

Warmup suppose $T : F^2 \rightarrow F^2$ sends

$$\begin{array}{ccc} v_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} & \text{to} & \begin{pmatrix} 2 \\ 2 \end{pmatrix} & v_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix} & \text{to} & \begin{pmatrix} 1 \\ -1 \end{pmatrix} \end{array}$$

matrix of T wrt std basis (e_1, e_2) of F^2 ?

1) matrix wrt (v_1, v_2) : $M = \begin{pmatrix} 2 & 0 \\ 0 & -1 \end{pmatrix}$

2) $\begin{array}{l} v_1 = e_1 + e_2 \\ v_2 = -e_1 + e_2 \end{array}$ $B = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$

3) $\det(B) = 2$ $[B^{-1}] = \begin{pmatrix} 1/2 & 1/2 \\ -1/2 & 1/2 \end{pmatrix}$
 $\text{adj}(B) = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$

$$\begin{aligned} BMB^{-1} &= (1/2) B M \text{adj}(B) \\ &= (1/2) \begin{pmatrix} 2 & 1 \\ 2 & -1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \\ &= (1/2) \begin{pmatrix} 1 & 3 \\ 3 & 1 \end{pmatrix} \\ &= \begin{pmatrix} 1/2 & 3/2 \\ 3/2 & 1/2 \end{pmatrix} \text{ [works]} \end{aligned}$$

(Axler §3A) given a linear op $T : V \rightarrow V$:

Df a subspace $W \subset V$ is T -stable iff
 $w \in W$ implies $Tw \in W$

Ex above: Fv_1, Fv_2 are T -stable lines
 Fe_1, Fe_2 are not T -stable
matrix wrt (v_1, v_2) easier to understand

Ex for any linear op $T : V$ to V ,
 $\{0\}$ and V are $[trivially]$ T -stable

Ex suppose that wrt some basis,
 $T : F^3$ to F^3 has the matrix

$$\begin{pmatrix} * & * & 0 \\ * & * & 0 \\ 0 & 0 & * \end{pmatrix}$$

nontrivial T -stable subspaces? $\{(x, y, 0) \mid x, y\}$
 $\{(0, 0, z) \mid z\}$

when a matrix for T has nontrivial diagonal blocks,
the blocks indicate nontrivial T -stable subspaces
[why care?]

when $V = \sum_i W_i$ for T -stable W_i ,
studying T reduces to studying $T|_{W_i}$ for all i

best situation: each W_i is a line
[what means?]

in this case: there is a basis $(w_i)_i$ s.t.
 $W_i = Fw_i$,
 $Tw_i = a_i w_i$ for some a_i
matrix of T wrt w_i is diagonal

Df for any linear op $T : V$ to V

an eigenline of T is a T -stable line [dim-1 sub.]
an eigenvector of T is v in V s.t. Fv is an eigenline
(which forces $v \neq 0$)
if $Tv = \lambda v$, then we call λ the eigenvalue of the line

Ex $T : F^2 \text{ to } F^2$ given by the matrix
 $\begin{pmatrix} 1/2 & 3/2 \\ 3/2 & 1/2 \end{pmatrix}$ wrt the std basis

$\{(x \text{ is an eigenline with eigenvalue } 2$
 $x)\}$

$\{(x \text{ is an eigenline with eigenvalue } -1$
 $-x)\}$

Ex $P : F^2 \text{ to } F^2$ given by the matrix
 $\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$ wrt the std basis

[does P have any eigenvectors?]

$$\begin{array}{lcl} \lambda x & = & 0 \quad 0 \\ \lambda y & & 0 \quad 1 \end{array} \quad \begin{array}{lcl} x & = & 0 \\ y & & y \end{array}$$

[take $\lambda = 0$:] Fe1 is an eigenline with eigenvalue 0

[take $\lambda \neq 0$:] Fe2 is an eigenline with eigenvalue 1

Ex $N : F^2 \text{ to } F^2$ given by the matrix
 $\begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$ wrt the std basis

$$\begin{array}{lcl} \lambda x & = & 0 \quad 0 \\ \lambda y & & 1 \quad 0 \end{array} \quad \begin{array}{lcl} x & = & 0 \\ y & & x \end{array}$$

[regardless of λ :] $x = 0$

Fe2 is the only eigenline with eigenvalue 0

[same regardless of whether $F = \mathbb{R}$ or $F = \mathbb{C}$]

<u>Ex</u>	$H : \mathbb{R}^2 \text{ to } \mathbb{R}^2$	given by the matrix
	$\begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$	wrt the std basis

$$\begin{array}{rcl} \lambda x & = & 1 \quad -1 \quad x = x - y \\ \lambda y & & 1 \quad 1 \quad y = x + y \end{array}$$

messy to solve...

notice: $(1/\sqrt{2}) H = \begin{pmatrix} 1/\sqrt{2} & -1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix} = \begin{pmatrix} \cos(\pi/4) & -\sin(\pi/4) \\ \sin(\pi/4) & \cos(\pi/4) \end{pmatrix}$

so H is the composition of:

- rotate by $\pi/4$
- scale by $\sqrt{2}$

no H-stable lines through **0**

compare to $H' : C^2 \rightarrow C^2$ given by

$$\begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$$

claim: $1 + i$ and $1 - i$ are eigenvalues

$$\begin{aligned}(1 + i)x &= x - y && \text{imply } ix = -y \text{ and } iy = x \\ (1 + i)y &= x + y\end{aligned}$$

so $\{(x \text{ is an eigenline with eigenvalue } 1 + i, ix)\}$

similarly

$$\{(x \text{ is an eigenline with eigenvalue } 1 - i - ix)\}$$

Rem \mathbb{C}^2 is iso to the complex'n of \mathbb{R}^2

	$H_{\mathbb{C}}$	
$(\mathbb{R}^2)_{\mathbb{C}}$	to	$(\mathbb{R}^2)_{\mathbb{C}}$
=		
\mathbb{C}^2	to	\mathbb{C}^2
	H'	

Moral choice of \mathbb{R} vs \mathbb{C} affects eigenstuff

even if $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ has no eigenvals,
 $T_{\mathbb{C}} : \mathbb{C}^n \rightarrow \mathbb{C}^n$ may have eigenvals

[later: we will show it has at least one]

Summary

if $W \subset V$ is stable under $T : V \rightarrow V$
then we can study T in terms of smaller op's $T|_W$

nicer when W is a line
nicest when V is a sum of eigenlines

over \mathbb{R}	T may have no eigenlines
over \mathbb{C}	T will have some eigenline [later], but V need not be sum(eigenlines)

Q for next time

let $D : F[x] \rightarrow F[x]$ be $D(p) = dp/dx$
what are the D -stable linear subspaces?