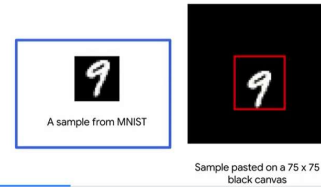
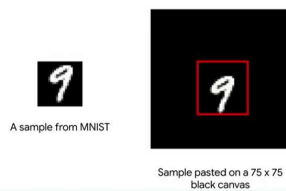


Object Localization and Detection

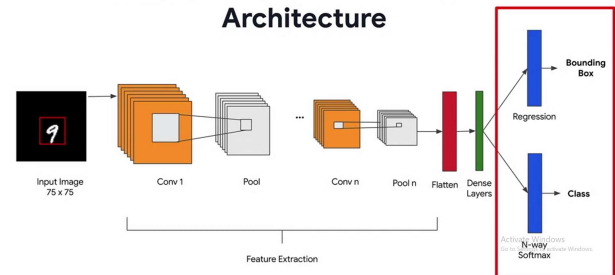
Augmenting MNIST for Object Localization



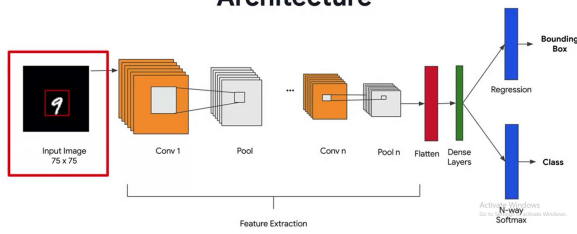
Augmenting MNIST for Object Localization



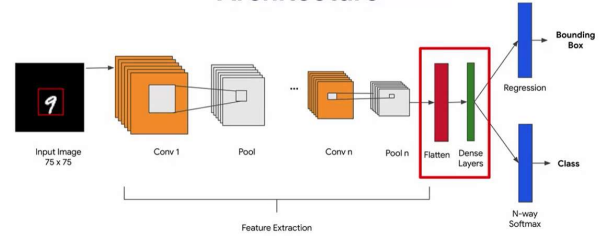
Convolutional Neural Networks Architecture



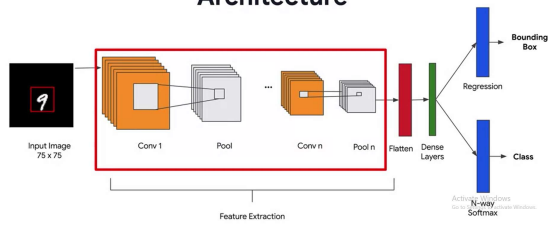
Convolutional Neural Networks Architecture



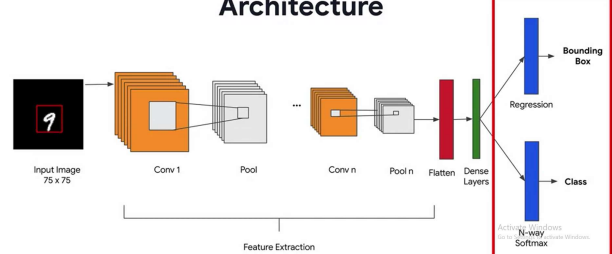
Convolutional Neural Networks Architecture

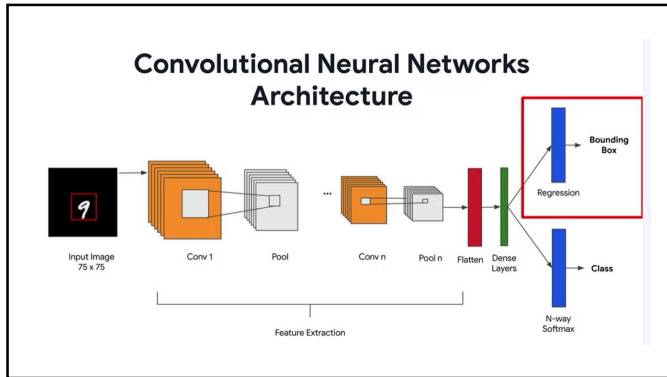


Convolutional Neural Networks Architecture



Convolutional Neural Networks Architecture



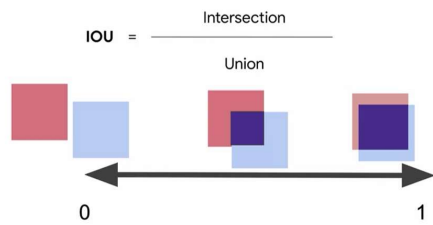


Evaluating Object Localization

Intersection Over Union

$$\text{IOU} = \frac{\text{Intersection}}{\text{Union}}$$

Intersection Over Union



Object Detection and Sliding Windows

Object Detection examples



Facial Detection / Recognition
[Amazon Rekognition](https://docs.aws.amazon.com/rekognition/latest/dg/faces.html)

<https://docs.aws.amazon.com/rekognition/latest/dg/faces.html>



Counting vehicles
[PowerAI](https://github.com/Mapbox/counting-cars)

<https://github.com/Mapbox/counting-cars>



Analyzing aerial imagery
[DIGITS](https://blogs.nvidia.com/deep-learning-networks/object-detection-digits/)

<https://blogs.nvidia.com/deep-learning-networks/object-detection-digits/>
Activate Windows

Object Detection examples



Facial Detection / Recognition
[Amazon Rekognition](https://docs.aws.amazon.com/rekognition/latest/dg/faces.html)

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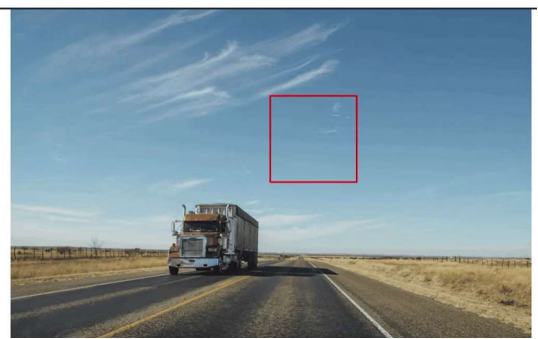
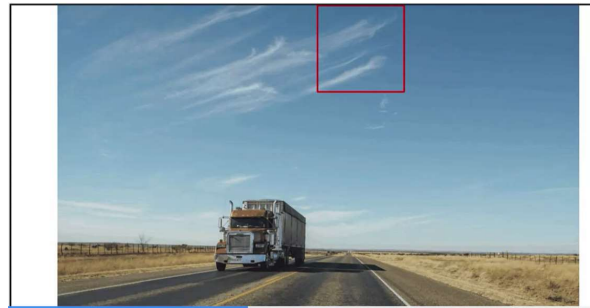
Counting vehicles
[PowerAI](https://github.com/IBM/powerai-counting-cars)

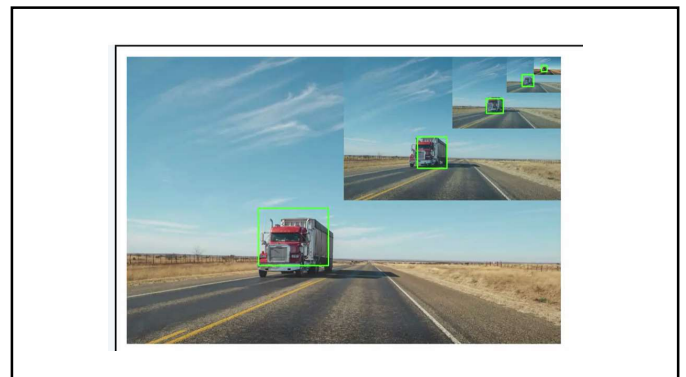
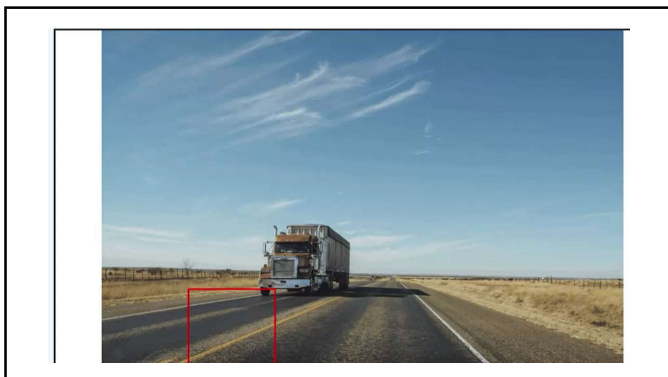
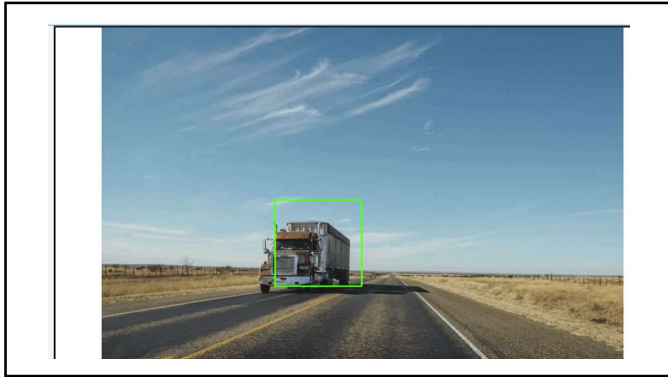
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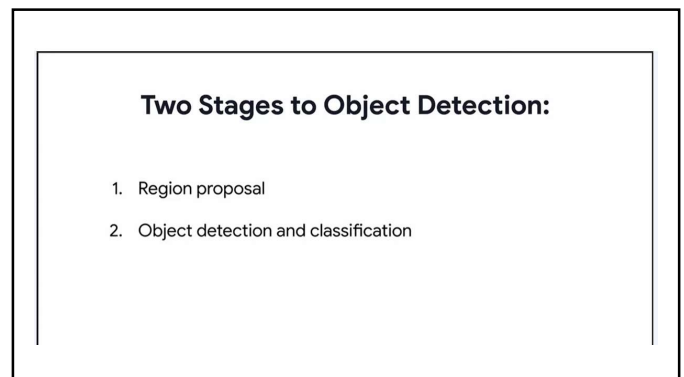
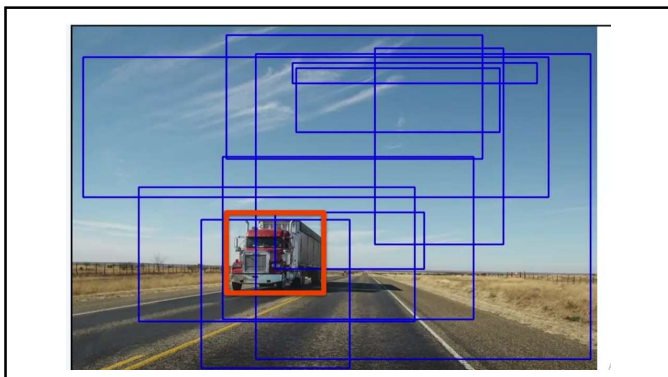
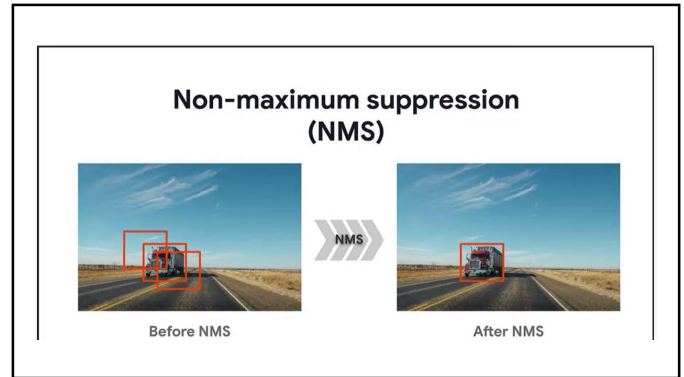
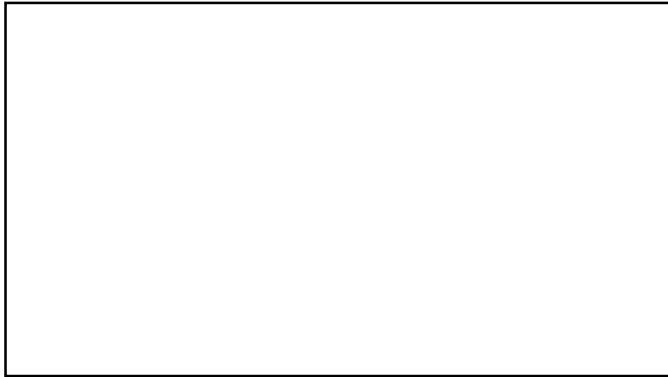


Analyzing aerial imagery
[DIGITS](https://devblogs.nvidia.com/autodetect-deep-neural-network-object-detection-digits/)

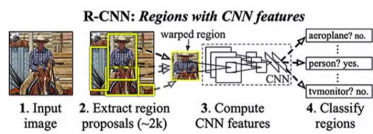
<https://devblogs.nvidia.com/autodetect-deep-neural-network-object-detection-digits/>





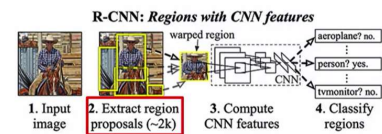


R-CNN

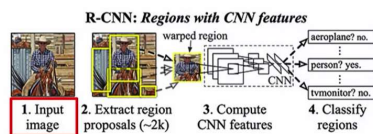


The R-CNN architecture (source: Girshick et al., 2013)

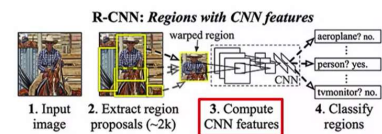
R-CNN



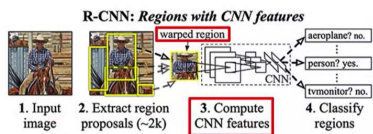
R-CNN



R-CNN



R-CNN



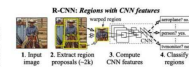
<https://arxiv.org/pdf/1311.2524.pdf>

Rich feature hierarchies for accurate object detection and semantic segmentation
Tech report (v5)

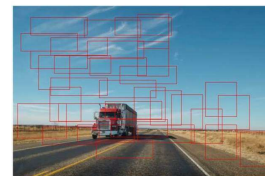
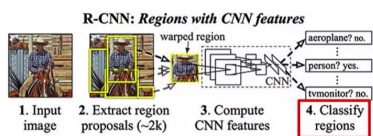
Ross Girshick Jeff Donahue Trevor Darrell Jitendra Malik
UC Berkeley
{rbg, jshonah, trevor, malik}@eecs.berkeley.edu

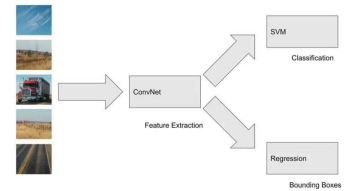
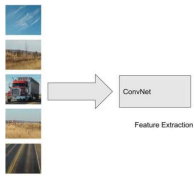
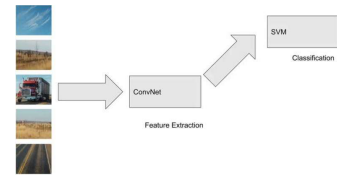
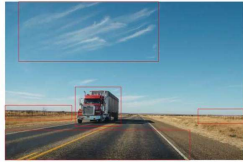
Abstract

Object detection performance, as measured on the canonical PASCAL VOC dataset, has plummeted in the last few years. The best performing methods are complex ensemble systems that typically combine multiple low-level image features with high-level context. In this paper, we



R-CNN





Transfer Learning for R-CNN

Pre-train: auxiliary task



Large auxiliary Data Set

Fine-tune: domain specific task



Warped region proposals

R-CNN disadvantages



Slow



memory

Transfer Learning for R-CNN

Pre-train: auxiliary task



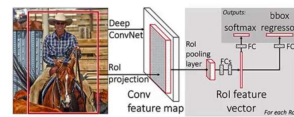
Large auxiliary Data Set

Fine-tune: domain specific task



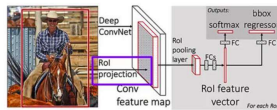
Warped region proposals

Fast R-CNN



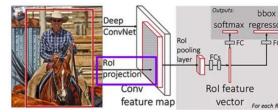
The Fast R-CNN architecture (source: Girshick et al., 2015)

Fast R-CNN



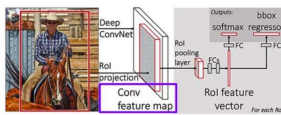
The Fast R-CNN architecture (source: Girshick et al., 2015).

Fast R-CNN



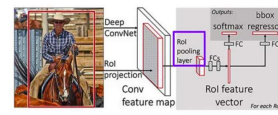
The Fast R-CNN architecture (source: Girshick et al., 2015).

Fast R-CNN



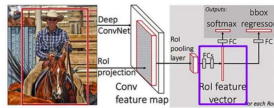
The Fast R-CNN architecture (source: Girshick et al., 2015).

Fast R-CNN



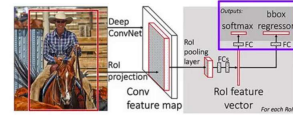
The Fast R-CNN architecture (source: Girshick et al., 2015).

Fast R-CNN



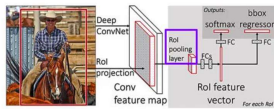
The Fast R-CNN architecture (source: Girshick et al., 2015)

Fast R-CNN



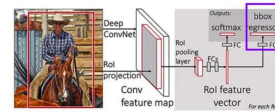
The Fast R-CNN architecture (source: Girshick et al., 2015)

Fast R-CNN



The Fast R-CNN architecture (source: Girshick et al., 2015)

Fast R-CNN



The Fast R-CNN architecture (source: Girshick et al., 2015)

<https://arxiv.org/pdf/1504.08083.pdf>

Fast R-CNN

Ross Girshick
Microsoft Research
rg@microsoft.com

Abstract

This paper proposes a Fast Region-based Convolutional Network method (Fast R-CNN) for object detection. Fast R-CNN builds on previous work to efficiently classify object proposals using deep convolutional networks. Compared to previous work, Fast R-CNN employs several innovations to improve training and testing speed while also increasing detection accuracy. Fast R-CNN makes the very deep VGG16 network 3x faster than R-CNN, is 2.1x faster at test-time, and achieves a higher mAP on PASCAL VOC

while achieving top accuracy on PASCAL VOC 2012 [7] with a mAP of 66% (vs. 62% for R-CNN).¹

1.1. R-CNN and SIFTnet

The Region-based Convolutional Network method (R-CNN) [9] achieves excellent object detection accuracy by using a deep ConvNet to classify object proposals. R-CNN, however, has notable drawbacks:

1. **Training is a multi-stage pipeline.** R-CNN first fine-tunes a ConvNet on object proposals using log loss.

