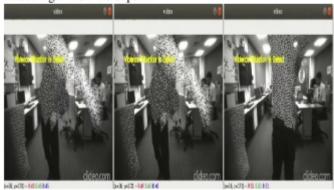
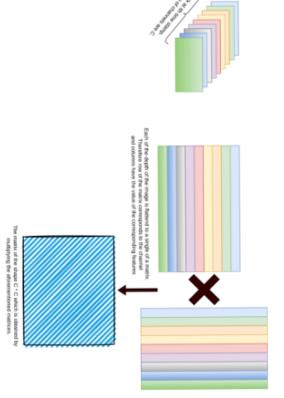




(a) Some Instances where Normal Situation Classified with Robot Ego View Perception





Each of the depth of the image is flattend to a single of a matrix. For the 0th time stamp the transpose of that matrix is taken. Therefore row of the matrix corresponds to the channel and columns have the value of the corresponding features.