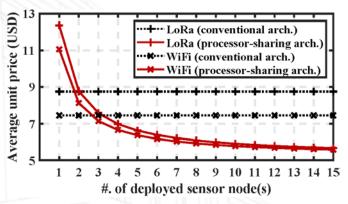


Node's power consumption compared with:

- embedded WiFi node 6.09 ×
- embedded LoRa node 6.69 ×

WiFi		LoRa	
embedded architecture	P.S. architecture	embedded architecture	P.S. architecture
364 ms	241 ms	1029 ms	300 ms

Response time comparison.



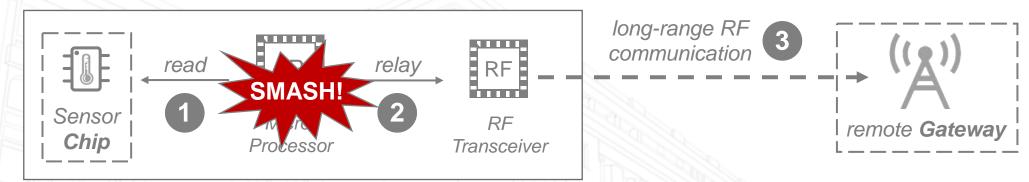
Node's manufacturing cost compared with:

- embedded WiFi node 23.5%
- embedded LoRa node 33.5%

Overview

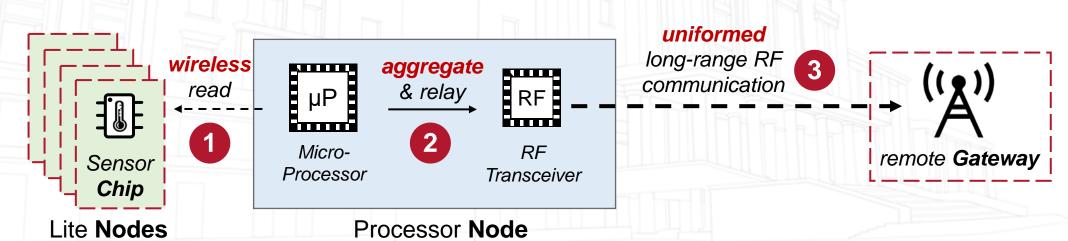


Embedded Solution:



conventional sensor Node

Processor-Sharing Solution:









Processor-Sharing Internet of Things Architecture for Large-scale Deployment

Qianhe Meng

qianhe@std.uestc.edu.cn

more at https://mqhyes.github.io/

