

Artificial Intelligence Nanodegree

Convolutional Neural Networks

Project: Write an Algorithm for a Dog Identification App

In this notebook, some template code has already been provided for you, and you will need to implement additional functionality to successfully complete this project. You will not need to modify the included code beyond what is requested. Sections that begin with '**(IMPLEMENTATION)**' in the header indicate that the following block of code will require additional functionality which you must provide. Instructions will be provided for each section, and the specifics of the implementation are marked in the code block with a 'TODO' statement. Please be sure to read the instructions carefully!

Note: Once you have completed all of the code implementations, you need to finalize your work by exporting the iPython Notebook as an HTML document. Before exporting the notebook to html, all of the code cells need to have been run so that reviewers can see the final implementation and output. You can then export the notebook by using the menu above and navigating to "\n", "**File -> Download as -> HTML (.html)**". Include the finished document along with this notebook as your submission.

In addition to implementing code, there will be questions that you must answer which relate to the project and your implementation. Each section where you will answer a question is preceded by a '**Question X**' header. Carefully read each question and provide thorough answers in the following text boxes that begin with '**Answer:**'. Your project submission will be evaluated based on your answers to each of the questions and the implementation you provide.

Note: Code and Markdown cells can be executed using the **Shift + Enter** keyboard shortcut. Markdown cells can be edited by double-clicking the cell to enter edit mode.

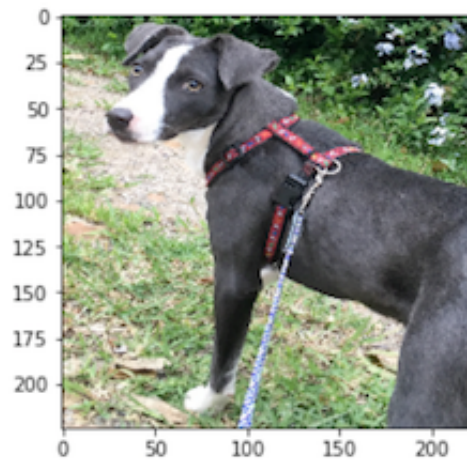
The rubric contains *optional* "Stand Out Suggestions" for enhancing the project beyond the minimum requirements. If you decide to pursue the "Stand Out Suggestions", you should include the code in this IPython notebook.

Why We're Here

In this notebook, you will make the first steps towards developing an algorithm that could be used as part of a mobile or web app. At the end of this project, your code will accept any user-supplied image as input. If a dog is detected in the image, it will provide an estimate of the dog's breed. If a human is detected, it will

provide an estimate of the dog breed that is most resembling. The image below displays potential sample output of your finished project (... but we expect that each student's algorithm will behave differently!).

```
hello, dog!  
your predicted breed is ...  
American Staffordshire terrier
```



In this real-world setting, you will need to piece together a series of models to perform different tasks; for instance, the algorithm that detects humans in an image will be different from the CNN that infers dog breed. There are many points of possible failure, and no perfect algorithm exists. Your imperfect solution will nonetheless create a fun user experience!

The Road Ahead

We break the notebook into separate steps. Feel free to use the links below to navigate the notebook.

- [Step 0: Import Datasets](#)
- [Step 1: Detect Humans](#)
- [Step 2: Detect Dogs](#)
- [Step 3: Create a CNN to Classify Dog Breeds \(from Scratch\)](#)
- [Step 4: Use a CNN to Classify Dog Breeds \(using Transfer Learning\)](#)
- [Step 5: Create a CNN to Classify Dog Breeds \(using Transfer Learning\)](#)
- [Step 6: Write your Algorithm](#)
- [Step 7: Test Your Algorithm](#)

Step 0: Import Datasets

Import Dog Dataset

In the code cell below, we import a dataset of dog images. We populate a few variables through the use of the `load_files` function from the scikit-learn library:

- `train_files, valid_files, test_files` - numpy arrays containing file paths to images
- `train_targets, valid_targets, test_targets` - numpy arrays containing onehot-encoded

classification labels

- `dog_names` - list of string-valued dog breed names for translating labels

```
In [1]: from sklearn.datasets import load_files
        from keras.utils import np_utils
        import numpy as np
        from glob import glob

        # define function to load train, test, and validation datasets
        def load_dataset(path):
            data = load_files(path)
            dog_files = np.array(data['filenames'])
            dog_targets = np_utils.to_categorical(np.array(data['target']), 133)
            return dog_files, dog_targets

        # load train, test, and validation datasets
        train_files, train_targets = load_dataset('dogImages/train')
        valid_files, valid_targets = load_dataset('dogImages/valid')
        test_files, test_targets = load_dataset('dogImages/test')

        # load list of dog names
        dog_names = [item[20:-1] for item in sorted(glob("dogImages/train/*/"))]

        # print statistics about the dataset
        print('There are %d total dog categories.' % len(dog_names))
        print('There are %s total dog images.\n' % len(np.hstack([train_files,
                                                                    valid_files,
                                                                    test_files])))
        print('There are %d training dog images.' % len(train_files))
        print('There are %d validation dog images.' % len(valid_files))
        print('There are %d test dog images.' % len(test_files))
```

Using TensorFlow backend.

There are 133 total dog categories.

There are 8351 total dog images.

There are 6680 training dog images.

There are 835 validation dog images.

There are 836 test dog images.

Import Human Dataset

In the code cell below, we import a dataset of human images, where the file paths are stored in the numpy array `human_files`.

```
In [2]: import random
        random.seed(8675309)

        # load filenames in shuffled human dataset
        human_files = np.array(glob("lfw/*/"))
        random.shuffle(human_files)

        # print statistics about the dataset
        print('There are %d total human images.' % len(human_files))
```

There are 13233 total human images.

Step 1: Detect Humans

We use OpenCV's implementation of Haar feature-based cascade classifiers (http://docs.opencv.org/trunk/d7/d8b/tutorial_py_face_detection.html) to detect human faces in images. OpenCV provides many pre-trained face detectors, stored as XML files on github (<https://github.com/opencv/opencv/tree/master/data/haarcascades>). We have downloaded one of these detectors and stored it in the `haarcascades` directory.

In the next code cell, we demonstrate how to use this detector to find human faces in a sample image.

```
In [3]: import cv2
import matplotlib.pyplot as plt
%matplotlib inline

# extract pre-trained face detector
face_cascade = cv2.CascadeClassifier('haarcascades/haarcascade_frontal
face_alt.xml')

# load color (BGR) image
img = cv2.imread(human_files[3])
# convert BGR image to grayscale
gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

# find faces in image
faces = face_cascade.detectMultiScale(gray)

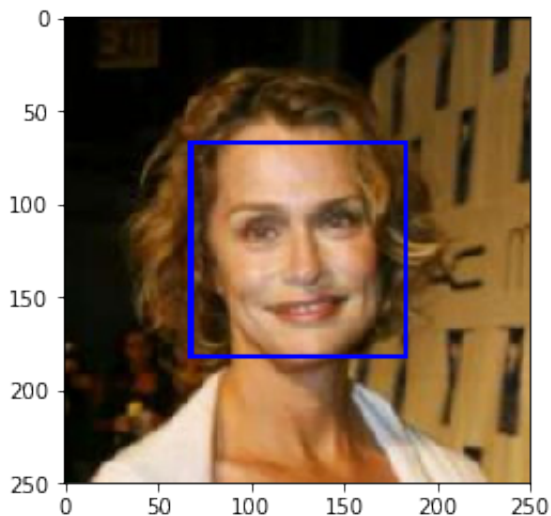
# print number of faces detected in the image
print('Number of faces detected:', len(faces))

# get bounding box for each detected face
for (x,y,w,h) in faces:
    # add bounding box to color image
    cv2.rectangle(img,(x,y),(x+w,y+h),(255,0,0),2)

# convert BGR image to RGB for plotting
cv_rgb = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)

# display the image, along with bounding box
plt.imshow(cv_rgb)
plt.show()
```

Number of faces detected: 1



Before using any of the face detectors, it is standard procedure to convert the images to grayscale. The `detectMultiScale` function executes the classifier stored in `face_cascade` and takes the grayscale image as a parameter.

In the above code, `faces` is a numpy array of detected faces, where each row corresponds to a detected face. Each detected face is a 1D array with four entries that specifies the bounding box of the detected face. The first two entries in the array (extracted in the above code as `x` and `y`) specify the horizontal and vertical positions of the top left corner of the bounding box. The last two entries in the array (extracted here as `w` and `h`) specify the width and height of the box.

Write a Human Face Detector

We can use this procedure to write a function that returns `True` if a human face is detected in an image and `False` otherwise. This function, aptly named `face_detector`, takes a string-valued file path to an image as input and appears in the code block below.

```
In [4]: # returns "True" if face is detected in image stored at img_path
def face_detector(img_path):
    img = cv2.imread(img_path)
    gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
    faces = face_cascade.detectMultiScale(gray)
    return len(faces) > 0
```

(IMPLEMENTATION) Assess the Human Face Detector

Question 1: Use the code cell below to test the performance of the `face_detector` function.

- What percentage of the first 100 images in `human_files` have a detected human face?
- What percentage of the first 100 images in `dog_files` have a detected human face?

Ideally, we would like 100% of human images with a detected face and 0% of dog images with a detected face. You will see that our algorithm falls short of this goal, but still gives acceptable performance. We extract the file paths for the first 100 images from each of the datasets and store them in the numpy arrays `human_files_short` and `dog_files_short`.

Answer: Human 98%, Dogs 11%

```
In [5]: human_files_short = human_files[:100]
dog_files_short = train_files[:100]
# Do NOT modify the code above this line.

## TODO: Test the performance of the face_detector algorithm
## on the images in human_files_short and dog_files_short.

#Check if the human face is detected
human_sum = 0
for human_image in human_files_short:
    human_sum += face_detector(human_image)

print('Humans Detected: %.2f%%' % ((human_sum/len(human_files_short))*100))

#Check if the dog face is detected
dog_sum = 0
for dog_image in dog_files_short:
    dog_sum += face_detector(dog_image)

print('Dogs Detected: %.2f%%' % ((dog_sum/len(dog_files_short))*100))

Humans Detected: 98.00%
Dogs Detected: 11.00%
```

Question 2: This algorithmic choice necessitates that we communicate to the user that we accept human images only when they provide a clear view of a face (otherwise, we risk having unnecessarily frustrated users!). In your opinion, is this a reasonable expectation to pose on the user? If not, can you think of a way to detect humans in images that does not necessitate an image with a clearly presented face?

Answer: I think I can be acceptable depending on the context this is been used. For example, if you want to reconize people to log-in in a door, you can put as policy that you have to remove your glasses and look straight to the camera. Now in other context this may be unacceptable. In that case, an option is to train another CNN just to identify if it's human. I am sure there are other alternatives to CV for face detection available as well.

We suggest the face detector from OpenCV as a potential way to detect human images in your algorithm, but you are free to explore other approaches, especially approaches that make use of deep learning :). Please use the code cell below to design and test your own face detection algorithm. If you decide to pursue this *optional* task, report performance on each of the datasets.

```
In [6]: ## (Optional) TODO: Report the performance of another
## face detection algorithm on the LFW dataset
### Feel free to use as many code cells as needed.
```

Step 2: Detect Dogs

In this section, we use a pre-trained [ResNet-50](http://ethereon.github.io/netscope/#/gist/db945b393d40bfa26006) (<http://ethereon.github.io/netscope/#/gist/db945b393d40bfa26006>) model to detect dogs in images. Our first line of code downloads the ResNet-50 model, along with weights that have been trained on [ImageNet](http://www.image-net.org/) (<http://www.image-net.org/>), a very large, very popular dataset used for image classification and other vision tasks. ImageNet contains over 10 million URLs, each linking to an image containing an object from one of 1000 categories (<https://gist.github.com/yrevar/942d3a0ac09ec9e5eb3a>). Given an image, this pre-trained ResNet-50 model returns a prediction (derived from the available categories in ImageNet) for the object that is contained in the image.

```
In [7]: from keras.applications.resnet50 import ResNet50

# define ResNet50 model
ResNet50_model = ResNet50(weights='imagenet')
```

Pre-process the Data

When using TensorFlow as backend, Keras CNNs require a 4D array (which we'll also refer to as a 4D tensor) as input, with shape

$$(nb_samples, rows, columns, channels),$$

where `nb_samples` corresponds to the total number of images (or samples), and `rows`, `columns`, and `channels` correspond to the number of rows, columns, and channels for each image, respectively.

The `path_to_tensor` function below takes a string-valued file path to a color image as input and returns a 4D tensor suitable for supplying to a Keras CNN. The function first loads the image and resizes it to a square image that is 224×224 pixels. Next, the image is converted to an array, which is then resized to a 4D tensor. In this case, since we are working with color images, each image has three channels. Likewise, since we are processing a single image (or sample), the returned tensor will always have shape $(1, 224, 224, 3)$.

The `paths_to_tensor` function takes a numpy array of string-valued image paths as input and returns a 4D tensor with shape

$$(nb_samples, 224, 224, 3).$$

Here, `nb_samples` is the number of samples, or number of images, in the supplied array of image paths. It is best to think of `nb_samples` as the number of 3D tensors (where each 3D tensor corresponds to a different image) in your dataset!


```
In [8]: from keras.preprocessing import image
        from tqdm import tqdm

        def path_to_tensor(img_path):
            # loads RGB image as PIL.Image.Image type
            img = image.load_img(img_path, target_size=(224, 224))
            # convert PIL.Image.Image type to 3D tensor with shape (224, 224,
            3)
            x = image.img_to_array(img)
            # convert 3D tensor to 4D tensor with shape (1, 224, 224, 3) and r
            eturn 4D tensor
            return np.expand_dims(x, axis=0)

        def paths_to_tensor(img_paths):
            list_of_tensors = [path_to_tensor(img_path) for img_path in tqdm(i
            mg_paths)]
            return np.vstack(list_of_tensors)
```

Making Predictions with ResNet-50

Getting the 4D tensor ready for ResNet-50, and for any other pre-trained model in Keras, requires some additional processing. First, the RGB image is converted to BGR by reordering the channels. All pre-trained models have the additional normalization step that the mean pixel (expressed in RGB as [103.939, 116.779, 123.68] and calculated from all pixels in all images in ImageNet) must be subtracted from every pixel in each image. This is implemented in the imported function `preprocess_input`. If you're curious, you can check the code for `preprocess_input` [here](https://github.com/fchollet/keras/blob/master/keras/applications/imagenet_utils.py) (https://github.com/fchollet/keras/blob/master/keras/applications/imagenet_utils.py).

Now that we have a way to format our image for supplying to ResNet-50, we are now ready to use the model to extract the predictions. This is accomplished with the `predict` method, which returns an array whose i -th entry is the model's predicted probability that the image belongs to the i -th ImageNet category. This is implemented in the `ResNet50_predict_labels` function below.

By taking the `argmax` of the predicted probability vector, we obtain an integer corresponding to the model's predicted object class, which we can identify with an object category through the use of this [dictionary](https://gist.github.com/yrevar/942d3a0ac09ec9e5eb3a) (<https://gist.github.com/yrevar/942d3a0ac09ec9e5eb3a>).

```
In [9]: from keras.applications.resnet50 import preprocess_input, decode_predi
        ctions

        def ResNet50_predict_labels(img_path):
            # returns prediction vector for image located at img_path
            img = preprocess_input(path_to_tensor(img_path))
            return np.argmax(ResNet50_model.predict(img))
```

Write a Dog Detector

While looking at the [dictionary](https://gist.github.com/yrevar/942d3a0ac09ec9e5eb3a) (<https://gist.github.com/yrevar/942d3a0ac09ec9e5eb3a>), you will notice that the categories corresponding to dogs appear in an uninterrupted sequence and correspond to dictionary keys 151-268, inclusive, to include all categories from 'Chihuahua' to 'Mexican hairless'. Thus, in order to check to see if an image is predicted to contain a dog by the pre-trained ResNet-50 model, we need only check if the `ResNet50_predict_labels` function above returns a value between 151 and 268 (inclusive).

We use these ideas to complete the `dog_detector` function below, which returns `True` if a dog is detected in an image (and `False` if not).

```
In [10]: ### returns "True" if a dog is detected in the image stored at img_path
def dog_detector(img_path):
    prediction = ResNet50_predict_labels(img_path)
    return ((prediction <= 268) & (prediction >= 151))
```

(IMPLEMENTATION) Assess the Dog Detector

Question 3: Use the code cell below to test the performance of your `dog_detector` function.

- What percentage of the images in `human_files_short` have a detected dog?
- What percentage of the images in `dog_files_short` have a detected dog?

Answer: Humans 1%, Dogs 100%

```
In [11]: ### TODO: Test the performance of the dog_detector function
        ### on the images in human_files_short and dog_files_short.

        human_sum2 = 0
        for human_img in human_files_short:
            if dog_detector(human_img):
                human_sum2 += 1

        print('Humans Detected: %.2f%%' % ((human_sum2/len(human_files_short))
        *100))

        dog_sum2 = 0
        for dog_img in dog_files_short:
            if dog_detector(dog_img):
                dog_sum2 += 1

        print('Dogs Detected: %.2f%%' % ((dog_sum2/len(dog_files_short))*100)
        )

        Humans Detected: 1.00%
        Dogs Detected: 100.00%
```

Step 3: Create a CNN to Classify Dog Breeds (from Scratch)

Now that we have functions for detecting humans and dogs in images, we need a way to predict breed from images. In this step, you will create a CNN that classifies dog breeds. You must create your CNN *from scratch* (so, you can't use transfer learning yet!), and you must attain a test accuracy of at least 1%. In Step 5 of this notebook, you will have the opportunity to use transfer learning to create a CNN that attains greatly improved accuracy.

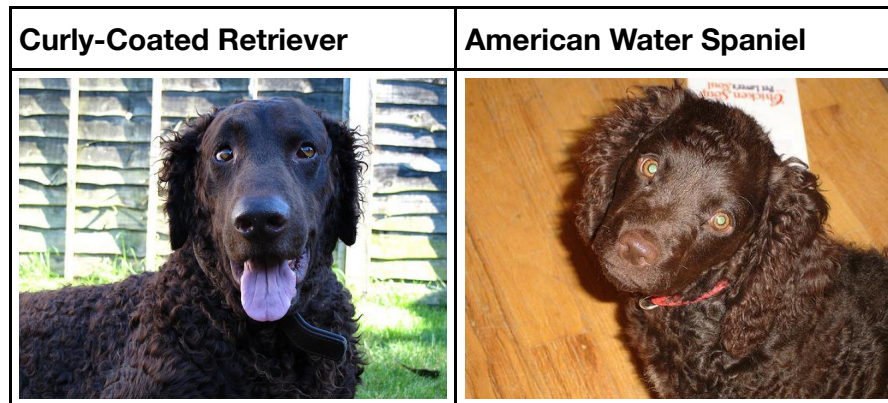
Be careful with adding too many trainable layers! More parameters means longer training, which means you are more likely to need a GPU to accelerate the training process. Thankfully, Keras provides a handy estimate of the time that each epoch is likely to take; you can extrapolate this estimate to figure out how long it will take for your algorithm to train.

We mention that the task of assigning breed to dogs from images is considered exceptionally challenging. To see why, consider that *even a human* would have great difficulty in distinguishing between a Brittany and a Welsh Springer Spaniel.

Brittany	Welsh Springer Spaniel



It is not difficult to find other dog breed pairs with minimal inter-class variation (for instance, Curly-Coated Retrievers and American Water Spaniels).



Likewise, recall that labradors come in yellow, chocolate, and black. Your vision-based algorithm will have to conquer this high intra-class variation to determine how to classify all of these different shades as the same breed.



We also mention that random chance presents an exceptionally low bar: setting aside the fact that the classes are slightly imbalanced, a random guess will provide a correct answer roughly 1 in 133 times, which corresponds to an accuracy of less than 1%.

Remember that the practice is far ahead of the theory in deep learning. Experiment with many different architectures, and trust your intuition. And, of course, have fun!

Pre-process the Data

We rescale the images by dividing every pixel in every image by 255.

```
In [12]: from PIL import ImageFile
ImageFile.LOAD_TRUNCATED_IMAGES = True

# pre-process the data for Keras
train_tensors = paths_to_tensor(train_files).astype('float32')/255
valid_tensors = paths_to_tensor(valid_files).astype('float32')/255
test_tensors = paths_to_tensor(test_files).astype('float32')/255

100%|██████████| 6680/6680 [02:08<00:00, 52.11it/s]
100%|██████████| 835/835 [00:15<00:00, 53.17it/s]
100%|██████████| 836/836 [00:15<00:00, 74.17it/s]
```

(IMPLEMENTATION) Model Architecture

Create a CNN to classify dog breed. At the end of your code cell block, summarize the layers of your model by executing the line:

```
model.summary()
```

We have imported some Python modules to get you started, but feel free to import as many modules as you need. If you end up getting stuck, here's a hint that specifies a model that trains relatively fast on CPU and attains >1% test accuracy in 5 epochs:

Layer (type)	Output Shape	Param #
conv2d_1 (Conv2D)	(None, 223, 223, 16)	208
max_pooling2d_1 (MaxPooling2D)	(None, 111, 111, 16)	0
conv2d_2 (Conv2D)	(None, 110, 110, 32)	2080
max_pooling2d_2 (MaxPooling2D)	(None, 55, 55, 32)	0
conv2d_3 (Conv2D)	(None, 54, 54, 64)	8256
max_pooling2d_3 (MaxPooling2D)	(None, 27, 27, 64)	0
global_average_pooling2d_1 (GlobalAveragePooling2D)	(None, 64)	0
dense_1 (Dense)	(None, 133)	8645
Total params: 19,189.0		
Trainable params: 19,189.0		
Non-trainable params: 0.0		

INPUT

CONV

POOL

CONV

POOL

CONV

POOL

GAP

DENSE

Question 4: Outline the steps you took to get to your final CNN architecture and your reasoning at each step. If you chose to use the hinted architecture above, describe why you think that CNN architecture should work well for the image classification task.

Answer: : I initially used the hinted model to see if what I was able to get as result. I ended up getting an accuracy around 2.9%. Not bad considering the size of the sample.

The hinted model is a combination of 3 groups of Convolutional Layers followed by a Pool layer.

Convolutional Layers will be used to to make the array deeper. (Discover hierarchies of spatial patterns). Usually are square and exponential. Filters are applied in exponential using a 'relu' activation function. This will gradually increase the depth without changing the size of width and the height.

Pool Layer are applied after each convolutional layer to decrease the spatial dimension (to half in this case) ended up an array matrix that goes from. 32, 16, 8.

Finally, you can flatter (contains no spatial information) and the array to fed to fully connected layers to determine what object is contained in the image.

Once I had the model working I decided to add 2 additional layers using the similar approach and I gained an additional accuracy of 3%.

But reviewing the course videos I decided to replace the Global Average Pooling with a combination of a Flatter() and Dense (500) instead. This gave me an accuracy of almost 13%.

I tried many other combinations. I decided on this architecture based on the results. It seems that adding additional layers for images when the sample is relatively small seems to be a good approach.

```
In [13]: from keras.layers import Conv2D, MaxPooling2D, GlobalAveragePooling2D
from keras.layers import Dropout, Flatten, Dense
from keras.models import Sequential

model = Sequential()

# Conv 1
model.add(Conv2D(filters=16, kernel_size=2, padding='valid', activation='relu', input_shape=(224, 224, 3)))
# Pool 1
model.add(MaxPooling2D(pool_size=2))
# Conv 2
model.add(Conv2D(filters=32, kernel_size=2, padding='valid', activation='relu'))
# Pool 2
model.add(MaxPooling2D(pool_size=2))
# Conv 3
model.add(Conv2D(filters=64, kernel_size=2, padding='valid', activation='relu'))
# Pool 3
model.add(MaxPooling2D(pool_size=2))

# Added Conv 4
model.add(Conv2D(filters=128, kernel_size=2, padding='valid', activation='relu'))
# Added Pool 4
model.add(MaxPooling2D(pool_size=2))

# Added Conv 5
model.add(Conv2D(filters=256, kernel_size=2, padding='valid', activation='relu'))
# Added Pool 5
model.add(MaxPooling2D(pool_size=2))

# Gap
# model.add(GlobalAveragePooling2D())

# Flatten and Dense
model.add(Flatten())
model.add(Dense(500, activation='relu'))

# Dense
model.add(Dense(133, activation='softmax'))

model.summary()
```

Layer (type)	Output Shape	Param #
conv2d_1 (Conv2D)	(None, 223, 223, 16)	208
max_pooling2d_2 (MaxPooling2D)	(None, 111, 111, 16)	0
conv2d_2 (Conv2D)	(None, 110, 110, 32)	2080
max_pooling2d_3 (MaxPooling2D)	(None, 55, 55, 32)	0
conv2d_3 (Conv2D)	(None, 54, 54, 64)	8256
max_pooling2d_4 (MaxPooling2D)	(None, 27, 27, 64)	0
conv2d_4 (Conv2D)	(None, 26, 26, 128)	32896
max_pooling2d_5 (MaxPooling2D)	(None, 13, 13, 128)	0
conv2d_5 (Conv2D)	(None, 12, 12, 256)	131328
max_pooling2d_6 (MaxPooling2D)	(None, 6, 6, 256)	0
flatten_2 (Flatten)	(None, 9216)	0
dense_1 (Dense)	(None, 500)	4608500
dense_2 (Dense)	(None, 133)	66633
Total params: 4,849,901.0		
Trainable params: 4,849,901.0		
Non-trainable params: 0.0		

Compile the Model

```
In [14]: model.compile(optimizer='rmsprop', loss='categorical_crossentropy', metrics=['accuracy'])
```

(IMPLEMENTATION) Train the Model

Train your model in the code cell below. Use model checkpointing to save the model that attains the best validation loss.

You are welcome to [augment the training data \(https://blog.keras.io/building-powerful-image-classification-models-using-very-little-data.html\)](https://blog.keras.io/building-powerful-image-classification-models-using-very-little-data.html), but this is not a requirement.


```
In [15]: from keras.callbacks import ModelCheckpoint
```

```
### TODO: specify the number of epochs that you would like to use to train the model.
```

```
epochs = 5
```

```
### Do NOT modify the code below this line.
```

```
checkpointer = ModelCheckpoint(filepath='saved_models/weights.best.from_scratch.hdf5',  
                               verbose=1, save_best_only=True)
```

```
model.fit(train_tensors, train_targets,  
          validation_data=(valid_tensors, valid_targets),  
          epochs=epochs, batch_size=20, callbacks=[checkpointer], verbose=1)
```

```
Train on 6680 samples, validate on 835 samples
```

```
Epoch 1/5
```

```
6660/6680 [=====>.] - ETA: 1s - loss: 4.8062  
- acc: 0.0186      Epoch 00000: val_loss improved from inf to 4.64683, saving model to saved_models/weights.best.from_scratch.hdf5
```

```
6680/6680 [=====] - 355s - loss: 4.8054 - acc: 0.0186 - val_loss: 4.6468 - val_acc: 0.0299
```

```
Epoch 2/5
```

```
6660/6680 [=====>.] - ETA: 1s - loss: 4.3000  
- acc: 0.0568      Epoch 00001: val_loss improved from 4.64683 to 4.10113, saving model to saved_models/weights.best.from_scratch.hdf5
```

```
6680/6680 [=====] - 352s - loss: 4.2995 - acc: 0.0569 - val_loss: 4.1011 - val_acc: 0.0802
```

```
Epoch 3/5
```

```
6660/6680 [=====>.] - ETA: 1s - loss: 3.8052  
- acc: 0.1240      Epoch 00002: val_loss improved from 4.10113 to 3.98954, saving model to saved_models/weights.best.from_scratch.hdf5
```

```
6680/6680 [=====] - 349s - loss: 3.8061 - acc: 0.1241 - val_loss: 3.9895 - val_acc: 0.1018
```

```
Epoch 4/5
```

```
6660/6680 [=====>.] - ETA: 1s - loss: 3.2356  
- acc: 0.2201      Epoch 00003: val_loss improved from 3.98954 to 3.98078, saving model to saved_models/weights.best.from_scratch.hdf5
```

```
6680/6680 [=====] - 349s - loss: 3.2341 - acc: 0.2208 - val_loss: 3.9808 - val_acc: 0.1114
```

```
Epoch 5/5
```

```
6660/6680 [=====>.] - ETA: 1s - loss: 2.4597  
- acc: 0.3845      Epoch 00004: val_loss did not improve
```

```
6680/6680 [=====] - 363s - loss: 2.4606 - acc: 0.3840 - val_loss: 4.4056 - val_acc: 0.1090
```

```
Out[15]: <keras.callbacks.History at 0x1267a7a58>
```

Load the Model with the Best Validation Loss

```
In [16]: model.load_weights('saved_models/weights.best.from_scratch.hdf5')
```

Test the Model

Try out your model on the test dataset of dog images. Ensure that your test accuracy is greater than 1%.

```
In [17]: # get index of predicted dog breed for each image in test set
dog_breed_predictions = [np.argmax(model.predict(np.expand_dims(tensor
, axis=0))) for tensor in test_tensors]

# report test accuracy
test_accuracy = 100*np.sum(np.array(dog_breed_predictions)==np.argmax(
test_targets, axis=1))/len(dog_breed_predictions)
print('Test accuracy: %.4f%%' % test_accuracy)
```

```
Test accuracy: 12.9187%
```

Step 4: Use a CNN to Classify Dog Breeds

To reduce training time without sacrificing accuracy, we show you how to train a CNN using transfer learning. In the following step, you will get a chance to use transfer learning to train your own CNN.

Obtain Bottleneck Features

```
In [18]: bottleneck_features = np.load('bottleneck_features/DogVGG16Data.npz')
train_VGG16 = bottleneck_features['train']
valid_VGG16 = bottleneck_features['valid']
test_VGG16 = bottleneck_features['test']
```

Model Architecture

The model uses the the pre-trained VGG-16 model as a fixed feature extractor, where the last convolutional output of VGG-16 is fed as input to our model. We only add a global average pooling layer and a fully connected layer, where the latter contains one node for each dog category and is equipped with a softmax.

```
In [19]: VGG16_model = Sequential()
VGG16_model.add(GlobalAveragePooling2D(input_shape=train_VGG16.shape[1
:]))
VGG16_model.add(Dense(133, activation='softmax'))

VGG16_model.summary()
```

Layer (type)	Output Shape	Param #
global_average_pooling2d_1 (None, 512)		0
dense_3 (Dense)	(None, 133)	68229
Total params: 68,229.0		
Trainable params: 68,229.0		
Non-trainable params: 0.0		

Compile the Model

```
In [20]: VGG16_model.compile(loss='categorical_crossentropy', optimizer='rmspro
p', metrics=['accuracy'])
```

Train the Model

```
In [21]: checkpointer = ModelCheckpoint(filepath='saved_models/weights.best.VGG
16.hdf5',

                                         verbose=1, save_best_only=True)

VGG16_model.fit(train_VGG16, train_targets,
                validation_data=(valid_VGG16, valid_targets),
                epochs=20, batch_size=20, callbacks=[checker], verbose=
1)
```

Train on 6680 samples, validate on 835 samples

Epoch 1/20

6440/6680 [=====>..] - ETA: 0s - loss: 12.1677
- acc: 0.1309 Epoch 00000: val_loss improved from inf to 10.890
20, saving model to saved_models/weights.best.VGG16.hdf5

6680/6680 [=====] - 1s - loss: 12.1433 - ac
c: 0.1338 - val_loss: 10.8902 - val_acc: 0.2156

Epoch 2/20

6620/6680 [=====>..] - ETA: 0s - loss: 10.3804
- acc: 0.2831Epoch 00001: val_loss improved from 10.89020 to 10.3072
1, saving model to saved_models/weights.best.VGG16.hdf5

6680/6680 [=====] - 1s - loss: 10.3795 - ac
c: 0.2832 - val_loss: 10.3072 - val_acc: 0.2790

Epoch 3/20
6500/6680 [=====>.] - ETA: 0s - loss: 9.9269
- acc: 0.3371 Epoch 00002: val_loss improved from 10.30721 to 10.06816, saving model to saved_models/weights.best.VGG16.hdf5
6680/6680 [=====] - 1s - loss: 9.9328 - acc: 0.3370 - val_loss: 10.0682 - val_acc: 0.3090
Epoch 4/20
6560/6680 [=====>.] - ETA: 0s - loss: 9.7429
- acc: 0.3598 Epoch 00003: val_loss improved from 10.06816 to 9.93531, saving model to saved_models/weights.best.VGG16.hdf5
6680/6680 [=====] - 1s - loss: 9.7416 - acc: 0.3596 - val_loss: 9.9353 - val_acc: 0.3222
Epoch 5/20
6600/6680 [=====>.] - ETA: 0s - loss: 9.5801
- acc: 0.3756 Epoch 00004: val_loss improved from 9.93531 to 9.85794, saving model to saved_models/weights.best.VGG16.hdf5
6680/6680 [=====] - 1s - loss: 9.5541 - acc: 0.3768 - val_loss: 9.8579 - val_acc: 0.3246
Epoch 6/20
6540/6680 [=====>.] - ETA: 0s - loss: 9.4116
- acc: 0.3881 Epoch 00005: val_loss improved from 9.85794 to 9.85533, saving model to saved_models/weights.best.VGG16.hdf5
6680/6680 [=====] - 1s - loss: 9.3929 - acc: 0.3894 - val_loss: 9.8553 - val_acc: 0.3246
Epoch 7/20
6640/6680 [=====>.] - ETA: 0s - loss: 9.2642
- acc: 0.4063 Epoch 00006: val_loss improved from 9.85533 to 9.66584, saving model to saved_models/weights.best.VGG16.hdf5
6680/6680 [=====] - 1s - loss: 9.2692 - acc: 0.4060 - val_loss: 9.6658 - val_acc: 0.3401
Epoch 8/20
6380/6680 [=====>..] - ETA: 0s - loss: 9.2371
- acc: 0.4138 Epoch 00007: val_loss improved from 9.66584 to 9.56307, saving model to saved_models/weights.best.VGG16.hdf5
6680/6680 [=====] - 1s - loss: 9.2135 - acc: 0.4147 - val_loss: 9.5631 - val_acc: 0.3437
Epoch 9/20
6500/6680 [=====>.] - ETA: 0s - loss: 9.1327
- acc: 0.4185 Epoch 00008: val_loss improved from 9.56307 to 9.50899, saving model to saved_models/weights.best.VGG16.hdf5
6680/6680 [=====] - 1s - loss: 9.1083 - acc: 0.4195 - val_loss: 9.5090 - val_acc: 0.3557
Epoch 10/20
6400/6680 [=====>..] - ETA: 0s - loss: 8.8871
- acc: 0.4241 Epoch 00009: val_loss improved from 9.50899 to 9.32161, saving model to saved_models/weights.best.VGG16.hdf5
6680/6680 [=====] - 1s - loss: 8.8951 - acc: 0.4237 - val_loss: 9.3216 - val_acc: 0.3557
Epoch 11/20
6540/6680 [=====>.] - ETA: 0s - loss: 8.7253
- acc: 0.4420 Epoch 00010: val_loss improved from 9.32161 to 9.14491, saving model to saved_models/weights.best.VGG16.hdf5
6680/6680 [=====] - 1s - loss: 8.7343 - acc:

```
: 0.4413 - val_loss: 9.1449 - val_acc: 0.3701
Epoch 12/20
6460/6680 [=====>.] - ETA: 0s - loss: 8.6963
- acc: 0.4508 Epoch 00011: val_loss did not improve
6680/6680 [=====] - 1s - loss: 8.6816 - acc
: 0.4512 - val_loss: 9.1711 - val_acc: 0.3725
Epoch 13/20
6580/6680 [=====>.] - ETA: 0s - loss: 8.6667
- acc: 0.4535 Epoch 00012: val_loss improved from 9.14491 to 9.10635,
saving model to saved_models/weights.best.VGG16.hdf5
6680/6680 [=====] - 1s - loss: 8.6568 - acc
: 0.4540 - val_loss: 9.1064 - val_acc: 0.3796
Epoch 14/20
6640/6680 [=====>.] - ETA: 0s - loss: 8.5903
- acc: 0.4602 Epoch 00013: val_loss did not improve
6680/6680 [=====] - 1s - loss: 8.6020 - acc
: 0.4594 - val_loss: 9.1365 - val_acc: 0.3832
Epoch 15/20
6560/6680 [=====>.] - ETA: 0s - loss: 8.5796
- acc: 0.4619 Epoch 00014: val_loss did not improve
6680/6680 [=====] - 1s - loss: 8.5902 - acc
: 0.4612 - val_loss: 9.1680 - val_acc: 0.3737
Epoch 16/20
6620/6680 [=====>.] - ETA: 0s - loss: 8.5824
- acc: 0.4625 Epoch 00015: val_loss did not improve
6680/6680 [=====] - 1s - loss: 8.5607 - acc
: 0.4638 - val_loss: 9.2143 - val_acc: 0.3725
Epoch 17/20
6540/6680 [=====>.] - ETA: 0s - loss: 8.4340
- acc: 0.4631 Epoch 00016: val_loss improved from 9.10635 to 8.98615,
saving model to saved_models/weights.best.VGG16.hdf5
6680/6680 [=====] - 1s - loss: 8.4282 - acc
: 0.4635 - val_loss: 8.9862 - val_acc: 0.3737
Epoch 18/20
6560/6680 [=====>.] - ETA: 0s - loss: 8.3225
- acc: 0.4727 Epoch 00017: val_loss improved from 8.98615 to 8.87812
, saving model to saved_models/weights.best.VGG16.hdf5
6680/6680 [=====] - 1s - loss: 8.3161 - acc
: 0.4732 - val_loss: 8.8781 - val_acc: 0.3952
Epoch 19/20
6420/6680 [=====>..] - ETA: 0s - loss: 8.1671
- acc: 0.4807 Epoch 00018: val_loss did not improve
6680/6680 [=====] - 1s - loss: 8.1873 - acc
: 0.4790 - val_loss: 8.9183 - val_acc: 0.3820
Epoch 20/20
6480/6680 [=====>.] - ETA: 0s - loss: 8.1247
- acc: 0.4877 Epoch 00019: val_loss improved from 8.87812 to 8.80235,
saving model to saved_models/weights.best.VGG16.hdf5
6680/6680 [=====] - 1s - loss: 8.1229 - acc
: 0.4880 - val_loss: 8.8024 - val_acc: 0.3952
```

```
Out[21]: <keras.callbacks.History at 0x12996ed68>
```

Load the Model with the Best Validation Loss

```
In [22]: VGG16_model.load_weights('saved_models/weights.best.VGG16.hdf5')
```

Test the Model

Now, we can use the CNN to test how well it identifies breed within our test dataset of dog images. We print the test accuracy below.

```
In [23]: # get index of predicted dog breed for each image in test set
VGG16_predictions = [np.argmax(VGG16_model.predict(np.expand_dims(feature, axis=0))) for feature in test_VGG16]

# report test accuracy
test_accuracy = 100*np.sum(np.array(VGG16_predictions)==np.argmax(test_targets, axis=1))/len(VGG16_predictions)
print('Test accuracy: %.4f%' % test_accuracy)
```

```
Test accuracy: 40.6699%
```

Predict Dog Breed with the Model

```
In [24]: from extract_bottleneck_features import *

def VGG16_predict_breed(img_path):
    # extract bottleneck features
    bottleneck_feature = extract_VGG16(path_to_tensor(img_path))
    # obtain predicted vector
    predicted_vector = VGG16_model.predict(bottleneck_feature)
    # return dog breed that is predicted by the model
    return dog_names[np.argmax(predicted_vector)]
```

Step 5: Create a CNN to Classify Dog Breeds (using Transfer Learning)

You will now use transfer learning to create a CNN that can identify dog breed from images. Your CNN must attain at least 60% accuracy on the test set.

In Step 4, we used transfer learning to create a CNN using VGG-16 bottleneck features. In this section, you must use the bottleneck features from a different pre-trained model. To make things easier for you, we have pre-computed the features for all of the networks that are currently available in Keras:

- [VGG-19 \(https://s3-us-west-1.amazonaws.com/udacity-aind/dog-project/DogVGG19Data.npz\)](https://s3-us-west-1.amazonaws.com/udacity-aind/dog-project/DogVGG19Data.npz) bottleneck features
- [ResNet-50 \(https://s3-us-west-1.amazonaws.com/udacity-aind/dog-project/DogResnet50Data.npz\)](https://s3-us-west-1.amazonaws.com/udacity-aind/dog-project/DogResnet50Data.npz) bottleneck features
- [Inception \(https://s3-us-west-1.amazonaws.com/udacity-aind/dog-project/DogInceptionV3Data.npz\)](https://s3-us-west-1.amazonaws.com/udacity-aind/dog-project/DogInceptionV3Data.npz) bottleneck features
- [Xception \(https://s3-us-west-1.amazonaws.com/udacity-aind/dog-project/DogXceptionData.npz\)](https://s3-us-west-1.amazonaws.com/udacity-aind/dog-project/DogXceptionData.npz) bottleneck features

The files are encoded as such:

```
Dog{network}Data.npz
```

where {network}, in the above filename, can be one of VGG19, Resnet50, InceptionV3, or Xception. Pick one of the above architectures, download the corresponding bottleneck features, and store the downloaded file in the `bottleneck_features/` folder in the repository.

(IMPLEMENTATION) Obtain Bottleneck Features

In the code block below, extract the bottleneck features corresponding to the train, test, and validation sets by running the following:

```
bottleneck_features = np.load('bottleneck_features/Dog{network}Data.npz')
train_{network} = bottleneck_features['train']
valid_{network} = bottleneck_features['valid']
test_{network} = bottleneck_features['test']
```

```
In [25]: ### TODO: Obtain bottleneck features from another pre-trained CNN.
bottleneck_features = np.load('bottleneck_features/DogResnet50Data.npz')
train_Resnet50 = bottleneck_features['train']
valid_Resnet50 = bottleneck_features['valid']
test_Resnet50 = bottleneck_features['test']
```

(IMPLEMENTATION) Model Architecture

Create a CNN to classify dog breed. At the end of your code cell block, summarize the layers of your model by executing the line:

```
<your model's name>.summary()
```

Question 5: Outline the steps you took to get to your final CNN architecture and your reasoning at each step. Describe why you think the architecture is suitable for the current problem.

Answer: I just took the information from the pre-trained CNN and applied a GAP and a dense (fully connected) layer as suggested on the videos. Basically I took the last 2 steps from the hinted CNN (from Scratch) (Step 3) and feed them with this a pre-trained CNN = transfer learning.

```
In [26]: ### TODO: Define your architecture.
Resnet50_model = Sequential()
Resnet50_model.add(GlobalAveragePooling2D(input_shape=train_Resnet50.s
hape[1:]))
Resnet50_model.add(Dense(133, activation='softmax'))

Resnet50_model.summary()
```

Layer (type)	Output Shape	Param #
=====		
global_average_pooling2d_2 ((None, 2048)	0
=====		
dense_4 (Dense)	(None, 133)	272517
=====		
Total params: 272,517.0		
Trainable params: 272,517.0		
Non-trainable params: 0.0		
=====		

(IMPLEMENTATION) Compile the Model


```
In [27]: ### TODO: Compile the model.
Resnet50_model.compile(loss='categorical_crossentropy', optimizer='rms
prop', metrics=['accuracy'])
```

(IMPLEMENTATION) Train the Model

Train your model in the code cell below. Use model checkpointing to save the model that attains the best validation loss.

You are welcome to [augment the training data \(https://blog.keras.io/building-powerful-image-classification-models-using-very-little-data.html\)](https://blog.keras.io/building-powerful-image-classification-models-using-very-little-data.html), but this is not a requirement.

```
In [28]: ### TODO: Train the model.

checkpointer = ModelCheckpoint(filepath='saved_models/weights.best.Res
net50.hdf5',
                                verbose=1, save_best_only=True)

Resnet50_model.fit(train_Resnet50, train_targets,
                    validation_data=(valid_Resnet50, valid_targets),
                    epochs=20, batch_size=20, callbacks=[checker], verbose=
1)
```

Train on 6680 samples, validate on 835 samples

Epoch 1/20

6620/6680 [=====>.] - ETA: 0s - loss: 1.6415
- acc: 0.5899 Epoch 00000: val_loss improved from inf to 0.8205
2, saving model to saved_models/weights.best.Resnet50.hdf5

6680/6680 [=====] - 2s - loss: 1.6328 - acc
: 0.5925 - val_loss: 0.8205 - val_acc: 0.7461

Epoch 2/20

6500/6680 [=====>.] - ETA: 0s - loss: 0.4420
- acc: 0.8635 Epoch 00001: val_loss improved from 0.82052 to 0.68167,
saving model to saved_models/weights.best.Resnet50.hdf5

6680/6680 [=====] - 1s - loss: 0.4431 - acc
: 0.8630 - val_loss: 0.6817 - val_acc: 0.7856

Epoch 3/20

6640/6680 [=====>.] - ETA: 0s - loss: 0.2714
- acc: 0.9145 Epoch 00002: val_loss improved from 0.68167 to 0.65090,
saving model to saved_models/weights.best.Resnet50.hdf5

6680/6680 [=====] - 1s - loss: 0.2710 - acc
: 0.9147 - val_loss: 0.6509 - val_acc: 0.7976

Epoch 4/20

6500/6680 [=====>.] - ETA: 0s - loss: 0.1729
- acc: 0.9472 Epoch 00003: val_loss did not improve

6680/6680 [=====] - 1s - loss: 0.1726 - acc
: 0.9472 - val_loss: 0.7219 - val_acc: 0.8048

Epoch 5/20

6480/6680 [=====>.] - ETA: 0s - loss: 0.1248
- acc: 0.9627 Epoch 00004: val_loss did not improve

```
6680/6680 [=====] - 1s - loss: 0.1240 - acc
: 0.9626 - val_loss: 0.6544 - val_acc: 0.8120
Epoch 6/20
6520/6680 [=====>.] - ETA: 0s - loss: 0.0869
- acc: 0.9732Epoch 00005: val_loss did not improve
6680/6680 [=====] - 1s - loss: 0.0901 - acc
: 0.9719 - val_loss: 0.6790 - val_acc: 0.8156
Epoch 7/20
6560/6680 [=====>.] - ETA: 0s - loss: 0.0684
- acc: 0.9816Epoch 00006: val_loss did not improve
6680/6680 [=====] - 1s - loss: 0.0698 - acc
: 0.9808 - val_loss: 0.6949 - val_acc: 0.8156
Epoch 8/20
6540/6680 [=====>.] - ETA: 0s - loss: 0.0511
- acc: 0.9839Epoch 00007: val_loss did not improve
6680/6680 [=====] - 1s - loss: 0.0516 - acc
: 0.9840 - val_loss: 0.7169 - val_acc: 0.8120
Epoch 9/20
6660/6680 [=====>.] - ETA: 0s - loss: 0.0388
- acc: 0.9887Epoch 00008: val_loss did not improve
6680/6680 [=====] - 1s - loss: 0.0390 - acc
: 0.9886 - val_loss: 0.7152 - val_acc: 0.8359
Epoch 10/20
6600/6680 [=====>.] - ETA: 0s - loss: 0.0289
- acc: 0.9920Epoch 00009: val_loss did not improve
6680/6680 [=====] - 1s - loss: 0.0289 - acc
: 0.9919 - val_loss: 0.6909 - val_acc: 0.8311
Epoch 11/20
6660/6680 [=====>.] - ETA: 0s - loss: 0.0237
- acc: 0.9932Epoch 00010: val_loss did not improve
6680/6680 [=====] - 1s - loss: 0.0237 - acc
: 0.9933 - val_loss: 0.7760 - val_acc: 0.8156
Epoch 12/20
6540/6680 [=====>.] - ETA: 0s - loss: 0.0184
- acc: 0.9960Epoch 00011: val_loss did not improve
6680/6680 [=====] - 1s - loss: 0.0181 - acc
: 0.9961 - val_loss: 0.7824 - val_acc: 0.8263
Epoch 13/20
6440/6680 [=====>..] - ETA: 0s - loss: 0.0144
- acc: 0.9970 - ETA: 1s - loss: 0.0217 - acc: 0.9962Epoch 00012:
val_loss did not improve
6680/6680 [=====] - 1s - loss: 0.0149 - acc
: 0.9970 - val_loss: 0.7606 - val_acc: 0.8240
Epoch 14/20
6540/6680 [=====>.] - ETA: 0s - loss: 0.0137
- acc: 0.9968Epoch 00013: val_loss did not improve
6680/6680 [=====] - 1s - loss: 0.0135 - acc
: 0.9969 - val_loss: 0.7828 - val_acc: 0.8251
Epoch 15/20
6500/6680 [=====>.] - ETA: 0s - loss: 0.0114
- acc: 0.9974Epoch 00014: val_loss did not improve
6680/6680 [=====] - 2s - loss: 0.0112 - acc
: 0.9975 - val_loss: 0.8801 - val_acc: 0.8204
```

```

Epoch 16/20
6560/6680 [=====>.] - ETA: 0s - loss: 0.0095
- acc: 0.9976      Epoch 00015: val_loss did not improve
6680/6680 [=====] - 1s - loss: 0.0094 - acc
: 0.9976 - val_loss: 0.8383 - val_acc: 0.8216
Epoch 17/20
6580/6680 [=====>.] - ETA: 0s - loss: 0.0093
- acc: 0.9983      Epoch 00016: val_loss did not improve
6680/6680 [=====] - 1s - loss: 0.0097 - acc
: 0.9982 - val_loss: 0.8909 - val_acc: 0.8263
Epoch 18/20
6640/6680 [=====>.] - ETA: 0s - loss: 0.0077
- acc: 0.9983      Epoch 00017: val_loss did not improve
6680/6680 [=====] - 1s - loss: 0.0077 - acc
: 0.9984 - val_loss: 0.8585 - val_acc: 0.8299
Epoch 19/20
6620/6680 [=====>.] - ETA: 0s - loss: 0.0065
- acc: 0.9983      Epoch 00018: val_loss did not improve
6680/6680 [=====] - 1s - loss: 0.0064 - acc
: 0.9984 - val_loss: 0.9326 - val_acc: 0.8216
Epoch 20/20
6620/6680 [=====>.] - ETA: 0s - loss: 0.0064
- acc: 0.9986      Epoch 00019: val_loss did not improve
6680/6680 [=====] - 1s - loss: 0.0064 - acc
: 0.9987 - val_loss: 0.9604 - val_acc: 0.8204

```

```
Out[28]: <keras.callbacks.History at 0x120215f98>
```

(IMPLEMENTATION) Load the Model with the Best Validation Loss

```
In [29]: ### TODO: Load the model weights with the best validation loss.
Resnet50_model.load_weights('saved_models/weights.best.Resnet50.hdf5')
```

(IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Ensure that your test accuracy is greater than 60%.

```
In [30]: ### TODO: Calculate classification accuracy on the test dataset.

# get index of predicted dog breed for each image in test set
Resnet50_predictions = [np.argmax(Resnet50_model.predict(np.expand_dims(feature, axis=0))) for feature in test_Resnet50]

# report test accuracy
test_accuracy = 100*np.sum(np.array(Resnet50_predictions)==np.argmax(test_targets, axis=1))/len(Resnet50_predictions)
print('Test accuracy: %.4f%%' % test_accuracy)

Test accuracy: 79.9043%
```

(IMPLEMENTATION) Predict Dog Breed with the Model

Write a function that takes an image path as input and returns the dog breed (Affenpinscher, Afghan_hound, etc) that is predicted by your model.

Similar to the analogous function in Step 5, your function should have three steps:

1. Extract the bottleneck features corresponding to the chosen CNN model.
2. Supply the bottleneck features as input to the model to return the predicted vector. Note that the argmax of this prediction vector gives the index of the predicted dog breed.
3. Use the dog_names array defined in Step 0 of this notebook to return the corresponding breed.

The functions to extract the bottleneck features can be found in `extract_bottleneck_features.py`, and they have been imported in an earlier code cell. To obtain the bottleneck features corresponding to your chosen CNN architecture, you need to use the function

```
extract_{network}
```

where {network}, in the above filename, should be one of VGG19, Resnet50, InceptionV3, or Xception.

```
In [31]: ### TODO: Write a function that takes a path to an image as input
### and returns the dog breed that is predicted by the model.

from extract_bottleneck_features import *

def Resnet50_predict_breed(img_path):
    # extract bottleneck features
    bottleneck_feature = extract_Resnet50(path_to_tensor(img_path))
    # obtain predicted vector
    predicted_vector = Resnet50_model.predict(bottleneck_feature)
    # return dog breed that is predicted by the model
    return dog_names[np.argmax(predicted_vector)]
```

Step 6: Write your Algorithm


Write an algorithm that accepts a file path to an image and first determines whether the image contains a human, dog, or neither. Then,

- if a **dog** is detected in the image, return the predicted breed.
- if a **human** is detected in the image, return the resembling dog breed.
- if **neither** is detected in the image, provide output that indicates an error.

You are welcome to write your own functions for detecting humans and dogs in images, but feel free to use the `face_detector` and `dog_detector` functions developed above. You are **required** to use your CNN from Step 5 to predict dog breed.

Some sample output for our algorithm is provided below, but feel free to design your own user experience!

```
hello, human!
```



```
You look like a ...  
Chinese_shar-pei
```

(IMPLEMENTATION) Write your Algorithm

```
In [32]: ### TODO: Write your algorithm.  
### Feel free to use as many code cells as needed.  
  
def detect(img_path):  
    if face_detector(img_path):  
        print('human like->', Resnet50_predict_breed(img_path))  
    elif dog_detector(img_path):  
        print('dog like->', Resnet50_predict_breed(img_path))  
    else:  
        print('not a human, neither a dog')
```

Step 7: Test Your Algorithm

In this section, you will take your new algorithm for a spin! What kind of dog does the algorithm think that **you** look like? If you have a dog, does it predict your dog's breed accurately? If you have a cat, does it mistakenly think that your cat is a dog?

(IMPLEMENTATION) Test Your Algorithm on Sample Images!

Test your algorithm at least six images on your computer. Feel free to use any images you like. Use at least two human and two dog images.

Question 6: Is the output better than you expected :) ? Or worse :(? Provide at least three possible points of improvement for your algorithm.

Answer: Yes. It's better than I expected. I put myself on the first image and my son in the last 2. The breed detected now matches both of us. :) Impressive.

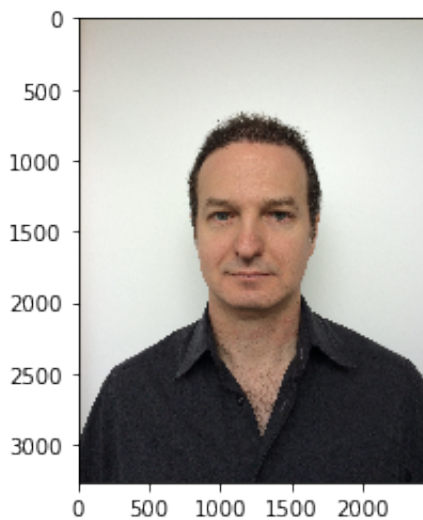
To improve this I think we can do several things:

- 1) Augment the training data: By having more training data or by doing Random Rotations and Translations of my current training data.
- 2) Add more Image detections in the algorithm. (Ex. If we add capacity to detect other common animals it's highly possible we will not be guessing wrongly. Just checking humans and dogs is very limited.)
- 3) Combine breed prediction models. If we have the compute capacity, we can always use more than one model to guess the breed. Right now, my model was based on resnet50, but since you can have several trained models in parallel, I can see that we can improve this just but using different CNN together.

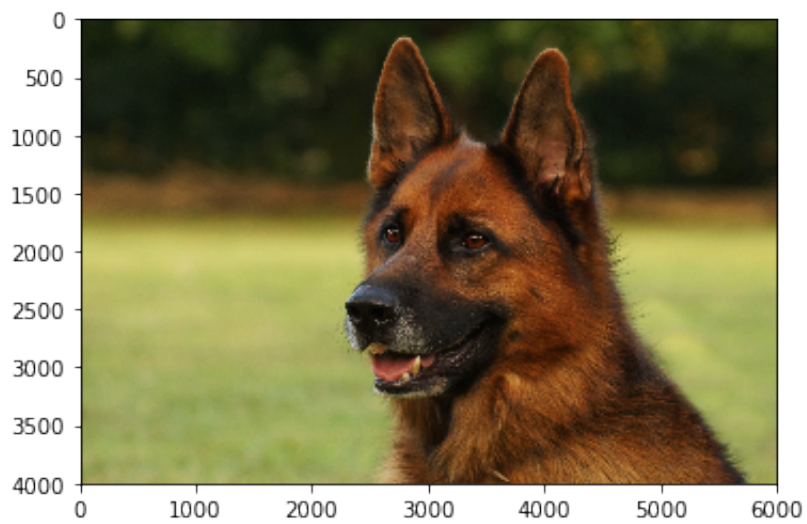
```
In [33]: ## TODO: Execute your algorithm from Step 6 on  
## at least 6 images on your computer.  
## Feel free to use as many code cells as needed.  
import cv2
```

```
#Load the images on the test folder  
test_files = np.array(glob("test/*"))  
  
for test_image in test_files:  
    detect(test_image)  
  
    # load color (BGR) image  
    img = cv2.imread(test_image)  
  
    # convert BGR image to RGB for plotting  
    cv_rgb = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)  
  
    # display the image  
    plt.imshow(cv_rgb)  
    plt.show()
```

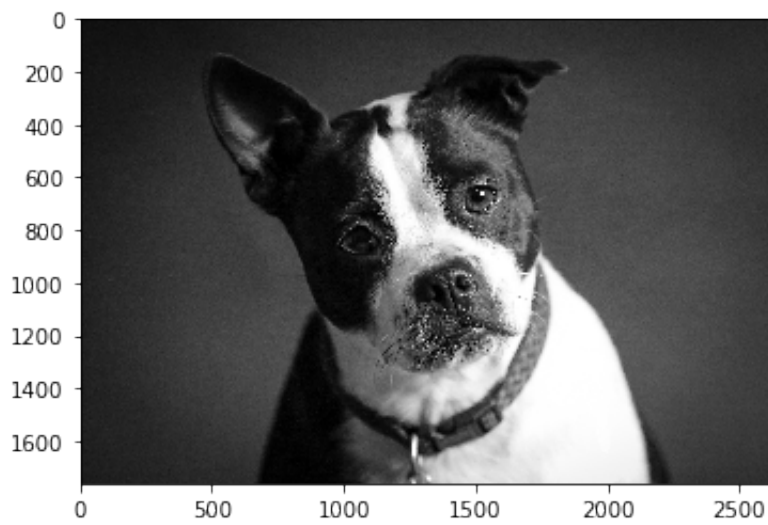
human like-> Greyhound



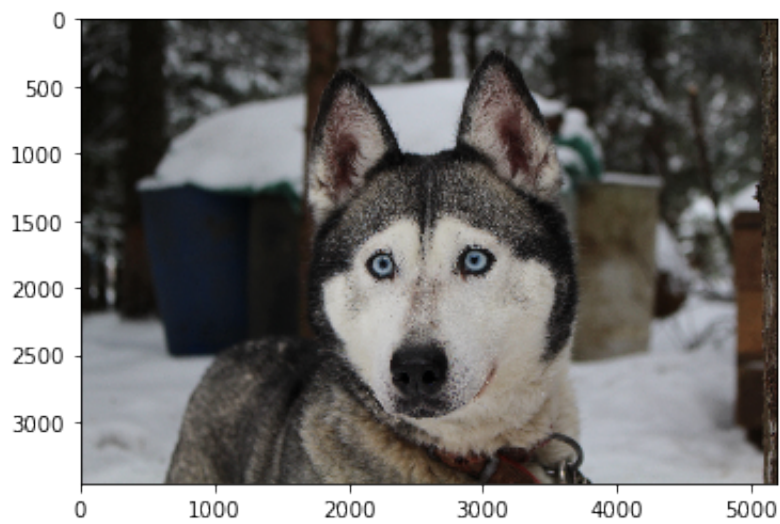
dog like-> German_shepherd_dog



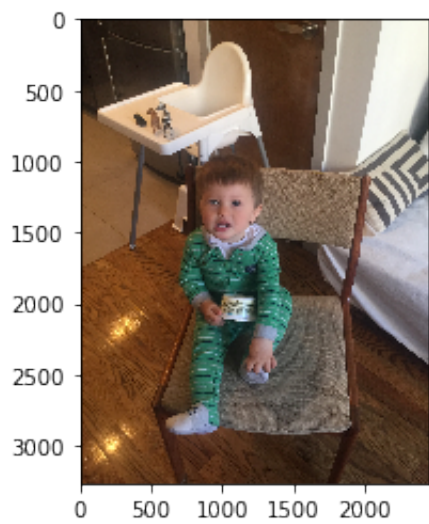
dog like-> Boston_terrier



dog like-> Alaskan_malamute



human like-> Basenji



human like-> Greyhound



In []: