Image Enhancement
Frequency Domain

September 26, 2015

Guillaume Lemaitre

Université de Bourgogne

Fundamentals

Fourier Series

- A **periodic** function which is represented by the sum of sin and cos of different frequencies and multiplied by a different coefficient

Fourier Transform

- A **non-periodic** function which is represented by the integral of sin and cos, by weighing function

Introduction to Fourier Transform

Fourier transform of continuous function $f(x)$

- $f(x)$, continuous function of real variable x

$$\Im\{f(x)\} = F(u) = \int_{-\infty}^{\infty} f(x) exp[-2j\pi ux]dx$$

where $j = \sqrt{-1}$ and u is the frequency variable

- Integral shows $F(u)$ composed of infinite sum of sine and cosine
- Each u value determines the frequency of its corresponding sin and cos pair

Introduction to Fourier Transform

Inverse Fourier transform of $F(u)$

- Having $F(u)$, $f(x)$ can be obtained by the inverse Fourier transform

$$\Im^{-1}\{f(u)\} = f(x) = \int_{-\infty}^{\infty} F(u) exp[2j\pi ux] du$$

- The above equations represent the Fourier transform pair

Introduction to Fourier Transform

Fourier transform pair for $f(x, y)$ of two variables

$$\Im\{f(x,y)\} = F(u,v) = \int \int_{-\infty}^{\infty} f(x,y) exp[-2j\pi(ux+vy)]dxdy$$

$$\Im^{-1}\{F(u,v)\} = f(x,y) = \int \int_{-\infty}^{\infty} F(u,v) exp[-2j\pi(ux+vy)]dudv$$

u and v are the frequency domain

Introduction to Fourier Transform
Discrete Fourier Transform (DFT), discrete signal

Fourier transform pair - 1D

$$F(u) = \frac{1}{M} \sum_{x=0}^{M-1} f(x) exp[-2\pi ux/M]$$

for $u = 0, 1, 2, ..., M-1$

$$f(x) = \sum_{u=0}^{M-1} f(u) exp[2\pi ux/M]$$

for $x = 0, 1, 2, ..., M-1$

Introduction to Fourier Transform
Discrete Fourier Transform (DFT)

Fourier transform pair - 2D

$$F(u, v) = \frac{1}{MN} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) exp[-2\pi(ux/M + uy/N)]$$

for $u = 0, 1, 2, ..., M - 1,$ and $v = 0, 1, 2, ..., N - 1$

$$f(x, y) = \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} f(u, v) exp[2\pi(ux/M + uv/N)]$$

for $x = 0, 1, 2, ..., M - 1$ and $y = 0, 1, 2, ..., N - 1$

Introduction to Fourier Transform
Discrete Fourier Transform (DFT)

- The Fourier transform of a real function is generally complex and we use polar coordinates:

1D - DFT

$$F(u) = R(u) + jI(u)$$

$$F(u) = |F(u)|e^{j\phi(u)}$$

Magnitude spectrum:

$$|F(u)| = [R^2(u) + I^2(u)]^{0.5}$$

Phase spectrum:

$$\phi(u) = \tan^{-1}\left[\frac{I(u)}{R(u)}\right]$$

2D - DFT

$$F(u,v) = R(u,v) + jI(u,v)$$

$$F(u,v) = |F(u,v)|e^{j\phi(u,v}$$

Magnitude spectrum:

$$|F(u)| = [R^2(u,v) + I^2(u,v)]^{0.5}$$

Phase spectrum:

$$\phi(u,v) = \tan^{-1}\left[\frac{I(u,v)}{R(u,v)}\right]$$

Introduction to Fourier Transform
Discrete Fourier Transform (DFT)

2D- DFT - Basic properties

- Power spectrum:

$$P(u,v) = |F(u,v)^2|$$

- Average gray level of the image:

$$F(0,0) = \frac{1}{MN}\sum_{x=0}^{M-1}\sum_{y=0}^{N-1} f(x,y)$$

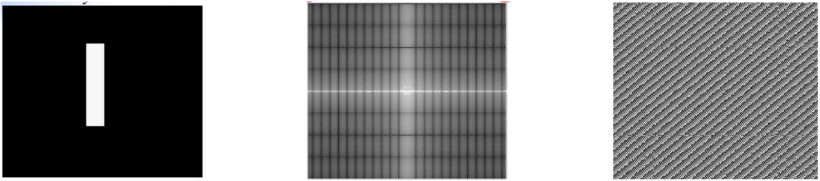
- Symmetric spectrum:

$$F(u,v) = F*(-u,-v)$$

$$|F(u,v)| = |F(-u,-v)|$$

Introduction to Fourier Transform
Discrete Fourier Transform (DFT)

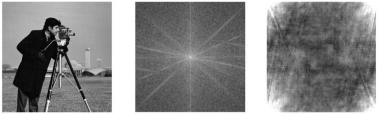
Phase and Magnitude Spectrum



Original magnitude phase

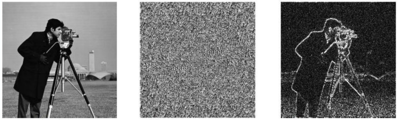
Introduction to Fourier Transform
Discrete Fourier Transform (DFT)

- Magnitude spectrum tells the amplitude of the sinusoids that forms the image
- For any given frequency, large amplitude indicates high influence of that frequency, while the low amplitude indicate the opposite
- Phase indicate the displacement of the sinusoids with respect to their origin
- Effect of magnitude, phase = 0



Original Image Magnitude response Reconstruction

- Effect of phase, magnitude = constant (80)



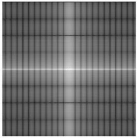
Original Image Phase response Reconstruction

Introduction to Fourier Transform
DFT properties

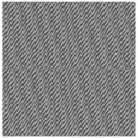
Effect of Translation in Spatial Domain

$$f(x - x0, y - y_0) \Leftrightarrow F(u, v)e^{-j2\pi(\frac{x_0 u}{M} + \frac{y_0 v}{N})}$$

Translated bar



Magnitude spectrum



Phase spectrum

- A shift in spatial domain, does not affect the magnitude in frequency domain

Introduction to Fourier Transform
DFT Properties

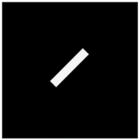
Effect of rotation in Spatial Domain

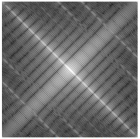
Considering the polar form i.e.

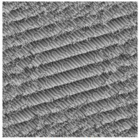
$$f(x, y) \Leftrightarrow f(r, \theta)$$

$$F(u, v) \Leftrightarrow F(w, \varphi)$$

$$f(r, \theta + \theta_0) \Leftrightarrow F(w, \varphi + \theta)$$


Rotated bar


Magnitude spectrum


Phase spectrum

- Rotating $f(x, y)$ by θ rotates $F(u, v)$ by the same angle and vice versa.

Introduction to Fourier Transform
DFT Properties

Distributing and Scaling

- Distributive over addition but not over multiplication

$$\Im\{f_1(x,y) + f_2(x,y)\} = \Im\{f_1(x,y)\} + \Im\{f_2(x,y)\}$$

$$\Im\{f_1(x,y).f_2(x,y)\} \neq \Im\{f_1(x,y)\}.\Im\{f_2(x,y)\}$$

- For two scalars a and b

$$af(x,y) \Leftrightarrow aF(u,v)$$

$$f(ax,by) \Leftrightarrow \frac{1}{|ab|}F(u/a, v/b)$$

Introduction to Fourier Transform
DFT Properties

Periodicity and Conjugate Symmetry

- The DFT and its inverse are periodic with period N

$$F(u, v) = F(u + M, v) = F(u, v + N) = F(u + M, v + N)$$

- Conjugate symmetry

$$F(u, v) = F * (-u, -v)$$

$$|F(u, v)| = |F(-u, -v)|$$

Separability

- DFT pair can be expressed in separable forms:

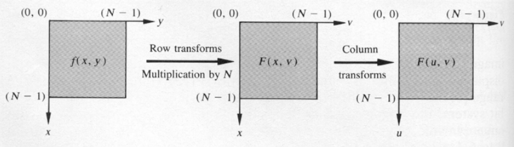
$$F(u, v) = \frac{1}{M} \sum_{x=0}^{M-1} F(x, v) exp[-j2\pi ux/M]$$

$$F(x, v) = \left[\frac{1}{N} \sum_{y=0}^{N-1} f(x, y) exp[-2\pi vy/N] \right]$$

Introduction to Fourier Transform
DFT Properties

Separability

- For each value of x, the expression inside the brackets is a 1-D transform
- 2-D $F(x, v)$ is obtained by taking a transform along each row of $f(x, y)$ and multiplying the result by N
- $F(u, v)$ is obtained by making a transform along each column of $F(x, v)$



Introduction to Fourier Transform
DFT Properties

Convolution

- Convolution theorem with FT pair:

$$f(x)^*g(x) \Leftrightarrow F(u)G(u)$$

$$f(x)g(x) \Leftrightarrow F(u)^*G(u)$$

- Discrete equivalent:

$$f_e(x)^*g_e(x) = \frac{1}{M}\sum_{m=0}^{M-1} f_e(m)g_e(x-m)$$

Introduction to Fourier Transform
DFT Properties

Correlation

- Convolution theorem with FT pair:

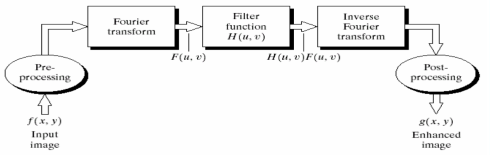
$$f(x,y) \circ g(x,y) \Leftrightarrow F^*(u,v)G(u,v)$$

$$f^*(x,y)g(x,y) \Leftrightarrow F(u,v) \circ G(u,v)$$

- Discrete equivalent:

$$f_e(x) \circ g_e(x) = \frac{1}{M}\sum_{m=0}^{M-1} f_e^*(m)g_e(x-m)$$

Image Enhancement
Basic Filtering in Frequency Domain



- Compute Fourier transform of image $F(u, v)$
- Multiply the result by a filter transfer function $H(u, v)$
- Take the inverse transform to produce the enhanced image

$$G(u, v) = H(u, v)F(u, v)$$

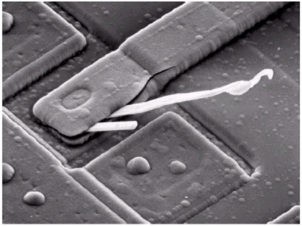
$$g(x, y) = \Im^{-1}[G(u, v)]$$

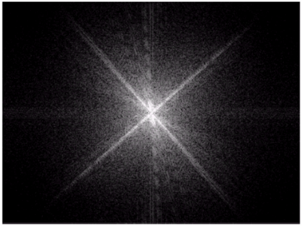
Attention!!

Because of periodicity when taking DFT we have to avoid wraparound error or aliasing

Image Enhancement

2D- DFT example





SEM image of a damaged integrated circuit Fourier spectrum

Image Enhancement
Zero-padding

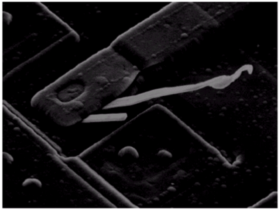
You need to add this section

Image Enhancement
Filtering

Notch Filter

- It forces the average of the image to be 0
- F(0,0) = 0 and then take the inverse

$$H(u,v) = \begin{cases} 0 & \text{if } (u,v) = M/2, N/2 \\ 1 & \text{otherwise} \end{cases}$$

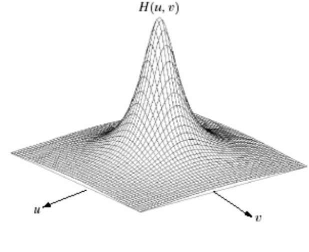


Notch filter

Image Enhancement
Filtering

Low-pass filter

- Reduces the high frequency contents (blurring or smoothing)



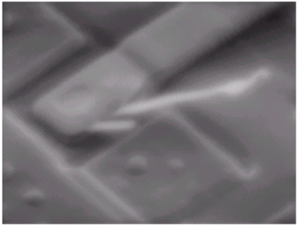
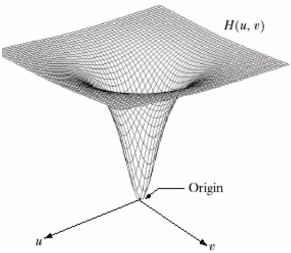


Image Enhancement
Filtering

High-pass filter

- Increase the magnitude of the high frequency components relative to low frequency components (sharpening)



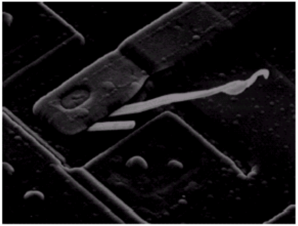


Image Enhancement
Low-pass filter (Smoothing)

- Edges, noise contribute significantly to the high-frequency content of the FT of an image
- Blurring/smoothing is achieved by reducing a specified range of high-frequency components

$$G(u, v) = H(u, v)F(u, v)$$

Different Types

- Ideal
- Butterworth
- Gaussian

Image Enhancement
Low-pass filter

Ideal Low-pass filter

$$H(u,v) = \begin{cases} 1 & \text{if } D(u,v) \leq D_0 \\ 0 & \text{if } D(u,v) > D_0 \end{cases}$$

D_0 is a specified non-negative quantity (Cutoff frequency)
D(u,v) is the distance from point (u, v) to the center of frequency rectangle
$F_c(u,v) = (M/2, N/2)$
$D(u,v) = (u^2 + v^2)^{1/2}$

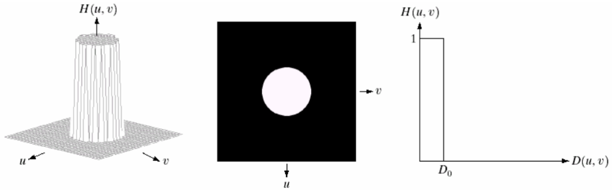


Image Enhancement
Low-pass filter

Ideal low-pass filter

Original image and results of ideal low-pass with cutoff frequencies {5,15,30,80,230}

Image Enhancement
Low-pass filter

Butterworth low-pass filter

$$H(u,v) = \frac{1}{1 + [D(u,v)/D_0]^{2n}}$$

- n is the order of the filter
- D_0 cutoff frequency locus (distance from the origin)
- $D(u,v) = (u^2 + v^2)^{1/2}$ filter characteristics

- Does not have a sharp discontinuity
- Does not establish a clear cutoff between passed and filtered frequencies
- When $D(u,v) = D_0$, $H(u,v) = 0.5$

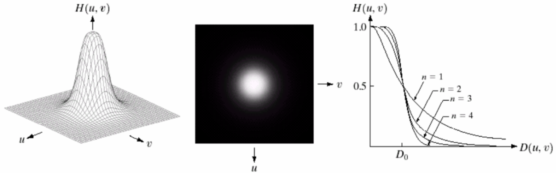


Image Enhancement
Low-pass filter

Butterworth low-pass filter

Original image and results of Butterworth low-pass with order 2 and cutoff frequencies {5,15,30,80,230}

Image Enhancement
Low-pass filter

Butterworth filter

Spatial representation of Butterworth low-pass with orders of {1,2,5,20}

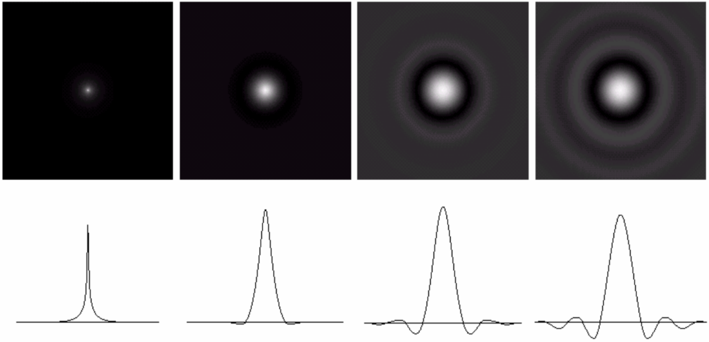


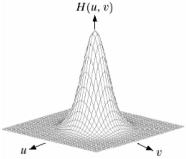
Image Enhancement
Low-pass filter

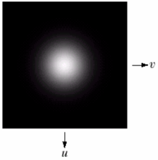
Gaussian low-pass filter

$$H(u, v) = e^{-D^2(u,v)/2\sigma^2}$$

- $\sigma = D_0$ cutoff frequency
- $D(u, v) = (u^2 + v^2)^{1/2}$ Distance from the FT center

- The inverse FT of Gaussian is also a Gaussian





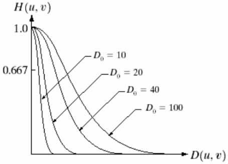


Image Enhancement
Low-pass filter

Gaussian low-pass filter

Original image and results of Gaussian low-pass with cutoff frequencies {5,15,30,80,230}

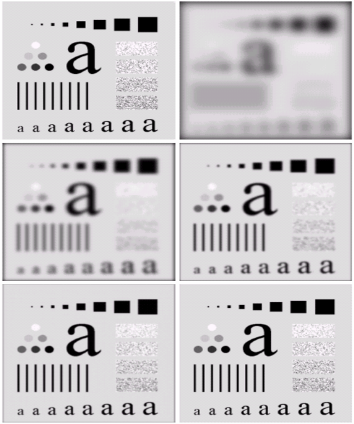


Image Enhancement
High-pass filter (Sharpening)

- Attenuating low-frequency components without disturbing high-frequency information.

$$H_{hp}(u, v) = 1 - H_{lp}(u, v)$$

Different Types

- Ideal
- Butterworth
- Gaussian

Image Enhancement
High-pass filter

Ideal High-pass filter

$$H(u,v) = \begin{cases} 0 & \text{if } D(u,v) \leq D_0 \\ 1 & \text{if } D(u,v) > D_0 \end{cases}$$

- Opposite of the ideal low-pass

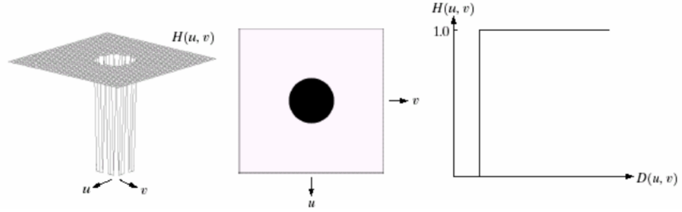


Image Enhancement
High-pass filter

Butterworth High-pass filter

$$H(u,v) = \frac{1}{1 + [D_0/D(u,v)]^{2n}}$$

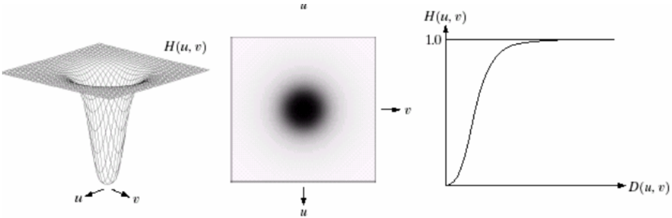


Image Enhancement
High-pass filter

Gaussian High-pass filter

$$H(u,v) = 1 - e^{-D^2(u,v)/2\sigma^2}$$

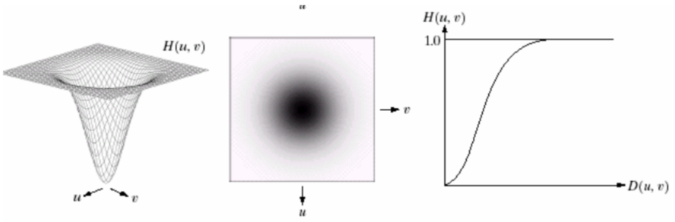


Image Enhancement
High-pass filter

example of Ideal, Butterworth and Gaussian High-pass

$D_0 = \{30, 60, 160\}$

Ideal High-pass

Butterworth High-pass, $n = 2$

Gaussian High-pass

Image Enhancement
High-pass filter

Recall

$$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2}$$

$$\nabla^2 f = [f(x+1,y) + f(x-1,y) + f(x,y+1) + f(x,y-1)] - 4f(x,y)$$

Laplacian in FD

$$\Im[\nabla^2 f(x,y)] = -(u^2+v^2)F(u,v)$$

$\rightarrow$ The Laplacian can be implemented in FD by using a filter

$$H(u,v) = -(u^2+v^2)$$

- FT pair:

$$\nabla^2 f(x,y) \Leftrightarrow [(u-M/2)^2(v-N/2)^2]F(u,v)$$