

# Principal Axes and Principal Moments

## *Principal axis of inertia*

$\mathbf{u}$  is a unit vector along a principal axis if  $\mathbf{I} \cdot \mathbf{u}$  is parallel to  $\mathbf{u}$

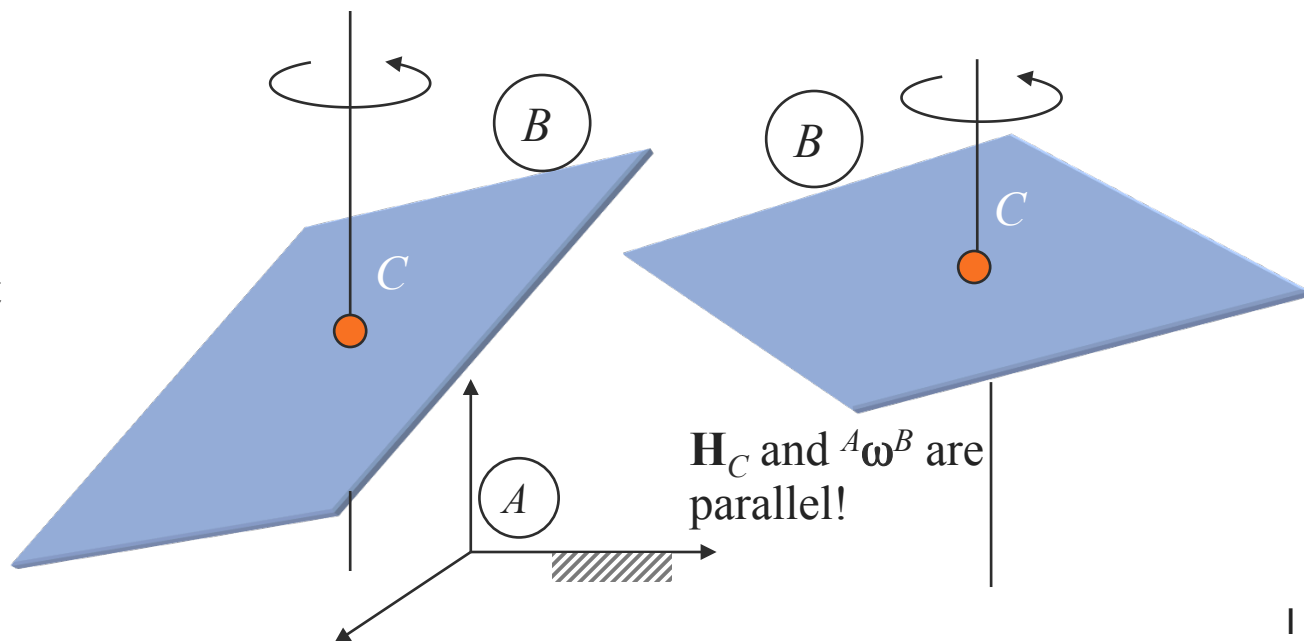
There are 3 independent principal axes!

## *Principal moment of inertia*

The moment of inertia with respect to a principal axis,  $\mathbf{u} \cdot \mathbf{I} \cdot \mathbf{u}$ , is called a principal moment of inertia.

## *Physical interpretation*

$\mathbf{H}_C$  and  ${}^A\boldsymbol{\omega}^B$  are not parallel!



# Euler's Equations

$$\frac{{}^A d\mathbf{H}_C}{dt} = \mathbf{M}_C \quad (1)$$

$$\begin{bmatrix} I_{11} & 0 & 0 \\ 0 & I_{22} & 0 \\ 0 & 0 & I_{33} \end{bmatrix} \begin{bmatrix} \dot{\omega}_1 \\ \dot{\omega}_2 \\ \dot{\omega}_3 \end{bmatrix} + \begin{bmatrix} 0 & -\omega_3 & \omega_2 \\ \omega_3 & 0 & -\omega_1 \\ -\omega_2 & \omega_1 & 0 \end{bmatrix} \begin{bmatrix} I_{11} & 0 & 0 \\ 0 & I_{22} & 0 \\ 0 & 0 & I_{33} \end{bmatrix} \begin{bmatrix} \overset{p}{\omega}_1 \\ \overset{q}{\omega}_2 \\ \overset{r}{\omega}_3 \end{bmatrix} = \begin{bmatrix} M_{C,1} \\ M_{C,2} \\ M_{C,3} \end{bmatrix}$$

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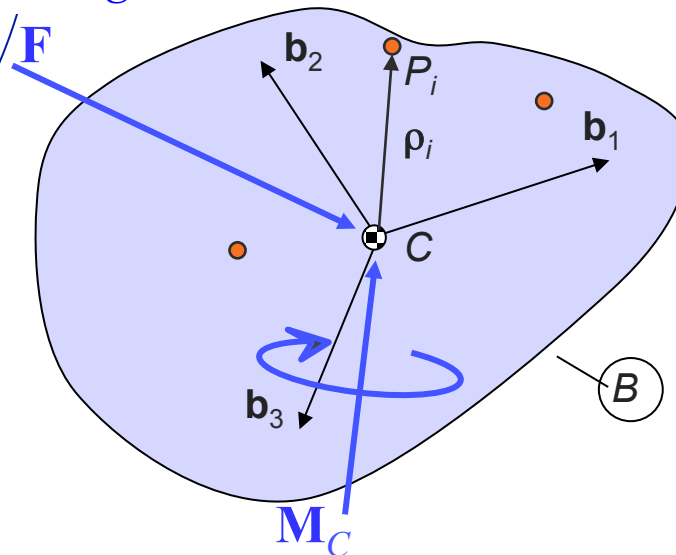
Let  $\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3$  be along principal axes and

$${}^A\boldsymbol{\omega}^B = \omega_1 \mathbf{b}_1 + \omega_2 \mathbf{b}_2 + \omega_3 \mathbf{b}_3$$

$$\frac{{}^B d\mathbf{H}_C}{dt} + {}^A\boldsymbol{\omega}^B \times \mathbf{H}_C = \mathbf{M}_C$$

$$\frac{{}^B d\mathbf{H}_C}{dt} = I_{11}\dot{\omega}_1\mathbf{b}_1 + I_{22}\dot{\omega}_2\mathbf{b}_2 + I_{33}\dot{\omega}_3\mathbf{b}_3$$

*differentiating*



*net external moment*