

# Geometrics

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# Chapter 1

## Class Index

### 1.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

<a href="#">Quaternion</a>	3
<a href="#">Vec3&lt; T &gt;</a>	4
<a href="#">Geometrics::Vector&lt; T &gt;</a>	4



## Chapter 2

# Class Documentation

### 2.1 Quaternion Class Reference

#### Public Member Functions

- **Quaternion** (float inW, float inX, float inY, float inZ)
- **Quaternion** (float alpha, float beta, float gamma)
- template<typename T >  
  **Quaternion** (float angle, [Vec3](#)< T > const &axis)
- template<typename T , typename U >  
  **Quaternion** ([Vec3](#)< T > const &v1, [Vec3](#)< U > const &v2)
- **Quaternion operator\*** ([Quaternion](#) const &rOp) const
- **Quaternion operator+** ([Quaternion](#) const &rOP) const
- void **normalize** ()
- bool **isNormalized** () const
- float **angle** ([Quaternion](#) const &toQuat) const
- **Quaternion slerp** ([Quaternion](#) const &destQt, float t, float eps=0.01) const
- **Quaternion lerp** ([Quaternion](#) const &destQt, float t) const
- void **toByteArray** (byte \*bArray) const
- float **rotAngleInDeg** ()

#### Public Attributes

- float **w**
- float **x**
- float **y**
- float **z**

The documentation for this class was generated from the following file:

- Geometrics/Quaternion.h

## 2.2 Vec3< T > Struct Template Reference

### Public Member Functions

- **Vec3** (T inX, T inY, T inZ)
- float **norm2** () const
- template<typename U >  
U **dot** (Vec3< U > const &v) const
- template<typename U >  
Vec3< U > **cross** (Vec3< U > const &v) const

### Public Attributes

- T **x**
- T **y**
- T **z**

```
template<typename T> struct Vec3< T >
```

The documentation for this struct was generated from the following file:

- Geometrics/Vec3.h

## 2.3 Geometrics::Vector< T > Class Template Reference

### Public Member Functions

- **Vector** (T coordinates[], const int dimension)
- **Vector** (const int dim, const T value)
- virtual **~Vector** ()
- bool **operator==** (const **Vector** &v)
- bool **operator!=** (const **Vector** &v)
- const **Vector** **operator+** (const **Vector** &v)
- const **Vector** **operator-** (const **Vector** &v)
- T & **operator[]** (const int &i)
- const T & **operator[]** (const int &i) const

```
template<class T = int> class Geometrics::Vector< T >
```

### 2.3.1 Constructor & Destructor Documentation

2.3.1.1 `template<class T = int> Geometrics::Vector< T >::Vector ( T coordinates[],  
const int dimension ) [inline]`

The first constructor.



## Parameters

<i>coordinates</i>	The coordinates of the <a href="#">Vector</a> .
<i>dimension</i>	The dimension of the <a href="#">Vector</a> .

2.3.1.2 `template<class T = int> Geometrics::Vector< T >::Vector ( const int dim, const T value ) [inline]`

The second constructor

## Parameters

<i>dim</i>	The dimension of the <a href="#">Vector</a> .
<i>value</i>	All coordinates are set to that value.

2.3.1.3 `template<class T = int> virtual Geometrics::Vector< T >::~~Vector ( ) [inline, virtual]`

The destructor, which deletes the array, storing the coordinates.

## 2.3.2 Member Function Documentation

2.3.2.1 `template<class T = int> bool Geometrics::Vector< T >::operator!= ( const Vector< T > & v ) [inline]`

Overloading the != operator.

## Parameters

<i>v</i>	The other <a href="#">Vector</a> .
----------	------------------------------------

## Returns

True, if not all the coordinates of both [Vector](#) are equal.

2.3.2.2 `template<class T = int> const Vector Geometrics::Vector< T >::operator+ ( const Vector< T > & v ) [inline]`

Overloading the + operator. Add two vector *v1* and *v2*. Throw an assertion, if the dimension of the vectors are not the same.

## Parameters

<i>v</i>	The other <a href="#">Vector</a> .
----------	------------------------------------

**Returns**

[Vector](#) v3, where all coordinate i holds:  $v3[i] = v1[i] + v2[i]$ .

**2.3.2.3** `template<class T = int> const Vector Geometrics::Vector< T >::operator- ( const Vector< T > & v ) [inline]`

Overloading the - operator. Add two vector v1 and v2. Throw an assertion, if the dimension of the vectors are not the same.

**Parameters**

<a href="#">v</a>	The other <a href="#">Vector</a> .
-------------------	------------------------------------

**Returns**

[Vector](#) v3, where all coordinate i holds:  $v3[i] = v1[i] - v2[i]$ .

**2.3.2.4** `template<class T = int> bool Geometrics::Vector< T >::operator== ( const Vector< T > & v ) [inline]`

Overloading the == operator.

**Parameters**

<a href="#">v</a>	The other <a href="#">Vector</a> .
-------------------	------------------------------------

**Returns**

True, if all the coordinates of both Vectors are the same.

**2.3.2.5** `template<class T = int> T& Geometrics::Vector< T >::operator[] ( const int & i ) [inline]`

Overloading the [] operator. Non-Const variante.

**Parameters**

<a href="#">i</a>	is the coordinate index
-------------------	-------------------------

**Returns**

The value of the coordinate with the index i.

**2.3.2.6** `template<class T = int> const T& Geometrics::Vector< T >::operator[] ( const int & i ) const` `[inline]`

Overloading the [] operator. Const variante.

#### Parameters

<i>i</i>	is the coordinate index
----------	-------------------------

#### Returns

The value of the coordinate with the index i.

The documentation for this class was generated from the following file:

- Geometrics/Vector.h