

Accelerated nested sampling with β -flows

Metha Prathaban
myp23@cam.ac.uk

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- ▶ 3rd year PhD student in Will Handley's group
- ▶ Work on gravitational waves and Bayesian numerical method development
- ▶ Office in K34

The Handley group!



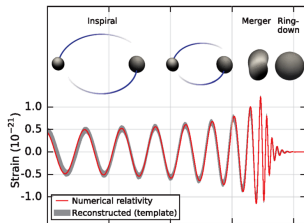
+ Part III students + others!

Current work is in collaboration with Will Handley and Harry Bevins.



Bayes' Theorem for Gravitational Waves

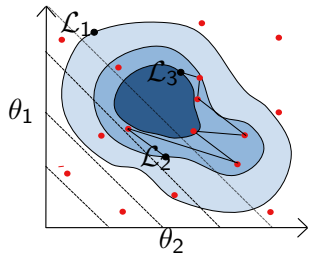
Given some model \mathcal{M} and observed signal \mathcal{D} , Bayes' theorem enables us to relate the posterior probability of the set of parameters θ which generated the signal to the likelihood of the \mathcal{D} given θ and the prior probability of θ given \mathcal{M} :



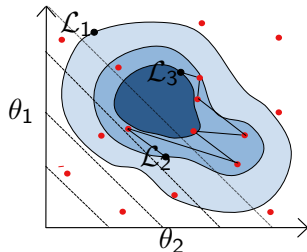
$$P(\theta|\mathcal{D}, \mathcal{M}) = \frac{P(\mathcal{D}|\theta, \mathcal{M})P(\theta|\mathcal{M})}{P(\mathcal{D}|\mathcal{M})} = \frac{\mathcal{L}(\mathcal{D}|\theta)\pi(\theta)}{\mathcal{Z}}$$

Abbott et al.
arXiv:1602.03837

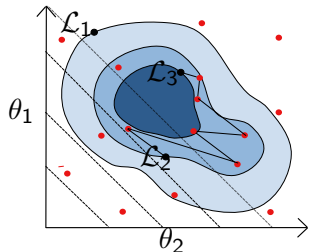
The evidence, \mathcal{Z} , plays a key role in model comparison.



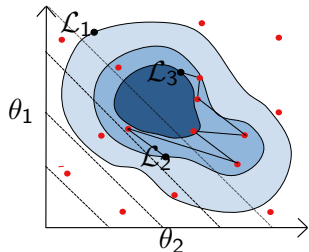
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- ▶ Evidence is calculated as weighted sum over deleted ('dead') points.

Time of convergence of NS

$$T \propto n_{\text{live}} \times T_{\mathcal{L}} \times f_{\text{sampler}} \times D_{\text{KL}} \quad (1)$$

Uncertainty in $\log \mathcal{Z}$

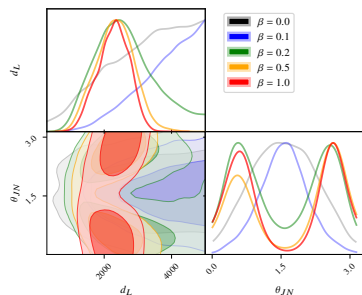
$$\sigma \propto \sqrt{D_{\text{KL}} / n_{\text{live}}} \quad (2)$$

Precision-normalized runtime has quadratic dependence on KL divergence – want to reduce amount of compression from prior to posterior. Petrosyan & Handley 212.01760

- ▶ REACH collaboration do this already (see e.g. [Anstey et al. 2010.09644](#)):
 - ▶ Perform a low-res pass of NS
 - ▶ Identify rough region of posterior and set box prior around this
 - ▶ Full high-res run with narrower prior
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- ▶ **Posterior repartitioning (PR)** (Chen et al. 1803.06387 & 1908.04655) allows one to do this **without needing to correct evidence** (see e.g. Petrosyan & Handley 2212.0176).



- ▶ NFs can perform density estimation of posteriors from NS/other sampling method.
- ▶ Nested sampling gives you a lot more information than just the posterior samples - we have access to samples at every “temperature”.
- ▶ In statistical mechanics, this temperature is used in context of partition function.
- ▶ Idea of β -flows is to explore this arm of NS to learn posterior better.



Thank you for listening!

Unlike other sampling algorithms, such as Metropolis-Hastings or Hamiltonian Monte Carlo, NS distinguishes between \mathcal{L} and π by 'sampling from the prior, subject to the hard likelihood constraint, \mathcal{L} '.

But evidence and posteriors only depend on product of \mathcal{L} and π :

$$\mathcal{Z} = \int \mathcal{L}(\theta)\pi(\theta)d\theta \quad (3)$$

$$\mathcal{P}(\theta) = \frac{\mathcal{L}(\theta)\pi(\theta)}{\mathcal{Z}} \quad (4)$$

Therefore, we are free to redefine the likelihood and prior however we like - as long as the product is the same! [arXiv:1908.04655](https://arxiv.org/abs/1908.04655)

$$\tilde{\mathcal{Z}} = \int \tilde{\mathcal{L}}(\theta)\tilde{\pi}(\theta)d\theta = \int \mathcal{L}(\theta)\pi(\theta)d\theta = \mathcal{Z} \quad (5)$$