

Numerical Analysis – Fall 2023

Assignment #3

Issued: Oct. 13, 2023

Due: Oct. 23, 2023

Please upload to the 'hw3' directory if you submit your homework in time.

Problem 1:

The following linear systems $A\mathbf{x} = \mathbf{b}$ have \mathbf{x} as the actual solution and $\tilde{\mathbf{x}}$ as an approximate solution. Compute $\|\mathbf{x} - \tilde{\mathbf{x}}\|_\infty$ and $\|A\tilde{\mathbf{x}} - \mathbf{b}\|_\infty$.

a. $x_1 + 2x_2 + 3x_3 = 1,$
 $2x_1 + 3x_2 + 4x_3 = -1,$
 $3x_1 + 4x_2 + 6x_3 = 2,$
 $\mathbf{x} = (0, -7, 5)^t,$
 $\tilde{\mathbf{x}} = (-0.2, -7.5, 5.4)^t.$

b. $x_1 + 2x_2 + 3x_3 = 1,$
 $2x_1 + 3x_2 + 4x_3 = -1,$
 $3x_1 + 4x_2 + 6x_3 = 2,$
 $\mathbf{x} = (0, -7, 5)^t,$
 $\tilde{\mathbf{x}} = (-0.33, -7.9, 5.8)^t.$

Problem 2:

Show that if A is symmetric, then $\|A\|_2 = \rho(A)$.

Problem 3:

Implement the algorithm of Gaussian elimination with scaled partial pivoting, and solve the following linear systems.

a. $0.03x_1 + 58.9x_2 = 59.2,$
 $5.31x_1 - 6.10x_2 = 47.0.$
Actual solution $[10, 1].$

b. $3.03x_1 - 12.1x_2 + 14x_3 = -119,$
 $-3.03x_1 + 12.1x_2 - 7x_3 = 120,$
 $6.11x_1 - 14.2x_2 + 21x_3 = -139.$
Actual solution $[0, 10, \frac{1}{7}].$

Problem 4:

Implement the Jacobi iterative method and list the first three iteration results when solving the following linear systems, using $\mathbf{x}^{(0)} = \mathbf{0}$.

$$\begin{aligned}\text{a.} \quad & 4x_1 + x_2 - x_3 = 5, \\ & -x_1 + 3x_2 + x_3 = -4, \\ & 2x_1 + 2x_2 + 5x_3 = 1.\end{aligned}$$

$$\begin{aligned}\text{b.} \quad & -2x_1 + x_2 + \frac{1}{2}x_3 = 4, \\ & x_1 - 2x_2 - \frac{1}{2}x_3 = -4, \\ & x_2 + 2x_3 = 0.\end{aligned}$$

Problem 5:

Use the Jacobi method and Gauss-Seidel method to solve the following linear systems, with TOL = 0.001 in the L^∞ norm.

$$\begin{aligned}\text{a.} \quad & 3x_1 - x_2 + x_3 = 1, \\ & 3x_1 + 6x_2 + 2x_3 = 0, \\ & 3x_1 + 3x_2 + 7x_3 = 4.\end{aligned}$$

$$\begin{aligned}\text{b.} \quad & 10x_1 - x_2 = 9, \\ & -x_1 + 10x_2 - 2x_3 = 7, \\ & -2x_2 + 10x_3 = 6.\end{aligned}$$

Problem 6:

Prove: If \mathbf{A} is a matrix and $\rho_1, \rho_2, \dots, \rho_k$ are distinct eigenvalues of \mathbf{A} with associated eigenvectors x_1, x_2, \dots, x_k , then $\{x_1, x_2, \dots, x_k\}$ is a linearly independent set.

Problem 7:

Prove that a strictly diagonally dominant matrix is invertible.