

Assignment 1

☰ Tags	
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⚙️ Status	Not started

Task Goal

Divide a given map into 4 equal chambers. If the map can't be equally divided into 4 chambers, divide it into the largest possible equal number of chambers (e.g., 3, 2, or 1).

Constraints

- Use beepers to divide the map
- You can use double line of beepers if you need
- Use API to setup beepers to 1,000
- Use only function given in Karel reference

Measurements

- Use less beepers
- Lowest number of moves
- Minimize number of lines by writing reusable functions

Functions

- Moves Counter

Instruction

- Print moves count in each step (optional print used beepers)
 - We can override move function to do this job
 - we need variable to count number of steps and number of beepers

Workflow Steps

1. Get Map dimensions (width and height)
 - a. if the map is square just get one of them
 - i. go to the most right or most top
 - b. if the map is not square we need to get both

We'll assume that the map is rectangle (General Case)
Karel always start from bottom left and his face to right so
we'll assume this point as (0,0)

2. Decide to how many champers and how many line of beepers
3. Start divide

Map Cases

1×1 → 1 → can't divided

1×2 → 2 → can't divided

1×3 → 3 → divide into 2

1×4 → 4 → divide into 2 using two beepers

1×5 → 5 → divide into 3

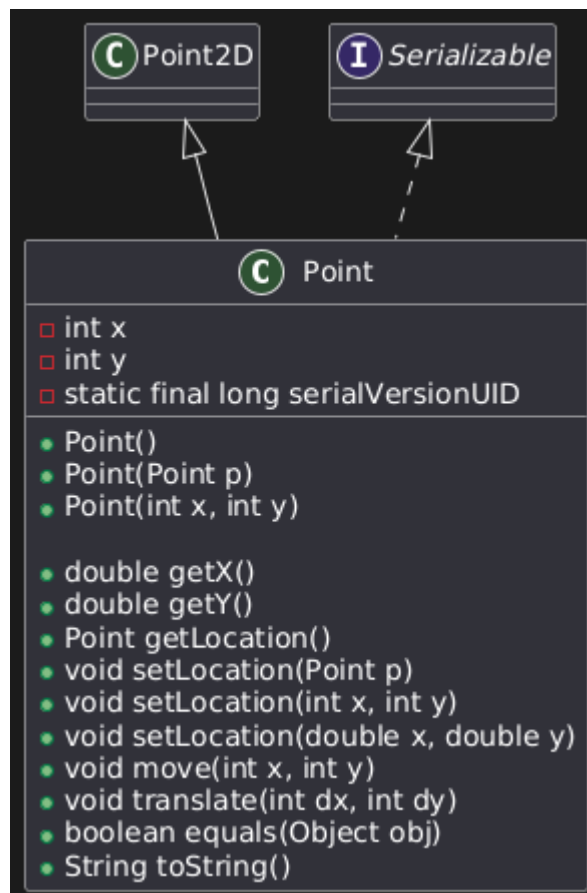
2×2 → 4 → can't divided

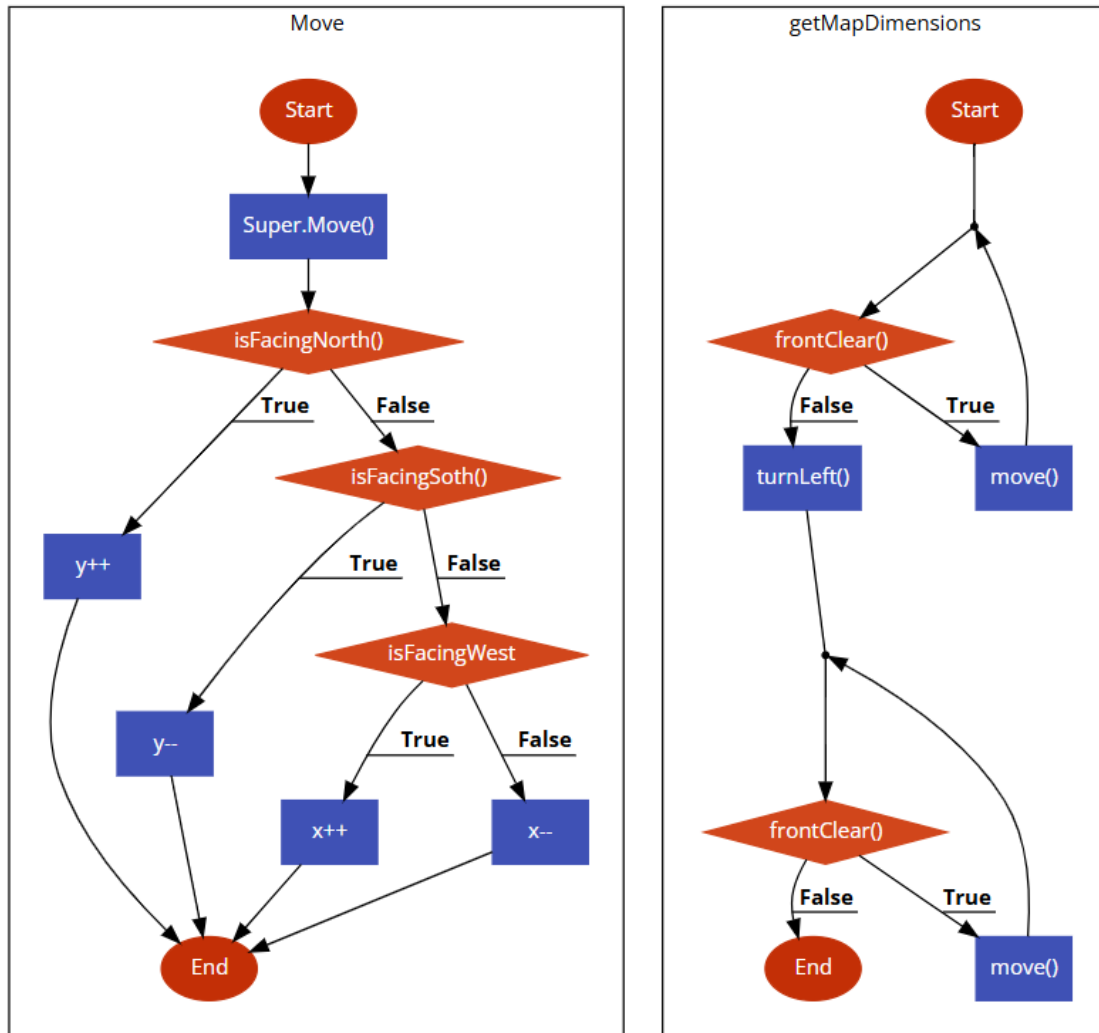
2×3 → 6 → into 2

r → rows

c → columns

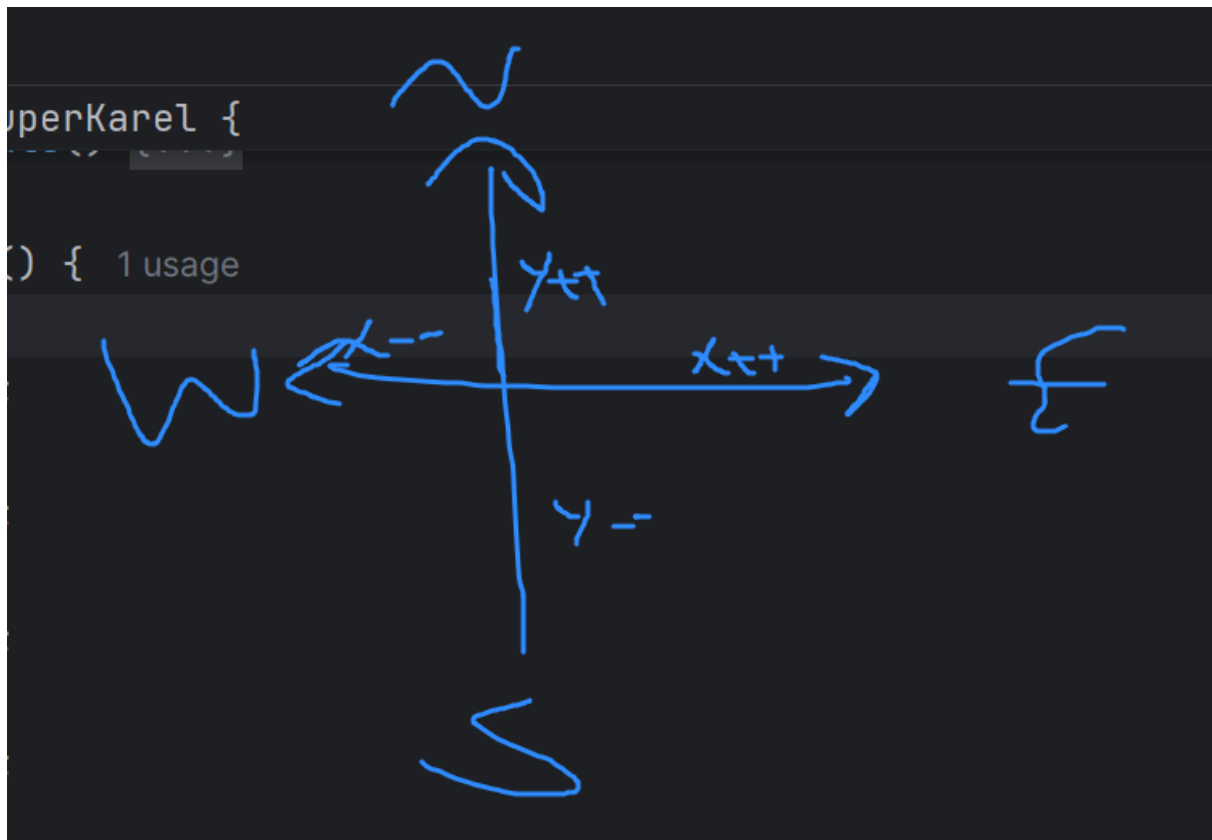
Point Class





Double line of beepers → when the width or height is even

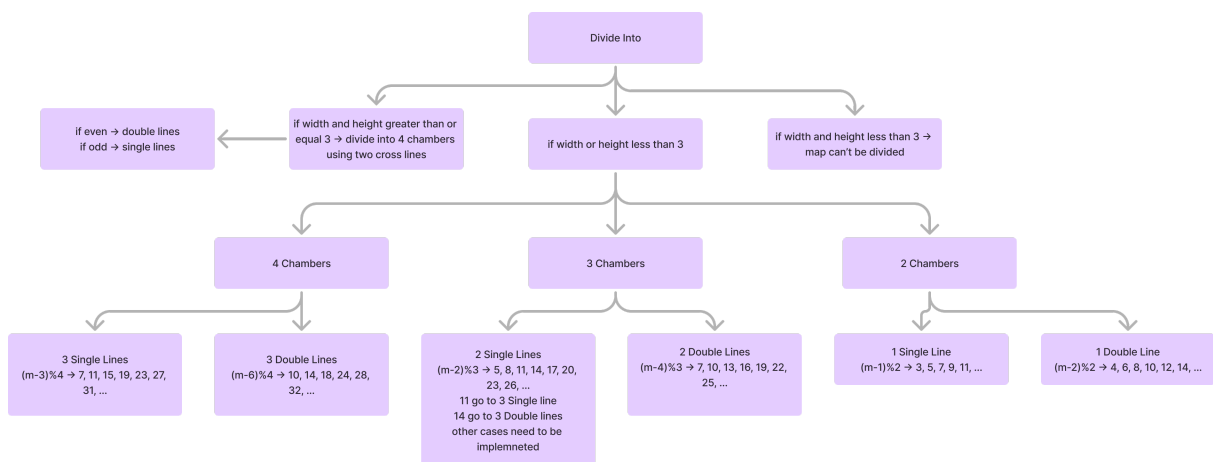
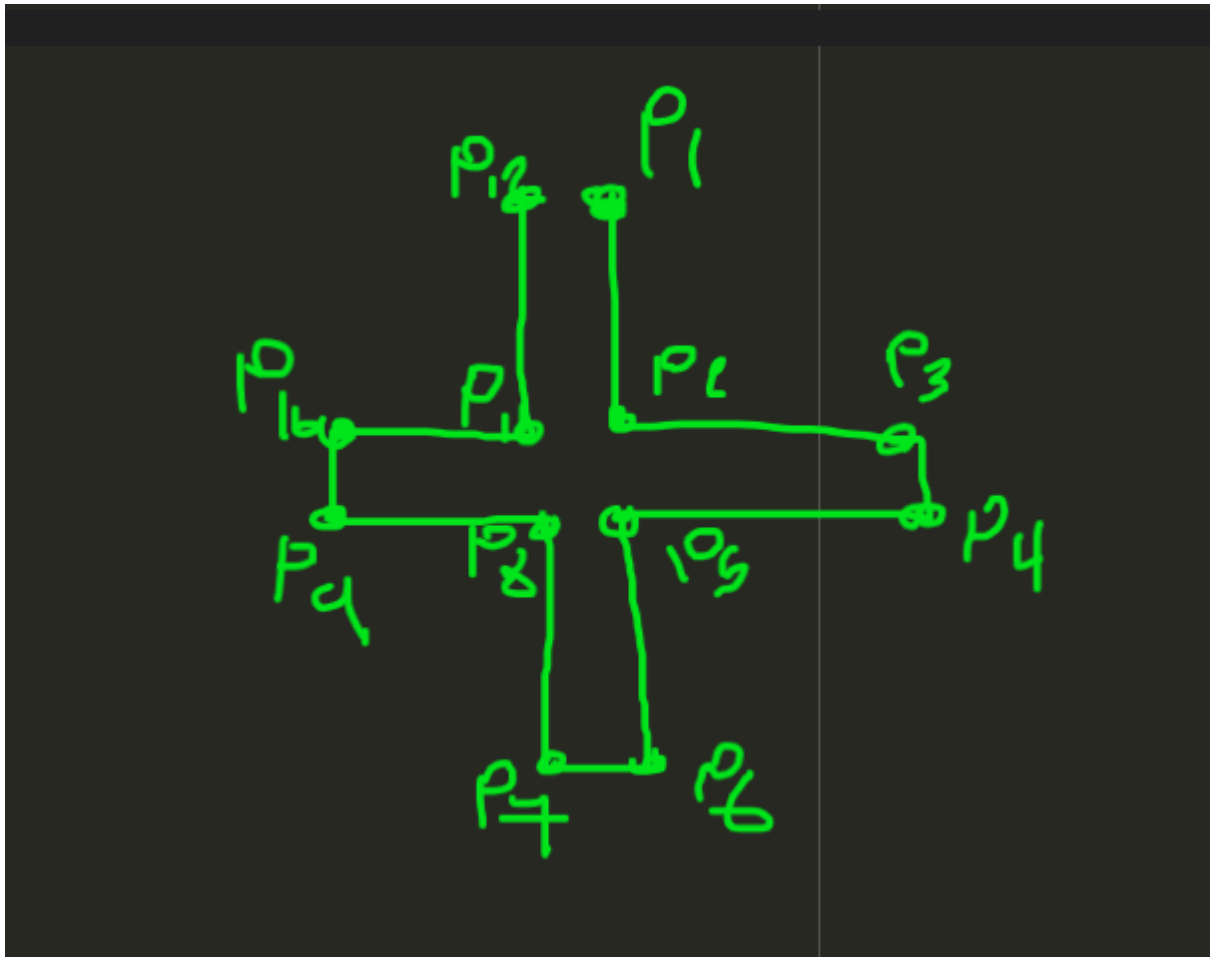
Update Location



```
function updateLocation(){
    Start;
    if (facingNorth())
        currentLocation.y++;
    else if(facingSouth())
        currentLocation.y--;
    else if (facingEast)
        currentLocation.x++;
    else
        currentLocation.x--;
    End;
}
```

```
function move(){
    Start;
    Super.Move();
    call updateLocation();
}
```

```
    End;  
}  
  
function getMapDimensions(){  
    Start;  
    while(frontClear()){  
        call move();  
    }  
    turnLeft();  
    while(frontClear()){  
        call move();  
    }  
    End;  
}  
  
function run(){  
    Start;  
    call getMapDimensions();  
    End;  
}
```



Class Diagram

