

turbineTelemetryService

Service Description

Abstract

This document describes the **turbineTelemetryService** service: an Arrowhead service that provides telemetry ingestion, retrieval and basic query capabilities for wind-turbine sensors (vibration, rotor speed, generated power, temperatures, and GPS position). The service is intended for both research/prototyping (e.g. supervised anomaly detection and predictive maintenance experiments) and light-weight operational monitoring within an Arrowhead-compliant system.

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1 Overview

This document describes the **turbineTelemetryService** service. The service enables collection, storage (short-term), and query of telemetry samples produced by sensors attached to a wind turbine. It is intentionally implementation-neutral: it specifies abstract operations and data types that an Arrowhead-compatible provider should expose while leaving storage and transport details to concrete implementations.

Primary use-cases:

- Real-time ingestion of sensor samples from turbine edge gateways.
- Retrieval of the latest telemetry for monitoring dashboards.
- Time-window queries for analytics and model training.
- Lightweight health check (Echo).

The rest of this document is organized as follows. In Section 2, we describe the abstract message operations provided by the service. In Section ??, we present the data types used by the mentioned operations.

1.1 Significant Prior Art

This service is inspired by typical industrial telemetry APIs and cloud telemetry ingestion patterns (message-based ingestion, time-series stores). It aligns with Arrowhead's service registration and discovery patterns and is suitable to integrate with data science experiments such as predictive maintenance models (vibration analysis, anomaly detection) commonly used in academic/industrial projects.

1.2 How This Service Is Meant to Be Used

A typical workflow:

1. A turbine edge gateway registers with the Arrowhead Service Registry and calls the `registerTelemetry` operation to push telemetry samples to the data ingestor.
2. Monitoring dashboards or analytics components call `getSensorData` for live displays.
3. Operators use the `echo` operation to verify liveness of the service.

1.3 Important Delimitations and Dependencies

- This SD defines abstract operations and message formats only. Persistence (time-series database, retention policies) and secure transport (TLS, OAuth2) are implementation details.
 - Integration with Arrowhead Service Registry and Authorization Framework (secure token exchange) is assumed but not mandated at the protocol level.
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2 Service Interface

This section describes the interfaces to the **turbineTelemetryService** service. Each subsection names an abstract operation, an input type and an output type, in that order. Input and output types are only denoted when accepted or returned, respectively, by the interface in question.

All abstract data types named in this section are defined in Section ??.

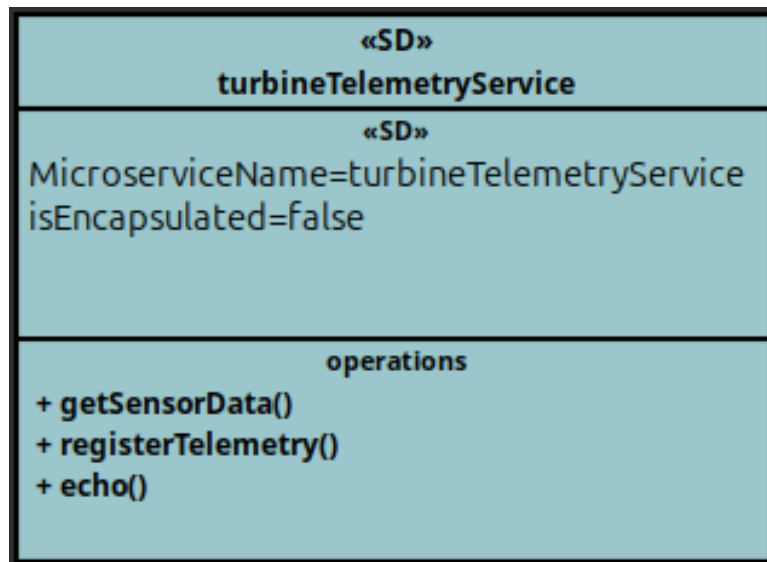


Figure 1: SysML block diagram example showing a monitoring consumer discovering the telemetry service via Arrowhead Service Discovery.

The following interface operations are available.

2.1 operation **registerTelemetry** (**turbineTelemetryService**) : **turbineTelemetryService**

The `registerTelemetry` operation is used by edge gateways or sensor agents to submit one or multiple telemetry samples. A `turbineTelemetryService` contains sensor identifiers, a UTC timestamp and a set of measured values (vibration, rotorSpeed, power, temperature, GPS coordinates, etc.). The service returns a `turbineTelemetryService` indicating acceptance and optionally an ingestion identifier.

2.2 operation **getSensorData** (**turbineTelemetryService**) : **turbineTelemetryService**

The `getSensorData` operation returns the most recent telemetry sample available. This operation is optimized for dashboard updates and health-checks.

2.3 operation **echo** () : **StatusCodeKind**

The `echo` operation provides a simple liveness check. The service returns a standard `StatusCodeKind` indicating OK or an error state.

3 Information Model

This section provides UML activity diagrams describing the behavior of each major operation of the **turbineTelemetryService** service. Each diagram illustrates how the service interacts with Arrowhead core systems and external clients during its execution.

3.1 Service Discovery and Authorization Workflow

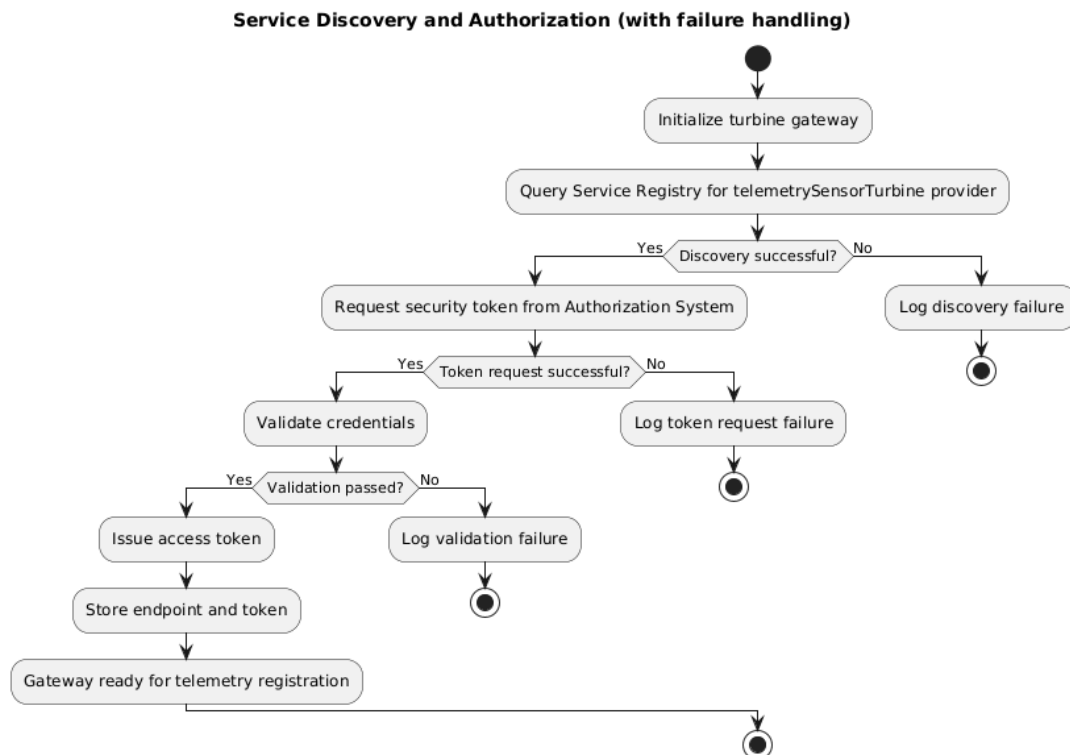


Figure 2: Activity diagram showing service discovery and authorization prior to telemetry transmission.

Swimlanes: *Edge Gateway, Service Registry, Authorization System*

3.2 registerTelemetry Operation

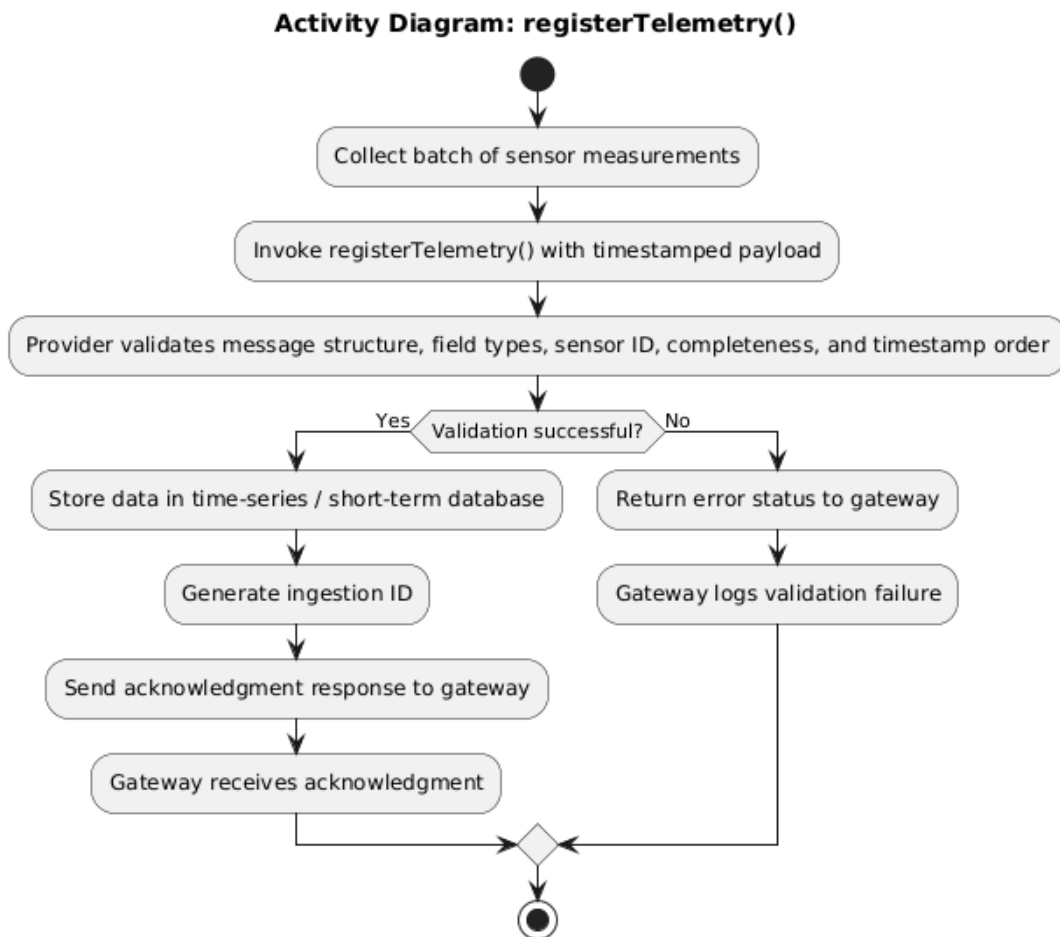


Figure 3: Activity diagram for the `registerTelemetry()` operation.

Swimlanes: *Edge Gateway, Telemetry Provider*

3.3 getSensorData Operation

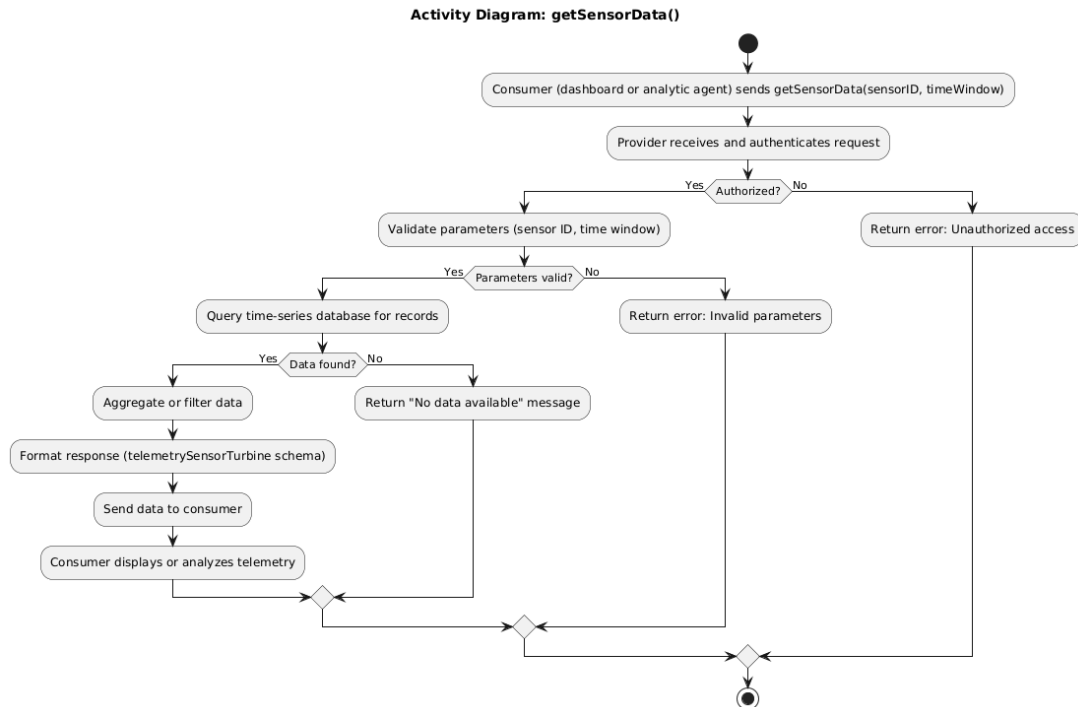


Figure 4: Simplified activity diagram for the `getSensorData()` operation.

Swimlanes: *Consumer (Dashboard/Analytics), Telemetry Provider*

3.4 echo Operation

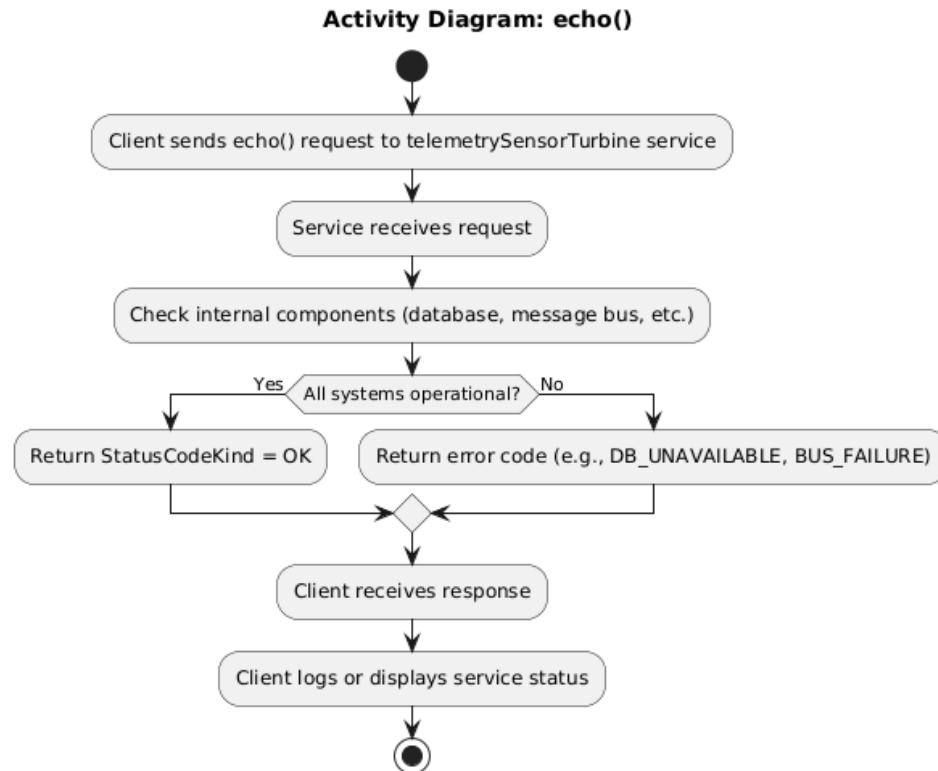


Figure 5: Activity diagram for the `echo()` operation, showing service health verification and status reporting.

Swimlanes: *Any Client, Telemetry Provider*

3.5 Overall Lifecycle Overview

High-Level Activity Diagram: Overall Telemetry Lifecycle

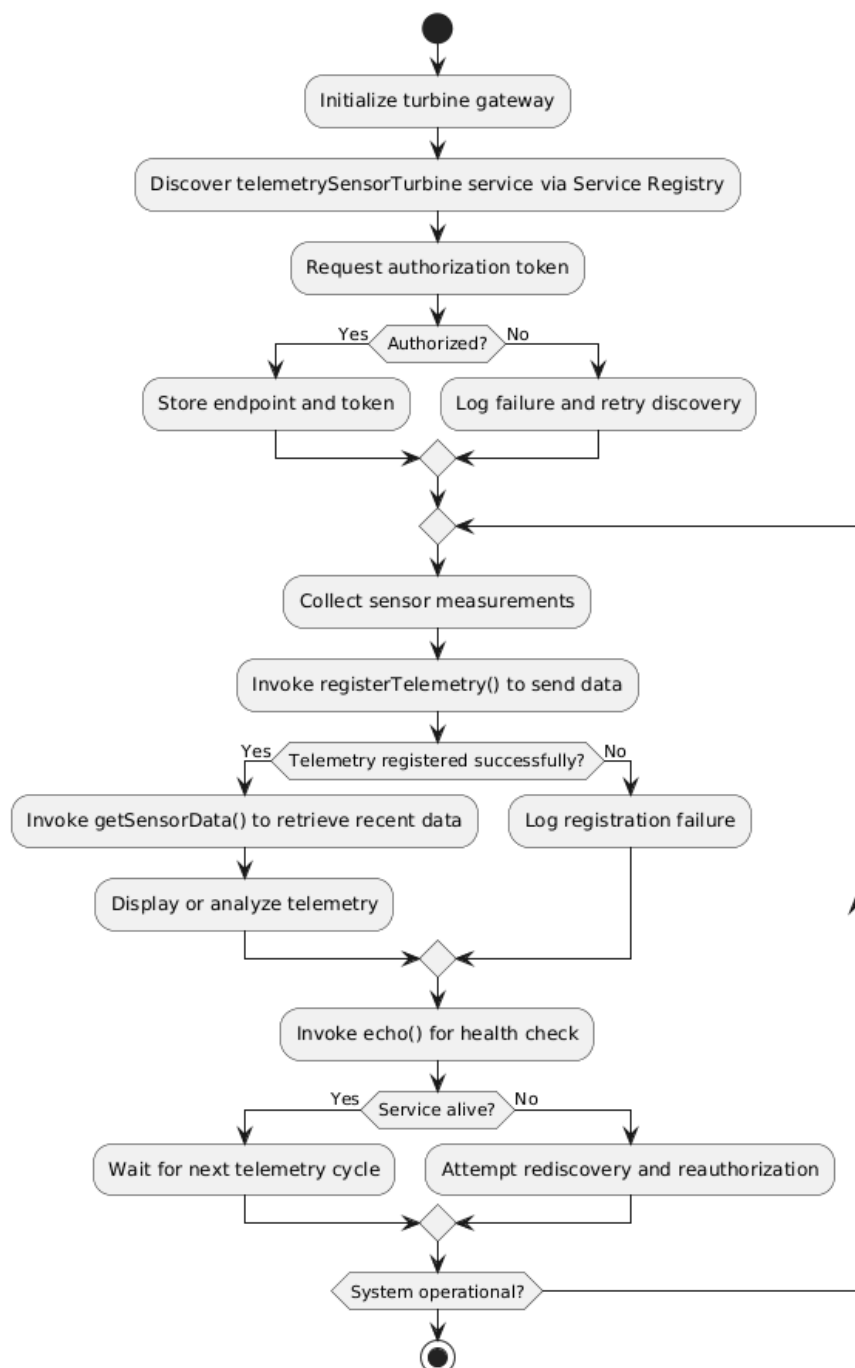


Figure 6: High-level activity diagram summarizing the complete telemetry lifecycle: discovery, authorization, telemetry registration, retrieval, and health-check.