# **Laboratory 3: LED Blinking**

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## CSE 2240 -Spring\_2017\_Lab\_Assignments

### **Assembly Language Programming and Machine Organization**

TA: Naseer Jan Junkins 215 & 217

Due date: 10 April, 2017

Section N11 - Tu 12:00PM - 1:50PM Junkins 215 Section N12 - Th 3:00PM - 4:50PM Junkins 217 Section N13 - Tu 8:00AM - 9:50AM Junkins 215

### **Laboratory 3: LED Blinking**

This lab comprises three parts: part-I (Board Set Up and Blinking LEDs Example), part II (i.e. Project setup) & Part-III (ARM assembly programming for LED Blinking). This lab enables you that how to control LEDs and introduce delay among LEDs

### STEP I: Board and Blinking LEDs Example

a) Open the ARM evaluation board user's guide

http://www.keil.com/support/man/docs/mcbstm32c/default.htm

b) Follow steps given in sub-topic 'setup' to setup your board

The MCBSTM32 board requires a power connection and a ULINK-USB adapter between your development PC and the JTAG connector.

To use the MCBSTM32C Evaluation Board with ULINK, you must:

- ➤ Connect the ULINK adapter to the JTAG connector of the MCBSTM32C board
- > Connect the ULINK adapter to the PC via a standard USB cable
- Connect power from your PC to the board using either a USB A to Micro A or USB A to Micro B cable
- c) Load and Debug Blinky project to understand the concept which is as follows:

You can see this in action using uVision Debugger.

 $Go\ to:\ C\backslash\ Keil\_v5\backslash ARM\backslash Boards\backslash Keil\backslash MCBSTM32C\backslash Blinky\backslash\ Blinky.uvproj$ 

Click the **Download to Flash** toolbar button. This executes the Flash download program (**Target Driver** or **External**) selected in **Project** — **Options for Target** — **Utilities** and downloads the application program into the STM32F10x device

## Start the Debugger

Use the **Start/Stop Debug Session** toolbar button to start debugging the program.

Or Use the  $\mu V$ ision command, **Debug** — **Start/Stop Debug Session**, to start debugging the program

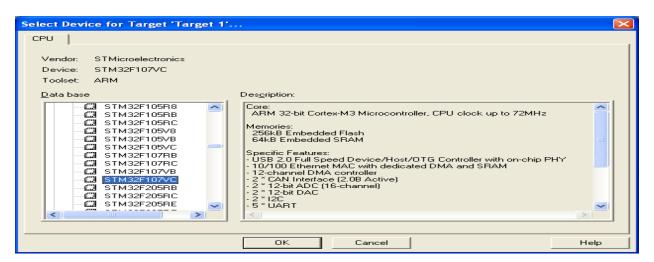
## STEP II: Project setup

a) Create new project under  $Project \rightarrow New \rightarrow \mu Vision \ Project$ , name it 'Led' and save it under project directory. Select the device STM32F107VC under STMicroelectronics. DO NOT add the default startup file. The default startup file is meant to work with C-programs. We have edited the default startup file so that it works with ASM code.

#### **Device selection**

Select the microcontroller from the Device Database

**Vendor**: STMicroelectronics **Device**: STM32F107VC



- b) Please check the appendix to verify if your project settings are correct.
- c) Create groups 'startup' and 'source' to organize all project files
- d) Copy the file *system\_stm32f10x\_cl.s* in the project directory and in Keil add under group 'system' link: <a href="https://drive.google.com/open?id=0BwUNL1MgoXQkcDl6em1ZUlBKZEE">https://drive.google.com/open?id=0BwUNL1MgoXQkcDl6em1ZUlBKZEE</a> or <a href="http://bit.ly/2dQoeee">http://bit.ly/2dQoeee</a>
- e) Add a new source file under 'source'. You can now start writing assembly codes for your lab (refers to **step III**).

## STEP III: ARM assembly programming for LED Blinking

Write an ARM assembly program using c code for Blinky project. The 'Blinky' project is a simple program for the ST 'STM32F107VC' microcontroller using Keil 'MCBSTM32C' Evaluation Board.

Functionality: 8 LEDs blink with speed depending on user defined value.

#### **Hints:**

- ➤ Ignore /\* Setup and initialize ADC converter in C program i.e. from line # 29 to line#53. Use user specify value instead of ADC converter.
- > Setup the clock for port E (GPIOE) and configure port E to work as an output port. LEDs are connected to this port.
- ➤ Calculate and determine the addresses of registers required to configure and use port E by referring to section 2.3 Memory map, Table 1. Register boundary addresses for RCC and GPIOE.
- ➤ RCC\_APB2ENR refers section 6.3.7 APB2 peripheral clock enable register (RCC\_APB2ENR)
  GPIOE\_CRH and GPIOE\_BSRR refers to section 8.2 GPIO registers.
- For example: address of GPIOE\_BSRR (Port bit set/reset register) is GPIOE boundary address =0x4001 1800 + and BSRR = 0x10 GPIOE BSRR = 0x40011810
- You will have to store these addresses in one the general purpose registers to access these port registers.
  - setup the clock for port E store value 0x40 in APB2ENR
- ➤ To setup port E as an output port store value 0x33333333 in GPIOE\_CRH
- ➤ To turn ON any port pins on port E set appropriate bits in lower half of GPIOE\_BSRR. Please refer to the 'ARM STM32 Reference Manual' for Cortex M3 for more information about BSRR.
- ➤ To turn OFF any port pins on port E set appropriate bits in lower half of GPIOE\_BSRR. Please refer the reference manual for Cortex M3 for more information about BSRR

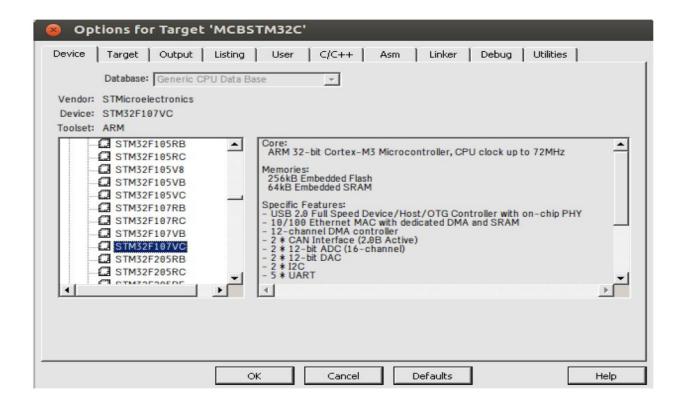
```
#include <stm32f10x cl.h>
#define LED NUM 8
                                    /* Number of user LEDs */
const long led_mask[] = { 1<<15, 1<<14, 1<<13, 1<<12, 1<<11, 1<<10, 1<<9, 1<<8 };
int main (void) {
int AD val, i;
int num = -1;
int dir = 1;
SystemInit();
                                    /* Setup GPIO for LEDs */
                                     /* Enable GPIOE clock */
RCC->APB2ENR |= 1 << 6;
/* Configure the GPIO for LEDs */
/* Setup and initialize ADC converter
RCC->APB2ENR |= 1 << 9;
                                    /* Enable ADC1 clock */
                                    /* Configure PC4 as ADC.14 input */
GPIOC->CRL &= 0xFFF0FFFF;
                                    /* Regular channel 1 conversion */
/* Clear register */
ADC1->SQR2 = 0x0000000000;
ADC1->SQR3 = 14 << 0;
                                    /* SQ1 = channel 14 */
ADC1->SMPR1 = 5 << 12;
                                    /* Channel 14 sample time is 55.5 cyc */
                                    /* Clear register */
ADC1->CR1 = 1 << 8;
                                     /* Scan mode on */
                                    /* Enable external trigger */
ADC1->CR2 = (1 << 20)
(7 << 17) \mid /* EXTSEL = SWSTART
(1 << 1) | /* Continuous conversion
                                    */
                                    */
(1 << 0); /* ADC enable
ADC1->CR2 = 1 << 3;
                                    /* Initialize calibration registers */
                                    /* Wait for initialization to finish */
while (ADC1->CR2 & (1 << 3));
ADC1->CR2 = 1 << 2;
                                    /* Start calibration */
while (ADC1->CR2 & (1 << 2));
                                    /* Wait for calibration to finish */
                                    /* Start first conversion */
ADC1->CR2 = 1 << 22;
                                    /* Loop forever */
for (;;) {
                                    /* If conversion has finished */
if (ADC1->SR & (1 << 1)) {
                                    /* Read AD converted value */
AD_val = ADC1 - DR \& 0x0FFF;
ADC1->CR2 = 1 << 22;
                                    /* Start new conversion */
/* Calculate 'num': 0, 1, ... , LED NUM-1, LED NUM-1, ... , 1, 0, 0, ... */
num += dir;
if (num >= LED_NUM) \{ dir = -1; num = LED_NUM-1; \}
else if (num < 0) \{ dir = 1; num = 0; \}
GPIOE->BSRR = led mask[num]; /* Turn LED on */
for (i = 0; i < ((AD_val << 8) + 100000); i++);
```

```
GPIOE->BSRR = led_mask[num] << 16; /* Turn LED off */
}

Demonstrate result to the lab instructor
Print and submit the file led.s
```

#### **APPENDIX**

Select STM32F107VC under devices.



Select appropriate range for read/write memory areas. Under 'Code Generation' make sure that 'Use MicroLIB' is checked

