# Key Components for Autonomous Flight



- State Estimation
- Control
- Mapping
- Planning



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estimate the position and velocity (including rotation and angular velocity of the robot)

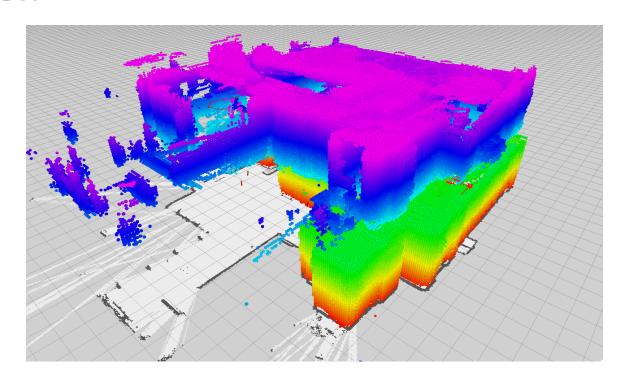


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command motors and produce desired actions in order to navigate to desired state



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