

from the HW:

if $\{W_i\}_{i \in I}$ is a collection of linear sub.'s of V ,
with I possibly infinite,
then their sum is defined to be [what?]

$$\begin{aligned} \sum_{i \in I} W_i &= \{ \sum_{i \in J} w_i \mid J \subseteq I \text{ finite,} \\ &\quad w_i \in W_i \text{ for all } i \} \\ (&= \{ \sum_i w_i \mid w_i \in W_i \text{ for all } i, \\ &\quad w_i = \mathbf{0} \text{ for all but fin many } i \}) \end{aligned}$$

[will use second version today]

Prop $\sum_{i \in I} W_i$ is the minimal lin. sub.
containing W_i for all i

Df $\sum_{i \in I} W_i$ is a direct sum
iff [what?]
every elt has a unique expression
 $\sum_{i \in I} w_i$
s.t. $w_i \in W_i$ for all i
(and $w_i = \mathbf{0}$ for all but fin many i)

[what does unique mean?]

for any sets $\{w_i\}_i, \{w'_i\}_i$
s.t. $w_i, w'_i \in W_i$ for all i
and $w_i, w'_i = \mathbf{0}$ for all but fin many i ,

$\sum_i w_i = \sum_i w'_i$ implies $(w_i = w'_i \text{ for all } i)$

Prop suppose the uniqueness holds for $\mathbf{0}$:
for any set $\{w_i\}_i$
s.t. w_i in W_i for all i
(and $w_i = \mathbf{0}$ for all but fin many i),

$\sum_{i \in I} w_i = \mathbf{0}$ implies ($w_i = \mathbf{0}$ for all i)

then the uniqueness holds in general: i.e.,
 $\sum_{i \in I} W_i$ is a direct sum

Pf suppose that
 $\sum_i w_i = v = \sum_i w'_i$

then $\sum_i (w_i - w'_i) = \mathbf{0}$
so $w_i - w'_i = \mathbf{0}$ for all i

(Axler §2A) $\{v_i\}_{i \in I}$ any set of vectors in V

Df $\{v_i\}_i$ is said to be
a linearly independent set of vectors iff
either of these equivalent cond's:

I) $\mathbf{0}$ has a unique expression as $\sum_i a_i v_i$:

for any set $\{a_i\}_i$
s.t. a_i in F for all i ,
 $a_i = 0$ for all but fin many i ,

$\sum_i a_i v_i = \mathbf{0}$ implies ($a_i = 0$ for all i)

II) $\sum_i Fv_i$ is a direct sum

else we say $\{v_i\}_i$ is a linearly dependent set

Lem $\{v_i\}_i$ is linearly dependent iff
 there exist finite subset $\{v_j\}_{j \in J}$,
 $i \notin J$
 s.t. $v_i = \sum_{j \in J} a_j v_j$

in this case, we say:

v_i is a linear combination of the v_j 's for $j \in J$,
 with coeffs a_j 's

also say:

v_i is linearly dependent upon the v_j 's

[motivates next defn:]

Df the span of $\{v_i\}_i$ is (simultaneously)

- 1) $\{\sum_i a_i v_i \mid a_i \in F \text{ for all } i, a_i = 0 \text{ for all but fin many } i\}$
- 2) $\sum_{i \in I} F v_i$, where $F v_i = \{a v_i \mid a \in F\}$
- 3) the minimal linear subspace of V containing v_i for all i

i.e. 1), 2), 3) are all the same
 and $\{v_i\}_i$ is said to span [verb] it

Ex in $F[x] = \{\text{set of polynomials in } x \text{ over } F\}$:

$\{x^k \mid k \geq 0\} = \{1, x, x^2, x^3, \dots\}$ spans $F[x]$

[why? every polynomial is a sum of monomials]

Ex let $\mathbf{N} = \{1, 2, 3, \dots\}$
in $F^{\mathbf{N}} = \{\text{functions from } \mathbf{N} \text{ into } F\}$:
let $e_i : \mathbf{N} \text{ to } F$ be the function
 $e_i(i) = 1,$
 $e_i(j) = 0 \text{ for } j \neq i$

$\{e_i \mid i \text{ in } \mathbf{N}\}$ does not span $F^{\mathbf{N}}$

[why?] consider the function f s.t. $f(i) = 1$ for all i

[most striking thm thus far:]

Thm (Steinitz Exchange) if
 $\{v_1, \dots, v_k\}$ is a lin. independent set in V ,
 $\{e_1, \dots, e_n\}$ spans V

then $k \leq n$

[crucially, both sets of vectors are finite]

Cor if V is spanned by n vectors,
 then any set with $> n$ vectors
 has some linear dependence

Cor if there is a linearly independent set
 of k vectors in V ,
 then any set with $< k$ vectors
 cannot span V

Pf of Thm let $S_0 = \{e_1, \dots, e_n\}$

will prove that for $\ell = 1, \dots, k$,
 we can construct S_ℓ from $S_{\ell-1}$ s.t.

- 1) S_{ℓ} still spans V
 - 2) S_{ℓ} has one more v_i and one fewer e_j than $S_{\ell-1}$
- thus $\ell \leq n$ at each step [and $k \leq n$ at the last step]

WLOG reindex the v_i 's and e_j 's s.t.

$$S_{\ell-1} = \{v_1, \dots, v_{\ell-1}, e_{\ell}, \dots, e_n\}$$

since $S_{\ell-1}$ spans V ,

$$v_{\ell} = \sum_{i=1}^{\ell-1} a_{iv_i} + \sum_{j=\ell}^n b_{je_j}$$

with some coeff nonzero

if $b_j = 0$ for all j , then $\{v_i\}_i$ lin. dep.

so we can pick j s.t. $b_j \neq 0$

so $e_j = (1/b_j)(v_{\ell} - \text{other stuff})$

build S_{ℓ} by appending v_{ℓ} and removing e_j \square

(Axler §2B–2C)

Df a basis for V is a set of vectors $\{v_i\}_i$
 s.t. 1) $\{v_i\}_i$ spans V
 2) $\{v_i\}_i$ is a linearly independent set

Cor if V has a finite basis of size r ,
 then any basis for V has size r

Pf if $\{e_1, \dots, e_r\}$ is a basis,
 and $\{f_1, \dots, f_s\}$ is another:

$r \leq s$ because

$\{e_i\}_i$ is lin. indep. and $\{f_j\}_j$ is spanning

$s \geq r$ because

$\{f_i\}_i$ is lin. indep. and $\{e_j\}_j$ is spanning

Df if V has a finite basis,
then we define the dimension of V to be

$$\dim(V) = \text{size of any basis for } V$$

else we say V is infinite-dimensional

“the Good, the Bad, and the Ugly”

V has finite dimension

V has infinite dimension, yet has an (infinite) basis

e.g., $F[x]$

V has infinite dimension and no basis

e.g., $F^{\mathbf{N}}$