

default: ch2 - [ch2:helloSLAM.cpp] — KDevelop

SessionProjectRunNavigationFileEditViewBookmarksToolsCodeWindowSettingsHelp

BuildStopStop AllDebugExecuteNewSaveSave AsUndoQuick Open...ContinueOutline...

helloSLAM.cpp

Line: 8 Col: 1

1#include <iostream>
2using namespace std;
3
4int main(int argc, char **argv) {
5 cout << "Hello SLAM!" << endl;
6 return 0;
7}
8

Close all other output viewsSearch...

helloSLAMhelloSLAM

DebugHello SLAM!

Disassemble/RegistersMemoryBreakpointsBuildGDBDebugFrame Stack