Dijkstras

0.1.0

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1 Final Project - Dijkstra's Algorithmm	1
1.1 What your project accomplishes/does	1
1.2 How to use your program with examples (don't forget to use markdown to make it look good)	1
1.3 The rationale for choosing your project	1
1.4 The data structures you chose and why you chose them	1
1.5 The algorithms you chose and why you chose them	1
1.6 References	1
2 Class Index	3
2.1 Class List	3
3 File Index	5
3.1 File List	5
4 Class Documentation	7
4.1 Graph Class Reference	7
4.1.1 Detailed Description	7
4.1.2 Constructor & Destructor Documentation	7
4.1.2.1 Graph()	7
4.1.3 Member Function Documentation	8
4.1.3.1 addEdge()	8
4.1.3.2 distance()	8
4.1.3.3 length()	9
4.1.3.4 matrixOut()	9
4.1.3.5 outEdges()	9
4.1.3.6 removeEdge()	10
5 File Documentation	11
5.1 /home/brandon/CPTR227/FinalProject/Dijkstras-Algorithm/README.md File Reference	11
5.2 /home/brandon/CPTR227/FinalProject/Dijkstras-Algorithm/src/main.cpp File Reference	11
5.2.1 Detailed Description	12
5.2.2 Function Documentation	12
5.2.2.1 Dijkstra()	12
5.2.2.2 main()	13
5.2.2.3 printShortPath()	13
Index	15

Final Project - Dijkstra's Algorithmm

- 1.1 What your project accomplishes/does
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- 1.5 The algorithms you chose and why you chose them

If you used multiple algorithms to compare, show and explain the results of the comparison

1.6 References

https://www.geeksforgeeks.org/dijkstras-shortest-path-algorithm-greedy-algo-7/http://www.gitta.info/Accessibiliti/en/html/Dijkstra_learningObject1.htmlhttp://www.cplusplus.com/forum/articles/7459/

Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:	
Graph	7

4 Class Index

File Index

3.1 File List

Here is a list of all files with brief descriptions:	
--	--

/home/brandon/CPTR227/FinalProject/Dijkstras-Algorithm/src/main.cpp				
This is Final Project for CPTR 227		1		

6 File Index

Class Documentation

4.1 Graph Class Reference

Public Member Functions

```
• Graph (int x)
```

- void addEdge (int i, int j, int dist)
- void removeEdge (int i, int j)
- int distance (int i, int j)
- vector< int > outEdges (int i)
- int length ()
- int ** matrixOut ()

4.1.1 Detailed Description

This class creates an integer matrix graph.

Definition at line 19 of file main.cpp.

4.1.2 Constructor & Destructor Documentation

4.1.2.1 Graph()

Graph constructor

Parameters

x The dimensions of the graph

8 Class Documentation

Definition at line 31 of file main.cpp.

4.1.3 Member Function Documentation

4.1.3.1 addEdge()

```
void Graph::addEdge (
                int i,
                 int j,
                 int dist ) [inline]
```

Adds an edge to the graph by setting [i][j] to the distance from the nodes

Parameters

i	Initial node
j	Node to connect

Definition at line 45 of file main.cpp.

```
45
46 matrix[i][j] = dist;
47 matrix[j][i] = dist;
48 }
```

4.1.3.2 distance()

Finds distance by checking the number stored in [i][j]

Parameters

i	Initial node
j	A connected node

```
Definition at line 66 of file main.cpp.
```

4.1.3.3 length()

```
int Graph::length ( ) [inline]
```

Returns the length by returning n

Returns

lenght of graph

Definition at line 91 of file main.cpp.

```
91 {
92     return n;
93 }
```

4.1.3.4 matrixOut()

```
int** Graph::matrixOut ( ) [inline]
```

Retruns the matrix

Returns

the matrix

Definition at line 100 of file main.cpp.

4.1.3.5 outEdges()

```
vector<int> Graph::outEdges (
    int i ) [inline]
```

Finds all nodes connected to i by checking all of it's rows

Parameters

```
i Initial node
```

Returns

A vector of all connected nodes

```
Definition at line 76 of file main.cpp.
```

```
76
77 vector<int> edges;
```

10 Class Documentation

4.1.3.6 removeEdge()

```
void Graph::removeEdge (  \qquad \qquad \text{int $i,$} \\  \qquad \text{int $j$} ) \quad [\text{inline}]
```

Removes an edge from the graph by setting [i][j] to 0

Parameters

	i	Initial node
ĺ	j	Connected node

```
Definition at line 56 of file main.cpp.
```

The documentation for this class was generated from the following file:

• /home/brandon/CPTR227/FinalProject/Dijkstras-Algorithm/src/main.cpp

File Documentation

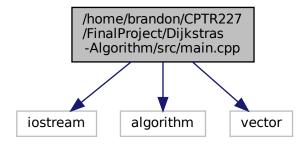
- 5.1 /home/brandon/CPTR227/FinalProject/Dijkstras-Algorithm/READ ← ME.md File Reference
- 5.2 /home/brandon/CPTR227/FinalProject/Dijkstras
 Algorithm/src/main.cpp File

 Reference

This is Final Project for CPTR 227.

#include <iostream>
#include <algorithm>
#include <vector>

Include dependency graph for main.cpp:



Classes

• class Graph

12 File Documentation

Functions

- void Dijkstra (Graph g, int source, int *dist, int *parent)
- void printShortPath (Graph g, int *dist, int *parent)
- int main (int, char **)

5.2.1 Detailed Description

This is Final Project for CPTR 227.

This is implementation of Dijkstra's Algorithm to find the shortest path.

Author

Nathan Quick & Brandon Yi

Date

5/5/2021

5.2.2 Function Documentation

5.2.2.1 Dijkstra()

Finds the shortest path in a graph using Dijkstras algorithm

Parameters

g	The graph
source	Initial node
dist	An empty array with the same size as g to store distance values
parent	An empty array with the same size as g to store path values

Definition at line 114 of file main.cpp.

```
114
115     int index = 0;
116     bool used[g.length()]; // An array that stors if the node's shortest path has already be found
117
118     for (int i=0; i<g.length(); i++){
119         dist[i] = -1;
120         used[i] = false;
121     }
122
123     dist[source] = 0; // The distance from source to source is 0</pre>
```

```
124
          used[source] = true; // Mark source as used
125
          parent[source] = 0; // Source has no path to source
126
127
          for (int i=0; i<g.length(); i++) {</pre>
128
                vector<int> edge = g.outEdges(index); // Stores all of index's connected nodes
129
130
131
                // Updates the distances from source to the edge
132
                for (int ii=0; ii<edge.size(); ii++){</pre>
                     int u = dist[index] + g.distance(index, edge[ii]);
if (u < dist[edge[ii]] || dist[edge[ii]] == -1){
   parent[edge[ii]] = index;
   dist[edge[ii]] = dist[index] + g.distance(index, edge[ii]);</pre>
133
134
135
136
137
138
139
                // Reset min
               int min = -1; // Stores the smalles distance value
140
141
142
                // Finds the shortest path of the discovered distances
               for (int ii=0; ii<g.length(); ii++) {
    if (!used[ii] && dist[ii] != -1) {
        if (dist[ii] < min || min == -1) {
143
144
145
                               min = dist[ii];
146
147
                                index = ii;
148
                          }
149
                     }
150
151
                // Marks shortest node path as used
152
               used[index] = true;
153
154 }
```

5.2.2.2 main()

```
int main (
    int ,
    char ** )
```

Definition at line 190 of file main.cpp.

```
191
         Graph g(9);
192
193
         int dist[g.length()];
194
        int parent[g.length()];
195
196
         g.addEdge(0,1,4);
197
         g.addEdge(1,2,8);
198
         g.addEdge(2,3,7);
199
         g.addEdge(3,4,9);
200
         g.addEdge(4,5,10);
         g.addEdge(5,6,2);
201
202
         g.addEdge(6,7,1);
203
         g.addEdge(7,8,7);
204
         g.addEdge(7,0,8);
205
         g.addEdge(1,7,11);
206
         g.addEdge(2,5,4);
207
         g.addEdge(3,5,14);
208
         g.addEdge(2,8,2);
209
         g.addEdge(6,8,6);
210
         g.addEdge(0,7,8);
211
        Dijkstra(g, 0, dist, parent);
printShortPath(g, dist, parent);
212
213
214 }
```

5.2.2.3 printShortPath()

Prints the distances and shortest path of each node from source

14 File Documentation

Parameters

g	The graph
dist	The list of smallest distances
parent	A list that hold path info

Definition at line 163 of file main.cpp.

```
163
164
             cout « "Distance Shortest" « endl;
cout « " from 0 path" « endl;
cout « "-----" « endl;
int index = 0;
165
166
167
168
             vector<int> items;
             for (int i=1; i<g.length(); i++) {
   cout « i « ": " « dist[i] « string(5, ' ');</pre>
169
170
                     items.clear();
171
172
173
                     index = i;
                    do
{
174
175
                                 items.push_back(parent[index]);
                    index = parent[index];
} while (index > 0);
176
177
                    f while (index > 0),
reverse(items.begin(),items.end());
for (int ii=0; ii<=items.size()-1; ii++){
    if (ii==0 && dist[i] < 10){
        cout « ' ';
}</pre>
178
179
180
181
182
                           cout « items[ii] « "->";
183
184
                     cout « i «endl;
185
186
187 }
```

Index

Graph, 10

```
/home/brandon/CPTR227/FinalProject/Dijkstras-Algorithm/README.md,\\
/home/brandon/CPTR227/FinalProject/Dijkstras-Algorithm/src/main.cpp,
         11
addEdge
    Graph, 8
Dijkstra
    main.cpp, 12
distance
    Graph, 8
Graph, 7
    addEdge, 8
    distance, 8
    Graph, 7
    length, 8
    matrixOut, 9
    outEdges, 9
    removeEdge, 10
length
    Graph, 8
main
    main.cpp, 13
main.cpp
    Dijkstra, 12
    main, 13
    printShortPath, 13
matrixOut
    Graph, 9
outEdges
    Graph, 9
printShortPath
    main.cpp, 13
removeEdge
```