

| Digital Sidecar 1 | | | | Digital Sidecar 2 | | | |
|----------------------|---------------------|------------------|---|-------------------|---------------------|--------------|-------------------|
| Connection Type | What is Plugged in? | Motor Type | What does it do? | Connection Type | What is Plugged in? | Motor Type | What does it do? |
| PWM | | | | | | | |
| 1 | Victor x2 | CIM | Left Drive / PTO | 1 | Victor | Window/AM PG | Shooter Elevation |
| 2 | Victor x2 | CIM | Right Drive / PTO | 2 | Victor | | Shooter Indexer |
| 3 | Servo | Servo | Left Drive Shifter | 3 | Victor | Fisher Price | Left Drive |
| 4 | Servo | Servo | Right Drive Shifter | 4 | Victor | Fisher Price | Right Drive |
| 5 | Servo | Servo | PTO Shifter | 5 | | | |
| 6 | Servo | | Flipper | 6 | | | |
| 7 | Victor | CIM | Shooter Wheel F | 7 | | | |
| 8 | Victor | CIM | Shooter Wheel B | 8 | | | |
| 9 | Victor x2 | AM 775 w/ Dewalt | Climber Deploy | 9 | | | |
| 10 | Victor | Banebot | Harvester Roller | 10 | | | |
| Digital I/O | | | | | | | |
| 1 | Encoder | | Left Drive | 1 | Limit Switch | | Climber 1 |
| 2 | Encoder | | Left Drive | 2 | Limit Switch | | Climber 2 |
| 3 | Encoder | | Right Drive | 3 | | | |
| 4 | Encoder | | Right Drive | 4 | | | |
| 5 | Encoder | | Left Drive Shaft | 5 | | | |
| 6 | Encoder | | Left Drive Shaft | 6 | | | |
| 7 | Encoder | | Right Drive Shaft | 7 | | | |
| 8 | Encoder | | Right Drive Shaft | 8 | | | |
| 9 | Encoder | | Shooter Wheel F | 9 | | | |
| 10 | Encoder | | Shooter Wheel F | 10 | | | |
| 11 | Encoder | | Shooter Wheel B | 11 | | | |
| 12 | Encoder | | Shooter Wheel B | 12 | | | |
| 13 | Photo-Electric | | Harvester | 13 | | | |
| 14 | Photo-Electric | | Flipper | 14 | | | |
| Relay | | | | | | | |
| 1 | Relay | Light | Ring Light | 1 | | | |
| 2 | Relay | Light | Disc entered harvester, Climber in contact with Pyramid | 2 | | | |
| 3 | | | | 3 | | | |
| 4 | | | | 4 | | | |
| 5 | | | | 5 | | | |
| 6 | | | | 6 | | | |
| 7 | | | | 7 | | | |
| 8 | | | | 8 | | | |
| Analog Inputs | | | | | | | |
| 1 | Gyro | | Robot Rotation | | | | |
| 2 | Pot | 5 Turn | Harvester/Shooter Position | | | | |
| 3 | Pot | 10 Turn | Climber Extension | | | | |
| 4 | Pot | 5 Turn | Climber Deploy | | | | |
| 5 | | | | | | | |
| 6 | Current | | Motor 1 Current | | | | |
| 7 | Current | | Motor 2 Current | | | | |
| 8 | Battery Voltage | | | | | | |
| I2C | | | | | | | |
| Left | | | | | | | |
| Right | | | | | | | |
| Router | | | | | | | |
| 1 | cRio | | | | | | |
| 2 | Camera 1 | 10.0.27.11 | | | | | |
| 3 | Camera 2 | 10.0.27.12 | | | | | |
| 4 | Tether Port | | | | | | |
| | | | | | | | |