

1.

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(a)	Linear	Time-invariant	Static	Causal	Stable
$y[n] = x[-n] * x[n]$	Yes	No	No	No	Yes
$2n^2 x[n] + n x[n+1]$	No	Yes	Yes	Yes	No
$\cos(2\pi x[n])$	No	Yes	Yes	Yes	Yes

(b) $x(t/T_s) = \cos(0.5\pi(100t)) = \cos(50\pi t)$

$$f = 50 \text{ Hz}$$

(c) $f_s = 0 \text{ Hz}$

(d) $H(z) = \frac{Y(z)}{X(z)} = \frac{3 + z^{-1}}{6 - z^{-1} + 2z^{-2} + z^{-3}} = \frac{3z + 1}{6z^3 - z^2 + 2z + 1}$

$$h[n] = \mathcal{Z}^{-1} \left[\frac{3z + 1}{6z^3 - z^2 + 2z + 1} \right]$$

(e) $Y(z) = H(z) X(z) = \frac{1}{1 - (0.7)^2 z^{-1}} \left[\frac{B(1 - z^{-1} \cos(0.2\pi))}{1 - (2 \cos(0.2\pi)) z^{-1} + z^{-2}} \right]$

i $K_1 (0.7)^n \cos(0.2\pi n + \theta) u[n]$

2.

$$(a) \quad y[n] - \frac{2}{15}y[n-1] - \frac{1}{15}y[n-2] = \delta[n] \quad y[-1] = 1 \quad y[-2] = -1$$

$$\lambda^{n-2}(\lambda^2 - \frac{2}{15}\lambda - \frac{1}{15}) = 0$$

$$\lambda_{1,2} = \frac{\frac{2}{15} \pm \sqrt{\frac{4}{225} + \frac{60}{225}}}{2} = \frac{\frac{2}{15} \pm \frac{8}{15}}{2} = \frac{1}{3}, -\frac{1}{5}$$

$$y[0] - \frac{2}{15}y[-1] - \frac{1}{15}y[-2] = 1 \rightarrow y[0] = 1 + \frac{2}{15} - \frac{1}{15} = \frac{16}{15}$$

$$y[1] - \frac{2}{15}y[0] - \frac{1}{15}y[-1] = 0 \rightarrow y[1] = (\frac{2}{15})(\frac{16}{15}) + \frac{1}{15}(1)$$

$$y[1] = -\frac{32}{15} + \frac{1}{15} = \frac{33}{15}$$

$$h[n] = c_1(\frac{1}{3})^n + c_2(-\frac{1}{5})^n$$

$$h[0] = c_1 + c_2 = 1$$

$$h[1] = \frac{1}{3}c_1 - \frac{1}{5}c_2 = \frac{33}{15}$$

$$\frac{1}{5}c_1 + \frac{1}{3}c_1 = \frac{1}{5} + \frac{33}{15}$$

$$\frac{3c_1}{15} + \frac{5c_1}{15} = \frac{36}{15} \Rightarrow 8c_1 = 36 \rightarrow c_1 = \frac{9}{2}$$

$$c_2 = 1 - \frac{9}{2} = -\frac{7}{2}$$

$$h[n] = \frac{9}{2}(\frac{1}{3})^n - \frac{7}{2}(-\frac{1}{5})^n$$

(b) The system has finite impulse response and is stable because $\lambda_1, \lambda_2 < 1$

$$(c) \quad y_p[n] = K\delta[n]$$

$$K\delta[n] - \frac{2}{15}K\delta[n-1] - \frac{1}{15}K\delta[n-2] = K\delta[n] \rightarrow K = 0$$

$$ZSR: y[-1] = y[-2] = 0$$

$$y[0] = 1$$

$$y[1] - \frac{2}{15}y[0] = 1 \rightarrow y[1] = 1 + \frac{2}{15} = \frac{17}{15}$$

$$c_1(\frac{1}{3})^n + c_2(-\frac{1}{5})^n$$

$$y[0] = c_1 + c_2 = 1$$

$$y[1] = \frac{1}{3}c_1 - \frac{1}{5}c_2 = \frac{17}{15}$$

$$\rightarrow \frac{8c_1}{15} = \frac{22}{5} = \frac{66}{15} \rightarrow c_1 = \frac{33}{4} \quad c_2 = -\frac{29}{4}$$

$$y_{ZSR} = \frac{33}{4}(\frac{1}{3})^n - \frac{29}{4}(-\frac{1}{5})^n$$

2. (d)

$$y[n] - 2/15 y[n-1] - 1/15 y[n-2] = 0$$

$$y[0] - 2/15 y[-1] - 1/15 y[-2] = 0$$

$$y[0] = 2/15(1) + 1/15(-1) = 1/15$$

$$y[1] - 2/15 y[0] - 1/15 y[-1] = 0 \Rightarrow y[1] = (2/15)(1/15) + 1/15 = 17/225$$

$$y[n] = c_1 (1/3)^n + c_2 (-1/5)^n$$

$$y[0] = c_1 + c_2 = 1/15$$

$$y[1] = 1/3 c_1 - 1/5 c_2 = 17/225$$

$$\rightarrow \frac{8c_1}{15} = \frac{1}{15} + \frac{17}{225} \rightarrow c_1 = \frac{4}{15}$$

$$c_2 = -\frac{3}{15}$$

$$y_{ZIR}[n] = 4/15 (1/3)^n - 2/15 (-1/5)^n$$

$$(e) y_{total} = \underbrace{(4/15 + 33/4)(1/3)^n - (20/4 + 3/15)(-1/5)^n}_{\text{Transient}}$$

no steady state response

$$3. (a) H(z) = \frac{z+1}{z^2 - 3/5z + 2/25} \quad z = \frac{3/5 \pm \sqrt{9/25 - 8/25}}{2} = \frac{3/5 \pm 1/5}{2} = 2/5, 1/5$$

$$H(z) = \frac{z+1}{(z+2/5)(z-1/5)} = \frac{A}{(z+2/5)} + \frac{B}{(z-1/5)}$$

$$A(z-1/5) + B(z+2/5) = z+1 \quad A+B=1$$

$$z(A+B) + (-1/5A + 2/5B) = z+1 \quad -1/5A + 2/5B = 1$$

$$3/5B = 6/5 \rightarrow B=2$$

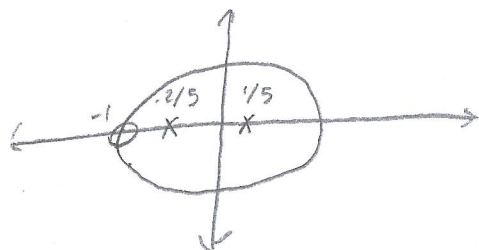
$$A=-1$$

$$h[n] = -(-2/5)^n u[n] + 2(1/5)^n u[n]$$

$$(b) \frac{Y(z)}{X(z)} = H(z) = \frac{z+1}{z^2 - 3/5z + 2/25}$$

3.

CC) $p: -2/5, 1/5 \quad z: -1$



(d) ROC: $|z| > 1/5$

(e) The system is stable because its poles are inside the unit circle

$$\begin{aligned}
 (f) \quad Y(z) &= H(z)X(z) = \frac{2}{z - 2/5} - \frac{1}{z - 1/5} = \frac{2(z - 1/5) - (z - 2/5)}{(z - 2/5)(z - 1/5)} \\
 &= \frac{2}{(z - 2/5)(z - 1/5)} \quad \rightarrow \quad X(z) = \frac{\left(\frac{2}{(z - 2/5)(z - 1/5)} \right)}{\left(\frac{z + 1}{(z + 2/5)(z - 4/5)} \right)}
 \end{aligned}$$