MATH 250: TOPOLOGY I

FALL 2025 LOOSE ENDS

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1. Wednesday, 9/3

1.1. Here I try to dispel some potential confusion about bases.

Let X be any set. Let \mathcal{B} be any collection of subsets of X. A useful general observation:

Lemma 1.1. For any subset $Y \subseteq X$, the following conditions are equivalent:

- (1) Y is the union of some elements of \mathcal{B} .
- (2) For any $x \in Y$, there is some $B \in \mathcal{B}$ such that $x \in B \subseteq Y$.

Now let \mathcal{T} be the collection of all subsets of X that can be written as unions of elements of \mathcal{B} . Using the lemma, we see that

$$\mathcal{T} = \left\{ \text{subsets } U \subseteq X \,\middle|\, \text{for any } x \in U, \text{ we have some } B \in \mathcal{B} \\ \text{such that } x \in B \subseteq U \right\}.$$

Theorem 1.2. Suppose that \mathcal{B} satisfies the following conditions:

- (I) Every point of X belongs to some element of \mathcal{B} .
- (II) For any $B, B' \in \mathcal{B}$ and any point x of the intersection $B \cap B'$, we can find some $B'' \in \mathcal{B}$ such that $x \in B'' \subseteq B \cap B'$.

Then \mathcal{T} is a topology on X.

We proved this theorem at the start of the course, implicitly using Lemma 1.1. The only hard part is checking that finite intersections of elements of \mathcal{T} are still elements of \mathcal{T} . To make this easier, I mentioned that it suffices by induction to check intersections between pairs of elements of \mathcal{T} .

Any collection \mathcal{B} that satisfies hypotheses (I)–(II) in the theorem above is called a *basis*. In the situation of the theorem, we say that \mathcal{B} generates or *induces* the topology \mathcal{T} , and that \mathcal{B} is a *basis for* \mathcal{T} specifically.

1.2. Separately, if we are given \mathcal{T} to start, then there is a way to <u>check</u> whether a subcollection $\mathcal{C} \subseteq \mathcal{T}$ is a basis that generates \mathcal{T} . In Munkres, this is Lemma 13.2.

Theorem 1.3. Fix a topology \mathcal{T} on X and a subset $\mathcal{C} \subseteq \mathcal{T}$. Suppose that for each $x \in X$ and $U \in \mathcal{T}$, there is some $C \in \mathcal{C}$ such that $x \in C \subseteq \mathcal{C}$. Then \mathcal{C} is a basis, and moreover, the topology it generates is \mathcal{T} .

2.1. Let X be a set, and let $d: X \times X \to [0, \infty)$ be a metric on X. For all $x \in X$ and $\delta > 0$, we define the d-ball with center x and radius δ to be

$$B_d(x,\delta) = \{ y \in X \mid d(x,y) < \delta \}.$$

Below is a cleaner version of a long proof from lecture.

Theorem 2.1. The set $\{B_d(x,\delta) \mid x \in X \text{ and } \delta > 0\}$ forms a basis.

Proof. Let \mathcal{B} denote the set in question. We must check two axioms:

- (I) Any point of X is contained in some element of \mathcal{B} .
- (II) Given any two elements of \mathcal{B} and a point in their intersection, we can find some other element of \mathcal{B} containing that point and contained within the intersection as a subset.
- (I) holds because for any $x \in X$, we have $x \in B(x, \delta)$ for any choice of δ .

To show (II): Pick balls $B_d(x, \delta)$ and $B_d(x', \delta')$ and a point z in their intersection $B_d(x, \delta) \cap B_d(x', \delta')$. We must exhibit some d-ball that contains z and is contained within the intersection as a subset.

It suffices to find some $\epsilon > 0$ such that

$$B_d(z,\epsilon) \subseteq B_d(x,\delta) \cap B_d(x',\delta').$$

Explicitly, this condition on ϵ means that

if
$$y \in X$$
 satisfies $d(z, y) < \epsilon$, then $d(x, y) < \delta$ and $d(x', y) < \delta'$.

(Informally, this means that if y is close enough to z, then it is close enough to x and x' as well.) By drawing a picture of the situation, we get the idea that we need to use the triangle inequality to bound the distance d(x,y) in terms of the distances d(x,z) and d(z,y).

Since $z \in B_d(x,\delta) \cap B_d(x',\delta')$, we know that $d(x,z) < \delta$ and $d(x',z) < \delta'$. Let $\alpha = \delta - d(x,z)$ and $\alpha' = \delta' - d(x',z)$, the respective distances from z to the boundaries of the balls $B_d(x,\delta)$ and $B_d(x',\delta')$. Now observe that if $y \in X$ satisfies $d(z,y) < \alpha$, then y also satisfies

$$d(x,y) \le d(x,z) + d(z,y)$$
 by the triangle inequality $< d(x,z) + \alpha$ by the hypothesis on $y = \delta$.

An analogous argument shows that if y satisfies $d(z,y) < \alpha'$, then $d(x',y) < \delta'$.

So let $\epsilon = \min(\alpha, \alpha')$. We see that if $y \in X$ satisfies $d(z, y) < \epsilon$, then we have both $d(x, y) < \delta$ and $d(x', y) < \delta'$. So we have found the desired ϵ .

3. Problem Set 2, #9

Problem. Let X be arbitrary, and let $d: X \times X \to [0, \infty)$ be an arbitrary metric. Assume that the function $e: X \times X \to [0, \infty)$ defined by

$$e(x,y) = \frac{d(x,y)}{1 + d(x,y)}.$$

is a bounded metric. Show that d and e induce the same topology on X.

Solution. Let \mathcal{T}_d and \mathcal{T}_e denote the topologies respectively induced by d and e.

We first show that \mathcal{T}_d is finer than \mathcal{T}_e , meaning $\mathcal{T}_e \subseteq \mathcal{T}_d$. Since elements of \mathcal{T}_e are unions of e-balls, it is suffices to check that any e-ball is an element of \mathcal{T}_d . So fix an e-ball $B_e(x,\delta)$. It suffices to show that for $y \in B_e(x,\delta)$, we can find some $\epsilon > 0$ such that $B_d(y,\epsilon) \subseteq B_e(x,\delta)$.

As a warmup, ignore d: Can we find some $\epsilon > 0$ such that $B_e(y, \epsilon) \subseteq B_e(x, \delta)$? Explicitly, for any y satisfying $e(x, y) < \delta$, we have to exhibit some $\epsilon > 0$ such that, if z satisfies $e(y, z) < \epsilon$, then z also satisfies $e(x, z) < \delta$. The argument will be similar to the latter half of the proof of Theorem 2.1. Namely, let $\epsilon = \delta - e(x, y) > 0$, the distance from y to the boundary of the ball $B_e(x, \delta)$. If z satisfies $e(y, z) < \epsilon$, then by the triangle inequality, it satisfies

$$e(x, z) \le e(x, y) + e(y, z) < e(x, y) + \epsilon = \delta,$$

as needed. So this choice of ϵ does give $B_e(y, \epsilon) \subseteq B_e(x, \delta)$.

Now go back to the original problem involving d. By combining $B_e(y, \epsilon) \subseteq B_e(x, \delta)$ with the following observation, we get $B_d(y, \epsilon) \subseteq B_e(x, \delta)$, as needed.

Lemma 3.1. For any $y \in X$ and $\epsilon > 0$, we have $B_d(y, \epsilon) \subseteq B_e(y, \epsilon)$.

Now we show the reverse inclusion: $\mathcal{T}_d \subseteq \mathcal{T}_e$. So fix a d-ball $B_d(x, \delta)$. We must show that for any $y \in B_d(x, \delta)$, we can find some $\epsilon > 0$ such that $B_e(x, \epsilon) \subseteq B_d(x, \delta)$. Explicitly, for any y satisfying $d(x, y) < \delta$, we have to exhibit some $\epsilon > 0$ such that, if z satisfies $e(y, z) < \epsilon$, then z also satisfies $d(x, z) < \delta$.

Since the roles of d and e in Lemma 3.1 cannot be switched, we cannot just replicate our earlier argument with d and e switched. But we still expect to use the triangle inequality that $d(x,z) \leq d(x,y) + d(y,z)$. Letting $\alpha = \delta - d(x,y) > 0$ gives us $d(x,y) + \alpha = \delta$. So we just need to exhibit $\epsilon > 0$ such that $e(y,z) < \epsilon$ implies $d(y,z) < \alpha$, because for such ϵ ,

$$e(y,z) < \epsilon$$
 will imply $d(x,z) \le d(x,y) + d(y,z) < d(x,y) + \alpha = \delta$,

as needed.

Rearranging the identity $e(y,z)=\frac{d(y,z)}{1+d(y,z)}$ gives $d(y,z)=\frac{e(y,z)}{1-e(y,z)}$. Moreover, rearranging $e(y,z)<\epsilon$ gives $\frac{e(y,z)}{1-e(y,z)}<\frac{\epsilon}{1-\epsilon}$. So the following lemma finishes the argument:

Lemma 3.2. For any $\alpha > 0$, there is some $\epsilon > 0$ such that $\frac{\epsilon}{1-\epsilon} < \alpha$. (Moreover, we can pick $\epsilon < 1$, so that $\frac{\epsilon}{1-\epsilon}$ is well-defined.)

Proof. Left as an exercise. Hint: If $0 < \epsilon < \frac{1}{2}$, then $\frac{1}{1-\epsilon} < 2$.

Since we have shown that \mathcal{T}_d and \mathcal{T}_e contain each other, they coincide. That is, d and e induce the same topology.