

from the HW:

if  $\{W_i\}_{i \in I}$  is a collection of linear sub.'s of  $V$ ,  
with  $I$  possibly infinite,  
then their sum is defined to be [what?]

$$\begin{aligned} \sum_{i \in I} W_i &= \{ \sum_{i \in J} w_i \mid J \subseteq I \text{ finite,} \\ &\quad w_i \in W_i \text{ for all } i \} \\ ( &= \{ \sum_i w_i \mid w_i \in W_i \text{ for all } i, \\ &\quad w_i = \mathbf{0} \text{ for all but fin many } i \} ) \end{aligned}$$

[will use second version today]

Prop  $\sum_{i \in I} W_i$  is the minimal lin. sub.  
containing  $W_i$  for all  $i$

Df  $\sum_{i \in I} W_i$  is a direct sum  
iff [what?]  
every elt has a unique expression  
 $\sum_{i \in I} w_i$   
s.t.  $w_i \in W_i$  for all  $i$   
(and  $w_i = \mathbf{0}$  for all but fin many  $i$ )

[what does unique mean?]

for any sets  $\{w_i\}_i, \{w'_i\}_i$   
s.t.  $w_i, w'_i \in W_i$  for all  $i$   
and  $w_i, w'_i = \mathbf{0}$  for all but fin many  $i$ ,

$\sum_i w_i = \sum_i w'_i$  implies  $(w_i = w'_i \text{ for all } i)$

Prop suppose the uniqueness holds for  $\mathbf{0}$ :  
for any set  $\{w_i\}_i$   
s.t.  $w_i$  in  $W_i$  for all  $i$   
(and  $w_i = \mathbf{0}$  for all but fin many  $i$ ),

$\sum_{i \in I} w_i = \mathbf{0}$  implies ( $w_i = \mathbf{0}$  for all  $i$ )

then the uniqueness holds in general: i.e.,  
 $\sum_{i \in I} W_i$  is a direct sum

Pf suppose that  
 $\sum_i w_i = v = \sum_i w'_i$

then  $\sum_i (w_i - w'_i) = \mathbf{0}$   
so  $w_i - w'_i = \mathbf{0}$  for all  $i$

(Axler §2A)  $\{v_i\}_{i \in I}$  any set of vectors in  $V$

Df  $\{v_i\}_i$  is said to be  
a linearly independent set of vectors iff  
either of these equivalent cond's:

I)  $\mathbf{0}$  has a unique expression as  $\sum_i a_i v_i$ :

for any set  $\{a_i\}_i$   
s.t.  $a_i$  in  $F$  for all  $i$ ,  
 $a_i = 0$  for all but fin many  $i$ ,

$\sum_i a_i v_i = \mathbf{0}$  implies ( $a_i = 0$  for all  $i$ )

II)  $\sum_i Fv_i$  is a direct sum

else we say  $\{v_i\}_i$  is a linearly dependent set

Lem  $\{v_i\}_i$  is linearly dependent iff  
 there exist finite subset  $\{v_j\}_{j \in J}$ ,  
 $i \notin J$   
 s.t.  $v_i = \sum_{j \in J} a_j v_j$

in this case, we say:

$v_i$  is a linear combination of the  $v_j$ 's for  $j \in J$ ,  
 with coeffs  $a_j$ 's

also say:

$v_i$  is linearly dependent upon the  $v_j$ 's

[motivates next defn:]

Df the span of  $\{v_i\}_i$  is (simultaneously)

- 1)  $\{\sum_i a_i v_i \mid a_i \in F \text{ for all } i, a_i = 0 \text{ for all but fin many } i\}$
- 2)  $\sum_{i \in I} F v_i$ , where  $F v_i = \{a v_i \mid a \in F\}$
- 3) the minimal linear subspace of  $V$  containing  $v_i$  for all  $i$

i.e. 1), 2), 3) are all the same  
 and  $\{v_i\}_i$  is said to span [verb] it

Ex in  $F[x] = \{\text{set of polynomials in } x \text{ over } F\}$ :

$\{x^k \mid k \geq 0\} = \{1, x, x^2, x^3, \dots\}$  spans  $F[x]$

[why? every polynomial is a sum of monomials]

Ex let  $\mathbf{N} = \{1, 2, 3, \dots\}$   
in  $F^{\mathbf{N}} = \{\text{functions from } \mathbf{N} \text{ into } F\}$ :  
let  $e_i : \mathbf{N} \text{ to } F$  be the function  
 $e_i(i) = 1,$   
 $e_i(j) = 0 \text{ for } j \neq i$

$\{e_i \mid i \text{ in } \mathbf{N}\}$  does not span  $F^{\mathbf{N}}$

[why?] consider the function  $f$  s.t.  $f(i) = 1$  for all  $i$

[most striking thm thus far:]

Thm (Steinitz Exchange) if  
 $\{v_1, \dots, v_k\}$  is a lin. independent set in  $V$ ,  
 $\{e_1, \dots, e_n\}$  spans  $V$

then  $k \leq n$

[crucially, both sets of vectors are finite]

Cor if  $V$  is spanned by  $n$  vectors,  
then any set with  $> n$  vectors  
has some linear dependence

Cor if there is a linearly independent set  
of  $k$  vectors in  $V$ ,  
then any set with  $< k$  vectors  
cannot span  $V$

Pf of Thm let  $S_0 = \{e_1, \dots, e_n\}$

will prove that for  $\ell = 1, \dots, k$ ,  
we can construct  $S_\ell$  from  $S_{\ell-1}$  s.t.

- 1)  $S_{\ell}$  still spans  $V$
  - 2)  $S_{\ell}$  has one more  $v_i$  and one fewer  $e_j$  than  $S_{\ell-1}$
- thus  $\ell \leq n$  at each step [and  $k \leq n$  at the last step]

WLOG reindex the  $v_i$ 's and  $e_j$ 's s.t.

$$S_{\ell-1} = \{v_1, \dots, v_{\ell-1}, e_{\ell}, \dots, e_n\}$$

since  $S_{\ell-1}$  spans  $V$ ,

$$v_{\ell} = \sum_{i=1}^{\ell-1} a_{iv_i} + \sum_{j=\ell}^n b_{je_j}$$

with some coeff nonzero

if  $b_j = 0$  for all  $j$ , then  $\{v_i\}_i$  lin. dep.

so we can pick  $j$  s.t.  $b_j \neq 0$

so  $e_j = (1/b_j)(v_{\ell} - \text{other stuff})$

build  $S_{\ell}$  by appending  $v_{\ell}$  and removing  $e_j$   $\square$

(Axler §2B–2C)

Df a basis for  $V$  is a set of vectors  $\{v_i\}_i$   
 s.t. 1)  $\{v_i\}_i$  spans  $V$   
 2)  $\{v_i\}_i$  is a linearly independent set

Cor if  $V$  has a finite basis of size  $r$ ,  
 then any basis for  $V$  has size  $r$

Pf if  $\{e_1, \dots, e_r\}$  is a basis,  
 and  $\{f_1, \dots, f_s\}$  is another:

$r \leq s$  because

$\{e_i\}_i$  is lin. indep. and  $\{f_j\}_j$  is spanning

$s \geq r$  because

$\{f_i\}_i$  is lin. indep. and  $\{e_j\}_j$  is spanning

Df if  $V$  has a finite basis,  
then we define the dimension of  $V$  to be

$$\dim(V) = \text{size of any basis for } V$$

else we say  $V$  is infinite-dimensional

“the Good, the Bad, and the Ugly”

$V$  has finite dimension

$V$  has infinite dimension, yet has an explicit basis

e.g.,  $F[x]$

$V$  has infinite dimension and no explicit basis

e.g.,  $F^{\mathbf{N}}$