

# Segmentation

October 5, 2015

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① Introduction

② Region Based

③ Clustering Based



## Image Segmentation

- ▶ Image segmentation is the partition of the image into non-overlapping regions, where their union is an entire image
- ▶ Purpose of segmentation: decompose an image into meaningful parts with respect to unique application
- ▶ Segmentation is based on the information taken from the image such as greylevel, texture, color and depth or motion



## Image Segmentation

### Applications ...

- ▶ Identifying objects in a scene for object-based measurements/recognition
- ▶ Identifying objects in a moving scene for object based video compression
- ▶ Identifying objects at different depths
- ▶ Its a necessary and fundamental step in a general frameworks of detection, tracking or classification



## Image Segmentation

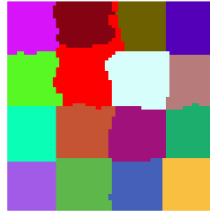
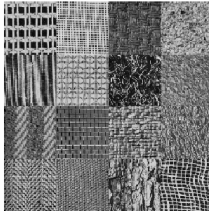
### Techniques

- ▶ Region-based
  - ▶ Region growing
  - ▶ Split and merge
- ▶ Edge-based
  - ▶ Contours/ boundary surface
  - ▶ Deformable wrapping
  - ▶ Deformable registration to atlases
- ▶ Clustering-based
  - ▶ Threshold
  - ▶ K-means
  - ▶ Hierarchical clustering, Graph cuts
- ▶ Texture-based

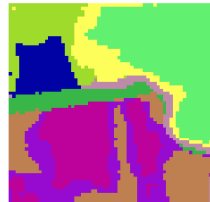


## Image Segmentation

**Texture  
Test Image**



**Aerial Image**





## Region Based Segmentation

### Region Growing

- ▶ Starting with some pixels (seeds) representing distinct image regions
- ▶ Grow the region of each seed, using connected pixels until they cover the entire image
- ▶ Two rules: growth mechanism and region homogeneity after each growth step
- ▶ Growth mechanism: for each stage  $k$  and each region  $R_i(k)$ ,  $i = 1, \dots, N$ , check if there are unclassified pixels in 8 neighborhood of each pixel in the region
- ▶ Region homogeneity: Pixel  $P_{x,y}$  can join  $R_i(k)$  if  $|f(x,y) - \mu_{R_i(k)}| \leq \Delta$



## Region Based Segmentation

### Region Growing

- ▶ Merging two region:
- ▶ Mean ( $\mu$ ) and standard deviation ( $\sigma$ ) of each region ( $R_i$ ) can be used to decide if two region can merge:

$$\mu_{R_i} = \frac{1}{n} \sum_{(r,c) \in R_i} I(r, c)$$

$$\sigma_{R_i} = \sqrt{\frac{1}{n} \sum_{(r,c) \in R_i} [I(r, c) - \mu_{R_i}]^2}$$

if  $|M_{R_1} - M_{R_2}| < k\sigma_{R_i}$  for  $i = 1, 2$  two region are merged





## Image Segmentation Region Based Methods

### Region Growing - Kind of unseeded RG

Using one seed only, the first pixel:

```

for All the pixels  $n$  the image do
  if  $P_{x,y} \notin R_{1,2,\dots,n}$  then
     $P_{x,y} \in R_{n+1}$ 
    for  $S$ : The 4 or 8 neighbors of  $x, y$  do
      if  $P_{x',y'} \notin R_{1,2,\dots,n}$  then
        if  $|f(x',y') - \mu_{R_i}| \leq \Delta$  then
           $P_{x',y'} \in R_{n+1}$ 
          Search the neighbors of  $x', y'$ 
        else
           $P_{x',y'} \in R_{n+2}$ 
          Search the 4 or 8 neighbors of  $x', y'$ 
        end if
      end if
    end for
  end if
end for

```

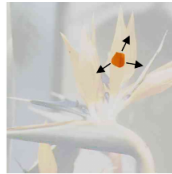


## Region Based Segmentation

### Region Growing



seed



growing



final region

Fabrice example



## Region Based Segmentation

### Split Method

- ▶ Opposite of previous method
- ▶ Top to down approach
- ▶ Starts with the assumption that the whole image is a homogeneous region
- ▶ If this is not true, subdivides the image to smaller homogeneous regions
- ▶ If original Image  $I_{N \times N} = I_{2^n \times 2^n} \rightarrow$  square produced regions  
 $R_{M \times M}^i = R_{2^m \times 2^m}^i$
- ▶ Recursive procedure  $\Rightarrow$  Image representation can be modeled by a tree whose nodes have four sons each
- ▶ **Quadtree**
- ▶ Created regions might be adjacent and homogeneous but are not merged



# Region Based Segmentation

## Split Method

Criterion of Homogeneity: Variance

|   |   |   |   |   |   |   |   |
|---|---|---|---|---|---|---|---|
| 0 | 1 | 0 | 0 | 7 | 7 | 7 | 7 |
| 1 | 0 | 2 | 2 | 7 | 7 | 7 | 7 |
| 0 | 2 | 2 | 2 | 7 | 7 | 7 | 7 |
| 4 | 4 | 2 | 2 | 7 | 7 | 7 | 7 |
| 0 | 0 | 1 | 1 | 3 | 3 | 7 | 7 |
| 1 | 1 | 2 | 2 | 3 | 7 | 7 | 7 |
| 2 | 4 | 3 | 0 | 5 | 7 | 7 | 7 |
| 2 | 3 | 3 | 5 | 5 | 0 | 7 | 7 |

original image

|   |   |   |   |   |   |   |   |
|---|---|---|---|---|---|---|---|
| 0 | 1 | 0 | 0 | 7 | 7 | 7 | 7 |
| 1 | 0 | 2 | 2 | 7 | 7 | 7 | 7 |
| 0 | 2 | 2 | 2 | 7 | 7 | 7 | 7 |
| 4 | 4 | 2 | 2 | 7 | 7 | 7 | 7 |
| 0 | 0 | 1 | 1 | 3 | 3 | 7 | 7 |
| 1 | 1 | 2 | 2 | 3 | 7 | 7 | 7 |
| 2 | 4 | 3 | 0 | 5 | 7 | 7 | 7 |
| 2 | 3 | 3 | 5 | 5 | 0 | 7 | 7 |

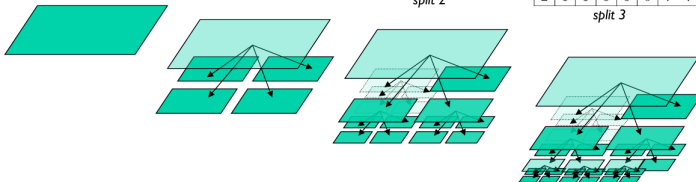
split 1

|   |   |   |   |   |   |   |   |
|---|---|---|---|---|---|---|---|
| 0 | 1 | 0 | 0 | 7 | 7 | 7 | 7 |
| 1 | 0 | 2 | 2 | 7 | 7 | 7 | 7 |
| 0 | 2 | 2 | 2 | 7 | 7 | 7 | 7 |
| 4 | 4 | 2 | 2 | 7 | 7 | 7 | 7 |
| 0 | 0 | 1 | 1 | 3 | 3 | 7 | 7 |
| 1 | 1 | 2 | 2 | 3 | 7 | 7 | 7 |
| 2 | 4 | 3 | 0 | 5 | 7 | 7 | 7 |
| 2 | 3 | 3 | 5 | 5 | 0 | 7 | 7 |

split 2

|   |   |   |   |   |   |   |   |
|---|---|---|---|---|---|---|---|
| 0 | 1 | 0 | 0 | 7 | 7 | 7 | 7 |
| 1 | 0 | 2 | 2 | 7 | 7 | 7 | 7 |
| 0 | 2 | 2 | 2 | 7 | 7 | 7 | 7 |
| 4 | 4 | 2 | 2 | 7 | 7 | 7 | 7 |
| 0 | 0 | 1 | 1 | 3 | 3 | 7 | 7 |
| 1 | 1 | 2 | 2 | 3 | 7 | 7 | 7 |
| 2 | 4 | 3 | 0 | 5 | 7 | 7 | 7 |
| 2 | 3 | 3 | 5 | 5 | 0 | 7 | 7 |

split 3





## Region Based Segmentation

### Split and Merge Method

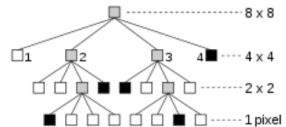
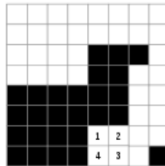
- ▶ Iterative technique that included both splitting and merging at each iteration
- ▶ If  $R_i$  is inhomogeneous, split  $R_i$  into four sub-regions
- ▶ If two adjacent region  $R_i$  and  $R_j$  are homogeneous, merge them
- ▶ The algorithm stops when no more merge or split is possible
- ▶ Produce more compact regions than just splitting



## Region Based Segmentation

### Split and Merge Method - Data Structure

- ▶ Quadtree for splitting  
Top-down approach,  
regions are split but not merged
- ▶ RAG(region adjacency graph)  
Split and merge iteratively  
at each iteration of  
quadtree partitioning  
RAG has quadtree  
embedded that represent 4  
relations  
4 adjacent relations(one  
per square side)

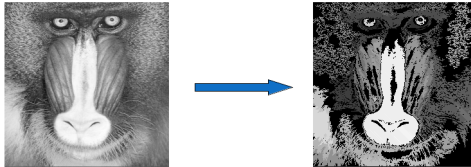


RAG with adjacency relations (in red) for big black region.

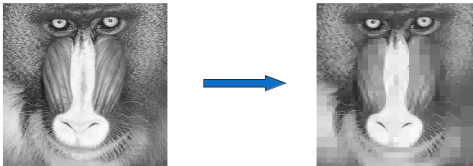


## Region Based Segmentation

### Region Growing



### Split and Merge





## Region Based Segmentation

### Splitting



### Split and Merge







## Clustering

### Image Clustering vs. Image Segmentation

- ▶ In clustering the grouping is done in measurement space
- ▶ In segmentation the grouping is done in spatial domain

### Approaches

- ▶ Threshold
- ▶ K-means
- ▶ Hierarchical clustering, Graph cut, ...



## Clustering

- ▶ Grouping of pixels considering 1 or more features
- ▶ Grouping similar features, feature selection
- ▶ Spatial distribution of the pixels is not considered
- ▶ Feature space is considered
- ▶ Clusters has compact shape, spherical, ellipsoidal, elongated, ..
- ▶ A pixel belongs to a cluster based on a proximity measure (distance)
- ▶ Result may be subjective
- ▶ **Question**, how to choose the number of clusters in the image ?
- ▶ How many times  $N$  points can be assigned to  $N$  clusters ?

$$S(N, m) = \frac{1}{m!} \sum_{i=0}^m (-1)^{m-i} \binom{m}{i} i^N$$

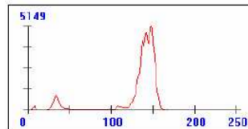
$$S(15, 3) = 2,375,101, \quad S(100, 5) = 10^{68} !!$$



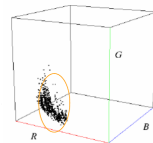
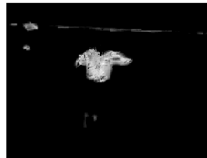
## Clustering Techniques

### Thresholding

- Clustering in 1D → histogram analysis → thresholding



- Clustering in 2D, color image → color thresholding





# Clustering Techniques

## Thresholding

- Fixed or Global threshold: Threshold value is fixed through the image



- Local or Adaptive threshold: Two or more threshold is used through the image
- Local or Adaptive threshold: Local threshold for small patches, Patch size  $(7 \times 7)$ ,  $P_{T_1} = \mu$ ,  $P_{T_2} = \mu - 7$ ,  $P_{T_3} = \mu - 10$





## Clustering Techniques

### Optimal Thresholding

- ▶ Isodata, Peak and valley, Otsu, p-tile,...
- ▶ **ISODATA** (Iterative Self-Organising Data Analysis Technique Algorithm):
  - ▶  $T_i = T_0$ , median, maximum gray level, ...
  - ▶ Segmenting the histogram into two parts
  - ▶ Computing the mean value associated to each part ( $\mu_1, \mu_2$ )
  - ▶ New threshold,  $T_{i+1} = (\mu_1 + \mu_2)/2$
  - ▶ Repeat until convergence,  $T_i = T_{i-1}$