Unification Algorithm, Orient and Decompose Cases

CS 421

Revision 1.0

1 Change Log

1.0 Initial Release.

2 Objectives

Your objective for this assignment is to understand the details of the basic algorithm for first order unification.

3 Preliminaries

In MP3 you implemented the first part of the type inferencer for the PicoML language. In this ML you will implement the second step of the inferencer: the unification algorithm *unify* that solves constraints generated by the inferencer. The unifier in MP3 was a black box that gave you the solution when fed the constraints generated by your implementation of the inferencer.

It is recommended that before or in tandem with completing this assignment, you go over lecture notes covering type inference and unification as well as the solution to MP3 to have a good understanding of how types are inferred.

4 Datatypes for Type Inference

Below is some of the code available for your use in the `Common` module. This module includes the following data types to represent the types of PicoML, which you should recognize from MP3:

```
type typeVar = int

type monoTy = TyVar of typeVar | TyConst of (string * monoTy list)
```

You can use `string_of_monoTy` in `Common` to convert your types into a readable concrete syntax for types.

5 Substitutions

In MP3, one of the things we returned was a substitution. Our substitutions have the type `(typeVar * monoTy) list`. The first component of a pair is the index (or "name") of a type variable. The second is the type that should be substituted for that type variable.

In this ML, you were to implement a function `subst_fun` that takes a substitution and return a substitution *function*, a function that takes a type variable as input and returns the replacement type as given by the substitution. (Recall that we are using the the type `int` for type variables, which we give the synonym `typeVar`.) When creating such a function from a substitution (i.e., a list of pairs as described above), if a given type variable does not have an entry in the list, the identity substitution is assumed for that type variable (i.e. the variable is substituted with itself). For instance, the substitution

```
# let phi = [(5, mk_fun_ty bool_ty (TyVar(2)))];;
val phi : (int * monoTy) list =
  [(5, TyConst ("->", [TyConst ("bool", []); TyVar 2]))]
```

is considered to represent the subsitution function

$$\phi(\tau_i) = \begin{cases} \texttt{bool} \to \tau_2 & \text{if } i = 5 \\ \tau_i & \text{otherwise} \end{cases}$$

Throughout this ML you may assume that substitutions we work on are always well-structured: there are no two pairs in a substitution list with the same index.

As described above, your function `subst_fun` should, given a substitution, return the function it represents. This should be a function that takes a `typeVar` and returns a `monoTy`.

```
# let subst_fun s = ...
val subst_fun : (typeVar * monoTy) list -> typeVar -> monoTy = <fun>
# let subst = subst_fun phi;;
val subst : typeVar -> monoTy = <fun>
# subst 1;;
- : monoTy = TyVar 1
# subst 5;;
- : monoTy = TyConst ("->", [TyConst ("bool", []); TyVar 2])
```

We can also *lift* a substitution to operate on types. A substitution ϕ, when lifted, replaces all the type variables occurring in its input type with the corresponding types. In this ML you were to implement a function `monoTy_lift_subst` for lifting substitutions to generic `monoTy`s.

```
# let rec monoTy_lift_subst s = ...
val monoTy_lift_subst : (typeVar * monoTy) list -> monoTy -> monoTy = <fun>
# let lifted_sub = monoTy_lift_subst phi;;
val lifted_sub : monoTy -> monoTy = <fun>
# lifted_sub (TyConst ("->", [TyVar 1; TyVar 5]));;
- : monoTy =
TyConst ("->", [TyVar 1; TyConst ("->", [TyConst ("bool", []); TyVar 2])])
```

6 Unification

The unification algorithm takes a set of pairs of types that are supposed to be equal. A system of constraints looks like the following set

$$\{(s_1, t_1), (s_2, t_2), ..., (s_n, t_n)\}$$

Each pair is called an *equation*. A (lifted) substitution ϕ *solves* an equation (s, t) if $\phi(s) = \phi(t)$. It solves a constraint set if $\phi(s_i) = \phi(t_i)$ for every (s_i, t_i) in the constraint set. The unification algorithm will return a substitution that solves the given constraint set (if a solution exists).

You will remember from lecture that the unification algorithm consists of four transformations. These transformations can be expressed in terms of how an action on the first element of the unification problem affects the remaining elements.

Given a constraint set C

1. If C is empty, return the identity substitution.
2. If C is not empty, pick an equation $(s, t) \in C$. Let C' be $C \setminus \{(s, t)\}$.
   (a) **Delete rule:** If s and t are are equal, discard the pair, and unify C'.

(b) **Orient rule:** If t is a variable, and s is not, then discard (s, t), and unify $\{(t, s)\} \cup C'$.

(c) **Decompose rule:** If $s = \texttt{TyConst}\ (name, [s_1; \ldots; s_n])$ and $t = \texttt{TyConst}\ (name, [t_1; \ldots; t_n])$, then discard (s, t), and unify $C' \cup \bigcup_{i=1}^{n} \{(s_i, t_i)\}$.

(d) **Eliminate rule:** If s is a variable, and s does not occur in t, substitute s with t in C' to get C''. Let ϕ be the substitution resulting from unifying C''. Return ϕ updated with $s \mapsto \phi(t)$.

(e) If none of the above cases apply, it is a unification error (your `unify` function should return the `None` option in this case).

In our system, function, integer, list, etc. types are the terms; `TyVar`s are the variables.

The above description of `unify` requires you to be able to check if a type variable occurs in a type. In the ML, you were to implement the function `occurs : typeVar -> monoTy -> bool`, where the first argument is the integer component of a `TyVar`. the second is the target type expression we are testing, and the output indicates whether the variable occurs within the target.

```
# let rec occurs v ty = ...
val occurs : typeVar -> monoTy -> bool = <fun>
# occurs 0 (TyConst ("->", [TyVar 0; TyVar 0]));;
- : bool = true
# occurs 0 (TyConst ("->", [TyVar 1; TyVar 2]));;
- : bool = false
```

1. Now you are ready to write the orient and decompose cases of the unification function. We will represent constraint sets simply by lists. If there exists a solution to a set of constraints (i.e., a substitution that solves the set), your function should return `Some` of that substitution. Otherwise it should return `None`. Here's a sample run.

```
# let rec unify constraints = ...
val unify : (monoTy * monoTy) list -> substitution option = <fun>
# let Some(subst) =
   unify [(TyVar 0,
           TyConst ("list",
             [TyConst ("int", [])]));
          (TyConst ("->", [TyVar 0; TyVar 0]),
           TyConst ("->", [TyVar 0; TyVar 1]))];;
... (* Warning message suppressed *)
val subst : substitution =
  [(0, TyConst ("list", [TyConst ("int", [])]));
   (1, TyConst ("list", [TyConst ("int", [])]))]
# subst_fun subst 0;;
- : monoTy = TyConst ("list", [TyConst ("int", [])])
# subst_fun subst 1;;
- : monoTy = TyConst ("list", [TyConst ("int", [])])
# subst_fun subst 2;;
- : monoTy = TyVar 2
```

Hint: You will find the functions you implemented in Problems 2,3,4 very useful in some rules.