## aos 575-pset 1-code-rios

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```
[2]: import numpy as np import matplotlib.pyplot as plt
```

## 0.0.1 Problem 3: Lorenz equation discretization

This is ugly but it works. Future work would include creating a single Runge-Kutta method to account for all variables discretized herein.

```
[82]: # Define differential functions for each coordinate direction
      def F_x(x, y, z, t, r):
         return -3*(x - y)
      def F_y(x, y, z, t, r):
          return -x*z + r*x - y
      def F_z(x, y, z, t, r):
          return x*y - z
      # Define the RK2 Heun method for each coordinate direction.
      # All three methods are equivalent, just for different directions.
      def diff_x(x, y, z, t, dt, r):
          # Define Heun-specific coefficients
          a, b, c = 1, 1/2, 1
          # Calculate xi values
          xi_1 = x
          xi_2 = x + dt*a*F_x(x, y, z, t, r)
          # Calculate approximation for timestep (n+1)
          x_{-} = x + dt*(b*F_x(xi_1, y, z, t + c*dt, r) + b*F_x(xi_2, y, z, t + c*dt, l)
       ⊶r))
          return x_
      def diff_y(x, y, z, t, dt, r):
          a, b, c = 1, 1/2, 1
          xi_1 = y
          xi_2 = y + dt*a*F_y(x, y, z, t, r)
          y = y + dt*(b*F_y(x, xi_1, z, t + c*dt, r) + b*F_y(x, xi_2, z, t + c*dt, u)
       -r))
         return y_
      def diff_z(x, y, z, t, dt, r):
          a, b, c = 1, 1/2, 1
          xi_1 = z
```

```
xi_2 = z + dt*a*F_z(x, y, z, t, r)
   z_{-} = z + dt*(b*F_z(x, y, xi_1, t + c*dt, r) + b*F_z(x, y, xi_2, t + c*dt, l)
 ⊶r))
   return z
# Define initial values
r = 25
x_0, y_0, z_0 = 1, 1, 1
# Initialize arrays to store x, y, z values
x = np.array([x_0])
y = np.array([y_0])
z = np.array([z_0])
# Define time and timestep
dt, t_0 = 0.01, 0
t = np.array([t_0])
N = 15000 \# number of steps
# Iterate through timesteps
for i in range(0, N):
    # Generate x^{n-1}
   x_{-} = diff_{x}(x[i], y[i], z[i], t[i], dt, r)
   x = np.append(x, x_{-})
   # Generate y^{n-1}
   y_{-} = diff_{y}(x[i], y[i], z[i], t[i], dt, r)
   y = np.append(y, y_)
    # Generate z^{n-1}
   z_{-} = diff_{z}(x[i], y[i], z[i], t[i], dt, r)
   z = np.append(z, z_)
    # Step forward in time
    t = np.append(t, t[i] + dt)
```