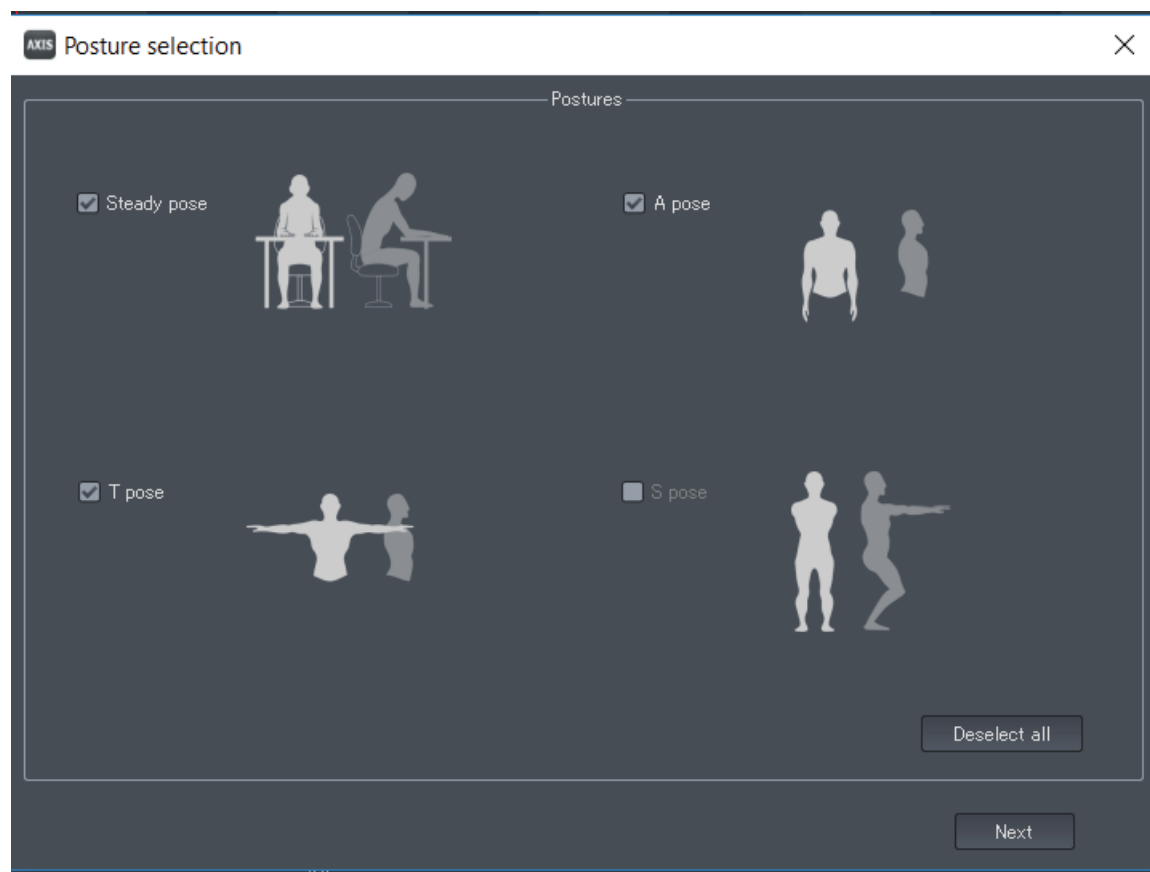(1) Check sensors connectivity

(2) Apply calibration postures

(3) Confirm tracking precision