

Not bad.

Need practice on time domain analysis (LCCDEs).

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(a)

	Linear	Time-invariant	Static	Causal	Stable
$y[n] = x[n]$	Yes	No	No	No	Yes
$2n^2 x[n] + nx[n+1]$	No	Yes	Yes	Yes	No
$\cos(2\pi n x[n])$	No	Yes	Yes	Yes	Yes

(b)  $x(t/T_s) = \cos(0.5\pi(100t)) = \cos(50\pi t)$

$f = 50 \text{ Hz}$

Missing  $\pi$

-2

(c)  $F_s = 0 \text{ Hz}$   
 $\infty$

-3

It's the opposite.

(d)  $H(z) = \frac{Y(z)}{X(z)} = \frac{3 + z^{-1}}{6 - z^{-1} + 2z^{-2} + z^{-3}} = \frac{3z + 1}{6z^3 - z^2 + 2z + 1}$

$h[n] = \mathcal{Z}^{-1} \left[ \frac{3z + 1}{6z^3 - z^2 + 2z + 1} \right] \Rightarrow \text{So!}$

Use convolution.

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(e)  $Y(z) = H(z) X(z) = \frac{1}{1 - (0.7)^n z^{-1}} \left[ \frac{B(1 - z^{-1} \cos(0.2\pi))}{1 - [2 \cos(0.2\pi)] z^{-1} + z^{-2}} \right]$

$i \quad K_1 (0.7)^n \cos(0.2\pi n + \theta) u[n]$

$\Rightarrow$  This would mean both poles of  $X(z)$  and  $H(z)$  would be protected.

$$\underline{i} \quad K_1 (0.7)^n \cos(0.2\pi n + \theta) u[n]$$

both poles of  $X(z)$  and  $H(z)$   
would be protected.  
Then, it's a linear combination  
of exponentials.

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2.

(a)  $y[n] - 2/15 y[n-1] - 1/15 y[n-2] = \delta[n]$   $y[-1] = 1$   $y[-2] = -1$  Q for impulse response.

$$\lambda^{n-2}(\lambda^2 - 2/15\lambda - 1/15) = 0$$

$$\lambda_{1,2} = \frac{2/15 \pm \sqrt{4/225 + 6/225}}{2} = \frac{2/15 \pm 8/15}{2} = 1/3, -1/5$$

$$y[0] - 2/15 y[-1] - 1/15 y[-2] = 1 \rightarrow y[0] = 1 + 2/15 - 1/15 = 16/15$$

$$y[1] - 2/15 y[0] - 1/15 y[-1] = 0 \rightarrow y[1] = (2/15)(16/15) + 1/15(1)$$

$$y[1] = 33/15$$

$$h[n] = c_1(1/3)^n + c_2(-1/5)^n$$

$$h[0] = c_1 + c_2 = 1$$

$$h[1] = 1/3c_1 - 1/5c_2 = 33/15$$

$$1/5c_1 + 1/3c_2 = 1/5 + 33/15$$

$$\frac{3c_1}{15} + \frac{5c_2}{15} = \frac{36}{15} \Rightarrow 3c_1 + 5c_2 = 36 \rightarrow c_1 = 9/2$$

$$h[n] = (9/2)(1/3)^n - 7/2(-1/5)^n$$

Infinite

(b) The system has finite impulse response and is stable ✓  
because  $\lambda_1, \lambda_2 < 1$

(c)  $y_p[n] = K u[n]$

$$K u[n] - 2/15 K u[n-1] - 1/15 K u[n-2] = K u[n] \rightarrow K = 0$$

ZSR:  $y[-1] = y[-2] = 0$  ✓

$$y[0] = 1$$

$$y[1] - 2/15 y[0] = 1 \rightarrow y[1] = 1 + 2/15 = 17/15$$

$$c_1(1/3)^n + c_2(-1/5)^n$$

$$y[0] = c_1 + c_2 = 1$$

$$y[1] = 1/3c_1 - 1/5c_2 = 17/15$$

$$y_{ZSR} = 33/4(1/3)^n - 29/4(-1/5)^n$$

This is wrong

$$c_2 - 1/5 c_2 \neq 0$$

2. (d)

$$y[n] - 2/15 y[n-1] - 1/15 y[n-2] = 0$$

$$y[0] - 2/15 y[-1] - 1/15 y[-2] = 0$$

$$y[0] = 2/15(1) + 1/15(-1) = 1/15 \checkmark$$

$$y[1] - 2/15 y[0] - 1/15 y[-1] = 0 \Rightarrow y[1] = (2/15)(1/15) + 1/15 = 17/225 \checkmark$$

$$y[n] = c_1 (1/3)^n + c_2 (-1/5)^n$$

$$y[0] = c_1 + c_2 = 1/15$$

$$y[1] = 1/3 c_1 - 1/5 c_2 = 17/225$$

$$c_2 - \frac{1}{5} c_2 = 0 \quad (-1)$$

$$\frac{8c_1}{15} = \frac{1}{15} + \frac{17}{225} \Rightarrow c_1 = \frac{4}{15}$$

$$c_2 = -\frac{2}{15}$$

$$y_{ZIR}[n] = 4/15 (1/3)^n - 2/15 (-1/5)^n$$

$$(c) y_{total} = (4/15 + 33/4) (1/3)^n - (20/4 + 3/15) (-1/5)^n$$

Transient  $\checkmark$

no steady state response  $\checkmark$

3. (a)  $H(z) = \frac{z+1}{z^2 - 3/5z + 2/25}$   $z = \frac{3/5 \pm \sqrt{9/25 - 8/25}}{2} = \frac{3/5 \pm 1/5}{2} = 2/5, 1/5$

$$H(z) = \frac{z+1}{(z+1/5)(z-1/5)} = \frac{A}{(z+1/5)} + \frac{B}{(z-1/5)}$$

$$A(z-1/5) + B(z+1/5) = z+1 \quad A+B=1$$

$$z(A+B) + (-1/5A + 1/5B) = z+1 \quad -1/5A + 1/5B = 1$$

$$h[n] = -(-2/5)^n u[n] + 2(1/5)^n u[n]$$

(b)  $\frac{Y(z)}{X(z)} = H(z) = \frac{z+1}{z^2 - 3/5z + 2/25}$

$\downarrow$

1  $(-1)$

$$A + \frac{1}{5} A \neq 0 \quad (-1)$$

$$3/5 B = 6/5 \Rightarrow B = 2$$

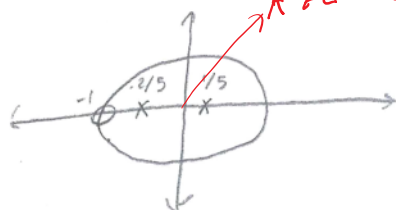
$$A = -1$$

Use Transfer Function  $\leftrightarrow$  LCCDE  
 $\&$  Transform

$(-2)$

3.

(c)  $p: -2/5, 1/5$   $z: -1$



\* zero is at -1 -1

(d) ROC:  $|z| > 1/5$  X  $|z| > \frac{2}{5}$  -2

(e) The system is stable because its poles are inside the unit circle ✓

$$(f) Y(z) = H(z)X(z) = \frac{2}{z - 2/5} - \frac{1}{z - 1/5} = \frac{2(z - 1/5) - (z - 2/5)}{(z - 2/5)(z - 1/5)}$$

$$= \frac{2}{(z - 2/5)(z - 1/5)} \rightarrow X(z) = \frac{2}{(z - 2/5)(z - 1/5)}$$

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