

## **Vibrational Motion**

### **Equilibrium Position**

The position at which a vibrating object resides when not distrubed. When resting at this position, the sum of the forces that other objects exert on it is zero. During vibrational motion the object passes back and forth through its position from two opposite directions.

### **Restoring Force**

When an object is displaced from equilibrium, some other object exerts a force with a component that always points opposite the direction of the vibrating object's displacement from equilibrium.

This force tends to restore the vibrating object back toward equilibrium.

## **Vibrational Motion**

### **Amplitude**

The amplitude of a vibration is the maximum displacement of the vibrating object from its equilibrium position.

## **Vibrational Motion**

### **Period**

The period T of a vibrating object is the time interval needed for the object to make one complete vibration—from clock reading when it passes through a position while moving in certain direction until the next clock reading when it passes through that same position moving in the same direction. Unit of period is the second.

### Frequency

The frequency f of vibrational motion is the number of complete vibrations of the system during one second. The frequency is related to period:

$$f = \frac{1}{T}$$

The unit for frequency is the hertz (Hz), where 1 Hz = 1 vib/s =  $1 \text{ s}^{-1}$ 

## **Vibrational Kinematics**

Draw on a whiteboard the position vs. time, velocity vs. time, and acceleration vs. time graphs for your oscillating mass.

# PAUSE THE VIDEO AND DO THIS BEFORE MOVING ON!

### **Kinematics**

<iframe style="width: 100%; height: 90%; overflow: hidden;"
src="http://physics.bu.edu/~duffy/HTML5/mass\_on\_spring\_graphs.html" width="100"
height="100" scrolling="no">Iframes not supported</iframe>

# **Simple Harmonic Motion**

Defined as periodic motion that produces a sinusoidal position vs. time graph.

Or another textbook definition:

A object executing simple harmonic motion is subject to a linear restoring force that tends to return the object to its equilibrium position and is linearly proportional to the object's displacement from its equilibrium position.

AP Equation:

$$x = A\cos(2\pi ft)$$

Also:  $\omega = 2\pi f$  so  $x = A\cos(\omega t)$ 

### **Energy**

<iframe style="width: 100%; height: 90%; overflow: hidden;"
src="http://physics.bu.edu/~duffy/HTML5/mass\_on\_spring\_energy.html" width="100"
height="100" scrolling="no">Iframes not supported</iframe>

# **Spring Dynamics**

Period:

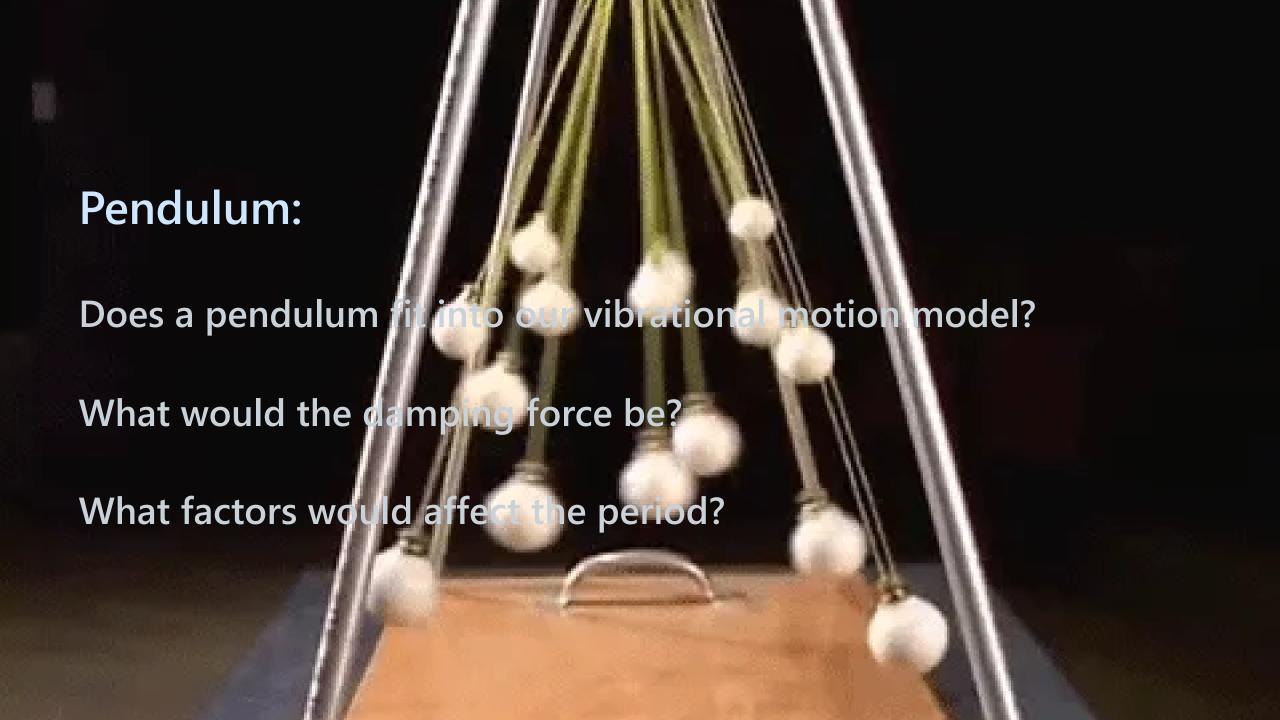
$$\left|T_s=2\pi\sqrt{rac{m}{k}}
ight|$$

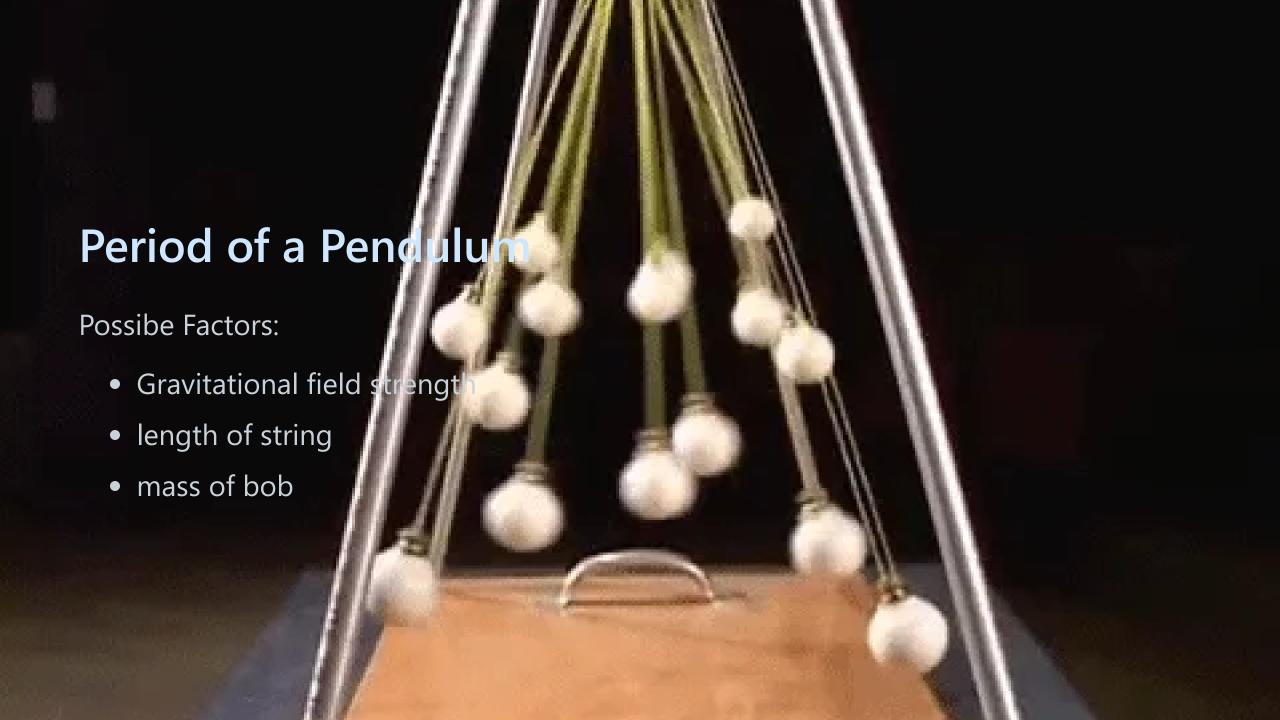
Frequency:

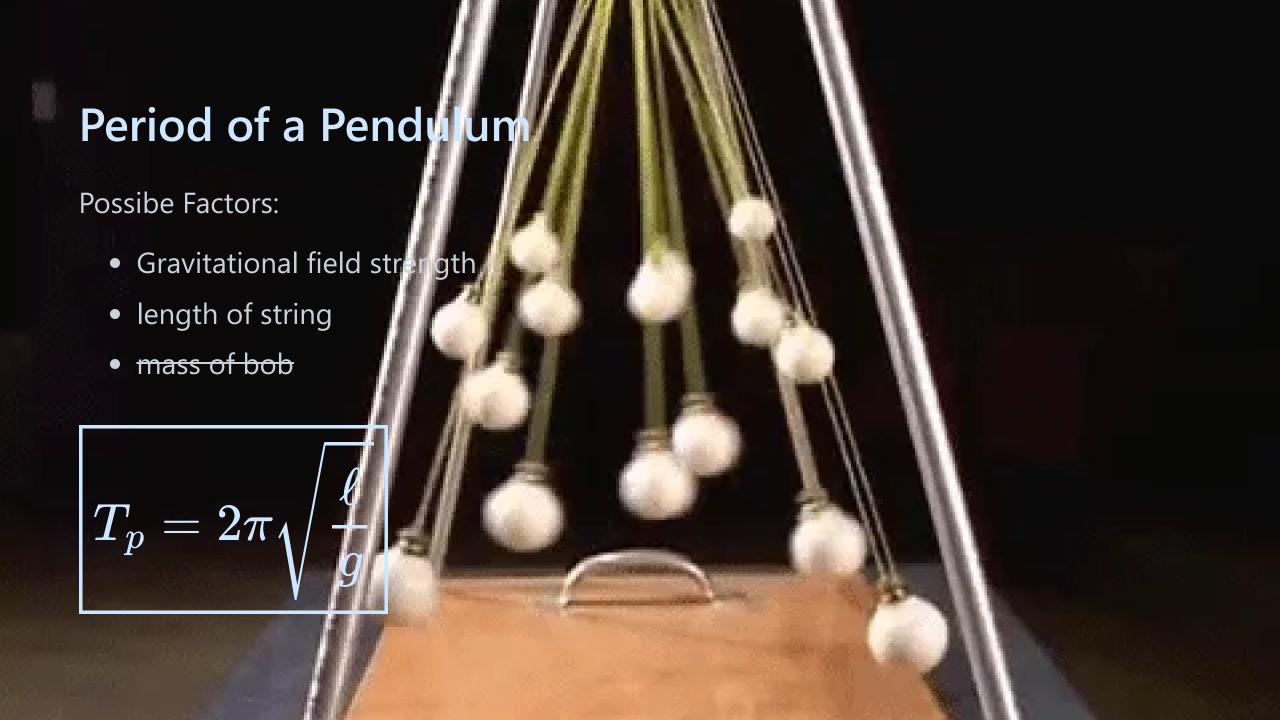
$$f_s = rac{1}{2\pi} \sqrt{rac{k}{m}}$$

## **Simple Harmonic Motion**

Simple harmonic motion is typified by the motion of a mass on a spring when it is subject to the linear elastic restoring force given by Hooke's Law.







## What about Friction?

- Would you masses in lab oscillate forever?
- Does this change the period?
- How would the position vs. time graph change?
- This idea is called *damping*

### **Damping**

<iframe style="width: 100%; height: 90%; overflow: hidden;"
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height="100" scrolling="no">Iframes not supported</iframe>

## **Test Yourself:**

The figures below show systems containing a block resting on a frictionless surface and attached to the end of a spring. The springs are stretched to the right by a distance given in each figure and then released from rest. The blocks oscillate back and forth. The mass and force constant are given for each system.

![]("../figures/Masshorzspring.jpg" width = "800 px")

Rank the systems on the basis of the frequency of vibratory motion.

???

Answer:

Looking for smallest fraction of m/k, so A > B > D = E > C > F

constant  $\(k\)$ . When the cart is displaced from its rest position and released, it oscillates with period  $\(T\)$  that is given by  $\(T = 2 \pi \{sqrt\{frac\{m\}\{k\}\}\})$ . The graph of the position of the cart as a function of time is shown below for Experiment A. Graphs for two other experiments are shown below this. The same spring is used in all three experiments.

.left-column[<img src="../figures/xtgraphs.jpg" width = "400 px"/>]
.right-column[Compared to Experiment A, in Experiment B the cart has:

- 1. twice as much mass
- 2. four times as much mass
- 3. one-half the mass
- 4. one-fourth the mass
- 5. the same mass

???

Answer: Same mass, same period, different amplitude, so it had a different initial

constant  $\(k\)$ . When the cart is displaced from its rest position and released, it oscillates with period  $\(T\)$  that is given by  $\(T = 2 \pi \{sqrt\{frac\{m\}\{k\}\}\})$ . The graph of the position of the cart as a function of time is shown below for Experiment A. Graphs for two other experiments are shown below this. The same spring is used in all three experiments.

.left-column[<img src="../figures/xtgraphs.jpg" width = "400 px"/>]
.right-column[Compared to Experiment A, in Experiment C the cart has:

- 1. twice as much mass
- 2. four times as much mass
- 3. one-half the mass
- 4. one-fourth the mass
- 5. the same mass

???

Answer. The period of C is 1/2 of A. So the mass needs to be smaller, but not 1/2 as

constant  $\(k\)$ . When the cart is displaced from its rest position and released, it oscillates with period  $\(T\)$  that is given by  $\(T = 2 \pi \{sqrt{rac}m\}\{k\}\}\)$ . The graph of the position of the cart as a function of time is shown below for Experiment A. Graphs for two other experiments are shown below this. The same spring is used in all three experiments.

.left-column[<img src="../figures/xtgraphs.jpg" width = "400 px"/>]

.right-column[Suppose that for a fourth experiment (Experiment D), the mass used in Experiment A was doubled and the spring was replaced with a spring with double the spring constant. The period in Experiment D would be:

- 1. the same as the period in Experiment A
- 2. double the period in Experiment A
- 3. four times the period in Experiment A
- 4. one-half the period in Experiment A
- 5. one-fourth the period in Experiment A