From Natural Deduction to the Sequent Calculus

by passing an accumulator

Matthias Puech



DANSAS'13 Odense, August 23, 2013 Logic can explain programs ...

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... and programs can explain logic

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Goal of this talk: understand the relationship between two calculi by means of functional program transformations

From natural deduction ...

$$I_{MPI} \begin{array}{c} [\vdash A] \\ \vdots \\ \vdash B \\ \vdash A \supset B \end{array} \qquad I_{MPE} \begin{array}{c} \vdash A \supset B \\ \vdash B \end{array} \begin{array}{c} \vdash A \end{array}$$

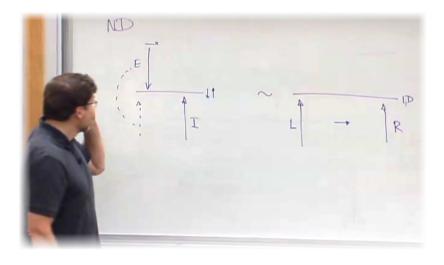
- "natural" reasoning steps
- inferences change the goal, hypotheses and "hanging"
- bidirectional reading, difficult proof search

... to the sequent calculus

$$\operatorname{IMPR} \ \frac{\Gamma, A \longrightarrow B}{\Gamma \longrightarrow A \supset B} \qquad \operatorname{IMPL} \ \frac{\Gamma \longrightarrow A \qquad \Gamma, B \longrightarrow C}{\Gamma, A \supset B \longrightarrow C}$$

- "fine-grained" reasoning steps
- left inferences change hypotheses
- bottom-up reading, easy proof search

Intuition



Natural deductions are "reversed" sequent calculus proofs

Intuition

Problem

How to make this intuition formal?

- how to define reversal generically?
- from N.D., how to derive S.C.?

and now, for something completely different. . .

A well-known programmer trick to save stack space

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• a function in direct style:

```
let rec tower1 = function
| [] \rightarrow 1
| x :: xs \rightarrow x ** tower1 xs
```

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the same in accumulator-passing style

```
let rec tower2 acc = function

| [] \rightarrow acc

| x :: xs \rightarrow tower2 (x ** acc) xs
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A well-known programmer trick to save stack space

• a function in direct style:

```
let rec tower1 = function

| [] → 1

| x :: xs → x ** tower1 xs
```

the same in accumulator-passing style

```
let rec tower2 acc = function
  | [] → acc
  | x :: xs → tower2 (x ** acc) xs

(* don't forget to reverse the input list *)
let tower xs = tower2 1 (List.rev xs)
```

In this talk

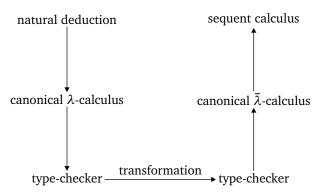
The message

- S.C. is an accumulator-passing N.D.
- there is a systematic transformation from N.D.-style systems to S.C.-style systems
- it is modular, i.e., it applies to variants of N.D./S.C.

In this talk

The method

Go through term assignments and reason on the type checker:



Outline

The intuition

The transformation

Some extensions

Starting point: the canonical λ -calculus [Pfenning, 2001]

$$M,N ::= \lambda x.M \mid \mathbf{inl}(M) \mid \mathbf{inr}(M) \mid M,N \mid \mathbf{case} \ R \ \mathbf{of} \ \langle x.M \mid x.M \rangle \mid R$$

$$R ::= RM \mid \pi_1(R) \mid \pi_2(R) \mid x$$

 $\Gamma \vdash M \Leftarrow A$ Checking

$$\begin{array}{c}
\text{LAM} \\
\Gamma, x : A \vdash M \Leftarrow B \\
\hline
\Gamma \vdash \lambda x . M \Leftarrow A \supset B
\end{array}$$

$$\begin{array}{c}
ATOM \\
\Gamma \vdash R \Rightarrow C \\
\hline
\Gamma \vdash R \Leftarrow C
\end{array}$$

$$\Gamma \vdash R \Rightarrow A$$
 Inference

$$VAR$$

$$x: A \in \Gamma$$

$$\Gamma \vdash x \Rightarrow A$$

$$\begin{array}{ccc}
APP & & & & & \Gamma \vdash M \Leftarrow A \\
\hline
\Gamma \vdash R \Rightarrow A \supset B & & & \Gamma \vdash M \Leftarrow A \\
\hline
\Gamma \vdash R M \Rightarrow B
\end{array}$$

Starting point: the canonical λ -calculus [Pfenning, 2001]

```
let rec check env: m \times a \rightarrow unit = function
  Lam (x, m), Arr (a, b) \rightarrow check ((x, a) :: env) (m, b)
   lnlm, Or(a, ) \rightarrow check env(m, a)
  | Inr m, Or (, b) \rightarrow \text{check env } (m, b)
 | Pair (m, n), And (a, b) \rightarrow check env <math>(m, a); check env (n, b)
 | Case (r, (x, m), (y, n)), c \rightarrow let (Or (a, b)) = infer env r in
    check ((x, a) :: env) (m, c); check ((y, b) :: env) (n, c)
 Atom r, Nat \rightarrow let Nat = infer env r in ()
and infer env: r \rightarrow a = function
 | Var x \rightarrow List.assoc x env
 | App (r, m) \rightarrow let (Arr (a, b)) = infer env r in
    check env (m, a); b
 | Pi| r \rightarrow let (And (a, )) = infer env r in a
 | Pirr \rightarrow let (And (, b)) = infer env r in b
```

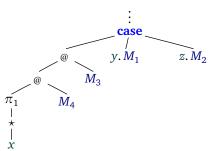
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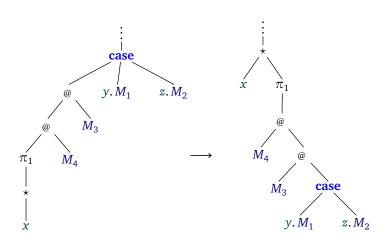
Inefficiency: no tail recursion

```
 \begin{tabular}{ll} (* ... *) & | Case (r, (x, m), (y, n)), c \rightarrow \textbf{let} (Or (a, b)) = infer env r in \\ & check ((x, a) :: env) (m, c); check ((y, b) :: env) (n, c) \\ & \textbf{and} \ infer env : r \rightarrow a = \textbf{function} \\ | Var x \rightarrow List.assoc x env \\ | App (r, m) \rightarrow \textbf{let} (Arr (a, b)) = infer env r in check env (m, a); b \\ | Pil r \rightarrow \textbf{let} (And (a, \_)) = infer env r in a \\ | Pir r \rightarrow \textbf{let} (And (\_, b)) = infer env r in b \\ \end{tabular}
```

Example



Solution: reverse atomic terms



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$$M,N ::= \lambda x.M \mid \mathbf{inl}(M) \mid \mathbf{inr}(M) \mid M,N \mid \mathbf{case} \ R \ \mathbf{of} \ \langle x.M \mid x.M \rangle \mid R$$

$$R ::= RM \mid \pi_1(R) \mid \pi_2(R) \mid x$$

$$\downarrow$$

$$V,W ::= \lambda x.V \mid \mathbf{inl}(V) \mid \mathbf{inr}(V) \mid V,W \mid x(S)$$

$$S ::= \cdot \mid V,S \mid \pi_1,S \mid \pi_2,S \mid \mathbf{case} \langle x.V \mid y.W \rangle$$

Solution: reverse atomic terms (and introduce an accumulator)

```
let rec check env: v \times a \rightarrow unit = function
  Lam (x, m), Arr (a, b) \rightarrow check ((x, a) :: env) (m, b)
  | Inl m, Or (a, ) \rightarrow check env (m, a)
 | \text{Inr m}, \text{Or } (, b) \rightarrow \text{check env } (m, b) |
 | Pair (m, n), And (a, b) \rightarrow \text{check env } (m, a); check env (n, b)
  | Var(x, s), c \rightarrow spine env(c, List.assoc x env, s) |
and spine env c: a \times s \rightarrow unit = function
  And (a, ), SPil s \rightarrow spine env (c, a, s)
  | And (, b), SPir s \rightarrow spine env (c, b, s)
  | Arr (a, b), SApp (m,s) \rightarrow check env (m, a); spine env (c, b, s)
 | Or (a, b), SCase (x, m, y, n) \rightarrow
    check ((x, a) :: env) (m, c); check ((y, b) :: env) (n, c)
  | c', SNil when c=c' \rightarrow ()
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 | Pair (m, n), And (a, b) \rightarrow \text{check env } (m, a); check env (n, b)
 | Var(x, s), c \rightarrow Spine env(c, List.assoc x env, s)
and spine env c: a \times s \rightarrow unit = function
 | And (a, ), SPil s \rightarrow Spine env (c, a, s)
 | And (, b), SPir s \rightarrow spine env(c, b, s)
 | Arr (a, b), SApp (m,s) \rightarrow check env (m, a); Spine env (c, b, s)
 | Or (a, b), SCase (x, m, y, n) \rightarrow
    check ((x, a) :: env) (m, c); check ((y, b) :: env) (n, c)
 | c', SNil when c=c' \rightarrow ()
```

End result: the $\bar{\lambda}$ -calculus [Herbelin, 1994]

a.k.a. spine calculus, or LJT, or n-ary application

$$V,W ::= \lambda x. V \mid V,W \mid \mathbf{inl}(V) \mid \mathbf{inr}(V) \mid x(S)$$
$$S ::= \cdot \mid V,S \mid \pi_1,S \mid \pi_2,S \mid \mathbf{case} \langle x.V \mid y.W \rangle$$

 $\Gamma \longrightarrow V : A$

Right rules

VLAM

$$\Gamma, x : A \longrightarrow M : B$$

 $\Gamma \longrightarrow \lambda x . M : A \supset B$

$$\frac{A \mapsto A \cap A}{x : A \in \Gamma \qquad \Gamma \mid A \longrightarrow S : C}{\Gamma \longrightarrow x(S) : C}$$

$$\Gamma \mid A \longrightarrow S : C$$

Focused left rules

$$\frac{\Gamma \longrightarrow V : A \qquad \Gamma \mid B \longrightarrow S : C}{\Gamma \mid A \supset B \longrightarrow V, S : C}$$

$$\frac{\mathsf{SATOM}}{\Gamma \mid C \longrightarrow \cdot : C}$$

Outline

The intuition

The transformation

Some extensions

The transformation

A new application for Danvy and Nielsen [2001]'s framework:

- (partial) CPS-transformation
- defunctionalization
- reforestation

Turns direct style into accumulator-passing style

Step 0. the initial type-checker

```
let rec check env: m \times a \rightarrow unit = function
 Lam (x, m), Arr (a, b) \rightarrow check ((x, a) :: env) (m, b)
  | Inl m, Or (a, ) \rightarrow check env (m, a)
 | \text{Inr m}, \text{Or } (, b) \rightarrow \text{check env } (m, b) |
 Pair (m, n), And (a, b) \rightarrow check env <math>(m, a); check env (n, b)
 | Case (r, (x, m), (y, n)), c \rightarrow let (Or (a, b)) = infer env r in
    check ((x, a) :: env) (m, c); check ((v, b) :: env) (n, c)
 Atom r, Nat \rightarrow let Nat = infer env r in ()
and infer env: r \rightarrow a = function
 | Var x \rightarrow List.assoc x env
 | App (r, m) \rightarrow let (Arr (a, b)) = infer env r in
    check env (m, a); b
 | Pi| r \rightarrow let (And (a, )) = infer env r in a
 | Pir r \rightarrow let (And (, b)) = infer env r in b
```

Step 1. CPS-transformation of infer

```
let rec check env: m \times a \rightarrow unit = function
  Lam (x, m), Arr (a, b) \rightarrow check ((x, a) :: env) (m, b)
  | Inl m, Or (a, ) \rightarrow check env (m, a)
 | \text{Inr m}, \text{Or } (, b) \rightarrow \text{check env } (m, b) |
 Pair (m, n), And (a, b) \rightarrow check env <math>(m, a); check env (n, b)
  | Case (r, (x, m), (y,n)), c \rightarrow infer env r (fun (Or (a, b)) \rightarrow
     check ((x, a) :: env) (m, c); check ((y, b) :: env) (n, c))
  Atom r, Nat \rightarrow infer env r (fun Nat \rightarrow ())
and infer env: r \rightarrow (a \rightarrow unit) \rightarrow unit = fun r s \rightarrow match r with
  | Var x \rightarrow s (List.assoc x env) |
  | App (r, m) \rightarrow infer env r (fun (Arr (a, b)) \rightarrow
     check env (m, a); s b)
 | Pi | r \rightarrow infer env r (fun (And (a, )) \rightarrow s a)
  | Pir r \rightarrow infer env r (fun (And (, b)) \rightarrow s b)
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```
let rec check env: m \times a \rightarrow unit = function
  Lam (x, m), Arr (a, b) \rightarrow check ((x, a) :: env) (m, b)
  | Inl m, Or (a, ) \rightarrow check env (m, a)
  | \text{Inr m}, \text{Or } (, b) \rightarrow \text{check env } (m, b) |
  Pair (m, n), And (a, b) \rightarrow check env <math>(m, a); check env (n, b)
  | Case (r, (x, m), (y,n)), c \rightarrow infer env r (fun (Or (a, b)) \rightarrow
     check ((x, a) :: env) (m, c); check ((y, b) :: env) (n, c)) (*SCase(x)
  Atom r, Nat \rightarrow infer env r (fun Nat \rightarrow ()) (* SNil *)
and infer env: r \rightarrow (a \rightarrow unit) \rightarrow unit = fun r s \rightarrow match r with
  | Var x \rightarrow s (List.assoc x env) |
  | App (r, m) \rightarrow infer env r (fun (Arr (a, b)) \rightarrow infer env r (fun (Arr (a, b))) \rightarrow infer env r (fun (Arr (a, b)))
     check env (m, a); s b) (*SApp(m,s) *)
  |\operatorname{Pil} r \to \operatorname{infer} \operatorname{env} r (\operatorname{fun} (\operatorname{And} (a, )) \to \operatorname{sa}) (*\operatorname{SPil}(s) *)
  | Pir r \rightarrow infer env r (fun (And (, b)) \rightarrow s b) (* SPir(s) *)
```

```
(* spines *)
type s =
    | SPil of s
    | SPir of s
    | SApp of m × s
    | SCase of string × m × string × m
    | SNil
```

```
let rec check env: m \times a \rightarrow unit = function
 (* ... *)
 | Case (r, (x, m), (y,n)), c \rightarrow infer env c (SCase <math>(x, m, y, n)) r
 | Atom r, Nat → infer env Nat SNil r
and infer env c: s \rightarrow r \rightarrow unit = fun s \rightarrow function
 | Var x \rightarrow apply env (c, List.assoc x env, s)
 | App (r, m) \rightarrow infer env c (SApp (m, s)) r
 | Pilr \rightarrow infer env c (SPils) r
 | Pirr \rightarrow inferenvc (SPirs) r
and apply env c: a \times s \rightarrow unit = function
 And (a, ), SPil s \rightarrow apply env (c, a, s)
 | And (, b), SPir s \rightarrow apply env (c, b, s)
 | Arr (a, b), SApp (m,s) \rightarrow check env (m, a); apply env (c, b, s)
 | Or (a, b), SCase (x, m, y, n) \rightarrow check ((x, a) :: env) (m, c);
                                    check ((y, b) :: env) (n, c)
 | c', SNil when c=c' \rightarrow ()
```

```
let rec check env: m \times a \rightarrow unit = function
 (* ... *)
 Case (r, (x, m), (y, n)), c \rightarrow rev_spine env c (SCase <math>(x, m, y, n))
 | Atom r, Nat → rev_spine env Nat SNil r
and rev_spine env c: s \rightarrow r \rightarrow unit = fun s \rightarrow function
 | Var x \rightarrow spine env (c, List.assoc x env, s) |
 | App (r, m) \rightarrow rev\_spine env c (SApp (m, s)) r
 | Pi| r \rightarrow rev_spine env c (SPil s) r
 | Pirr \rightarrow rev_spine env c (SPir s) r
and spine env c: a \times s \rightarrow unit = function
 | And (a, ), SPil s \rightarrow spine env (c, a, s)
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 | Arr (a, b), SApp (m,s) \rightarrow check env (m, a); spine env (c, b, s)
 | Or (a, b), SCase (x, m, y, n) \rightarrow check ((x, a) :: env) (m, c);
                                   check ((y, b) :: env) (n, c)
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```

Step 3. Reforestation

Goal

Introduce intermediate data structure of *reversed term V* to decouple *reversal* from *checking*:

let final_check env (m, a) = check env (rev_term m, a)

Step 3. Reforestation

```
let rec rev_term : m \rightarrow v = function
  | Lam(x, m) \rightarrow VLam(x, rev_term m) |
  Pair (m, n) \rightarrow VPair (rev_term m, rev_term n)
  | \ln m \rightarrow V \ln (rev term m) |
  | \text{Inr m} \rightarrow \text{VInr (rev term m)} |
  | Case (r, x, m, y, n) \rightarrow
   VHead (rev_spine r (SCase (x, rev_term m, y, rev_term n)))
  Atom r \rightarrow VHead (rev_spine r SAtom)
and rev_spine: r \rightarrow s \rightarrow h = \text{fun } r s \rightarrow \text{match } r \text{ with}
  | Var x \rightarrow HVar (x. s)
  | App (r, m) \rightarrow rev\_spine r (SApp (rev\_term m, s)) |
 | Pilr \rightarrow rev\_spiner (SPils) |
  | Pir r \rightarrow rev_spine r (SPir s)
```

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 | Pair (m, n), And (a, b) \rightarrow \text{check env } (m, a); check env (n, b)
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Example 1. Multiplicative connectives

We can define conjunction multiplicatively [Girard et al., 1989]:

$$\begin{array}{c|c} & [\vdash A] & [\vdash B] \\ \vdots & & \vdash C \\ \hline \vdash A \land B & \vdash C \end{array}$$

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$$\begin{array}{c|c} & [\vdash A] & [\vdash B] \\ \vdots & \vdots \\ \vdash A \land B & \vdash C \\ \hline \vdash C & \text{ConjE'} \end{array}$$

Term assignment:

$$M,N ::= \lambda x.M \mid M,N \mid \text{let } x,y = R \text{ in } M \mid R$$

$$R ::= x \mid RM$$

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Term assignment:

$$M,N ::= \lambda x.M \mid M,N \mid \text{let } x,y = R \text{ in } M \mid R$$

$$R ::= x \mid RM$$

Reversed terms:

$$V,W ::= \lambda x.V \mid V,W \mid x(S) \mid R$$

 $S ::= \cdot \mid M,S \mid (x,y).M$

Example 2. A modal logic of necessity

We can introduce a necessity operator: [Pfenning and Davies, 2001]

$$\begin{array}{c} \text{BoxI} & \text{BoxE} \\ \underline{\Delta; \cdot \vdash A} \\ \underline{\Delta; \Gamma \vdash \Box A} & \underline{\Delta; \Gamma \vdash C} \end{array}$$

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$$\begin{array}{c|c} \operatorname{BoxI} & \operatorname{BoxE} \\ \Delta; \cdot \vdash A & \Delta; \Gamma \vdash \Box A & \Delta, A; \Gamma \vdash C \\ \hline \Delta; \Gamma \vdash \Box A & \Delta; \Gamma \vdash C \end{array}$$

Term assignment:

$$M ::= \lambda x.M \mid \mathbf{box}(M) \mid \mathbf{let} \ \mathbf{box} \ X = R \ \mathbf{in} \ M \mid R$$

$$R ::= x \mid X \mid R M$$

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Term assignment:

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$$R ::= x \mid X \mid R M$$

Reversed terms:

$$V ::= \lambda x. V \mid \mathbf{box}(V) \mid x(S) \mid \mathbf{X}(S)$$
$$S ::= \cdot \mid M, S \mid \mathbf{X}. M$$

Conclusion

- a systematic derivation of S.C.-style calculi from N.D.-style calculi, using off-the-shelf program transformations
- data type + checker → data type + reversal + checker
- works for non-canonical λ-calculus (but it has to be bidirectional)
- works for unfocused sequent calculus $(\lambda_{Nat}/\lambda^{Gtz})$ calculi of Espírito Santo [2007])

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- works for unfocused sequent calculus $(\lambda_{Nat}/\lambda^{Gtz})$ calculi of Espírito Santo [2007])

Further work

- justification of bidirectional type checking
- what about Moggi's monadic calculus, a.k.a. LJQ?
- what about classical logic?

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