



## BART Webinar #2: Reproducing CG-SENSE

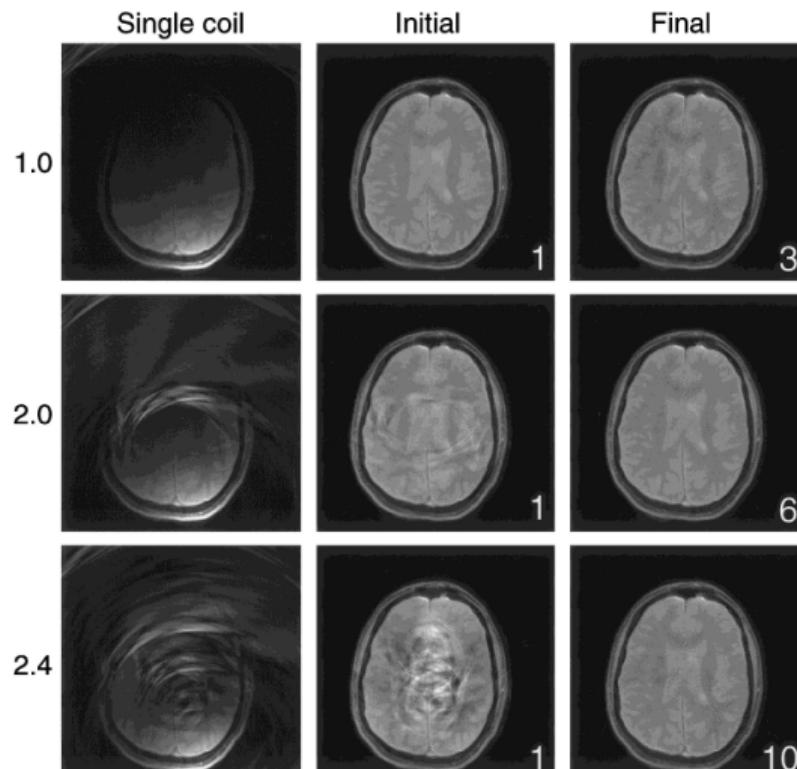
2020-12-02

- Aim: Reproducing Pruessmann et al. “Advances in Sensitivity Encoding With Arbitrary  $k$ -Space Trajectories”, MRM 2001.
- Reproducing this paper was a challenge of the ISMRM Reproducible Research Study Group in 2019, leading to Maier et al. “CG-SENSE revisited: Results from the first ISMRM reproducibility challenge”, MRM 2020.
- This challenge produced many different attempted replications
- We will focus on a reference solution by Oliver Maier

# Intro

BART

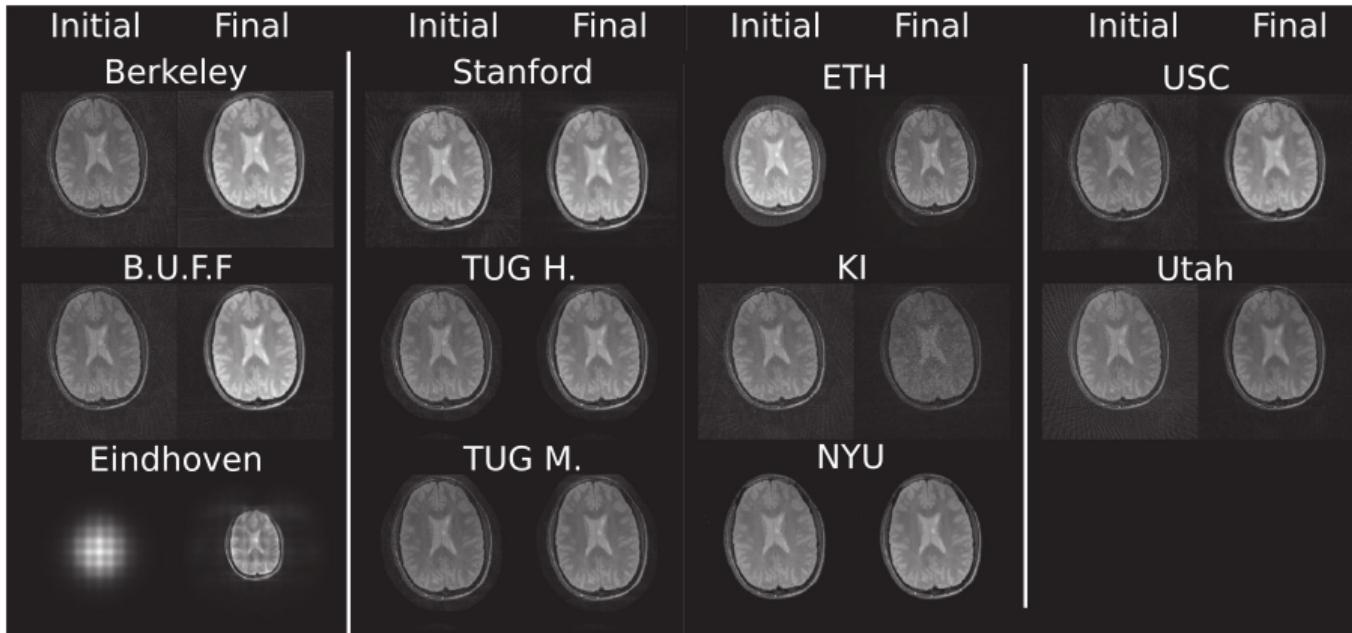
Pruessmann et al. 2001:



# Intro

BART

Different replications (Maier et al. MRM 2020):



# The Challenge



- Pruessmann et al. describes an iterative reconstruction, using the Conjugate Gradient method, solving the SENSE problem (so parallel imaging in image space) for non-Cartesian data
- This can be written as an optimization problem

$$\mathbf{v}^* = \arg \min_{\mathbf{v}} \|\mathbf{Ev} - \mathbf{m}\|_2^2 + \frac{\lambda}{2} \|\mathbf{v}\|_2^2$$

with image  $\mathbf{v}$ , encoding matrix (including coil sensitivity profiles)  $\mathbf{E}$ , measured multi-channel data  $\mathbf{m}$  and Tikhonov regularization factor  $\lambda$ .

- The Conjugate Gradient method can be applied to the normal equation

$$(\mathbf{E}^H \mathbf{E} + \lambda \mathbf{I}) \mathbf{v} = \mathbf{E}^H \mathbf{m}$$

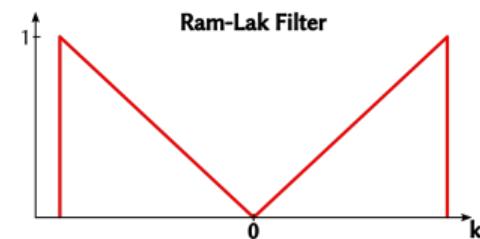
# The Challenge

BART

- $(\mathbf{E}^H \mathbf{E} + \lambda \mathbf{I}) \mathbf{v} = \mathbf{E}^H \mathbf{m}$
- For faster convergence, a density correction  $\mathbf{D}$  is introduced
- Weighs each k-space sample with its spatial density  $\Rightarrow$  for radial sampling, we use a Ram-Lak Filter
- This leads to the normal equation:

$$\begin{aligned} & (\mathbf{E}^H \mathbf{D} \mathbf{E} + \lambda \mathbf{I}) \mathbf{v} = \mathbf{E}^H \mathbf{D} \mathbf{m} \\ \Leftrightarrow & (\mathbf{E}^H \mathbf{D}^{\frac{1}{2}} \mathbf{D}^{\frac{1}{2}} \mathbf{E} + \lambda \mathbf{I}) \mathbf{v} = \mathbf{E}^H \mathbf{D}^{\frac{1}{2}} \mathbf{D}^{\frac{1}{2}} \mathbf{m} \\ \Leftrightarrow & (\bar{\mathbf{E}}^H \bar{\mathbf{E}} + \lambda \mathbf{I}) \mathbf{v} = \bar{\mathbf{E}}^H \mathbf{D}^{\frac{1}{2}} \mathbf{m}, \text{ with } \bar{\mathbf{E}} = \mathbf{D}^{\frac{1}{2}} \mathbf{E} \end{aligned}$$

- (Pruessmann's paper also includes an intensity correction and a k-space filter, which we will exclude here)



# The Challenge



- In the original paper, both radial and spiral sampling are used
- Only radial sampling for the challenge
- Datasets were provided (similar to the original data)
- With that, implement an algorithm and reproduce the main results of the paper

# The Challenge



- So the following is our task:
  1. Convert data to BART's cfl format and to BART's conventions
  2. Undersample to the desired degree (1, 2, 3 and 4)
  3. Calculate the density correction (Ram-Lak filter)
  4. Reconstruct with CG and optional regularization
  - (5. Apply intensity correction)
  - (6. Create plots)

# Data Wrangling



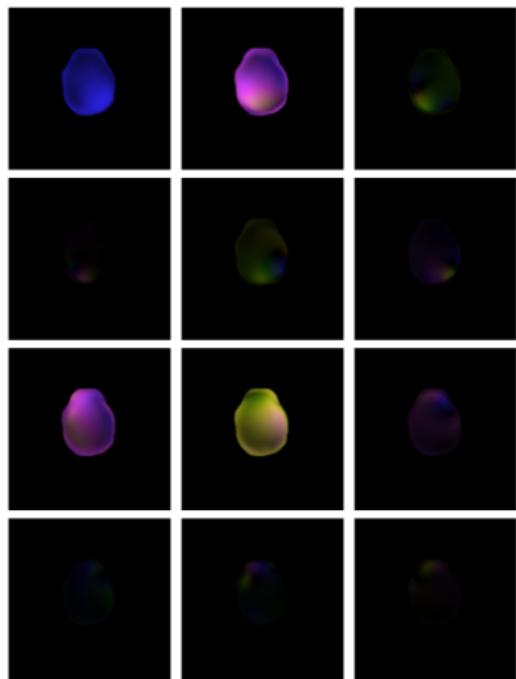
- Raw data can be found on Zenodo <https://zenodo.org/record/3975887>

<a href="#">rawdata_brain_radial_96proj_12ch.h5</a>	53.8 MB	<a href="#">Download</a>
md5:6d52f9fd01c0441f3e680811a6839824 ⓘ		
<a href="#">rawdata_heart_radial_55proj_34ch.h5</a>	150.4 MB	<a href="#">Download</a>
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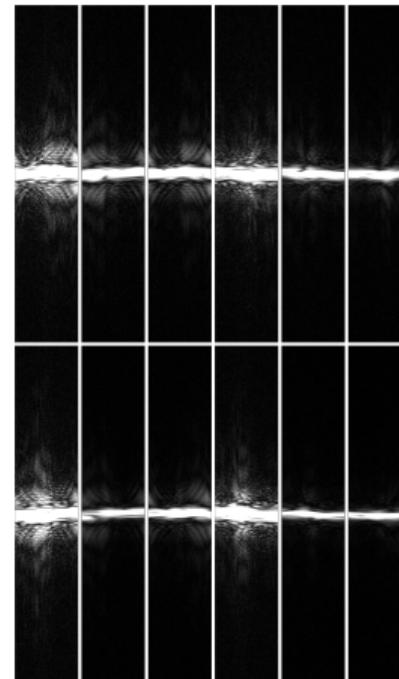
- HDF5 Format containing raw k-space data, trajectory, coil sensitivities, intensity correction maps and a mask
- BART does not (yet) read HDF5
- Fortunately, it can be done in a few lines of python (which will be shown later)

# Data Wrangling

BART



Coil sensitivity profiles

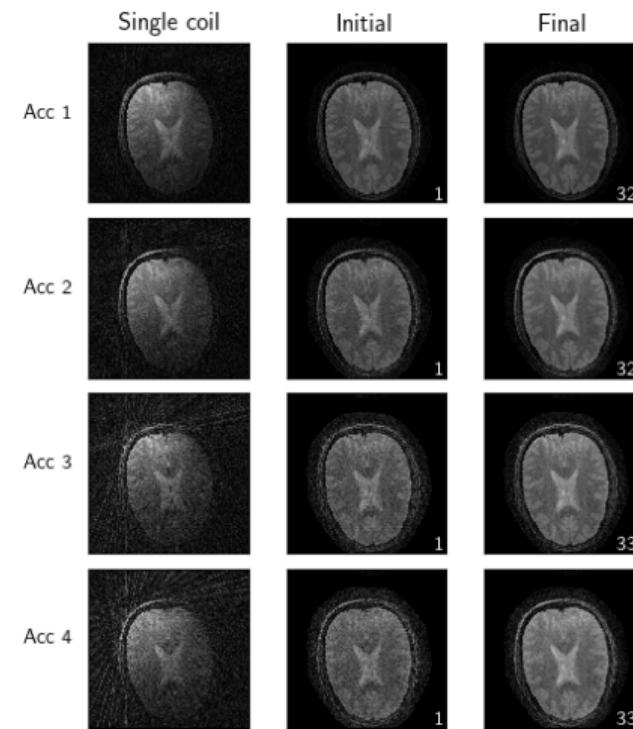
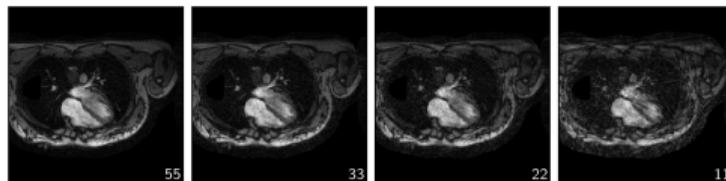


k-space data

# The Challenge: Solution

BART

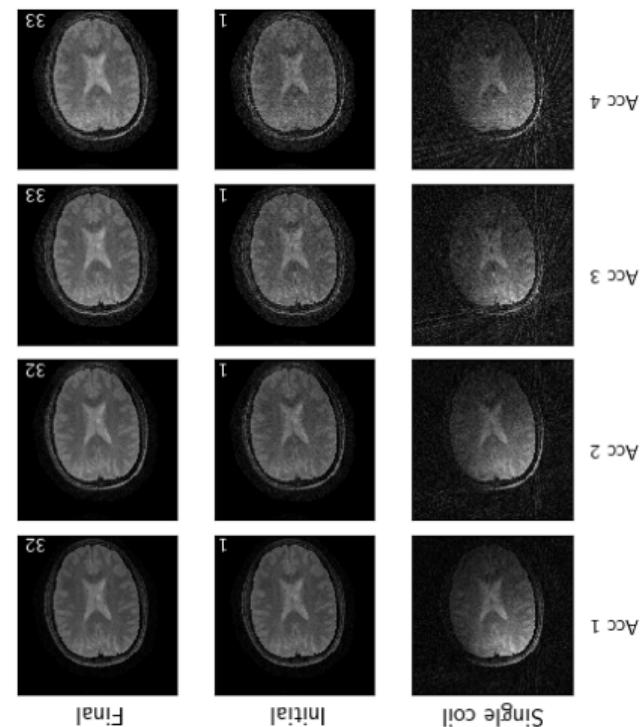
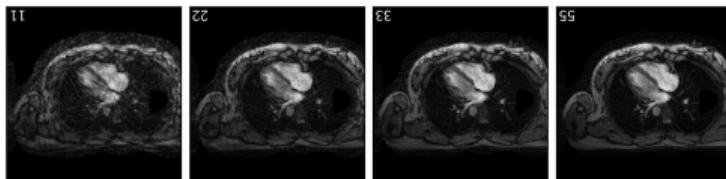
- Oliver Maier's solution looks like this:  
([https://github.com/MaierOli2010/ISMRM\\_RRSG](https://github.com/MaierOli2010/ISMRM_RRSG))



# The Challenge: Solution

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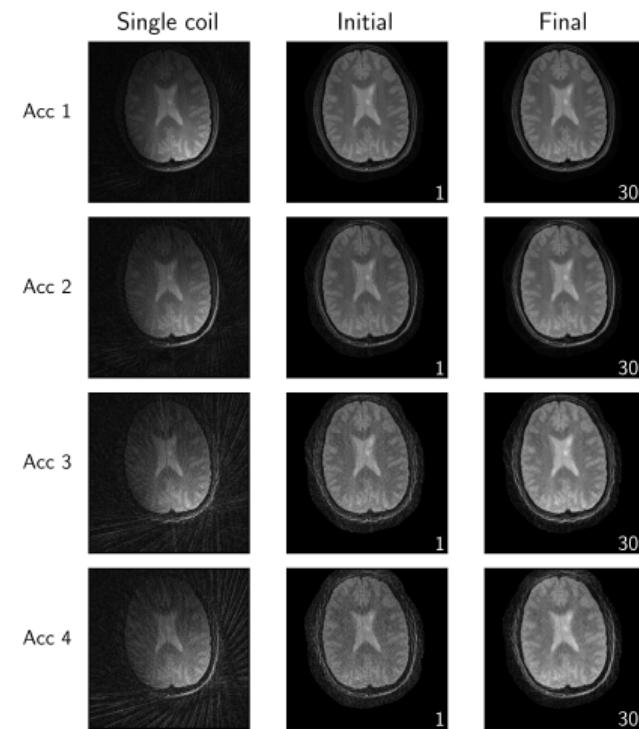
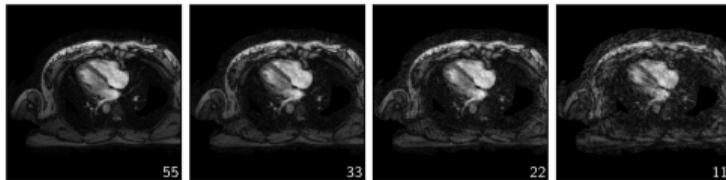
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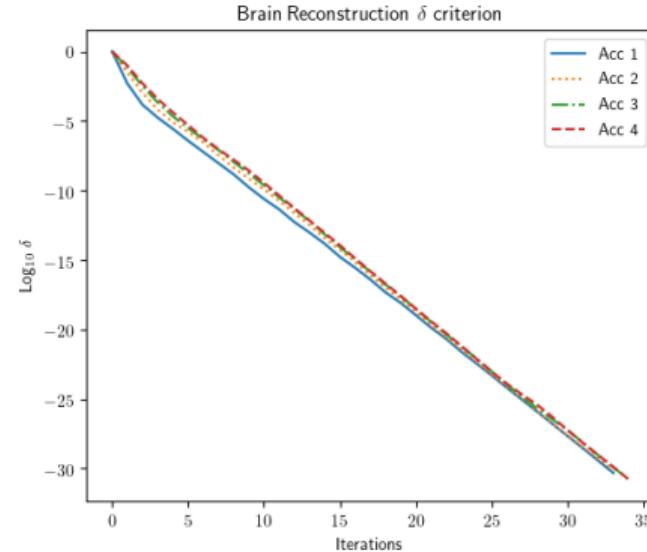
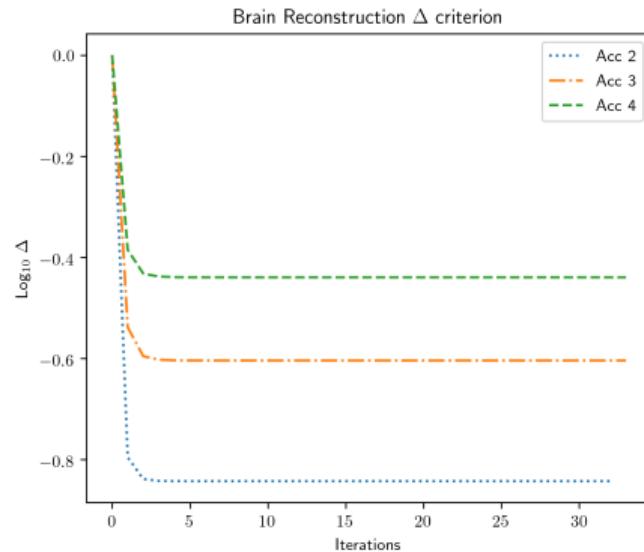
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$\Delta$ : squared normalized root-mean-square error to a ground truth – here to the reconstruction using undersampling 1.

$\delta$ : squared residual of the CG, normalized to the initial residual.