6th Semester

Matrix Minimization

Design patterns group project

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Code

```
package src;
import java.util.LinkedList;
import java.util.Queue;
class MatrixOptimization {
  static int ROW = 9;
   static int COL = 10;
  // to store matrix cell coordinates
   static class Point {
      int x;
      int y;
      public Point(int x, int y) {
           this.x = x;
           this.y = y;
       }
  };
   // a Data Structure for queue used in BFS
   static class queueNode {
       Point pt; // the coordinates of a cell
       int dist; // cell's distance of from the source
       public queueNode(Point pt, int dist) {
           this.pt = pt;
           this.dist = dist;
       }
  };
   // check whether given cell (row, col) is a valid cell or not.
```

```
static boolean isValid(int row, int col) {
       // return true if row number and column number is in range
       return (row ≥ 0) && (row < ROW) && (col ≥ 0) && (col < COL);
  }
  // these arrays are used to get row and column numbers of 4 neighbours
of a
   // given cell
  static int rowNum[] = { -1, 0, 0, 1 };
  static int colNum[] = { 0, -1, 1, 0 };
   // function to find the shortest path between a given source cell to a
   // destination cell.
  static int BFS(int mat[][], Point src, Point dest) {
       // check source and destination cell of the matrix have value 1
       if (mat[src.x][src.y] \neq 1 \mid | mat[dest.x][dest.y] \neq 1)
           return -1;
       boolean[][] visited = new boolean[ROW][COL];
       // mark the source cell as visited
       visited[src.x][src.y] = true;
       // create a queue for BFS
       Queue<queueNode> q = new LinkedList ♦();
       // distance of source cell is 0
       queueNode s = new queueNode(src, 0);
       q.add(s); // Enqueue source cell
       // do a BFS starting from source cell
      while (!q.isEmpty()) {
           queueNode curr = q.peek();
           Point pt = curr.pt;
           // if we have reached the destination cell, we are done
           if (pt.x = dest.x \&\& pt.y = dest.y)
               return curr.dist;
           // otherwise dequeue the front cell in the queue and enqueue
its adjacent cells
```

```
q.remove();
          for (int i = 0; i < 4; i \leftrightarrow) {
              int row = pt.x + rowNum[i];
              int col = pt.y + colNum[i];
              // if adjacent cell is valid, has path and not visited yet,
enqueue it.
              if (isValid(row, col) && mat[row][col] = 1 &&
!visited[row][col]) {
                  // mark cell as visited and enqueue it
                  visited[row][col] = true;
                  queueNode Adjcell = new queueNode(new Point(row, col),
curr.dist + 1);
                  q.add(Adjcell);
              }
          }
      }
      // return -1 if destination cannot be reached
      return -1;
  }
  // Driver Code
  public static void main(String[] args) {
      // __ is Path, XX is Obstacle
      final int _{-} = 1;
      final int XX = 0;
      int mat[][] = {
              { _, XX, _, _, _, XX, _, _, _},
              { _, XX, _, XX, _, _, XX, _, },
              { _, _, _, XX, _, _, XX, _, XX, _ },
              { XX, XX, XX, XX, __, XX, XX, XX, XX, __ },
              { __, _, _, XX, _, _, _, XX, _, XX },
              { _, XX, _, _, _, XX, _, XX, XX },
              { __, XX, XX, XX, XX, XX, XX, XX, XX, __ },
```

```
{ _, XX, _, _, _, XX, _, _, _, },
              { __, __, XX, XX, XX, XX, __, XX, XX, __ } };
      System.out.println("Matrix Minimization App \n");
      // Source cell input
      System.out.print("Enter the source cell row: ");
      int srcRow = Integer.parseInt(System.console().readLine());
      System.out.print("Enter the source cell column: ");
      int srcCol = Integer.parseInt(System.console().readLine());
      // Destination cell input
      System.out.print("\nEnter the destination cell row: ");
      int destRow = Integer.parseInt(System.console().readLine());
      System.out.print("Enter the destination cell column: ");
      int destCol = Integer.parseInt(System.console().readLine());
      Point source = new Point(srcRow, srcCol);
      Point dest = new Point(destRow, destCol);
      System.out.println("\nFor Source (" + source.x + ", " + source.y +
") to Destination (" + dest.x + ", "
              + dest.y + "): ");
      int dist = BFS(mat, source, dest);
      if (dist \neq -1)
          System.out.println("Shortest Path: " + dist);
      else
          System.out.println("\nShortest Path doesn't exist");
```

Output