Homework 2 - ME I4600, Computational Fluid Mechanics, Spring 2022, City College of New York

General imports

```
In [554... import matplotlib.pyplot as plt import numpy as np
```

Problem 1

```
In [555...
          def runge(x):
              1.1.1
              Runge's function.
              Input(s):
                  x: float
              Output(s):
                 y: float
              return 1/(1 + 25*x**2)
          def lpi(x, arr x, arr y, n=None):
              Lagrange polynomial interpolation.
              Input(s):
                  x: (float) the point on the x-axis at which interpolation is desired
                  arr x: (list or NumPy array) array of points on the x-axis
                  arr y: (list or NumPly array) array of functions based on points from the x-axis
                  n: (int, optional) order of interpolation
              Outputs(s):
                  p: (float) interpolated point that is a function of 'x'
              # If no order was specified, set order to be equal to umber of points
                  n = len(arr x)
              # Intialize interpolation
              # Iterate through products
              for j in range(0, n):
                  # Initialize inner sum
                  s = 1
                  # Iterate through sums
                  for i in range(0, n):
                      \# i =/= j condition
                      if i != j:
                           s = s * (x - arr x[i])/(arr x[j] - arr x[i])
                  p += arr y[j]*s
              return p
```

Problem 1a: Using the above data in the table, find the interpolated value at x=0.9. (10 pts)

```
In [558... # Define points along the x-axis
    step_x = 0.2
    arr_x_a = np.arange(-1, 1+step_x, step_x)
    # Define functions of the arr_x points
```

```
arr_y_a = np.array([runge(x) for x in arr_x_a])

# Define point at which interpolation is desired
x = 0.9
# Calculate the interpolation
p_a = lpi(x, arr_x_a, arr_y_a)
```

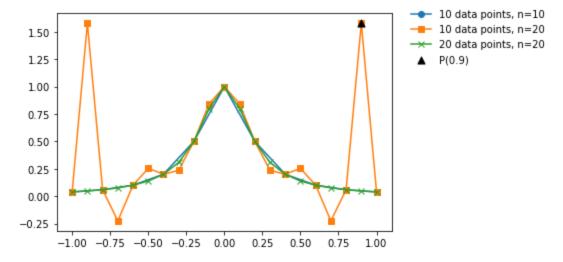
Problem 1b: Use Runge's function to generate a table of 21 equally spaced data points. Interpolate these data using a Lagrange polynomial of order 20. Plot this polynomial and comment on the comparison between your result and the plot of part (a). (10 pts)

```
In [569...
# Define points along the x-axis
arr_x_b = np.linspace(-1, 1, 21)
# Define functions of the arr_x points
arr_y_b = np.array([runge(x) for x in arr_x_b])

# Define point at which interpolation is desired
x = 0.9
# Calculate the interpolation
p_b_10 = [lpi(i, arr_x_a, arr_y_a) for i in arr_x_b]
p_b_20 = [lpi(i, arr_x_b, arr_y_b) for i in arr_x_b]
print(arr_y_b[-2])
```

0.04705882352941175

```
fig, ax = plt.subplots()
    ax.plot(arr_x_a, arr_y_a, marker='o', label='10 data points, n=10')
    ax.plot(arr_x_b, p_b_10, marker='s', label='10 data points, n=20')
    ax.plot(arr_x_b, p_b_20, marker='x', label='20 data points, n=20')
    ax.scatter(x, p_a, marker='^', c='k', s=50, zorder=10, label='P(0.9)')
    fig.legend(loc='upper right', bbox_to_anchor=(1.275, 0.925), frameon=False);
```



Problem 2

Problem 2a: Interpolate the data with the Lagrange polynomial (5 pts). Plot the polynomial and the data points (5 pts). Use the polynomial to predict the condition of the lakes in 2009 (5 pts). Discuss this prediction (5 pts).

```
In [581... # List of years
    interval = 2
    years = np.arange(1993, 2009, interval)
    # Toxin concentrations
    conc = np.array([12, 12.7, 13, 15.2, 18.2, 19.8, 24.1, 28.1])
```

```
# Interpolate concentrations annually
years_annual = np.arange(1993, 2009, interval/2)
conc_p = [lpi(year, years, conc) for year in years_annual]

# Predict concentration in 2009
conc_p_2009 = lpi(2009, years, conc)
print('Toxin concentration prediction for 2009: {0:.2f}'.format(conc_p_2009))
```

Toxin concentration prediction for 2009: -38.40

Problem 2b: Interpolation may also be used to fill "holes" in the date. Say the data from 1997 and 1999 disappeared. Predict these values using the Lagrange polynomial fitted through the other known data points (10 pts).

```
In [584...
          # Boolean mask
          mask = np.where((years != 1997) & (years != 1999))
          # List of years
          years missing = years[mask]
          # Toxin concentrations
          conc missing = conc[mask]
          # Interpolate concentrations annually
          years annual = np.arange(1993, 2009, interval/2)
          conc p hole = [lpi(year, years missing, conc missing) for year in years annual]
          # Plot the concentrations
          fig, ax = plt.subplots(figsize=(4, 3))
          ax.plot(years annual, conc p, marker='o', markevery=interval, label='Complete dataset')
          ax.scatter(years missing, conc missing, s=50, color='tab:orange')
          ax.plot(years annual, conc p hole, color='tab:orange', label='Missing data')
          ax.set xlabel('Year')
          ax.set xticks(years)
          ax.set ylabel('Concentration')
          fig.legend(loc='upper right', bbox to anchor=(1.4, 0.925), frameon=False);
```

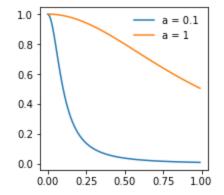
```
27.5 - Complete dataset Missing data

25.0 - 22.5 - 20.0 - 17.5 - 15.0 - 12.5 - 1993 1995 1997 1999 2001 2003 2005 2007
```

```
2004.0 21.658515625000003
2005.0 24.1
2006.0 26.586067708333335
2007.0 28.1
2008.0 27.045703125000003
```

Problem 3

Problem 3a: For a = 0.1 and 1, (a) plot the function from 0 to 1 (5 pts).



Problem 3b: Integrate this function from 0 to 1 using Newton-Cotes methods of various orders (n = 2, 3, and 6) with fixed number of intervals (number of intervals = 12) (10 pts).

```
B = [(n**(i+1))/(i+1) for i in range(0, n+1)]
# Generate Vandermonde matrix
M = np.vander(arr, max(arr)+1, increasing=True)
# Generate coefficients
coeffs = np.dot(np.linalg.inv(M.T), B)/n
return coeffs
```

In [586...

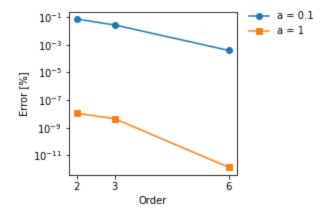
def ncc_integration(n, lower, upper, a):

 # Define lower and upper bounds
 arr = np.linspace(lower, upper, n+1)
 # Generate Newton-Cotes coefficients
 coeffs = ncc(n)
 # Initialize integration
 s = 0
 # Perform integration
 s = (upper - lower)*np.nansum([coeffs[k]*lorentz(arr[k], a) for k in range(0, n+1)])

return s

```
In [590...
          # Define number of intervals
          N = 12
          # Define x-values
          arr x = np.linspace(0, 1, N)
          # Initialize list of integrations and errors
          ints, errors = [], []
          # Define actual value (from Wolfram)
          actual = [0.147113, np.pi/4]
          # Define orders of interest
          ns = [2, 3, 6]
          # Perform integrations
          for j, a in enumerate([0.1, 1]):
              # Initialize list to capture coefficient-specific errors
              error = []
              for n in ns:
                  s = np.nansum([ncc integration(n, arr x[i], arr x[i+1], a) for i in range(0, len(a))
                  print('When a is {0}, the integral of function with order {1} is: {2:.6f}'.format
                  ints.append(s)
                  # Catalogue error
                  error.append(100*np.abs((s - actual[j])/actual[j]))
              # Append to master error list
              errors.append(error)
          # Plotting
          fig, ax = plt.subplots(figsize=(3,3))
          ax.plot(ns, errors[0], marker='o', label='a = 0.1')
          ax.plot(ns, errors[1], marker='s', label='a = 1')
          ax.set yscale('log')
          ax.set_xticks(ns)
          ax.set xlabel('Order')
          ax.set ylabel('Error [%]')
          fig.legend(loc='upper right', bbox to anchor=(1.3, 0.925), frameon=False);
```

When a is 0.1, the integral of function with order 2 is: 0.147009 When a is 0.1, the integral of function with order 3 is: 0.147074 When a is 0.1, the integral of function with order 6 is: 0.147112 When a is 1, the integral of function with order 2 is: 0.785398 When a is 1, the integral of function with order 3 is: 0.785398 When a is 1, the integral of function with order 6 is: 0.785398



 10^{-1}

10-2

12

Intervals

24

Problem 3c: Integrate this function from 0 to 1 using trapezoidal rule (n = 1) with variable number of intervals (number of intervals = 6, 12, and 24) (10 pts).

```
In [592...
          # Define order
          n = 1
          # Define Lorentz coefficients
          Ns = [6, 12, 24]
          # Intialize list of actuals and errors
          actual, errors = [0.147113, np.pi/4], []
          # Perform integrations
          for j, a in enumerate([0.1, 1]):
              error = []
              for N in Ns:
                  arr x = np.linspace(0, 1, N)
                  s = np.nansum([ncc integration(n, arr x[i], arr x[i+1], a) for i in range(0, len(a))
                  print('Integral of function with {0} intervals is: {1:.6f}'.format(N, s))
                  error.append(100*np.abs((s - actual[j])/actual[j]))
              errors.append(error)
          # Plotting
          fig, ax = plt.subplots(figsize=(3, 3))
          ax.plot(Ns, errors[0], marker='o', label='a = 0.1')
          ax.plot(Ns, errors[1], marker='s', label='a = 1')
          ax.set yscale('log')
          ax.set xticks(Ns)
          ax.set xlabel('Intervals')
          ax.set ylabel('Error [%]')
          ax.legend(frameon=False);
         Integral of function with 6 intervals is: 0.161237
         Integral of function with 12 intervals is: 0.147413
         Integral of function with 24 intervals is: 0.147110
         Integral of function with 6 intervals is: 0.783732
         Integral of function with 12 intervals is: 0.785054
         Integral of function with 24 intervals is: 0.785319
            10¹
                               a = 0.1
                               a = 1
            10°
```

Problem 4: Integrate the function of Problem 3 using Gauss quadrature of various numbers of Gauss points

```
In [594...
          def gq(n, a):
              1.1.1
              Gauss quadrature for use with the Lorentz profile.
              Input(s):
                  n: int
                  a: int, for Lorentz profile
              Output(s):
                  s: float
              \# Catalogue abscissas and weights for orders (n = 2 to n = 5)
                  arr x = [-1, -np.sqrt(3)/3, np.sqrt(3)/3, 1]
                  w = [1, 1, 1, 1]
              elif n == 3:
                  arr x = [-1, -np.sqrt(15)/5, 0, np.sqrt(15)/5, 1]
                  w = [1, 5/9, 8/9, 5/9, 1]
              elif n == 4:
                  arr x = [-1,
                            -np.sqrt(525 + 70*np.sqrt(30))/35,
                            -np.sqrt(525 - 70*np.sqrt(30))/35,
                            np.sqrt(525 - 70*np.sqrt(30))/35,
                            np.sqrt(525 + 70*np.sqrt(30))/35,
                  w = [1,
                        (18-np.sqrt(30))/36,
                        (18+np.sqrt(30))/36,
                        (18+np.sqrt(30))/36,
                        (18-np.sqrt(30))/36, 1]
              elif n == 5:
                  arr x = [-1,
                            -np.sqrt(245 + 14*np.sqrt(70))/21,
                            -np.sqrt(245 - 14*np.sqrt(70))/21,
                            0,
                            np.sqrt(245 - 14*np.sqrt(70))/21,
                            np.sqrt(245 + 14*np.sqrt(70))/21,
                  w = [1,
                        (322 - 13*np.sqrt(70))/900,
                        (322 + 13*np.sqrt(70))/900,
                        128/225,
                        (322 + 13*np.sqrt(70))/900,
                        (322 - 13*np.sqrt(70))/900,
                        1]
              else:
                  return None
              # Get quadrature
              s = np.nansum([w[k]*lorentz(arr x[k], a) for k in range(1, n+1)])
              return s
```

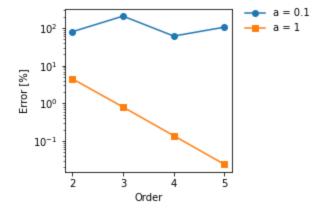
```
In [596... # Initialize quadrature orders
    ns = [2, 3, 4, 5]
    # Intialize list of actuals and errors
    actual, errors = [0.147113, np.pi/4], []

# Iterate over each value of a
for j, a in enumerate([0.1, 1]):
    error = []
```

```
for n in ns:
    value = gq(n, a)/2
    print('Gauss quadrature for Lorentz profile with coefficient {0} and order {1} is:
    error.append(100*np.abs(actual[j] - value)/actual[j])
    errors.append(error)

fig, ax = plt.subplots(figsize=(3, 3))
    ax.plot(ns, errors[0], marker='o', label='a = 0.1')
    ax.plot(ns, errors[1], marker='s', label='a = 1')
    ax.set_xticks(ns)
    ax.set_xtlabel('Order')
    ax.set_ylabel('Error [%]')
    ax.set_yscale('log')
    fig.legend(loc='upper right', bbox_to_anchor=(1.3, 0.925), frameon=False);
```

```
Gauss quadrature for Lorentz profile with coefficient 0.1 and order 2 is: 0.029126 Gauss quadrature for Lorentz profile with coefficient 0.1 and order 3 is: 0.453552 Gauss quadrature for Lorentz profile with coefficient 0.1 and order 4 is: 0.056556 Gauss quadrature for Lorentz profile with coefficient 0.1 and order 5 is: 0.303252 Gauss quadrature for Lorentz profile with coefficient 1 and order 2 is: 0.750000 Gauss quadrature for Lorentz profile with coefficient 1 and order 3 is: 0.791667 Gauss quadrature for Lorentz profile with coefficient 1 and order 4 is: 0.784314 Gauss quadrature for Lorentz profile with coefficient 1 and order 5 is: 0.785586
```



```
In []:
```