Races versus tournaments – the model

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Current version: November 9, 2016

Abstract

We want compare races and tournaments in one single common framework. Here, we are going to build a new framework then estimate the *primitives* of the model, and simulate data to show under what conditions one mechanism dominates the other.

1 The model

- » Consider n+1 agents competing in a contest over k prizes of value $V_1 > V_2 > ... > V_k$.
- » To be eligible for the j'th prize, an agent has to complete a task within a deadline d and produce an output that is ranked j'th in the competition. The output is evaluated and ranked by the sponsor of the contest along two dimensions.
- » Let $y_i \in \mathbb{R}^+$ denote the first dimension indicative of an agent *i*'s output quality. And let $t_i \in \mathbb{R}^+$ denote the second that is indicative of the time to complete the task.
- » In a tournament, agents who completed the task in time $t_i \leq d$ are then ranked by their output quality. Let $y_{r:n+1}$ denote the r'th smallest value of the y_i 's $(y_{1:n+1}$ being the smallest, $y_{2:n+1}$ being the second smallest, and so on). Then the agent having achieved the highest quality $y_{n+1:n+1}$ is ranked first and gets the first prize, the agent having achieved the second highest quality $y_{n:n+1}$ is awarded the second prize, and so on.
- » In a race, agents are required to meet a minimum quality which we denote q. Agents who complete the task in time and meet this requirement are then ranked by their time to complete the task. As before, let $t_{r:n+1}$ denote the r'th smallest time to achieve the minimum quality requirement of the t_i 's. Then the agent being the first to achieve the required quality $t_{1:n+1}$ is ranked first and gets the first prize, the agent being the second $t_{2:n+1}$ is awarded the second prize, and so on.
- » FOOTNOTE: Since time and quality are continuous variables we do not need to consider what happens when there are ties.

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- » FOOTNOTE The case in which agents are ranked by a (linear) combination of time and quality can been studied as the traditional one-dimensional case.
- » Output requires effort and each agent incurs a cost from effort that is increasing in the output's quality and decreasing in the output's timing (achieving output of higher quality requires time and time is costly). This cost is represented by the multiplicative cost function (e.g., Cobb-Douglas)

$$C(y,t) = \gamma(y)\delta(t) \tag{1}$$

with $\gamma(0) = 0$, $\gamma' > 0$, $\delta(d) = \delta_0 > 0$, and $\delta' < 0$.

- » The individual ability of a player $x_i \in \mathbb{R}^+$, which we will also call her "type," will shift these costs down (or up) by a factor $1/x_i$.
- » Ability is privately observed by the agent before making any decision. And it is common knowledge that types are iid with common distribution F_X on the support $[\underline{c}, \overline{c}]$ with $\underline{c} > 0$ and F_X everywhere differentiable.
- » Each agent face the same problem

maximize
$$\sum_{j=1}^{k} \Pr(\text{ranked } j'\text{th})V_j - C(y_i, t_i)/x_i.$$
 (2)

» The sponsor of the contest chooses the rules of the competition including prize structure $\{V_j\}_{j=1}^k$, deadline d, target quality q, and competition format (race or tournament). The sponsor maximizes an objective function that is the sum of total quality $Y = \sum_{i=1}^{n+1} Y_i$, time spent $T = \sum_{i=1}^{n+1} T_i$ and prizes paid $V = \sum_{j=1}^k p_j V_j$ (with $p_j = 1$ if the prize is awarded and $p_j = 0$ otherwise). Hence, the problem faced by the sponsor is

maximize
$$\mathbf{E} Y - c_t \mathbf{E} T - \mathbf{E} V$$
 (3)

with the intensity of preferences towards time weighted by $c_t \geq 0$.

1.1 Tournament

- » Let consider the case of 2 prizes for simplicity.
- » We characterize the equilibrium strategy of a player in a tournament which we denote by t^* and y^* .¹
- » It is readily verifiable that $t_i^* = d$ is a weakly dominant strategy for every x_i (any $t_i < d$ is strictly dominated by $t_i = d$ and any $t_i \ge d$ leads to zero utility).

¹The strategy is a mapping $b_i : [\underline{c}, \overline{c}] \to \mathbb{R}^+ \times \mathbb{R}^+$ that maps types to two real numbers for quality and time. We focus on symmetric equilibria. In a symmetric equilibrium, agents are using the same strategy and the strategy is an equilibrium (because information is imperfect we use the Bayesian Nash Equilibrium notion).

- » Since there is imperfect information each agent will view all y_j with $j \neq i$ as random variables. Let $F_{Y_{j:n}}$ denote the distribution of the jth smallest value of the (n less the agent) Y_j 's
- » The problem faced by each agent i is

maximize
$$\Pr(y > Y_{n:n})V_1 + \Pr(Y_{n:n} > y > Y_{n-1:n})(y)V_2 - C(y,t)/x$$
 (4)

Using the distribution we have:

maximize
$$F_{Y_{n:n}}(y)V_1 + [1 - F_{Y_{n:n}}(y)]F_{Y_{n-1:n-1}}(y)V_2 - C(y,t)/x$$
 (5)

$$\Pr(y \ge Y_{n:n})V_1 + \sum_{r=1}^{k-1} \Pr(Y_{n+1-r:n} > y \ge Y_{n-r:n})V_{r+1};$$

and it is zero otherwise. That can be written

$$[1 - F_{Y_{n:n}}]V_1 + \sum_{r=1}^{k-1} [1 - F_{Y_{1:n+1-r}}]F_{Y_{n-r:n}}V_{r+1}.$$

- » Suppose that $t_i = T$. Suppose further that the performance of other players is a monotone decreasing function of their type. So we have $Y_j = b(X_j)$ and $b^{-1}(Y_j) = X_j$.
- » This implies that we can use a simple change of variable to rewrite the payoff as a function of F_X . And we have:

$$[1 - F_{X_{n:n}}(b^{-1}(y_i))]V_1 + \sum_{r=1}^{k-1} \Pr(Y_{n+1-r:n} > y_i \ge Y_{n-r:n})V_{r+1};$$

Using Bayesian rule and one of the properties of *iid* order statistics to express conditional probability, we have

$$[1 - F_{X_{n:n}}(b^{-1}(y_i))]V_1 + \sum_{r=1}^{k-1} (1 - F_{X_{1:n-r}})F_{X_{n-r:n}}V_r$$

2 In a tournament

- Consider an agent i.
- Let $Y_1, ..., Y_n$ denote the scores of i's opponents.
- It is readily verified that $t_i^* = d$ is a dominant strategy (any $t_i < d$ yields higher costs without affecting the probability of winning). [if we assumed that $t_i \leq d$]

• The agent faces the following problem

maximize
$$Pr(y_i > Y_{n:n})V - x_iC(y_i, d)$$

where $y_i \in R_+$ is the optimization variable.

• In a symmetric equilibrium, we have $Y_{n:n} = b(X_{n:n})$ with b^{-1} denoting the inverse of $b(\cdot)$. Hence, the problem can be written as

maximize
$$[1 - F_{X_{n:n}}(b^{-1}(y_i))]V - x_iC(y_i, d)$$

• The first order condition is

$$-F'_{X_{n:n}}(b^{-1}(y_i))]\frac{1}{b'(b^{-1}(y_i))}V = x_iC'(y_i, d).$$

At equilibrium, we have

$$-F'_{X_{n:n}}(x_i)\frac{1}{b'(x_i)}V = x_i C'(b(x_i), d)$$

by replacing $b^{-1}(y_i) = x_i$. By rearranging and integrating both sides, this leads to

$$-\int F'_{X_{n:n}}(x_i)\frac{V}{x_i}dx_i = \int b'(x_i)C'(b(x_i),d)dx_i$$

$$-\int F'_{X_{n:n}}(x_i)\frac{V}{x_i}dx_i = C(b(x_i), d) + constant$$

• To solve the differential equation we use $b(\bar{c}) = 0$,

$$-V \int_{\underline{c}}^{\overline{c}} F'_{X_{n:n}}(z) \frac{1}{z} dz = C(0, d) + constant$$

• If the costfunction is separable, we have

$$b(x) = C^{-1} \left[-\hat{V} \int_{\underline{c}}^{\bar{c}} F'_{X_{n:n}}(z) \frac{1}{z} dz - \hat{V} \int_{\underline{c}}^{x} F'_{X_{n:n}}(z) \frac{1}{z} dz \right]$$

where $\hat{V} = V/\delta(d)$ (the reward per hours worked).

3 The model

Consider $k \geq 3$ agents competing over $n \geq 1$ prizes of value $V_1 > V_2 > ... > V_n$.

To enjoy the i'th prize, an agent has to perform a certain task (the same for everyone) and be ranked i'th in the competition.

In a tournament, agents are ranked by their performance. So, the agent having achieved the highest performance gets the first prize, the one having achieved the second highest performance is awarded the second prize, and so on. In a race, agents are ranked by the time to perform. So, the first agent to achieve a given performance, which we denote \bar{Y} , gets the first prize, the second to achieve \bar{Y} is awarded the second prize, and so on. In both cases, the taks must be performed within a given deadline T otherwise agents are not eligible for prizes.

Agents simultaneously choose a real number $y \ge 0$ that is representative of their performance and a real number $t \ge 0$ that is the time to perform the task. Each agent incurs a cost from performing the task that is increasing in the performance level and decreasing in the time to perform. This cost is represented by the multiplicative cost function (like the Cobb-Douglas)

$$C(x,t) = \gamma(x)\delta(t) \tag{6}$$

with
$$\gamma(0) = 0, \ \gamma' > 0, \ \delta(T) = 1, \ \delta' < 0.$$

Agents are rational and make decisions to maximize an additive utility function. Each agent knows privately the weight attached to the cost function in her utility function. Let $X_1, ..., X_k$ denote these weights. It is common knowledge that $X_1, ..., X_k$ are iid with common distribution F on the support [a, b] with F being everywhere differentiable. Thus, the utility for an agent k is:

$$U_k = \sum_{i=1}^n P(\text{ranked } i'\text{th})V_i - x_k C(y_k, t_k).$$
(7)

Since there is private information on X_i , agents' choices are viewed as random variables by the other agents. Let $Y_1, ..., Y_k$ denote iid random variables distributed according to F_Y . Let $Y_{i:k-1}$ denote the *i*'th smallest of the Y_i . In a tournament, the probability of being ranked *i*'th can be expressed as the probability of the realized y_k being higher than i-1'th order statistic and the d Thus the utility can be written

4 Equilibrium

4.1 The case of tournaments

Consider the case of a competition with two prizes (n=2) and normalize the value of prizes to $V_1 = \alpha$ and $V_2 = 1 - \alpha$ so that the fraction $\alpha \le 1/2$ denotes the fraction of the prize pool that goes to the winner (if $\alpha = 1$ the winner gets all).

The equilibrium of a tournament competition is described in the next proposition.

Proposition 1. Consider a tournament with $k \geq 3$ agents, n = 2 prizes, and $\alpha \leq 1/2$. Let t^* and y^* denote the equilibrium values. It is a (weakly) dominant strategy to choose the time to submit $t^* = T$. And, in a symmetric equilibrium, agents choose a score $y^* = b(x)$ where

$$b(x) = [A(x)(1-\alpha) + B(x)\alpha]. \tag{9}$$

where

$$A(c) = (k-1) \int_{c}^{1} \frac{1}{a} [1 - F(a)]^{k-2} F'(a) da, \tag{10}$$

$$B(c) = (k-1) \int_{c}^{1} \frac{1}{a} [1 - F(a)]^{k-3} [(k-1)F(a) - 1]F'(a) da.$$
 (11)

Proof. Let denote the *i*'th smallest value of the rivals X_i 's by $X_{i:k-1}$ (with $X_{1:k-1}$ being the smallest, $X_{2:k-1}$ being the second smallest, etc.). Then the distribution of $X_{i:k-1}$ can be easily derived (Arnold and Balakrishnan, 2012) and we have

$$F_{X_{i:k-1}}(x) = \sum_{j=i}^{k-1} {k-1 \choose j} F(x)^j (1 - F(x))^{k-1-j}.$$
 (12)

And the corresponding density is

$$f_{X_{i:k-1}}(x) = \frac{k-1!}{(i-1)!(k-1-i)!} F(x)^{i-1} (1 - F(x))^{k-1-i} f(x).$$
(13)

Let b^{-1} denote the inverse of the equilibrium xxx function. Then

$$b^{-1}(Y_j) = X_j. (14)$$

and

$$b^{-1}(Y_{j:k-1}) = X_{j:k-1}. (15)$$

(equal in distribution)

Then we have

$$P(b^{-1}(Y_i) \ge X_{k-1:k-1}) = 1 - F_{X_{k-1:k-1}}(b^{-1}(Y_i)).$$
(16)

we have that the probability of a competitor with a bid x winning the first prize is equal to the probability of $b^{-1}(x)$ being the first order statistic of k-1 iid random bids.

Hence, the problem faced by the agent is

$$\max U = F'_{(1:k-1)}(b^{-1}x)(1-\alpha) + + (1 - F'_{(1:k-1)}(b^{-1}x))F'_{(1:k-2)}(b^{-1}x)\alpha + - \gamma(x)\delta(T)\theta$$
(17)

Let us call $F'_{(1:k-1)} = g_{k-1}(x)$. Rearranging

$$\max U = g_{k-1}(b^{-1}x)(1-\alpha) + g_{k-2}(b^{-1}x)\alpha$$

$$- g_{k-1}(b^{-1}x)g_{k-2}(b^{-1}x)\alpha +$$

$$- \gamma(x)\delta(T)\theta$$
(18)

First order condition:

$$\max U = \frac{db^{-1}}{dx} [g'_{k-1}(b^{-1}x)(1-\alpha) + g'_{k-2}(b^{-1}x)\alpha + g'_{k-1}(b^{-1}x)g_{k-2}(b^{-1}x)\alpha - g_{k-1}(b^{-1}x)g'_{k-2}(b^{-1}x)\alpha] + g'_{k-1}(a^{-1}x)(a^$$

In equilibrium $b^{-1}x = \theta$ and $db^{-1}/dx = 1/b'(\theta)$

$$\max U = g'_{k-1}(\theta)(1-\alpha) + g'_{k-2}(\theta)\alpha +$$

$$-g'_{k-1}(\theta)g_{k-2}(\theta)\alpha - g_{k-1}(\theta)g'_{k-2}(\theta)\alpha$$

$$= b'(\theta)\gamma'(b(\theta))\delta(T)\theta$$
(20)

Example uniform

Consider k=3 and F is uniform on [m,1] so that the CDF is F(x)=(x-m)/(1-m). Then,

$$A(c) = \frac{1-x}{(m-1)^2 x},\tag{21}$$

$$B(c) = -\frac{(1+m-2x)(x-1)}{(m-1)^3x}. (22)$$

1.2 Example lognormal

1.2 Example Kumaraswamy

Consider F is Kumaraswamy on (0,1) with shape parameters s_1 and s_2 and CDF equal to $1 - (1 - x^{s_1})^{s_2}$. When $s_1 = s_2 = 1$ we have a uniform distribution.

4.2 Expected utility

Let $x_{(n)}$ denote the n-th order statistic of k types. Then the expected payoff in equilibrium in both the race and the tournament but the costs are different. So the expected utility is

$$\Pr(\theta \le \theta_{1:k-1})(1-\alpha) + \Pr(\theta_{1:k-1} > \theta \le \theta_{2:k-1})\alpha - C(b_{to}(\theta), T, \theta). \tag{23}$$

and

$$\Pr(\theta \le \theta_{1:k-1})(1-\alpha) + \Pr(\theta_{1:k-1} > \theta \le \theta_{2:k-1})\alpha - C(Q, b_{ra}(\theta), \theta). \tag{24}$$

5 Empirical analysis

Consider n observations from the same type of competition. Our dataset is $(y_i, x_i), ..., (y_n, x_n)$ where y_i is a vector of time t_i and scores s_i .

For a tournament with k competitors, our model gives the equilibrium relationship

$$t_i = T \text{ and } s_i = b(\theta_i, F, \alpha)$$
 (25)

Suppose we know the distribution F up to some parameter β , then we have

$$s_i = b(\theta_i, \beta, \alpha). \tag{26}$$

Note that the score is linear in α but nonlinear in β .

Suppose the observed relationship is nondeterministic, and assume that our model is correct on average. That is, the conditional mean of scores is

$$E[s_i \mid x_i, \beta] = b(\theta_i, \beta, \alpha) \tag{27}$$

For example, we assume

$$s_i = b(\theta_i, \beta, \alpha) + \epsilon_i \tag{28}$$

and errors are assumed to be normally distributed with mean zero.

The parameters are estimated by min residual summ of squares (RSS) with respect to β and α .

$$RSS(\beta, \alpha) = \sum_{i=1}^{n} (y_i - b(x_i))^2$$
 (29)

Censoring

Lots of zeros. It could be that people participated but did not submit their solutions so that zeros are missing observations. However, this situation seems unlikely given that to win you need to submit solutions and get feedback. In reality, we believe that a zero submission is a competitor who dropped the competition.

Drop outs. Reasons are they see their rivals and decide to quit. This is consistent with theory. High number of drop outs suggests our model fits better with a fixed cost.

A Order statistics

Following Arnold and Balakrishnan (2012), we let $X_1, ..., X_n$ denote n jointly distributed random variables. We denote the i'th smallest of the X_i 's by $X_{i:n}$ ($X_{1:n}$ being the smallest, $X_{2:n}$ being the second smallest, etc.).

If $X_1, ..., X_n$ are iid with common distribution F, the distribution of an individual order statistic

is

$$F_{X_{i:n}}(x) = P(X_{i:n} \le x) = \sum_{j=i}^{n} \binom{n}{j} F(x)^{j} (1 - F(x))^{n-j}.$$
 (30)

Another representation is possible. Consider $U_1, ..., U_n$ denote iid variables with uniform distribution on the unit interval. Define the inverse $F^{-1}(x)$. It is readily verified that

$$F^{-1}(U_i) = X_i \tag{31}$$

and

$$F^{-1}(U_{i:n}) = X_{i:n}. (32)$$

Now the distribution (30) (replace F(u) with u) is absolutely continuous with corresponding density:

$$f_{U_{i:n}}(u) = \frac{n!}{(i-1)!(n-i)!} u^{i-1} (1-u)^{n-i}.$$
 (33)

The distribution can then be written:

$$F_{U_{i:n}}(u) = \int_0^u \frac{n!}{(i-1)!(n-i)!} t^{i-1} (1-t)^{n-i} dt$$
(34)

This yields the general expression

$$F_{X_{i:n}}(x) = \int_0^F (x) \frac{n!}{(i-1)!(n-i)!} t^{i-1} (1-t)^{n-i} dt$$
 (35)

If F(x) is everywhere differentiable, then the density is

$$f_{X_{i:n}}(x) = \frac{n!}{(i-1)!(n-i)!} F(x)^{i-1} (1 - F(x))^{n-i} f(x).$$
(36)

Another important result is the probability of being in between two values

$$P(X_{i:n} > x > X_{i:n}) \tag{37}$$

with i < j. We can use bayes and we have

$$P(X_{i:n} > x > X_{j:n}) = P(x > X_{j:n} | X_{i:n} > x) P(X_{i:n} > x)$$
(38)

Important result: for i < j the conditional distribution of $X_{j:n}$ given $X_{i:n} = x$ is the same as the unconditional distribution of $Y_{j-i:n-i}$

Contents

1 The model 1

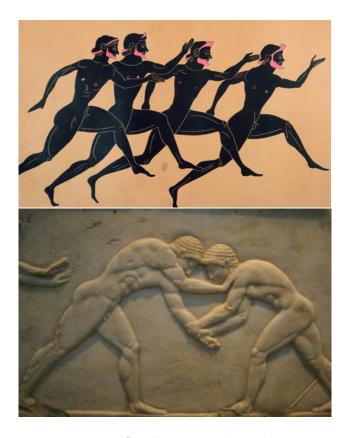


Figure 1: Greek racers and wrestlers

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References

Arnold, Barry and Narayanaswamy Balakrishnan, Relations, bounds and approximations for order statistics, Vol. 53, Springer Science & Business Media, 2012.